

# SpatialLLM

GEOIT1501

## Bridging the Gap Between Natural Language and 3D Scans

### Under supervision of:

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### Team members:

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Julia Pille

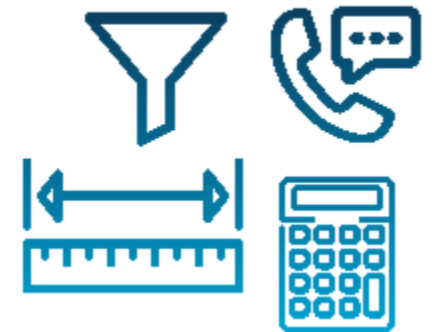
Neelabh Singh





*“What does it cost to  
repaint all the walls  
in the living room?”*

Pictures  
3D-scan  
BIM-models



*“What does it cost to repaint all the walls in the living room?”*

# SpatiaLLM

# The Team

**Project manager**



Mark van der Meer

**Technical manager**



Hongyu Ye

**Technical manager**



Segher ter Braak

**Communication manager**



Neelabh Singh

**Reporting manager**



Julia Pille



- **Motto:** Make point cloud data accessible, intelligent, and usable anywhere. Their AI-driven platform stores, classifies, and streamlines raw scans into BIM, simplifying complex 3D workflows.
- **Need:** A chatbot interface so non-experts can get quick, intuitive insights.



What are you working on?

