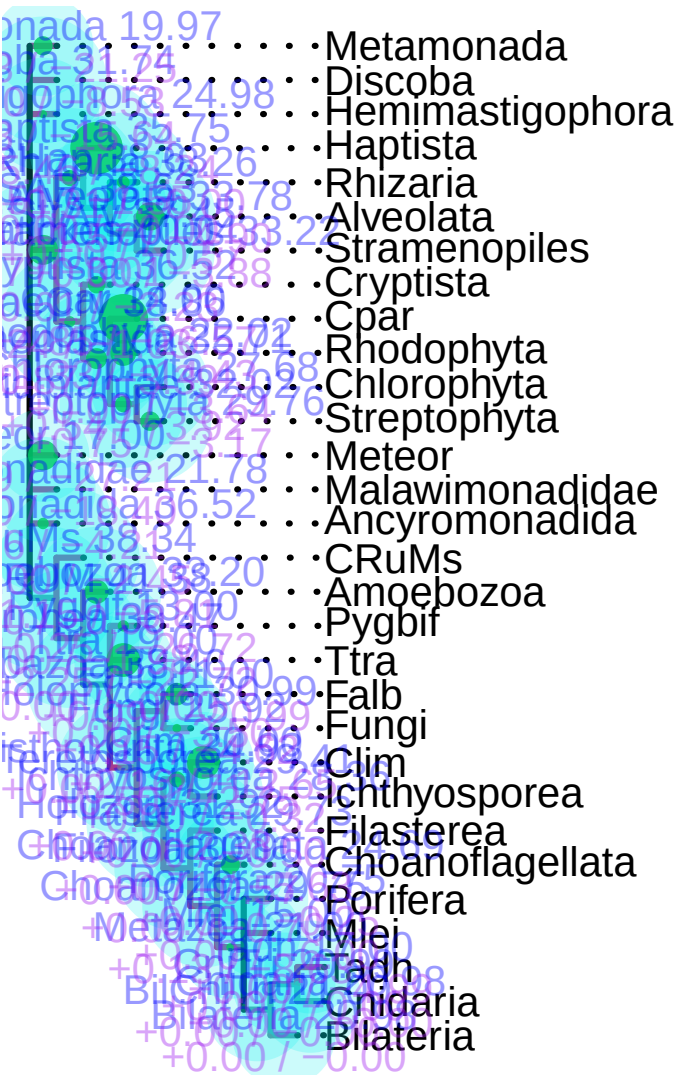
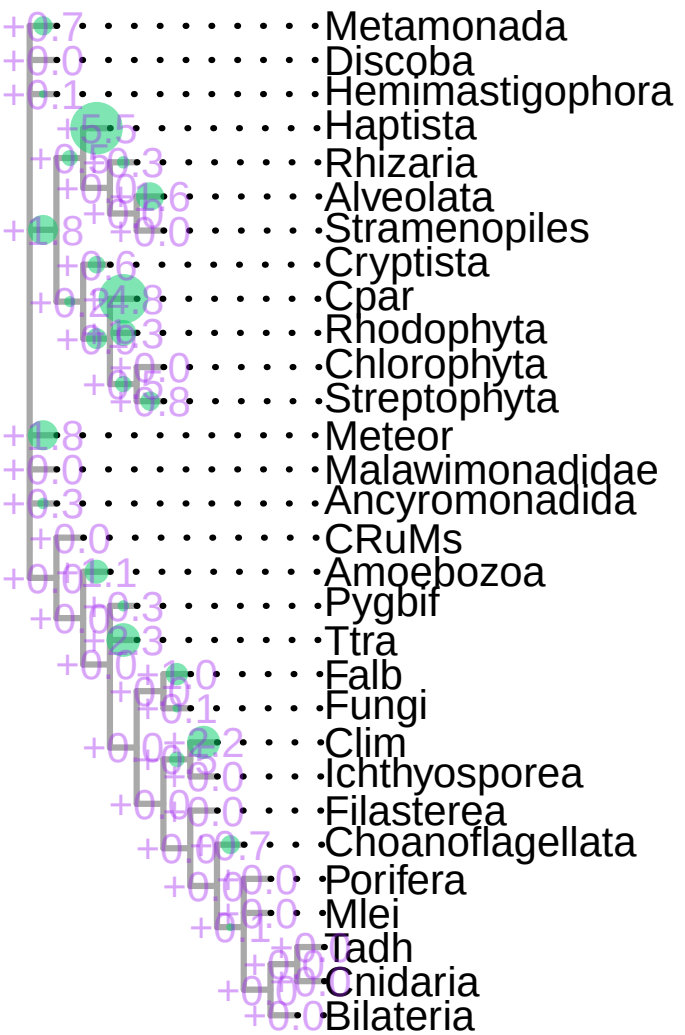
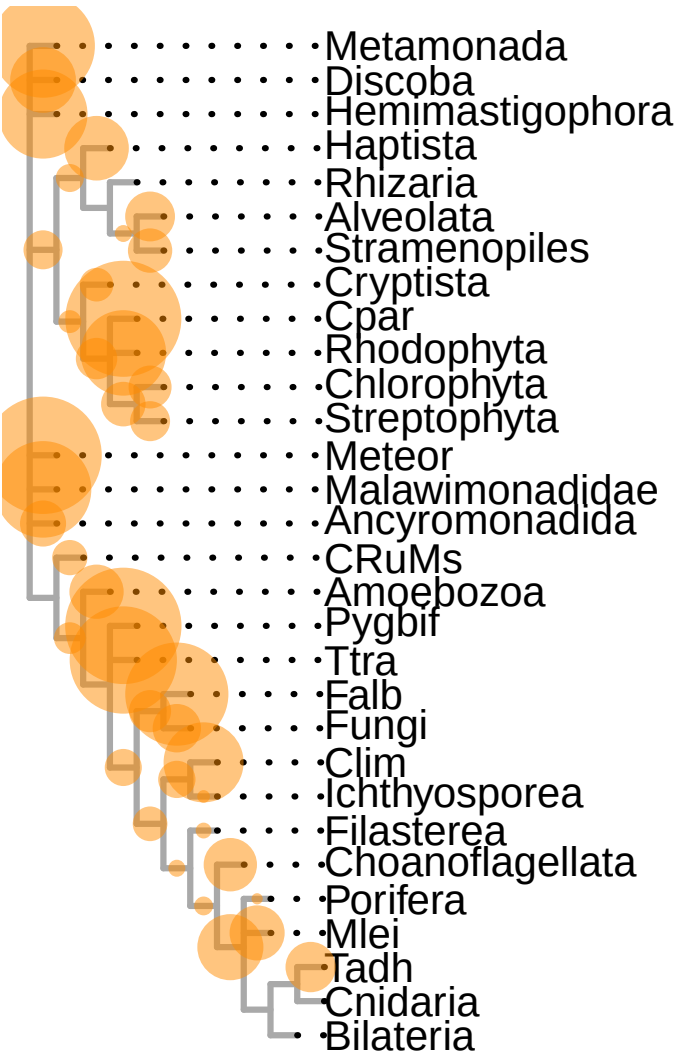
Presence and gains Remodeller

