

3

Efficient Sorting

18 February 2020

Sebastian Wild

Outline

3 Efficient Sorting

- 3.1 Mergesort
- 3.2 Quicksort
- 3.3 Comparison-Based Lower Bound
- 3.4 Integer Sorting
- 3.5 Parallel computation
- 3.6 Parallel primitives
- 3.7 Parallel sorting

Why study sorting?

- ▶ fundamental problem of computer science that is still not solved
- ▶ building brick of many more advanced algorithms
 - ▶ for preprocessing
 - ▶ as subroutine
- ▶ playground of manageable complexity to practice algorithmic techniques

Algorithm with optimal #comparisons in worst case?



Here:

- ▶ “classic” fast sorting method
- ▶ parallel sorting

Part I

The Basics

Rules of the game

► **Given:**

- ▶ array $A[0..n - 1]$ of n objects
- ▶ a total order relation \leq among $A[0], \dots, A[n - 1]$
(a comparison function)

► **Goal:** rearrange (=permute) elements within A ,
so that A is *sorted*, i. e., $A[0] \leq A[1] \leq \dots \leq A[n - 1]$

- for now: A stored in main memory (*internal sorting*)
single processor (*sequential sorting*)



3.1 Mergesort

Clicker Question



How does mergesort work?

- A** Split elements around median, then recurse on small / large elements.
- B** Recurse on left / right half, then combine sorted halves.
- C** Grow sorted part on left, repeatedly add next element to sorted range.
- D** Repeatedly choose 2 elements and swap them if they are out of order.
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Clicker Question



How does mergesort work?

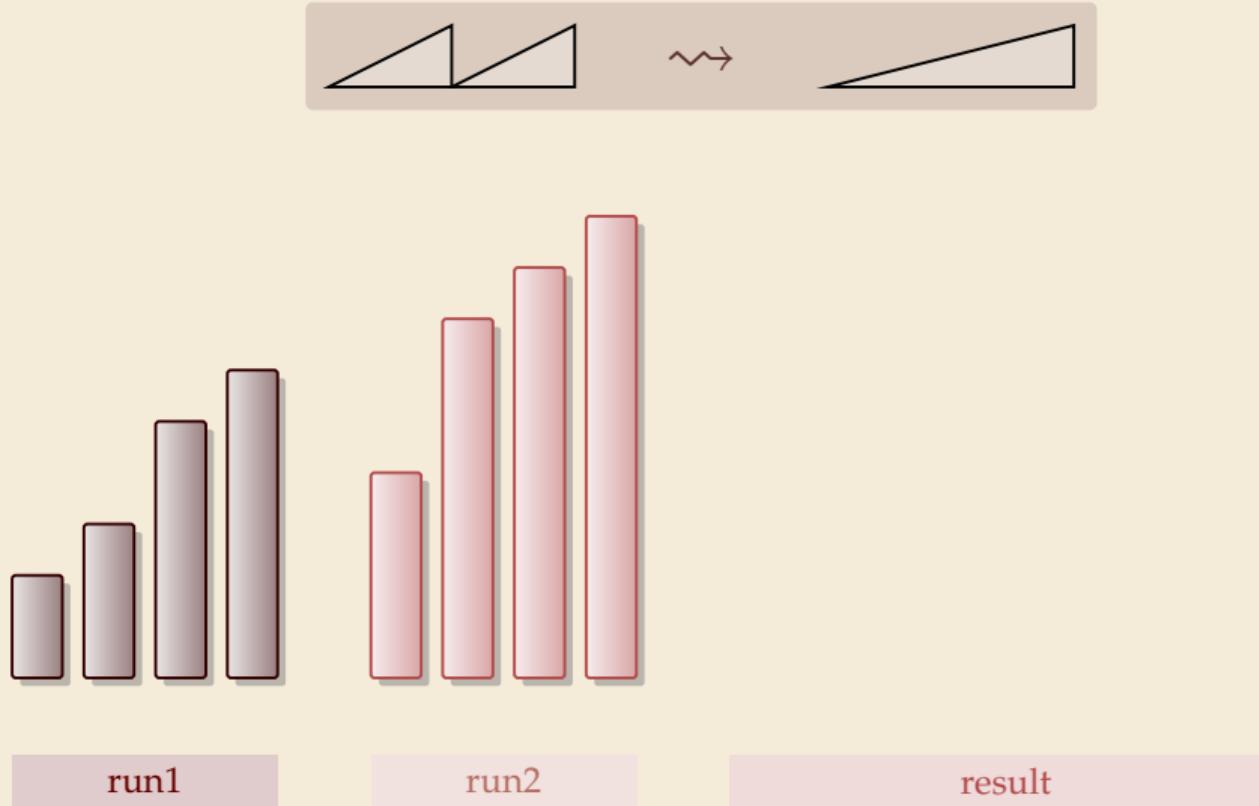
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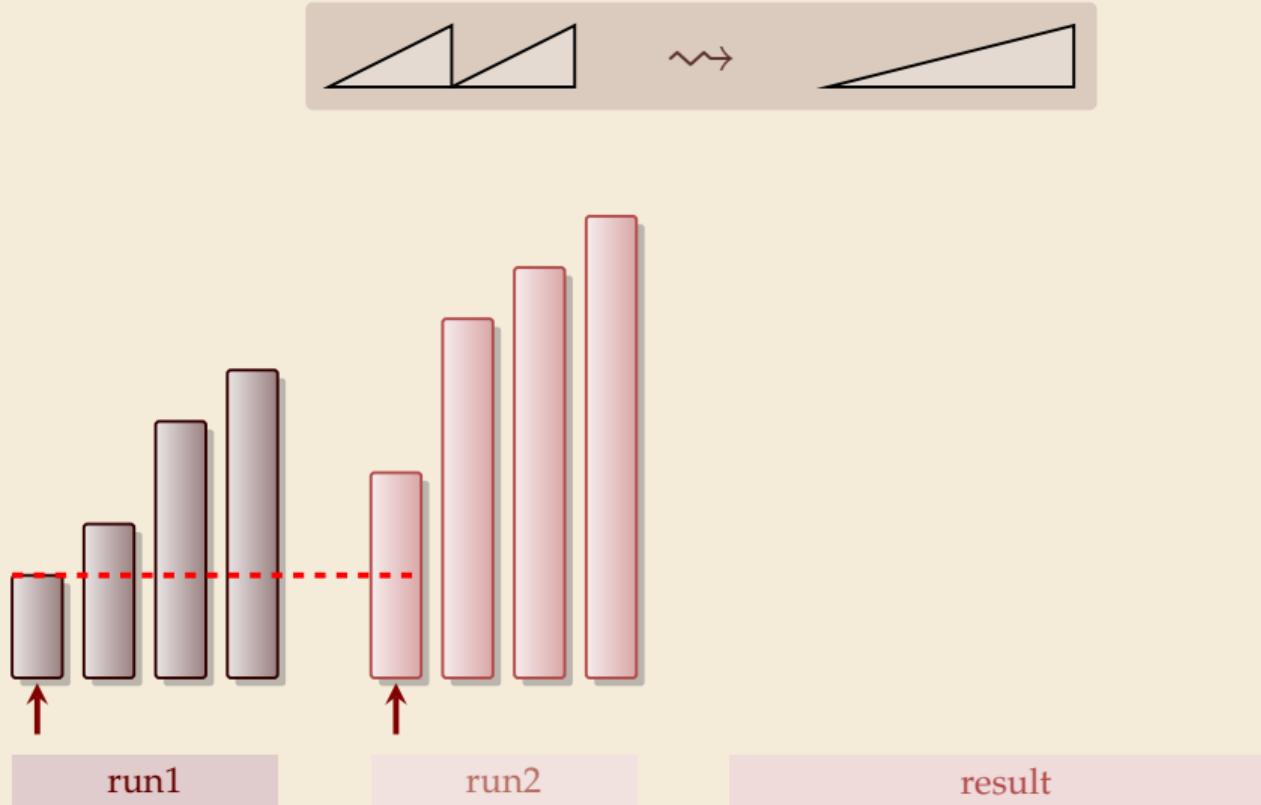
Merging sorted lists



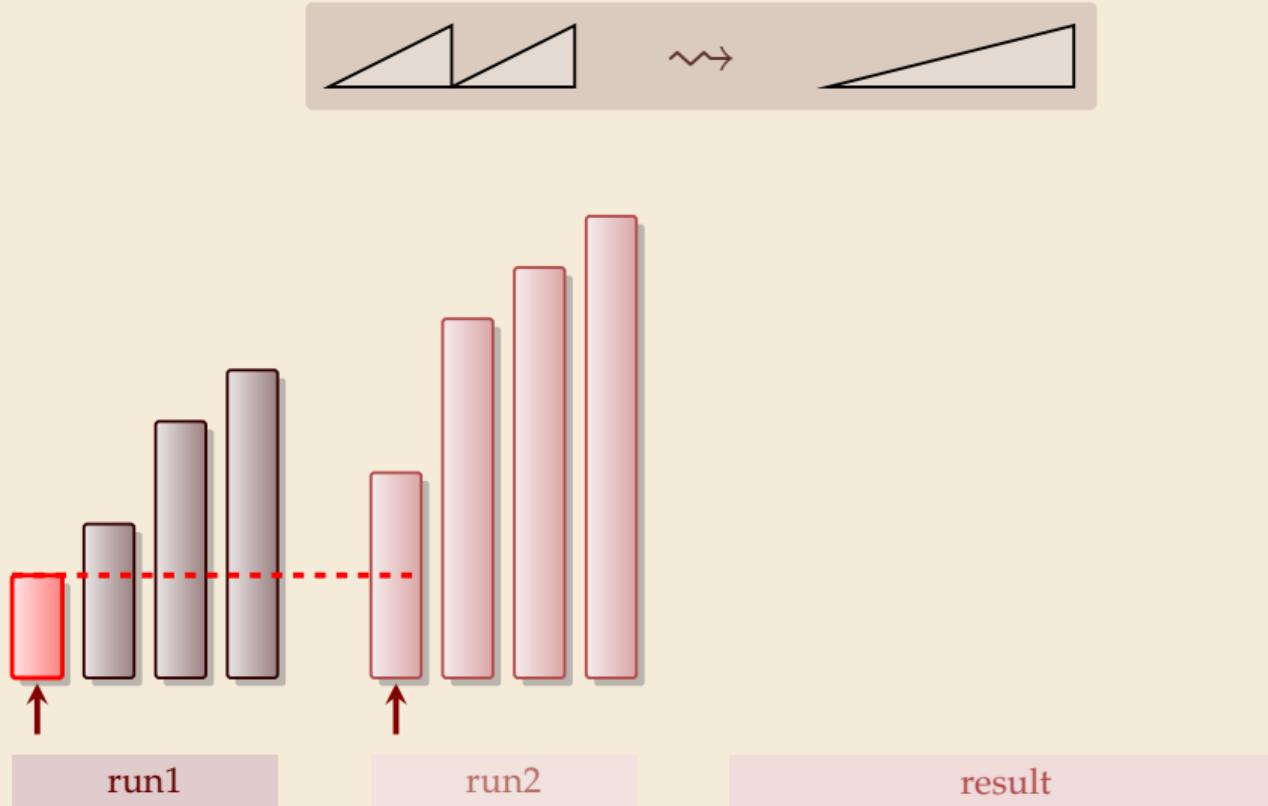
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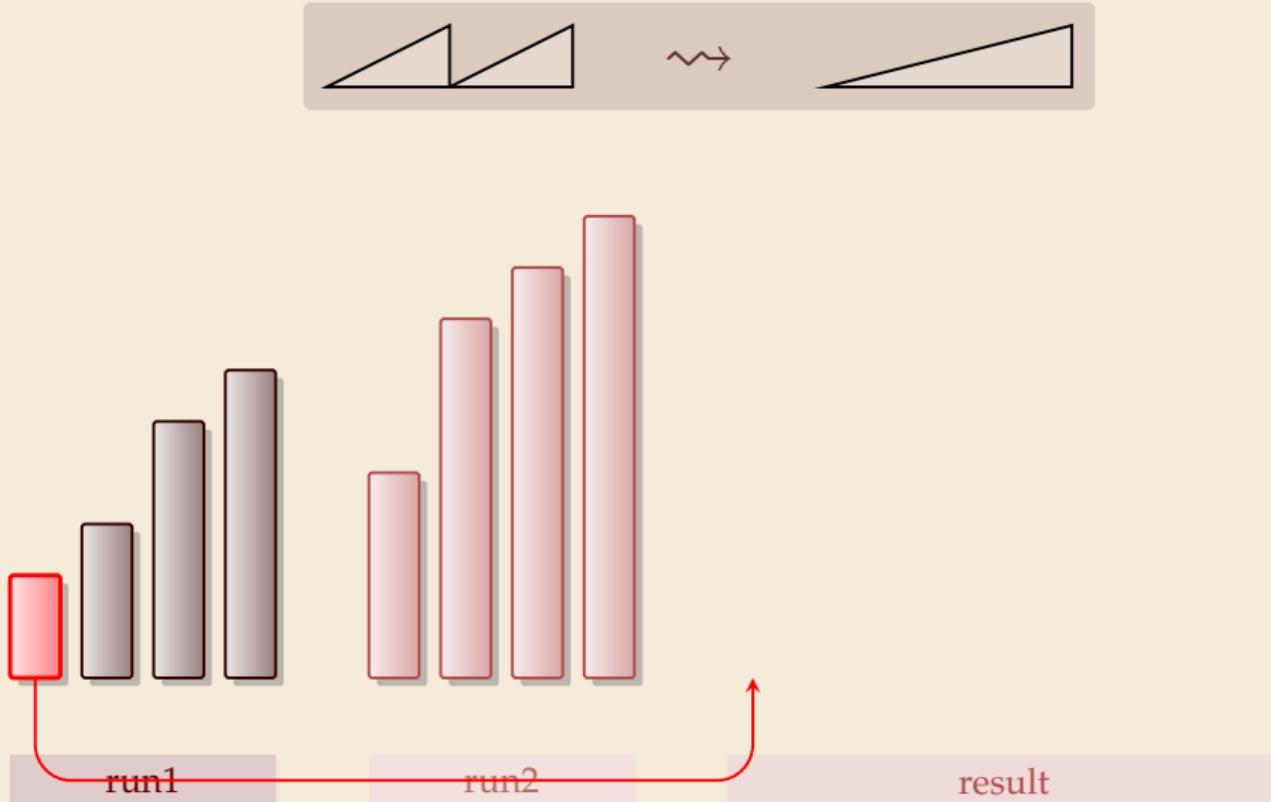
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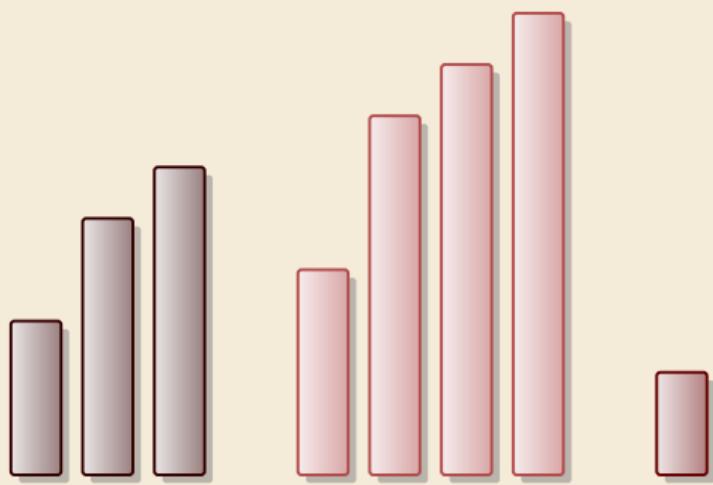
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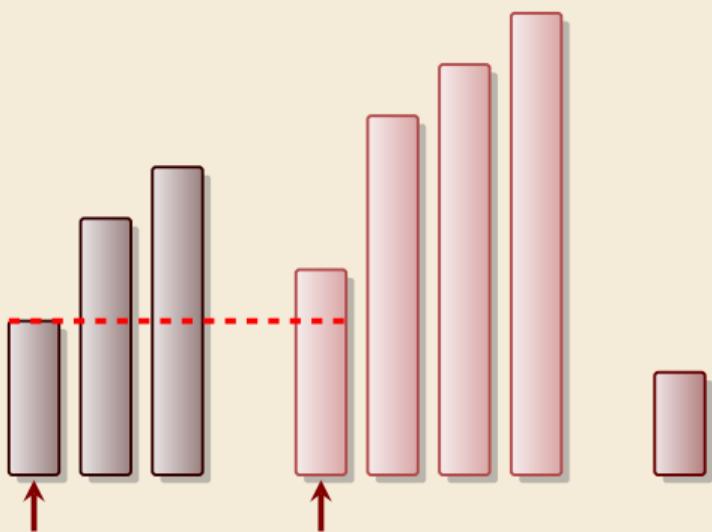


