

## UNIVERSITY OF CALOOCAN CITY COMPUTER ENGINEERING DEPARTMENT



Data Structure and Algorithm

Laboratory Activity No. 11

# Implementation of Graphs

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### I. Objectives

#### Introduction

A graph is a visual representation of a collection of things where some object pairs are linked together. Vertices are the points used to depict the interconnected items, while edges are the connections between them. In this course, we go into great detail on the many words and functions related to graphs.

An undirected graph, or simply a graph, is a set of points with lines connecting some of the points. The points are called nodes or vertices, and the lines are called edges.

A graph can be easily presented using the python dictionary data types. We represent the vertices as the keys of the dictionary and the connection between the vertices also called edges as the values in the dictionary.

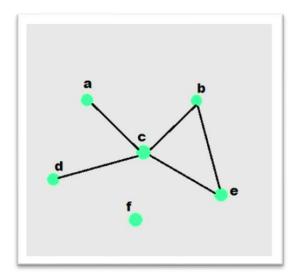


Figure 1. Sample graph with vertices and edges

This laboratory activity aims to implement the principles and techniques in:

- To introduce the Non-linear data structure Graphs
- To implement graphs using Python programming language
- To apply the concepts of Breadth First Search and Depth First Search

### II. Methods

- A. Copy and run the Python source codes.
- B. If there is an algorithm error/s, debug the source codes.
- C. Save these source codes to your GitHub.

from collections import deque

```
class Graph:
  def __init__(self):
     self.graph = \{\}
  def add edge(self, u, v):
     """Add an edge between u and v"""
     if u not in self.graph:
       self.graph[u] = []
     if v not in self.graph:
       self.graph[v] = []
     self.graph[u].append(v)
     self.graph[v].append(u) # For undirected graph
  def bfs(self, start):
     """Breadth-First Search traversal"""
     visited = set()
     queue = deque([start])
     result = []
     while queue:
       vertex = queue.popleft()
       if vertex not in visited:
          visited.add(vertex)
          result.append(vertex)
          # Add all unvisited neighbors
          for neighbor in self.graph.get(vertex, []):
             if neighbor not in visited:
               queue.append(neighbor)
     return result
  def dfs(self, start):
     """Depth-First Search traversal"""
     visited = set()
     result = []
     def dfs util(vertex):
       visited.add(vertex)
       result.append(vertex)
       for neighbor in self.graph.get(vertex, []):
          if neighbor not in visited:
            dfs util(neighbor)
     dfs util(start)
     return result
  def display(self):
     """Display the graph"""
     for vertex in self.graph:
       print(f"{vertex}: {self.graph[vertex]}")
# Example usage
if __name__ == "__main__":
  # Create a graph
```

```
g = Graph()
# Add edges
g.add edge(0, 1)
g.add edge(0, 2)
g.add edge(1, 2)
g.add edge(2, 3)
g.add edge(3, 4)
# Display the graph
print("Graph structure:")
g.display()
# Traversal examples
print(f"\nBFS starting from 0: {g.bfs(0)}")
print(f"DFS starting from 0: {g.dfs(0)}")
# Add more edges and show
g.add\_edge(4, 5)
g.add edge(1, 4)
print(f"\nAfter adding more edges:")
print(f"BFS starting from 0: {g.bfs(0)}")
print(f"DFS starting from 0: {g.dfs(0)}")
```

#### Questions:

1. What will be the output of the following codes?

```
Graph structure:
0: [1, 2]
1: [0, 2]
2: [0, 1, 3]
3: [2, 4]
4: [3]

BFS starting from 0: [0, 1, 2, 3, 4]

DFS starting from 0: [0, 1, 2, 3, 4]

After adding more edges:
BFS starting from 0: [0, 1, 2, 4, 3, 5]

DFS starting from 0: [0, 1, 2, 3, 4, 5]
```

- 2. Explain the key differences between the BFS and DFS implementations in the provided graph code. Discuss their data structures, traversal patterns, and time complexity. How does the recursive nature of DFS contrast with the iterative approach of BFS, and what are the potential advantages and disadvantages of each implementation strategy?
  - BFS uses a queue to visit nodes level by level, while DFS uses recursion to explore deeper paths first. Both have the same time complexity, but BFS is better for shortest paths, and DFS is useful for exploring or checking connections.
- 3. The provided graph implementation uses an adjacency list representation with a dictionary. Compare this approach with alternative representations like adjacency matrices or edge lists.

- The adjacency list is efficient because it only stores existing edges. Unlike an adjacency matrix that takes more space, it's easier to work with and fits most graph problems well.
- 4. The graph in the code is implemented as undirected. Analyze the implications of this design choice on the add\_edge method and the overall graph structure. How would you modify the code to support directed graphs? Discuss the changes needed in edge addition, traversal algorithms, and how these modifications would affect the graph's behavior and use cases.
  - The graph is undirected, meaning edges connect both ways. To make it
    directed, the second connection line in add\_edge can be removed so that
    edges only go one way, which is useful for representing one-way roads or
    data flow.
- 5. Choose two real-world problems that can be modeled using graphs and explain how you would use the provided graph implementation to solve them. What extensions or modifications would be necessary to make the code suitable for these applications? Discuss how the BFS and DFS algorithms would be particularly useful in solving these problems and what additional algorithms you might need to implement.
  - Social networks, where each person can be a node and each friendship an edge. Using BFS, we can find the shortest connection path between two people, while DFS can explore a person's entire network of connections. Another example is city road maps, where intersections are nodes and roads are edges. In this case, BFS can find the shortest route in terms of the number of roads, while DFS could explore all possible routes between two locations. To make the given graph implementation suitable for these problems, we might need to add weights to edges to represent distances or costs and use algorithms like Dijkstra's algorithm or A\* for shortest path finding. Both BFS and DFS serve as a foundation for solving such problems, and by extending this code with weights, direction, or path-tracking features, it can handle more complex real-world graph applications effectively.

#### III. Results

```
Graph structure:
0: [1, 2]
1: [0, 2]
2: [0, 1, 3]
3: [2, 4]
4: [3]

BFS starting from 0: [0, 1, 2, 3, 4]
DFS starting from 0: [0, 1, 2, 3, 4]

After adding more edges:
BFS starting from 0: [0, 1, 2, 4, 3, 5]
DFS starting from 0: [0, 1, 2, 3, 4, 5]
```

Figure 1 Screenshot of program

### IV. Conclusion

Overall, the graph program effectively demonstrates how BFS and DFS work in exploring connected nodes. It shows the importance of choosing the right traversal method depending on the problem—BFS for shortest paths and DFS for deeper exploration. Using an adjacency list makes the graph efficient and easy to understand, and with a few adjustments, it can represent both directed and undirected graphs. Graphs are very useful in real-world situations like social networks and maps, proving how powerful and practical these algorithms are in solving complex problems.

## References

[1] Co Arthur O.. "University of Caloocan City Computer Engineering Department Honor Code," UCC-CpE Departmental Policies, 2020.