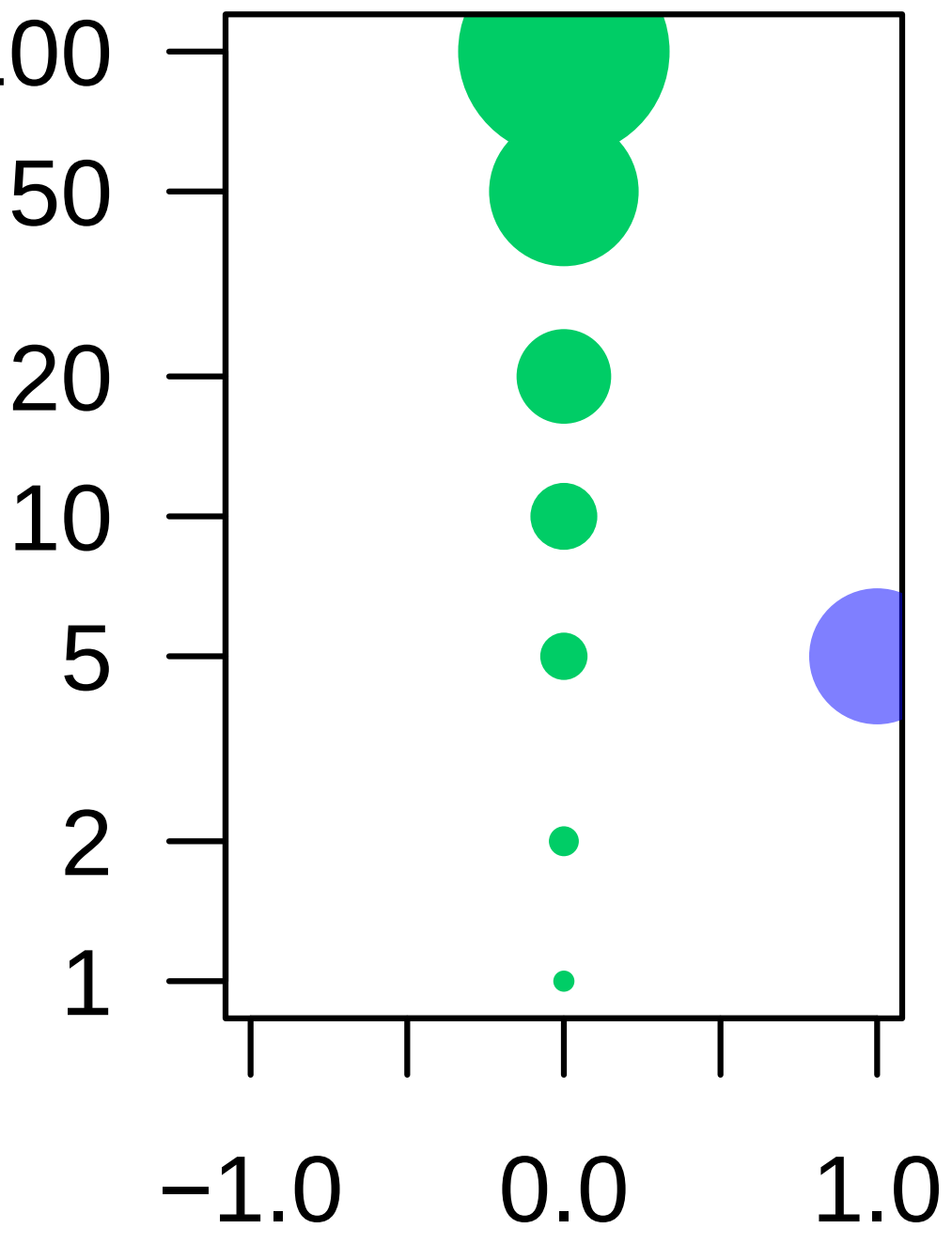


Gains Remodeller



Losses Remodeller




100
50
20
10
5
2
1
−1.0
0.0
1.0