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REAL ANALYSIS

THIRD WEEK

Exercise 1.9.8

Give examples to show that if $r = 1$ in the statement of the Ratio Test, anything may happen.

First consider the harmonic series, $\sum_{n=1}^{\infty} \frac{1}{n}$. The $\lim_{n \rightarrow \infty} \left| \frac{a_{n+1}}{a_n} \right| = 1$

$$\lim_{n \rightarrow \infty} \left| \frac{\frac{1}{n+1}}{\frac{1}{n}} \right| = \lim_{n \rightarrow \infty} \left| \frac{n}{n+1} \right| = 1$$

However, we know that the series $\sum_{n=1}^{\infty} \frac{1}{n}$ diverges.

Next consider $\sum_{n=1}^{\infty} \frac{(-1)^{n+1}}{n}$. Again $\lim_{n \rightarrow \infty} \left| \frac{a_{n+1}}{a_n} \right| = 1$

$$\begin{aligned} \lim_{n \rightarrow \infty} \left| \frac{\frac{(-1)^{n+2}}{n+1}}{\frac{(-1)^{n+1}}{n}} \right| &= \lim_{n \rightarrow \infty} \left| \frac{(-1)^{n+2}}{n+1} \cdot \frac{n}{(-1)^{n+1}} \right| \\ &= \lim_{n \rightarrow \infty} \left| \frac{-n}{n+1} \right| \\ &= 1 \end{aligned}$$

This series, $\sum_{n=1}^{\infty} \frac{(-1)^{n+1}}{n}$ converges since $\left| \sum_{k=m+1}^n \frac{(-1)^{k+1}}{k} \right| < \frac{1}{m}$ but not absolutely because $\sum_{n=1}^{\infty} \left| \frac{(-1)^n}{n} \right|$ goes to infinity.

Finally, consider the series $\sum_{n=1}^{\infty} \frac{1}{n^2}$. This too has $\lim_{n \rightarrow \infty} \left| \frac{a_{n+1}}{a_n} \right| = 1$.

$$\begin{aligned} \lim_{n \rightarrow \infty} \left| \frac{\frac{1}{(n+1)^2}}{\frac{1}{n^2}} \right| &= \lim_{n \rightarrow \infty} \left| \frac{1}{(n+1)^2} \cdot \frac{n^2}{1} \right| \\ &= \lim_{n \rightarrow \infty} \frac{n^2}{(n+1)^2} \\ &= 1 \end{aligned}$$

The series $\sum_{n=1}^{\infty} \frac{1}{n^2}$ is absolutely convergent because $\sum_{n=1}^{\infty} \left| \frac{1}{n^2} \right|$ converges.

Exercise 1.9.20

Give examples to show that if $r = 1$ in the statement of the Root Test, anything may happen.

Borrowing from the ideas in the last exercise, consider the series $\sum_{n=1}^{\infty} \frac{1}{n^2}$ and $\sum_{n=1}^{\infty} \frac{1}{n}$. Both have $r = 1$.

$$\limsup_{n \rightarrow \infty} \left| \frac{1}{n} \right|^{\frac{1}{n}} = 1$$

$$\limsup_{n \rightarrow \infty} \left| \frac{1}{n^2} \right|^{\frac{1}{n}} = 1$$

Anything may happen when $r = 1$

Exercise 1.9.26

Determine the radius of convergence of the following power series:

$$r = \limsup_{n \rightarrow \infty} |a_n|^{\frac{1}{n}}$$

Where the radius of convergence is $\frac{1}{r}$ if $r > 0$, ∞ if $r = 0$ and 0 if \limsup does not exist, ($r = \infty$).

1. $\sum_{n=1}^{\infty} \frac{z^n}{n!}$

$$\sum_{n=1}^{\infty} \frac{z^n}{n!} = \sum_{n=1}^{\infty} \frac{1}{n!} z^n$$

$$\lim_{n \rightarrow \infty} \left| \frac{1}{n!} \right|^{\frac{1}{n}} = 0$$

Radius of convergence is ∞

2. $\sum_{n=2}^{\infty} \frac{z^n}{\ln(n)}$

$$\sum_{n=1}^{\infty} \frac{z^n}{\ln(n)} = \sum_{n=2}^{\infty} \frac{1}{\ln(n)} z^n$$

$$\lim_{n \rightarrow \infty} \left| \frac{1}{\ln(n)} \right|^{\frac{1}{n}} = 1$$

Radius of convergence is 1.

