



**THE MOST COMPLETE STARTER KIT**

**TUTORIAL FOR UNO**

## Preface

### Our Company

Established in 2011, Elegoo Inc. is a professional manufacturer and exporter that is involved in the design, development, production and marketing of Arduino accessories, 3D printers, Raspberry Pi accessories and STM32. We are located in Shenzhen which is known as the Chinese Silicon Valley. All of our products comply with international quality standards and are greatly appreciated in a variety of different markets throughout the world.

Official website: <http://www.elegoo.com>

US Amazon storefront: <http://www.amazon.com/shops/A2WWHQ25ENKVJ1>

### Our Tutorial

This tutorial is geared for beginners. You will learn all the basic information about how to use Arduino controller board, sensors and components. If you want to study Arduino in more depth, we recommend that you read the Arduino Cookbook written by Michael Margolis.

### Our after-sales

If you have any question, comment or suggestion about our company, product or tutorial, please don't hesitate to send an email to [service@elegoo.com](mailto:service@elegoo.com). We are committed to continuous improvement so your feedback is invaluable.

# Packing list

[www.elegoo.com](http://www.elegoo.com)



Servo Motor  
(SG90)  
1PC



ULN2003 Stepper  
Motor Driver  
Board  
1PC



Power Supply  
Module  
1PC



Elegoo UNO R3  
Controller  
Board  
1PC



ADXL335 Module  
1PC



LCD 1602 Module  
(with pin header)  
1PC



Rc522  
RFID Module  
1PC



Stepper Motor  
1PC



Prototype Expansion  
Board  
1PC

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IR Receiver  
Module  
1PC



Joystick Module  
1PC



DHT11 Temperature  
and Humidity  
Module  
1PC



Ultrasonic Sensor  
1PC



Rotary Encoder  
Module  
1PC



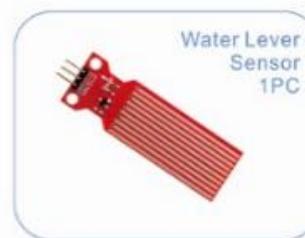
Ds3231 RTC  
Module  
1PC



HC-SR501 PIR  
Motion Sensor  
1PC



Sound Sensor  
Module  
1PC



Water Lever  
Sensor  
1PC

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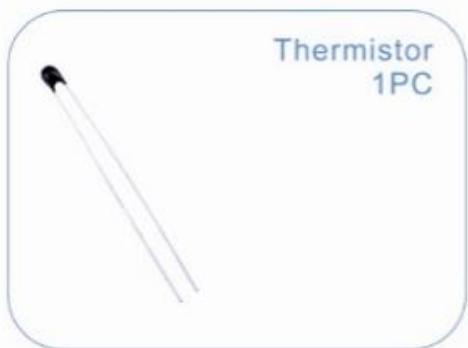
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Red LED  
5PCS



Yellow LED  
5PCS



Blue LED  
5PCS



Photoresistor  
(Photocell)  
2PCS



Green LED  
5PCS



RGB LED  
1PC



White LED  
5PCS



22pF Ceramic  
Capacitor  
5PCS



104pF Ceramic  
Capacitor  
5PCS

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# Lesson 0 Installing IDE

## Introduction

In this lesson, you will learn how to setup your computer to use Arduino and how to set about the lessons that follow.

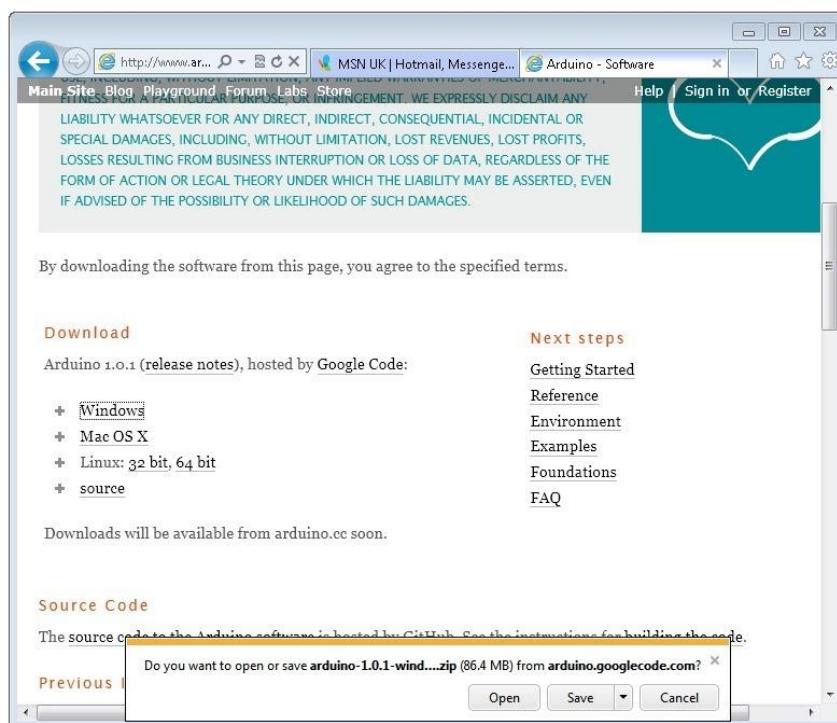
The Arduino software that you will use to program your Arduino is available for Windows, Mac and Linux. The installation process is different for all three platforms and unfortunately there is a certain amount of manual work to install the software. There is no installer program, but rather you have to unzip a folder which gives you an Arduino folder that contains the Arduino program and a few other items.

In a separate step, you must then install USB drivers,

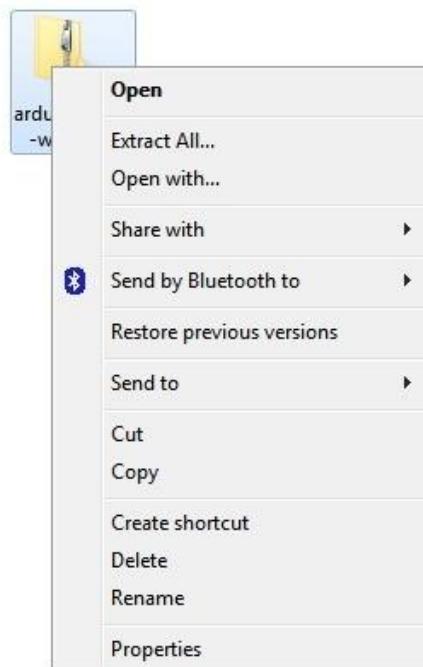
## Installing Arduino (Windows)

Get started by visiting the Arduino.cc website. As of April 2014, we suggest using v1.05 as 1.5 is still in beta. If 1.5 is no longer in beta by the time you read this, you can try it out!

Start by downloading the zip file for Windows. There is only one version of the software, whether you are using Windows XP through to Windows 7.



When the zip file has downloaded, extract the contents onto the Desktop, by right-clicking on the file and selecting 'Extract All...' from the pop-up menu.



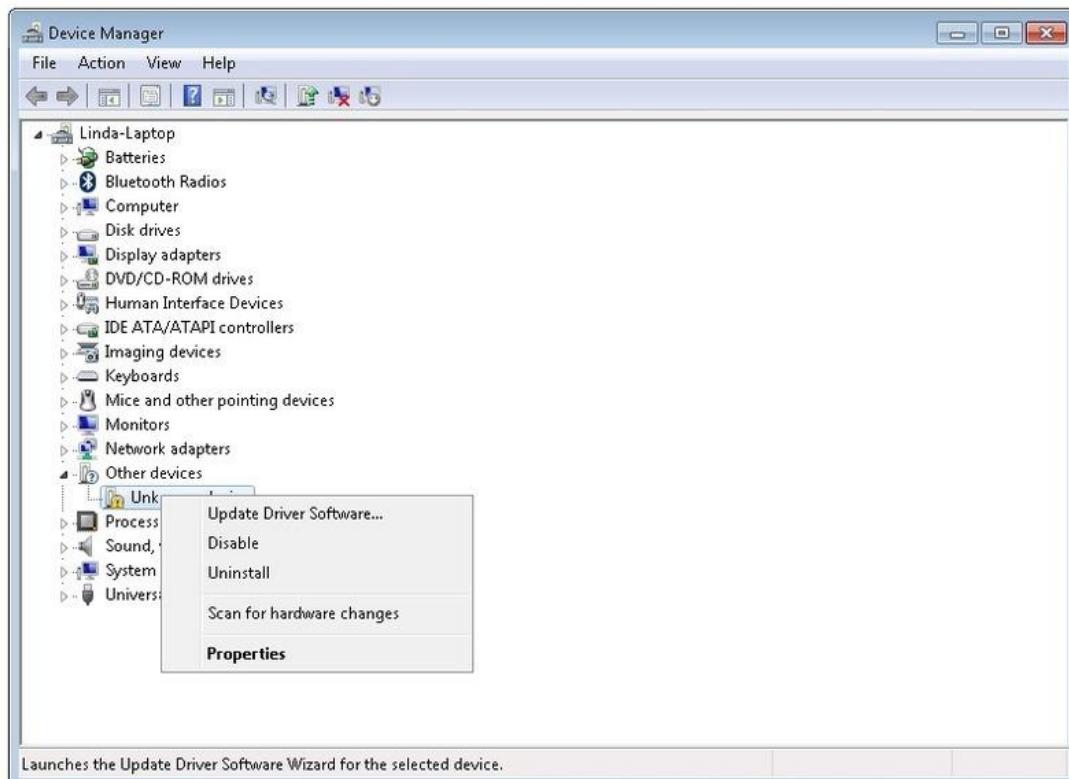
Next, select your Desktop and click 'Extract'. You can move it somewhere else onto your computer later, just by moving the folder, but for now, just keep it on the Desktop.

The Arduino folder contains both the Arduino program itself and the drivers that allow the Arduino to be connected to your computer by a USB cable. Before we launch the Arduino software, you are going to install the USB drivers.

Plug one end of your USB cable into the Arduino and the other into a USB socket on your computer. The power light on the LED will light up and you may get a 'Found New Hardware' message from Windows. Ignore this message and cancel any attempts that Windows makes to try and install drivers automatically for you.

The most reliable method of installing the USB drivers is to use the Device Manager. This is accessed in different ways depending on your version of Windows. In Windows 7, you first have to open the Control Panel, then select the option to view Icons, and you should find the Device Manager in the list.

Under 'Other Devices', you should see an icon for 'unknown device' with a little yellow warning triangle next to it. This is your Arduino.



Right-click on the device and select the top menu option (Update Driver Software...). You will then be prompted to either 'Search Automatically for updated driver software' or 'Browse my computer for driver software'. Select the option to browse and navigate to the arduino-1.0.2-windows\arduino1.0.2\drivers.



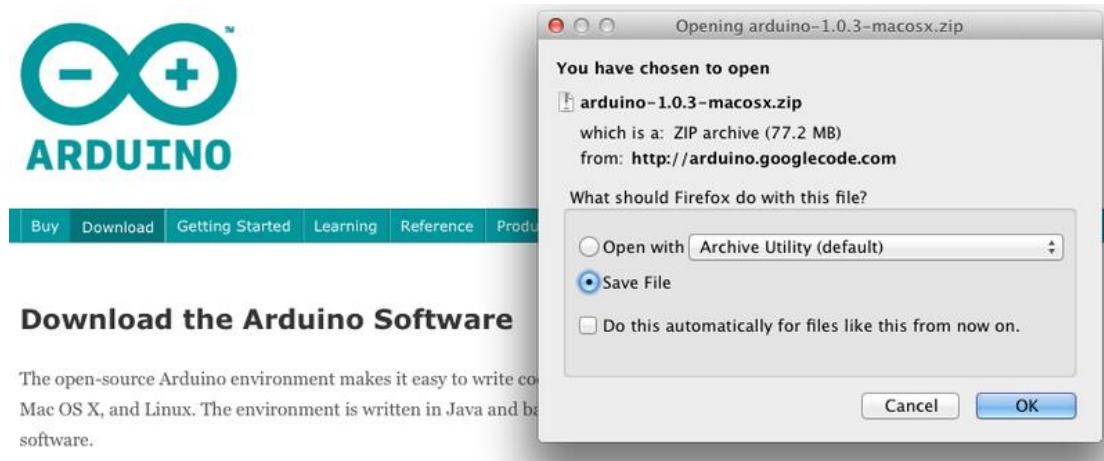
Click 'Next' and you may get a security warning, if so, allow the software to be installed. Once the software has been installed, you will get a confirmation message.



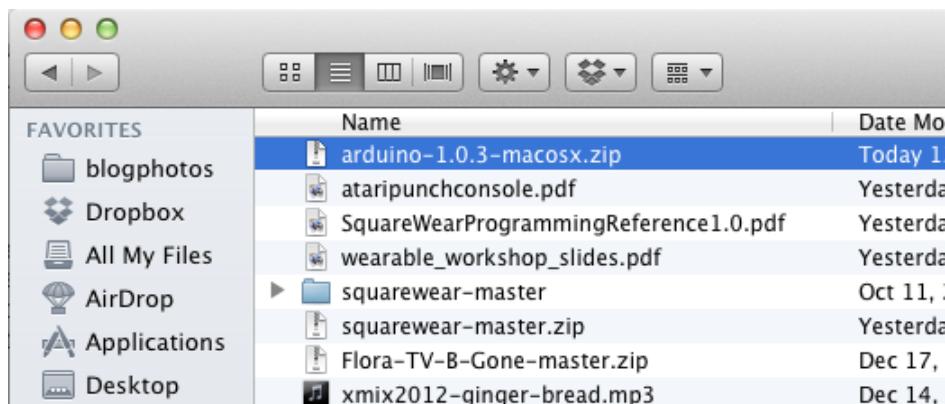
That's it, you are now ready for action, so Skip the next section on installation on Mac and Linux and move straight on to 'Boards and Ports'.

## Installing Arduino (Mac and Linux)

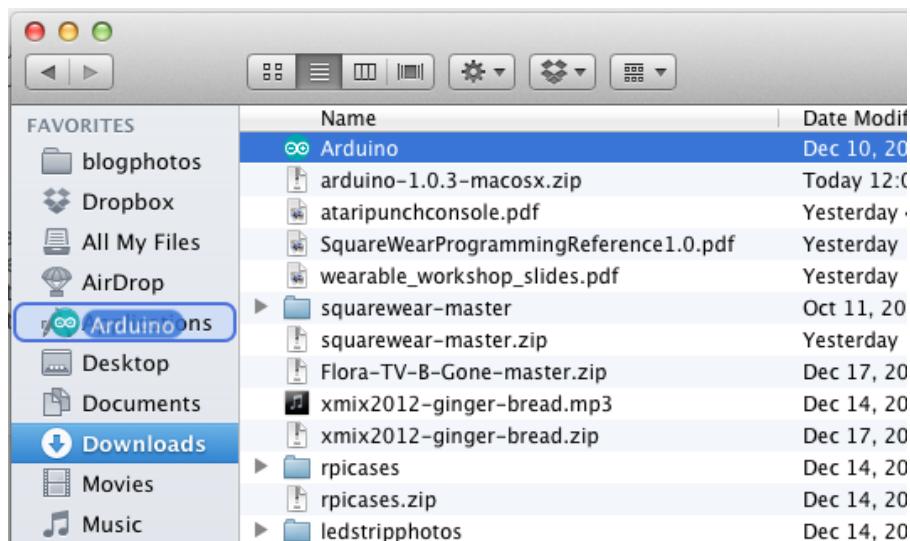
Get started by visiting the Arduino.cc website and downloading the matching IDE for your operating system. As of April 2014, we suggest using v1.05 as 1.5 is still in beta. If 1.5 is no longer in beta by the time you read this, you can try it out!

The image shows two side-by-side screenshots. On the left is the Arduino website homepage with the Arduino logo and navigation links for Buy, Download, Getting Started, Learning, Reference, and Products. A prominent "Download the Arduino Software" button is visible. On the right is a Mac OS X file download dialog box titled "Opening arduino-1.0.3-macosx.zip". It displays the file path, type (ZIP archive), and source (http://arduino.googlecode.com). It asks "What should Firefox do with this file?", with "Save File" selected. There are checkboxes for "Open with Archive Utility (default)" and "Do this automatically for files like this from now on.". At the bottom are "Cancel" and "OK" buttons.

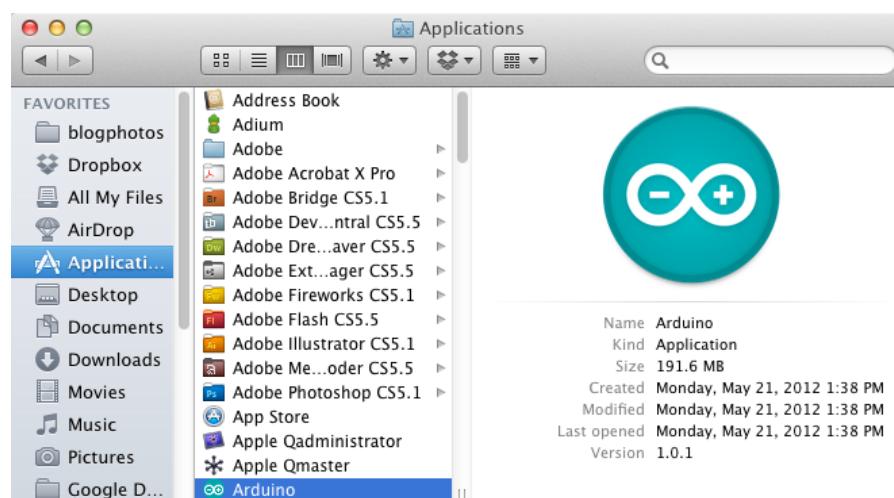
Save the install software to your desktop or wherever

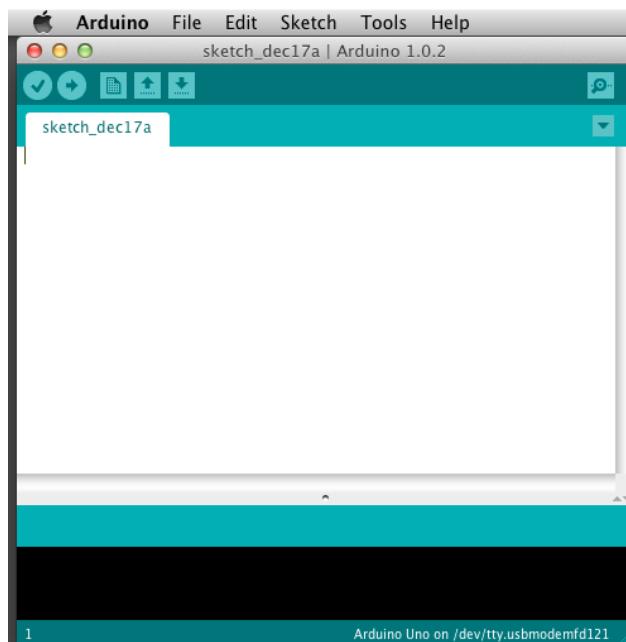


The process for installing the Arduino software on the Mac is a lot easier than on the PC. As before, the first step is to download the file. In the case of the Mac, it is a zip file.



Once downloaded, double-click on the zip file, which will extract a single file called 'Arduino.app'. This is the whole Arduino application, just drag it into your Applications Folder.



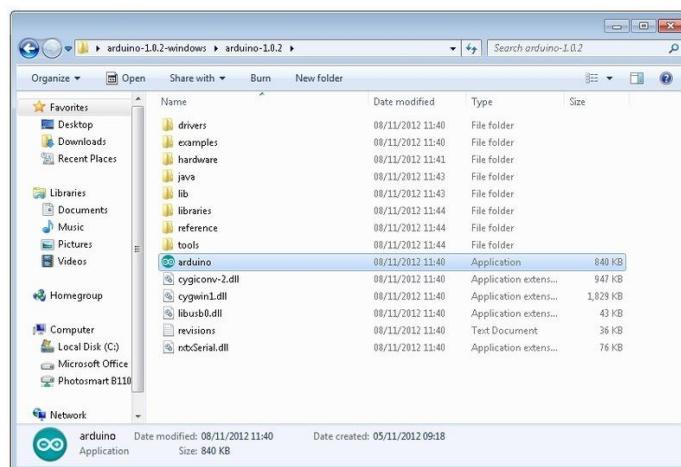


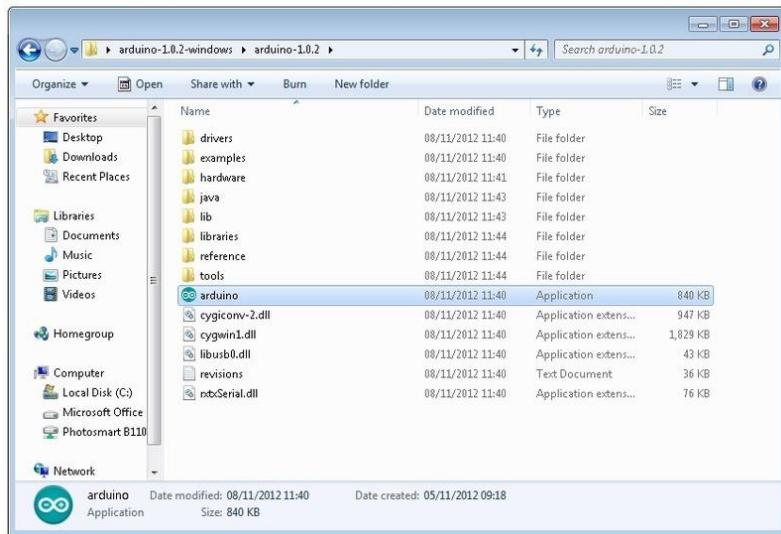
You can now find and launch the Arduino software in your Applications folder. As you are going to use it frequently, you may wish to right-click its icon in the dock and set it to 'Keep In Dock'.

There are many different LINUX distributions and the instructions for each distribution are a little different. The Arduino community has done a great job of putting together sets of instructions for each distribution.

## Boards and Ports

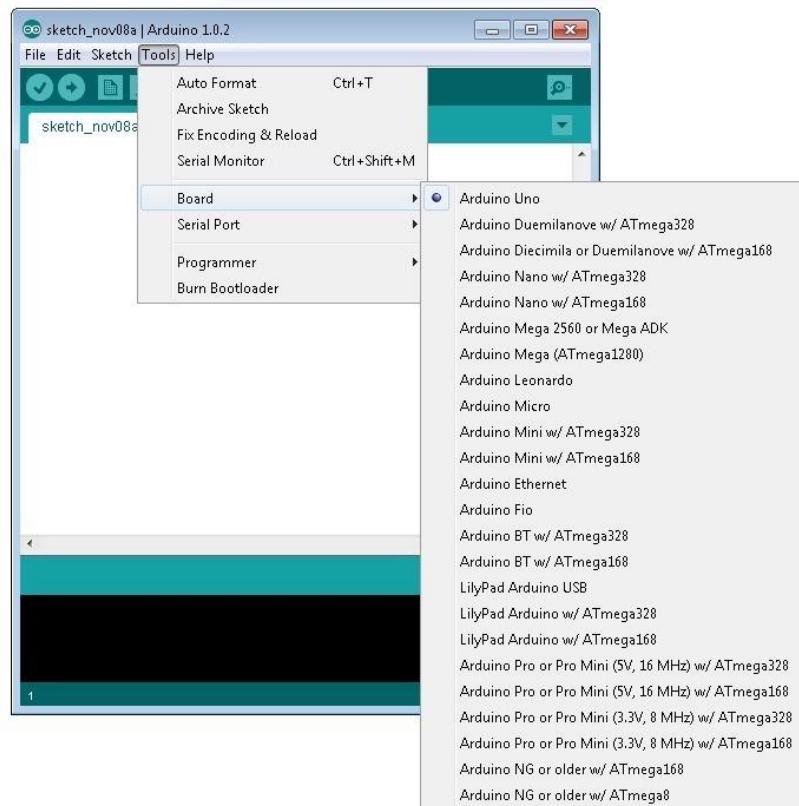
You are now ready to start the Arduino Software, so whatever platform you are using, open the Arduino folder and open the Arduino application contained within it.



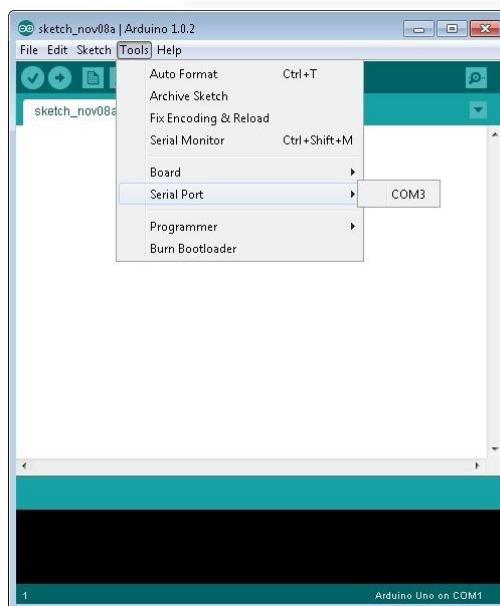


This will start the Arduino IDE, but before you can start programming, you have to tell the Arduino software which type of Arduino board you are using and also select the port to which it is connecting.

To tell the Arduino IDE which type of board you are using, from the 'Tools' menu, select Board and then 'Arduino Uno' or 'Leonardo' as appropriate.

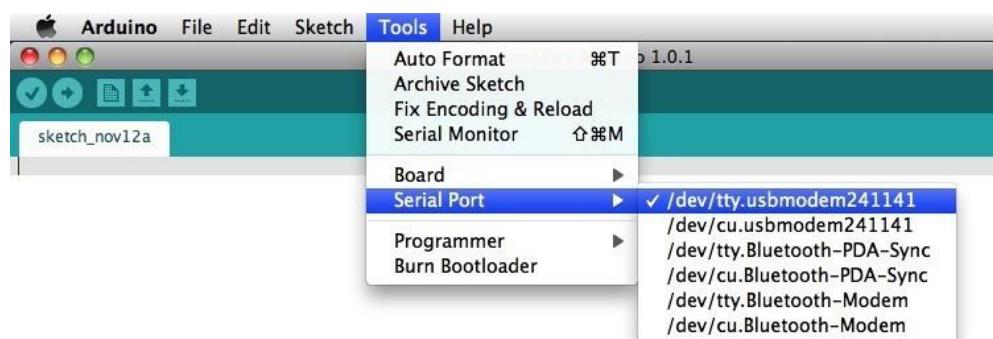


Also on the 'Tools' menu, you will find the 'Serial Port' option. Select this option.



If you are using Windows, there will probably only be one option here and it will either say COM3 or COM4. Even though there is only one option, you will still need to select it.

If you are using a Mac or Linux, there will be more options there, but it will usually be the top option in the list, as this will be the device most recently plugged in. This is useful, as the name of the port may not look like it has anything to do with Arduino. It will probably be called something like /dev/tty.usbmodemXXXX or /dev/ttYSBn.



# Lesson 1 Add Libraries

Once you are comfortable with the Arduino software and using the built-in functions, you may want to extend its functionality with additional libraries.

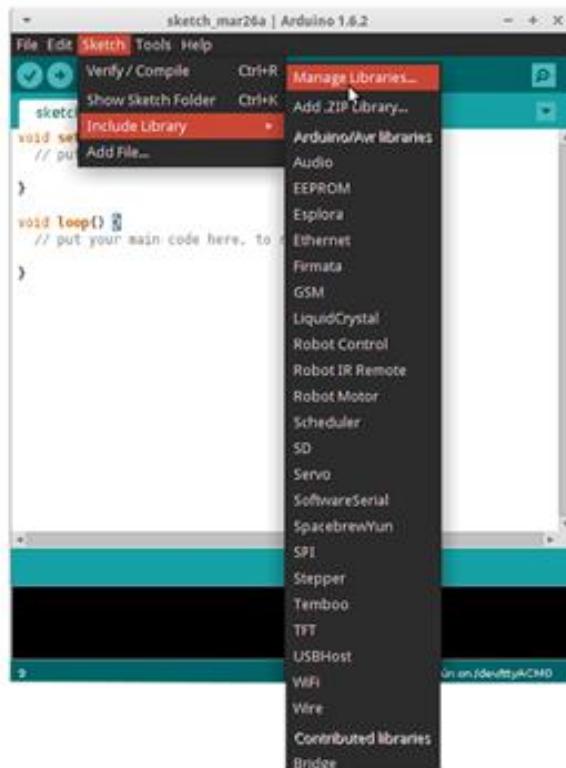
## What are Libraries?

Libraries are a collection of code that makes it easy for you to connect to a sensor, display, module, etc. For example, the built-in LiquidCrystal library makes it easy to talk to character LCD displays. There are hundreds of additional libraries available on the Internet for download. The built-in libraries and some of these additional libraries are listed in the reference. To use these additional libraries, you will need to install them.

## How to Install a Library

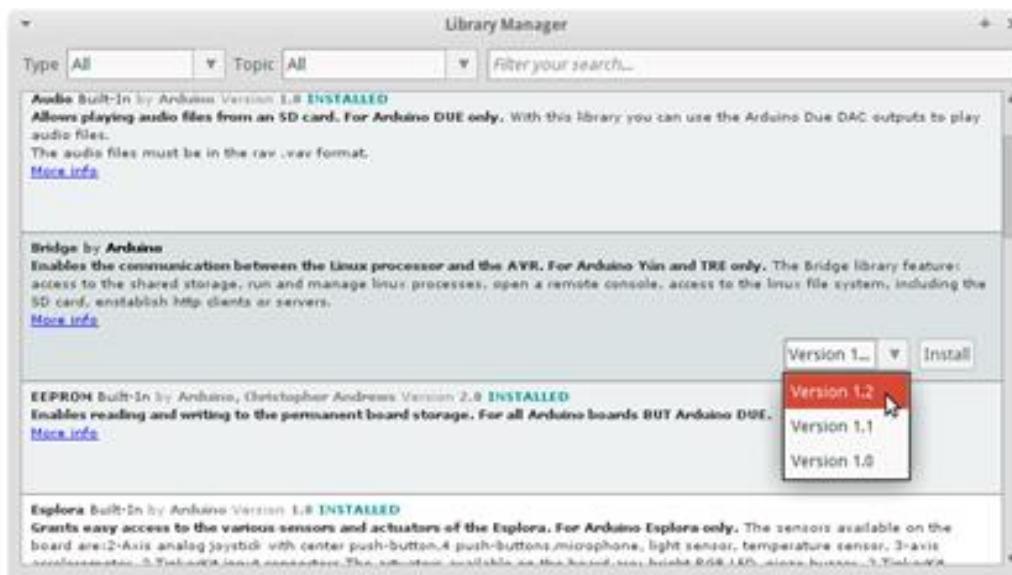
### Using the Library Manager

To install a new library into your Arduino IDE, you can use the Library Manager (available from IDE version 1.6.2). Open the IDE and click Sketch > Include > Library > Manage Libraries.

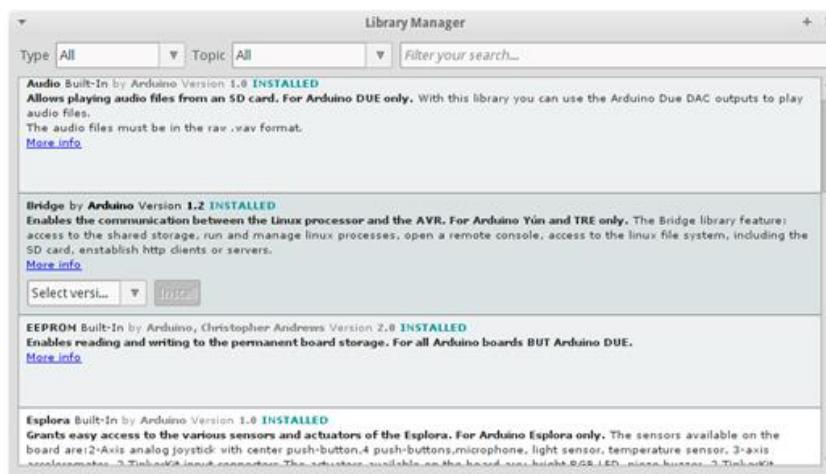


The library manager will open and you will find a list of libraries that are already installed or

ready for installation. In this example, we will install the Bridge library. Scroll down the list to find it, then select the version of the library you want to install. Sometimes, only one version of the library is available. If the version selection menu does not appear, don't worry; it is normal.



Finally click on install and wait for the IDE to install the new library. Downloading may take time depending on your connection speed. Once it has finished, an Installed tag should appear next to the Bridge library. You can close the library manager.

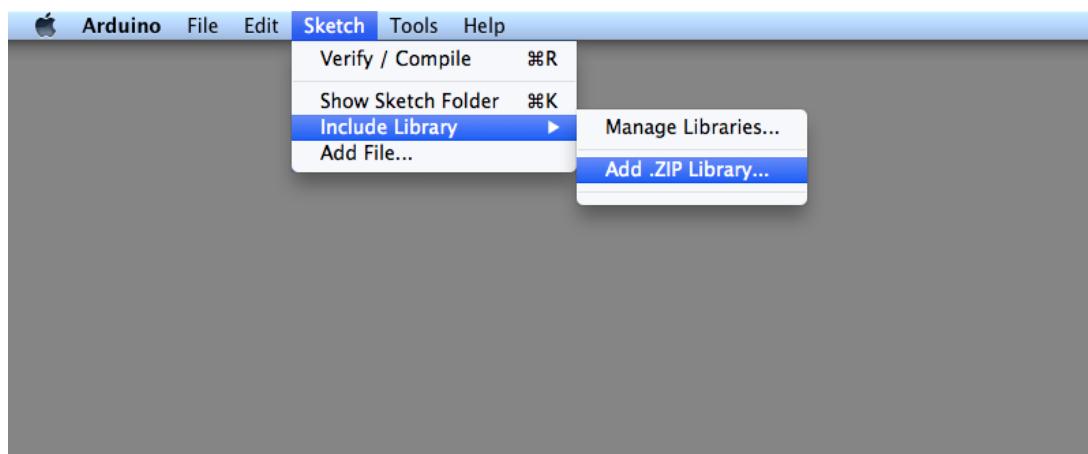


You can now find the new library available in the Include Library menu. If you want to add your own library open a new issue on github.

## Importing a .zip Library

Libraries are often distributed as a ZIP file or folder. The name of the folder is the name of the library. Inside the folder will be the following: .cpp file, .h file, often a keywords.txt file, examples folder, and other files required by the library. Starting with version 1.0.5, you can install third-party libraries in the IDE. Do not unzip the downloaded library; leave it as-is.

In the Arduino IDE, navigate to Sketch > Include Library > Add .ZIP Library.



You will be prompted to select the library you would like to add. Navigate to the .zip file's location and open it.

Return to the Sketch > Import Library menu. You should now see the library at the bottom of the drop-down menu. It is ready to be used in your sketch. The zip file will have been expanded in the libraries folder in your Arduino sketches directory.

NB: The Library will be available to use in sketches, but examples for the library will not be shown in the File > Examples until after the IDE has restarted.

## Manual installation

To install the library, first, quit the Arduino application. Then unzip the ZIP file containing the library. For example, if you're installing a library called "ArduinoParty", uncompress ArduinoParty.zip. It should contain a folder called ArduinoParty, with files like ArduinoParty.cpp and ArduinoParty.h inside. (If the .cpp and .h files aren't in a folder, you'll need to create one. In this case, you'd make a folder called "ArduinoParty" and move into it all the files that were in the ZIP file, like ArduinoParty.cpp and ArduinoParty.h.)

Drag the ArduinoParty folder into this folder (your libraries folder). Under Windows, it will likely

be called "My Documents\Arduino\libraries". For Mac users, it will likely be called "Documents/Arduino/libraries". On Linux, it will be the "libraries" folder in your sketchbook.

Your Arduino library folder should now look like this (on Windows):

My Documents\Arduino\libraries\ArduinoParty\ArduinoParty.cpp

My Documents\Arduino\libraries\ArduinoParty\ArduinoParty.h

My Documents\Arduino\libraries\ArduinoParty\examples

....

or like this (on Mac and Linux):

Documents/Arduino/libraries/ArduinoParty/ArduinoParty.cpp

Documents/Arduino/libraries/ArduinoParty/ArduinoParty.h

Documents/Arduino/libraries/ArduinoParty/examples

....

There may be more files than just the .cpp and .h files so make sure they're all there. (The library won't work if you put the .cpp and .h files directly into the libraries folder or if they're nested in an extra folder. For example: Documents\Arduino\libraries\ArduinoParty.cpp and Documents\Arduino\libraries\ArduinoParty\ArduinoParty.cpp won't work.)

Restart the Arduino application. Make sure the new library appears in the Sketch > Import Library menu. That's it. You've installed a library!

## Summary

In this lesson, we will install all the libraries that we will use in the tutorial. Open the libraries folder and install the ZIP files one by one so we won't need to do this step in the following lessons. We just connect the component as the schematic and upload the code provided. Then the kit will work.

## Lesson 2 Blink

### Overview

In this lesson, you will learn how program your UNO R3 controller board to make the Arduino's built-in LED blink.

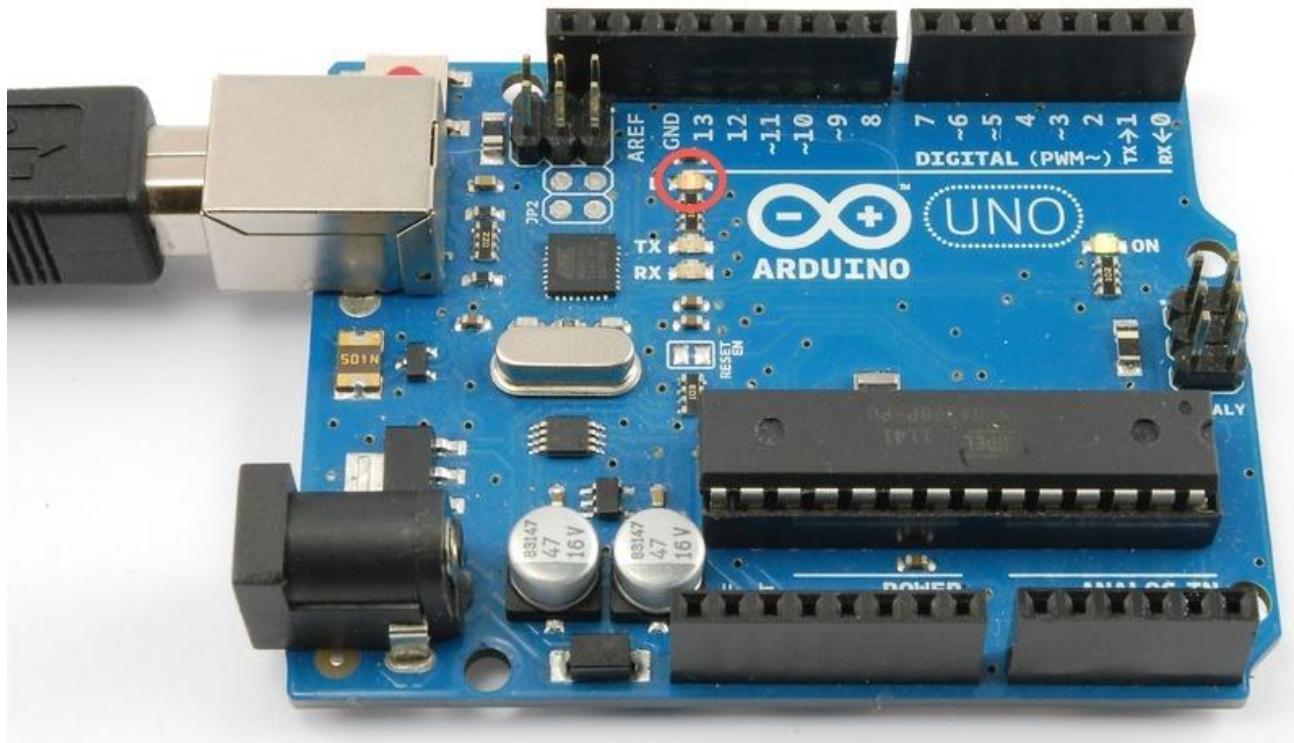
### Component Required:

- (1) x Elegoo Uno R3

### Principle

The UNO R3 board has rows of connectors along both sides that are used to connect to several electronic devices and plug-in 'shields' that extends its capability.

It also has a single LED that you can control from your sketches. This LED is built onto the UNO R3 board and is often referred to as the 'L' LED as this is how it is labeled on the board.



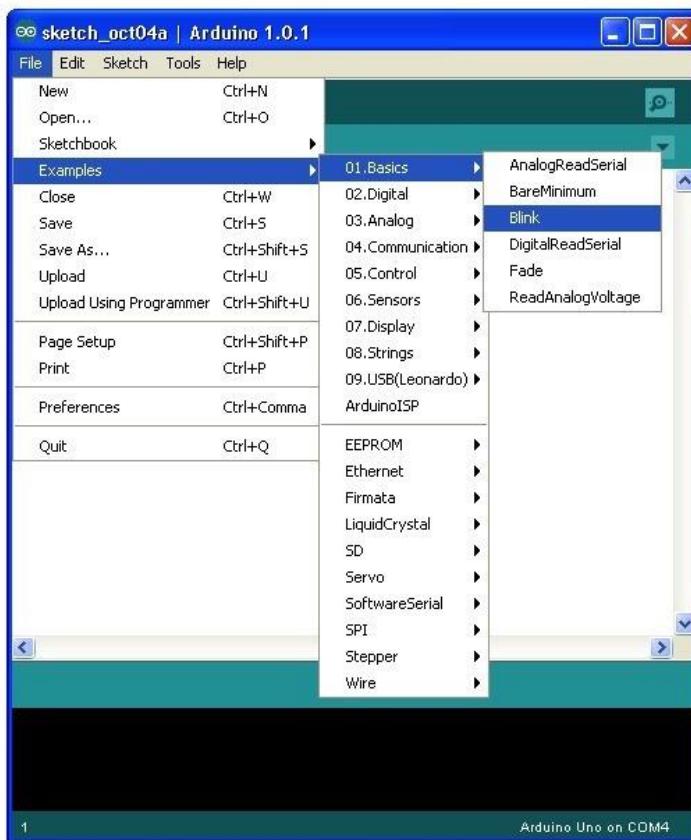
You may find that your UNO R3 board's 'L' LED already blinks when you connect it to a USB plug. This is because the boards are generally shipped with the 'Blink' sketch pre-installed.

In this lesson, we will reprogram the UNO R3 board with our own Blink sketch and then change the rate at which it blinks.

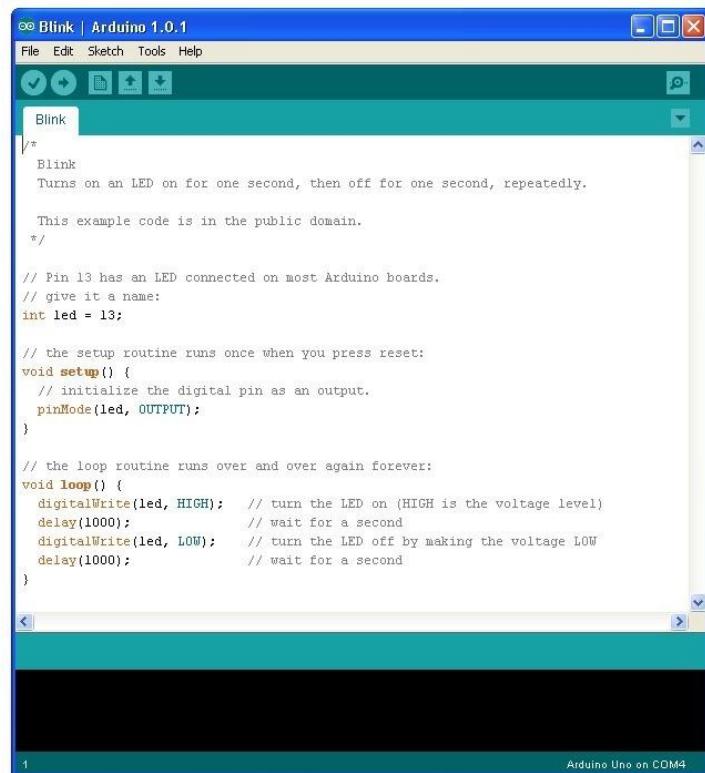
In Lesson 0, you set up your Arduino IDE and made sure that you could find the right serial port for it to connect to your UNO R3 board. The time has now come to put that connection to the test and program your UNO R3 board.

The Arduino IDE includes a large collection of example sketches that you can load up and use. This includes an example sketch for making the 'L' LED blink.

Load the 'Blink' sketch that you will find in the IDE's menu system under File > Examples > 01.Basics

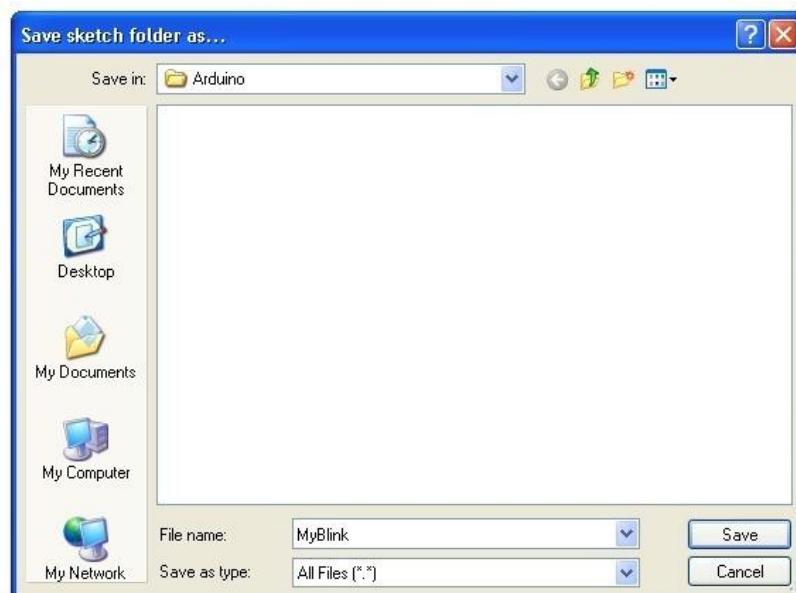


When the sketch window opens, enlarge it so that you can see the entire sketch in the window.



The example sketches included with the Arduino IDE are 'read-only'. That is, you can upload them to an UNO R3 board, but if you change them, you cannot save them as the same file. Since we are going to change this sketch, the first thing you need to do is save your own copy.

From the File menu on the Arduino IDE, select 'Save As..' and then save the sketch with the name 'MyBlink'.



You have saved your copy of 'Blink' in your sketchbook. This means that if you ever want to

find it again, you can just open it using the File > Sketchbook menu option.



Attach your Arduino board to your computer with the USB cable and check that the 'Board Type' and 'Serial Port' are set correctly. You may need to refer back to Lesson 0.

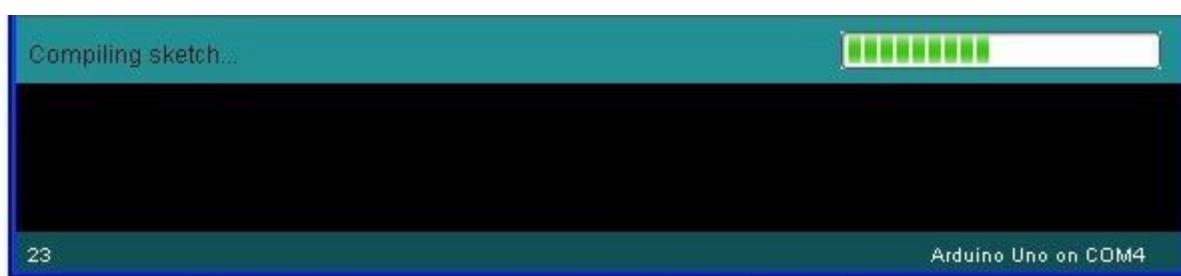
The Arduino IDE will show you the current settings for board at the bottom of the window.



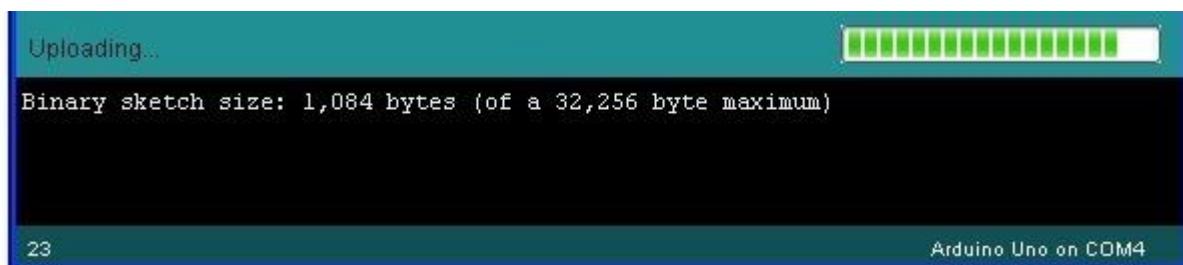
Click on the 'Upload' button. The second button from the left on the toolbar.



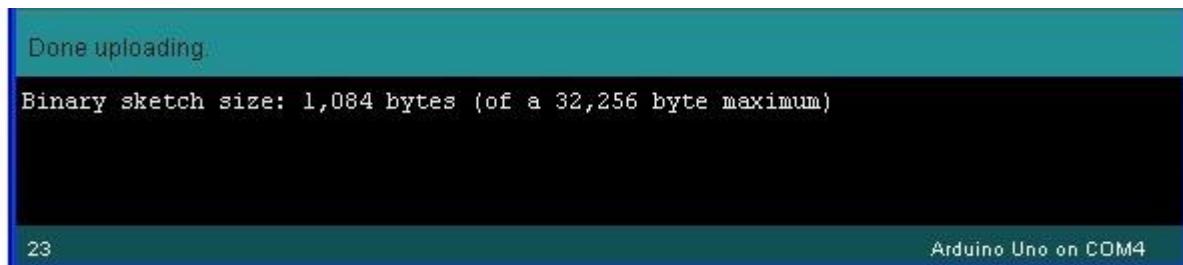
If you watch the status area of the IDE, you will see a progress bar and a series of messages. At first, it will say 'Compiling Sketch...'. This converts the sketch into a format suitable for uploading to the board.



Next, the status will change to 'Uploading'. At this point, the LEDs on the Arduino should start to flicker as the sketch is transferred.



Finally, the status will change to 'Done'.



The other message tells us that the sketch is using 1,084 bytes of the 32,256 bytes available. After the 'Compiling Sketch..' stage you could get the following error message:



It can mean that your board is not connected at all, or the drivers have not been installed (if necessary) or that the wrong serial port is selected.

If you encounter this, go back to Lesson 0 and check your installation.

Once the upload has completed, the board should restart and start blinking.

Open the code

Note that a huge part of this sketch is composed of comments. These are not actual program instructions; rather, they just explain how the program works. They are there for your benefit.

Everything between /\* and \*/ at the top of the sketch is a block comment; it explains what the sketch is for.

Single line comments start with // and everything up until the end of that line is considered a comment.

The first line of code is:

```
int led = 13;
```

As the comment above it explains, this is giving a name to the pin that the LED is attached to. This is 13 on most Arduinos, including the UNO and Leonardo.

Next, we have the 'setup' function. Again, as the comment says, this is executed when the reset button is pressed. It is also executed whenever the board resets for any reason, such as power first being applied to it, or after a sketch has been uploaded.

```
void setup() {  
    // initialize the digital pin as an output.  
    pinMode(led, OUTPUT);  
}
```

Every Arduino sketch must have a 'setup' function, and the place where you might want to add instructions of your own is between the { and the }.

In this case, there is just one command there, which, as the comment states tells the Arduino board that we are going to use the LED pin as an output.

It is also mandatory for a sketch to have a 'loop' function. Unlike the 'setup' function that only runs once, after a reset, the 'loop' function will, after it has finished running its commands, immediately start again.

```
void loop() {  
    digitalWrite(led, HIGH);    // turn the LED on (HIGH is the voltage level)  
    delay(1000);              // wait for a second  
    digitalWrite(led, LOW);    // turn the LED off by making the voltage LOW  
    delay(1000);              // wait for a second  
}
```

Inside the loop function, the commands first of all turn the LED pin on (HIGH), then 'delay' for 1000 milliseconds (1 second), then turn the LED pin off and pause for another second.

You are now going to make your LED blink faster. As you might have guessed, the key to this lies in changing the parameter in () for the 'delay' command.

```
// the loop routine runs over and over again forever:  
void loop() {  
    digitalWrite(led, HIGH);      // turn the LED on (HIGH is the voltage level)  
    delay(1000);                // wait for a second  
    digitalWrite(led, LOW);       // turn the LED off by making the voltage LOW  
    delay(1000);                // wait for a second  
}
```

This delay period is in milliseconds, so if you want the LED to blink twice as fast, change the value from 1000 to 500. This would then pause for half a second each delay rather than a whole second.

Upload the sketch again and you should see the LED start to blink more quickly.

## Lesson 3 LED

### Overview

In this lesson, you will learn how to change the brightness of an LED by using different values of resistor.

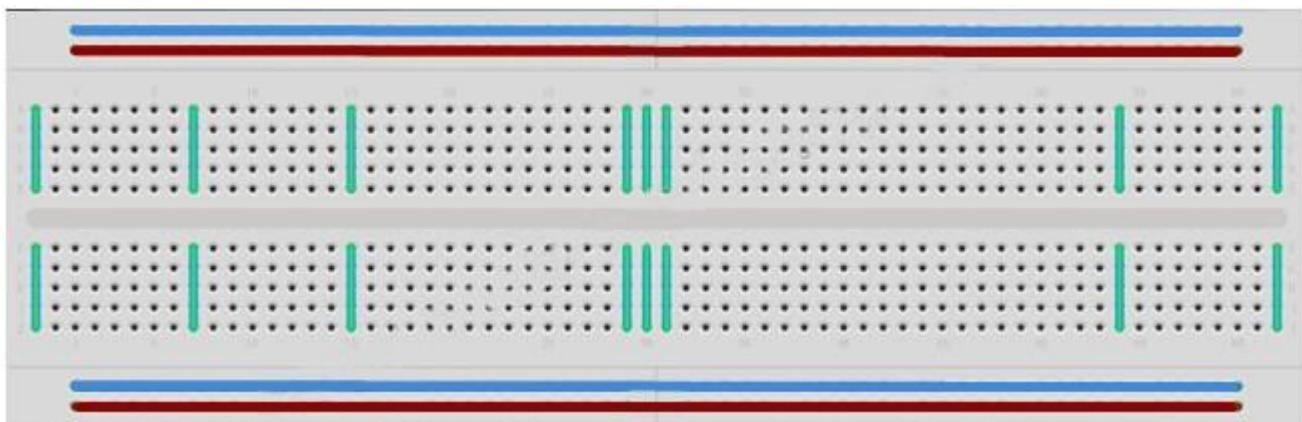
### Component Required:

- (1) x Elegoo Uno R3
- (1) x 5mm red LED
- (1) x 220 ohm resistor
- (1) x 1k ohm resistor
- (1) x 10k ohm resistor
- (2) x M-M wires

### Component Introduction

#### BREADBOARD MB-102:

A breadboard enables you to prototype circuits quickly, without having to solder the connections. Below is an example.



