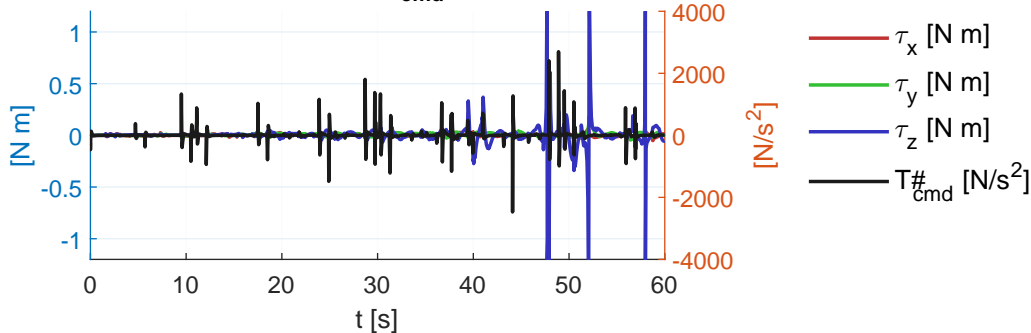


$u_{\text{QC}}$  (M\_block  $\rightarrow$  QC dynamics) — ON

### Torques & $T_{\text{cmd}}^{\#}$ (ON)



### Gimbal acceleration commands (ON)