3. $\sum_{n=1}^{\infty} \frac{n^n}{n!} z^n$

$$e^n = \sum_{n=1}^{\infty} \frac{n^n}{n!}$$

$$\lim_{n \rightarrow \infty} \left| \frac{n^n}{n!} \right|^{\frac{1}{n}} = e$$

Radius of convergence is $\frac{1}{e}$

Exercise 2.5.8

Prove that the scalar product is a positive definite symmetric bilinear form on \mathbb{E}^n .

Proof. The scalar product of vectors $\mathbf{v} = (v_1, v_2, v_3, \dots, v_n)$ and $\mathbf{w} = (w_1, w_2, w_3, \dots, w_n)$ is $\langle \mathbf{v}, \mathbf{w} \rangle = v_1 w_1 + v_2 w_2 + v_3 w_3 + \dots + v_n w_n$.

Let $V = \mathbb{E}^n$ be a vector space over $F = \mathbb{R}$. A bilinear form $\langle \cdot, \cdot \rangle$ on V is a map

$$\langle \cdot, \cdot \rangle : V \times V \rightarrow F$$

That satisfies linearity in both variables. That is, for all $\mathbf{v}, \mathbf{v}_1, \mathbf{v}_2, \mathbf{w}, \mathbf{w}_1, \mathbf{w}_2 \in V$ and all $\alpha \in F$

$$\begin{aligned}
 \langle \mathbf{v}_1 + \mathbf{v}_2, \mathbf{w} \rangle &= (v_{1_1} + v_{2_1})w_1 + (v_{1_2} + v_{2_2})w_2 + (v_{1_3} + v_{2_3})w_3 + \dots + (v_{1_n} + v_{2_n})w_n \\
 &= v_{1_1}w_1 + v_{2_1}w_1 + v_{1_2}w_2 + v_{2_2}w_2 + v_{1_3}w_3 + v_{2_3}w_3 + \dots + v_{1_n}w_n + v_{2_n}w_n \\
 &= (v_{1_1}w_1 + v_{1_2}w_2 + v_{1_3}w_3 + \dots + v_{1_n}w_n) + (v_{2_1}w_1 + v_{2_2}w_2 + v_{2_3}w_3 + \dots + v_{2_n}w_n) \\
 &= \langle \mathbf{v}_1, \mathbf{w} \rangle + \langle \mathbf{v}_2, \mathbf{w} \rangle
 \end{aligned}$$

$$\begin{aligned}
 \langle \alpha \mathbf{v}, \mathbf{w} \rangle &= \alpha v_1 w_1 + \alpha v_2 w_2 + \alpha v_3 w_3 + \dots + \alpha v_n w_n \\
 &= \alpha(v_1 w_1) + \alpha(v_2 w_2) + \alpha(v_3 w_3) + \dots + \alpha(v_n w_n) \\
 &= \alpha(v_1 w_1 + v_2 w_2 + v_3 w_3 + \dots + v_n w_n) \\
 &= \alpha \langle \mathbf{v}, \mathbf{w} \rangle
 \end{aligned}$$

$$\begin{aligned}
 \langle \mathbf{v}, \mathbf{w}_1 + \mathbf{w}_2 \rangle &= v_1(w_{1_1} + w_{2_1}) + v_2(w_{1_2} + w_{2_2}) + v_3(w_{1_3} + w_{2_3}) + \dots + v_n(w_{1_n} + w_{2_n}) \\
 &= v_1 w_{1_1} + v_1 w_{2_1} + v_2 w_{1_2} + v_2 w_{2_2} + v_3 w_{1_3} + v_3 w_{2_3} + \dots + v_n w_{1_n} + v_n w_{2_n} \\
 &= (v_1 w_{1_1} + v_2 w_{1_2} + v_3 w_{1_3} + \dots + v_n w_{1_n}) + (v_1 w_{2_1} + v_2 w_{2_2} + v_3 w_{2_3} + \dots + v_n w_{2_n}) \\
 &= \langle \mathbf{v}, \mathbf{w}_1 \rangle + \langle \mathbf{v}, \mathbf{w}_2 \rangle
 \end{aligned}$$

$$\begin{aligned}
 \langle \mathbf{v}, \alpha \mathbf{w} \rangle &= v_1 \alpha w_1 + v_2 \alpha w_2 + v_3 \alpha w_3 + \dots + v_n \alpha w_n \\
 &= \alpha(v_1 w_1) + \alpha(v_2 w_2) + \alpha(v_3 w_3) + \dots + \alpha(v_n w_n) \\
 &= \alpha(v_1 w_1 + v_2 w_2 + v_3 w_3 + \dots + v_n w_n) \\
 &= \alpha \langle \mathbf{v}, \mathbf{w} \rangle
 \end{aligned}$$