Breadboards come in various sizes and configurations. The simplest kind is just a grid of holes in a plastic block. Inside are strips of metal that provide electrical connection between holes in the shorter rows. Pushing the legs of two different components into the same row joins

them together electrically. A deep channel running down the middle indicates that there is a break in connections there, meaning, you can push a chip in with the legs at either side of the channel without connecting them together. Some breadboards have two strips of holes running along the long edges of the board that are separated from the main grid. These have strips running down the length of the board inside and provide a way to connect a common voltage. They are usually in pairs for +5 volts and ground. These strips are referred to as rails and they enable you to connect power to many components or points in the board.

While breadboards are great for prototyping, they have some limitations. Because the connections are push-fit and temporary, they are not as reliable as soldered connections. If you are having intermittent problems with a circuit, it could be due to a poor connection on a breadboard.

#### **LED:**

LEDs make great indicator lights. They use very little electricity and they pretty much last forever.

In this lesson, you will use perhaps the most common of all LEDs: a 5mm red LED. 5mm refers to the diameter of the LED. Other common sizes are 3mm and 10mm.

You cannot directly connect an LED to a battery or voltage source because 1) the LED has a positive and a negative lead and will not light if placed the wrong way and 2) an LED must be used with a resistor to limit or 'choke' the amount of current flowing through it; otherwise, it will burn out!



If you do not use a resistor with an LED, then it may well be destroyed almost immediately, as too much current will flow through, heating it and destroying the 'junction' where the light is produced.

There are two ways to tell which is the positive lead of the LED and which the negative.

Firstly, the positive lead is longer.

Secondly, where the negative lead enters the body of the LED, there is a flat edge to the case of the LED.

If you happen to have an LED that has a flat side next to the longer lead, you should assume that the longer lead is positive.

### **RESISTORS:**

As the name suggests, resistors resist the flow of electricity. The higher the value of the resistor, the more it resists and the less electrical current will flow through it. We are going to use this to control how much electricity flows through the LED and therefore, how brightly it shines.

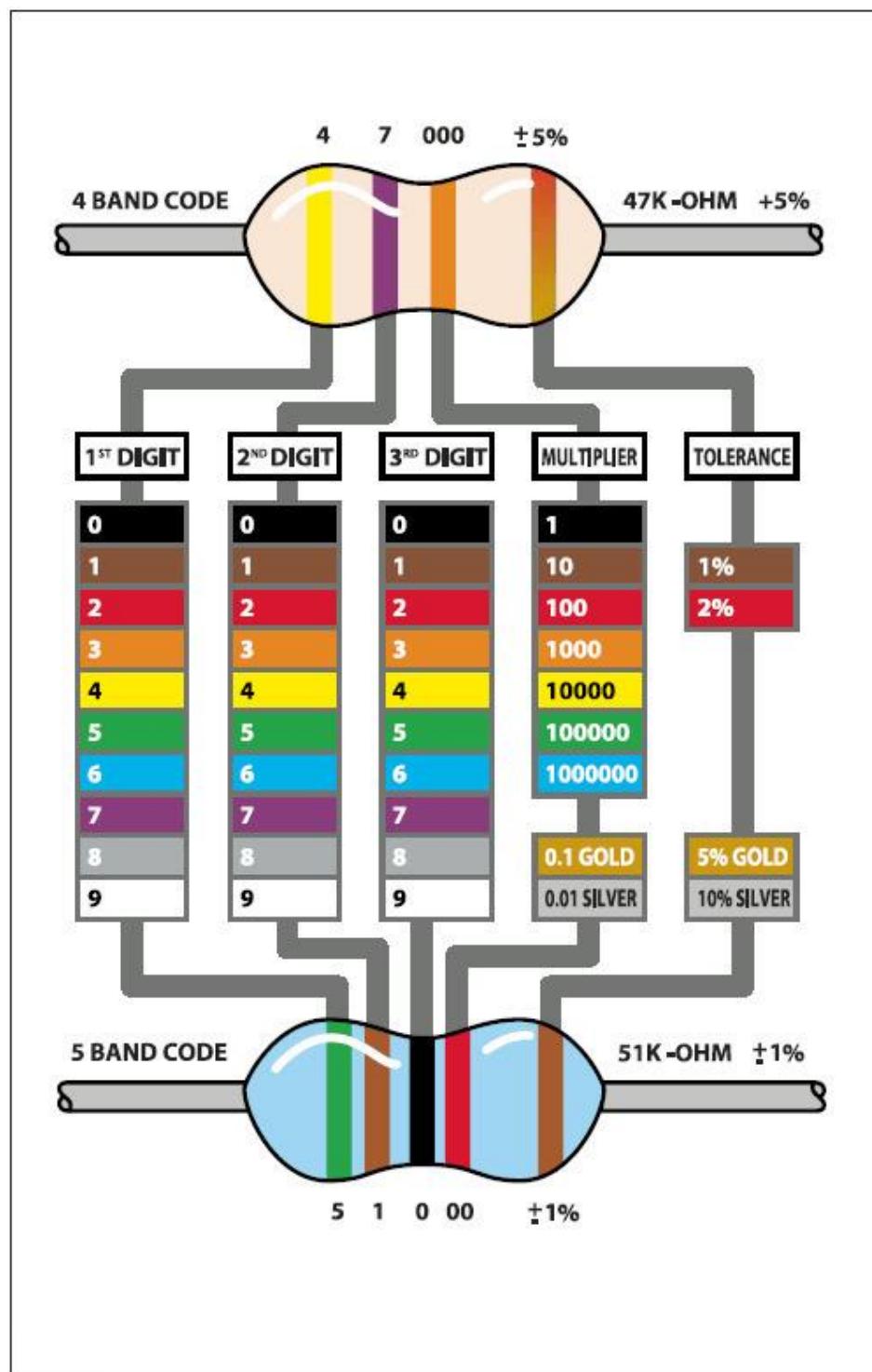


But first, more about resistors...

The unit of resistance is called the Ohm, which is usually shortened to  $\Omega$  the Greek letter Omega. Because an Ohm is a low value of resistance (it doesn't resist much at all), we also denote the values of resistors in  $k\Omega$  (1,000  $\Omega$ ) and  $M\Omega$  (1,000,000  $\Omega$ ). These are called kilo-ohms and mega-ohms.

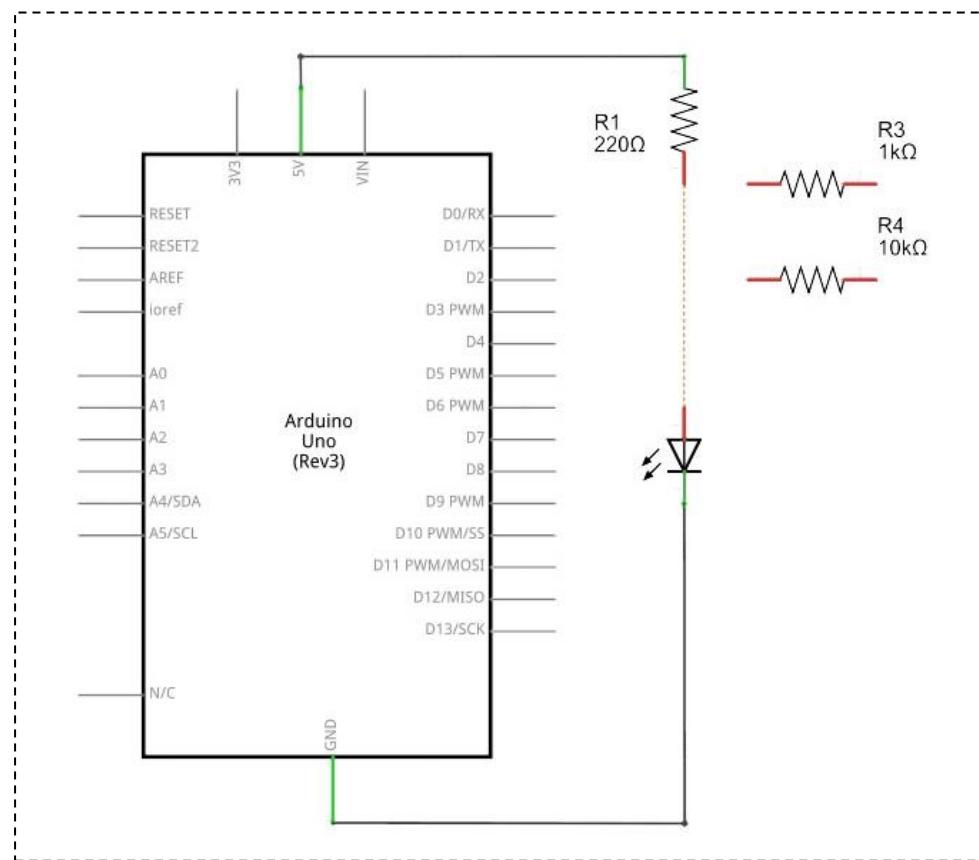
In this lesson, we are going to use three different values of resistor:  $220\Omega$ ,  $1k\Omega$  and  $10k\Omega$ . These resistors all look the same, except that they have different colored stripes on them. These stripes tell you the value of the resistor.

The resistor color code has three colored stripes and then a gold stripe at one end.

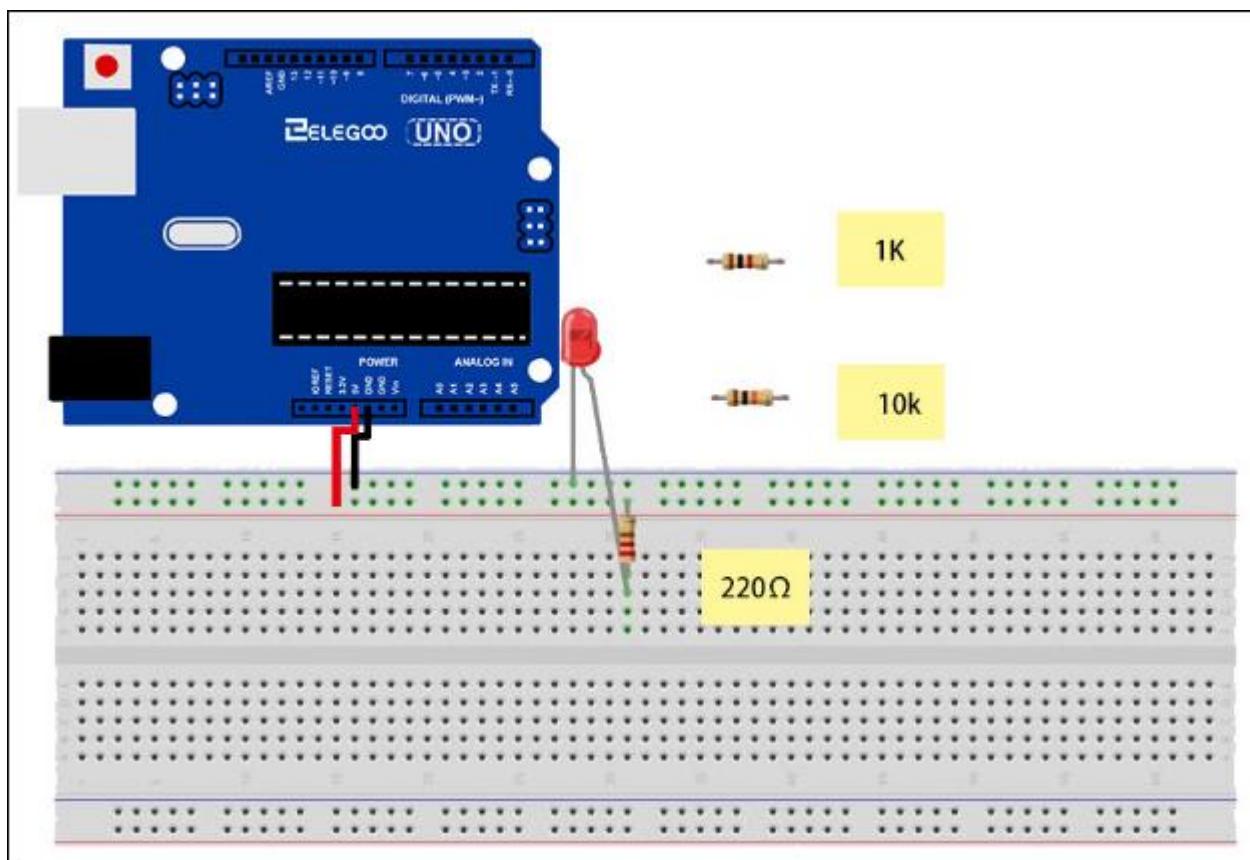


Unlike LEDs, resistors do not have a positive and negative lead. They can be connected either way around.

## Connection Schematic



wiring diagram



The UNO is a convenient source of 5 volts, which we will use to provide power to the LED and

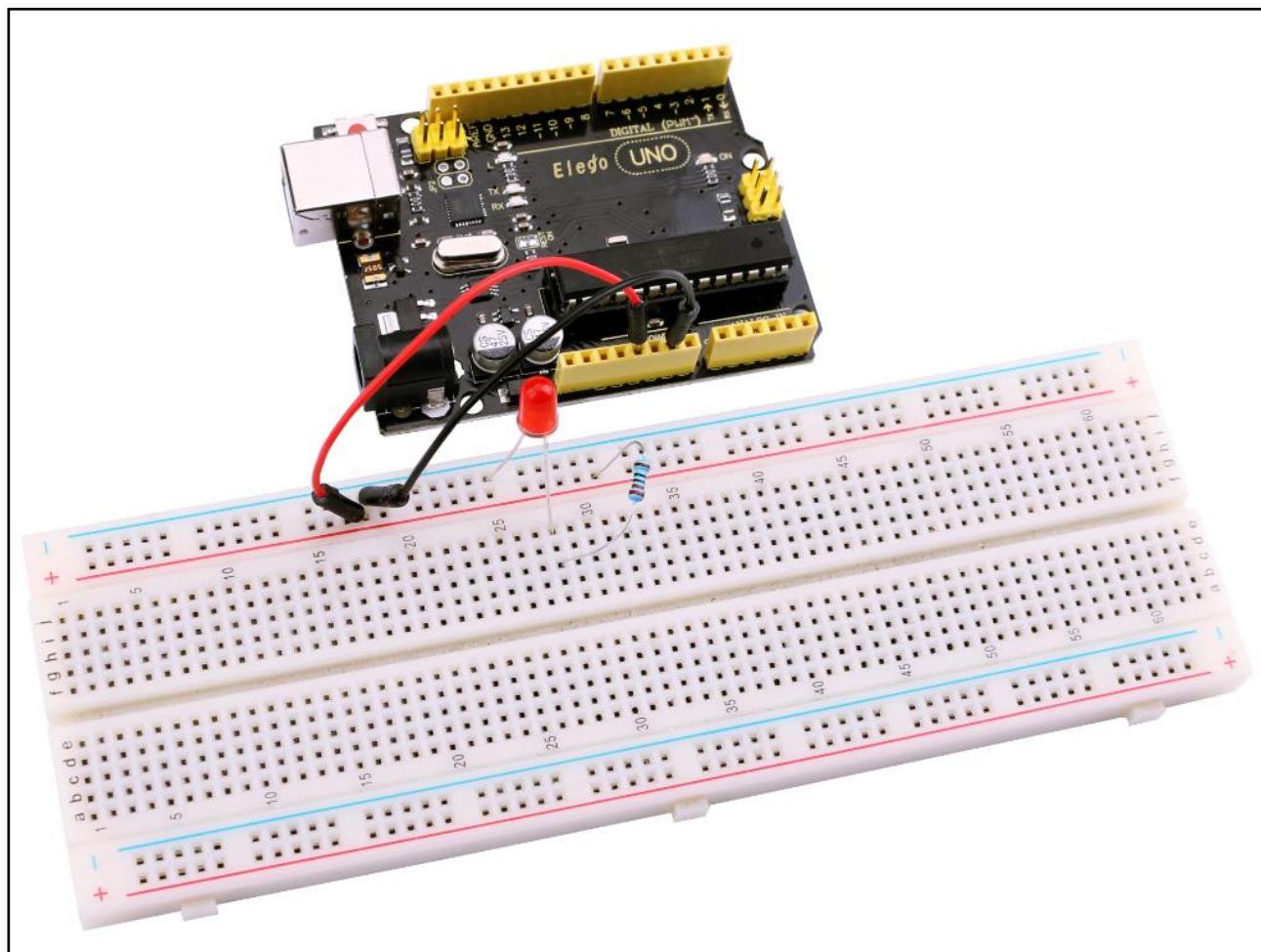
the resistor. You do not need to do anything with your UNO, except to plug it into a USB cable.

With the  $220\ \Omega$  resistor in place, the LED should be quite bright. If you swap out the  $220\ \Omega$  resistor for the  $1k\Omega$  resistor, then the LED will appear a little dimmer. Finally, with the  $10\ k\Omega$  resistor in place, the LED will be just about visible. Pull the red jumper lead out of the breadboard and touch it into the hole and remove it, so that it acts like a switch. You should just be able to notice the difference.

At the moment, you have 5V going to one leg of the resistor, the other leg of the resistor going to the positive side of the LED and the other side of the LED going to GND. However, if we moved the resistor so that it came after the LED, as shown below, the LED will still light.

You will probably want to put the  $220\Omega$  resistor back in place.

It does not matter which side of the LED we put the resistor, as long as it is there somewhere.



## Lesson 4 RGB LED

### Overview

RGB LEDs are a fun and easy way to add some color to your projects. Since they are like 3 regular LEDs in one, how to use and connect them is not much different.

They come mostly in 2 versions: Common Anode or Common Cathode.

Common Anode uses 5V on the common pin, while Common Cathode connects to ground.

As with any LED, we need to connect some resistors inline (3 total) so we can limit the current being drawn.

In our sketch, we will start with the LED in the Red color state, then fade to Green, then fade to Blue and finally back to the Red color. By doing this we will cycle through most of the color that can be achieved.

### Component Required:

- (1) x Elegoo Uno R3
- (1) x Bread board
- (4) x M-M wires
- (1) x RGB LED
- (3) x 220 ohm resistors

### Component Introduction

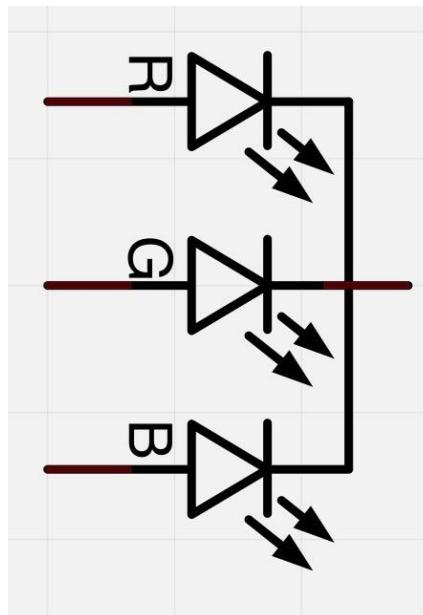
#### RGB:

At first glance, RGB (Red, Green, Blue) LEDs look just like regular LEDs. However, inside the usual LED package, there are actually three LEDs, one red, one green and yes, one blue. By controlling the brightness of each of the individual LEDs you can mix pretty much any color you want.

We mix colors the same way you would mix paint on a palette - by adjusting the brightness of each of the three LEDs. The hard way to do this would be to use different value resistors

(or variable resistors) as we did with in Lesson 2, but that's a lot of work! Fortunately for us, UNO R3 board has an `analogWrite` function that you can use with pins marked with a `~` to output a variable amount of power to the appropriate LEDs.

The RGB LED has four leads. There is one lead going to the positive connection of each of the single LEDs within the package and a single lead that is connected to all three negative sides of the LEDs.



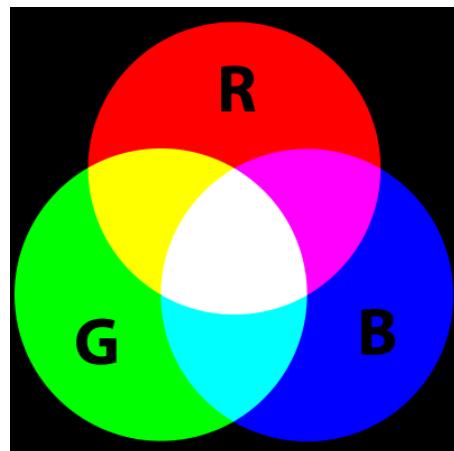
The common negative connection of the LED package is the second pin from the flat side. It is also the longest of the four leads and will be connected to the ground.

Each LED inside the package requires its own  $270\Omega$  resistor to prevent too much current flowing through it. The three positive leads of the LEDs (one red, one green and one blue) are connected to UNO output pins using these resistors.

### COLOR:

The reason that you can mix any color you like by varying the quantities of red, green and blue light is that your eye has three types of light receptor in it (red, green and blue). Your eye and brain process the amounts of red, green and blue and convert it into a color of the spectrum.

In a way, by using the three LEDs, we are playing a trick on the eye. This same idea is used in TVs, where the LCD has red, green and blue color dots next to each other making up each pixel.



If we set the brightness of all three LEDs to be the same, then the overall color of the light will be white. If we turn off the blue LED, so that just the red and green LEDs are the same brightness, then the light will appear yellow.

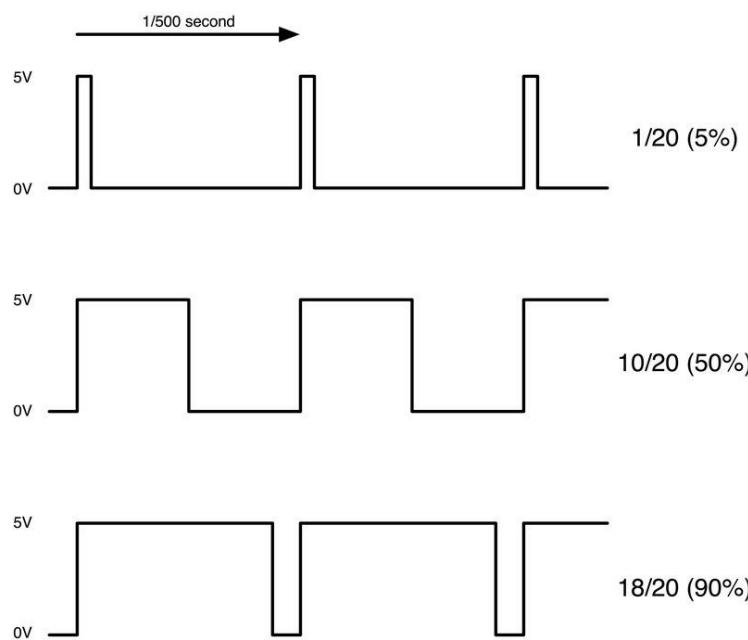
We can control the brightness of each of the red, green and blue parts of the LED separately, making it possible to mix any color we like.

Black is not so much a color as an absence of light. Therefore, the closest we can come to black with our LED is to turn off all three colors.

## Theory(PWM)

Pulse Width Modulation ( PWM ) is a technique for controlling power. We also use it here to control the brightness of each of the LEDs.

The diagram below shows the signal from one of the PWM pins on the UNO.



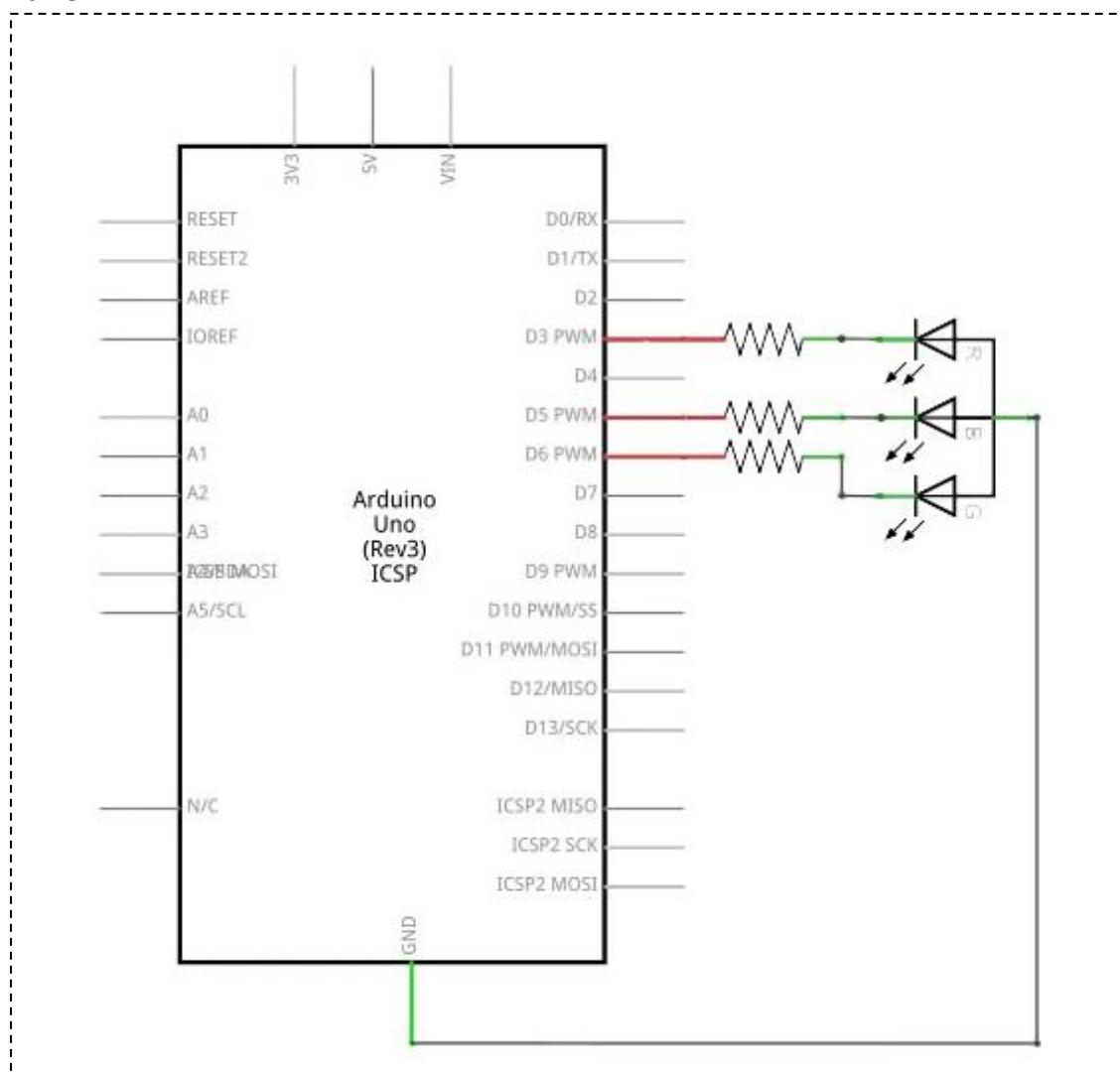
Roughly every 1/500 of a second, the PWM output will produce a pulse. The length of this pulse is controlled by the 'analogWrite' function. So 'analogWrite(0)' will not produce any pulse at all and 'analogWrite(255)' will produce a pulse that lasts all the way until the next pulse is due, so that the output is actually on all the time.

If we specify a value in the analogWrite that is somewhere in between 0 and 255, then we will produce a pulse. If the output pulse is only high for 5% of the time, then whatever we are driving will only receive 5% of full power.

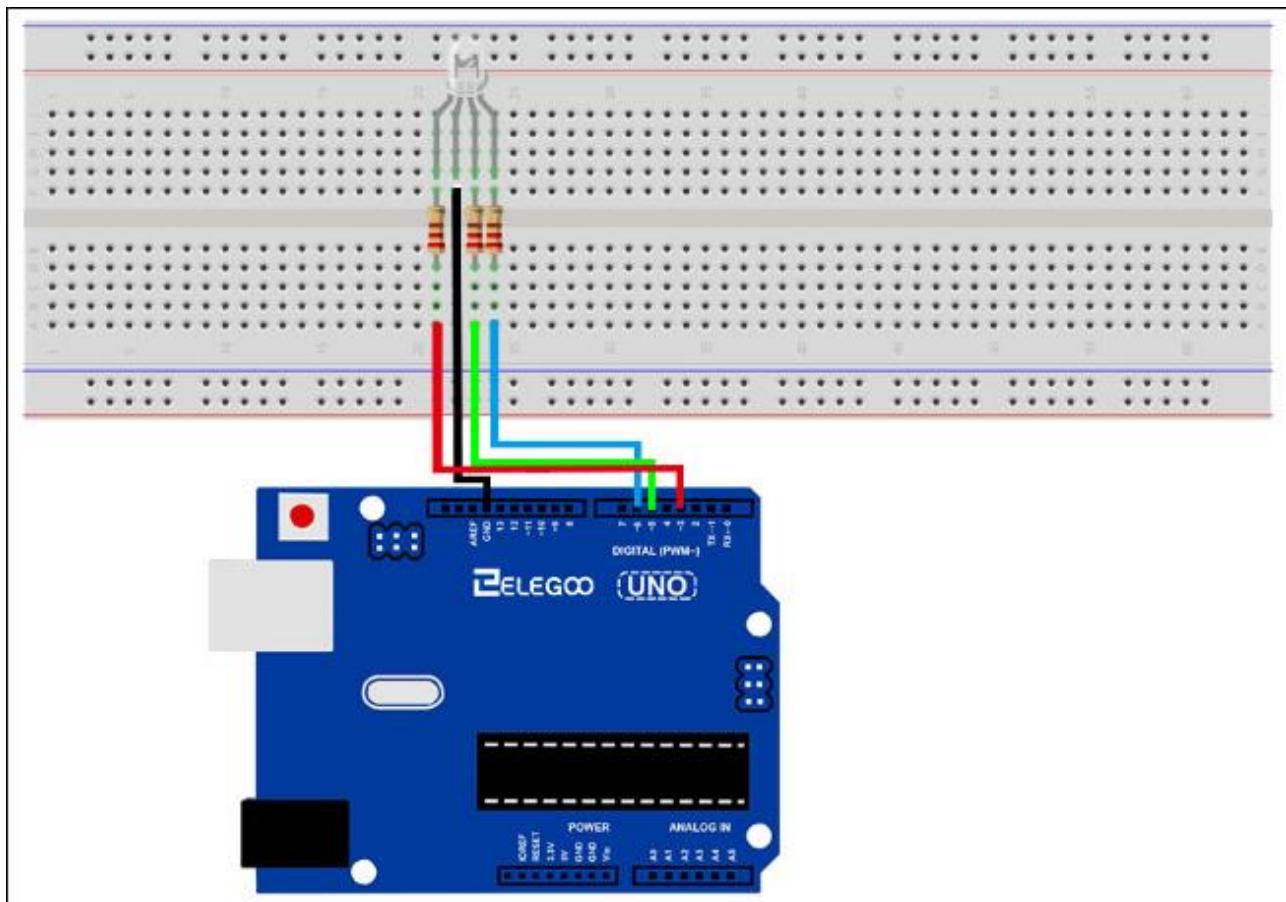
If, however, the output is at 5V for 90% of the time, then the load will get 90% of the power delivered to it. We cannot see the LEDs turning on and off at that speed, so to us, it just looks like the brightness is changing.

## Connection

### Schematic



## wiring diagram



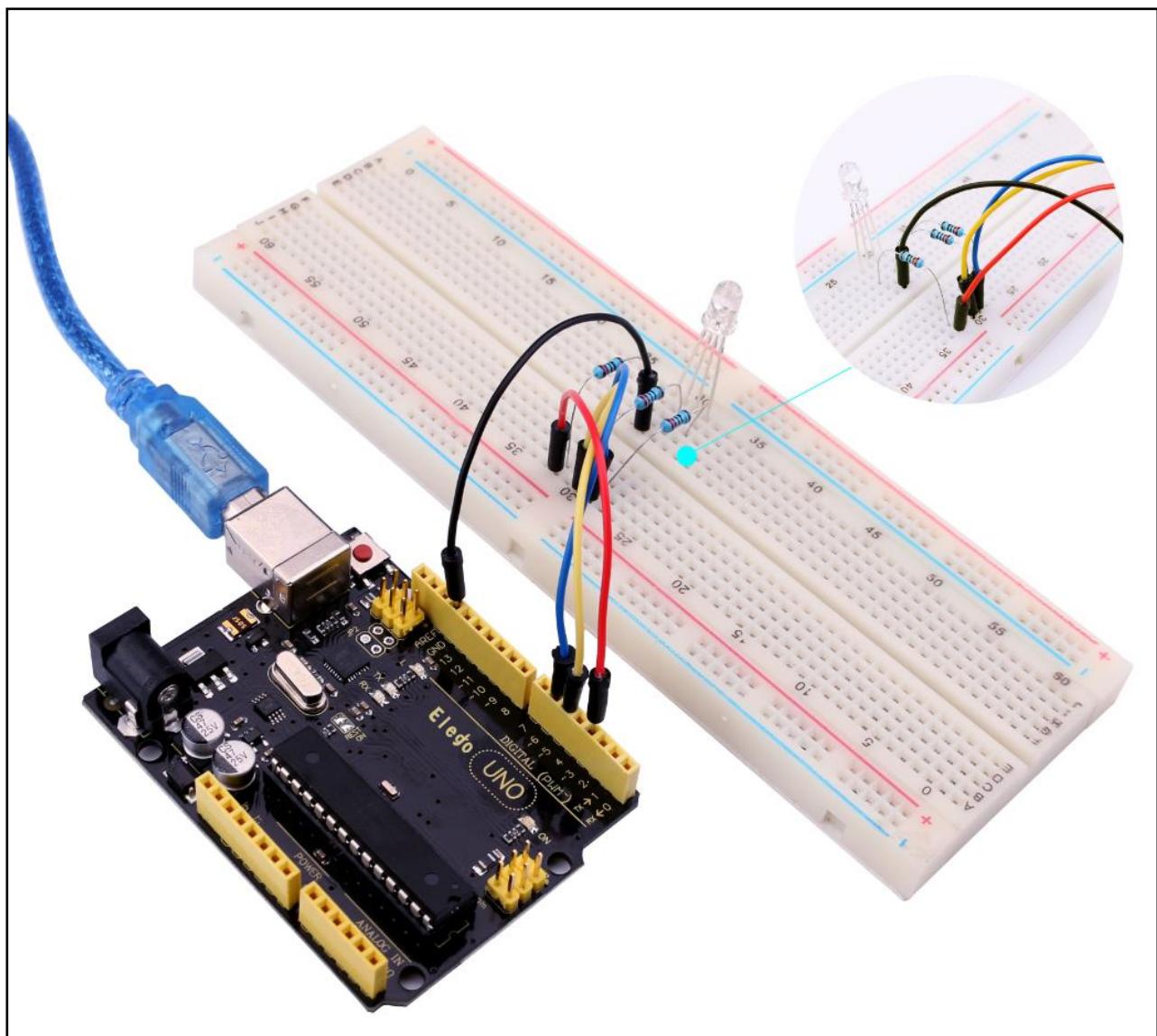
## Code

Our code will use FOR loops to cycle through the colors.

The first FOR loop will go from RED to GREEN.

The second FOR loop will go from GREEN to BLUE.

The last FOR loop will go from BLUE to RED.



# Lesson 5 Digital Inputs

## Overview

In this lesson, you will learn to use push buttons with digital inputs to turn an LED on and off.

Pressing the button nearer the top of the breadboard will turn the LED on; pressing the other button will turn the LED off.

## Component Required:

(1) x Elegoo Uno R3

(1) x Breadboard

(1) x 5mm red LED

(1) x 220 ohm resistor

(2) x push switches

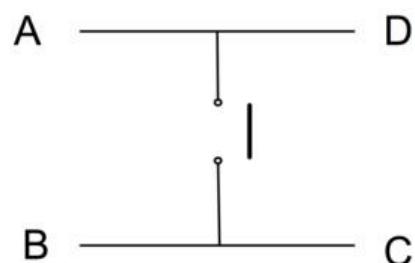
(6) x M-M wires

## Component Introduction

### PUSH SWITCHES:

Switches are really simple components. When you press a button or flip a lever, they connect two contacts together so that electricity can flow through them.

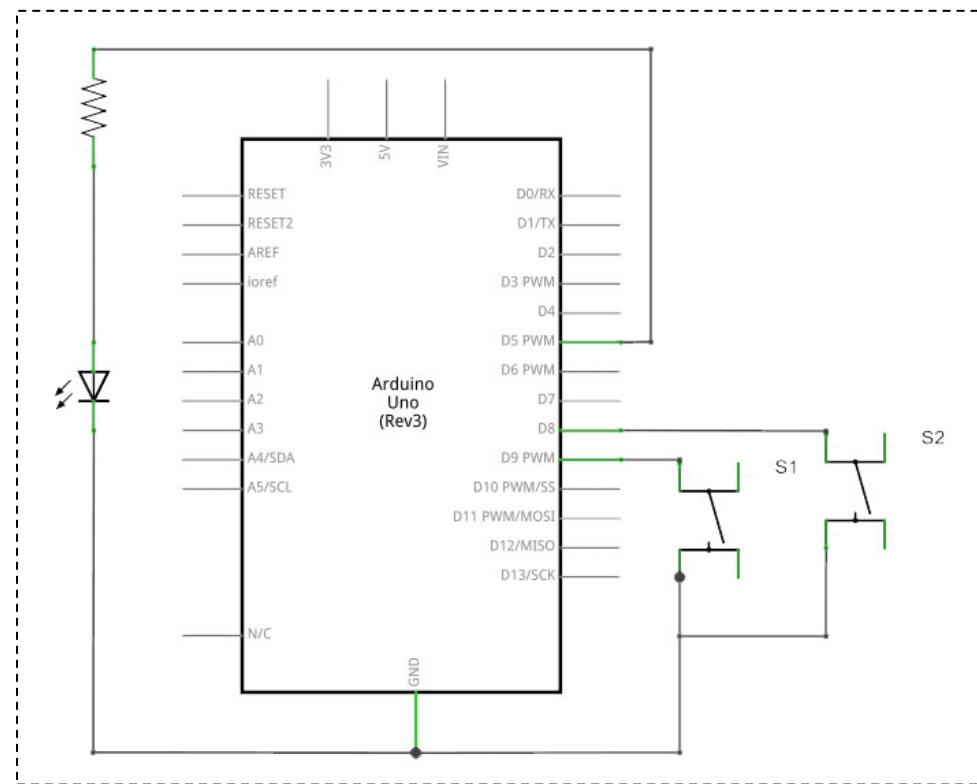
The little tactile switches that are used in this lesson have four connections, which can be a little confusing.



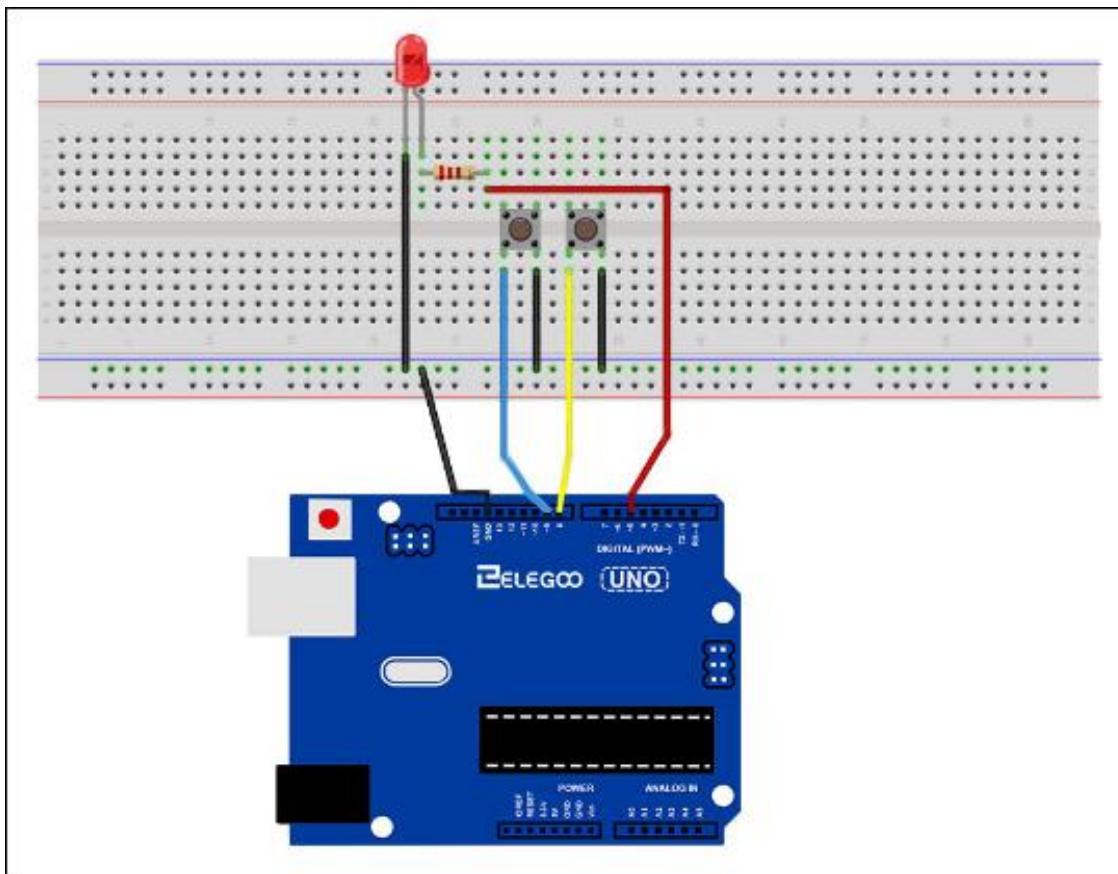
Actually, there are only really two electrical connections. Inside the switch package, pins B and C are connected together, as are A and D.

## Connection

## Schematic



## wiring diagram



Although the bodies of the switches are square, the pins protrude from opposite sides of the switch. This means that the pins will only be far enough apart when they are placed correctly on the breadboard.

Remember that the LED has to have the shorter negative lead to the right.

## Code

Load the sketch onto your UNO board. Pressing the top button will turn the LED on while pressing the bottom button will turn it off.

The first part of the sketch defines three variables for the three pins that are to be used. The 'ledPin' is the output pin and 'buttonApin' will refer to the switch nearer the top of the breadboard and 'buttonBpin' to the other switch.

The 'setup' function defines the ledPin as being an OUTPUT as normal, but now we have the two inputs to deal with. In this case, we use the set the pinMode to be 'INPUT\_PULLUP' like this:

```
pinMode(buttonApin, INPUT_PULLUP);  
pinMode(buttonBpin, INPUT_PULLUP);
```

The pin mode of INPUT\_PULLUP means that the pin is to be used as an input, but that if nothing else is connected to the input, it should be 'pulled up' to HIGH. In other words, the default value for the input is HIGH, unless it is pulled LOW by the action of pressing the button.

This is why the switches are connected to GND. When a switch is pressed, it connects the input pin to GND, so that it is no longer HIGH.

Since the input is normally HIGH and only goes LOW when the button is pressed, the logic is a little upside down. We will handle this in the 'loop' function.

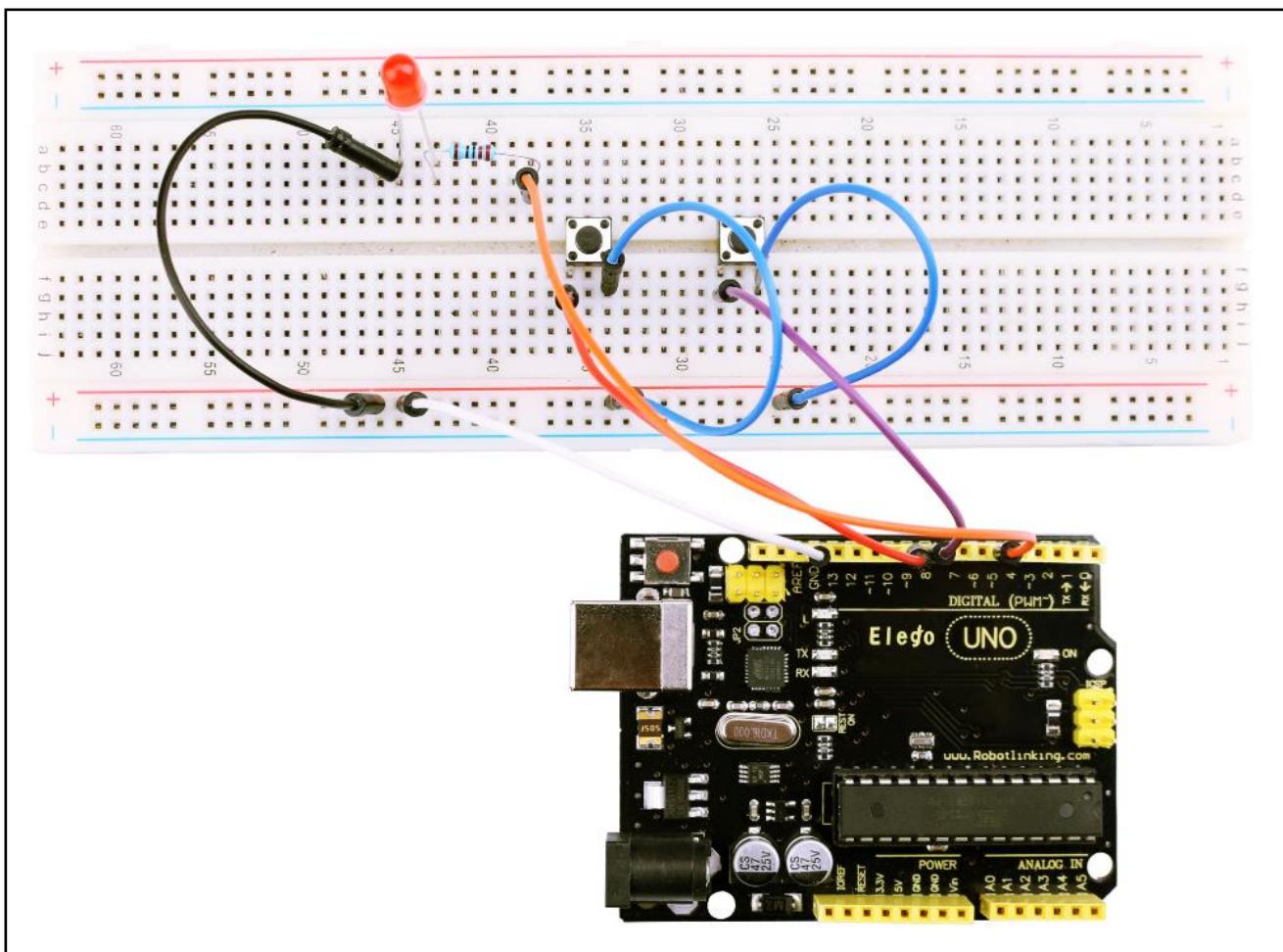
```
void loop()  
{  
    if (digitalRead(buttonApin) == LOW)  
    {  
        digitalWrite(ledPin, HIGH);  
    }  
    if (digitalRead(buttonBpin) == LOW)
```

```
{  
    digitalWrite(ledPin, LOW);  
}  
}
```

In the 'loop' function there are two 'if' statements. One for each button. Each does an 'digitalRead' on the appropriate input.

Remember that if the button is pressed, the corresponding input will be LOW, if button A is low, then a 'digitalWrite' on the ledPin turns it on.

Similarly, if button B is pressed, a LOW is written to the ledPin.



# Lesson 6 Eight LED with 74HC595

## Overview

In this lesson, you will learn how to use eight large red LEDs with an UNO without needing to give up 8 output pins!

Although you could wire up eight LEDs each with a resistor to an UNO pin you would rapidly start to run out of pins on your UNO. If you don't have a lot of stuff connected to your UNO. It's OK to do so - but often times we want buttons, sensors, servos, etc and before you know it you've got no pins left. So, instead of doing that, you are going to use a chip called the 74HC595 Serial to Parallel Converter. This chip has eight outputs (perfect) and three inputs that you use to feed data into it a bit at a time.

This chip makes it a little slower to drive the LEDs (you can only change the LEDs about 500,000 times a second instead of 8,000,000 a second) but it's still really fast, way faster than humans can detect, so it's worth it!

## Component Required:

(1) x Elegoo Uno R3

(1) x Breadboard

(8) x led

(8) x 220 ohm resistors

(1) x Breadboard

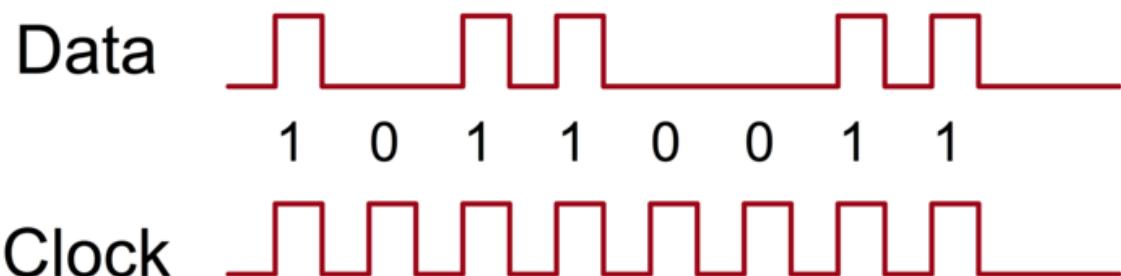
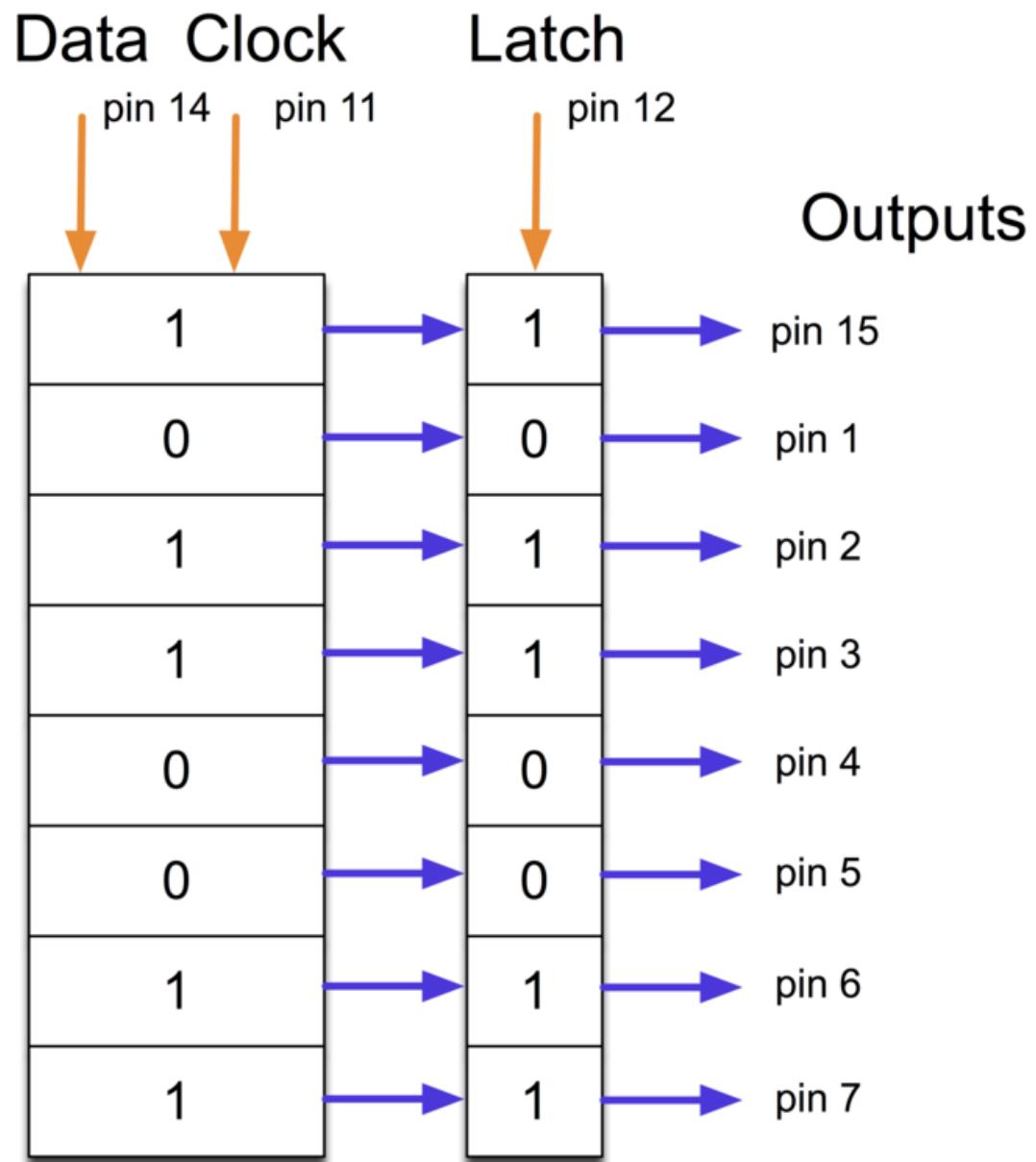
(1) x 74hc595 ic

(14) x M-M wires

## Component Introduction

### 74HC595 Shift Register:

The shift register is a type of chip that holds what can be thought of as eight memory locations, each of which can either be a 1 or a 0. To set each of these values on or off, we feed in the data using the 'Data' and 'Clock' pins of the chip.



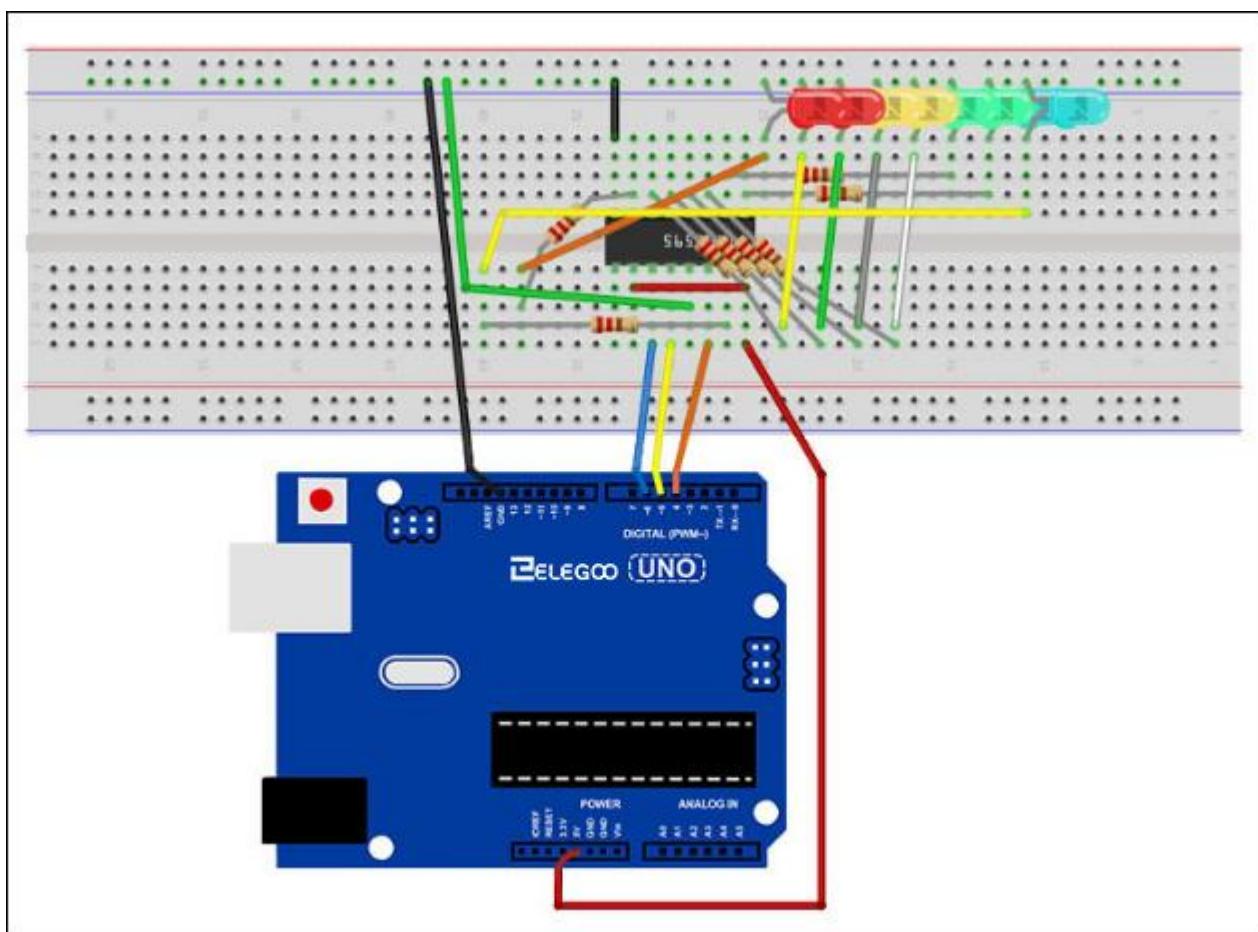
The clock pin needs to receive eight pulses. At each pulse, if the data pin is high, then a 1 gets pushed into the shift register; otherwise, a 0. When all eight pulses have been received, enabling the 'Latch' pin copies those eight values to the latch register. This is necessary;

otherwise, the wrong LEDs would flicker as the data is being loaded into the shift register.

