

1 2 3 4 5 6

Prelim. research period



Research details of chosen actuation/power/control methods



Review and finalise plans with supervisor. Alter if required.



Project lab work begins

Design robot morphology. Finalise with supervisor

Fabricate MFCs

Test MFC capabilities and ensure correct function

Fabricate actuators

Test actuator capabilities, ensure correct function

Fabricate full prototype

Test prototype capabilities

Dissertation write up