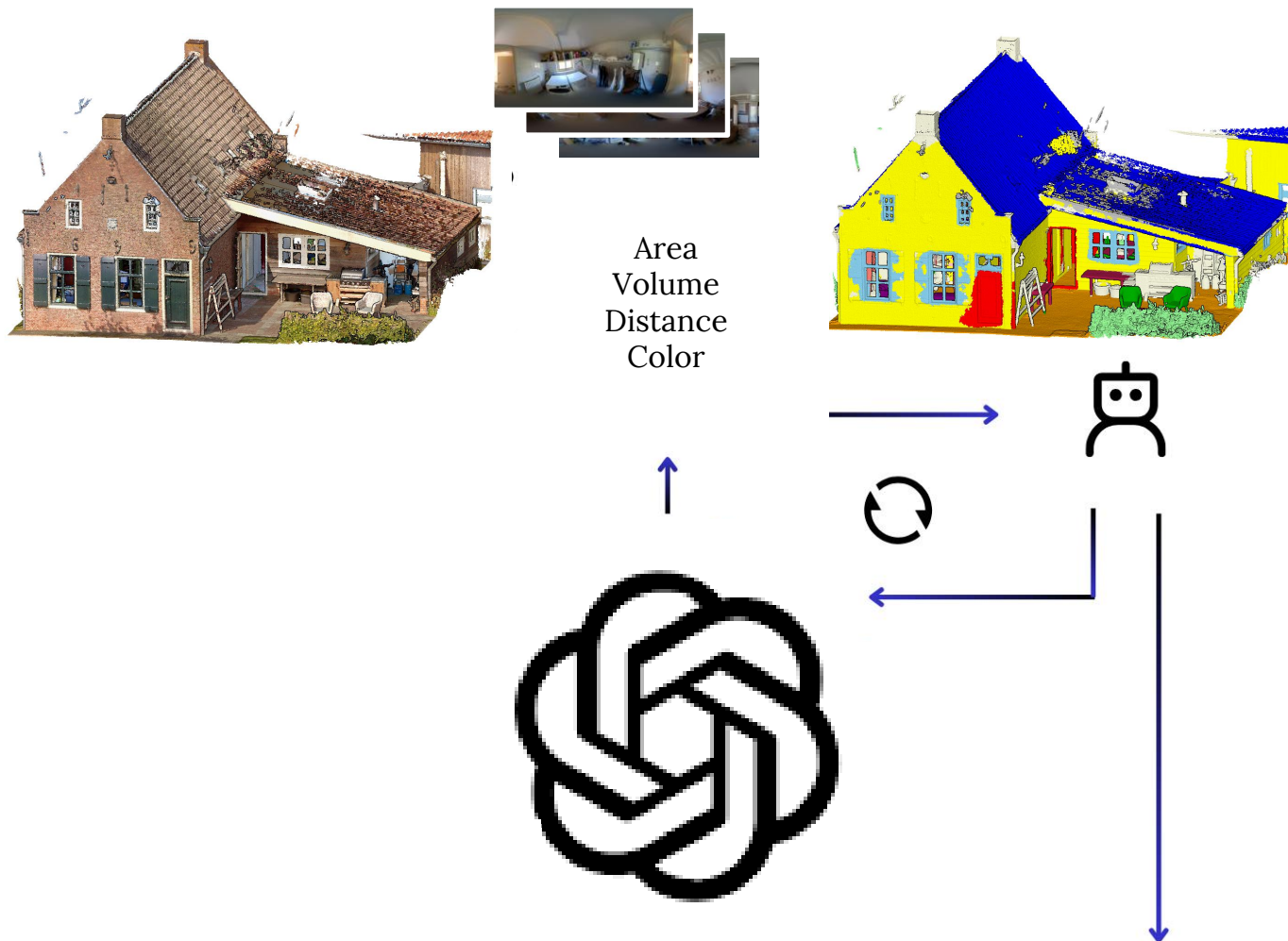
+ Ask anything





# Problem, Summary and Goal

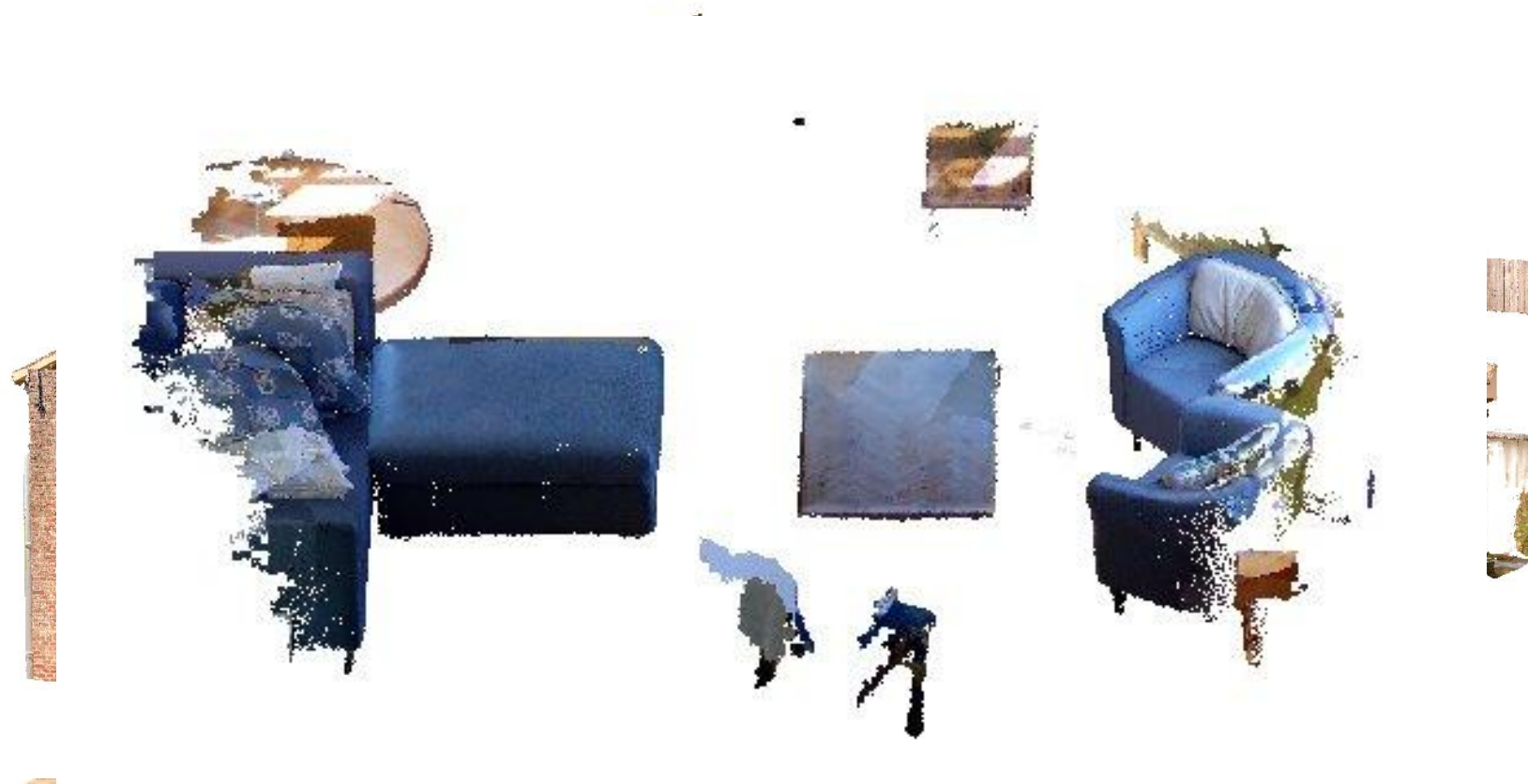
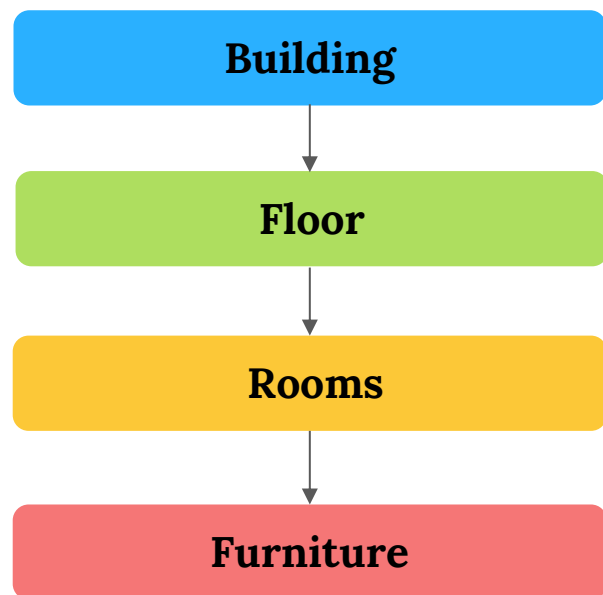
- **Problem:** LLMs can answer questions from an image, showing basic visual understanding, but can they can not yet answer questions directly from 3D scans.
- **Summary:** Develop a chatbot that understands natural-language queries and gives back relevant spatial and visual evidence.
- **Goal:** Bridge human language with spatial-visual reasoning.



