

The phylodynamic threshold of measurably evolving populations

Ariane Weber^{1,*}, Sanni Översti¹, Julia Kende², and Sebastian Duchene^{3,4,*}.

¹ Pending.

² Institut Pasteur, Université Paris Cité, Bioinformatics and Biostatistics Hub, Paris, France.

³ ED-ID unit, Dept of Computational Biology, Institut Pasteur, Paris, France.

⁴ Peter Doherty Institute for Infection and Immunity, Dept of Microbiology and Immunology, University of Melbourne, Melbourne, Australia.

*email: weber@gea.mpg.de, sduchene@pasteur.fr

Abstract

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1 Introduction

Molecular sequence data have become nearly ubiquitous for studying the evolution of modern and ancient organisms. A fundamental concept in molecular evolution is the ‘molecular clock’, which posits that substitutions accumulate roughly constantly over time (Zuckerkandl and Pauling, 1965). An underlying assumption of the classic molecular clock is that selective constraints are negligible for most sites and over time. The development of molecular clock models as a statistical processes relax this and other assumptions by allowing for rate variation among branches in phylogenetic trees (reviewed by Ho and Duchêne (2014)).

Molecular clock models necessarily involve two key quantities, the evolutionary timescale and the ‘evolutionary rate’, with the latter representing the combination of mutations and substitutions that accrue over time. However, evolutionary times and rates cannot be jointly identified using genetic sequence data alone, that is they are unidentifiable (Dos Reis and Yang (2013) and reviewed by Bromham et al. (2018)). To overcome this problem, all molecular clock methods require prior assumption about evolutionary times or rates, known as a ‘molecular clock calibration’. For example, one can constraint the age of the common ancestor between two lineages (i.e. an internal node in a phylogenetic tree) to a given time or fix the evolutionary rate to a known value. The choice of calibration depends on the information available and its reliability (Duchêne et al., 2014, Warnock et al., 2012).

1.1 Measurably evolving populations

Rapidly evolving organisms, notably viruses and some bacteria, have been found to accrue an appreciable number of mutations over the sampling timescale. Influenza viruses, for example, have evolutionary rates of around 6×10^{-3} subs/site/year (Ghafari et al., 2021, Sanjuán, 2012). Assuming a genome size of 13,500 Kb, one would expect to observe one mutation every 4 to 5 days ($\frac{365 \text{ days/year}}{13500 \text{ sites} \times 6 \times 10^{-3} \text{ subs/site/year}} \approx 4.5 \text{ days/subs}$). If genome samples are collected over the course of a few weeks, then the sampling times themselves can be used

to calibrate the molecular clock, a practice known as ‘tip calibration’ (reviewed by Rieux and Balloux (2016)). Data sets for which the molecular clock can be calibrated using sequence sampling times are considered to have been sampled from a ‘measurably evolving population’ (Drummond et al., 2003b).

Advances in sequencing technologies have dramatically expanded the range of organisms from which data sets can be considered to have been sampled from a measurably evolving population. First, ancient DNA techniques have effectively expanded the genome sampling window for many organisms (Duchene et al., 2020b, Spyrou et al., 2019a). One of many examples, is mitochondrial DNA recovered from dogs from 36,000 years before present (Thalmann et al., 2013), which was found to be sufficient to calibrate its molecular clock. Second, whole genome sequencing has meant that data sets of ‘slowly’ evolving microbes often carry sufficient information for calibrating the molecular clock (Biek et al., 2015). The causative agent of tuberculosis, the bacterium *Mycobacterium tuberculosis*, was commonly considered to evolve too slowly for calibrating the molecular clock using samples collected over a few years (Duchene et al., 2016). However, data sets involving the full genome, of about 4.4 Mb, have demonstrated that a genome sampling window of a few decades might be sufficient for reliable clock calibration (Menardo et al., 2019).

1.2 The phylodynamic threshold

The emergence of SARS-CoV-2 saw the rapid generation of genome data from the early stages of the outbreak, with phylodynamic analyses conducted in near to real-time (Attwood et al., 2022). The first attempts to estimate the evolutionary rate and time of origin were highly uncertain due to two factors; a narrow sampling window and low genetic diversity. In Duchene et al. (2020a) Bayesian phylodynamic analyses of the available genomes were conducted as the outbreak unfolded, such that the number of genomes and the width of the sampling window increased over time and ranged from 22 genomes sampled over 31 days to 122 genomes sampled over 63 days. The early estimates of the evolutionary rate and time of origin had high uncertainty, but they rapidly converged to values that were robust to the addition of more data. The term ‘phylodynamic threshold’ refers to the time where an organism has accrued a sufficient amount of genetic change *since its emergence* for tip-calibrations to be informative (Duchene et al., 2020a).

