

## Recitation 12 - NP-Completeness

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# Introduction

- Most algorithms we've looked at thus far has had a polynomial running time.
  - Input size  $n \Rightarrow \mathcal{O}(n^k)$  for some constant  $k$ .
- Not all problems can be solved in polynomial time, however.
- Some problems can't be solved at all, regardless of how much time we're given.
- NP-complete problems: status unknown.
  - No polynomial time algorithm has been found for an NP-complete problem.
  - No one has proved that no polynomial algorithm can exist for any NP-complete problem.
- This is the famous  $P = NP$  question.

# Slippery slope into NP-Complete land

- Some NP-complete problems are only slight variations on problems we've seen before:
  - SSSP: no problem. Longest path is NP-complete.
  - Euler tour of a graph is a cycle that traverses each edge exactly once. This can be solved in  $\mathcal{O}(E)$  time. A Hamiltonian cycle of a graph is a cycle containing each vertex. The problem of finding a Hamiltonian cycle is NP-complete.

# Complexity classes

- The class  $P$  consists of problems solvable in polynomial time.
  - $\Rightarrow \mathcal{O}(n^k)$  for constant  $k$ .
- The class  $NP$  consists of problems that are *verifiable* in polynomial time.
  - Given a “certificate” of a solution, we can verify its correctness in polynomial time (as a function of problem size).
- Note that any problem in  $P$  is also in  $NP$ , since we can generate the solution of a problem in  $P$  in polynomial time without a certificate.
- The NP-complete ( $NPC$ ) class refers to any problem that is as hard as any problem in  $NP$ .
  - If *any*  $NPC$  problem can be solved in polynomial time, then *all*  $NPC$  problems can be solved in polynomial time.

## Complexity classes, cont.

- It is conjectured that  $P \neq NP$ , simply given the large number of NP-complete problems in existence. It would be remarkable if it turned out that *all* of them could be solved in polynomial time.
- From a practical perspective, why would you care about complexity classes?
  - If you could show that the problem you are trying to solve is NP-complete, you could then spend your time developing an efficient approximation algorithm instead of trying to solve the problem exactly.

# Decision vs. Optimization

- NP-completeness applies to decision problems, not optimization problems.
  - Decision problems are problems to which we get either 1 or 0 (yes or no).
  - Optimization problems involve finding the best solution out of many feasible solutions, e.g. SSSP.
- So how can we apply NP-completeness to optimization problems?
- → cast an optimization problem as a decision problem.
  - Impose a bound on the value to be optimized.
  - For example, in shortest path we could ask: Given a directed graph  $G$ , source vertex  $s$  and destination vertex  $t$ , and an integer  $k$ , does a path exist from  $s$  to  $t$  consisting of at most  $k$  edges?
  - Solve shortest path, count edges in shortest path and compare to decision parameter  $k$ .
- If an optimization problem is easy, its related decision problem is easy as well.

# Reductions

- We want to show that two problems are equally hard (even when both are decision problems).
- Let  $A$  be a decision problem we wish to solve (in polynomial time).
- Assume we already know how to solve some other decision problem  $B$  in polynomial time, and that we can transform any instance  $\alpha$  of  $A$  into some instance  $\beta$  of  $B$  such that
  - The transformation itself takes polynomial time.
  - The answers to the two problems are the same, i.e. the answer for  $\alpha$  is 1 iff answer to  $\beta$  is 1.
- This is called a reduction algorithm.
- Given a reduction algorithm, we can solve  $A$ :
  - Transform an instance  $\alpha$  in  $A$  to an instance  $\beta$  in  $B$ .
  - Run the polynomial decision algorithm for  $B$  on  $\beta$ .
  - Use the answer for  $\beta$  as the answer for  $\alpha$ .

## Reductions, cont.

- Goal: Use polynomial-time reductions to show that no polynomial-time algorithm can exist for a particular problem  $B$ .
- Suppose we have a decision problem  $A$  for which we know no polynomial-time algorithm can exist.
- Also suppose that we have a polynomial-time reduction to transform an instance in  $A$  to an instance in  $B$ .
- For a contradiction, assume that  $B$  has a polynomial-time algorithm.
- Then we could use a reduction to conclude that  $A$  has a polynomial-time algorithm, which contradicts our assumption.
- Proof methodology: Can't assume no polynomial algorithm exists for  $A$  (for NP-complete). Instead, prove  $B$  is NP-complete on the assumption that  $A$  is also NP-complete.



