

# IH SIL GOLF G

### **Greedy Algorithms**

14 January 2025

Prof. Dr. Sebastian Wild

#### **Learning Outcomes**

#### Unit 11: Greedy Algorithms

- 1. Describe informally what greedy algorithms are.
- **2.** Know exemplary problems and their greedy solutions: Change-Making Problem, MSTs, SSSPP, Assignment Problem.
- **3.** Be able to design and proof correctness of greedy algorithms for (simple) algorithmic problems.
- **4.** Be able to explain the matroid properties and its relation to greedy algorithms.

#### **Outline**

## **11** Greedy Algorithms

- 11.1 Introduction
- 11.2 How Can Greed Succeed?
- 11.3 Greed in Graphs I: MSTs
- 11.4 Greed in Graphs II: Prim's MST Algorithm
- 11.5 Greed in Graphs III: Shortest Paths
- 11.6 Greedy Schedules
- 11.7 The Essence of Greed: Matroids



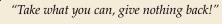
#### **Myopic Optimization**

► In a "greedy" algorithm, we assemble a solution to an optimization problem step by step always picking the next step to maximize current gain, and we never take back earlier steps.

"Take what you can, give nothing back!"

#### **Myopic Optimization**

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- reminiscent of gradient-descent algorithms
   but discrete and even more unwilling to undo mistakes
- → greedy algorithms only yield optimal solutions for certain problems
  - but where they do, their speed is usually unbeatable
  - → it is understanding where they succeed

(unknown quality)

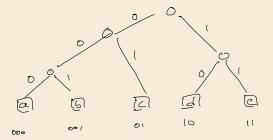
even where they are not optimal, greedy approaches can be efficient heuristics or approximation algorithms

#### Plan for the Unit

- We will first see a few examples (known and new) of greedy algorithms to make the vague generic description concrete
  - ▶ in particular minimum spanning trees and shortest paths in graphs
- Unlike other algorithm design techniques, greedy algorithms have a formal basis: matroids (and greedoids)
  - ▶ The second part will introduce these and how they can unify correctness proofs

#### A First Example: Reunion With An Old Friend

- ▶ We have seen an example of a Greedy Algorithm in Unit 7: *Huffman Codes!*
- ► Recall the problem:
  - ▶ **Given:** Set of symbols  $\Sigma = [0..\sigma)$ , weights  $w : \Sigma \to \mathbb{R}_{\geq 0}$
  - ▶ **Goal:** prefix code E (= code trie) that minimizes  $\sum_{c \in \Sigma} w(c) \cdot |E(c)|$



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- Since only *code tries* are valid, all solutions consist in repeatedly merging tries (starting from single-leaf tries, until single trie left)
- each merge contributes the subtree's total weight to overall cost (since all leaves in merged tries move one level down / all codewords get one extra bit)
- ▶ **Huffman's Algorithm:** Always choose current cheapest merge.

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  - ▶ **Goal:** prefix code E (= code trie) that minimizes  $\sum_{c \in \Sigma} w(c) \cdot |E(c)|^{-2}$
- Since only *code tries* are valid, all solutions consist in repeatedly merging tries (starting from single-leaf tries, until single trie left)
- each merge contributes the subtree's total weight to overall cost (since all leaves in merged tries move one level down / all codewords get one extra bit)
- ▶ Huffman's Algorithm: Always choose current cheapest merge.
- ► In the correctness proof, we had to show:

  There is always an optimal code trie where the two lowest-weight symbols are siblings.

This is typical: To show that Greedy is optimal, we need a structural insight into optimal solutions.

# 11.2 How Can Greed Succeed?

#### **Greed For Change**

The Change-Making Problem (a.k.a. Coin-Exchange Problem)

- ► Given: a set of integer denominations of coins  $w_1 < w_2 < \cdots < w_k$  with  $w_1 = 1$ , target value  $n \in \mathbb{N}_{\geq 1}$  (we have sufficient supply of all coins ...)
- ▶ **Goal:** "fewest coins to give change n", i. e., multiplicities  $c_1, \ldots, c_k \in \mathbb{N}_{\geq 0}$  with  $\sum_{i=1}^k c_i \cdot w_i = n$  minimizing  $\sum_{i=1}^k c_i$

