



ALGORITHMS OF BIOINFORMATICS

3

Comparing Sequences

13 November 2025

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Outline

3 Comparing Sequences

- 3.1 Sequence Alignment
- 3.2 Dynamic Programming
- 3.3 Global – Local – Semilocal
- 3.4 General Scores & Affine Gap Costs
- 3.5 Bounded-Distance Alignments
- 3.6 Exhaustive Tabulation
- 3.7 Linear-Space Alignments
- 3.8 Multiple Sequence Alignment

3.1 Sequence Alignment

Sequence Similarity

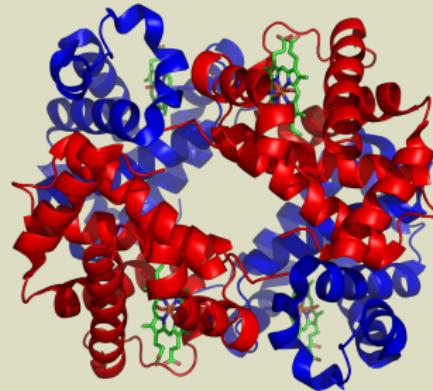
Example: two proteins from *human hemoglobin*

Human Hemoglobin α globin subunit <https://www.uniprot.org/uniprotkb/P69905>

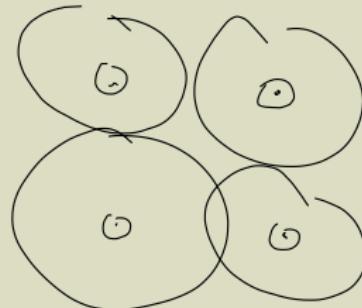
Human Hemoglobin β globin subunit <https://www.uniprot.org/uniprotkb/P68871>

~ essentially symmetric copies with same function

3D Structure of hemoglobin



https://commons.wikimedia.org/wiki/File:1GZX_Haemoglobin.png



Sequence Similarity

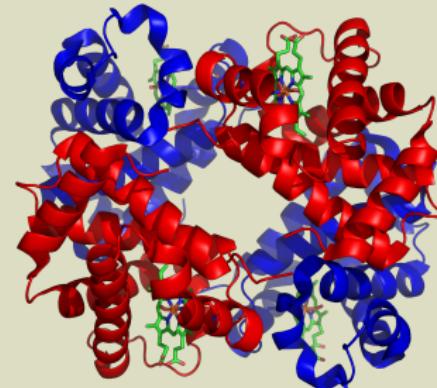
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Sequences of the subunits (142 resp. 147 amino acids):

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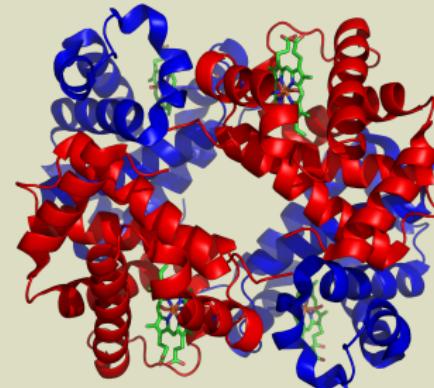
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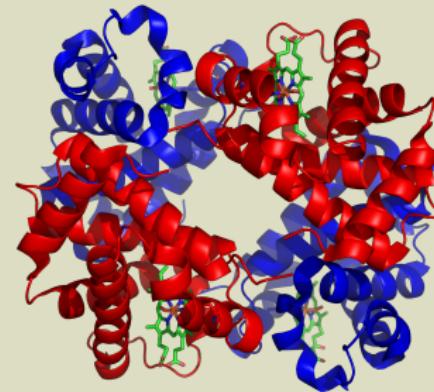
Alignment by EMBOSS Needle <https://www.ebi.ac.uk/jdispatcher/psa>

