

# SpatialLLM

## Bridging the Gap Between Natural Language and 3D Scans

Under supervision of:

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Team members:

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Hongyu Ye

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Julia Pille

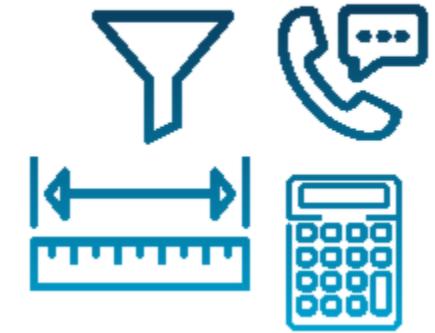
Neelabh Singh





*“What does it cost to repaint all the walls in the living room?”*

Pictures  
3D-scan  
BIM-models



*“What does it cost to repaint all the walls in the living room?”*

# SpatiaLLM

# The Team

**Project manager**



Mark van der Meer

**Technical manager**



Hongyu Ye

**Technical manager**



Segher ter Braak

**Communication manager**



Neelabh Singh

**Reporting manager**



Julia Pille



- **Motto:** Make point cloud data accessible, intelligent, and usable anywhere. Their AI-driven platform stores, classifies, and streamlines raw scans into BIM, simplifying complex 3D workflows.
- **Need:** A chatbot interface so non-experts can get quick, intuitive insights.



What are you working on?

+ Ask anything

0

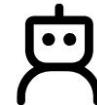


# Problem, Summary and Goal

- **Problem:** LLMs can answer questions from an image, showing basic visual understanding, but can they can not yet answer questions directly from 3D scans.
- **Summary:** Develop a chatbot that understands natural-language queries and gives back relevant spatial and visual evidence.
- **Goal:** Bridge human language with spatial-visual reasoning.



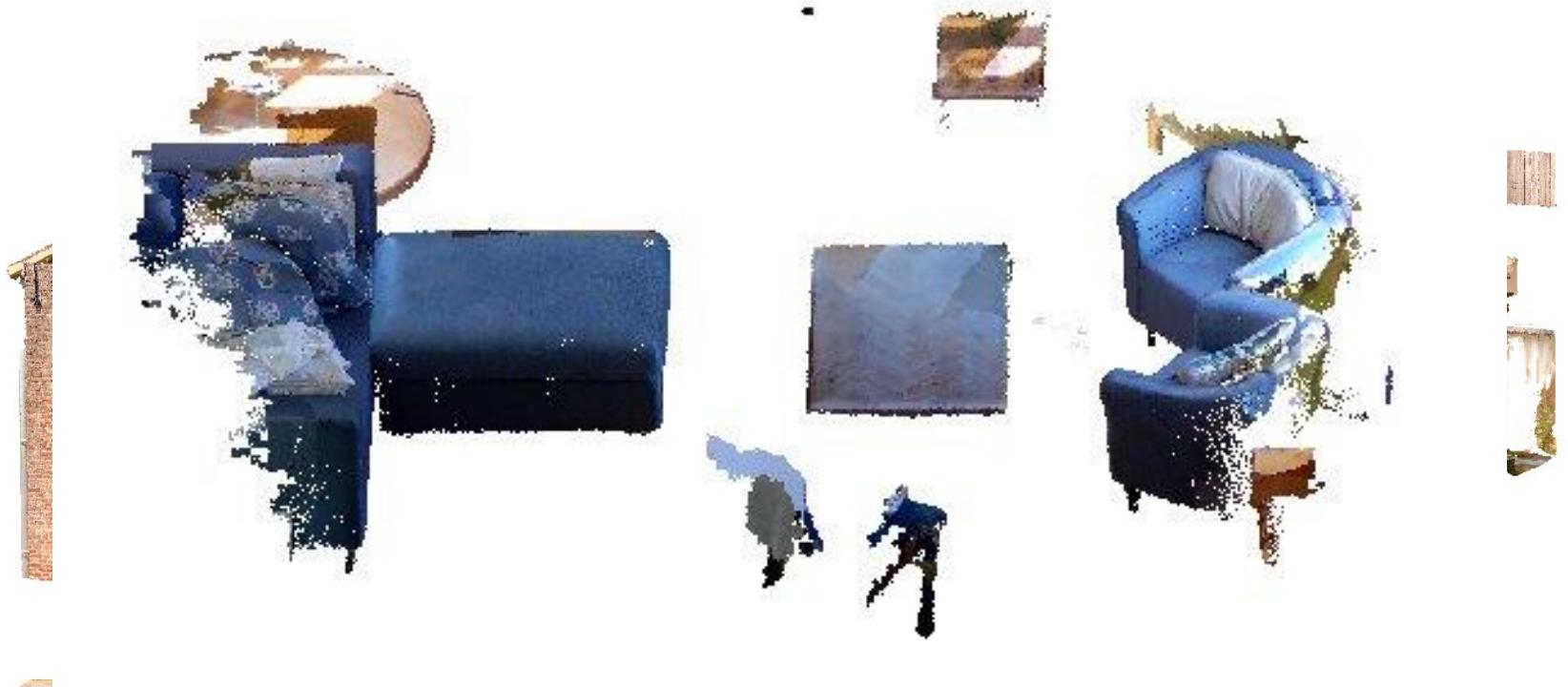
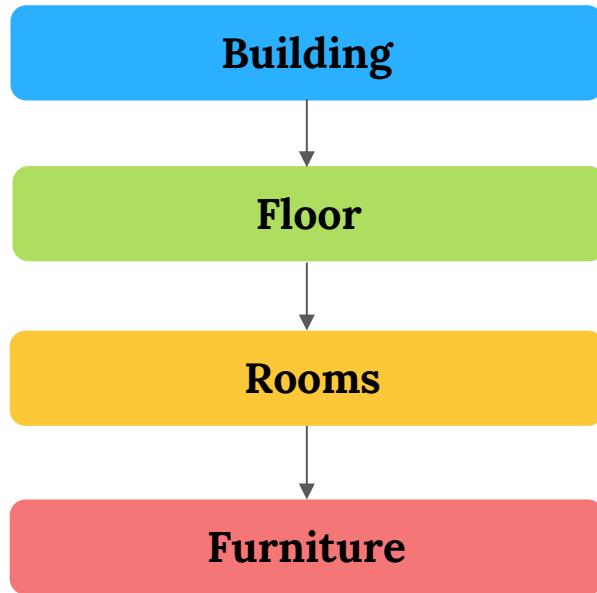
Area  
Volume  
Distance  
Color



