

# 5

# Divide & Conquer

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# Learning Outcomes

## Unit 5: *Divide & Conquer*

1. Know the steps of the Divide & Conquer paradigm.
2. Be able to solve simple Divide & Conquer recurrences.
3. Be able to design and analyze new algorithms using the Divide & Conquer paradigm.
4. Know the performance characteristics of selection-by-rank algorithms.
5. Know the divide and conquer approaches for integer multiplication, matrix multiplication, finding majority elements, and the closest-pair-of-points problem.

# Outline

## 5 Divide & Conquer

- 5.1 Divide & Conquer Recurrences
- 5.2 Order Statistics
- 5.3 Linear-Time Selection
- 5.4 Fast Multiplication
- 5.5 Majority
- 5.6 Closest Pair of Points in the Plane

# Divide and conquer

**Divide and conquer** *idiom* (Latin: *divide et impera*)

to make a group of people disagree and fight with one another  
so that they will not join together against one

(Merriam-Webster Dictionary)

~~ in politics & algorithms, many independent, small problems are better than one big one!

## Divide-and-conquer algorithms:

1. Break problem into smaller, independent subproblems. (Divide!)
2. Recursively solve all subproblems. (Conquer!)
3. Assemble solution for original problem from solutions for subproblems.

## Examples:

- ▶ Mergesort
- ▶ Quicksort
- ▶ Binary search
- ▶ (arguably) Tower of Hanoi

## 5.1 Divide & Conquer Recurrences

# Back-of-the-envelope analysis

- ▶ before working out the details of a D&C idea,  
it is often useful to get a quick indication of the resulting performance
  - ▶ don't want to waste time on something that's not competitive in the end anyways!
- ▶ since D&C is naturally recursive, running time often not obvious  
instead: given by a recursive equation
- ▶ unfortunately, rigorous analysis often tricky

- ▶ Remember mergesort?

$$C(n) = \begin{cases} 0 & n \leq 1 \\ C(\lfloor n/2 \rfloor) + C(\lceil n/2 \rceil) + 2n & n \geq 2 \end{cases}$$

$$\rightsquigarrow C(n) = 2n\lfloor \lg(n) \rfloor + 2n - 4 \cdot 2^{\lfloor \lg(n) \rfloor} \quad \text{💡}$$
$$= \Theta(n \log n) \quad \text{Θ}$$

- ▶ the following method works for many typical cases to give the right **order of growth**

# The Master Method

- ▶ Assume a stereotypical D&C algorithm
  - ▶  $a$  recursive calls on      (for some constant  $a > 0$ )
  - ▶ subproblems of size  $n/b$       (for some constant  $b > 1$ )
  - ▶ with non-recursive “conquer” effort  $f(n)$       (for some function  $f : \mathbb{R} \rightarrow \mathbb{R}$ )
  - ▶ base case effort  $d$       (some constant  $d > 0$ )

↝ running time  $T(n)$  satisfies

$$T(n) = \begin{cases} a \cdot T\left(\frac{n}{b}\right) + f(n) & n > 1 \\ d & n \leq 1 \end{cases}$$

## Theorem 5.1 (Master Theorem)

With  $c := \log_b(a)$ , we have for the above recurrence:

- (a)  $T(n) = \Theta(n^c)$       if  $f(n) = O(n^{c-\varepsilon})$  for constant  $\varepsilon > 0$ .
- (b)  $T(n) = \Theta(n^c \log n)$  if  $f(n) = \Theta(n^c)$ .
- (c)  $T(n) = \Theta(f(n))$       if  $f(n) = \Omega(n^{c+\varepsilon})$  for constant  $\varepsilon > 0$  and  $f$  satisfies the regularity condition  $\exists n_0, \alpha < 1 \forall n \geq n_0 : a \cdot f\left(\frac{n}{b}\right) \leq \alpha f(n)$ .