MV-LSPADKTNVKAAGKVGGAHAGEYGAEALERMFLSFPTTKTYFPFH-DLS-----HGSAQVKHGKKVADALTNAVAHVDDMPNALSALSDLHAHKLRVPVNFKLLSHCLLVTAAHLPAEFTPASLDKFLASVSTVLTSKYR
|| | :| :| | | ||| : | | ||| : :| :| :| | ||| : | :|| | ||| | :: :||:| :| :| ||| | :| :| | ||| | :| | :| | |||
MVHLTPEEKSAVTALWGKV--NVDEVGGEALGRLLVVYPWTQRFFESFGDLSTPDAVMGNPKVKAHGKKVLGAFSDGLAHDNLKGTFATLSELHCDKLHVDPENFRLLGNVLVCVLAHHFGKEFTPPVQAAYQKVAGVANALAHKYH

| = same amino acid (65x); : = similar amino acids (25x)

~~ 60% same

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String Distances

Mutations mean much in bioinformatics needs fuzzy comparisons . . .

How can we formally define these?

- ▶ This unit studies wide class of options
- ▶ Algorithmically, all are similar to deal with
- ▶ Unfortunately, general case again hard . . .

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- ▶ How about strings like this:

$A = \text{alongsharedstring}$
 $B = \cancel{\text{longshared}}\text{edstrings}$ $\rightsquigarrow d_H(A, B) = |A| = 17$ These are maximally different!?

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 - ▶ How about strings like this:

$A = \text{alongsharedstring}$ $\rightsquigarrow d_H(A, B) = |A| = 17$ *These are maximally different!?*
 $B = \text{longsharedstrings}$

\rightsquigarrow Need a more flexible notion . . .

Edit Distance

Natural idea for distances: describe how to get from A to B \rightsquigarrow relative compression!

$A[0..17) = \cancel{A}$ longsharedstrings

$B[0..17) = \text{longsharedstrings}$

“Edit script”:

0. Start with \cancel{A}_1 .
1. Delete $\cancel{B}_1[0]$
2. Insert s at end of \cancel{B}_1 .

\rightsquigarrow 2 character operations needed $\rightsquigarrow d_{\text{edit}}(A, B) = 2$

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Natural idea for distances: describe **how** to get from A to B \rightsquigarrow *relative compression!*

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Edit Distance Problem

- **Given:** String $\underbrace{A[0..m]}$ and $\underbrace{B[0..n]}$ over alphabet $\Sigma = [0..\sigma]$.
- **Goal:** $d_{\text{edit}}(A, B) =$ minimal # symbol operations to transform A into B
operations can be insertion/deletion/substitution of single character
+ optimal edit script (with this number of operations)

Edit Distance Example

Example: edit distance $d_{\text{edit}}(A, B)$ with $A = \text{algorithm}$, $B = \text{logarithm}$?

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012345678
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Compact representation of edit script: *String alignment*

```
0123456789  
al-gorithm  
-|+|x|||||  
-logarithm
```

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- + x
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Formally: string over pairs of letters or *gap symbols*

$$\left\{ \begin{bmatrix} c \\ c \end{bmatrix} : c \in \Sigma \right\} \cup \left\{ \begin{bmatrix} c \\ - \end{bmatrix}, \begin{bmatrix} - \\ c \end{bmatrix} : c \in \Sigma \right\} \cup \left\{ \begin{bmatrix} c \\ c' \end{bmatrix} : c, c' \in \Sigma, c \neq c' \right\}$$

~ Edit distance = # $\begin{bmatrix} c \\ - \end{bmatrix}$, $\begin{bmatrix} - \\ c \end{bmatrix}$, $\begin{bmatrix} c \\ c' \end{bmatrix}$ with $c \neq c'$

Edit Distance and Longest Common Subsequence

- ▶ Note: close relation to *longest common subsequence*

Optimal edit script \approx maximal number of matches = longest common subsequence

