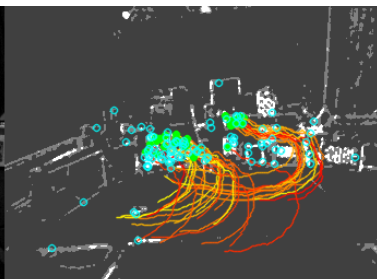
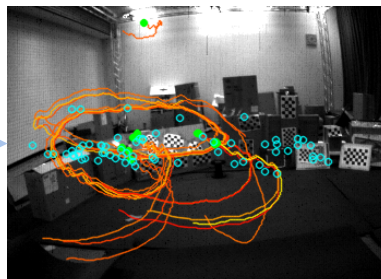


Depth estimation



Enhanced event image & ORB-based tracking