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# **tenma-serial**

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# CHAPTER 1

## tenma API

### Contents

- *tenma API*
  - *Instantiation*
  - *API Documentation*

## 1.1 Instantiation

You can use the tenma class you deem necessary by directly creating an instance of the class referencing your model.

The api can autodetect the model and return a proper instance (or a default one which may or may not suit your limits) by simply using the provided function:

```
from tenma import instantiate_tenma_class_from_device_response
tenma = instantiate_tenma_class_from_device_response('/dev/ttyUSB0')
```

or the more manual (with your own knowledge) approach:

```
from tenma import Tenma72_2550
tenma = Tenma72_2550('/dev/ttyUSB0')
```

In case something does not work as you would expect, instantiate the class with the debug option enabled so all the transmissions to and from the unit are printed to stdout:

```
from tenma import Tenma72_2550
tenma = Tenma72_2550('/dev/ttyUSB0')
```

## 1.2 API Documentation

tenmaDcLib is small python library to control a Tenma 72-XXXX programmable DC power supply, either from USB or Serial.

Supported models:

- 72\_2545 -> tested on HW
- 72\_2535 -> Set as manufacturer manual (not tested)
- 72\_2540 -> Set as manufacturer manual (not tested)
- 72\_2550 -> Set as manufacturer manual (not tested)
- 72\_2930 -> Set as manufacturer manual (not tested)
- 72\_2940 -> Set as manufacturer manual (not tested)

Other units from Korad or Vellman might work as well since they use the same serial protocol.

**class** tenma.tenmaDcLib.**Tenma72Base** (*serialPort, debug=False*)

Control a tenma 72-XXXX DC bench power supply

Defaults in this class assume a 72-2540, use subclasses for other models

**OFF** ()

Turns OFF the output

**ON** ()

Turns on the output

**getStatus** ()

Returns the power supply status as a dictionary of values

- ch1Mode: "C.V | C.C"
- ch2Mode: "C.V | C.C"
- **tracking:**
  - 00=Independent
  - 01=Tracking series
  - 11=Tracking parallel
- BeepEnabled: True | False
- lockEnabled: True | False
- outEnabled: True | False

**getVersion** ()

Returns a single string with the version of the Tenma Device and Protocol user

**recallConf** (*conf*)

Load existing configuration in Memory. Same as pressing any Mx button on the unit

**runningCurrent** (*channel*)

Returns the current read of a running channel

**runningVoltage** (*channel*)

Returns the voltage read of a running channel

**saveConf** (*conf*)

Save current configuration into Memory.

Does not work as one would expect. SAV(4) will not save directly to memory 4. We actually need to recall memory 4, set configuration and then SAV(4)

**saveConfFlow** (*conf, channel*)

Performs a full save flow for the unit. Since saveConf only calls the SAV<NR1> command, and that does not work as advertised, or expected, at least in 72\_2540.

**This will:**

- turn off the output
- Read the voltage that is set
- recall memory conf
- Save to that memory conf

**Parameters**

- **conf** – Memory index to store to
- **channel** – Channel with output to store

**setBEEP** (*enable=True*)

Enable or disable BEEP

There's no feedback from the serial connection to determine whether BEEP was set or not.

**Parameters** **enable** – Boolean to enable or disable

**setOCP** (*enable=True*)

Enable or disable OCP.

There's no feedback from the serial connection to determine whether OCP was set or not.

**Parameters** **enable** – Boolean to enable or disable

**setOVP** (*enable=True*)

Enable or disable OVP

There's no feedback from the serial connection to determine whether OVP was set or not.