Edit Distance and Longest Common Subsequence

- ▶ Note: close relation to *longest common subsequence*
Optimal edit script \approx maximal number of matches = longest common subsequence
- ▶ But: Optimal alignment may not contain any longest common subsequence

axxa	axxa	axxa			
a	ayya	ayya	ayy		

- axxaaxxaaxxa
| s | | s | | s | 8
aayyaayyaayy -

- ▶ LCS and edit distance are equivalent if we only allow insert and delete operations

3.2 Dynamic Programming

Recap: The 6 Steps of Dynamic Programming

1. Define **subproblems** (and relate to original problem)
2. **Guess** (part of solution) \rightsquigarrow local brute force
3. Set up **DP recurrence** (for quality of solution)
4. Recursive implementation with **Memoization**
5. Bottom-up **table filling** (topological sort of subproblem dependency graph)
6. **Backtracing** to reconstruct optimal solution

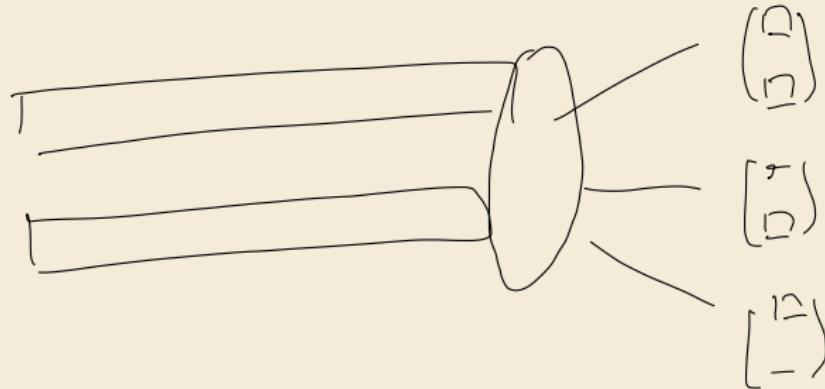
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- Steps 1–3 require insight / creativity / intuition;
Steps 4–6 are mostly automatic / same each time
- \rightsquigarrow Correctness proof usually at level of DP recurrence
-  running time too! worst case time = #subproblems · time to find single best guess

Edit Distance by DP

original $i = m, j = n$

1. Subproblems: (i, j) for $0 \leq i \leq m, 0 \leq j \leq m$ compute $d_{\text{edit}}(A[0..i], B[0..j])$
2. Guess: What to do with last positions? (insert/delete/(mis)match)



Edit Distance by DP

1. **Subproblems:** (i, j) for $0 \leq i \leq m, 0 \leq j \leq m$ compute $d_{\text{edit}}(A[0..i], B[0..j])$
2. **Guess:** What to do with last positions? (insert/delete/(mis)match)
3. **Recurrence:** $D(i, j) = d_{\text{edit}}(A[0..i], B[0..j])$

$$D(i, j) = \begin{cases} i & // i: \text{deletions} & \text{if } j = 0 \\ j & // j: \text{insertions} & \text{if } i = 0 \\ \min \begin{cases} D(i-1, j) + 1, & \xrightarrow{\text{del}} \square \\ D(i, j-1) + 1, & \xrightarrow{\text{ins}} \\ D(i-1, j-1) + [A[i-1] \neq B[j-1]] & \xrightarrow{\text{if}} \\ & \text{inversen bracket} & \begin{cases} 1 & \text{and true} \\ 0 & \text{else} \end{cases} \end{cases} & \text{otherwise} \end{cases}$$

Edit Distance by DP

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$\rightsquigarrow O(nm)$ subproblems

- ▶ $O(1)$ time to check all guesses (per subproblem)

$\rightsquigarrow O(nm)$ overall time and space

- ▶ An optimal *edit script* can be constructed by a *backtrace* (see below)

Edit Distance – Step 4: Memoization

- ▶ Write **recursive** function to compute recurrence
- ▶ But *memoize* all results! (symbol table: subproblem \mapsto optimal cost)
 - ~~ First action of function: check if subproblem known
 - ▶ If so, return cached optimal cost
 - ▶ Otherwise, compute optimal cost and remember it!

