

2

Fundamental Data Structures

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ADT = abstract data type

- list of supported operations
- what should happen
- not how to do this
- not how data is stored

VS

data structures

- o how data is stored in memory
- o algorithms to work on data

ex: stack pop() → removes topmost element
push(v) → adds v to top of stack



1

pop

pop

push(1)

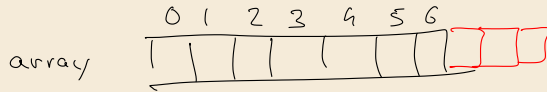
Outline

2 Fundamental Data Structures

- 2.1 Stacks & Queues
- 2.2 Resizable Arrays
- 2.3 Priority Queues
- 2.4 Binary Search Trees

2.1 Stacks & Queues

2.2 Resizable Arrays



- o arrays have fixed size

- ↳ if we need more space, allocate new array & copy old data

- o doubling arrays: when array is full double its size

- o if array becomes too empty (deletions)

- ↳ if $\leq \frac{1}{4}$ full \leadsto halve size

\rightarrow space $\Theta(n)$ $n = \#$ elements stored

Java Generics

Stack < String >

Stack < Integer >

implement ^{ONCE} stack with type parameter

use stack with many different types

Iterators

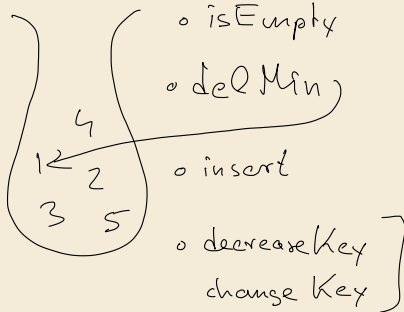
ADT abstracts linear scan over collection of items

- o hasNext()

- o next move ahead & return element

2.3 Priority Queues

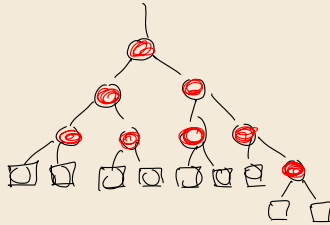
ADT



Heaps

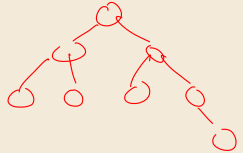
o binary tree

extended binary trees



every node has
0 or 2 children

binary trees



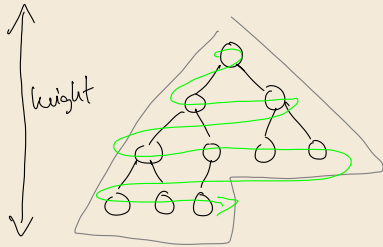
nodes have
left / right children
(both can be missing)

o complete binary tree + flush-left — lowest level as far to the left as possible



— "heap-shaped trees"

Why heap-shaped trees?



o minimal height
among binary
trees with n nodes

n nodes \rightarrow 1 heap-shape

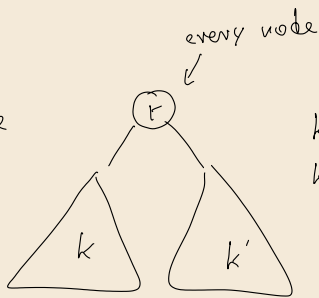
\Rightarrow easy

can use array : store nodes in
level-order starting
at 1

\rightarrow find parent of
node k at $\lfloor \frac{k}{2} \rfloor$
left child at $2k$
right $\sim 2k+1$