“What does it cost to  
repaint all the walls  
in the living room?”



“It costs ... euros to  
paint all the walls in  
the living room.”



**Structural**



**Non-structural**



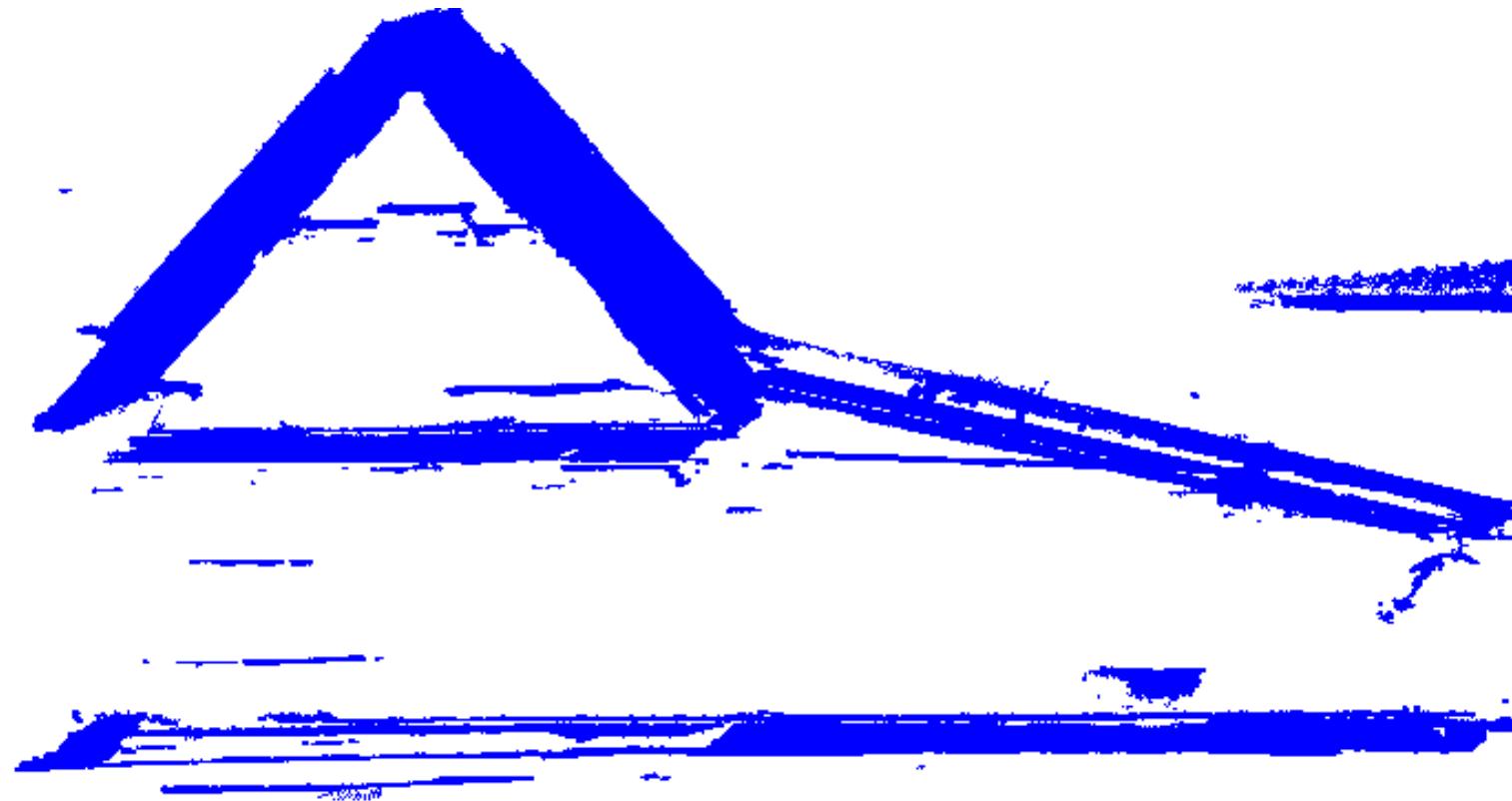
**Building**



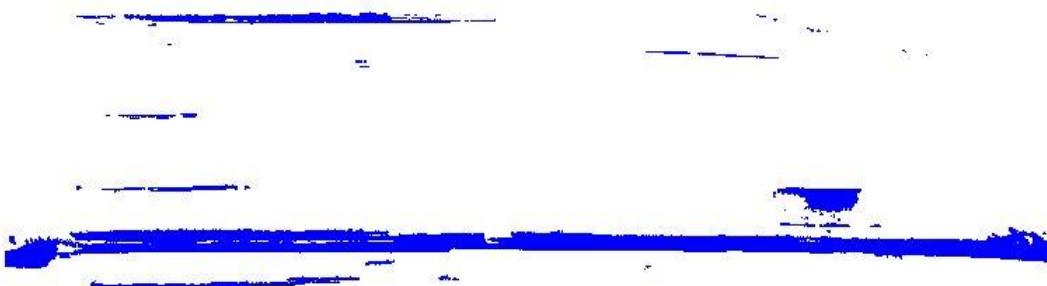
