ALGORITHMS \$ EFFICIENT

CIENTALGORITHMS \$ EFFI

EFFICIENTALGORITHMS \$

ENTALGORITHMS \$ EFFICI

FFICIENTALGORITHMS \$ E

FICIENTALGORITHMS \$ E

GORITHMS \$ EFFICIENTAL

HMS \$ EFFICIENTALGORIT



Divide & Conquer

11 November 2024

Prof. Dr. Sebastian Wild

Learning Outcomes

Unit 5: Divide & Conquer

- **1.** Know the steps of the Divide & Conquer paradigm.
- **2.** Be able to solve simple Divide & Conquer recurrences.
- 3. Be able to design and analyze new algorithms using the Divide & Conquer paradigm.
- **4.** Know the performance characteristics of selection-by-rank algorithms.

Outline

5 Divide & Conquer

- 5.1 Divide & Conquer Recurrences
- 5.2 Order Statistics
- 5.3 Linear-Time Selection
- 5.4 Fast Multiplication
- 5.5 Majority
- 5.6 Closest Pair of Points in the Plane

Divide and conquer

Divide and conquer idiom (Latin: divide et impera)
to make a group of people disagree and fight with one another
so that they will not join together against one (Merriam-Webster Dictionary)

→ in politics & algorithms, many independent, small problems are better than one big one!

Divide-and-conquer algorithms:

- **1.** Break problem into smaller, independent subproblems. (Divide!)
- **2.** Recursively solve all subproblems. (Conquer!)
- **3.** Assemble solution for original problem from solutions for subproblems.

Divide and conquer

Divide and conquer idiom (Latin: divide et impera)
to make a group of people disagree and fight with one another
so that they will not join together against one (Merriam-Webster Dictionary)

in politics & algorithms, many independent, small problems are better than one big one!

Divide-and-conquer algorithms:

- **1.** Break problem into smaller, independent subproblems. (Divide!)
- 2. Recursively solve all subproblems. (Conquer!)
- **3.** Assemble solution for original problem from solutions for subproblems.

Examples:

- ► Mergesort
- ▶ Quicksort
- Binary search
- (arguably) Tower of Hanoi

5.1 Divide & Conquer Recurrences

Back-of-the-envelope analysis

- before working out the details of a D&C idea, it is often useful to get a quick indication of the resulting performance
 - don't want to waste time on something that's not competitive in the end anyways!
- ▶ since D&C is naturally <u>recursive</u>, running time often not obvious instead: given by a recursive equation

Back-of-the-envelope analysis

- before working out the details of a D&C idea, it is often useful to get a quick indication of the resulting performance
 - don't want to waste time on something that's not competitive in the end anyways!
- since D&C is naturally recursive, running time often not obvious instead: given by a recursive equation
- unfortunately, rigorous analysis often tricky
 - ► Remember mergesort?

$$C(n) = \begin{cases} 0 & n \le 1 \\ C(\lfloor n/2 \rfloor) + C(\lceil n/2 \rceil) + 2n & n \ge 2 \end{cases}$$

$$\Rightarrow C(n) = 2n |\lg(n)| + 2n - 4 \cdot 2^{\lfloor \lg(n) \rfloor}$$

$$C(n) = 2n \lfloor \lg(n) \rfloor + 2n - 4 \cdot 2^{\lfloor \lg(n) \rfloor}$$

= $\Theta(n \log n)$

Back-of-the-envelope analysis

- before working out the details of a D&C idea, it is often useful to get a quick indication of the resulting performance
 - don't want to waste time on something that's not competitive in the end anyways!
- ► since D&C is naturally recursive, running time often not obvious instead: given by a recursive equation
- unfortunately, rigorous analysis often tricky
 - ► Remember mergesort?