# Master Theorem – Intuition & Proof Idea

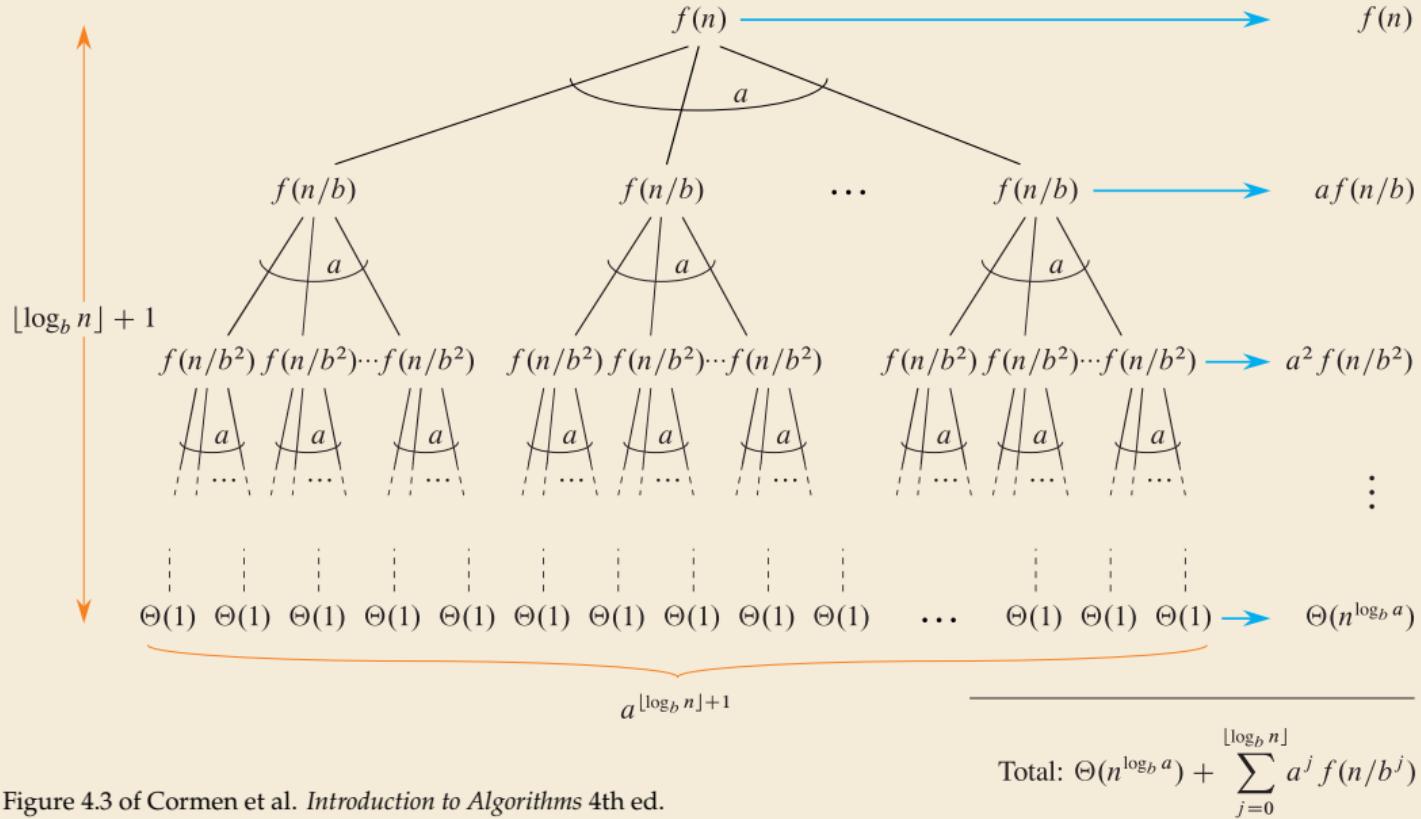


Figure 4.3 of Cormen et al. *Introduction to Algorithms* 4th ed.

# When it's fine to ignore floors and ceilings

## Lemma 5.2 (Polynomial-growth master method)

If the toll function  $f(n)$  satisfies the *polynomial-growth condition*, then the  $\Theta$ -class of the solution of a D&C recurrence remains the same when ignoring floors and ceilings on subproblem sizes.

The *polynomial-growth condition*

- $f : \mathbb{R}_{>0} \rightarrow \mathbb{R}$  satisfies the *polynomial-growth condition* if

$$\exists n_0 \ \forall C \geq 1 \ \exists D > 1 \quad \forall n \geq n_0 \ \forall c \in [1, C] \ : \ \frac{1}{D}f(n) \leq f(cn) \leq Df(n)$$