The chip also has an output enable (OE) pin, which is used to enable or disable the outputs all at once. You could attach this to a PWM-capable UNO pin and use 'analogWrite' to control the brightness of the LEDs. This pin is active low, so we tie it to GND.

## Connection

### wiring diagram



As we have eight LEDs and eight resistors to connect, there are actually quite a few connections to be made.

It is probably easiest to put the 74HC595 chip in first, as pretty much everything else connects to it. Put it so that the little U-shaped notch is towards the top of the breadboard.

Pin 1 of the chip is to the left of this notch.

- Digital 4 from the UNO goes to pin #14 of the shift register
- Digital 5 from the UNO goes to pin #12 of the shift register

- Digital 6 from the UNO goes to pin #11 of the shift register

All but one of the outputs from the IC is on the left side of the chip. Hence, for ease of connection, that is where the LEDs are, too.

After the chip, put the resistors in place. You need to be careful that none of the leads of the resistors are touching each other. You should check this again before you connect the power to your UNO. If you find it difficult to arrange the resistors without their leads touching, then it helps to shorten the leads so that they are lying closer to the surface of the breadboard.

Next, place the LEDs on the breadboard. The longer positive LED leads must all be towards the chip, whichever side of the breadboard they are on.

Attach the jumper leads as shown above. Do not forget the one that goes from pin 8 of the IC to the GND column of the breadboard.

Load up the sketch listed a bit later and try it out. Each LED should light in turn until all the LEDs are on, and then they all go off and the cycle repeats.

## Code

The first thing we do is define the three pins we are going to use. These are the UNO digital outputs that will be connected to the latch, clock and data pins of the 74HC595.

```
int latchPin = 5;  
int clockPin = 6;  
int dataPin = 4;
```

Next, a variable called 'leds' is defined. This will be used to hold the pattern of which LEDs are currently turned on or off. Data of type 'byte' represents numbers using eight bits. Each bit can be either on or off, so this is perfect for keeping track of which of our eight LEDs are on or off.

```
byte leds = 0;
```

The 'setup' function just sets the three pins we are using to be digital outputs.

```
void setup()  
{  
    pinMode(latchPin, OUTPUT);
```

```
pinMode(dataPin, OUTPUT);
pinMode(clockPin, OUTPUT);
}
```

The 'loop' function initially turns all the LEDs off, by giving the variable 'leds' the value 0. It then calls 'updateShiftRegister' that will send the 'leds' pattern to the shift register so that all the LEDs turn off. We will deal with how 'updateShiftRegister' works later.

The loop function pauses for half a second and then begins to count from 0 to 7 using the 'for' loop and the variable 'i'. Each time, it uses the Arduino function 'bitSet' to set the bit that controls that LED in the variable 'leds'. It then also calls 'updateShiftRegister' so that the leds update to reflect what is in the variable 'leds'.

There is then a half second delay before 'i' is incremented and the next LED is lit.

```
void loop()
{
    leds = 0;
    updateShiftRegister();
    delay(500);
    for (int i = 0; i < 8; i++)
    {
        bitSet(leds, i);
        updateShiftRegister();
        delay(500);
    }
}
```

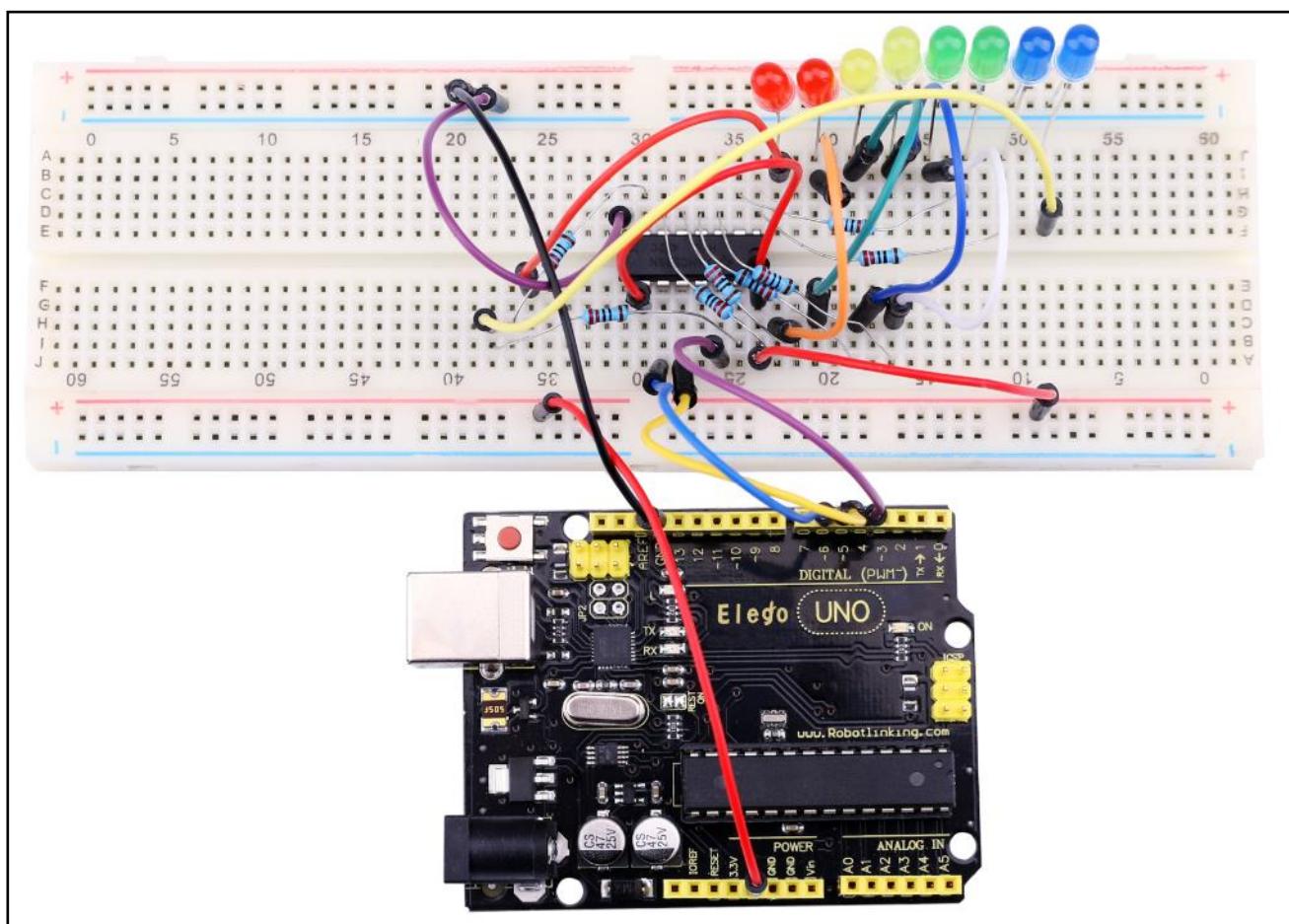
The function 'updateShiftRegister', first of all sets the latchPin to low, then calls the UNO function 'shiftOut' before putting the 'latchPin' high again. This takes four parameters, the first two are the pins to use for Data and Clock respectively.

The third parameter specifies which end of the data you want to start at. We are going to start with the right most bit, which is referred to as the 'Least Significant Bit' (LSB).

The last parameter is the actual data to be shifted into the shift register, which in this case is 'leds'.

```
void updateShiftRegister()
{
    digitalWrite(latchPin, LOW);
    shiftOut(dataPin, clockPin, LSBFIRST, leds);
    digitalWrite(latchPin, HIGH);
}
```

If you wanted to turn one of the LEDs off rather than on, you would call a similar Arduino function (`bitClear`) with the 'leds' variable. This will set that bit of 'leds' to be 0 and you would then just need to follow it with a call to '`updateShiftRegister`' to update the actual LEDs.



# Lesson 7 The Serial Monitor

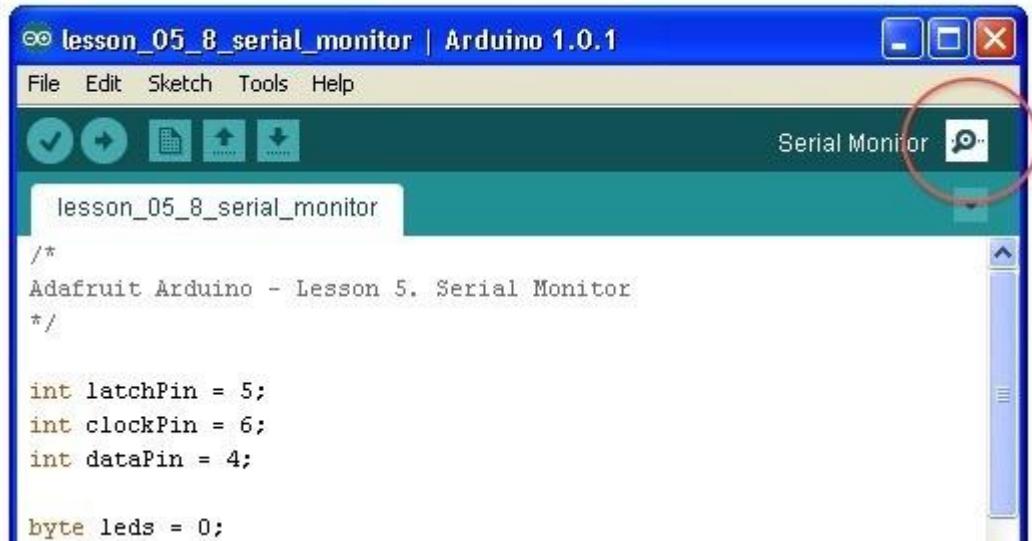
## Overview

In this lesson, you will build on Lesson 6, adding the facility to control the LEDs from your computer using the Arduino Serial Monitor. The serial monitor is the 'tether' between the computer and your UNO. It lets you send and receive text messages, handy for debugging and also controlling the UNO from a keyboard! For example, you will be able to send commands from your computer to turn on LEDs.

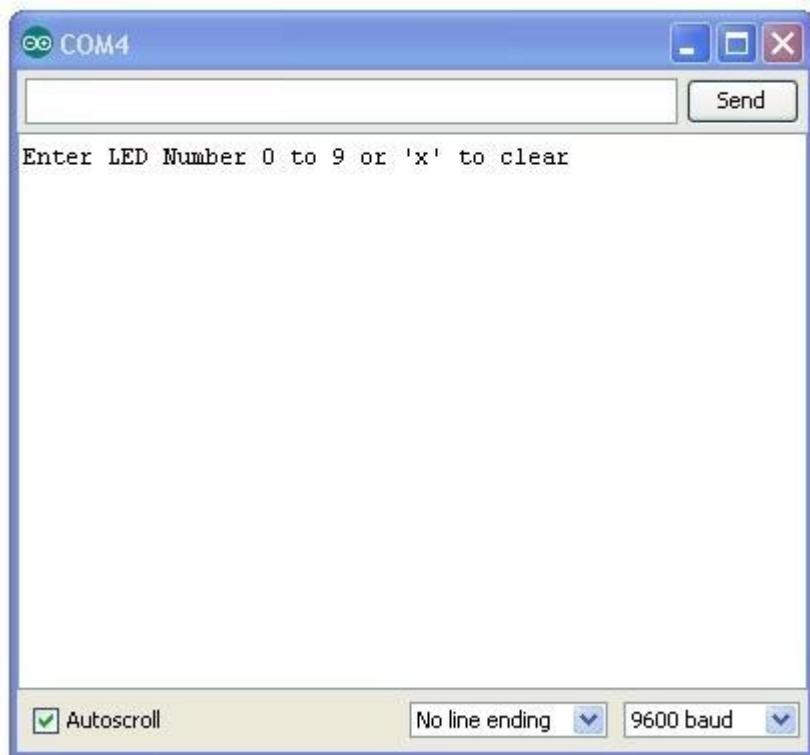
In this lesson, you will use exactly the same parts and a similar breadboard layout as Lesson 6. So, if you have not already done so, follow Lesson 6 now.

## Steps taken

After you have uploaded this sketch onto your UNO, click on the right-most button on the toolbar in the Arduino IDE. The button is circled below.



The following window will open.

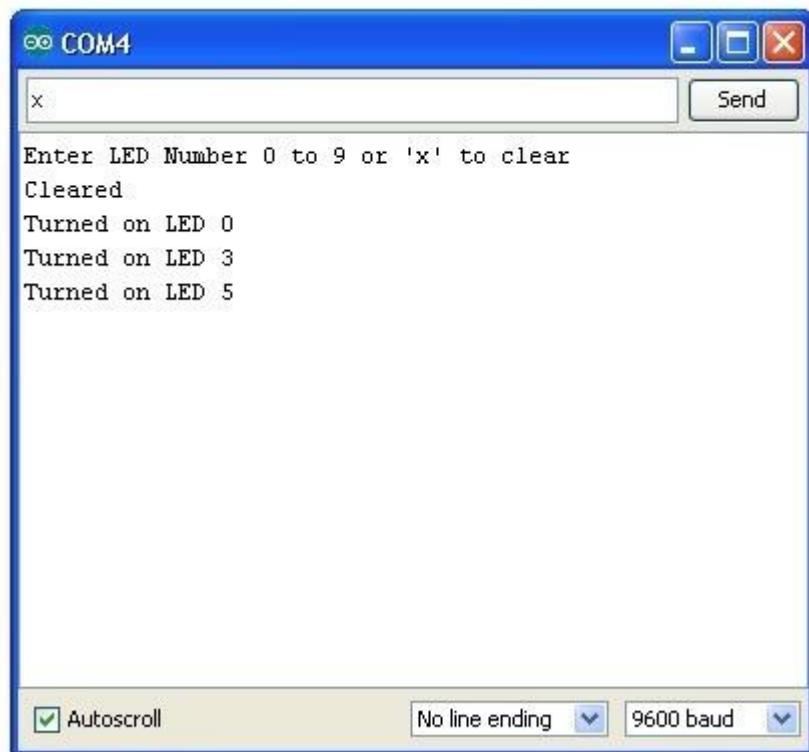


This window is called the Serial Monitor and it is part of the Arduino IDE software. Its job is to allow you to both send messages from your computer to an UNO board (over USB) and also to receive messages from the UNO.

The message "Enter LED Number 0 to 9 or 'x' to clear" has been sent by the Arduino. It is telling us what commands we can send to the Arduino: either send the 'x' (to turn all the LEDs off) or the number of the LED you want to turn on (where 0 is the bottom LED, 1 is the next one up, all the way to 7 for the top LED).

Try typing the following commands into the top area of the Serial Monitor that is level with the 'Send' button. Press 'Send', after typing each of these characters: x 0 3 5

Typing x will have no effect if the LEDs are already all off, but as you enter each number, the corresponding LED should light and you will get a confirmation message from the UNO board. The Serial Monitor will appear as shown below.



Type x again and press 'Send' to turn off all LEDs.

## Code

As you might expect, the sketch is based on the sketch used in Lesson 6. So, we will just cover the new bits here. You will find it useful to refer to the full sketch in your Arduino IDE.

In the 'setup' function, there are three new lines at the end:

```
void setup()
{
    pinMode(latchPin, OUTPUT);
    pinMode(dataPin, OUTPUT);
    pinMode(clockPin, OUTPUT);
    updateShiftRegister();
    Serial.begin(9600);
    while (! Serial); // Wait until Serial is ready - Leonardo
    Serial.println("Enter LED Number 0 to 7 or 'x' to clear");
}
```

Firstly, we have the command 'Serial.begin(9600)'. This starts serial communication, so that the UNO can send out commands through the USB connection. The value 9600 is called the 'baud rate' of the connection. This is how fast the data is to be sent. You can change this to a higher value, but you will also have to change the Arduino Serial monitor to the same value. We will discuss this later; for now, leave it at 9600.

The line beginning with 'while' ensures that there is something at the other end of the USB connection for the Arduino to talk to before it starts sending messages. Otherwise, the message might be sent, but not displayed. This line is actually only necessary if you are using an Arduino Leonardo because the Arduino UNO automatically resets the Arduino board when you open the Serial Monitor, whereas this does not happen with the Leonardo.

The last of the new lines in 'setup' sends out the message that we see at the top of the Serial Monitor.

The 'loop' function is where all the action happens:

```
void loop()
{
    if (Serial.available())
    {
        char ch = Serial.read();
        if (ch >= '0' && ch <= '7')
        {
            int led = ch - '0';
            bitSet(leds, led);
            updateShiftRegister();
            Serial.print("Turned on LED ");
            Serial.println(led);
        }
        if (ch == 'x')
        {
            leds = 0;
            updateShiftRegister();
        }
    }
}
```

```
Serial.println("Cleared");  
}  
}  
}
```

Everything that happens inside the loop is contained within an 'if' statement. So unless the call to the built-in Arduino function 'Serial.available()' is 'true' then nothing else will happen. Serial.available() will return 'true' if data has been send to the UNO and is there ready to be processed. Incoming messages are held in what is called a buffer and Serial.available() returns true if that buffer is Not empty.

If a message has been received, then its on to the next line of code:

```
char ch = Serial.read();
```

This reads the next character from the buffer, and removes it from the buffer. It also assigns it to the variable 'ch'. The variable 'ch' is of type 'char' which stands for 'character' and as the name suggests, holds a single character.

If you have followed the instructions in the prompt at the top of the Serial Monitor, then this character will either be a single digit number between 0 and 7 or the letter 'x'.

The 'if' statement on the next line checks to see if it is a single digit by seeing if 'ch' is greater than or equal to the character '0' and less than or equal to the character '7'. It looks a little strange comparing characters in this way, but is perfectly acceptable.

Each character is represented by a unique number, called its ASCII value. This means that when we compare characters using <= and >= it is actually the ASCII values that were being compared.

If the test passes, then we come to the next line:

```
int led = ch - '0';
```

Now we are performing arithmetic on characters! We are subtracting the digit '0' from whatever digit was entered. So, if you typed '0' then '0' – '0' will equal 0. If you typed '7' then '7' – '0' will equal the number 7 because it is actually the ASCII values that are being used in the subtraction.

Since that we know the number of the LED that we want to turn on, we just need to set that bit in the variable 'leds' and update the shift register.

```
bitSet(leds, led);
```

```
updateShiftRegister();
```

The next two lines write back a confirmation message to the Serial Monitor.

```
Serial.print("Turned on LED ");
```

```
Serial.println(led);
```

The first line uses `Serial.print` rather than `Serial.println`. The difference between the two is that `Serial.print` does not start a new line after printing whatever is in its parameter. We use this in the first line, because we are printing the message in two parts. Firstly the general bit: 'Turned on LED ' and then the number of the LED.

The number of the LED is held in an 'int' variable rather than being a text string. `Serial.print` can take either a text string enclosed in double-quotes, or an 'int' or for that matter pretty much any type of variable.

After the 'if' statement that handles the case, when a single digit has been handled, there is a second 'if' statement that checks to see if 'ch' is the letter 'x'.

```
if (ch == 'x')  
{  
    leds = 0;  
    updateShiftRegister();  
    Serial.println("Cleared");  
}
```

If it is, then it clears all the LEDs and sends a confirmation message.

# Lesson 8 Photocell

## Overview

In this lesson, you will learn how to measure light intensity using an Analog Input. You will build on lesson 8 and use the level of light to control the number of LEDs to be lit.

The photocell is at the bottom of the breadboard, where the pot was above.

## Component Required:

(1) x Elegoo Uno R3

(1) x Breadboard

(8) x led

(8) x 220 ohm resistors

(1) x 1k ohm resistors

(1) x Breadboard

(1) x 74hc595 ic

(1) x Photocell

(14) x M-M wires

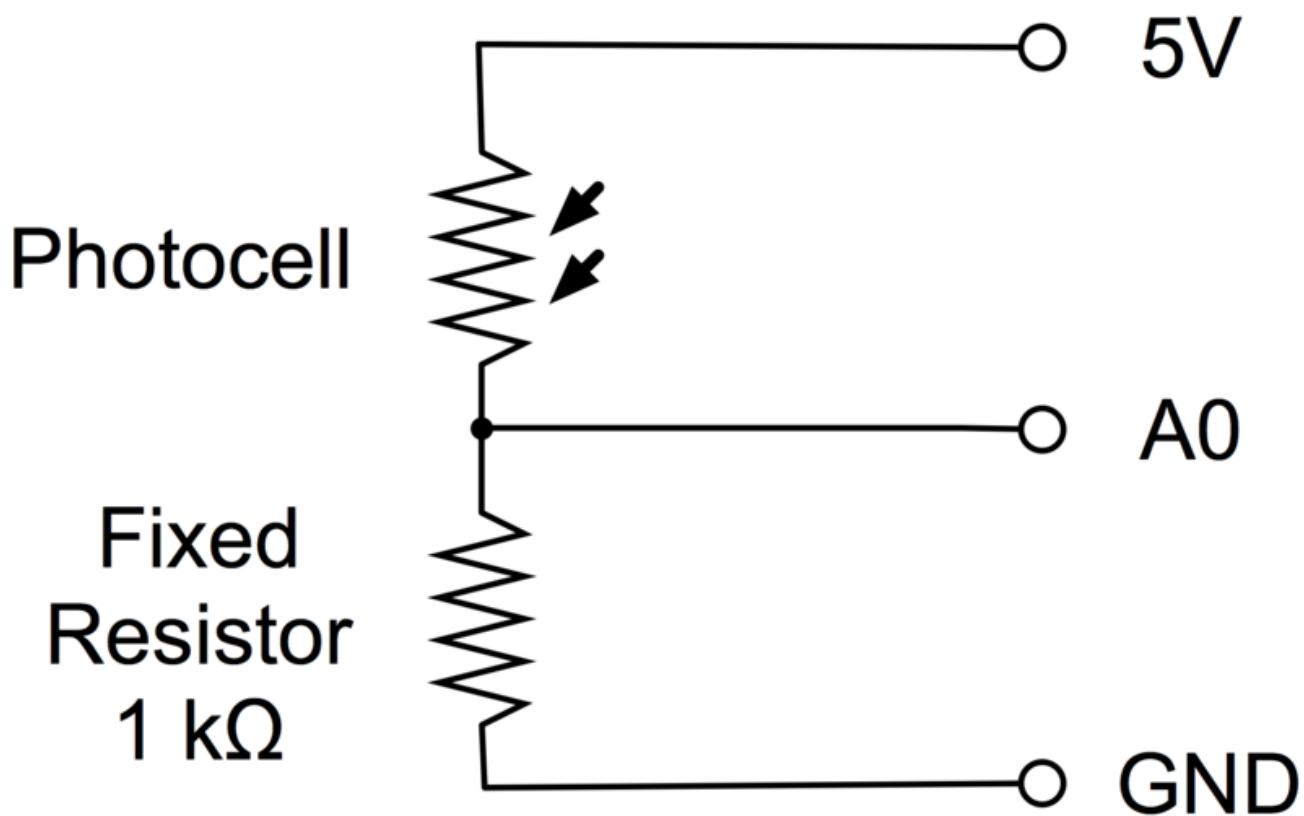
## Component Introduction

### PHOTOCELL:

The photocell used is of a type called a light dependent resistor, sometimes called an LDR. As the name suggests, these components act just like a resistor, except that the resistance changes in response to how much light is falling on them.

This one has a resistance of about  $50\text{ k}\Omega$  in near darkness and  $500\text{ }\Omega$  in bright light. To convert this varying value of resistance into something we can measure on an UNO R3 board's analog input, it need to be converted into a voltage.

The simplest way to do that is to combine it with a fixed resistor.



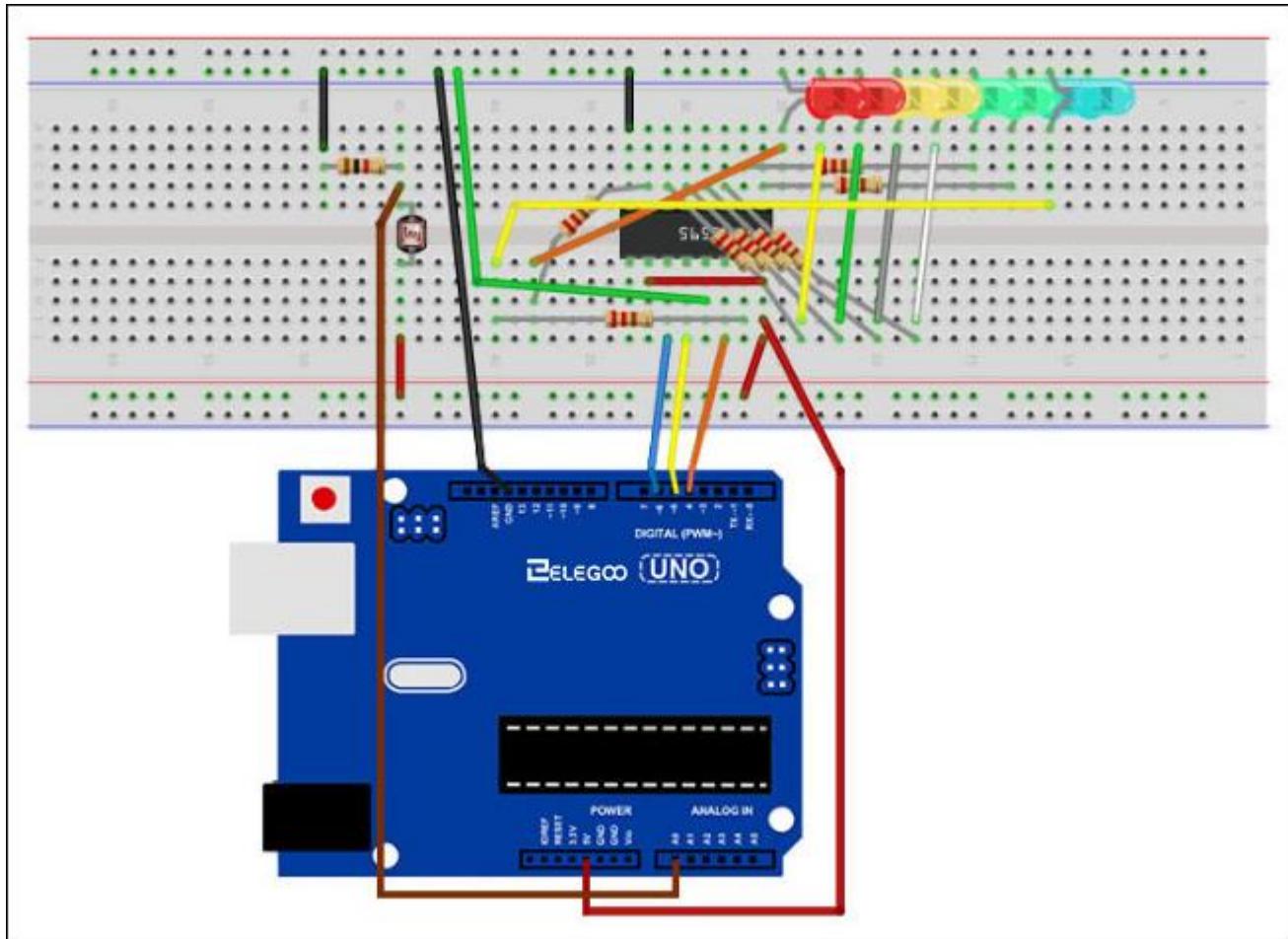
The resistor and photocell together behave like a pot. When the light is very bright, then the resistance of the photocell is very low compared with the fixed value resistor, and so it is as if the pot were turned to maximum.

When the photocell is in dull light, the resistance becomes greater than the fixed 1 kΩ resistor and it is as if the pot were being turned towards GND.

Load up the sketch given in the next section and try covering the photocell with your finger, and then holding it near a light source.

## Connection

### wiring diagram



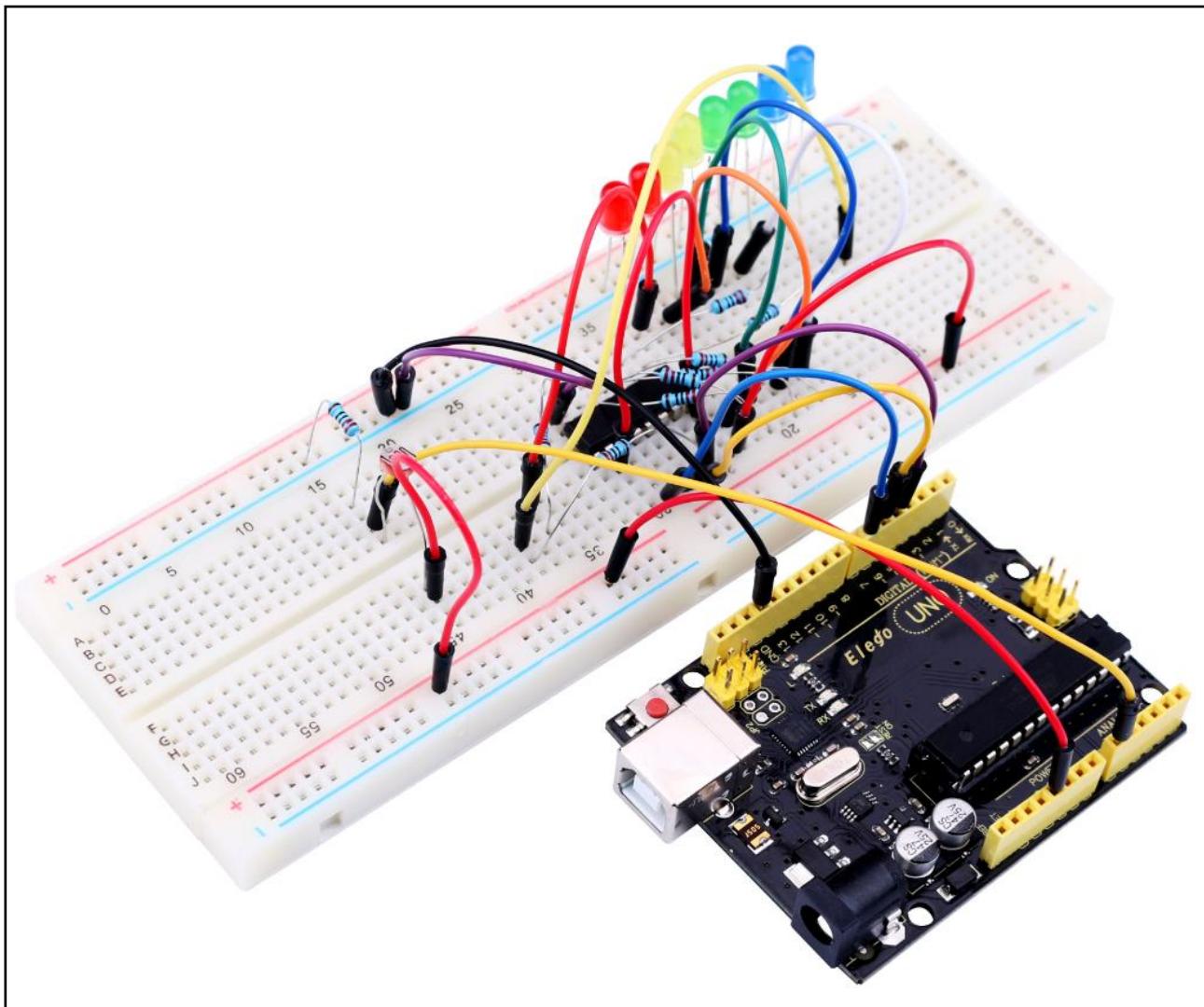
## Code

The first thing to note is that we have changed the name of the analog pin to be 'lightPin' rather than 'potPin' since we no longer have a pot connected.

The only other substantial change to the sketch is the line that calculate how many of the LEDs to light:

```
int numLEDSLit = reading / 57; // all LEDs lit at 1k
```

This time, we divide the raw reading by 57 rather than 114. In other words, we divide it by half as much as we did with the pot to split it into nine zones, from no LEDs lit to all eight lit. This extra factor is to account for the fixed 1 kΩ resistor. This means that when the photocell has a resistance of 1 kΩ (the same as the fixed resistor), the raw reading will be  $1023 / 2 = 511$ . This will equate to all the LEDs being lit and then a bit (numLEDSLit) will be 9.



# Lesson 9 Making Sounds

## Overview

In this lesson, you will learn how to generate a sound with an active buzzer.

## Component Required:

- (1) x Elegoo Uno R3
- (1) x Active buzzer
- (2) x F-M wires

## Component Introduction

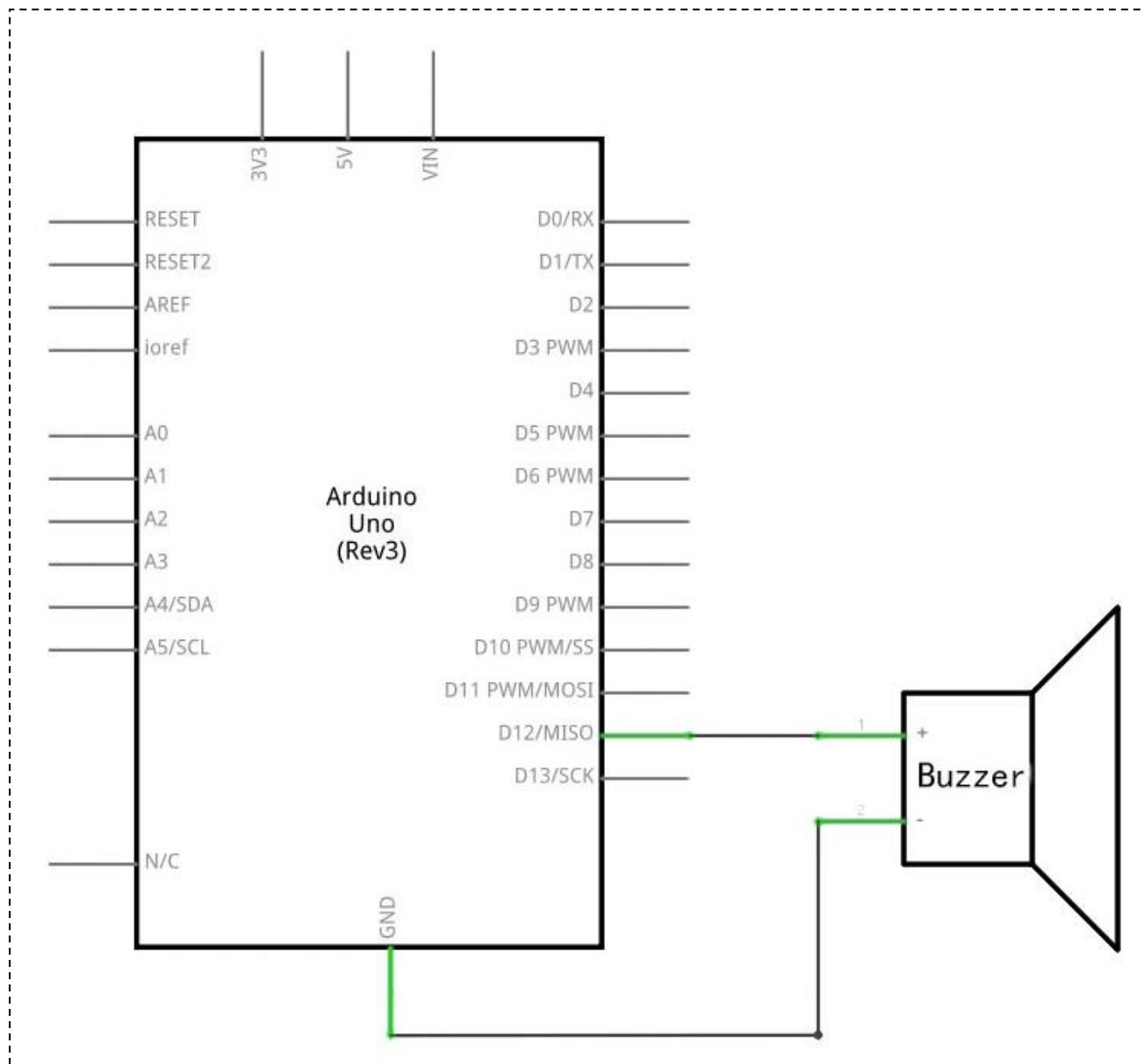
### BUZZER:

Electronic buzzers are DC-powered and equipped with an integrated circuit. They are widely used in computers, printers, photocopiers, alarms, electronic toys, automotive electronic devices, telephones, timers and other electronic products for voice devices. Buzzers can be categorized as active and passive ones. Turn the pins of two buzzers face up. The one with a green circuit board is a passive buzzer, while the other enclosed with a black tape is an active one.

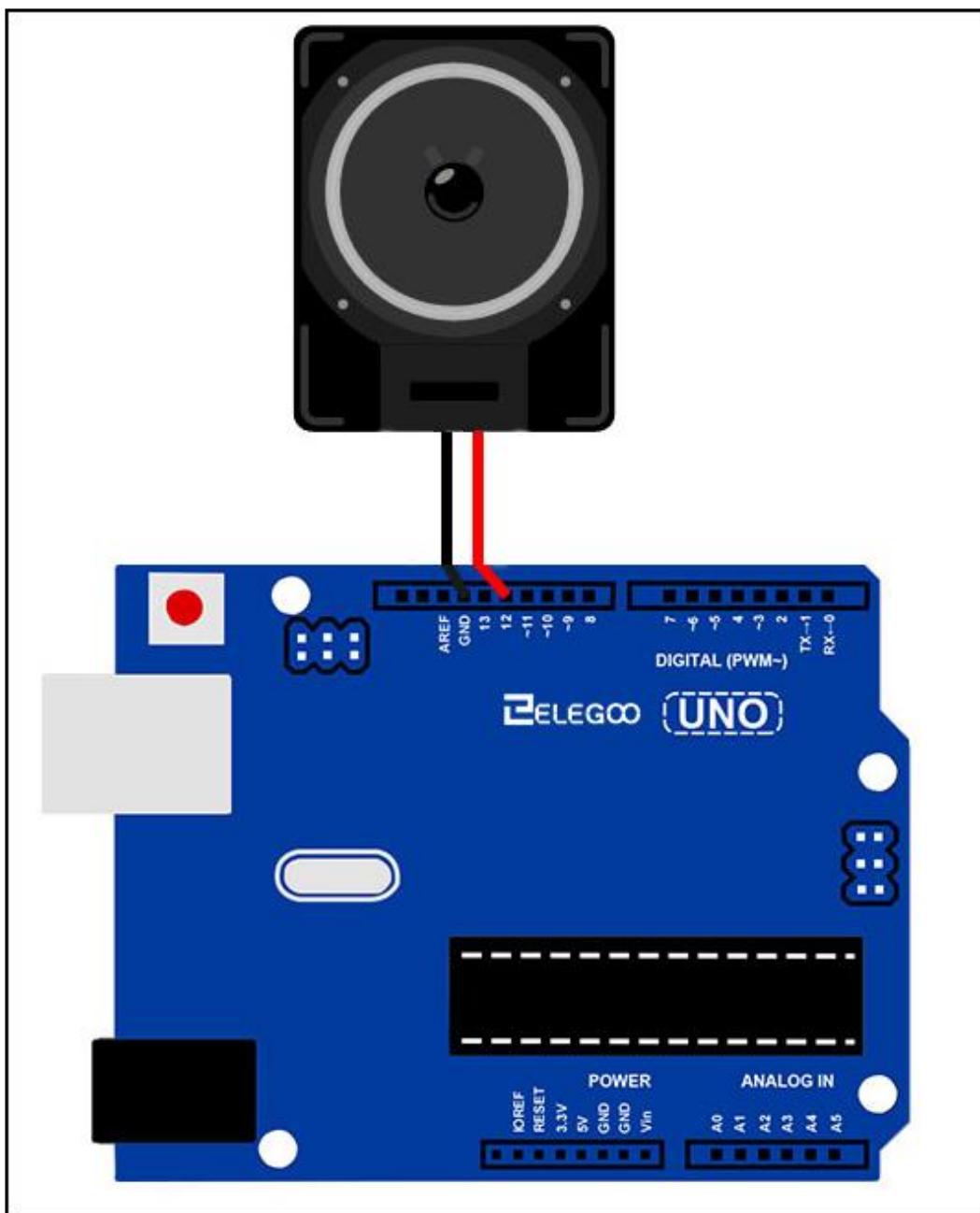
The difference between the two is that an active buzzer has a built-in oscillating source, so it will generate a sound when electrified. A passive buzzer does not have such a source so it will not tweet if DC signals are used; instead, you need to use square waves whose frequency is between 2K and 5K to drive it. The active buzzer is often more expensive than the passive one because of multiple built-in oscillating circuits.

## Connection

### Schematic

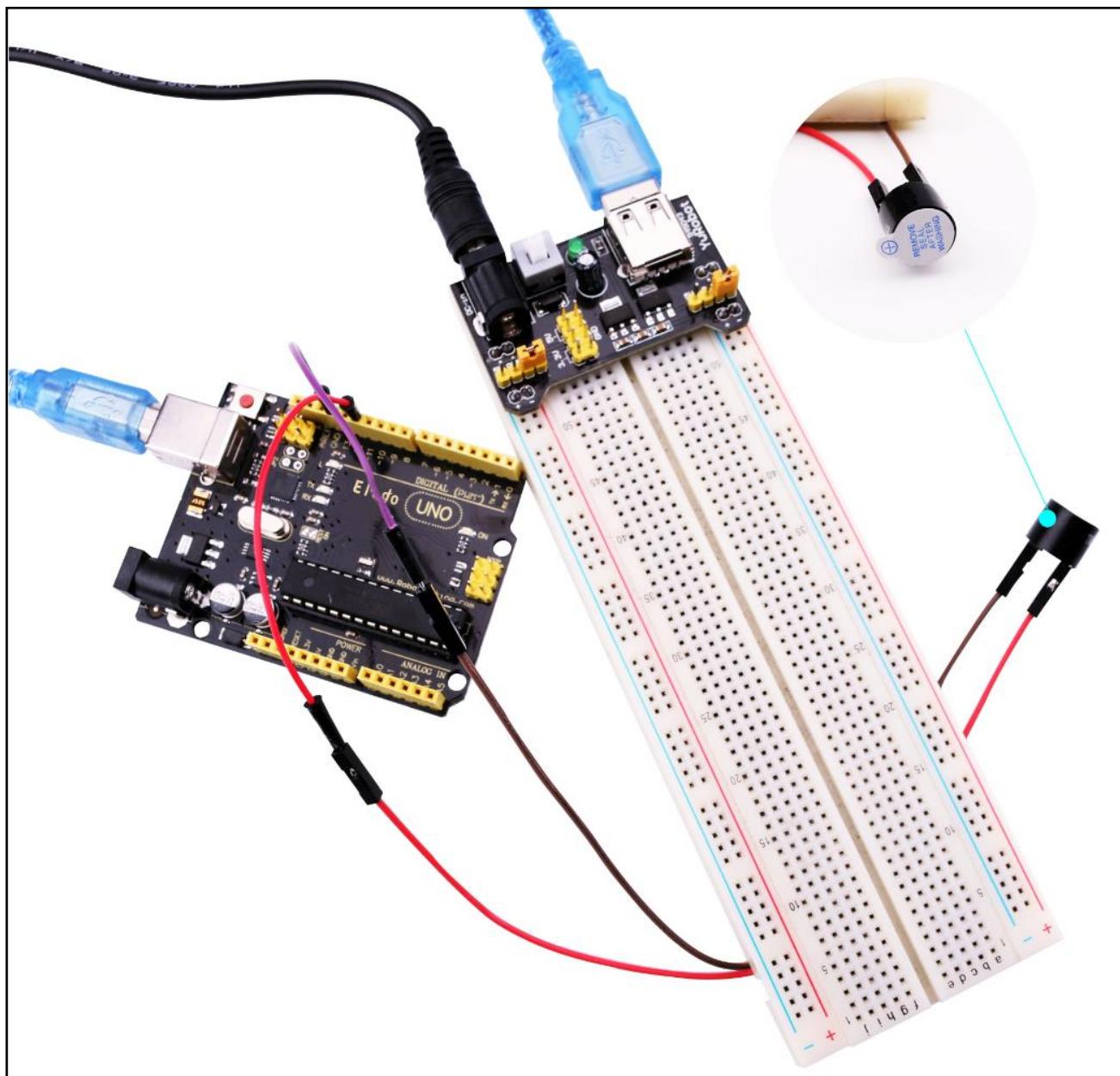


wiring diagram



## Code

See the code file.



# Lesson 10 Passive Buzzer

## Overview

In this lesson, you will learn how to use a passive buzzer.

The purpose of the experiment is to generate eight different sounds, each sound lasting 0.5 seconds: from Alto Do (523Hz), Re (587Hz), Mi (659Hz), Fa (698Hz), So (784Hz), La (880Hz), Si (988Hz) to Treble Do (1047Hz).

## Component Required:

- (1) x Elegoo Uno R3
- (1) x Passive buzzer
- (2) x F-M wires

## Component Introduction

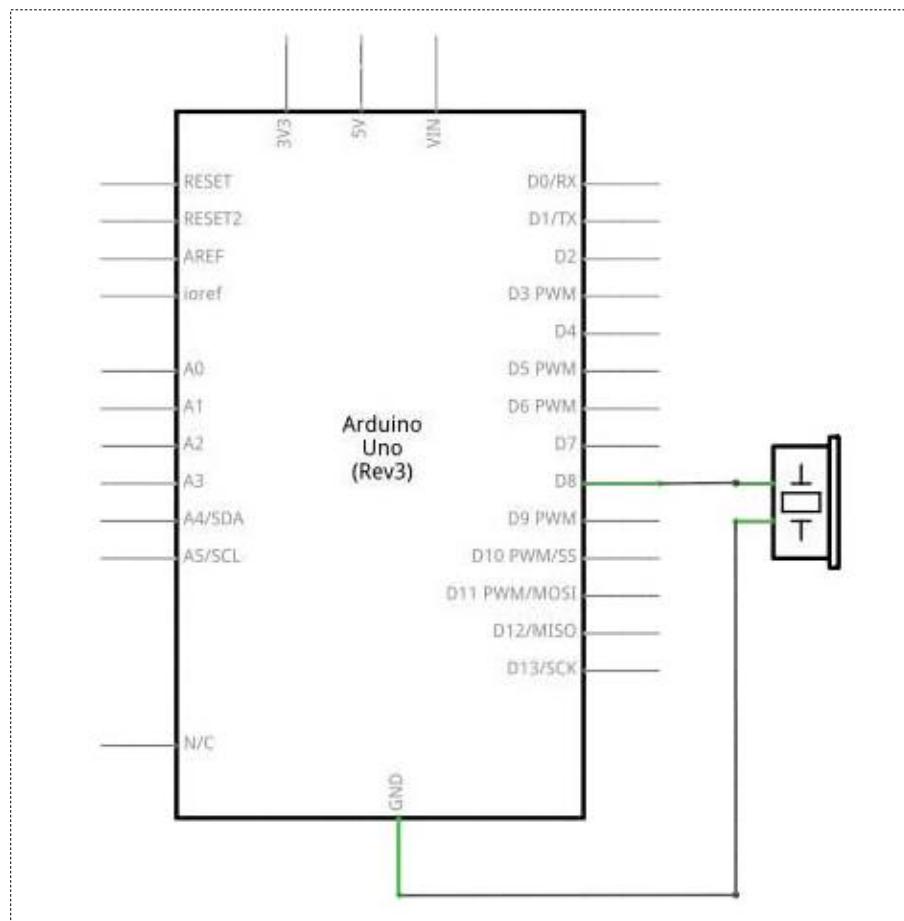
### Passive Buzzer:

The working principle of passive buzzer it to use PWM generating audio to make the air to vibrate. Appropriately changed as long as the vibration frequency, it can generate different sounds. For example, sending a pulse of 523Hz, it can generate Alto Do, pulse of 587Hz, it can generate midrange Re, pulse of 659Hz, it can produce midrange Mi. By the buzzer, you can play a song.

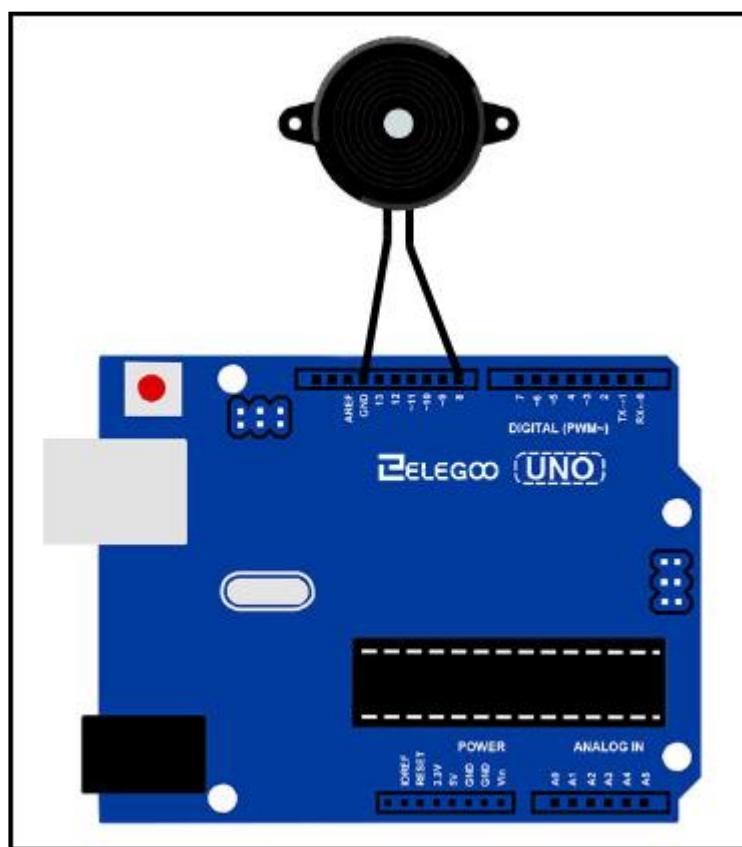
We should be careful not to use the UNO R3 board analog Write () function to generate a pulse to the buzzer, because the pulse output of analog Write () is fixed (500Hz).

## Connection

### Schematic



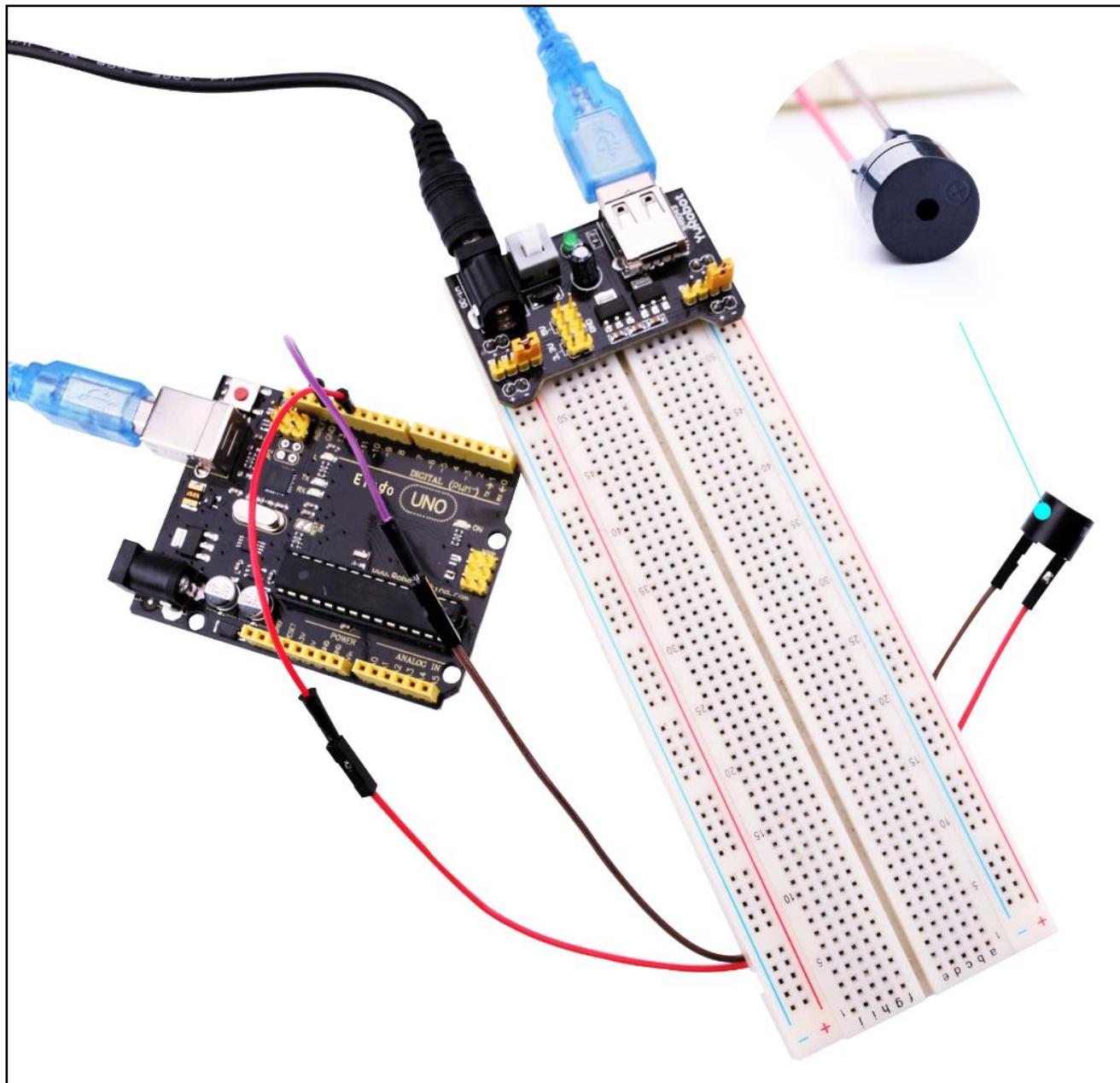
wiring diagram



Wiring the buzzer connected to the UNO R3 board, the red (positive) to the pin8, black wire (negative) to the GND.

