in1
PRIMARY_INPUT
AraC_sensor

in2
PRIMARY_INPUT
TetR_sensor

in3
PRIMARY_INPUT
LacI_sensor

$2
NOR
P2_PhlF

$4
NOT
A1_AmtR

$3
NOR
E1_BetI

$1
NOR
B1_BM3R1

out
PRIMARY_OUTPUT
YFP_reporter

m0x1D