- intuitively: increasing  $n$  by up to a factor  $C$  (and anywhere in between!) changes the function value by at most a factor  $D = D(C)$   
(for sufficiently large  $n$ )
- examples:  $f(n) = \Theta(n^\alpha \log^\beta(n) \log \log^\gamma(n))$  for constants  $\alpha, \beta, \gamma$   
~~~  $\rightsquigarrow f$  satisfies the polynomial-growth condition

zero allowed  
↓

# A Rigorous and Stronger Meta Theorem

## Theorem 5.3 (Roura's Discrete Master Theorem)

Let  $T(n)$  be recursively defined as

$$T(n) = \begin{cases} b_n & 0 \leq n < n_0, \\ f(n) + \sum_{d=1}^D a_d \cdot T\left(\frac{n}{b_d} + r_{n,d}\right) & n \geq n_0, \end{cases}$$

where  $D \in \mathbb{N}$ ,  $a_d > 0$ ,  $b_d > 1$ , for  $d = 1, \dots, D$  are constants, functions  $r_{n,d}$  satisfy  $|r_{n,d}| = O(1)$  as  $n \rightarrow \infty$ , and function  $f(n)$  satisfies  $f(n) \sim B \cdot n^\alpha (\ln n)^\gamma$  for constants  $B > 0$ ,  $\alpha$ ,  $\gamma$ .

Set  $H = 1 - \sum_{d=1}^D a_d (1/b_d)^\alpha$ ; then we have:

- (a) If  $H < 0$ , then  $T(n) = O(n^{\tilde{\alpha}})$ , for  $\tilde{\alpha}$  the unique value of  $\alpha$  that would make  $H = 0$ .
- (b) If  $H = 0$  and  $\gamma > -1$ , then  $T(n) \sim f(n) \ln(n)/\tilde{H}$  with constant  $\tilde{H} = (\gamma + 1) \sum_{d=1}^D a_d b_d^{-\alpha} \ln(b_d)$ .
- (c) If  $H = 0$  and  $\gamma = -1$ , then  $T(n) \sim f(n) \ln(n) \ln(\ln(n))/\hat{H}$  with constant  $\hat{H} = \sum_{d=1}^D a_d b_d^{-\alpha} \ln(b_d)$ .
- (d) If  $H = 0$  and  $\gamma < -1$ , then  $T(n) = O(n^\alpha)$ .
- (e) If  $H > 0$ , then  $T(n) \sim f(n)/H$ .



## 5.2 Order Statistics

# Selection by Rank

- ▶ Standard data summary of numerical data: (Data scientists, listen up!)
    - ▶ mean, standard deviation
    - ▶ min/max (range)
    - ▶ histograms
    - ▶ median, quartiles, other quantiles (a.k.a. order statistics)
- easy to compute in  $\Theta(n)$  time
- ?  ? computable in  $\Theta(n)$  time?

General form of problem: **Selection by Rank**

- ▶ Given: array  $A[0..n]$  of numbers and number  $k \in [0..n]$ .
- ▶ Goal: find element that would be in position  $k$  if  $A$  was sorted ( $k$ th smallest element).  
but 0-based & counting dups
- ▶  $k = \lfloor n/2 \rfloor \rightsquigarrow$  median;  $k = \lfloor n/4 \rfloor \rightsquigarrow$  lower quartile  
 $k = 0 \rightsquigarrow$  minimum;  $k = n - \ell \rightsquigarrow$   $\ell$ th largest

# Quicksort

- ▶ Key observation: Finding the element of rank  $k$  seems hard.  
But computing the rank of a given element is easy!
  - ~~ Pick any element  $A[b]$  and find its rank  $j$ .
    - ▶  $j = k$ ? ~~ Lucky Duck! Return chosen element and stop
    - ▶  $j < k$ ? ~~ ... not done yet. But: The  $j + 1$  elements smaller than  $\leq A[b]$  can be excluded!
    - ▶  $j > k$ ? ~~ similarly exclude the  $n - j$  elements  $\geq A[b]$

- ▶ partition function from Quicksort:

- ▶ returns the rank of pivot
- ▶ separates elements into smaller/larger

- ~~ can use same building blocks

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```
1 procedure quickselect(A[l..r], k):
2     if r - l ≤ 1 then return A[l]
3     b := choosePivot(A[l..r])
4     j := partition(A[l..r], b)
5     if j == k
6         return A[j]
7     else if j < k
8         quickselect(A[j + 1..r], k)
9     else // j > k
10        quickselect(A[l..j], k)
```

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# Quickselect – Iterative Code

Recursion can be replaced by loop (*tail-recursion elimination*)

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```
1  procedure quickselect( $A[l..r]$ ,  $k$ ):
2      if  $r - l \leq 1$  then return  $A[l]$ 
3           $b := \text{choosePivot}(A[l..r])$ 
4           $j := \text{partition}(A[l..r], b)$ 
5          if  $j == k$ 
6              return  $A[j]$ 
7          else if  $j < k$ 
8              quickselect( $A[j + 1..r]$ ,  $k$ )
9          else //  $j > k$ 
10             quickselect( $A[l..j]$ ,  $k$ )
```

---

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```
1  procedure quickselectIterative( $A[0..n]$ ,  $k$ ):
2       $l := 0; r := n$ 
3      while  $r - l > 1$ 
4           $b := \text{choosePivot}(A[l..r])$ 
5           $j := \text{partition}(A[l..r], b)$ 
6          if  $j \geq k$  then  $r := j - 1$ 
7          if  $j \leq k$  then  $l := j + 1$ 
8      return  $A[k]$ 
```

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- ▶ implementations should usually prefer iterative version
- ▶ analysis more intuitive with recursive version