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```
For Euro coins, denominations are (0), (20), (50), (10), (200), (500), (10), and (20). formally: 1 , 2 , 5 , 10 , 20 , 50 , 100 , and 200 . w_1 w_2 w_3 w_4 w_5 w_6 w_7 w_8
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```

- → Simple greedy algorithm: largest coins first
  - ightharpoonup optimal time (O(k) if coins sorted)
  - ▶ is  $\sum c_i$  minimal?

```
procedure greedyChange(w[1..k], n):

// Assumes 1 = w[1] < w[2] < \cdots < w[k]

for i := k, k - 1, \dots, 1:

c[i] := \lfloor n/w[i] \rfloor

n := n - c[i] \cdot w[i]

// Now n == 0

return c[1..k]
```

#### **Clicker Question**



Does greedyChange give the optimal answer for the Euro coins change-making problem?

- (A) Always
- B Sometimes
- (C) Never



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- B) Sometimes
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▶ **Theorem:** greedyChange computes an optimal c[1..8] for w[1..8] = [1, 2, 5, 10, 20, 50, 100, 200] for every  $n \in N_{\geq 1}$ .

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  - ► The greedy algorithm can be interpreted as picking one coin at a time, each time choosing the largest possible denomination  $\hat{w}(n) = \max\{w[i] : w[i] \le n\}$ .
  - ▶ We prove by induction over n: Any optimal solution for n must contain  $(\hat{w}(n))$ .
    - $n = 1: \text{ can only use } \hat{w}(n) = 1$

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    - ▶  $n \in [2..5]$ : Assume we had a solution without  $(2e) \longrightarrow \text{must be } n \times (1e)$  with  $n \ge 2$ ;
      - $\rightarrow$  we can make this strictly better by replacing (1c)(1c) by (2c)

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    - ▶  $n \in [2..5)$ : Assume we had a solution without 2c  $\longrightarrow$  must be  $n \times 1c$  with  $n \ge 2$ ;  $\longrightarrow$  we can make this strictly better by replacing 1c 1c by 2c 4
    - ▶  $n \in [5..10)$ : Assume solution without (5c) summing to  $n \ge 5$ .

The solution must fall into one of the following cases:

- (a)  $\geq 3 \times (2e) \implies \text{replacing } (2e)(2e)(2e) \text{ by } (5e)(1e) \text{ strictly better } \mathbf{f}$
- (b)  $\leq 1 \times (2\mathfrak{c}) \implies \text{value } n 2 \geq 3 \text{ without } (2\mathfrak{c}) \text{ } \text{ by IH}$
- (c)  $2 \times (2\mathfrak{e})$  and  $\geq 1 \times (1\mathfrak{e}) \implies (2\mathfrak{e})(2\mathfrak{e})(1\mathfrak{e}) \rightarrow (5\mathfrak{e})$  strictly better  $\P$
- (d)  $2 \times (2\mathfrak{c})$ , no  $(1\mathfrak{c}) \longrightarrow \text{only obtain value} \le 4 < n$

- ▶ **Theorem:** greedyChange computes an optimal c[1..8] for w[1..8] = [1, 2, 5, 10, 20, 50, 100, 200] for every  $n \in N_{\geq 1}$ .
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  - We prove by induction over n: Any optimal solution for n must contain  $(\hat{w}(n))$ .

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    - ▶  $n \in [5..10)$ : Assume solution without (5c) summing to  $n \ge 5$ . The solution must fall into one of the following cases:
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      - (b)  $\leq 1 \times (2\mathfrak{c}) \implies \text{value } n-2 \geq 3 \text{ without } (2\mathfrak{c}) \neq \text{ by IH}$
      - (c)  $2 \times (2e)$  and  $\geq 1 \times (1e) \rightarrow (2e)(2e)(1e) \rightarrow (5e)$  strictly better  $\P$
      - (d)  $2 \times (2\mathfrak{c})$ , no  $(1\mathfrak{c}) \longrightarrow \text{only obtain value} \le 4 < n$
    - ▶  $n \in [10, 20)$ : Any solution without (10c) contains
      - (a)  $(5c)(5c) \longrightarrow \text{replace by } (10c); \text{ or }$
      - (b) at most one (5c)  $\longrightarrow$  at least value 5 without (5c)  $\uparrow$  by IH