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```
1 procedure editDist(i, j):
2     if i == 0
3         return j
4     else if j == 0
5         return i
6     end if
7     best := +∞
8      $D_i := \text{cachedED}(i, j - 1) + 1$ 
9      $D_d := \text{cachedED}(i - 1, j) + 1$ 
10     $D_m := \text{cachedED}(i - 1, j - 1) + [A[i] \neq B[j]]$ 
11    best := min{ $D_d, D_i, D_m$ }
12    return best
```

$$D(i, j) = \begin{cases} i & \text{if } j = 0 \\ j & \text{if } i = 0 \\ \min \begin{cases} D(i, j - 1) + 1, \\ D(i - 1, j) + 1, \\ D(i - 1, j - 1) + [A[i - 1] \neq B[j - 1]] \end{cases} & \text{otherwise} \end{cases}$$

```
13 procedure cachedED(r[i..j], c[i..j]):
14     //  $D[0..m][0..n]$  initialized to NULL at start
15     if  $D[i][j] == \text{NULL}$ 
16          $D[i][j] := \text{editDist}(i, j)$ 
17     return  $D[i][j]$ 
```

Edit Distance – Step 5: Table Filling

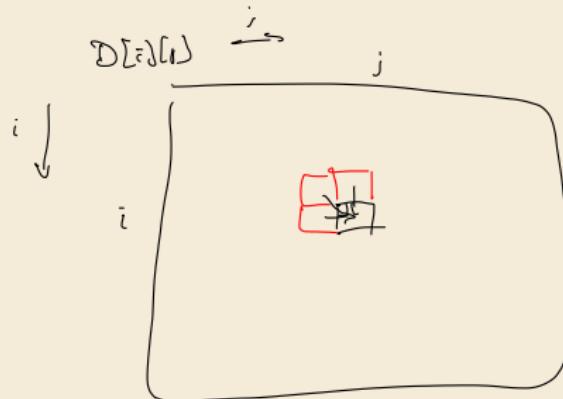
- ▶ Recurrence induces a DAG on subproblems (who calls whom)
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 - ▶ We can slightly improve performance by systematically computing subproblems following a fixed topological order

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```
1 procedure editDist(A[0..m], B[0..n]):  
2     D[0..m][0..n] := ∞ // initialize to ∞  
3     for i = 0, 1, ..., m // iterate over subproblems ...  
4         for j = 0, 1, ..., n // ... in topological order  
5             if i == 0  
6                 D[i][j] := j  
7             else if j == 0  
8                 D[i][j] := i  
9             else  
10                D[i][j] := min {  
11                    D[i][j - 1] + 1,  
12                    D[i - 1][j] + 1,  
13                    D[i - 1][j - 1] + [A[i - 1] ≠ B[j - 1]]}  
14    return D[m][n]
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- 1 Subproblems
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- 3 DP Recurrence
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- ▶ Same Θ -class as memoized recursive function
- ▶ In practice usually substantially faster
 - ▶ lower overhead
 - ▶ predictable memory accesses

Edit Distance – Step 6: Backtracing

- ▶ So far, only determine the **cost** of an optimal solution
 - ▶ But we also want the solution itself
- ▶ By *retracing* our steps, we can construct optimal edit script

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```
1 procedure editScript( $A[0..m]$ ,  $B[0..n]$ ):  
2      $D[0..m][0..n] := \text{editDist}(A[0..m], B[0..n])$   
3     return traceback( $m, n$ )  
4  
5 procedure traceback( $i, j$ ):  
6     if  $i == 0$   
7         return Insert( $B[0]$ ), ..., Insert( $B[j - 1]$ )  
8     else if  $j == 0$   
9         return Delete( $A[0]$ ), ..., Delete( $A[i - 1]$ )  
10    else if  $D[i][j] == D[i][j - 1] + 1$   
11        return traceback( $i, j - 1$ ), Insert( $B[j - 1]$ )  
12    else if  $D[i][j] == D[i - 1][j] + 1$   
13        return traceback( $i - 1, j$ ), Delete( $B[i - 1]$ )  
14    else if  $A[i - 1] == B[j - 1]$   
15        return traceback( $i - 1, j - 1$ )  
16    else return traceback( $i - 1, j - 1$ ), Replace( $A[i - 1] \rightarrow B[j - 1]$ )
```