heap-order

entire subtree
version



$$k \geq r$$

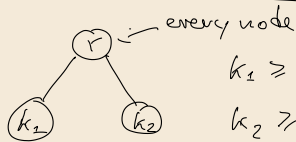
$$k' \geq r$$

all keys in subtrees
are \leq key in root

\Rightarrow root stores minimum



children-version

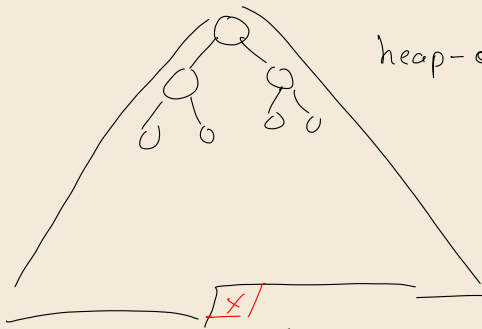


$$k_1 \geq r$$

$$k_2 \geq r$$

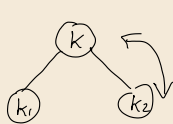
Insertion

insert new key x



heap-ordered

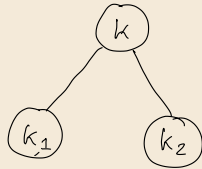
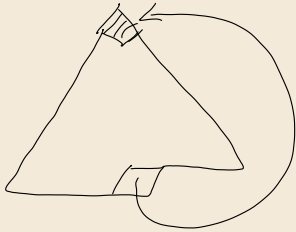
- ① store x in lowest level, next free position
- ② repair heap-order



$k_2 \leq k$ violation

→ swap them!
repeat up the tree

delete Min



- ① delete root (and return its key)
- ② move "last" element to root
↳ rightmost on lowest level
- ③ repair heap-order

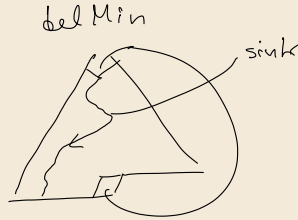
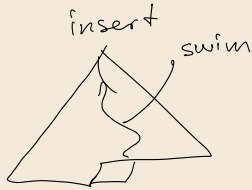
$k > k_1$ and/or $k > k_2$

(a) find $\min\{k_1, k_2\}$

(b) swap k with smaller child

continue along the changed
child links

Analysis



worst case in both cases: follow one path

$\Rightarrow \text{cost} = \# \text{ levels} = \text{height of tree}$

$\sim \lg n$

PQ = 2 ADT

MinPQ		MaxPQ
insert		
del Min		del Max

2 separate ADTs

min-oriented binary heaps

max-oriented binary heaps

2.4 Binary Search Trees

ADT : Symbol table

aka dictionaries

associative arrays

maps

$A['hello'] = 17$

partial

\approx mathematical functions

dynamic — change function over time

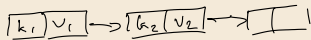
primitive implementations

① unsorted list

sequential search

easy add

hard find



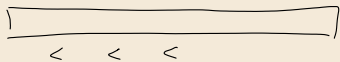
= checks every

$O(n)$ $n = \# \text{ keys}$

② sorted array binary search

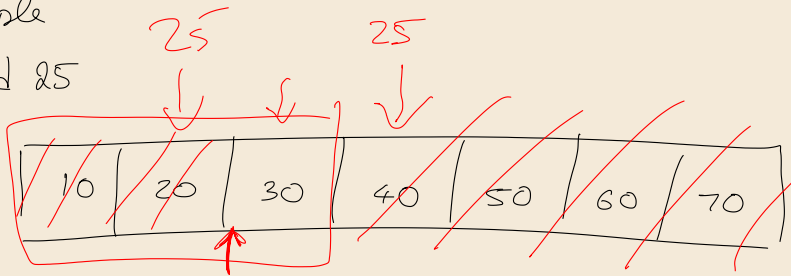
good find

hard to change



Example

find 25



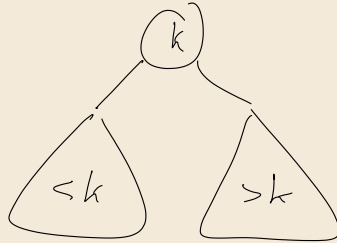
$\sim \lg n$

BSTs $\hat{=}$ dynamic sorted "array"

o binary tree = nodes have left / right child
both can be empty

(+)

