Cupertino, CA, USA

- ₹ SKILLS Advanced embedded control system design acquired from project and hands-on laboratory experiences
 - Exceptional critical thinking and problem-solving skills allowing for complex engineering analysis
 - Highly motivated and organized self-starter with a strong attention to detail and work ethic
 - Outstanding oral and written communication to share creative ideas fluently in both English and French
 - Able to thrive and lead in a team or work independently in a dynamic deadline driven environment
 - Proficient in iWork, SOLIDWORKS, MATLAB/Simulink, Python, C++, C, LabVIEW, IATEX, Bash
 - Experience with PLC/SCADA/HMI systems, embedded microcontroller programming (TI, Raspberry Pi, Arduino, x86 Assembler), Xilinx FPGA, Linux, ECAD tools, ANSYS FEA and CFD

EDUCATION University of Waterloo

Waterloo, ON, CAN

Candidate for B.ASc. 3.3/4.0 GPA

Sept. 2013 - Present

Honours Mechanical Engineering Co-op Program

EXPERIENCE Apple Inc.

Cupertino, CA, USA

Controls Engineering: Special Projects Group (SPG)

Aug. 2017 - Present

- Developed a HIL system to validate power electronic control algorithms for autonomous technologies
- Designed system harness to interface HIL with PCBA from schematics and hardware specifications
- Programmed LabVIEW HMI for communication of PXIe RTOS controller and FPGA models and circuit solver final deployment
- Implementation of MATLAB/Simulink models firmware in C on embedded MCU, DSP with discrete implementatio of second order filters
- Converted continious MATLAB/Simulink models to discrete time for FPGA
- Control system plant model emulation on NI cRIO Linux controller and x32 FPGA
- Assured robustness of control architecture with verification of safety-critical diagnostics algorithms
- Automated regression testing with Python and LabVIEW
- Hardware communication protocols serial, ethernet, SPI PCIe, I2C, UART
- Debug and bring-up of high voltage PCBAs with JTAG, ethernet, serial, safely with in-house test racks, electronic lab equipment and NI instrumentation, realiability
- Employed Agile software development with Atlassian tools (JIRA, Confluence, Sourcetree) to track firmware bugs and fixes

Altaeros Energies

Boston, MA, USA

Systems Engineering

Jan. - Apr. 2017

- Performed FEA in ANSYS and PYTHON on prototype of worlds first commercial autonomous aerostat
- Coordinated with vendors and ControlEng SERVOsoft to size all control system components (servos, VFDs)
- Utilized electronic lab equipment, sensors and LabVIEW HMI to gather test data and analyze with MATLAB electromechanical

Ontario Die International Inc.

Kitchener, ON, CAN

Research & Development

- May Aug. 2016
- Designed robotic components (electrical, hydraulic) of PLC/CNC bending systems in SOLIDWORKS • Automated tedious SOLIDWORKS tasks in VBA and C++ with the API in MS Visual Studio IDE
- Performed hands-on Q&A HMI testing, machined components, fabricated assemblies with power/hand tools

Pratt & Whitney Canada

Mississauga, ON, CAN

Operations Program Management Analyst

Sept. - Dec. 2015

- Assured on time OEM delivery of a quality turbofan engine while meeting their expectations and needs
- Developed Excel VBA programs allowing for improvements in methods of business metric preparation

Skyjack Inc.

Guelph, ON, CAN

Manufacturing Engineering

Jan. - Apr. 2015

• Worked with a team of engineers to troubleshoot production issues at an aerial work platform manufacturer

PROJECTS Ball & Beam Lab

ECE481: Digital Control Systems

Aug 2017

• Designed LabVIEW HMI, performed system ID, implemented/tuned digital controller on NI cRIO FPGA

Drum Rhythm Arduino Hack Personal: WIT Hackathon

• Coded firmware in C and communicated over UART to MATLAB for real-time monitoring of drumming vibration

Wind Turbine Pitch Actuator ME360: Control Systems

Dec. 2016

• Studied time/frequency domain responses in MATLAB for closed loop stability of PI controlled Simulink

Mining Safety Device ME380: Engineering Design

Nov. 2016

• Developed a 3D printed enclosure to protect internal Arduino and sensors of severe underground environment

DC Motor Control System ME360: Control Systems

• Designed real-time PID control in simulation with Simulink for DC motor; implemented with QUARC C code generation

WKRPT 300: Co-op 4 **CNC Bending Powertrain**

Sept. 2016

• Performed iterative testing with HMI to gather data for selection; assured compatibility into control system

Dune-Buggy Repairs

Personal

Aug. 2016

 \bullet Diagnosted fuel system ignition issue then replaced carburetor, \mathbf{coils} and $\mathbf{armature}$

- □ INTERESTS Further developing skills while gaining new exposure to firmware, real-time controls and electronics Repairing off-road vehicles, DIY Arduino projects, hockey, golf, swimming and socializing with friends