run1

run2

result

Merging sorted lists

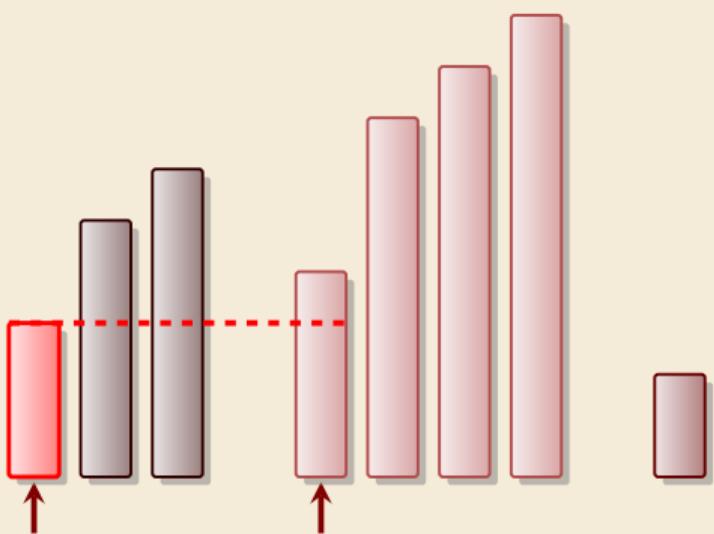


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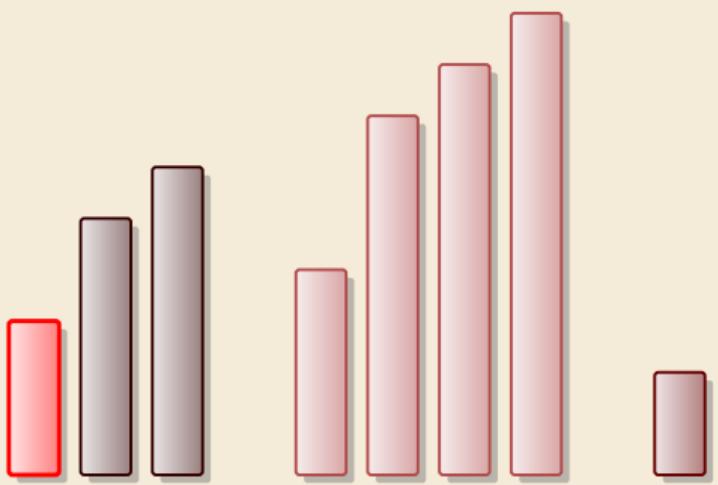


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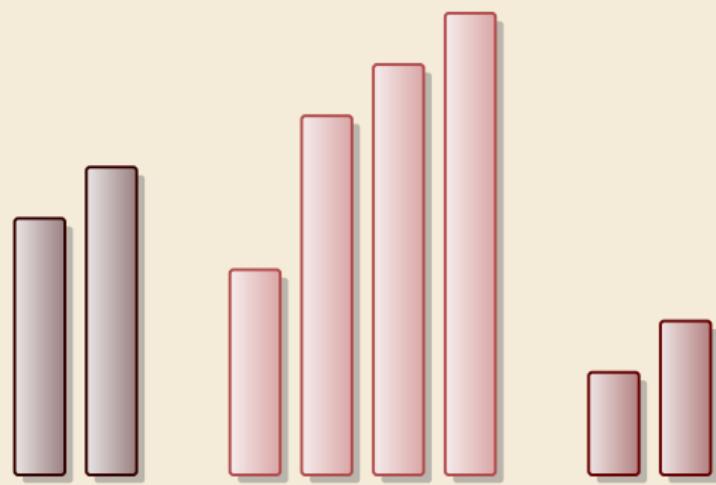
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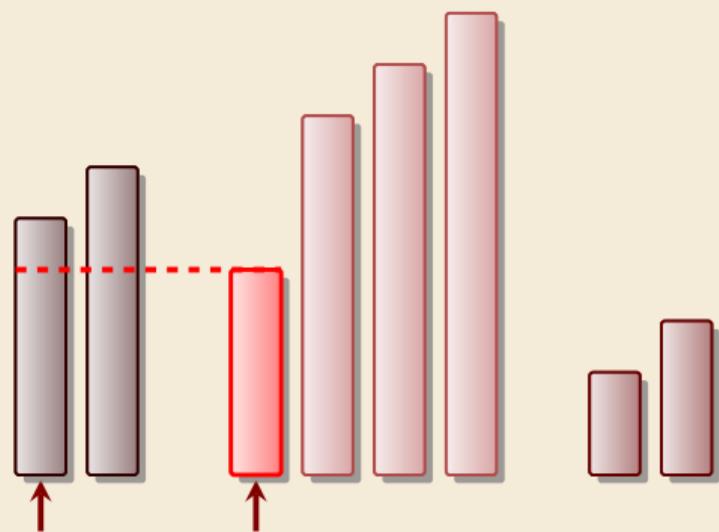


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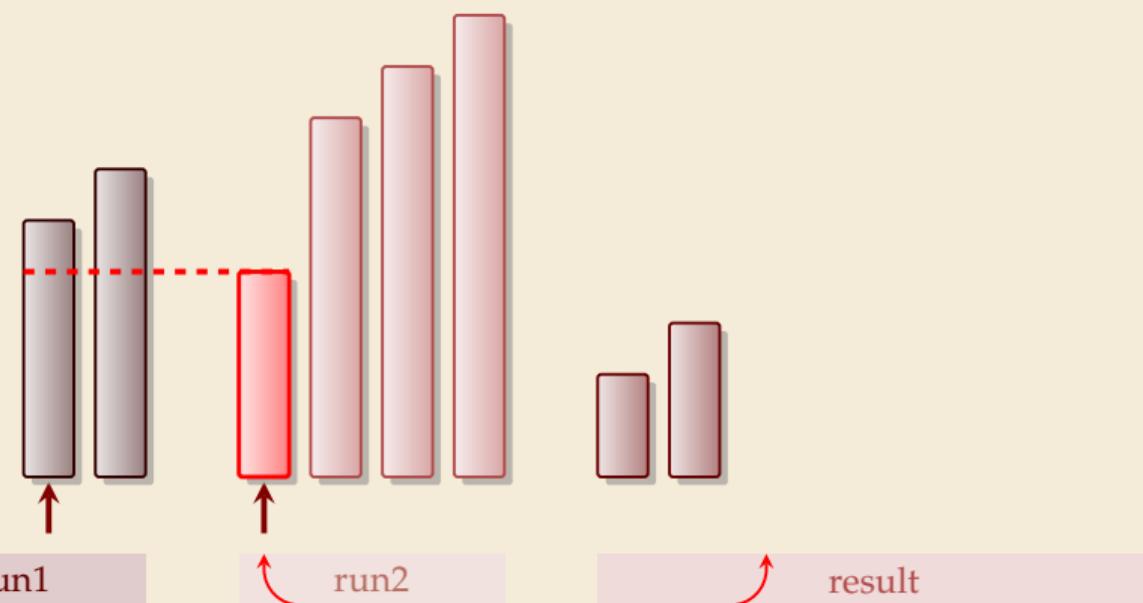


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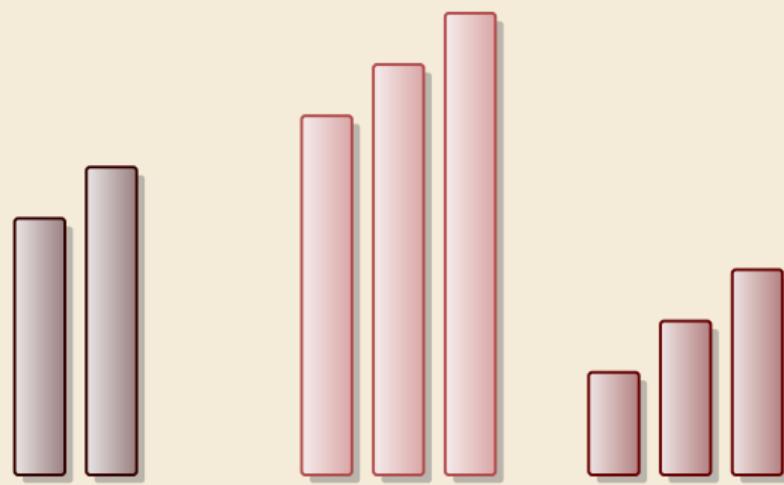
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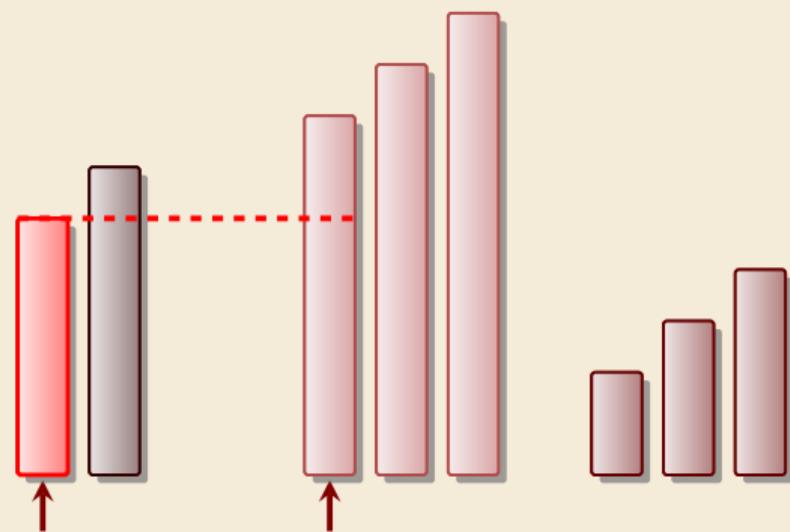


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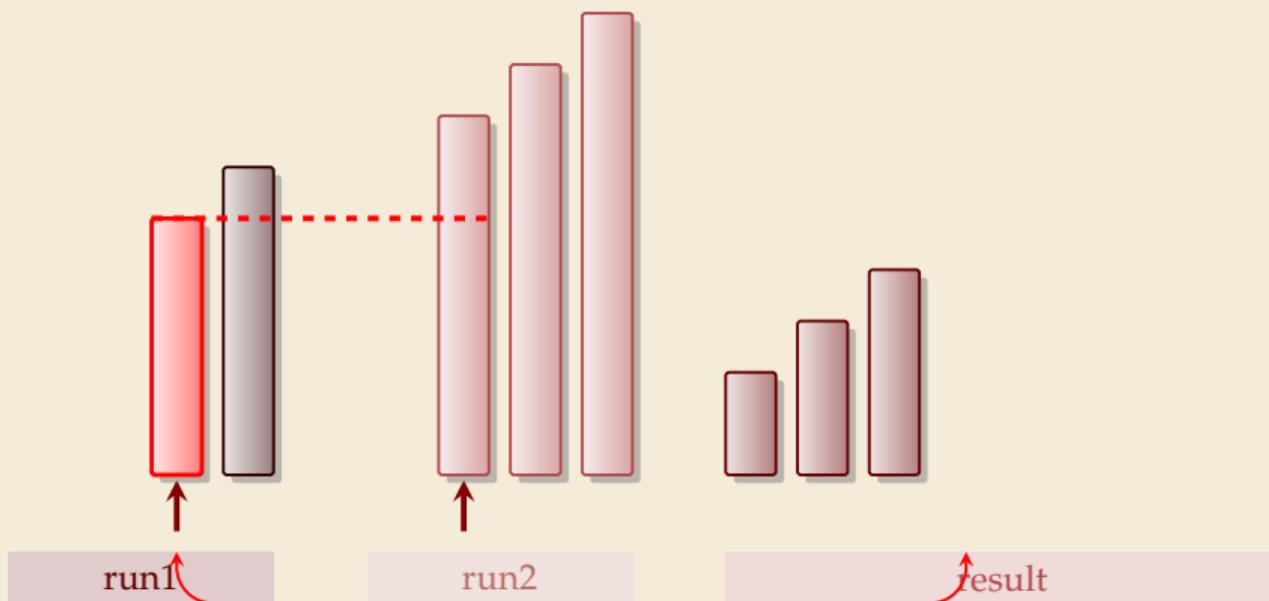


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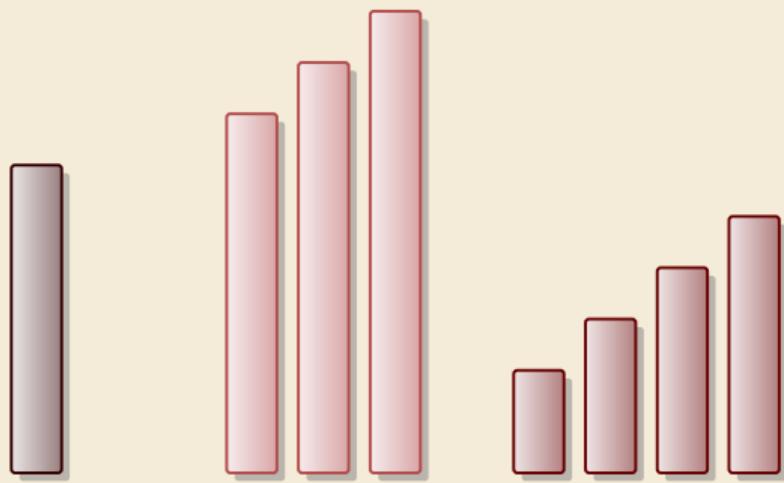
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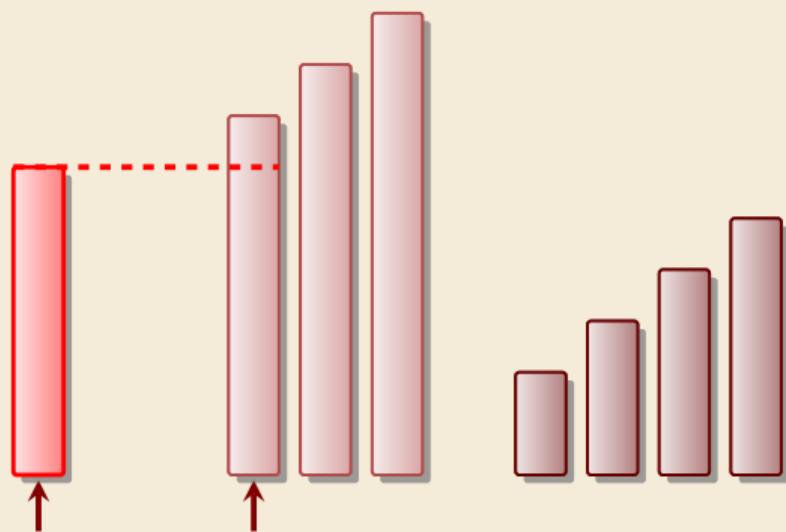