“What does it cost to  
repaint all the walls  
in the living room?”



“It costs ... euros to  
paint all the walls in  
the living room.”



## Structural



## Non-structural





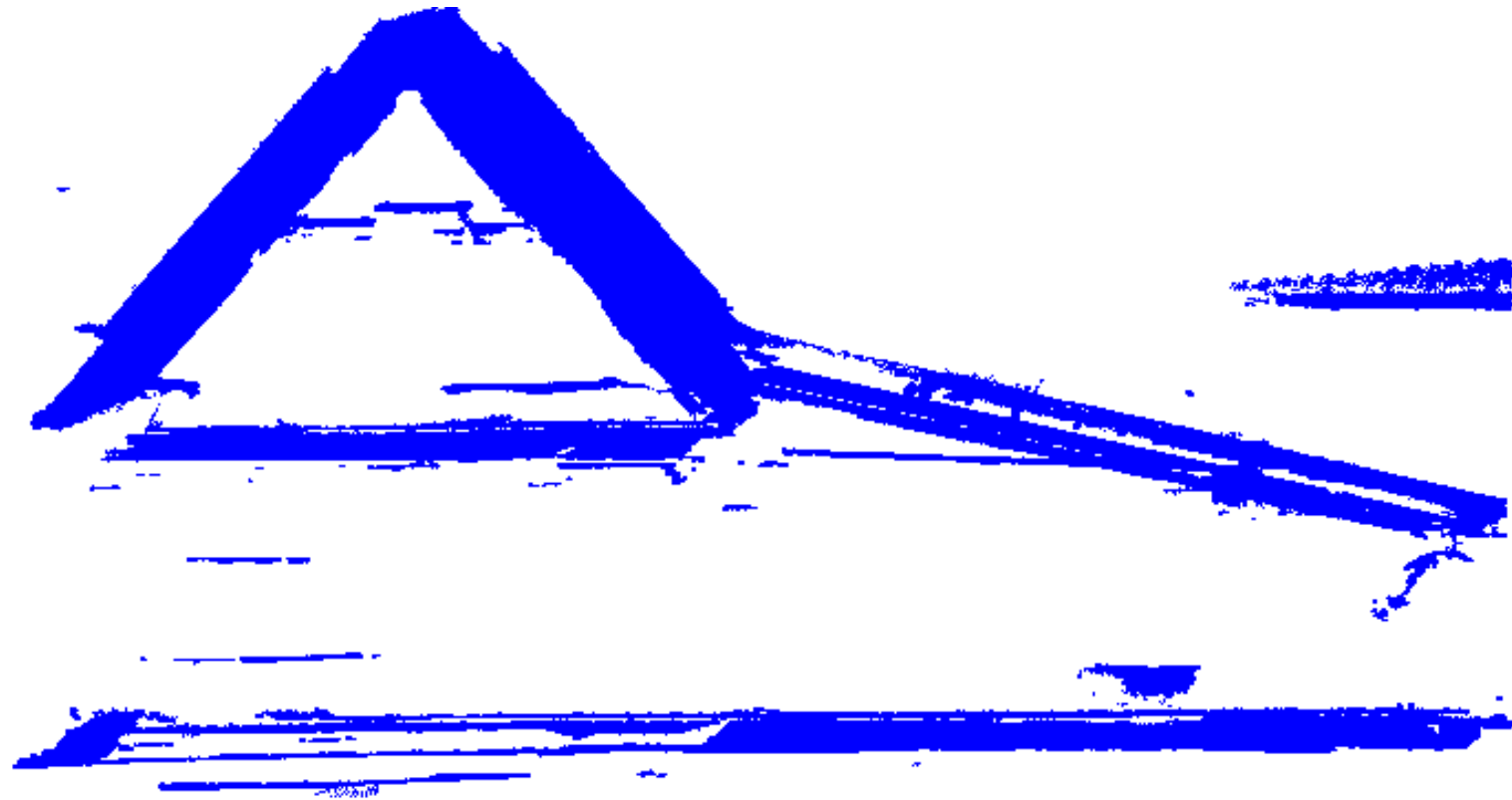
**Building**



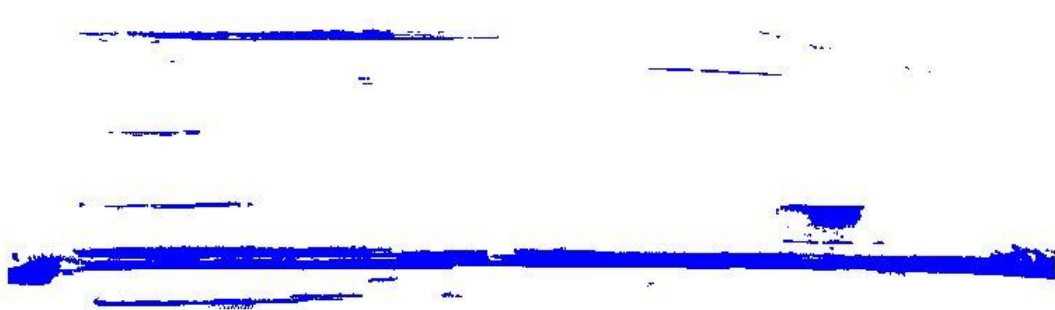
**Floor**