- proof continued
  - ▶  $n \in [20..50)$  Without (20c), we must have
    - (a) 10c 10c  $\rightarrow$  20c  $\uparrow$
    - (b) at most one  $(10c) \rightarrow \text{value } n 10 \ge 10 \text{ without } (10c) \text{ } by \text{ IH}$

- proof continued
  - ▶  $n \in [20..50)$  Without (20c), we must have
    - (a) 10c 10c  $\rightarrow$  20c  $\uparrow$
    - (b) at most one  $(10c) \rightarrow \text{value } n 10 \ge 10 \text{ without } (10c) \text{ } by \text{ IH}$
  - ▶  $n \in [50..100)$  Without (50c), we must have
    - $(a) \ge 3 \times (20c) \quad \rightsquigarrow \quad (20c)(20c)(20c) \rightarrow (50c)(10c)$
    - (b)  $\leq 1 \times (20c) \implies \text{value } n 20 \geq 30 \text{ without } (20c) \text{ } by \text{ IH}$
    - (c)  $2 \times (20c)$  and  $\geq 1 \times (10c)$   $\Rightarrow$   $(20c)(20c)(10c) \rightarrow (50c)$
    - (d)  $2 \times (20c)$ , no  $(10c) \rightarrow value n 40 \ge 10$  without (10c) by IH

- proof continued
  - ▶  $n \in [20..50)$  Without (20c), we must have
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    - (d)  $2 \times (20c)$ , no (10c)  $\rightarrow$  value  $n 40 \ge 10$  without (10c) by IH
  - ▶  $n \in [100..200)$ : as for  $n \in [10, 20)$ , mutatis mutandis.
  - ▶  $n \ge 200$ : as for  $n \in [20, 50)$ .

- proof continued
  - ▶  $n \in [20..50)$  Without (20c), we must have
    - (a) 10c 10c  $\rightarrow$  20c  $\uparrow$
    - (b) at most one  $(10c) \rightarrow \text{value } n 10 \ge 10 \text{ without } (10c) \text{ } by \text{ IH}$
  - ▶  $n \in [50..100)$  Without (50c), we must have

$$(a) \ge 3 \times 20c \longrightarrow 20c 20c 20c \longrightarrow 50c 10c$$

(b) ≤ 
$$1 \times (20c)$$
  $\rightarrow$  value  $n - 20 \ge 30$  without  $(20c)$   $\uparrow$  by IH

(c) 
$$2 \times (20c)$$
 and  $\geq 1 \times (10c)$   $\Rightarrow$   $(20c)(20c)(10c) \rightarrow (50c)$ 

(d) 
$$2 \times (20c)$$
, no  $(10c) \rightarrow value n - 40 \ge 10$  without  $(10c)$  by IH

- ▶  $n \in [100..200)$ : as for  $n \in [10, 20)$ , mutatis mutandis.
- ▶  $n \ge 200$ : as for  $n \in [20, 50)$ .
- ▶ The same arguments work for adding coins  $1 \cdot 10^m$ ,  $2 \cdot 10^m$ ,  $5 \cdot 10^m$  for m = 3, 4, ...

- proof continued
  - ▶  $n \in [20..50)$  Without (20c), we must have

(a) 
$$10c$$
  $10c$   $\rightarrow$   $20c$   $\uparrow$ 

- (b) at most one  $(10c) \rightarrow \text{value } n 10 \ge 10 \text{ without } (10c) \text{ } by \text{ IH}$
- ▶  $n \in [50..100)$  Without (50c), we must have

$$(a) \ge 3 \times 20c \longrightarrow 20c \times 20c \times 20c \longrightarrow 50c \times 10c$$

(b) ≤ 
$$1 \times (20c)$$
  $\rightarrow$  value  $n - 20 \ge 30$  without  $(20c)$   $\uparrow$  by IH

(c) 
$$2 \times (20c)$$
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- ▶  $n \in [100..200)$ : as for  $n \in [10, 20)$ , mutatis mutandis.
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- ► The same arguments work for adding coins  $1 \cdot 10^m$ ,  $2 \cdot 10^m$ ,  $5 \cdot 10^m$  for m = 3, 4, ...

#### That went smoothly!

And we proved a nice structural statement about how optimal solutions look like as a bonus.

Maybe Greedy always works?

► *Unfortunately, No.* See w = (1, 3, 4) and n = 6.