▶ the following method works for many typical cases to give the right **order of growth**

The Master Method

Mersesort a=2

► Assume a stereotypical D&C algorithm

6 = 2

▶ *a* recursive calls on (for some constant $a \ge 1$)

f(u) = Zn

- subproblems of size n/b (for some constant b > 1)
- ▶ with non-recursive "conquer" effort f(n) (for some function $f : \mathbb{R} \to \mathbb{R}$)
- ▶ base case effort d (some constant d > 0)

ben care
$$\left(n=1 \implies d=0\right)$$

$$n=2 \implies d=2$$

The Master Method

- ► Assume a stereotypical D&C algorithm
 - ▶ *a* recursive calls on (for some constant $a \ge 1$)
 - subproblems of size n/b (for some constant b > 1)
 - ▶ with non-recursive "conquer" effort f(n) (for some function $f : \mathbb{R} \to \mathbb{R}$)
 - ▶ base case effort *d* (some constant d > 0)

The Master Method

- ► Assume a stereotypical D&C algorithm
 - ightharpoonup a recursive calls on (for some constant $a \ge 1$)
 - subproblems of size n/b (for some constant b > 1)
 - ▶ with non-recursive "conquer" effort f(n) (for some function $f : \mathbb{R} \to \mathbb{R}$)
 - base case effort d (some constant d > 0)

$$ightharpoonup \text{running time } T(n) \text{ satisfies}$$

$$T(n) = \begin{cases} a \cdot T\left(\frac{n}{b}\right) + f(n) & n > 1 \\ d & n \leq 1 \end{cases}$$

Theorem 5.1 (Master Theorem)

With $c := \log_h(a)$, we have for the above recurrence:

(a)
$$T(n) = \Theta(n^c)$$
 if $f(n) = O(n^{c-\varepsilon})$ for constant $\varepsilon > 0$.

(b)
$$T(n) = \Theta(n^c \log n)$$
 if $f(n) = \Theta(n^c)$.

(c)
$$T(n) = \Theta(f(n))$$
 if $f(n) = \Omega(n^{c+\varepsilon})$ for constant $\varepsilon > 0$ and f satisfies the regularity condition $\exists n_0, \alpha < 1 \ \forall n \ge n_0 : a \cdot f\left(\frac{n}{b}\right) \le \alpha f(n)$.

$$= a \left(aT \left(\frac{n}{b^2} \right) + f(\frac{n}{b}) \right) + f(n)$$

$$= a^2 \cdot T \left(\frac{n}{b^2} \right) + f(n) + a f(\frac{n}{b})$$

$$= a^3 \cdot T \left(\frac{n}{b^3} \right) + f(n) + a f(\frac{n}{b}) + a^2 \cdot f(\frac{n}{b^2})$$

$$= a^3 \cdot T \left(\frac{n}{b^3} \right) + f(n) + a \cdot f(\frac{n}{b}) + a^2 \cdot f(\frac{n}{b^2})$$

$$\vdots$$

$$= a^3 \cdot T \left(\frac{n}{b^3} \right) + f(n) + a \cdot f(\frac{n}{b}) + a^2 \cdot f(\frac{n}{b^2})$$

$$\vdots$$

$$= a^3 \cdot T \left(\frac{n}{b^3} \right) + f(n) + a \cdot f(\frac{n}{b}) + a^2 \cdot f(\frac{n}{b^2})$$

 $= \underbrace{a_{095}(n)}_{i=0} + \underbrace{a_{095}(n)}_{i=0} = \underbrace{a_{i}^{i} f(\frac{a}{5i})}_{i=0}$

elna en(n)

= lossias

 $T(u) = aT(\frac{u}{b}) + f(u)$

Case 1: terms with

i near losp(n) dominate

Master Theorem - Intuition & Proof Idea

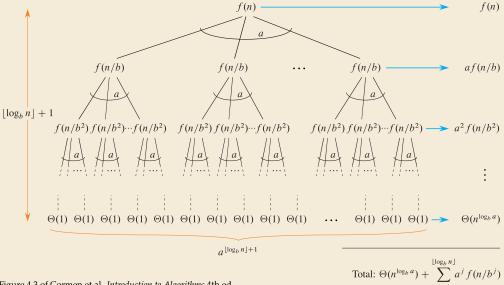


Figure 4.3 of Cormen et al. Introduction to Algorithms 4th ed.

