

Recent Advances of the Lattice-Boltzmann Method for the Simulation of Transonic Flows

Swen Noelting

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Ehab Fares, Damiano Casalino, Benedikt König, Benjamin Duda, André Ribeiro et al

Applied Modeling & Simulation (AMS) Seminar Series

May 10, 2016

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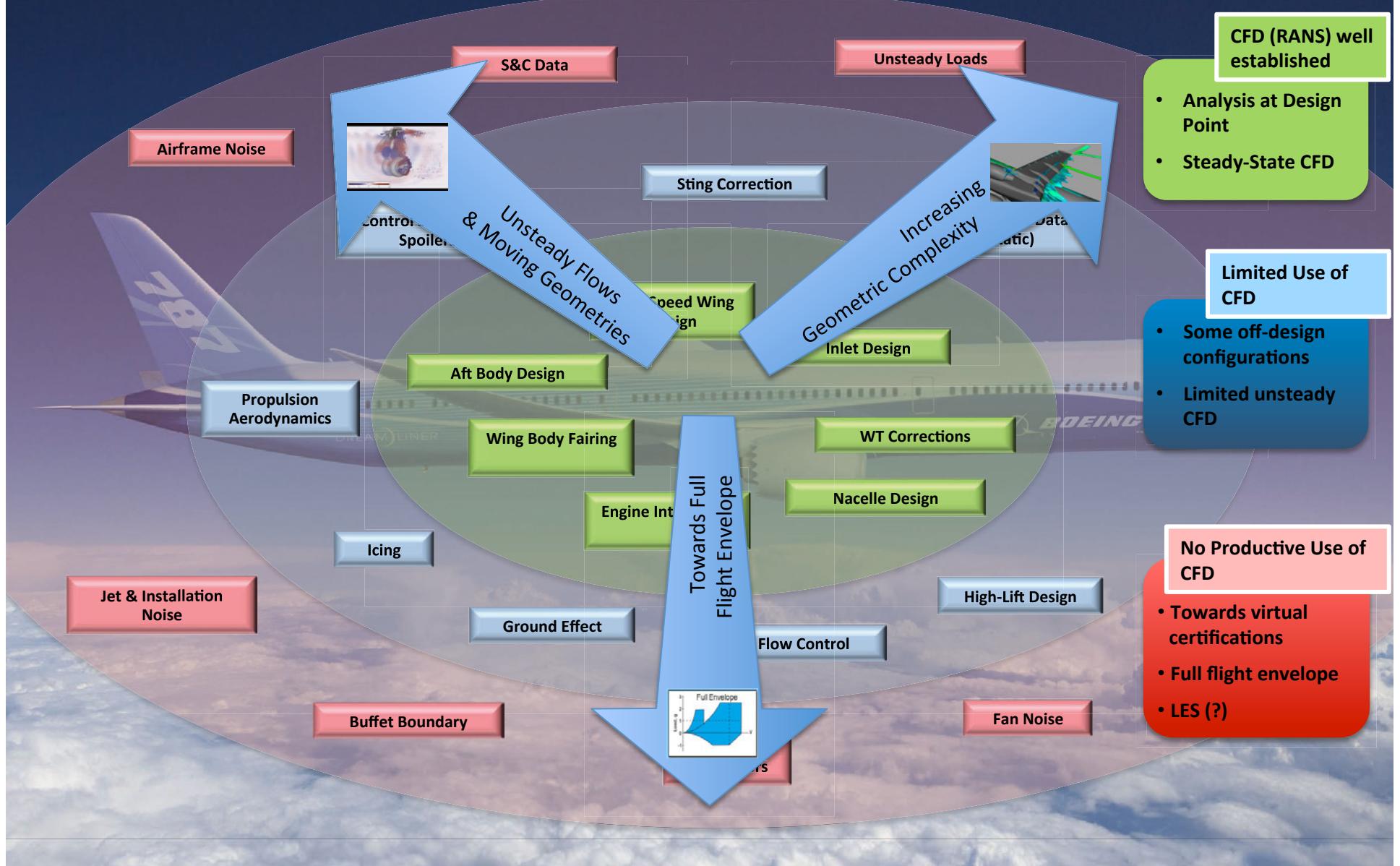


Outline

- Motivation: CFD Applications in Aerospace
- Overview of PowerFLOW Projects at NASA
- Theory & Background
 - *LBM*
 - *Turbulence model*
 - *Wall treatment*
 - *Extension to transonic flows*
- Transonic Code Validation and Application Examples
 - *Fundamental Validations*
 - *Industrial Application Examples*



CFD Applications in Aerospace



Motivation – Vision 2030

- CFD Vision 2030
 - *2014 Report to NASA by Key Industry Players (Boeing, Lockheed, Pratt&Whitney,...)*
- Main challenges for CFD to move beyond current status:
 - *Efficient handling of unsteady turbulent flows with significant regions of separation*
 - *Mesh generation*
 - *Robustness and automation of CFD simulations*
 - *Efficient use of HPC infrastructure*
 - *Managing very large amounts of data*
 - *Multi-disciplinary analysis & optimization*
- Hybrid RANS-LES and wall-modeled LES seen as best prospects
- Can LBM provide a contribution to address these challenges?

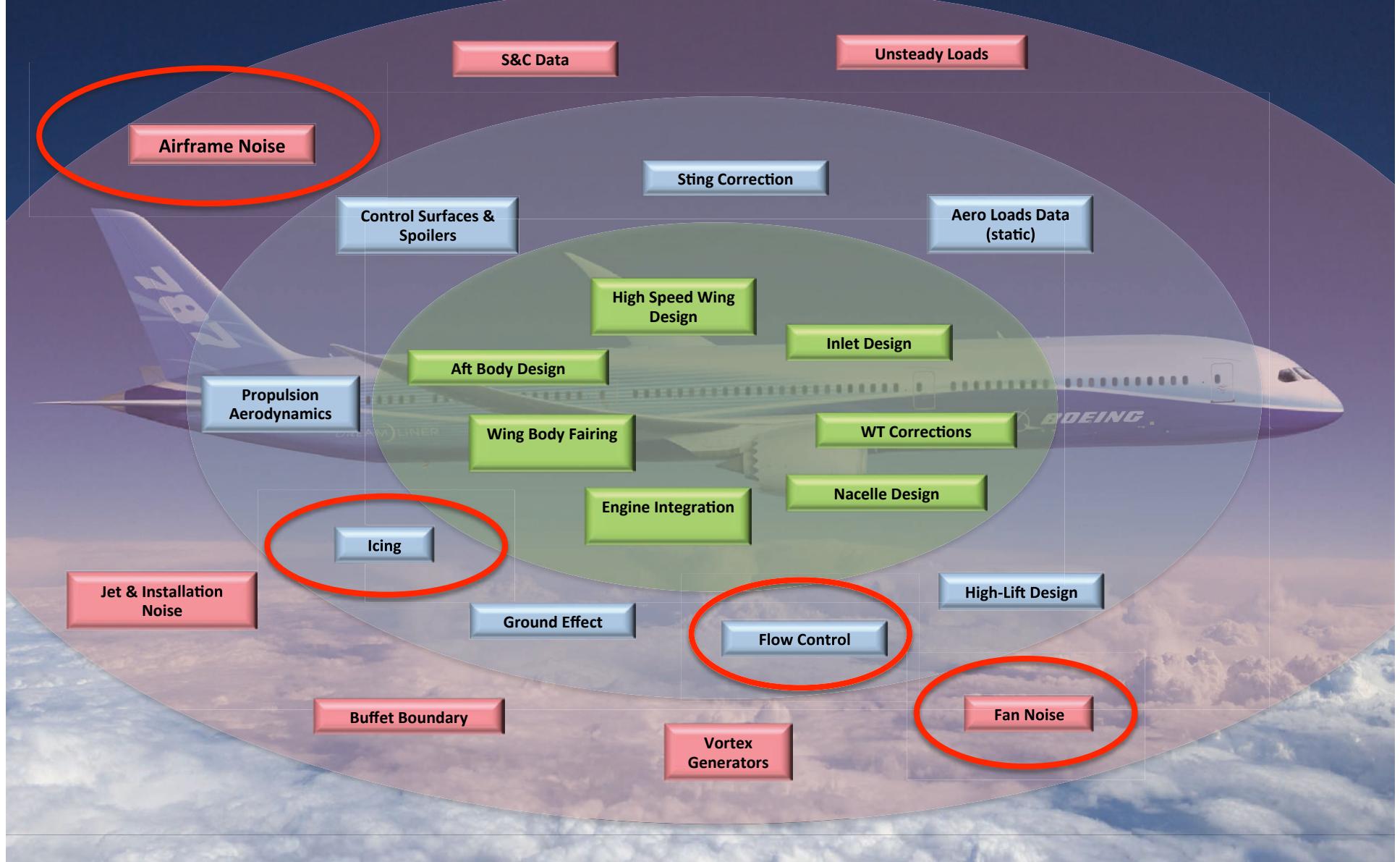


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PowerFLOW Projects at NASA



Aeroacoustic Predictions

NASA ERA Project

□ Simulation-based airframe noise predictions

- Simulated geometry: As-built 18% scale Gulfstream model
- Baseline configurations
 - 39° flap deflection, main gear removed
 - 39° flap deflection, main gear deployed
- Most flap and gear concepts simulated prior to wind tunnel testing
 - ROLD, FENOFRFins, FLEXSEL, etc.
 - Solid and porous versions of knee, wheel, brake fairings
- Sample quiet configuration
 - FENOFRFins plus fully treated main gear

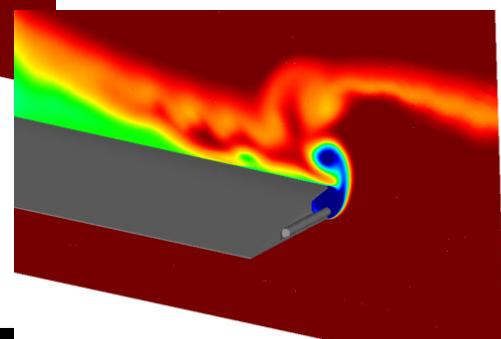
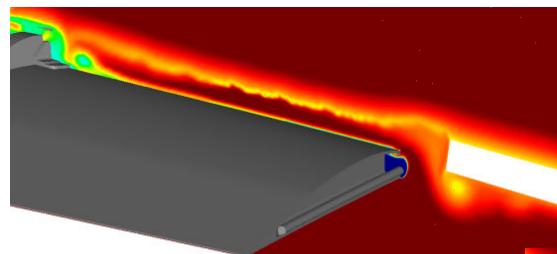
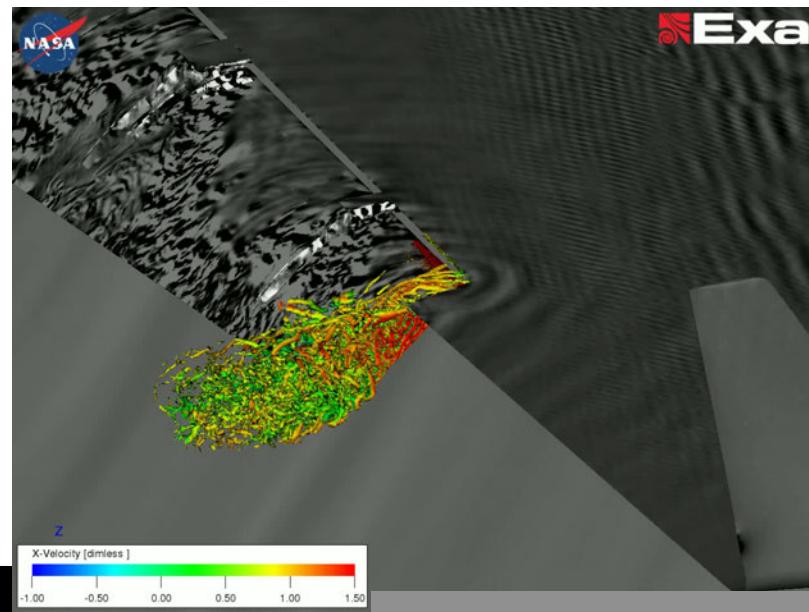
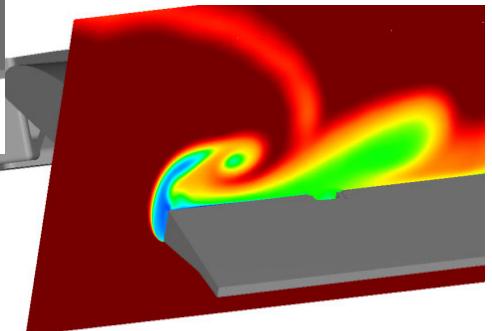
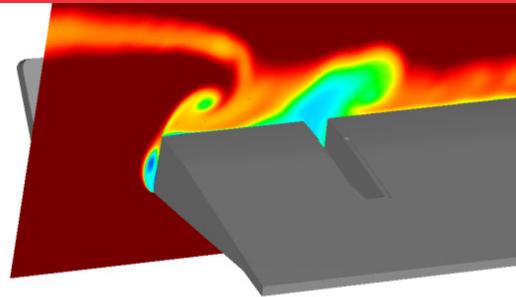
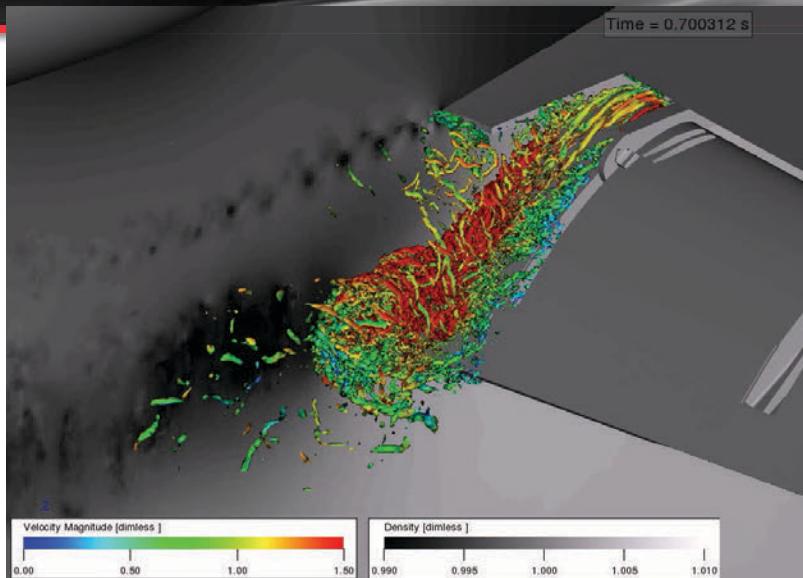


□ Accomplishments

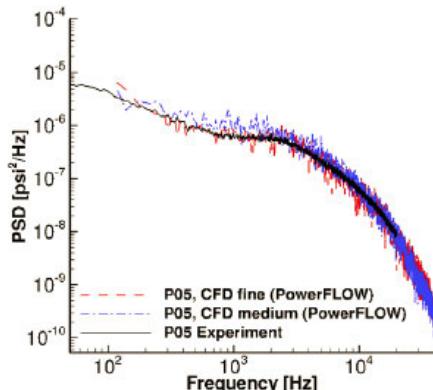
- Predicted farfield noise for baseline and quiet configurations in good agreement with 14x22 measurements
 - Established computational simulations as an accurate predictive tool
 - Paved the way for application to full-scale

Airframe Noise – Flap Edge Noise

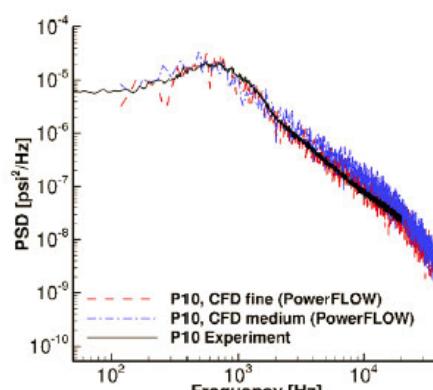
NASA ERA Project – G550



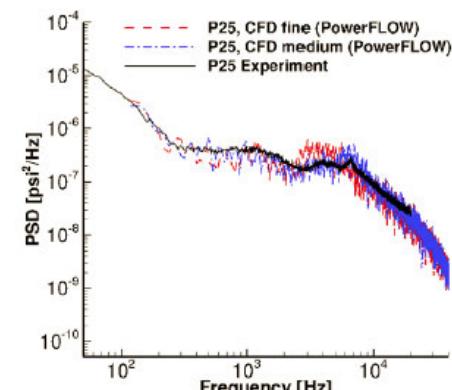
Airframe Noise – Flap Edge Noise



d) Probe 5 location

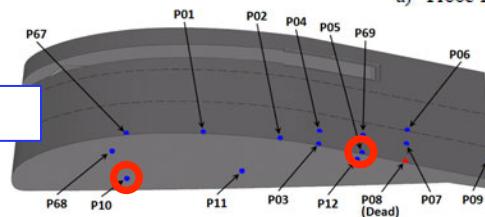


a) Probe 10 location

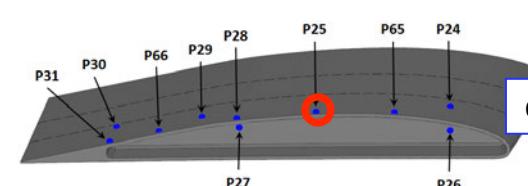


b) Probe 25 location

Surface Probes

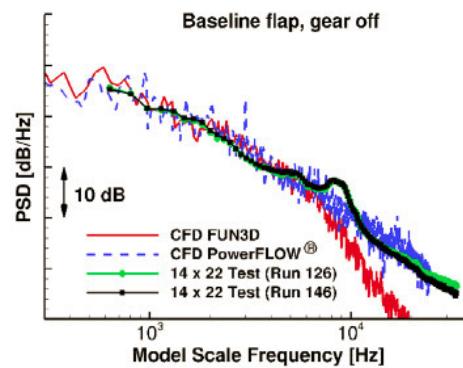


Inboard Flap



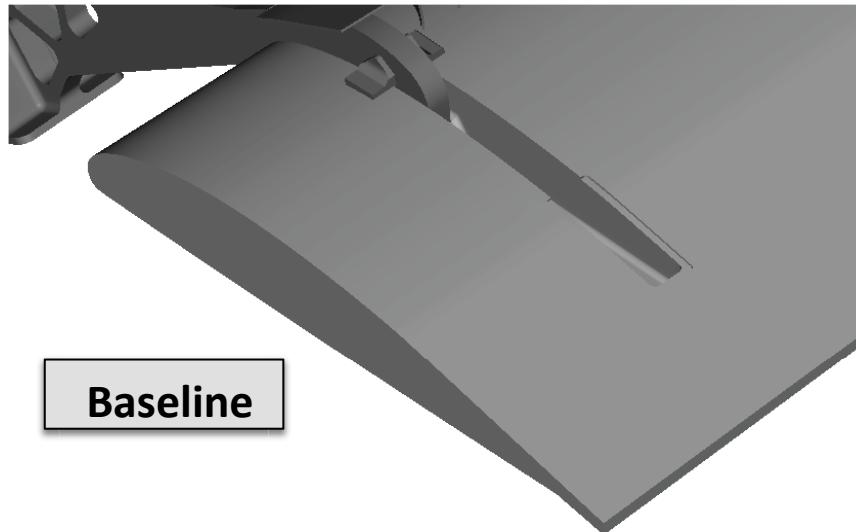
Outboard Flap

All simulations were carried out prior to wind tunnel tests

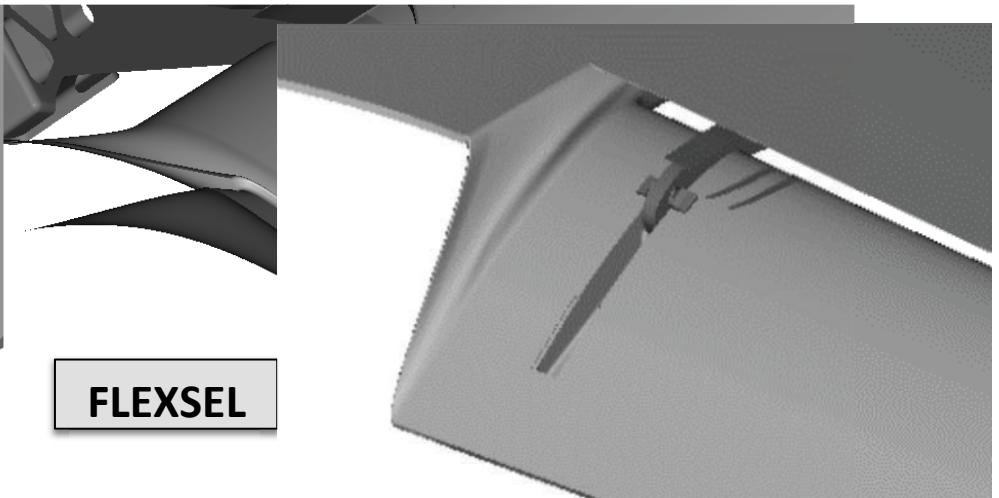


Far-Field
Probes

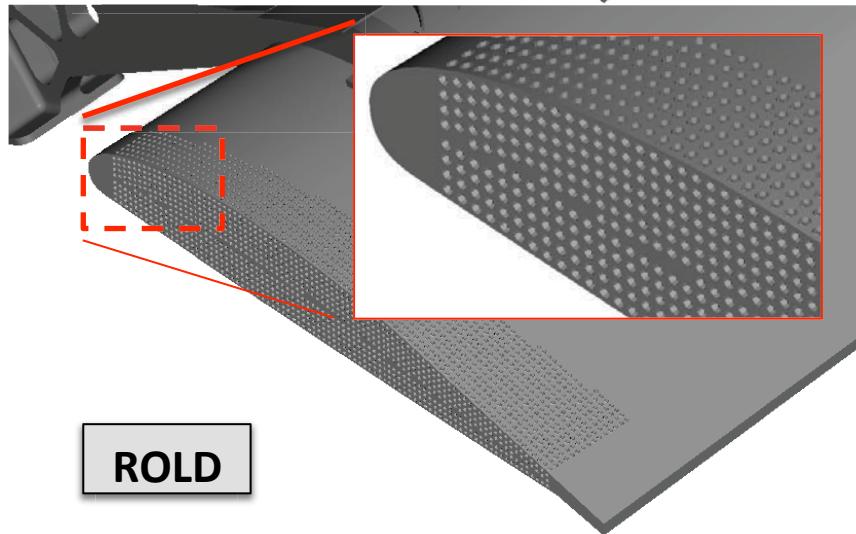
Airframe Noise – Noise Reduction Concepts



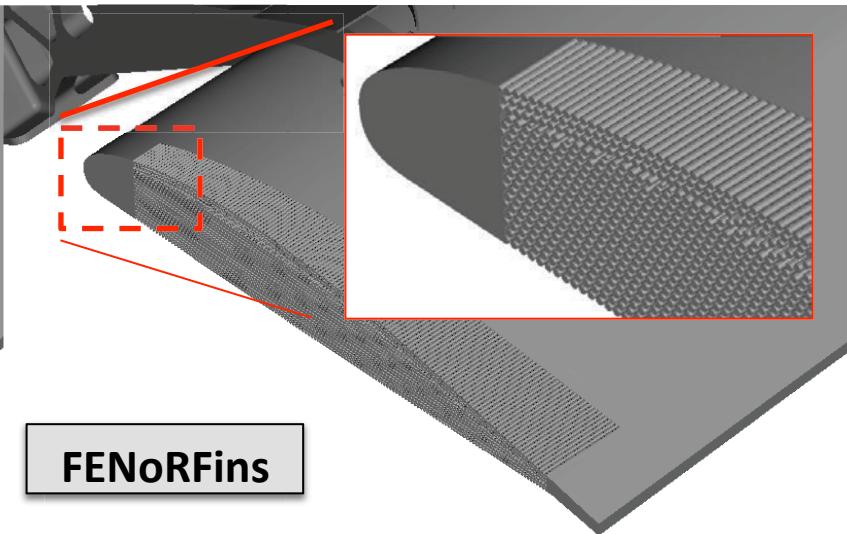
Baseline



FLEXSEL



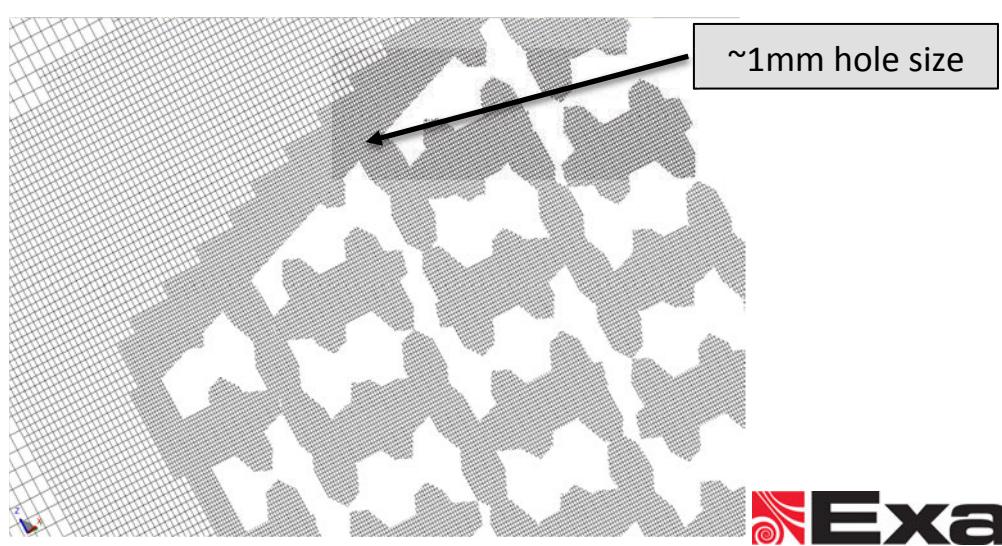
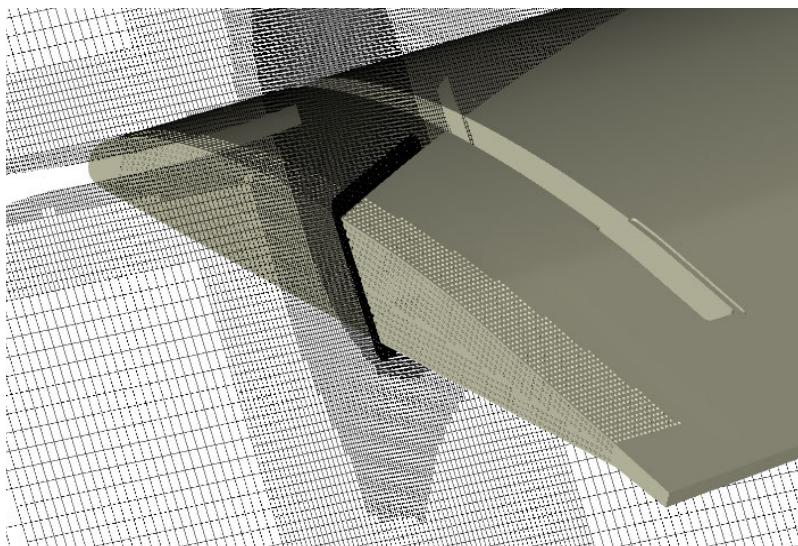
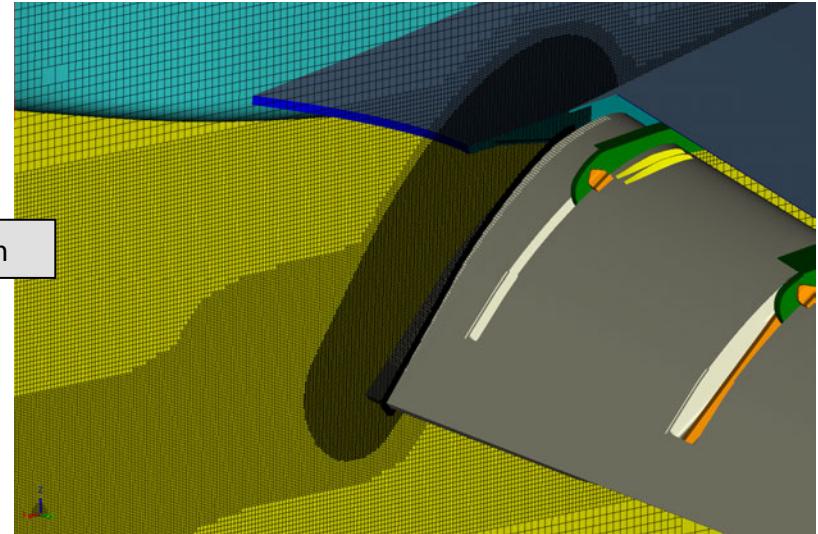
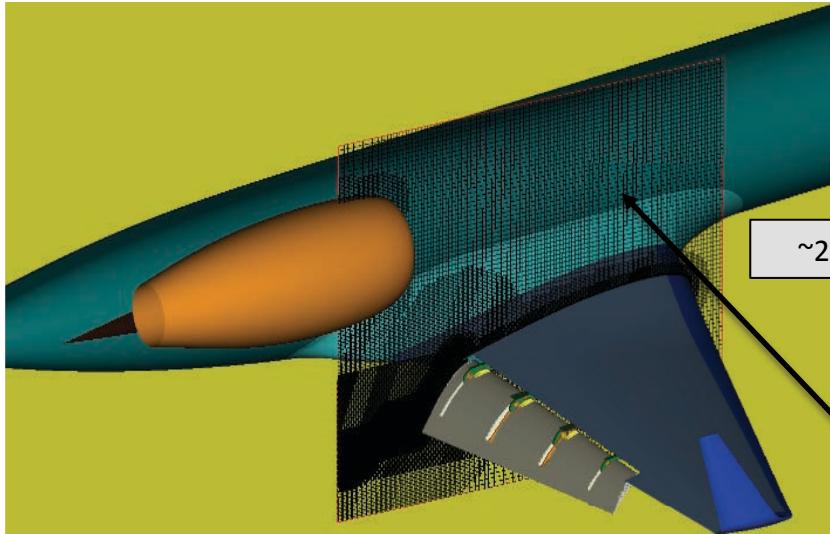
ROLD



FENoRFins

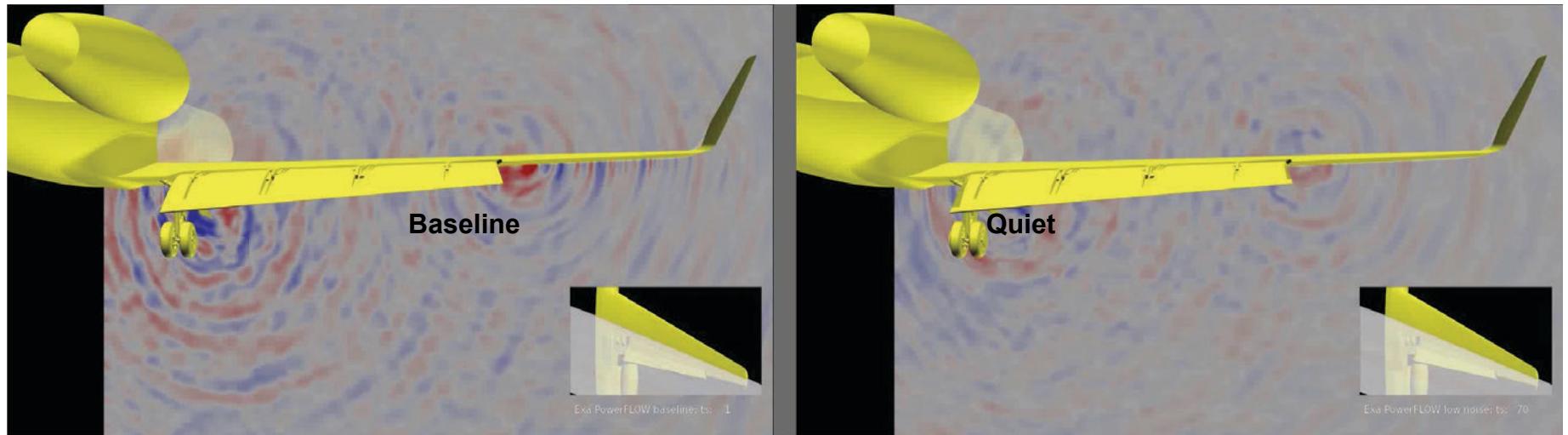
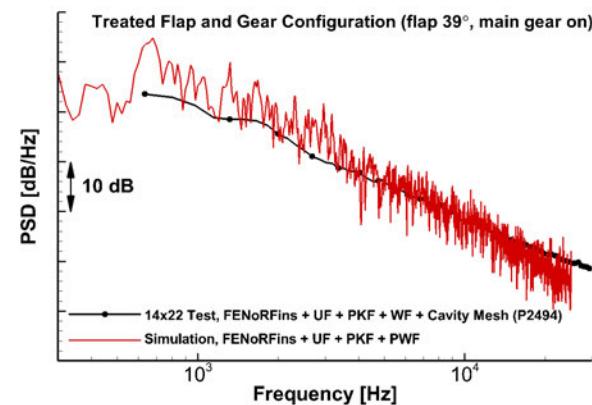
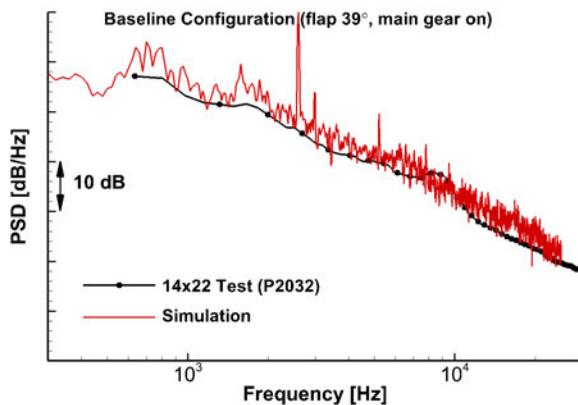
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Computational Mesh

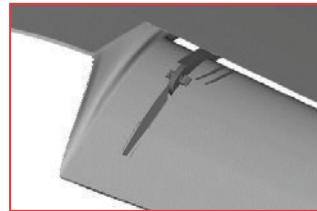


Baseline v. quiet Configurations

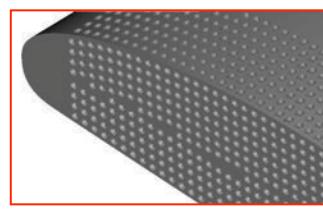
Flap 39°, main gear on configuration



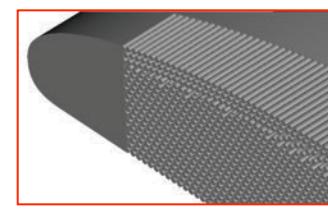
Flap Noise Reduction Concepts



FLEXSEL



ROLD



FENoRFINS

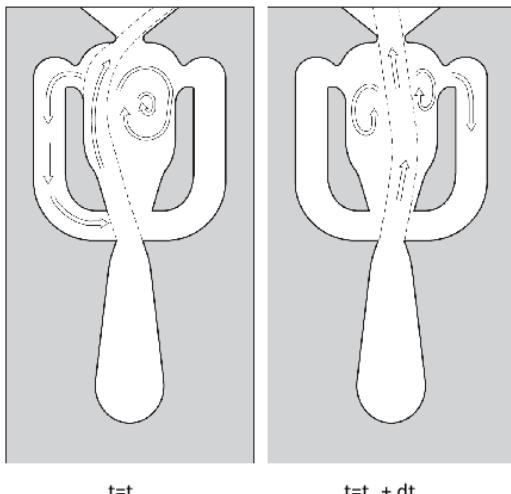
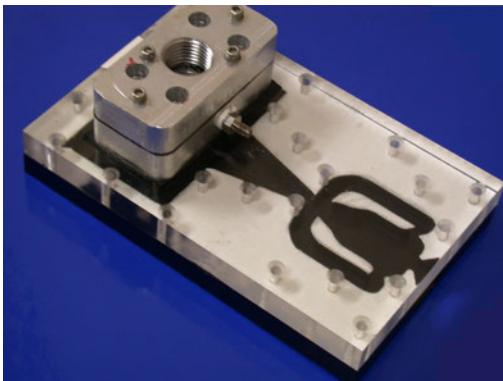
	Experiment 14x22 WT			PowerFLOW Simulations		
	FLEXSEL	ROLD*	FINS*	FLEXSEL	ROLD*	FINS*
📢 (baseline – concept) OASPL [dB] (1kHz – 30kHz)	3.6	3.9	3.5	4.3	4.7	3.9

All simulations were carried out prior to wind tunnel tests

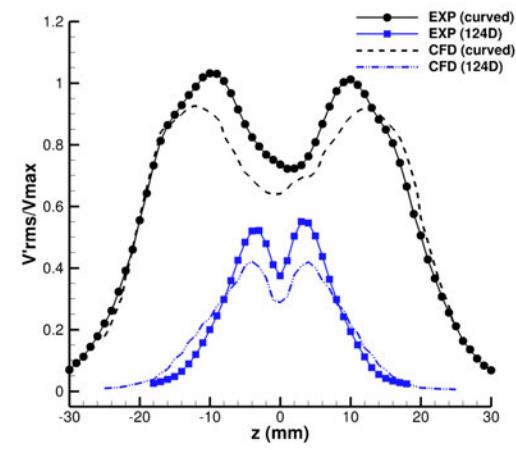
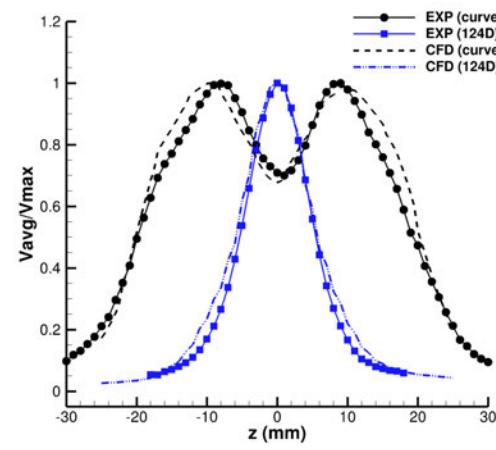
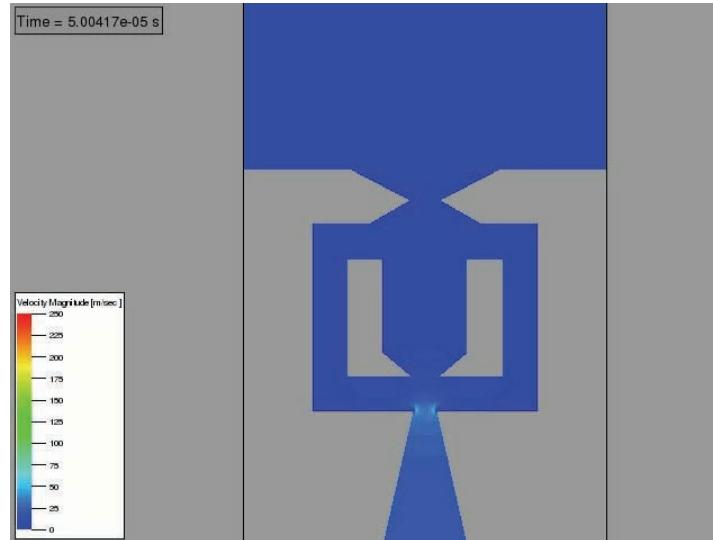
*The aerodynamic values shown here correspond to the smallest holes and fin diameter tested



