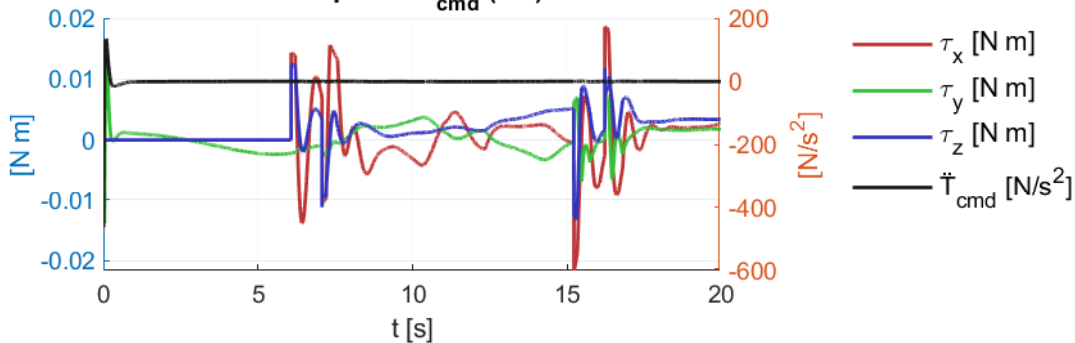


$u_{\text{QC}}$  (M\_block  $\rightarrow$  QC dynamics) — ON

**Torques &  $\ddot{T}_{\text{cmd}}$  (ON)**



**Gimbal acceleration commands (ON)**