# Quickselect – Analysis

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```
1 procedure quickselect( $A[l..r]$ ,  $k$ ):  
2     if  $r - l \leq 1$  then return  $A[l]$   
3      $b := \text{choosePivot}(A[l..r])$   
4      $j := \text{partition}(A[l..r], b)$   
5     if  $j == k$   
6         return  $A[j]$   
7     else if  $j < k$   
8         quickselect( $A[j + 1..r]$ ,  $k$ )  
9     else //  $j > k$   
10        quickselect( $A[l..j]$ ,  $k$ )
```

---

- ▶ cost = #cmps
- ▶ costs depend on  $n$  and  $k$
- ▶ **worst case:**  $k = 0$ , but always  $j = n - 2$ 
  - ~~ each recursive call makes  $n$  one smaller at cost  $\Theta(n)$
  - ~~  $T(n, k) = \Theta(n^2)$  worst case cost

average case:

- ▶ let  $T(n, k)$  expected cost when we choose a pivot uniformly from  $A[0..n]$

~~ formulate recurrence for  $T(n, k)$       similar to BST/Quicksort recurrence

$$T(n, k) = n + \frac{1}{n} \sum_{r=0}^{n-1} [r = k] \cdot 0 + [k < r] \cdot T(r, k) + [k > r] \cdot T(n - r - 1, k - r - 1)$$

## Quickselect – Average Case Analysis

- $T(n, k) = n + \frac{1}{n} \sum_{r=0}^{n-1} [r = k] \cdot 0 + [k < r] \cdot T(r, k) + [k > r] \cdot T(n - r - 1, k - r - 1)$
- Set  $\hat{T}(n) = \max_{k \in [0..n)} T(n, k)$

$$\rightsquigarrow \hat{T}(n) \leq n + \frac{1}{n} \sum_{r=0}^{n-1} \max\{\hat{T}(r), \hat{T}(n - r - 1)\}$$

- analyze hypothetical, worse algorithm:  
if  $r \notin [\frac{1}{4}n, \frac{3}{4}n]$ , discard partition and repeat with new pivot!

$$\rightsquigarrow \hat{T}(n) \leq \tilde{T}(n) \text{ defined by } \tilde{T}(n) \leq n + \frac{1}{2}\tilde{T}(n) + \frac{1}{2}\tilde{T}(\frac{3}{4}n)$$

$$\rightsquigarrow \tilde{T}(n) \leq 2n + \tilde{T}(\frac{3}{4}n)$$

- Master Theorem Case 3:  $\tilde{T}(n) = \Theta(n)$

# Quickselect Discussion

  $\Theta(n^2)$  worst case (like Quicksort)

 expected cost  $\Theta(n)$  (best possible)

 no extra space needed

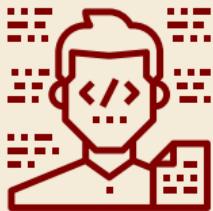
 adaptations possible to find several order statistics at once

 expected cost can be further improved by choosing pivot from a small sorted sample  
~~ asymptotically optimal randomized cost:  $n + \min\{k, n - k\}$  comparisons in expectation  
achieved asymptotically by the *Floyd-Rivest algorithm*

## 5.3 Linear-Time Selection

# *Interlude – A recurring conversation*

## Cast of Characters:



Hi! I'm a *computer science practitioner*.

I love algorithms for the sometimes miraculous **applications** they enable.

I care for things I can **implement** and **that actually work in practice**.



Hi! I'm a *theoretical computer science researcher*.

I find beauty in elegant and **definitive** answers to questions about complexity.

I care for **eternal truths** and mathematically proven facts;

**asymptotically optimal** is what counts! (Constant factors are secondary.)

# Quickselect Disagreements



For practical purposes, (randomized) Quickselect is perfect.

e.g. used in C++ STL `std::nth_element`



Yeah . . . maybe. But can we select by rank in  $O(n)$  deterministic **worst case** time?

# Better Pivots

It turns out, we can!

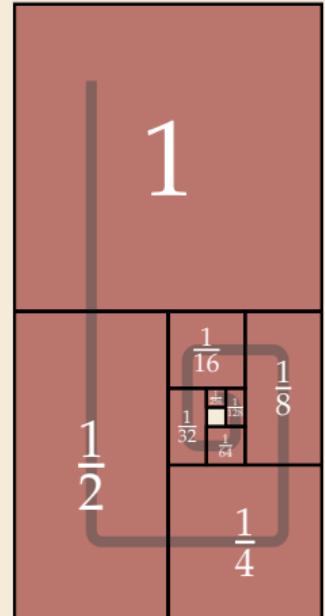
- ▶ All we need is better pivots!
  - ▶ If pivot was the exact median,  
we would at least halve #elements in each step
  - ▶ Then the total cost of all partitioning steps is  $\leq 2n = \Theta(n)$ .



But: finding medians is (basically) our original problem!



It totally suffices to find an element of rank  $\alpha n$  for  $\alpha \in (\varepsilon, 1 - \varepsilon)$  to get overall costs  $\Theta(n)$ !



# The Median-of-Medians Algorithm

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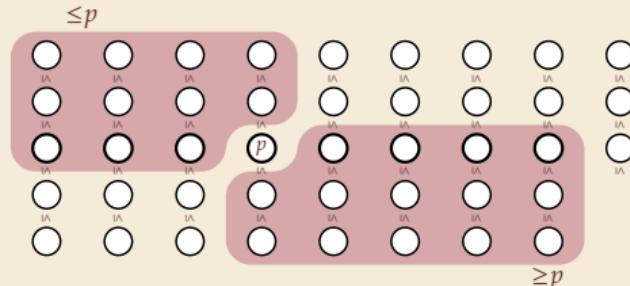
```
1 procedure choosePivotMoM( $A[l..r]$ ):  
2    $m := \lfloor n/5 \rfloor$   
3   for  $i := 0, \dots, m - 1$   
4     sort( $A[5i..5i + 4]$ )  
5     // collect median of 5  
6     Swap  $A[i]$  and  $A[5i + 2]$   
7   return quickselectMoM( $A[0..m]$ ,  $\lfloor \frac{m-1}{2} \rfloor$ )  
8  
9 procedure quickselectMoM( $A[l..r]$ ,  $k$ ):  
10  if  $r - l \leq 1$  then return  $A[l]$   
11   $b :=$  choosePivotMoM( $A[l..r]$ )  
12   $j :=$  partition( $A[l..r]$ ,  $b$ )  
13  if  $j == k$   
14    return  $A[j]$   
15  else if  $j < k$   
16    quickselectMoM( $A[j + 1..r]$ ,  $k$ )  
17  else //  $j > k$   
18    quickselectMoM( $A[l..j]$ ,  $k$ )
```

---

## Analysis:

- ▶ Note: 2 mutually recursive procedures  
~~ effectively 2 recursive calls!

1. recursive call inside choosePivotMoM  
on  $m \leq \frac{n}{5}$  elements
2. recursive call inside quickselectMoM



~~ partition excludes  $\sim 3 \cdot \frac{m}{2} \sim \frac{3}{10}n$  elem.

$$\rightsquigarrow C(n) \leq \Theta(n) + C\left(\frac{1}{5}n\right) + C\left(\frac{7}{10}n\right)$$

ansatz: overall cost linear

$$\begin{aligned} &\leq \Theta(n) + C\left(\frac{1}{5}n + \frac{7}{10}n\right) \\ &= \Theta(n) + C\left(\frac{9}{10}n\right) \rightsquigarrow C(n) = \Theta(n) \end{aligned}$$

## 5.4 Fast Multiplication

# Integer Multiplication

- ▶ What's the cost of computing  $x \cdot y$  for two integers  $x$  and  $y$ ?
  - ~~ depends on how big the numbers are!
    - ▶ If  $x$  and  $y$  have  $O(w)$  bits, multiplication takes  $O(1)$  time on word-RAM
    - ▶ otherwise, need a dedicated algorithm!

## Long multiplication (»Schulmethode«)

- ▶ Given  $x = \sum_{i=0}^{n-1} x_i 2^i$  and  $y = \sum_{i=0}^{n-1} y_i 2^i$ , want  $z = \sum_{i=0}^{2n-1} z_i 2^i$

---