The terms *phylodynamic threshold* and *measurably evolving population* are different, albeit related, concepts. A population is measurably evolving if the samples available are sufficiently informative as to warrant tip calibration. In contrast, the phylodynamic threshold is the amount of time over which we would need to draw samples for the data set to behave as a measurably evolving population. For a recently evolving pathogen it would simply correspond to the point in time at which it has accrued sufficient genetic diversity since its emergence, under the condition that the data have been collected constantly over time. In contrast, an ancient organism may have attained its phylodynamic threshold, with substantial genetic diversity, but drawing a samples from a very short time window may fail to capture a representative amount of such genetic diversity (fig. 1).

1.3 Temporal signal

Tests of temporal signal are designed to assess our ability to extract information from data for estimating evolutionary rates and timescales (reviewed by Rieux and Balloux (2016)). These tests do not differentiate between recently emerging organisms (i.e. they have not attained their phylodynamic threshold; fig. 1a) and

those with narrow sampling windows (i.e. the data cannot be treated as being drawn from a measurably evolving population; fig. 1d), both of which may lack temporal signal. Additionally, these tests assume that the phylogenetic model adequately captures the evolutionary process. However, pervasive evolutionary rate variation (an 'overdispersed molecular clock') may lead to rejection of temporal signal under a strict clock model. Thus, temporal signal is not solely a property of the data but also depends on model performance. Recent research suggests that the choice of tree prior and molecular clock model significantly impacts the sensitivity and specificity of temporal signal tests, with relaxed molecular clocks being particularly effective (Tay et al., 2024).

Various methods exist for assessing temporal signal, including root-to-tip regression (Buonagurio et al., 1986, Drummond et al., 2003a, Gojobori et al., 1990), date-randomization tests (Duchêne et al., 2015, Duchene et al., 2018, Ramsden et al., 2009, Trovão et al., 2015), and the Bayesian Evaluation of Temporal Signal (BETS; Duchene et al. (2020c)). Root-to-tip regression fits a regression of root-to-tip distance against sampling time, with the R^2 value indicating clocklike behavior. Date-randomization tests compare evolutionary rate estimates using correct sampling times against permutations. BETS evaluates whether including sampling times improves model performance using Bayes factors. Importantly, a lack of temporal signal does not necessarily preclude estimating evolutionary rates and timescales, as additional sources of information (e.g., prior rate estimates or known internal node ages) can provide valid calibration, albeit potentially less precise than sequence sampling times for microbial pathogens.

A lack of temporal signal is typically considered to be associated with unreliable molecular clock estimates. In practice, this situation is thought to be alleviated by broadening the sampling window or by including more ancient samples. However, the presence and direction of a possible bias in estimates of evolutionary rates and timescales is poorly understood.

