



CI-5313

Arquitectura y Administración de Bases de Datos

Clase 3 – Indices (I)

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Cost of Operations

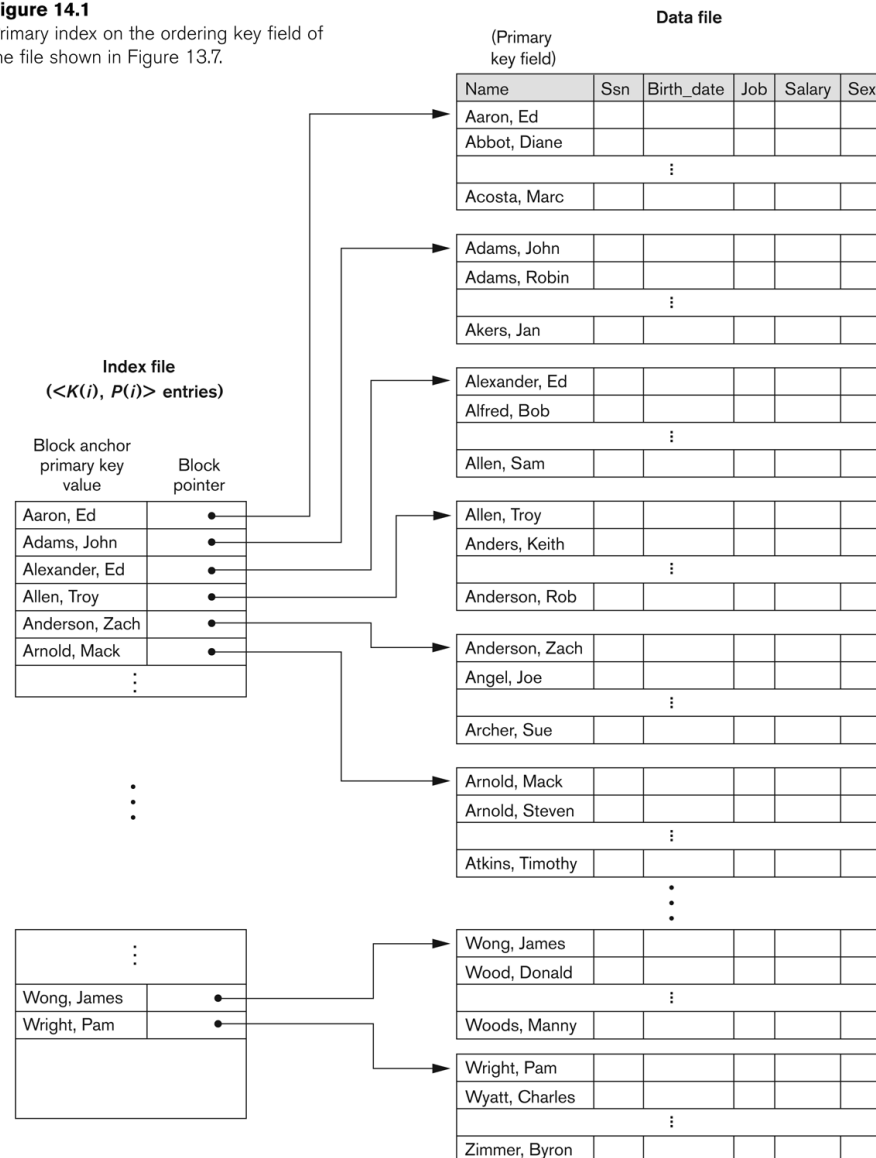
	Heap File	Sorted File	
Scan all recs	BD	BD	1
Equality Search	0.5 BD	$D \log_2 B$	1
Range Search	BD	$D (\log_2 B + \# \text{ of pages with matches})$	1
Insert	2D	Search + BD	2
Delete	Search + D	Search + BD	2

Index

- Data structure that organizes data records on disk.
- An index on a file speeds up selections on the search key fields for the index.
 - Any subset of the fields of a relation can be the search key for an index on the relation.
 - Search key is not the same as key (minimal set of fields that uniquely identify a record in a relation).
- An index contains a collection of data entries, and supports efficient retrieval of all data entries k^* with a given key value k .

Primary index on the ordering key field

Figure 14.1
Primary index on the ordering key field of
the file shown in Figure 13.7.



Index

❖ Three alternatives:

① Data record with key value k

② $\langle k, \text{rid of data record with search key value } k \rangle$

③ $\langle k, \text{list of rids of data records with search key } k \rangle$

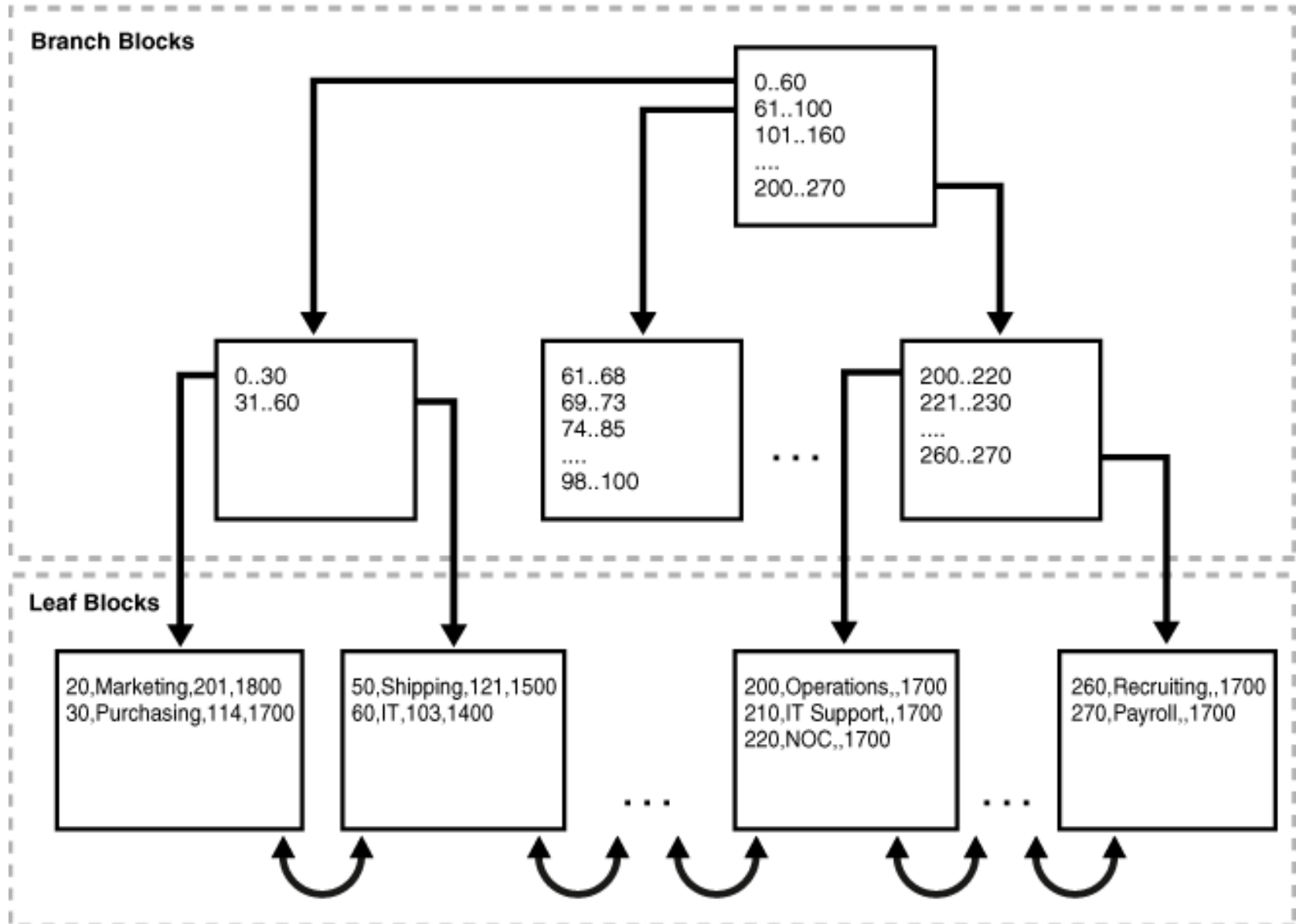
❖ Choice of alternative for data entries is orthogonal to the indexing technique used to locate data entries with a given key value k .