$$f(u) = 2n$$

$$c = \log_{10}(a) = 1$$

$$f(u) \quad vs: \quad n^{c}$$

a= 6=2

 $T(a) = 2n + 2T(\frac{a}{2})$

$$2n = \Theta(n')$$

$$\Rightarrow Case 2 applies$$

$$T(n) = \Theta(f(n) \cdot los n)$$

$$= \Theta(n los n)$$

When it's fine to ignore floors and ceilings

The polynomial-growth condition

▶ $f: \mathbb{R}_{>0} \to \mathbb{R}$ satisfies the *polynomial-growth condition* if

$$\exists n_0 \ \forall C \geq 1 \ \exists D > 1 \quad \forall n \geq n_0 \ \forall c \in [1,C] \ : \ \frac{1}{D} f(n) \leq f(cn) \leq D f(n)$$

When it's fine to ignore floors and ceilings

The polynomial-growth condition

▶ $f: \mathbb{R}_{>0} \to \mathbb{R}$ satisfies the *polynomial-growth condition* if

$$\exists n_0 \ \forall C \geq 1 \ \exists D > 1 \quad \forall n \geq n_0 \ \forall c \in [1,C] \ : \ \frac{1}{D} f(n) \leq f(cn) \leq D f(n)$$

- ▶ intuitively: increasing n by up to a factor C (and anywhere in between!) changes the function value by at most a factor D = D(C) (for sufficiently large n) zero allowed
- examples: $f(n) = \Theta(n^{\alpha} \log^{\beta}(n) \log \log^{\gamma}(n))$ for constants α , β , γ \rightarrow f satisfies the polynomial-growth condition

When it's fine to ignore floors and ceilings

The polynomial-growth condition

▶ $f: \mathbb{R}_{>0} \to \mathbb{R}$ satisfies the *polynomial-growth condition* if

$$\exists n_0 \ \forall C \ge 1 \ \exists D > 1 \quad \forall n \ge n_0 \ \forall c \in [1, C] : \frac{1}{D} f(n) \le f(cn) \le D f(n)$$

- intuitively: increasing n by up to a factor C (and anywhere in between!) changes the function value by at most a factor D = D(C) (for sufficiently large n) zero allowed
- examples: $f(n) = \Theta(n^{\alpha} \log^{\beta}(n) \log \log^{\gamma}(n))$ for constants α , β , γ \rightarrow f satisfies the polynomial-growth condition

Lemma 5.2 (Polynomial-growth master method)

If the toll function f(n) satisfies the polynomial-growth condition, then the Θ -class of the solution of a D&C recurrence remains the same when ignoring floors and ceilings on subproblem sizes.

A Rigorous and Stronger Meta Theorem

& exam

Theorem 5.3 (Roura's Discrete Master Theorem)

Let T(n) be recursively defined as

$$T(n) = \begin{cases} b_n & 0 \le n < n_0, \\ f(n) + \sum_{d=1}^{D} a_d \cdot T\left(\frac{n}{b_d} + r_{n,d}\right) & n \ge n_0, \end{cases}$$

where $D \in \mathbb{N}$, $a_d > 0$, $b_d > 1$, for $d = 1, \ldots, D$ are constants, functions $r_{n,d}$ satisfy $|r_{n,d}| = O(1)$ as $n \to \infty$, and function f(n) satisfies $\underline{f(n) \sim B \cdot n^{\alpha} (\ln n)^{\gamma}}$ for constants B > 0, α , γ . Set $H = 1 - \sum_{d=1}^{D} a_d (1/b_d)^{\alpha}$; then we have:

- (a) If H < 0, then $T(n) = O(n^{\tilde{\alpha}})$, for $\tilde{\alpha}$ the unique value of α that would make H = 0.
- **(b)** If H = 0 and $\gamma > -1$, then $T(n) \sim f(n) \ln(n)/\tilde{H}$ with constant $\tilde{H} = (\gamma + 1) \sum_{d=1}^{D} a_d b_d^{-\alpha} \ln(b_d)$.
- (c) If H=0 and $\gamma=-1$, then $T(n)\sim f(n)\ln(n)\ln(\ln(n))/\hat{H}$ with constant $\hat{H}=\sum_{d=1}^D a_d \ b_d^{-\alpha}\ln(b_d)$.
- (d) If H = 0 and $\gamma < -1$, then $T(n) = O(n^{\alpha})$.
- (e) If H > 0, then $T(n) \sim f(n)/H$.

5.2 Order Statistics

Selection by Rank

► Standard data summary of numerical data: (Data scientists, listen up!)

▶ mean, standard deviation

► min/max (range)

histograms

median, quartiles, other quantiles (a.k.a. order statistics)

easy to compute in $\Theta(n)$ time

? computable in $\Theta(n)$ time?

Selection by Rank

- ► Standard data summary of numerical data: (Data scientists, listen up!)
 - ► mean, standard deviation
 - ► min/max (range)
 - histograms
 - median, quartiles, other quantiles (a.k.a. order statistics)

easy to compute in $\Theta(n)$ time

? computable in $\Theta(n)$ time?

General form of problem: Selection by Rank

▶ **Given:** array A[0..n) of numbers and number $k \in [0..n)$.

but 0-based & /counting dups

- ▶ **Goal:** find element that would be in position k if A was sorted (kth smallest element).
- ▶ $k = \lfloor n/2 \rfloor$ \leadsto median; $k = \lfloor n/4 \rfloor$ \leadsto lower quartile k = 0 \leadsto minimum; $k = n \ell$ \leadsto ℓ th largest

Quickselect

- ► Key observation: Finding the element of rank *k* seems hard. But computing the rank of a given element is easy!
- \rightarrow Pick any element A[b] and find its rank j.
 - ▶ j = k? \rightarrow Lucky Duck! Return chosen element and stop
 - ▶ j < k? \longrightarrow ... not done yet. But: The j + 1 elements smaller than $\leq A[b]$ can be excluded!
 - ▶ j > k? \rightsquigarrow similarly exclude the n j elements $\geq A[b]$

Quickselect

- ► Key observation: Finding the element of rank *k* seems hard.

 But computing the rank of a given element is easy!
- \rightsquigarrow Pick any element A[b] and find its rank j.

```
▶ j = k? \rightarrow Lucky Duck! Return chosen element and stop
```

- ▶ j < k? \longrightarrow ... not done yet. But: The j + 1 elements smaller than $\leq A[b]$ can be excluded!
- ▶ j > k? \rightarrow similarly exclude the n j elements $\geq A[b]$
- ▶ partition function from Quicksort:
 - returns the rank of pivot
 - ► separates elements into smaller/larger

```
procedure quickselect(A[l..r), k)

if r - l \le 1 then return A[l]

b := \text{choosePivot}(A[l..r))

j := \text{partition}(A[l..r), b)

if j == k

return A[j]

else if j < k

quickselect(A[j + 1..n), k

else l

l

quickselect(A[0..j), k)
```

Quickselect – Iterative Code

Recursion can be replaced by loop (tail-recursion elimination)

```
procedure quickselect(A[1..r), k)
           if r - \ell \le 1 then return A[l]
2
           b := \text{choosePivot}(A[l..r))
3
           j := partition(A[1..r), b)
           if i == k
5
                return A[i]
           else if j < k
7
                quickselect(A[j+1..n), k AND A
8
           else //i > k
                quickselect(A[0..i), k)
10
```

```
procedure quickselectIterative(A[0..n), k)

l := 0; r := n

while r - l > 1

b := \text{choosePivot}(A[l..r))

j := \text{partition}(A[l..r), b)

if j \ge k then r := j - 1

return A[k]
```