```
1 for i := 0, ..., n - 1
2   c := 0
3   for j := 0, ..., n - 1
4     zi+j := zi+j + c + xi · yj
5     c := ⌊zi+j/2⌋
6     zi+j := zi+j mod 2
7   end for
8   zi+n := c
9 end for
```

---

- ▶  $\Theta(n^2)$  bit operations
- ▶ could work with base  $2^w$  instead of 2
  - ~~  $\Theta((n/w)^2)$  time
- ▶ here: count bit operations for simplicity can be generalized

**Example:**  
easier in binary!  
("shift and add")

1001010101 \* 101101

---

1001010101  
0000000000  
1001010101  
1001010101  
0000000000  
1001010101  

---

  
110100011110001

# Divide & Conquer Multiplication

- ▶ assume  $n$  is power of 2 (fill up with 0-bits otherwise)

- ▶ We can write

- ▶  $x = a_1 2^{n/2} + a_2$  and
- ▶  $y = b_1 2^{n/2} + b_2$
- ▶ for  $a_1, a_2, b_1, b_2$  integers with  $n/2$  bits

$$\rightsquigarrow x \cdot y = (a_1 2^{n/2} + a_2) \cdot (b_1 2^{n/2} + b_2) = \color{red}{a_1 b_1} 2^n + (\color{red}{a_1 b_2 + a_2 b_1}) 2^{n/2} + \color{red}{a_2 b_2}$$

- ▶ recursively compute 4 smaller products
- ▶ combine with shifts and additions ( $O(n)$  bit operations)

- ▶ ... but is this any good?

- ▶  $T(n) = 4 \cdot T(n/2) + \Theta(n)$

$\rightsquigarrow$  Master Theorem Case 1:  $T(n) = \Theta(n^2)$  ... just like the primary school method!?

- ▶ but Master Theorem gives us a hint: cost is dominated by the leaves
- $\rightsquigarrow$  try to do more work in conquer step!

# Karatsuba Multiplication

- ▶ how can we do “less divide and more conquer”?

Recall:  $x \cdot y = \textcolor{red}{a_1 b_1} 2^n + (\textcolor{red}{a_1 b_2 + a_2 b_1}) 2^{n/2} + \textcolor{red}{a_2 b_2}$

- 💡 Let’s do some algebra.

$$\begin{aligned} c &:= (a_1 + a_2) \cdot (b_1 + b_2) \\ &= a_1 b_1 + (a_1 b_2 + a_2 b_1) + a_2 b_2 \end{aligned}$$

$$\rightsquigarrow (\textcolor{red}{a_1 b_2 + a_2 b_1}) = c - a_1 b_1 - a_2 b_2$$

this can be computed with 3 recursive multiplications

$a_1 + a_2$  and  $b_1 + b_2$  still have roughly  $n/2$  bits

---

