

# RL: Basics

## The Markov Reward Process

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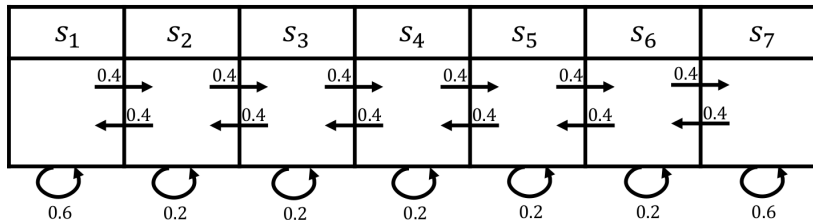


Automated  
Machine Learning  
Hannover

# Markov Reward Process (MRP)

- Extend Markov Process by rewards
- Definition of Markov Reward Process (MRP)  $M = (S, P, R, \gamma)$ 
  - ▶  $S$  is a (finite)
  - ▶  $P$  is dynamics/transition model that specifies  $P(s_{t+1} = s' \mid s_t = s)$
  - ▶  $R$  is a reward function  $R(s_t = s) = \mathbb{E}[r_t \mid s_t = s]$
  - ▶ Discount factor  $\gamma \in [0, 1]$
- Note: no actions
- If finite number ( $N$ ) of states, we can express  $R$  as a vector

# Mars Rover as MRP



Rewards:

- +1 in  $s_1$ ,
- +10 in  $s_7$ ,
- 0 in all other states

- Definition of Horizon

- ▶ Number of time steps in each episode
- ▶ Can be infinite
- ▶ Otherwise called finite Markov reward process

# Return & Value Function

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  - ▶ Can be infinite
  - ▶ Otherwise called finite Markov reward process
- Definition of Return:  $G_t$  (for a MRP)
  - ▶ Discounted sum of rewards from time step  $t$  to horizon

$$G_t = r_t + \gamma r_{t+1} + \gamma^2 r_{t+2} + \gamma^3 r_{t+3} + \dots$$

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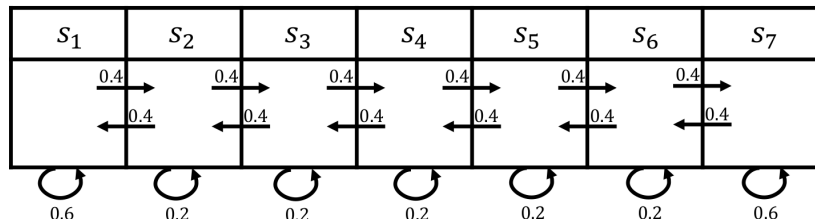
- Definition of State Value Function:  $V(s)$  for a MRP
  - ▶ Expected return from starting in state  $s$

$$V(s) = \mathbb{E}[G_t \mid s_t = s] == \mathbb{E}[r_t + \gamma r_{t+1} + \gamma^2 r_{t+2} + \gamma^3 r_{t+3} + \dots \mid s_t = s]$$

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- Mathematically convenient (avoid infinite returns and values)
- Humans often act as if there's a discount factor  $\gamma < 1$
- $\gamma = 0$ : Only care about immediate reward
- $\gamma = 1$ : Future reward is as beneficial as immediate reward
- If episode lengths are always finite, can use  $\gamma = 1$  (but don't have to)

# Mars Rover as MRP



Rewards:

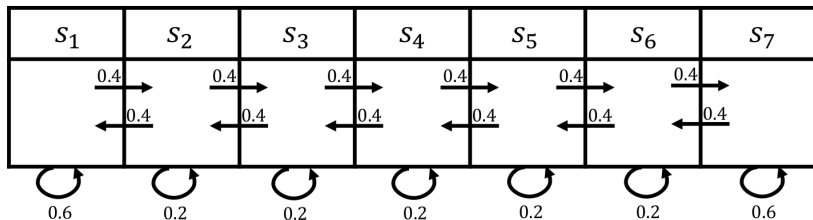
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Sample returns for 4-step episodes,  $\gamma = 1/2$

- $s_4, s_5, s_6, s_7 : 0 + \frac{1}{2} \cdot 0 + \frac{1}{4} \cdot 0 + \frac{1}{8} \cdot 10 = 1.25$



# Mars Rover as MRP



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$$\rightsquigarrow V(s_1) = 1.53, V(s_2) = 0.37, \dots, V(s_7) = 15.31$$

# Computing the Value of a Markov Reward Process

- Could estimate by simulation:
  - 1 Generate a large number of episodes
  - 2 Average returns
- Requires no assumption of Markov structure

# Computing the Value of a Markov Reward Process

- Could estimate by simulation:
- Markov property yields additional structure
- MRP value function satisfies

$$V(s) = R(s) + \gamma \sum_{s' \in S} P(s' \mid s) V(s')$$

# Matrix Form of Bellman Equation for MRP

$$\begin{pmatrix} V(s_1) \\ \dots \\ V(s_n) \end{pmatrix} = \begin{pmatrix} R(s_1) \\ \dots \\ R(s_n) \end{pmatrix} + \gamma \begin{pmatrix} P(s_1|s_1) & \dots & P(s_n | s_1) \\ \dots & & \\ P(s_1|s_n) & \dots & P(s_n | s_n) \end{pmatrix} \begin{pmatrix} V(s_1) \\ \dots \\ V(s_n) \end{pmatrix}$$

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$$V = R + \gamma PV \quad (1)$$

$$V - \gamma PV = R \quad (2)$$

$$(1 - \gamma P)V = R \quad (3)$$

$$V = (1 - \gamma P)^{-1} R \quad (4)$$

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↪ Solving directly requires taking a matrix inverse  $O(n^3)$

# Iterative Algorithm for Computing Value of a MRP

- Dynamic Programming :
  - ▶ Initialize  $V_0(s) = 0$  for all  $s$
  - ▶ For  $k = 1$  until convergence
    - ★ For all  $s$  in  $S$

$$V_k(s) = R(s) + \gamma \sum_{s' \in S} P(s' | s) V_{k-1}(s')$$

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- Computational complexity:  $O(|S|^2)$  for each iteration ( $|S| = n$ )