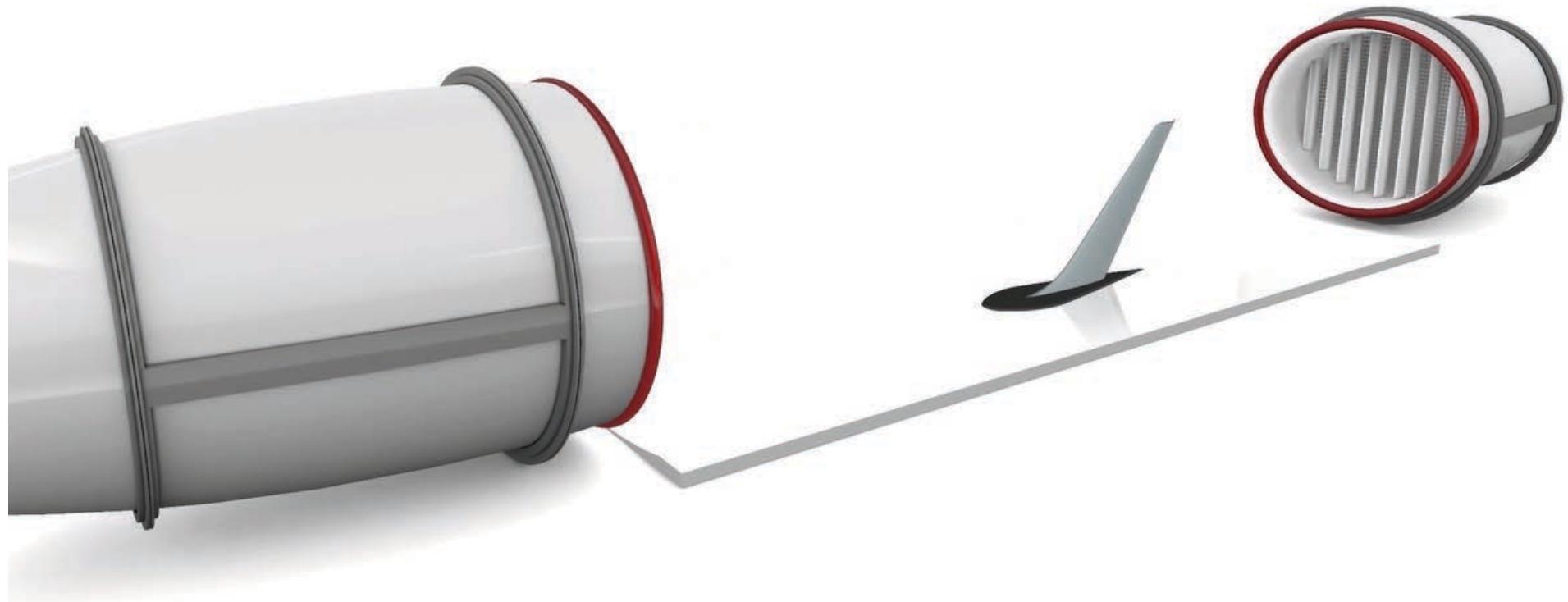
Flow Control



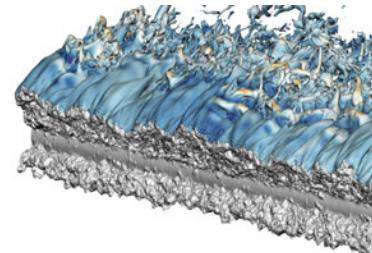
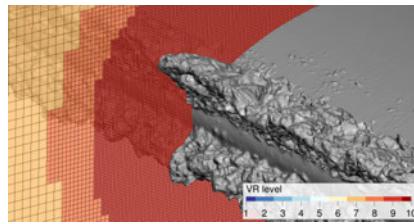
Source
AIAA 2012-3239



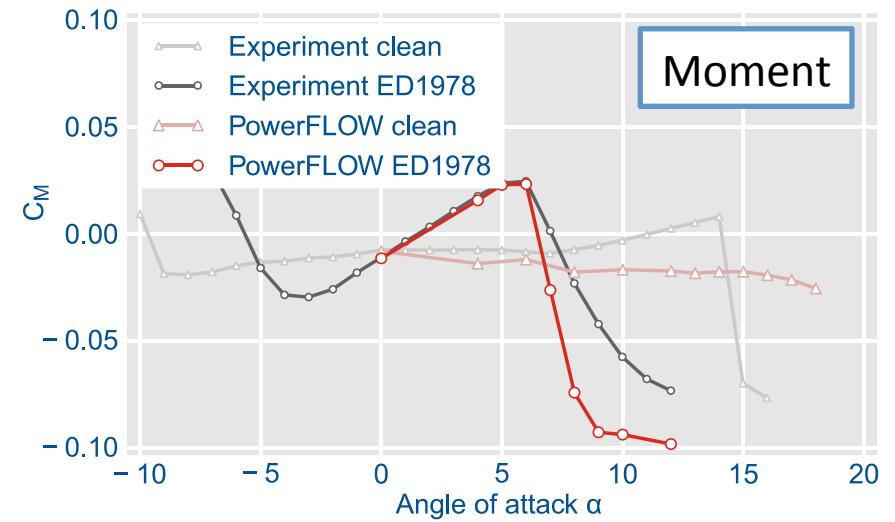
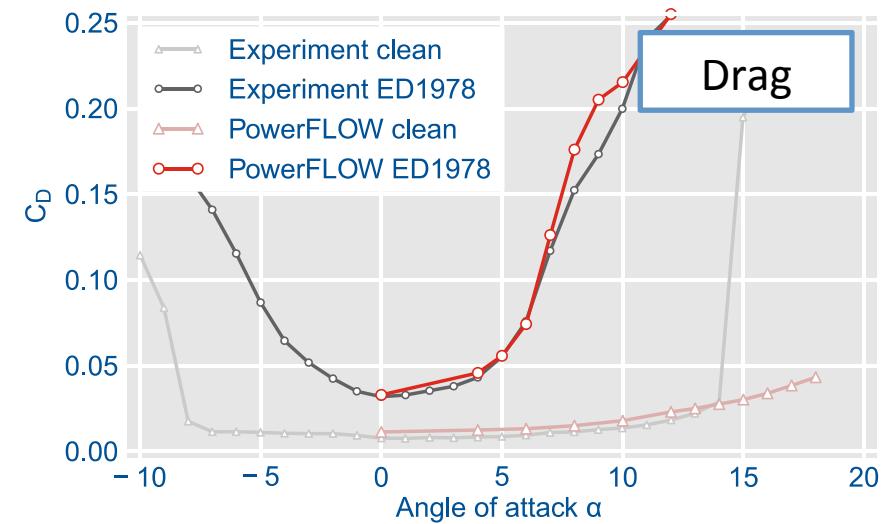
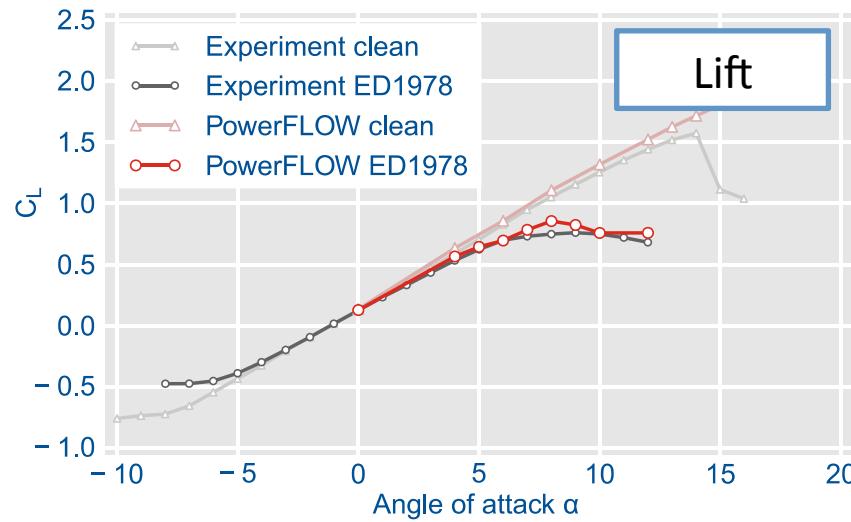
Tail Rudder with Active Flow Control



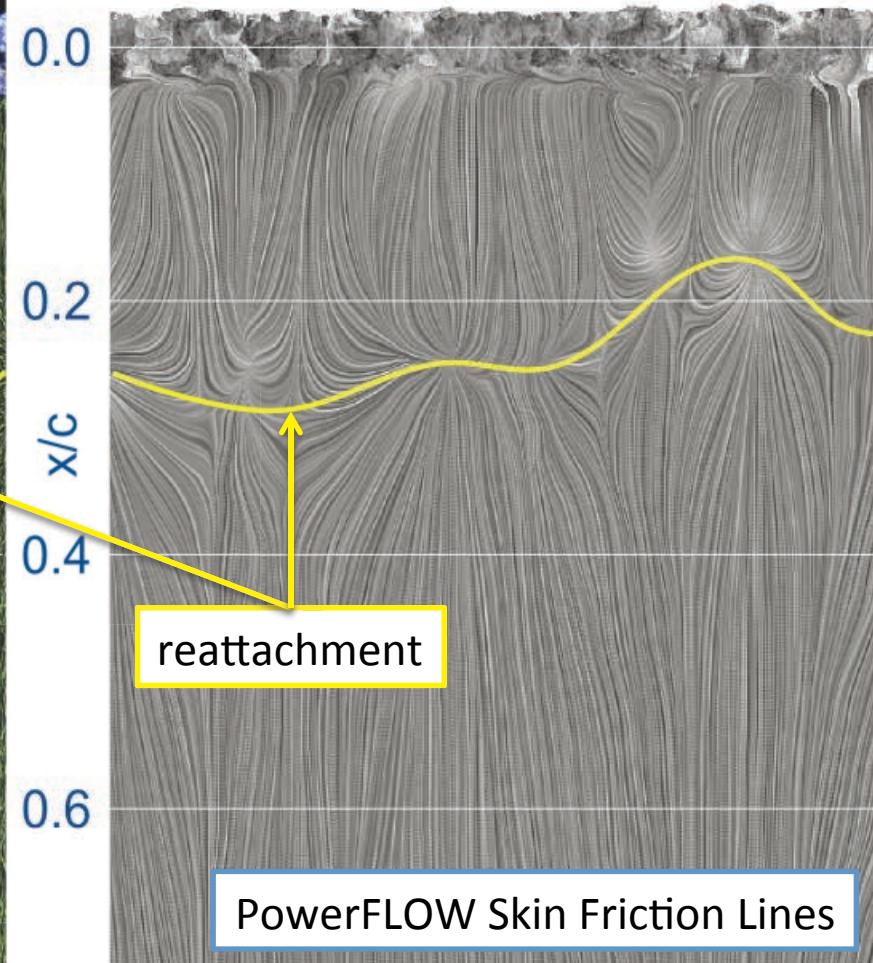
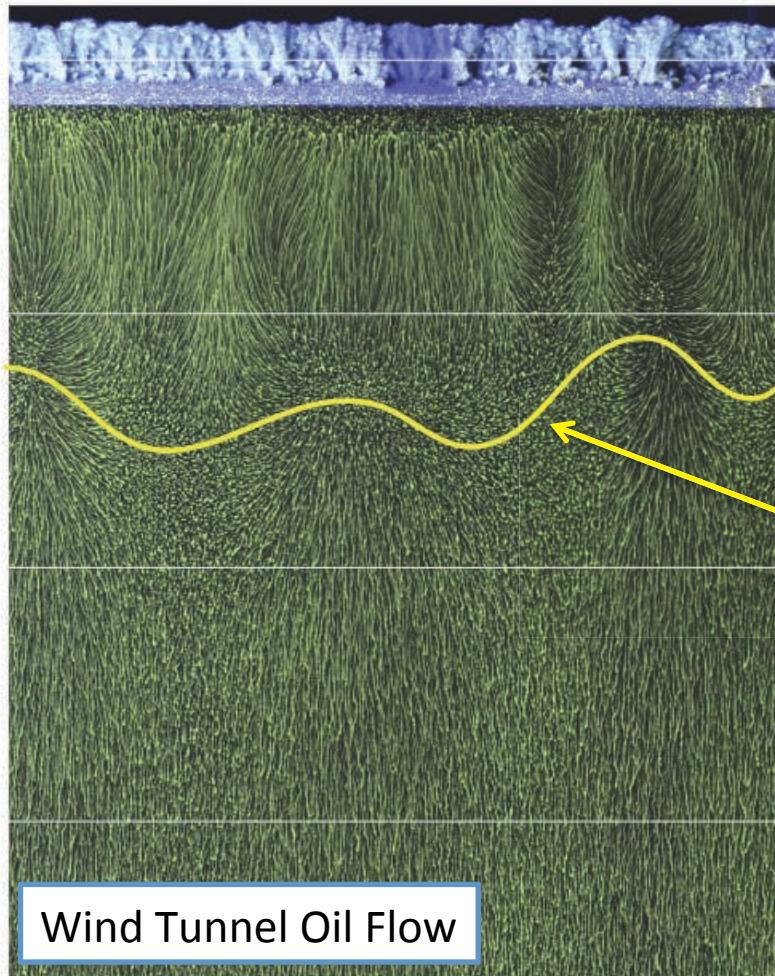
Aerodynamic Simulation of Realistic 3D Ice Shapes



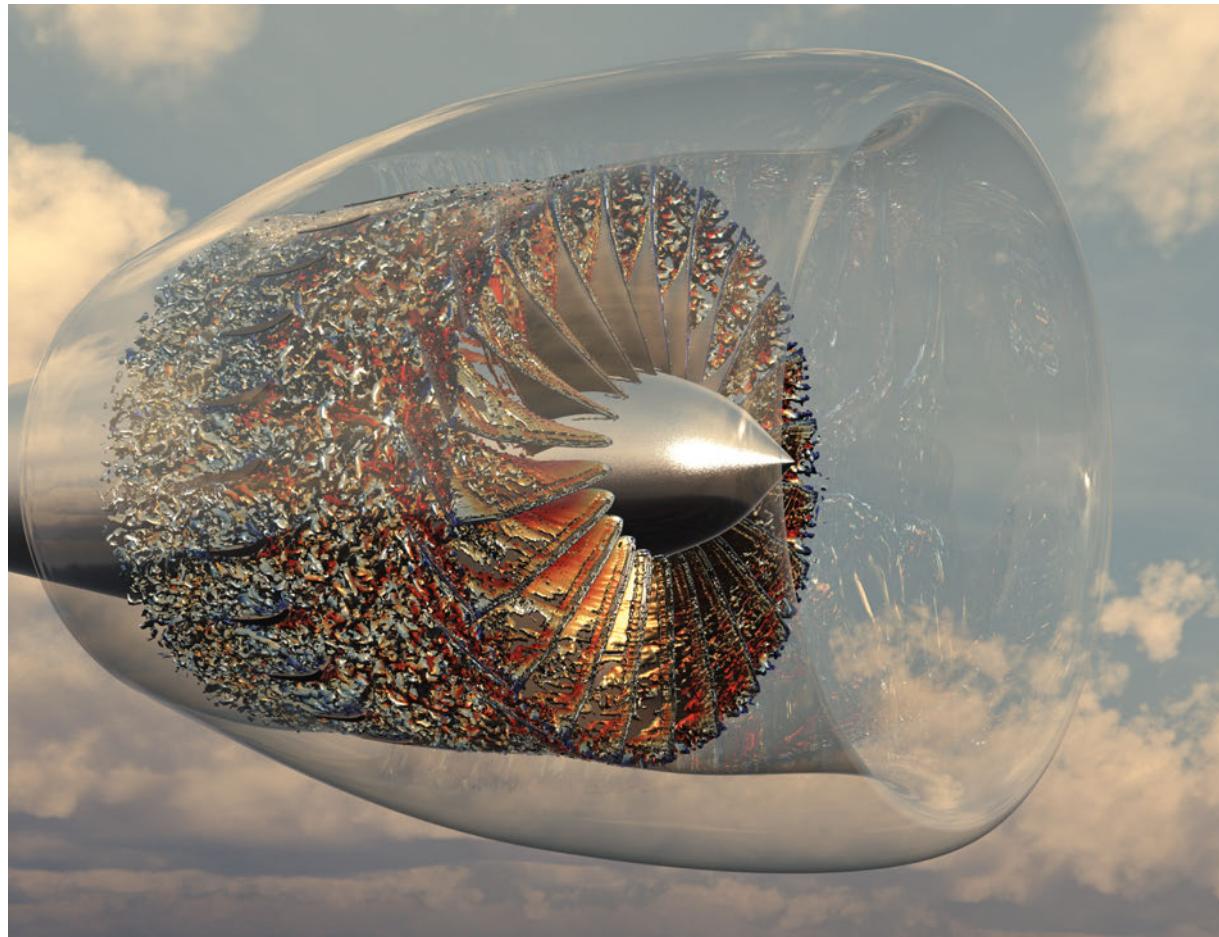
3D Ice Shapes provided by NASA/Glenn



3D Ice Shape – Surface Flow Visualization

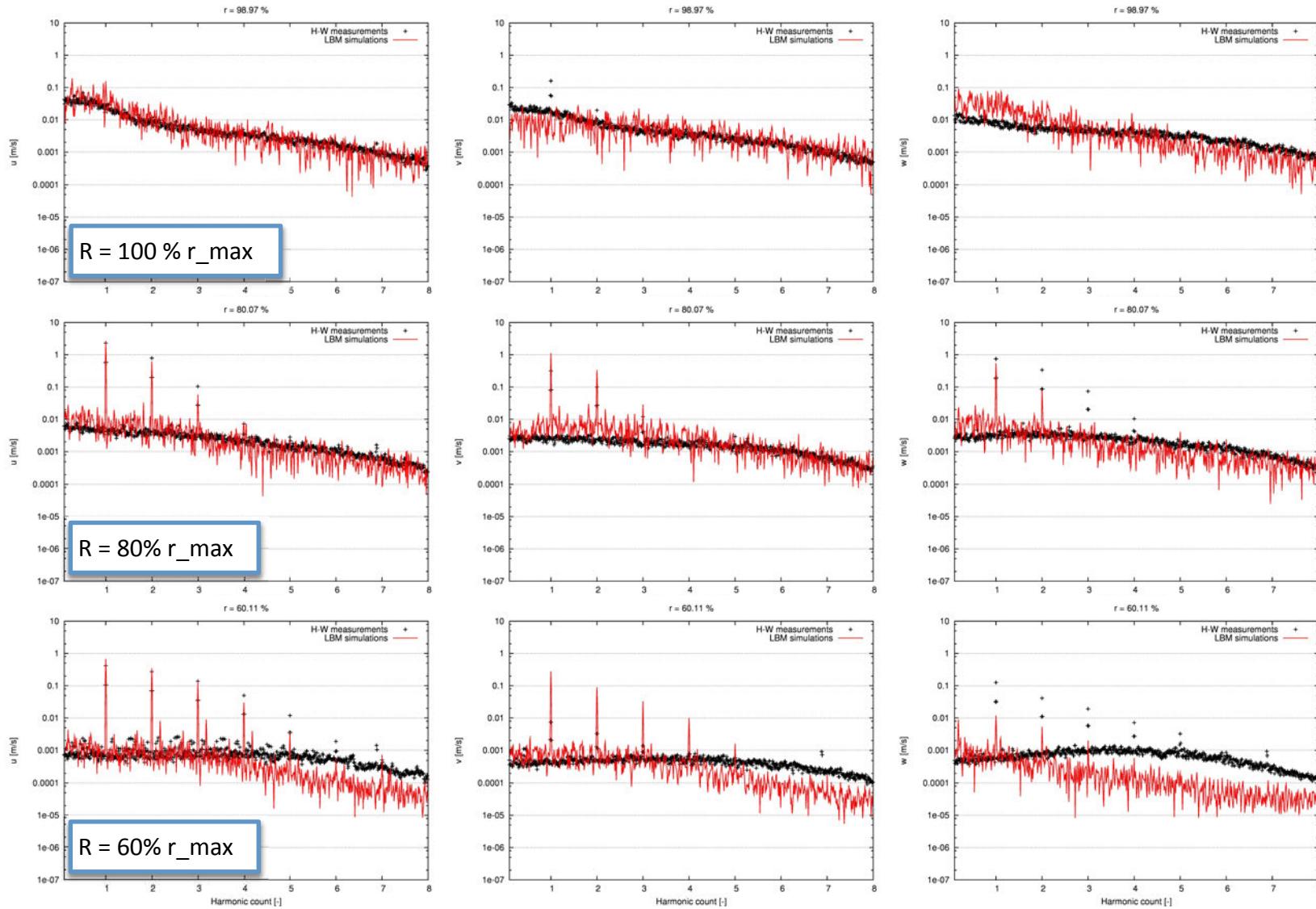


Fan Noise: RC2 Fan/OGV Configuration

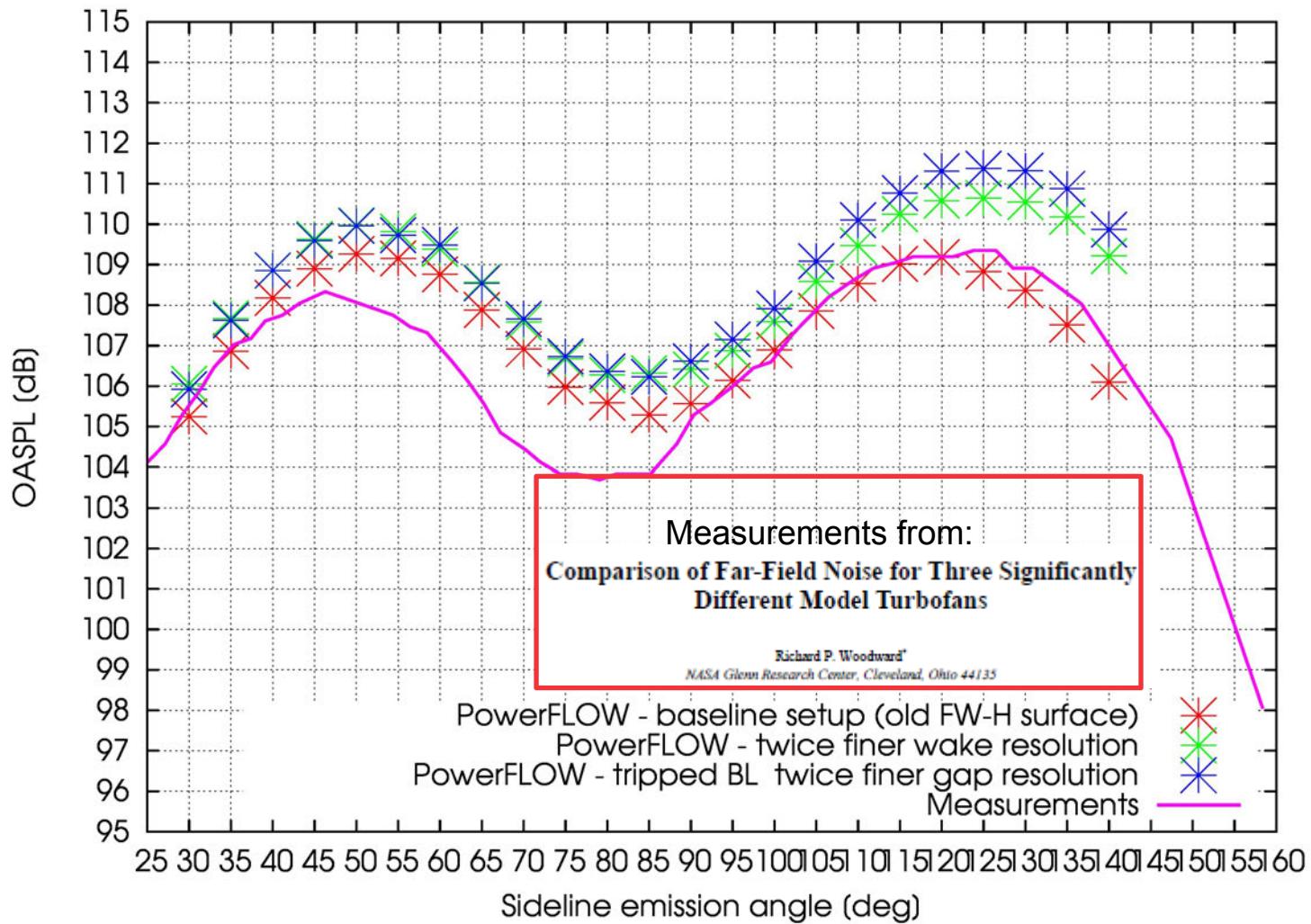


 **Exa**

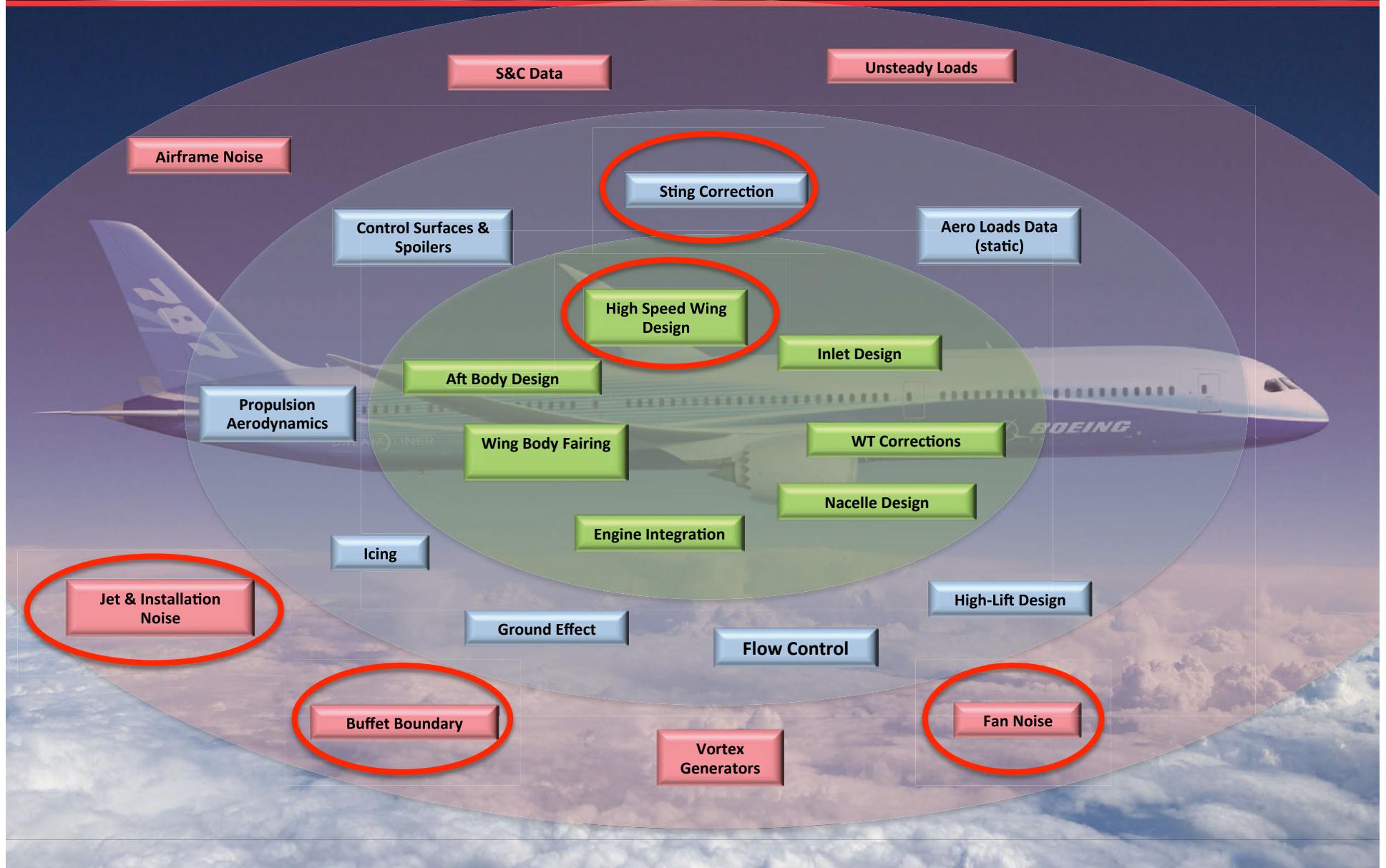
Flow results between rotor & stator – comparison with NASA measurements



Far-field noise results



High Speed Applications



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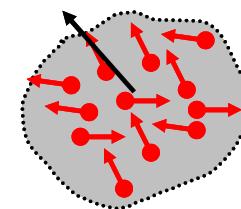


Kinetic theory: Basics

Boltzmann kinetic theory describes fluid behaviour based on particle density distribution function

$$f(\bar{x}, \bar{c}, t)$$

particle number density at time t and position x with velocity c



Boltzmann Equation:

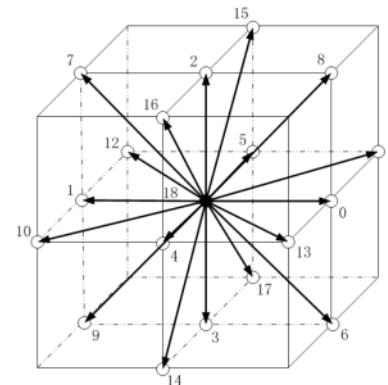
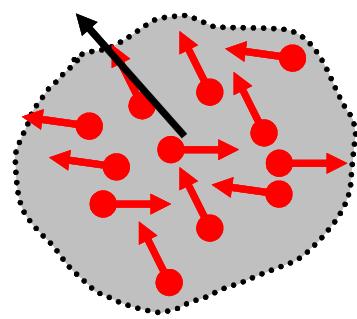
$$\frac{\partial}{\partial t} f(\bar{x}, \bar{c}, t) + \bar{c} \cdot \nabla f(\bar{x}, \bar{c}, t) = \Omega$$

- LHS represents advects of particle distribution in space at fixed velocity for each c
- RHS defined the collision process that involves inter-particle interactions
- Collision process can be modeled as simple relaxation to its equilibrium state (e.g. the BGK form*)



Lattice Boltzmann Methods

Discretization in space and time, using a finite set of discrete particle velocity values to represents the hydrodynamic properties*:



D3Q19 lattice

Lattice Boltzmann Equation :

$$f_i(\bar{x} + \bar{c}_i, t+1) - f_i(\bar{x}, t) = \Omega_i(\bar{x}, t)$$

BGK form of collision:

$$\Omega_i(\bar{x}, t) = -\frac{1}{\tau} [f_i(\bar{x}, t) - f_i^{eq}(\bar{x}, t)]$$

Lower order LBE model recovers the Navier-Stokes equation at the nearly incompressible limit**



*Chen & Doolen 1998 **Qian et al. 1992., Chen et al 92

Lattice Boltzmann Methods

- Macroscopic quantities are direct results of the moments of particle density distributions

- *Density* $\rho(\bar{x}, t) = \sum_i f_i(\bar{x}, t)$

- *Velocity* $\rho(\bar{x}, t)\bar{u}(\bar{x}, t) = \sum_i \bar{c}_i f_i(\bar{x}, t)$

- ...

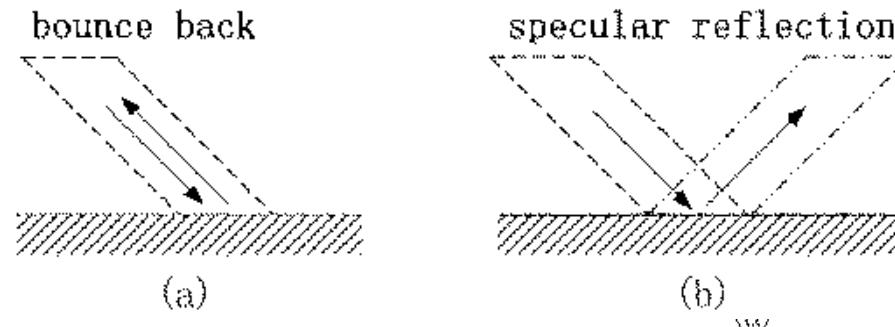
- Pressure obeys the thermally perfect gas law

$$P = \rho\theta \quad \theta = RT$$



LBM Surface Dynamics

- No-slip/freeslip BCs are achieved via bounce-back/specular-reflection process*



- Momentum flux across the fluid-solid interface corresponds to surface pressure and wall shear stress*

$$\mathbf{F} = p\hat{n} + \tau_w\hat{t} \sim \sum_{m \in Pgrams,out} \left[(\mathbf{c}_m f_m)^{out} - \sum_{n \in Pgrams,in} (\mathbf{c}_n f_n)^{in} \right]$$

- Generalized slip algorithm has been formulated to realize turbulence wall boundary conditions (slip velocity with imposed wall frictions)

Remarks

- Properly constructed LBE models can recover N-S physics, ... and beyond!
 - LBM is a very accurate solver with extremely low numerical dissipation
 - *Convection is exact due to the limited discrete velocities*
 - Very efficient for performing time dependent flow simulations
 - A very robust solver due to realizability, and stability condition is *a priori* guaranteed
-
- Plus Special Features of LBM Implementation in PowerFLOW
 - *Near wall physics (surfel concept)*
 - *LBM-VLES turbulence model*
 - *Variable resolution*
 - *Efficient parallel implementation*
 - *Extension to supersonic speeds*



LBM-VLES Turbulence Model

- LBM-VLES turbulence model concept
 - *Single turbulence model for all flow conditions*
 - *Resolved turbulent structures are simulated directly, unresolved scales are modeled*
 - *Subgrid contributions are accounted for by an effective relaxation time scale*

$$f_i(\vec{x} + \vec{c}_i \Delta t, t + \Delta t) - f_i(\vec{x}, t) = -\frac{1}{\tau} (f_i - f_i^{eq}) \quad \Leftrightarrow \quad F_i(\vec{x} + \vec{c}_i \Delta t, t + \Delta t) - F_i(\vec{x}, t) = -\frac{1}{\tau_{\text{effective}}} (F_i - F_i^{eq})$$

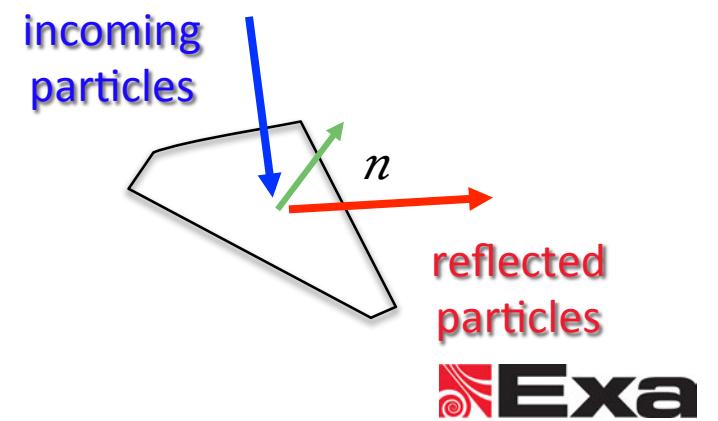
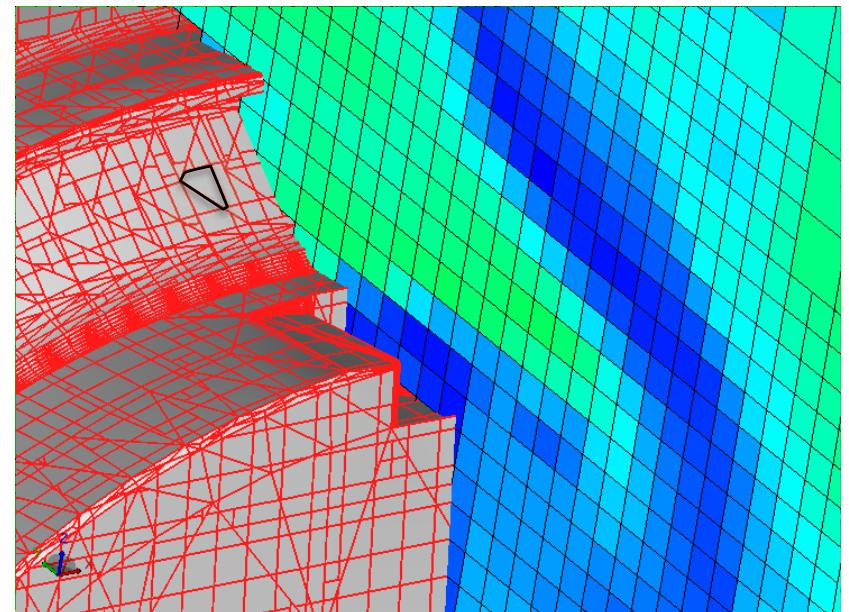
- Modification of turbulent flow relaxation time
 - *Derived from a systematic renormalization group (RNG) procedure*
 - $\tau_{\text{effective}} = \tau_0 + \tau_{\text{turb}}, \quad \tau_{\text{turb}} = C_\mu \frac{k^2}{\varepsilon} \frac{1}{T \sqrt{1 + \tilde{\eta}^2}}, \quad \tilde{\eta} = \psi(\eta_s, \eta_\Omega, \eta_h, \dots)$
 - *where $\tilde{\eta}$ is the time scale of mean flow (strain, swirl, buoyancy,)*
 - *Effectively reduces eddy-viscosity in regions of high vortical fluctuations (e.g. separated regions)*
 - *Conceptually similar to DDES & SAS*
- LBM-VLES contains HOT to account for non-linearity of the Reynolds stress