- 1. Subproblems
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- ▶ follow recurrence a second time

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- 1. Subproblems
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- ▶ follow recurrence a second time
- ▶ always have for running time:
backtracing = $\mathcal{O}(\text{computing } M)$
- ~~ computing optimal cost and
computing optimal solution have
same complexity

3.3 Global – Local – Semilocal

Local Alignment

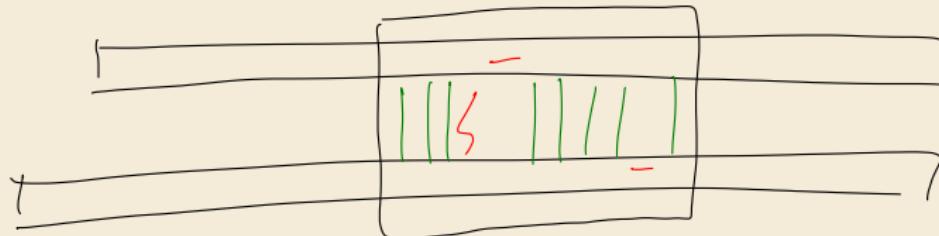
So far, we assumed that we know similar regions.

How to detect significantly similar regions hidden in larger strings?

~~ Allow new edit script operations (all cost 0):

- ▶ $\text{IgnorePrefix}(A[0..i])$ free deletes at beginning
- ▶ $\text{IgnorePrefix}(B[0..j])$ free inserts at beginning
- ▶ $\text{IgnoreSuffix}(A[i..m])$ free deletes at end
- ▶ $\text{IgnoreSuffix}(B[j..n])$ free inserts at end

~~ Local Alignment



Local Alignment

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~ Allow new edit script operations (all cost 0):

- ▶ IgnorePrefix($A[0..i)$) free deletes at beginning
- ▶ IgnorePrefix($B[0..j)$) free inserts at beginning
- ▶ IgnoreSuffix($A[i..m)$) free deletes at end
- ▶ IgnoreSuffix($B[j..n)$) free inserts at end

~ Local Alignment

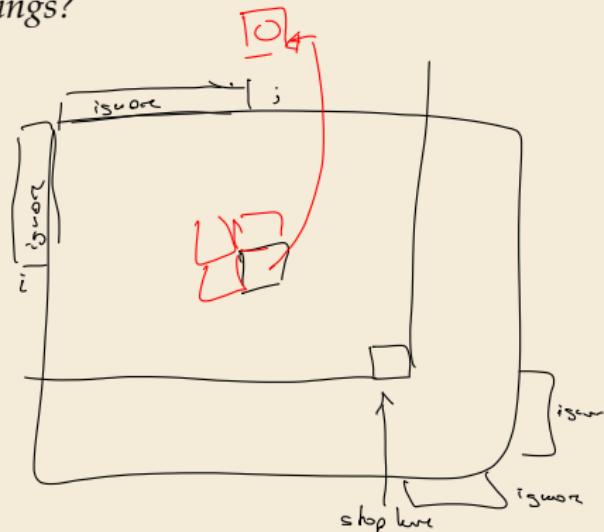
▶ Easy to incorporate in DP recurrence:

0. switch to **maximizing score** (instead min difference), otherwise empty substring is best

~ Matches contribute +1 reward, rest penalty (negative score)

