sheet05

November 26, 2022

1 sheet 05

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```
[1]: import numpy as np
from matplotlib import pyplot as plt

plt.rcParams['figure.figsize'] = [12, 8]
plt.rcParams['figure.dpi'] = 300 # higher resolution figures
plt.rc('text', usetex=True) # use LaTeX in axis and plot titles
```

1.1 1 QDA

(a)

We have 320 points 170 of which have label "0"

(b) To calculate the posterior p(y=0|x), we use Bayes' rule:

$$p(y=0|x) = \frac{p(x|y=0)p(y=0)}{p(x)}$$
 (1)

$$= \frac{p(x|y=0)p(y=0)}{p(x|y=0)p(y=0) + p(x|y=1)p(y=1)}$$

$$= \frac{p(x|y=0)p(y=0)}{p(x|y=0)p(y=0) + p(x|y=1)p(y=0)}$$
(2)
$$= \frac{p(x|y=0)p(y=0)}{p(x|y=0)p(y=0) + p(x|y=1)p(y=0)}$$
(3)

$$= \frac{p(x|y=0)p(y=0)}{p(x|y=0)p(y=0) + p(x|y=1)p(y=0)}$$
(3)

$$= \frac{p(x|y=0)}{p(x|y=0) + p(x|y=1)},$$
(4)

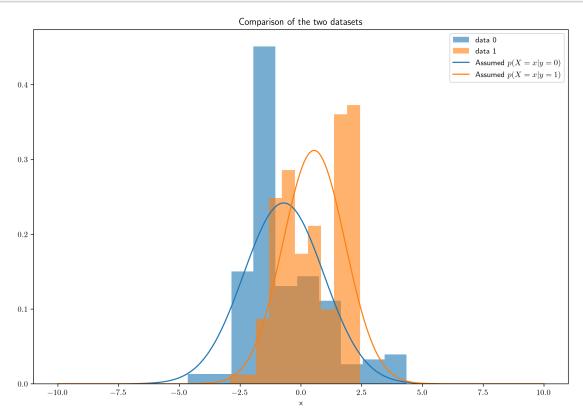
where all the probabilities remaining in the last expression are taken to be the gaussians calculated in part (a).

```
[3]: from scipy.stats import norm
     # TODO: evaluate the Gaussian class densities in a range from -10 to 10
     #plt.hist(pts0, density=True)
     x=np.linspace(-10,10,250)
     \#plt.plot(x, norm.pdf(x, mean0, std0))
     #plt.title('Gaussian estimation of points labelled "0"')
     #plt.show()
     #plt.hist(pts1, density=True)
     \#x=np.linspace(mean1-4*std1, mean1+4*std1, 150)
     \#plt.plot(x, norm.pdf(x, mean1, std1))
     #plt.title('Gaussian estimation of points labelled "1"')
     #plt.show()
     # add transparency to histograms (bc we use default matplotlib-colors, they
      ⇔even match the fits :D)
     plt.hist(pts0, density=True, label='data 0', color='#1f77b499')
     plt.hist(pts1, density=True, label='data 1', color='#ff7f0e99')
     \#x=np.linspace(mean0-4*std0,mean0+4*std0,150)
     plt.plot(x, norm.pdf(x, mean0, std0), label=r'Assumed $p(X=x|y=0)$')
     \#x=np.linspace(mean0-4*std1,mean1+4*std0,150)
     plt.plot(x, norm.pdf(x, mean1, std1), label=r'Assumed $p(X=x|y=1)$')
     plt.title('Comparison of the two datasets')
     plt.legend(loc='best')
     plt.xlabel('x')
     plt.show()
     # TODO: evaulate the posterior p(y=1/x)
     prob0 = norm.pdf(x, mean0, std0)
     prob1 = norm.pdf(x, mean1, std1)
     posterior = prob0/(prob0+prob1)
     plt.xlabel(r'$x$')
     plt.ylabel(r'$p(y=0|X=x)$')
```

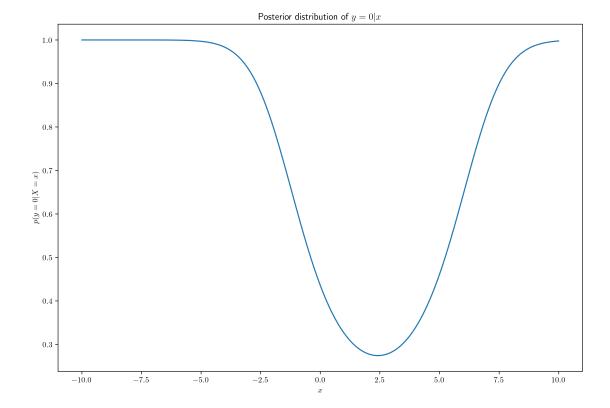
```
plt.title(r'Posterior distribution of $y=0|x$')
plt.plot(x,posterior)