```
1 procedure karatsuba(x, y):
2     // Assume x and y are n = 2k bit integers
3     a1 := ⌊x/2n/2⌋; a2 := x mod 2n/2 // implemented by shifts
4     b1 := ⌊y/2n/2⌋; b2 := y mod 2n/2
5     c1 := karatsuba(a1, b1)
6     c2 := karatsuba(a2, b2)
7     c := karatsuba(a1 + a2, b1 + b2) - c1 - c2
8     return c12n + c2n/2 + c2 // shifts and additions
```

---

## Analysis:

- ▶ nonrecursive cost: only additions and shifts
  - ▶ all numbers  $\mathcal{O}(n)$  bits
- rightsquigarrow conquer cost  $f(n) = \Theta(n)$

## Recurrence:

- ▶  $T(n) = 3T(n/2) + \Theta(n)$
  - ▶ Master Theorem Case 1
- rightsquigarrow  $T(n) = \Theta(n^{\lg 3}) = \mathcal{O}(n^{1.585})$

much cheaper (for large  $n$ )!

# Integer Multiplication

- ▶ until 1960, integer multiplication was conjectured to take  $\Omega(n^2)$  bit operations
- ~~ Karatsuba's algorithm was a big breakthrough
  - ▶ which he discovered as a student!
- ▶ idea can be generalized to breaking numbers into  $k \geq 2$  parts (*Toom-Cook algorithm*)
- ▶ asymptotically *much* better algorithms are now known!
  - ▶ e. g., the *Schönhage-Strassen algorithm* with  $O(n \log n \log \log n)$  bit operations (!)
  - ▶ these are based on the *Fast Fourier Transform* (FFT) algorithm
    - ▶ numbers = polynomials evaluated at base (e. g.,  $z = 2$ )
    - ~~ multiplication of numbers = convolution of polynomials
    - ▶ FFT makes computation of this convolution cheap by computing the polynomial via interpolation
    - ▶ Schönhage-Strassen adds careful finite-field algebra to make computations efficient

# Matrix Multiplication

- The same trick can also be used for faster matrix multiplication

- Recall: For  $A, B \in \mathbb{R}^{n \times n}$  we define  $C = A \cdot B$  via  $c_{i,j} = \sum_{k=1}^n a_{i,k} b_{k,j}$

~~ Naive cost:  $n^2$  sums with  $n$  terms each ~~  $\Theta(n^3)$  arithmetic operations

- Can use D&C as follows (assuming  $n$  is a power of 2 again)

► Decompose  $A = \begin{pmatrix} A_{1,1} & A_{1,2} \\ A_{2,1} & A_{2,2} \end{pmatrix}, \quad B = \begin{pmatrix} B_{1,1} & B_{1,2} \\ B_{2,1} & B_{2,2} \end{pmatrix}, \quad C = \begin{pmatrix} C_{1,1} & C_{1,2} \\ C_{2,1} & C_{2,2} \end{pmatrix}$   
(cut in half hor. & vert.)

~~ We get  $C$  as  $C_{1,1} = A_{1,1} \cdot B_{1,1} + A_{1,2} \cdot B_{2,1}$

$C_{1,2} = A_{1,1} \cdot B_{1,2} + A_{1,2} \cdot B_{2,2}$  (note “.” and “+” operate on matrices here)

$C_{2,1} = A_{2,1} \cdot B_{1,1} + A_{2,2} \cdot B_{2,1}$

$C_{2,2} = A_{2,1} \cdot B_{1,2} + A_{2,2} \cdot B_{2,2}$

4 matrix sums with  $(\frac{n}{2})^2$  entries each

- 8 recursive matrix multiplications on two  $\frac{n}{2} \times \frac{n}{2}$  matrices +  $\Theta(n^2)$  summations

- # operations  $T(n) = 8T(n/2) + \Theta(n^2)$

~~ Master Theorem Case 1:  $T(n) = \Theta(n^3)$  😊

(but: still useful for better memory locality!)

# Strassen Algorithm for Matrix Multiplication

- ▶ Observation (again): Can do more conquer for less divide!
- ▶ We recursively compute the following 7 products:

$$M_1 := (A_{1,2} - A_{2,2}) \cdot (B_{2,1} + B_{2,2})$$

$$M_2 := (A_{1,1} + A_{2,2}) \cdot (B_{1,1} + B_{2,2})$$

$$M_3 := (A_{1,1} - A_{2,1}) \cdot (B_{1,1} + B_{1,2})$$

$$M_4 := (A_{1,1} + A_{1,2}) \cdot B_{2,2}$$

$$M_5 := A_{1,1} \cdot (B_{1,2} - B_{2,2})$$

$$M_6 := A_{2,2} \cdot (B_{2,1} - B_{1,1})$$

$$M_7 := (A_{2,1} + A_{2,2}) \cdot B_{1,1}$$

~~ We then obtain the 4 parts of  $C$  as

$$C_{1,1} = M_1 + M_2 - M_4 + M_6$$

$$C_{1,2} = M_4 + M_5$$

$$C_{2,1} = M_6 + M_7$$

$$C_{2,2} = M_2 - M_3 + M_5 - M_7$$

(Proof: left as exercise 😊)

## Analysis:

▶ **conquer step:** larger but still  $O(1)$  # matrix add/subtract

~~  $\Theta(n^2)$  operations for conquer

~~ total # arithmetic operations  
 $T(n) = 7T(n/2) + \Theta(n^2)$

~~ Master Theorem Case 1:  