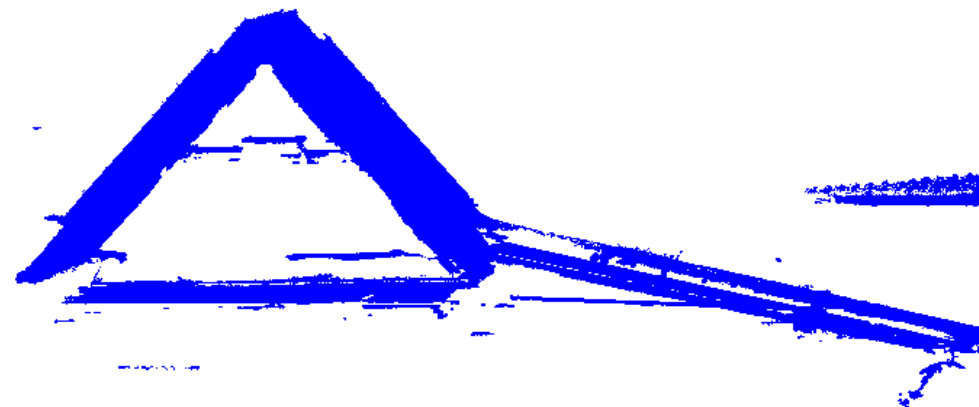
## Floor & Ceiling



Floor



Ceiling









**Building**

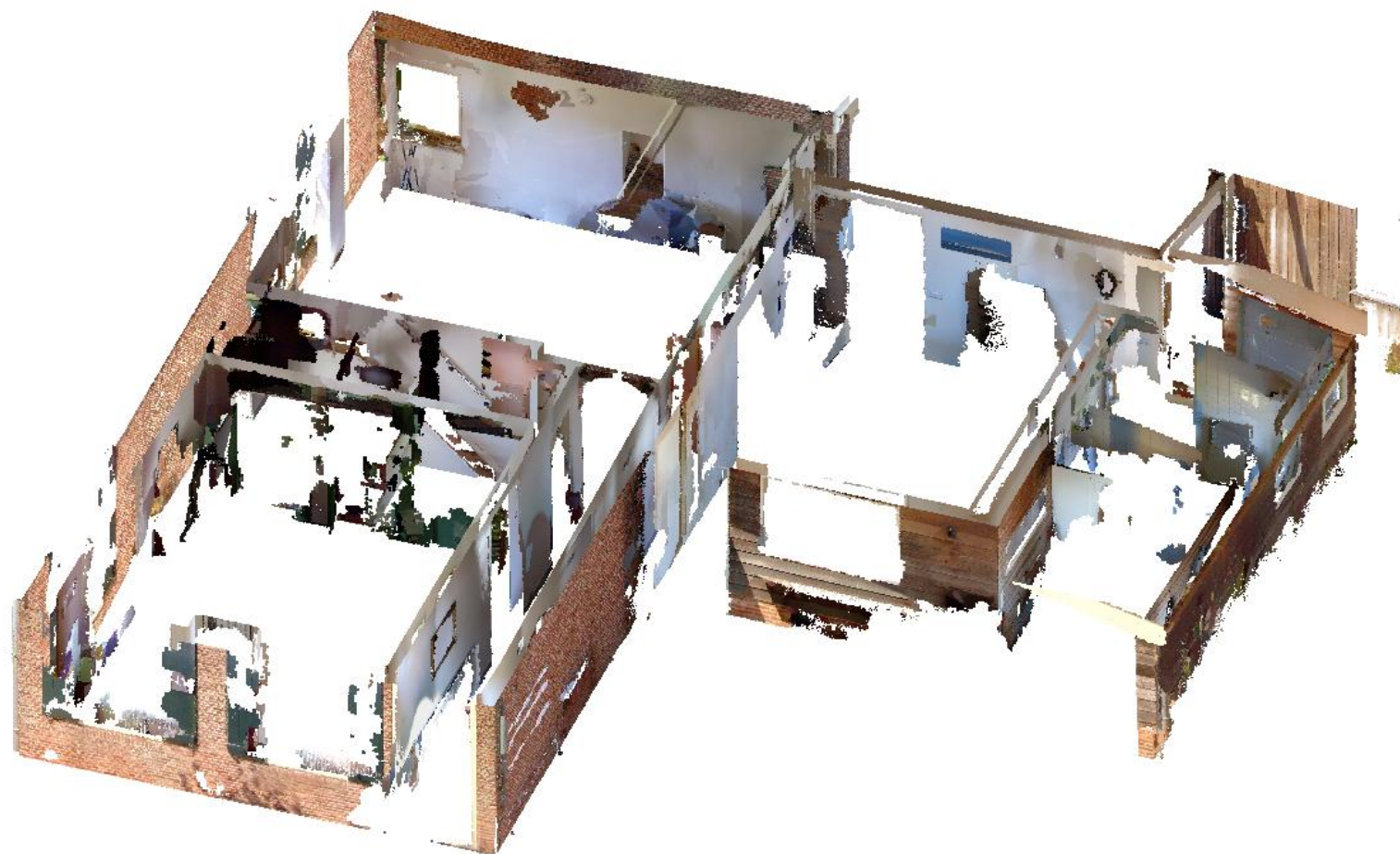