**Floor**



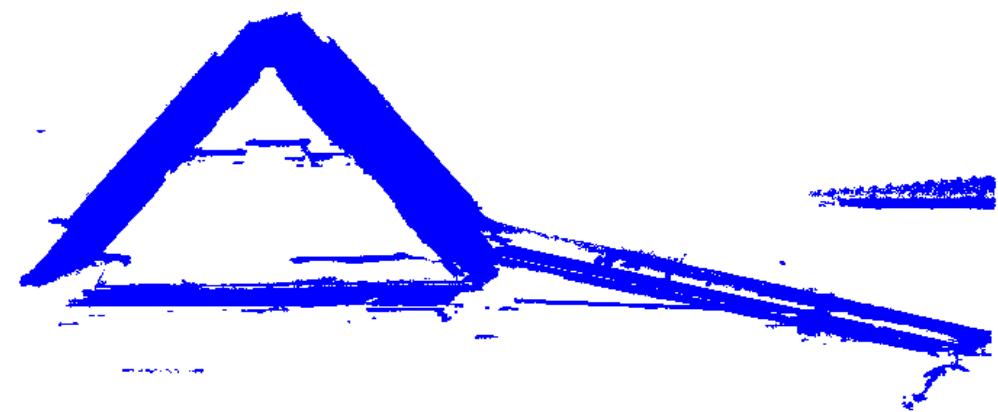
## Floor & Ceiling



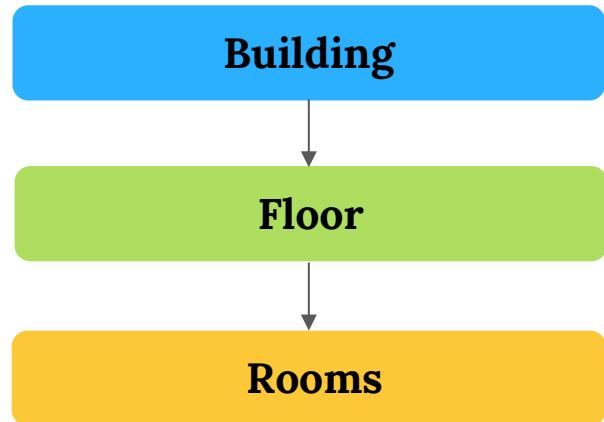