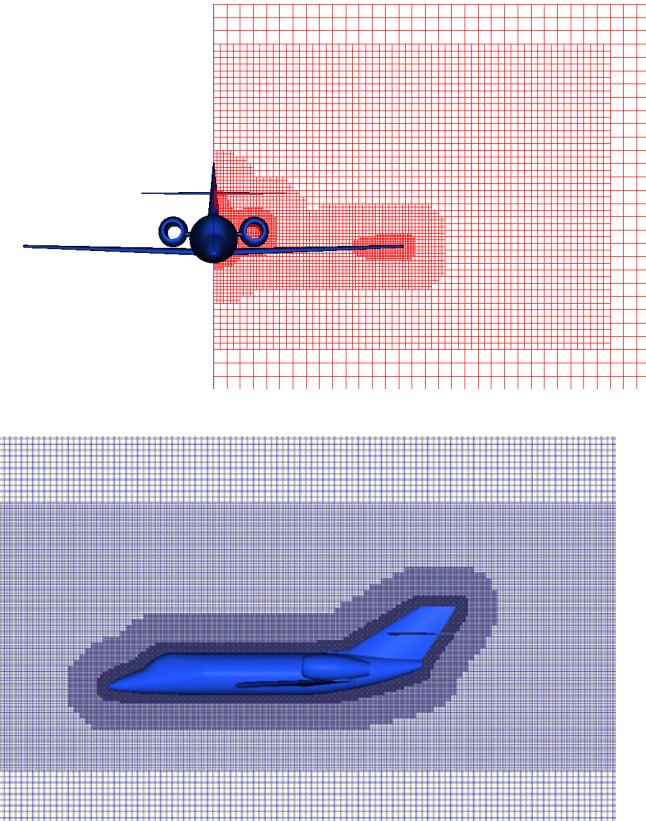
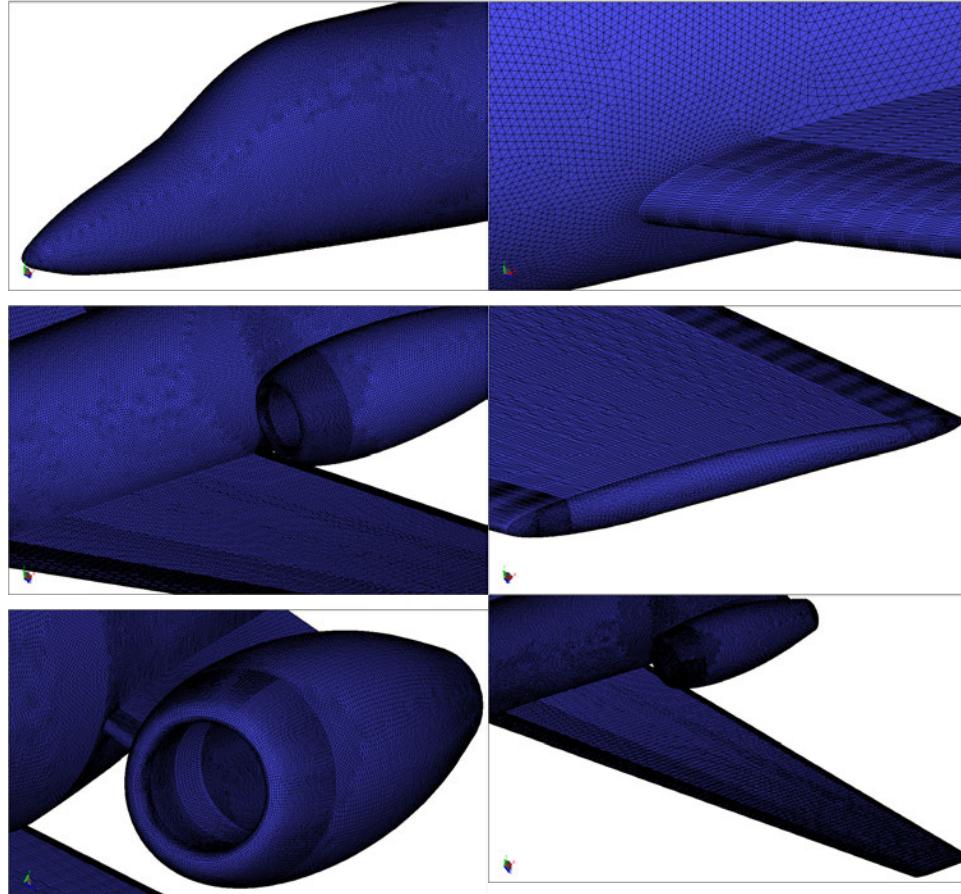
Near Wall Physics in PowerFLOW

Surfel Concept

- Arbitrary orientation & shape of elements
- Near wall Sampling
 - All needed weights pre-computed based on near wall volume elements
 - Ensure Conservation
- Momentum exchange
 - Correspond to changes in pressure and friction
- Second Order Accuracy
- Extended wall model for high Re#
 - Including pressure gradient effects



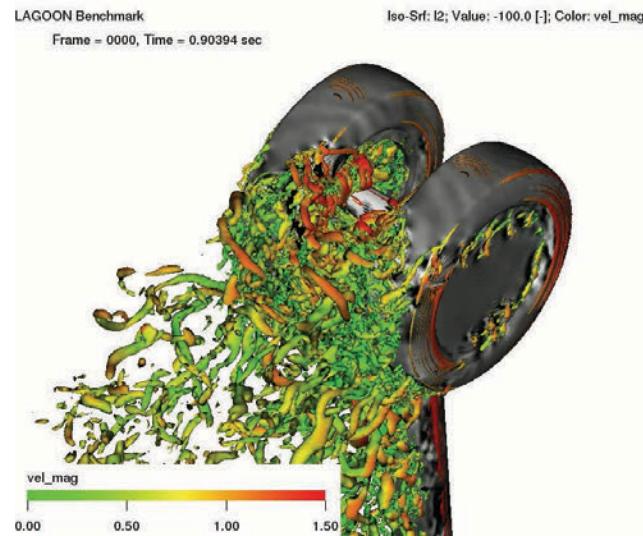
Typical Cartesian Grids Generation



Once surface grids and regions of refinement are defined, volume grid generation is fully automatic



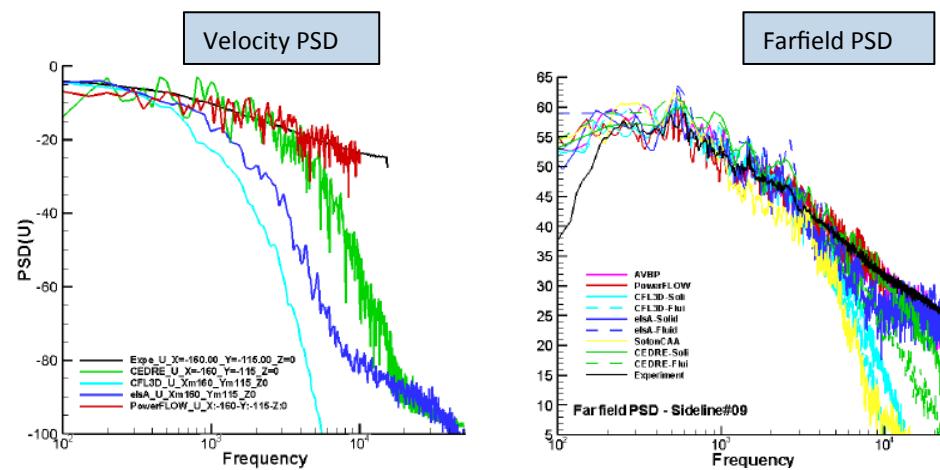
Efficient Parallel Implementation



Lagoon (BANC-III)

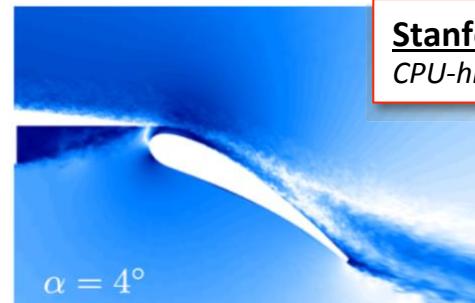
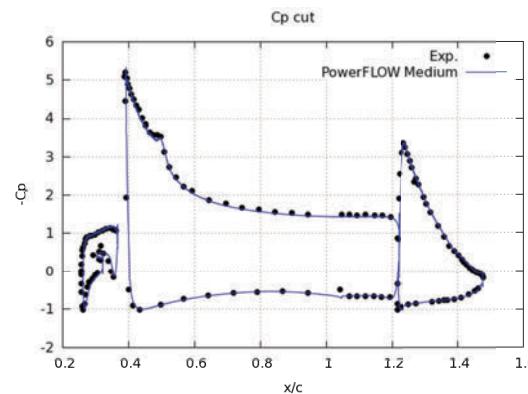
	Power-FLOW	CFL3D	CEDRE
Turb. Model	VLES	MDDES	ZDES
Number of Elements	123M	43M	61M
Number of Procs.	276	240	480
CPU-hrs for 1s simulated time*	21,000	854,000	1,960,000

* Manoha (Onera), Caruelle (Airbus), AIAA-2015



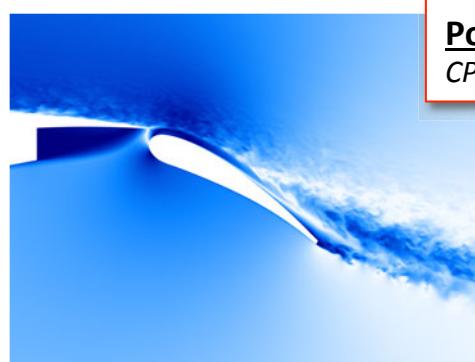
exa

Efficient Parallel Implementation



Stanford WMLES*

CPU-hrs: 17,000,000**



CPU-hrs: 5,000**

* Bodart, Larson, Moin, "Large eddy simulation of high-lift devices", AIAA 2013-2724.

** CPUh normalized for 1 flow pass and a span of 1 chord

*** Simulations executed in collaboration with NASA



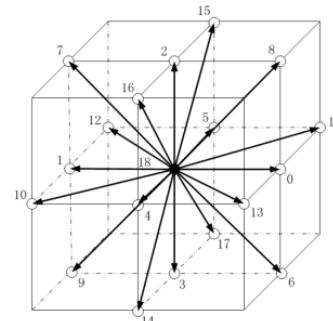
Extension of LBM to Transonic/High speed Flows

- Rigorous Theory based on Hermite Expansions (Shan et al, 1998, 2006)
 - *Projection of LBM in Hermite Polynomials*
 - Expansion coefficients are the moments of distribution function
 - No assumption on small Ma# or constant Temperature
 - *Truncate the expansion to certain order*
 - *Represent solution in Velocity Space*

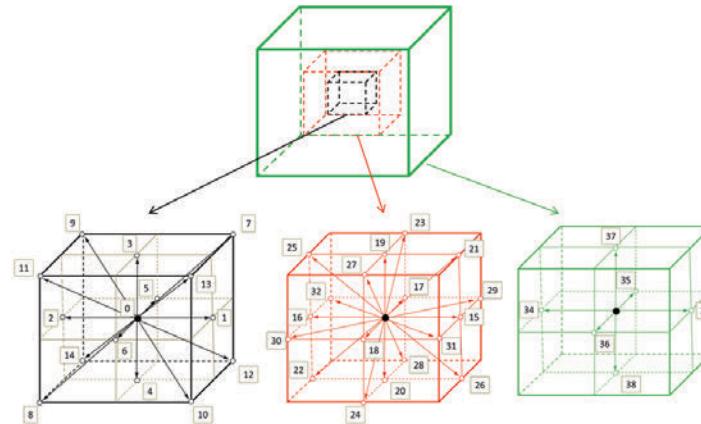


Extension of LBM to Transonic/High speed Flows

- High order multi-speed LBE models (D3Q27, D3Q39, D3Q125 ...)



D3Q19 Model
 $\text{Ma}_{\infty} \sim 0.4$ ($\text{Ma}_{\text{local}} \sim 0.99$)



Hybrid D3Q39 Model $\text{Ma}_{\text{max}} \sim 2.0$

- Hybrid approach to couple with thermal dynamics field

$$\partial_t S + u_\alpha \partial_\alpha S = -\frac{1}{\rho\theta} \partial_\alpha q_\alpha + \frac{\Phi}{\rho\theta}. \quad S = c_v \ln \left(\frac{\theta}{\rho^{\gamma-1}} \right)$$

Nie, X.B., Shan, X., and Chen, H., "Lattice-Boltzmann/Finite-Difference Hybrid Simulation of Transonic Flow", AIAA-Paper 2009-139



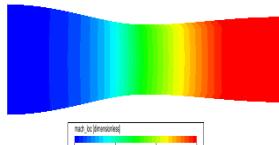
Outline

- Motivation: CFD Applications in Aerospace
- Overview of PowerFLOW Projects at NASA
- Theory & Background
 - *LBM*
 - *Turbulence model*
 - *Wall treatment*
 - *Extension to transonic flows*
- Transonic Code Validation and Application Examples
 - *Fundamental Validations*
 - *Industrial Application Examples*

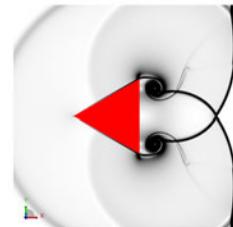


Transonic Code Validation & Application

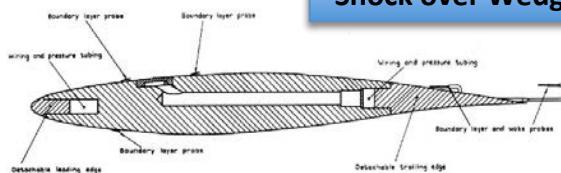
Fundamental Validations



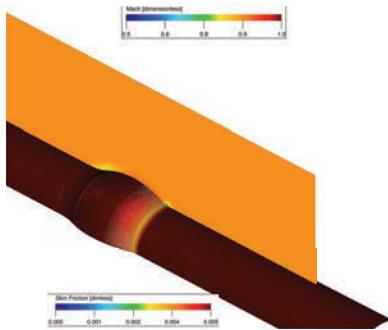
CDV nozzle



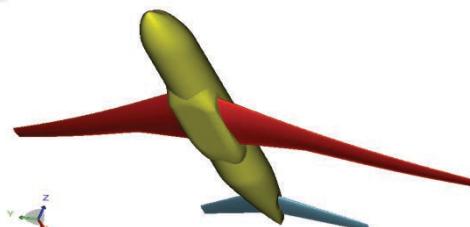
Shock over Wedge



RAE 2822 Airfoil

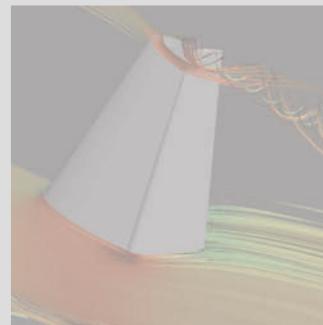


Transonic Bump

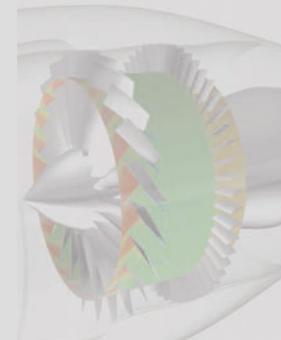


CRM

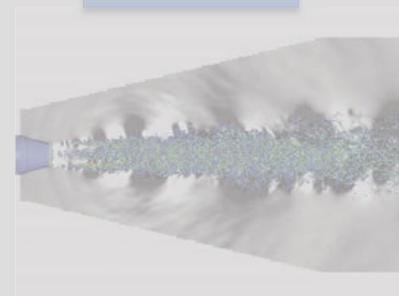
Industrial Applications



Fan Noise



Flow Control



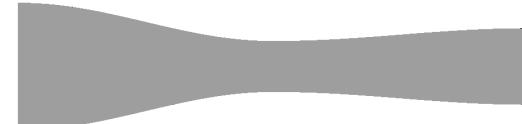
Jet Noise



Buffet

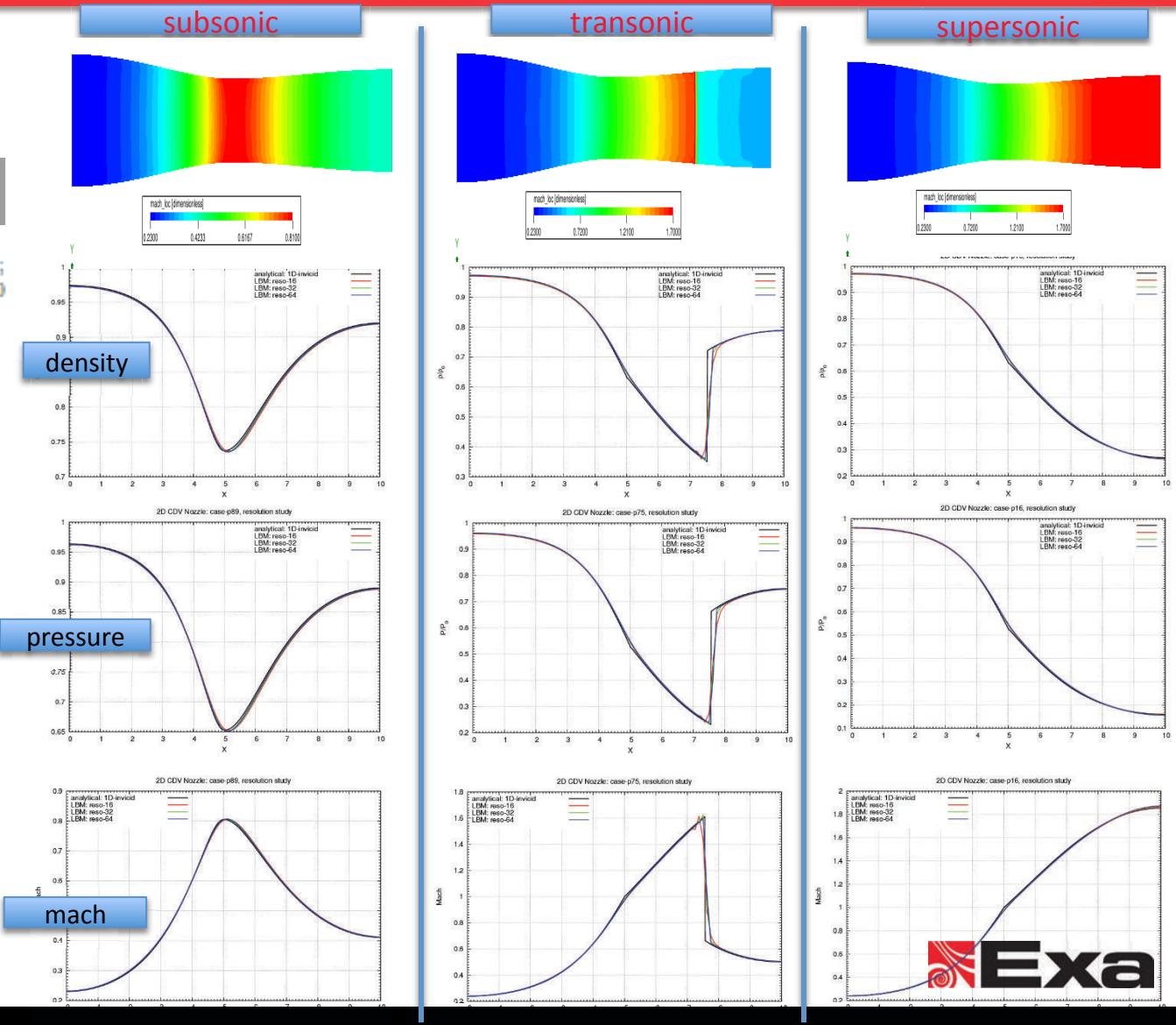
 **Exa**

2D CDV Nozzle (DNS): Sub-sonic/Transonic/Supersonic Flow Conditions



$$y(x) = \begin{cases} \pm[1.75 - 0.75 \cos((0.2x - 1.0)\pi)], & \text{if } x \leq 0.0; \\ \pm[1.25 - 0.25 \cos((0.2x - 1.0)\pi)], & \text{if } x > 0.0 \end{cases}$$

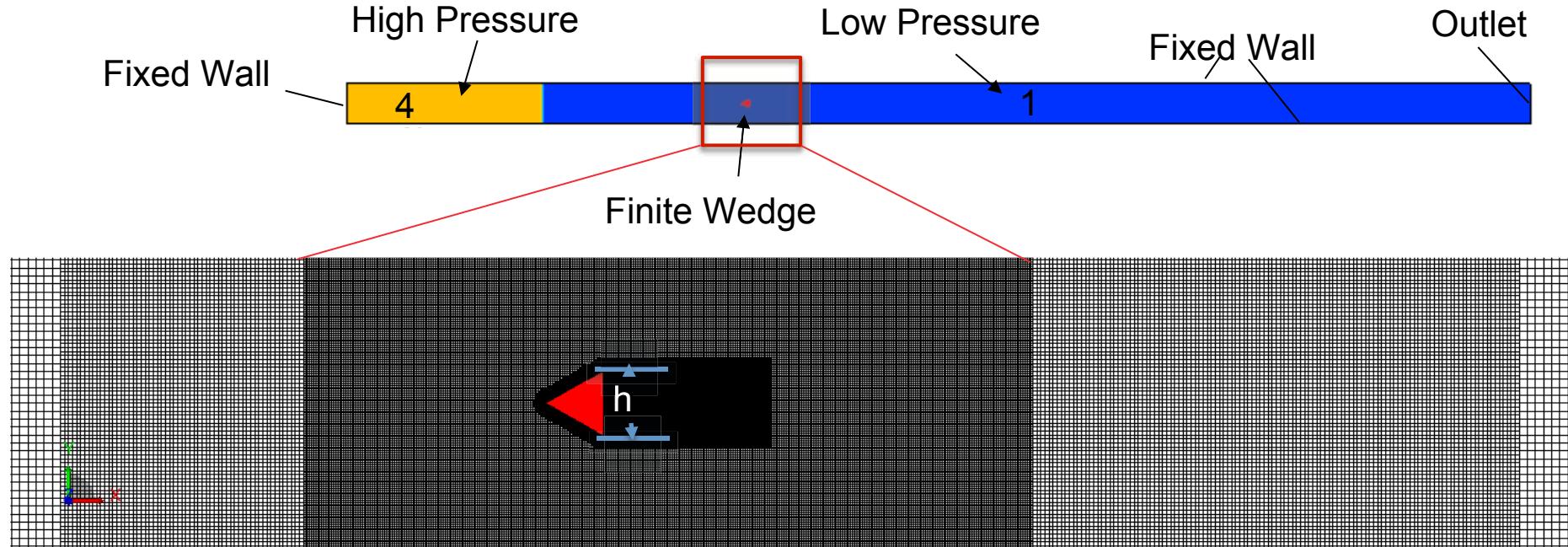
- Converge-Diverge Nozzle configuration
- Compared with analytical 1D invicid flow solution
- Simulated at low viscosity at various flow conditions



Collision of a Planar Shock with a Finite Wedge Setup

Shock Tube Setup

S-M. Chang and K-S. Chang: On the shock-vortex interaction in Schardin's problem, Shock Waves, 10:333-343, 2000



Initial Conditions:

$$P_4/P_1 = 4.0, T_4/T_1 = 1$$

Boundary Conditions:

No-slip walls
Outlet pressure P_1
Re 50000

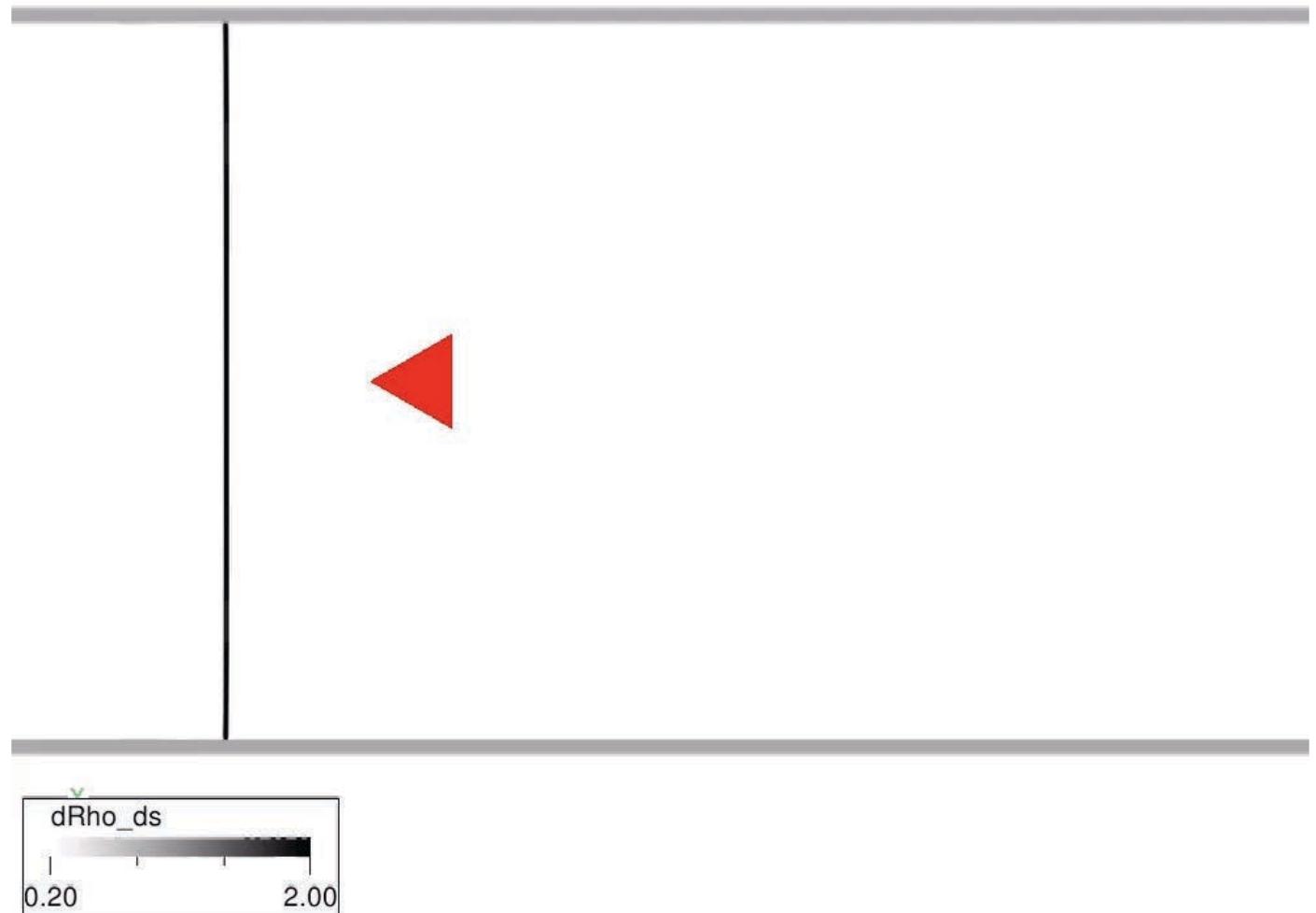
Grid Resolutions:

Coarse	$h/128$
Medium	$h/256$
Fine	$h/512$

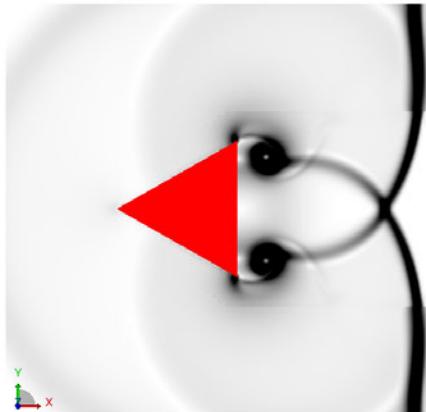
Collision of a Planar Shock with a Finite Wedge

Animation of the plane shock moving over the finite wedge (Animation time 0.001 s)

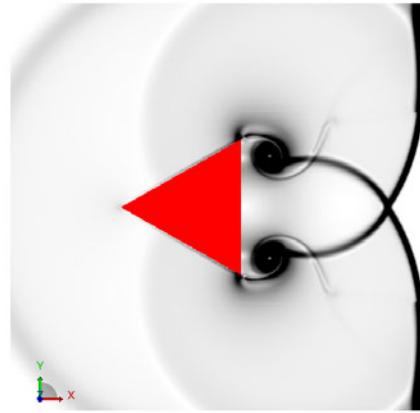
Planar shock moves
at Mach 1.34



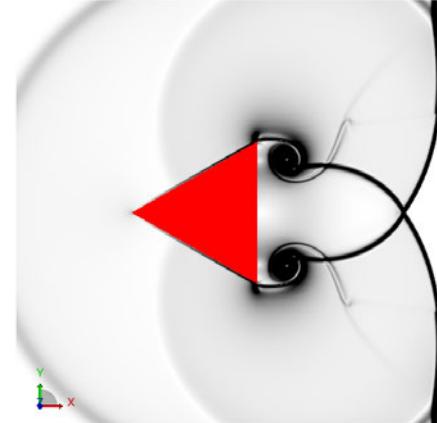
Collision of a Planar Shock with a Finite Wedge



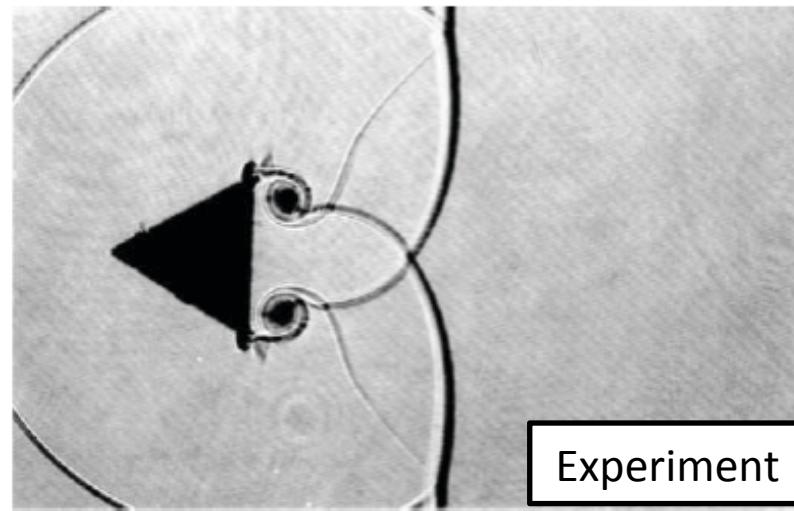
coarse



medium



fine



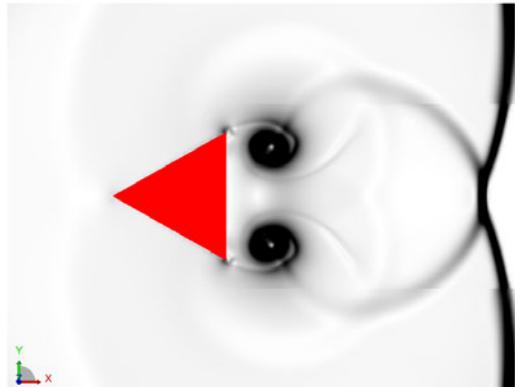
Experiment

$t = 91 \mu \text{ sec}$

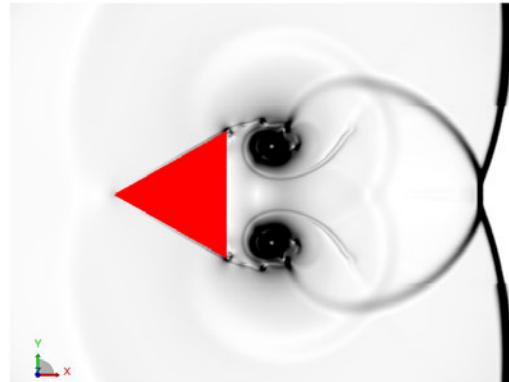
$t = 0$ corresponds to the instant, when the planar shock first collides with the finite wedge

 **Exa**

Collision of a Planar Shock with a Finite Wedge



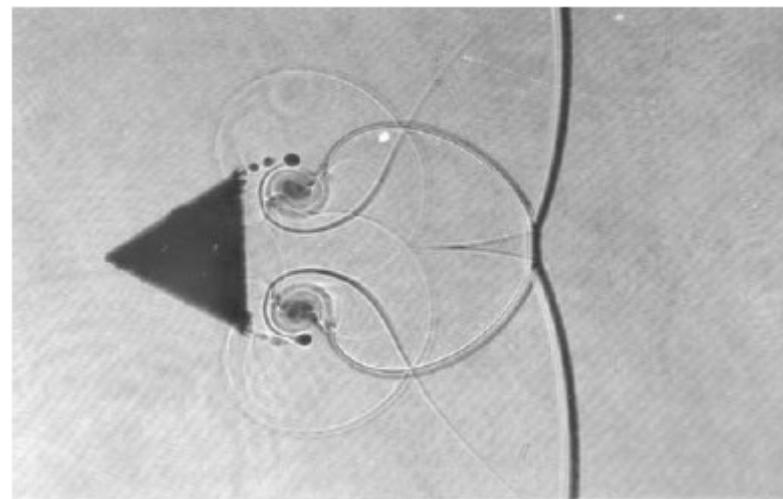
coarse



medium



fine



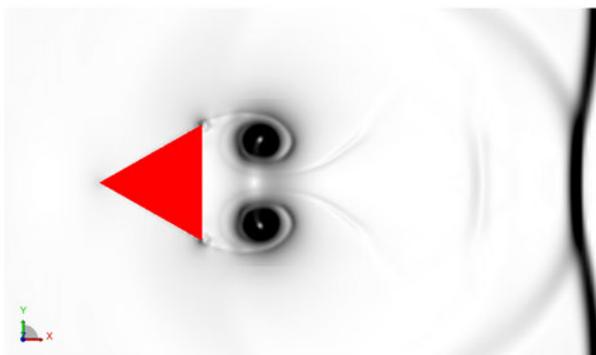
Experiment

$t = 128 \mu \text{ sec}$

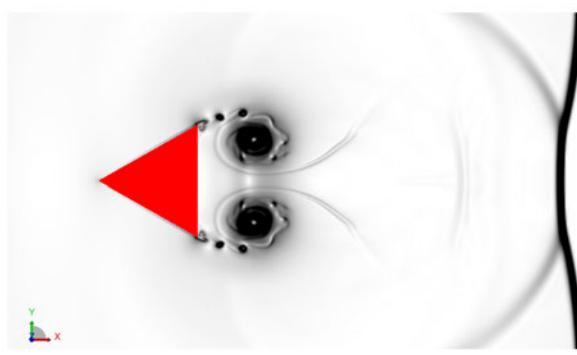
$t = 0$ corresponds to the instant, when the planar shock first collides with the finite wedge

 **Exa**

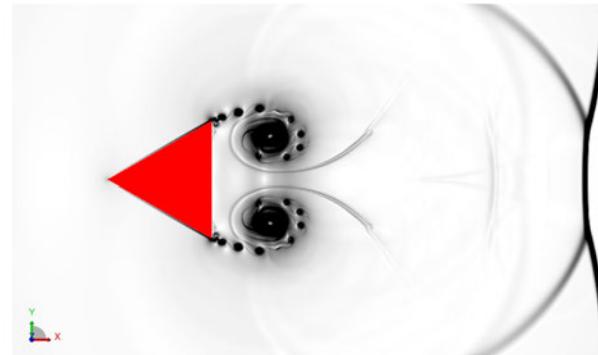
Collision of a Planar Shock with a Finite Wedge



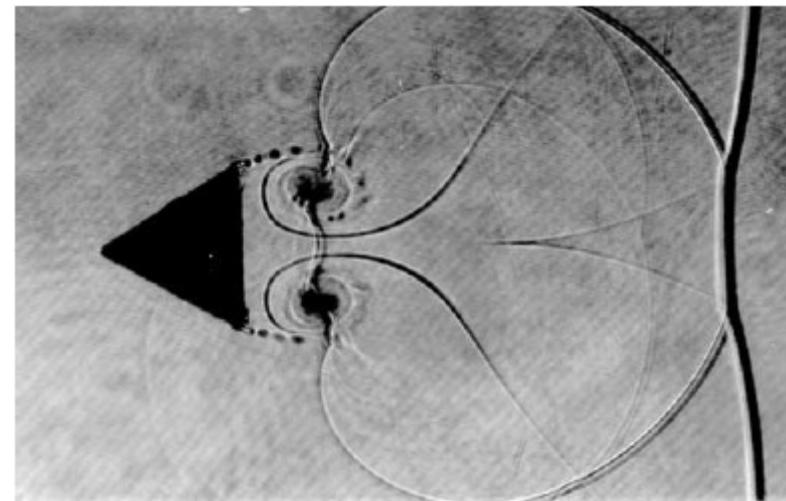
coarse



medium



fine



Experiment

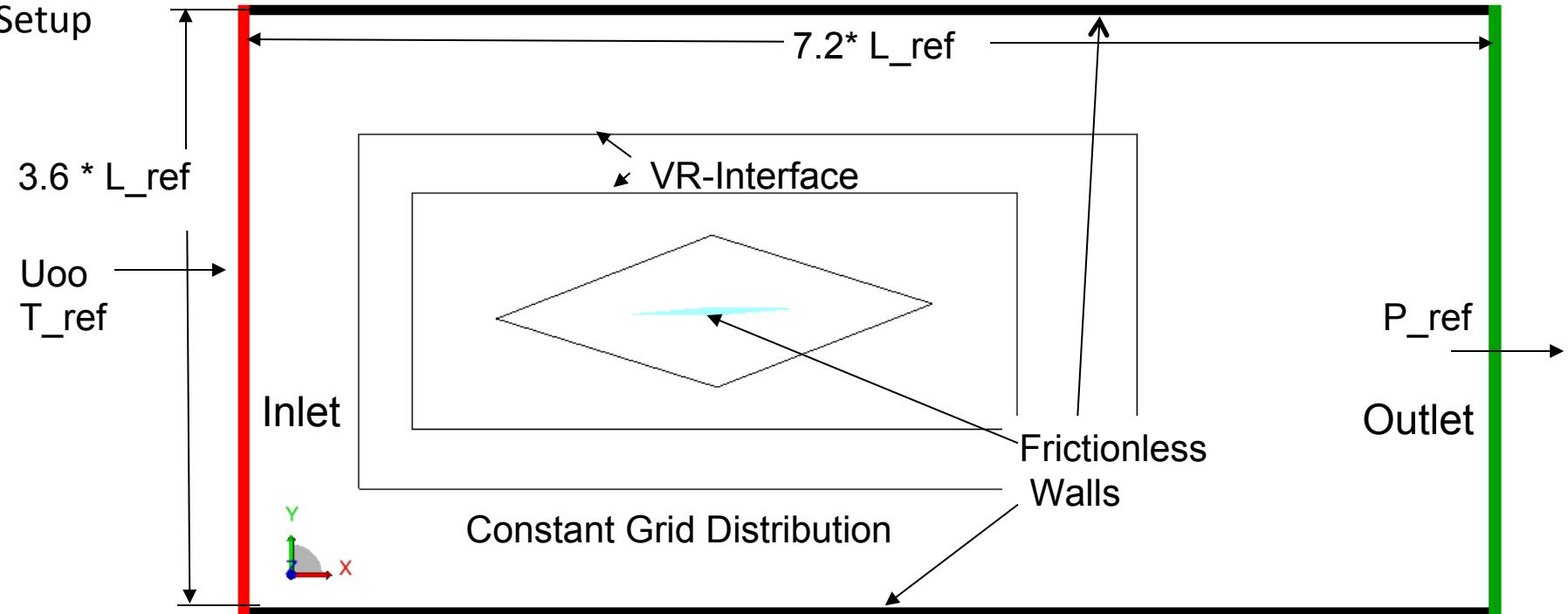
$t = 151 \mu \text{ sec}$

$t = 0$ corresponds to the instant, when the planar shock first collides with the finite wedge