**Floor**

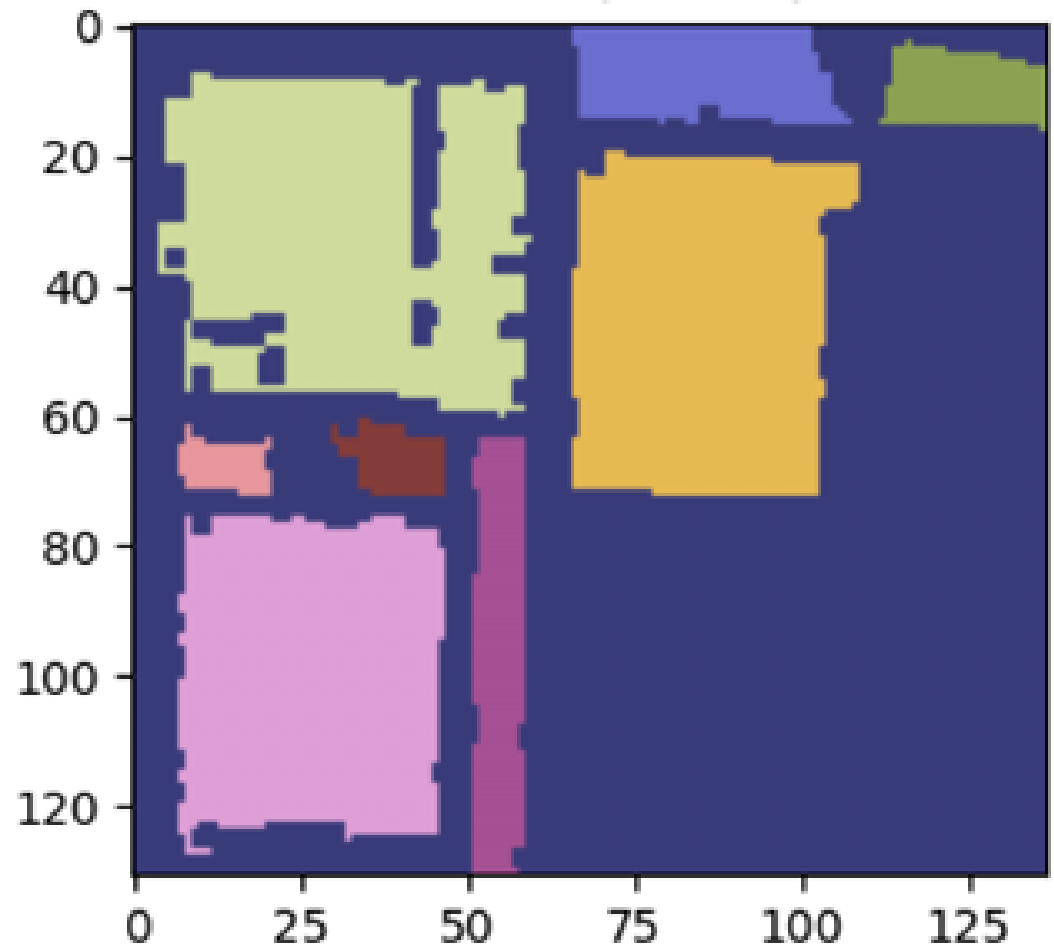


**Rooms**





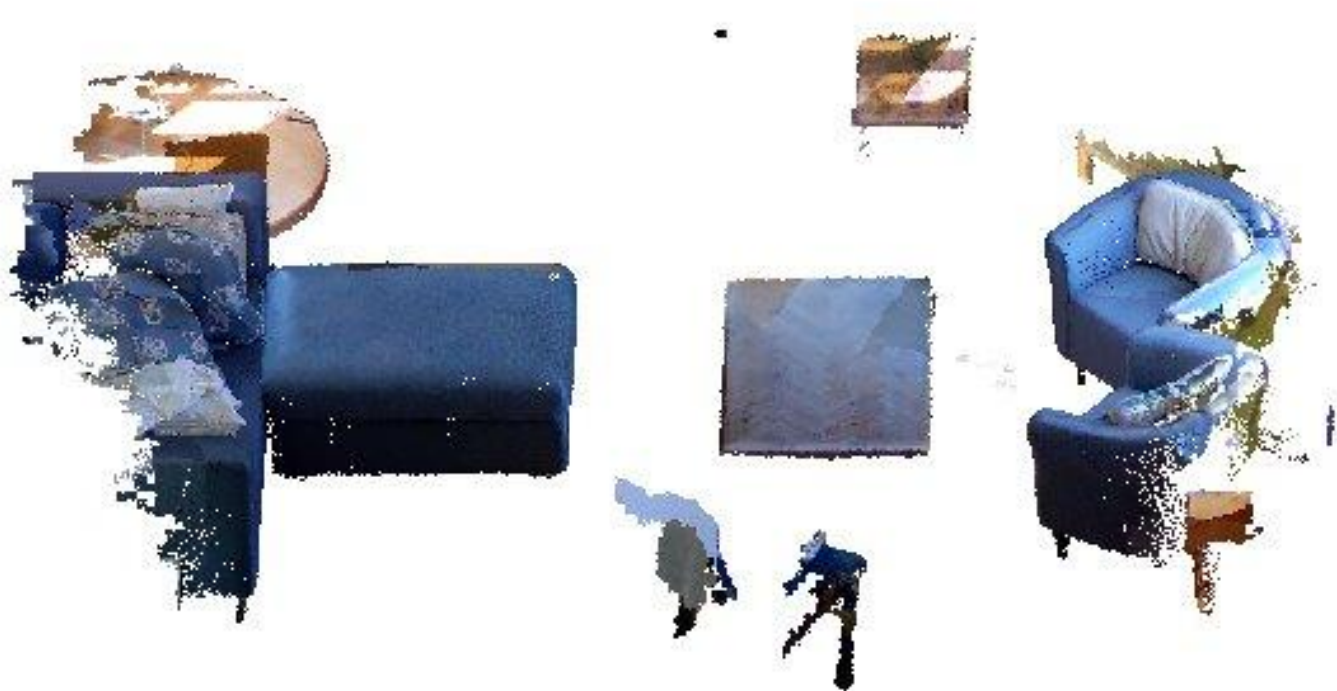
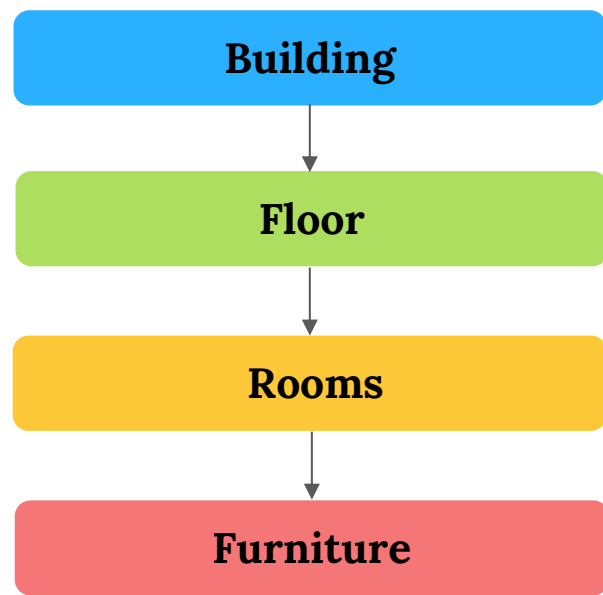
## Floor plan