3) (

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$$w = (1, 3, 4)$$
 and  $n = 6$ . or  $w = (1, 4, 9)$  and  $n = 12$ 

Where/Why does our proof from above fail?

- ▶ Unfortunately, No. See w = (1, 3, 4) and n = 6. Where/Why does our proof from above fail? or w = (1, 4, 9) and n = 12
- ▶ Indeed, Greedy can be **arbitrarily bad** compared to the optimal solution: See w = (1,999,1000) and n = 1998.
- Need to be careful about the details of a correctness argument for greedy algorithms.

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Where/Why does our proof from above fail?

- ▶ Indeed, Greedy can be **arbitrarily bad** compared to the optimal solution: See w = (1,999,1000) and n = 1998.
- Need to be careful about the details of a correctness argument for greedy algorithms.

- ▶ The Change-Making problem is still only partially understood.
  - Exactly characterizing the denomination sequences that are optimally handled by greedyChange is an open research problem.
    - ▶ Sufficient criteria for "greed-compatible" denominations found in the literature.
  - ► The general problem is (weakly) NP-hard
  - ▶ Yet, for moderate *n*, we will see a solution for general denomination sequences later!

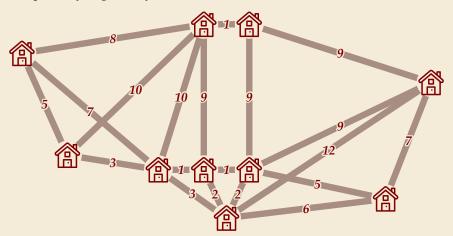
# 11.3 Greed in Graphs I: MSTs

#### Metaphor: Planning an electricity grid

**Given:** Houses to be connected to central power grid

Possible connections with building costs given

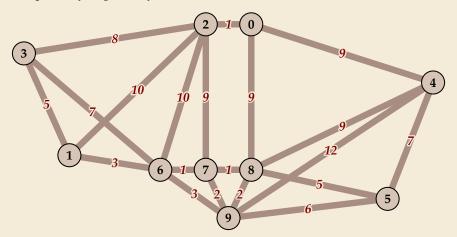
Goal: Cheapest way to get every house connected



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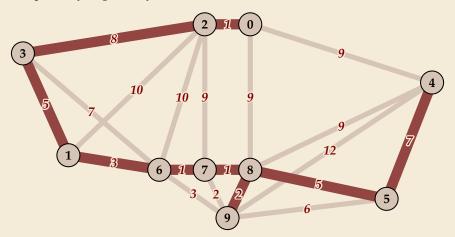
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**Given:** Houses to be connected to central power grid Possible connections with building costs given

Goal: Cheapest way to get every house connected



#### **Clicker Question**

Which algorithm allows to efficiently test whether a given (undirected) graph is connected?

bubble sort

depth-first search

breadth-first search

generic tricolor search

Kosaraju-Sharir's algorithm

Dijkstra's algorithm

Edmonds-Karp algorithm



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- B depth-first search √
- C breadth-first search 🗸
- D generic tricolor search 🗸
- E Kosaraju-Sharir's algorithm 🗸
- F) <del>Dijkstra's algorithm</del>
- G Edmonds Karp algorithm



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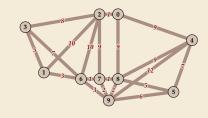
# The Minimum Spanning Tree (MST) Problem

Given: undirected, edge-weighted, simple,

**connected** graph G = (V, E, c) no self loops, no parallel edges

Formally: Recall assumption V = [0..n) ( $\leadsto$  array indices) edges  $E \subseteq \{\{u,v\}: u,v \in V \land u \neq v\}$  edge weights (costs)  $c: E \to \mathbb{R}_{>0}$ 

for all  $u, v \in V$  there exists a path  $u \rightsquigarrow v$  in (V, E)



**Goal:** a spanning tree (V, T)

with **minimal** total cost 
$$c(T) := \sum_{e \in T} c(e)$$

Formally:  $T \subseteq E$ 

 $(\overline{V}, T)$  is connected and acyclic ("spanning tree") for every spanning tree (V, T') of G we have  $c(T') \ge c(T)$ .



# **Further MST Applications**

#### **Direct Applications**

- single-linkage hierarchical clustering
- ► Bottleneck-shortest paths
- Approximation algorithms, e.g.,
  - Christofides's Metric TSP Approximation
  - ► Steiner-tree problem

#### As a cheap subroutine

- ► Routing protocols
- medical image processing
- **.**..



