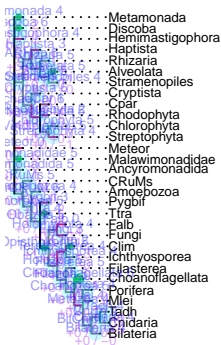
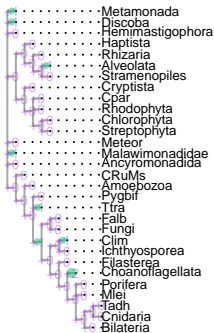


Presence and gains Dpy-30



Gains Dpy-30



Losses Dpy-30