 $T(n) = \Theta(n^{\lg 7}) = O(n^{2.808})$

# Open Problems

*Multiplication is extremely fundamental, but its computational complexity is an open problem and subject of active research!*

## Integer multiplication:

- ▶ conjectured to require  $\Omega(n \log n)$  bit operations (no proof known!)
- ▶ Harvey & van der Hoeven 2021:  $O(n \log n)$  algorithm possible!

## Matrix multiplication (MM):

- ▶ more relevant than it might seem since complexity identical to
  - ▶ computing inverse matrices, determinants
  - ▶ Gaussian elimination ( $\rightsquigarrow$  solving systems of linear equations)
  - ▶ recognition of context free languages
- $\rightsquigarrow$  best exponent even has standard notation:  
smallest  $\omega \in [2, 3]$  so that MM takes  $O(n^\omega)$  operations
- ▶ Big open question: Is  $\omega > 2$ ?
- ▶ best known bound:  $\omega \leq 2.371339$  (from 2024!)

| Timeline of matrix multiplication exponent |                |                                                         |
|--------------------------------------------|----------------|---------------------------------------------------------|
| Year                                       | Bound on omega | Authors                                                 |
| 1969                                       | 2.8074         | Strassen <sup>[1]</sup>                                 |
| 1978                                       | 2.796          | Pan <sup>[10]</sup>                                     |
| 1979                                       | 2.780          | Bini, Capovani <sup>[8]</sup> , Roman <sup>[11]</sup>   |
| 1981                                       | 2.522          | Schönhage <sup>[12]</sup>                               |
| 1981                                       | 2.517          | Roman <sup>[13]</sup>                                   |
| 1981                                       | 2.496          | Coppersmith, Winograd <sup>[14]</sup>                   |
| 1986                                       | 2.479          | Strassen <sup>[15]</sup>                                |
| 1990                                       | 2.3755         | Coppersmith, Winograd <sup>[16]</sup>                   |
| 2010                                       | 2.3737         | Stothers <sup>[17]</sup>                                |
| 2012                                       | 2.3729         | Williams <sup>[18][19]</sup>                            |
| 2014                                       | 2.3728639      | Le Gall <sup>[20]</sup>                                 |
| 2020                                       | 2.3728596      | Alman, Williams <sup>[21][22]</sup>                     |
| 2022                                       | 2.371866       | Duan, Wu, Zhou <sup>[23]</sup>                          |
| 2024                                       | 2.371552       | Williams, Xu, Xu, and Zhou <sup>[24]</sup>              |
| 2024                                       | 2.371339       | Alman, Duan, Williams, Xu, Xu, and Zhou <sup>[24]</sup> |

## 5.5 Majority

# Majority

- ▶ **Given:** Array  $A[0..n]$  of objects
- ▶ **Goal:** Check if there is an object  $x$  that occurs at  $> \frac{n}{2}$  positions in  $A$   
if so, return  $x$
- ▶ Naive solution: check each  $A[i]$  whether it is a majority  $\rightsquigarrow \Theta(n^2)$  time
- ▶ Assumption: all we can do to elements is ask “ $x = y?$ ”

# Majority – Divide & Conquer

Can be solved faster using a simple Divide & Conquer approach:

- ▶ If  $A$  has a majority, that element must also be a majority of at least one half of  $A$ .
- ~~> Can find majority (if it exists) of left half and right half recursively
- ~~> Check these  $\leq 2$  candidates.
- ▶ Costs similar to mergesort:  $\Theta(n \log n)$

---