Regarding being positive definite, consider $\langle \mathbf{v}, \mathbf{v} \rangle$

$$\begin{aligned}
 \langle \mathbf{v}, \mathbf{v} \rangle &= v_1 v_1 + v_2 v_2 + v_3 v_3 + \dots + v_n v_n \\
 &= v_1^2 + v_2^2 + v_3^2 + \dots + v_n^2 \\
 &\geq 0
 \end{aligned}$$

Notice also, that $\langle \mathbf{v}, \mathbf{v} \rangle = 0$ if and only if $\mathbf{v} = 0$

□

Exercise 2.5.11

Prove the following properties of the norm if $\mathbf{v}, \mathbf{w} \in \mathbb{E}^n$

1. $\|\mathbf{v}\| \geq 0$

Proof. If $\mathbf{v} \in \mathbb{E}^n$ the norm is defined by

$$\begin{aligned}\|\mathbf{v}\| &= \sqrt{\langle \mathbf{v}, \mathbf{v} \rangle} \\ &= \sqrt{(v_1v_1 + v_2v_2 + v_3v_3 + \dots + v_nv_n)} \\ &= \sqrt{(v_1^2 + v_2^2 + v_3^2 + \dots + v_n^2)} \\ &= (v_1^2 + v_2^2 + v_3^2 + \dots + v_n^2)^{\frac{1}{2}} \\ &\geq 0\end{aligned}$$

□

2. $\|\mathbf{v}\| = 0$ if and only if $\mathbf{v} = 0$

From the definition of positive definite, $\langle \mathbf{v}, \mathbf{v} \rangle = 0$ if and only if $\mathbf{v} = 0$

Proof. " \Rightarrow " Let $\|\mathbf{v}\| = 0$. Then

$$\|\mathbf{v}\| = \sqrt{\langle \mathbf{v}, \mathbf{v} \rangle} = 0$$

$$\begin{aligned}\sqrt{\langle \mathbf{v}, \mathbf{v} \rangle} &= 0 \\ \sqrt{(v_1v_1 + v_2v_2 + v_3v_3 + \dots + v_nv_n)} &= 0 \\ (v_1^2 + v_2^2 + v_3^2 + \dots + v_n^2)^{\frac{1}{2}} &= 0 \\ (v_1^2 + v_2^2 + v_3^2 + \dots + v_n^2) &= 0\end{aligned}$$

So $\mathbf{v} = 0$

□

Proof. " \Leftarrow "

Let $\mathbf{v} = 0$

So $\langle \mathbf{v}, \mathbf{v} \rangle = 0$.

$$\begin{aligned}\|\mathbf{v}\| &= \sqrt{\langle \mathbf{v}, \mathbf{v} \rangle} \\ &= \sqrt{0} \\ &= 0\end{aligned}$$

□

3. $\|\alpha\mathbf{v}\| = |\alpha|\|\mathbf{v}\|, \alpha \in$

Proof.

$$\begin{aligned}
 \|\alpha \mathbf{v}\| &= \sqrt{\langle \alpha \mathbf{v}, \alpha \mathbf{v} \rangle} \\
 &= \sqrt{(\alpha^2 v_1^2 + \alpha^2 v_2^2 + \alpha^2 v_3^2 + \dots + \alpha^2 v_n^2)} \\
 &= \sqrt{\alpha^2 (v_1^2 + v_2^2 + v_3^2 + \dots + v_n^2)} \\
 &= |\alpha| \sqrt{(v_1^2 + v_2^2 + v_3^2 + \dots + v_n^2)} \\
 &= |\alpha| \sqrt{\langle \mathbf{v}, \mathbf{v} \rangle} \\
 &= |\alpha| \|\mathbf{v}\|
 \end{aligned}$$

□

4. $\|\mathbf{v} + \mathbf{w}\| \leq \|\mathbf{v}\| + \|\mathbf{w}\|$

Proof. First recall the Pythagorean theorem, $a^2 + b^2 = c^2$ and Cauchy-Schwarz Inequality, let $\mathbf{v}, \mathbf{w} \in \mathbb{E}^n$, then $|\langle \mathbf{v}, \mathbf{w} \rangle| \leq \|\mathbf{v}\| \|\mathbf{w}\|$