# TODO: plot the class densities and the posterior p(y=1|x). (Don't forget

→ title, axis labels, legend)
```



[3]: [<matplotlib.lines.Line2D at 0x7fa8e40ed660>]



Our observation: The probability, that y=0 is very high (almost 1) for x>9.5 and x<5. This is because the Gaussian for y=1 is slimmer, so that the probability of y=0 is much higher than y=1 in these areas. In the interval (-5,7.5), p(y=0) has a lot of variation. This is centered around the area where the two gaussians pictured above overlap. At $x\approx2.5$, the probability of y being zero takes its minimum. This is not located at the peak of the distribution of p(X=x|y=1), but rather further to the right.

1.2 2 Mean of the Bernoulli distribution

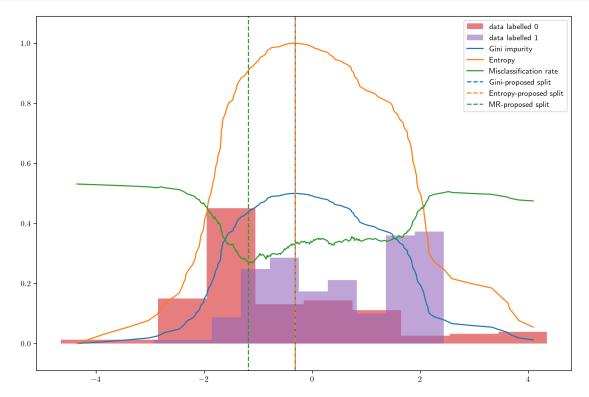
$$\mathbb{E}[X] = \sum_{x \in \{0,1\}} \left(\mu^x (1-\mu)^{1-x} \cdot x \right) = \mu^1 (1-\mu)^0 + 0 = \mu$$

1.3 3 Trees and Random Forests

(a)

```
[4]: # load the data
pts = np.load('data/data1d.npy')
labels = np.load('data/labels1d.npy')
#plt.hist(pts[np.where(labels==1)])
# TODO: Sort the points to easily split them
order = np.argsort(pts)
#print(order)
```

```
pts = pts[order]
labels = labels[order]
#plt.show()
#plt.hist(pts[np.where(labels==1)])
#plt.show()
splits=np.zeros(pts.shape[0]-1)
gini=np.zeros(pts.shape[0]-1)
entropy=np.zeros(pts.shape[0]-1)
misclassif=np.zeros(pts.shape[0]-1)
# TODO: Implement or find implementation for Gini impurity, entropy and
 ⇔misclassifcation rate
for i in range(len(pts)-1):
    splits[i] = (pts[i]+pts[i+1])/2
    p0 = i/len(pts)
    p1 = 1-i/len(pts)
    gini[i] = 1 - p0**2 - p1**2
    if p0 == 0:
        entropy[i] = -p1*np.log(p1)/np.log(2)
    elif p1 == 0:
        entropy[i] = -p0*np.log(p0)/np.log(2)
    else:
        entropy[i] = (-p1*np.log(p1) - p0*np.log(p0))/np.log(2)#divide by <math>ln(2)_{\cup}
 \rightarrow for log_2(...)
    classification = np.zeros(pts.shape)
    classification[i:] = 1
    misclassif[i] = np.sum(np.abs(classification-labels)) / pts.shape[0]
# TODO: Iterate over the possible splits, evaulating and saving the three |
 ⇔criteria for each one
# TODO: Compute the split that each criterion favours and visualize them
        (e.g. with a histogram for each class and vertical lines to show the
⇔splits)
# use transparency for the histograms; use C3 and C4 from matplotlib
plt.hist(pts[labels==0], density=True, label='data labelled 0', __
 ⇔color='#d6272899')
plt.hist(pts[labels==1], density=True, label='data labelled 1', u
 plt.plot(splits, gini, label='Gini impurity')
plt.plot(splits, entropy, label='Entropy')
plt.plot(splits, misclassif, label='Misclassification rate')
plt.ylim(-.09, 1.09)
plt.vlines(splits[np.argmax(gini)], -.13, 1.12, colors='CO', __
 ⇔label='Gini-proposed split', linestyles='dashed')
# we add 0.02, because the proposed splits
```



(b)