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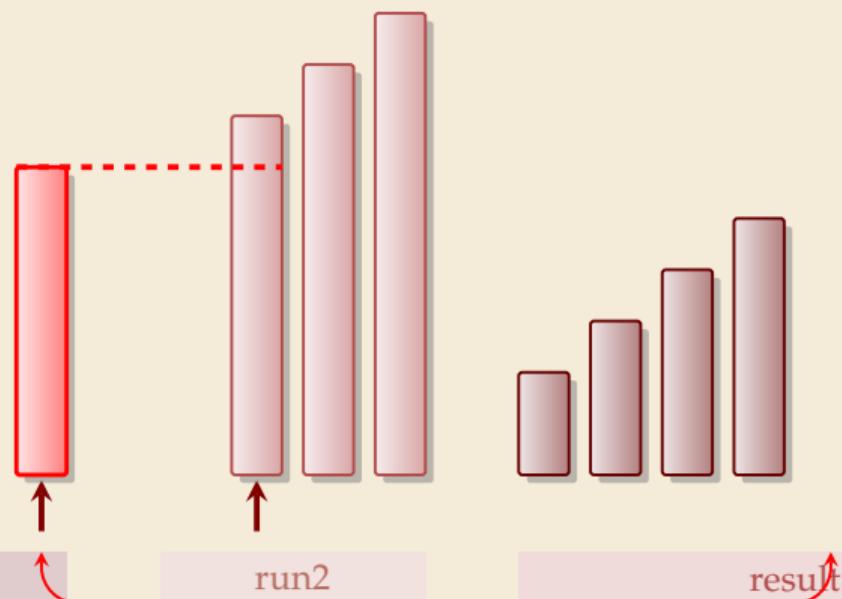


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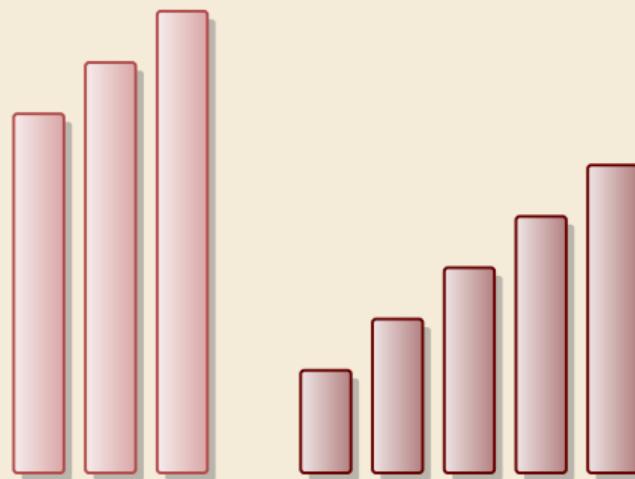
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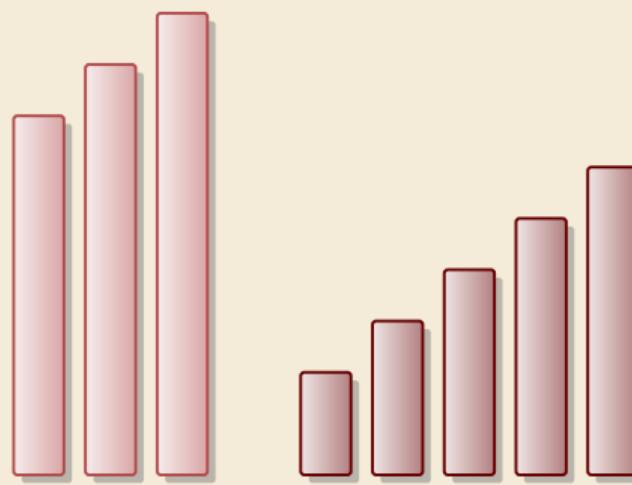


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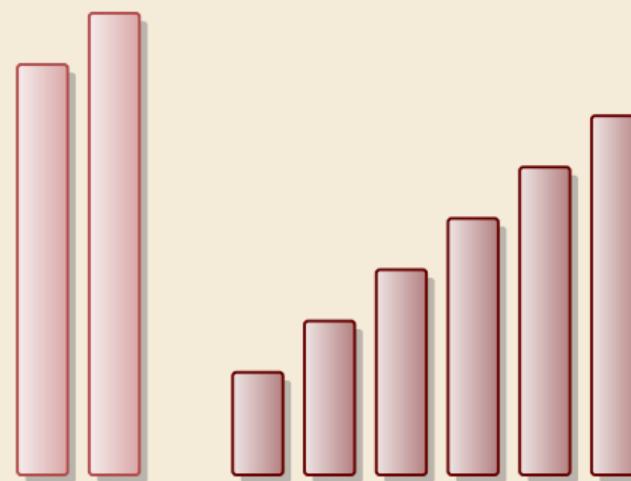
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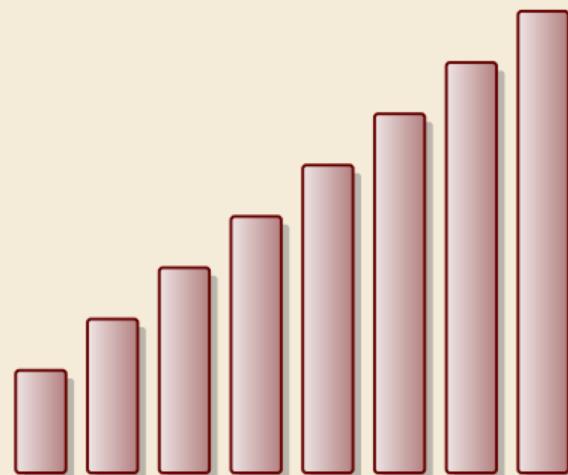
Merging sorted lists



Merging sorted lists



Merging sorted lists



Mergesort

```
1 procedure mergesort(A[l..r])
2     n := r - l + 1
3     if n ≥ 1 return
4         m := l + ⌊ $\frac{n}{2}$ ⌋
5         mergesort(A[l..m - 1])
6         mergesort(A[m..r])
7         merge(A[l..m - 1], A[m..r], buf)
8         copy buf to A[l..r]
```

- ▶ recursive procedure; *divide & conquer*
- ▶ merging needs
 - ▶ temporary storage for result *buf*
of same size as merged runs
 - ▶ to read and write each element twice
(once for merging, once for copying back)

Mergesort

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- ▶ recursive procedure; *divide & conquer*
 - ▶ merging needs
 - ▶ temporary storage for result of same size as merged runs
 - ▶ to read and write each element twice (once for merging, once for copying back)
- $2n$

Analysis: count “element visits” (read and/or write)

$$C(n) = \begin{cases} 0 & n \leq 1 \\ C(\lfloor n/2 \rfloor) + C(\lceil n/2 \rceil) + 2\underline{n} & n \geq 2 \end{cases}$$

same for best and worst case!

Simplification $n = 2^k$

$$C(2^k) = \begin{cases} 0 & k \leq 0 \\ 2 \cdot C(2^{k-1}) + 2 \cdot 2^k & k \geq 1 \end{cases} = 2 \cdot 2^k + 2^2 \cdot \underline{2^{k-1}} + 2^3 \cdot 2^{k-2} + \cdots + 2^k \cdot 2^1 = \underbrace{2k \cdot 2^k}_{\log n}$$

$$C(n) = \underline{2n \lg(n)} = \Theta(n \log n)$$

Mergesort – Discussion

thumb up optimal time complexity of $\Theta(n \log n)$ in the worst case

thumb up *stable* sorting method i. e., retains relative order of equal-key items

2 3 1 2 2 5

thumb up memory access is sequential (scans over arrays)

→ 1 2 2 2 3 5 sorted

thumb down requires $\Theta(n)$ extra space

there are in-place merging methods,
but they are substantially more complicated
and not (widely) used

but not stable sorted

3.2 Quicksort

Clicker Question



How does quicksort work?

- A** split elements around median, then recurse on small / large elements.
- B** recurse on left / right half, then combine sorted halves.
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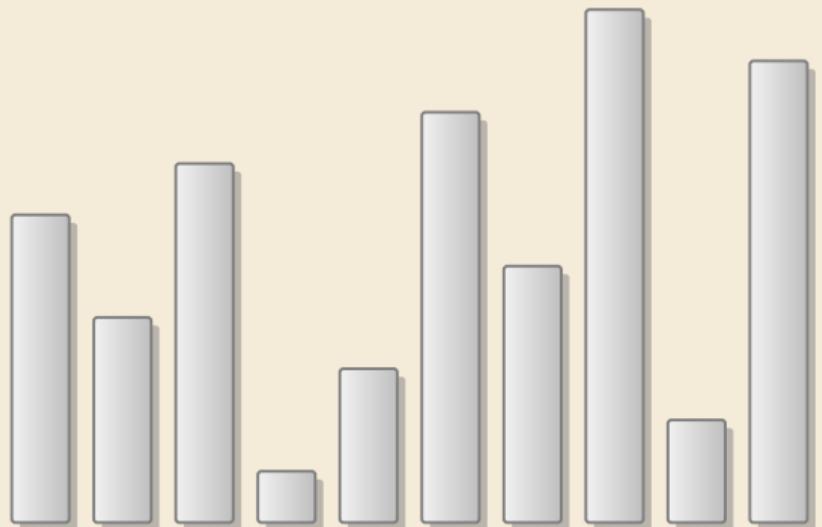
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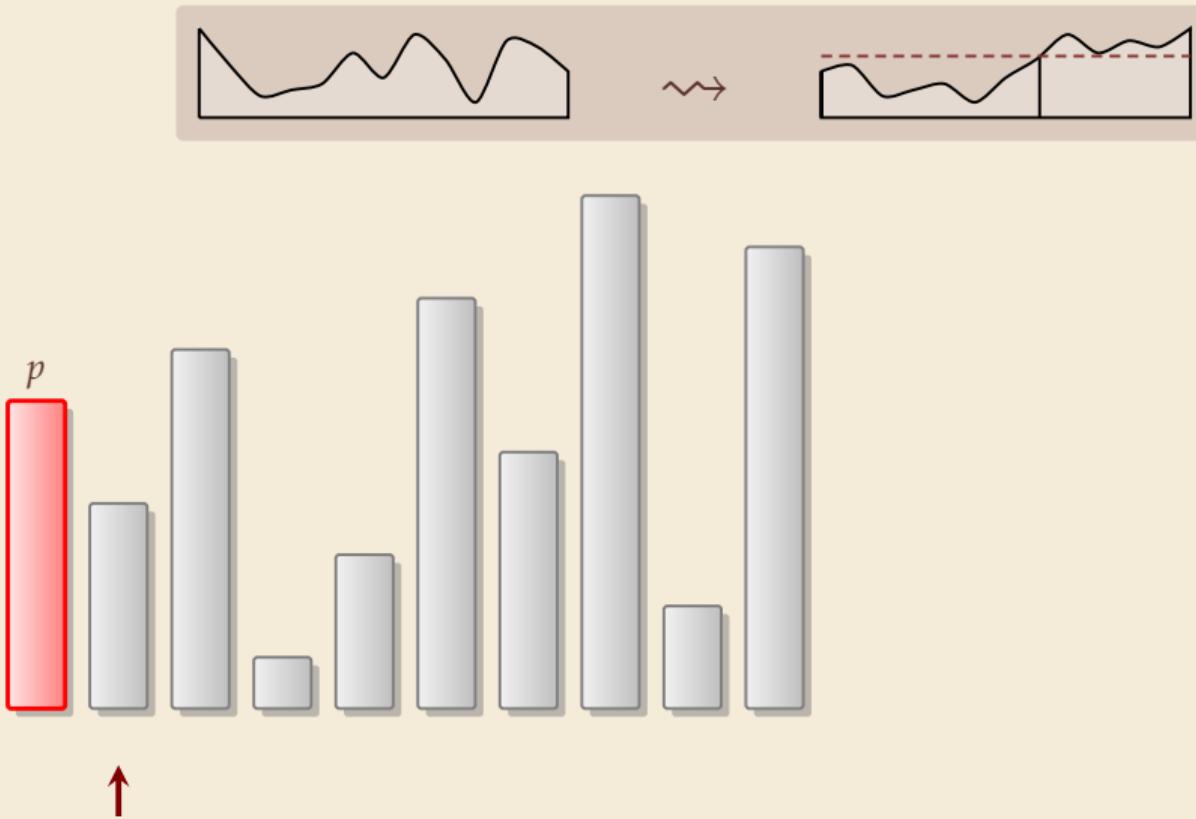
Partitioning around a pivot



