

12

Dynamic Programming

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Learning Outcomes

Unit 12: Dynamic Programming

1. Be able to apply the DP paradigm to solve new problems.

Outline

12 Dynamic Programming

- 12.1 Elements of Dynamic Programming
- 12.2 DP & Matrix Chain Multiplication
- 12.3 Greedy as Special Case of DP
- 12.4 The Bellman-Ford Algorithm
- 12.5 Making Change in pre 1971 UK
- 12.6 Optimal Merge Trees & Optimal BSTs
- 12.7 Edit Distance

12.1 Elements of Dynamic Programming

Introduction

applicable to many problems

- ► *Dynamic Programming (DP)* is a powerful algorithm **design pattern** for exact solutions to **optimization** problems
- Some commonalities with Greedy Algorithms, but with an element of brute force added in

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DP = "careful brute force" (Erik Demaine)
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- often yields polynomial time, but usually not linear time algorithms
- ▶ for many problems the *only* way we know to build efficient algorithms

Naming fun: The term "dynamic programming", due to Richard Bellman from around 1953, does not refer to computer programming; rather to a program (= plan, schedule) changing with time. It seems to have been at least partly marketing babble devoid of technical meaning . . .

Plan of the Unit

- **1.** Abstract steps of DP (briefly)
- **2.** Details on a concrete example (*matrix chain multiplication*)
- **3.** More examples!

The 6 Steps of Dynamic Programming

- 1. Define **subproblems** (and relate to original problem)
- **2. Guess** (part of solution) → local brute force
- **3.** Set up **DP recurrence** (for quality of solution)
- **4.** Recursive implementation with **Memoization**
- **5.** Bottom-up **table filling** (topological sort of subproblem dependency graph)
- **6. Backtracing** to reconstruct optimal solution
- ► Steps 1–3 require insight / creativity / intuition; Steps 4–6 are mostly automatic / same each time
- → Correctness proof usually at level of DP recurrence
- $\stackrel{\frown}{\Box}$ running time too! worst case time = #subproblems \cdot time to find single best guess

When does DP (not) help?

- No Silver Bullet
 DP is the most widely applicable design technique, but can't always be applied
- **1.** Vitally important for DP to be correct:

Bellman's Optimality Criterion

For a *correctly guessed* fixed part of the solution, any optimal solution to the corresponding subproblems must yield an *optimal solution* to the overall problem (once combined).

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at most polynomial in n

 Also, the total number of different subproblems should be "small" (DP potentially still works correctly otherwise, but won't be efficient.)

12.2 DP & Matrix Chain Multiplication

The Matrix-Chain Multiplication Problem

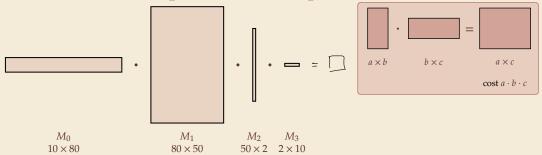
Consider the following exemplary problem

- ▶ We have a product $M_0 \cdot M_1 \cdot \cdots \cdot M_{n-1}$ of n matrices to compute
- ▶ Since (matrix) multiplication is associative, it can be evaluated in different orders.
- ▶ For non-square matrices of different sizes, different order can change costs dramatically
 - ► Assume elementary matrix multiplication algorithm:
 - \rightarrow Multiplying $a \times b$ -matrix with $b \times c$ matrix costs $a \cdot b \cdot c$ integer multiplications
- ▶ Given: Row and column counts e[0..n) and w[0..n) with r[i+1] = c[i] for $i \in [0..n-1)$ (corresponding to matrices M_0, \ldots, M_{n-1} with $M_i \in \mathbb{R}^{r[i] \times c[i]}$)
- ▶ Goal: parenthesization of the product chain with minimal cost

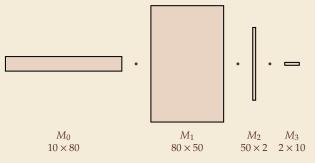
really a binary tree with
$$n$$
 leaves!

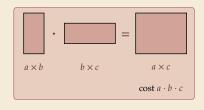
$$\left(M_{o}\left(M_{c},M_{z}\right)\right)$$

Matrix-Chain Multiplication – Example



Matrix-Chain Multiplication – Example





Parenthesization	Cost (integer multiplications)		
$M_0 \cdot (M_1 \cdot (M_2 \cdot M_3))$	1000 + 40 000 + 8000	=	49 000
$M_0 \cdot ((M_1 \cdot M_2) \cdot M_3)$	8000 + 1600 + 8000	=	17600
$(M_0 \cdot M_1) \cdot (M_2 \cdot M_3)$	40000 + 1000 + 5000	=	46 000
$(M_0 \cdot (M_1 \cdot M_2)) \cdot M_3$	8000 + 1600 + 200 \	=	9800
$((M_0 \cdot M_1) \cdot M_2) \cdot M_3$	40 000 + 1000 + 200	=	41 200

first or last operation

Greedy fails both ways!