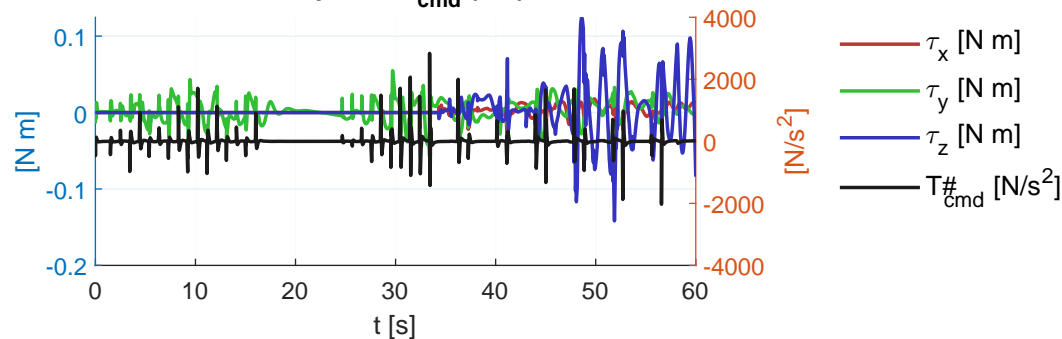


u_{QC} (M_block \rightarrow QC dynamics) — ON

Torques & $T_{\text{cmd}}^{\#}$ (ON)



Gimbal acceleration commands (ON)