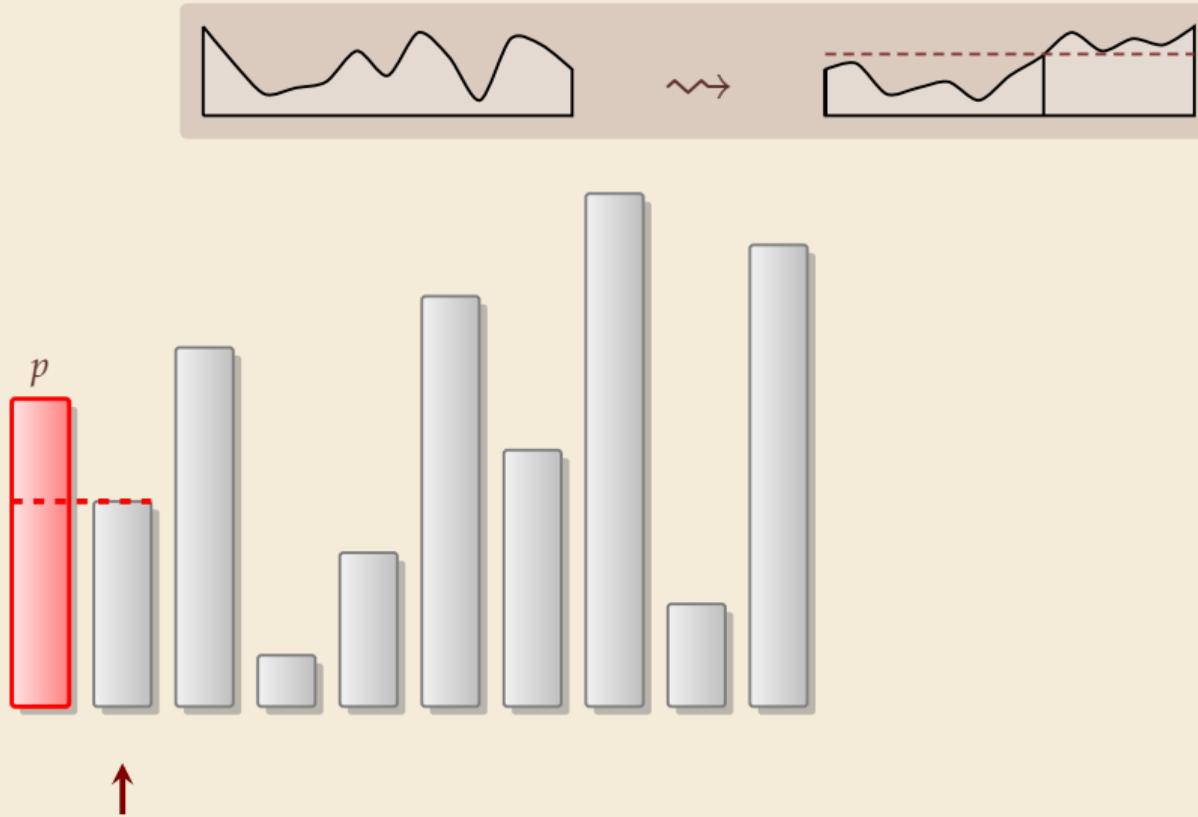
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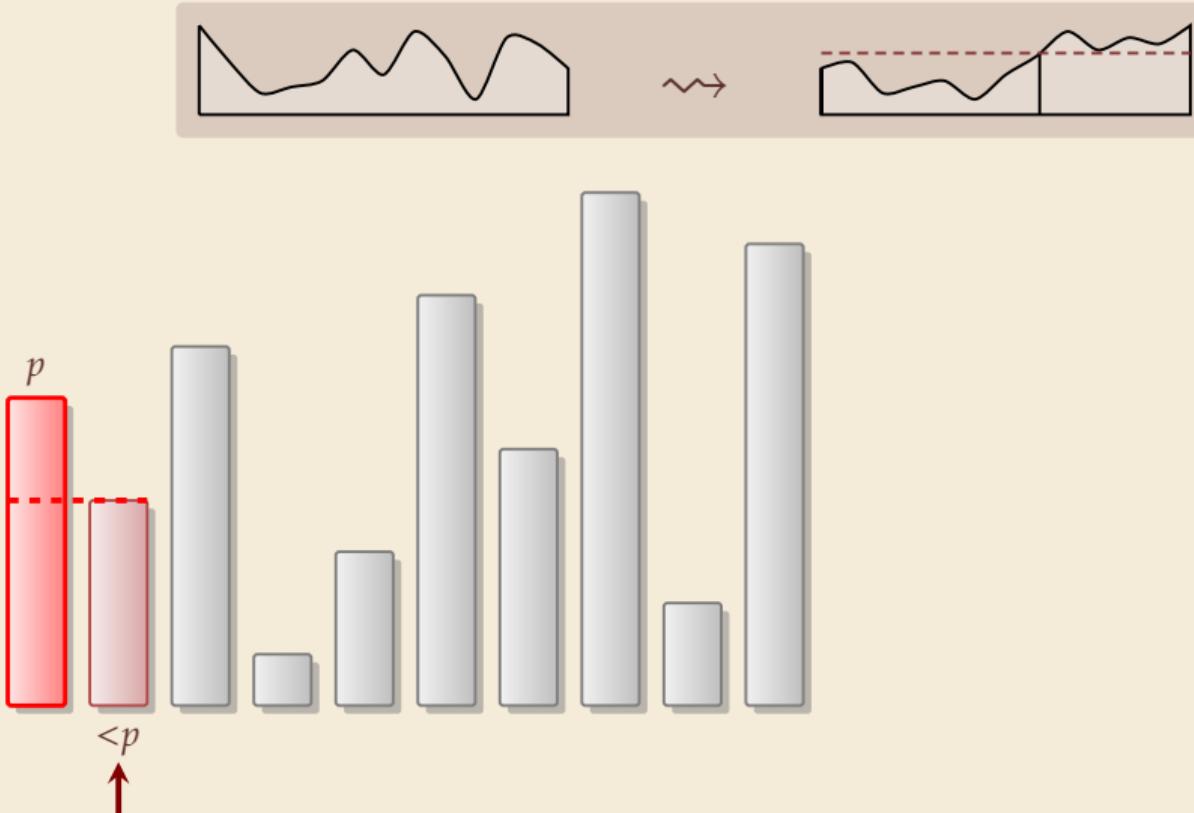
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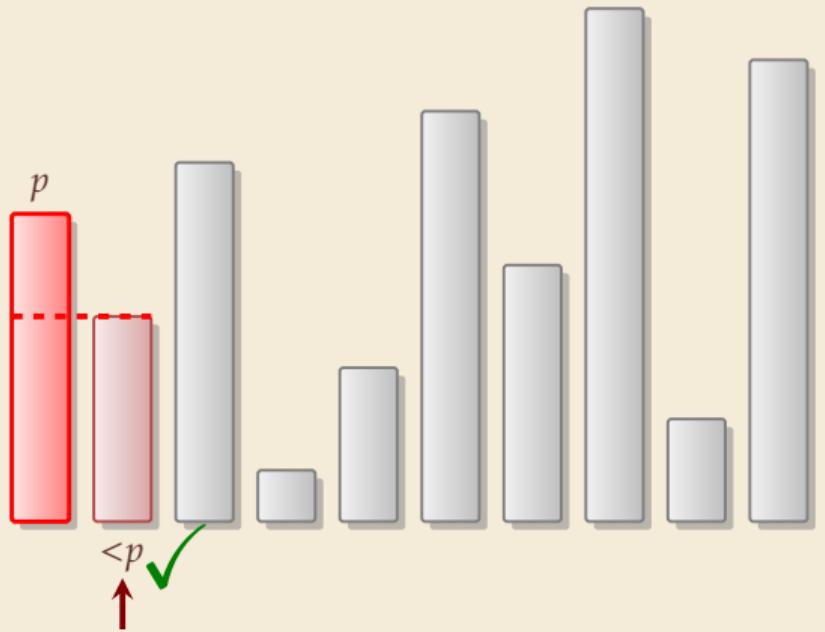
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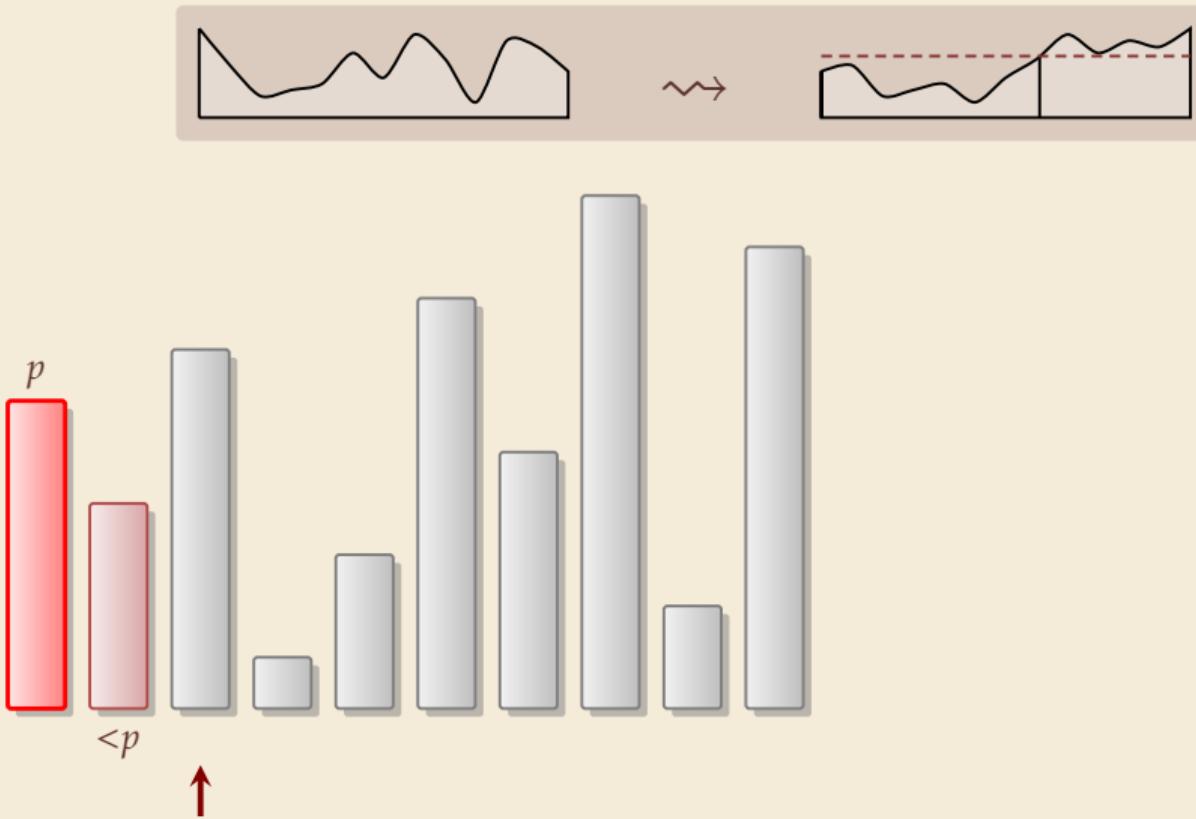
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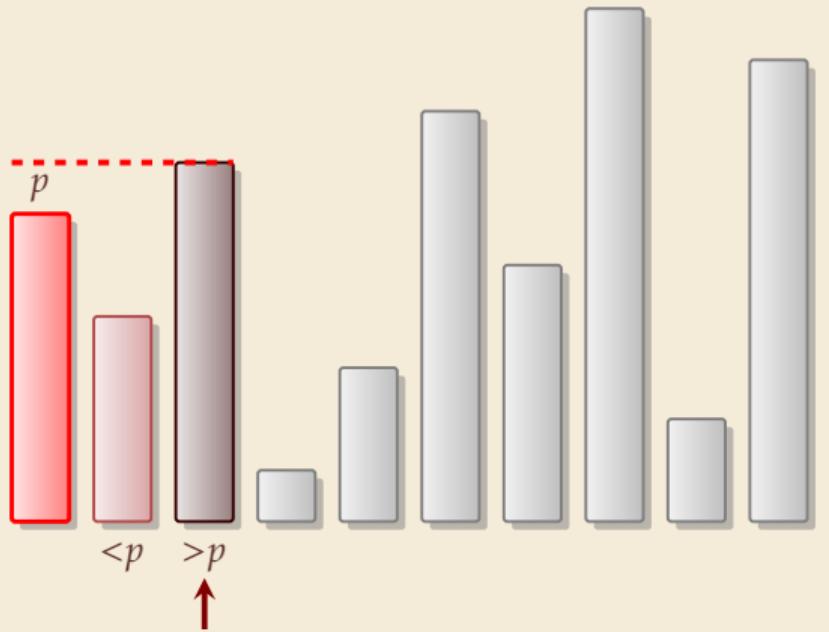
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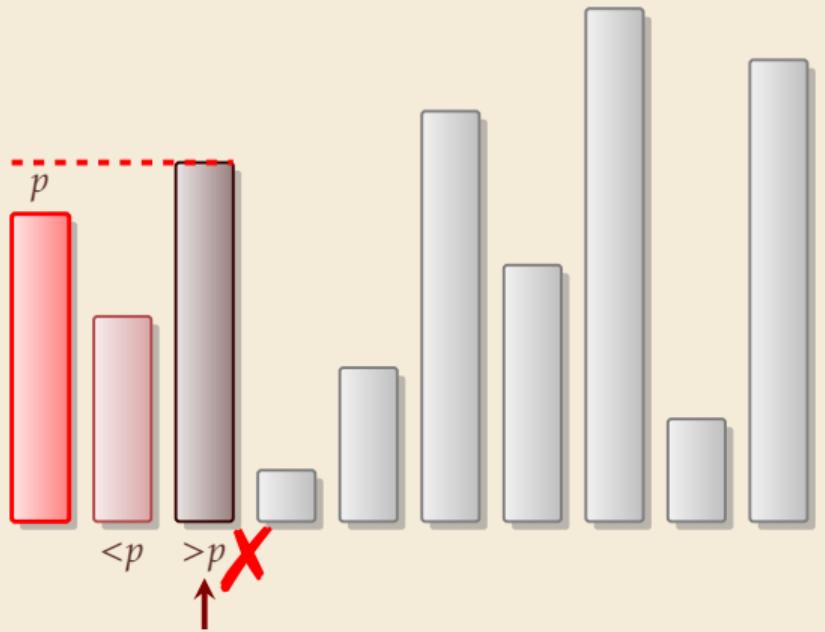
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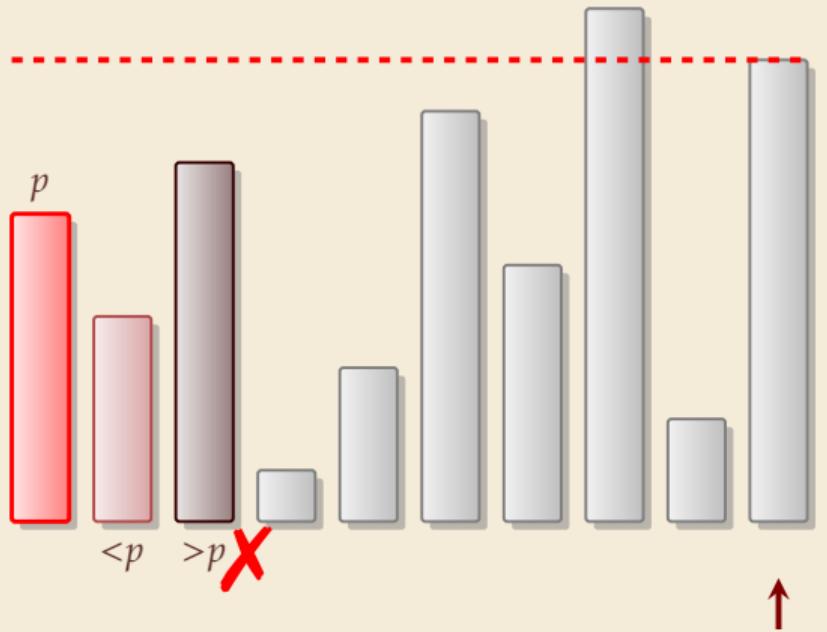
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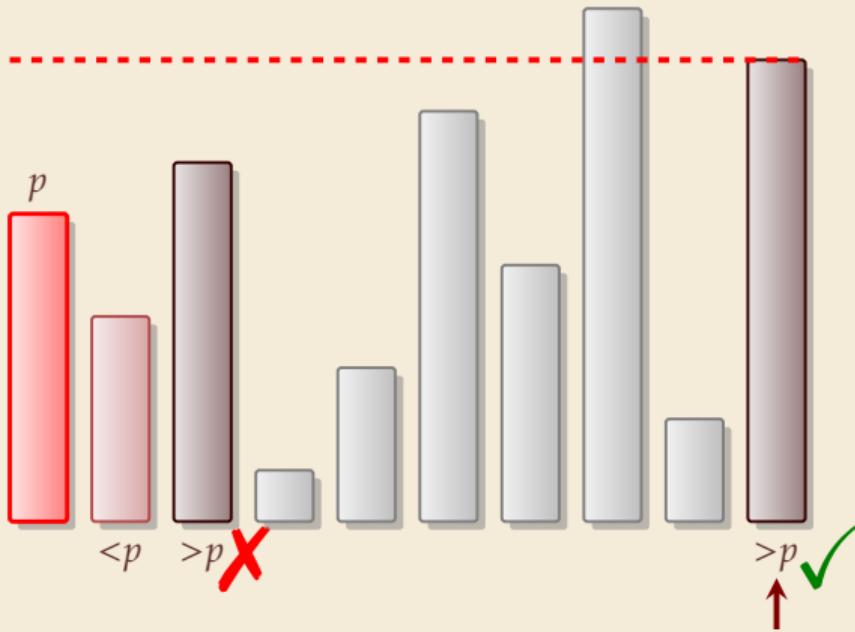
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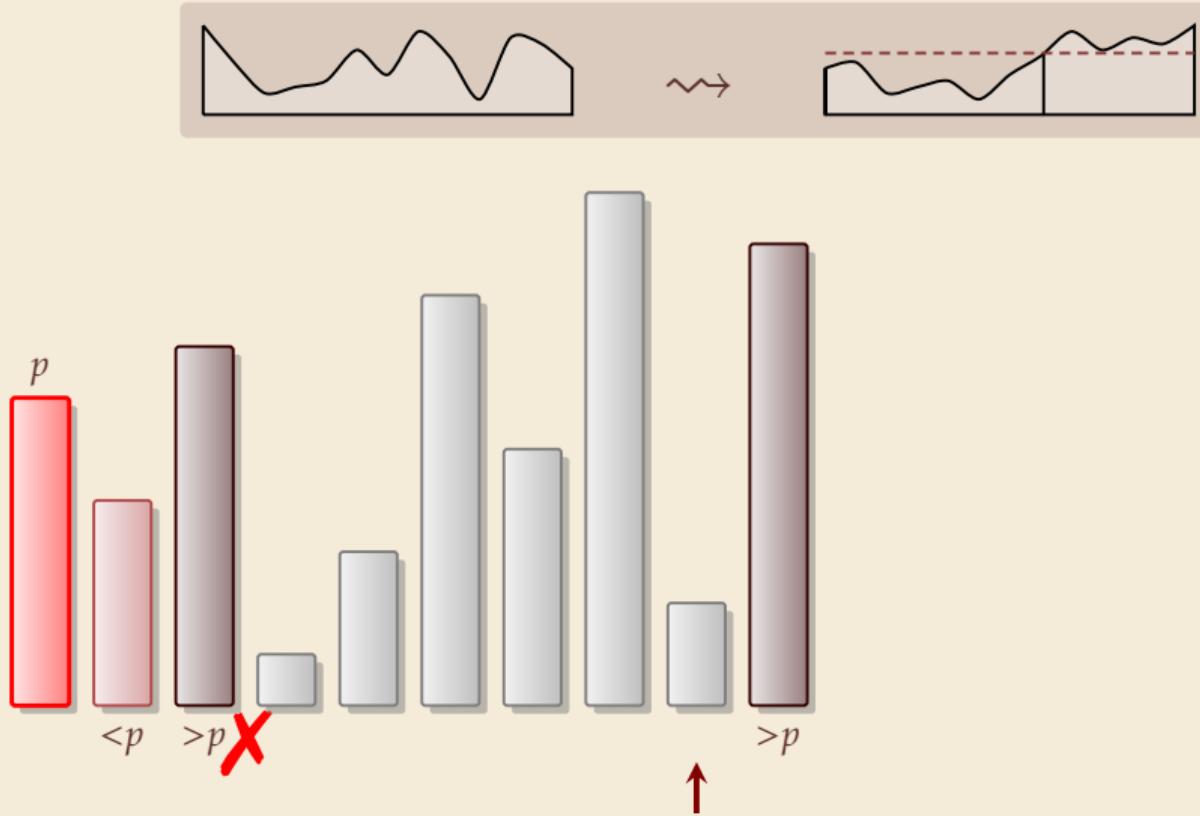
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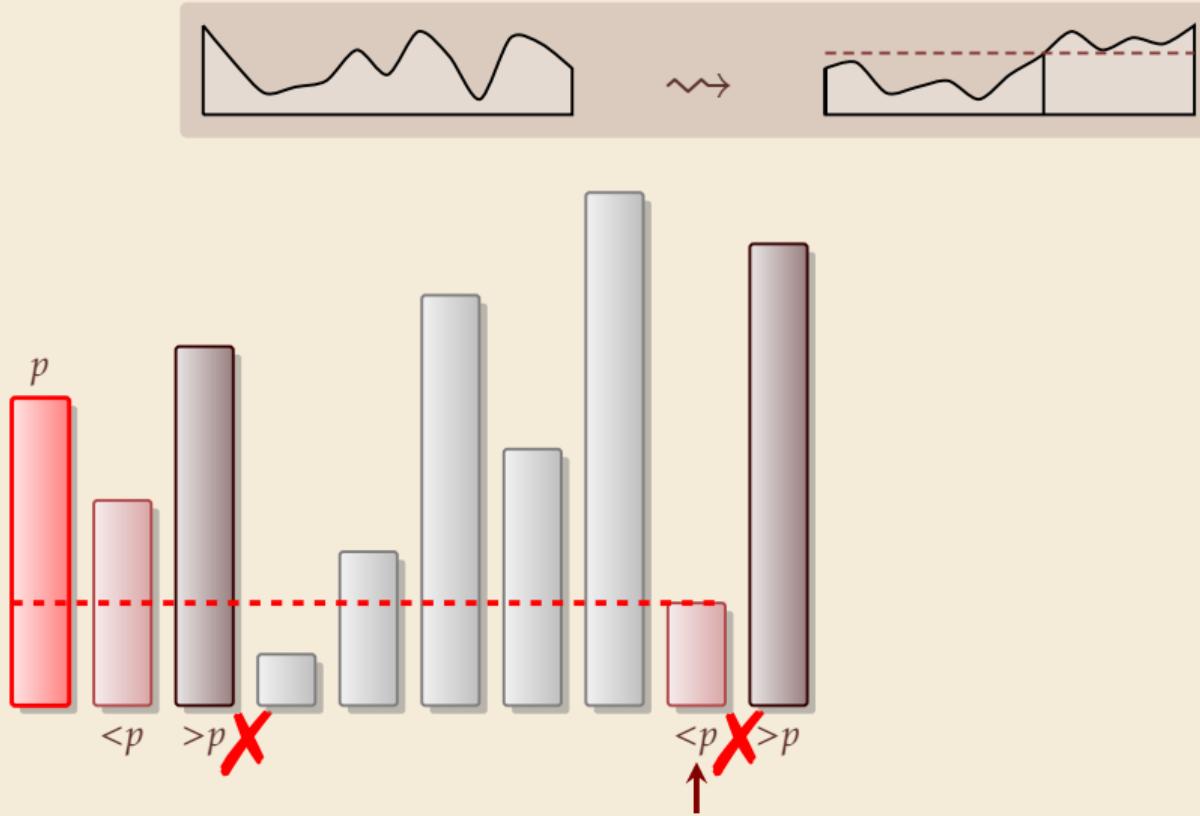