 **Exa**

Supersonic Diamond Airfoil

Setup



Diamond Aifoil

AOA (Angle of Attack) = -2°

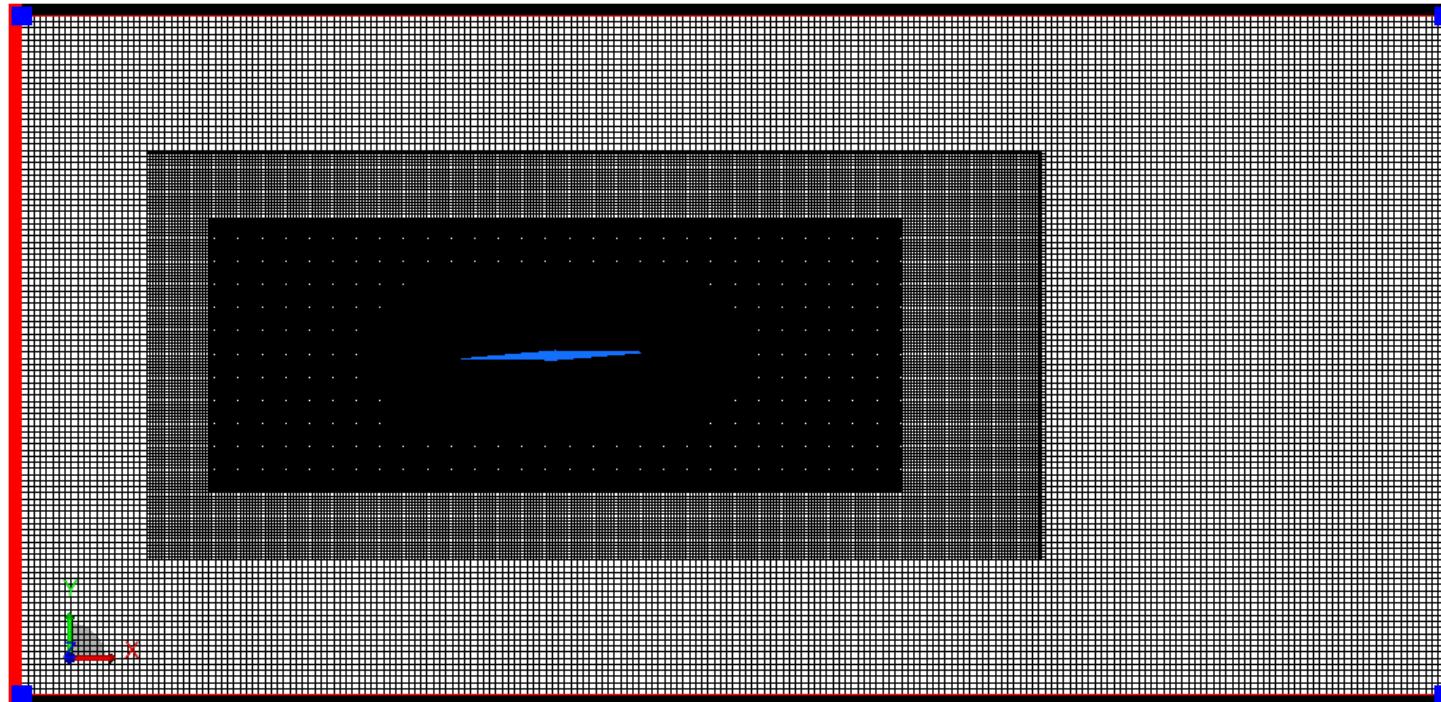
$$L_{ref} = 1 \text{ m}$$
$$\text{Area}_{ref} = 1 \text{ m}^2$$

2D-Turbulent-Simulation
 $M_{oo} = 1.4$
 $Re = 3.24E+07$

$$P_{ref} = 100000 \text{ Pa}$$
$$\rho_{ref} = 1.161 \text{ kg/m}^3$$
$$T_{ref} = 300^\circ \text{ K}$$
$$AOA = -2^\circ$$



Supersonic Diamond Airfoil



Grid

Resolution 512 per chord (coarse)

Voxel-Size $1000/512 = 1.95$ mm

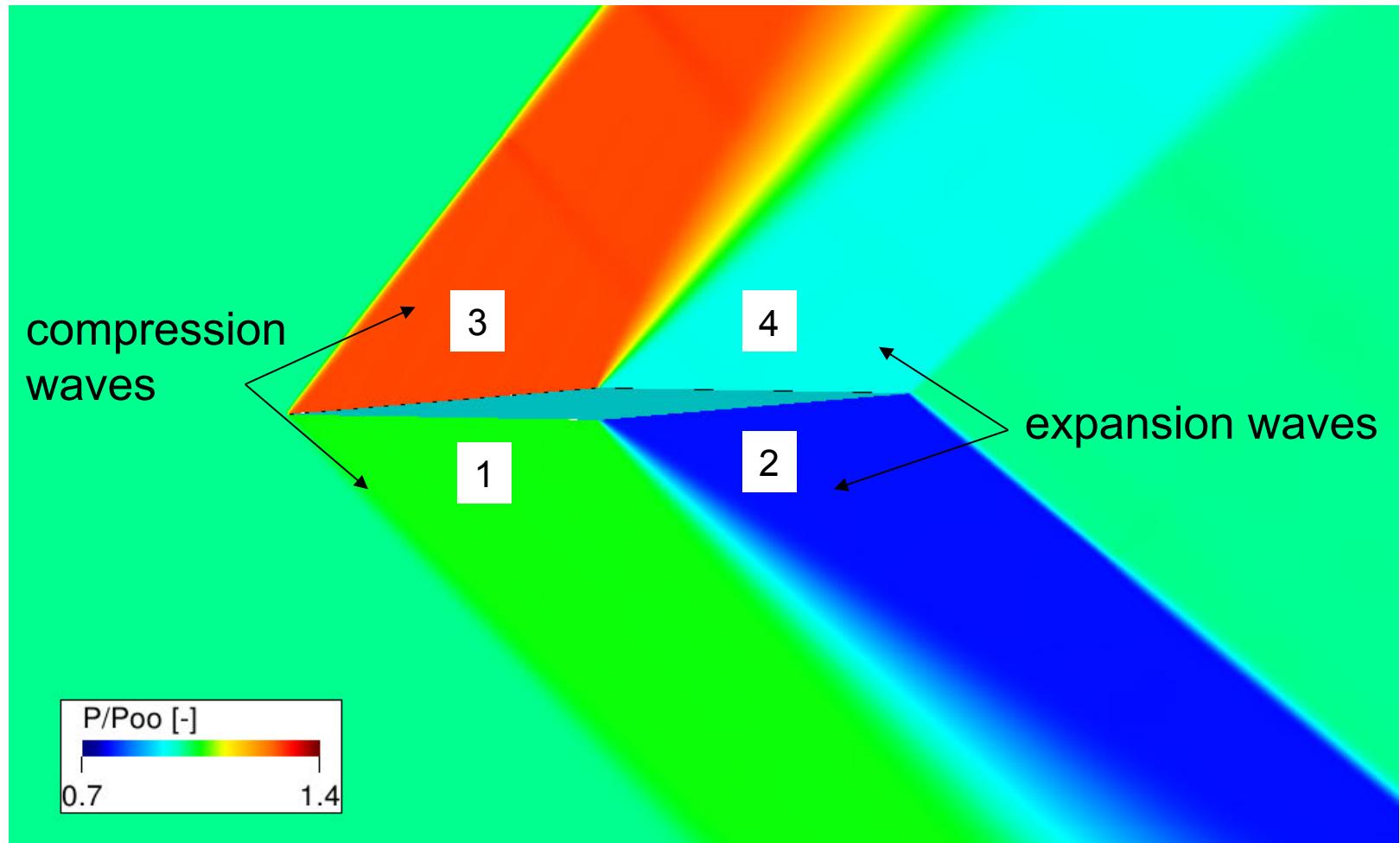
Total Voxels 1.46 Mill.

Fine Equivalent Voxels 1.01 Mill.



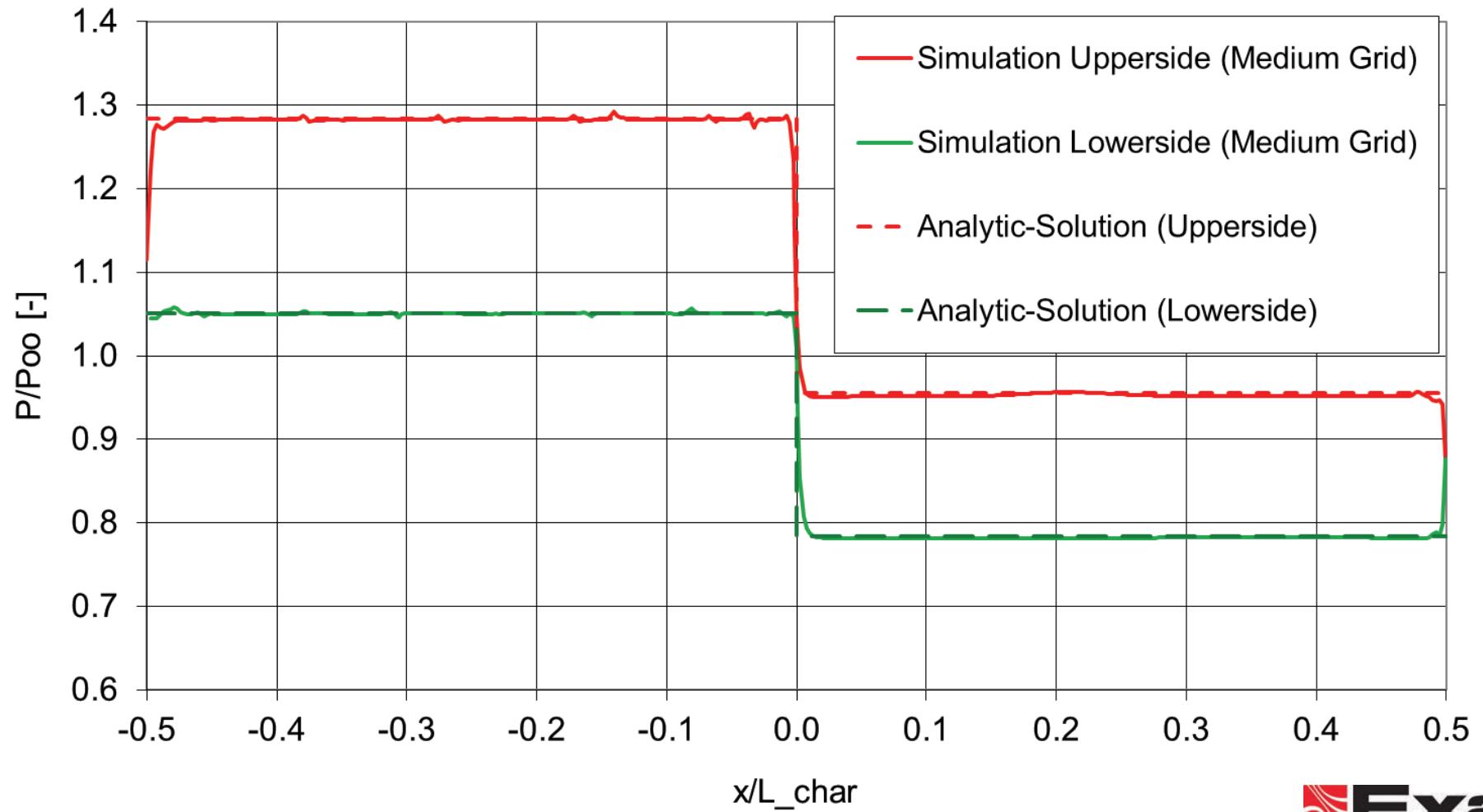
Supersonic Diamond Airfoil

Pressure Distribution for Moo 1.4 and AOA -2



Supersonic Diamond Airfoil

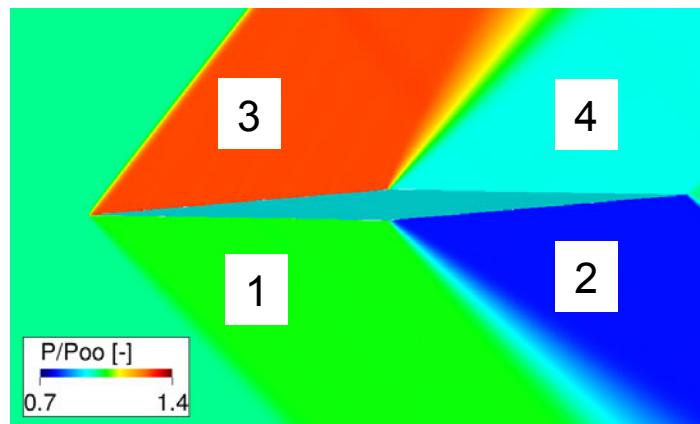
P/P₀₀ on the Upper- and Lowerside of the Diamond Airfoil at $M_\infty = 1.4$ and AOA -2°



Supersonic Diamond Airfoil

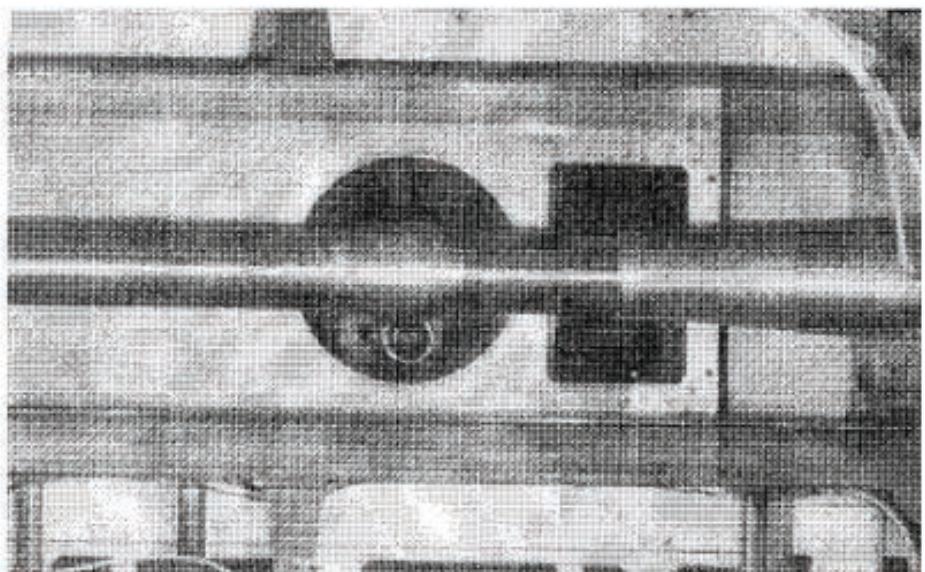
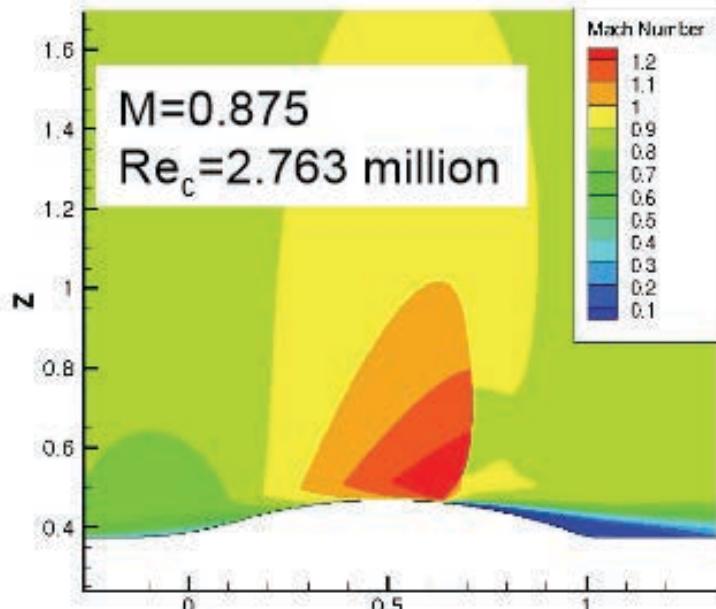
Angle of Attack AOA °	-2.0		
Inflow Mach Number Moo	1.4		
	Turbulent-Simulation		Analytic-Solution
Grid	Coarse	Medium	Fine
Lift Cl [-]	0.1471	0.1474	0.1463
Drag Cd [-]	0.0165	0.0165	0.0165
Pressure Relation P1/Poo[-]	1.0502	1.0501	1.0502
Pressure Relation P2/Poo[-]	0.7821	0.7819	0.7838
Pressure Relation P3/Poo[-]	1.2823	1.2820	1.2841
Pressure Relation P4/Poo[-]	0.9551	0.9555	0.9553
Mach Number M1 [-]	1.3617	1.3637	1.3661
Mach Number M2 [-]	1.5616	1.5625	1.5652
Mach Number M3[-]	1.2109	1.2165	1.2215
Mach Number M4 [-]	1.4241	1.4260	1.4267

Resolution coarse = 512 per chord
 Resolution medium= 768 per chord
 Resolution fine = 1024 per chord



Axisymmetric Transonic Bump

- Part of NASA's 40% challenge
- Includes shock-induced separation, widely-used dataset for many years, axi-symmetry removes 2D questions
- RANS typically overestimates separation bubble by 20-30%

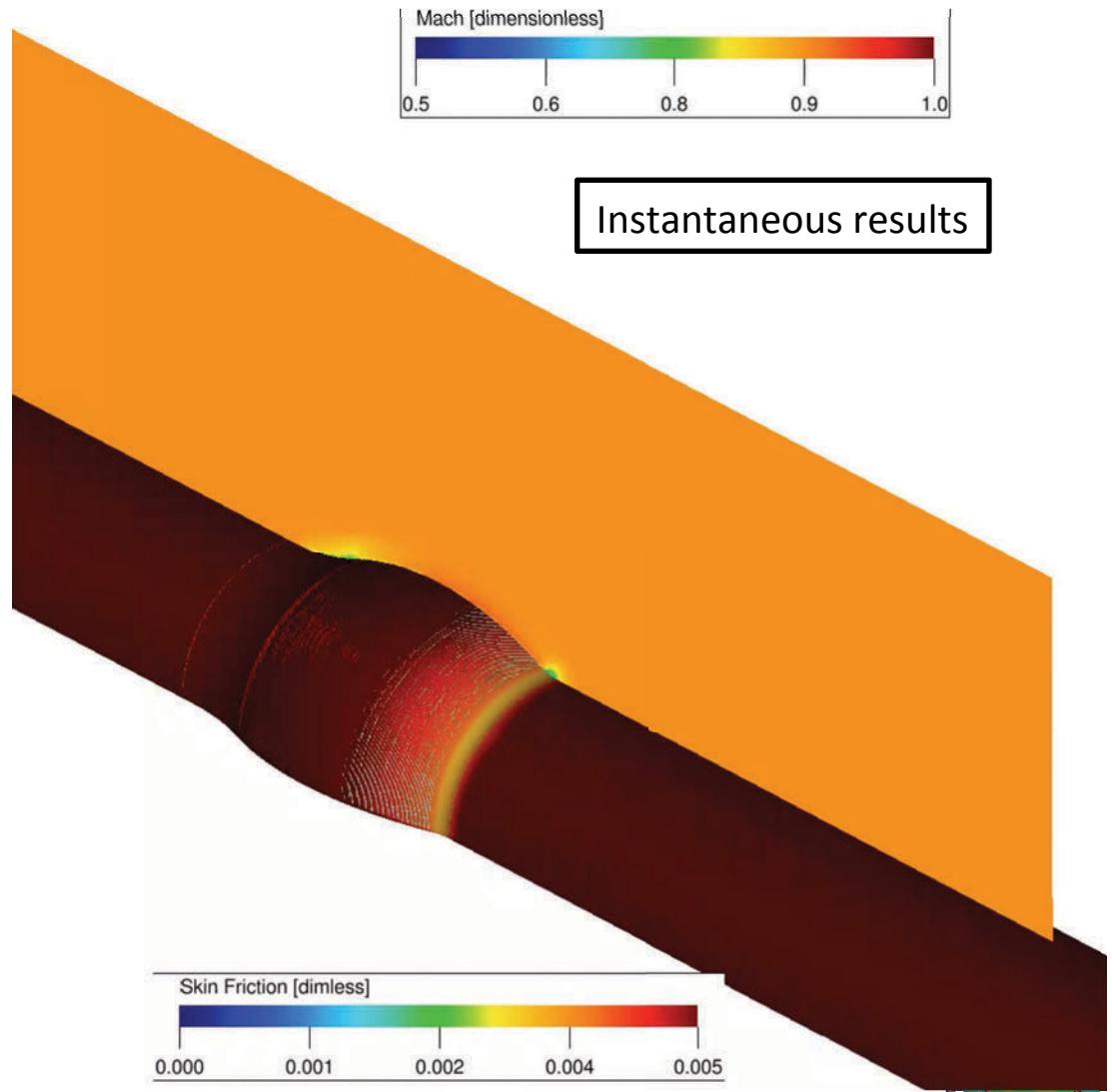


Bachalo, W. D., Johnson, D. A., "Transonic, Turbulent Boundary-Layer Separation Generated on an Axisymmetric Flow Model," AIAA Journal, vol. 24, no. 3, pp. 437-443, 1986.

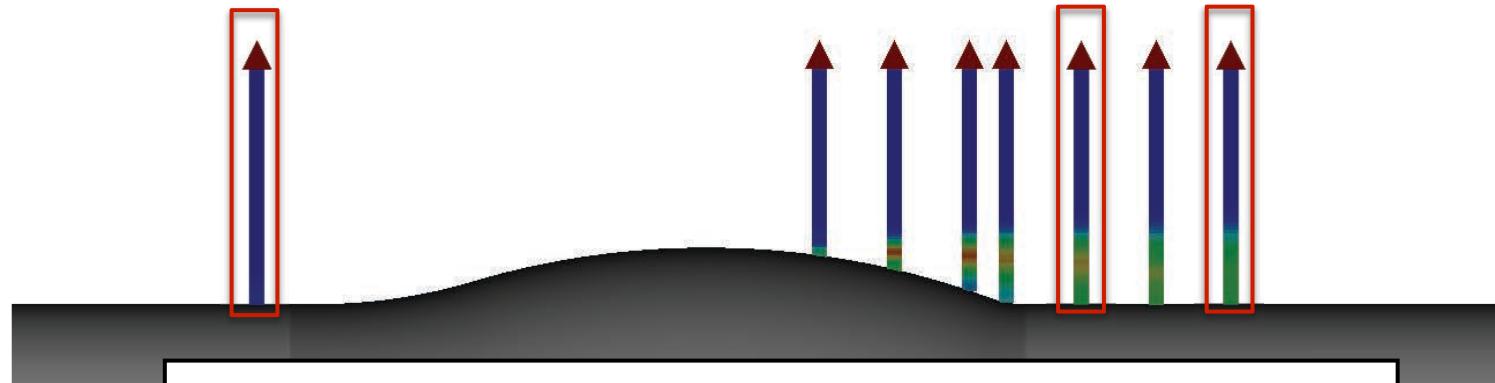
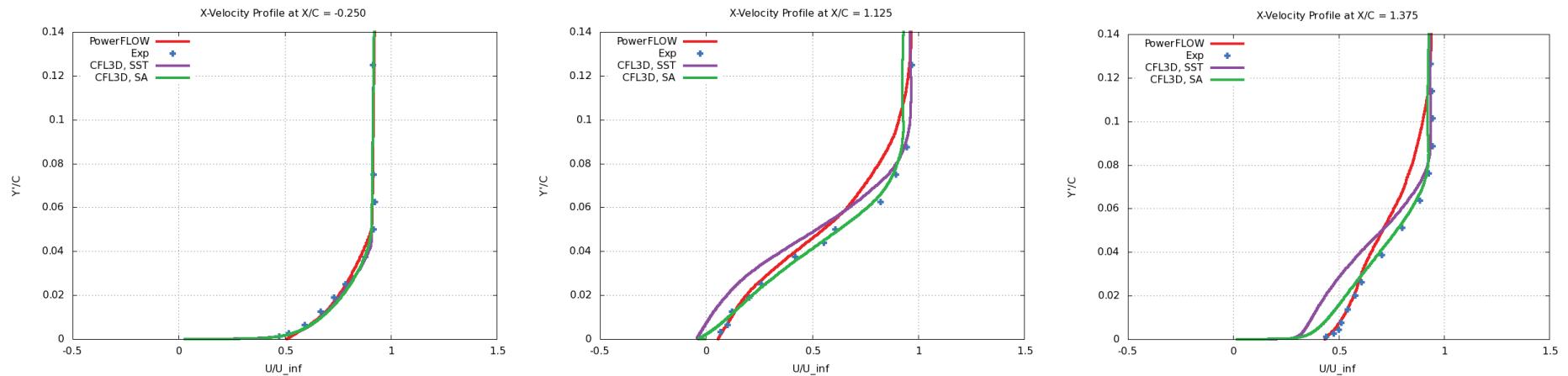


Axisymmetric Transonic Bump

- Volume cut shows location and sharpness of shock
- Skin friction contours indicate flow separation
- Iso-surfaces of λ_2 highlight resolved turbulent fluctuations in wake



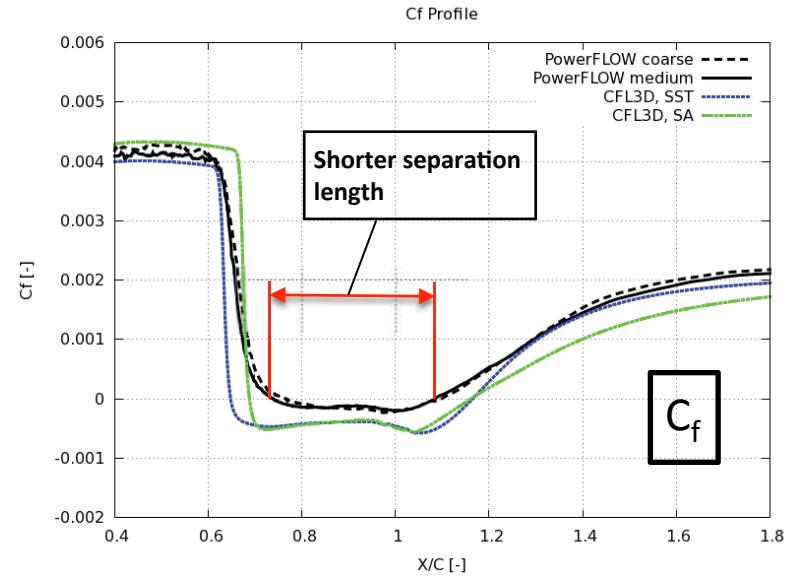
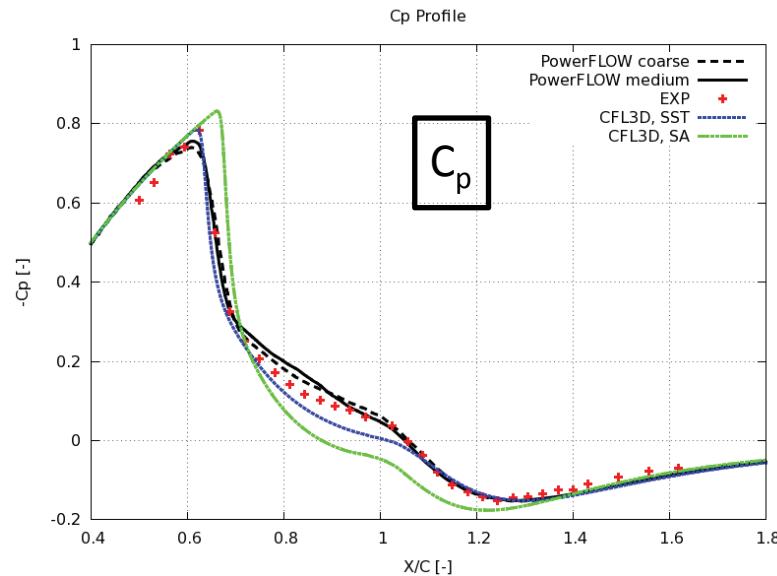
Axisymmetric Transonic Bump X-Velocity Profiles



Reference Results from : Rumsey, C. L., “Turbulence Modeling Resource,” <http://turbmodels.larc.nasa.gov>



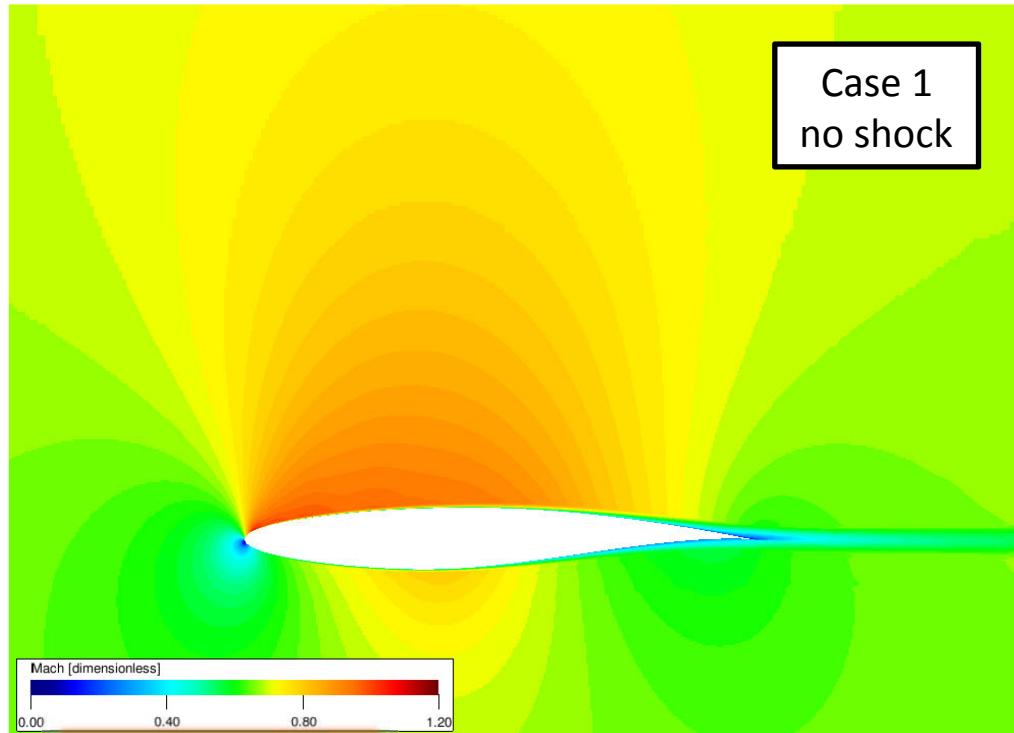
Axisymmetric Transonic Bump Pressure and Skin Friction Distribution



- Unsteady flow in separation after shock captured
- Improved prediction of separation length and skin friction compared to standard RANS



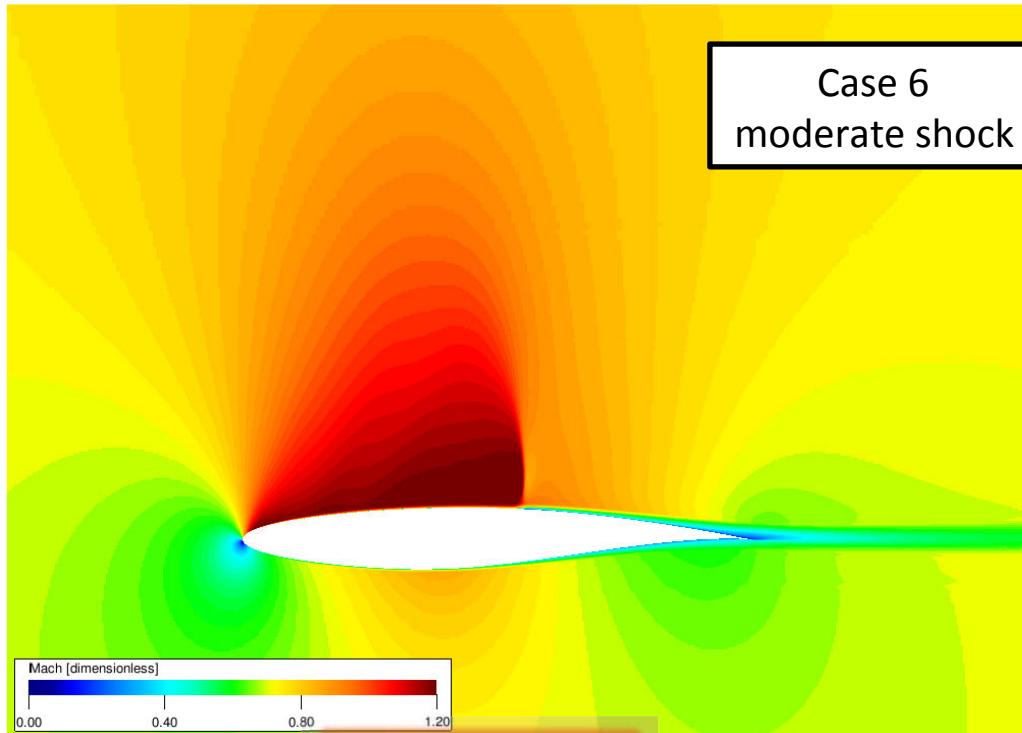
Transonic Flow over the RAE 2822 airfoil



	Case 1	Case 6	Case 9	Case 10
Ma [-]	0.676	0.729	0.73	0.75
AoA [°]	1.8148	2.4508	2.6873	2.7147
Re [10^6]	5.7	6.5	6.5	6.2



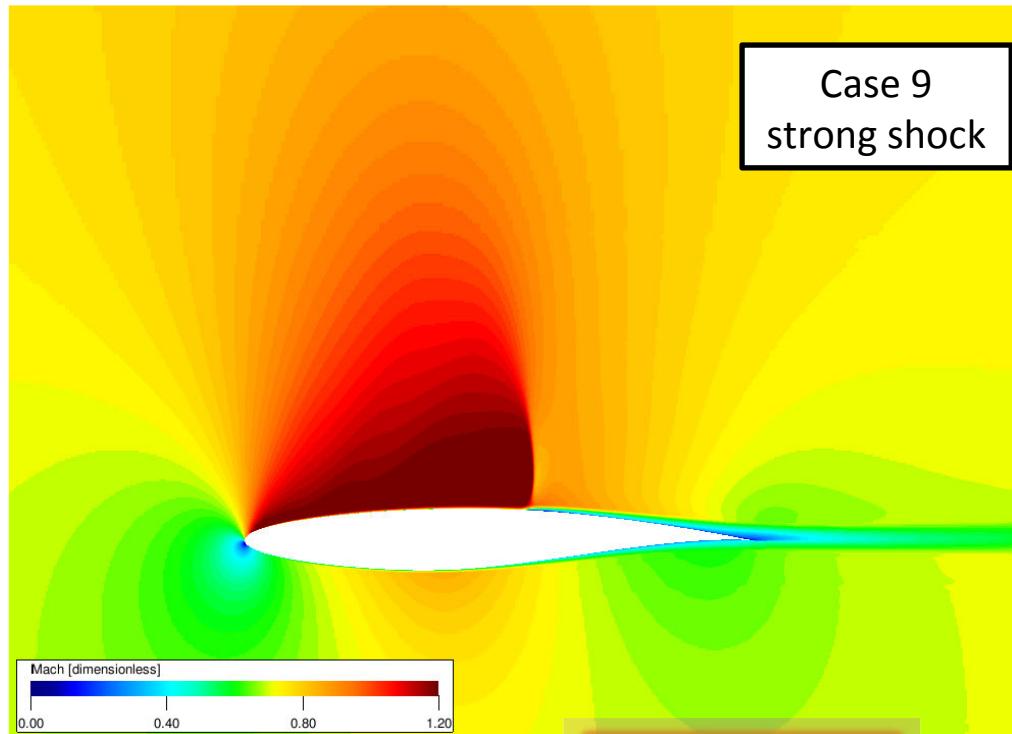
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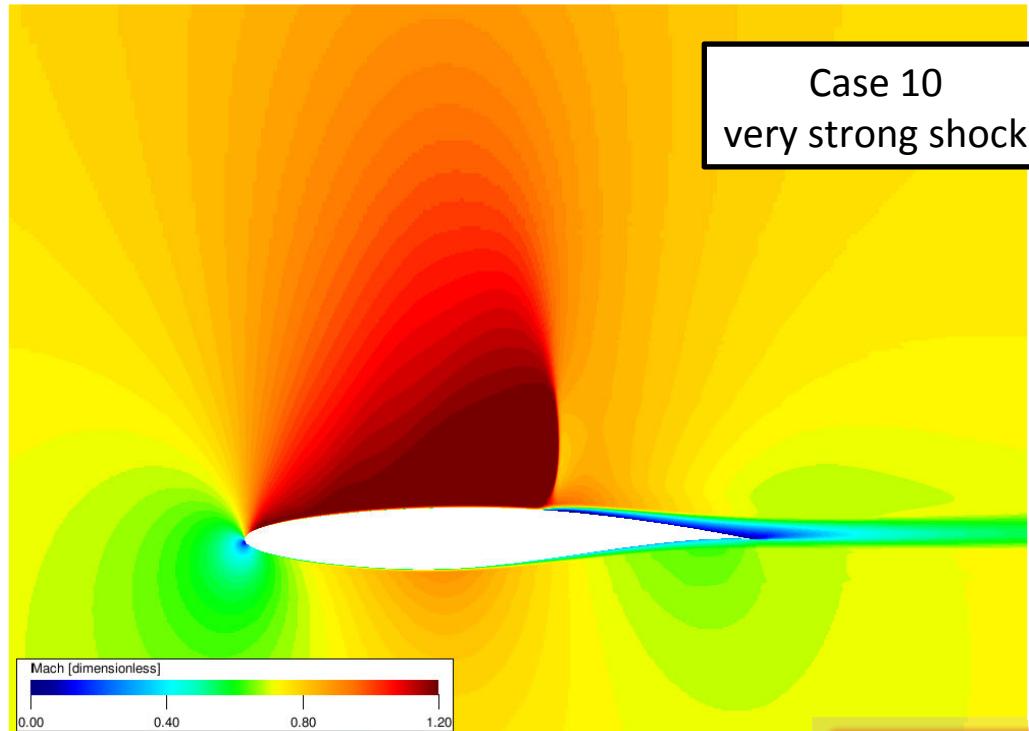
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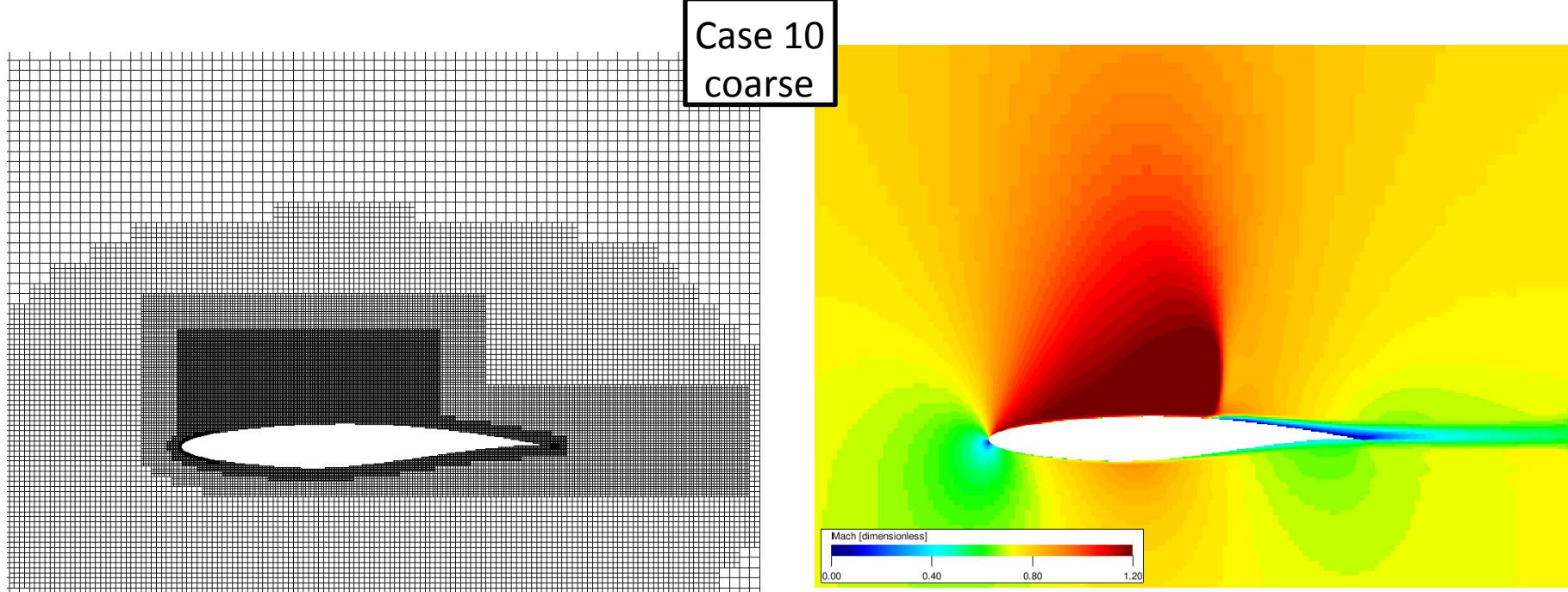
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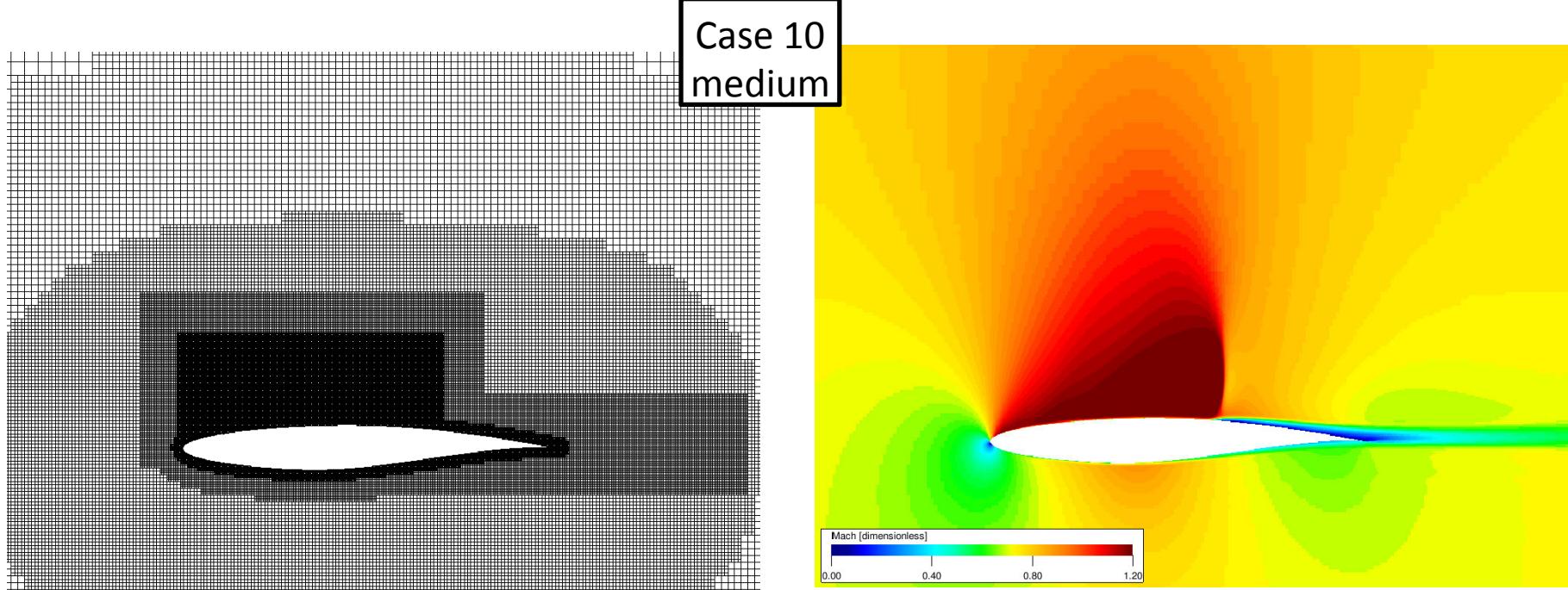


