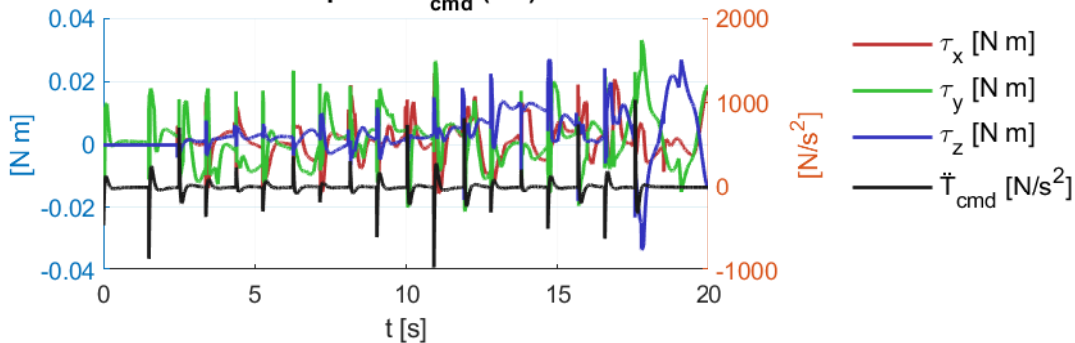


u_{QC} ($M_{\text{block}} \rightarrow \text{QC dynamics}$) — ON

Torques & \ddot{T}_{cmd} (ON)



Gimbal acceleration commands (ON)