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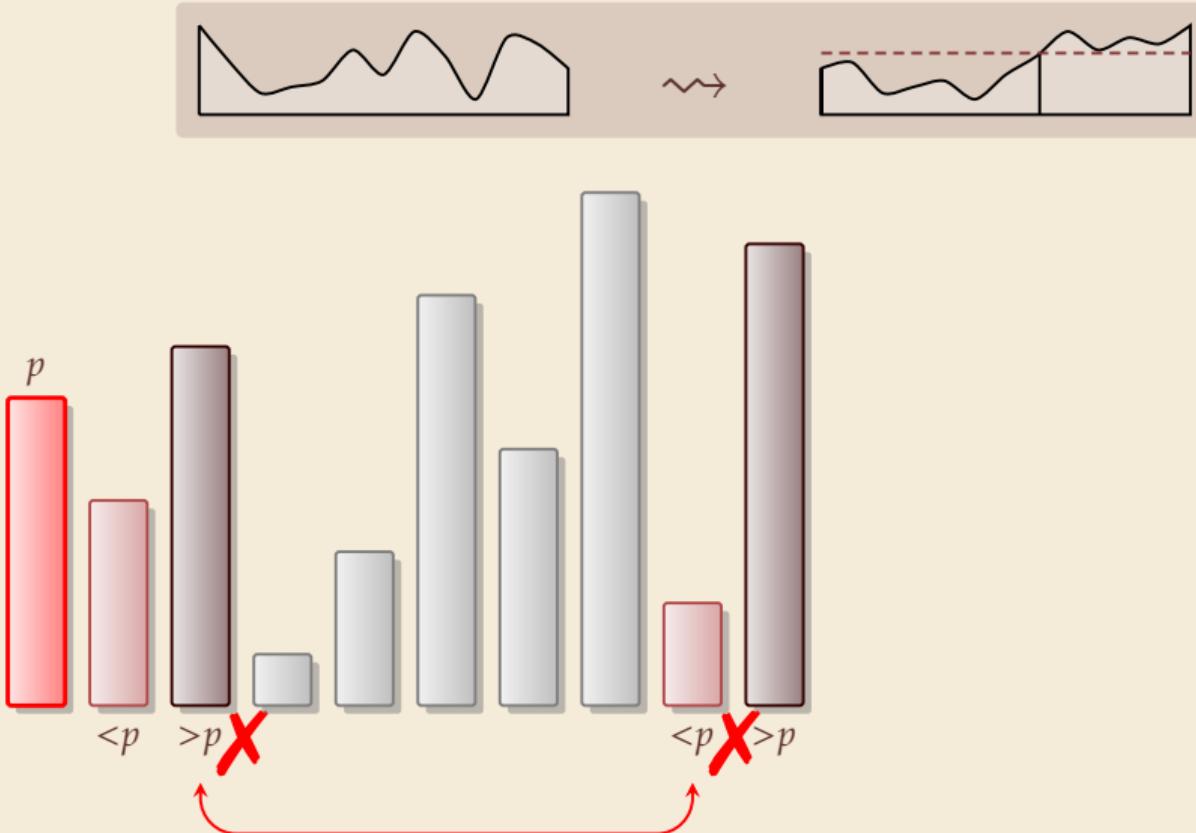
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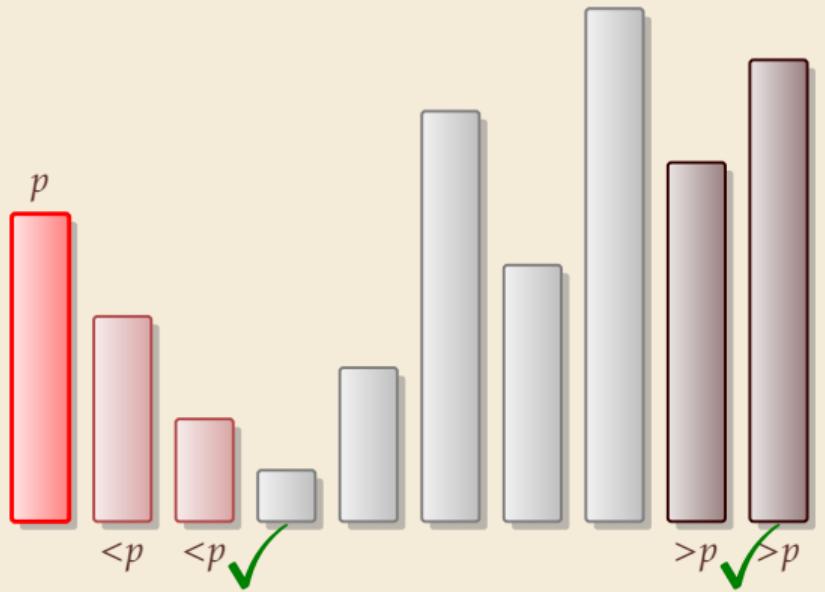
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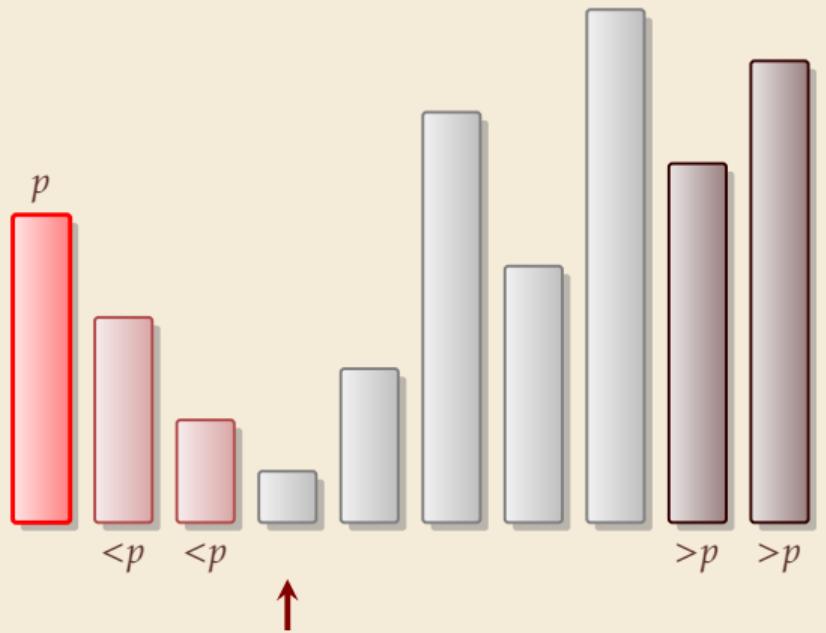
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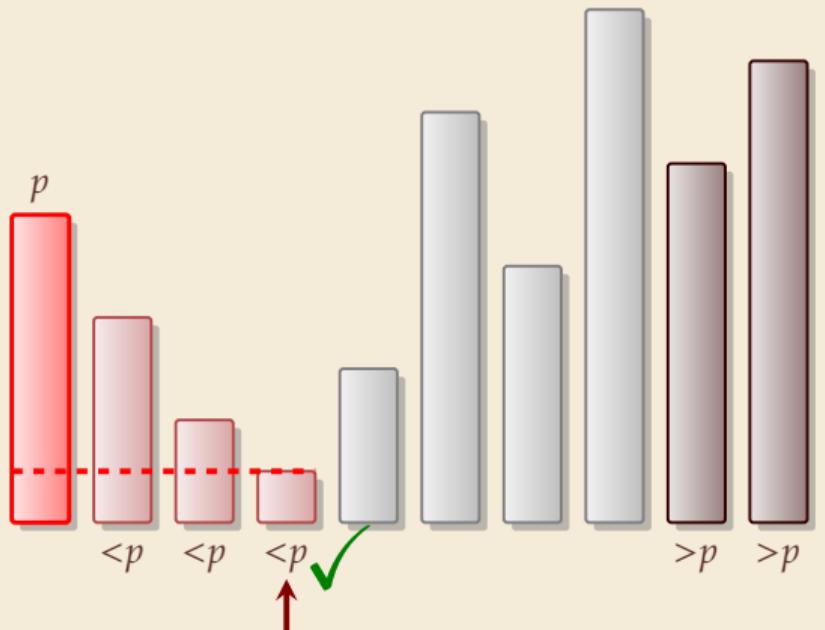
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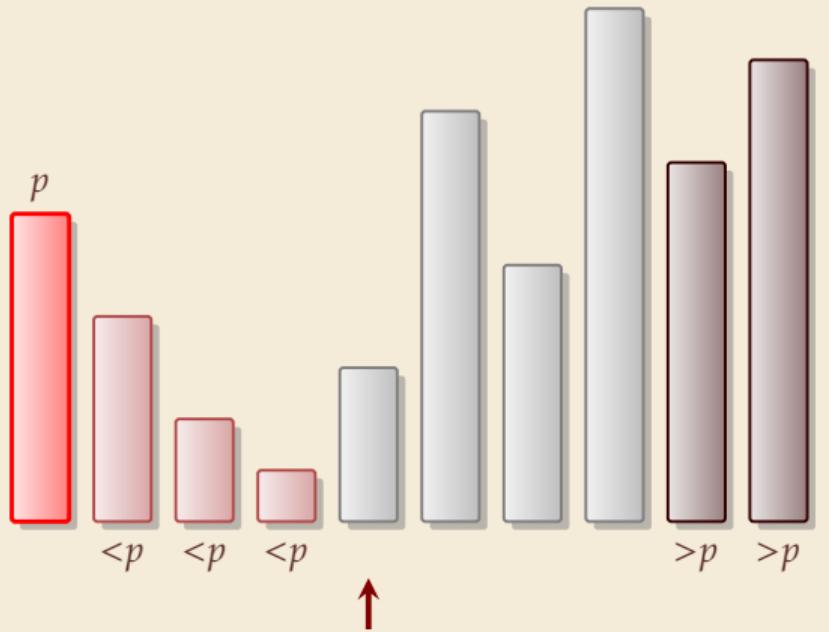
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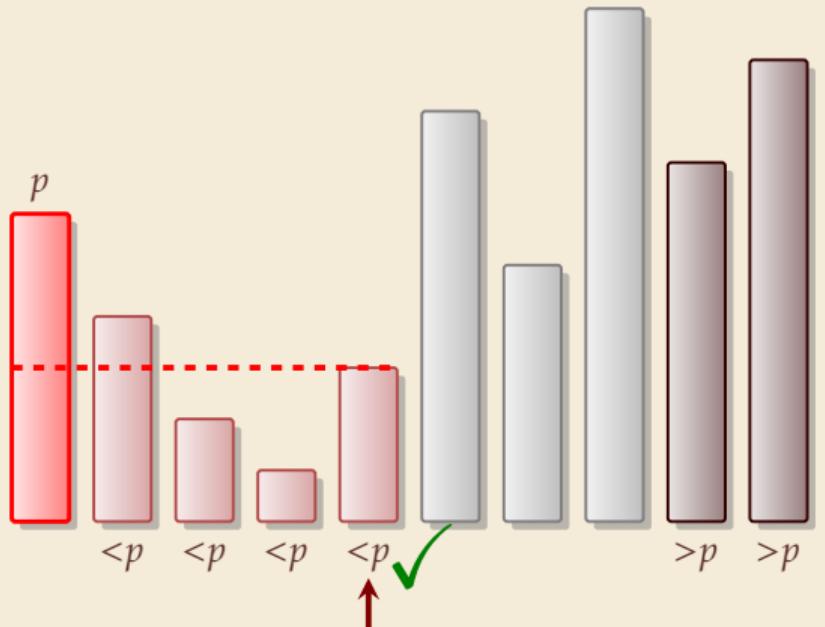
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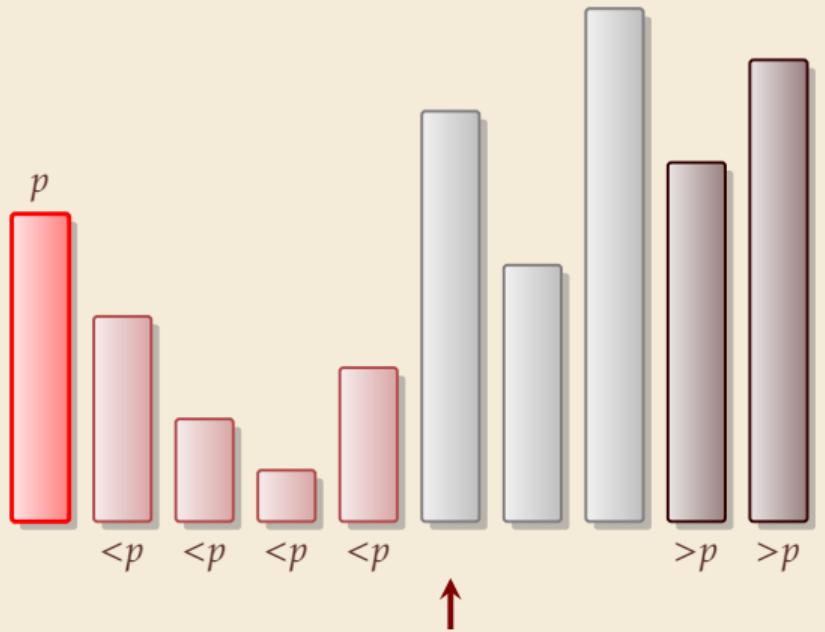
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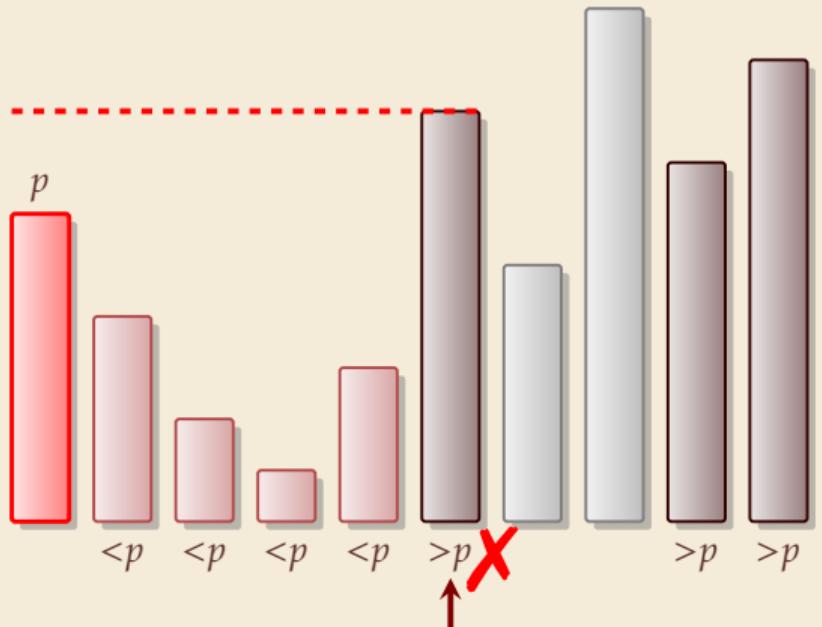
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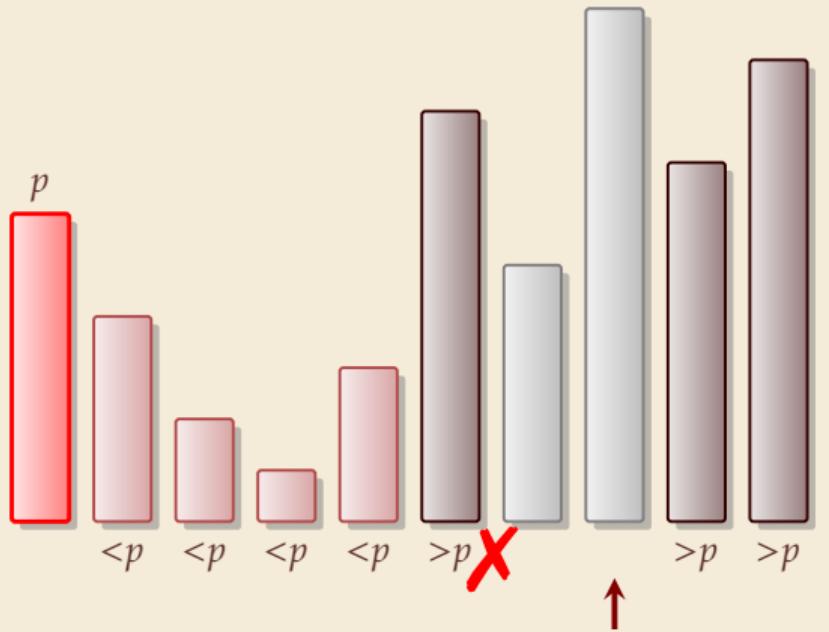