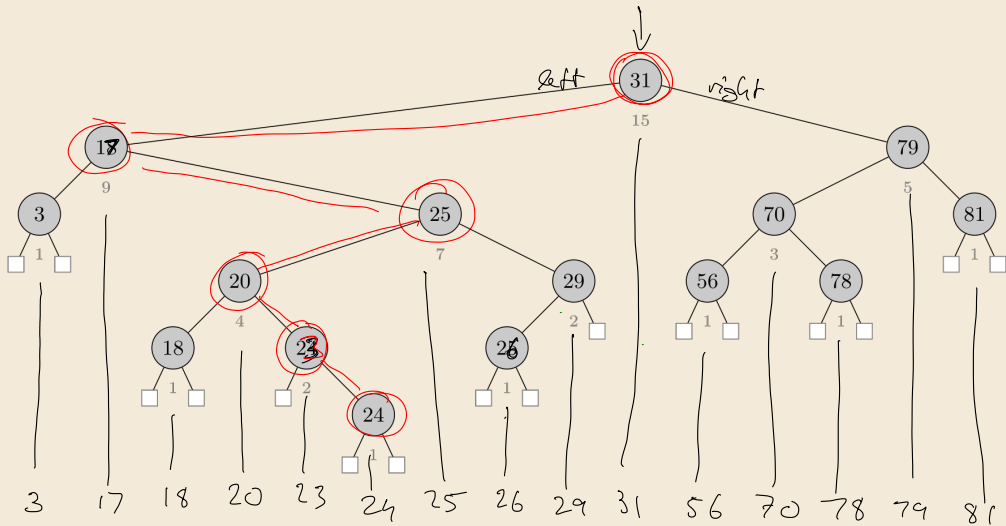
o search-tree property
(symmetric order)



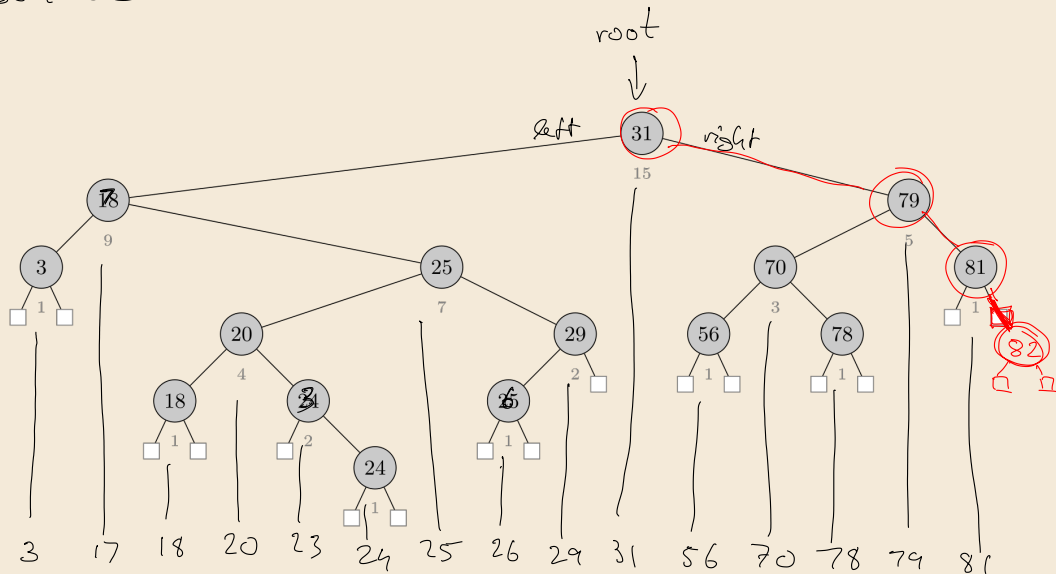
in Java : Node { left, right }
 BST { root }

search 24

root



insert 82



delete 3	easy	leaf
delete 29	easy	unary node
delete 79	hard	binary

- find inorder predecessor (left, right, right, ...)
- swap with 79
- delete 78