# Boolean Satisfiability

- Our methodology for proving that a problem is NP-complete requires a reduction to a problem we *know* is NP-complete.
- But at this point we don't know any such algorithms.
- The problem we choose to use is that of Boolean Satisfiability, i.e. the problem of deciding whether a string of boolean variables, chained together with *AND*, *OR*, and *NOT* operations, can return 1 (true).
- Cook-Levin Theorem states that Boolean Satisfiability is NP-complete.

# Subset-sum problem

- Given a finite set  $S$  of positive integers and a target  $t > 0$ , does there exist a subset  $S' \subseteq S$  whose elements sum to  $t$ ?
- SUBSET-SUM =  $\{(S, t) : \exists \text{ subset } S' \subseteq S \text{ such that } \sum_{s \in S'} s = t\}$ .

# Subset-sum is NP-complete

- **Proof:**

- First show that SUBSET-SUM  $\in NP$ .
- Easy to check whether a finite set of integers add up to  $t$ .  
→ polynomial time verification.
- To show that SUBSET-SUM is NP-complete, we reduce an instance of 3-CNF-SAT to one of SUBSET-SUM.
- Given a 3-CNF formula  $\phi = x_1, x_2, \dots, x_n$  with  $k$  clauses  $C_1, C_2, \dots, C_k$  (each of which contains three literals), we aim to construct an instance  $(S, t)$  of SUBSET-SUM.
- Want to show that  $\phi$  is satisfiable iff there exists a subset of  $S$  whose sum is exactly  $t$ .
- Let's assume (WLOG) that no clause contains both a variable and its negation, for that automatically satisfies the clause.
- Also assume that each variable appears in some clause, otherwise it wouldn't matter what value we assigned to it.

## Subset-sum proof, cont.

- Construct set  $S$  and target  $t$  as follows:
  - Create two numbers in  $S$  for each variable  $x_i$  and two numbers in  $S$  for each clause  $C_j$ .
  - Each number has  $n + k$  digits.
  - The target  $t$  has a 1 in each variable digit and 4 in each clause digit.
  - For each variable  $x_i$ ,  $S$  contains two integers  $v_i$  and  $v'_i$ . Each  $v_i$  and  $v'_i$  has a 1 in the variable digit  $x_i$  and a 0 in every other variable digit. In addition, if  $x_i$  appears in clause  $C_j$ , then the corresponding clause digit gets assigned a 1.
  - Furthermore, each clause  $C_j$  contains two integers  $s_j$  and  $s'_j$ . Each  $s_j$  and  $s'_j$  has a 0 in the variable digits.  $s_j$  gets a 1 in the  $C_j$  digit and  $s'_j$  gets a 2 in the  $C_j$  digit.

## Subset-sum proof, cont.

- Note: The greatest sum of any of the digit positions is 6. Why?
- Thus, if we use, e.g. base 10 to interpret these numbers, no carry can occur from lower to higher digits.
- We can perform this reduction in polynomial time, i.e. each of the  $n + k$  digits can be produced in constant time, and there are  $2n + 2k$  such numbers, each of which has  $n + k$  digits.
- Now we just need to show that the 3-CNF-SAT FORMULA  $\phi$  is satisfiable iff there exists a subset  $S' \subseteq S$  whose sum is  $t$ .

## Subset-sum proof, cont.

- $\Rightarrow$ : Suppose that  $\phi$  has a satisfying assignment.
- For  $i = 1, \dots, n$ , if  $x_i = 1$  in this assignment, then include  $v_i$  in  $S'$ , otherwise include  $v'_i$ .
- So we only include the  $v_i$  and  $v'_i$  numbers that correspond to literals with value 1.
- Since we include only one of  $v_i$  or  $v'_i$  and since we labeled the variable digits for  $s_j$  and  $s'_j$  with 0, the sum of any variable digit in  $S'$  must be 1 (which matches that of the target  $t$ ).
- Because we have a satisfying assignment, each clause must contain a 1, meaning each clause digit has at least one 1 (could be 1, 2, or 3) contributed to its sum by  $v_i$  or  $v'_i$  in  $S'$ .
- To get the clause digit sum to add to 4, we include in  $S'$  the appropriate slack values.