```
[5]: # load the dijet data
features = np.load('data/dijet_features_normalized.npy').T
labels = np.load('data/dijet_labels.npy')

#print(features.shape)
#print(labels.shape)
# TODO: define train, val and test splits as specified (make sure to shuffleuthe data before splitting it!)
order = np.random.shuffle(np.arange(len(labels)))
features = features[order][0]
labels = labels[order][0]
#print(features.shape)
#print(labels.shape)
#data is now shuffled
```

```
# to get validation and training sets, we use sklearn.cross_validation.

train_test_split

# this only splits in training and validation set, so we use it twice :D

#from sklearn.cross_validation import train_test_split

from sklearn.model_selection import train_test_split

features_train, features_test, labels_train, labels_test=_u

train_test_split(features, labels, test_size=200)

features_train, features_val, labels_train, labels_val =_u

train_test_split(features_train, labels_train, test_size=200)
```

```
[6]: from sklearn.ensemble import RandomForestClassifier
     # TODO: train\ a\ random\ forest\ classifier\ for\ each\ combination\ of
      →hyperparameters as specified on the sheet
             and evaluate the performances on the validation set.
     nTreess = [5, 10, 20, 100]
     criteria = ['gini', 'entropy']
     depths = [2, 5, 10, None] # according to documentation: When passing ⊔
     \rightarrow max_depth=None,
     # sklearn will work until all leaves are pure
     scores = np.zeros((4, 2, 4))
     for i, nTrees in enumerate(nTreess):
         for j, criterion in enumerate(criteria):
             for k, depth in enumerate(depths):
                 forest = RandomForestClassifier(n_estimators=nTrees,_
      ⇔criterion=criterion, max_depth=depth)
                 forest.fit(features_train, labels_train)
                 scores[i,j,k] = forest.score(features_val, labels_val)
```

```
[7]: # TODO: for your preferred configuration, evaluate the performance of the best_
configuration on the test set

best_params = np.unravel_index(scores.argmax(), scores.shape)

print(f'The best set of hyperparameters are:\nNumber of Trees:_
fnTreess[best_params[0]]}\nCriterion: {criteria[best_params[1]]}\nMax depth:_
fdepths[best_params[2]] if depths[best_params[2]] is not None else "pure"}')

forest = RandomForestClassifier(n_estimators=nTreess[best_params[0]], criterion_
forest.fit(features_train, labels_train)

score = forest.score(features_test, labels_test)

