A Original IDE Algorithm

Algorithm 4 Original IDE algorithm from [21]. Shortened version of the ForwardCompute-JumpFunctionsSLRPs procedure.

```
1  while PathWorkList ≠ ∅ do
2      Select and remove an item ⟨s_p, d_1⟩ → ⟨n, d_2⟩ from PathWorkList;
3      f ⟵ JumpFn(⟨s_p, d_1⟩ → ⟨n, d_2⟩);
4      switch n do
5          case n is call node in p calling a procedure q do
6              foreach d_3 s.t. ⟨n, d_2⟩ → ⟨s_q, d_3⟩ ∈ E^# do
7                  Propagate(⟨s_q, d_3⟩ → ⟨s_q, d_3⟩ , λx.x);
8              r ⟵ return-site node for n;
9              foreach d_3 s.t. e = ⟨n, d_2⟩ → ⟨r, d_3⟩ ∈ E^# do
10                 Propagate(⟨s_p, d_1⟩ → ⟨r, d_3⟩ , EdgeFn(e) ∘ f);
11             foreach d_3 s.t. f_3 = SummaryFn(⟨n, d_2⟩ → ⟨r, d_3⟩) ≠ λx.⊤ do
12                 Propagate(⟨s_p, d_1⟩ → ⟨r, d_3⟩ , f_3 ∘ f);
13         case n is exit node of p do
14             foreach call node c calling p do
15                 r ⟵ return-site for c;
16                 foreach d_4, d_5 s.t. ⟨c, d_4⟩ → ⟨s_p, d_1⟩ ∈ E^# ∧ ⟨e_p, d_2⟩ → ⟨r, d_5⟩ ∈ E^# do
17                     ...
18                     if f' ≠ SummaryFn(⟨c, d_4⟩ → ⟨r, d_5⟩) then
19                         SummaryFn(⟨c, d_4⟩ → ⟨r, d_5⟩) ⟵ f';
20                         s_q ⟵ start node of c's procedure;
21                         foreach d_3 s.t. f_3 = JumpFn(⟨s_q, d_3⟩ → ⟨c, d_4⟩) ≠ λx.⊤ do
22                             Propagate(⟨s_q, d_3⟩ → ⟨r, d_5⟩ , f' ∘ f_3);
23         otherwise do
24             foreach m, d_3 s.t. ⟨n, d_2⟩ → ⟨m, d_3⟩ ∈ E^# do
25                 Propagate(⟨s_p, d_1⟩ → ⟨m, d_3⟩ , EdgeFn(⟨n, d_2⟩ → ⟨m, d_3⟩) ∘ f);
26 end
```

Algorithm 5 The Propagate procedure from the original IDE algorithm [21].

```
1  Procedure Propagate(e, f)
2      let f' = f ⊓ JumpFn(e);
3      if f' ≠ JumpFn(e) then
4          JumpFn(e) := f';
5          Insert e into PathWorkList;
```

Algorithm 6 Phase II of the original IDE algorithm [21]

```
1  Procedure ComputeValues()
       // Phase II.i (value propagation)
2      foreach (n, d) ∈ N × D do val(n, d) ⟵ ⊤;
3      val(s_main, Λ) ⟵ ⊥;
4      NodeWorkList ⟵ {(s_main, Λ)};
5      while NodeWorkList ≠ ∅ do
6          Select and remove an ESG node (n, d) from NodeWorkList;
7          switch n do
8              case n is start node of p do
9                  foreach call node c inside p do
10                     foreach d' s.t. f' = JumpFn(⟨n, d⟩ → ⟨c, d'⟩) ≠ λℓ.⊤ do
11                         PropagateValue(c, d', f'(val(s_p, d)));
12             case n is call node in p, calling q do
13                 foreach d' s.t. ⟨n, d⟩ → ⟨s_q, d'⟩ ∈ E# do
14                     PropagateValue(s_q, d', EdgeFn(⟨n, d⟩ → ⟨s_q, d'⟩)(val(n, d)));
       // Phase II.ii (value computation)
15     foreach node n in procedure p, that is not call or start node do
16         foreach d, d' s.t. f' = JumpFn(⟨s_p, d'⟩ → ⟨n, d⟩) ≠ λℓ.⊤ do
17             val(n, d) ⟵ val(n, d) ⊓ f'(val(s_p, d'));
```

Algorithm 7 The PropagateValue procedure from the original IDE algorithm [21]

```
1  Procedure PropagateValue(n, d, v)
2      v' ⟵ v ⊓ val(n, d);
3      if v' ≠ val(n, d) then
4          val(n, d) ⟵ v';
5          Insert (n, d) into NodeWorkList;
```