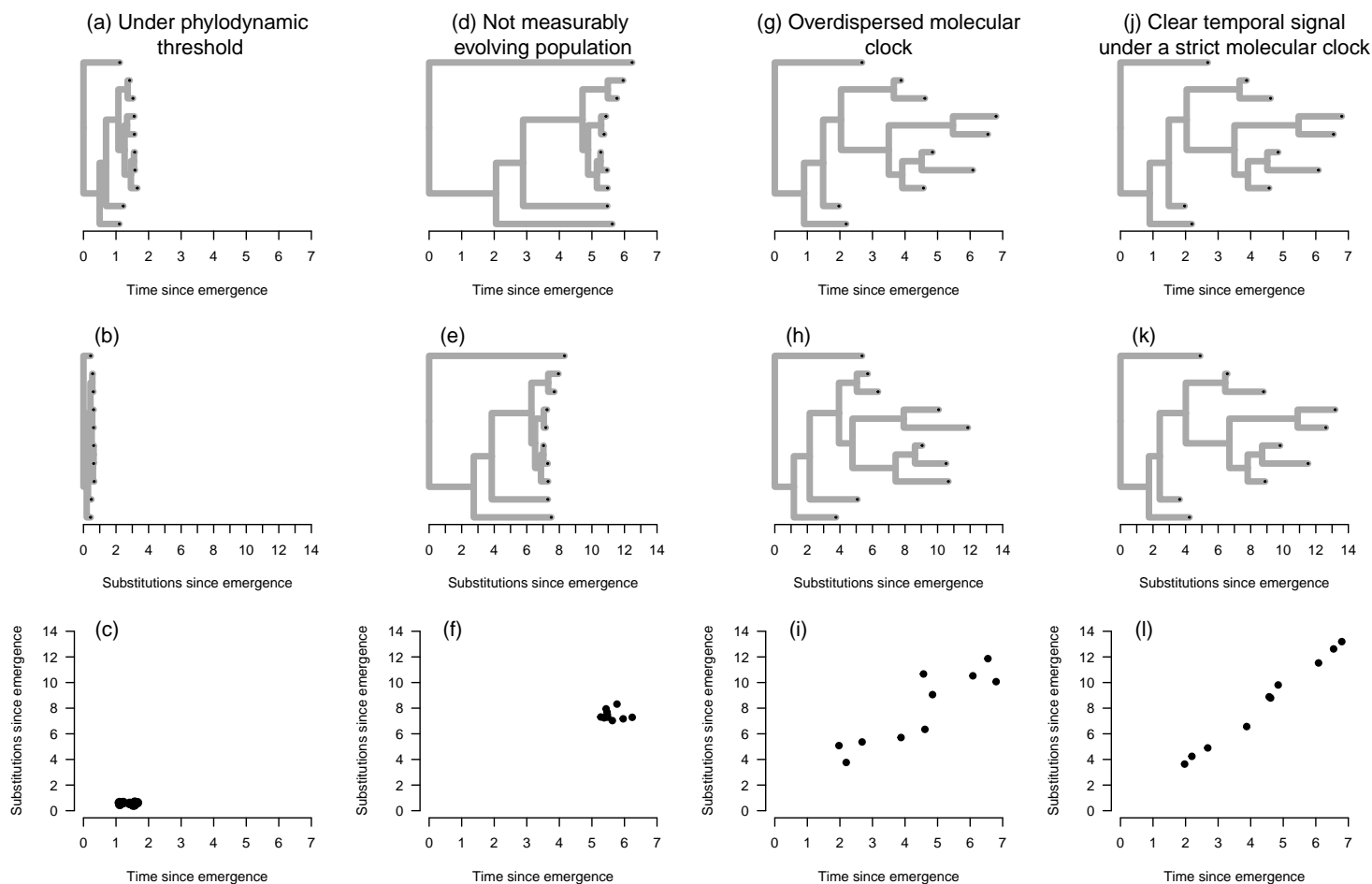


Figure 1: Examples of situations where temporal signal is typically not detected. An organism that has not attained its phylodynamic threshold has a recent time of emergence (with a phylogenetic time tree shown in (a)) because it has not had sufficient time to accrue an appreciable number of substitutions (phylogenetic tree with branch lengths in subs/site, i.e. a ‘phylogram’, shown in (b)), such that it is not possible to establish a statistical relationship between molecular evolution (substitutions) and time (shown in (c)). Sequence data from an organism that has evolved for a substantial amount of time may have been sampled over a very narrow window of time that is not sufficient to treat it as a measurably evolving population (time tree in (d) and phylogram in (e)), which results in no temporal signal (root-to-tip regression in (f)). A data set may involve a wide sampling window of time and from a population that has attained its phylodynamic threshold, but an overdispersed molecular clock (substantial rate variation among lineages; panels (g) - (i)) may result in a lack of temporal signal. In (j) through (l) we show the situation where an organism has attained its phylodynamic threshold and it has been sampled for sufficiently long, as to produce a clear relationship between molecular evolution and time, and unequivocal temporal signal.

2 Results

In this study we sought to pinpoint the impact of sampling strategies on these estimates. We focused our attention on two major problems for emerging microbes and studies involving ancient DNA. First, we varied the sampling window of a population that has attained its phylodynamic threshold. Second, we subsampled a population over time to vary the number of ancient samples, leading to a temporal sampling bias. Finally, we illustrate these results in an empirical data set of Hepatitis B virus (HBV) that includes a large number of ancient samples (Kocher et al., 2021). This virus has been the subject of intense research due to its close association with human populations and complex evolutionary dynamics (Kahila Bar-Gal et al., 2012, Paraskevis et al., 2013, Ross et al., 2018).

2.1 Sampling windows relative to the phylodynamic threshold

We simulated sequence data that resembled the evolution of HBV, a double-stranded DNA (dsDNA) virus that has evolved in humans for around 10 thousand years (Kocher et al., 2021). Our synthetic data had a genome length of 3,200 Kb and an evolutionary rate of 1.5×10^{-5} subs/site/year (Kocher et al., 2021, Mühlemann et al., 2018). Under these conditions we expect to observe one mutation every 20 years ($\frac{1}{3200 \text{ sites} \times 1.5 \times 10^{-5} \text{ subs/site/year}} \approx 20 \text{ years}$). This number is important for the design of our simulation experiments: 20 years is the time we would expect for it to attain its phylodynamic threshold and it is typically the required sampling window to detect temporal signal. We analysed the data under a Bayesian phylogenetic framework and considered whether the posterior contained the true value used to generate the data, known as coverage, and the width of the posterior, known as precision (a ‘precise’ estimate has a narrow posterior distribution).