rate = 1 - np.sum(np.abs(forest.predict(features_test)-labels_test))/200

print(f'Performance of the test set: score = {score}, got {rate*100}% right')
```

The best set of hyperparameters are:

Number of Trees: 10 Criterion: entropy Max depth: pure

Performance of the test set: score = 0.75, got 74.5% right

1.4 4 Beta Distribution

a) The prior distribution is taken to be

$$\mu_x = \frac{c_{x,1}}{c_{x,0} + c_{x,1}}.$$

The posterior distribution is then $p(\mu_x|c_{x,y}=1)$, because $c_{x,y}$ are per definition our observations. It is obtained following Bayes' rule:

$$p(\mu_x|c_{x,y}=1) = \frac{p(c_{x,y}=1|\mu_x)p(\mu_x)}{p(c_{x,y}=1)}, \tag{5}$$

where

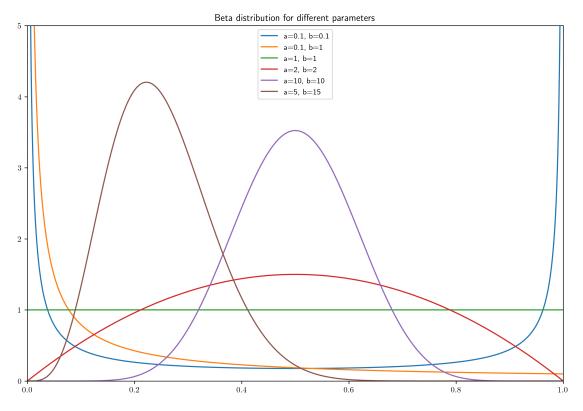
$$p(c_{x,y} = 1 | \mu_x) = \text{Bern}(c_{x,y} = 1; \mu_x) = \mu_x \tag{6}$$

$$p(\mu_x) = 1 \tag{7}$$

$$p(c_{x,y} = 1) = \frac{c_{x,1}}{c_{x,0} + c_{x,1}},\tag{8}$$

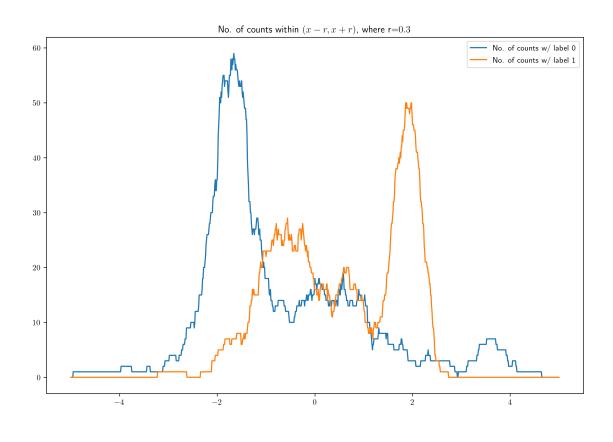
where $p(\mu_x) = 1$ follows from what is given in the code cell below, i.e. we use a flat prior.

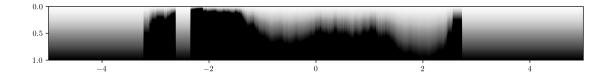
```
[9]: from scipy.special import gamma, gammaln
     def beta_pdf(x, a, b):
         """Probability density function for the Beta distribution with parameters a_{\sqcup}
      ⇔and b. Works verctorized over all inputs"""
         return (gamma(a+b) * x**(a-1) * (1-x)**(b-1)) / gamma(a) / gamma(b) #__
      ⇒breaks down for larger a, b
         return np.exp(gammaln(a+b) - gammaln(a) - gammaln(b) + np.log(x)*(a-1) + np.
      \rightarrowlog(1-x)*(b-1)) # works for larger a, b
     eps = 1e-6
     x = np.linspace(eps, 1-eps, 1000, endpoint=True)
     for a, b in ((0.1, 0.1), (0.1, 1), (1, 1), (2, 2), (10, 10), (5, 15)):
         plt.plot(x, beta_pdf(x, a, b), label=f'{a=}, {b=}')
     plt.legend()
     plt.ylim(0, 5)
     plt.xlim(0, 1)
     plt.title('Beta distribution for different parameters')
     plt.show()
```

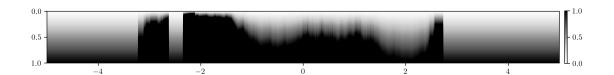


