

Light Transport Techniques for Tensor Field Visualization

Sebastian Bek

Heidelberg University
Visual Computing Group (VCG)
Master's Thesis Presentation
Supervisors: Prof. Filip Sadlo, Dr. Susanne Krömker

19. Juli 2019

Outline

- 1 Introduction
- 2 Fundamentals
- 3 Method
- 4 Results and Evaluation
- 5 Conclusion and Future Work

Outline

- 1 Introduction
- 2 Fundamentals
- 3 Method
- 4 Results and Evaluation
- 5 Conclusion and Future Work

Motivation

- visualization in general is needed to generate a more readable, explorable and intuitive representation
- tensor representations are needed to describe a directional distribution for each point in space, when:
 - e.g. for vector fields: to describe the directionally dependent spatial gradient called Jacobian-matrix,
 - e.g. for fluid and solid continuum mechanics: to describe a whole distribution of stresses
 - e.g. for DT-MRI: diffusion tensor - magnetic resonance imaging: to describe the diffusion characteristics of water molecules within tissue

Objectives

- a light transport model (propagation scheme) following basic but crucial physical principles,
- application of this model for tensor field visualization interpreting tensors as light transmission properties,
- a FTLE (Finite-time Lyapunov exponents)-related approach called light transport gradient (LTG) for visualizing key structures, namely LCS (Lagrangian coherent structures) in 2D second-order tensor fields, and
- application of our approach to both synthetic and real data involving brain and heart datasets.

Related Work - Global Illumination Methods

- Discrete Ordinates Method: discretizes RTE in both spatial and angular domain
- Lattice-Boltzmann method: light propagation modeled as a diffusion process
- Light Propagation Volumes: light exchanged between neighboring cells and stored locally in capacities

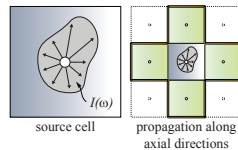


Fig.: Light Propagation Volumes, *Source:* ①

Related Work - Symmetric Tensor Field Visualization

- Glyphs: represent anisotropy with shape and orientation
- Tensor Field Lines (TFLs): follow the eigenvector along tensor field lines
- Tensorlines: introduce artificial inertia on TFLs to increase stability
- HyperLIC: use Line Integral Convolution from Vector Field Visualization on TFLs
- FTLE: exploit the gradient of the flow map of TFLs to generate an FTLE field
- Scalar Measures: tensor magnitude, diffusivity, fractional anisotropy, anisotropy coefficients (measures)

Related Work - Asymmetric Tensor Field Visualization

- Dual Eigenvectors: use complex conjugate eigenvectors as co-visualization for the complex domain along with ordinary eigenvectors to represent the real domain
- Pseudo Eigenvectors: extension for dual eigenvectors to a full set or graph
- Scalar Measures: tensor magnitude, tensor mode, isotropy index

Outline

- 1 Introduction
- 2 Fundamentals
- 3 Method
- 4 Results and Evaluation
- 5 Conclusion and Future Work

Fundamentals

Tensor Fields

- order- o generalization of a matrix with indices of run length n for $n \times n$ matrices
- number arrays following covariant or contravariant transformation rules
- representation needed for a whole directional distribution for each point in space

Tab.: Tensor Shapes

order	0	1	2	3	...	o
shape	scalar	vector	matrix	"3D matrix"	...	order- o matrix

Fundamentals

Cauchy stress tensor

- classical physical example of a tensor
- consistent of 3 stress vectors arranged in row-major order
- these represent the magnitude and orientation of the resulting stress at plane x, y, z in direction x, y, z
- maps an incoming direction vector \mathbf{n} a resulting stress vector $\mathbf{T}^{(\mathbf{n})} = \mathbf{n} \cdot \boldsymbol{\sigma}$ per transformation

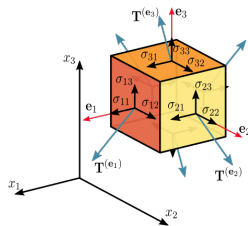


Fig.: Cauchy stress tensor, Source: ②

Polar Coordinates

Conversion Formulas

Polar \mapsto Cartesian

$$x = r \cos \omega,$$

$$y = r \sin \omega.$$

Cartesian \mapsto Polar

$$r = \sqrt{x^2 + y^2},$$

$$\omega = \text{atan2}(y, x).$$

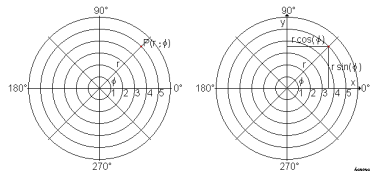


Fig.: Polar coordinates, *Source:* ③

- polar function $f : \omega \mapsto r$ maps each angle ω a magnitude $r(\omega)$