Transonic Flow over the RAE 2822 airfoil



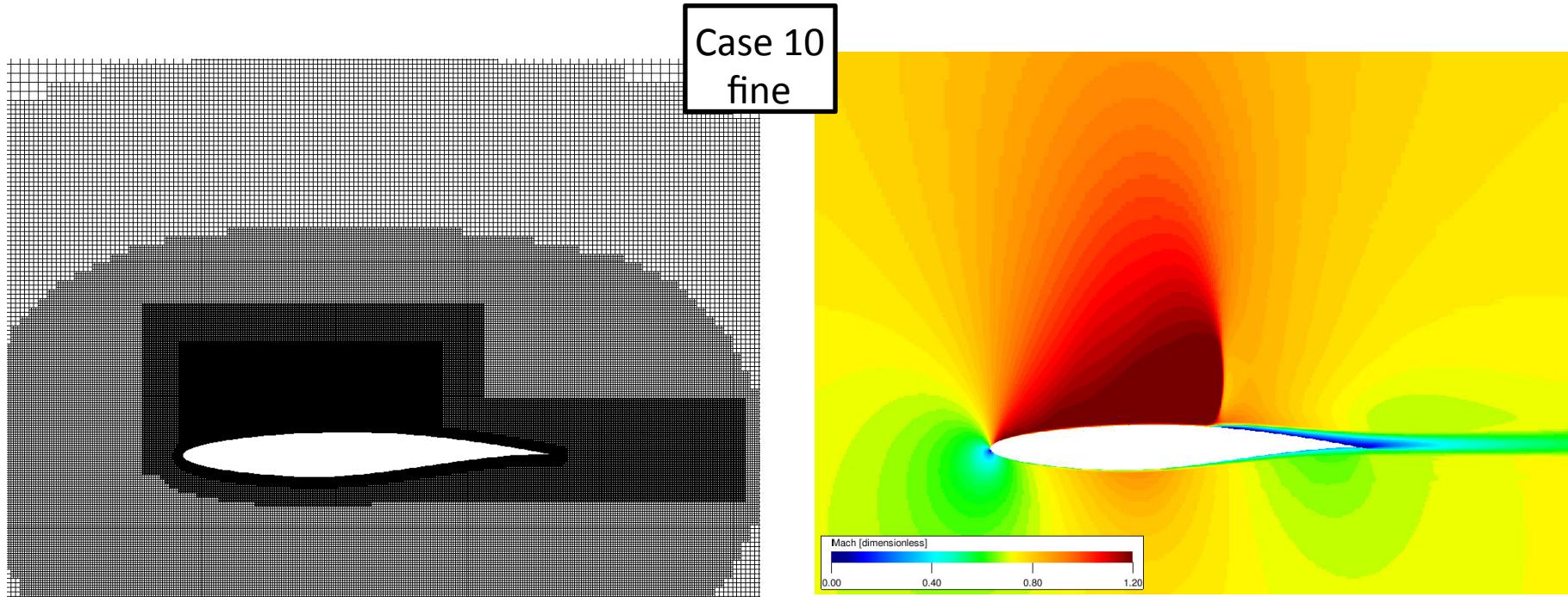
	coarse	Medium	Fine	X-fine	XX-fine
Resolution (cells / chord)	592	888	1333	2000	3000
Voxels [10^3]	63	138	300	667	1500
CPUh	30	65	160	480	1880
Wallclock on 32 cores [h]	1	2	5	15	36

Transonic Flow over the RAE 2822 airfoil



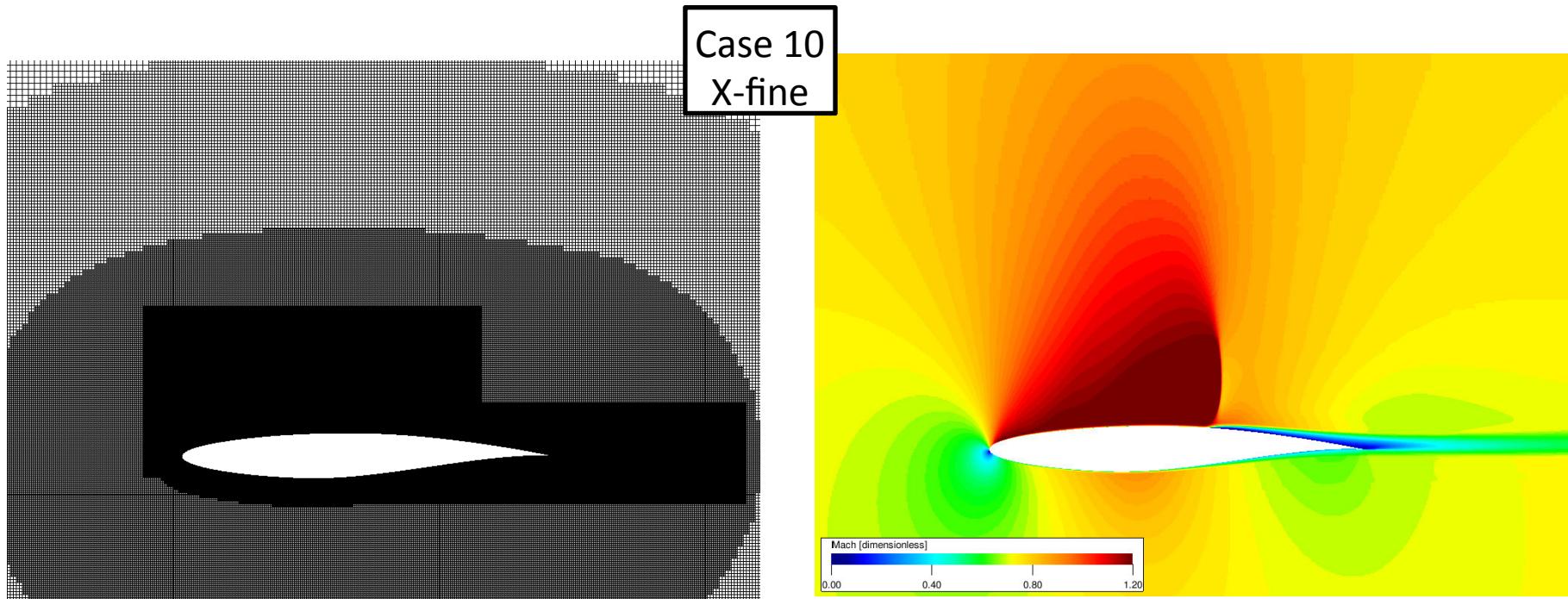
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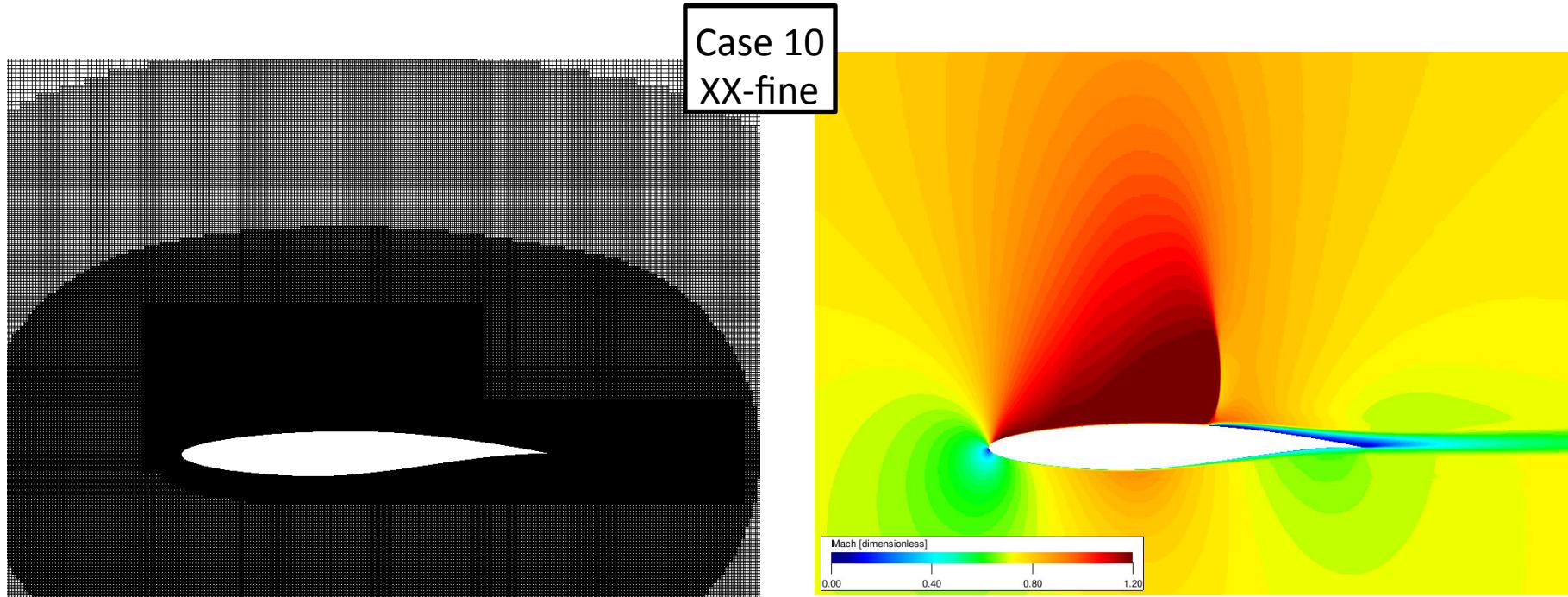
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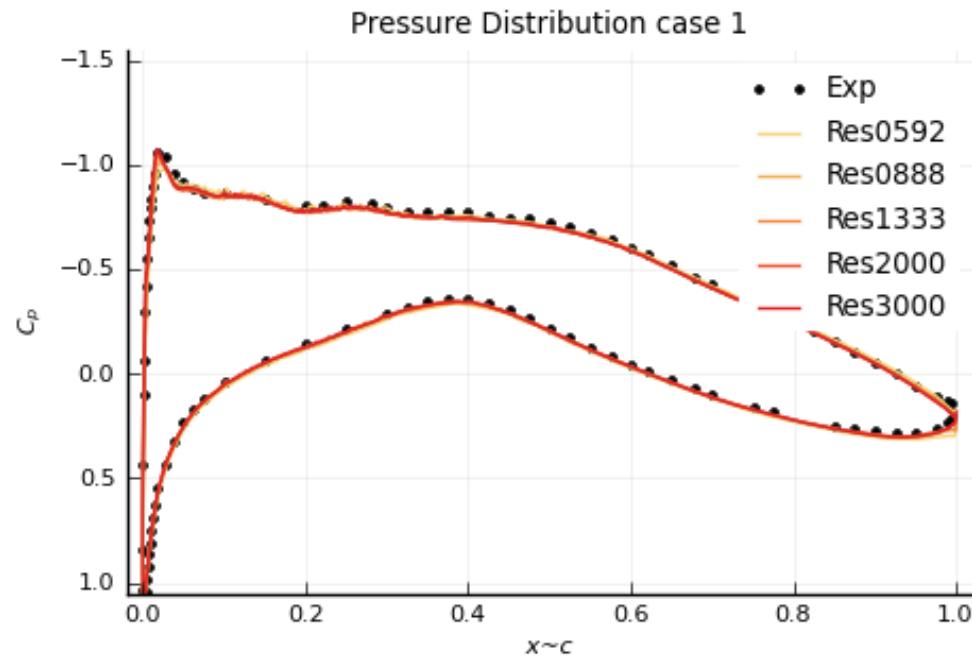
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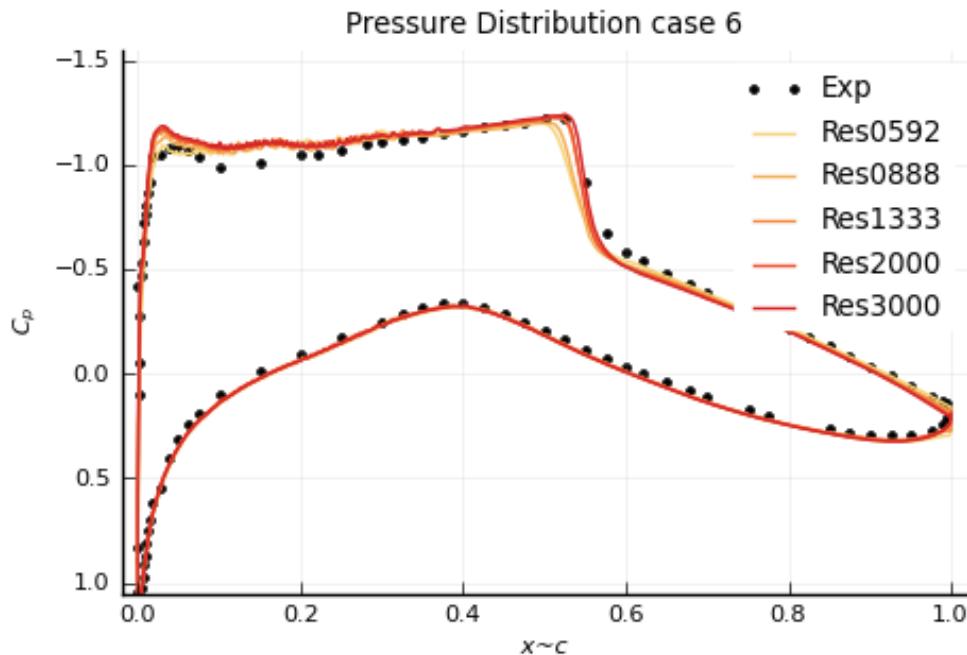
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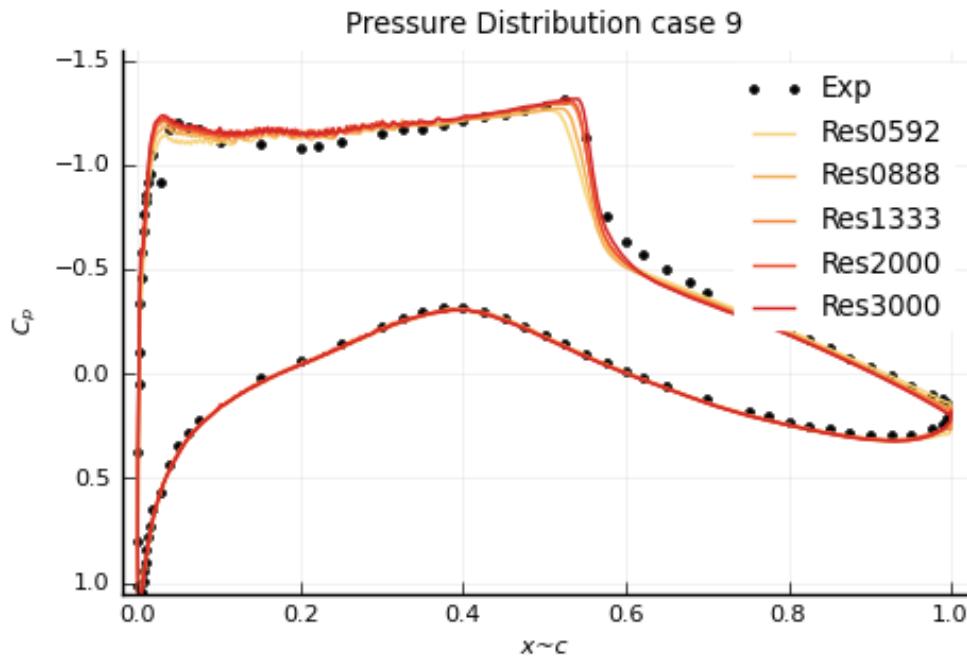
Transonic Flow over the RAE 2822 airfoil



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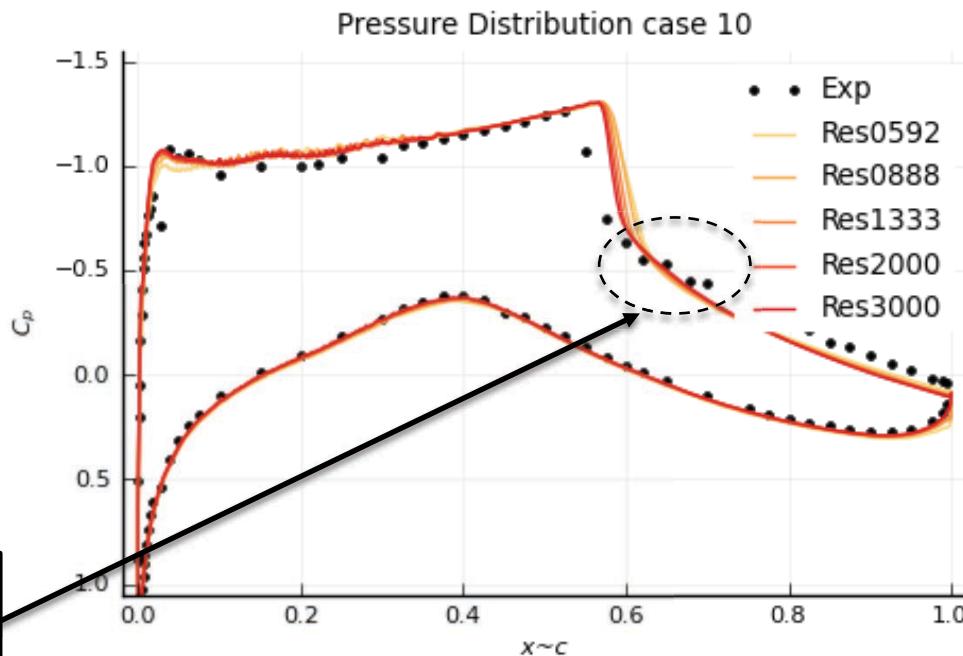
Transonic Flow over the RAE 2822 airfoil



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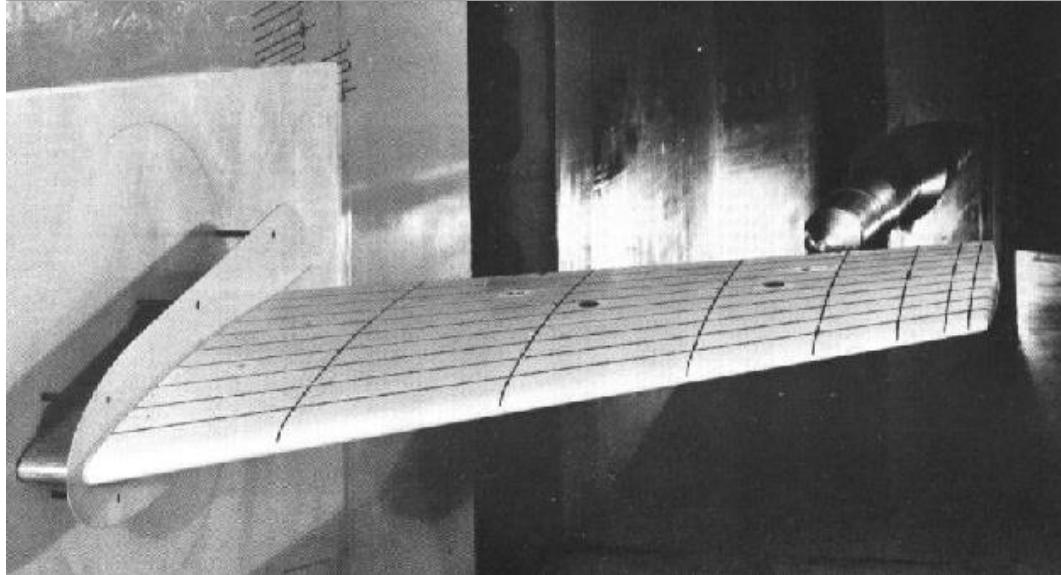
Transonic Flow over the RAE 2822 airfoil



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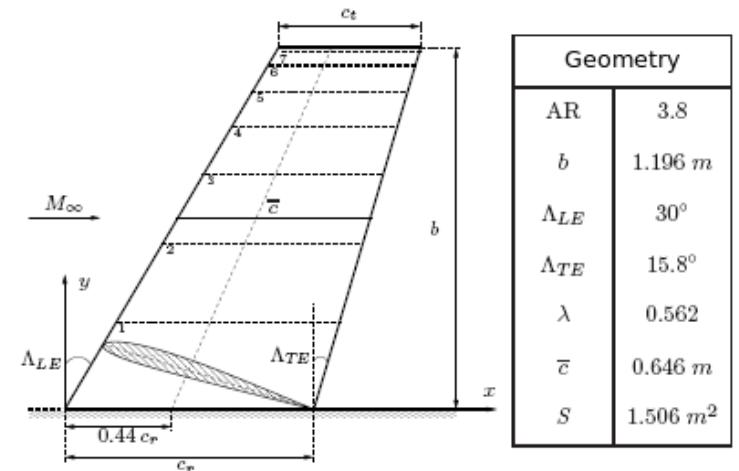


3D Onera-M6



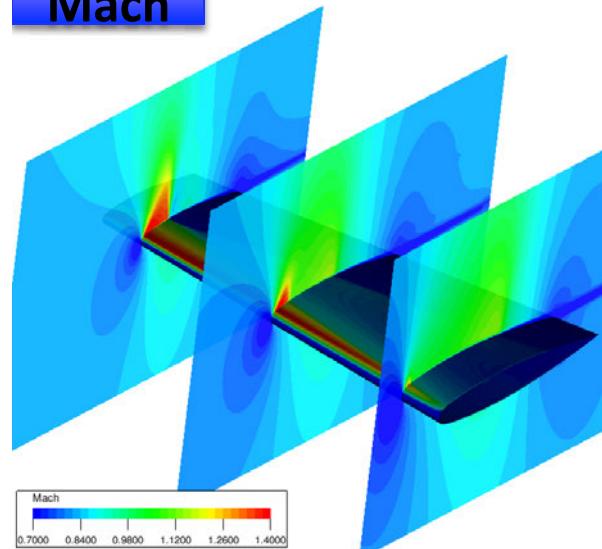
Span, b	1.1963 meters
Mean Aerodynamic Chord, c	0.64607 meters
Aspect Ratio	3.8
Taper Ratio	0.562
Leading-edge Sweep	30.0 degrees
Trailing-edge Sweep	15.8 degrees

Mach #	Reynolds #	AoA
0.84	11.72E6	3.06

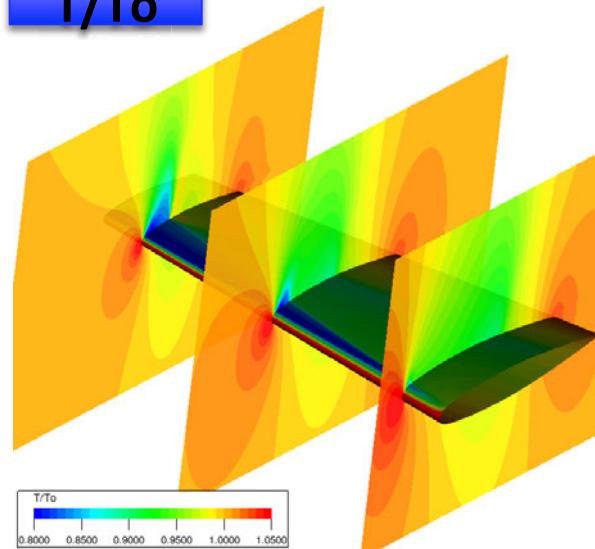


Flow-field Images

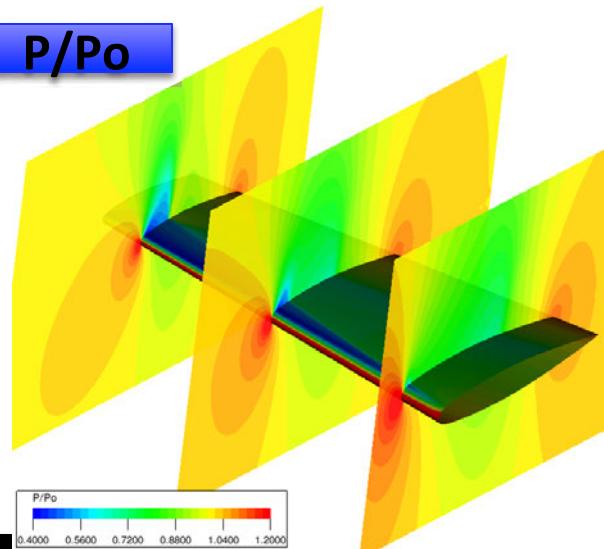
Mach



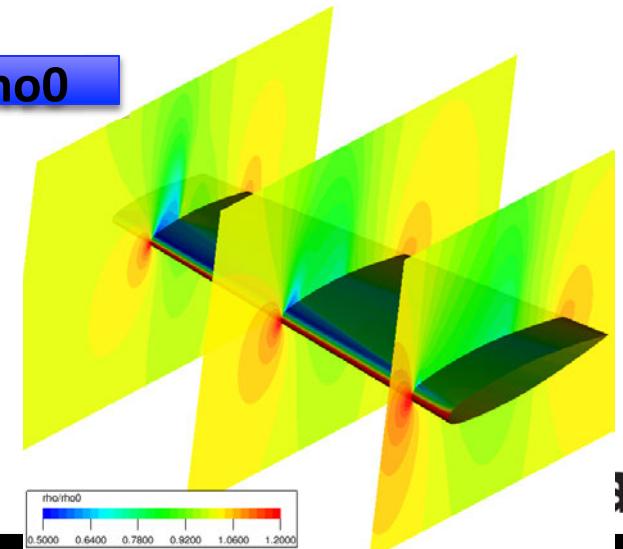
T/To



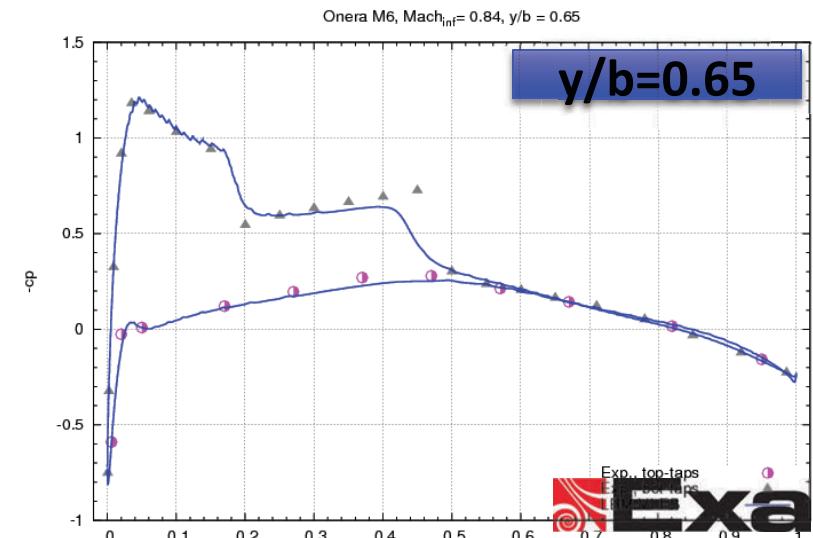
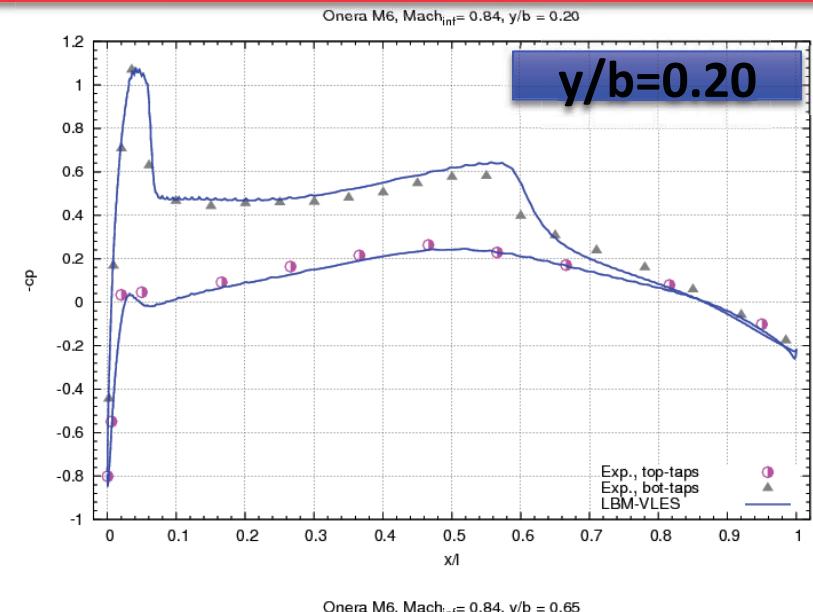
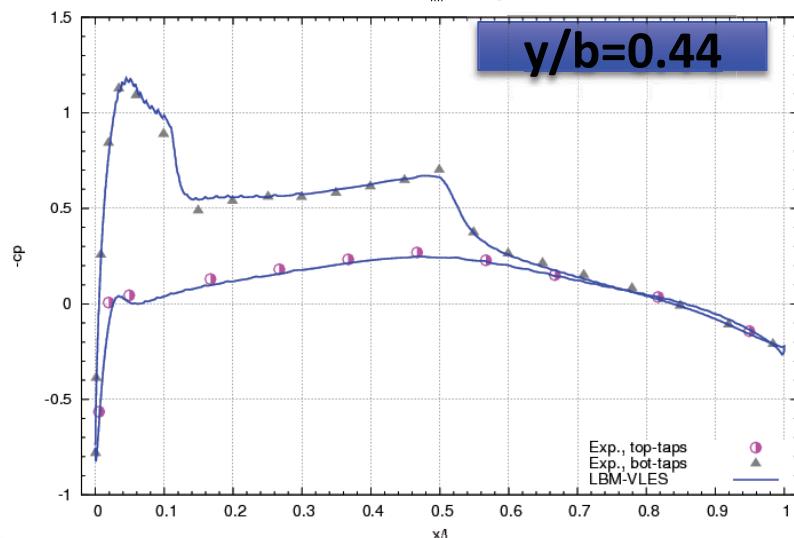
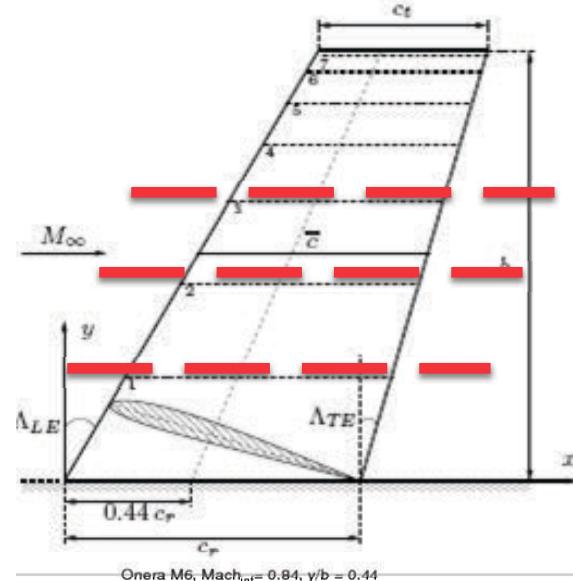
P/Po



rho/rho0

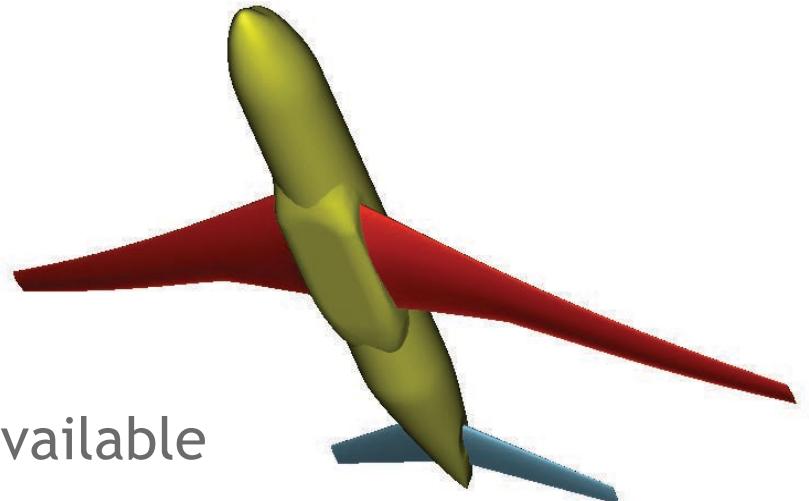


3D Onera-M6 Sectional Cp on Surface

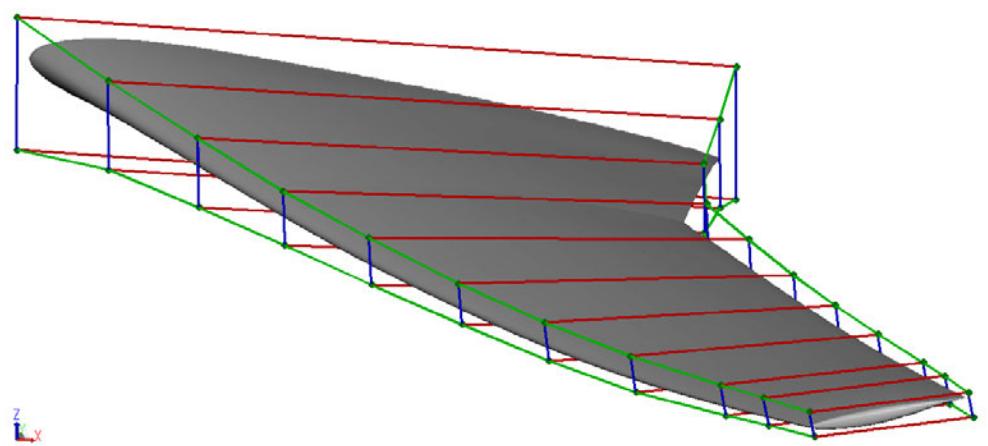
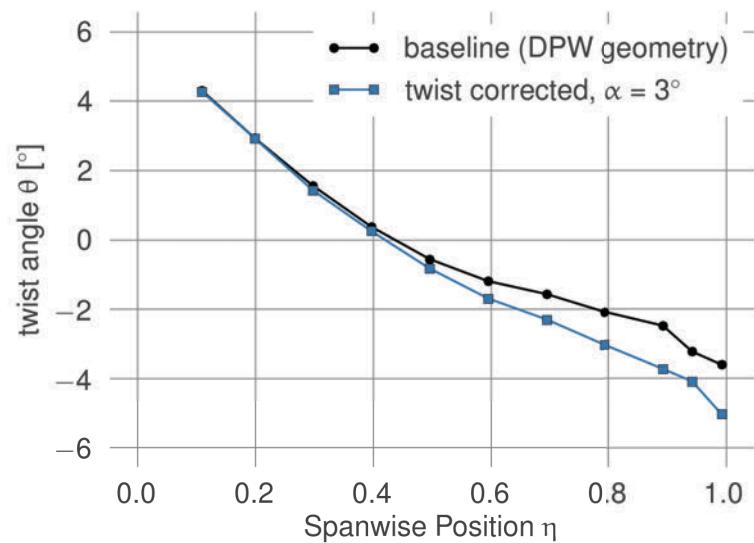


NASA-CRM Model

- DPW4 Geometry
 - *Reference CFD Data*
 - *Wing-body & tail*
 - Supercritical wing
 - Built to the design-shape
 - Twist correction information available
- Measured at several Windtunnels
 - *ETW, NTF, NASA Ames 11ft, JAXA JTWT*