$$\begin{aligned}
 \|\mathbf{v} + \mathbf{w}\|^2 &= \langle \mathbf{v} + \mathbf{w}, \mathbf{v} + \mathbf{w} \rangle \\
 &= (v_1 + w_1)^2 + (v_2 + w_2)^2 + \dots + (v_n + w_n)^2 \\
 &= (v_1^2 + v_2^2 + \dots + v_n^2) + (w_1^2 + w_2^2 + \dots + w_n^2) + (v_1 w_1 + \dots + v_n w_n) + (w_1 v_1 + \dots + w_n v_n) \\
 &= \langle \mathbf{v}, \mathbf{v} \rangle + \langle \mathbf{v}, \mathbf{w} \rangle + \langle \mathbf{w}, \mathbf{v} \rangle + \langle \mathbf{w}, \mathbf{w} \rangle \\
 &\leq \|\mathbf{v}\|^2 + 2|\langle \mathbf{v}, \mathbf{w} \rangle| + \|\mathbf{w}\|^2 \\
 &\leq \|\mathbf{v}\|^2 + 2\|\mathbf{v}\| \|\mathbf{w}\| + \|\mathbf{w}\|^2 \\
 &= (\|\mathbf{v}\| + \|\mathbf{w}\|)^2
 \end{aligned}$$

□

5. $\|\mathbf{v} + \mathbf{w}\|^2 + \|\mathbf{v} - \mathbf{w}\|^2 = 2(\|\mathbf{v}\|^2 + \|\mathbf{w}\|^2)$

Proof.

$$\begin{aligned}
 \|\mathbf{v} + \mathbf{w}\|^2 + \|\mathbf{v} - \mathbf{w}\|^2 &= \langle \mathbf{v} + \mathbf{w}, \mathbf{v} + \mathbf{w} \rangle + \langle \mathbf{v} - \mathbf{w}, \mathbf{v} - \mathbf{w} \rangle \\
 &= (v_1 + w_1)^2 + \dots + (v_n + w_n)^2 + (v_1 - w_1)^2 + \dots + (v_n - w_n)^2 \\
 &= (v_1^2 + 2v_1 w_1 + w_1^2 + \dots + v_n^2 + 2v_n w_n + w_n^2) + (v_1^2 - 2v_1 w_1 + w_1^2 + \dots + v_n^2 - 2v_n w_n + w_n^2) \\
 &= (2v_1^2 + \dots + 2v_n^2) + (2w_1^2 + \dots + 2w_n^2) \\
 &= 2(v_1^2 + \dots + v_n^2) + 2(w_1^2 + \dots + w_n^2) \\
 &= 2(\langle \mathbf{v}, \mathbf{v} \rangle + \langle \mathbf{w}, \mathbf{w} \rangle) \\
 &= 2(\|\mathbf{v}\|^2 + \|\mathbf{w}\|^2)
 \end{aligned}$$

□

2.5.20

1. Show that $\|\mathbf{v} \times \mathbf{w}\| = \|\mathbf{v}\|\|\mathbf{w}\| \sin \theta$, where θ is the angle between \mathbf{v} and \mathbf{w} .

Proof. First right out the cross product of $\mathbf{v} \times \mathbf{w}$

$$\mathbf{v} \times \mathbf{w} = (v_2w_3 - v_3w_2, v_3w_1 - v_1w_3, v_1w_2 - v_2w_1) \quad (1)$$

$$\begin{aligned} \|\mathbf{v} \times \mathbf{w}\|^2 &= (v_2w_3 - v_3w_2)^2 + (v_3w_1 - v_1w_3)^2 + (v_1w_2 - v_2w_1)^2 \\ &= v_2^2w_3^2 - 2v_2v_3w_2w_3 + v_3^2w_2^2 \\ &\quad + v_3^2w_1^2 - 2v_1v_3w_1w_3 + v_1^2w_3^2 \\ &\quad + v_1^2w_2^2 - 2v_1v_2w_1w_2 + v_2^2w_1^2 \end{aligned}$$

So

$$\begin{aligned} \|\mathbf{v} \times \mathbf{w}\|^2 &= v_1^2(w_2^2 + w_3^2) + v_2^2(w_1^2 + w_3^2) + v_3^2(w_1^2 + w_2^2) \\ &\quad - 2(v_2v_3w_2w_3 + v_1v_3w_1w_3 + v_1v_2w_1w_2) \end{aligned} \quad (2)$$