- ▶ implementations should usually prefer iterative version
- ▶ analysis more intuitive with recursive version

Quickselect – Analysis

```
1 procedure quickselect(A[l..r), k)

2 if r - \ell \le 1 then return A[l]

3 b := \text{choosePivot}(A[l..r))

4 j := \text{partition}(A[l..r), b)

5 if j := k

6 return A[j]

7 else if j < k

8 quickselect(A[j+1..n), A-j-1)

9 else //j > k

10 quickselect(A[0..j), A)
```

- ► cost = #cmps
- ightharpoonup costs depend on n and k

Quickselect – Analysis

```
\begin{array}{ll} & \textbf{procedure} \ \text{quickselect}(A[l..r),k) \\ & \textbf{if} \ r-\ell \leq 1 \ \textbf{then} \ \textbf{return} \ A[l] \\ & \textbf{3} \qquad b := \text{choosePivot}(A[l..r)) \\ & \textbf{4} \qquad j := \text{partition}(A[l..r),b) \\ & \textbf{5} \qquad \textbf{if} \ j = k \\ & \qquad \qquad \textbf{return} \ A[j] \\ & \textbf{7} \qquad \textbf{else} \ \textbf{if} \ j < k \\ & \textbf{8} \qquad \qquad \text{quickselect}(A[j+1..n),k-j-1) \\ & \textbf{9} \qquad \textbf{else} \ / j > k \\ & \text{quickselect}(A[0..j),k) \end{array}
```

- ightharpoonup cost = #cmps
- ightharpoonup costs depend on n and k
- ▶ worst case: k = 0, but always j = n 2 \Rightarrow each recursive call makes n one smaller at cost $\Theta(n)$
 - \rightarrow $T(n, k) = \Theta(n^2)$ worst case cost

Quickselect – Analysis

```
1 procedure quickselect(A[1..r), k)
       if r - \ell \le 1 then return A[t]
      b := \text{choosePivot}(A[l..r))
      j := partition(A[1..r), b)
      if i == k
           return A[i]
      else if i < k
           quickselect(A[i+1..n), k-i-1)
      else //i > k
           quickselect(A[0..i), k)
10
```

- \triangleright cost = #cmps
- costs depend on n and k
- ▶ worst case: k = 0, but always j = n 2
 - \rightarrow each recursive call makes *n* one smaller at cost $\Theta(n)$
 - \rightarrow $T(n,k) = \Theta(n^2)$ worst case cost

average case:

- \blacktriangleright let T(n,k) expected cost when we choose a pivot uniformly from A[0..n)
- \rightarrow formulate recurrence for T(n, k) similar to BST/Quicksort recurrence

formulate recurrence for
$$T(n,k)$$
 similar to BST/Quicksort recurrence
$$T(n,k) = \underbrace{n}_{r=0} + \frac{1}{n} \sum_{r=0}^{n-1} [r=k] \cdot 0 + [k < r] \cdot T(r,k) + [k > r] \cdot T(n-r-1,k-r-1)$$

Pr [pivol rank r]

$$T(n,k) = n + \frac{1}{n} \sum_{r=0}^{n-1} [r=k] \cdot 0 + [k < r] \cdot T(r,k) + [k > r] \cdot T(n-r-1,k-r-1)$$

$$\blacktriangleright \operatorname{Set} \hat{T}(\underline{n}) = \max_{k \in [0..n]} T(n, k)$$

$$T(n,k) = n + \frac{1}{n} \sum_{r=0}^{n-1} \underbrace{[r=k] \cdot 0}_{r=0} + \underbrace{[k < r] \cdot \underline{T(r,k)}}_{r=0} + \underbrace{[k > r] \cdot \underline{T(n-r-1,k-r-1)}}_{r=0}$$

