

1. a) $\frac{dx}{dt} + \frac{dy}{dt} + \frac{dz}{dt} = rxz + ryz - rxz - ryz = 0$

b) $\frac{dx}{dt} = rx(N-x-y)$

$\frac{dy}{dt} = ry(N-x-y)$

c) $0 = rx(N-x-y)$ when $\begin{matrix} x=0 \\ x+y=N \end{matrix}$

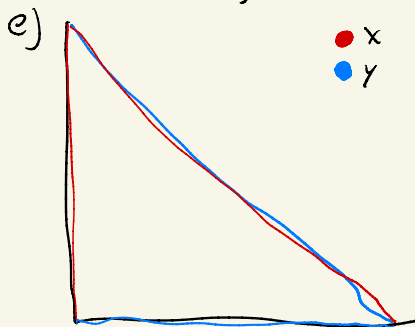
$0 = ry(N-x-y)$ when $\begin{matrix} y=0 \\ x+y=N \end{matrix}$

Steady when $x=y=0$ or $x+y=N$

d) $J = \begin{bmatrix} rN-2rx-ry & rx \\ ry & rN-2ry-cx \end{bmatrix}$

$J_{0,0} = \begin{bmatrix} rN & 0 \\ 0 & rN \end{bmatrix}$

$\lambda = rN$ $(0,0)$ is stable when $r < 0$



f) when $r > 0$ $x+y=N$ is stable
meaning everyone will become radical

when $r < 0$ $x=y=0$ is stable
meaning everyone will become centrist

when $r=0$ all points are stable
meaning nothing will change

2. a) The first term makes the lovers tend towards 0

The second term is a constant increase in love. The first and second term cause the lovers to tend towards A_{SR}

The third term represents a preference for a lovers partner to be around /

b) when $S=0$ & $R>0$

$\frac{dS}{dt} = 0 + A_S + kRe^{-R}$ is positive
+ +

$\frac{dR}{dt} = 0 + A_R + kSe^{-S}$ is positive
+ +

neither axis can be crossed from the 1st quadrant

c) $J = \begin{bmatrix} -1 & k(1-S)e^{-S} \\ k(1-R)e^{-R} & -1 \end{bmatrix}$

$J_{0,0} = \begin{bmatrix} -1 & k \\ k & -1 \end{bmatrix}$

$\lambda^2 + 2\lambda + 1 - k^2$

$\lambda = \frac{-2 \pm \sqrt{4 - 4(1-k^2)}}{2}$

$-1 \pm k$ if $k > 1$, unstable
 $k < 1$, stable