```
1 procedure majority( $A[0..n]$ ):  
2     if  $n == 1$  then return  $A[0]$  end if  
3      $k := \lfloor \frac{n}{2} \rfloor$   
4      $M_\ell :=$  majority( $A[0..k]$ )  
5      $M_r :=$  majority( $A[k..n]$ )  
6     if  $M_\ell == M_r$  then return  $M_\ell$  end if  
7      $m_\ell := 0$ ;  $m_r := 0$   
8     for  $i := 0, \dots, n - 1$   
9         if  $A[i] == M_\ell$  then  $m_\ell = m_\ell + 1$  end if  
10        if  $A[i] == M_r$  then  $m_r = m_r + 1$  end if  
11    end for  
12    if  $m_\ell \geq k + 1$   
13        return  $M_\ell$   
14    else if  $m_r \geq k + 1$   
15        return  $M_r$   
16    else  
17        return NO_MAJORITY_ELEMENT
```

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# Majority – Linear Time

We can actually do much better!

---

```
1 def MJRTY( $A[0..n]$ )
2      $c := 0$ 
3     for  $i := 1, \dots, n - 1$ 
4         if  $c == 0$ 
5              $x := A[i]; c := 1$ 
6         else
7             if  $A[i] == x$  then  $c := c + 1$  else  $c := c - 1$ 
8     return  $x$ 
```

---



- ▶  $\text{MJRTY}(A[0..n])$  returns *candidate* majority element
- ▶ either that candidate is the majority element or none exists(!)

👍 Clearly  $\Theta(n)$  time

## 5.6 Closest Pair of Points in the Plane

# Closest Pair of Points in the Plane

- ▶ Given: Array  $P[0..n]$  of points in the plane ( $\mathbb{R}^2$ )  
each has  $x$  and  $y$  coordinates:  $P[i].x$  and  $P[i].y$
- ▶ Goal: Find pair  $P[i], P[j]$  that is closest in (Euclidean) distance  
i.e.,  $i$  and  $j$  that minimize  $d_2(P[i], P[j]) = \sqrt{(P[i].x - P[j].x)^2 + (P[i].y - P[j].y)^2}$
- ▶ Naive solution: compute distance of each pair  $\rightsquigarrow \Theta(n^2)$  time
  - ▶ cost here = # arithmetic operations  $\rightsquigarrow O(1)$  cost to compute  $d_2$
  - ▶ ignore numerical accuracy      Note: Since  $\sqrt{\cdot}$  monotonic, suffices to minimize  $d_2^2(P[i], P[j])$ 

$\rightsquigarrow$  formally work on the *real RAM*
    - ▶ like word-RAM, but words contain **exact** real numbers
    - ▶ support arithmetic operations and comparisons,  
but **not** bitwise operations or  $\lfloor \cdot \rfloor$  and  $\lceil \cdot \rceil$
- ▶ We focus on computing  $\delta = \min d_2(P[i], P[j])$   
remembering actual pair of points is an easy modification

## Closest Pair – Divide & Conquer

1. Partition points around median  $x$ -coordinate  $m.x$
2. Recurse on points left resp. right of  $m.x$
3. Consider 3 cases of where  $\delta$  can be achieved:
  - a) closest pair left of  $m.x$
  - b) closest pair right of  $m.x$
  - c) closest pair straddling  $m.x$

## Closest Pair – Checking Straddle Pairs

- ▶ number of straddle pairs is  $\sim \frac{n}{2} \times \frac{n}{2}$   $\rightsquigarrow$  just as slow as brute force!
  - ▶ **Insight:** Can exclude any points far from dividing line! (cannot be close)
    - ▶ precisely: let  $\delta$  be closest pair distance from (a) and (b)
    - ▶ only points with  $x$ -coordinate in  $m.x \pm \delta$  relevant
    - ▶ worst case: no single point excluded!
  - ▶ **Insight 2:** Also points of vertical distance  $> \delta$  cannot be closest!
    - ▶ consider points in  $m.x \pm \delta$  strip in order sorted by  $y$ -coordinate
    - ▶ use vertical “sweep lines” and compare only all pairs in  $2\delta \times \delta$  rectangle.
    - ▶ ... how many points can be in one rectangle?
    - ▶ since in left and right subproblem closest dist  $\geq \delta$ : at most 8.
- $\rightsquigarrow$  After sorting by  $y$ -coordinate, only do a linear number of distance checks!

# Closest Pair – Divide and Conquer is not all

- ~~ Total running time  $T(n) = 2T(\frac{n}{2}) + \Theta(n \log n)$
- ▶ Recursion tree method:  $T(n) = O(n \log^2(n))$   
Roura's Master Theorem shows  $T(n) = \Theta(n \log^2 n)$
- ▶ Can we do better?
- ▶ non-recursive cost is dominated by sorting
  - ▶ linear number of straddling pairs of distances to consider
  - ▶ median by  $x$ -coordinate can be found in linear time (median-of-medians algorithm)!
- ▶ **Insight 3:** We sort points **once** at beginning and use stable partitioning.
  - ~~ Remain sorted for recursive subproblems ~~ no need to sort in conquer step!
  - ▶ By also sorting (a copy/pointers) by  $x$ -coordinate initially, we can avoid selection algorithm!

# Closest Pair – Code

```
1 procedure closestDist( $P[0..N]$ ,  $byX[0..n]$ ,  $byY[0..n]$ ):  
2     //  $P$  contains all  $N \geq n$  points  
3     //  $P[byX[0]].x \leq P[byX[1]].x \leq \dots \leq P[byX[n]].x$   
4     //  $P[byY[0]].y \leq P[byY[1]].y \leq \dots \leq P[byY[n]].y$   
5     if  $n == 2$  return  $d_2(P[byX[0]], P[byX[1]])$   
6     if  $n == 3$  return min{ $d_2(P[byX[0]], P[byX[1]])$ ,  
7                            $d_2(P[byX[1]], P[byX[2]])$ ,  
8                            $d_2(P[byX[0]], P[byX[2]])$ }  
9     // 1. Split by median  $x$  and recurse  
10     $k := \lfloor n/2 \rfloor$ ;  
11     $m := P[byX[k]]$   
12     $byX_L := byX[0..k]$ ;  $byX_R := byX[k..n]$   
13     $byY_L, byY_R :=$  new empty array list  
14    for  $i := 0, \dots, n - 1$   
15        if  $P[byY[i]].x \leq m.x$  // breaking ties as in  $byX$   
16             $byY_L.append(byY[i])$   
17        else  
18             $byY_R.append(byY[i])$   
19        end if  
20    end for  
21    // ...
```

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```
22    // ... closestDist continued  
23     $\delta_L := closestDist(P, byX_L, byY_L)$   
24     $\delta_R := closestDist(P, byX_R, byY_R)$   
25     $\delta := \min\{\delta_L, \delta_R\}$   
26    // 2. Check straddling pairs  
27    // Find points close to dividing line  
28    for  $i := 0, \dots, n - 1$   
29        if  $|P[byY[i]].x - m.x| \leq \delta$   
30             $C.append(byY[i])$   
31        end if  
32    end for  
33    // Distance  $\leq \delta$  implies within 8 positions in  $C$   
34    for  $i := 0, \dots, C.size()$   
35        for  $j := i + 1, \dots, i + 7$   
36             $\delta := \min\{\delta, d_2(P[C[i]], P[C[j]])\}$   
37        end for  
38    end for  
39    return  $\delta$   
40  
41 procedure  $d_2(P, Q)$ :  
42     return  $\sqrt{(P.x - Q.x)^2 + (P.y - Q.y)^2}$ 
```

---

## Closest Pair – Analysis

- ▶ initial sorting of the points:  $\Theta(n \log n)$
- ▶ time for closestDist fulfills recurrence  $T(n) = 2T(\frac{n}{2}) + \Theta(n)$ 
  - ~~> Master Theorem Case 2:  $T(n) = \Theta(n \log n)$
  - ~~> Total time  $\Theta(n \log n)$