## Subset-sum proof, cont.

- $\Leftarrow$ : Suppose that there is a subset  $S' \subseteq S$  that sums to  $t$ .
- $S'$  must include one of  $v_i$  or  $v'_i$  for each  $i = 1, \dots, n$ .
- If  $v_i \in S'$ , set  $x_i = 1$ , otherwise if  $v'_i \in S'$ , set  $x_i = 0$ .
- To get any clause digit  $C_j$  to sum to 4,  $S'$  must include one  $v_i$  or  $v'_i$  that has value 1 in  $C_j$ , since the slack variables account for a value of at most 3.
- If  $S'$  includes a  $v_i$  that has a 1 in position  $C_j$ , then  $x_i$  appears in clause  $C_j$ . We have set this  $x_i = 1$  when  $v_i \in S'$ , so clause  $C_j$  is satisfied.
- If  $S'$  includes a  $v'_i$  with a 1 in position  $C_j$ , then  $\neg x_i$  appears in  $C_j$ , which we have set to  $x_i = 0$  when  $v'_i \in S'$ , which again satisfies the clause  $C_j$ .
- That satisfies all clauses, so  $\phi$  itself is satisfied.

## Example of 3-CNF-SAT to Subset-sum reduction

- Consider the following 3-CNF-SAT formula:
- $\phi = (x_1 \vee \neg x_2 \vee \neg x_3) \wedge (\neg x_1 \vee \neg x_2 \vee \neg x_3) \wedge (\neg x_1 \vee \neg x_2 \vee x_3) \wedge (x_1 \vee x_2 \vee x_3)$ .
- $n = 3$  variables,  $k = 4$  clauses.
- Let's apply the reduction to subset-sum.
- Fill out the following table using our reduction algorithm:



## Example, cont.

-	$x_1$	$x_2$	$x_3$	$C_1$	$C_2$	$C_3$	$C_4$
$v_1$	-	-	-	-	-	-	-
$v_1'$	-	-	-	-	-	-	-
$v_2$	-	-	-	-	-	-	-
$v_2'$	-	-	-	-	-	-	-
$v_3$	-	-	-	-	-	-	-
$v_3'$	-	-	-	-	-	-	-
$s_1$	-	-	-	-	-	-	-
$s_1'$	-	-	-	-	-	-	-
$s_2$	-	-	-	-	-	-	-
$s_2'$	-	-	-	-	-	-	-
$s_3$	-	-	-	-	-	-	-
$s_3'$	-	-	-	-	-	-	-
$s_4$	-	-	-	-	-	-	-
$s_4'$	-	-	-	-	-	-	-
$t$	-	-	-	-	-	-	-

## Example, cont.

-	$x_1$	$x_2$	$x_3$	$C_1$	$C_2$	$C_3$	$C_4$
$v_1$	1	0	0	1	0	0	1
$v_1'$	1	0	0	0	1	1	0
$v_2$	0	1	0	0	0	0	1
$v_2'$	0	1	0	1	1	1	0
$v_3$	0	0	1	0	0	1	1
$v_3'$	0	0	1	1	1	0	0
$s_1$	0	0	0	1	0	0	0
$s_1'$	0	0	0	2	0	0	0
$s_2$	0	0	0	0	1	0	0
$s_2'$	0	0	0	0	2	0	0
$s_3$	0	0	0	0	0	1	0
$s_3'$	0	0	0	0	0	2	0
$s_4$	0	0	0	0	0	0	1
$s_4'$	0	0	0	0	0	0	2
$t$	1	1	1	4	4	4	4

## Example, cont.

- Sample satisfying assignment:  $x_1 = 0, x_2 = 0, x_3 = 1$ .
- We now have our  $S$  for the subset problem:

$$\begin{aligned} S &= \{v_1, v'_1, v_2, v'_2, v_3, v'_3, s_1, s'_1, s_2, s'_2, s_3, s'_3, s_4, s'_4\} \\ &= \{1001001, 1000110, 100001, 101110, 10011, 11100, \\ &\quad 1000, 2000, 100, 200, 10, 20, 1, 2\} \end{aligned} \tag{1}$$

- We also have our subset  $S'$ , i.e.  $S' = \{v'_1, v'_2, v_3, s_1, s'_1, s'_2, s_3, s_4, s'_4\}$ .
- Note that the members of  $S'$  sum to  $t$ :
- $1000110 + 101110 + 10011 + 1000 + 2000 + 200 + 10 + 1 + 2 = 1114444$ .