- Examples of indexing techniques: B+ trees, hash-based structures
- Typically, index contains auxiliary information that directs searches to the desired data entries

Archivo "Clustered" - Primera alternativa

- If this is used, index structure is a file organization for data records (like Heap files or sorted files).
- At most one index on a given collection of data records can use Alternative 1. (Otherwise, data records duplicated, leading to redundant storage and potential inconsistency.)
- If data records very large, # of pages containing data entries is high. Implies size of auxiliary information in the index is also large, typically.

Archivo "Clustered" - Primera alternativa



Index – Alternatives 2 and 3 – separate file for index

- ❖ The index file usually occupies considerably less disk blocks than the data file because its entries are much smaller
- ❖ A binary search on a single-level index yields a pointer to the file record
- ❖ Indexes can also be characterized as dense or sparse
 - A dense index has an index entry for every search key value (and hence every record) in the data file.
 - A sparse (or nondense) index, on the other hand, has index entries for only some of the search values

Index example

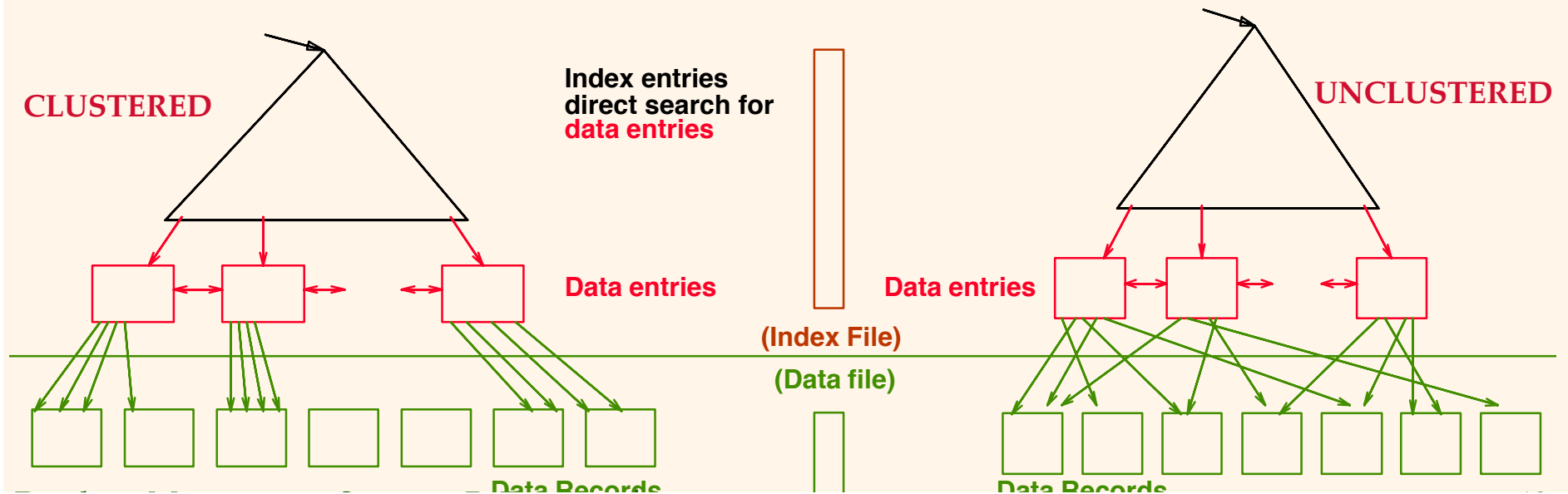
- Example: Given the following data file EMPLOYEE(NAME, SSN, ADDRESS, JOB, SAL, ...)
- Suppose that:
 - record size $R=150$ bytes block size $B=512$ bytes $r=30000$ records
- Then, we get:
 - blocking factor $Bfr = B \div R = 512 \div 150 = 3$ records/block
 - number of file blocks $b = (r/Bfr) = (30000/3) = 10000$ blocks
- For an index on the SSN field, assume the field size $V_{SSN}=9$ bytes, assume the block pointer size $P_B=7$ bytes. Then:
 - index entry size $R_i = (V_{SSN} + P_B) = (9+7) = 16$ bytes
 - index blocking factor $Bfr_i = B \div R_i = 512 \div 16 = 32$ entries/block
 - number of index blocks $b_i = (r / Bfr_i) = (30000/32) = 938$ blocks
 - binary search needs $\log_2 b_i = \log_2 938 = 10$ block accesses
 - This is compared to an average linear search cost of:
 - $(b/2) = 10000/2 = 5000$ block accesses
 - If the file records are ordered, the binary search cost would be:
 - $\log_2 b = \log_2 10000 = 14$ block accesses

Index taxonomies

- Dense vs. Sparse.
- Simple vs. Composite
- Single-level vs. Multi-level (trees).
- Primary vs. Secondary.
 - Primary is index on a key (unique).
 - A secondary index provides a secondary means of accessing a file for which some primary access already exists.
- Clustered vs. Unclustered.
 - If order of data records is the same as, or `close to', order of data entries, then called clustered index.
 - Alternative 1 implies clustered, but not vice-versa.
 - A file can be clustered on at most one search key.
 - Cost of retrieving data records through index varies greatly based on whether index is clustered or not!
- Points to record vs. Points to block