```
[10]: def count_points_within_distance(x, pts, r):
          Count number of points among pts within a distance r of query points x (in_
       \hookrightarrow 1D).
          Parameters
          x : np.ndarray
              Query points of shape (M).
          pts : np.ndarray
              Points to be searched, shape (N).
          r:float
              radius.
          Returns
          _____
          np.ndarray
              Array of counts of shape (M)
          # TODO: sort the points
          spts = np.sort(pts)
          # TODO: use np.searchsorted on the interval boundaries
                  to find number of points inside each interval (don't use loops!)
          counts = np.searchsorted(spts, x+r) - np.searchsorted(spts, x-r)
          return counts
      # use a flat prior
      prior_a, prior_b = 1, 1
      # define value range
      vmin, vmax = -5, 5
      # set the radius
      r = .3
      \# TODO: sample x and mu as described in the exercise
      x = np.linspace(-5, 5, 1001, endpoint=True)
      mu = np.linspace(0, 1, 101, endpoint=True)
      # TODO: use count_points_within_distance to calculate the counts
      cts0 = count_points_within_distance(x, pts[labels==0], r)
      cts1 = count_points_within_distance(x, pts[labels==1], r)
      \# TODO (optional): plot the counts vs x
      plt.plot(x, cts0, label='No. of counts w/ label 0')
```

```
plt.plot(x, cts1, label='No. of counts w/ label 1')
plt.title(r'No. of counts within (x-r,x+r), where r=\{(:.1f)\}'.format(r))
plt.legend(loc='best')
plt.show()
# TODO: evaluate the posterior to get an image (use broadcasting, no loops<sub>\square</sub>
\hookrightarrowneeded!)
# avoid divide-by-zero-errors; in this case just keep the prior
denom1 = (cts0+cts1)
denom1[denom1==0] = 1
denom = cts1/denom1
denom[denom==0] = 1
denom[denom1==0] = 1
posterior = np.tile(mu, (1001,1)).T / np.tile(denom, (101,1))
# TODO: plot the posterior as an image, specify the correct origin and extent
plt.imshow(posterior, origin='upper', extent=(-5,5,1,0), cmap='Greys', vmin=0., ___
 \rightarrowvmax=1.)
plt.show()
# we plot it again with a colorbar, but then the x-axes of the counts and the
→matrix do not line up anymore
plt.imshow(posterior, origin='upper', extent=(-5,5,1,0), cmap='Greys', vmin=0., u
 \rightarrowvmax=1.)
# colorbar with scaling magic courtesy of: https://stackoverflow.com/a/26720422
plt.colorbar(fraction=0.005, pad=0.01)
plt.show()
```







Interpretation of the results above:

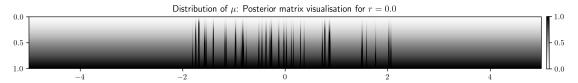
If the number of counts with label 0 is higher (i.e. when our observation is mostly zero), the probability of μ_x being lower is higher. In these regions, the lower μ -values are much darker.

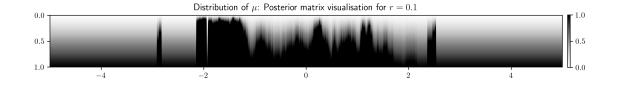
Further we observe, that all high values of μ still have a dark color, i.e. a high posterior probability. This shows the high influence of the prior distribution.

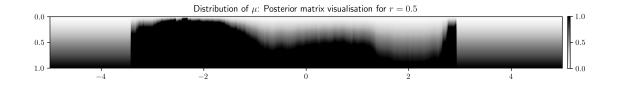
(d) Repetition for higher and lower values of r:

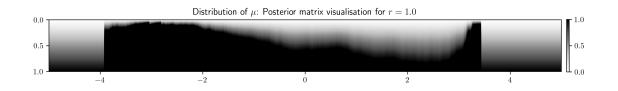
```
[11]: def plot_posterior_matrix(r):
          # this is just the code taken from above for easier repetition with
       \hookrightarrow different values for r
          prior_a, prior_b = 1, 1
          # define value range
          vmin, vmax = -5, 5
          \# TODO: sample x and mu as described in the exercise
          x = np.linspace(-5, 5, 1001, endpoint=True)
          mu = np.linspace(0, 1, 101, endpoint=True)
          # TODO: use count_points_within_distance to calculate the counts
          cts0 = count_points_within_distance(x, pts[labels==0], r)
          cts1 = count_points_within_distance(x, pts[labels==1], r)
          # TODO: evaluate the posterior to get an image (use broadcasting, no loops,
       →needed!)
          # avoid divide-by-zero-errors; in this case just keep the prior
          denom1 = (cts0+cts1)
          denom1[denom1==0] = 1
          denom = cts1/denom1
          denom[denom==0] = 1
          denom[denom1==0] = 1
          posterior = np.tile(mu, (1001,1)).T / np.tile(denom, (101,1))
          # TODO: plot the posterior as an image, specify the correct origin and
       \rightarrow extent
          plt.imshow(posterior, origin='upper', extent=(-5,5,1,0), cmap='Greys',__