$$\Rightarrow \text{Set } \hat{T}(n) = \max_{k \in [0..n)} T(n,k)$$

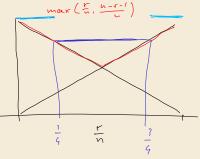
$$\leqslant \max_{k \in [0..n]} \underbrace{\hat{T}(r,k)}_{r=0} \underbrace{\hat{T}(r,k)}_{$$

$$T(n,k) = n + \frac{1}{n} \sum_{r=0}^{n-1} [r=k] \cdot 0 + [k < r] \cdot T(r,k) + [k > r] \cdot T(n-r-1,k-r-1)$$

$$\blacktriangleright \operatorname{Set} \hat{T}(n) = \max_{k \in [0..n)} T(n, k)$$

$$\rightarrow \hat{T}(n) \le n + \frac{1}{n} \sum_{r=0}^{n-1} \max{\{\hat{T}(r), \hat{T}(n-r-1)\}}$$

▶ analyze hypothetical, worse algorithm: if $r \notin [\frac{1}{4}n, \frac{3}{4}n)$, discard pivot and repeat with new one!



$$\rightarrow$$
 $\hat{T}(n) \leq \tilde{T}(n)$ defined by $\tilde{T}(n) \leq n + \frac{1}{2}\tilde{T}(n) + \frac{1}{2}\tilde{T}(\frac{3}{4}n)$

$$T(n,k) = n + \frac{1}{n} \sum_{r=0}^{n-1} [r=k] \cdot 0 + [k < r] \cdot T(r,k) + [k > r] \cdot T(n-r-1,k-r-1)$$

 $\blacktriangleright \operatorname{Set} \hat{T}(n) = \max_{k \in [0..n)} T(n, k)$

$$\rightarrow \hat{T}(n) \le n + \frac{1}{n} \sum_{r=0}^{n-1} \max{\{\hat{T}(r), \hat{T}(n-r-1)\}}$$

▶ analyze hypothetical, worse algorithm: if $r \notin [\frac{1}{4}n, \frac{3}{4}n)$, discard pivot and repeat with new one!

$$T(n,k) = n + \frac{1}{n} \sum_{r=0}^{n-1} [r=k] \cdot 0 + [k < r] \cdot T(r,k) + [k > r] \cdot T(n-r-1,k-r-1)$$

 $\blacktriangleright \operatorname{Set} \hat{T}(n) = \max_{k \in [0..n)} T(n, k)$

$$\rightarrow \hat{T}(n) \le n + \frac{1}{n} \sum_{r=0}^{n-1} \max{\{\hat{T}(r), \hat{T}(n-r-1)\}}$$

▶ analyze hypothetical, worse algorithm: if $r \notin [\frac{1}{4}n, \frac{3}{4}n)$, discard pivot and repeat with new one!

$$ightharpoonup ilde{T}(n) \leq ilde{T}(n) \text{ defined by } ilde{T}(n) \leq n + \frac{1}{2} ilde{T}(n) + \frac{1}{2} ilde{T}(\frac{3}{4}n)$$

 $ightharpoonup ilde{T}(n) \leq 2n + ilde{T}(\frac{3}{4}n)$

► Master Theorem Case 3: $\tilde{T}(n) = \Theta(n)$

Quickselect Discussion

- \bigcap $\Theta(n^2)$ worst case (like Quicksort)
- no extra space needed
- adaptations possible to find several order statistics at once

Quickselect Discussion

- \bigcap $\Theta(n^2)$ worst case (like Quicksort)
- expected $cost \Theta(n)$ (best possible)
- no extra space needed
- adaptations possible to find several order statistics at once
- expected cost can be further improved by choosing pivot from a small sorted sample
 - \rightarrow asymptotically optimal randomized cost: $n + \min\{k, n k\}$ comparisons in expectation achieved asymptotically by the *Floyd-Rivest algorithm*