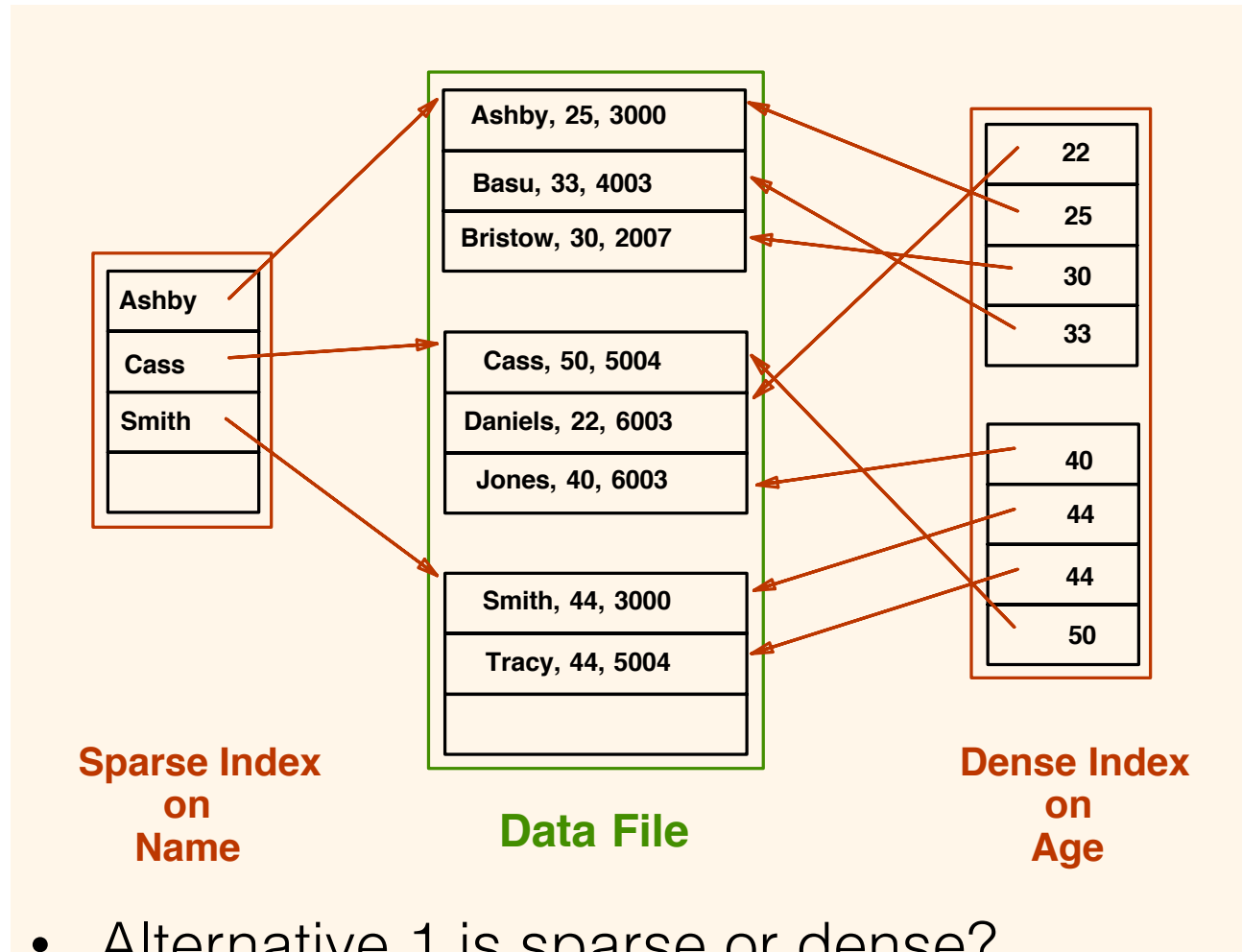
Clustered vs. Unclustered

- To build clustered index, first sort the Heap file (with some free space on each page for future inserts).
- Overflow pages may be needed for inserts. (Thus, order of data recs is 'close to', but not identical to, the sort order.)



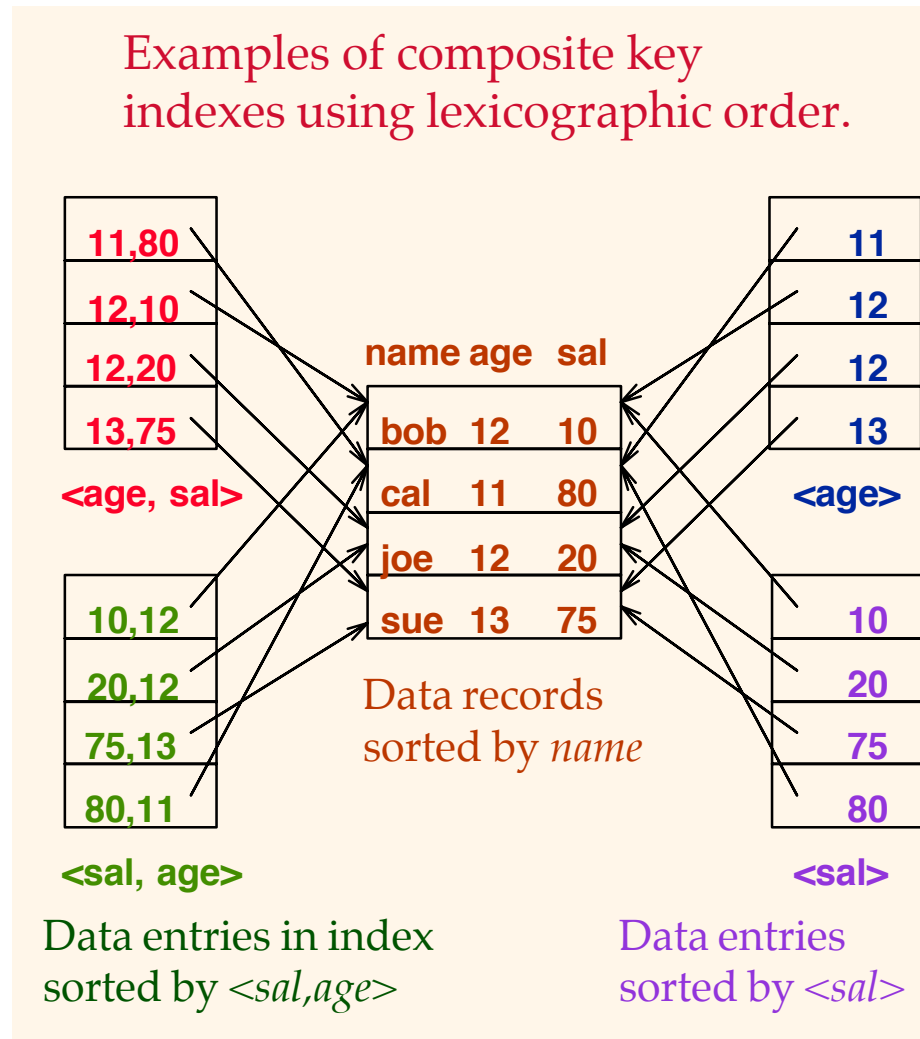
Dense vs. Sparse

- Dense vs. Sparse.



- Alternative 1 is sparse or dense?
- A sparse index is clustered or unclustered?

Example – Category in each taxonomy?



Example – Category in each taxonomy?

DATA FILE

(CLUSTERING
FIELD)

DEPTNUMBER NAME SSN JOB BIRTHDATE SALARY

1					
1					
1					
2					

2					
3					
3					
3					

3					
3					
4					
4					

5					
5					
5					
5					

6					
6					
6					
6					

6					
8					
8					
8					

INDEX FILE
(<K(i), P(i)> entries)

CLUSTERING
FIELD VALUE BLOCK
POINTERS

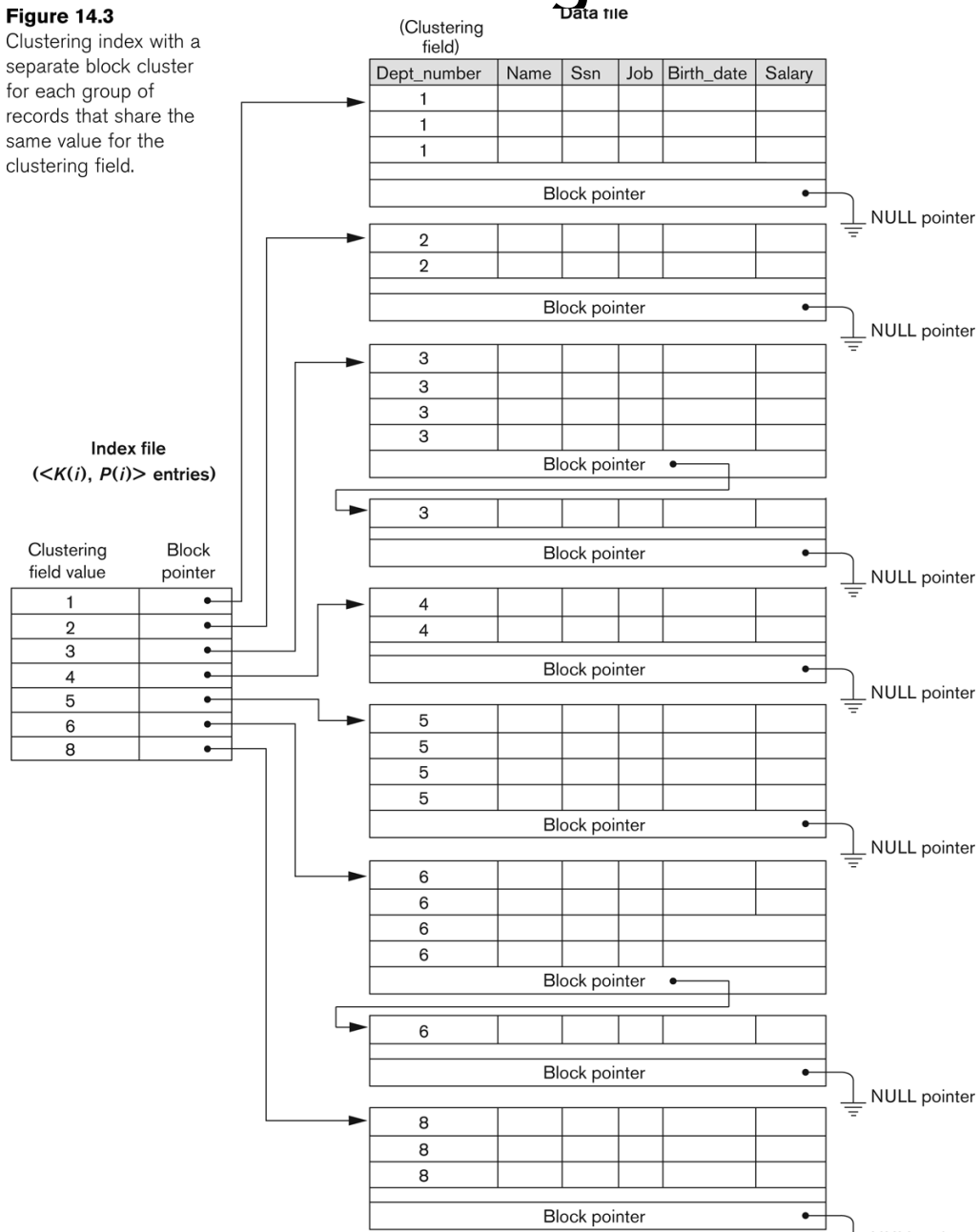
1	•
2	•
3	•
4	•
5	•
6	•
8	•

A clustering index on the DEPTNUMBER ordering non-key field of an EMPLOYEE file.

