

Signal Filter

- Signals in Time and Frequency:
 - A signal is just a value that changes over time. But looking only in terms of time hides what actually makes the shape. Every signal can also be viewed as a mixture of simpler waves/sinusoids (frequencies). This second view makes structure visible.
 - $x[n] \leftrightarrow X[k]$
- The DFT turns a time signal into a list of frequency strengths:
 - $$X[k] = \sum_{n=0}^{N-1} x[n]e^{-j2\pi kn/N}$$
- Why frequency helps us understand signals
 - Sharp edges = lots of frequencies
 - Smooth waves = mostly low frequencies
 - Noise = many frequencies
 - Frequency is like seeing the ingredients of the signal, the visualiser shows these ingredients.
- Filtering as choosing what to keep
 - If a signal is made of ingredients, a filter simply just chooses which ones stay.
 - Low-pass: keep slow waves = smooth output
 - High pass: keep fast waves = highlight details
 - Band-pass: keep a specific range
 - $$Y[k] = H[k]X[k]$$
 - Where $H[k]$ is just a mask of 0s and 1s.
 - This is the entire basis of digital filtering.
- Reconstructing the filtered signal
 - Once selected, the remaining frequencies are added back together to rebuild the time signal.
 - $$y[n] = \frac{1}{N} \sum_{k=0}^{N-1} Y[k]e^{j2\pi kn/N}$$

- The visualiser shows this happening instantly as you toggle filters.
- How sampling affects frequency
 - A digital signal is just a list of samples.
 - The sampling rate determines:
 - The maximum frequency you can represent.
 - The spacing between frequency bins.
 - This explains why the spectrum goes from 0 to $\frac{N}{2}$.
 - $f_{\text{Nyquist}} = \frac{f_s}{2}$
 - This is the Nyquist-Shannon sampling theorem, frequencies above f_{Nyquist} will fold back, causing aliasing.
- Why edges create high frequencies
 - Sudden jumps require rapid oscillations to approximate them.
 - Removing high frequencies smooths the signal because it removes the oscillations that try to "build" those corners.
 - This concept builds the foundations of both DSP and Fourier.
- Ideal vs Real filters
 - Real filters have limits.
 - Ideal filters instantly cut frequencies, which is perfect for demonstration but not physically possible or realisable.
 - Ideal low-pass filter's impulse response:
 - $h[n] = \sin c(x)$
- Why this matters in engineering
 - Filtering is used in:
 - communications (noise removal, channel shaping)
 - audio processing
 - antennas and RF systems
 - ECG and biomedical filtering
 - control systems
 - data processing