Principal Component Analysis

Matrix Decompositions

Eigenvalue Decomposition: $\mathbf{A} = \mathbf{R}\mathbf{S}\mathbf{R}^*$

Singular Value Decomposition (SVD): $\mathbf{A} = \mathbf{U}\mathbf{\Sigma}\mathbf{V}^*$

- used to determine the main directions of variance (principal components) in stochastic data
- used to determine the subsequent base transformations composing affine transformations

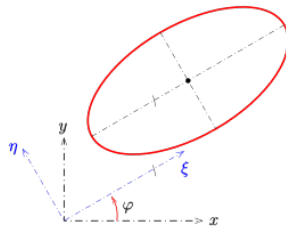


Fig.: Principal component analysis,
Source: ④

Principal Component Analysis

Finite-Time Lyapunov exponents

Definition

Local: $\sigma = \frac{1}{|T|} \ln \frac{\Delta}{\delta}$

Global: $\sigma(\mathbf{x}) = \frac{1}{|T|} \ln \|\nabla \varphi(\mathbf{x})\|_2$

whereas $\|A\|_2 = \sqrt{\lambda_{\max}(A^T A)}$ is the spectral norm of matrix A

- measure for separation abilities of time-dependent dynamical systems concerning massless tracer particles
- in particular concerning Lagrangian view in vector fields: placing two close-by particles into and moving with the flow



Fig.: Path line separation, Source: ④

Glyphs

- glyphs are used to represent the principal component ellipsoid, i.e., the anisotropy characteristics and/or tensor magnitude
- glyphs can be found in varying shapes, we define ellipsoids here for simplicity

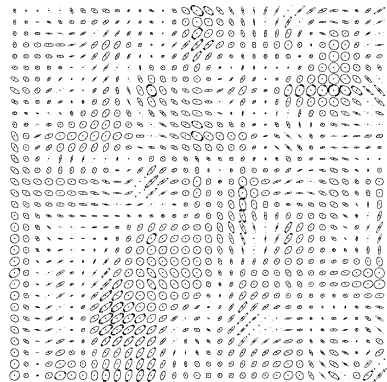


Fig.: 2D glyphs for Random field

Tensor Field Lines

Procedure

follow major/minor eigenvectors along pathlines

- ambiguity for nearly isotropic cases: small changes in magnitude effect large changes in glyph orientation
- therefore susceptible to noise in data