2.2 Calibration windows for tips

We conceived a simulation process under which the evolutionary timescale had an expected time of 10 thousand years and with a sampling window of 0, 10, 20, 200, or 2,000 years. A sampling window spanning 0 years results in ultrametric trees with the sampling times providing no calibration information. In contrast, a sampling window of 10 years is half of the phylodynamic threshold and is expected to have weak temporal signal (see fig. 1(d)-(f)). Sampling windows of 20 years (the phylodynamic threshold) or wider are expected to behave as measurably evolving populations and with increasingly strong temporal signal (see fig. 1(j)-(l)). All our simulations were analysed under Bayesian phylogenetic framework, as implemented in the BEASTv2.5 platform (Bouckaert et al., 2019).

All our simulations produced posterior estimates that included the correct value used to generate the data (i.e. 100% coverage; fig. 2). Increasingly wide sampling windows improved the precision of the estimates, while still including the correct value. This result is unsurprising, given our configuration of the prior. Notably, the prior on the phylogenetic tree and the evolutionary rate are particularly influential for estimating evolutionary rates and timescales (for a detailed investigation see Tay et al. (2024)). Here, the tree prior is a constant-size coalescent for which the prior on the population size (known as Θ) is an exponential distribution with mean of 5,000, which matches the value used to generate the data. Similarly, the evolutionary rate had a prior in the form of a Γ distribution with *shape* = 1.5 and *rate* = 10^5 , whose mean is *shape* \times *rate* = 1.5×10^{-5} .

134 and thus also matches the ‘true’ value. Although these priors are centred on the correct values, they are
135 vague, and it is important to note that in all cases, the posterior distribution of the evolutionary rate and
136 tree height was narrower than the prior, meaning that even in the absence of sampling times the sequence
137 data provide some information about these two parameters.

138 We reanalysed this data with a different priors on the population size and the evolutionary rate that
139 were deliberately ‘misleading’. The prior on the population size was an exponential distribution with mean
140 of 50,000, whereas the prior on the evolutionary rate was $\Gamma(shape = 1.5, rate = 10^6)$ (mean= 1.5^{-6}). Under
141 this configuration the mean prior mass corresponds to trees that are one order of magnitude older than
142 the truth and evolutionary rates that are an order of magnitude slower. The objective of this experiment
143 is to determine whether the sampling window is sufficiently informative to overcome such misleading prior
144 information.

145 The posterior distribution was largely contained within the prior, resulting in low coverage for the evo-
146 lutionary rate for sampling windows of 0, 10, and 20 years (0% coverage; fig. 3). A sampling window of 200
147 years was necessary to obtain 92% coverage, while a sampling window of 2,000 years had 100% coverage and
148 with even higher precision (fig. 3). These results demonstrate that a misleading prior that excludes, or poses
149 a very low probability on the true value, requires a sampling window that is potentially much wider than
150 that corresponding to the phylodynamic threshold.

151 We did not detect a systematic bias associated with the width of the sampling window, contrary to the
152 expectation that low temporal signal necessarily results in an underestimation of the evolutionary rate and
153 an overestimation of the tree height (Duchêne et al., 2015). Instead, we find that a lack of temporal signal
154 due to narrow sampling windows may simply lend more influence to the prior.