## Code

Before you can run this, make sure that you have installed the <pitches> library or re-install it, if necessary. Otherwise, your code won't work.



# Lesson 11 Ball Switch

## Overview

In this lesson, you will learn how to use a ball switch in order to detect small angle of inclination.

## Component Required:

- (1) x Elegoo Uno R3
- (1) x Ball switch
- (2) x F-M wires

## Component Introduction

### Tilt sensor:

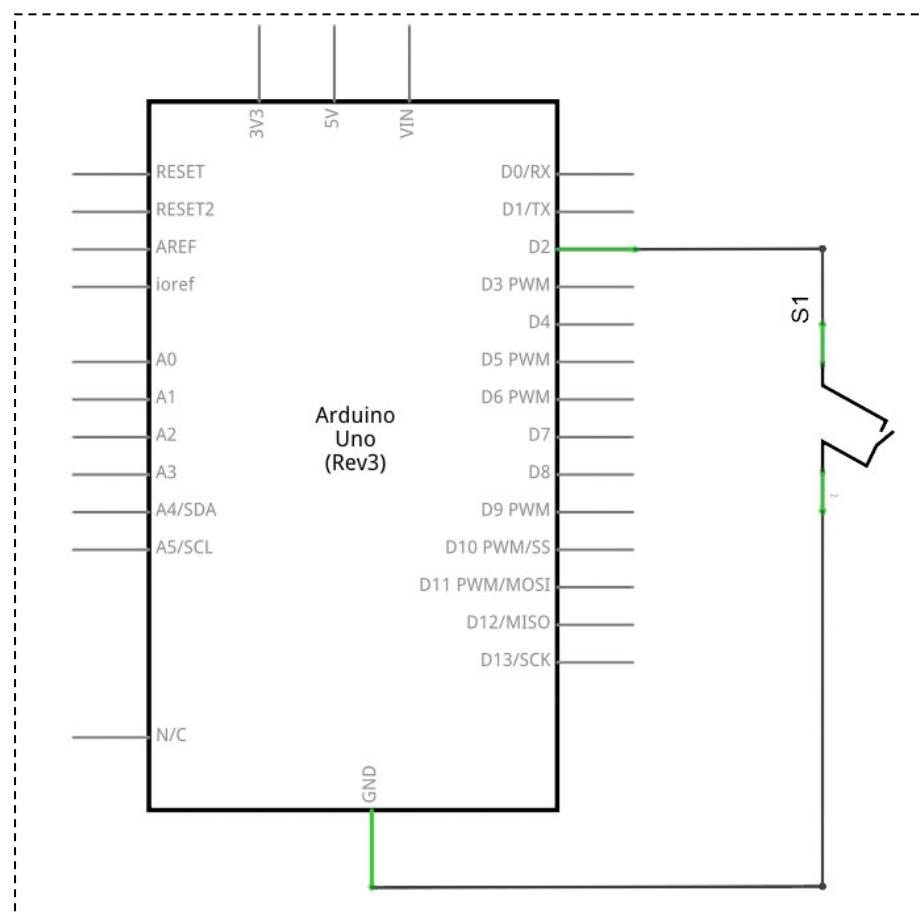
Tilt sensors allow you to detect orientation or inclination. They are small, inexpensive, low-power and easy-to-use. If used properly, they will not wear out. Their simplicity makes them popular for toys, gadgets and appliances. Sometimes, they are referred to as "mercury switches", "tilt switches" or "rolling ball sensors" for obvious reasons.

They are usually made up of a cavity of some sort (cylindrical is popular, although not always) with a conductive free mass inside, such as a blob of mercury or rolling ball. One end of the cavity has two conductive elements (poles). When the sensor is oriented so that that end is downwards, the mass rolls onto the poles and shorts them, acting as a switch throw.

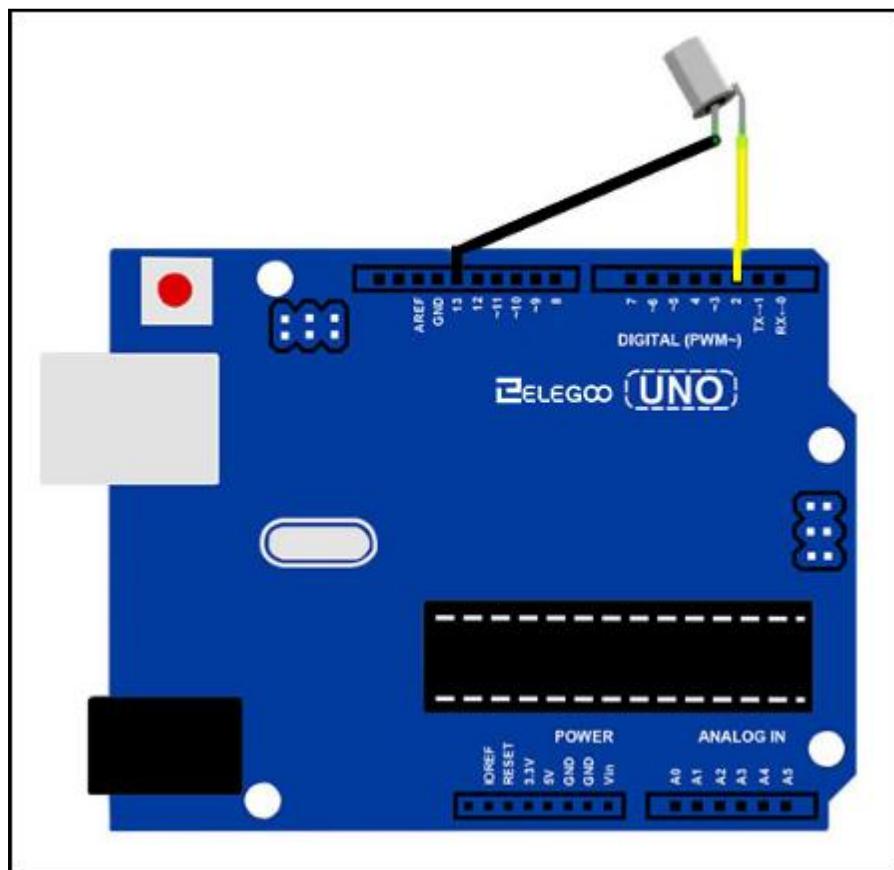
While not as precise or flexible as a full accelerometer, tilt switches can detect motion or orientation. Another benefit is that the big ones can switch power on their own. Accelerometers, on the other hand, output digital or analog voltage that must then be analyzed using extra circuitry.

## Connection

### Schematic

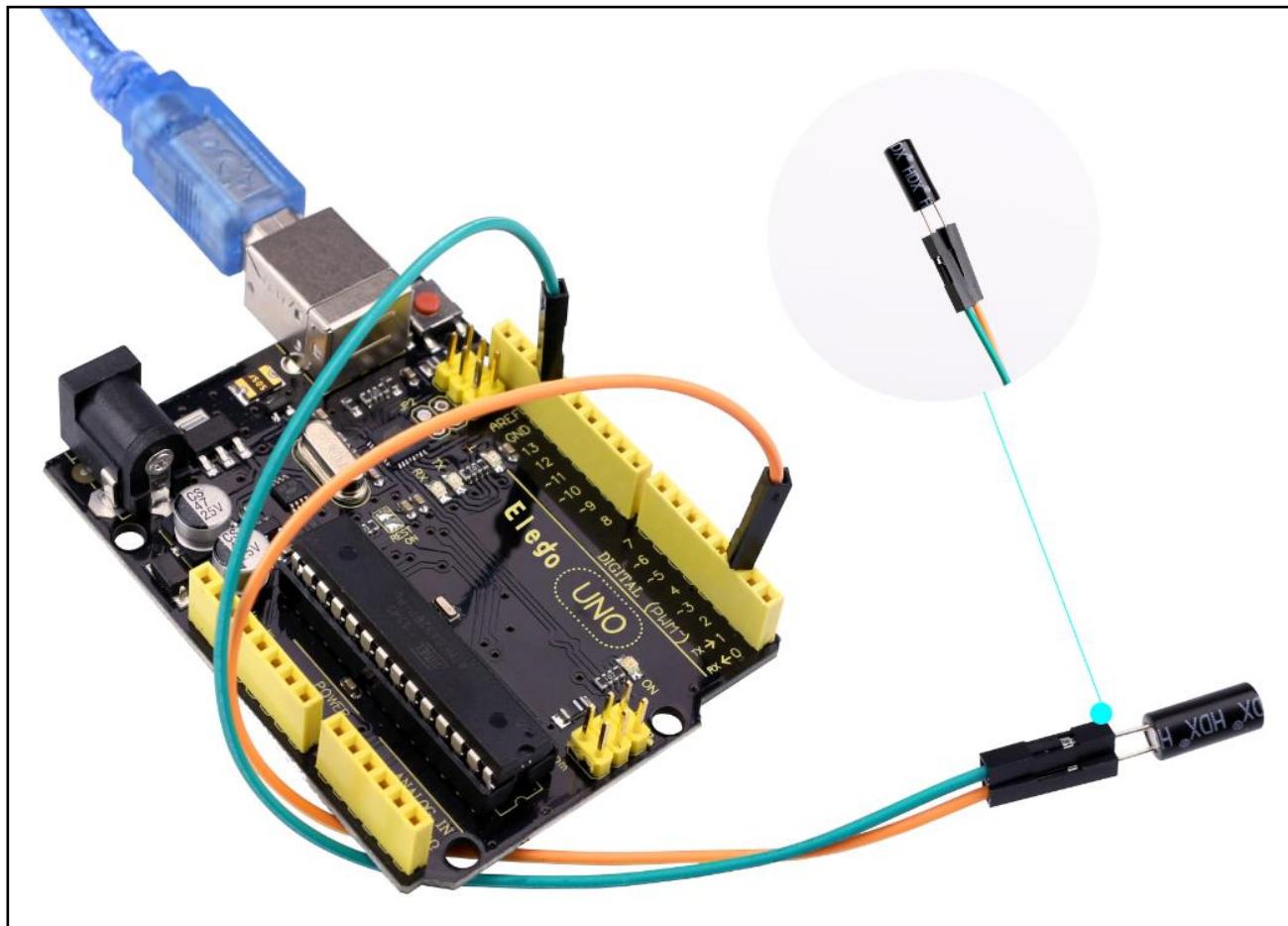


wiring diagram



## Code

See the code file.



# Lesson 12 Relay

## Overview

In this lesson, you will learn how to use a relay.

## Component Required:

- (1) x Elegoo Uno R3
- (1) x Breadboard
- (1) x PN2222
- (1) x 1N4007
- (1) x 220 ohm resistor
- (1) x 6v dc motor
- (1) x Relay
- (1) x Breadboard power supply module
- (1) x 9v power supply adapter
- (8) x M-M wires

## Component Introduction

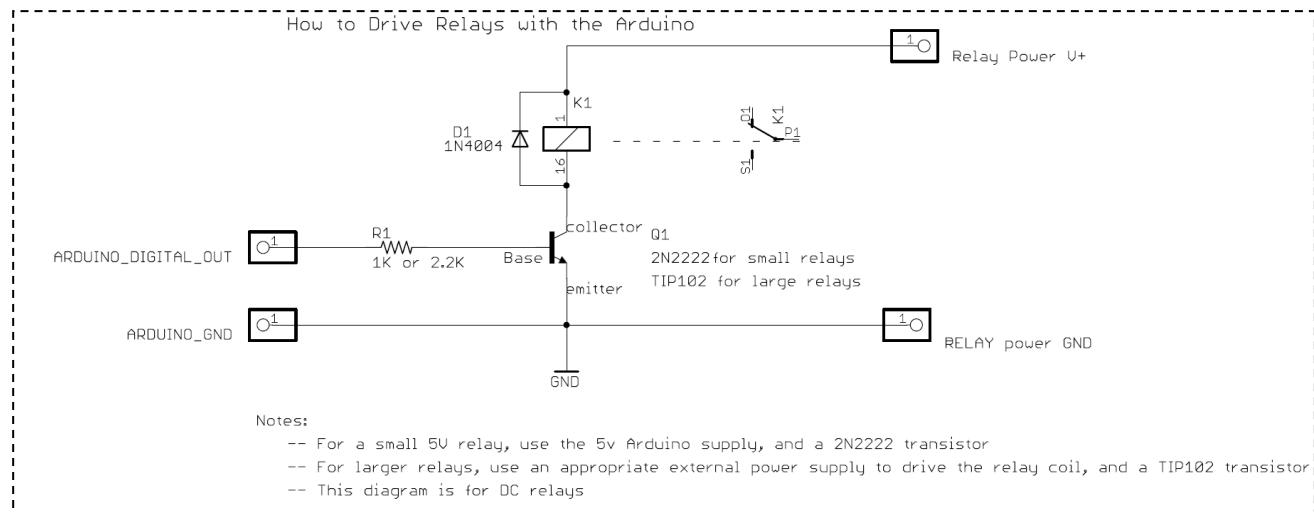
### Relay:

A relay is an electrically operated switch. Many relays use an electromagnet to mechanically operate a switch, but other operating principles are also used as in solid-state relays. Relays are used where it is necessary to control a circuit by a low-power signal (with complete electrical isolation between control and controlled circuits), or where several circuits must be controlled by one signal. The first relays were used in long-distance telegraph circuits as amplifiers. They repeated the signal coming in from one circuit and re-transmitted it on another circuit. Relays were used extensively in telephone exchanges and early computers to perform logical operations.

A type of relay that can handle the high power required to directly control an electric motor or other loads is called a contactor. Solid-state relays control power circuits with no moving

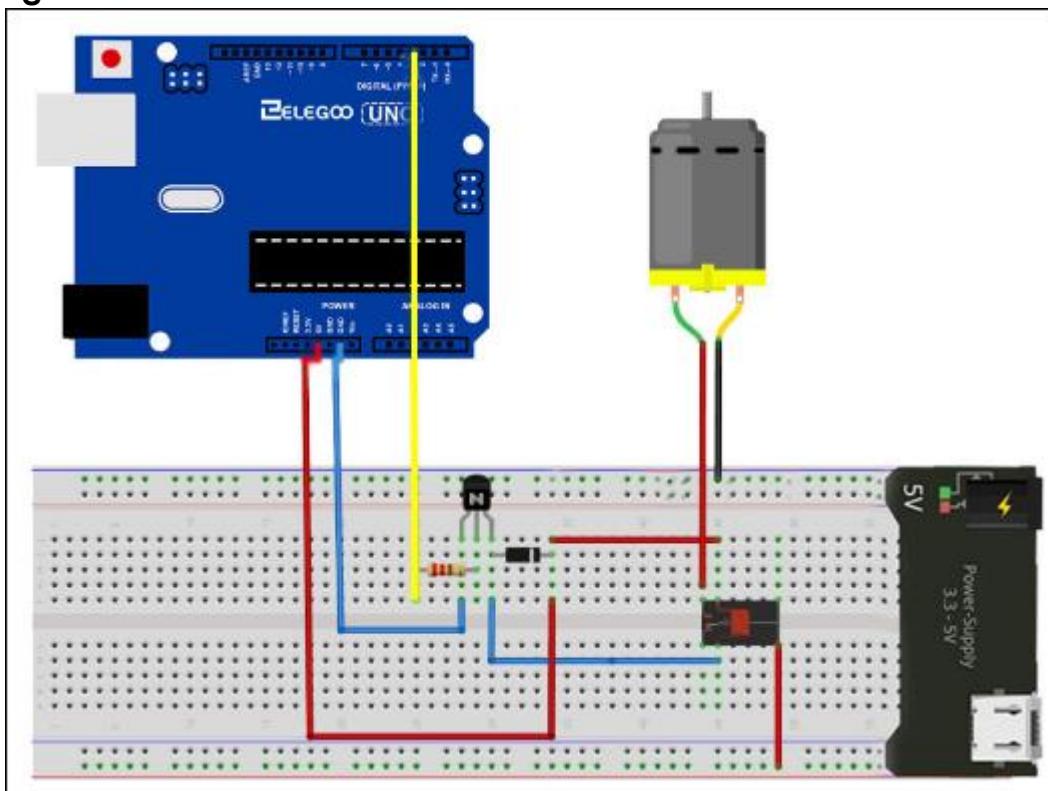
parts, instead using a semiconductor device to perform the switching. Relays with calibrated operating characteristics and sometimes multiple operating coils are used to protect electrical circuits from overload or faults. In modern electric power systems, these functions are performed by digital instruments called "protective relays".

Below is the schematic of how to drive relay with Arduino (download from the arduino.cc)



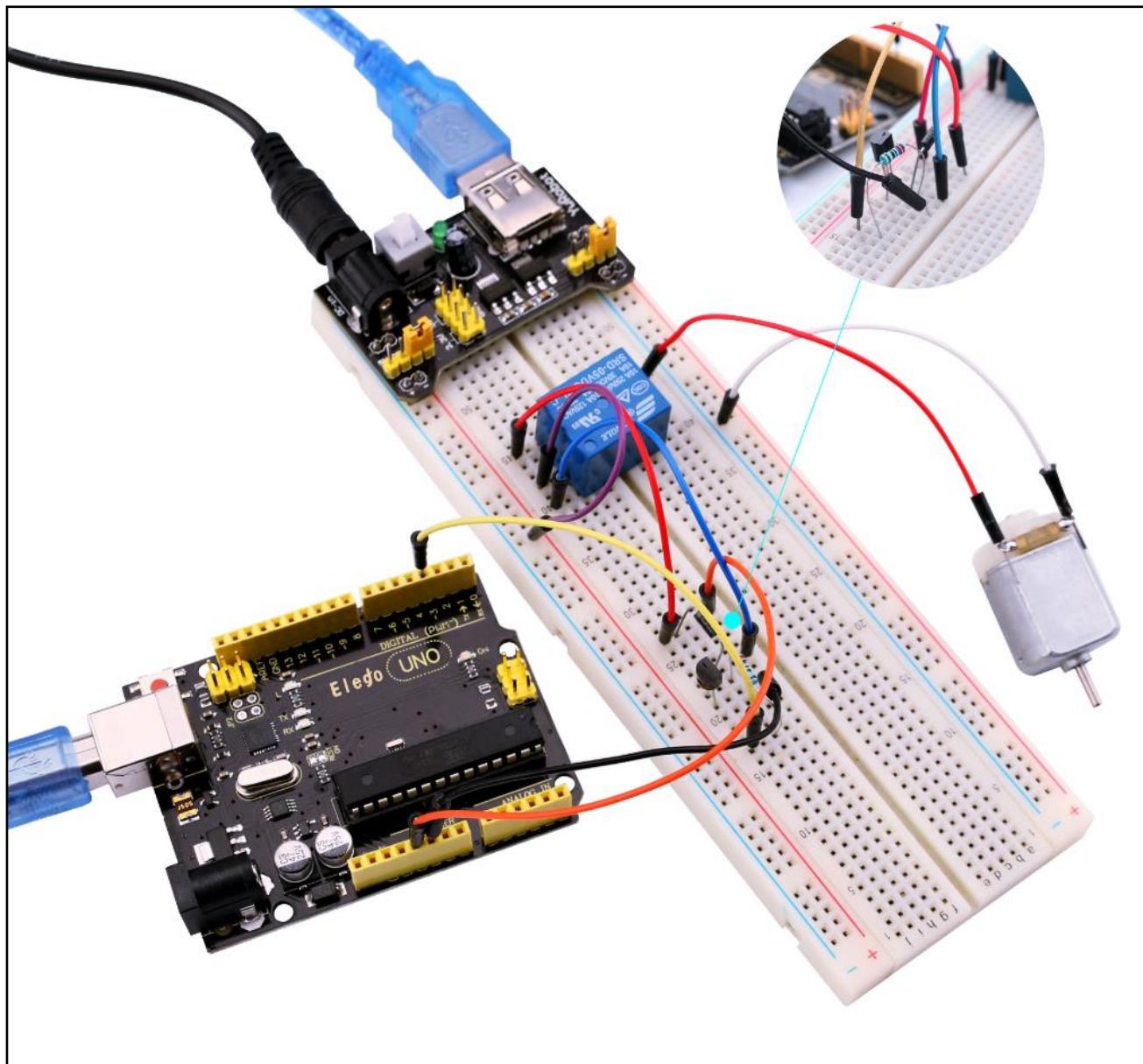
## Connection

### wiring diagram



## Code

See the code file.



# Lesson 13 74HC595 And Segment Display

## Overview

After learning Lesson 6 and Lesson 7, we will use the 74HC595 shift register to control the segment display. The segment display will show number from 9-0.

## Component Required:

(1) x Elegoo Uno R3

(2) x Breadboard

(1) x 74HC595

(1) x Segment Display

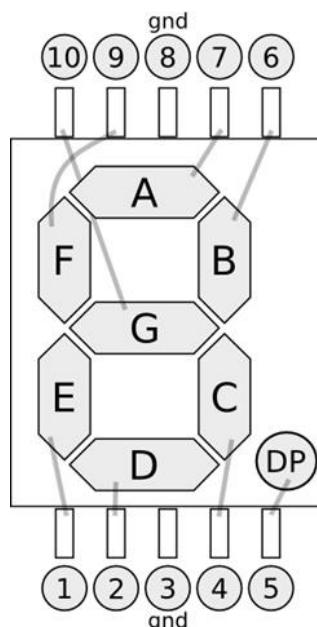
(8) x 220 ohm resistor

(20) x M-M wires

## Component Introduction

### Seven segment display

Below is the seven-segment pin diagram.



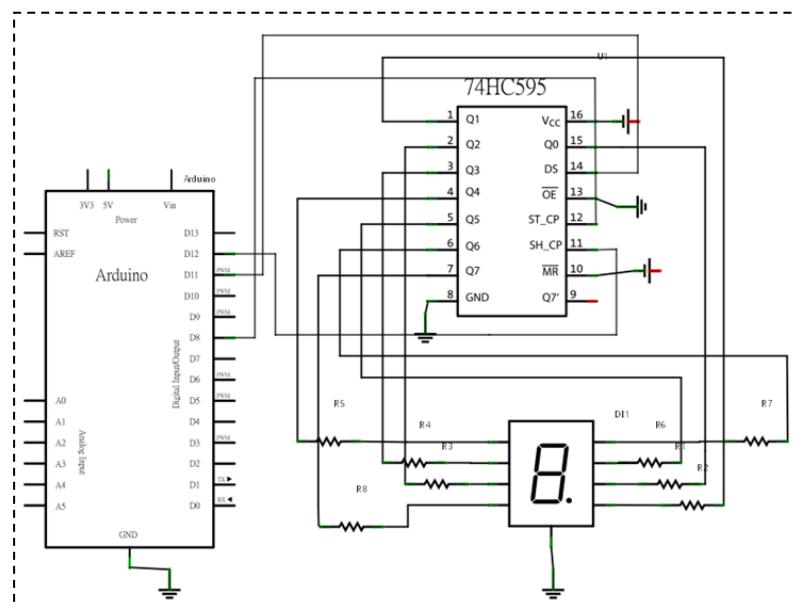
0-9 ten digits correspond with each segment are as follows (the following table applies

common cathode seven segment display device, if you are using a common anode, the table should be replaced every 1 0 0 should all replaced by 1):

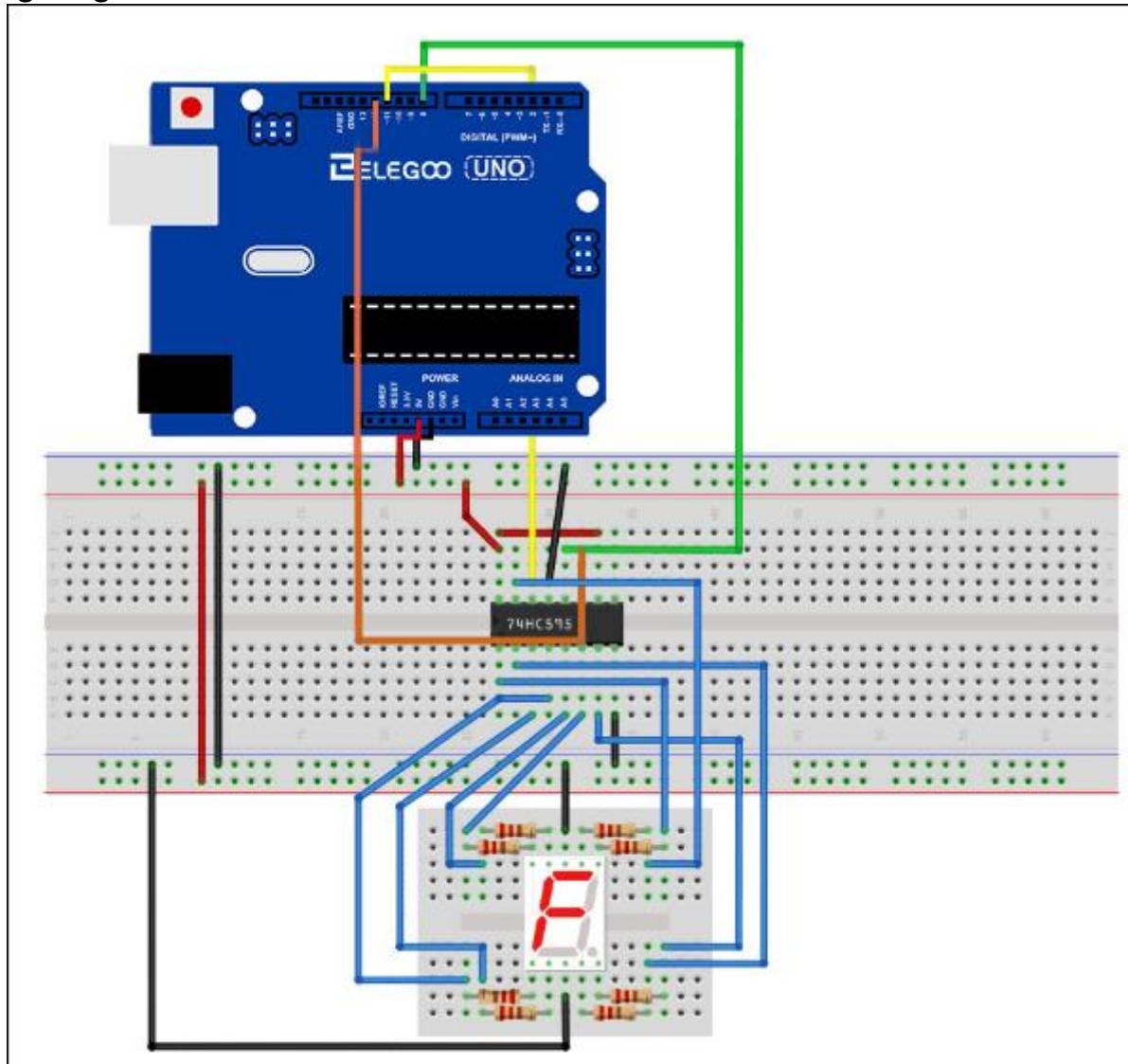
Display digital	dp	a	b	c	d	e	f	g
0	0	1	1	1	1	1	1	0
1	0	0	1	1	0	0	0	0
2	0	1	1	0	1	1	0	1
3	0	1	1	1	1	0	0	1
4	0	0	1	1	0	0	1	1
5	0	1	0	1	1	0	1	1
6	0	1	0	1	1	1	1	1
7	0	1	1	1	0	0	0	0
8	0	1	1	1	1	1	1	1
9	0	1	1	1	1	0	1	1

## Connection

### Schematic



## wiring diagram



The following table shows the seven-segment display 74HC595 pin correspondence table:

74HC595 pin	Seven shows remarkable control pin (stroke)
Q0	7 (A)
Q1	6 (B)
Q2	4 (C)
Q3	2 (D)
Q4	1 (E)
Q5	9 (F)
Q6	10 (G)

Q7	5 (DP)
----	--------

### Step one: Connect 74HC595

First, the wiring is connected to power and ground:

- Vcc (pin 16) and MR (pin 10) connected to 5V
- GND (pin 8) and OE (pin 13) to ground

Connection DS, ST\_CP and SH\_CP pin:

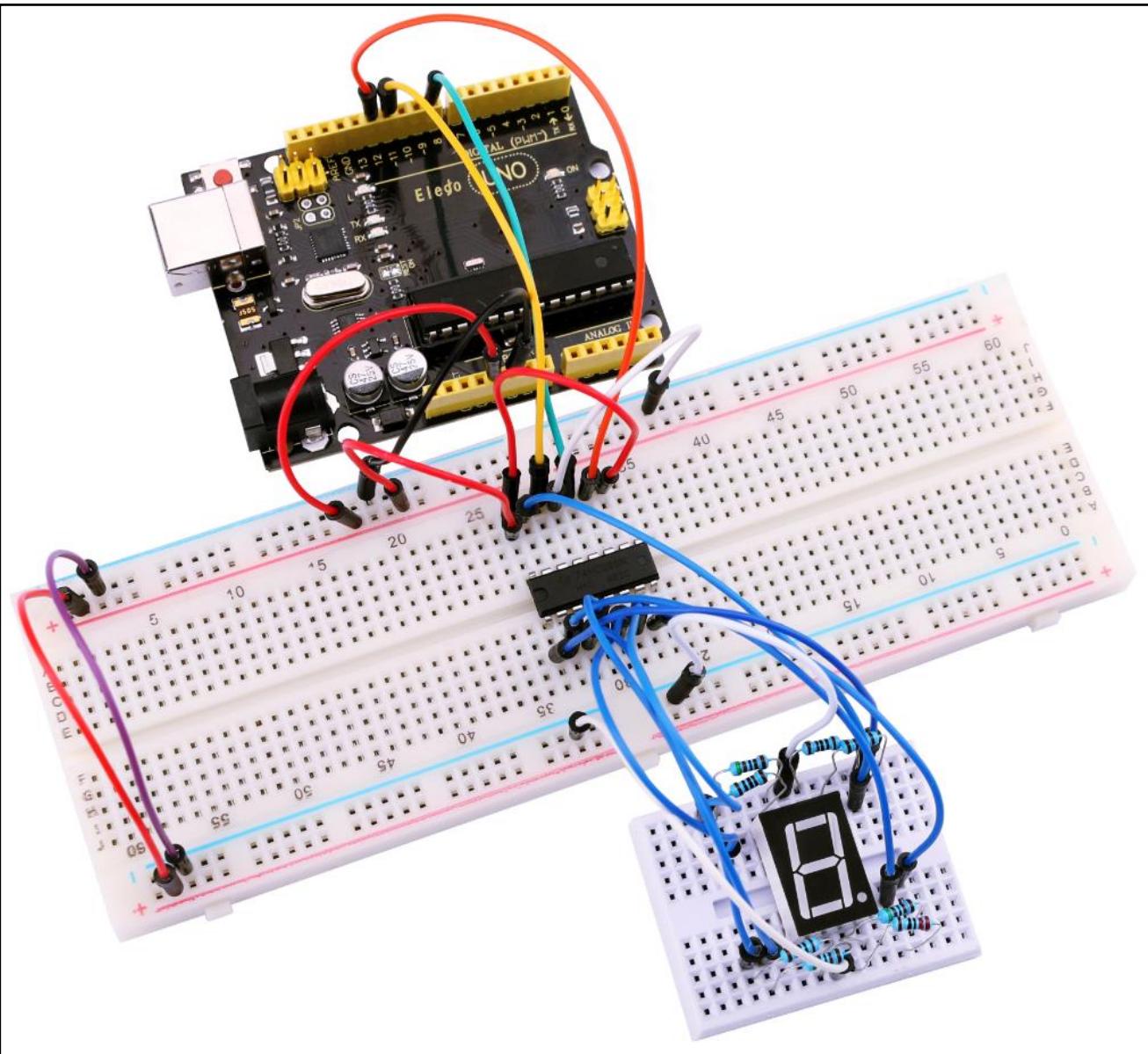
- DS (pin 14) connected to UNO R3 board pin 11 (the figure below the blue line)
- ST\_CP (pin 12, latch pin) connected to UNO R3 board pin 8 (FIG green line below)
- SH\_CP (pin 11, clock pin) connected to UNO R3 board pin 12 (the figure below the yellow line)

### Step two: Connect the seven segment display

- The seven-segment display 3, 8 pin to UNO R3 board GND (This example uses the common cathode, if you use the common anode, please connect the 3, 8 pin to UNO R3 board + 5V)
- According to the table above, connect the 74HC595 Q0 ~ Q7 to seven-segment display corresponding pin (A ~ G and DP), and then each foot in a 220 ohm resistor in series.

## Code

See the code file.



# Lesson 14 Four Digital Seven Segment Display

## Overview

In this lesson, you will learn how to use a 4-digit 7-segment display.

When using 1-digit 7-segment display and it is common anode, the common anode pin connects to the power source; if it is common cathode, the common cathode pin connects to the GND.

When using 4-digit 7-segment display, the common anode or common cathode pin is used to control which digit is displayed. Even though there is only one digit working, the principle of Persistence of Vision enables you to see all numbers displayed because each the scanning speed is so fast you hardly notice the intervals.

## Component Required:

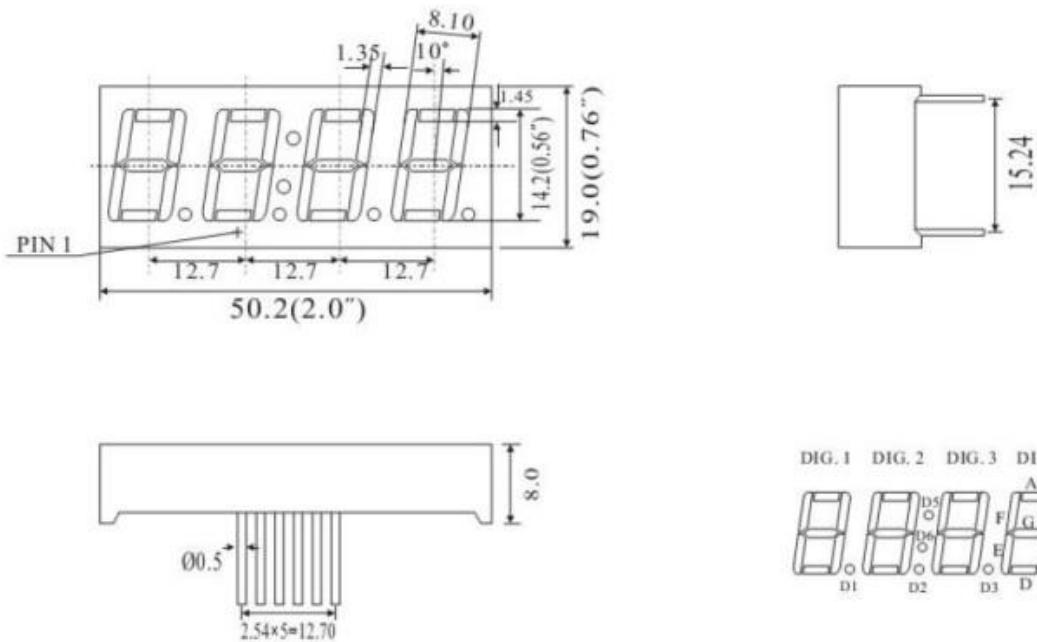
- (1) x Elegoo Uno R3
- (1) x Breadboard
- (1) x 74HC595
- (1) x Four Digital Tube Segment Display
- (4) x 220 ohm resistor
- (20) x M-M wires

## Component Introduction

### Four Digital Seven segment display

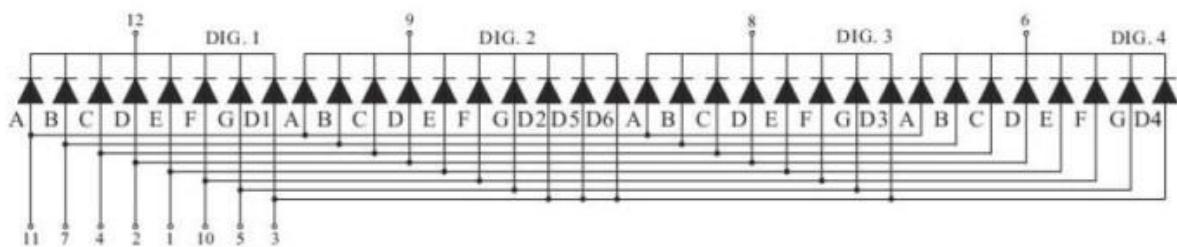
## Package Dimensions

**CPS05643AB**

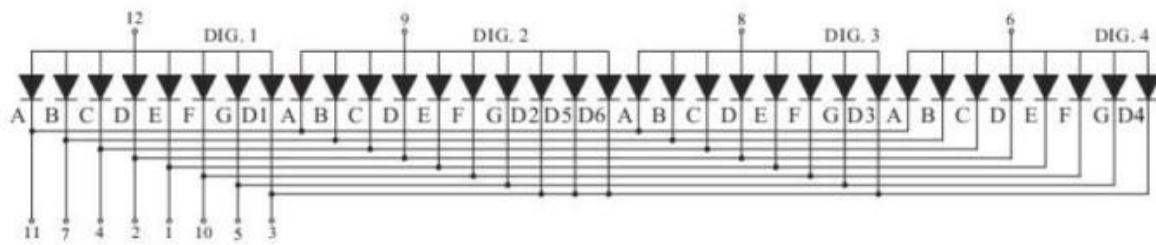


UNIT: MM(INCH) TOLERANCE:  $\pm 0.25(0.01")$

## Internal Circuit Diagram



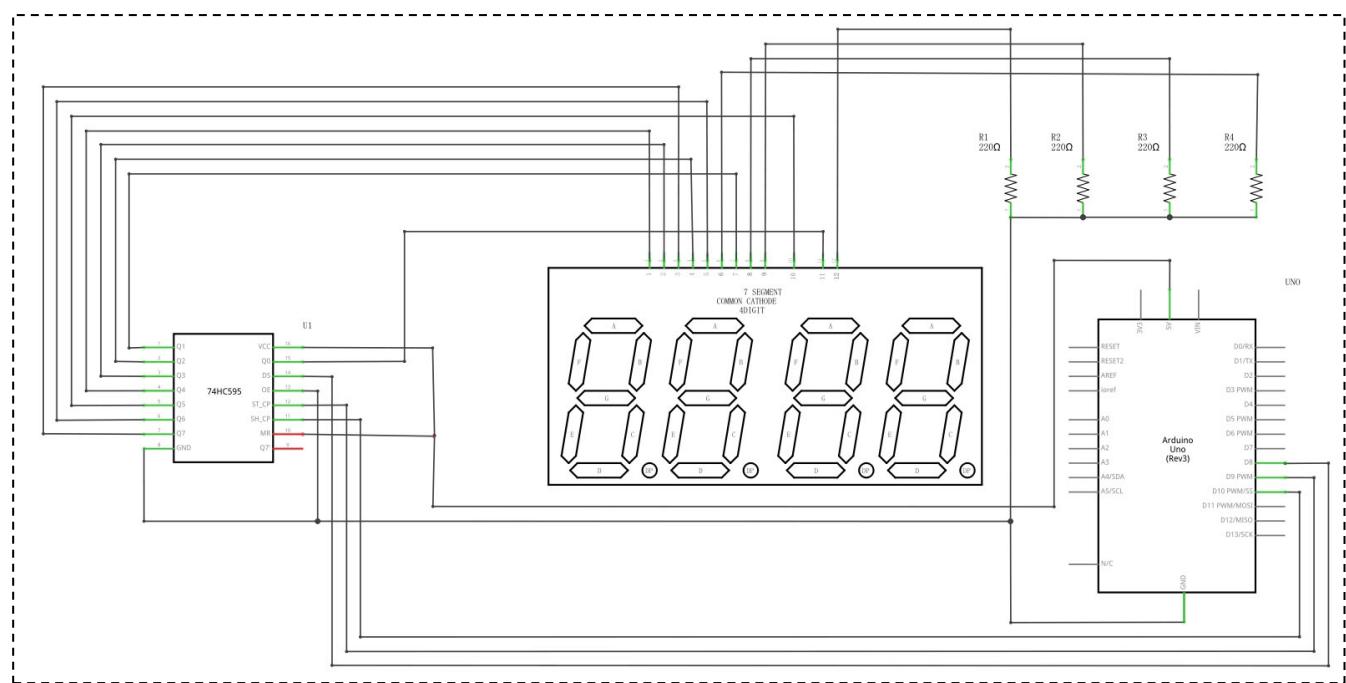
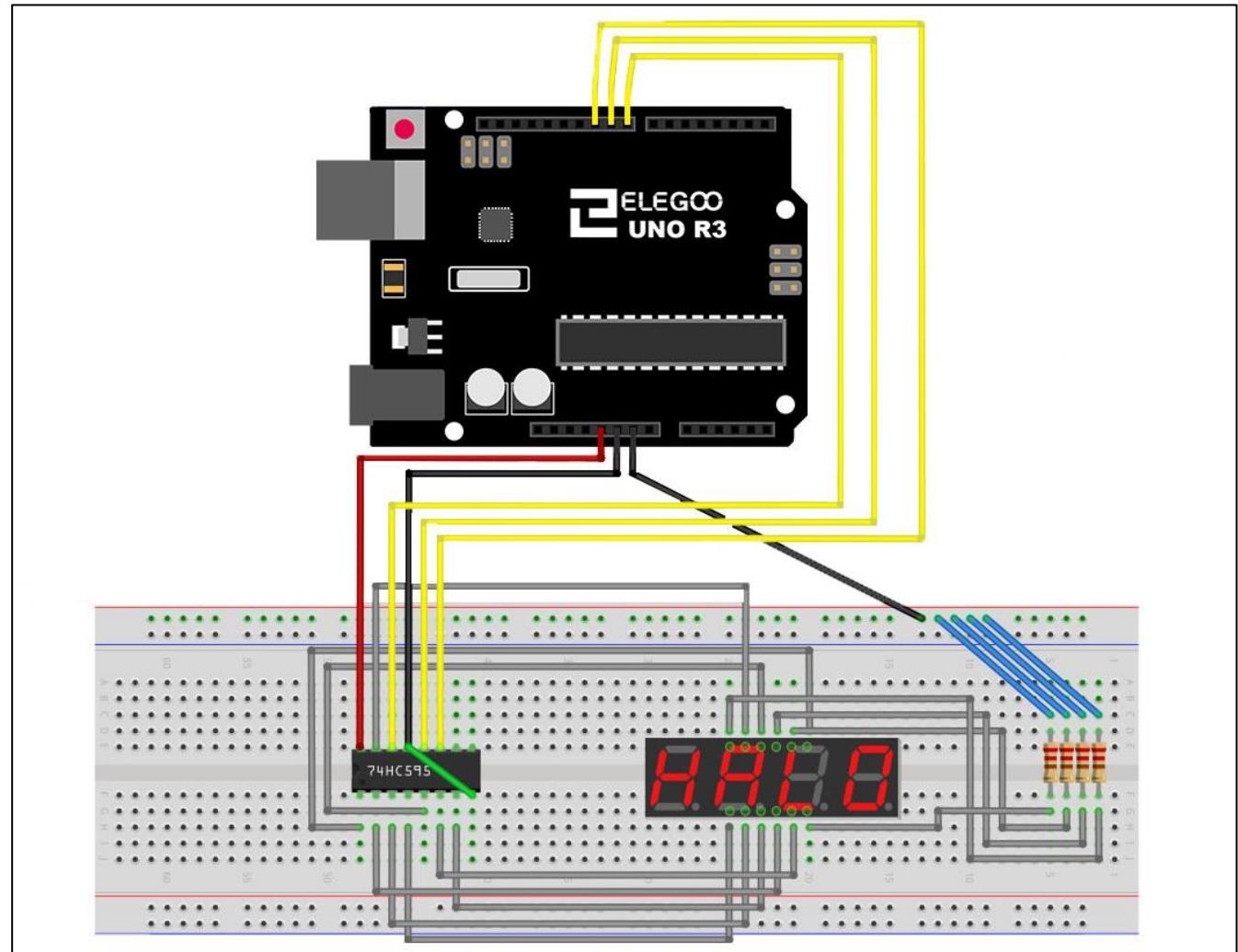
**5643A**



**5643B**

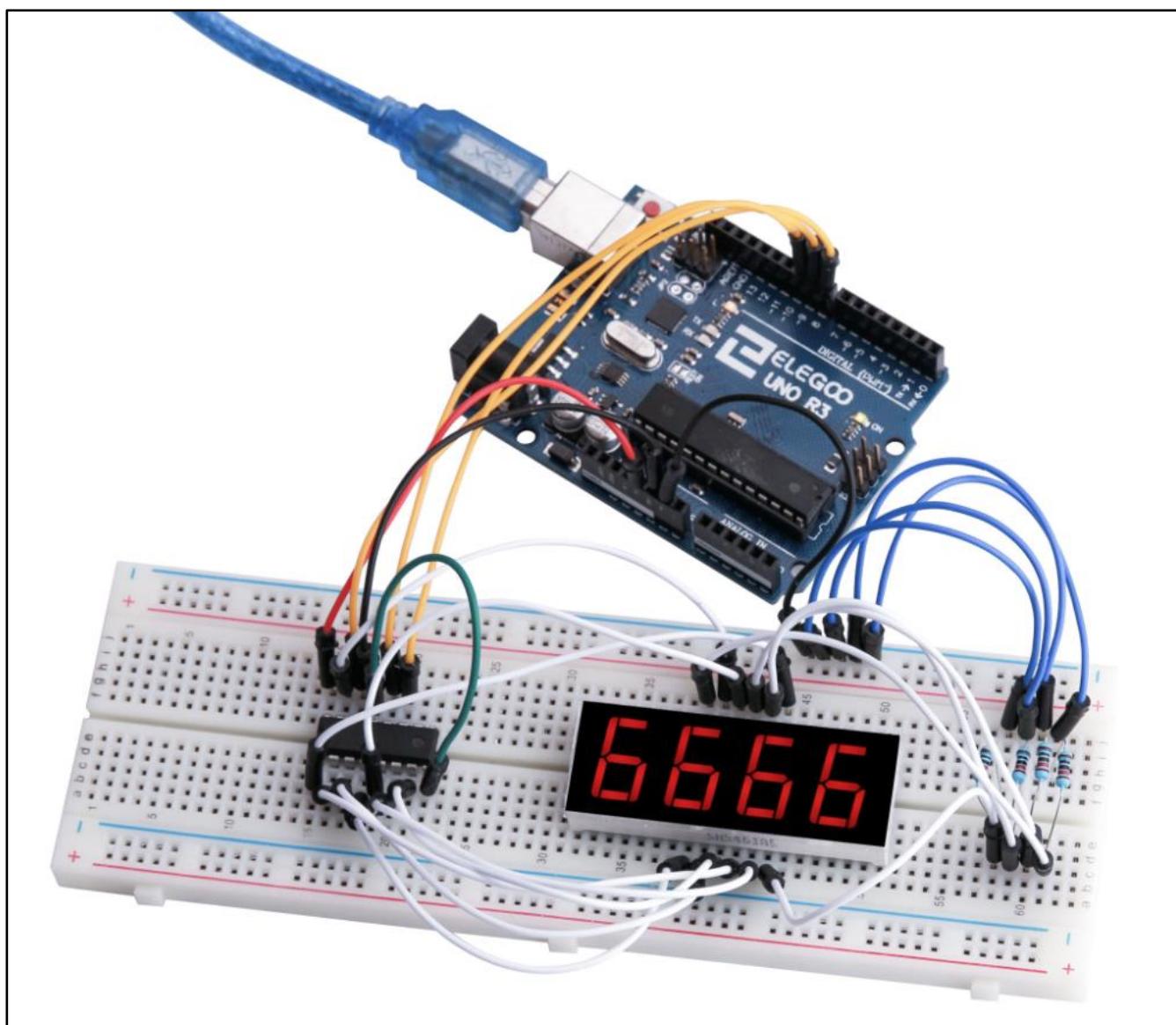
## Four Digits Displays Series

## Connection

**Schematic****wiring diagram**

## Code

See the code file.



# Lesson 15 Servo

## Overview

Servo is a type of geared motor that can only rotate 180 degrees. It is controlled by sending electrical pulses from your UNO R3 board. These pulses tell the servo what position it should move to. A servo has three wires, the brown wire is GND, the red one is VCC, and the orange one is signal line.

## Component Required:

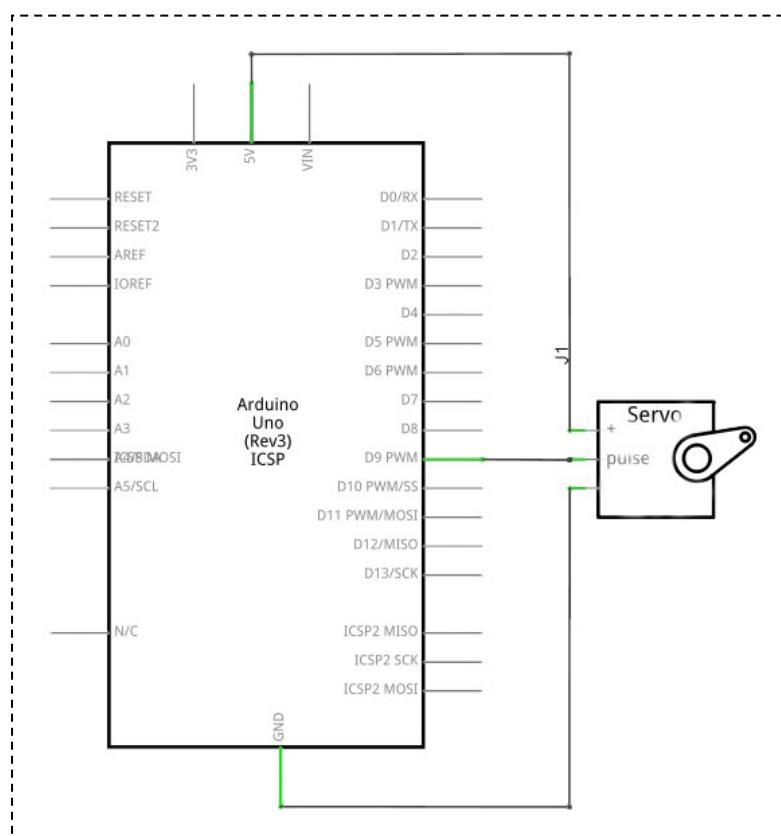
(1) x Elegoo Uno R3

(1) x Servo

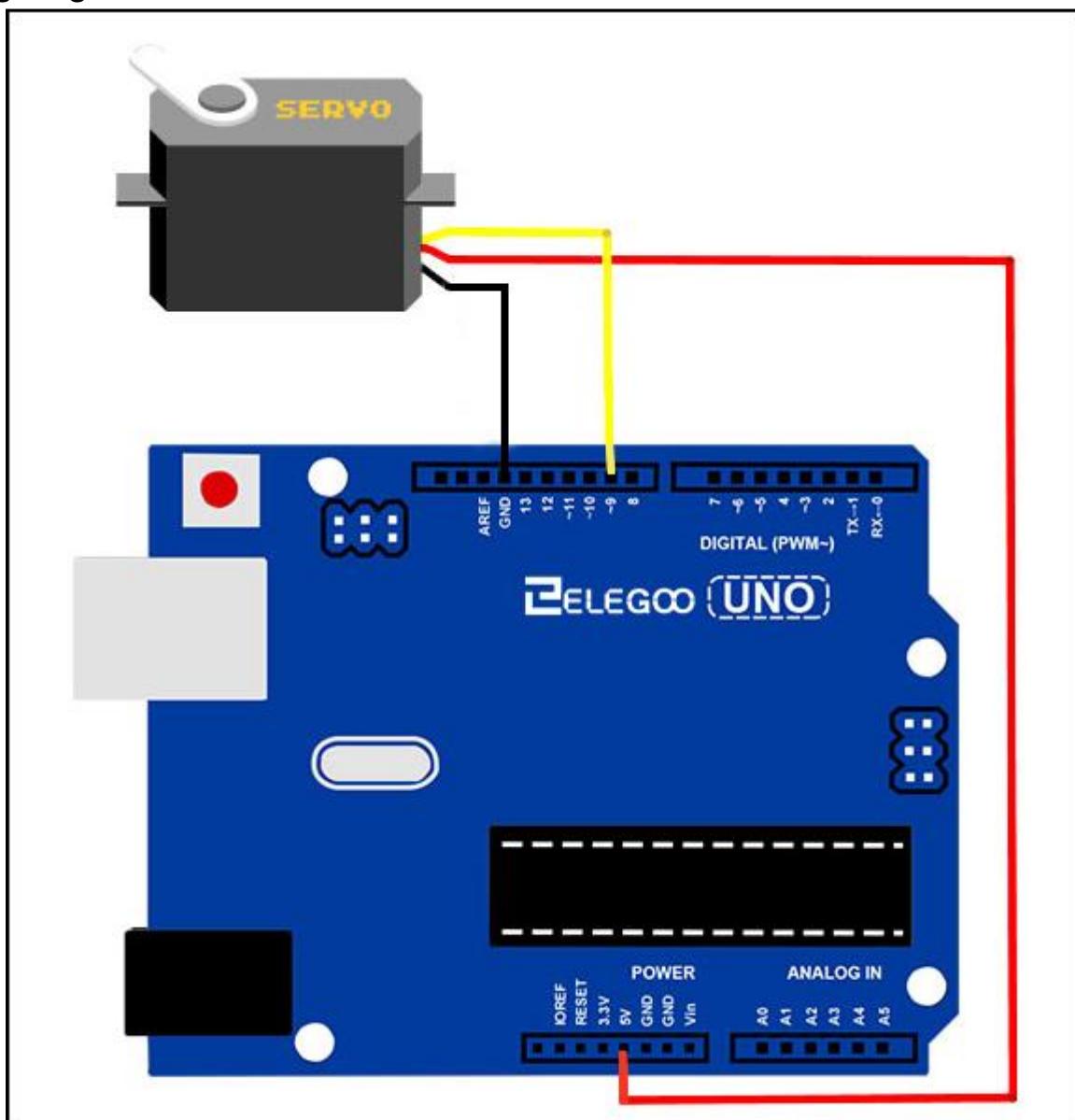
(2) x F-M wires

## Connection

### Schematic

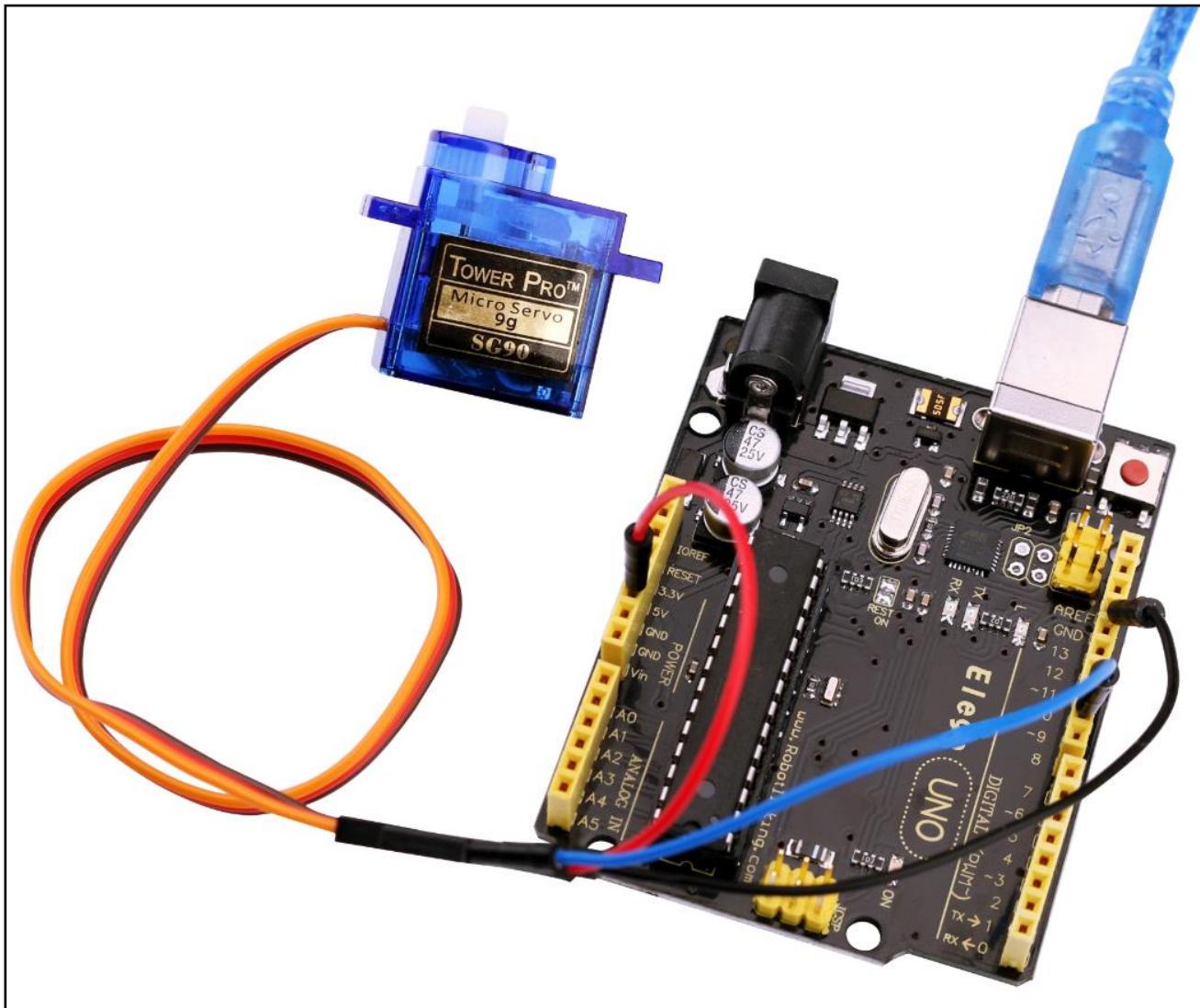


## wiring diagram



## Code

See the code file.



