

Jisung (Ji) Jeong

M.Sc. Mobile Robotics · University of Bonn

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Education

MSc, Mobile Robotics

University of Bonn

October 2025 – Present

Bonn, Germany

BASc, Mechatronic Systems Engineering (Honours)

Simon Fraser University (SFU)

September 2020 – August 2025

Vancouver, Canada

- Thesis: Photorealistic Multi-Robot Simulation and GPS-Based UGV Localization using Synthetic Aerial Imagery (Supervisor: Dr. Simon Monckton)
- Cumulative GPA: 3.68/4.33

Research Experience

Robotics Research Co-op

Defence Research and Development Canada (DRDC)

September 2024 – April 2025

Suffield, Canada

- Generated over 10,000 synthetic aerial images of a moving pickup truck in NVIDIA Isaac Sim using domain randomization and ROS2 topic control
- Mapped 3D bounding boxes to oriented bounding boxes (OBBs) and trained custom YOLOv11n-OBB models, improving generalization and reducing training time with limited real-world data.
- Processed drone-captured photogrammetry data in Blender and exported it to Isaac Sim as a terrain mesh for synthetic data generation.
- Created a SITL test framework combining ROS2 and PX4 for UAV-UGV teleoperation and wrote a pyMAVLink script to replay flight telemetry with visualization in QGroundControl and RViz2.

Research Assistant Co-op

SFU Fuel Cell Research Lab (FCReL)

May – December 2022

Vancouver, Canada

- Prepared catalyst layer samples on PTFE membranes and transferred them via decal; supported ink formulation and lab-scale direct film coating.
- Conducted accelerated stress tests (temperature, humidity, cross-pressure) to analyze mechanical durability of fuel cell membranes.
- Observed performance trends in a commercial hydrocarbon-based membrane under varying test conditions.

Publications

Published or Appeared

Mirfarsi SH., Kumar A., **Jeong J.**, Brown E., Adamski M., Jones S., McDermid S., Britton B., and Kjeang E. Mechanical durability of reinforced sulfo-phenylated polyphenylene-based proton exchange membranes: Impacts of ion exchange capacity and reinforcement thickness.” Journal of Power Sources, 630, 236137, 2025.

Stoll J., **Jeong J.**, Huynh P., and Kjeang E. Impacts of Catalyst Ink Composition and Wet Film Thickness on Fuel Cell Catalyst Layers Fabricated by Direct Film Coating Method. Journal of The Electrochemical Society, 171(5), 054520, 2024.

Mirfarsi, SH., Kumar, A., **Jeong, J.**, Adamski, M., McDermid, S., Britton, B., and Kjeang, E. High-Temperature Stability of Hydrocarbon-Based Pemion® Proton Exchange Membranes: A Thermo-Mechanical Stability Study. International Journal of Hydrogen Energy, 50, 1507-1522, 2024.

Mirfarsi, SH., Kumar, A., **Jeong, J.**, Adamski, M., McDermid, S., Britton, B., and Kjeang, E. Thermo-Mechanical Stability of Hydrocarbon-Based Pemion® Proton Exchange Membranes. Electrochemical Society Meeting Abstracts 244, 39, 1903-1903, 2023.

Mirfarsi, SH., Kumar, A., **Jeong, J.**, Adamski, M., McDermid, S., Britton, B., and Kjeang, E. High Durability of Pemion® Proton Exchange Membranes in Cross-Pressure Accelerated Mechanical Stress Tests. Electrochemical Society Meeting Abstracts 244, 39, 1920-1920, 2023.

In preparation

Jeong J., Monckton S., Simulated GPS Localization of UGV using Synthetic Aerial Imagery: Technical Manual for Synthetic Data Generation & Rigid-Body Simulation in NVIDIA Isaac Sim. Draft for DRDC Suffield Defense Research Reports

Projects

ROS 2 Kilted Tutorial Party	May 2025
Open Robotics	Remote
<ul style="list-style-type: none">Tested core features (rviz, rqt, demo_nodes_py, topic monitor) on Windows for the upcoming “Kilted” release.Provided detailed logs and screen-capture videos that helped Open Robotics resolve four issues before the feature-freeze.	
ML-Based Prediction of Hydraulic Conductivity	March – April 2024
MSE 413: Machine Learning in Mechatronics	Surrey, Canada
<ul style="list-style-type: none">Developed supervised machine learning models to predict hydraulic conductivity in BC soil using government soil data.Implemented regression algorithms and feature engineering techniques to optimize model performance.Employed 10-fold cross-validation and hyperparameter tuning to optimize model performance and ensure robustness.	
Automated Live Braille (Winner)	February –March 2024
SFU Faculty of Applied Science Speak Out Competition 2024	Vancouver, Canada
<ul style="list-style-type: none">Advocated for accessibility by addressing physical barriers for blind and visually impaired students.	