We freely use "tree" to mean different things in different contexts . . . mind the confusion.

here: "tree" = undirected, nonplane tree = an undirected, connected and acyclic graph in spanning tree no order on edges



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The digraph flavor is a rooted tree: (hence undirected trees sometimes called *unrooted*)

▶ rooted (nonplane/unordered) tree = digraph (V, E) with root  $r \in V$  s.t.  $\forall v \in V \setminus \{r\} : d_{\text{out}}(v) = 1 \text{ and } d_{\text{out}}(r) = 0$ out-degree = #outgoing edges

We draw trees with the single(!) root on top ...



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out-degree = #outgoing edges

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Other "trees" don't originate from graphs naturally, but rather from recursion / terms:

- ▶ binary tree = a null pointer or a node with left and right children, each a binary tree (formally: the set of binary trees is the smallest fixed point of that construction)
- ▶ ordinal trees = a node with a sequence of 0 or more children, each ordinal trees= rooted ordered trees (rooted unordered + total order on children)
- ▶ plus many more variants out there ... → if in doubt, double check definitions!

## A Naive Approach

How to start finding an MST?

Using the **cheapest** edge shouldn't hurt . . .

```
1 procedure greedyMST(V, E, c):

2   // Assume (V, E) is simple & connected, c : E \to \mathbb{R}_{\geq 0}

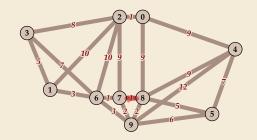
3   T := \emptyset

4   while (V, T) not connected

5   e := cheapest edge that doesn't close a cycle in T

6   T := T \cup \{e\}

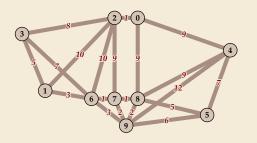
7   return T
```



# A Naive Approach Works – Kruskal's Algorithm

How to start finding an MST?

Using the **cheapest** edge shouldn't hurt . . .

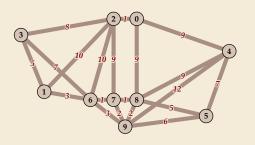


Apart from implementing line 4 and line 5 efficiently, this is **Kruskal's Algorithm!** 

# A Naive Approach Works – Kruskal's Algorithm

How to start finding an MST?

Using the **cheapest** edge shouldn't hurt . . .



Apart from implementing line 4 and line 5 efficiently, this is Kruskal's Algorithm!

As so often with greedy algorithms, the hardest bit is the correctness argument. We have:

**Theorem:** Kruskal's Algorithm finds a minimum spanning tree.

This immediately follows from proving the following invariant:

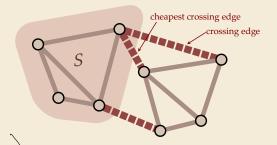
**Kruskal's Invariant:** There is some MST  $T^*$  with  $T \subseteq T^*$ .

# Crossing Edges and the MST-Cut Lemma

To prove the correctness of Kruskal's Algorithm, we need a tool.

#### Notation:

- ► Cut S: non-trivial set of vertices  $\emptyset \neq S \subsetneq V$
- ► **crossing edge** e wrt. cut S:  $e = \{u, v\}$  with  $u \in S, v \in \bar{S} := V \setminus S$



#### The MST-Cut Lemma:

Let  $T^*$  be an MST und  $W \subseteq T^*$ .

For every cut S, not cutting any edges in W, and every *cheapest* crossing edge e wrt. S there is an MST  $\hat{T}^*$  that contains  $W \cup \{e\}$ .

#### **Proof of MST-Cut Lemma**

#### Proof:

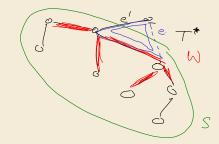
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#### **Proof of MST-Cut Lemma**

#### *Proof:*

- ► Case 1:  $e \in T^*$ . Then picking  $\hat{T}^* = T^*$  proves the claim.
- ► Case 2:  $e \notin T^*$ .
  - $\rightarrow$   $T^* \cup \{e\}$  contains unique cycle C using e.
  - ► Since *e* crosses cut *S*, *C* crosses *S*
  - $\rightsquigarrow$  There is a second crossing edge  $e' \in C$ .