# Lesson 16 LCD Display

## Overview

In this lesson, you will learn how to wire up and use an alphanumeric LCD display.

The display has an LED backlight and can display two rows with up to 16 characters on each row. You can see the rectangles for each character on the display and the pixels that make up each character. The display is just white on blue and is intended for showing text.

In this lesson, we will run the Arduino example program for the LCD library, but in the next lesson, we will get our display to show the temperature and light level, using sensors.

## Component Required:

(1) x Elegoo Uno R3

(1) x LCD1602 display

(1) x Potentiometer

(1) x Breadboard

(16) x F-M wires

## Component Introduction

### LCD1602

Introduction to the pins of LCD1602:

**V<sub>SS</sub>:** A pin that connects to ground

**V<sub>DD</sub>:** A pin that connects to a +5V power supply

**VO:** A pin that adjust the contrast of LCD1602

**RS:** A register select pin that controls where in the LCD's memory you are writing data to. You can select either the data register, which holds what goes on the screen, or an instruction register, which is where the LCD's controller looks for instructions on what to do next.

**R/W:** A Read/Write pin that selects reading mode or writing mode

**E:** An enabling pin that, when supplied with low-level energy, causes the LDC module to execute

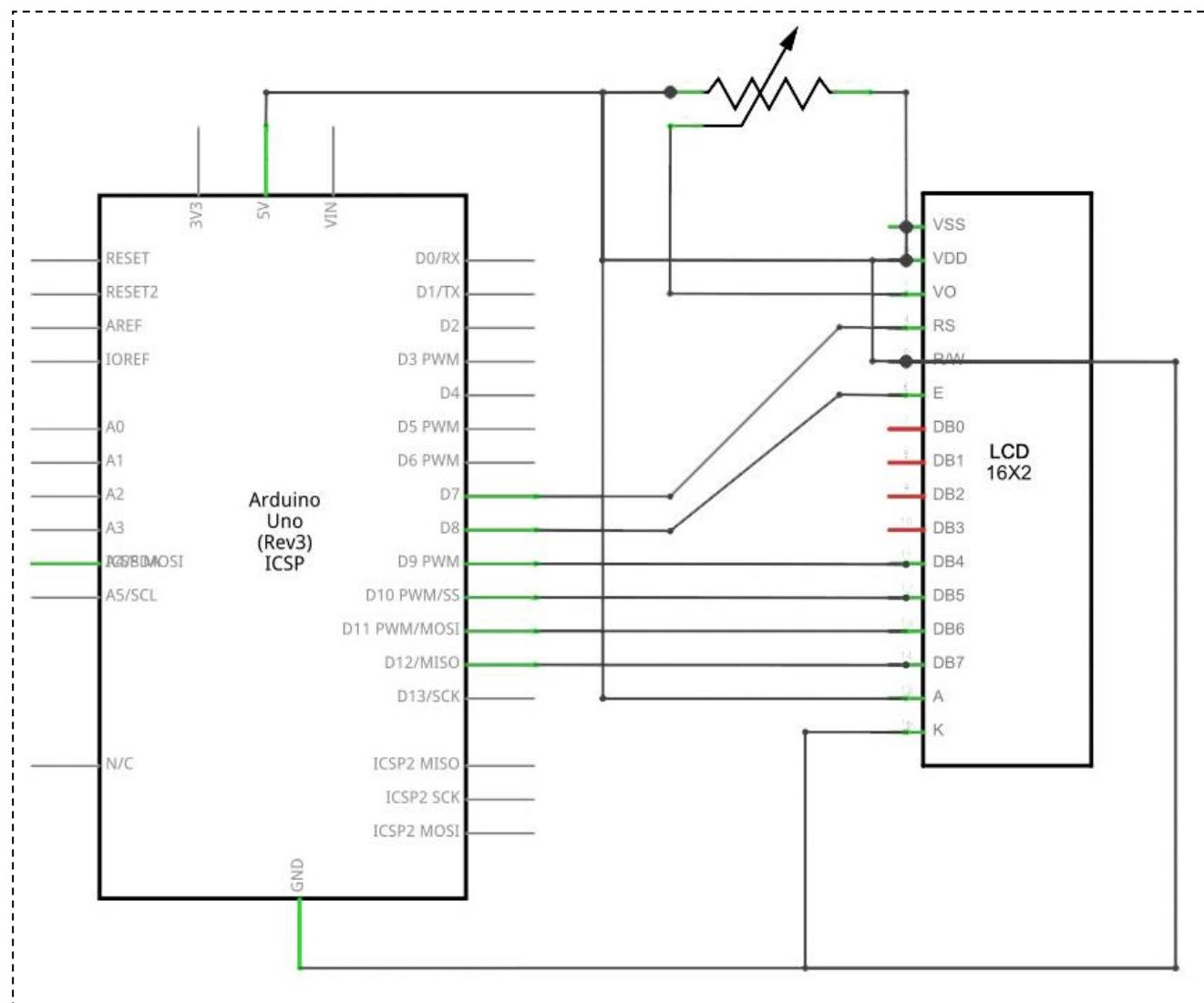
relevant instructions.

**D0-D7:** Pins that read and write data

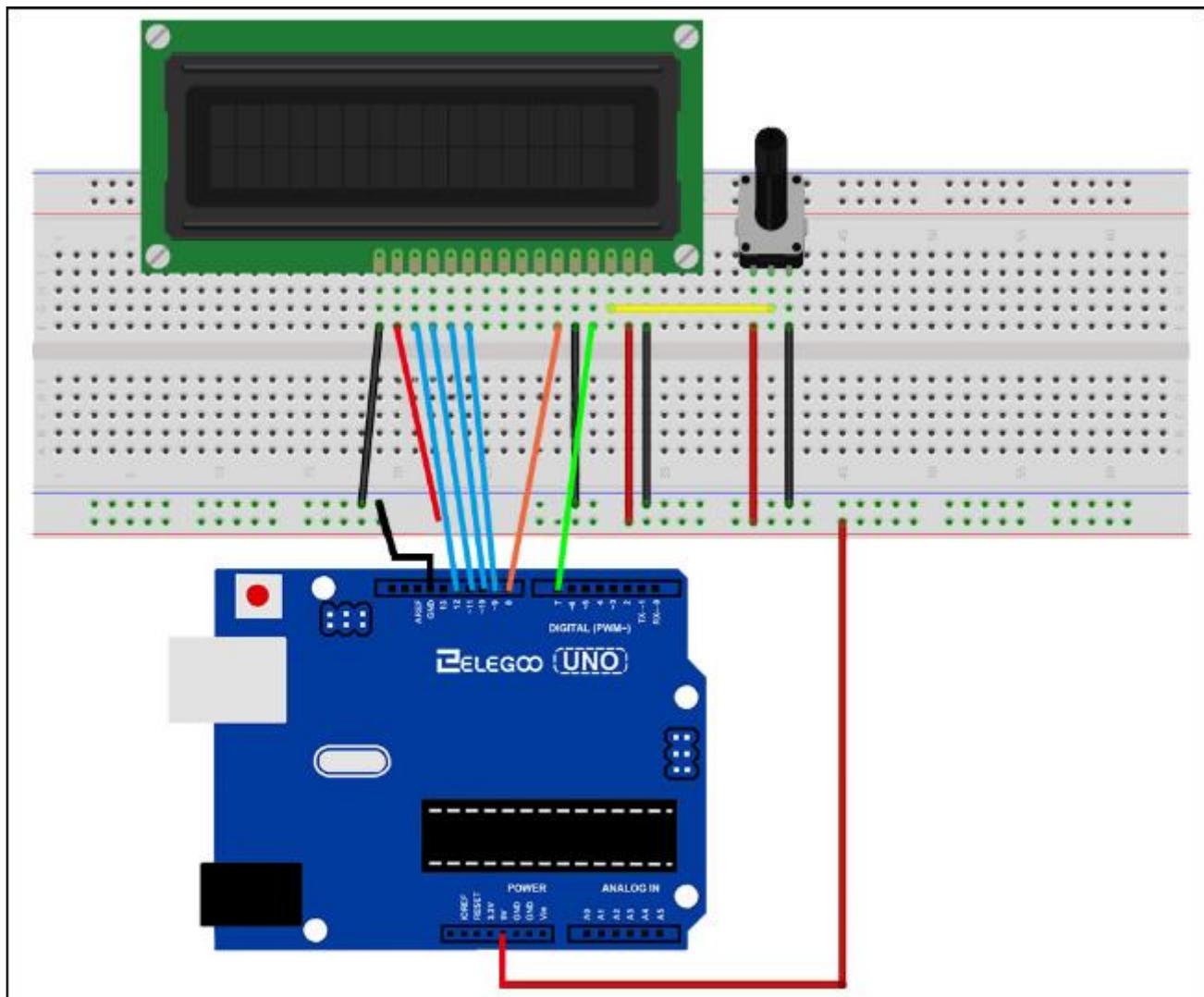
**A and K:** Pins that control the LED backlight

## Connection

### Schematic



wiring diagram



The LCD display needs six Arduino pins, all set to be digital outputs. It also needs 5V and GND connections.

There are a number of connections to be made. Lining up the display with the top of the breadboard helps to identify its pins without too much counting, especially if the breadboard has its rows numbered with row 1 as the top row of the board. Do not forget, the long yellow lead that links the slider of the pot to pin 3 of the display. The 'pot' is used to control the contrast of the display.

You may find that your display is supplied without header pins attached to it. If so, follow the instructions in the next section.

## Code

Now that we have the physical setup, all we need now is the code.

Before you can run this, you have to make sure that you have install the <LiquidCrystal> library. Or you need to install again. If you do not do this, your code won't work.

This example uses different pins to the ones we use, so find the line of code below:

```
LiquidCrystal lcd(12, 11, 5, 4, 3, 2);
```

and change it to be:

```
LiquidCrystal lcd(7, 8, 9, 10, 11, 12);
```

Upload the code to your Arduino board and you should see the message 'hello, world' displayed, followed by a number that counts up from zero.

The first thing of note in the sketch is the line:

```
#include <LiquidCrystal.h>
```

This tells Arduino that we wish to use the Liquid Crystal library.

Next we have the line that we had to modify. This defines which pins of the Arduino are to be connected to which pins of the display.

```
LiquidCrystal lcd(7, 8, 9, 10, 11, 12);
```

The arguments to this are as follows:

Display Pin Name	Display Pin Number	Arduino Pin (in this example)
RS	4	7
E	6	8
D4	11	9
D5	12	
D6	13	
D7	11	
D8	14	
D9	12	

After uploading this code, make sure the backlight is lit up, and adjust the potentiometer all the way around until you see the text message

In the 'setup' function, we have two commands:

```
lcd.begin(16, 2);
```

```
lcd.print("hello, world!");
```

The first tells the Liquid Crystal library how many columns and rows the display has. The second line displays the message that we see on the first line of the screen.

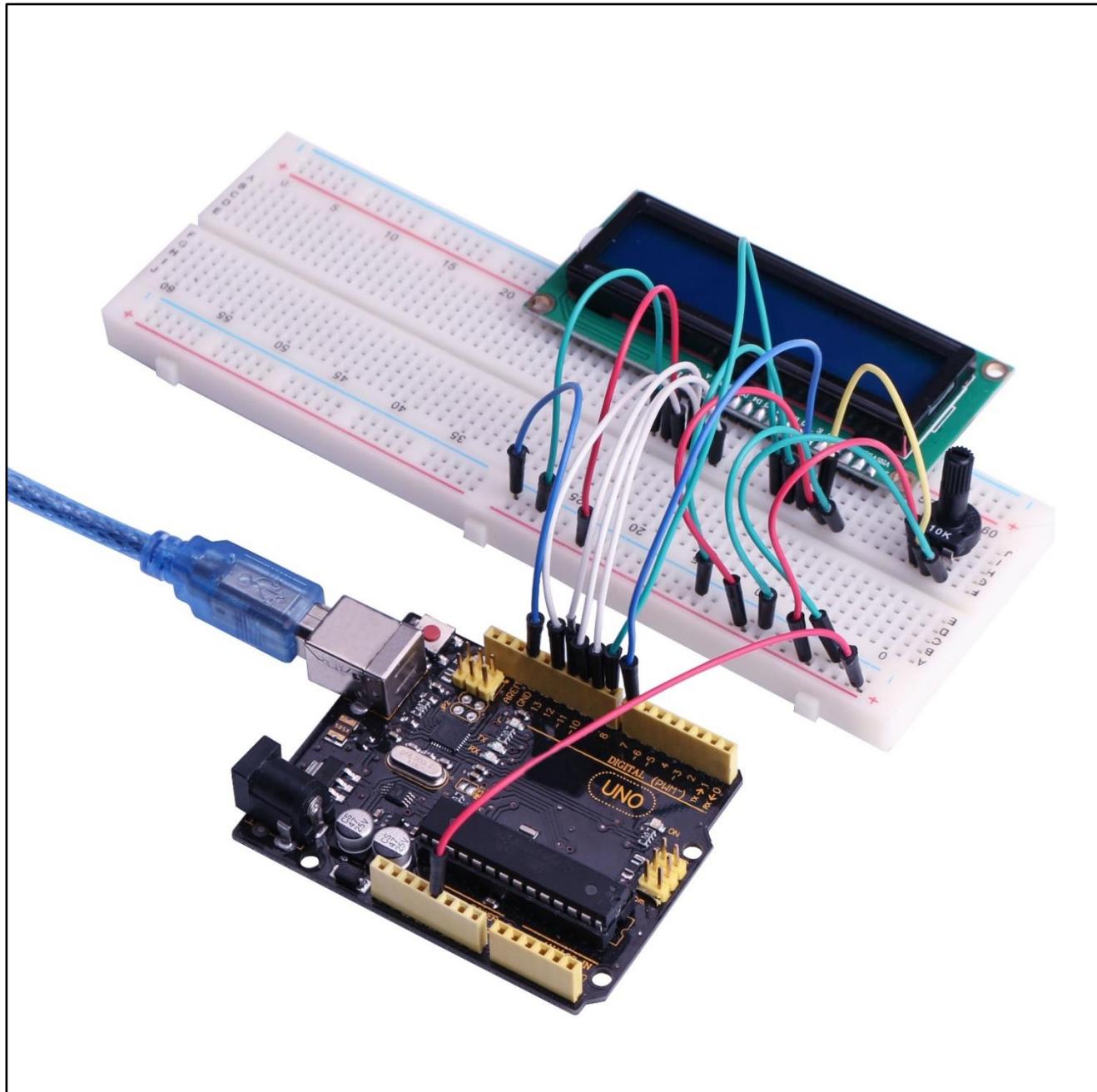
In the 'loop' function, we also have two commands:

```
lcd.setCursor(0, 1);
```

```
lcd.print(millis()/1000);
```

The first sets the cursor position (where the next text will appear) to column 0 & row 1. Both column and row numbers start at 0 rather than 1.

The second line displays the number of milliseconds since the Arduino was reset.



## Lesson 17 Thermometer

## Overview

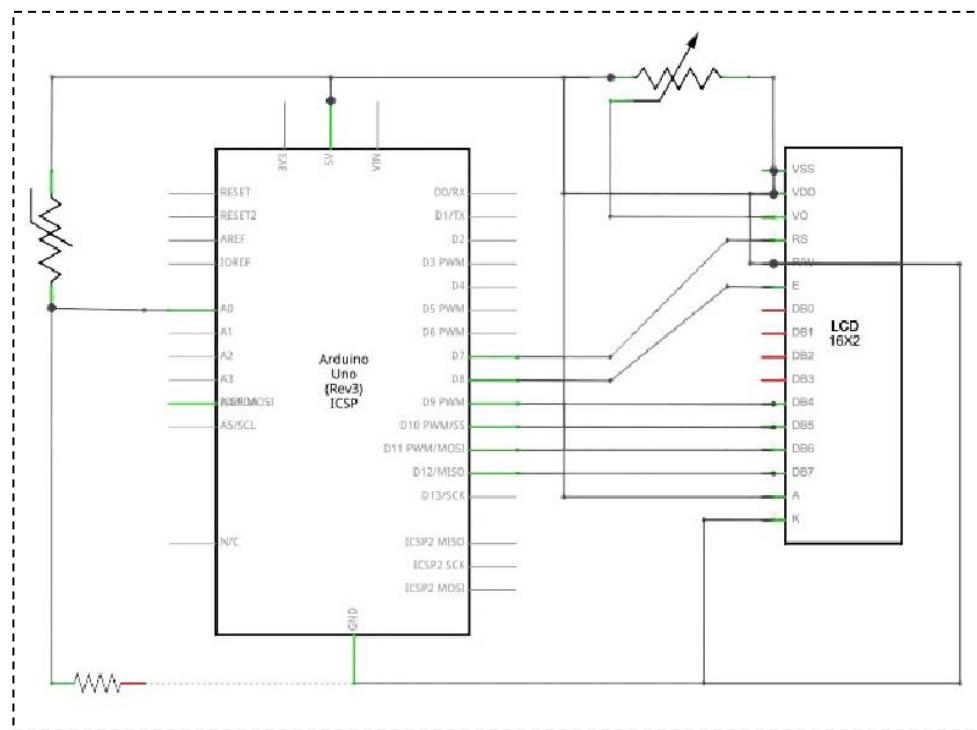
In this lesson, you will use an LCD display to show the temperature.

## **Component Required:**

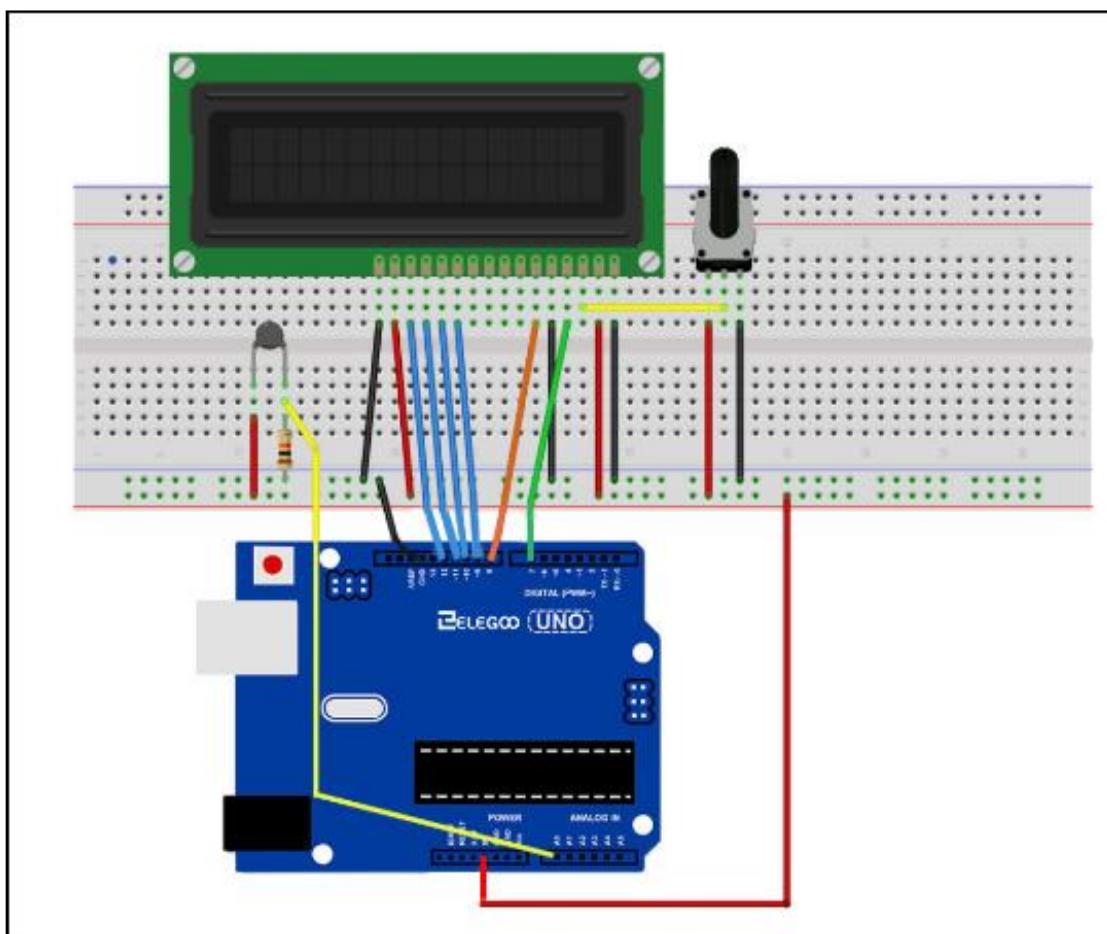
- (1) x Elegoo Uno R3
  - (1) x LCD1602 display
  - (1) x 10k ohm resistor
  - (1) x Thermistor
  - (1) x Potentiometer
  - (1) x Breadboard
  - (16) x F-M wires

# Connection

## Schematic



## Wiring diagram



The breadboard layout is based on the layout from Lesson 16, so it will simplify things if you still have this on the breadboard.

There are a few jumper wires near the pot that have been moved slightly on this layout.

The photocell, 1 kΩ resistor and thermistor are all new additions to the board.

## Code

Now that we have the physical setup, all we need now is the code.

Before you can run this, you have to make sure that you have install the `<LiquidCrystal>` library. Or you need to install again. If you do not do this, your code won't work.

The sketch for this is based on that of lesson 14. Load it up onto your Arduino and you should find that warming the temperature sensor by putting your finger on it will increase the temperature reading.

I find it useful to put a comment line above the 'lcd' command.

```
//           BS  E  D4 D5  D6 D7
```

```
LiquidCrystal lcd(7, 8, 9, 10, 11, 12);
```

This makes things easier if you decide to change which pins you use.

In the 'loop' function there are now two interesting things going on. Firstly we have to convert the analog from the temperature sensor into an actual temperature, and secondly we have to work out how to display them.

First of all, let's look at calculating the temperature.

```
int tempReading = analogRead(tempPin);
float tempVolts = tempReading * 5.0 / 1024.0;
float tempC = (tempVolts - 0.5) * 100.0;
float tempF = tempC * 9.0 / 5.0 + 32.0;
```

The raw reading from the temperature sensor is first multiplied by 5 and then divided by 1024 to give us the voltage (between 0 and 5) at the 'tempPin' analog input.

To convert the voltage coming from the TMP36 into a temperature in degrees C, you have to subtract 0.5V from the measurement and then multiply by 100.

To convert this into a temperature in Fahrenheit, you then have to multiply it by 9/5 and then add 32.

Displaying changing readings on an LCD display can be tricky. The main problem is that the reading may not always be the same number of digits. So, if the temperature changed from 101.50 to 99.00 then the extra digit from the old reading is in danger of being left on the display.

To avoid this, write the whole line of the LCD each time around the loop.

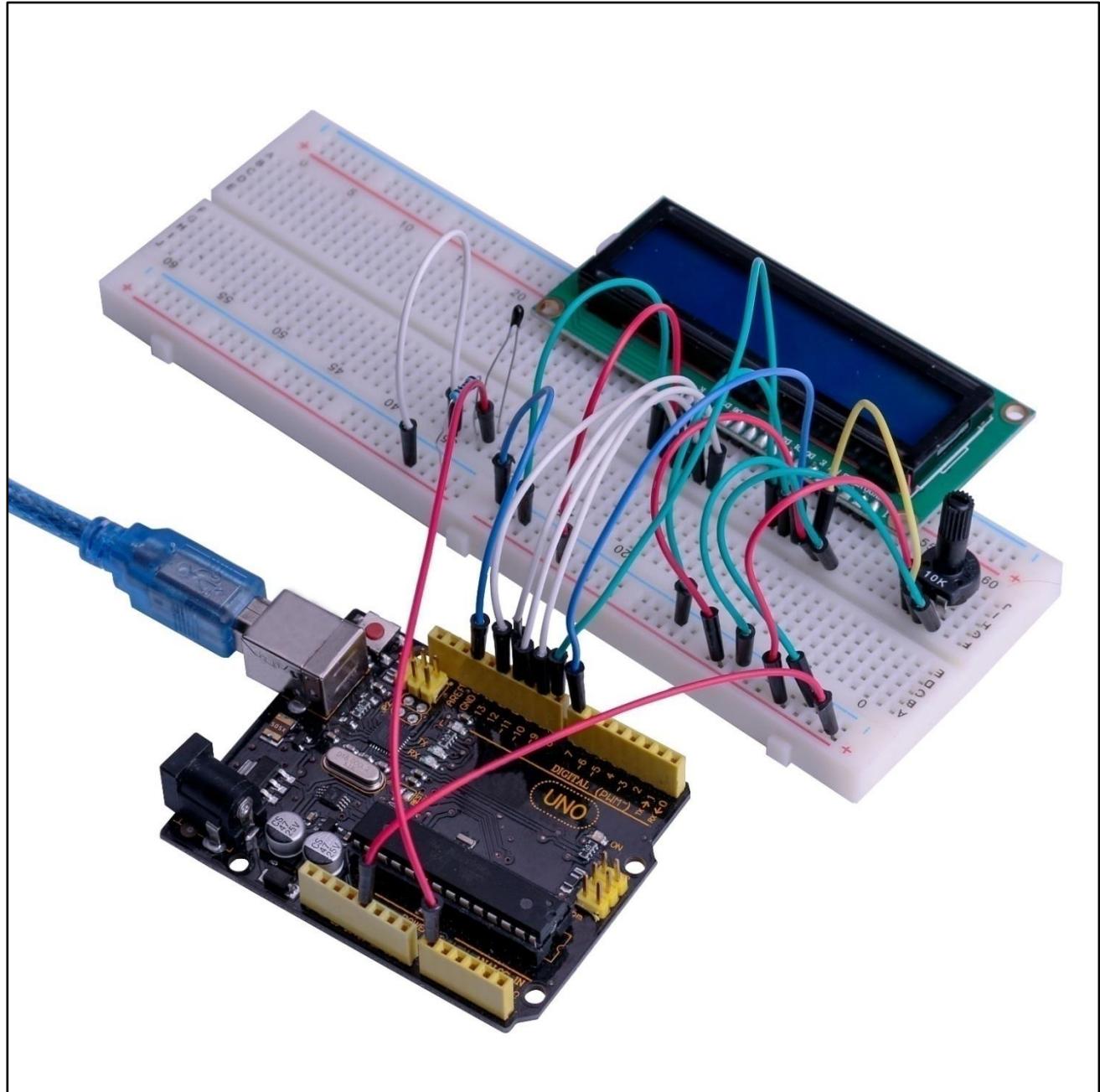
```
//           -----
lcd.print("Temp      F  ");
lcd.setCursor(6, 0);
lcd.print(tempF);
```

The rather strange comment serves to remind you of the 16 columns of the display. You can then print a string of that length with spaces where the actual reading will go.

To fill in the blanks, set the cursor position for where the reading should appear and then

print it.

Exactly the same approach is used for displaying the light level. There are no units for the light level, we just display the raw reading from the analog read.



# Lesson 18 Ultrasonic Sensor Module

## Overview

Ultrasonic sensor are great for all kind of projects that need distance measurements, avoiding obstacles as examples.

The HC-SR04 are inexpensive and easy to use since we will be using a Library specifically designed for these sensor.

## Component Required:

- (1) x Elegoo Uno R3
- (1) x Ultrasonic sensor module
- (4) x F-M wires

## Component Introduction

### Ultrasonic sensor

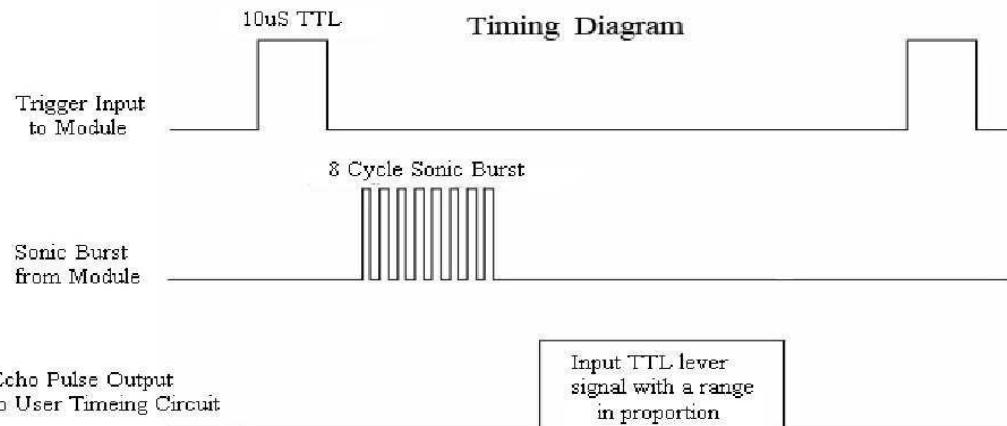
Ultrasonic ranging module HC - SR04 provides 2cm - 400cm non-contact measurement function, the ranging accuracy can reach to 3mm. The module includes ultrasonic transmitters, receiver and control circuit. The basic principle of work:

- (1) Using IO trigger for at least 10us high level signal,
- (2) The Module automatically sends eight 40 kHz and detect whether there is a pulse signal back.
- (3) If the signal back, through high level , time of high output IO duration is the time from sending ultrasonic to receiving.

Test distance = (high level time × velocity of sound (340M/S) / 2

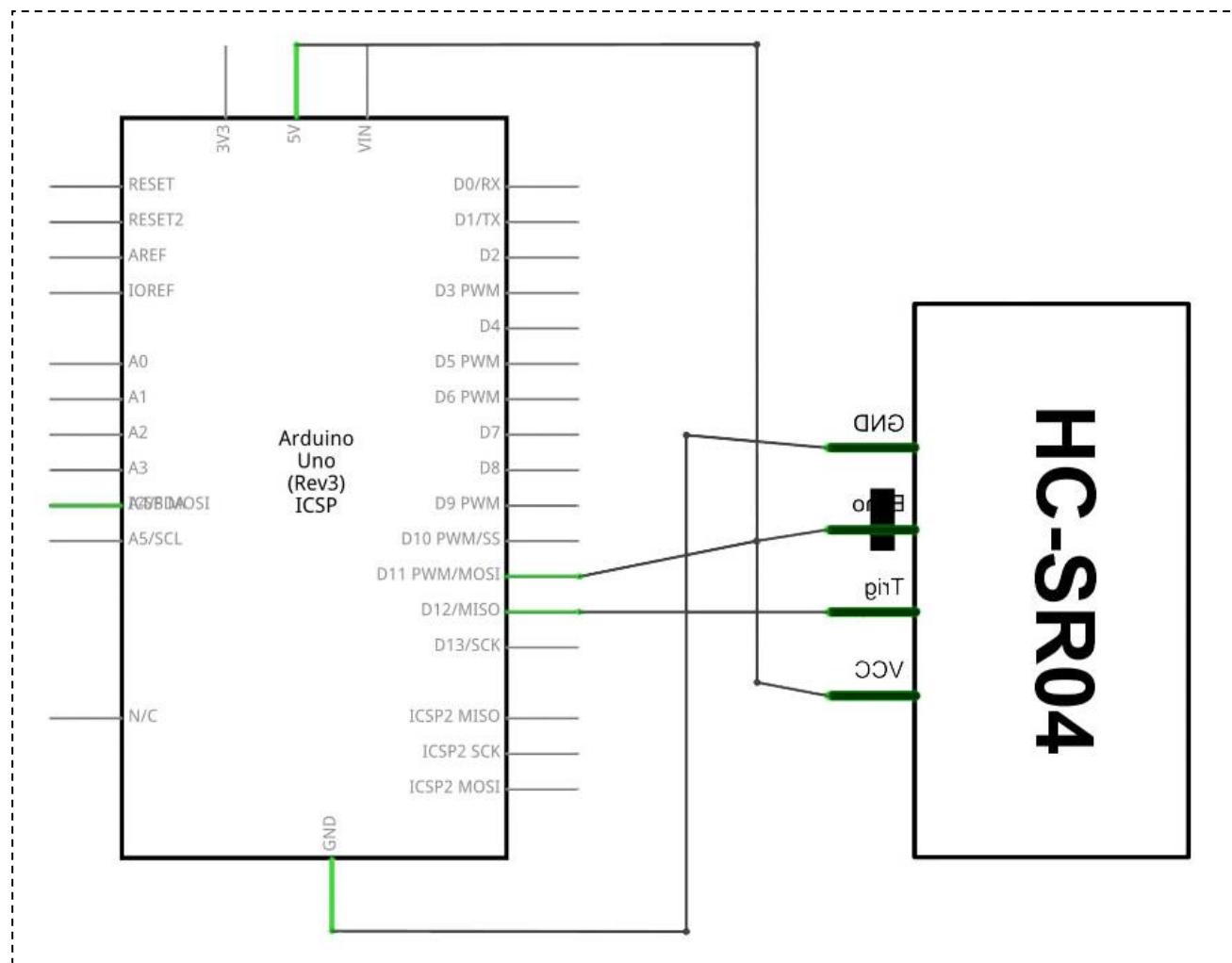
The Timing diagram is shown below. You only need to supply a short 10μs pulse to the trigger input to start the ranging, and then the module will send out an 8 cycle burst of ultrasound at 40 kHz and raise its echo. The Echo is a distance object that is pulse width and the range in proportion .You can calculate the range through the time interval between sending trigger signal and receiving echo signal. Formula:  $μS / 58 = \text{centimeters}$  or  $μS / 148 = \text{inch}$ ; or:

the range = high level time \* velocity (340M/S) / 2; we suggest to use over 60ms measurement cycle, in order to prevent trigger signal to the echo signal.

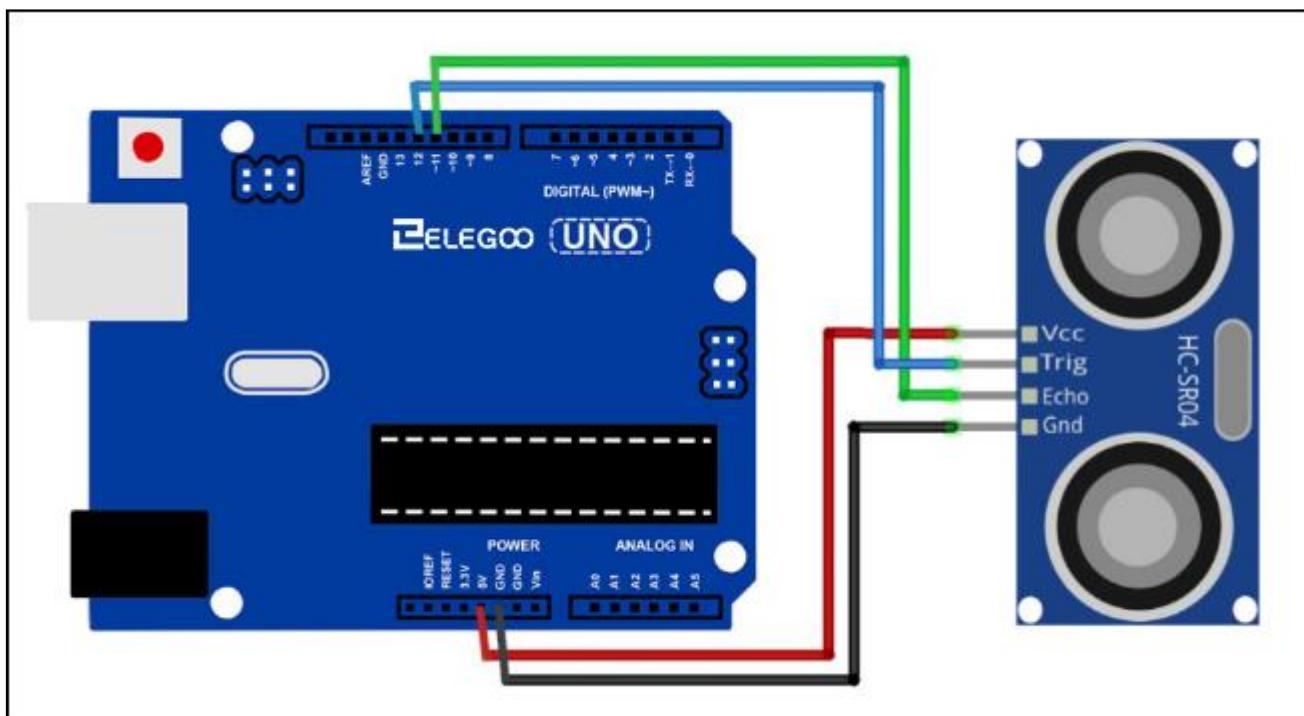


## Connection

### Schematic



## Wiring diagram



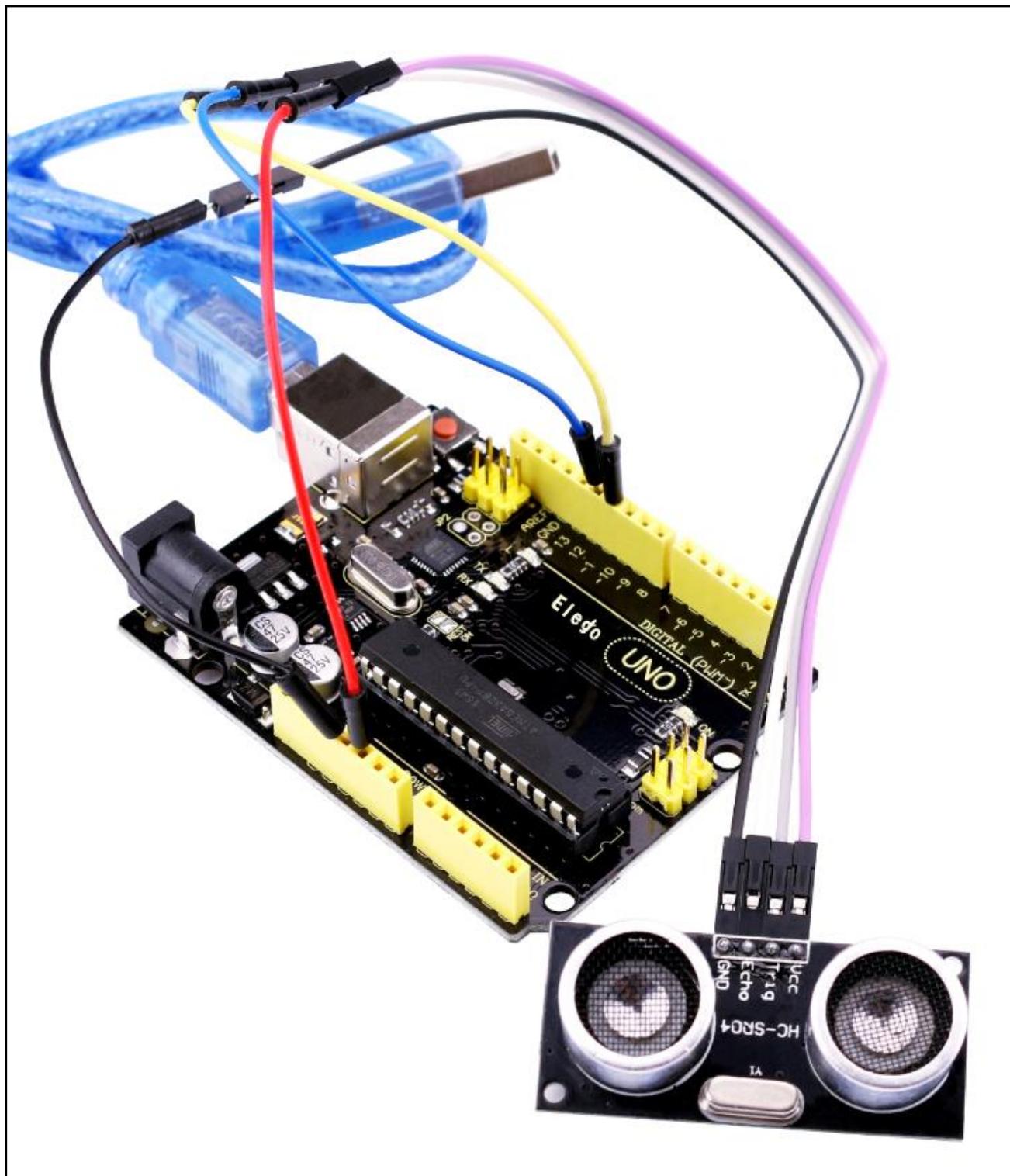
## Code

Using a Library designed for these sensors will make our code short and simple.

We include the library at the beginning of our code, and then by using simple commands we can control the behavior of the sensor.

**Now that we have the physical setup, all we need now is the code.**

**Before you can run this, you have to make sure that you have install the < HC-SR04\_Library> library. Or you need to install again. If you do not do this, your code won't work.**



# Lesson 19 Keypad Module

## Overview

In this project, we will go over how to integrate a keyboard with an UNO R3 board so that the UNO R3 can read the keys being pressed by a user.

Keypads are used in all types of devices, including cell phones, fax machines, microwaves, ovens, door locks, etc. They're practically everywhere. Tons of electronic devices use them for user input.

So knowing how to connect a keypad to a microcontroller such as an UNO R3 board is very valuable for building many different types of commercial products.

At the end when all is connected properly and programmed, when a key is pressed, it shows up at the Serial Monitor on your computer. Whenever you press a key, it shows up on the Serial Monitor. Later, in another project, we will connect the keypad circuit, so that it will get displayed on an LCD. But for now, for simplicity purposes, we start at simply showing the key pressed on the computer.

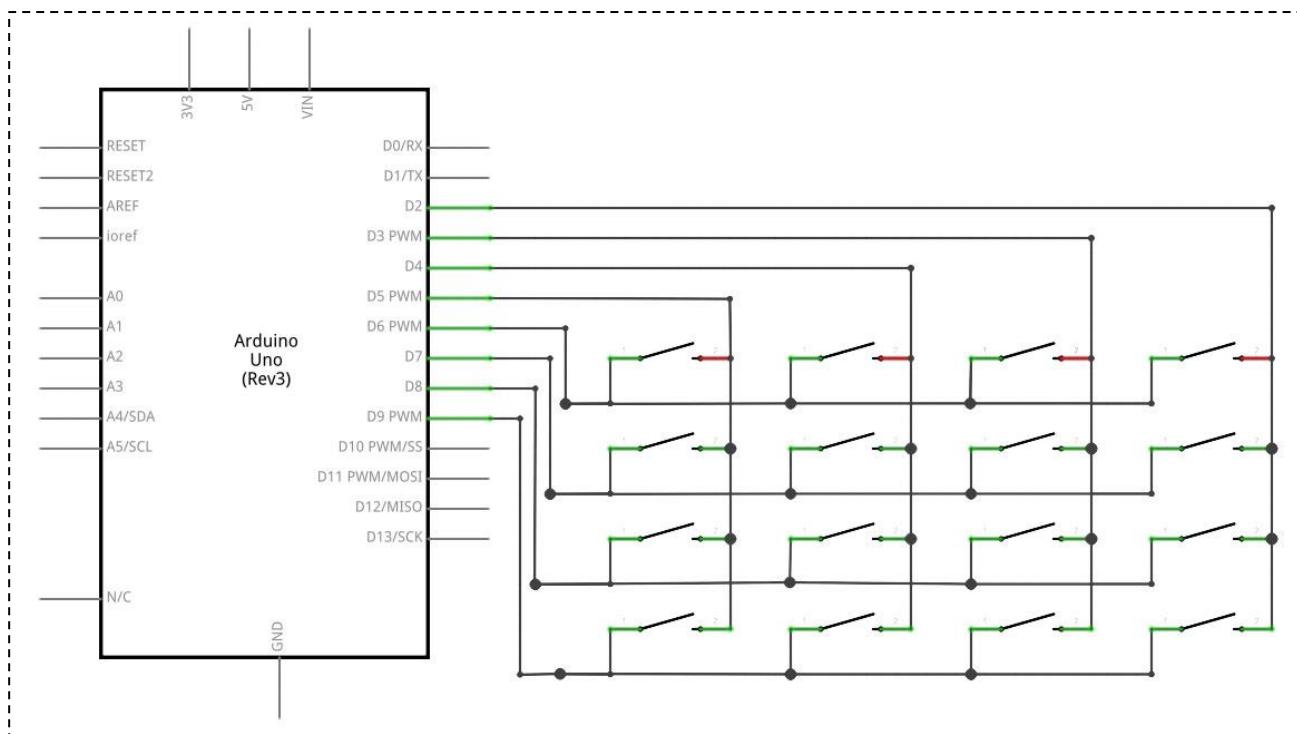
For this project, the type of keypad we will use is a matrix keypad. This is a keypad that follows an encoding scheme that allows it to have much less output pins than there are keys. For example, the matrix keypad we are using has 16 keys (0-9, A-D, \*, #), yet only 8 output pins. With a linear keypad, there would have to be 17 output pins (one for each key and a ground pin) in order to work. The matrix encoding scheme allows for less output pins and thus much less connections that have to be made for the keypad to work. In this way, they are more efficient than linear keypads, being that they have less wiring.

## Component Required:

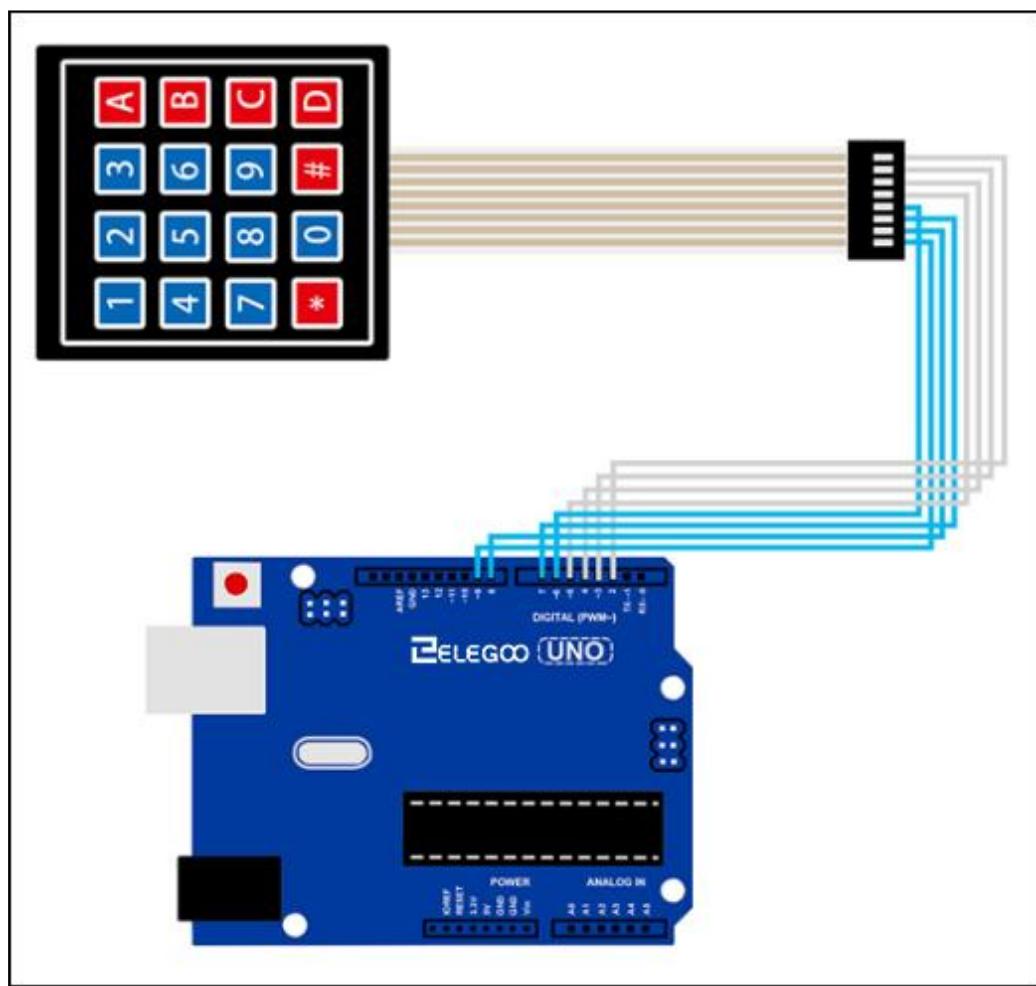
- (1) x Elegoo Uno R3
- (1) x Membrane switch module
- (8) x M-M wires

## Connection

## Schematic



## Wiring diagram



When connecting the pins to the UNO R3 board, we connect them to the digital output pins, D9-D2. We connect the first pin of the keypad to D9, the second pin to D8, the third pin to D7, the fourth pin to D6, the fifth pin to D5, the sixth pin to D4, the seventh pin to D3, and the eighth pin to D2.

These are the connections in a table:

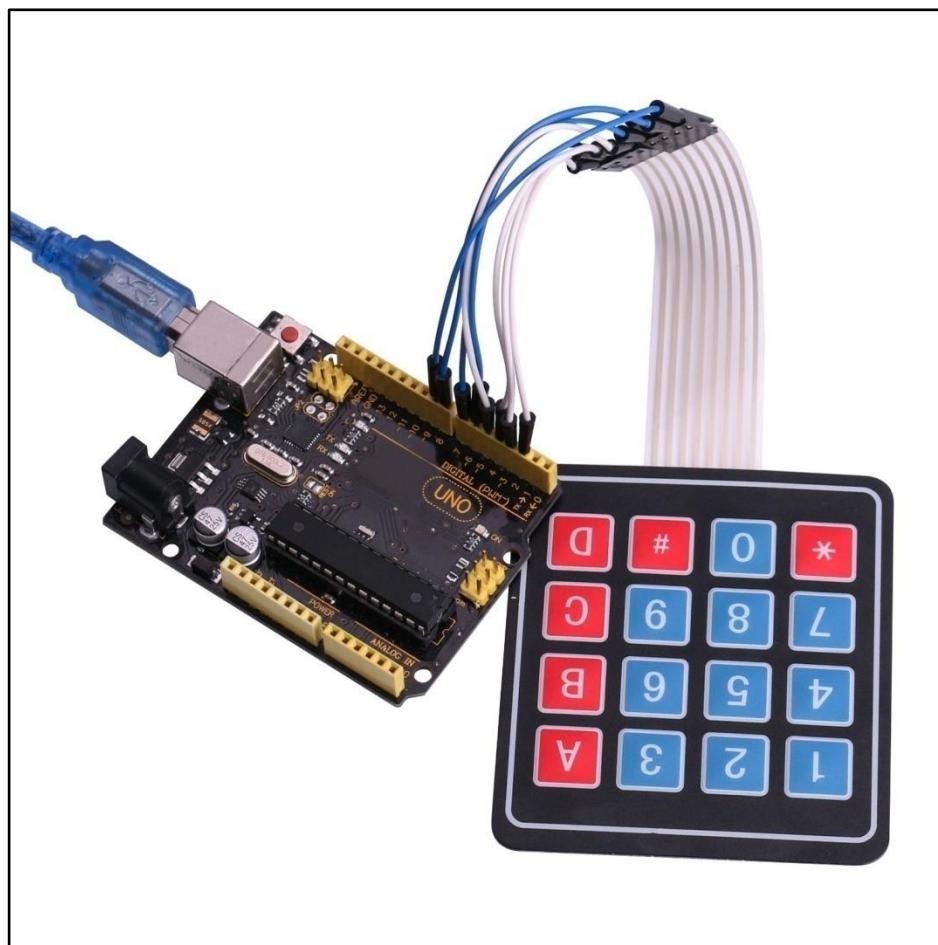
Keypad Pin	Connects to Arduino Pin...
1	D9
2	D8
3	D7
4	D6
5	D5
6	D4
7	D3
8	D2

## Code

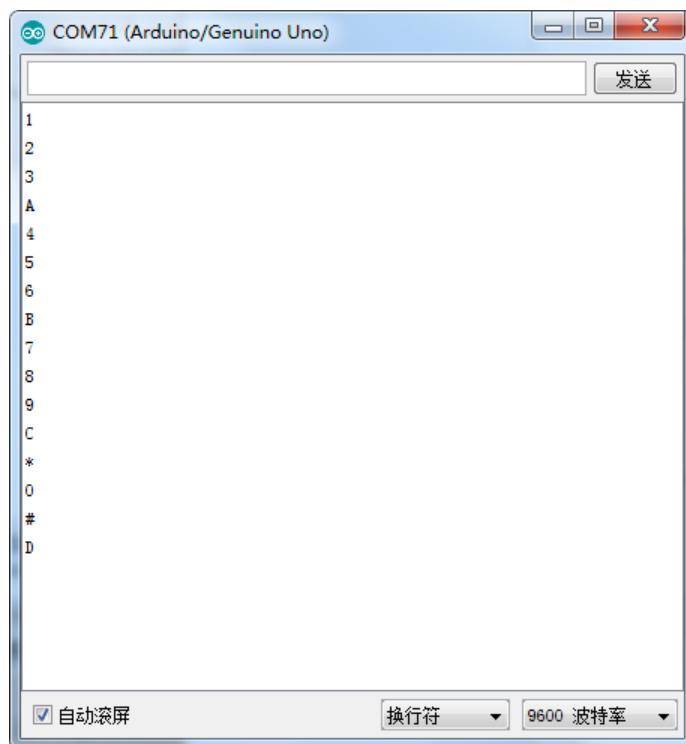
Now that we have the physical setup, all we need now is the code.