**Floor**

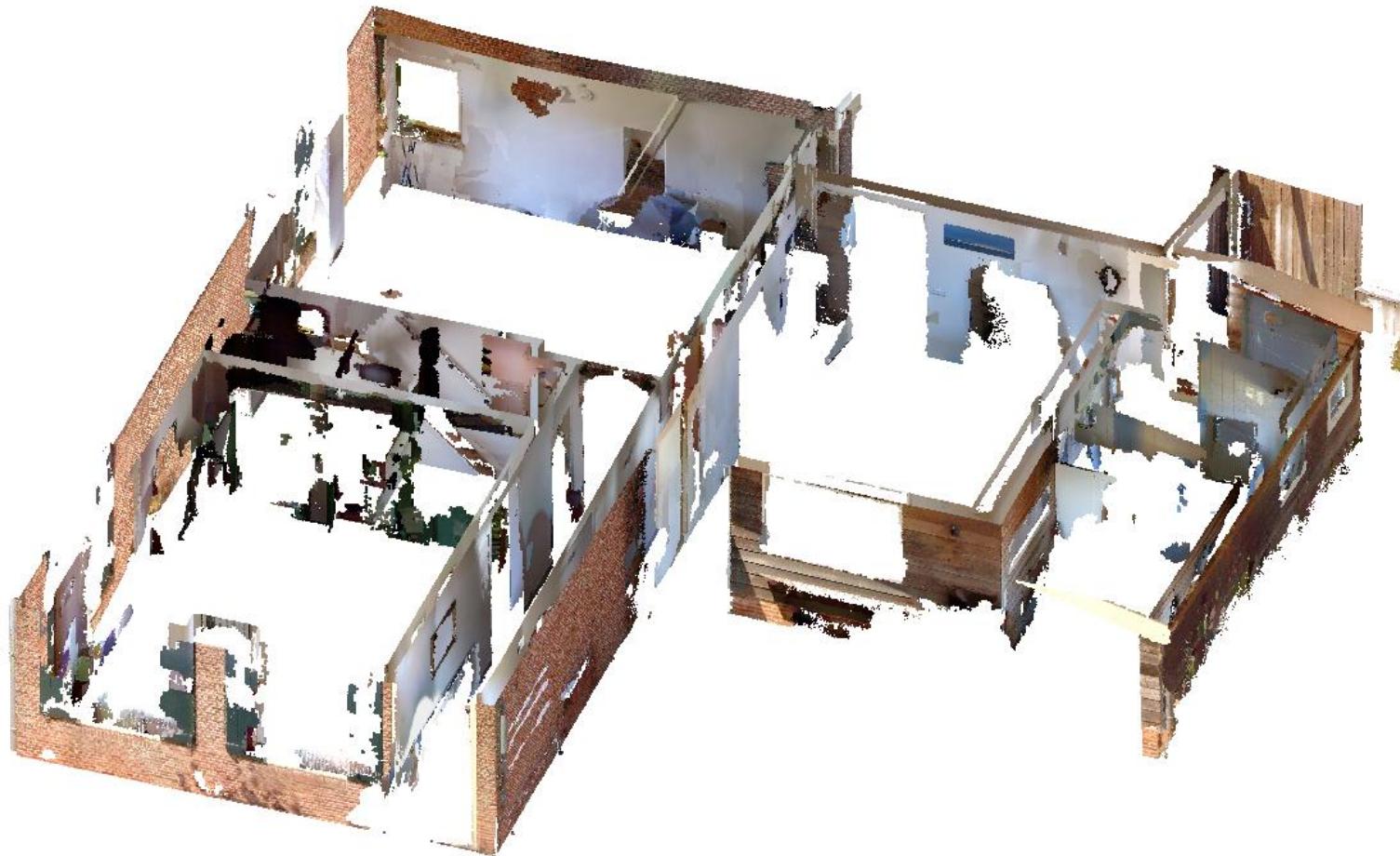


**Ceiling**

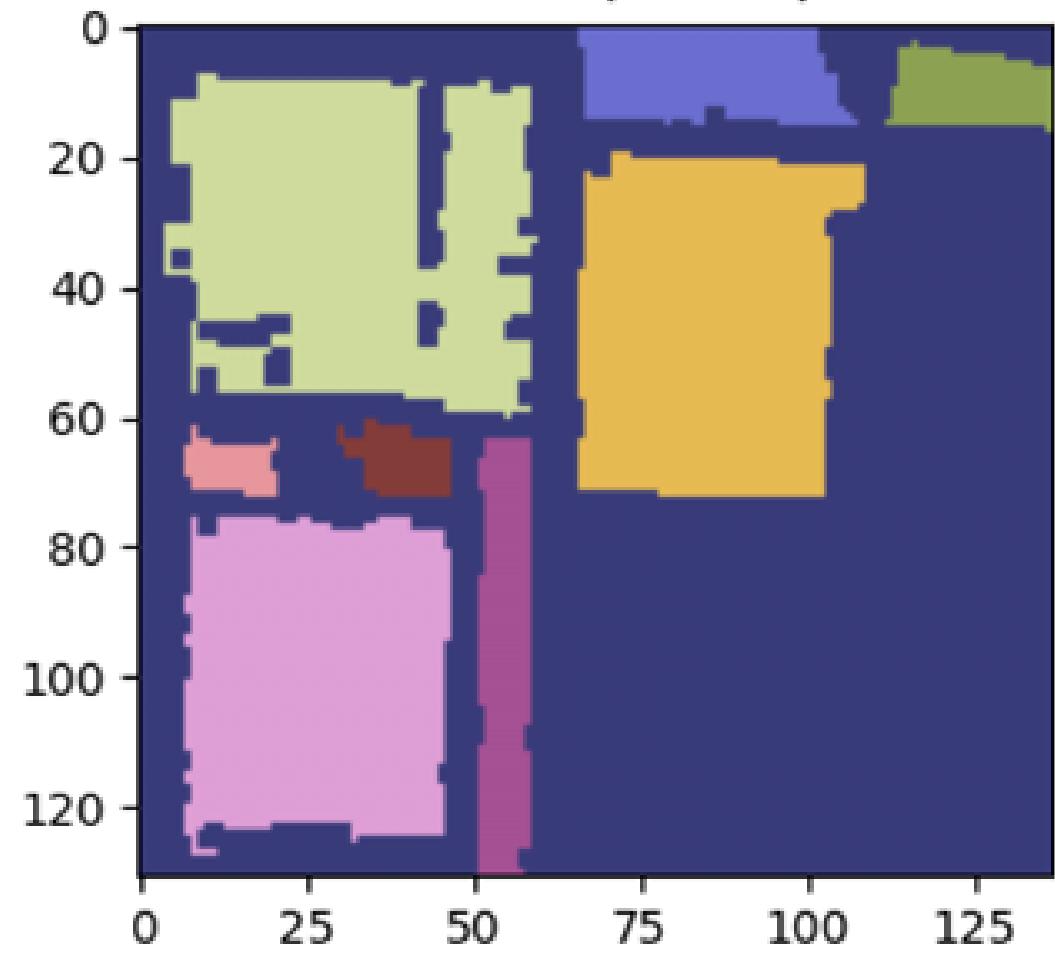
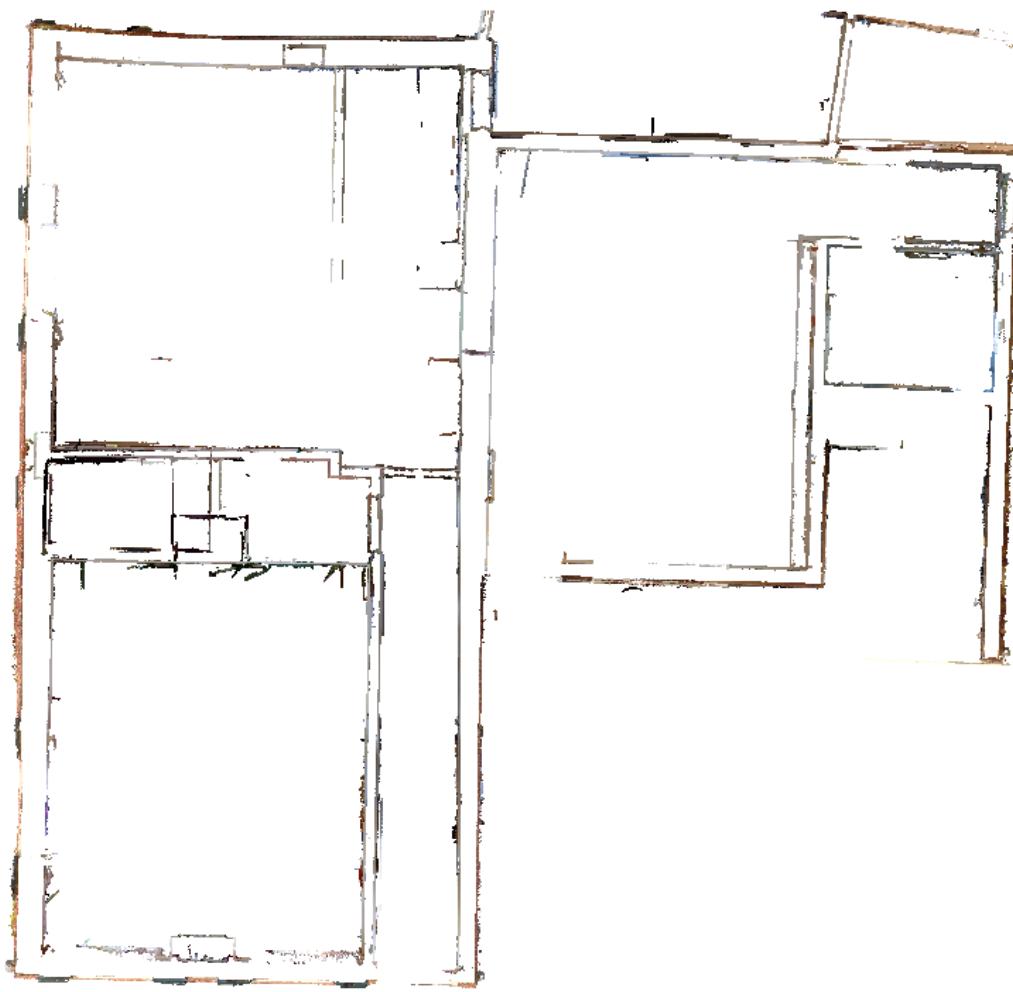