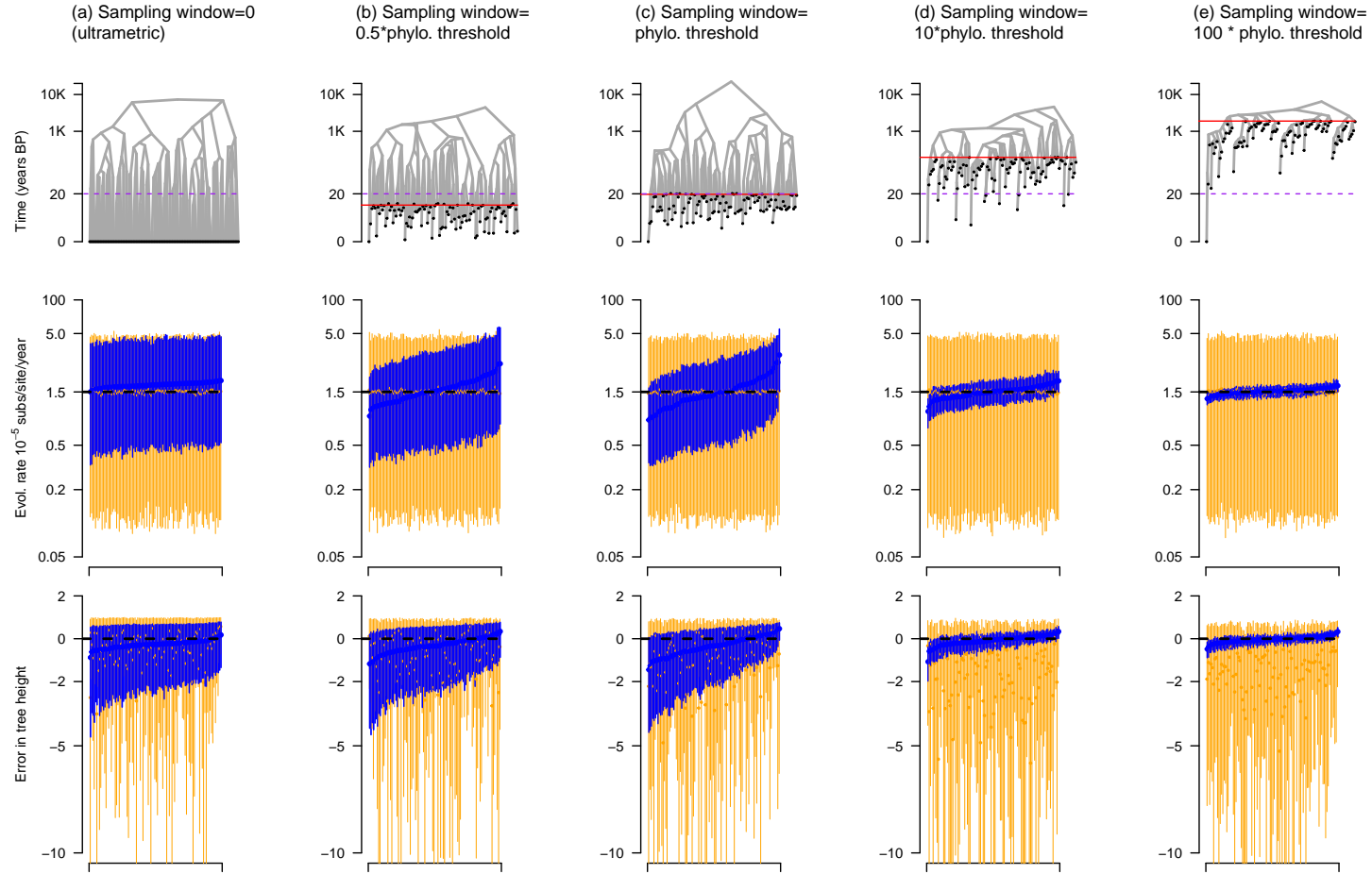


Figure 2: Simulations of varying sampling window widths. Each column corresponds to a simulation setting: (a) is for ultrametric trees where all samples are collected at the same point in time, (b) is for the situation where the sampling window is 10 years (half the phylodynamic threshold), (c) is where the sampling window is exactly the phylodynamic threshold of 20 years. Scenarios (d) and (e) denote sampling windows that are 10 and 100 times the phylodynamic threshold. The first row is an example of a simulated phylogenetic tree with branch lengths scaled in units of time. The black circles represent genomic samples. The purple dashed line is the phylodynamic threshold and the solid red line is for the oldest sample, such that it represents the sampling window. Note that time here is shown in \log_{10} scale. The second row is the estimated evolutionary rate over 100 simulations. The dashed black line is the value used to generate the data (i.e. the ground truth), the dark blue bars are the posterior, and those in orange are the prior. For the prior and the posterior we use solid circles to show the mean estimate and the width of the error bars denotes the 95% quantile range. The third row is the estimate of the error in tree height (the age of the tree). The error in tree height is calculated as $\frac{\text{true} - \text{estimated}}{\text{true}}$.