Another Clustering Index Example

Figure 14.3

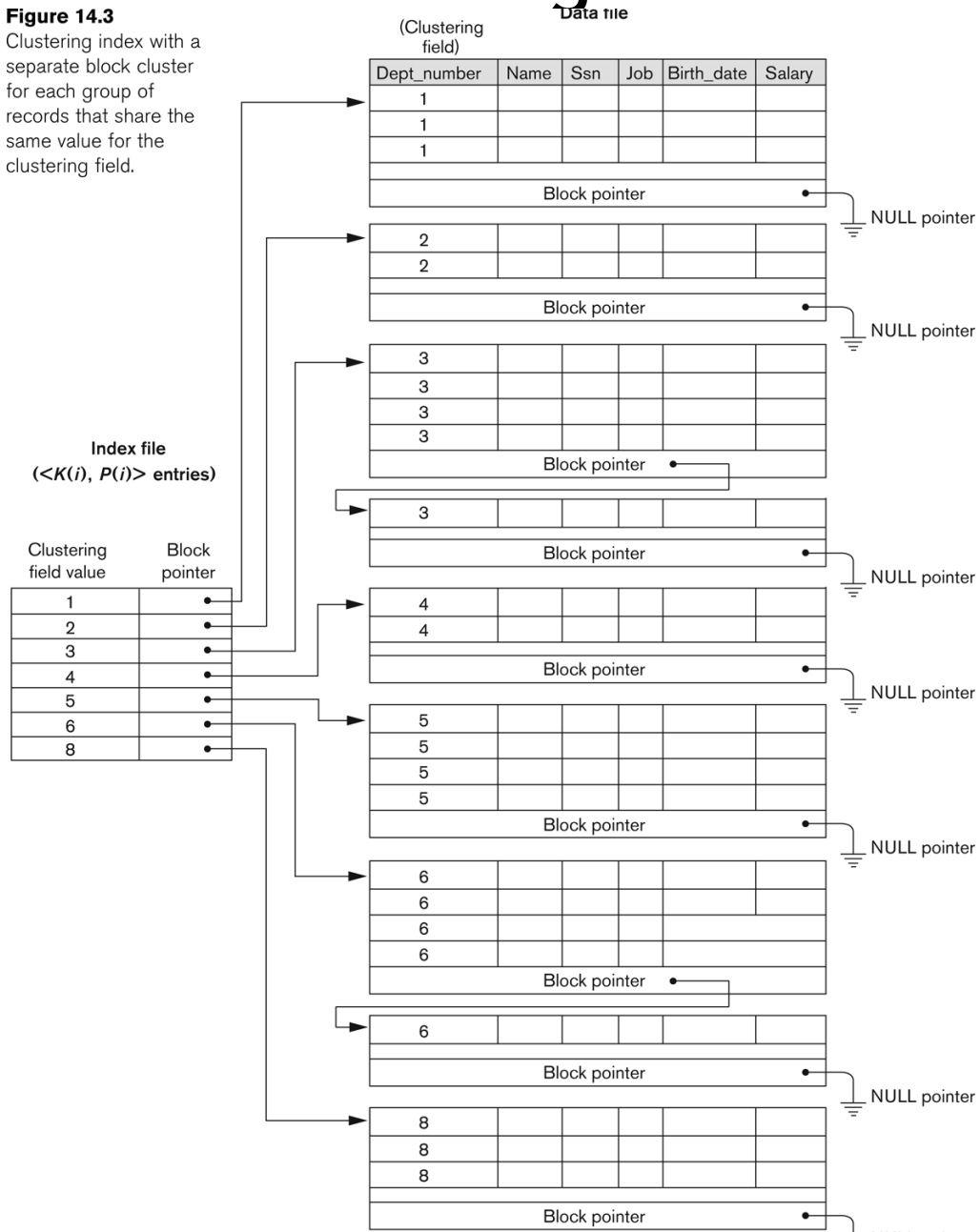
Clustering index with a separate block cluster for each group of records that share the same value for the clustering field.



Another Clustering Index Example

Figure 14.3

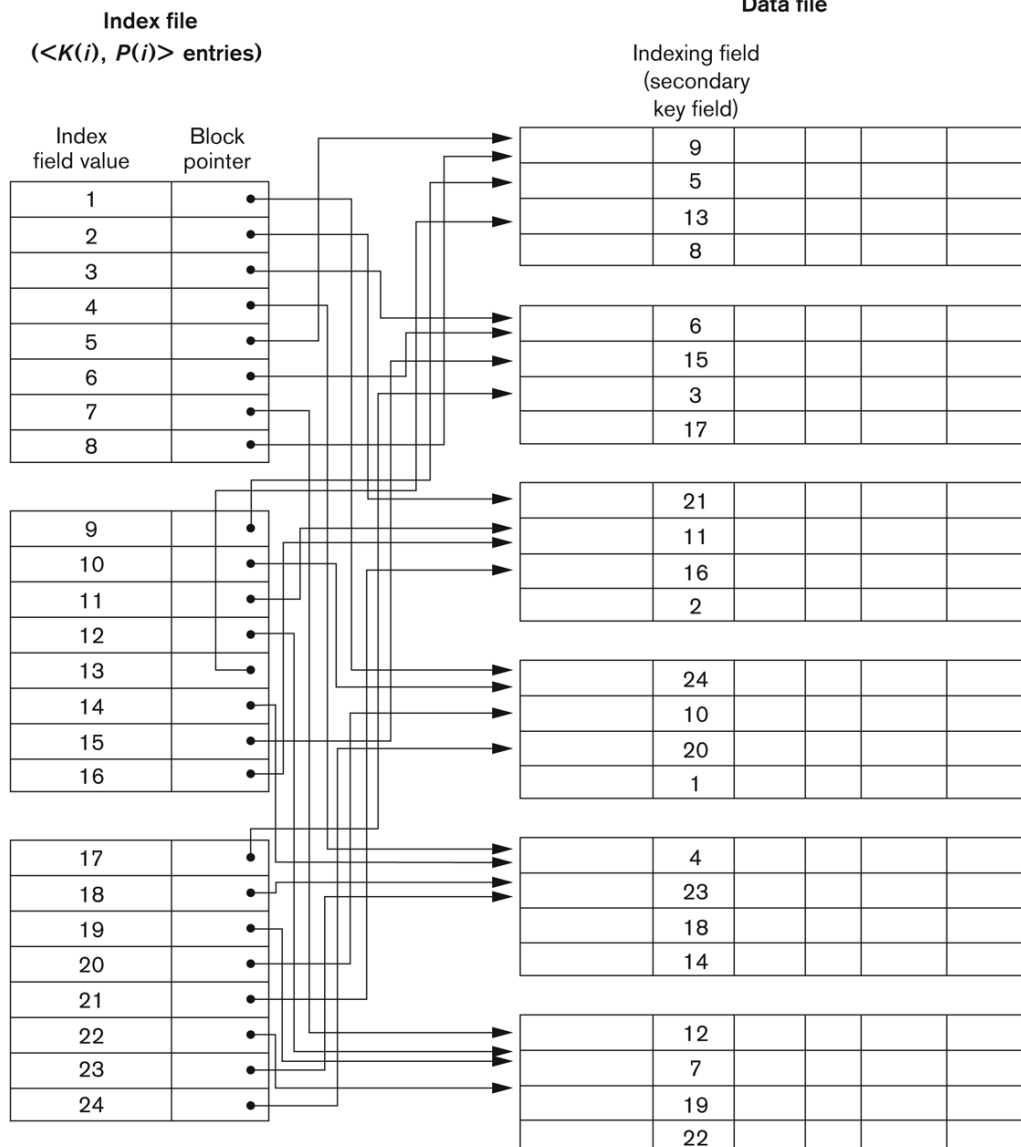
Clustering index with a separate block cluster for each group of records that share the same value for the clustering field.