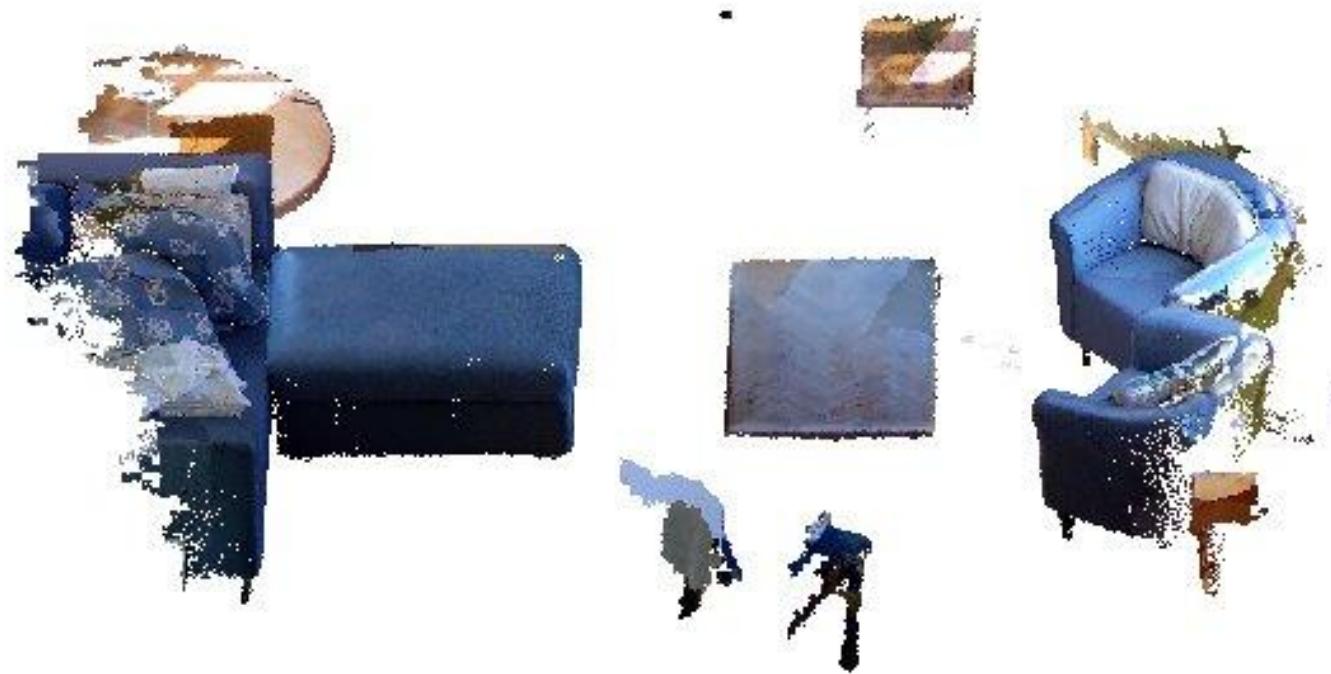
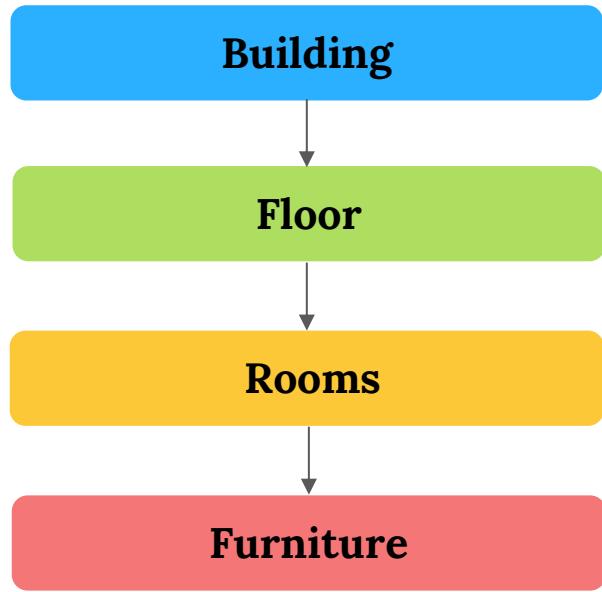