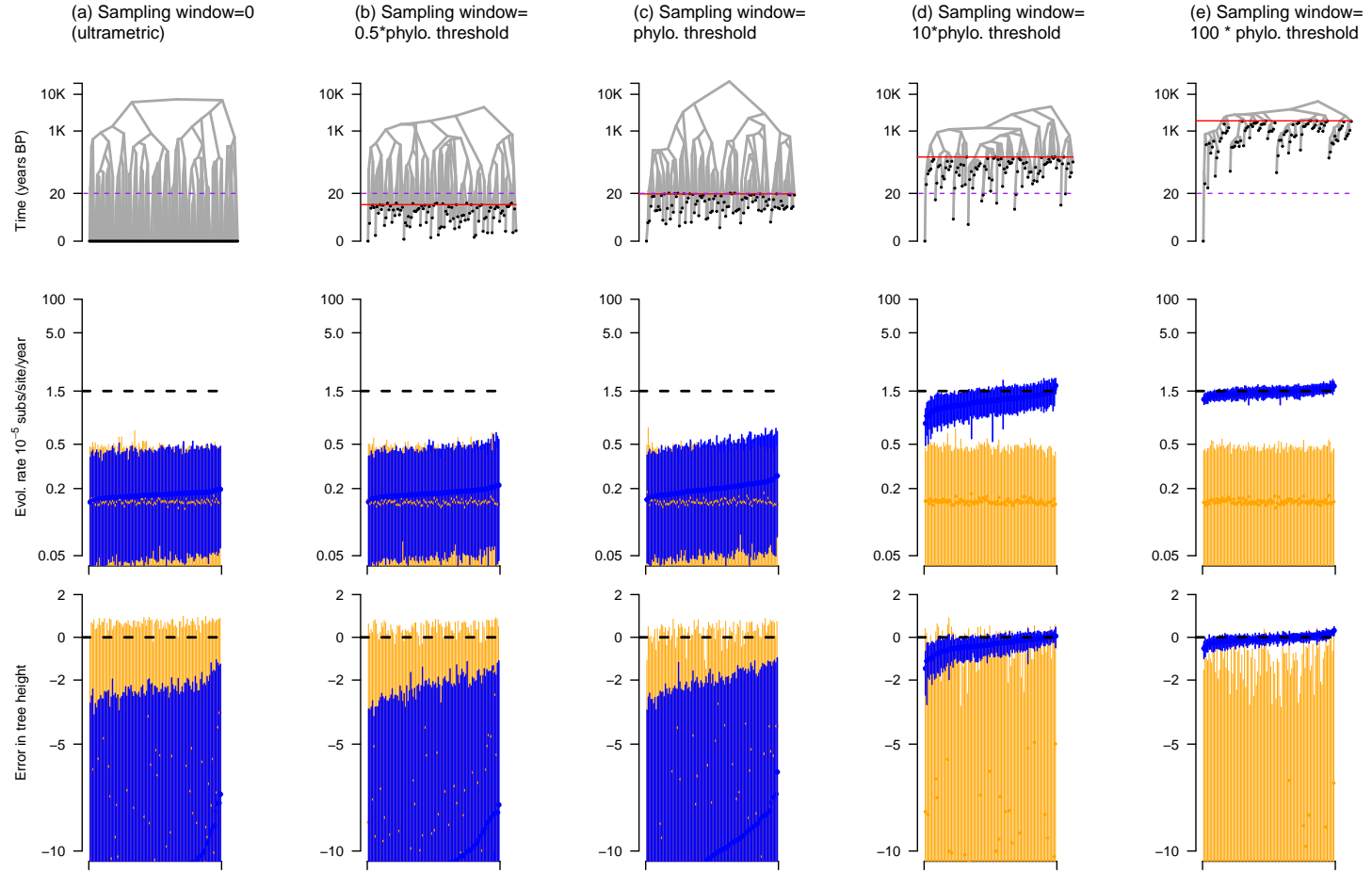


Figure 3: Simulations of varying sampling window widths. The colours, labels and legends match those from fig 2. However, in these analyses we deliberately use misleading priors on two key parameters, with an exponential distribution with mean 5,000 for the coalescent population size (true value=5,000), and a $\Gamma(shape = 1.5, rate = 10^6)$ with mean 1.5×10^{-6} (true value 1.5×10^{-5}).

2.3 Temporal sampling bias

We investigated the impact of temporal sampling bias on the precision and accuracy on molecular clock estimates. For this purpose we simulated data with the same genomic characteristics as HBV and where genome sampling was conducted over five periods of time uniformly distributed between the present and the root of the trees (fig. 4(a)). The fully sampled trees contained 500 genome samples, equally distributed over each of the five sampling times. Such stratified sampling is expected in ancient DNA studies, for example when a set of samples are drawn from archaeological sites (e.g. Spyrou et al. (2019b)). We sampled the complete data sets by randomly selecting 20 samples from each strata, which we refer to as ‘time-uniform’ sampling, and by sampling with a probability that is inversely proportional to the age of the strata, referred to as ‘time-biased’. The time-uniform and time-biased sampling strategies both contain 100 samples ($1/5^{th}$ of the complete data), but the time-biased only includes a small number of ancient samples.

