`learnPolicy`

minimize	$\rbrack$ Find $\theta^* \in \arg\min_\theta J(\theta)$		
value	$\rbrack$ Compute $J(\theta) = \sum_{t=1}^T \mathrm{E}[c(\mathbf{x}_t)|\theta]$		
propagate			
controller	Compute $p(\mathbf{x}_{t+1}|\theta)$	Policy Evaluation	Policy Search
gp*			
cost.fcn	$\rbrack$ Compute $\mathrm{E}[c(\mathbf{x}_{t+1})|\theta]$		
BFGS	$\rbrack$ Update θ	$\rbrack$ Policy Improvement	