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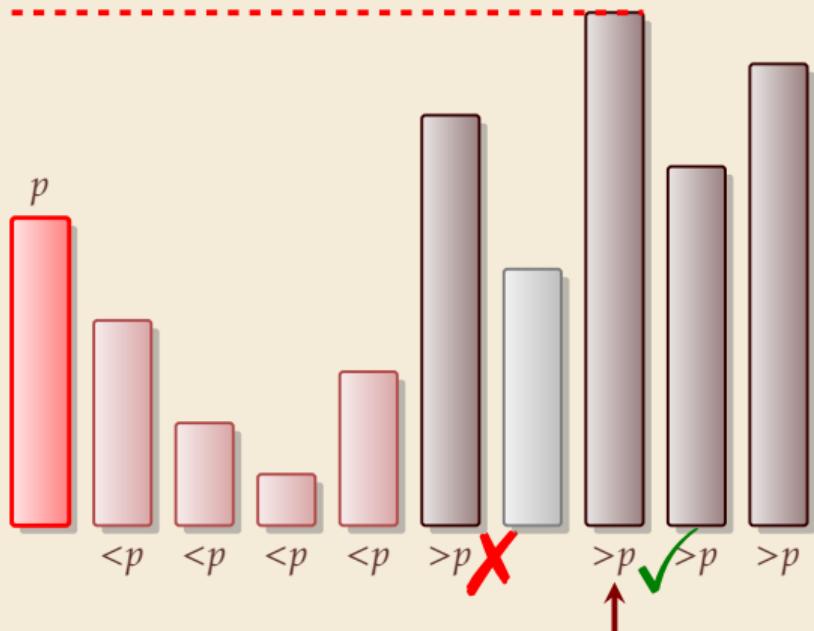
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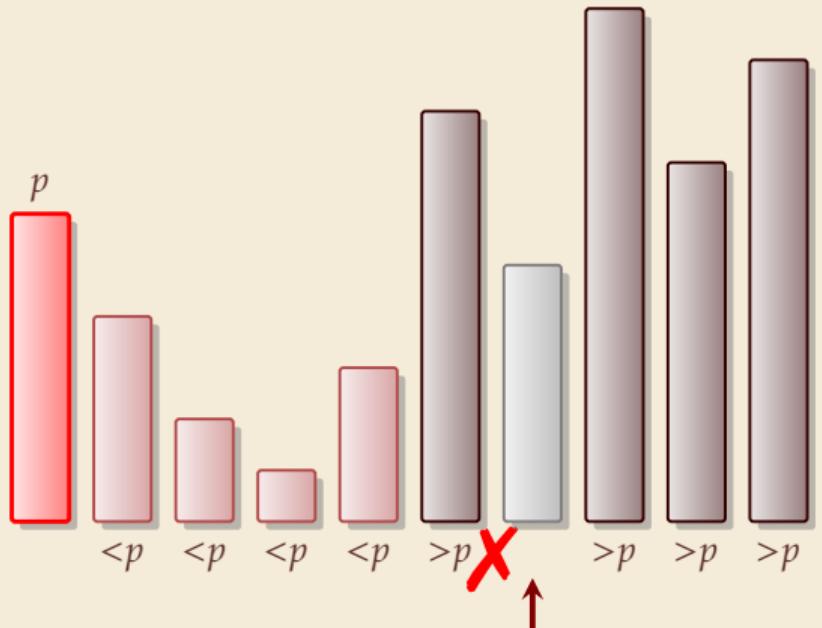
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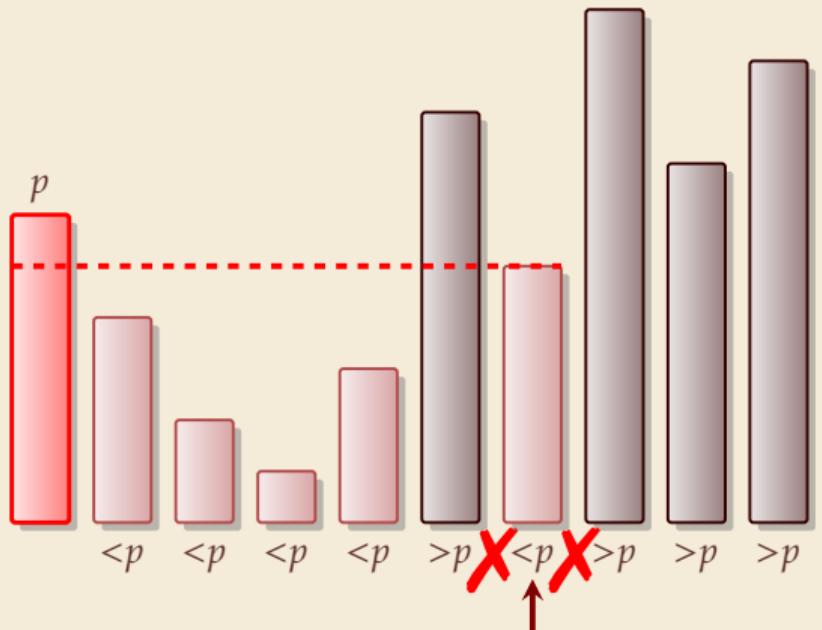
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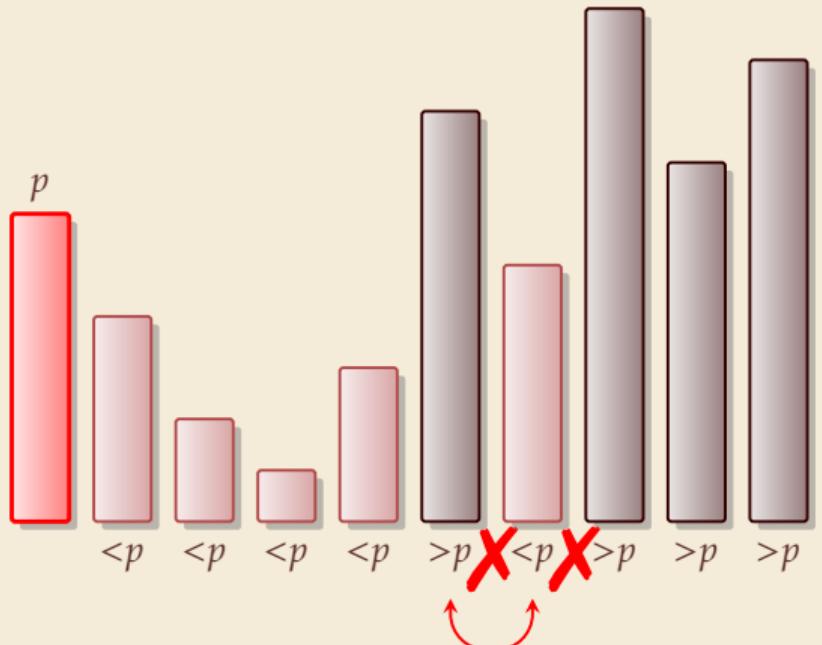
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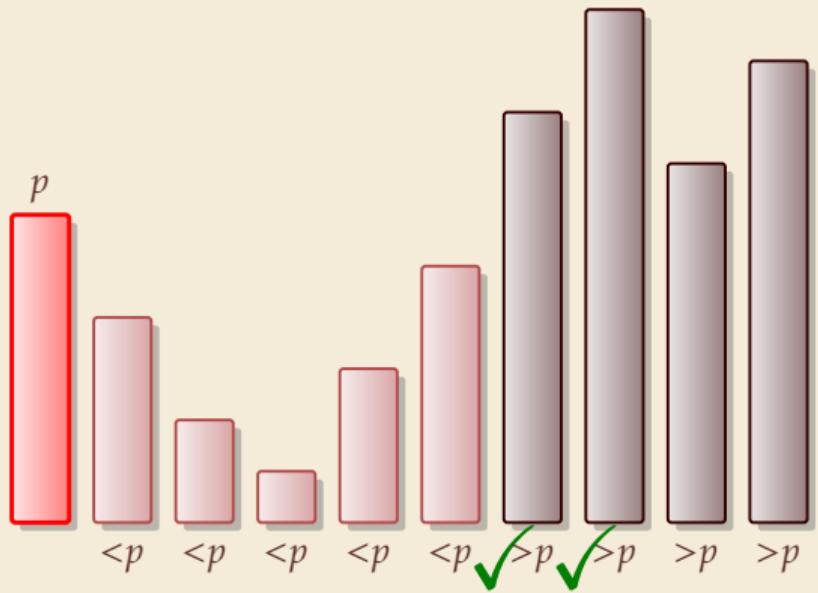
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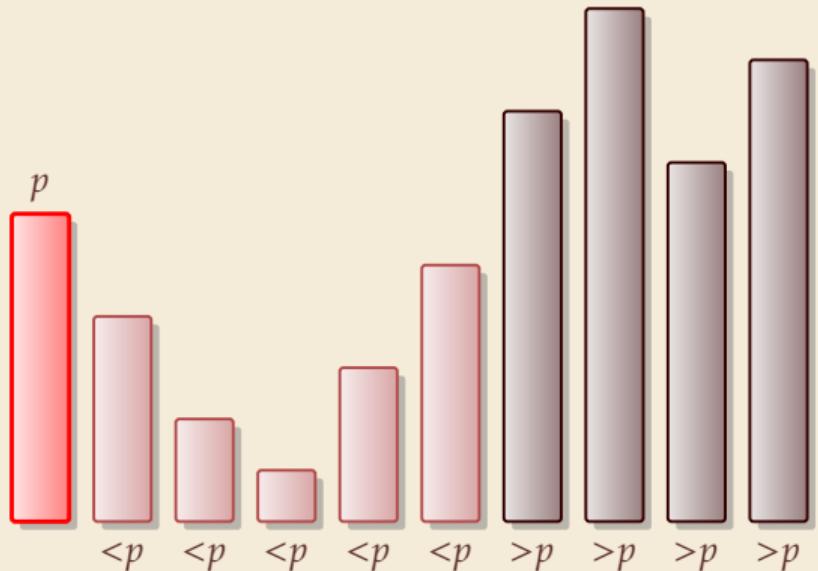
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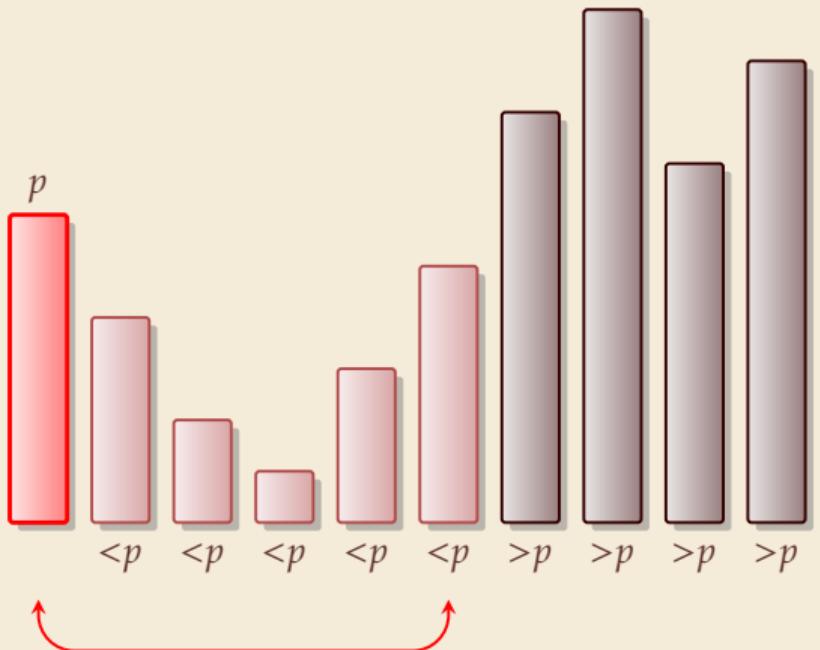
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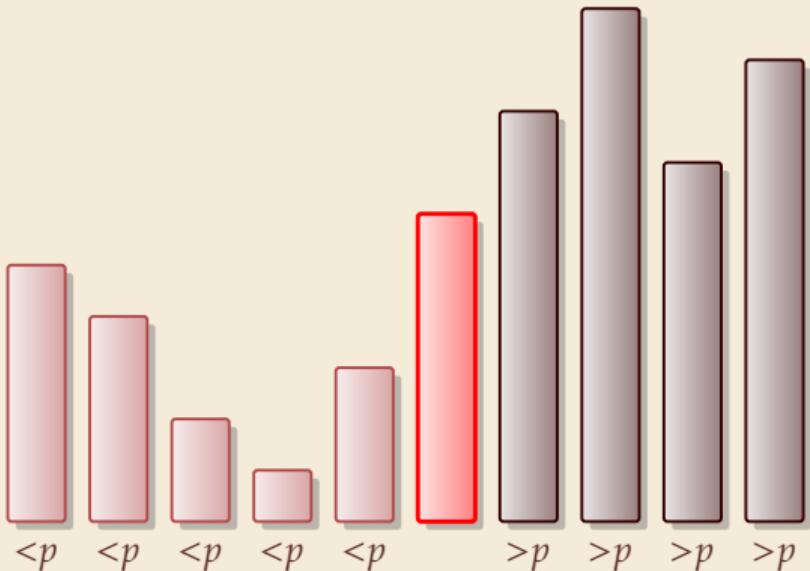
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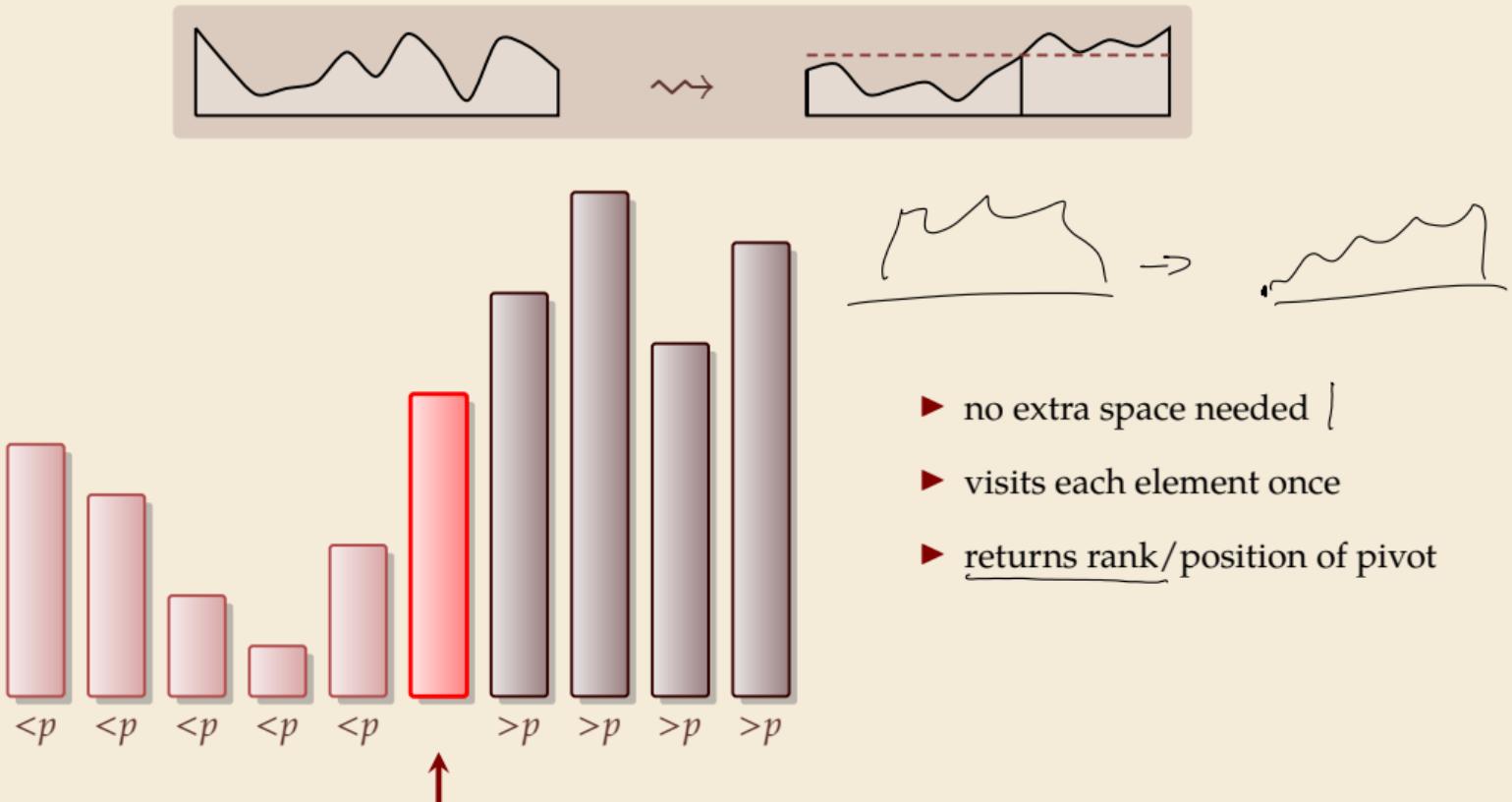
Partitioning around a pivot



