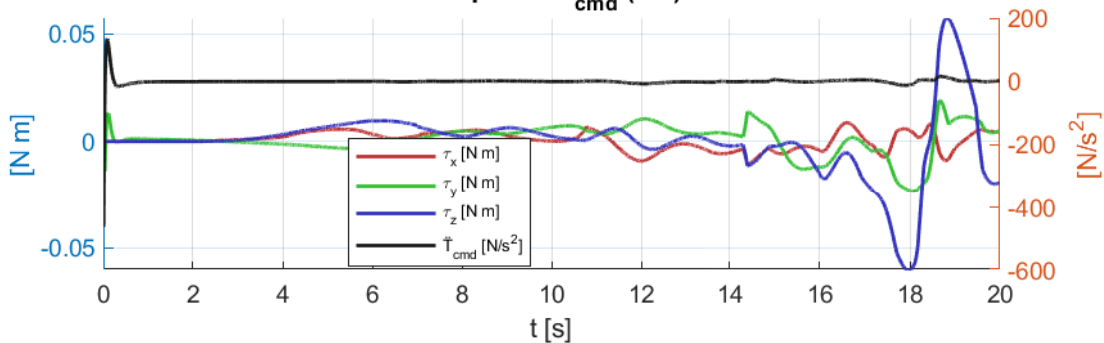


$u_{\text{QC}}$  ( $M_{\text{block}} \rightarrow \text{QC dynamics}$ ) — ON

**Torques &  $\ddot{\tau}_{\text{cmd}}$  (ON)**



**Gimbal acceleration commands (ON)**