Dense Scndary Index Example

Figure 14.4

A dense secondary index (with block pointers) on a nonordering key field of a file.



Secondary Index Example

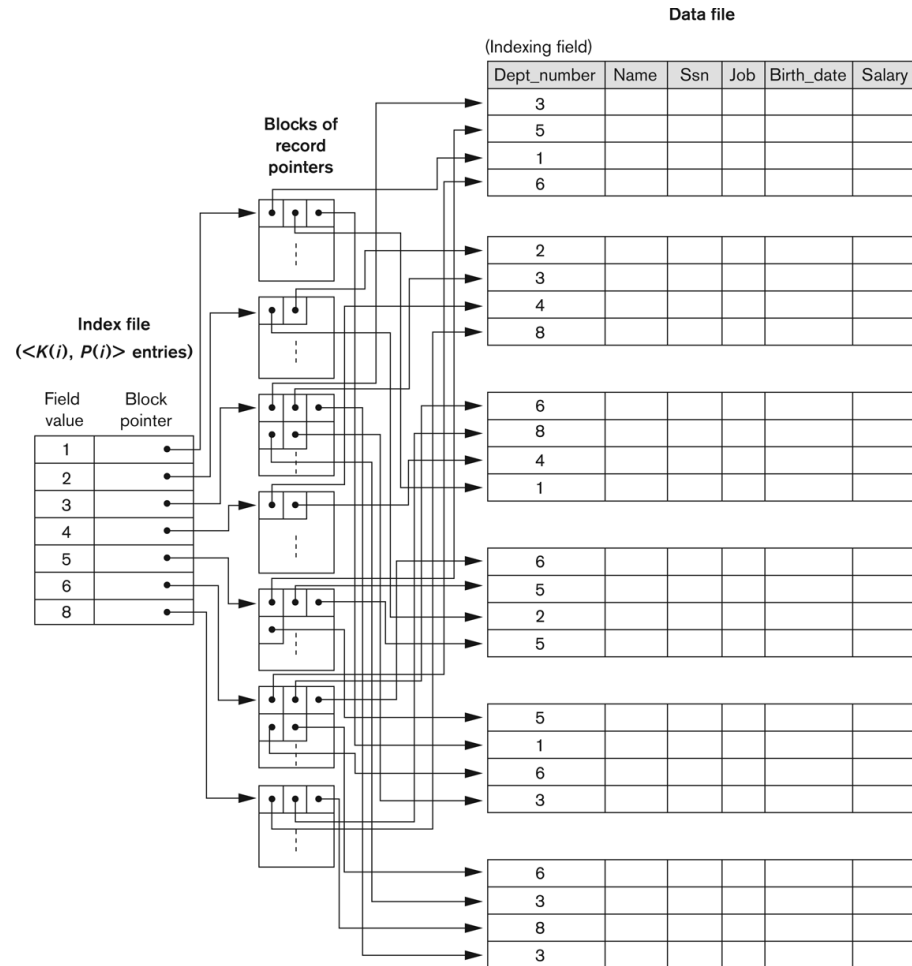
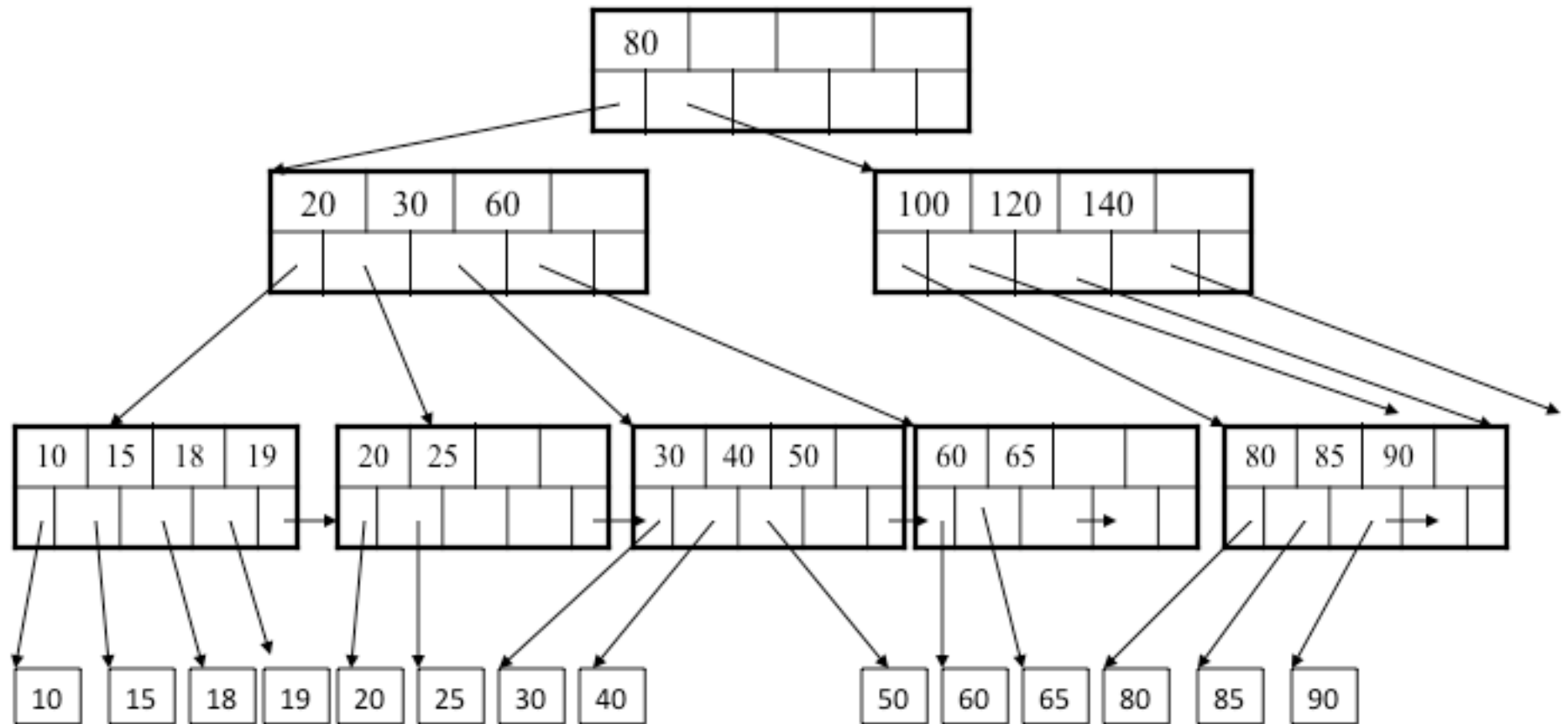