**Parameters** **enable** – Boolean to enable or disable

```
class tenma.tenmaDcLib.Tenma72_2535 (serialPort, debug=False)
```

```
MATCH_STR = '72-2535'
```

```
MAX_MA = 3000
```

```
MAX_MV = 30000
```

```
NCHANNELS = 1
```

```
NCONFS = 5
```

```
class tenma.tenmaDcLib.Tenma72_2540 (serialPort, debug=False)
```

```
MAX_MA = 5000
```

```
MAX_MV = 30000
```

```
NCHANNELS = 1
```

```
NCONFS = 5
```

Only 4 physical buttons. But 5 memories are available

```
class tenma.tenmaDcLib.Tenma72_2545(serialPort, debug=False)
```

```
MATCH_STR = '72-2545'
```

```
MAX_MA = 2000
```

```
MAX_MV = 60000
```

```
NCHANNELS = 1
```

```
NCONFS = 5
```

```
class tenma.tenmaDcLib.Tenma72_2550(serialPort, debug=False)
```

```
MATCH_STR = '72-2550'
```

```
MAX_MA = 3000
```

```
MAX_MV = 60000
```

```
NCHANNELS = 1
```

```
NCONFS = 5
```

```
class tenma.tenmaDcLib.Tenma72_2930(serialPort, debug=False)
```

```
MATCH_STR = '72-2930'
```

```
MAX_MA = 10000
```

```
MAX_MV = 30000
```

```
NCHANNELS = 1
```

```
NCONFS = 5
```

```
class tenma.tenmaDcLib.Tenma72_2940(serialPort, debug=False)
```

```
MATCH_STR = '72-2940'
```

```
MAX_MA = 5000
```

```
MAX_MV = 60000
```

```
NCHANNELS = 1
```

```
NCONFS = 5
```

```
exception tenma.tenmaDcLib.TenmaException
```

```
tenma.tenmaDcLib.instantiate_tenma_class_from_device_response(device, debug=False)
```

Get a proper Tenma subclass depending on the version response from the unit.

The subclasses mainly deal with the limit checks for each unit.



### Contents

- *tenma-control*
  - *General Description*
  - *Print the Tenma version*
  - *Set the current and the voltage*
  - *Turn on the channel output*
  - *Turn off the channel output*
  - *Load an existing memory*
  - *Create a new value for a memory 4*
  - *Verbose output*
  - *Serial output*

## 2.1 General Description

tenma-control (tenmaControl.py) lets you control your bench power supply directly from the command line via a serial connection.

This page provides a set of common examples on how to use the tenma-control command. For a full description of the options provided simply run:

```
tenma-control -h
```

The command always expects its input input as milliAmperes and milliVolts:

## 2.2 Print the Tenma version

```
tenma-control /dev/ttyUSB0
```

## 2.3 Set the current and the voltage

For example: 2.2 Amperes 5V:

```
tenma-control -c 2200 -v 5000 /dev/ttyUSB0
```

## 2.4 Turn on the channel output

```
tenma-control --on /dev/ttyUSB0
```

## 2.5 Turn off the channel output

```
tenma-control --off /dev/ttyUSB0
```

## 2.6 Load an existing memory

```
tenma-control -r 1  
tenma-control --recall 2
```

## 2.7 Create a new value for a memory 4

```
tenma-control -c 2200 -v 5000 --save 4 /dev/ttyUSB0
```

## 2.8 Verbose output

```
tenma-control -c 2200 -v 5000 --save 4 --verbose /dev/ttyUSB0
```

## 2.9 Serial output

```
tenma-control -c 2200 -v 5000 --save 4 --debug /dev/ttyUSB0
```

#### Contents

- *tenma-applet*
  - *General Description*
  - *Select the serial connection*

### 3.1 General Description

tenma-applet (gtkIndicator.py) lets you control your bench power supply using a simple GTK applet sitting on the system bar.

It provides basic ON/OFF and Memory selection. Current version is limited to the values already set in the unit.

To start it:

```
tenma-applet
```

### 3.2 Select the serial connection

tenma-applet lists the available serial connections under the *serial* menu. Simply selecting a connection and the applet tries to retrieve the model information and connect to it.



## CHAPTER 4

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### Indices and tables

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