view_frames Result Recorded at time: 1638582893.431 base_link camera_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /camera/realsense2_camera_manager Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1638582893.431 sec old) Most recent transform: 0.000 (1638582893.431 sec old) Most recent transform: 0.000 (1638582893.431 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec base_link_inertia camera_depth_frame base Broadcaster: /robot_state_publisher Broadcaster: /ur_hardware_interface Broadcaster: /camera/realsense2_camera_manager Average rate: 47.485 Hz Average rate: 499.209 Hz Average rate: 10000.000 Hz Most recent transform: 1638582893.423 (0.007 sec old) Most recent transform: 1638582893.427 (0.003 sec old) Most recent transform: 0.000 (1638582893.431 sec old) Buffer length: 0.000 sec Buffer length: 4.988 sec Buffer length: 4.970 sec camera_depth_optical_frame tool0_controller shoulder_link Broadcaster: /robot_state_publisher Average rate: 47.485 Hz Most recent transform: 1638582893.423 (0.007 sec old) Buffer length: 4.970 sec upper_arm_link Broadcaster: /robot_state_publisher Average rate: 47.485 Hz Most recent transform: 1638582893.423 (0.007 sec old) Buffer length: 4.970 sec forearm_link Broadcaster: /robot_state_publisher Average rate: 47.485 Hz Most recent transform: 1638582893.423 (0.007 sec old) Buffer length: 4.970 sec wrist_1_link Broadcaster: /robot_state_publisher Average rate: 47.485 Hz Most recent transform: 1638582893.423 (0.007 sec old) Buffer length: 4.970 sec wrist_2_link Broadcaster: /robot_state_publisher Average rate: 47.485 Hz Most recent transform: 1638582893.423 (0.007 sec old) Buffer length: 4.970 sec wrist_3_link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1638582893.431 sec old) Buffer length: 0.000 sec flange Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz

Most recent transform: 0.000 (1638582893.431 sec old)
Buffer length: 0.000 sec

tool0

Broadcaster: /camera/realsense2_camera_manager Average rate: 10000.000 Hz Most recent transform: 0.000 (1638582893.431 sec old) Buffer length: 0.000 sec camera_color_frame Broadcaster: /camera/realsense2_camera_manager Average rate: 10000.000 Hz Most recent transform: 0.000 (1638582893.431 sec old) Buffer length: 0.000 sec camera_color_optical_frame