- Prototyped real-time processing software utilizing OpenCV and Machine Learning to convert annotated lecture content into digital Braille.
- Developed a Python program for real-time transmission of predicted characters to Arduino, generating corresponding Braille character outputs instantly.

Robotic Arm for Engine Block Assembly

March – April 2024

MSE 429: Advanced Kinematics for Robotic System

Vancouver, Canada

- Designed a three-degree-of-freedom robotic arm in SolidWorks and simulated assembly in MATLAB.
- Developed algorithms for robot arm kinematics, dynamics, trajectory and motion planning, and force and torque analysis for valve cap installation.

Extracurricular Activities

Power Systems Lead

January 2022 – August 2023

Team Phantom – SFU Formula SAE

Vancouver, Canada

- Led electrical sub-system integration for a Formula SAE team, coordinating across disciplines to ensure hardware reliability and system safety.
- Designed PCBs in Altium for safety indicators and mentored junior members in circuit design, soldering, and embedded systems fundamentals.

Controls Engineer

October 2022 – September 2023

SFU Rocketry

Vancouver, Canada

- Configured SPI communication in Embedded C between Arduino DAQ and Raspberry Pi control module to monitor real-time engine pressure.

Leadership Experience

Home for Interactive Virtual Environment (HIVE)

August – November 2021

Welcome Leader

SFU - Student Engagement and Retention

Vancouver, Canada

- Facilitated the integration of new students into the SFU community by fostering connections and promoting a culture of inclusion.
- Led HIVE groups in an online course, creating a supportive and accessible space for students to cultivate friendships.

First Year Representative (Elected)

September 2020 – September 2021

Mechatronic Systems Engineering Student Society (MSESS)

Vancouver, Canada

- Collaborated with instructors and students to address and resolve academic challenges in first-year mechatronics courses.
- Represented the first-year student body to enhance the overall campus experience by organizing recreational events that addressed student needs and concerns.

Honours & Awards

Triple A Award in Mechatronics | SFU

October 2023

- Recognized for good academic standing and leadership skills.

Natural Sciences and Engineering Research Council of Canada
Undergraduate Student Research Award (USRA) | SFU

March 2022

- Associated with SFU Fuel Cell Research Lab.
- Awarded for high academic aptitude and research potential.

Dean's Honour Roll | SFU

- Spring 2021; Fall 2021, 2023; Summer 2021, 2023, 2024, 2025

Certifications

Drone Pilot Certificate - Basic Operations

September 2024

- Allows legal and safe operations of drones within Canada.

Certificate of Training: Automation and Digital Technology for Agriculture and Food Processing

April 2024

- Covered core mechatronics systems with application to agricultural automation (PLCs, sensors, pneumatics, and system integration).

Siemens Certified Mechatronic Systems Assistant

May 2023

- Completed foundational industrial mechatronics certification (mechanical, electrical, PLC, and diagnostic systems).

Certified SOLIDWORKS Associate in Simulation

February 2022

- Demonstrates a foundational understanding of engineering simulations and skills in analyzing and simulating mechanical designs.

Certified SOLIDWORKS Associate in Mechanical Design

September 2021

- Indicates a foundation in and apprentice knowledge of 3D CAD design and engineering practices and principles.

Skills

Robotics: Isaac Sim, ROS 2 (Humble), MAVLink, PX4-Autopilot, QGroundControl

Programming: Python, MATLAB, C/C++

Software Tools & DevOps: Blender, Linux, Docker, Git/GitHub, GitLab, LaTeX

Relevant Coursework: Machine Learning, Computer Vision, Robot Kinematics, Control Theory, Embedded Systems, Digital Logic, 3D Modelling

Languages: Fluent English, Fluent Japanese, Native Korean