1. Always allow 4th option: **start a new local alignment from here** (at score 0)

2. Allow to finish at any $D[i][j]$ ~ free suffix



Local Alignment Recurrence

$$D(i, j) = \begin{cases} \begin{matrix} \textcolor{red}{0} \\ \textcolor{red}{0} \end{matrix} & \text{if } j = 0 \\ & \text{if } i = 0 \\ \min \left\{ \begin{matrix} \textcolor{red}{0}, \\ D(i - 1, j) - 1, \\ D(i, j - 1) - 1, \\ D(i - 1, j - 1) + [A[i - 1] = B[j - 1]] \\ \quad - [A[i - 1] \neq B[j - 1]] \end{matrix} \right\} & \text{otherwise} \end{cases}$$

Optimal local alignment score: $\max_{i \in [0..m], j \in [0..n]} D[i][j]$

Semilocal Alignment a.k.a. Fitting Alignment

Slight twist: We know conserved region, but need to find best match in larger sequence.

What substring of $B[0..n]$ is the best match for $A[0..m]$? (typically then $m \ll n$)

Semilocal Alignment a.k.a. Fitting Alignment

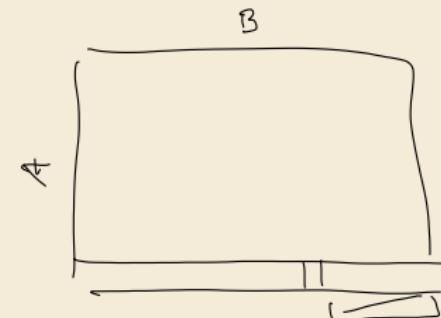
Slight twist: We know conserved region, but need to find best match in larger sequence.

What substring of $B[0..n]$ is the best match for $A[0..m]$? (typically then $m \ll n$)

↪ only allow IgnorePrefix($B[0..j]$) and IgnoreSuffix($B[j..n]$)

$$\hookrightarrow D(i, j) = \begin{cases} -i & \text{if } j = 0 \\ \mathbf{0} & \text{if } i = 0 \\ \min \begin{cases} D(i - 1, j) - 1, \\ D(i, j - 1) - 1, \\ D(i - 1, j - 1) + [A[i - 1] = B[j - 1]] \end{cases} & \text{otherwise} \end{cases}$$

Optimal local alignment score: $\max_{j \in [0..n]} D[m][j]$



3.4 General Scores & Affine Gap Costs

General Scores

DP algorithm remains unchanged if we let contribution of (mis)match $A[i - 1]$ vs $B[j - 1]$ depend on used letters.

- ▶ For example, replacing amino acid with chemically similar one might not affect function
 - ~~ contributes small positive score
- ▶ replacing amino acid with dissimilar one ~~ negative score

General Scores

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- ▶ replacing amino acid with dissimilar one ~~ negative score

Formally, any function giving additive scores for columns $S : (\Sigma \cup \{-\})^2 \setminus \{[\underline{\underline{\cdot}}]\} \rightarrow \mathbb{R}$ works.

General Alignment Score S :

- ▶ symmetric matches/substitutions matrix $p : \Sigma \times \Sigma \rightarrow \mathbb{R}$ ($p(a, b) = p(b, a)$)
- ▶ gap penalty $g \in \mathbb{R}$
 - ~~ $S([\underline{c}]) = p(a, b)$, $S([\underline{\underline{c}}]) = S([\underline{\underline{c}}]) = g$
 - ~~ score of alignment sum of scores of columns

