

01. Intro

What is

1. Supervised Learning - Classification/Regression
2. Unsupervised - Kmeans, PCA
3. Reinforcement - Giving rewards and punishment

Linear regression

- Data - tuples of points $\{(x_n, t_n)\}_{0 \rightarrow N}$
- Model - $y = w_0 + xw_1$
- Loss - Mean square error $\frac{1}{2} \sum_{n=1}^N (y_n - t_n)^2$
- Derivative to find lowest point to find w
- $t_n = [x_n][w_n]^T$

Non-Linear regression

- Basis factor expansion $x \rightarrow [x, x^2, x^3 \dots, x^P]$
- Find weights for each polynomial/exponential/..
- Note that minimization of error function has a unique solution
 - Unique weight that optimises the model

Regularization

Ridge regression solution

- Add regularizer $(\frac{\lambda}{2} ||w||^2)$ to error function
 - Lambda is a constant
 - smaller = error matters more
 - larger = penalise weights more

02. Regression II

- $t_n = y(x_n, w) + \epsilon$
 - ϵ is random "noise" modelled via some distribution
- Assumption is that each point is IID
 - Independently identically distributed variables
- MLE is a generalised model estimator given a set of data and predicted distribution

Examples

- MSE is a loss function for MLE assuming data is normally distributed
- Variance of gaussian known but mean is unknown
- Model used to derive mean and minimise loss/maximum likelihood

Bayesian Linear Regression

- $\text{posterior} = \frac{\text{likelihood} \times \text{prior}}{\text{evidence}} = \frac{p(y|w)p(w)}{p(y)}$
- Repeatedly updating model based on additional data points
- Initial estimator (prior) that can be modelled in different distributions
 - By CLM, posterior distribution becomes independent to prior
 - Prior models normal distribution
- Maximum-a-Posteriori estimation (MAP)
 - For given prior, after observing data, how to update distr of params?
 - Adds "regularisation" component to normally distributed datasets

03. Linear classification

- Binary splitting of points to classify them (separation line is linear)

Bernoulli Distribution

- Binary possibilities with a probability of $p(t = 1) = \mu$
- $E[t] = \mu, \text{var}[t] = \mu(1 - \mu)$

Activation function

- Squashing function that constraints output to distinct classes

Logistic sigmoid

- formula: $\sigma(z) = \frac{1}{1 + \exp(-Z)}$
 1. $\sigma(-z) = 1 - \sigma(z)$
 2. $z = \lg(\frac{\sigma(z)}{1 - \sigma(z)})$ (log odds)
 3. $\frac{d\sigma(z)}{dz} = \sigma(z)(1 - \sigma(z))$

Approach

Data Logistic sigmoid on $w^T \phi_n$

- Note that $T_n \in \{0, 1\}$ and $y_n = \sigma(w^T \phi_n)$

Model Bayesian model with Bernoulli likelihood and Normal prior

- Likelihood: $y_n^{t_n} (1 - y_n)^{1 - t_n}$
- Prior: $p(w) \sim N(w|0, \frac{1}{\alpha} I)$

Loss MAP estimation $\lg(p(w|D))$

- $\text{argmin}_w - [\sum_{n=1}^N t_n \lg y_n + (1 - t_n) \lg(1 - y_n)] + \frac{\alpha}{2} w^T w$
- Cross entropy error encourages y_n to match t_n
- Regulariser continues to prevent overfitting by minimising weights

Solving

- No close form solution so Gradient Descent used on loss function
- $w_{k+1} = w_k - \eta \nabla_w \mathcal{L}(w)$
- $\nabla_w \mathcal{L}(w) = \sum_{n=0}^N (y_n - t_n) \phi_n + \alpha w$