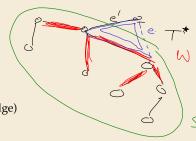
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  - $\rightsquigarrow$  There is a second crossing edge  $e' \in C$ .
  - ► Since e' is crossing,  $e' \notin W$
  - ▶ by assumption,  $c(e) \le c(e')$  (we pick cheapest crossing edge)
  - $\rightarrow$   $\hat{T}^* = T^* \cup \{e\} \setminus \{e'\}$  is a spanning tree, and  $W \cup \{e\} \subseteq \hat{T}^*$
  - $ightharpoonup c(\hat{T}^*) = c(T^*) + c(e) c(e') \le c(T^*)$
  - $\rightsquigarrow \hat{T}^*$  is an MST.

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# Kruskal's Algorithm - Correctness

With these preparations, we can prove

**Kruskal's Invariant:** There is some MST  $T^*$  with  $T \subseteq T^*$ .

*Proof:* by induction over the loop iterations

- ▶ IB: initially  $T = \emptyset$  and  $\emptyset \subseteq T^*$  for every MST  $T^*$ .
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- ▶ IS: Let e = vw be the edge considered in iteration i + 1.
  - Let S be the connected component of v in (V, T) (T: before potentially adding e)
  - ► Case 1:  $w \in S$ .

Then e closes a cycle in T and is not added to T.

→ invariant still satisfied.

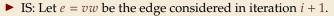
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Since we only terminate when T is spanning, upon termination  $T = T^*$  for an MST  $T^*$ .

For an efficient implementation of Kruskal's algorithm, we need to efficiently

- **1.** check whether *T* is spanning
- 2. find the next cheapest edge to consider
- 3. test whether an edge closes a cycle

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- **1.** Since we maintain T acyclic, checking |T| = n 1 suffices!
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- 3. Use a **Union-Find data structure** (see Algorithmen & Datenstrukturen!)
  - dynamically maintain connected components
  - initially, every vertex has its own id
  - ▶ adding vw to  $T \rightsquigarrow call union(v, w)$
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& exam

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- $\rightarrow$   $O(m \log m) = O(m \log n)$  time and O(m) extra space.

#### **Clicker Question**

#### What is the running time of Prim's algorithm?



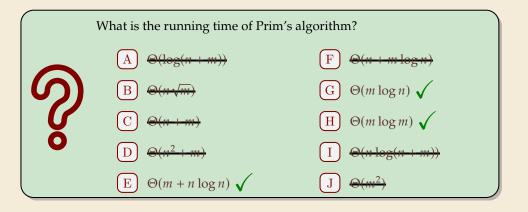
- $(A) \Theta(\log(n+m))$ 
  - $\Theta(n\sqrt{m})$
- $\bigcirc$   $\Theta(n+m)$
- $\bigcirc$   $\Theta(n^2+m)$
- $\bullet$   $\Theta(m + n \log n)$

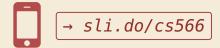
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- H  $\Theta(m \log m)$
- I)  $\Theta(n\log(n+m))$
- J  $\Theta(m^2)$



→ sli.do/cs566

#### **Clicker Question**





# 11.4 Greed in Graphs II: Prim's MST Algorithm

# Prim's Algorithm

- ► An alternative greedy approach that tries to consider only crossing edges.
  - ightharpoonup start with  $S = \{s\}$  for some vertex s
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 $\leadsto$  Correctness as for Kruskal's algorithm: [Invariant:  $\exists$  MST  $T^*$  with  $T \subseteq T^*$ .]

IB: initially true with  $T = \emptyset$ 

IS: whenever we add an edge, it is the cheapest crossing edge w.r.t. cut  $(S, \bar{S})$ .

How to efficiently find the cheapest crossing edge?