BLOSUM Matrices

C	S	T	A	G	P	D	E	Q	N	H	R	K	M	I	L	V	W	Y	F
C	9																		
S	-1	4																	
T	-1	1	5																
A	0	1	0	4															
G	-3	0	-2	0	6														
P	-3	-1	-1	-1	-2	7													
D	-3	0	-1	-2	-1	-1	6												
E	-4	0	-1	-1	-2	-1	2	5											
Q	-3	0	-1	-1	-2	-1	0	2	5										
N	-3	1	0	-2	0	-2	1	0	0	6									
H	-3	-1	-2	-2	-2	-2	-1	0	0	1	8								
R	-3	-1	-1	-1	-2	-2	-2	0	1	0	0	5							
K	-3	0	-1	-1	-2	-1	-1	1	1	0	-1	2	5						
M	-1	-1	-1	-1	-3	-2	-3	-2	0	-2	-2	-1	-1	5					
I	-1	-2	-1	-1	-4	-3	-3	-3	-3	-3	-3	-3	-3	1	4				
L	-1	-2	-1	-1	-4	-3	-4	-3	-2	-3	-3	-2	-2	2	2	4			
V	-1	-2	0	0	-3	-2	-3	-2	-2	-3	-3	-2	-2	1	3	1	4		
W	-2	-3	-2	-3	-2	-4	-4	-3	-2	-4	-2	-3	-3	-1	-3	-2	-3	11	
Y	-2	-2	-2	-2	-3	-3	-3	-2	-1	-2	2	-2	-2	-1	-1	-1	-1	2	7
F	-2	-2	-2	-2	-3	-4	-3	-3	-3	-3	-1	-3	-3	0	0	0	-1	1	3
C	S	T	A	G	P	D	E	Q	N	H	R	K	M	I	L	V	W	Y	F

<https://en.wikipedia.org/wiki/BLOSUM#/media/File:Blosum62-dayhoff-ordering.svg>

Affine Gap costs

In sequence evolution, insertions of single stretch of k characters much more likely than k isolated (single-character) insertions

So far, we score these the same.

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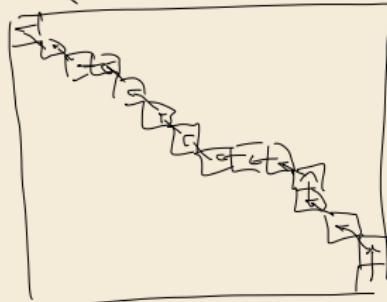
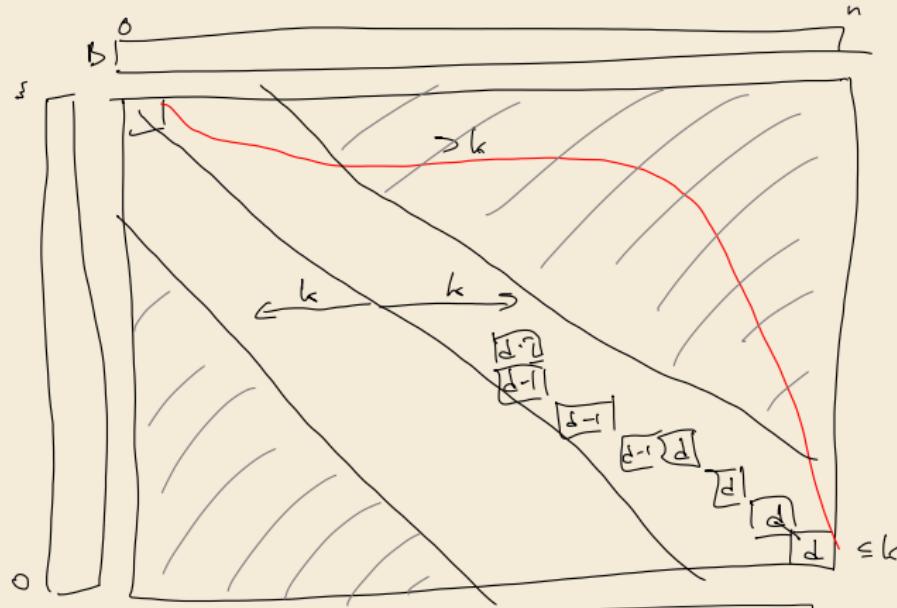
~> *affine gap costs:*

score k contiguous insertions (or k contiguous deletions) instead as $\underline{g_0 + k \cdot g}$
(usually then $g_0 \gg g$)