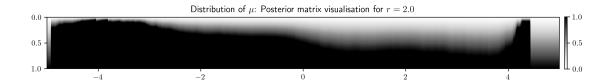
ymin=0., vmax=1.)
          plt.colorbar(fraction=0.005, pad=0.01)
          plt.title(r'Distribution of $\mu$: Posterior matrix visualisation for $r={:.
       \hookrightarrow1f}$'.format(r))
          plt.show()
      for r in [.01, .1, .5, 1, 2]:
          plot_posterior_matrix(r)
```











We observe: The lower r, the more artefacts we have because of divide-by-zero-errors, where there are no counts. With higher r, the posterior distribution of $\mu_x|c_{x,y}$ is smoothed out.

We would opt for a value of r=0.3 or at least something in the range (0.1,0.3) as we see that here for $x\approx 2$, we still have a very low posterior probability of μ_x close to one, which is what would be expected from the distribution of the data.

(e) Bonus We did not do this bonus exercise.

1.5 5 The Multivariate Normal

5×	$\frac{P(x y_x)\rho(y_x)}{\rho(x)}$
PLA	ν _κ × = Γίχ)
Ex	<u> </u>
06	serve only the exponent:
(×	$\vec{x} - \vec{p}$) \vec{r} $(\vec{x} - \vec{p}) = (x_1 - p_1) \begin{pmatrix} x_1 - p_1 \\ x_2 - p_2 \end{pmatrix} \begin{pmatrix} x_1 - p_1 \\ x_2 - p_2 \end{pmatrix}$
=	(1/1/(×1-μ1) + 1/21 (×2-μ2)) 1/12 (×1-μ1) + 1/22 (×2-μ2) (×2-μ2)
7	1/11 (x1-p1)2+121 (x1-p1)(x2-p2) + 1/12 (x1-p1) (x2-p2) + 1/22 (x2-p2)2
= >	×3 101 -2×1/2 100 + 42 100 + ×1 (x2-42) 1 121-121 (x2-42)
+	×1112 (×2-P2) -112 p2 (×2-p2) + 122 (×2-p2)
= >	\times^2 (Λ_{11})
t >	x, [-2 p, 1, + (x2-p,) 121 + 1 = (x2-p2)]
+1	1 [pi 11 + p1 121 (x1-p2) + 122 p1 (x2-p2) + 122 (x2-p2)]
1	$(x_1-y)\lambda(x_1-y)=x_1^2\lambda-x_1\cdot2y\lambda+y_2^2\lambda$
=) ,	1 102 2 = The Symmetric >> 1= 5 is also symmetrics
-23	×2 = -2 β μης \$ Λης = -2μη Ληη + (xz - μz) Λzη + Λης (xz - μz)
=)	P112 = V = -1 (-2 p1 11 + (x2 - P2) 121 + 112 (x2 - P2)
	= p1 - (x2-p2) (121+112) = p1 - (x2-p2) 122
112=111 = 12 P	112 = p1 - (x2-p2) 111 E12 E22 = p1 - (x2-p2) E12 E22
2112 = 1	11 = (Z11 - Z12 Z2-1 Z21) ** #MGCET