Wing Twist Correction

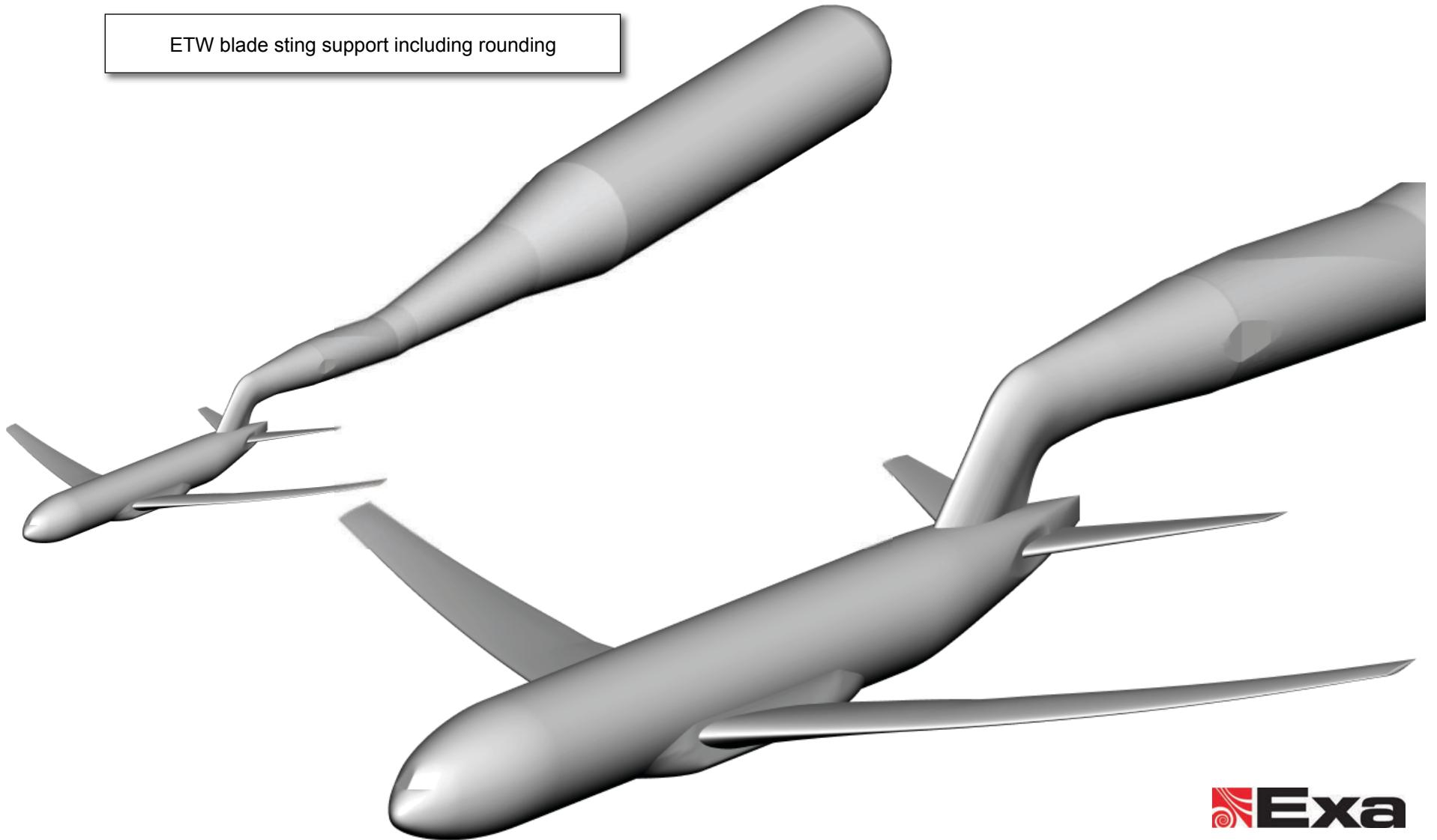


PowerDELTA®
morphing

 **Exa**

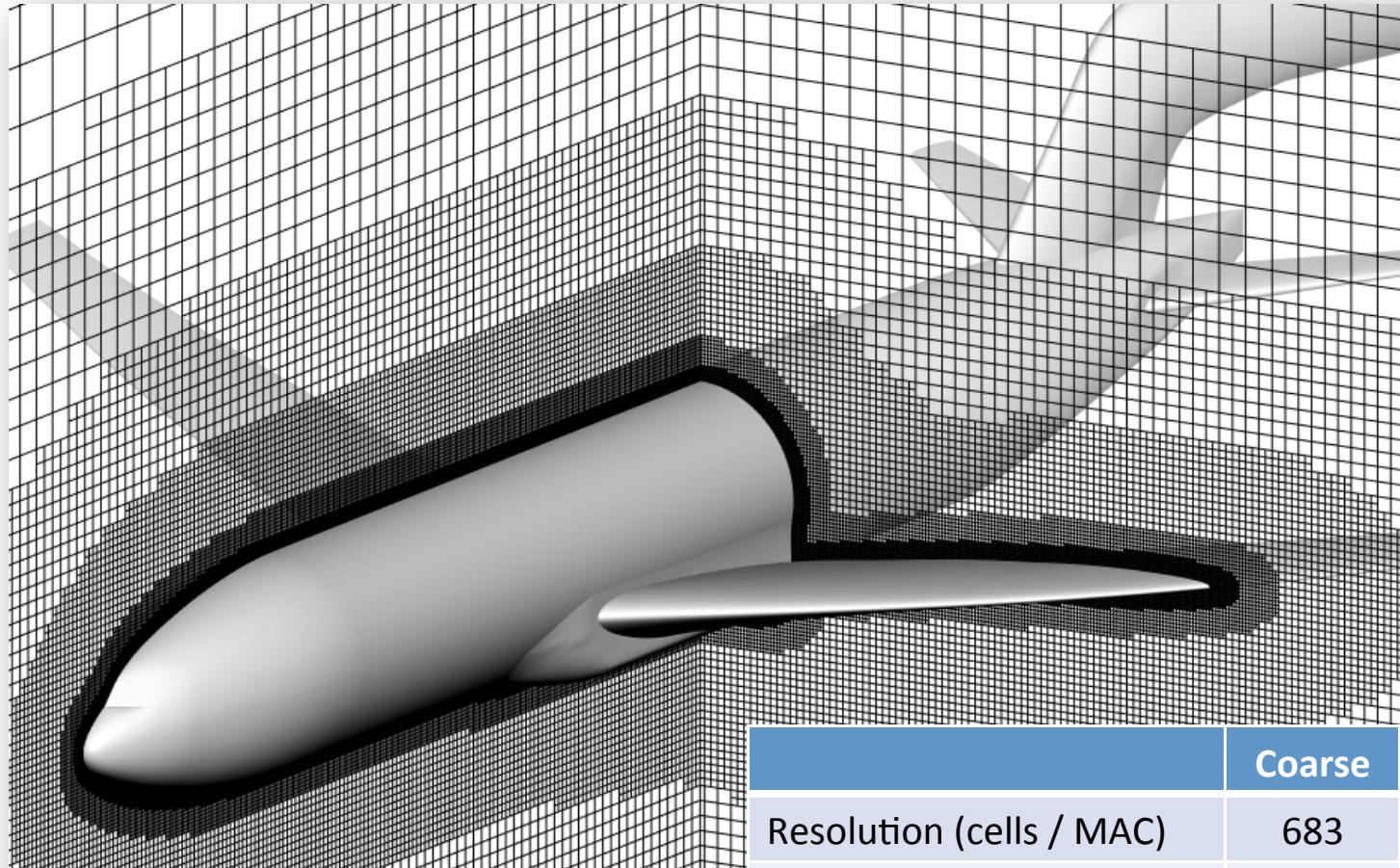
Simulated Geometry

ETW blade sting support including rounding



 **Exa**

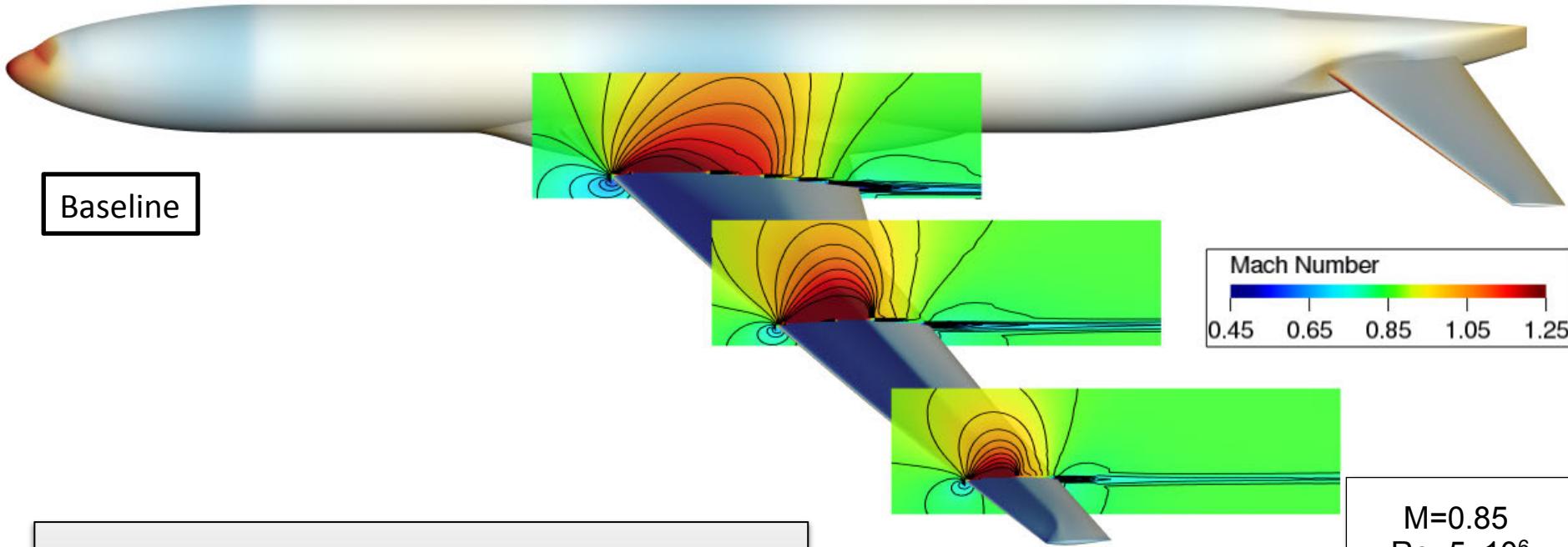
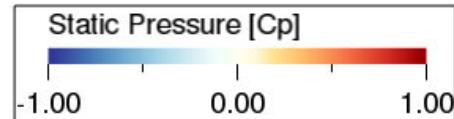
Computational Mesh*



* Simulated with Symmetry
* additional resolution to resolve sting negligible

	Coarse	Medium	Fine
Resolution (cells / MAC)	683	1024	1536
Voxels [10^6]	30	88	274
CPUh [10^3]	5.4	17	38
Wallclock on 360 cores [d]	0.6	2	4.4

Results

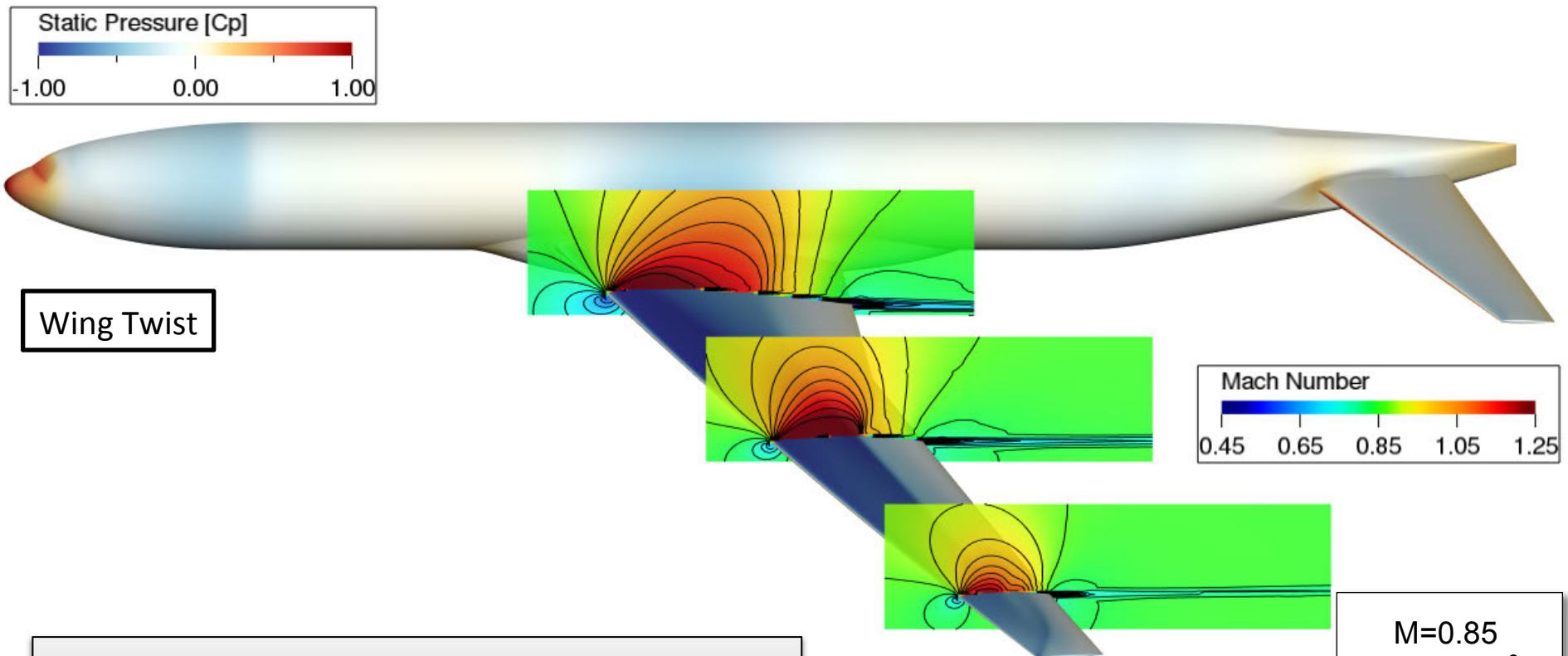


Koenig, B., and Fares, E. "Validation of a Transonic Lattice-Boltzmann Method on the NASA Common Research Model", AIAA 2023-2016.



Results

- DPW4 Geometry (NASA CRM model)



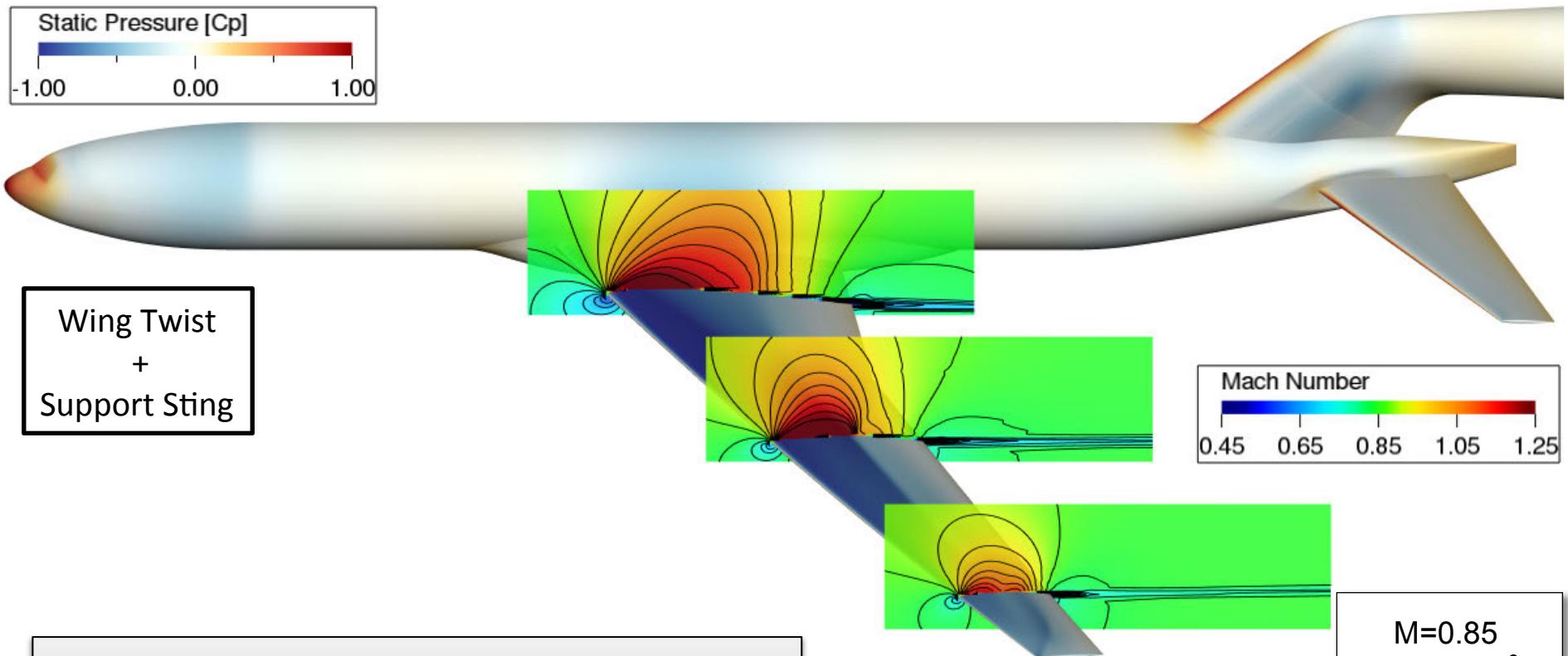
Koenig, B., and Fares, E. "Validation of a Transonic Lattice-Boltzmann Method on the NASA Common Research Model", AIAA 2023-2016.

$M=0.85$
 $Re=5\times 10^6$
 $\alpha=2.9^\circ$



Results

- DPW4 Geometry (NASA CRM model)

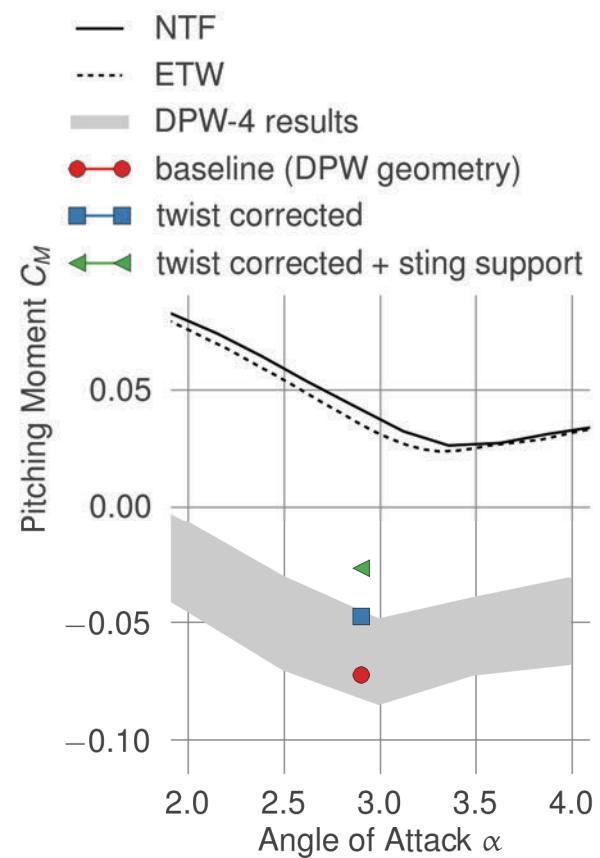
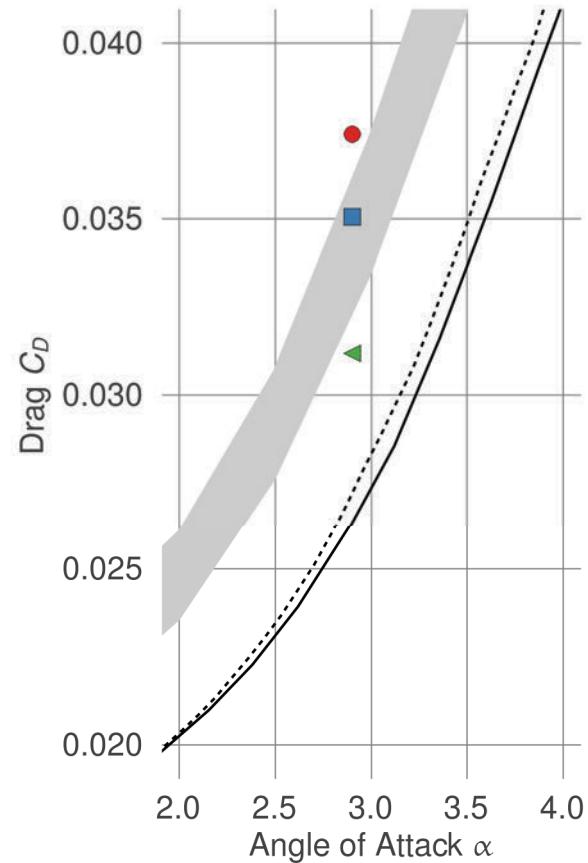
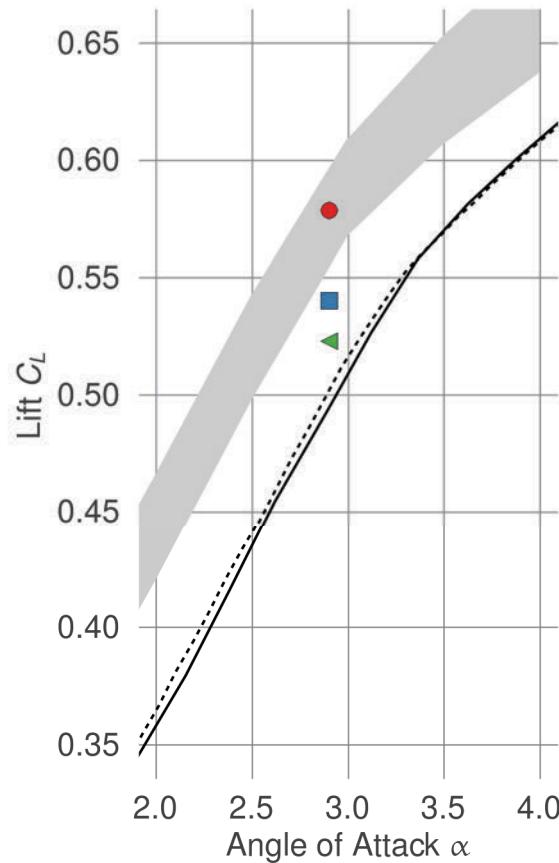


Koenig, B., and Fares, E. "Validation of a Transonic Lattice-Boltzmann Method on the NASA Common Research Model", AIAA 2023-2016.

$M=0.85$
 $Re=5\times 10^6$
 $\alpha=2.9^\circ$



Results – Wing Twist and Sting Effects

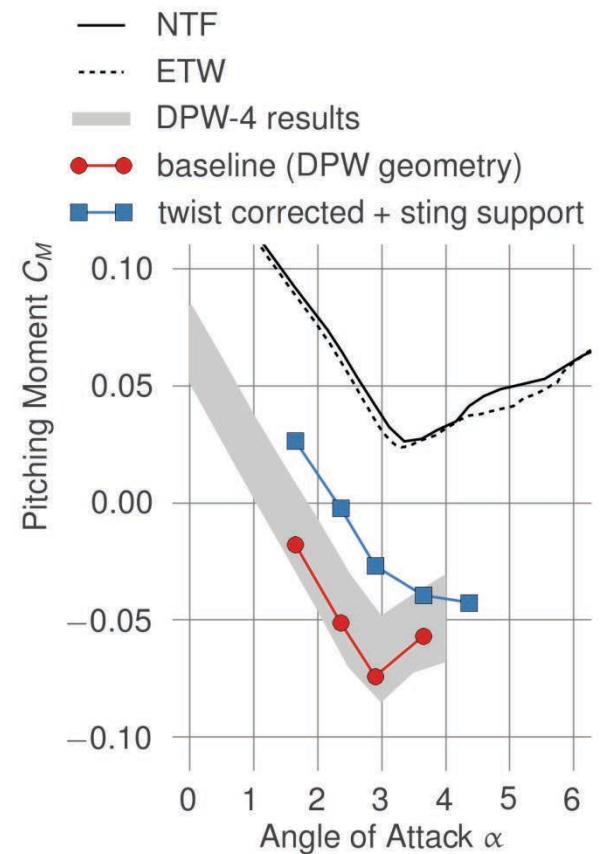
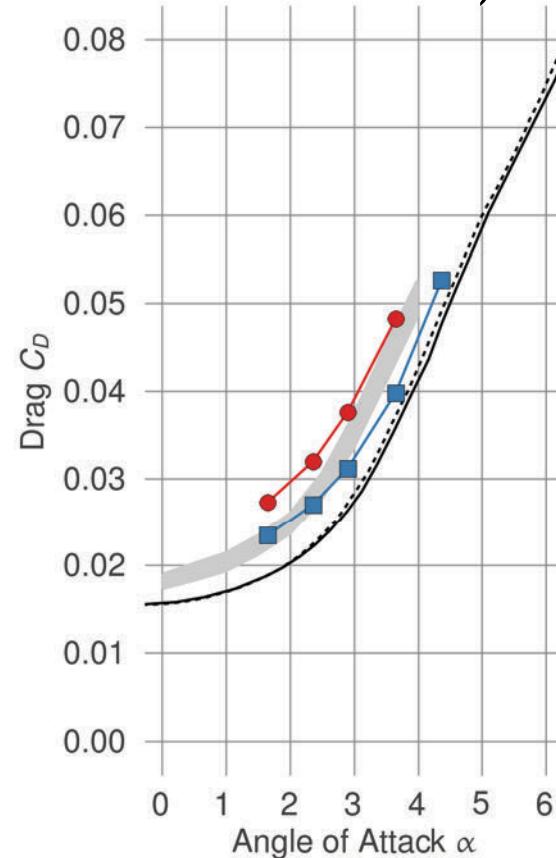
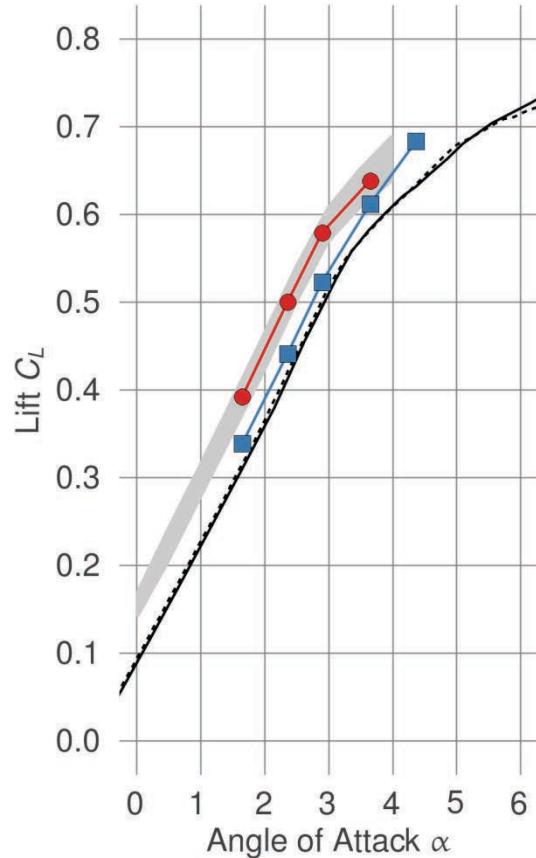


M=0.85
Re= 5×10^6



Results – Wing Twist and Sting Effects

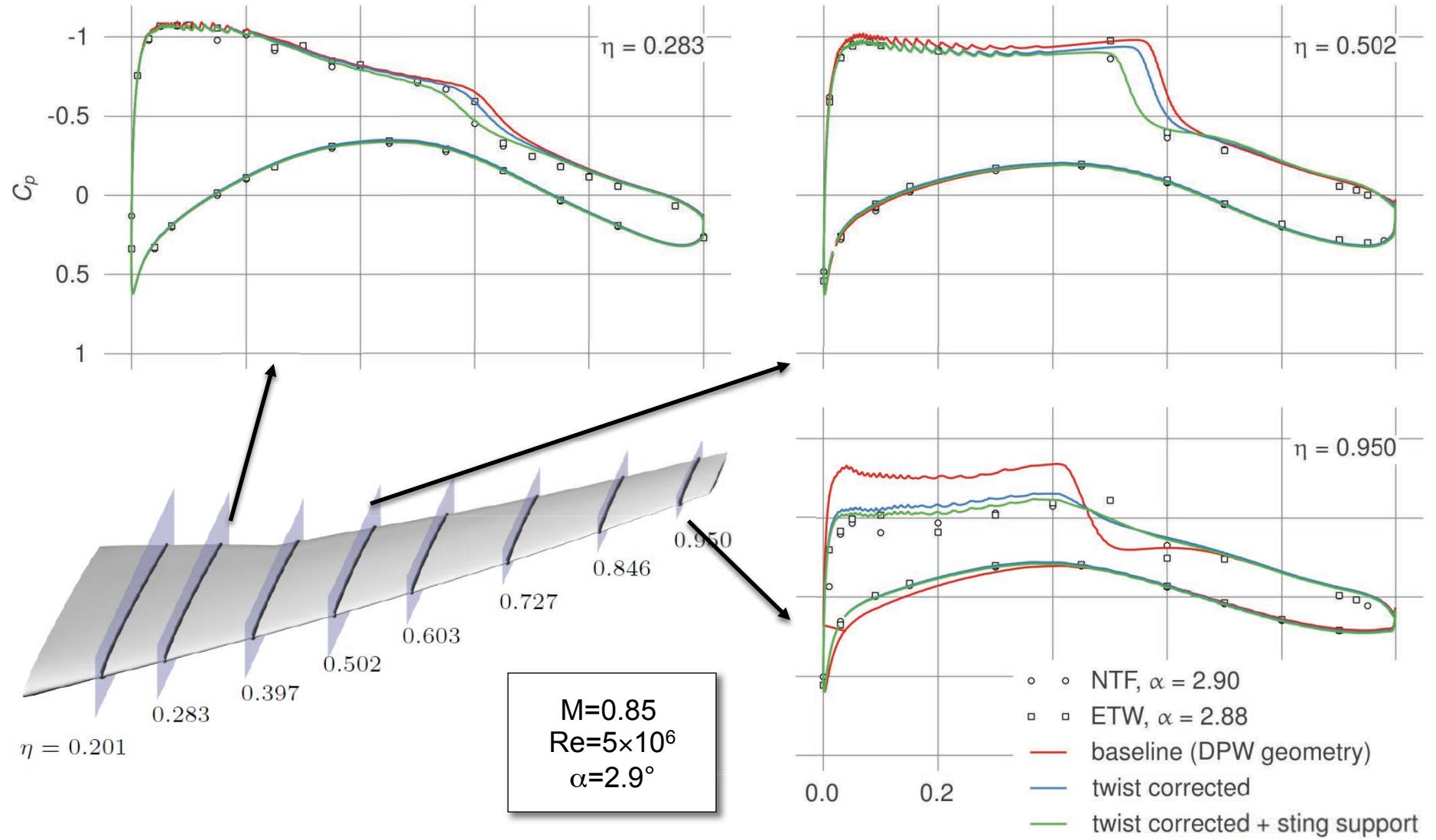
- DPW4 Geometry (NASA CRM model)



M=0.85
Re=5×10⁶

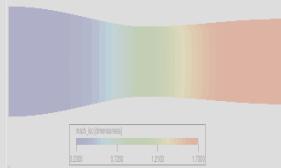


Results – Wing Twist and Sting Effects

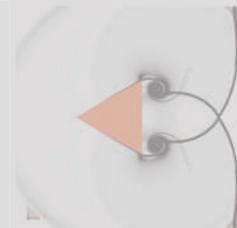


Transonic Code Validation & Application

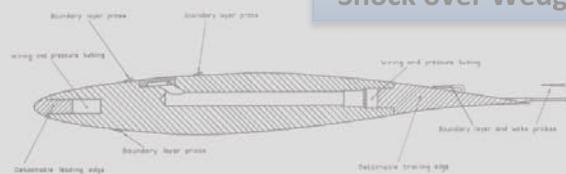
Fundamental Validations



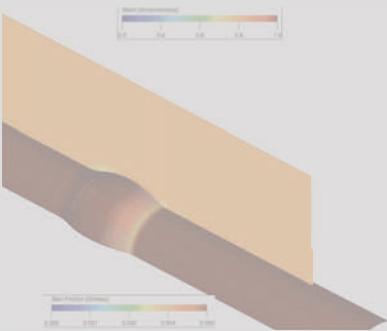
CDV nozzle



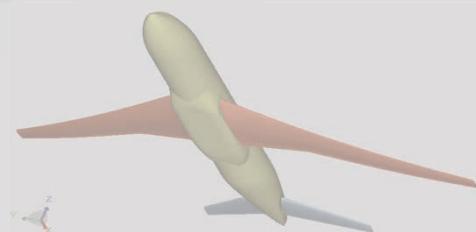
Shock over Wedge



RAE 2822 Airfoil

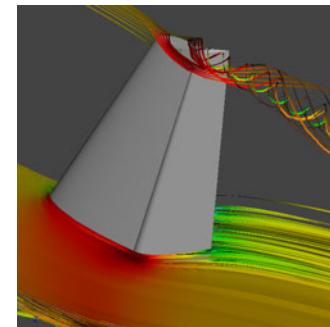


Transonic Bump

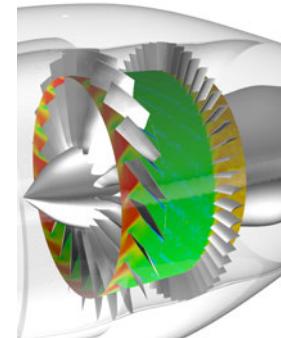


CRM

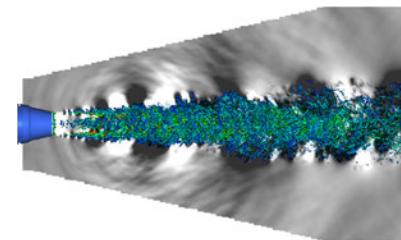
Industrial Applications



Flow Control



Fan Noise



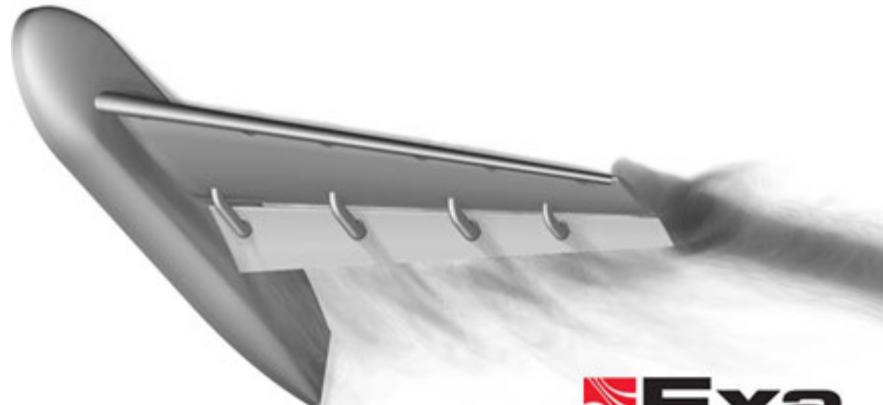
Jet Noise



Buffet

 **Exa**

Trapezoidal Wing FSF Configurations

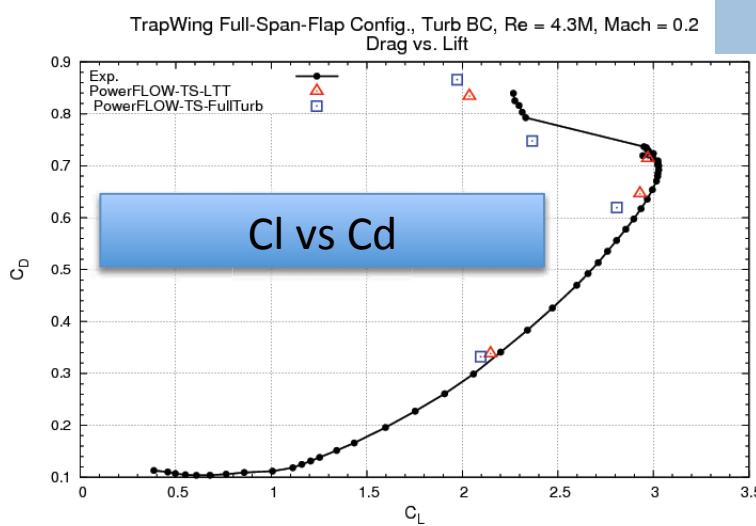
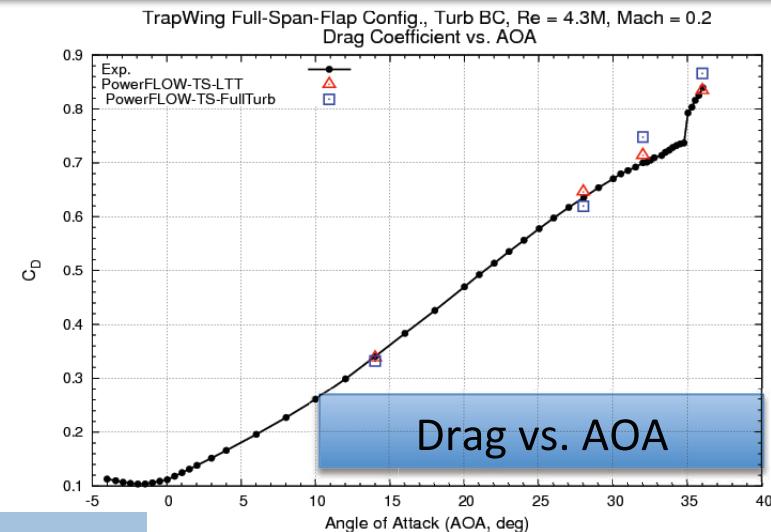
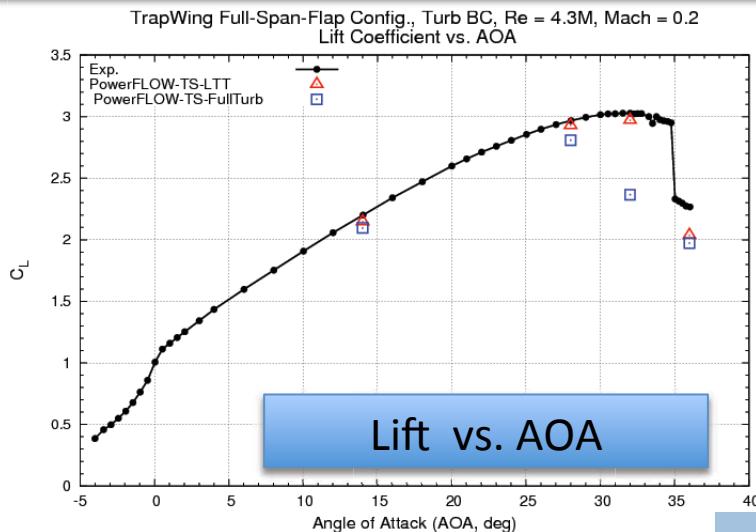


 Exa

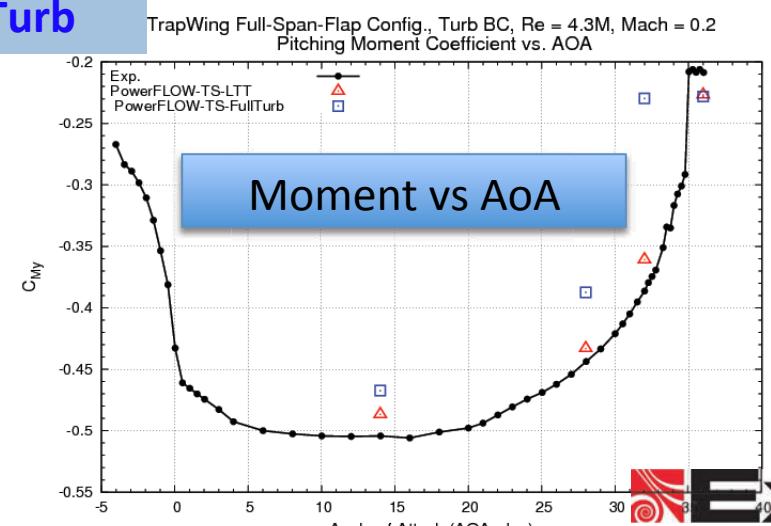
- Full Span Flap (FSF) Configuration
- $Re = 4.3 \text{ M}$
- $Mach = 0.2$
- Laminar to turbulence transition (LTT) included