Floor plan



## Room reconstruction





## Furniture reconstruction

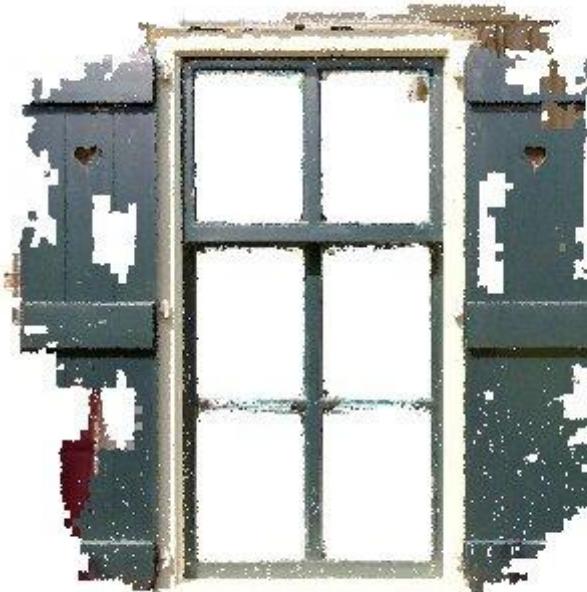


## Clustering

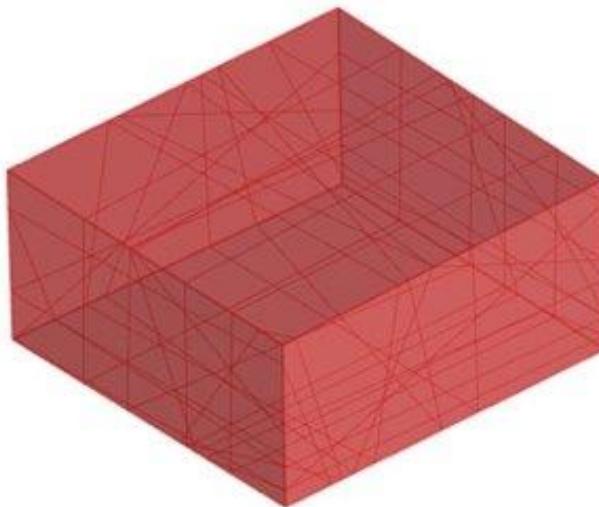
Window\_001



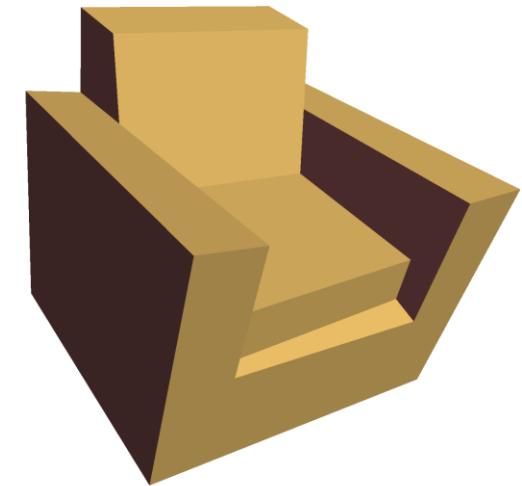
Window\_002

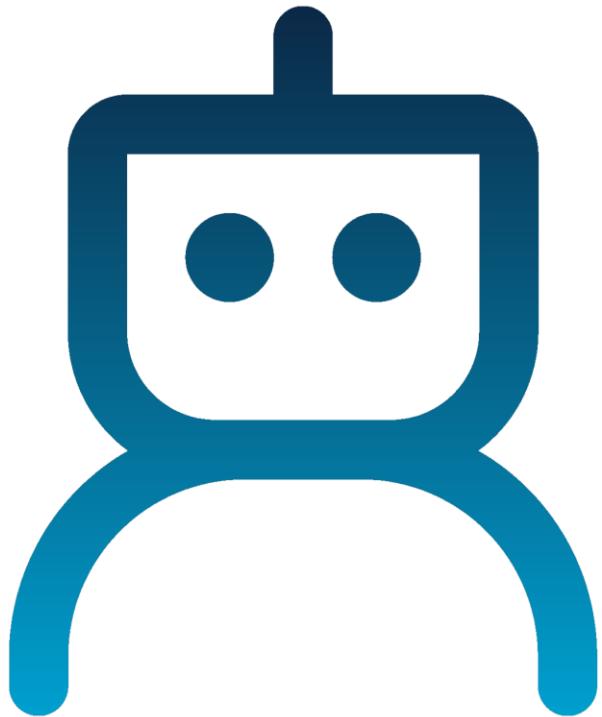


## PolyFit



## Surface reconstruction





# **Building**

*Database*

## **Floor**

*Defines Building Levels*

## **Rooms**

*Stores rooms data and links to floor*

## **Objects**

*Stores all 3D objects of a room*

## **Planes**

*Stores walls, floors and ceiling*

## **Images**

*Stores panoramas to rooms*

# Images

*Stores panoramas to rooms*

**Room type = unknown**

**Get room panorama image**

**Ask LLM semantic meaning**

**LLM response: "This is a kitchen"**

**Room type = kitchen**



"What does it cost to repaint all the walls in the living room?"

1. Scope classification

2. Retrieve data from database

3. Use tool functions

4. Augment and generate answer