Figure 14.5

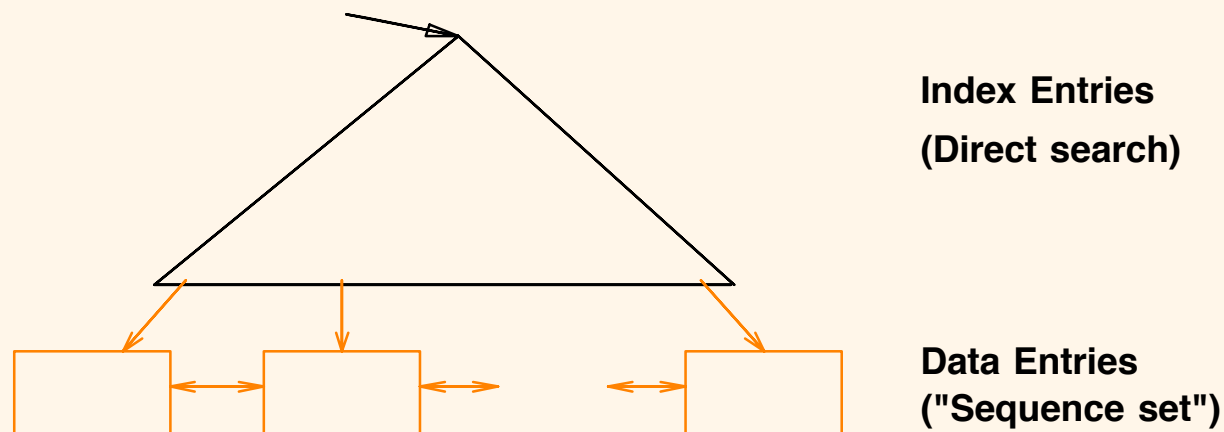
A secondary index (with record pointers) on a nonkey field implemented using one level of indirection so that index entries are of fixed length and have unique field values.

B+ Tree



B+ Tree

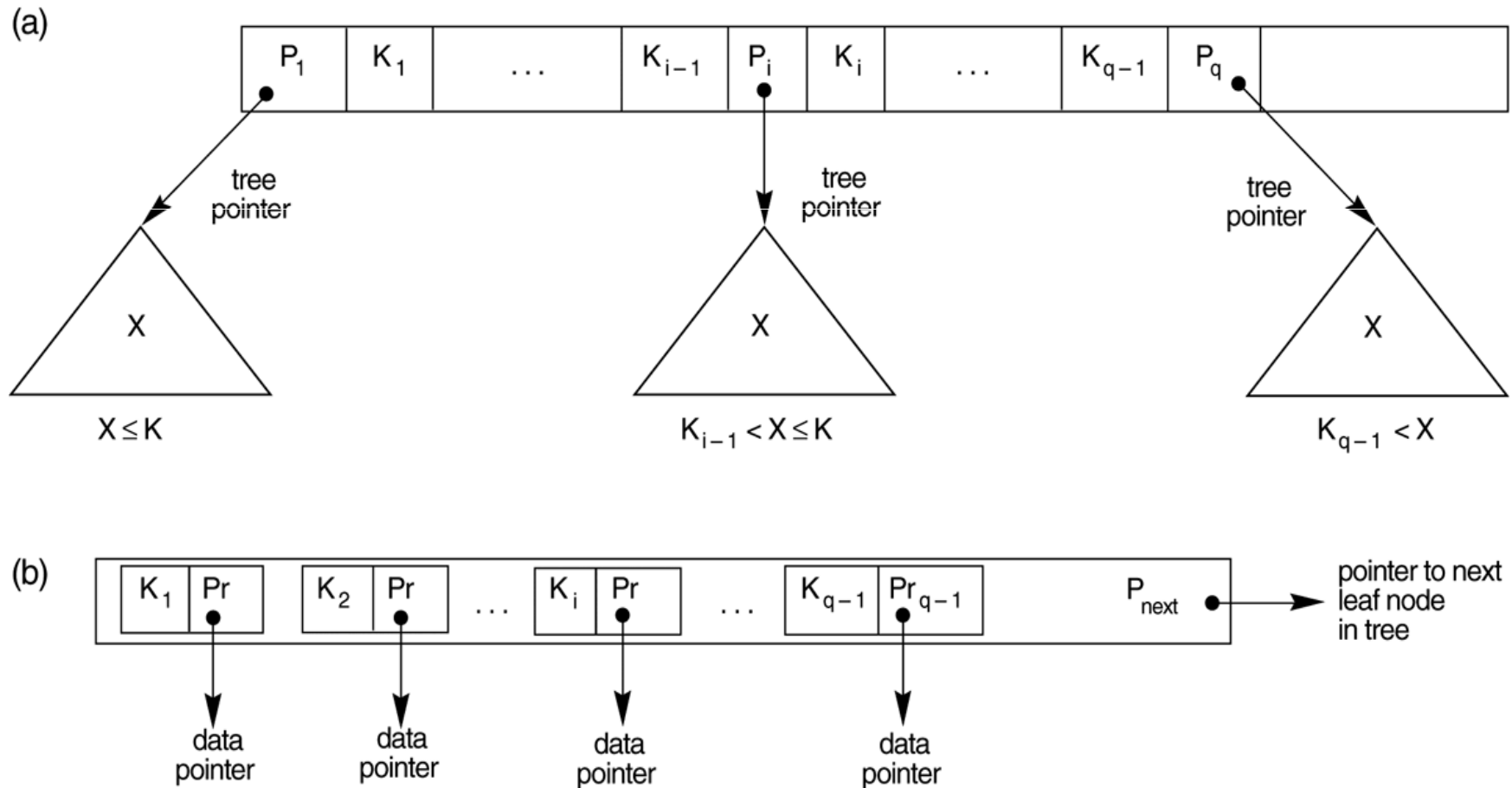
- ❖ Insert/delete at $\log_F N$ cost; keep tree *height-balanced*. (F = fanout, N = # leaf pages)
- ❖ Minimum 50% occupancy (except for root). Each node contains $d \leq \underline{m} \leq 2d$ entries. The parameter d is called the *order* of the tree.
- ❖ Supports equality and range-searches efficiently.



B+ Tree

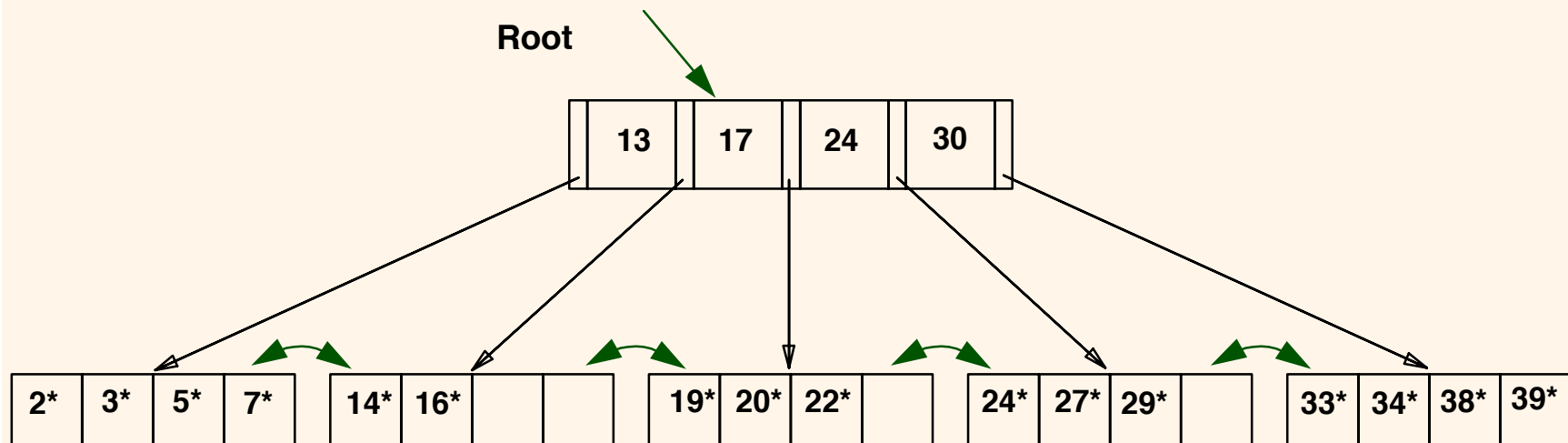
■ FIGURE 14.11 The nodes of a B+-tree

- (a) Internal node of a B+-tree with $q - 1$ search values.
- (b) Leaf node of a B+-tree with $q - 1$ search values and $q - 1$ data pointers.