TrapWing : Drag & Lift

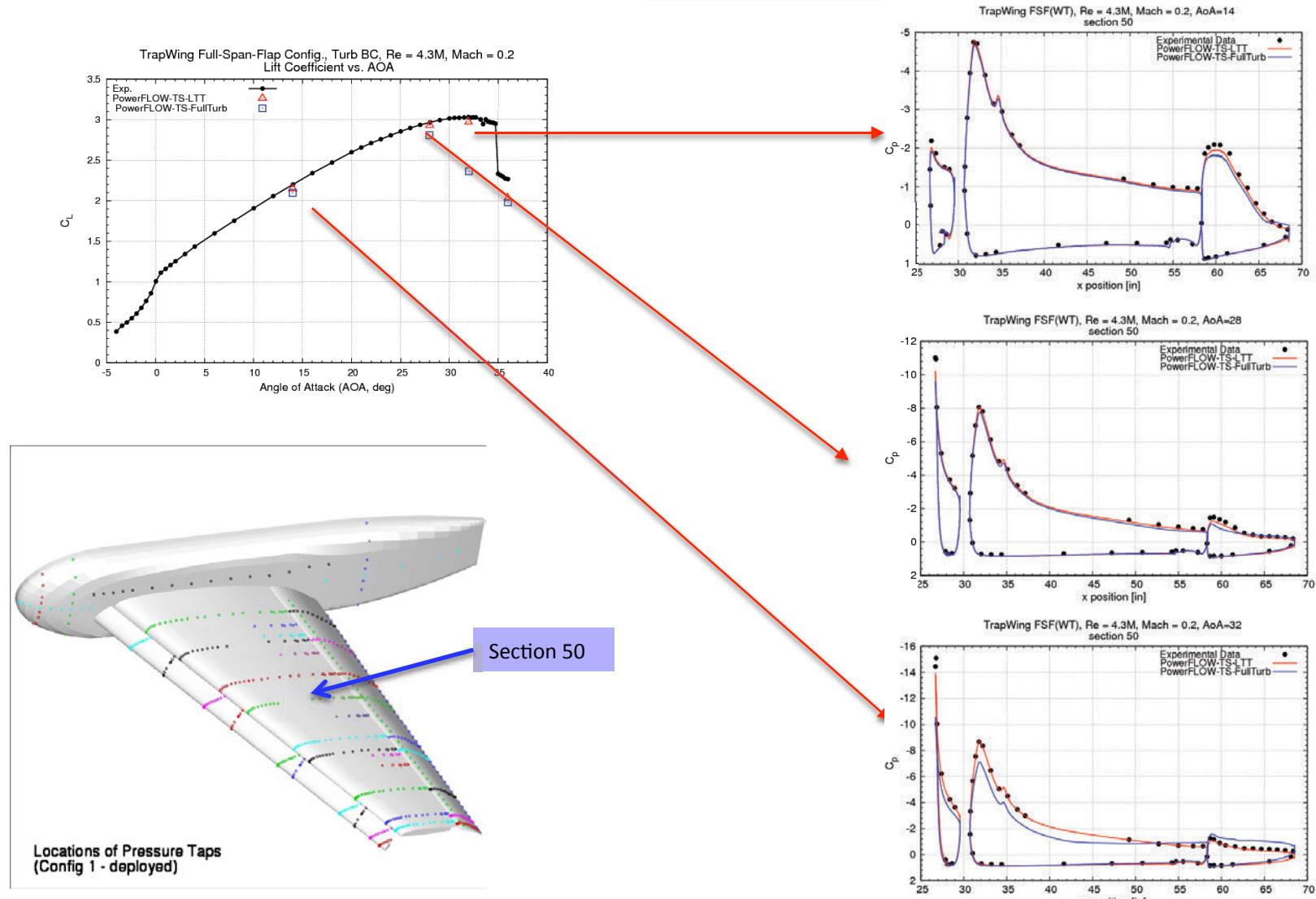


LTT
Full-Turb

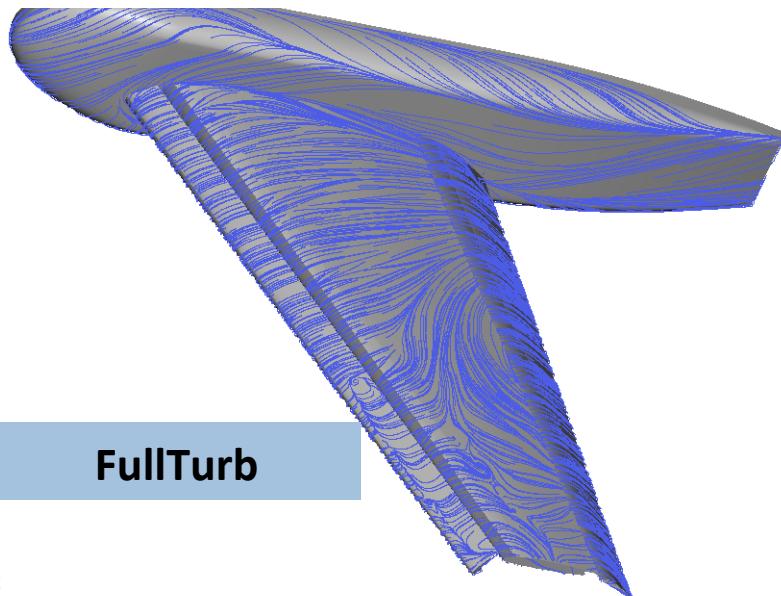
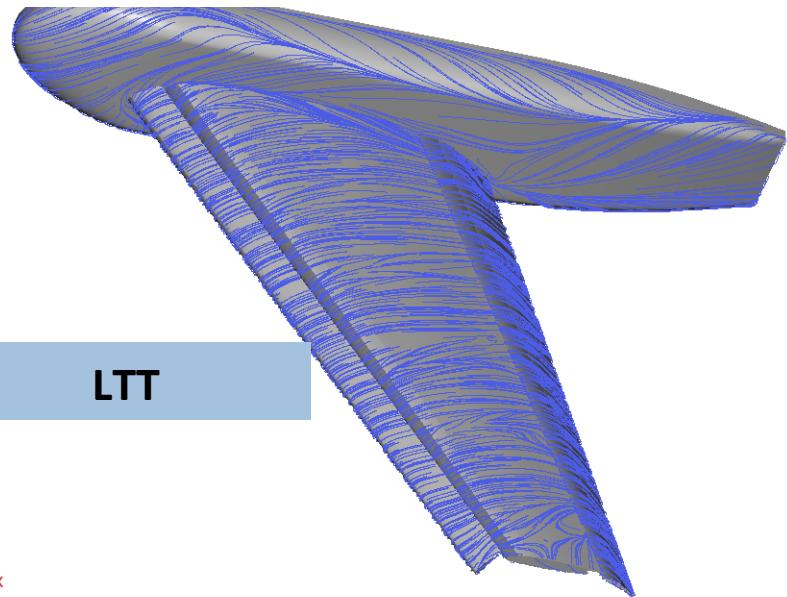


Sectional Surface Pressure

LTT
Full-Turb

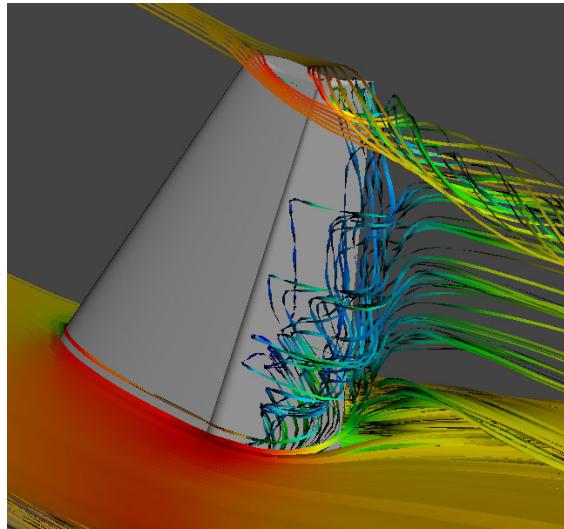


Surface Streamlines – AoA 32

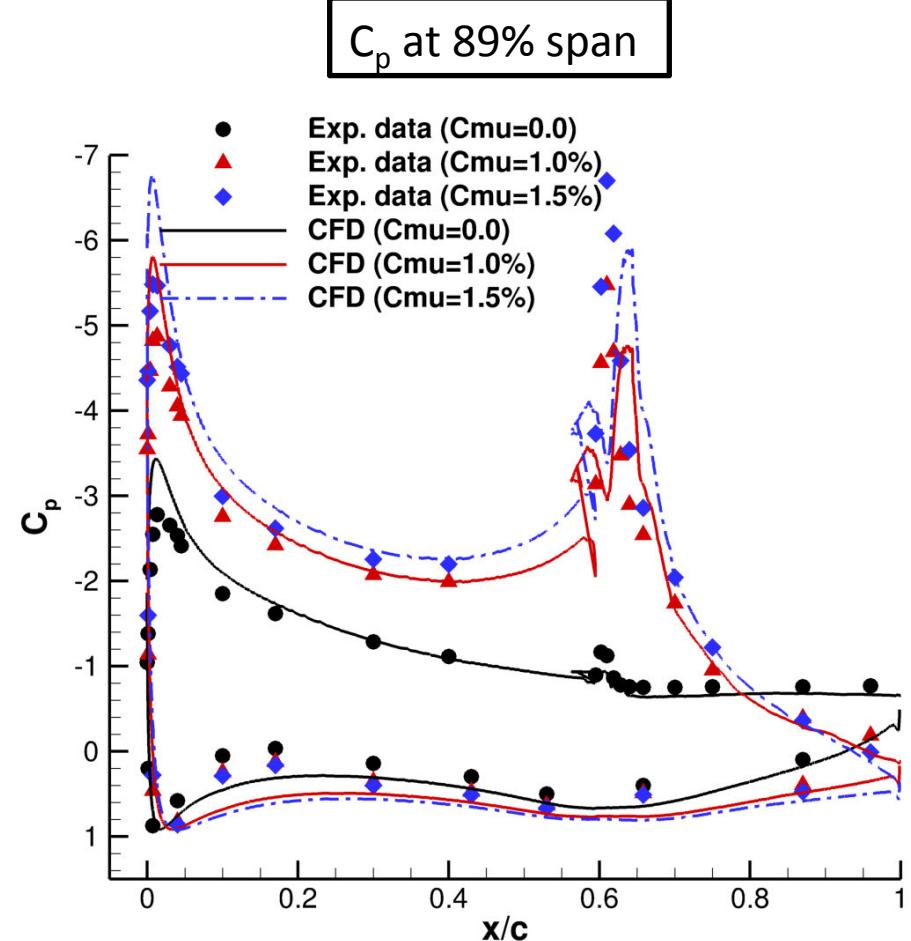
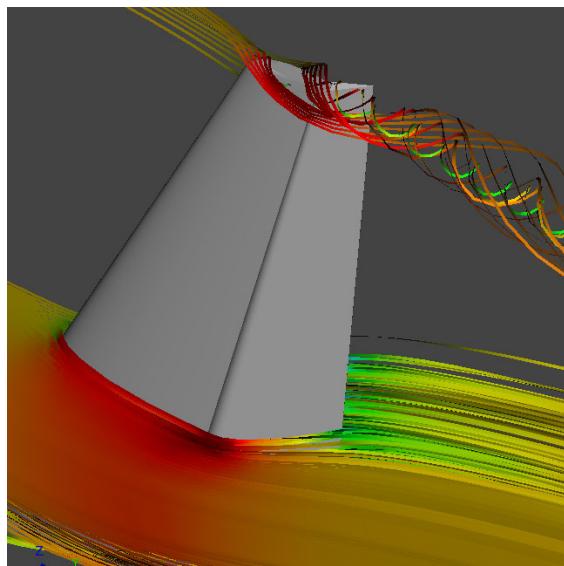


NASA - Active Flow Control

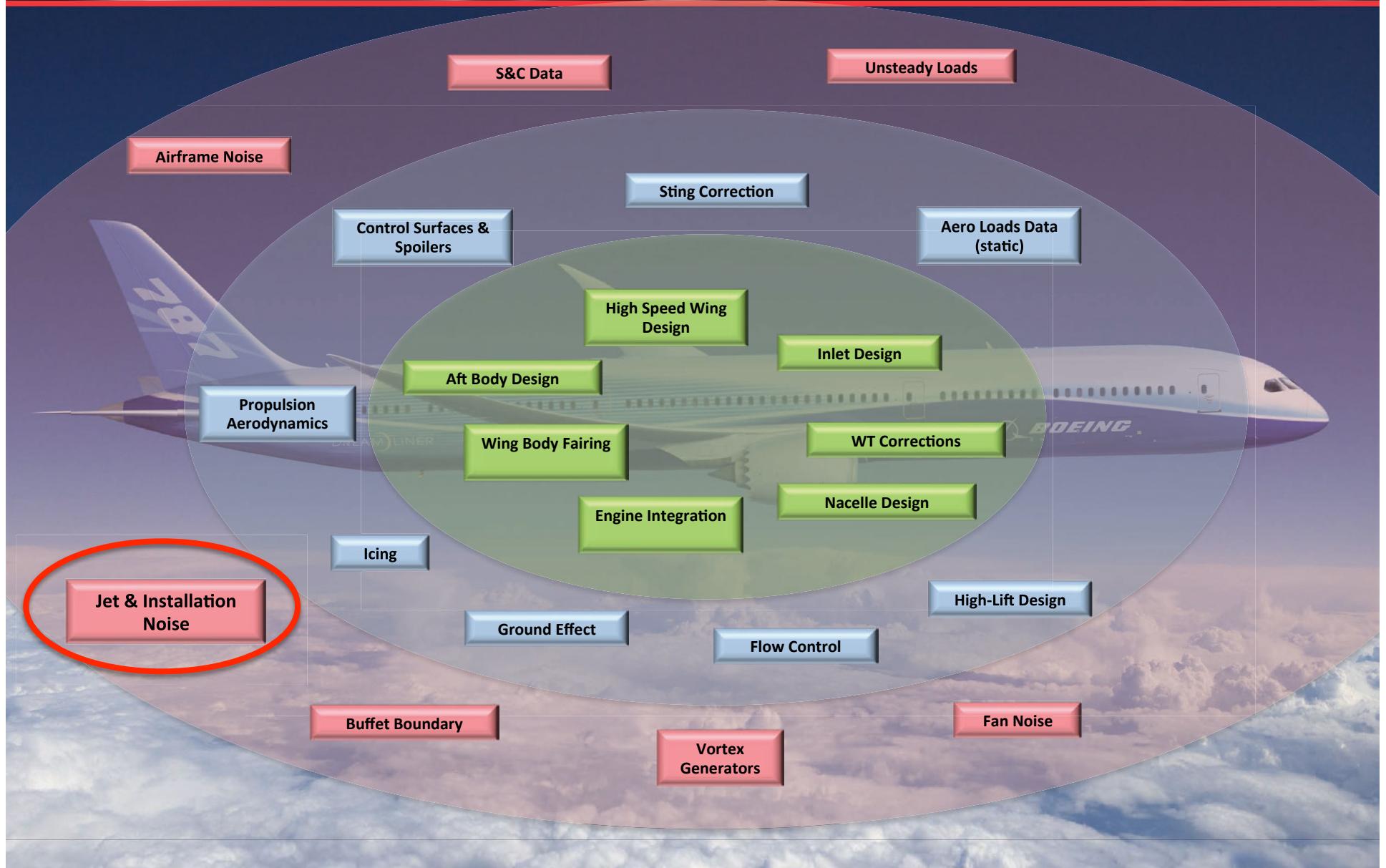
Unactuated, $C_{mu}=0.0$



Actuated, $C_{mu}=1.5\%$

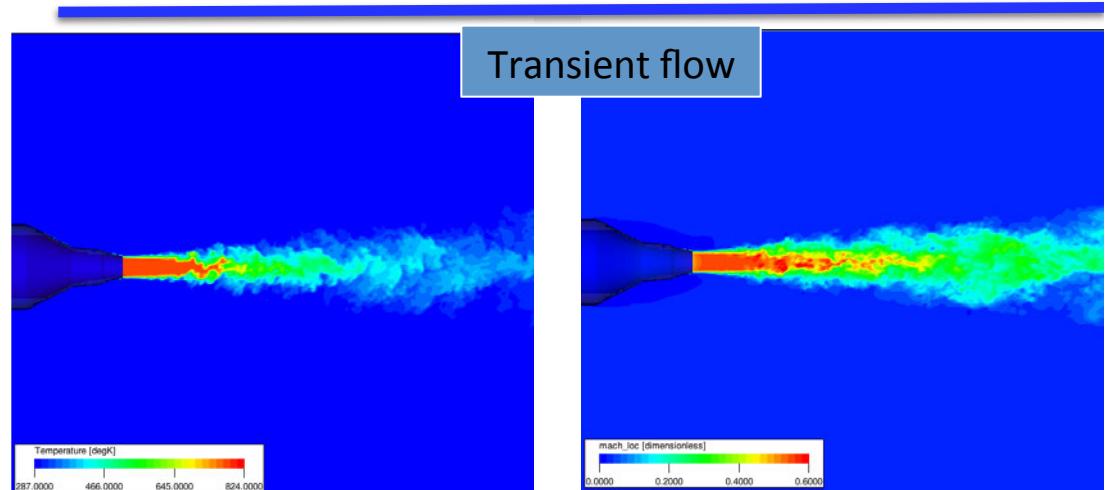
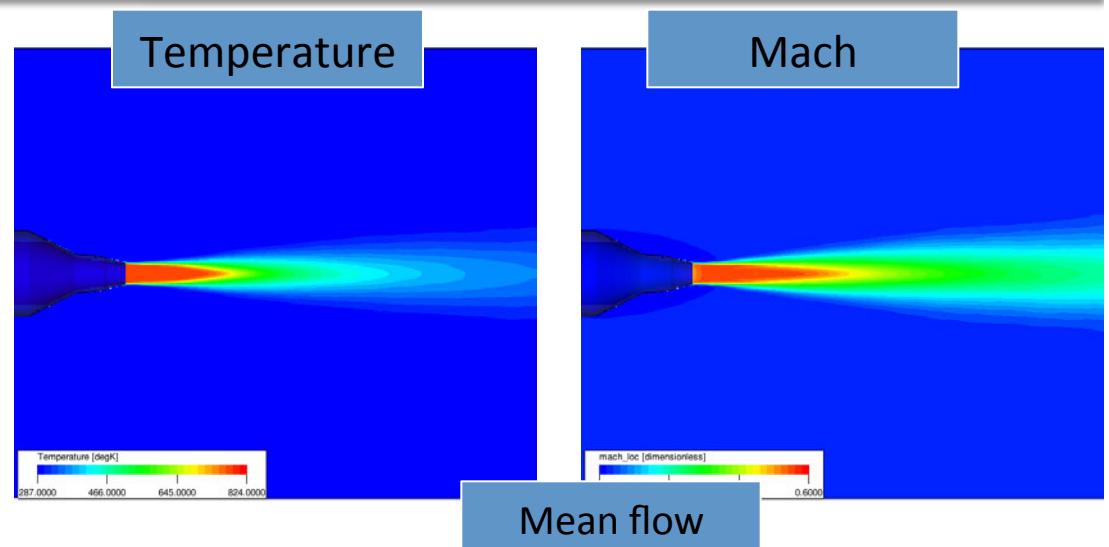
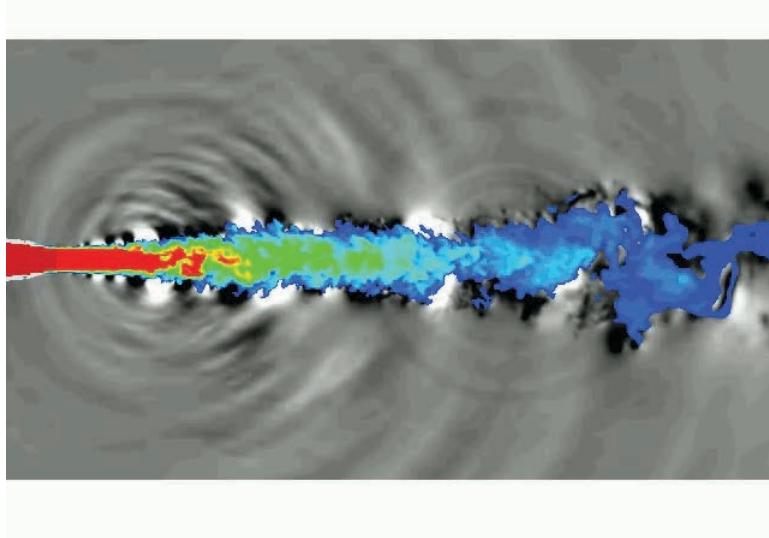


Applications



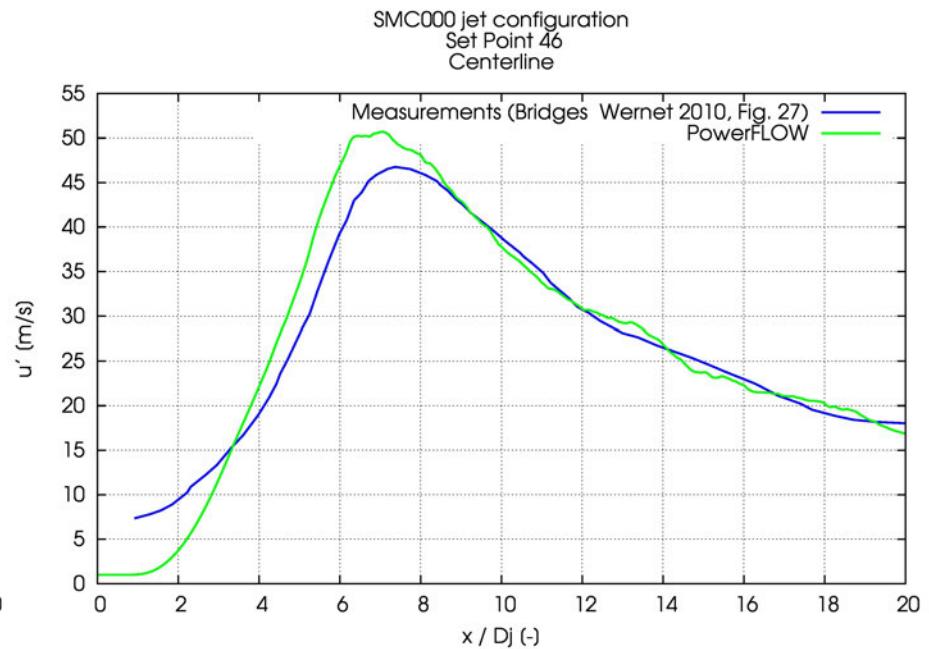
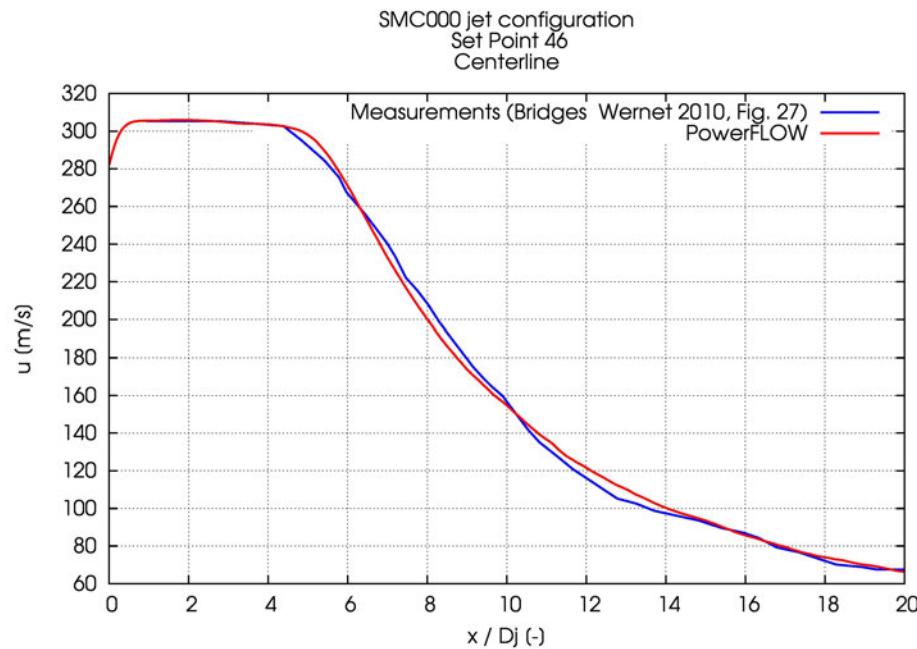
Jet Noise: SMC000 (SP46): $Ma=0.9$, $T_j/T_o=2.7$

$M_j = U_j/a_j$	$M_a = U_j/a_{inf}$	T_j/T_{inf}
0.548	0.90	2.70



 Exa

3D SMC Jet, SP46: Centerline mean and RMS velocity

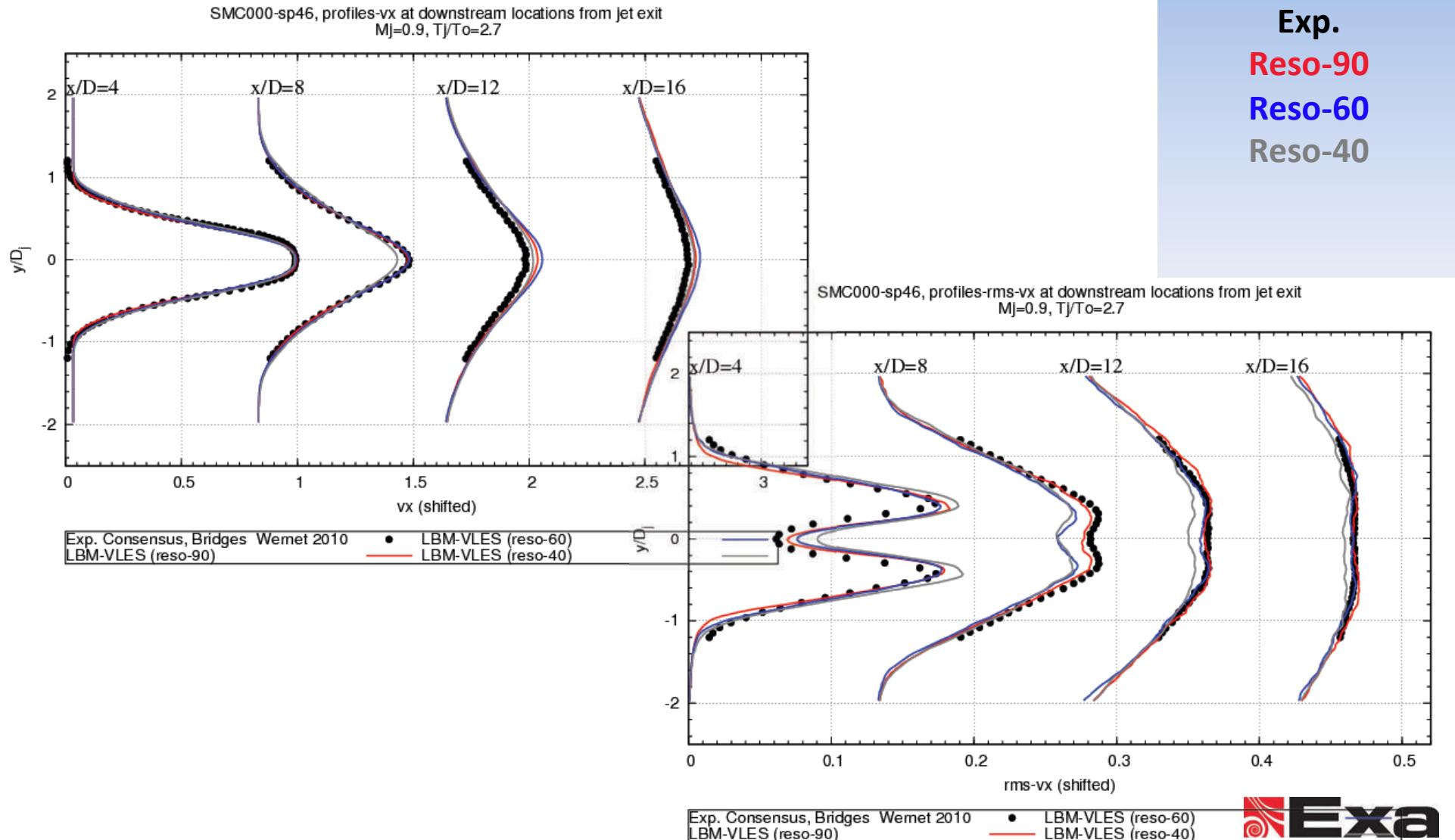


Mean velocity

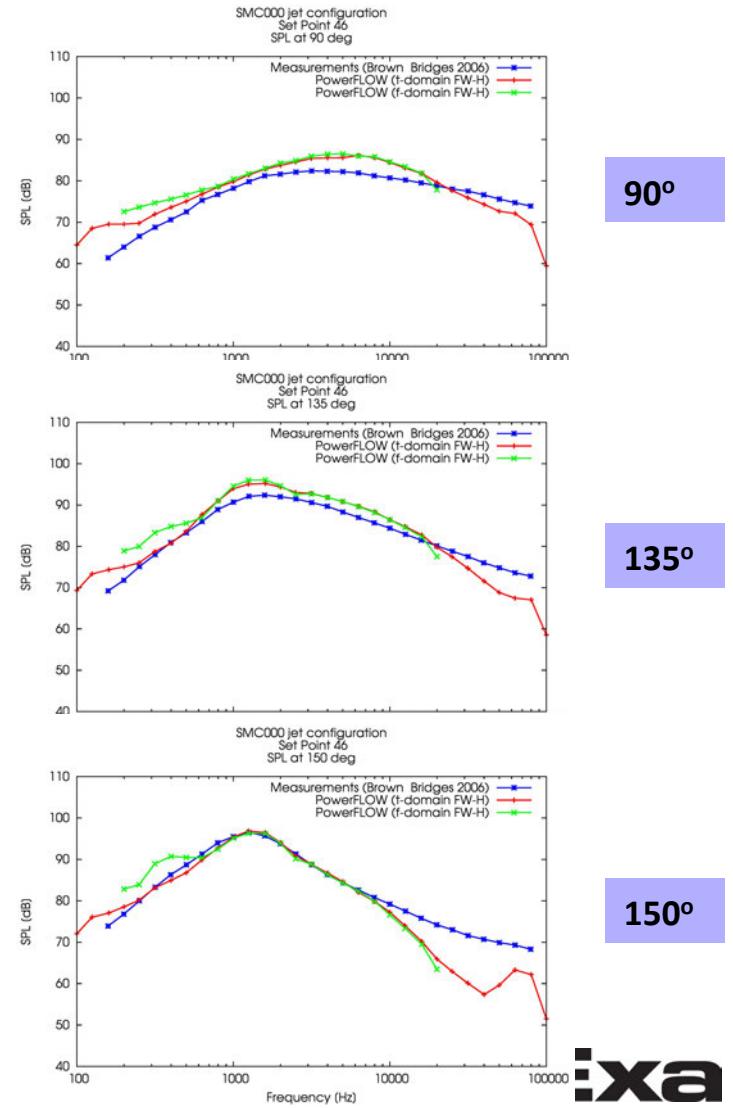
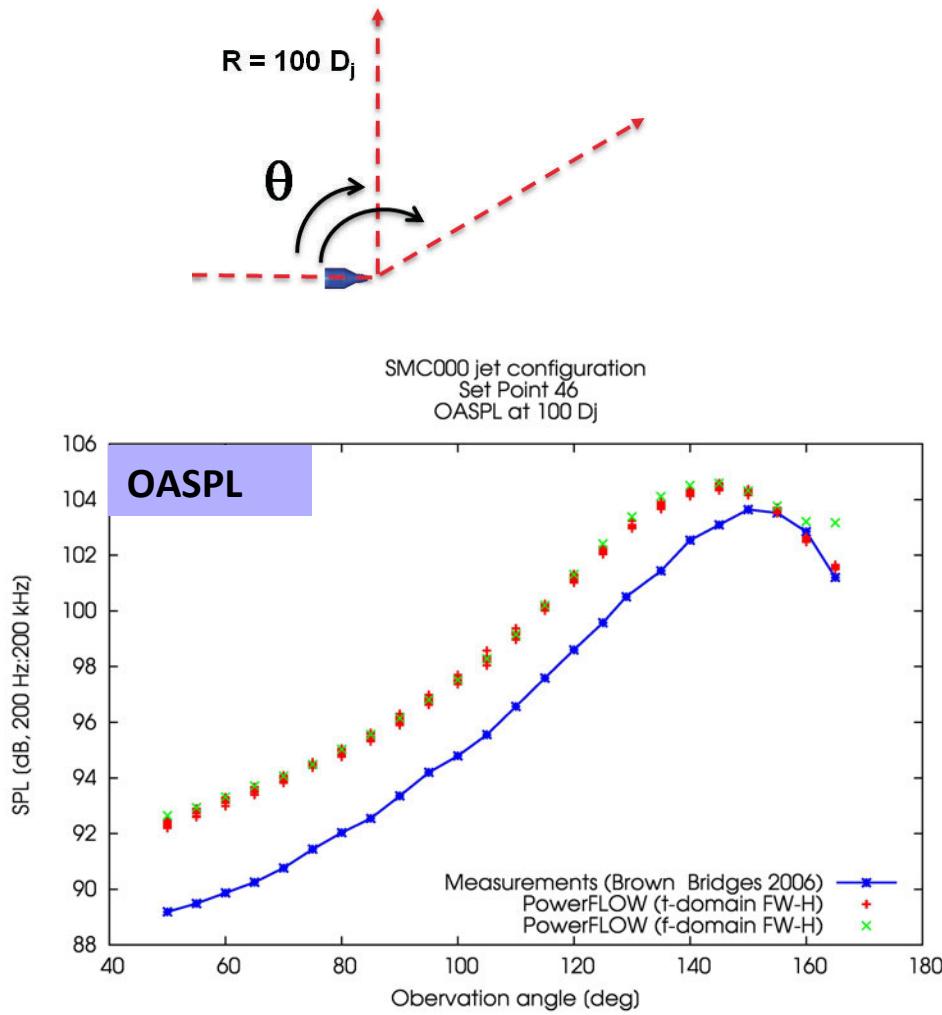
RMS velocity



3D SMC Jet, SP46: Radical profiles of mean and RMS velocity

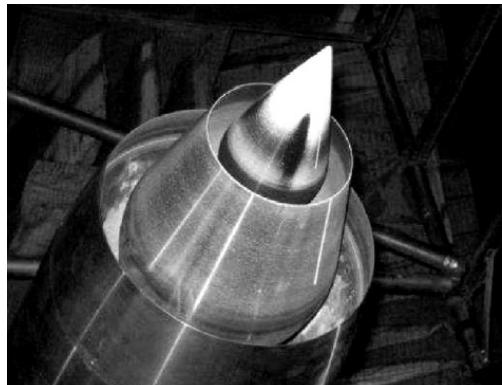
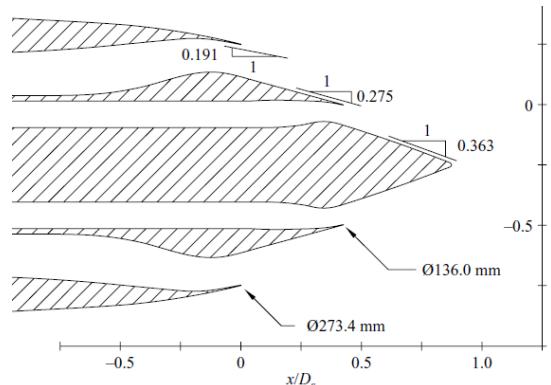