▶ **Option 1**: Maintain priority queue *Q* of **edges**, ordered by weight.

```
procedure lazyPrimMST(G):
       // Assume G = (V, E, c) simple & connected, c : E \to \mathbb{R}_{\geq 0}
       T := \emptyset; inS[0..n) := false
       O := \text{new MinPO()}
       visit(0)
       while |T| < n - 1:
            vw := O.delMin()
            if \neg inS[w] then visit(w); T.insert(vw) end if
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(n≤m+1)

with binary heaps, total time  $O(m \log m) = O(m \log n)$   $m \le \ln^2$ 

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Easy modification: store parent in tree rooted at vertex 0

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We can reduce the extra space to O(n) if we avoid storing multiple edges to the same  $w \in \overline{S}$ .

- ▶ **Option 2:** Maintain priority queue Q of **vertices** in  $\bar{S}$ , ordered by **weight of cheapest edge** connecting them to S.
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# Prim's Algorithm - Eager Implementation

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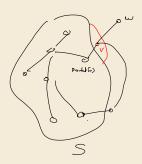
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  - after adding a vertex u to S, distance to w can **shrink** (to c(uw)) (but never grow)
  - → need a MinPQ that supports decreaseKey
    - ▶ implementation hassle: efficient implementations require a "pointer" into data structure cleaner design: let data structure handle pointers internally
- - **Assumption:** stored objects are from [0..n) and n known/fixed at construction time
  - ► IndexMinPQ implementations maintain array positions e.g., for binary heaps, maintain *heapIndex*[0..n), update whenever heap modified
  - → easy to support decreaseKey(i, p') and contains(i)

    (for a full implementation see Sedgewick & Wayne or Nebel & Wild)

# Prim's Algorithm – Eager Implementation Code

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procedure primMST(G):
       // Assume G = (V, E, c) is simple & connected, c : E \to \mathbb{R}_{>0}
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       Q := \text{new IndexMinPQ}(n)
       Q.insert(0,0)
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       while \neg Q.isEmpty()
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       return \{ \{father[v], v\} : v \in [1..n) \}
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  - $\rightarrow$  with binary heaps  $O(m \log n)$  with Fibonacci heaps  $O(m + n \log n)$

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- very efficient to compute even for arbitrary weights
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- ► Yes, if graph is **dense**, e. g.,  $m = \Omega(n \log n)$ . Then  $O(m + n \log n) = O(m)$ 
  - stronger results known, as well
- ▶ Yes, for **integer** weights on the word-RAM (Fredman, Willard 1994)
- Yes, if **randomization** is allowed (Karger, Klein, Tarjan 1995)
  - uses that linear time suffices to verify a given ST as minimal(!)

- MSTs are a versatile modeling tool
- very efficient to compute even for arbitrary weights
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- ► General (deterministic, comparison-based, on sparse graphs)? **Open research problem!** 
  - **b** Best known general time  $O(m\alpha(m,n))$  where  $\alpha$  is an "inverse Ackermann function"

 $\alpha(m, n) = \min\{z \ge 1 : A(z, 4\lceil m/n \rceil) > \lg n\}$   $A(0, x) = 2x, A(i, 0) = 0, A(i, 1) = 2, (i \ge 1),$  $A(i, x) = A(i - 1, A(i, x - 1)); (i \ge 1, x \ge 2)$ 

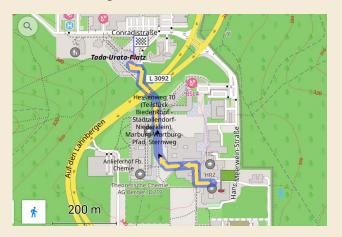
# 11.5 Greed in Graphs III: Shortest Paths

## **Metaphor: Route Planning**

**Given:** Road network (map), current location, target location

crossings = vertices, roads = edges, road length = edge weight

Goal: Find shortest path from current location to target



It turns out that a cleaner algorithmic problem is to find shortest paths to *all* vertices.

#### Single Source Shortest Path Problem (SSSPP)

- **▶ Given:** directed, edge-weighted, simple graph G = (V, E, c) with edge costs  $c : E \to \mathbb{R}$ , a start vertex  $s \in V$
- ▶ **Goal:** a <u>data structure</u> that reports for every  $v \in V$ :  $\delta_G(s,v)$ : the shortest-path distance from s to v spath(v): a shortest path from s to v (if it exists)

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#### Formally:

▶ for a walk 
$$w[0..m]$$
 in  $G$ , we define  $c(w) = \sum_{i=0}^{m-1} c(w[i]w[i+1])$ 

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- ▶ spath(v) returns a walk w with  $c(w) = \delta_G(s, v)$  if such a walk exists

► The complications in the definition all stem from **negative-weight edges** 