## Room reconstruction





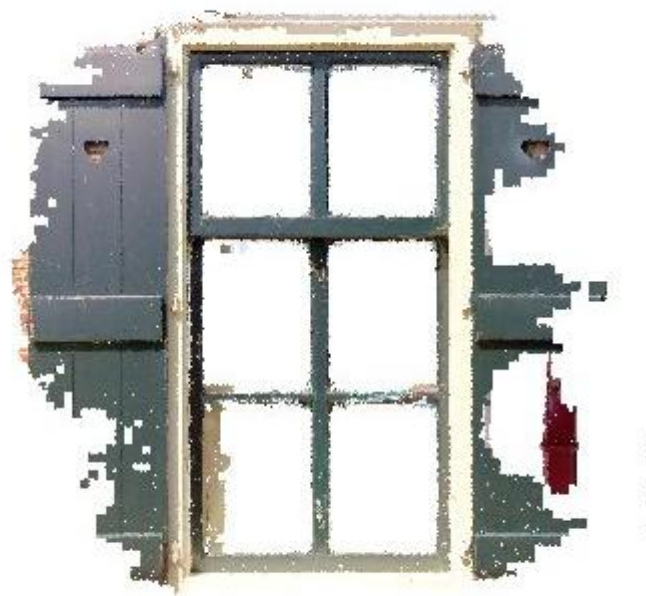


## Furniture reconstruction



## Clustering

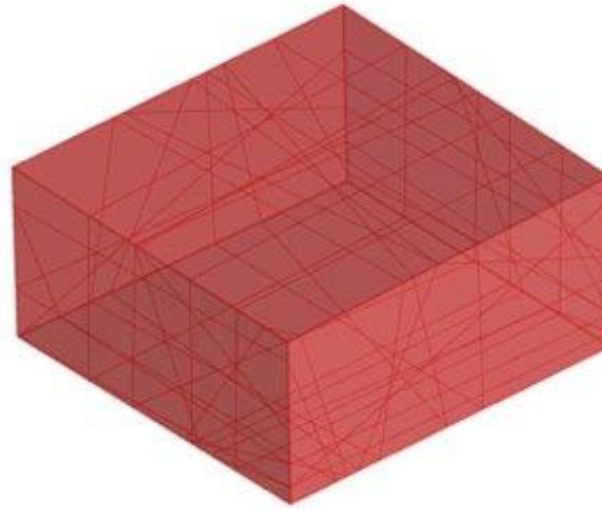
Window\_001



Window\_002

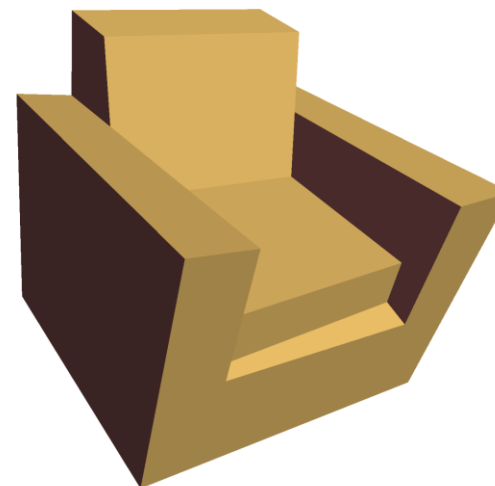


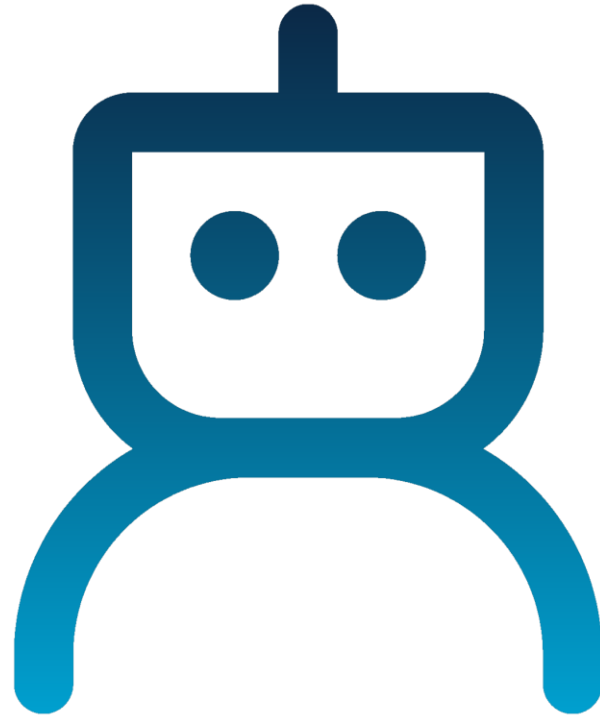
## PolyFit





## Surface reconstruction





# **Building**

*Database*

## **Floor**

*Defines Building Levels*

## **Rooms**

*Stores rooms data and links to floor*

## **Objects**

*Stores all 3D objects of a room*

## **Planes**

*Stores walls, floors and ceiling*

## **Images**

*Stores panoramas to rooms*

# Images

*Stores panoramas to rooms*

Room type = unknown

Get room panorama image

Ask LLM semantic meaning

LLM response: "This is a kitchen"

Room type = kitchen



**"What does it cost to repaint all the walls in the living room?"**

**1. Scope classification**

**2. Retrieve data from database**

**3. Use tool functions**

**4. Augment and generate answer**

**"It costs ... euros to paint all the walls in the living room"**



# Images

*Stores panoramas to rooms*

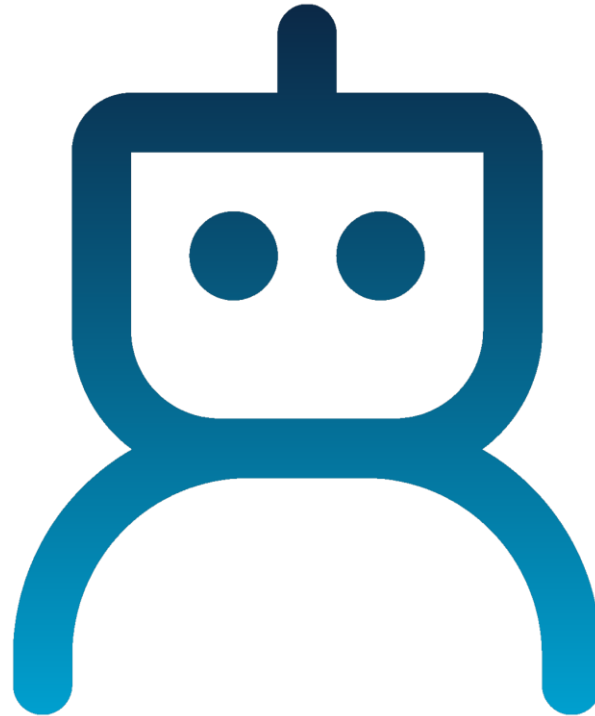
**Room type = unknown**

**Get room panorama image**

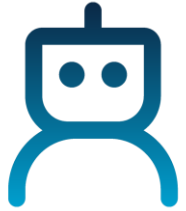
**Ask LLM semantic meaning**

**LLM response: "This is a kitchen"**

**Room type = kitchen**



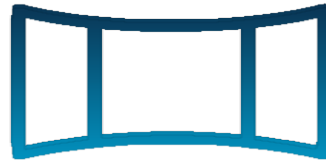
# User Interface



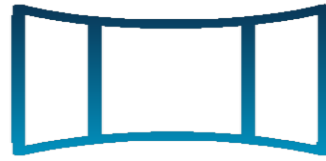
Chatbot



3D viewer



Panorama viewer



2D-to-3D workflow





# 2D-to-3D workflow





# 2D-to-3D workflow



# 2D-to-3D workflow



# 2D-to-3D workflow



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Deploy ⋮

# Spatial LLM

Bridging The Gap Between Natural Language and 3D Scans



- Overall structure works as intended.
- Application is not perfect.
- Performance vary between different environments.
- Improve product based on input different stakeholders.
- Hard to verify the accuracy of results from the chatbot.

Bridged some gaps between natural language and spatial reasoning.