3D SMC Jet, SP46, FW-H OASPL and Far-field probes

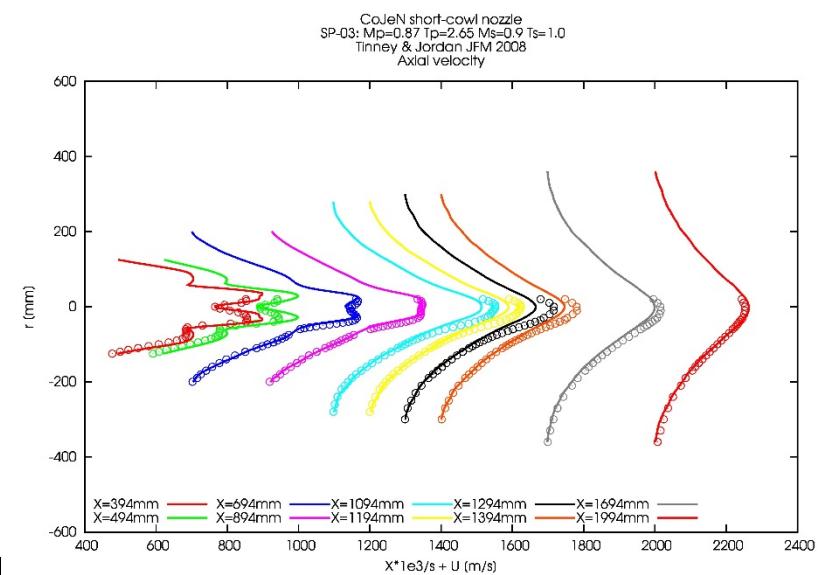
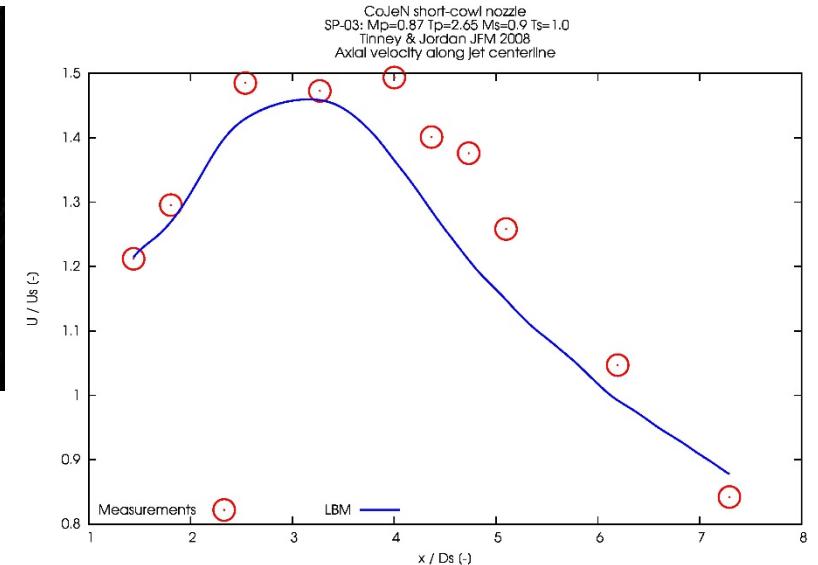
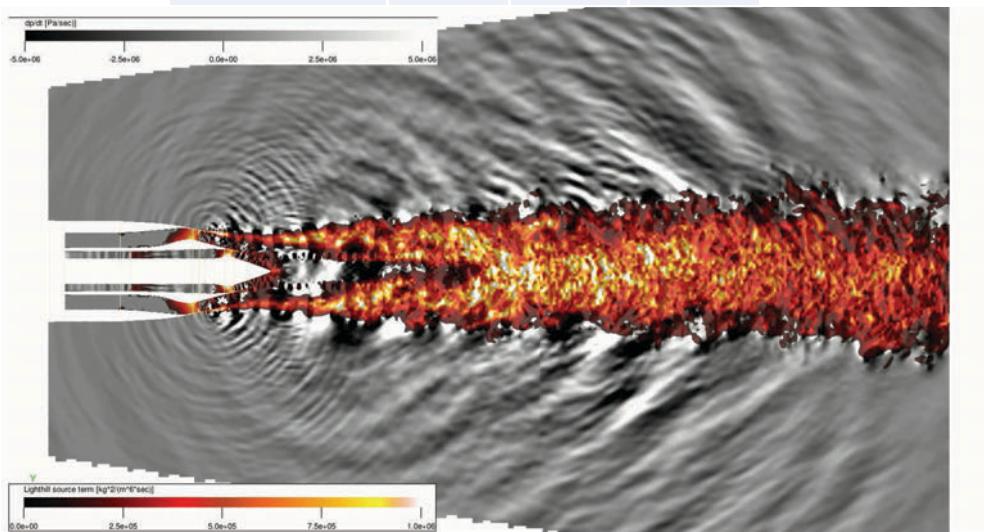


exa

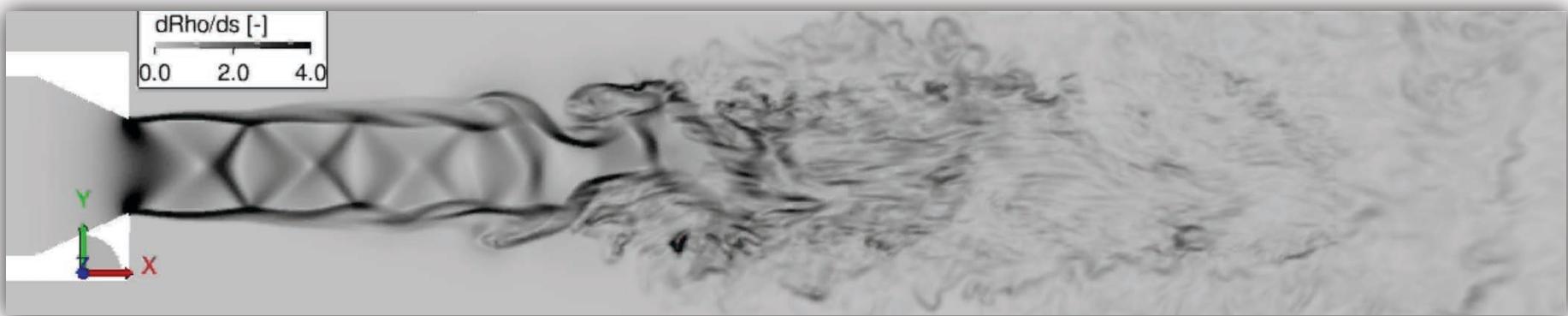
Co-axial Nozzle case



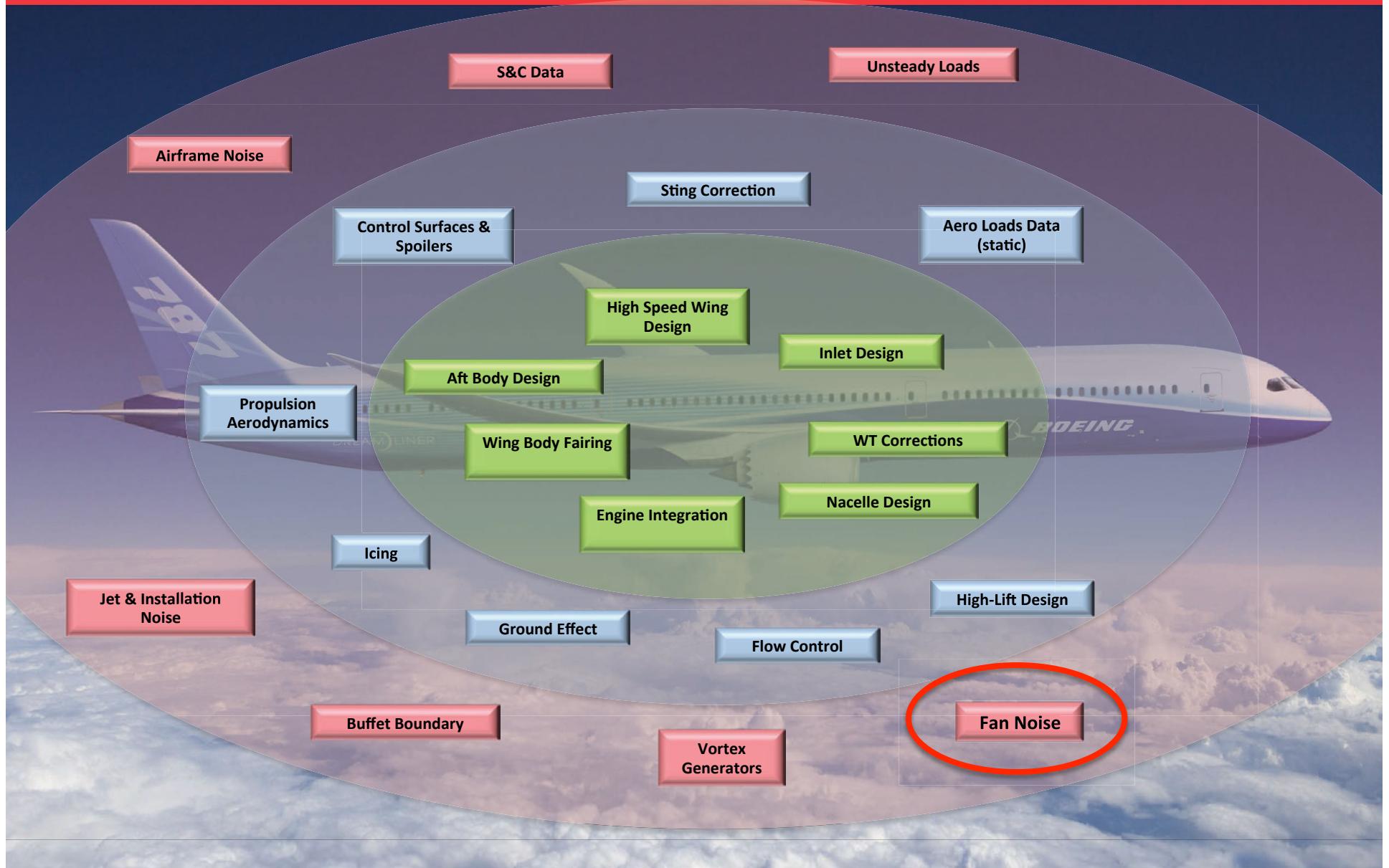
jet	M	Ma	Tr
primary	0.87	1.41	2.65
secondary	0.90	0.90	1.0



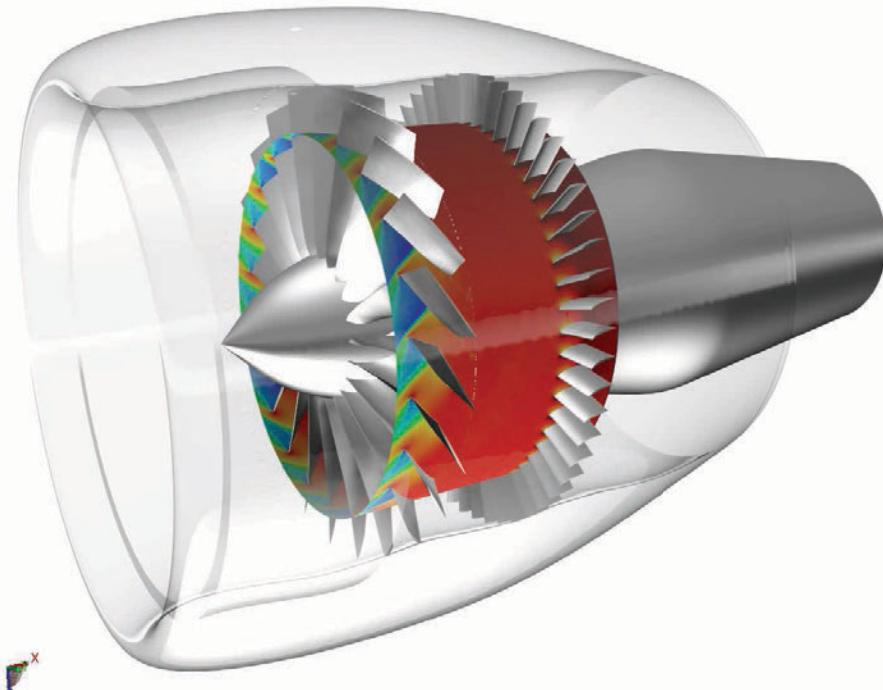
Supersonic Jets (Work in Progress)



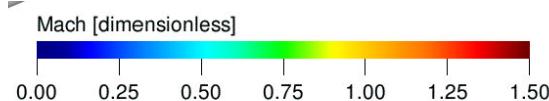
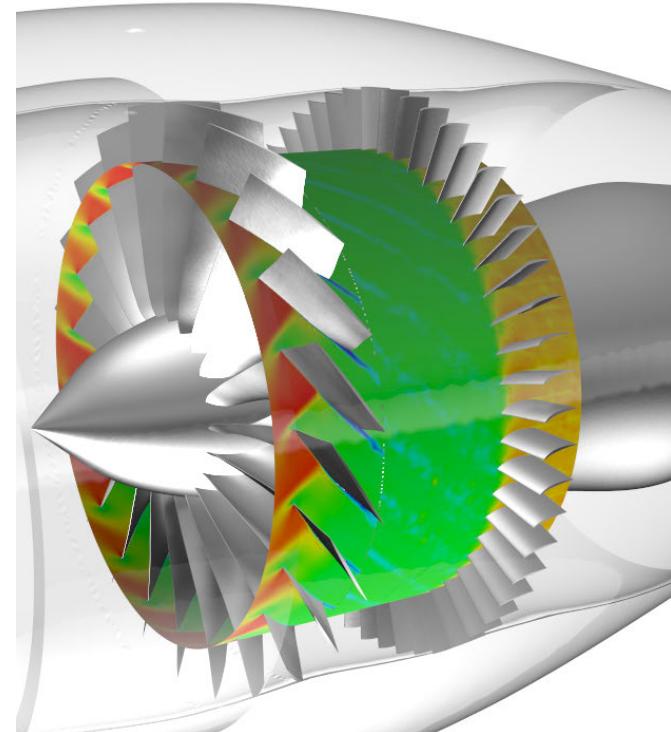
Applications



RC2 Case @12567 rpm

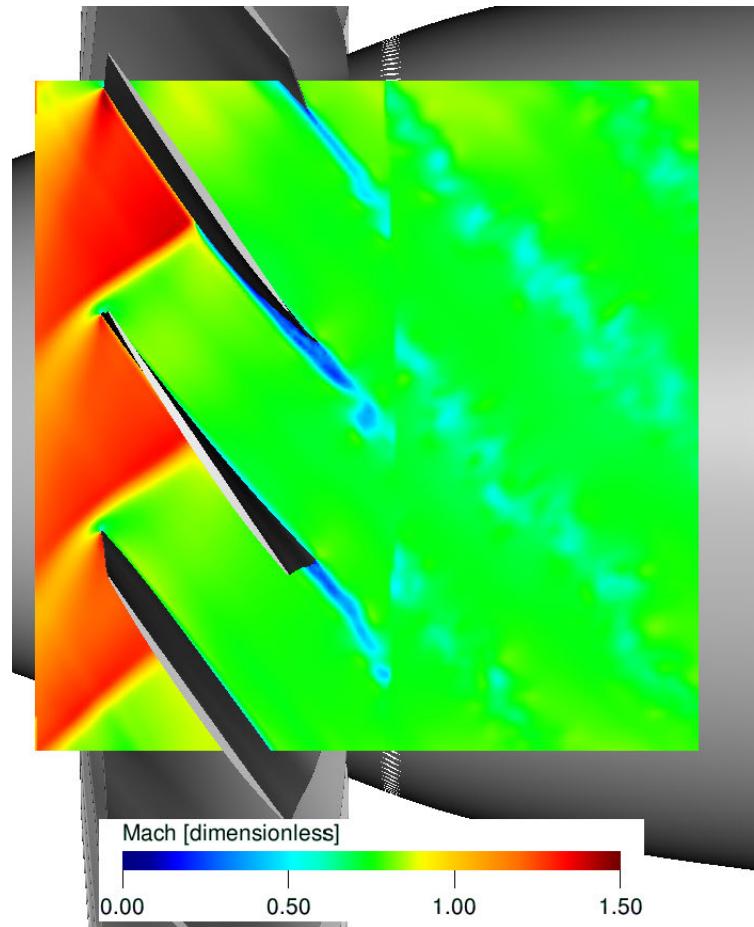


Density on rotor suction side

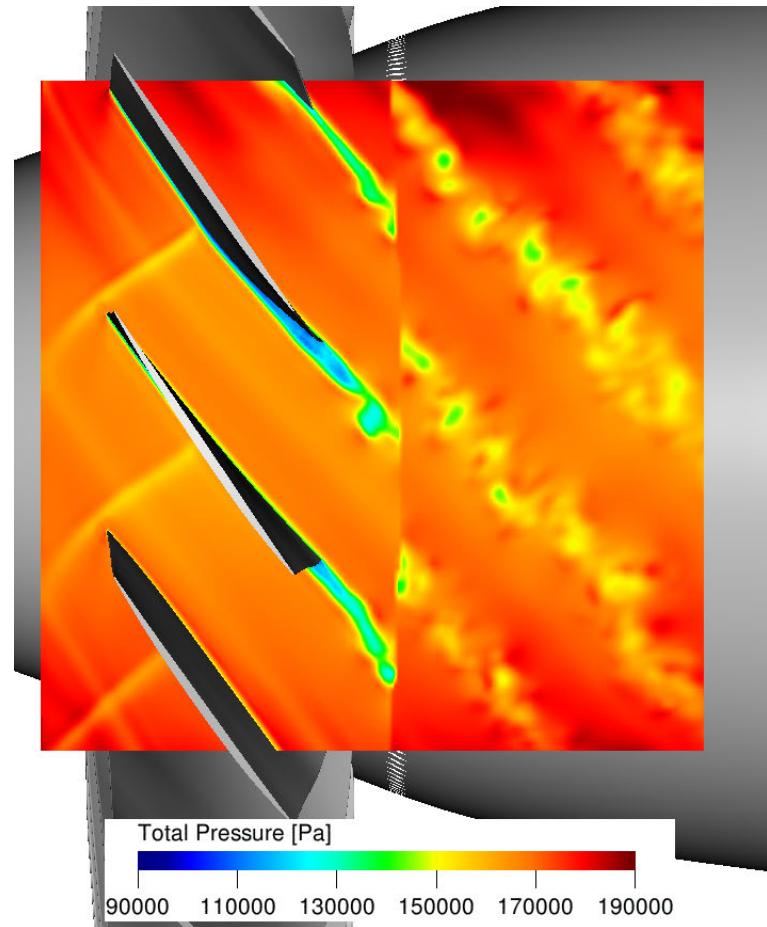


Flow analysis: slice @ $r/R=0.8$

Relative Mach number

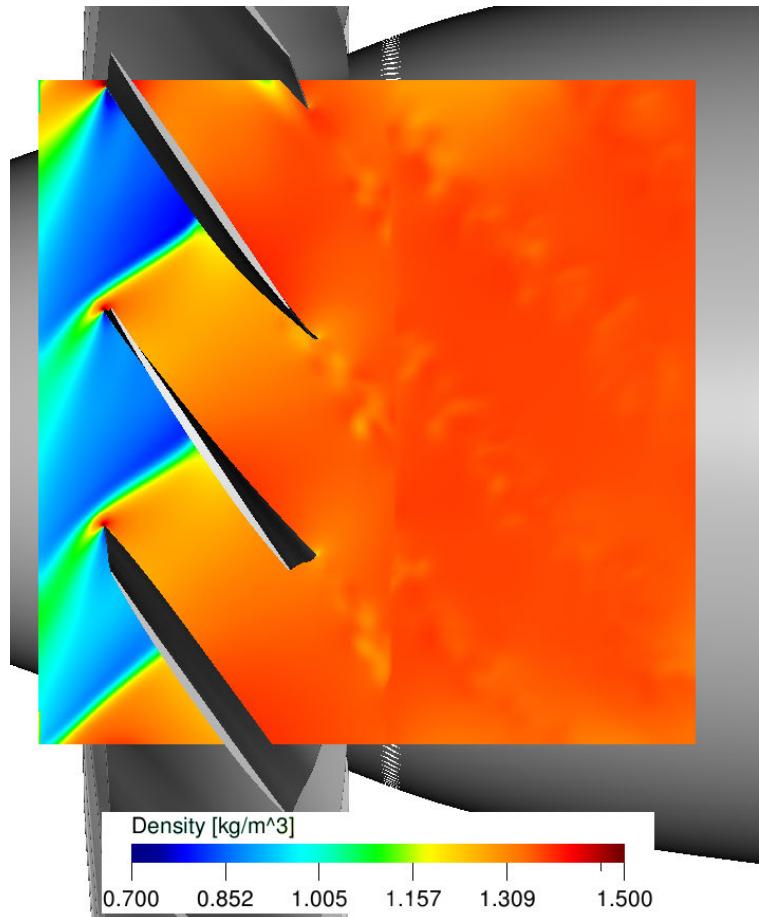


Total Pressure



Flow analysis: slice @ $r/R=0.8$

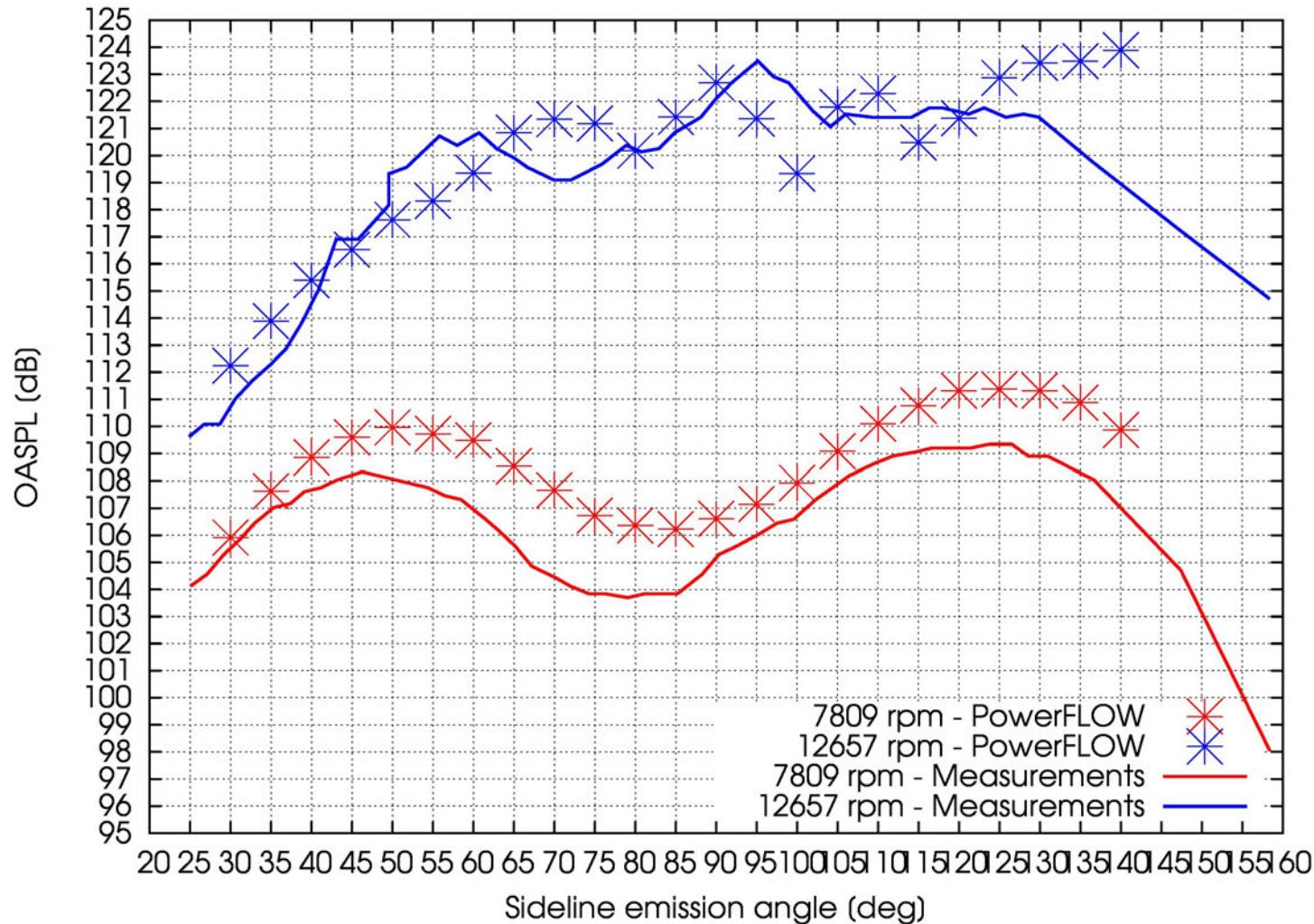
Density



Density Gradient

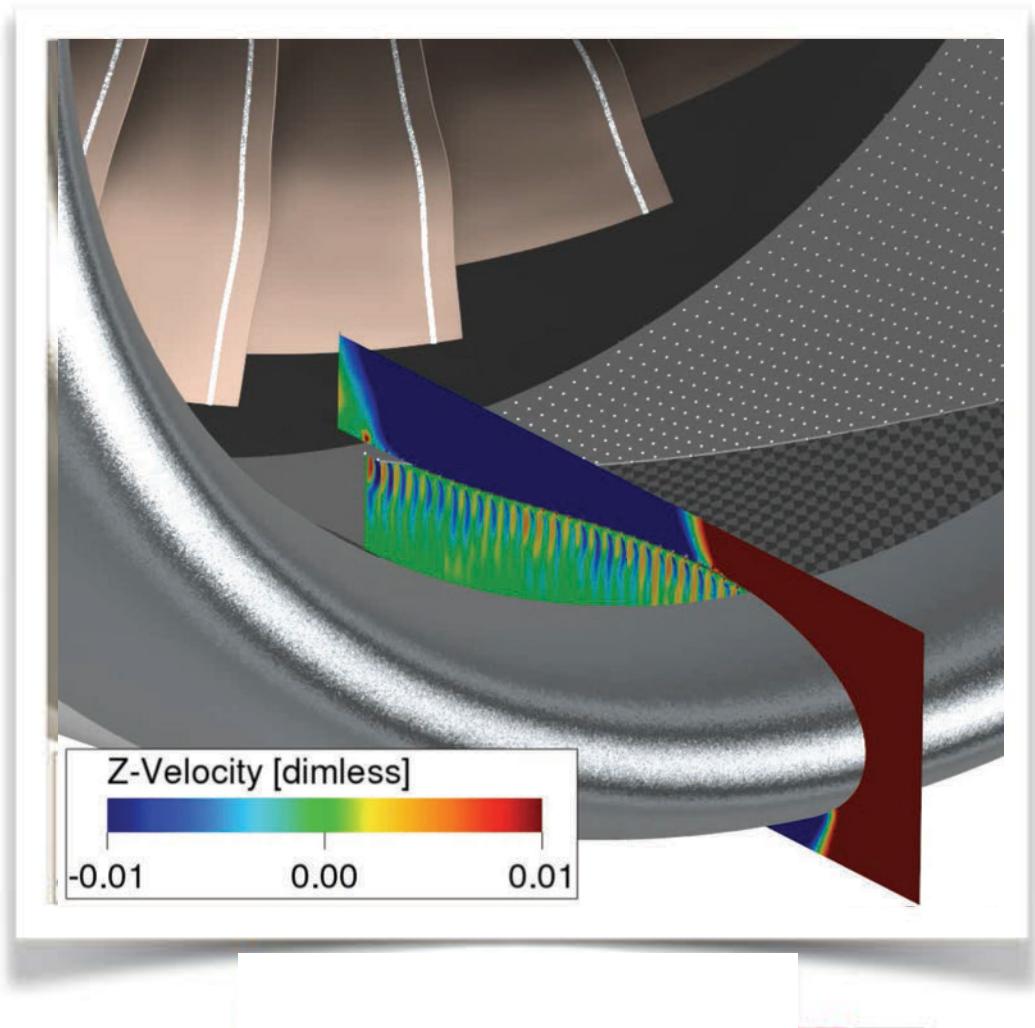
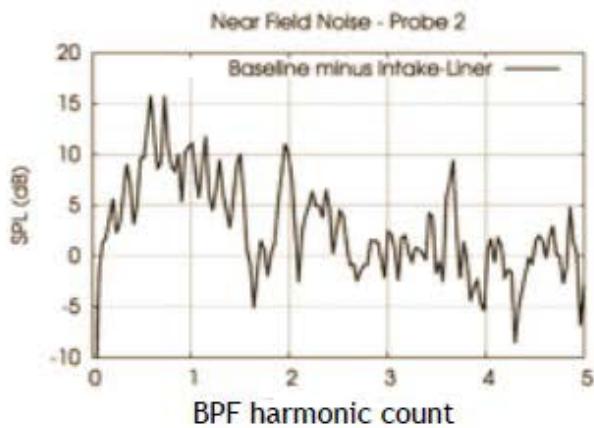
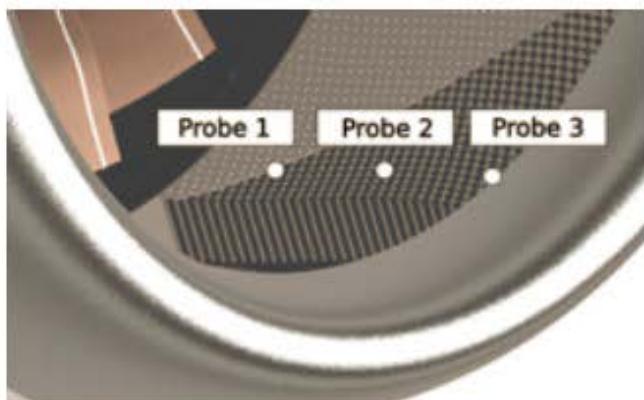


Far-field noise results



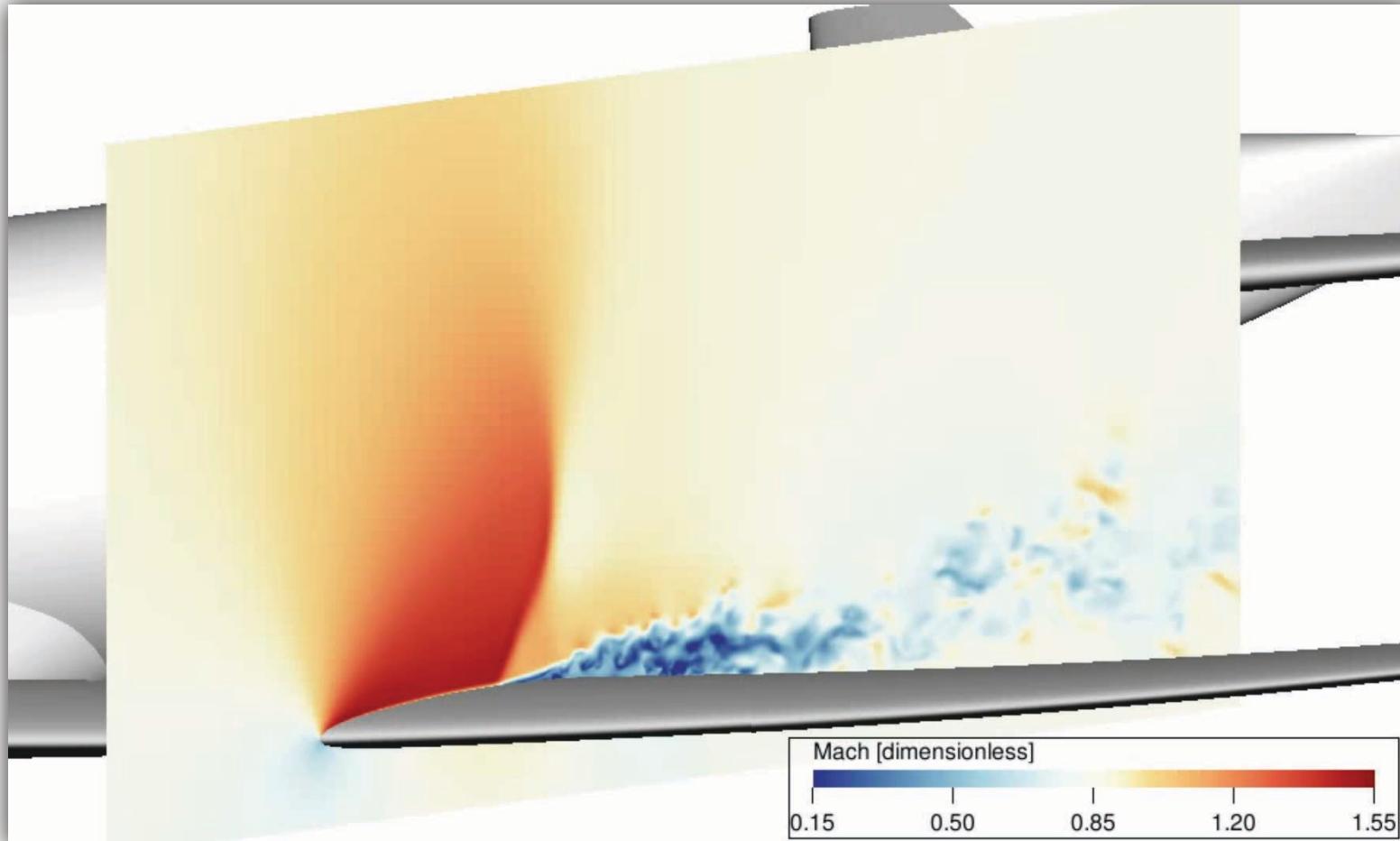
Liner Simulation - Preview

- 1 DoF honeycomb liner
- Realistic orifice diameter, face sheet thickness and porosity (> 8000 orifices and honeycomb cells)
- Optimal design for BPF-2 and ~BPF-4
- Expected broadband properties because of slightly variable depth



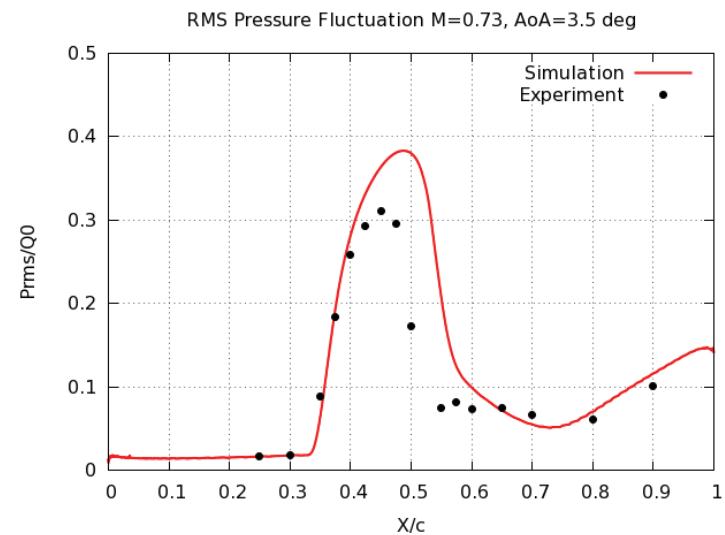
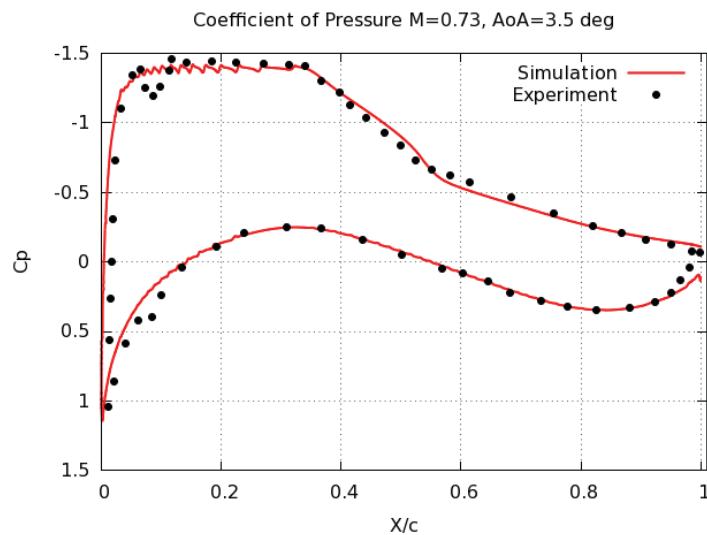
 Exa

Outlook: High-Speed Buffet



Transonic/Buffeting (Preliminary)

- Buffeting study on OAT15A Supercritical Airfoil
 - Shock wave- boundary layer interaction involving large scale instabilities.*
 - Preliminary 2D simulation at $M= 0.73$, angle of attack= 3.5° , $Re \approx 3e6$*



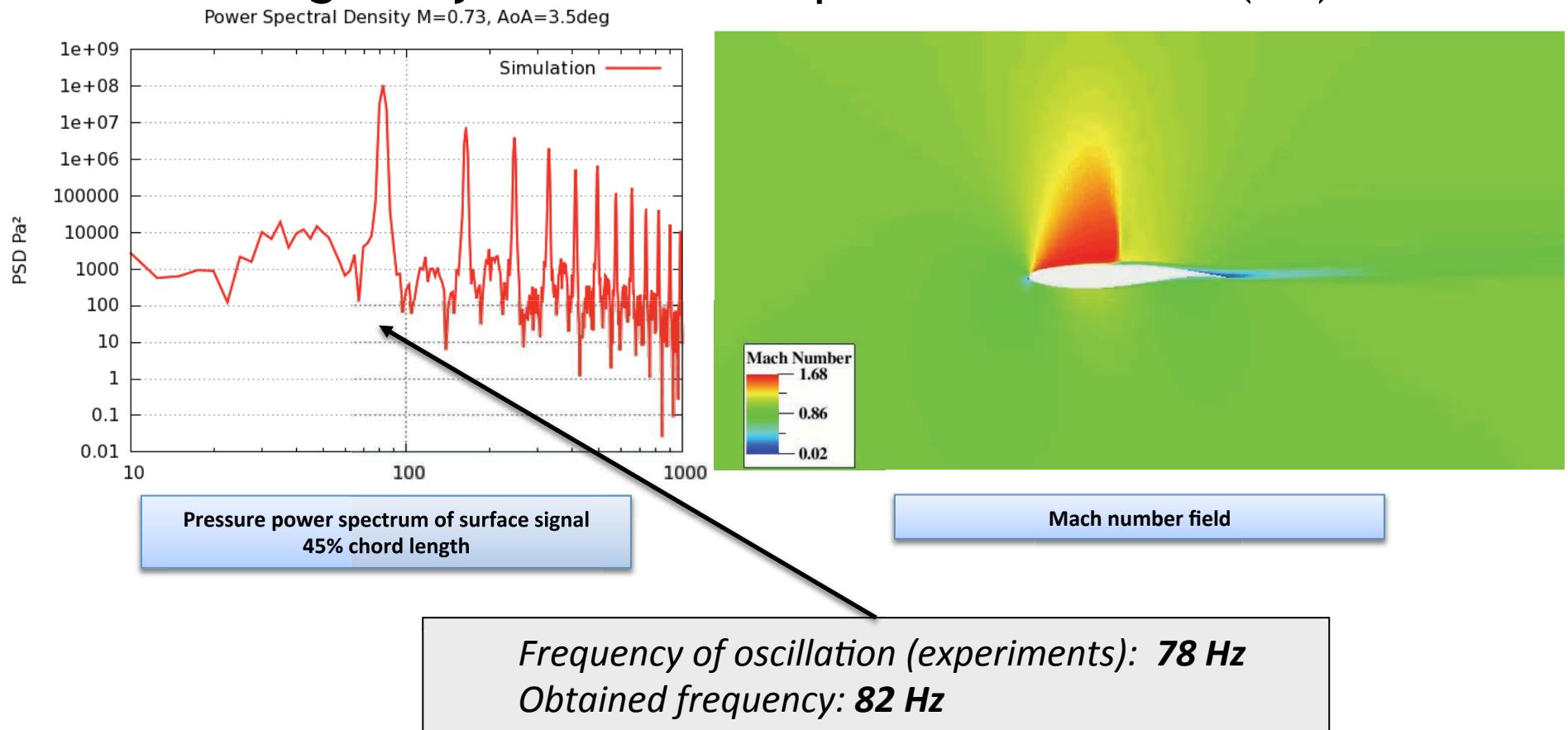
- Close agreement of average coefficient of pressure over the surface and amplitude of oscillation with experiments*.*

***Reference:** Jacquin L., Molton P., Deck S., Maury B., Soulevant D., 'An Experimental Study of Shock Oscillation over a Transonic Supercritical Profile', AIAA Journal Vol 47, No 9, 2009.



Transonic/Buffeting (Preliminary)

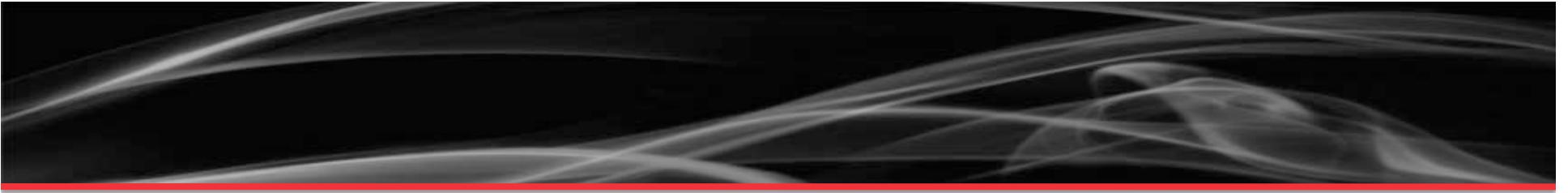
- Buffeting study on OAT15A Supercritical Airfoil (2D)



Summary

- Extension of LBM to transonic & supersonic flows
 - Achieved through hybrid higher-order LBM scheme
 - Enables simulations up to ~Mach 2.0
 - Preserves all key advantages of low speed LBM versions
- Main Initial Application Targets
 - Unsteady high-speed aerodynamics (buffet, ...)
 - Flow control
 - Propulsion noise: fan, jet & installation noise
- Status of LBM with regard to CFD Vision 2030 Report
 - Efficient handling of unsteady turbulent flows with significant regions of separation
 - Mesh generation
 - Robustness and automation of CFD simulations
 - Efficient use of HPC infrastructure
 - Managing very large amounts of data
 - Multi-disciplinary analysis & optimization





Thank You!