B+ Tree Search

- ❖ Search begins at root, and key comparisons direct it to a leaf (as in ISAM).
- ❖ Search for 5*, 15*, all data entries $\geq 24^*$...



👉 *Based on the search for 15*, we know it is not in the tree!*

B+ Tree in practice

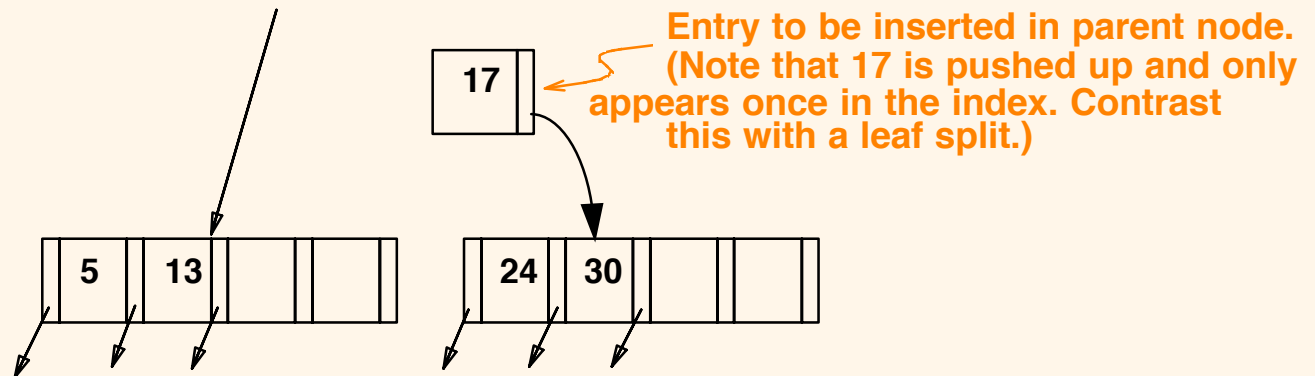
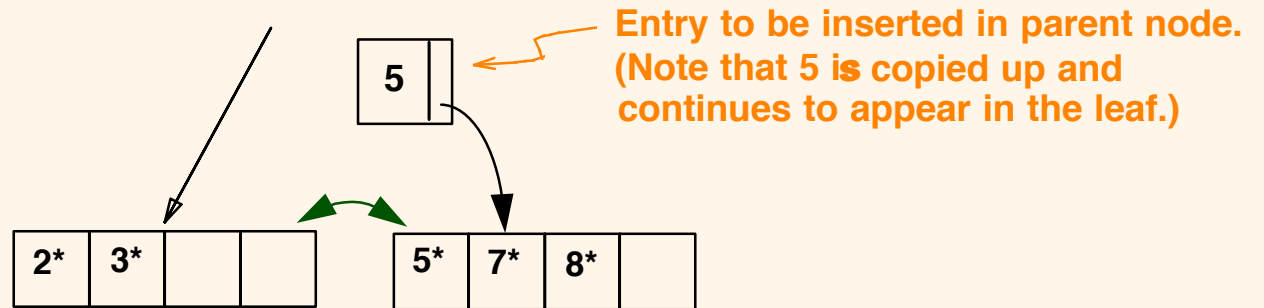
- ❖ Typical order: 100. Typical fill-factor: 67%.
 - average fanout = 133
- ❖ Typical capacities:
 - Height 4: $133^4 = 312,900,700$ records
 - Height 3: $133^3 = 2,352,637$ records
- ❖ Can often hold top levels in buffer pool:
 - Level 1 = 1 page = 8 Kbytes
 - Level 2 = 133 pages = 1 Mbyte
 - Level 3 = 17,689 pages = 133 MBytes

Inserting B+ Tree

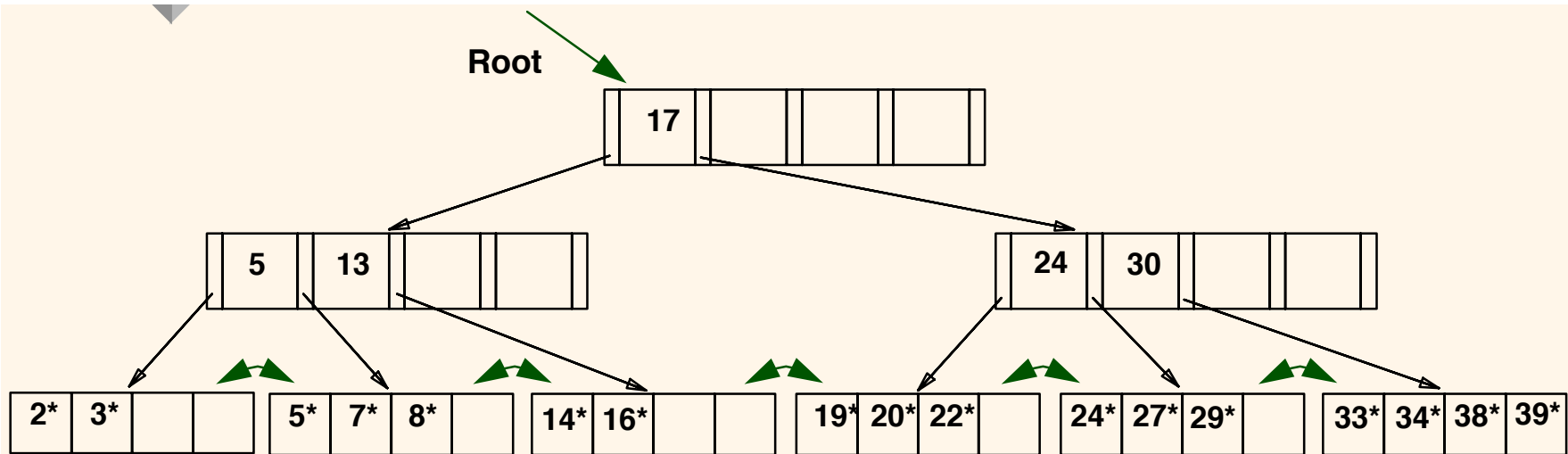
- ❖ Find correct leaf L .
- ❖ Put data entry onto L .
 - If L has enough space, *done!*
 - Else, must split L (*into L and a new node $L2$*)
 - ◆ Redistribute entries evenly, copy up middle key.
 - ◆ Insert index entry pointing to $L2$ into parent of L .
- ❖ This can happen recursively
 - To split index node, redistribute entries evenly, but push up middle key. (Contrast with leaf splits.)
- ❖ Splits “grow” tree; root split increases height.
 - Tree growth: gets wider or one level taller at top.

Inserting B+ Tree

- ❖ Observe how minimum occupancy is guaranteed in both leaf and index pg splits.
- ❖ Note difference between *copy-up* and *push-up*; be sure you understand the reasons for this.



Inserting node 8 B+ Tree

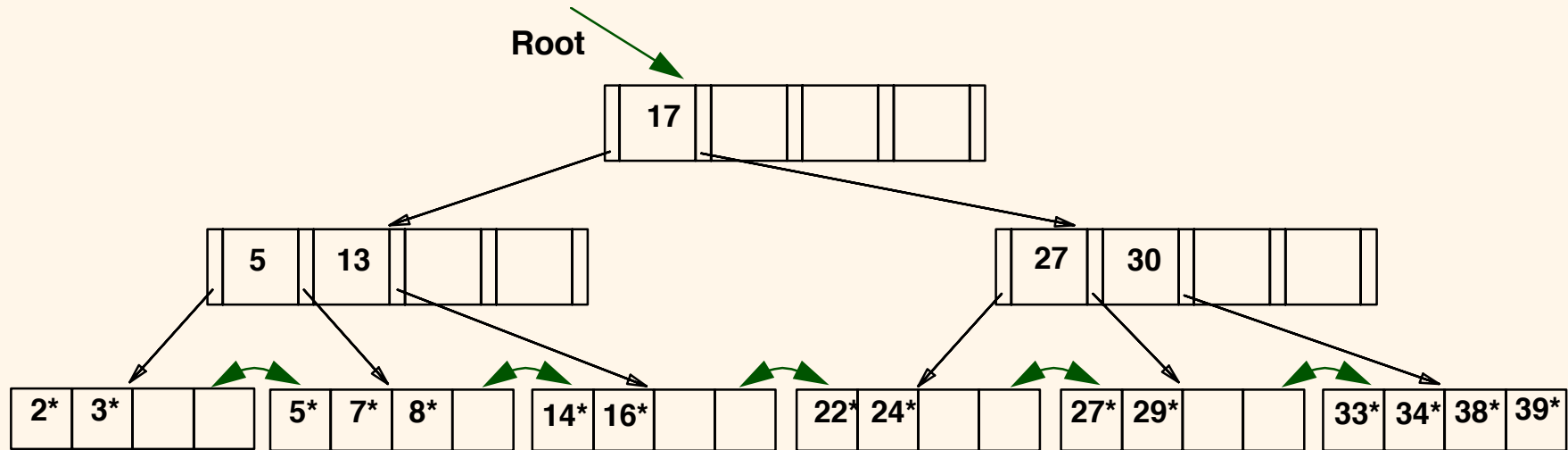


- ❖ Notice that root was split, leading to increase in height.
- ❖ In this example, we can avoid split by re-distributing entries; however, this is usually not done in practice.