Before you can run this, you have to make sure that you have install the <Keypad> library.

Or you need to install again. If you do not do this, your code won't work.



With this code, once we press a key on the keypad, it should show up on the serial monitor of the Arduino software once the code is compiled and uploaded to the UNO R3 board.



# Lesson 20 DHT11 Temperature and Humidity Sensor

## Overview

In this tutorial we will learn how to use a DHT11 Temperature and Humidity Sensor.

It's accurate enough for most projects that need to keep track of humidity and temperature readings.

Again we will be using a Library specifically designed for these sensors that will make our code short and easy to write.

## Component Required:

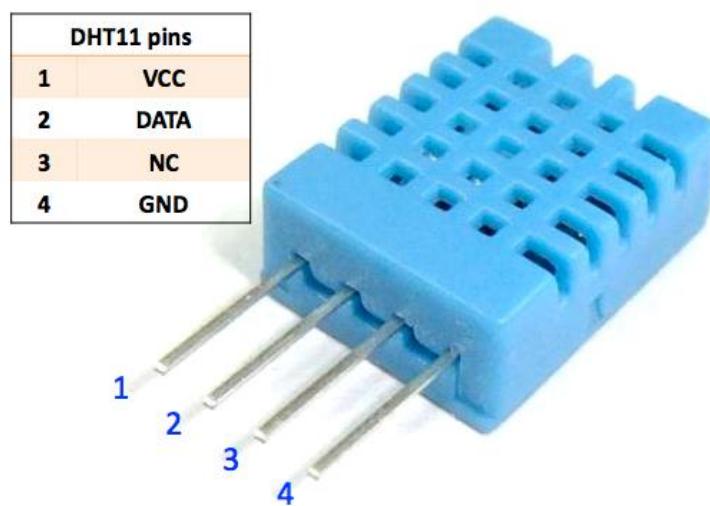
(1) x Elegoo Uno R3

(1) x DHT11 module

(3) x F-M wires

## Component Introduction

### Temp and humidity sensor:



DHT11 digital temperature and humidity sensor is a composite Sensor contains a calibrated digital signal output of the temperature and humidity. Application of a dedicated digital modules collection technology and the temperature and humidity sensing technology, to ensure that the product has high reliability and excellent long-term stability. The sensor

includes a resistive sense of wet components and an NTC temperature measurement devices, and connected with a high-performance 8-bit microcontroller.

Applications: HVAC, dehumidifier, testing and inspection equipment, consumer goods, automotive, automatic control, data loggers, weather stations, home appliances, humidity regulator, medical and other humidity measurement and control.

### **Product parameters**

Relative humidity:

Resolution: 16Bit

Repeatability:  $\pm 1\%$  RH

Accuracy: At 25°C  $\pm 5\%$  RH

Interchangeability: fully interchangeable

Response time: 1 / e (63%) of 25°C 6s

1m / s air 6s

Hysteresis:  $<\pm 0.3\%$  RH

Long-term stability:  $<\pm 0.5\%$  RH / yr in

Temperature:

Resolution: 16Bit

Repeatability:  $\pm 0.2^\circ\text{C}$

Range: At 25°C  $\pm 2^\circ\text{C}$

Response time: 1 / e (63%) 10s

Electrical Characteristics

Power supply: DC 3.5~5.5V

Supply Current: measurement 0.3mA standby 60 $\mu$ A

Sampling period: more than 2 seconds

Pin Description:

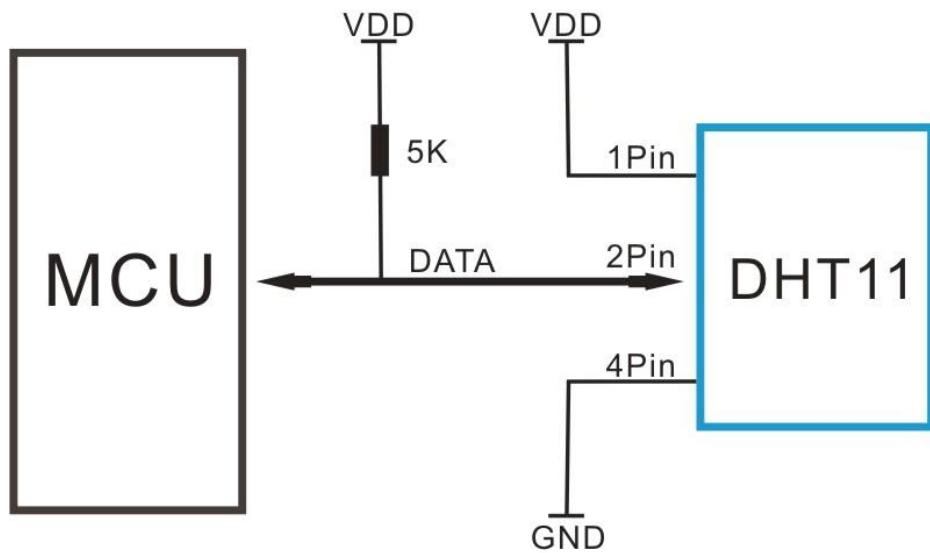
1, the VDD power supply 3.5~5.5V DC

2 DATA serial data, a single bus

3, NC, empty pin

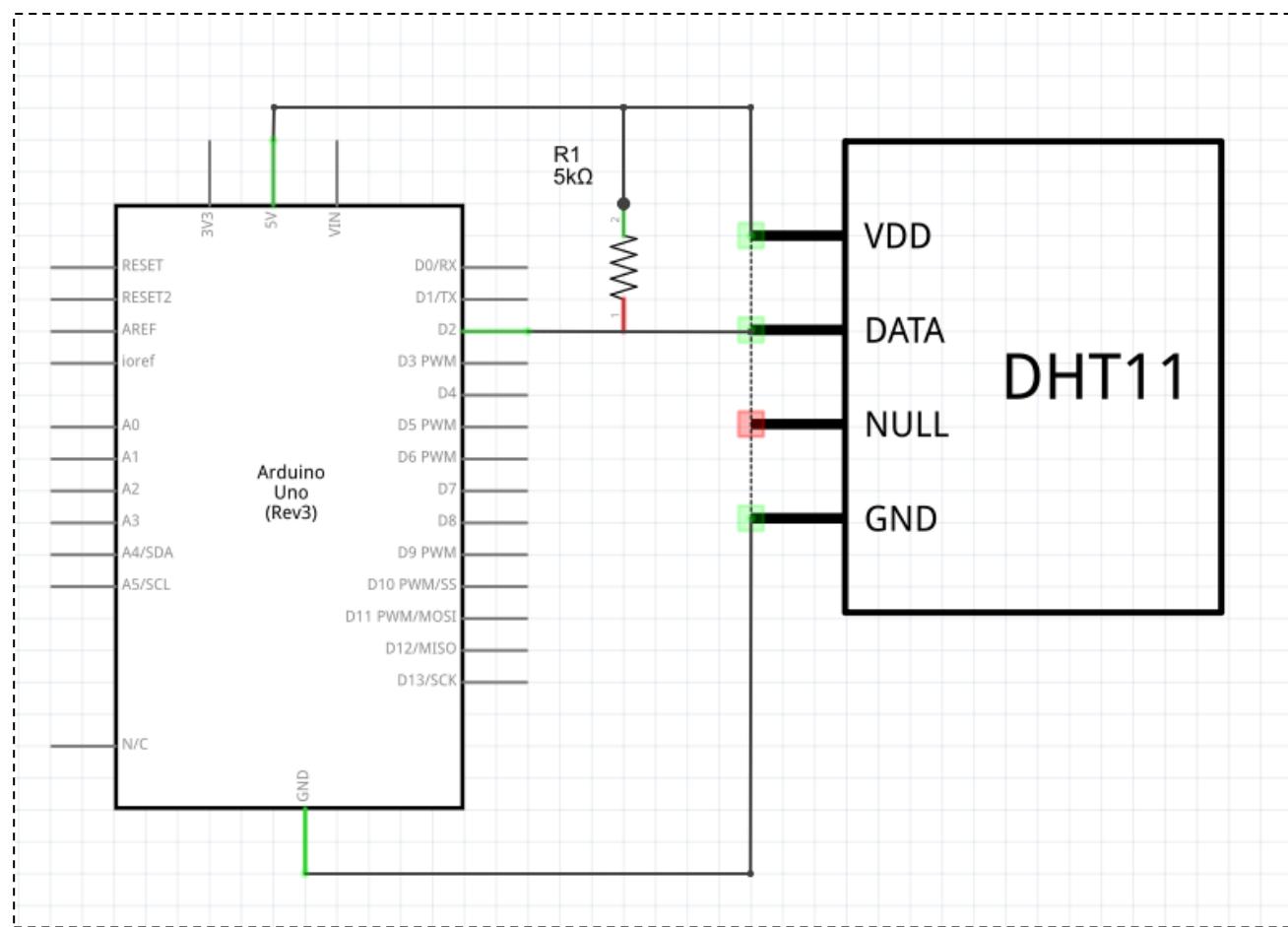
4, GND ground, the negative power

## Typical Application

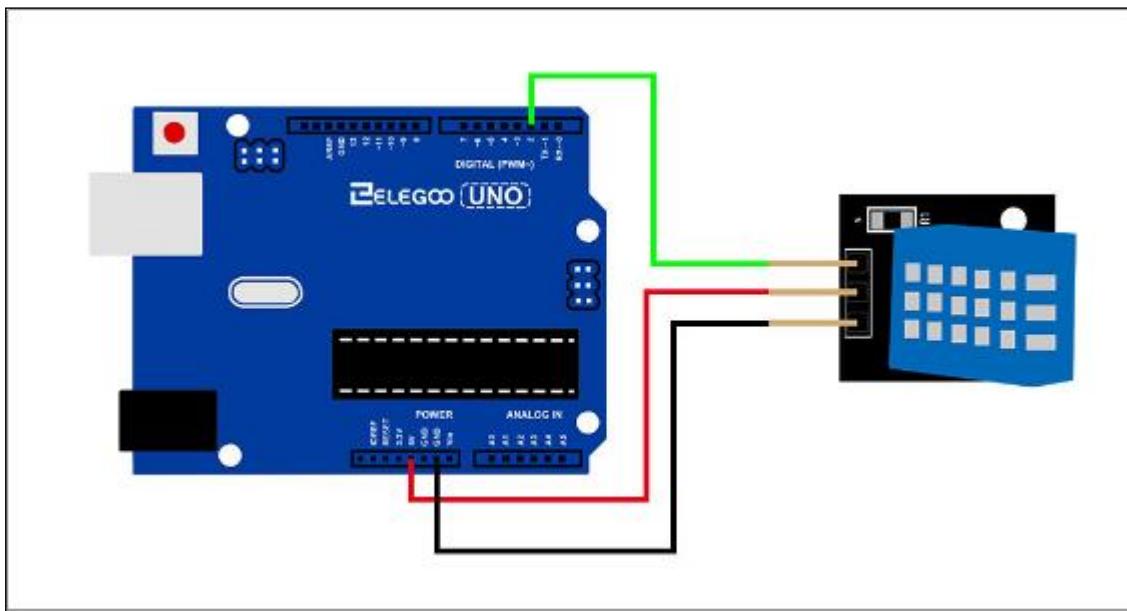


## Connection

### Schematic



### Wiring diagram



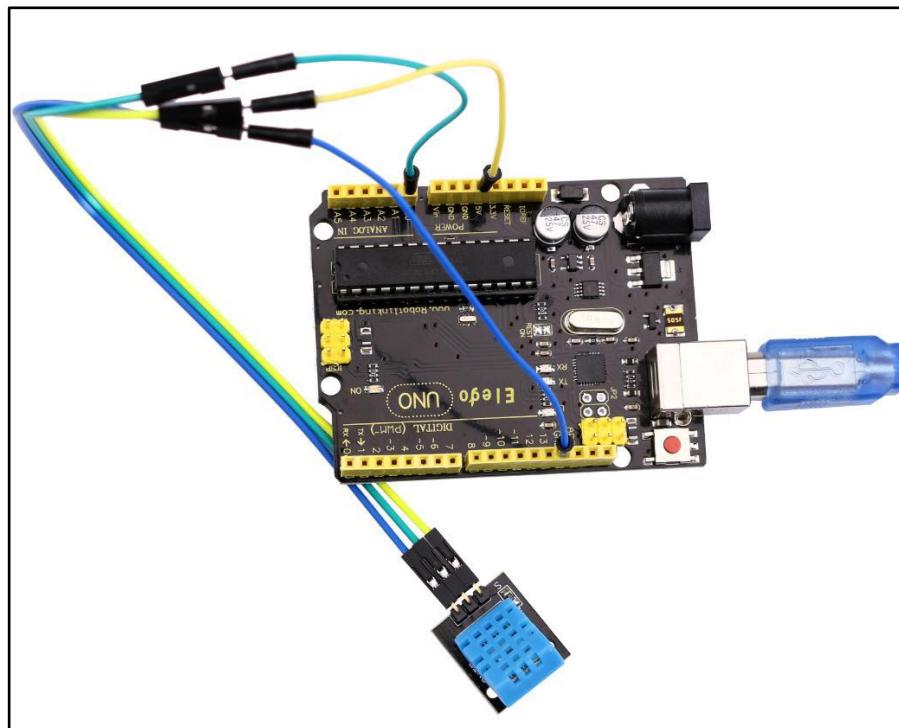
As you can see we only need 3 connections to the sensor, since one of the pin is not used.

The connection are: Voltage, Ground and Signal which can be connected to any Analog Pin on our UNO.

## Code

Now that we have the physical setup, all we need now is the code.

Before you can run this, you have to make sure that you have install the <simpleDHT> library. Or you need to install again. If you do not do this, your code won't work.



Upload the program then open the monitor, we can see the data as below:(It shows the temperature of the environment, we can see it is 21 degree)

```
COM16 (Arduino/Genuine Uno)
发送
Sample OK: 21 *C, 71 %
=====
Sample DHT11...
Sample RAW Bits: 0100 0111 0000 0000 0001 0101 0000 0000 0101 1100
Sample OK: 21 *C, 71 %
=====
Sample DHT11...
Sample RAW Bits: 0100 0111 0000 0000 0001 0101 0000 0000 0101 1100
Sample OK: 21 *C, 71 %
=====
Sample DHT11...
Sample RAW Bits: 0100 0111 0000 0000 0001 0101 0000 0000 0101 1100
Sample OK: 21 *C, 71 %
=====
Sample DHT11...
Sample RAW Bits: 0100 0111 0000 0000 0001 0101 0000 0000 0101 1100
Sample OK: 21 *C, 71 %
=====
Sample DHT11...
Read DHT11 failed=====
Sample DHT11...
Sample RAW Bits: 0100 0111 0000 0000 0001 0101 0000 0000 0101 1100
Sample OK: 21 *C, 71 %

自动滚屏 没有结束符 9600 波特率
```

# Lesson 21 Analog Joystick Module

## Overview

Analog joysticks are a great way to add some control in your projects.

In this tutorial we will learn how to use the analog joystick module.

## Component Required:

- (1) x Elegoo Uno R3
- (1) x Joystick module
- (5) x F-M wires

## Component Introduction

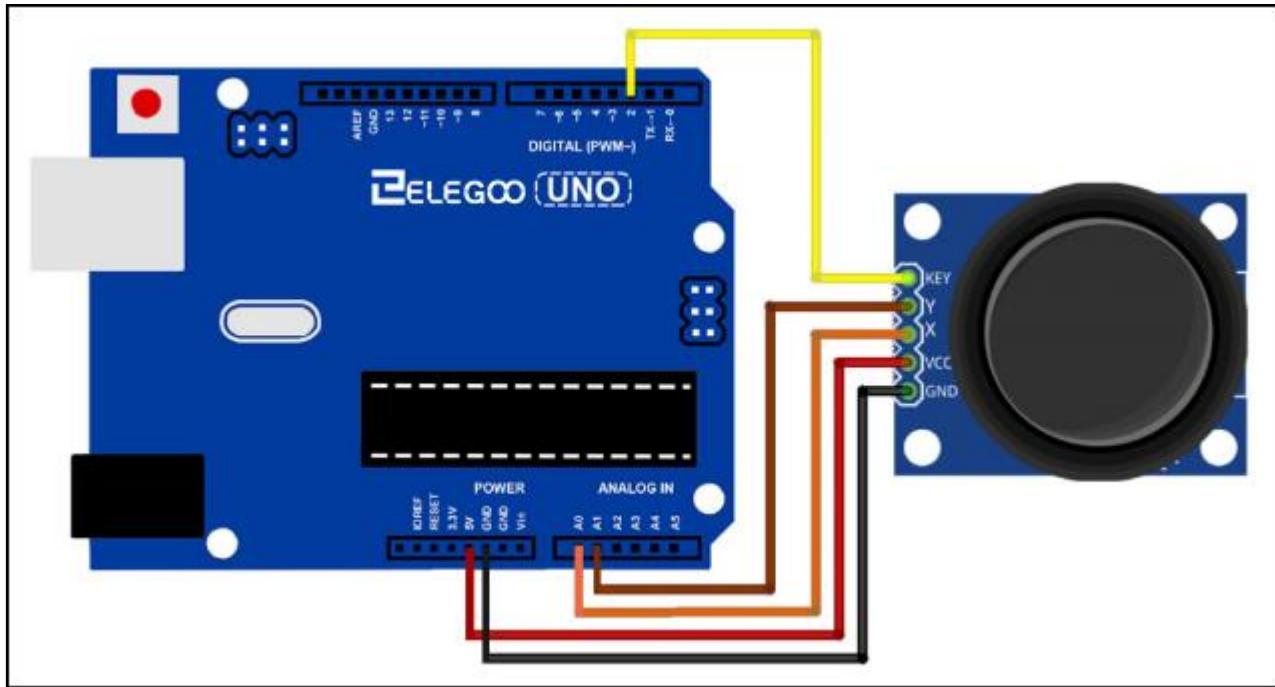
### Joystick

The module has 5 pins: Vcc, Ground, X, Y, Key. Note that the labels on yours may be slightly different, depending on where you got the module from. The thumb stick is analog and should provide more accurate readings than simple 'directional' joysticks that use some forms of buttons, or mechanical switches. Additionally, you can press the joystick down (rather hard on mine) to activate a 'press to select' push-button.

We have to use analog Arduino pins to read the data from the X/Y pins, and a digital pin to read the button. The Key pin is connected to ground, when the joystick is pressed down, and is floating otherwise. To get stable readings from the Key /Select pin, it needs to be connected to Vcc via a pull-up resistor. The built in resistors on the Arduino digital pins can be used. For a tutorial on how to activate the pull-up resistors for Arduino pins, configured as inputs

## Connection

### Wiring diagram



We need 5 connections to the joystick.

The connection are: Key, Y, X, Voltage and Ground.

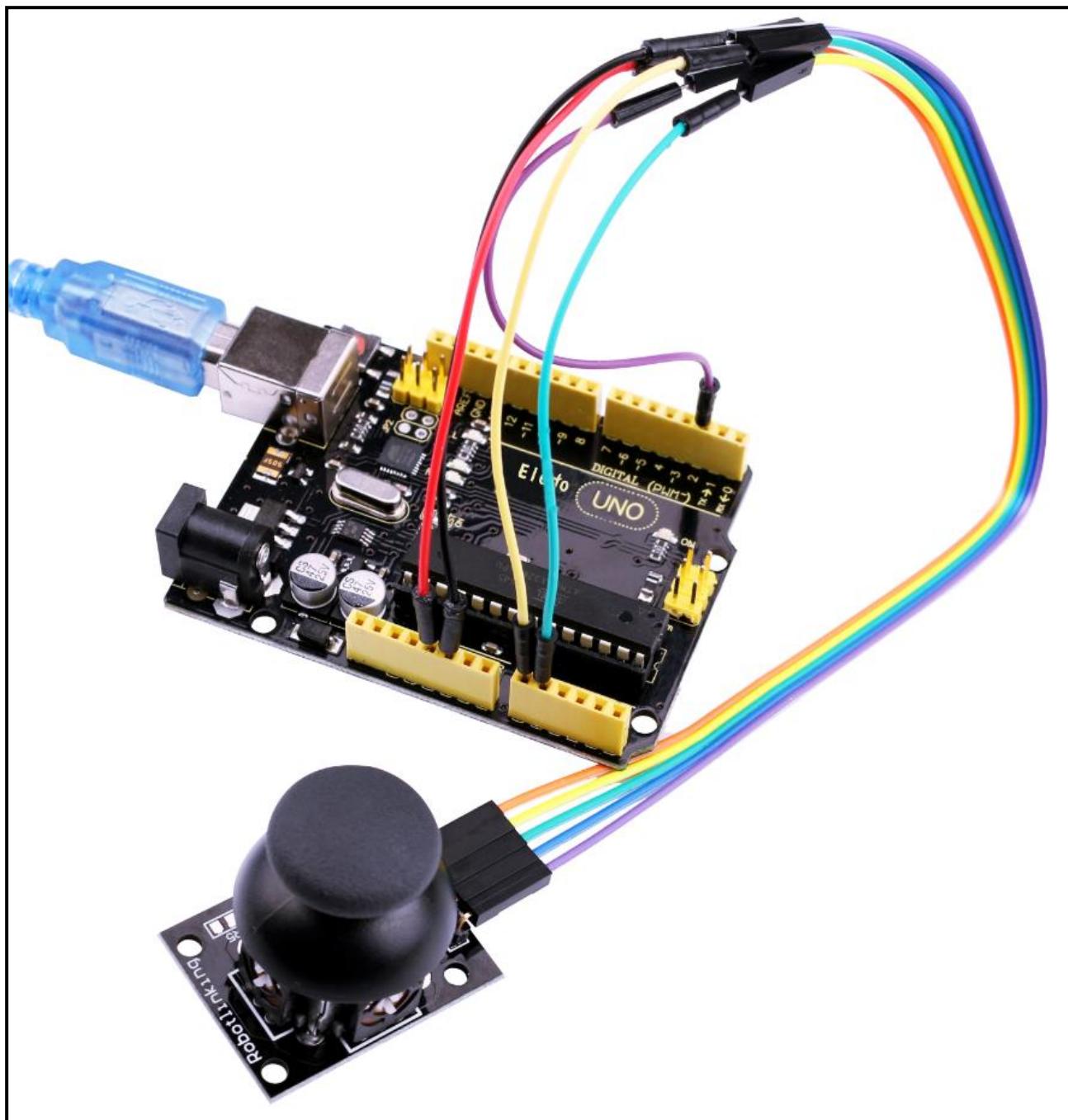
"Y and X" are Analog and "Key" is Digital. If you don't need the switch then you can use only 4 pins.

## Code

Analog joysticks are basically potentiometers so they return analog values.

When the joystick is in the resting position or middle, it should return a value of about 512.

The range of values go from 0 to 1024.



# Lesson 22 IR Receiver Module

## Overview

Using an IR Remote is a great way to have wireless control of your project.

Infrared remotes are simple and easy to use. In this tutorial we will be connecting the IR receiver to the UNO, and then use a Library that was designed for this particular sensor.

In our sketch we will have all the IR Hexadecimal codes that are available on this remote, we will also detect if the code was recognized and also if we are holding down a key.

## Component Required:

(1) x Elegoo Uno R3

(1) x IR receiver module

(1) x IR remote

(3) x F-M wires

## Component Introduction

### IR RECEIVER SENSOR:

IR detectors are little microchips with a photocell that are tuned to listen to infrared light. They are almost always used for remote control detection - every TV and DVD player has one of these in the front to listen for the IR signal from the clicker. Inside the remote control is a matching IR LED, which emits IR pulses to tell the TV to turn on, off or change channels. IR light is not visible to the human eye, which means it takes a little more work to test a setup.

There are a few differences between these and say a CdS Photocells:

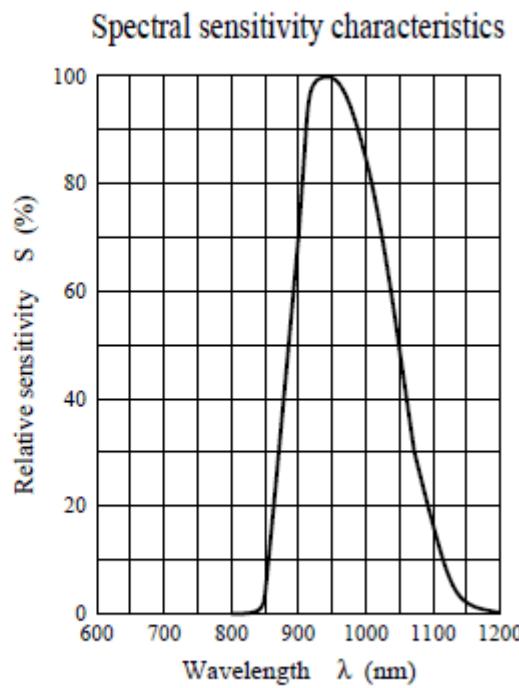
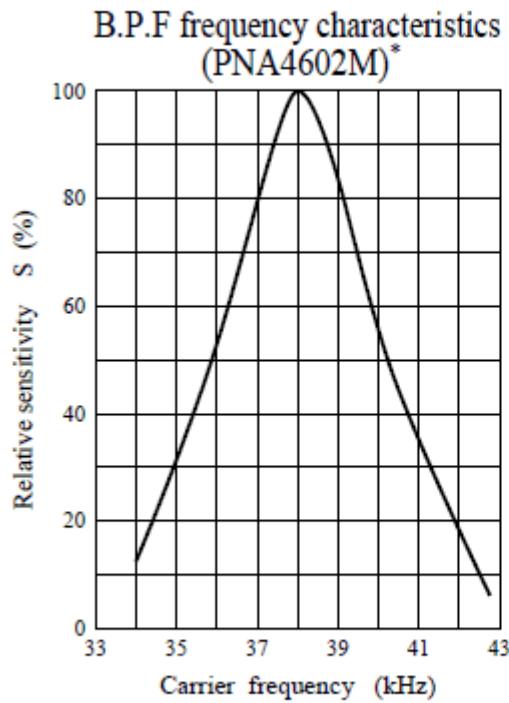
IR detectors are specially filtered for Infrared light, they are not good at detecting visible light. On the other hand, photocells are good at detecting yellow/green visible light, not good at IR light.

- IR detectors have a demodulator inside that looks for modulated IR at 38 KHz. Just shining an IR LED won't be detected, it has to be PWM blinking at 38KHz. Photocells do not have any sort of demodulator and can detect any frequency (including DC) within

the response speed of the photocell (which is about 1KHz)

- IR detectors are digital out - either they detect 38KHz IR signal and output low (0V) or they do not detect any and output high (5V). Photocells act like resistors, the resistance changes depending on how much light they are exposed to.

## What You Can Measure



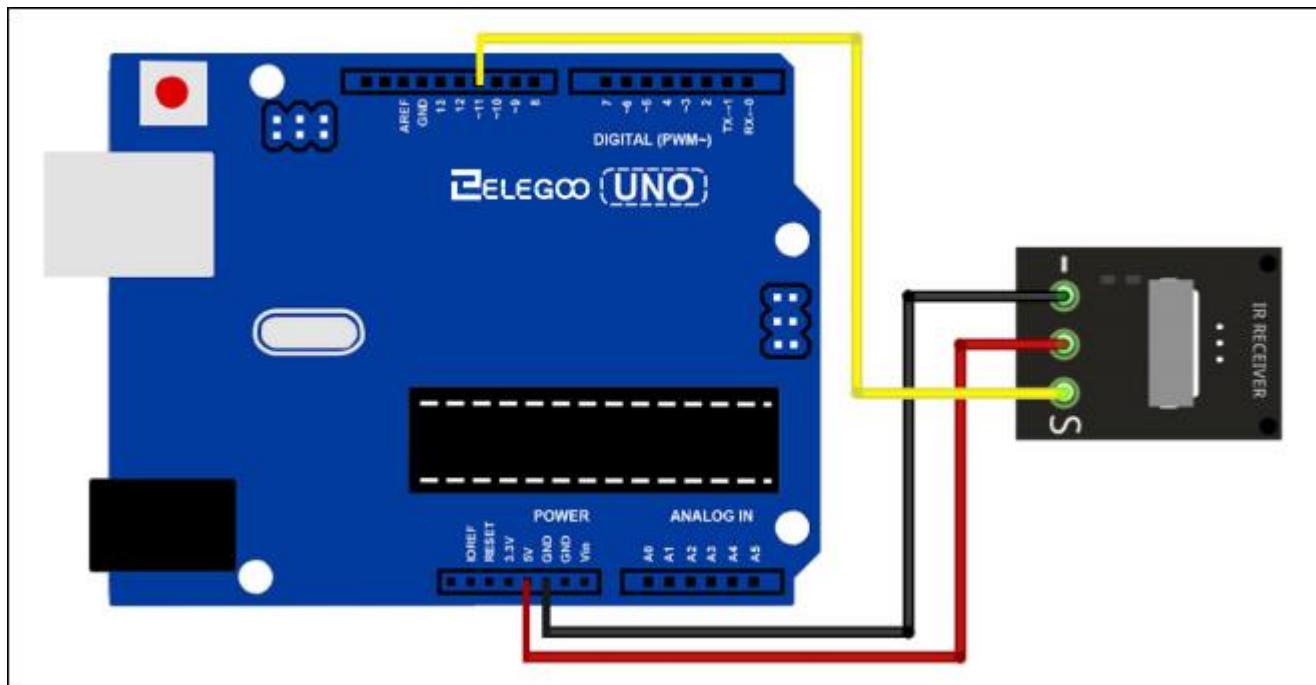
\* The peaks for PNA4601M, PNA4608M, and PNA4610M are all  $f_0$ .

As you can see from these datasheet graphs, the peak frequency detection is at 38 KHz and the peak LED color is 940 nm. You can use from about 35 KHz to 41 KHz but the sensitivity will drop off so that it won't detect as well from afar. Likewise, you can use 850 to 1100 nm LEDs but they won't work as well as 900 to 1000nm so make sure to get matching LEDs! Check the datasheet for your IR LED to verify the wavelength.

Try to get a 940nm - remember that 940nm is not visible light (its Infra Red)!

## Connection

### wiring diagram



There are 3 connections to the IR Receiver.

The connections are : Signal, Voltage and Ground.

The “-” is the Ground, “S” is signal, and middle pin is Voltage 5V.

## Code

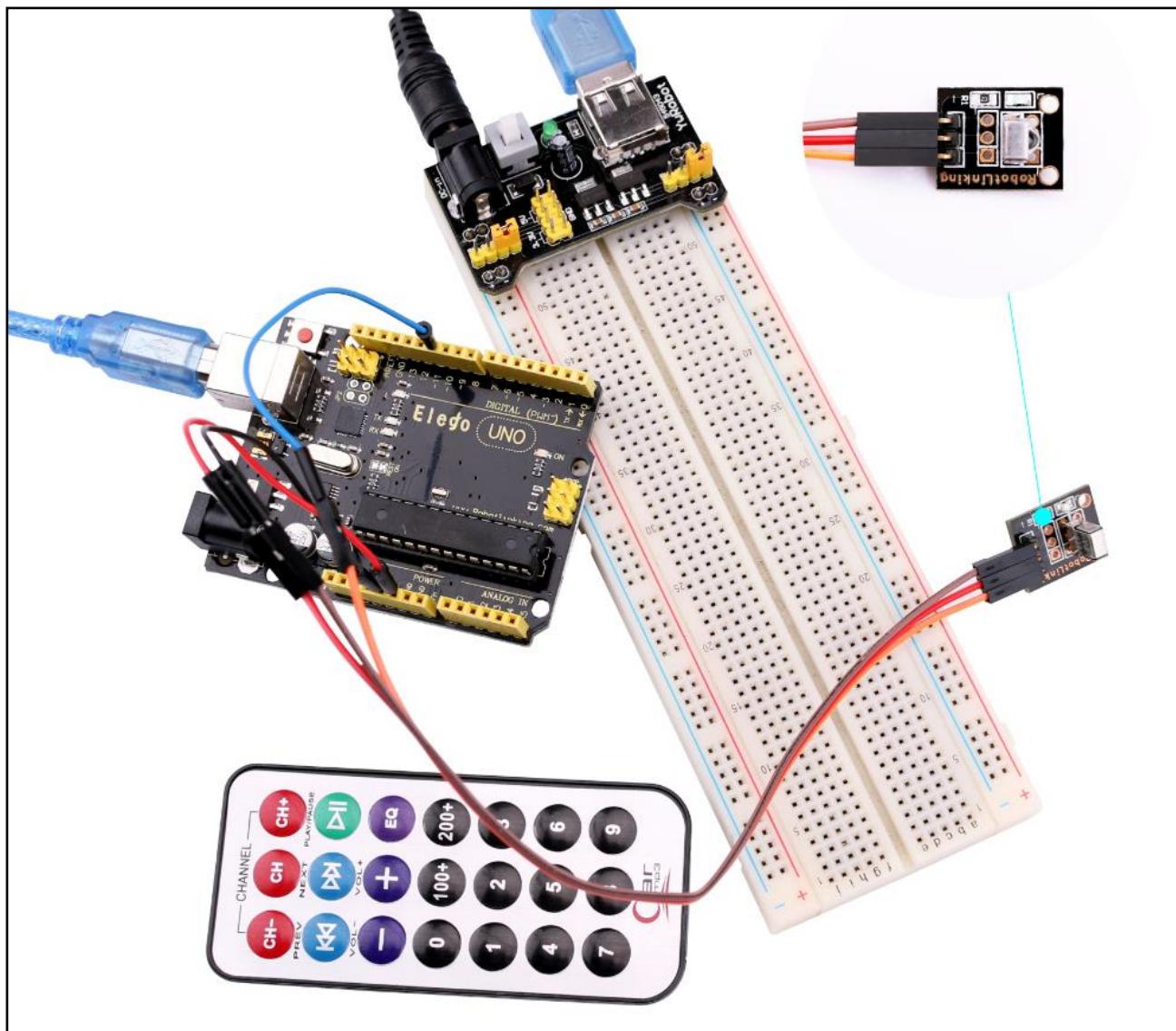
Now that we have the physical setup, all we need now is the code.

Before you can run this, you have to make sure that you have install the <IRremote> library.

Or you need to install again. If you do not do this, your code won't work.

Next we will move the <RobotIRremote> out of the Library folder, we do this because that library conflicts with the one we will be using. You can just drag it back inside the library folder once you are done programming your microcontroller.

Once you have installed the Library, just go ahead and restart your IDE Software.



# Lesson 23 MAX7219 LED Dot Matrix Module

## Overview

In this tutorial we will connect a MAX7219 and scroll the text across.

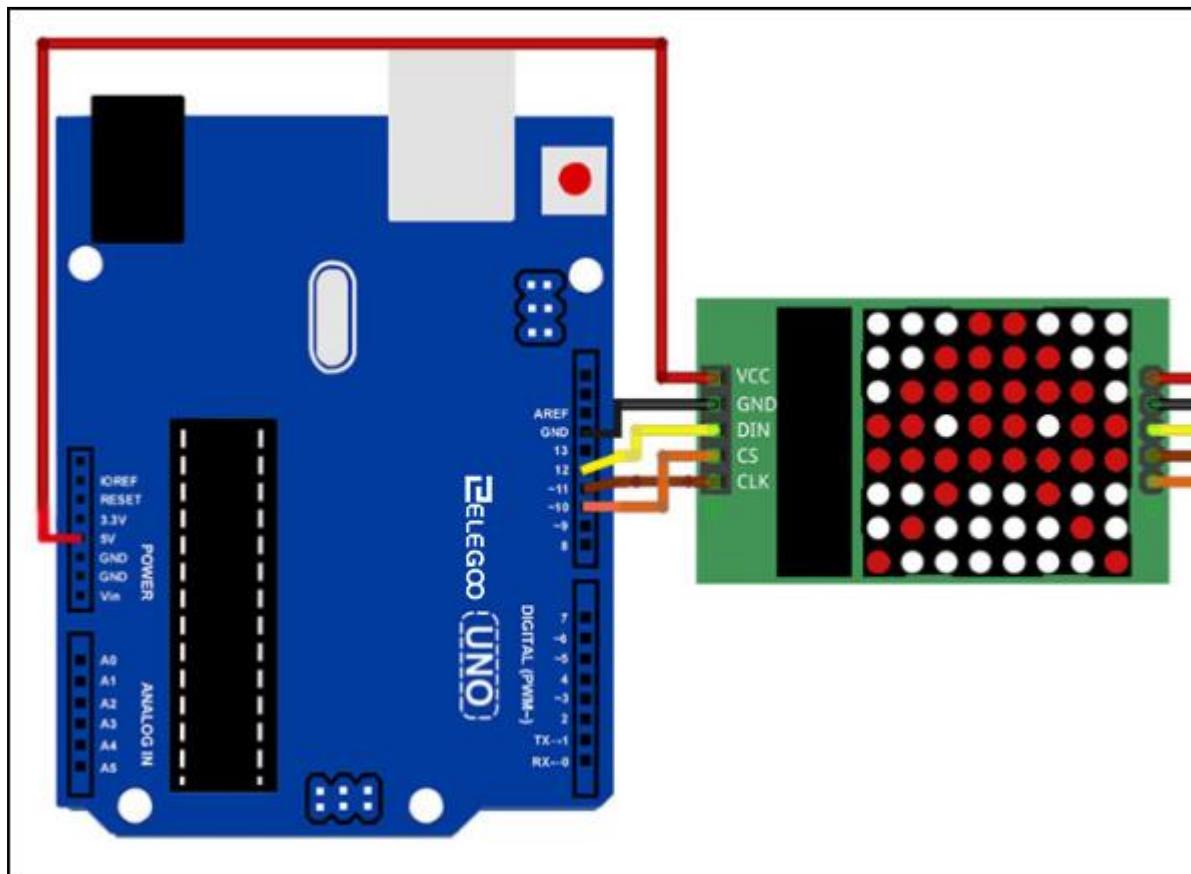
Since these modules use the MAX7219 LED driver chip, we will be able to turn on and off the 64 LEDs of each modules, using only 3 pins on our UNO.

## Component Required:

- (1) x Elegoo Uno R3
- (1) x Max7219 module
- (5) x F-M wires

## Connection

### wiring diagram



VCC and Ground are connected to the Arduino.

Pin 12 is connected to DIN, Pin 10 is connected to CS and Pin 11 is connected to CLK.

We then daisy-chain the modules together.

## Code

Our Sketch will make use of the “Maxmatrix” Library to communicate with the MAX7219 modules.

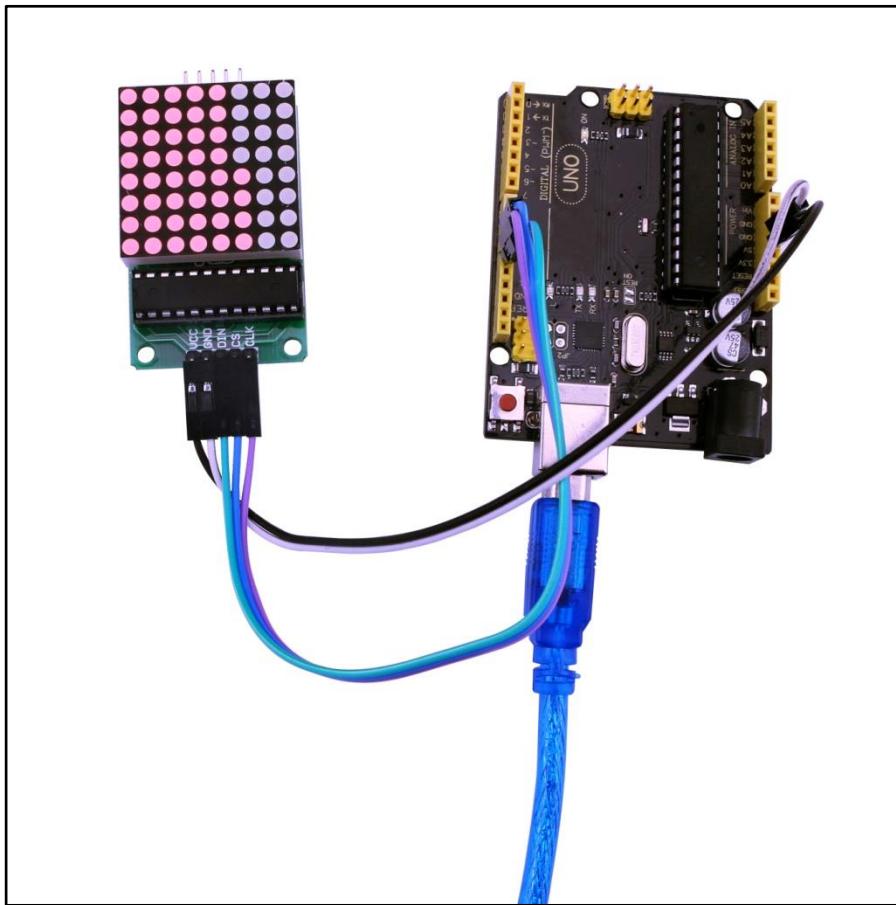
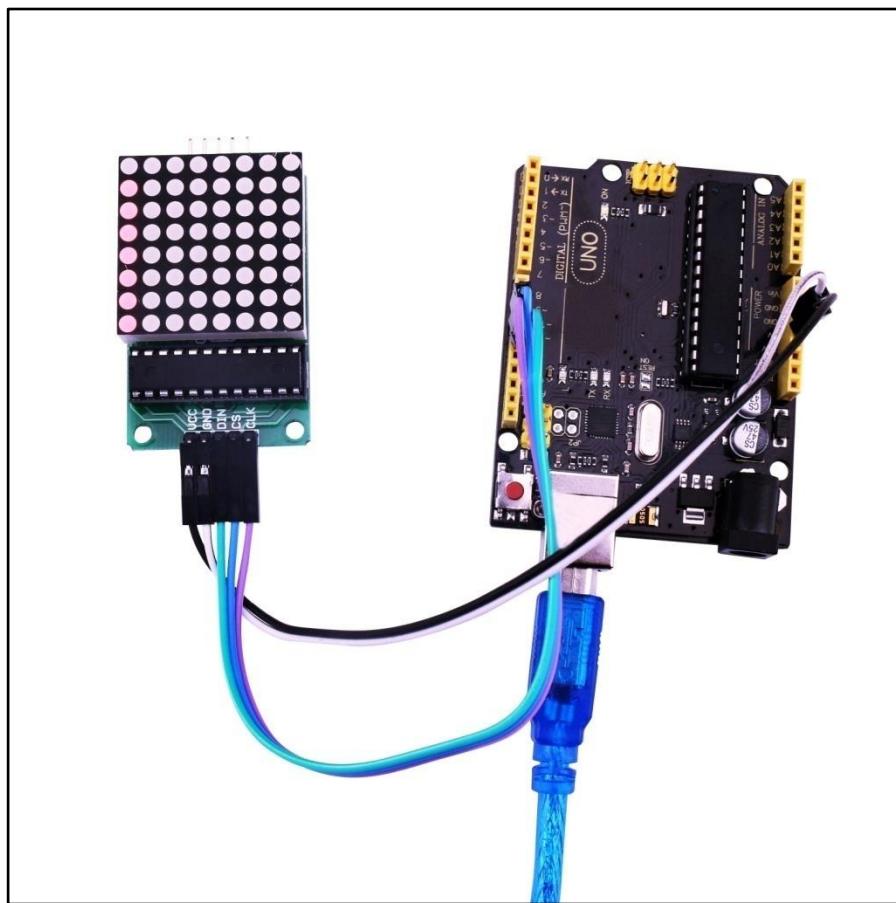
**Now that we have the physical setup, all we need now is the code.**

**Before you can run this, make sure that you have installed the <LedControl> library or re-install it, if necessary. Otherwise, your code won't work.**

Since we are defining all the characters possible (0-9 a-z etc..), instead of using the SRAM (2048 bytes), we will put that information in Flash memory on our UNO since that information will not change and also there's more Flash memory available (32k).

We do this by using the “#include <avr/pgmspace.h>” and then “PROGMEM prog uchar CH[] =” to put our array information in Flash memory.

Note: Flash (PROGMEM) memory can only be populated when we upload the code to our UNO. You can't change the values in the flash after the program has started running, unlike SRAM where our sketch is run.



# Lesson 24 ADXL335 Module

## Overview

In this lesson, you will learn to use the ADXL335 3-Axis module which measures magnetic fields in three directions: X, Y, and Z.

ADXL335 is a kind of acceleration sensor which is high precision, low power consumption and single IC chip. The voltage is between 1.8 V to 3.6 V. And its temperature range is between - 55 ° C to 125 ° C. This product size is only 22 mm x 23 mm so that it is a very convenient project-embedded hardware. Special reminder: do not power the module by the UNO R3 board 5v pin. The 3v pin is better.

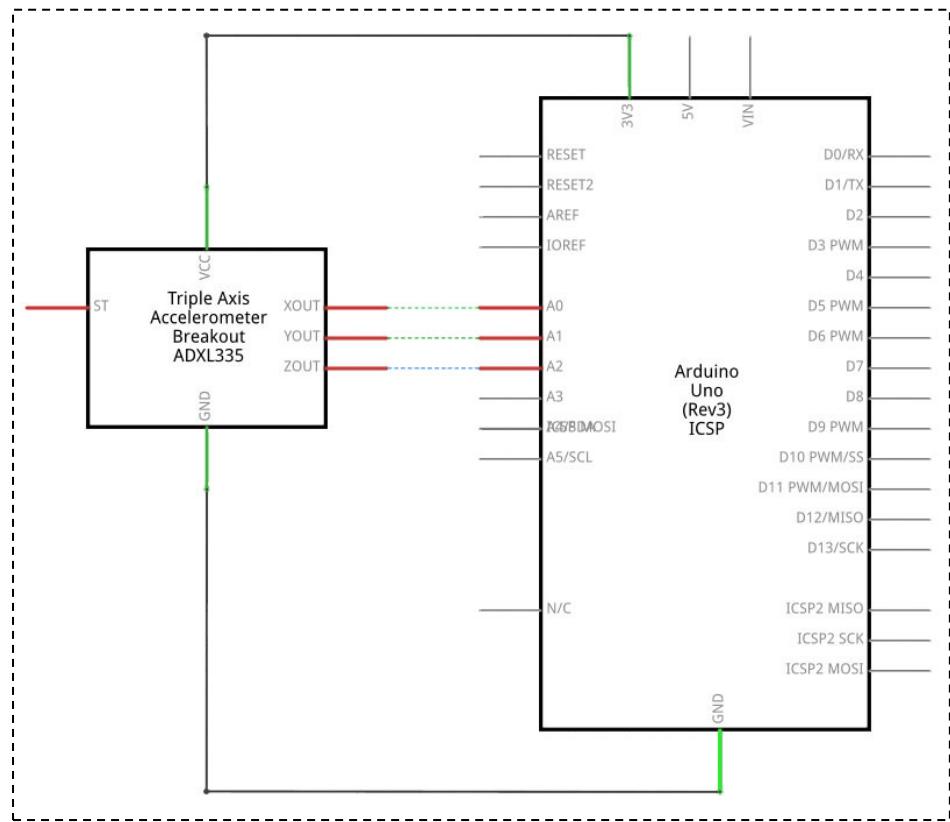
There are libraries available for this sensor that will enable you to tap into more capabilities.

## Component Required:

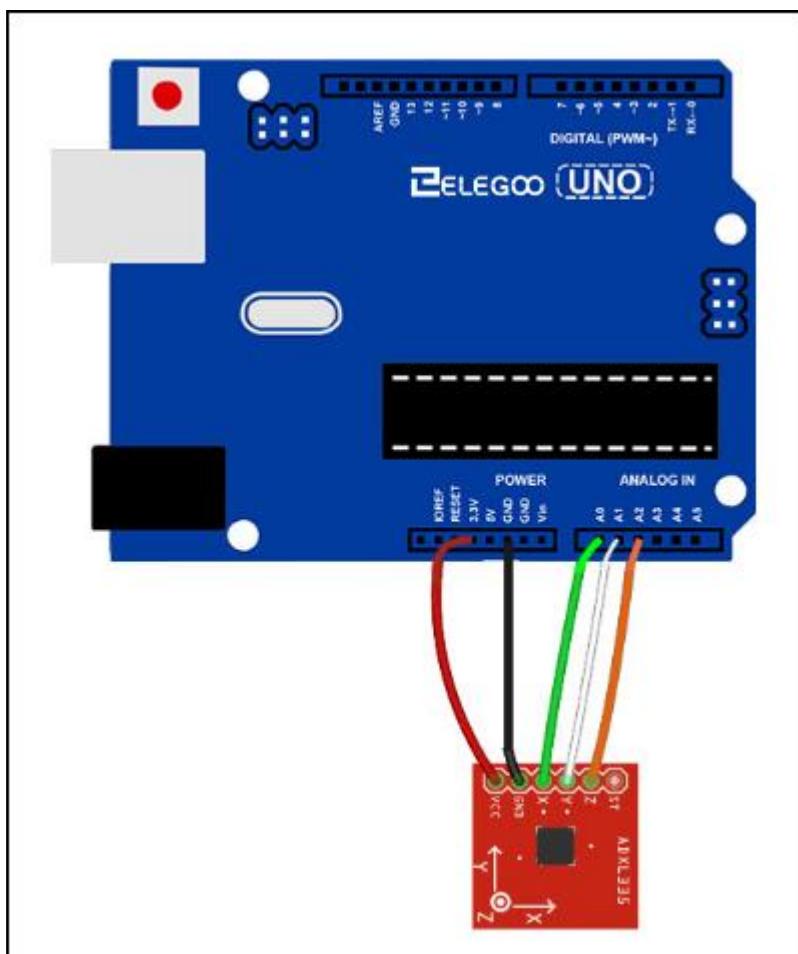
- (1) x Elegoo Uno R3
- (1) x ADXL335 module
- (5) x F-M wires

## Connection

### Schematic



wiring diagram

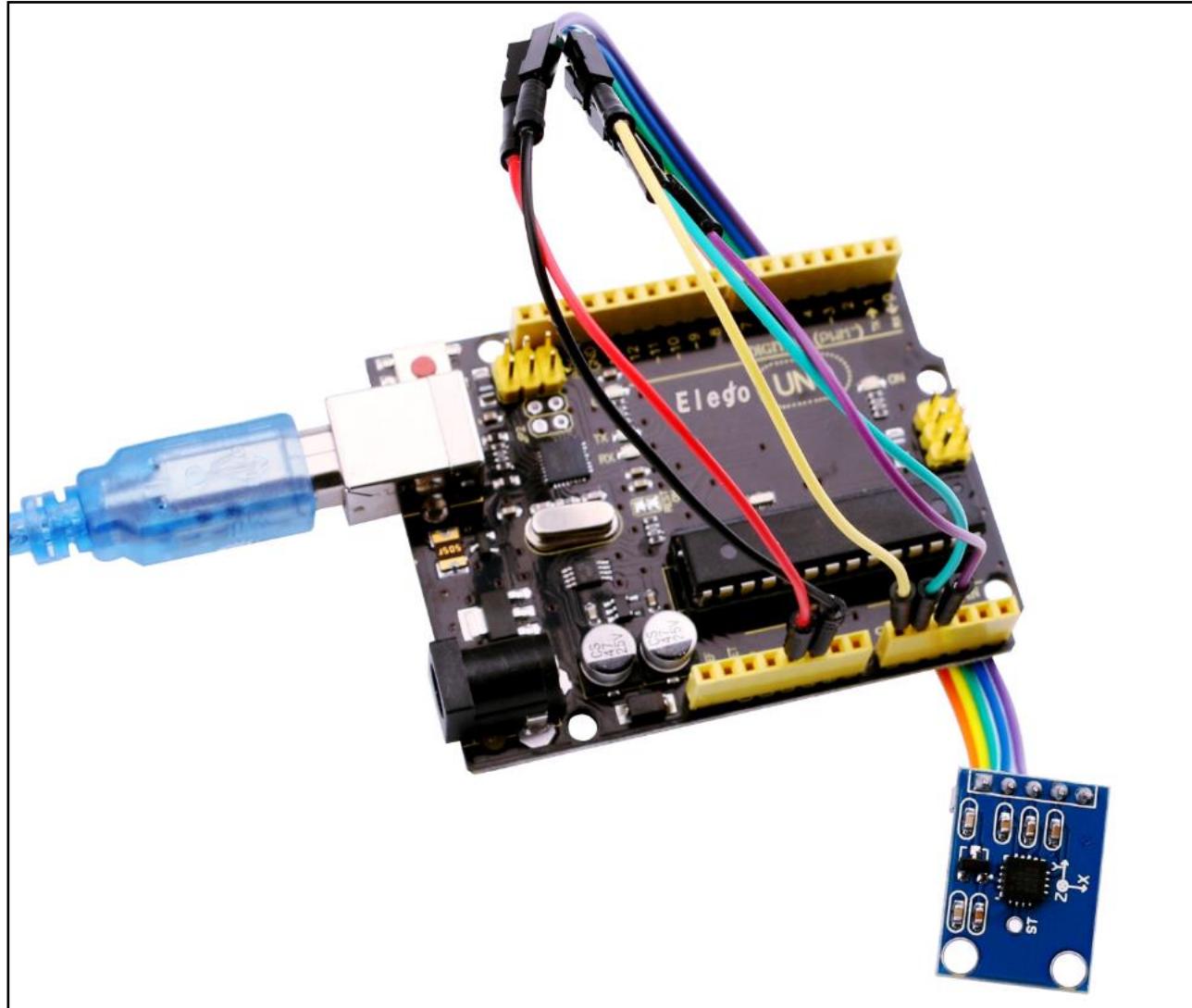


Because the output of ADXL335 is analog voltage value, when we write programs, our focus is to collect the output voltage. But if you need to do some big project like accurately measuring the specific number, you need to search the technical data for reference.

After uploading program, we open the serial port. You will see we test data shown on the window. When the acceleration changes, the corresponding number changes, too.

## Code

See the code file.



# Lesson 25 HC-SR501 PIR Sensor

## Overview

In this lesson you will learn how to use a PIR movement detector with an UNO.

The UNO is the heart of this project. It 'listens' to the PIR sensor and when motion is detect, instructs the LED to light on or shut off.