The coverage of the evolutionary rate estimate was comparable across simulation treatments, at 88% for the complete data set, 83% for the time-uniform, and 89% for the time-biased (fig. 4(b)). The somewhat higher coverage for the estimates from the time-biased analyses is likely because this sampling treatment reduces the precision of the posterior, rather than an improvement in both accuracy and precision.

We also calculated a measure of bias for both sampling strategies by counting the number of simulations for which the posterior mean with either sampling strategy was higher than that with the complete data. We found that 50% of the estimates under time-uniform sampling had higher means than the complete data, where as the same was true for 45% of those with time-biased sampling (fig. 5(a)). Although these numbers do not indicate a substantial bias, we do note that time-biased sampling tends to lead to lower mean evolutionary rate estimates than using the complete data or time-uniform sampling.

The most striking result from temporal sampling strategies was in the precision of the posterior. Both sampling treatments resulted in posterior distributions that were wider than that with the complete data, which is to be expected because they are effectively smaller data sets with less information. However, the time-biased sampling data sets almost invariably has posterior distributions that were less precise than those from the time-uniform sampling.

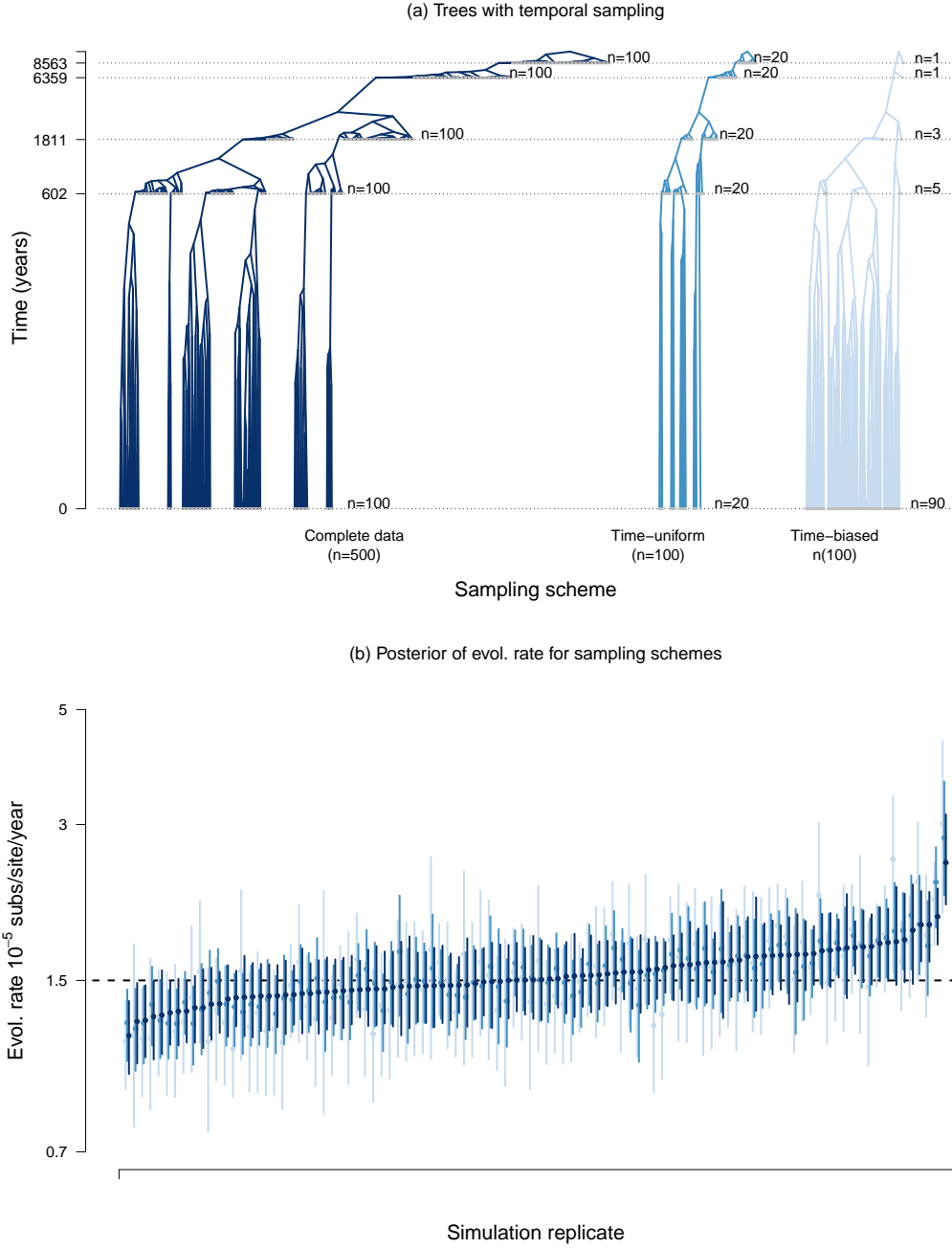


Figure 4: Analyses under sampling treatments over time. In (a) we show an example of a the trees for a simulation replicate, with branch lengths and time in \log_{10} scale. The complete data set consists of 500 genome samples, collected in five points in time, with an equal number of samples per time point ($n=100$). The first sampling strategy is unbiased, where 20 samples are drawn from