- ▶ If we represent contiguous insertions as $[^+_{c_1}] [^-_{c_2}] \cdots [-_{c_k}]$
can assign $S([^+_c]) = g_0 + g$ and $S[-_c] = g$.
- ▶ DP algorithm can be extended to handle these refined scores

3.5 Bounded-Distance Alignments

Good Alignment or Abort



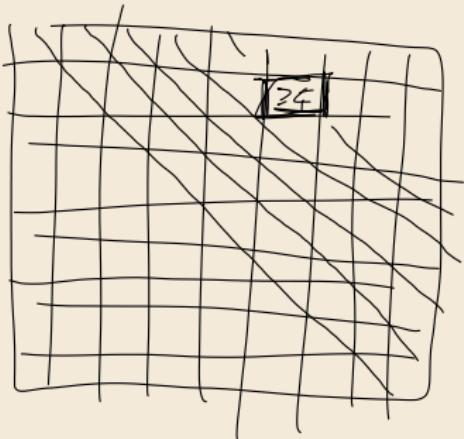
Given: $A[0 \dots m]$

$B[0 \dots n]$

$\frac{\text{ED score}}{\text{global alignment}}$

$$+ k \in \mathbb{N}$$

Goal: If $d_{\text{edit}}(A, B) \leq k$
output alignment
otherwise "large dist"

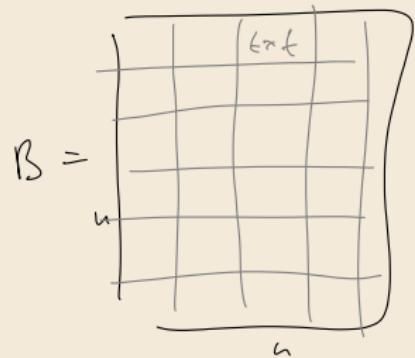
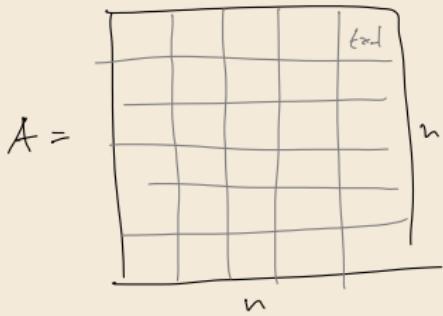


- off diagonal by d steps $\Rightarrow D \geq d$
- \Rightarrow only need to consider band matrix of size $n \cdot 2k$ instead of full $n \cdot n$ matrix
- \Rightarrow in DP recurrence, skip any option where $|j-i| > k$

if $D[m][n] > k$ don't get correct distance!
 if $\leq k$ yes,

3.6 Exhaustive Tabulation

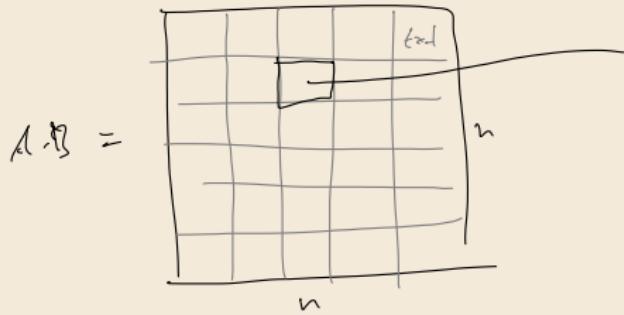
Boolean matrix multiplication



$$\frac{n^3}{\log^3 n}$$

$$A \cdot B \quad O(n^3)$$

(ignore DLC)



\sum of products of $t \times t$ matrices from $A \otimes B$

2^{t^2} different \square

→ compute ALL products
up front!

+ use indirect addressing