$$\delta_G(s,v) = \left[\inf\left(\{+\infty\} \cup \{c(w): w \text{ an } s\text{-}v\text{-walk in } G\}\right)\right]$$

- ▶ In general,  $\delta_G(s, v)$  can be
  - $\blacktriangleright$  + $\infty$  if there is no *s-v*-walk at all, or

("no-path case" easy to detect and handle)

► -∞ if there are *s-v-walks* of arbitrarily small (negative) value

This happens *iff* we reach a negative cycle that we can repeat indefinitely,
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*Proof:* Suppose *w* contains a cycle *C*.

- ▶ If c(C) < 0, w is not shortest as we can repeat C and reduce cost  $\P$
- ▶ If c(C) > 0, w is not shortest as we can remove C and reduce cost  $\P$
- ▶ If c(C) = 0 for all cycles in w, we can remove them from w to obtain a path p and c(p) = c(w).

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- ▶ If c(C) = 0 for all cycles in w, we can remove them from w to obtain a path p and c(p) = c(w).
- In the absense of negative cycles, all shortest walks are **shortest paths** (of at most n-1 edges).

#### **Variants of Shortest Path Problems**

#### Important special cases

- 1. | Positive SSSPP
  - $ightharpoonup c: E o \mathbb{R}_{>0}$
  - ► most relevant case for many applications → focus of this section
- 2. Unweighted SSSPP
  - $ightharpoonup c(e) = 1 \text{ for } e \in E \implies c(w) = \text{\#edges for every walk } w$
  - → solved by BFS in linear time
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  - ► G is a DAG
  - ► can be solved in linear time based on topological sort (for *arbitrary c*)
- ▶ For the rest of this section, we will assume c(e) > 0.
- ▶ But: The general case of cyclic graphs with negative edge weights is also relevant
  - ▶ We will come back to this case in Unit 12!

► **Intuition:** Imagine sending out many little pioneers, walking at unit speed from *s* across all edges in *G*. The first pioneer to reach a vertex *v* "claims" *v* and proclaims the current time (= distance). Dijkstra's Algorithm is a event-driven simulation of this process!



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Event: Some pioneer reaches a new vertex.Can set a "timer" for that as soon as they start walking over an edge.

- ► Maintain priority queue of events, sorted by time.
  - ▶ Discard events for vertices that have been claimed already.
  - Avoid generating events when already clear that they will be discarded.
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- ► **Implementation:** Store unclaimed vertices in <u>IndexMinPQ</u>

  Priority = earliest time known so far when this vertex will be claimed
  - ► To claim w at time t, must have claimed some v at time t c(vw)
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  - $\leadsto$  whenever we claim a vertex v, update successors' claim times (via decreaseKey)
  - → overall process is a graph traversal! claimed = *done*

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procedure dijkstra(G):
       // Assume G = (V, E, c) is simple (di)graph, c : E \to \mathbb{R}_{>0}
       father[0..n) := NONE; inS[0..n) := false; dist[0..n) := +\infty
3
       Q := \text{new IndexMinPQ}(n)
       Q.insert(0,0); dist[\mathbf{6}] := 0
5
       while \neg Q.isEmpty()
            visit(Q.delMin())
7
       return (dist, father)
8
9
10 procedure visit(v):
       for (w, c) \in G.adj[v] // edge vw with cost c > 0
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            if \neg inS[w]
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                if dist[v] + c < dist[w]
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  - ▶  $n \times \text{insert}$ ,  $(n-1) \times \text{delMin}$ , up to  $m \times \text{decreaseKey}$
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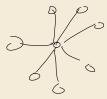
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#### **Shortest Paths Discussion**

- Simple and efficient solution if edge weights are positive
- - Dijkstra's Algorithm (with Fibonaccin heaps) is worst-case optimal

- ▶ (for sorting vertices by distance from *s* in a comparison-addition model)
- another fine example of a greedy algorithm!



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  - ▶ (for sorting vertices by distance from *s* in a comparison-addition model)
  - ▶ another fine example of a greedy algorithm!
- ▶ improvements often possible for *s-t* shortest paths (although worst case remains same)
  - ▶ in SSSPP Dijkstra, can stop once *t* is *done*
  - bidirectional Dijkstra (alternatingly work from both ends until we "meet")
  - $ightharpoonup A^*/goal$ -directed search (use cheap lower bound for  $\delta_G(v,t)$  in vertex selection)
- ▶ we will revisit the general SSSPP (with negative weights)