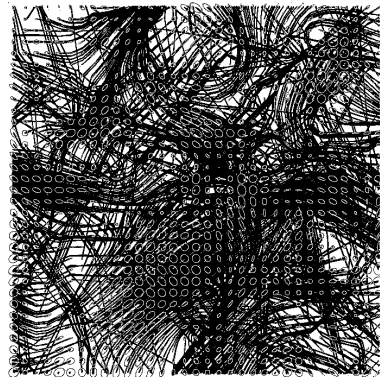


Fig.: 2D glyphs and tensor field lines

Asymmetric Tensor Fields

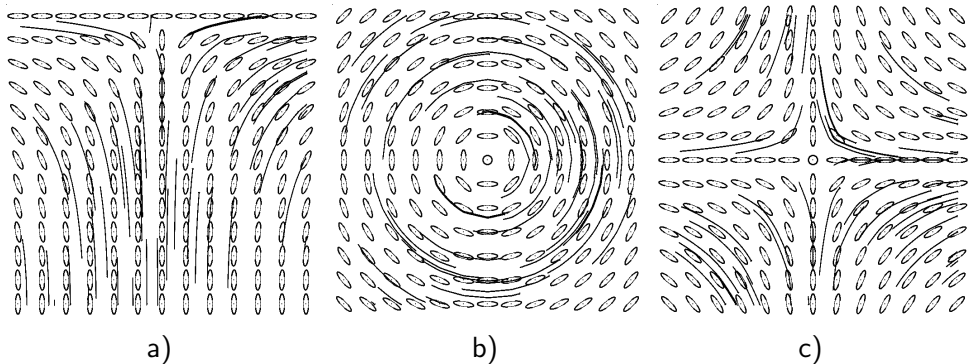


Fig.: Several test fields: a) Drain, Rings, Inverse

Symmetric Tensor Fields

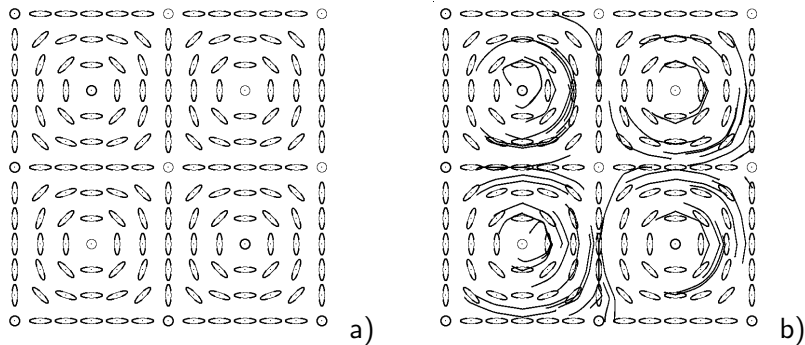
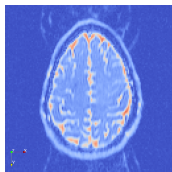
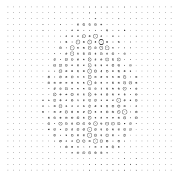


Fig.: Gyre test field: a) glyphs, b) tensor field lines for a)

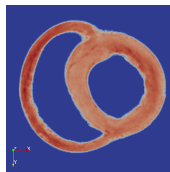
Asymmetric Tensor Fields



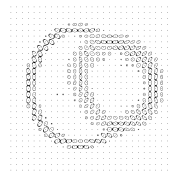
a)



b)



a)



b)

Fig.: Brain and Heart dataset: a) tensor magnitude, b) ellipsoid glyphs

Outline

- 1 Introduction
- 2 Fundamentals
- 3 Method
- 4 Results and Evaluation
- 5 Conclusion and Future Work

Outline

- 1 Introduction
- 2 Fundamentals
- 3 Method
- 4 Results and Evaluation
- 5 Conclusion and Future Work

Outline

- 1 Introduction
- 2 Fundamentals
- 3 Method
- 4 Results and Evaluation
- 5 Conclusion and Future Work

Summary

- GANs: new framework for estimating **generative models** defined by multilayer perceptrons (Convolutional Layers) trained by standard backpropagation → no need for any Markov chains (MCMC-approaches), which can have problems Mixing (Converging)
- Results Samples considered to be **competitive** with those of the state-of-the-art generative models
- Empirical Evaluation (Fitting a Gaussian Parzen window to measure distribution similarity of p_g as log-likelihood metric) indicates comparable scores than achieved for state-of-the-art methods like DBNs, Stacked CAE, GSN, Adversarial nets and **comparable validity/representativity**

Conclusion

- approach is, besides DGMs (directed graphical models), the only one, inducing **no problems** or further elaborations for sampling (generating samples) or training → rather simple implementation
- experiments show **comparable similarities** against state-of-the-art methods in log-likelihood score and variance in matching the prior distribution p_z with the generative one (p_g), but the method proposed is regarded to be more simple than others
- the **synchronization of D** is yet an effortful factor, since sufficient reasoning for the number of steps of the inner loop is needed to avoid the previously named "Helvetica scenario"!
- **future applications** might involve the synthetic generation of morphologically correct segmentation masks of separable objects, fake images (databases), keys/passwords (cryptography), image processing

Outlook

Straightforward extensions:

- 1 Conditional generative Model $p(\mathbf{x}|c)$ w. adding condition c
- 2 Learned approximate inference: Predict prior- z w. given latent x
- 3 Modeling of multiple Conditionals: $p(\mathbf{x}_S|\mathbf{x}_S^{\setminus})$
- 4 Semi-Supervised Learning: Better Performance w. partially labeled training data
- 5 Efficiency improvements: Better methods to coordinate G and D , better distributions to sample z from during training

Questions?



Sources and further reading

Literature

- 1 Goodfellow, Ian, et al. "Generative adversarial nets."
- 2 Izadi, Saeed & Mirikharaji, Zahra & Kawahara, Jeremy & Hamarneh, Ghassan. Generative adversarial networks to segment skin lesions.

Images

- 1 <https://www.sevendaysvt.com/vermont/some-counterfeiters-still-do-it-old-school/Content?oid=3276910>
- 2 <https://www.altoros.com/blog/the-diversity-of-tensorflow-wrappers-gpus-generative-adversarial-networks-etc/> & <https://medium.freecodecamp.org/an-intuitive-introduction-to-generative-adversarial-networks-gans-7a2264a81394>
- 3 Goodfellow, Ian, et al. "Generative adversarial nets."