## Component Required:

(1) x Elegoo Uno R3

(1) x HC-SR501

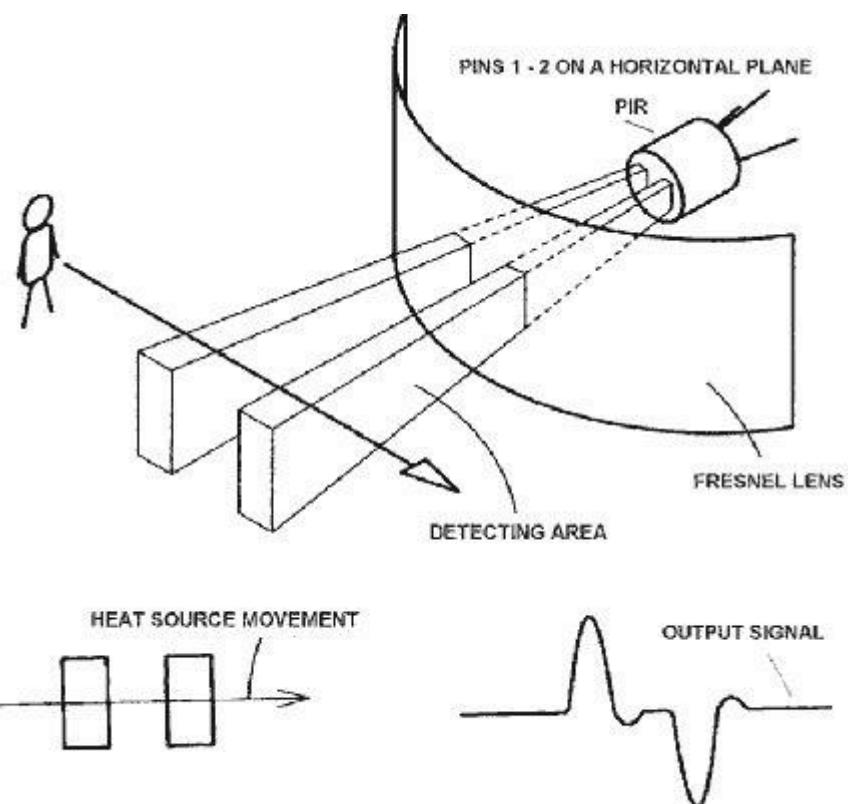
(3) x F-M wires

## Component Introduction

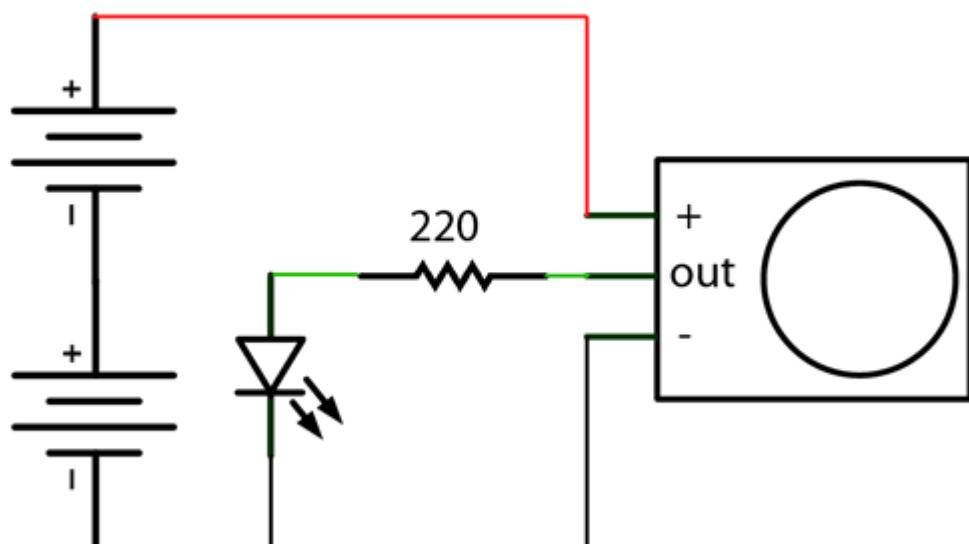
### PIR SENSOR:

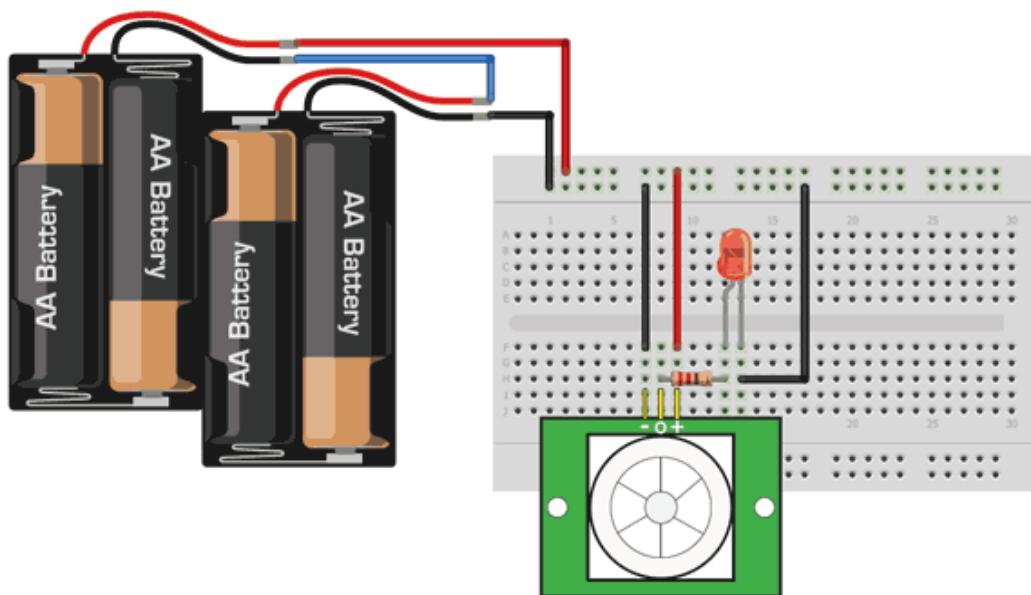
PIR sensors are more complicated than many of the other sensors explained in this tutorial (like photocells, FSRs and tilt switches) because there are multiple variables that affect the sensors input and output. .

The PIR sensor itself has two slots. Each slot is made of a special material that is sensitive to IR. The lens used here is not really doing much and so we see that the two slots can 'see' out past some distance (basically the sensitivity of the sensor). When the sensor is idle, both slots detect the same amount of IR, the ambient amount radiated from the room or walls or outdoors. When a warm body like a human or an animal passes by, it first intercepts one half of the PIR sensor, which causes a positive differential change between the two halves. When the warm body leaves the sensing area, the reverse happens, whereby the sensor generates a negative differential change. These change pulses are what is detected.



#### TESTING PIR SENSOR MODULE:





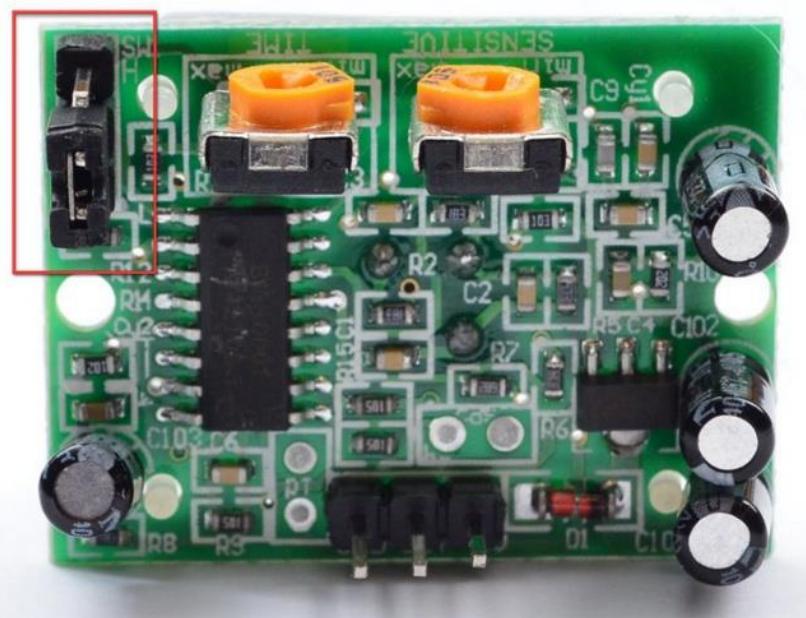
Now when the PIR detects motion, the output pin will go "high" to 3.3V and light up the LED!

Once you have the breadboard wired up, insert the batteries and wait 30-60 seconds for the PIR to 'stabilize'. During that time the LED may blink a little. Wait until the LED is off and then move around in front of it, waving a hand, etc, to see the LED light up!

### **Retriggering**

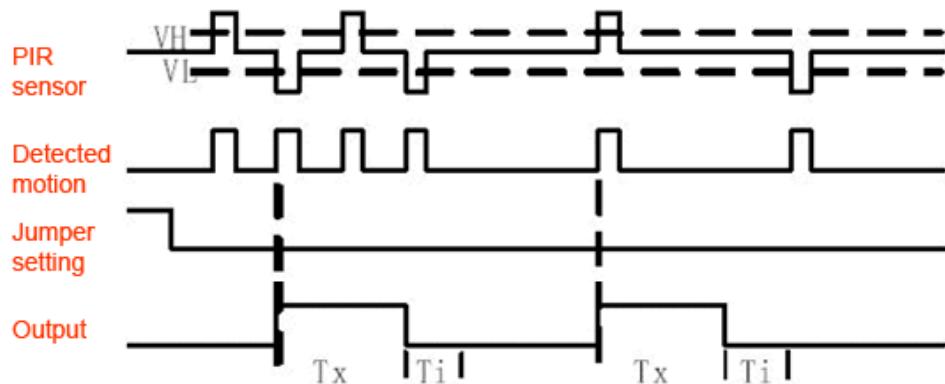
There are a couple options you may have with your PIR. The first is the 'retriggering' option.

Once you have the LED blinking, look on the back of the PIR sensor and make sure that the jumper is placed in the L position as shown below.

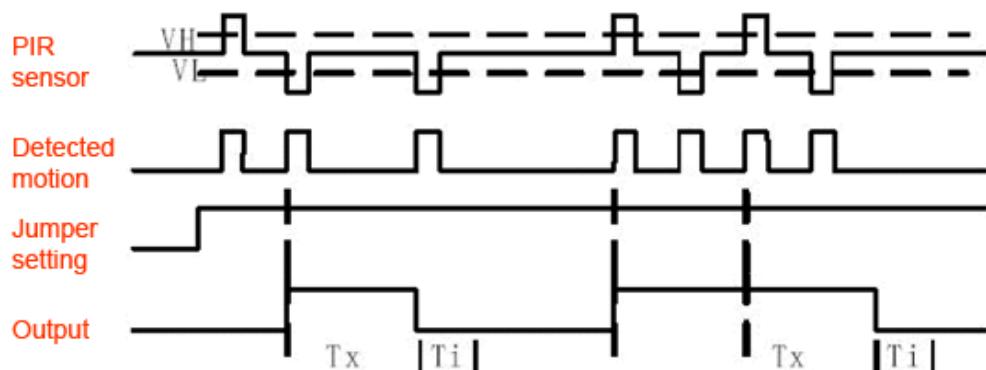


Now set up the testing board again. You may notice that when connecting up the PIR

sensor as above, the LED does not stay on when moving in front of it but actually turns on and off every second or so. That is called "non-retriggering".

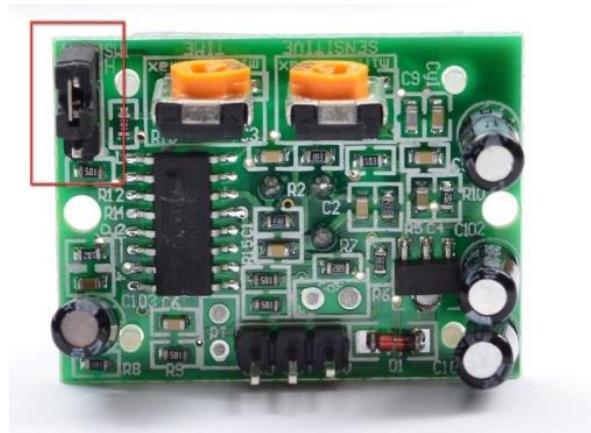


Change the jumper so that it is in the H position. If you set up the test, you will notice that now the LED does stay on the entire time that something is moving. That is called "retriggering".



(The graphs above are from the BISS0001 datasheet.)

For most applications, "retriggering" (jumper in H position as shown below) mode is a little nicer.

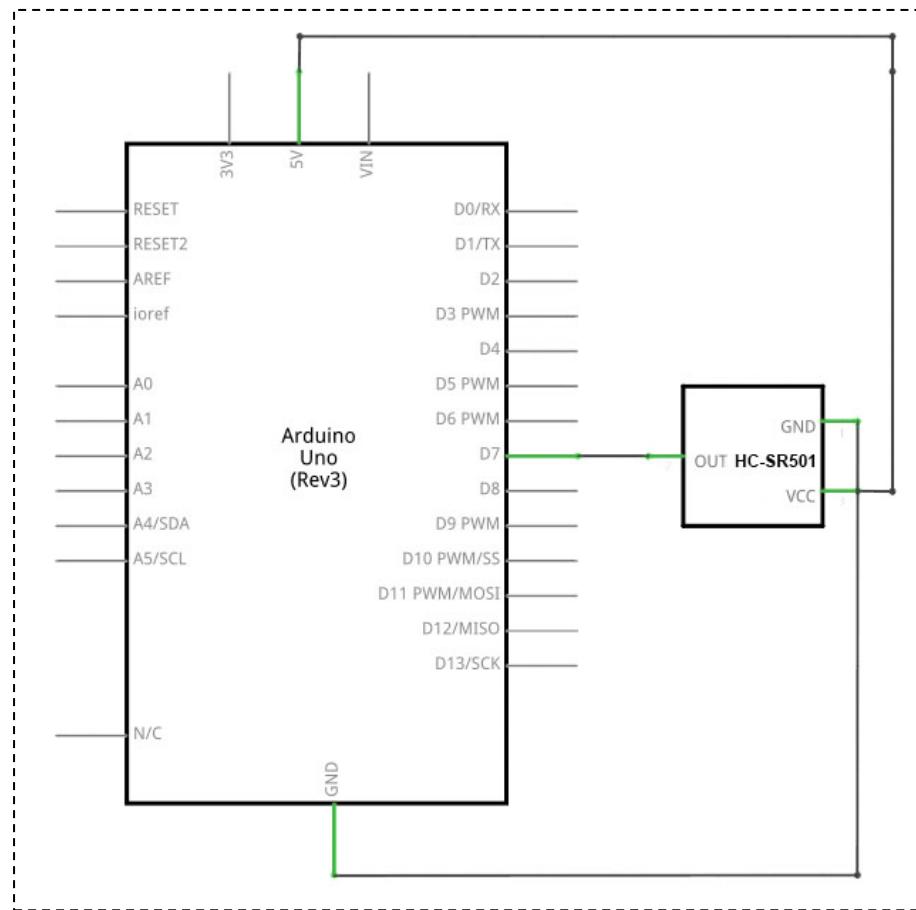


If you need to connect the sensor to something edge-triggered, you'll want to set it to

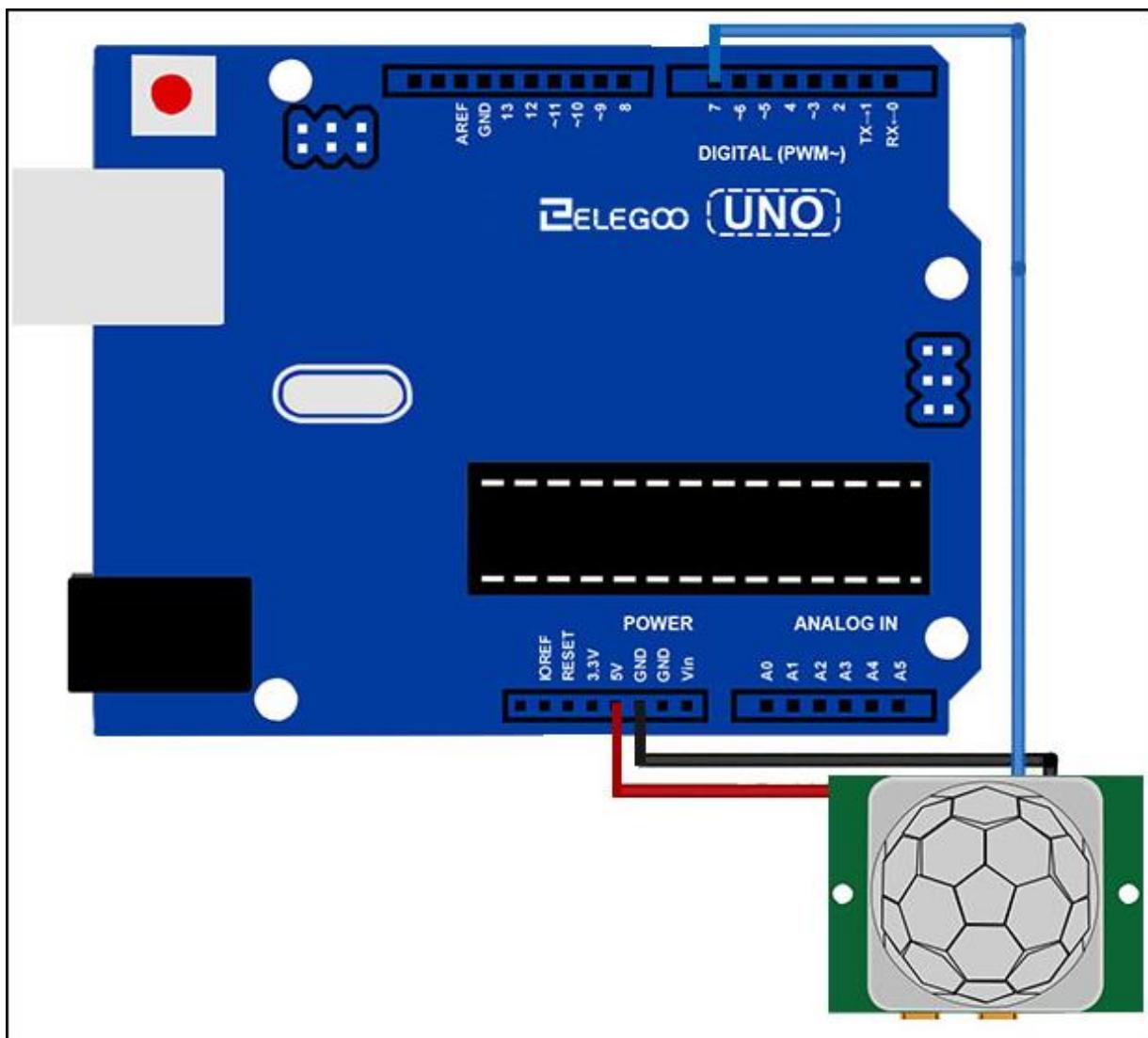
"non-retriggering" (jumper in L position).

## Connection

### Schematic



wiring diagram



Connecting PIR sensors to a microcontroller is really simple. The PIR acts as a digital output so all you need to do is listen for the pin to flip high (detected) or low (not detected).

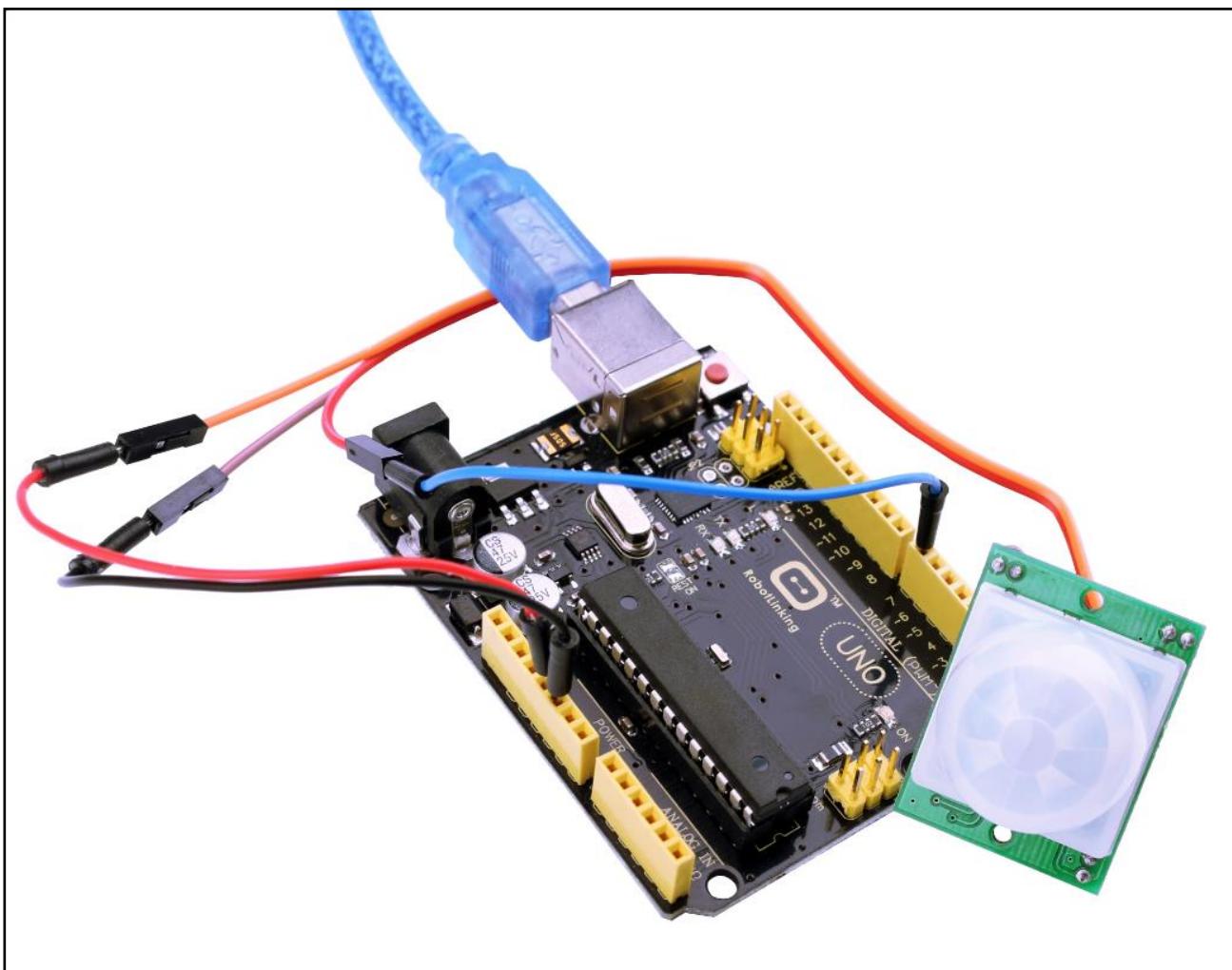
It's likely that you'll want retriggering, so be sure to put the jumper in the H position!

Power the PIR with 5V and connect ground to ground. Then connect the output to a digital pin. In this example, we'll use pin 2.

## Code

The code is very simple, and it basically just keeps track of whether the input to pin 2 is high or low. It also tracks the state of the pin, so that it prints out a message when motion has started and stopped.

Don't forget that there are times when you don't need a microcontroller. A PIR sensor can be connected to a relay (perhaps with a transistor buffer) without a micro!



# Lesson 26 Water Level Detection Sensor Module

## Overview

In this lesson, you will learn how to use a water level detection sensor module.

This module can perceive the depth of water and the core component is an amplifying circuit which is made up of a transistor and several pectinate PCB routings. When put into the water, these routings will present a resistor that can change along with the change of the water's depth. Then, the signal of water's depth is converted into the electrical signal, and we can know the change of water's depth through the ADC function of UNO R3.

## Component Required:

- (1) x Elegoo Uno R3
- (1) x Water lever detection sensor module
- (3) x F-M wires

## Component Introduction

### Water sensor:

A water sensor brick is designed for water detection, which can be widely used in sensing the rainfall, water level, even the liqueate leakage. The brick is mainly composed of three parts: an electronic brick connector, a  $1\text{ M}\Omega$  resistor, and several lines of bare conducting wires.

This sensor works by having a series of exposed traces connected to ground. Interlaced between the grounded traces are the sense traces.

The sensor traces have a weak pull-up resistor of  $1\text{ M}\Omega$ . The resistor will pull the sensor trace value high until a drop of water shorts the sensor trace to the grounded trace. Believe it or not this circuit will work with the digital I/O pins of your UNO R3 board or you can use it with the analog pins to detect the amount of water induced contact between the grounded and sensor traces.

This item can judge the water level through with a series of exposed parallel wires stitch to

measure the water droplet/water size. It can easily change the water size to analog signal, and output analog value can directly be used in the program function, then to achieve the function of water level alarm.

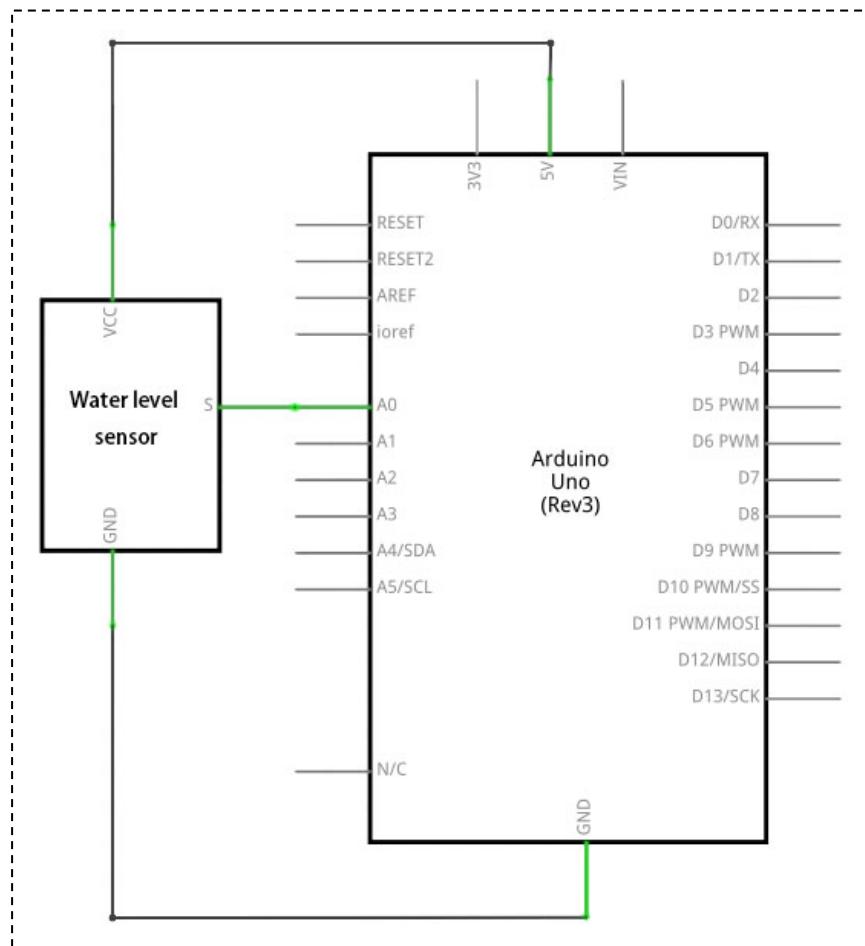
It has low power consumption, and high sensitivity.

Features:

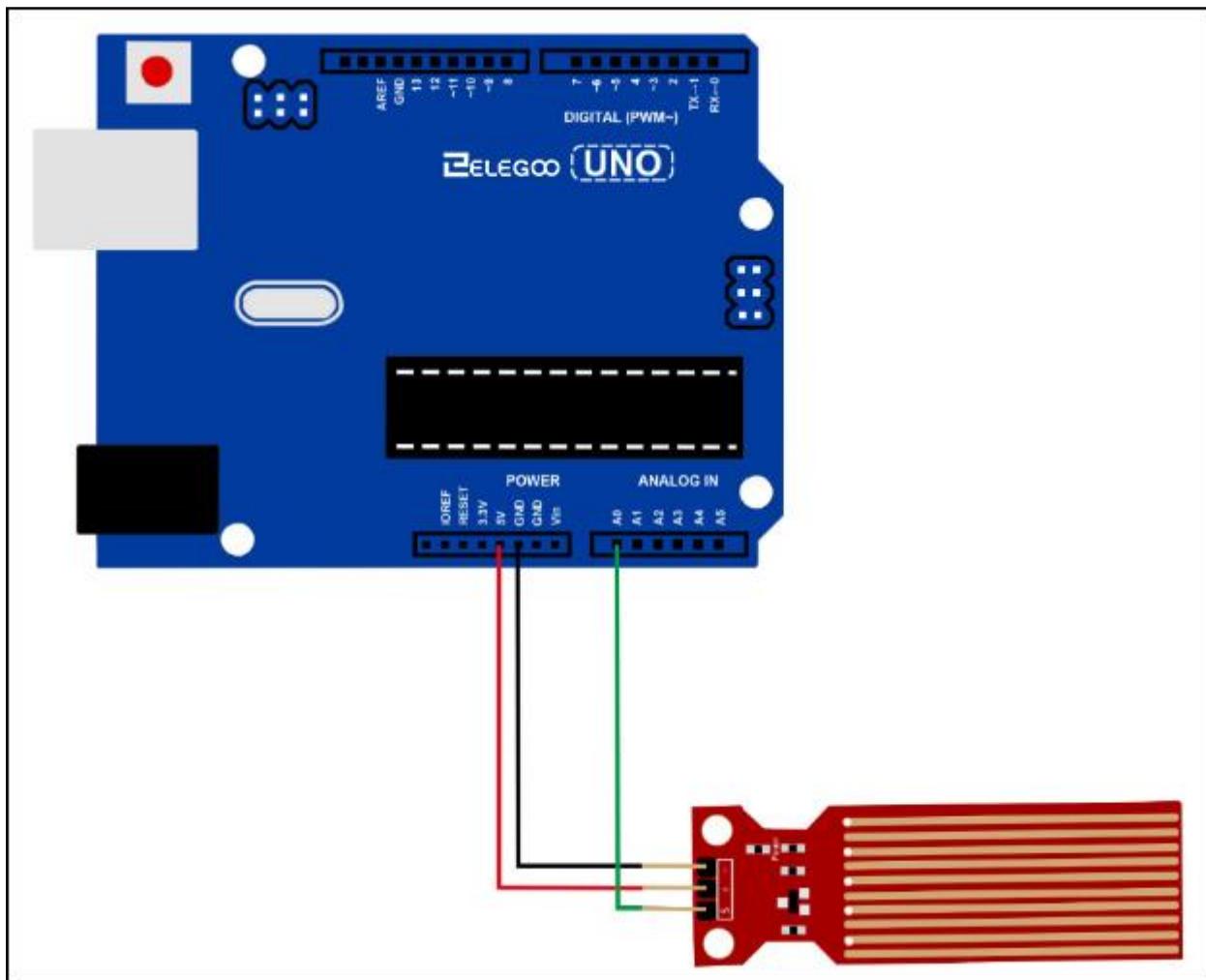
- 1、Working voltage: 5V
- 2、Working Current: <20ma
- 3、Interface: Analog
- 4、Width of detection: 40mm×16mm
- 5、Working Temperature: 10°C~30°C
- 6、Output voltage signal: 0~4.2V

## Connection

### Schematic



## wiring diagram



Wiring tips: Power supply (+) is connected to 5V of UNO R3 board, ground electrode (-) is connected to GND. Signal output (S) is connected to the ports (A0-A5) which have function of inputting analog signal in UNO R3 board, random one is OK, but it should define the same demo code as the routine.

## Code

See the code file.



open the monitor you can see the data as below:

ADC14 level is 83  
ADC14 level is 94  
ADC14 level is 105  
ADC14 level is 116  
ADC14 level is 127  
ADC14 level is 116  
ADC14 level is 105  
ADC14 level is 94  
ADC14 level is 83  
ADC14 level is 72  
ADC14 level is 61  
ADC14 level is 50  
ADC14 level is 39  
ADC14 level is 28  
ADC14 level is 17  
ADC14 level is 6  
ADC14 level is 17  
ADC14 level is 28  
ADC14 level is 39  
ADC14 level is 50  
ADC14 level is 61  
ADC14 level is 72  
ADC14 level is 83  
ADC14 level is 94  
ADC14 level is 105  
ADC14 level is 116  
ADC14 level is 127

自动滚屏 换行符 9600 波特率

# Lesson 27 Real Time Clock Module

## Overview

In this lesson, you will learn how to use the DS3231, clock module that displays the year, month, day, hour, minute, second and week. Support is via a backup battery trickle charger, which can be used unless being connected to UNO with only three data cables.

## Component Required:

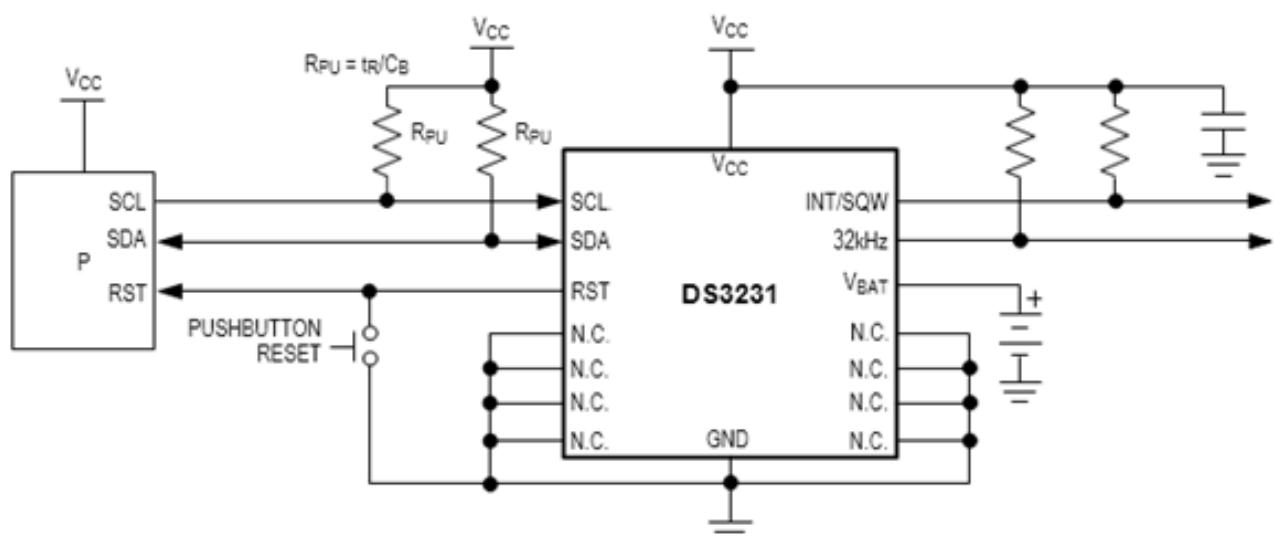
- (1) x Elegoo Uno R3
- (1) x DS3231 real time clock module
- (4) x F-M wires

## Component Introduction

### DS1302

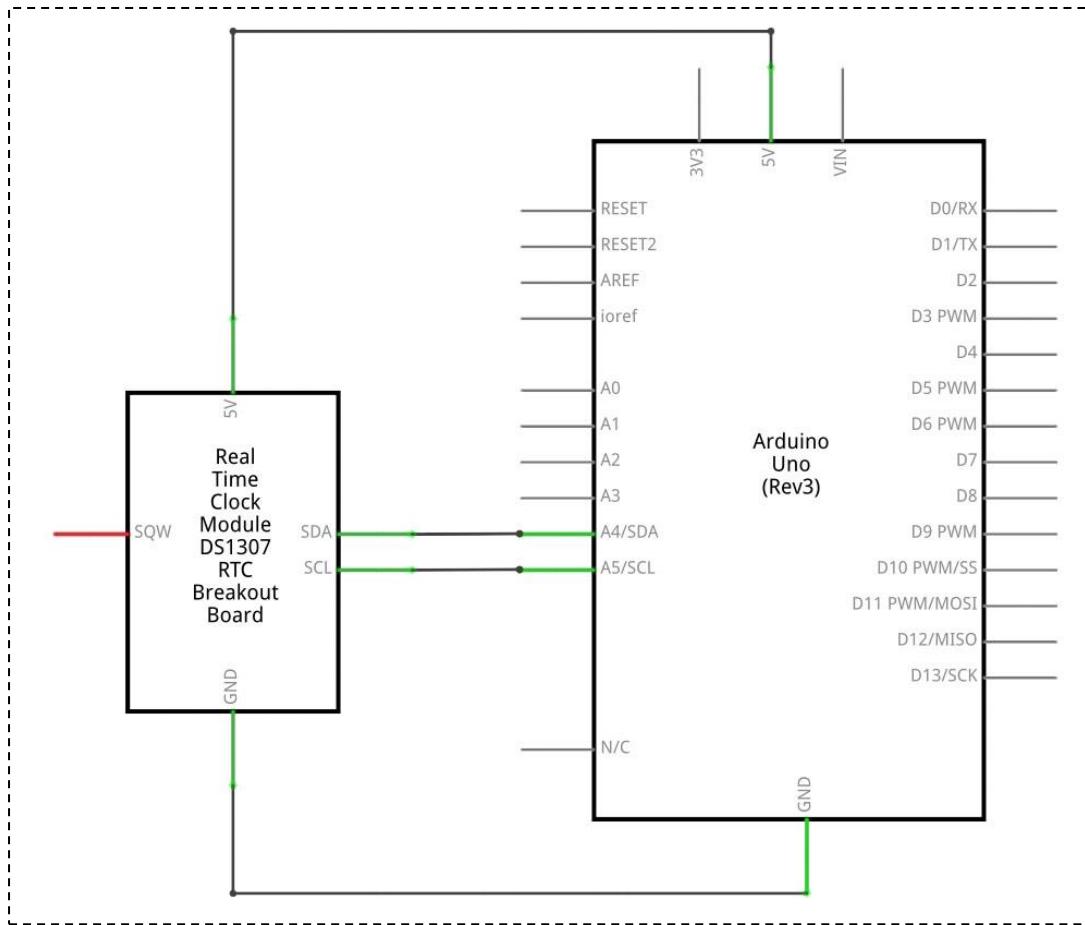
### DS3231

The DS3231 is a simple time-keeping chip. It has an integrated battery, so the clock can continue keeping time even when unplugged.

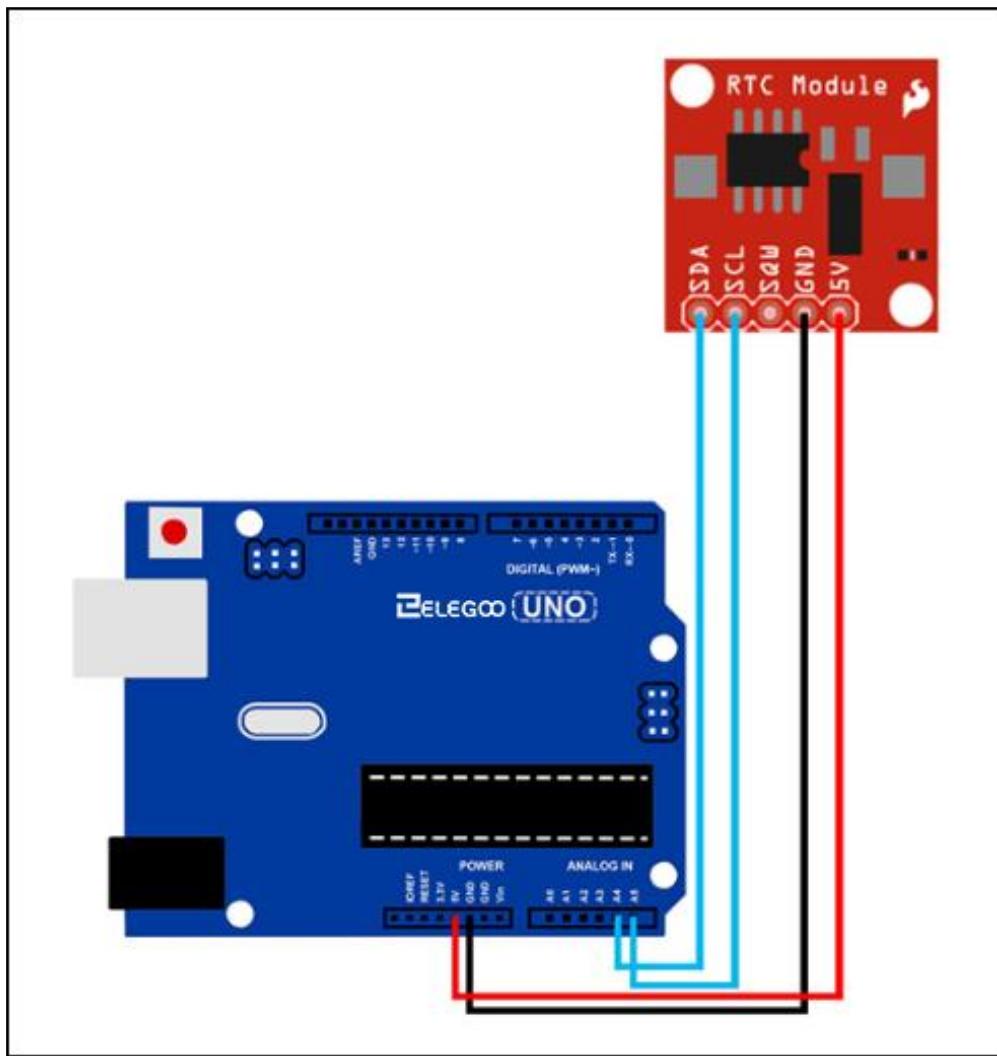


## Connection

### Schematic



wiring diagram



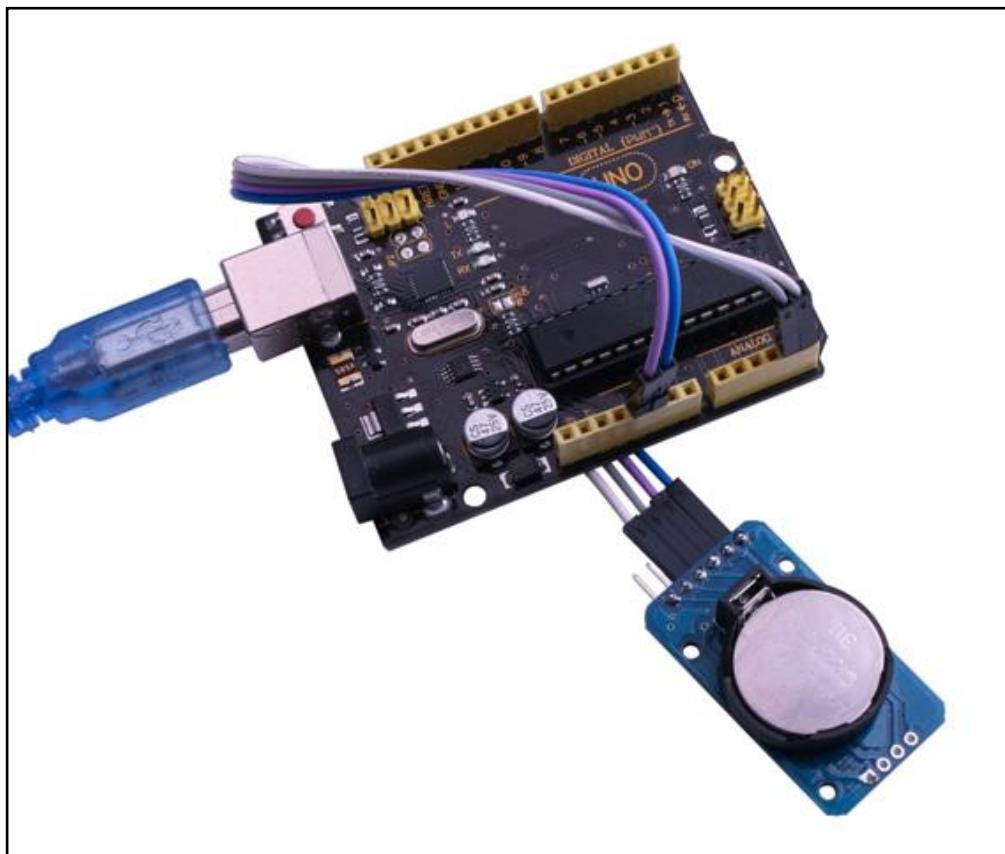
Set up according to the following image.

Ignore the 32K and SQW pins; you will not need them. Plug the SCL pin into your UNO R3 board A5 port, and the SDA pin into the A4 port. The VCC pin plugs into the 5V port, and the GND plugs into the GND port.

## Code

**Now that we have the physical setup, all we need now is the code.**

**Before you can run this, make sure that you have installed the `<DS3231>` `<OneWireKeypad>` library or re-install it if needed. Otherwise, your code won't work.**



open the monitor you can see the module can read the time as below:

```
Raw data: 2016-4-29 14:10:36
Raw data: 2016-4-29 14:10:37
Raw data: 2016-4-29 14:10:38
Raw data: 2016-4-29 14:10:39
Raw data: 2016-4-29 14:10:40
Raw data: 2016-4-29 14:10:41
Raw data: 2016-4-29 14:10:42
Raw data: 2016-4-29 14:10:43
Raw data: 2016-4-29 14:10:44
Raw data: 2016-4-29 14:10:45
Raw data: 2016-4-29 14:10:46
Raw data: 2016-4-29 14:10:47
Raw data: 2016-4-29 14:10:48
Raw data: 2016-4-29 14:10:49
Raw data: 2016-4-29 14:10:50
Raw data: 2016-4-29 14:10:51
Raw data: 2016-4-29 14:10:52
Raw data: 2016-4-29 14:10:53
Raw data: 2016-4-29 14:10:54
Raw data: 2016-4-29 14:10:55
```

## Lesson 28 Sound Sensor Module

### Overview

In this lesson, you will learn how to use a sound sensor module. This module has two outputs:

AO: analog output, real-time output voltage signal of microphone

DO: when the intensity of the sound reaches a certain threshold, the output is a high or low level signal. The threshold sensitivity can be achieved by adjusting the potentiometer.



- 1.DO:digital output
- 2.VCC: 3.3V-5V DC
- 3.GND:ground
- 4.AO:analog output

### Component Required:

- (1) x Elegoo Uno R3
- (1) x Sound sensor module
- (3) x F-M wires

### Component Introduction

#### Microphone

Transducers are devices which convert energy from one form to other. A microphone is a transducer which converts sound energy to electrical signals. It works opposite to a speaker. Microphones are available in different shapes and sizes. Depending on the application, a microphone may use different technologies to convert sound to electrical signals. Here, we are going to discuss about the electret condenser microphone which is widely used in mobile phones, laptops, etc.

As the name suggests, the electret condenser microphone is a parallel plate capacitor and works on the principle of a variable capacitance. It consists of two plates, one fixed (called the back plate) and the other moveable (called the diaphragm) with a small gap between them. An electric potential charges the plate. When sound strikes the diaphragm it starts moving, thereby changing the capacitance between the plates which in turn results in a variable electric current to flow.



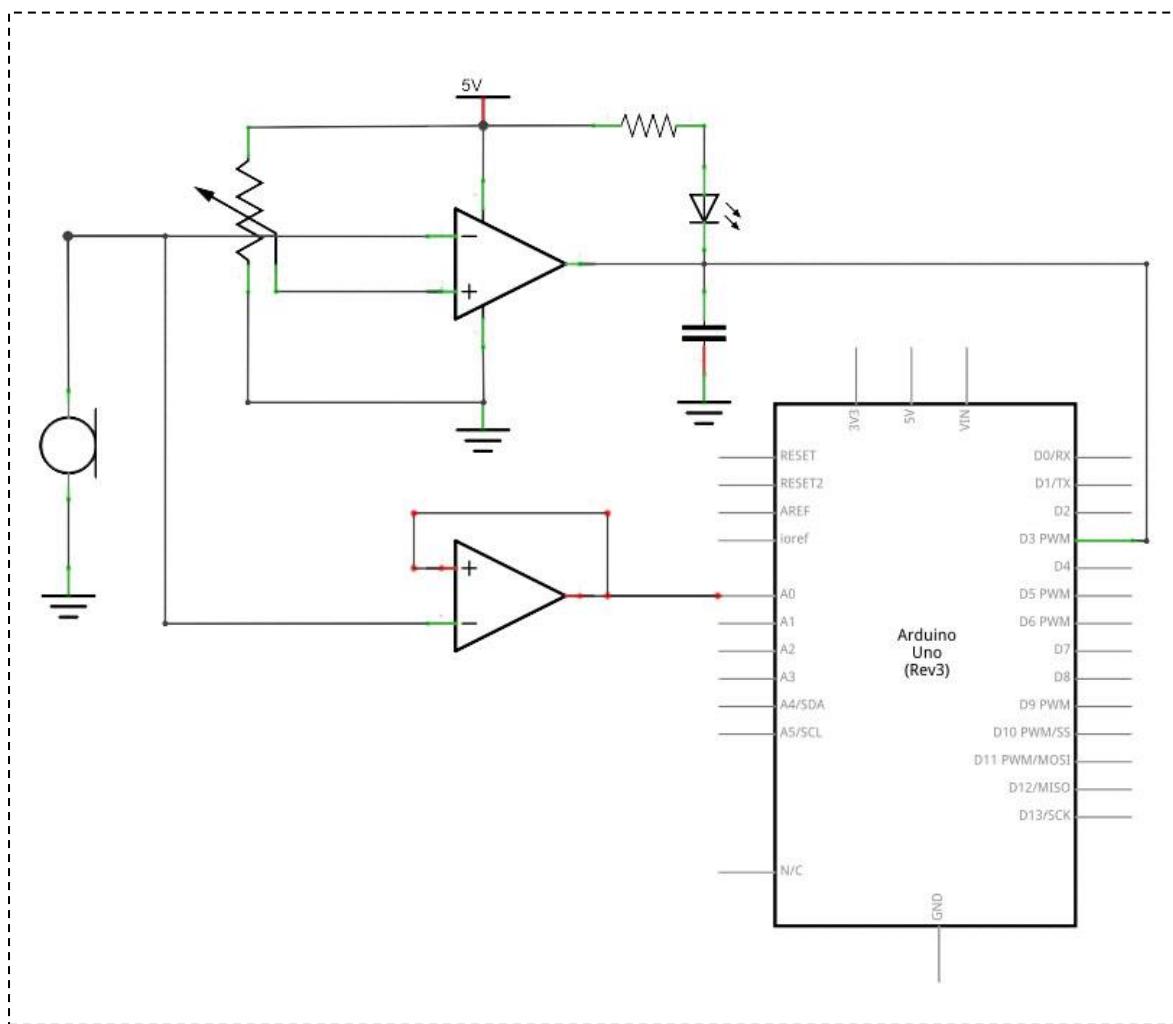
These microphones are widely used in electronic circuits to detect minor sounds or air vibrations which in turn are converted to electrical signals for further use. The two legs as shown in the image above are used to make electrical connection with the circuit.



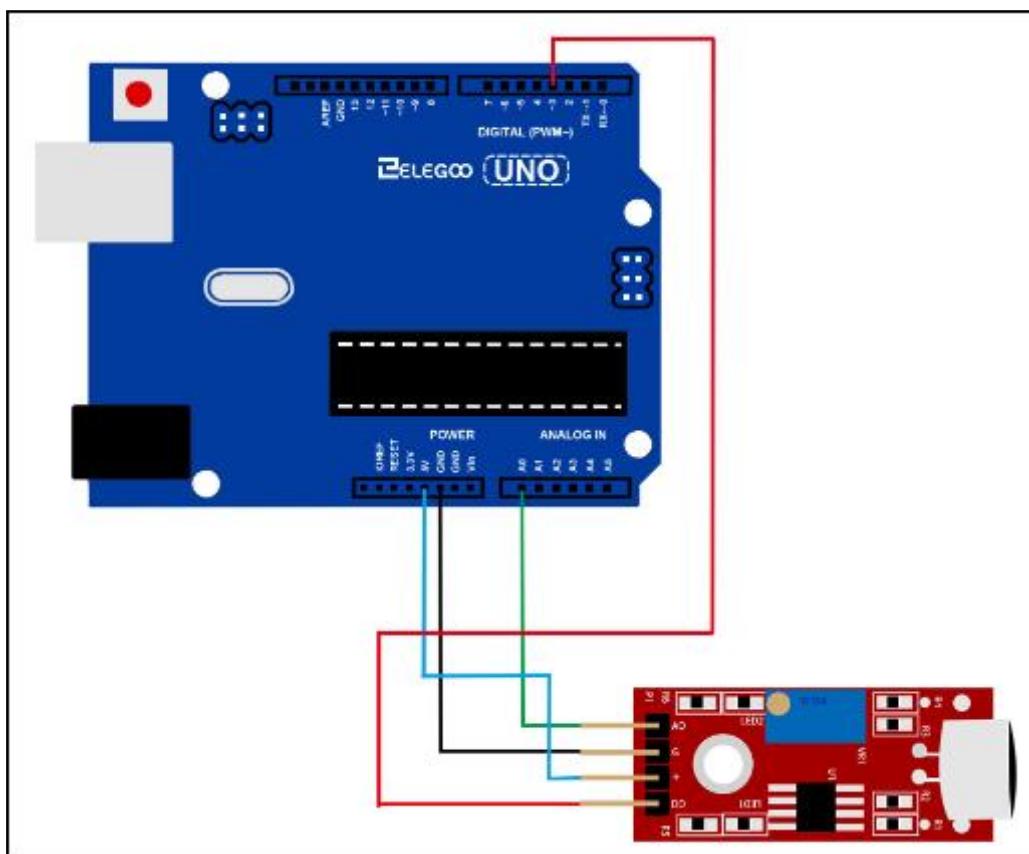
A solid conducting metal body encapsulates the various parts of the microphone. The top face is covered with a porous material with the help of glue. It acts as a filter for the dust particles. The sound signals/air vibrations passes through the porous material and falls on the diaphragm through the hole shown in the image above.

## Connection

### Schematic

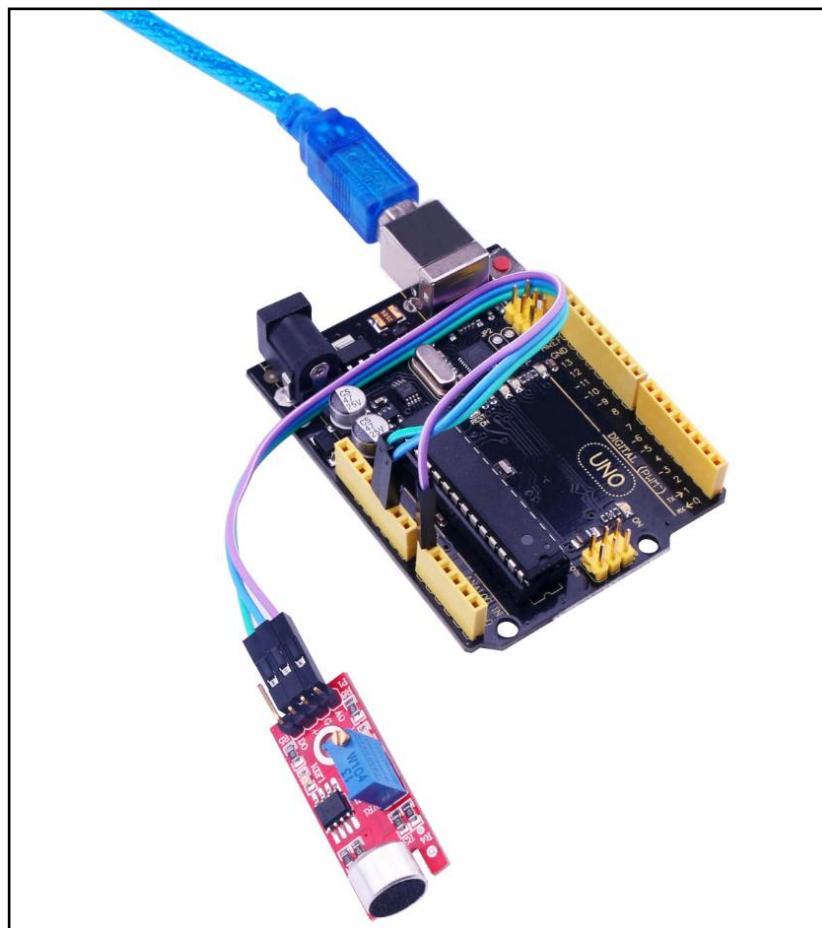


### wiring diagram



## The code

See the code file.



open the monitor you can see the data as below:

The screenshot shows the Arduino Serial Monitor window titled "COM16 (Arduino/Genuino Uno)". The window displays a series of numerical values: 40, 47, 42, 34, 24, 43, 43, 43, 47, 42, 50, 36, 31, 28, 37, 53, 26, 58, 34, 45, 35, 40, 35, 42, 56, 36, 36. At the bottom of the window, there are three status indicators: a checked checkbox for "自动滚屏" (Auto Scroll), a dropdown menu for "换行符" (Line Break), and a dropdown menu for "9600 波特率" (9600 Baud Rate).