Partitioning around a pivot



Partitioning around a pivot



Partitioning – Detailed code

Beware: details easy to get wrong; use this code!

```
1 procedure partition( $A, b$ )
2     // input: array  $A[0..n - 1]$ , position of pivot  $b \in [0..n - 1]$ 
3     swap( $A[0], A[b]$ )
4      $i := 0, j := n$ 
5     while true do
6         do  $i := i + 1$  while  $i < n$  and  $A[i] < A[0]$ 
7         do  $j := j - 1$  while  $j \geq 1$  and  $A[j] > A[0]$ 
8         if  $i \geq j$  then break (goto 8)
9         else swap( $A[i], A[j]$ )
10    end while
11    swap( $A[0], A[j]$ )
12    return  $j$ 
```

Loop invariant (5–10):

A	p	$\leq p$	$?$	$\geq p$
		i		j

Quicksort

```
1 procedure quicksort( $A[l..r]$ )
2   if  $l \geq r$  then return
3    $b := \text{choosePivot}(A[l..r])$ 
4    $j := \text{partition}(A[l..r], b)$ 
5   quicksort( $A[l..j - 1]$ )
6   quicksort( $A[j + 1..r]$ )
```

- ▶ recursive procedure; *divide & conquer*
- ▶ choice of pivot can be
 - ▶ fixed position ↗ dangerous!
 - ▶ random
 - ▶ more sophisticated, e. g., median of 3

Quicksort & Binary Search Trees

Quicksort

7	4	2	9	1	3	8	5	6
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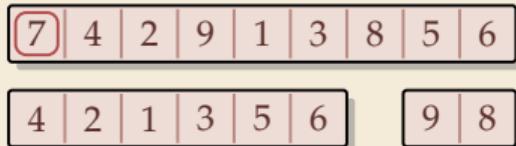
Quicksort & Binary Search Trees

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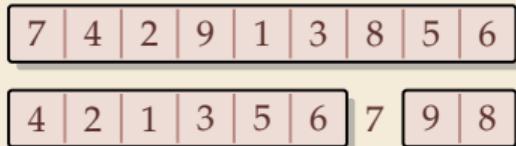
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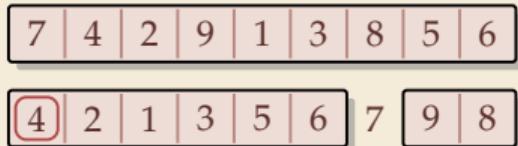
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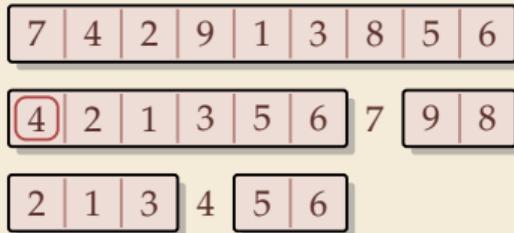
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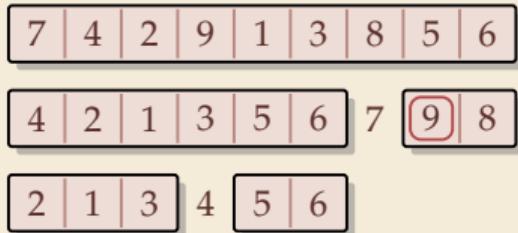
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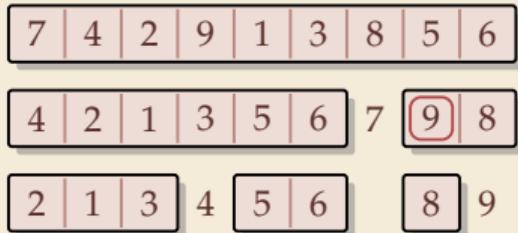
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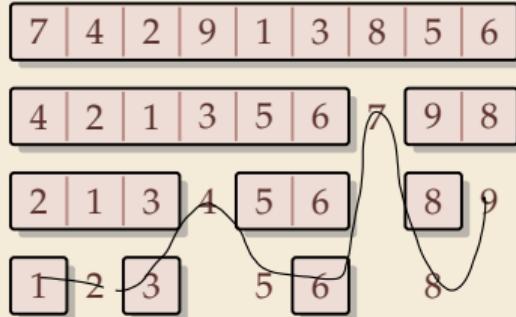
Quicksort



Quicksort & Binary Search Trees

Quicksort

time ↓



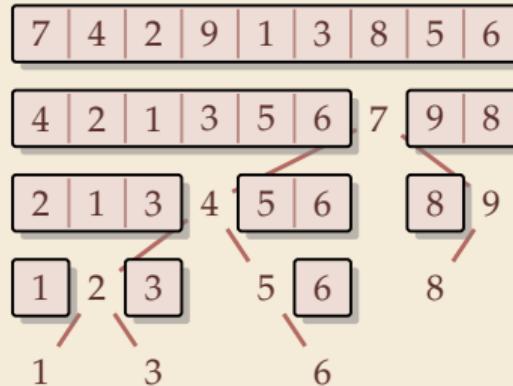
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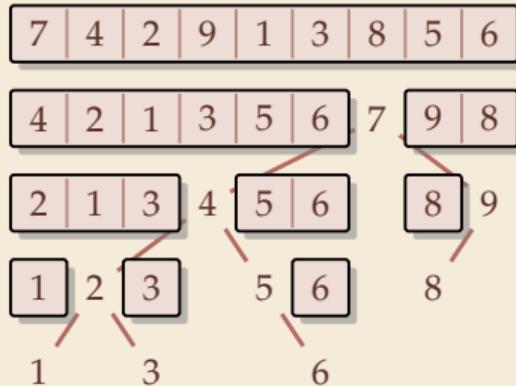
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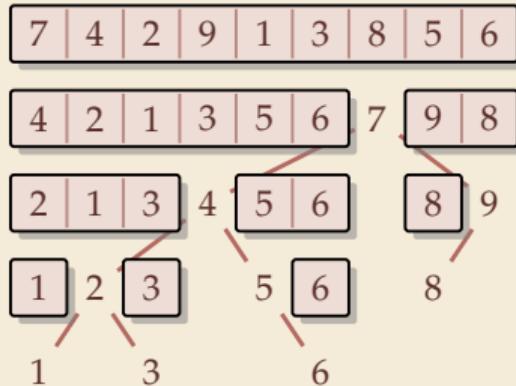


Binary Search Tree (BST)

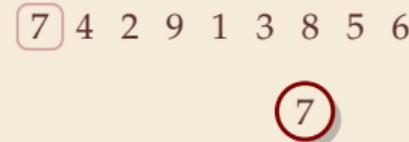
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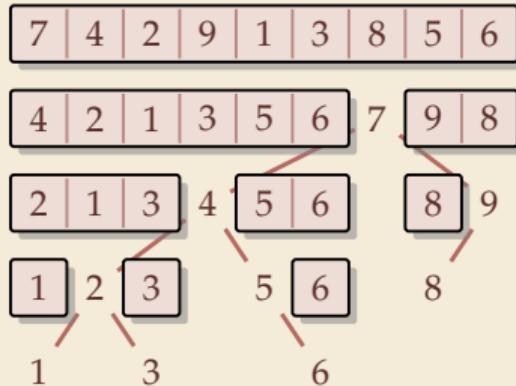


Binary Search Tree (BST)

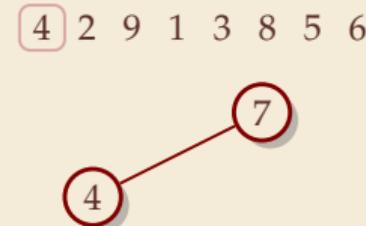


Quicksort & Binary Search Trees

Quicksort

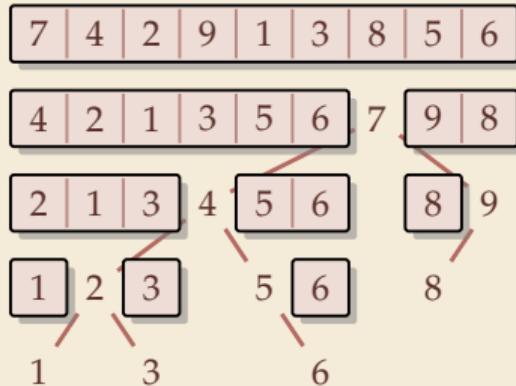


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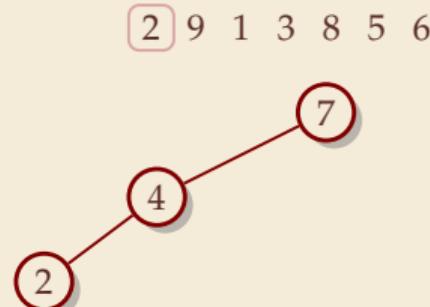


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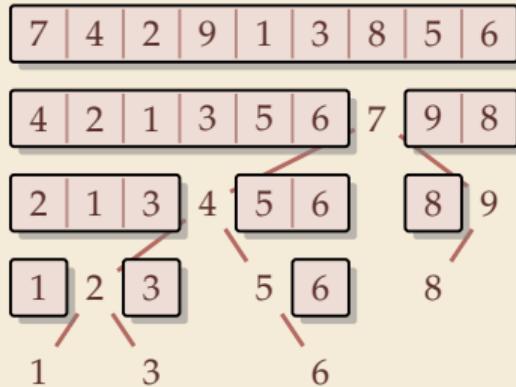


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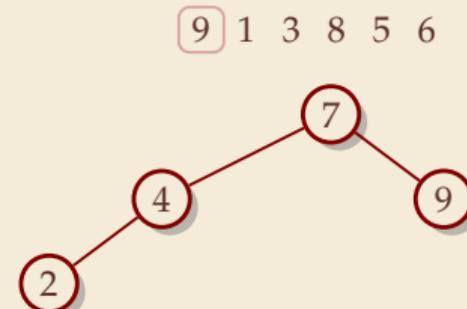


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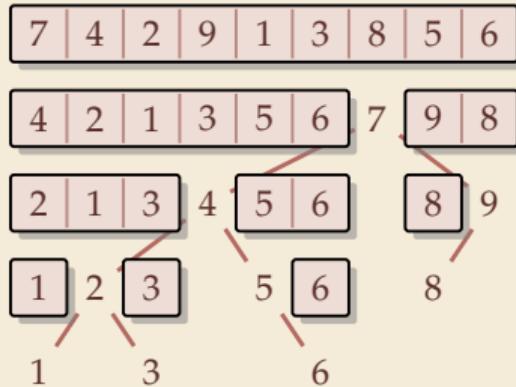


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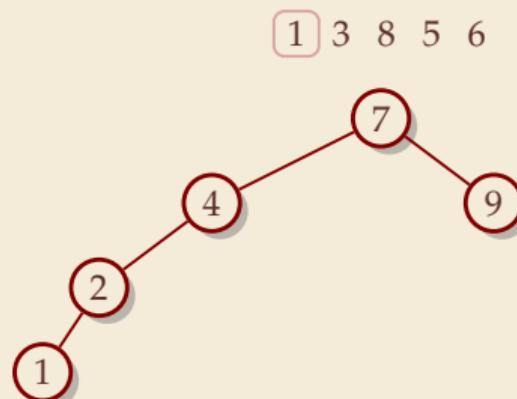