each time point, and is known here as ‘time-uniform’. The ‘time-biased’ regime is where sampling intensity decreases over time. Note that the total number of samples in the time-uniform and time-biased treatments is identical. In (b) we show the posterior estimates of the evolutionary rate for each treatment. Each simulation replicate is represented by three error bars: dark blue for the complete data, and lighter shades of blue for the estimates from the time-uniform and time-biased sampling treatments. The width of the error bars denotes the 95% quantile range and the dots are the mean value. The dashed line shows the true value used to generate the data.

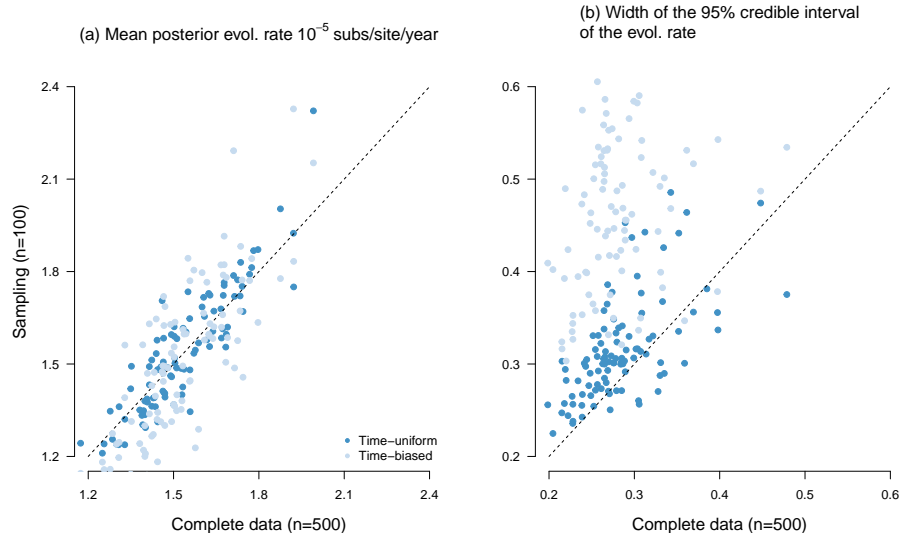


Figure 5: Trees plot thing pending

DRAFT UP TO HERE. FIGURE 5 NEEDS A LEGEND AND THEN WE NEED A SUMMARY FROM THE EMPIRICAL DATA

Table 1: placeholder for any tables

Model	ps logML	ss logML	ps rank	ss rank	ps BF	ss BF
FLC shared stems	-55427.65	-55428.17	1	1	0	0
FLC stems	-55431.50	-55432.14	2	2	-3.85	-3.97
UCG	-55433.64	-55434.26	3	3	-6.00	-6.01
UCLN	-55434.32	-55434.69	4	4	-6.67	-6.52
FLC shared clades+stems	-55443.30	-55443.50	5	5	-15.64	-15.34
SC	-55443.53	-55444.21	6	6	-15.88	-16.04
FLC shared clades	-55449.89	-55450.52	7	7	-22.23	-22.35
FLC clades+stems	-55453.91	-55454.58	8	8	-26.25	-26.41
FLC	-55461.87	-55462.54	9	9	-34.21	-34.38

3 Discussion

Pending. Key points to mention:

- That sequences are informative, even when there is no sampling time information and when they are identical. They are simply consistent with a very slow rate. In popular Bayesian analyses the prior puts a lot of weight on small values, which probably explains favours low values even when the sampling window is narrow.
- thus using a reasonable prior and to conduct prior sensitivity is important.

4 Materials and methods

Pending.

5 Acknowledgements

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