"It costs ... euros to paint all the walls in the living room"



# Images

*Stores panoramas to rooms*

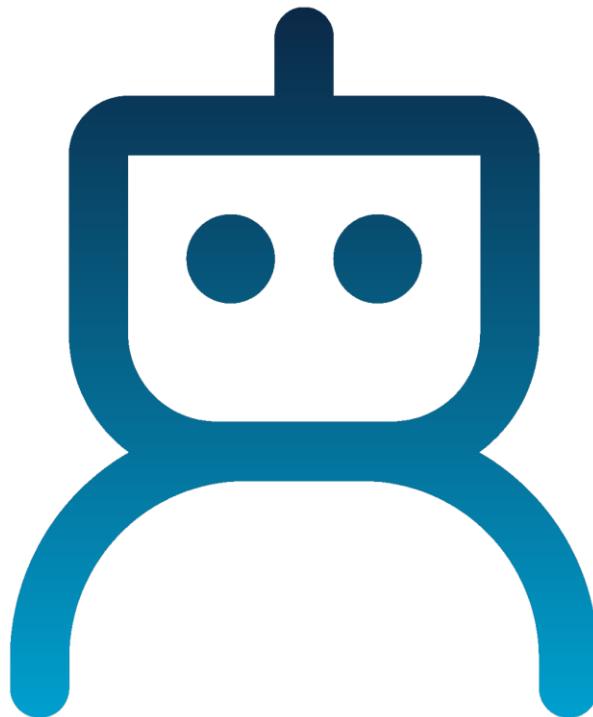
**Room type = unknown**

**Get room panorama image**

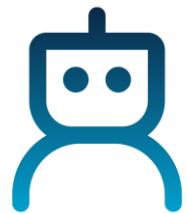
**Ask LLM semantic meaning**

**LLM response: "This is a kitchen"**

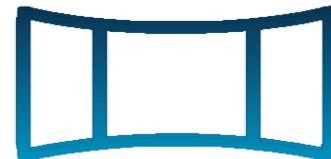
**Room type = kitchen**



# User Interface



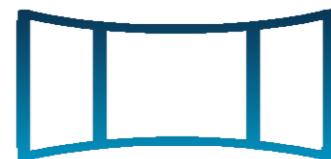
Chatbot



Panorama viewer



3D viewer



2D-to-3D workflow

# 2D-to-3D workflow



# 2D-to-3D workflow



# 2D-to-3D workflow



# 2D-to-3D workflow



>>

Deploy :

# Spatial LLM

Bridging The Gap Between Natural Language and 3D Scans



- Overall structure works as intended.
- Application is not perfect.
- Performance vary between different environments.
- Improve product based on input different stakeholders.
- Hard to verify the accuracy of results from the chatbot.

Bridged some gaps between natural language and spatial reasoning.