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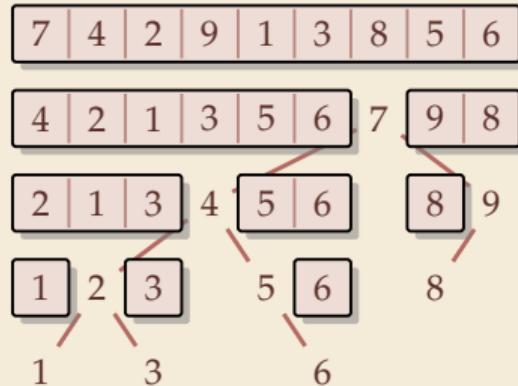


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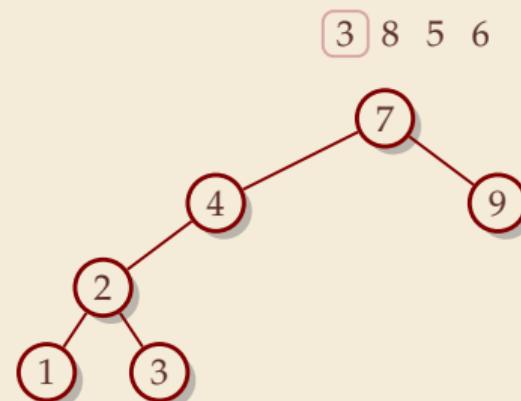


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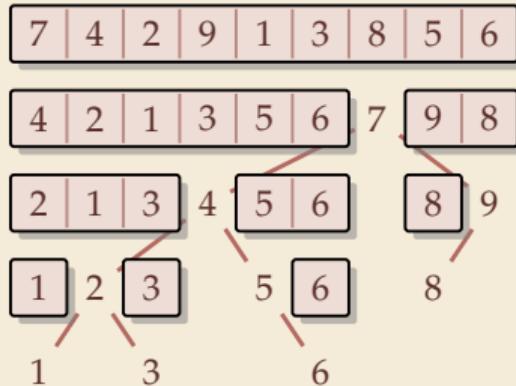


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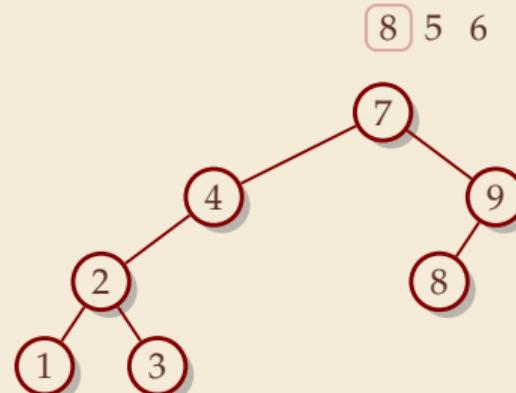


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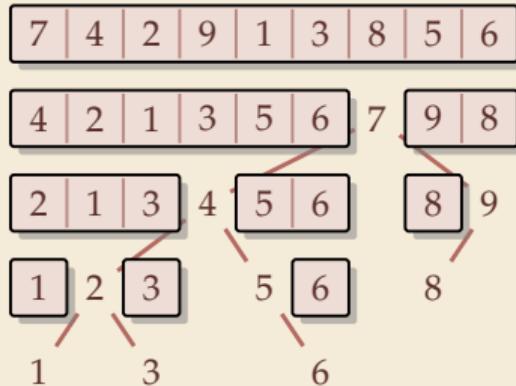


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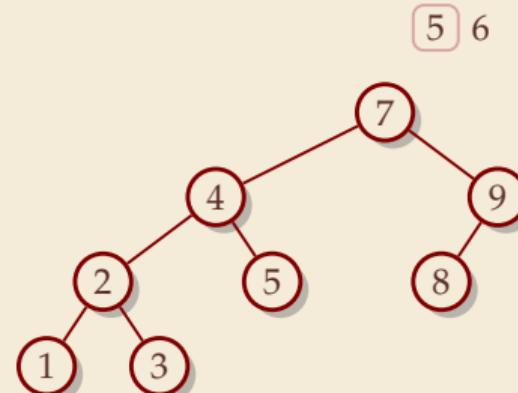


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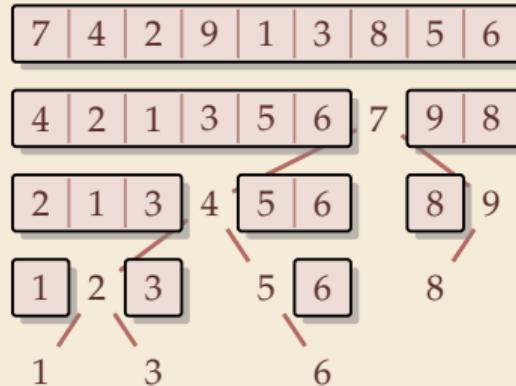


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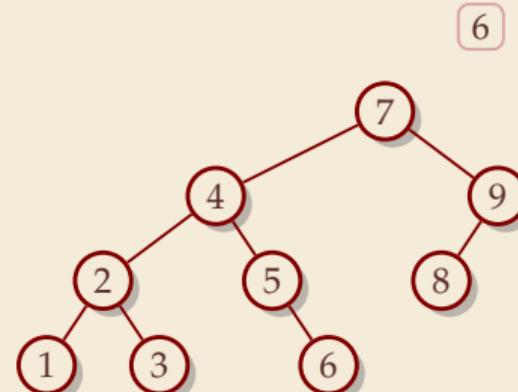


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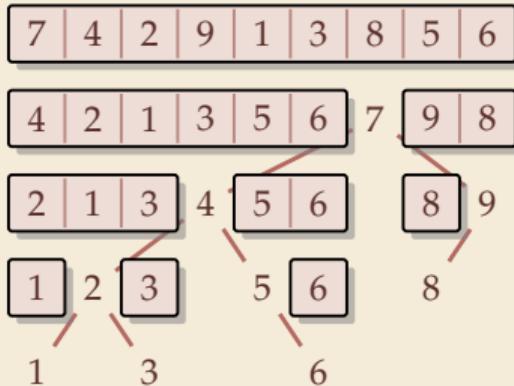


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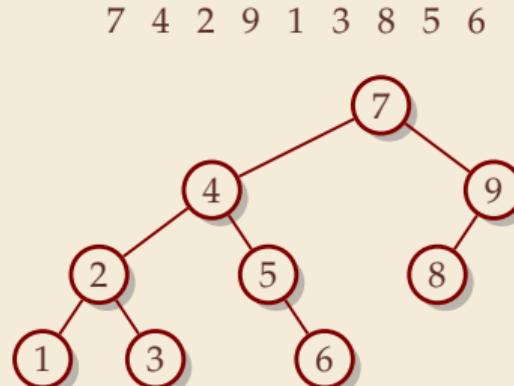


Quicksort & Binary Search Trees

Quicksort



Binary Search Tree (BST)



- recursion tree of quicksort = binary search tree from successive insertion
- comparisons in quicksort = comparisons to built BST
- comparisons in quicksort \approx comparisons to search each element in BST

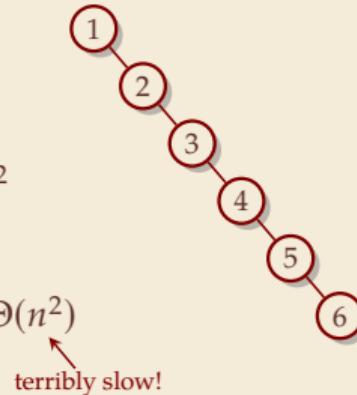
Quicksort – Worst Case

- ▶ Problem: BSTs can degenerate

- ▶ Cost to search for k is $k - 1$

$$\rightsquigarrow \text{Total cost } \sum_{k=1}^n (k - 1) = \frac{n(n - 1)}{2} \sim \frac{1}{2}n^2$$

rightsquigarrow quicksort worst-case running time is in $\Theta(n^2)$



But, we can fix this:

Randomized quicksort:

- ▶ choose a *random pivot* in each step

rightsquigarrow same as randomly shuffling input before sorting ↴

Randomized Quicksort – Analysis

- ▶ $C(n)$ = element visits (as for mergesort)
 - ~~ quicksort needs $\sim 2 \ln(2) \cdot n \lg n \approx \underline{1.39n \lg n}$ *in expectation*
- ▶ also: very unlikely to be much worse:
 - e. g., one can prove: $\Pr[\text{cost} > 10n \lg n] = O(n^{-2.5})$
 - distribution of costs is “concentrated around mean”
- ▶ intuition: have to be constantly unlucky with pivot choice]

Quicksort – Discussion

- thumb up fastest general-purpose method
- thumb up $\Theta(n \log n)$ average case
- thumb up works *in-place* (no extra space required)
- thumb up memory access is sequential (scans over arrays)
- thumb down $\Theta(n^2)$ worst case (although extremely unlikely) —————
- thumb down not a *stable* sorting method

Open problem: Simple algorithm that is fast, stable and in-place.

3.3 Comparison-Based Lower Bound

Lower Bounds

- ▶ **Lower bound:** mathematical proof that no algorithm can do better.
 - ▶ very powerful concept: bulletproof *impossibility* result
≈ *conservation of energy* in physics
 - ▶ **(unique?) feature of computer science:**
for many problems, solutions are known that (asymptotically) *achieve the lower bound*
~~ can speak of “*optimal* algorithms”

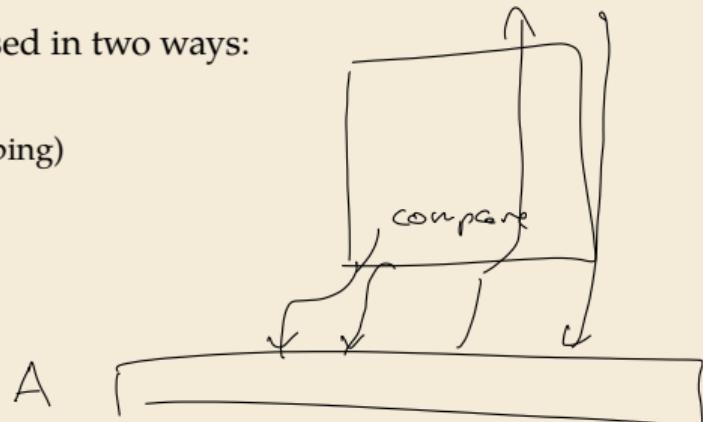
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for many problems, solutions are known that (asymptotically) *achieve the lower bound*
~~ can speak of “*optimal* algorithms”
- ▶ To prove a statement about *all algorithms*, we must precisely define what that is!
- ▶ already know one option: the word-RAM model
- ▶ Here: use a simpler, more restricted model.

The Comparison Model

buffer

- ▶ In the *comparison model* data can only be accessed in two ways:
 - ▶ comparing two elements
 - ▶ moving elements around (e.g. copying, swapping)
 - ▶ Cost: number of these operations.



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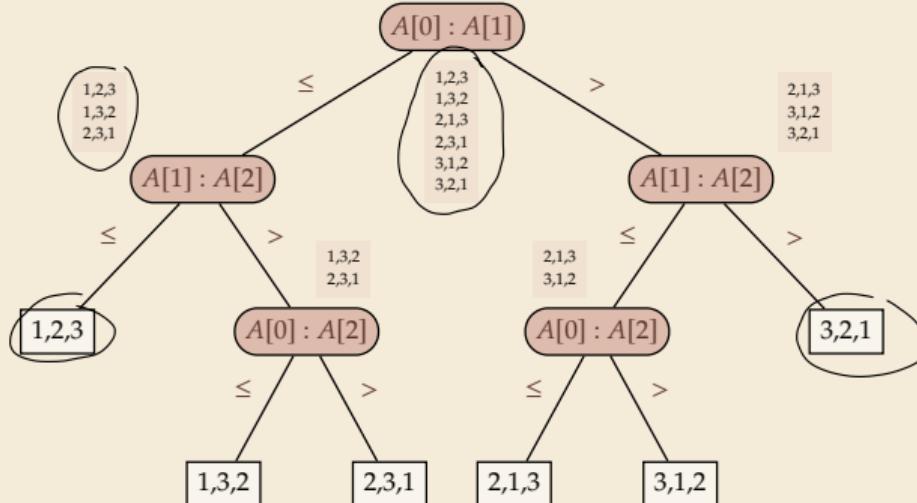
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 - That's good!
Keeps algorithms general!
 - ▶ Mergesort and Quicksort work in the comparison model.
- ~~ Every comparison-based sorting algorithm corresponds to a *decision tree*.
- ▶ only model comparisons ~~ ignore data movement
 - ▶ nodes = comparisons the algorithm does —
 - ▶ next comparisons can depend on outcomes ~~ different subtrees
 - ▶ child links = outcomes of comparison
 - ▶ leaf = unique initial input permutation compatible with comparison outcomes

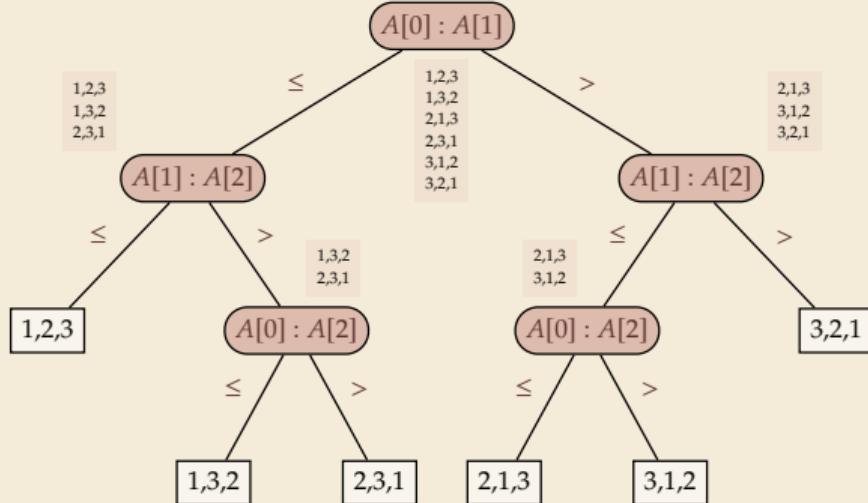
Comparison Lower Bound

Example: Comparison tree for a sorting method for $A[0..2]$:



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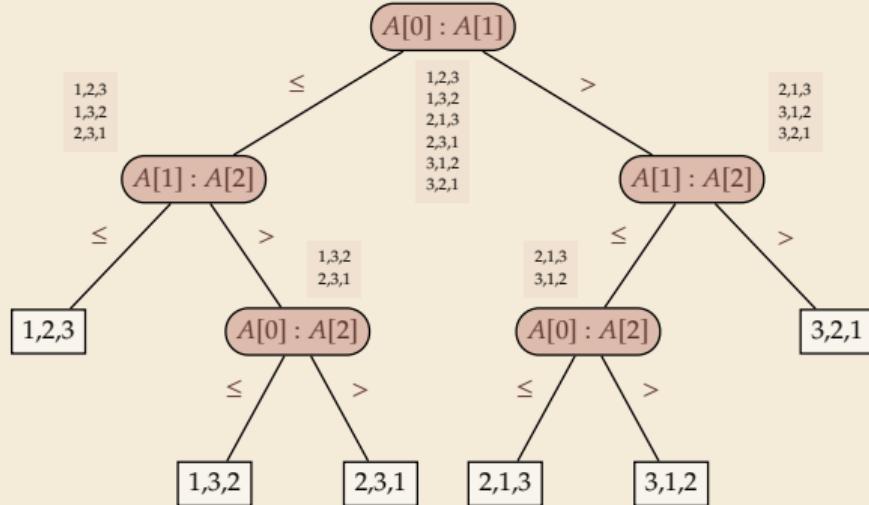


- ▶ Execution = follow a path in comparison tree.
 - ~~ height of comparison tree = worst-case # comparisons
- ▶ comparison trees are *binary* trees
 - ~~ ℓ leaves ~~ height $\geq \lceil \lg(\ell) \rceil$
- ▶ comparison trees for sorting method must have $\geq \underline{n!}$ leaves
 - ~~ height $\geq \lg(n!) \sim \underline{n \lg n}$

more precisely: $\lg(n!) = n \lg n - \lg(e)n + O(\log n)$

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