## Lesson 29 RC522 RFID Module

### Overview

In this lesson, you will learn to how to apply the RC522 RFID Reader Module on UNO R3. This module uses the Serial Peripheral Interface (SPI) bus to communicate with controllers such as Arduino, Raspberry Pi, beagle board, etc.

### Component Required:

(1) x Elegoo Uno R3

(1) x RC522 module

(3) x F-M wires

### Component Introduction

#### RC522

The MFRC522 is a highly integrated reader/writer for contactless communication at 13.56 MHz. The MFRC522 reader supports ISO 14443A / MIFARE® mode.

The MFRC522's internal transmitter part is able to drive a reader/writer antenna designed to communicate with ISO/IEC 14443A/MIFARE® cards and transponders without additional active circuitry. The receiver part provides a robust and efficient implementation of a demodulation and decoding circuitry for signals from ISO/IEC 14443A/MIFARE® compatible cards and transponders. The digital part handles the complete ISO/IEC 14443A framing and error detection (Parity & CRC).The MFRC522 supports MIFARE®Classic (e.g. MIFARE® Standard) products. The MFRC522 supports contactless communication using MIFARE® higher transfer speeds up to 848 kbit/s in both directions.

Various host interfaces are implemented:

- SPI interface
- serial UART (similar to RS232 with voltage levels according pad voltage supply)
- I2C interface.

The figure below shows a typical circuit diagram, using a complementary antenna

connection to the MFRC522.

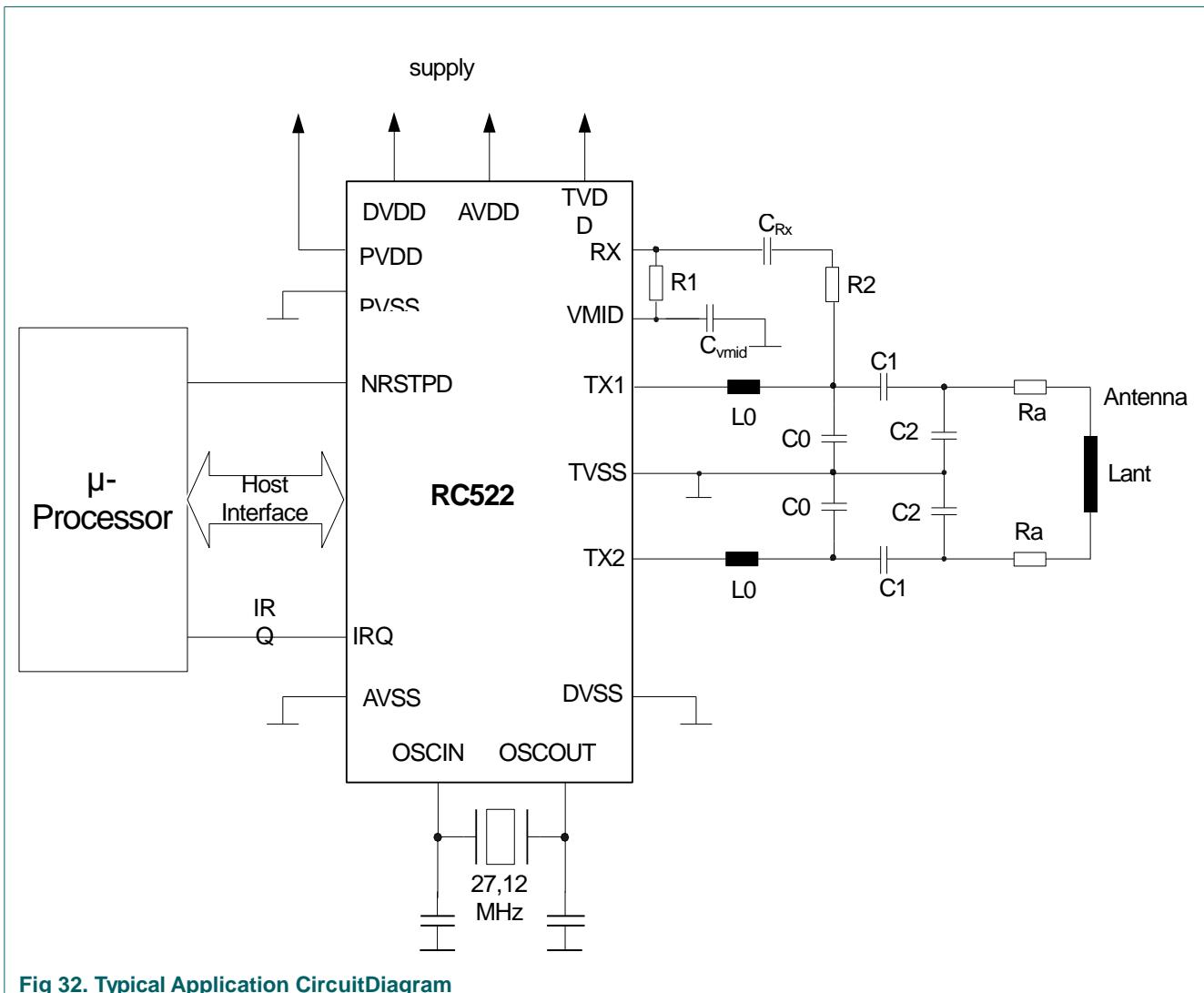
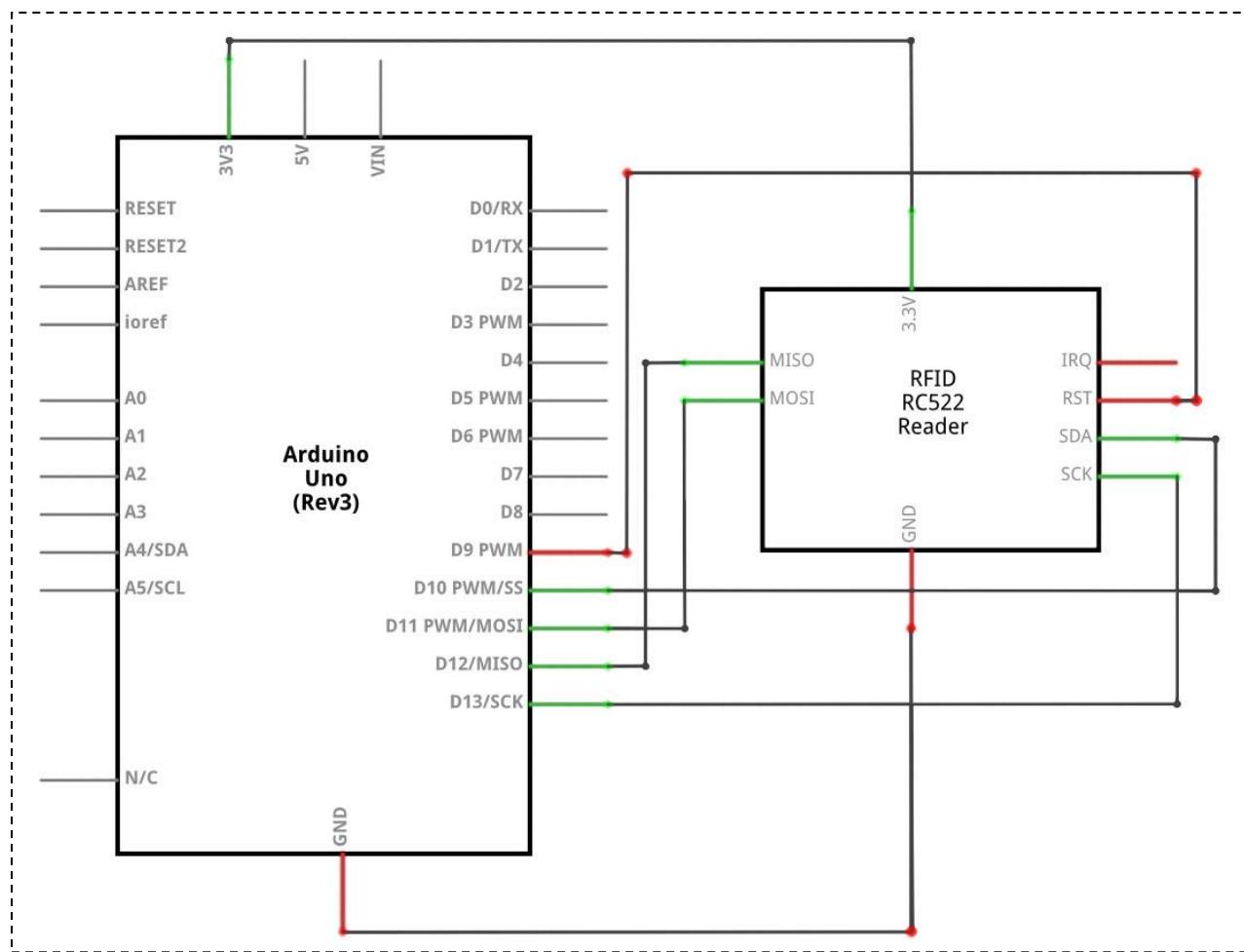
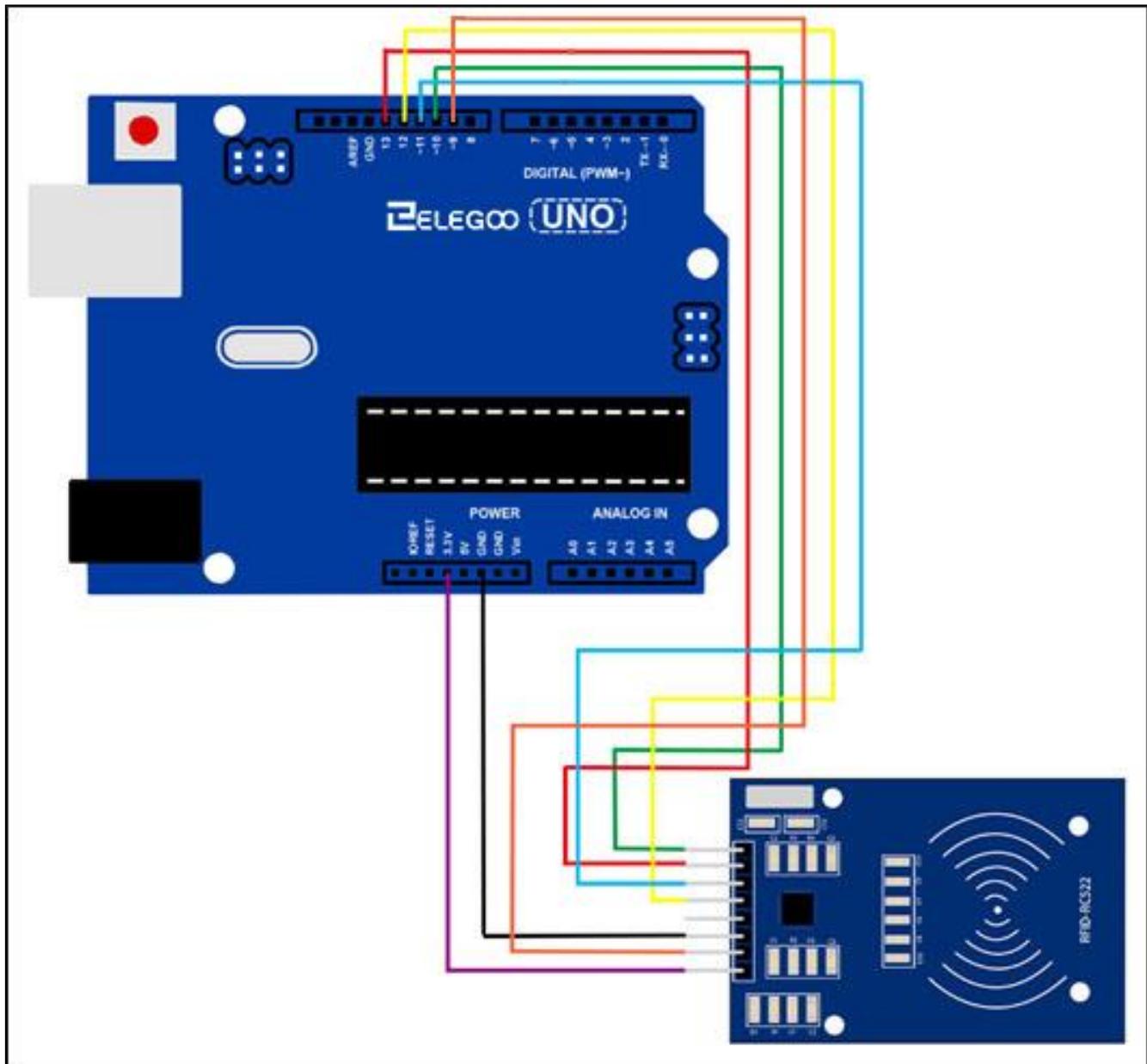


Fig 32. Typical Application CircuitDiagram

## Connection

### Schematic

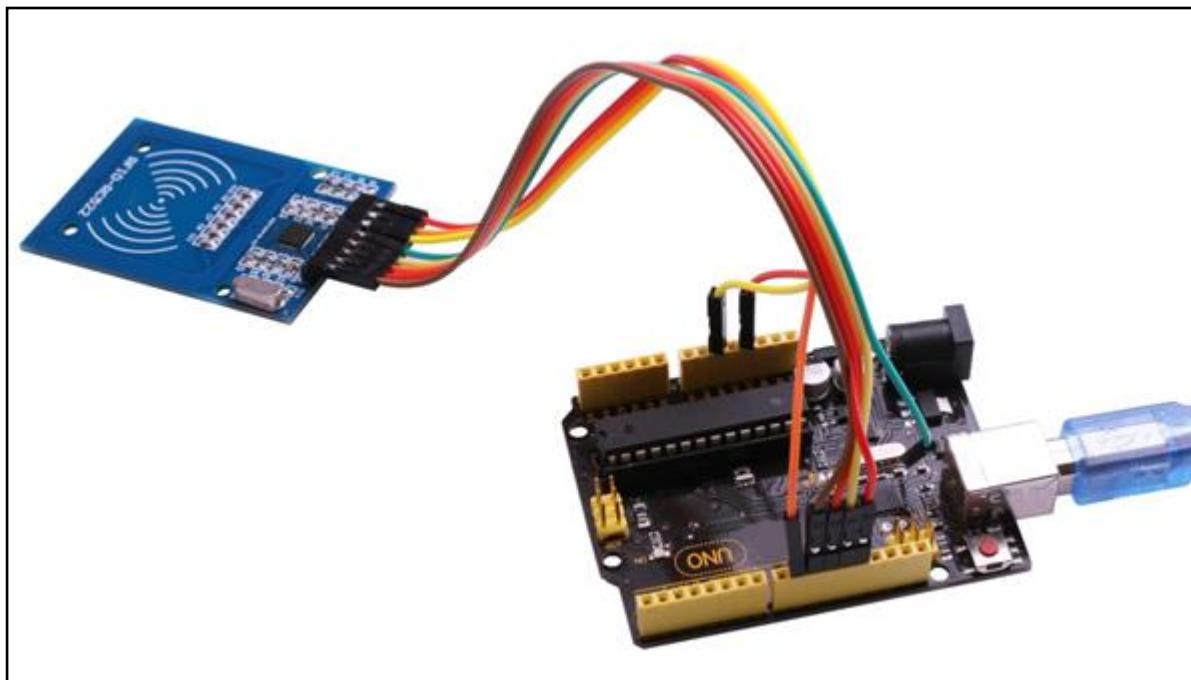
**wiring diagram**



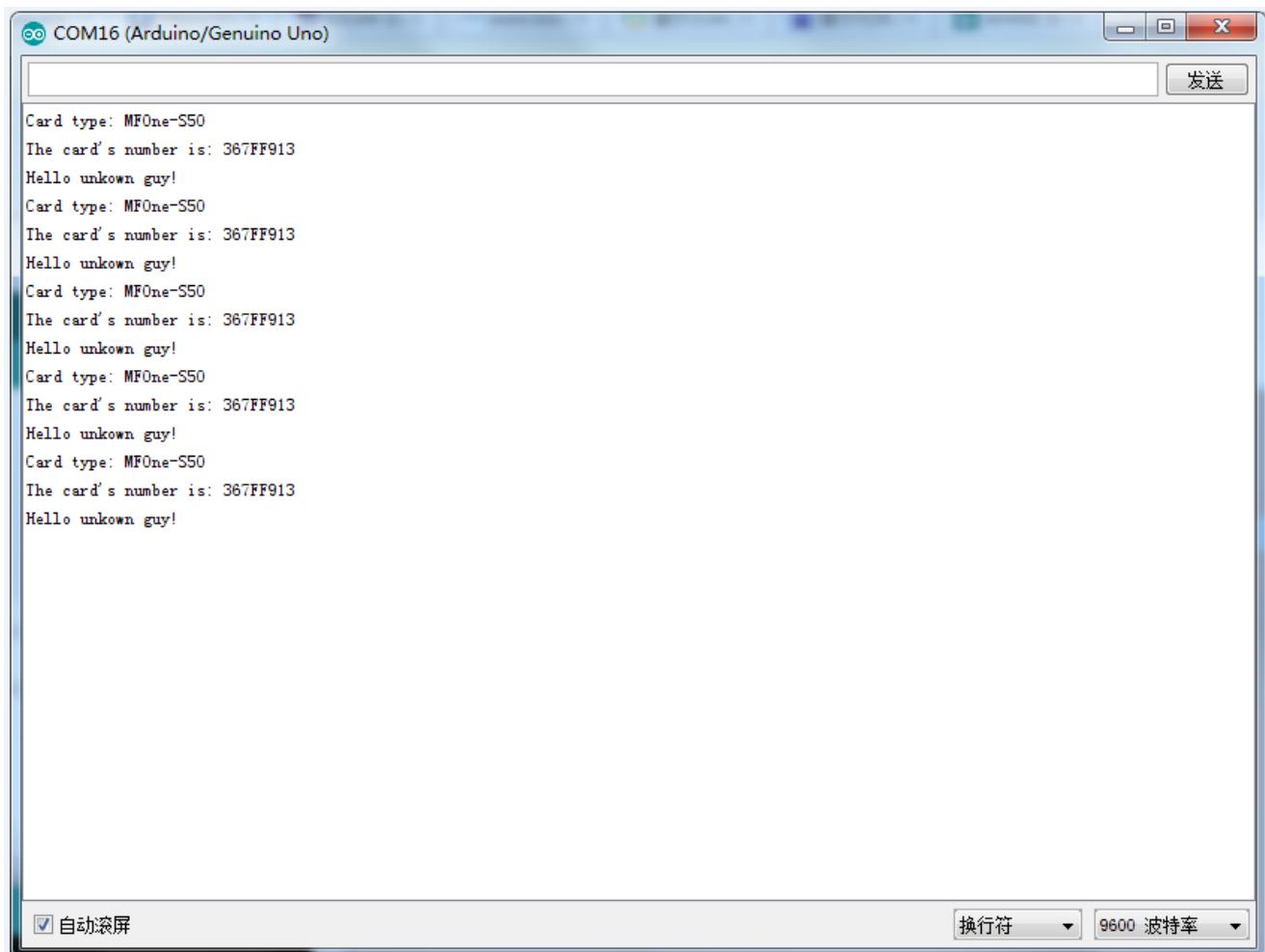
## Code

Now that we have the physical setup, all we need now is the code.

Before you can run this, make sure that you have installed the <rfid> library or re-install it, if necessary. Otherwise, your code won't work.



open the monitor you can see the data as blow:



```
Card type: MFOne-S50
The card's number is: 367FF913
Hello unkown guy!
Card type: MFOne-S50
The card's number is: 367FF913
Hello unkown guy!
Card type: MFOne-S50
The card's number is: 367FF913
Hello unkown guy!
Card type: MFOne-S50
The card's number is: 367FF913
Hello unkown guy!
```

自动滚屏      换行符      9600 波特率

# Lesson 30 DC Motors

## Overview

In this lesson, you will learn how to control a small DC motor using an UNO R3 and a transistor.

## Component Required:

(1) x Elegoo Uno R3

(1) x Breadboard

(1) x 6v dc motor

(1) x PN2222

(1) x 1N4007

(1) x 220 ohm resistor

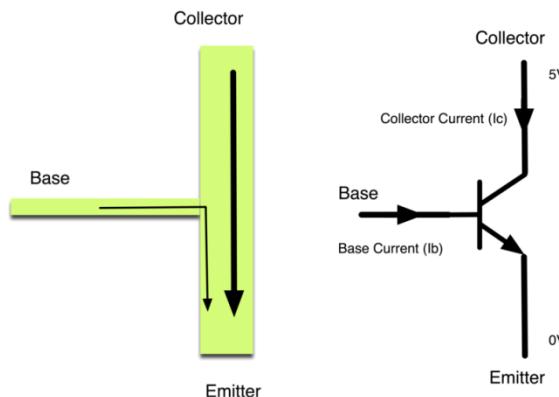
(3) x M-M wires

## Component Introduction

### TRANSISTORS

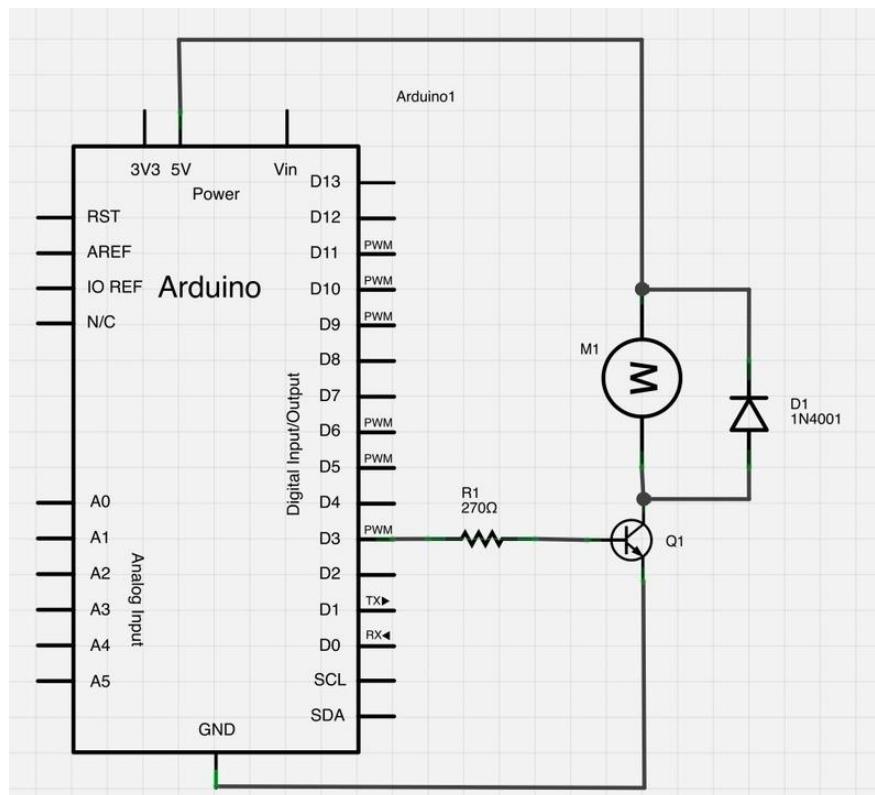
The small DC motor is likely to use more power than an UNO R3 board digital output can handle directly. If we tried to connect the motor straight to an UNO R3 board pin, there is a good chance that it could damage the UNO R3 board.

A small transistor like the PN2222 can be used as a switch that uses just a little current from the UNO R3 board digital output to control the much bigger current of the motor.



The transistor has three leads. Most of the electricity flows from the Collector to the Emitter, but this will only happen if a small amount is flowing into the Base connection. This small current is supplied by the UNO R3 board digital output.

Below is called a schematic diagram of the . Like a breadboard layout, it is a way of showing how the parts of an electronic project are connected together.



The pin D3 of the UNO R3 board is connected to the resistor. Just like when using an LED, this limits the current flowing into the transistor through the base.

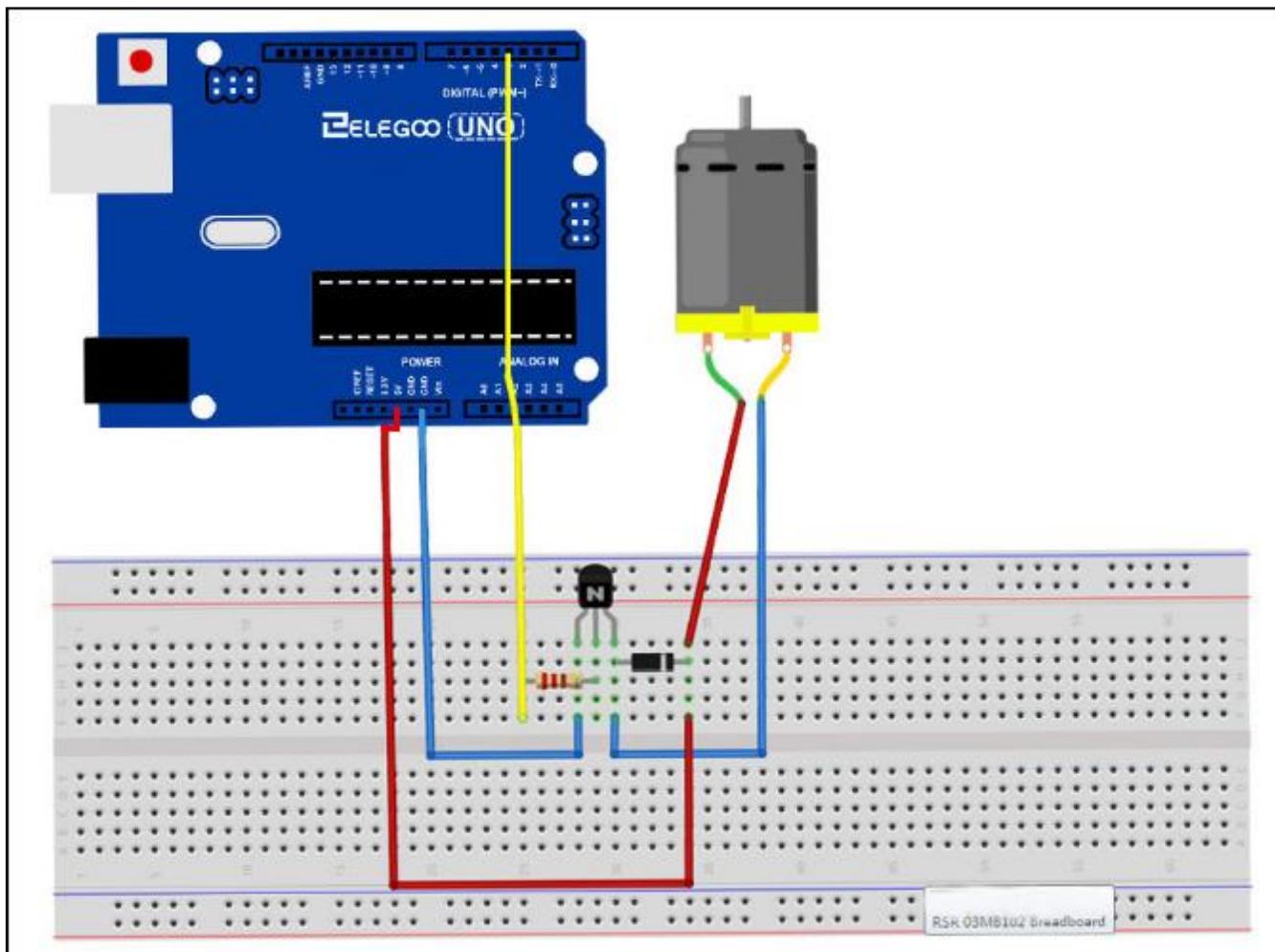
There is a diode connected across the connections of the motor. Diodes only allow electricity to flow in one direction (the direction of their arrow).

When you turn the power off to a motor, you get a negative spike of voltage, that can damage your UNO R3 board or the transistor. The diode protects against this, by shorting out any such reverse current from the motor.

Through this experiment, you've learned how to drive LCD1602. Now you can create your own messages to display! You can also try letting your LCD1602 display numbers.

## Connection

### wiring diagram



You will use an UNO R3 board analog output (PWM) to control the speed of the motor by sending a number between 0 and 255 from the Serial Monitor.

When you put together the breadboard, there are two things to look out for.

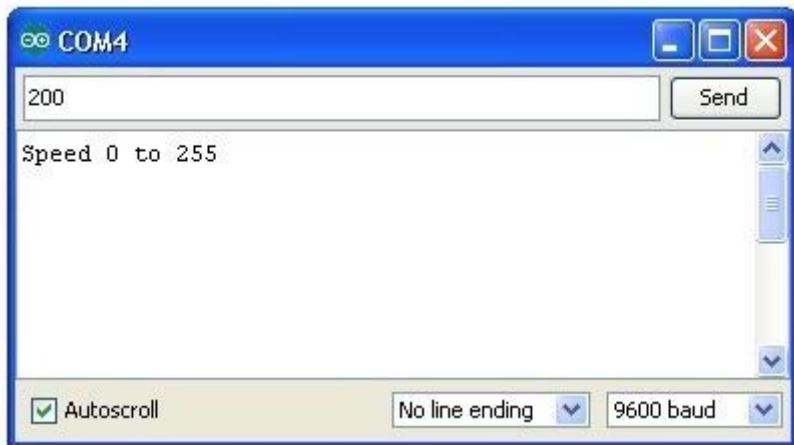
First, make sure that the flat side of the transistor is on the right-hand side of the breadboard.

Second, the striped end of the diode should be towards the +5V power line - see the image below!

The motor that comes with the kits does not draw more than 250mA but if you have a different motor, it could easily draw 1000mA, more than a USB port can handle! If you aren't sure of a motor's current draw, power the UNO R3 board from a wall adapter, not just USB.

The transistor acts like a switch, controlling the power to the motor, UNO R3 board pin 3 is used to turn the transistor on and off and is given the name 'motorPin' in the sketch.

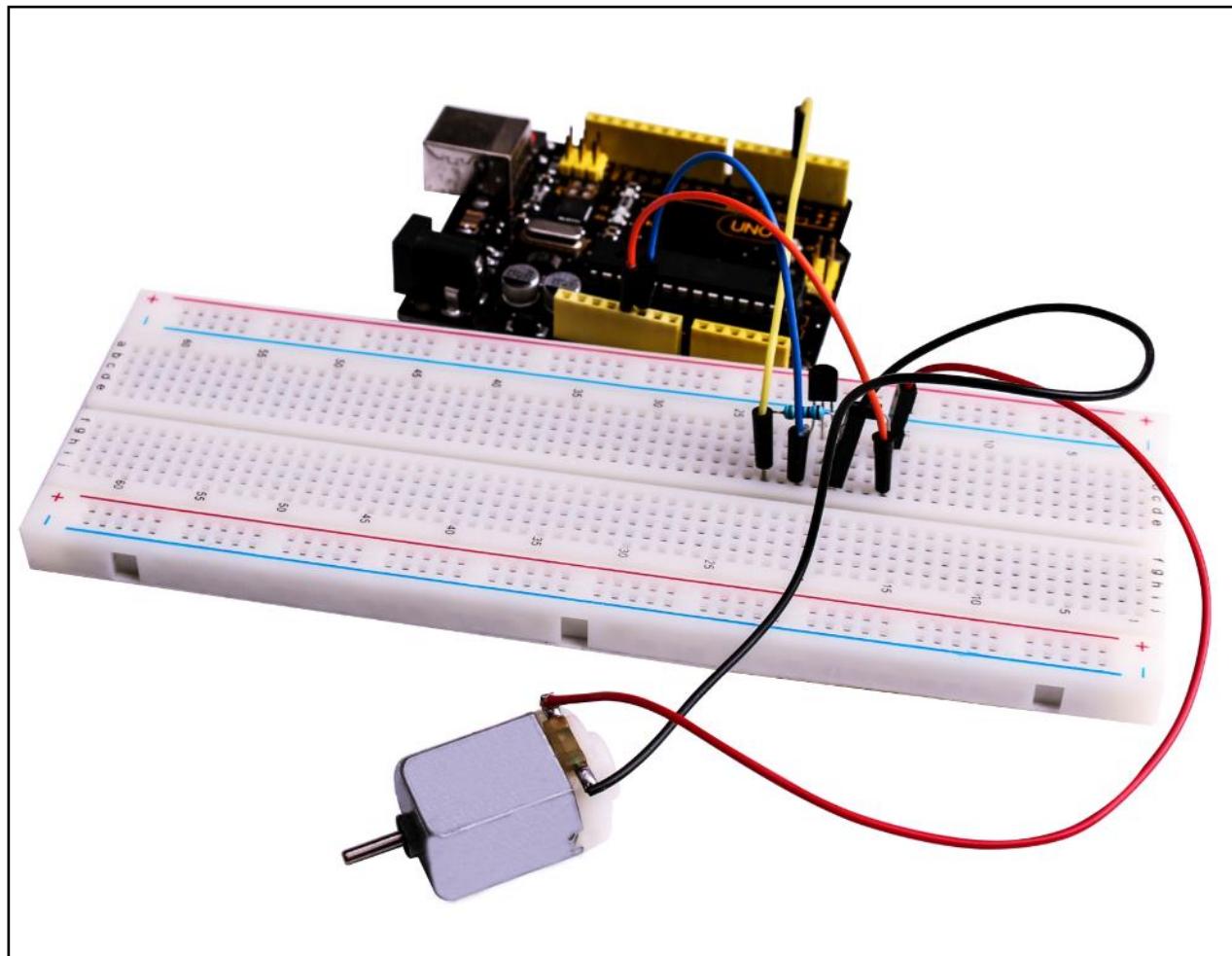
When the sketch starts, it prompts to remind you that to control the speed of the motor, you need to enter a value between 0 and 255 in the Serial Monitor.



In the 'loop' function, the command 'Serial.parseInt' is used to read the number entered as text in the Serial Monitor and convert it into an 'int'.

You could type any number here, so the 'if' statement on the next line only does an analog write with this number if the number is between 0 and 255.

## Code



# Lesson 31 Stepper Motor

## Overview

In this lesson, you will learn a fun and easy way to drive a stepper motor.

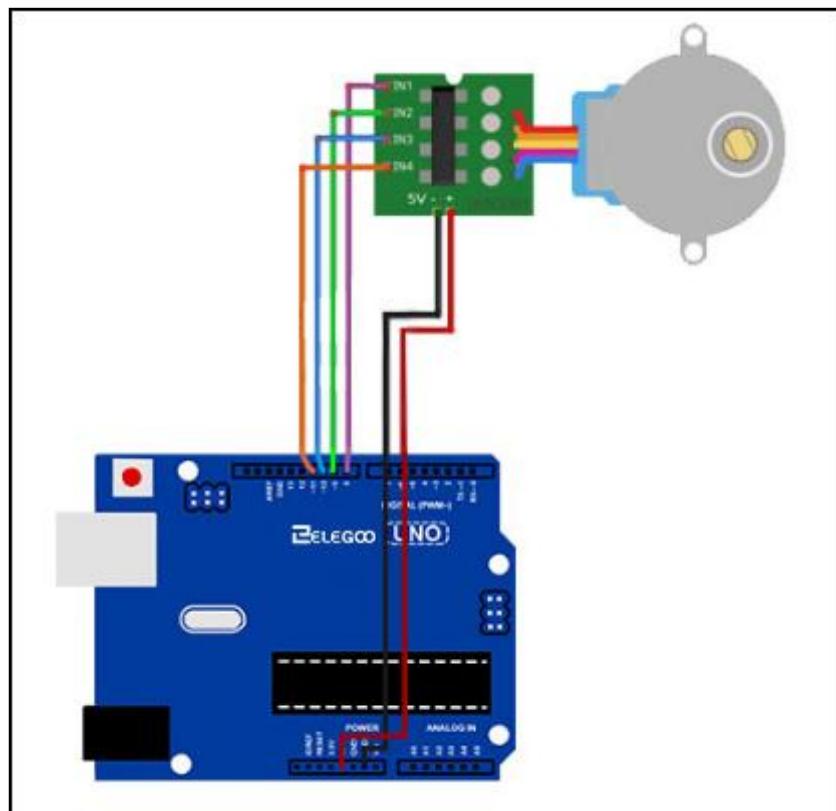
The stepper we are using comes with its own driver board making it easy to connect to our UNO.

## Component Required:

- (1) x Elegoo Uno R3
- (1) x Uln2003 stepper motor driver module
- (1) x Stepper motor
- (9) x F-M wires

## Connection

### wiring diagram



We are using 4 pins to control the Stepper.

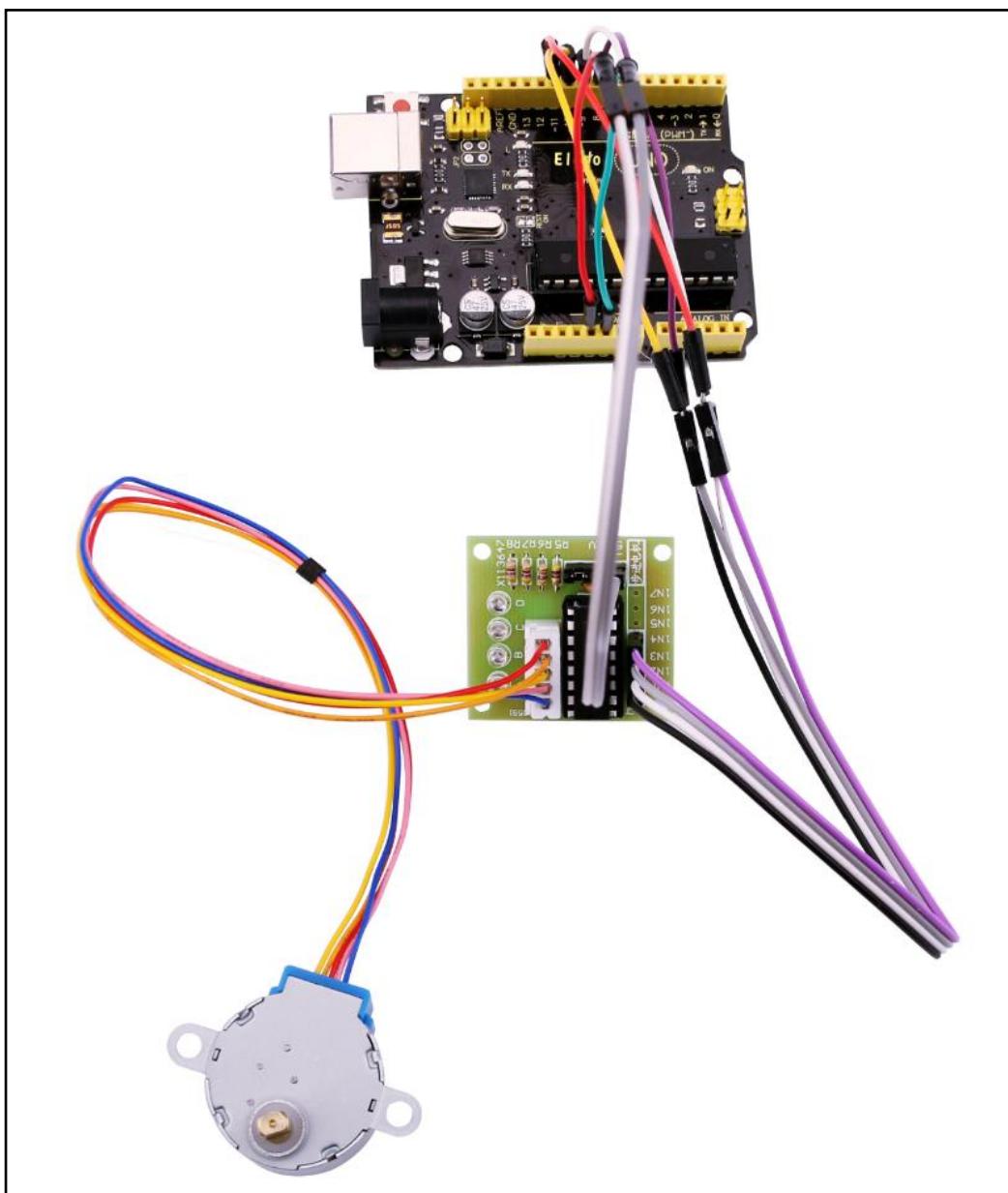
Pin 8-11 are controlling the Stepper motor.

We connect the 5V and Ground from to UNO to the Stepper motor.

## Code

Now that we have the physical setup, all we need now is the code.

Before you can run this, make sure that you have installed the <Stepper\_Motor\_Control> library or re-install it, if necessary. Otherwise, your code won't work.



# Lesson 32 Controlling Stepper Motor With Remote

## Overview

In this lesson, you will learn a fun and easy way to control a stepper motor from a distance using an IR remote control.

The stepper we are using comes with its own driver board making it easy to connect to our UNO.

Since we don't want to drive the motor directly from the UNO, we will be using an inexpensive little breadboard power supply that plugs right into our breadboard and power it with a 9V 1Amp power supply.

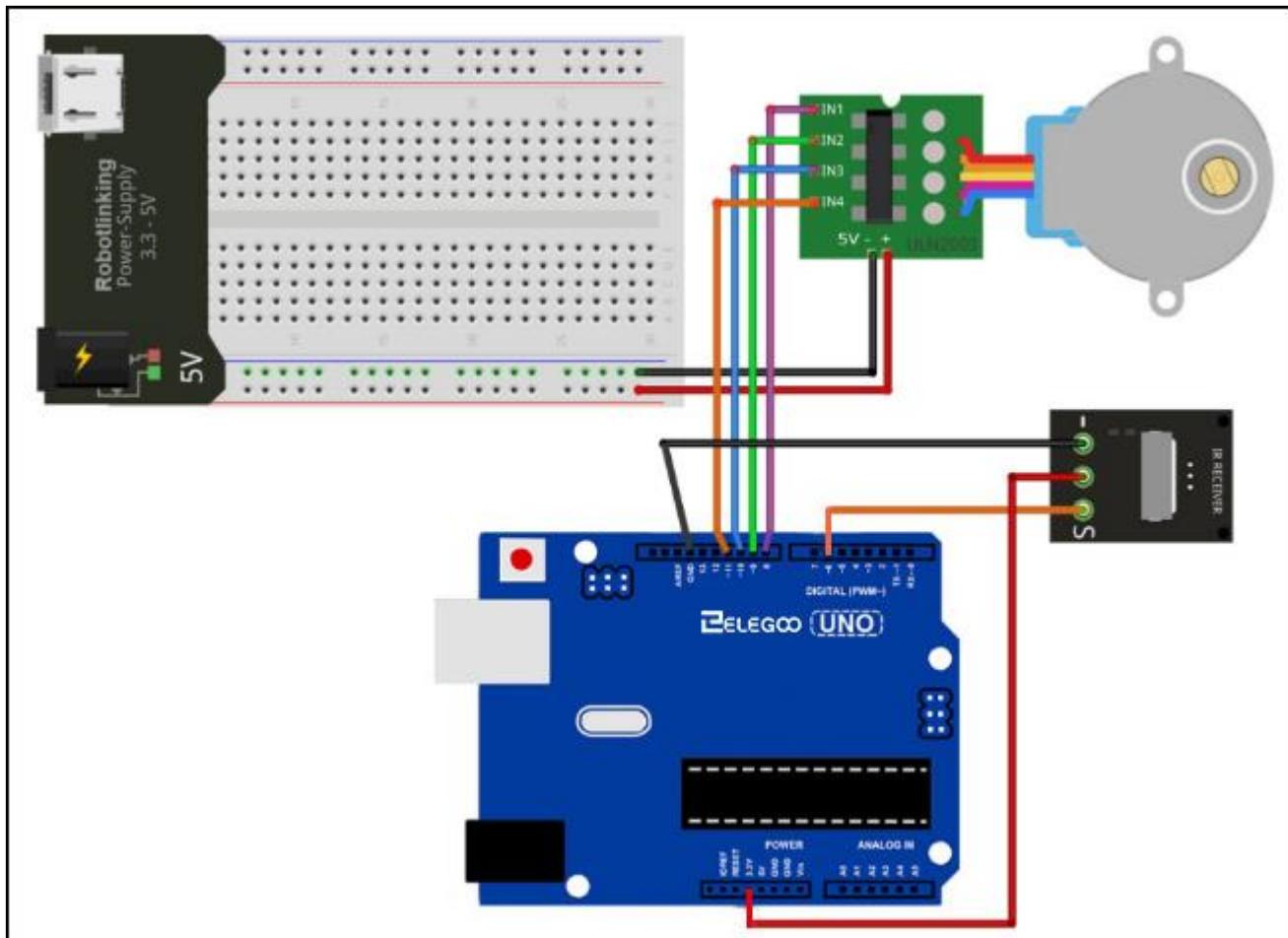
The IR sensor is connected to the UNO directly since it uses almost no power.

## Component Required:

- (1) x Elegoo Uno R3
- (1) x Breadboard
- (1) x IR receiver module
- (1) x IR remote
- (1) x ULN2003 stepper motor driver module
- (1) x Stepper motor
- (1) x Power supply module
- (1) x Adapter
- (9) x F-M wires

## Connection

### wiring diagram



We are using 4 pins to control the Stepper and 1 pin for the IR sensor.

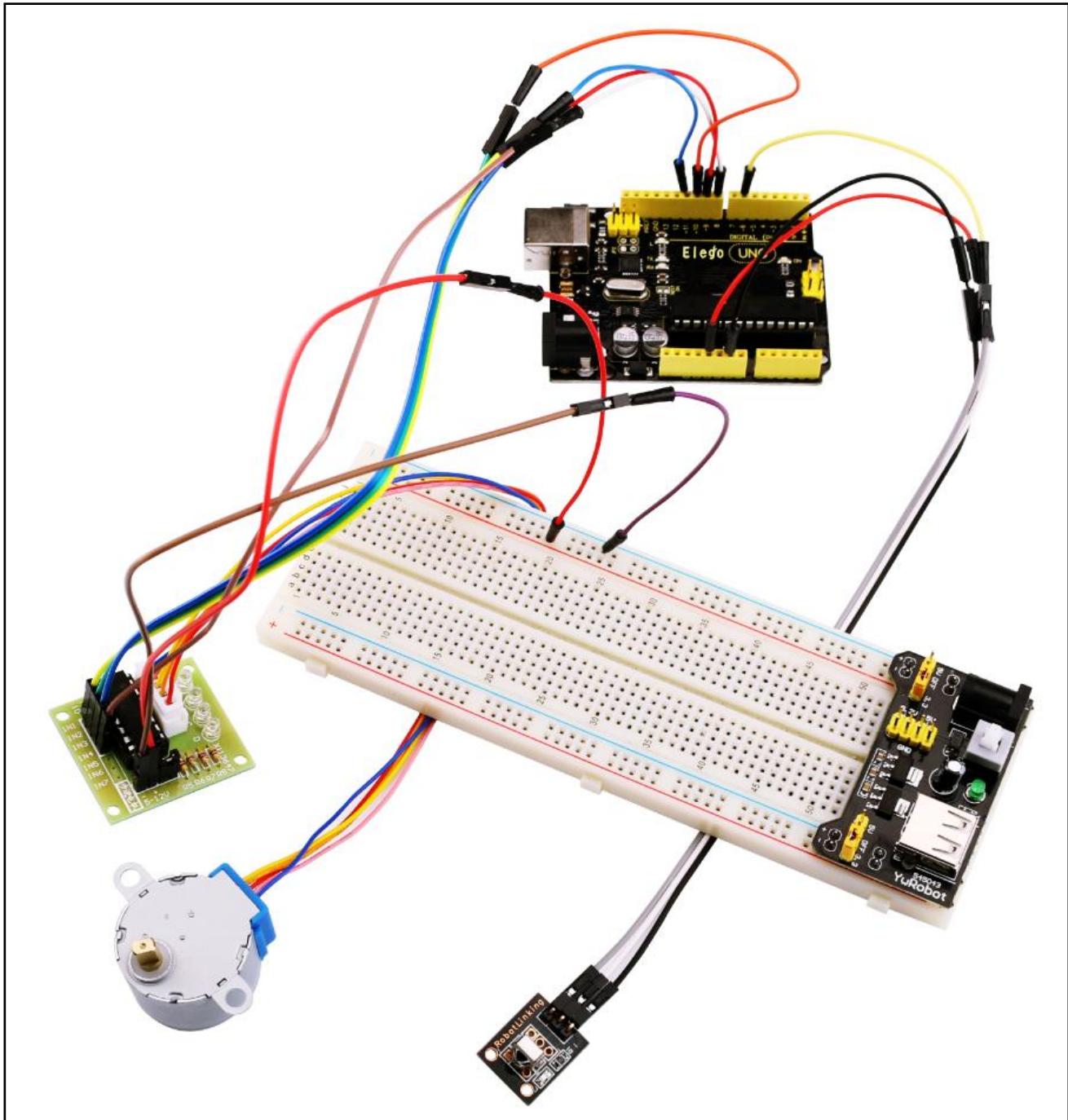
Pins 8-11 are controlling the Stepper motor and pin 6 is receiving the IR information.

We connect the 5V and Ground from the UNO to the sensor. As a precaution, use a breadboard power supply to power the stepper motor since it can use more power and we don't want to damage the power supply of the UNO.

## Code

Now that we have the physical setup, all we need now is the code.

Before you can run this, make sure that you have installed the `<IRremote>` `<Stepper_Motor_Control>` library or re-install it, if necessary. Otherwise, your code won't work.



# Lesson 33 Controlling Stepper Motor With Encoder

## Overview

In this multi-part lesson, you will learn how to control different stepper motors using a rotary encoder.

In this first part, we will use the inexpensive and popular stepper motor that comes with its own control board: the 28BYJ-48 stepper motor with the ULN2003 board.

The 28BYJ-48 motor is not very fast or very strong, but it's great for beginners to start experimenting with controlling a stepper motor with an Arduino.

We will write some code to have the motor move in the direction that we turn the rotary encoder, and will also keep track of how many steps we have taken, so that we can have the motor move back to the starting position by pressing down on the rotary encoder switch.

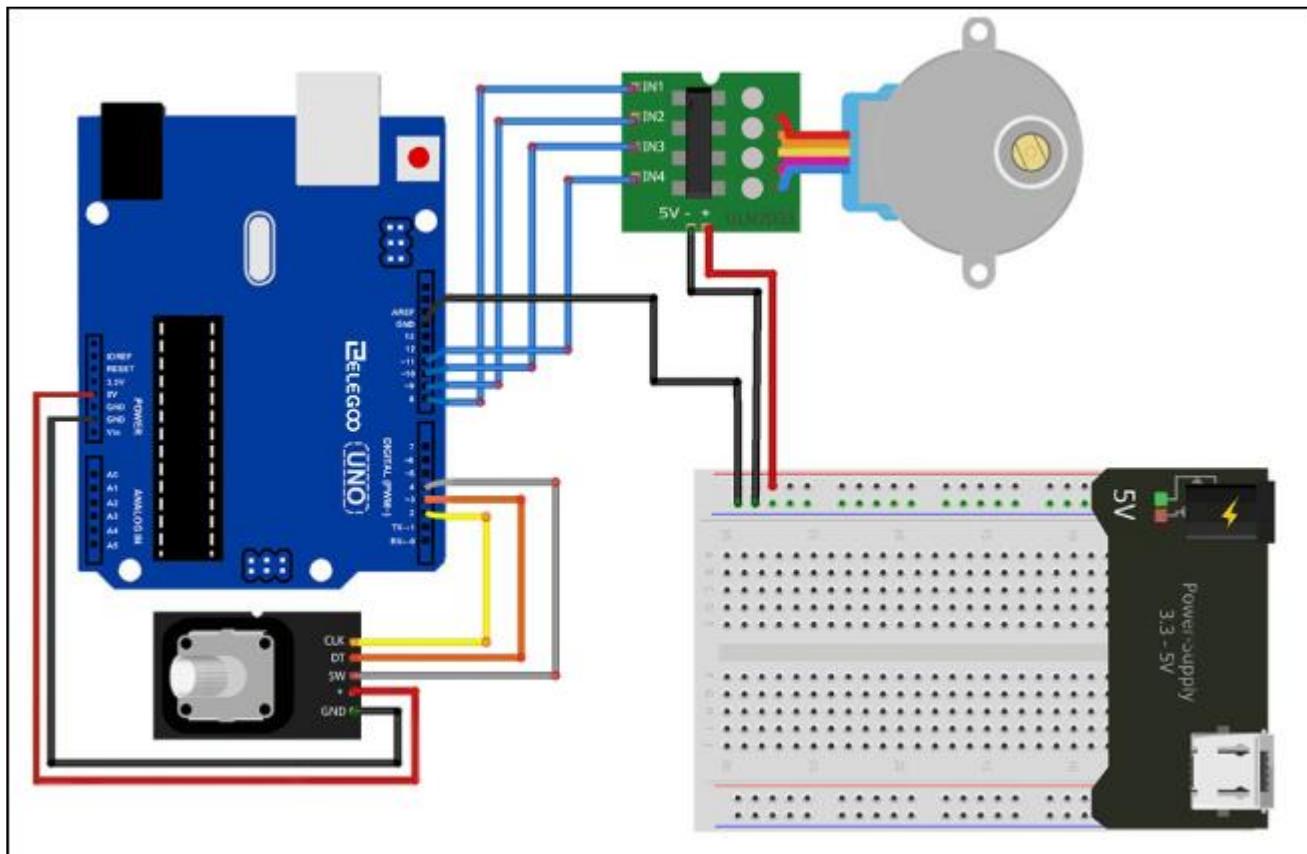
For the next part, we will use a Nema 17 stepper motor and the EasyDriver board.

## Component Required:

- (1) x Elegoo Uno R3
- (1) x Breadboard
- (1) x Rotary Encoder
- (1) x ULN2003 stepper motor driver module
- (1) x Stepper motor
- (1) x Power supply module
- (1) x Adapter
- (9) x F-M wires

## Connection

### wiring diagram



We are using 4 pins to control the Stepper and 3 pins for the rotary encoder module.

Pins 8-11 are controlling the Stepper motor and pins 2-4 are receiving information from the rotary encoder.

We connect the 5V and Ground from to UNO to the rotary encoder and as a precaution, use a breadboard power supply to power the stepper motor since it can use more power than the UNO can provide.

We also connect the UNO Ground to the breadboard to serve as a reference.

## Code

**Now that we have the physical setup, all we need now is the code.**

**Before you can run this, make sure that you have installed the <Stepper\_Motor\_Control> library or re-install it, if necessary. Otherwise, your code won't work.**

We are using some variables to store the current position, since we want to keep track of the position of the stepper motor so we can make it move back to the starting position.

We also included some error checking code to make sure that the rotary encoder is not missing steps, since that would make our motor position inaccurate.