Deleting B+ Tree

- ❖ Start at root, find leaf L where entry belongs.
- ❖ Remove the entry.
 - If L is at least half-full, *done!*
 - If L has only $d-1$ entries,
 - ◆ Try to **re-distribute**, borrowing from sibling (*adjacent node with same parent as L*).
 - ◆ If re-distribution fails, merge L and sibling.
- ❖ If merge occurred, must delete entry (pointing to L or sibling) from parent of L .
- ❖ Merge could propagate to root, decreasing height.

Deleting B+ Tree

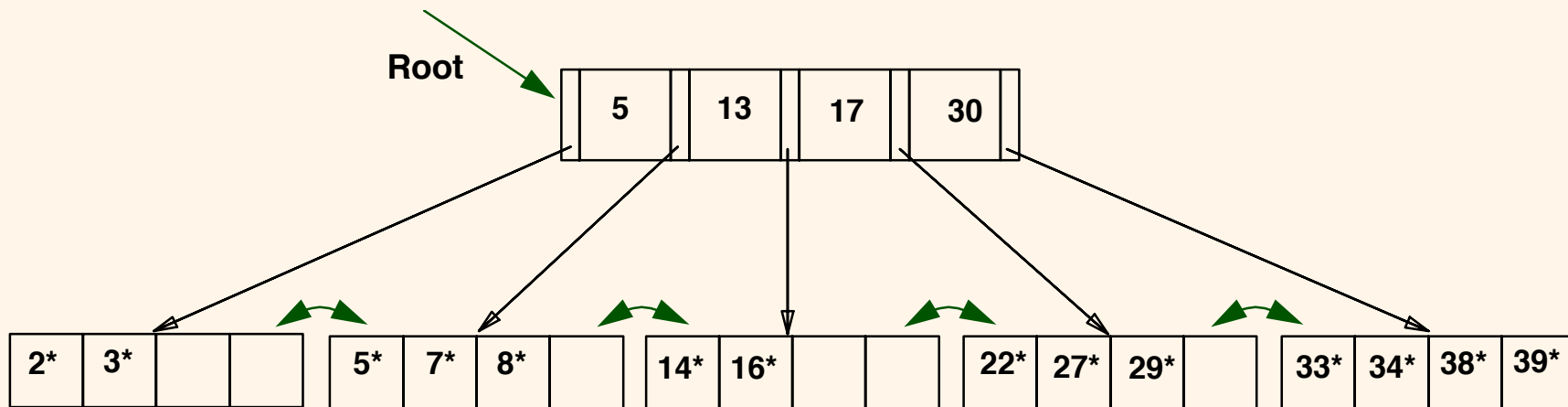
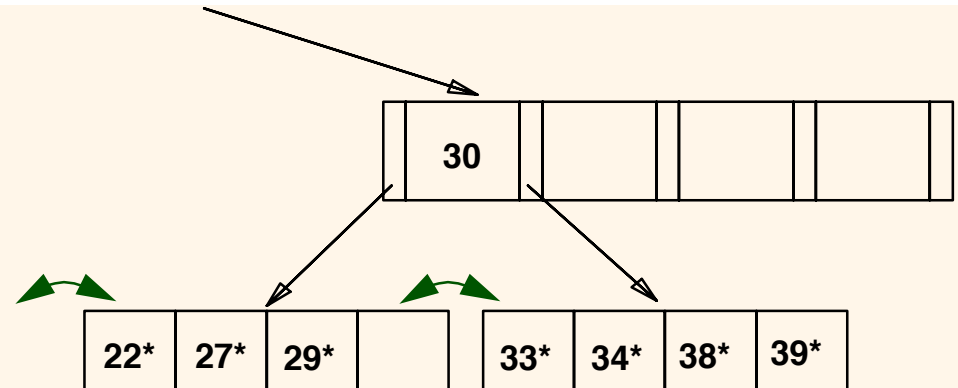


- ❖ Deleting 19* is easy.
- ❖ Deleting 20* is done with re-distribution.
Notice how middle key is *copied up*.

Deleting 24 B+ Tree

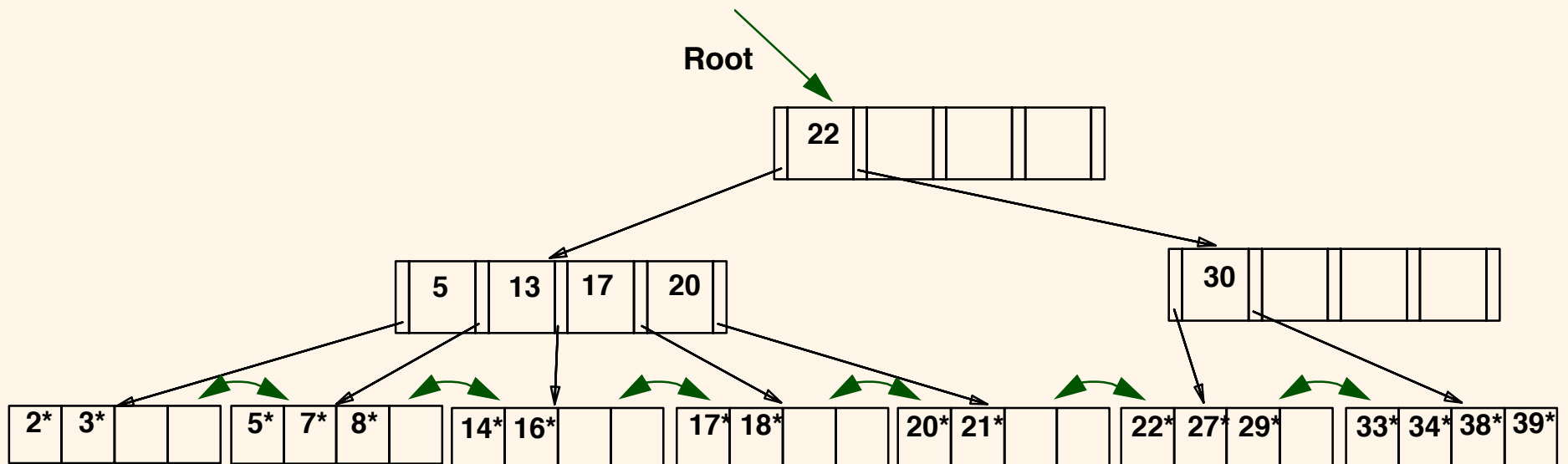
toss 27, pull down 17

- ❖ Must merge.
- ❖ Observe *'toss'* of index entry (on right), and *'pull down'* of index entry (below).



Example of non-leaf redistribution

- ❖ Tree is shown below *during deletion* of 24^* . (What could be a possible initial tree?)
- ❖ In contrast to previous example, can re-distribute entry from left child of root to right child.



After redistribution

- ❖ Intuitively, entries are **re-distributed by 'pushing through'** the splitting entry in the parent node.
- ❖ It suffices to re-distribute index entry with key 20; we've re-distributed 17 as well for illustration.