Recall that $\cos \theta = \frac{\langle \mathbf{v}, \mathbf{w} \rangle}{\|\mathbf{v}\|\|\mathbf{w}\|}$ implies $\langle \mathbf{v}, \mathbf{w} \rangle = \cos \theta \|\mathbf{v}\|\|\mathbf{w}\|$. Therefore

$$\cos^2 \theta \|\mathbf{v}\|^2 \|\mathbf{w}\|^2 = (\langle \mathbf{v}, \mathbf{w} \rangle)^2 \quad (3)$$

$$(\langle \mathbf{v}, \mathbf{w} \rangle)^2 = (v_1w_1 + v_2w_2 + v_3w_3)^2 \quad (4)$$

$$\begin{aligned} (v_1w_1 + v_2w_2 + v_3w_3)^2 &= (v_1w_1 + v_2w_2 + v_3w_3)(v_1w_1 + v_2w_2 + v_3w_3) \\ &= v_1^2w_1^2 + v_1v_2w_1w_2 + v_1v_3w_1w_3 \\ &\quad + v_1^2w_1^2 + v_1v_2w_1w_2 + v_2v_3w_2w_3 \\ &\quad + v_3^2w_3^2 + v_1v_3w_1w_3 + v_2v_3w_2w_3 \end{aligned}$$

So applying (3) with our result from (4),

$$\begin{aligned} \cos^2 \theta \|\mathbf{v}\|^2 \|\mathbf{w}\|^2 &= v_1^2w_1^2 + v_1^2w_1^2 + v_3^2w_3^2 + \\ &\quad 2(v_1v_2w_1w_2 + v_1v_3w_1w_3 + v_2v_3w_2w_3) \end{aligned} \quad (5)$$

Combining (4) with (2), $\|\mathbf{v} \times \mathbf{w}\|^2 + \cos^2 \theta \|\mathbf{v}\|^2 \|\mathbf{w}\|^2$ we get

$$\begin{aligned}
 & v_1^2 w_1^2 + v_1^2 w_2^2 + v_3^2 w_3^2 + 2(v_1 v_2 w_1 w_2 + v_1 v_3 w_1 w_3 + v_2 v_3 w_2 w_3) \\
 & + v_1^2 (w_2^2 + w_3^2) + v_2^2 (w_1^2 + w_3^2) + v_3^2 (w_1^2 + w_2^2) \\
 & - 2(v_2 v_3 w_2 w_3 + v_1 v_3 w_1 w_3 + v_1 v_2 w_1 w_2) \\
 & = v_1^2 w_1^2 + v_1^2 w_2^2 + v_3^2 w_3^2 \\
 & + v_1^2 (w_2^2 + w_3^2) + v_2^2 (w_1^2 + w_3^2) + v_3^2 (w_1^2 + w_2^2) \\
 & = v_1^2 (w_1^2 + w_2^2 + w_3^2) + v_2^2 (w_1^2 + w_2^2 + w_3^2) + v_3^2 (w_1^2 + w_2^2 + w_3^2) \\
 & = (w_1^2 + w_2^2 + w_3^2)(v_1^2 + v_2^2 + v_3^2)
 \end{aligned}$$

So from this we can conclude

$$\|\mathbf{v} \times \mathbf{w}\|^2 + \cos^2 \theta \|\mathbf{v}\|^2 \|\mathbf{w}\|^2 = \|\mathbf{w}\|^2 \|\mathbf{v}\|^2 \quad (6)$$

The result of (6) implies that $\|\mathbf{v} \times \mathbf{w}\|^2 = \|\mathbf{v}\|^2 \|\mathbf{w}\|^2 - \cos^2 \theta \|\mathbf{v}\|^2 \|\mathbf{w}\|^2$.

So our last steps

$$\begin{aligned}
 \|\mathbf{v} \times \mathbf{w}\|^2 &= \|\mathbf{v}\|^2 \|\mathbf{w}\|^2 - \cos^2 \theta \|\mathbf{v}\|^2 \|\mathbf{w}\|^2 \\
 &= \|\mathbf{v}\|^2 \|\mathbf{w}\|^2 (1 - \cos^2 \theta) \\
 &= \|\mathbf{v}\|^2 \|\mathbf{w}\|^2 (\sin^2 \theta)
 \end{aligned}$$

We can take the square root to reach our conclusion.

$$\|\mathbf{v} \times \mathbf{w}\| = \|\mathbf{v}\| \|\mathbf{w}\| \sin \theta$$

□

Exercise 2.5.26

Let $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_{n-1}$ be linearly independent vectors in \mathbb{E}^n . Let \mathbf{p}_0 be a point of \mathbb{R}^n . Let \mathbf{H} be the hyperplane plane through \mathbf{p}_0 spanned by $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_{n-1}$. If \mathbf{p} is any point in \mathbb{R}^n , show that the distance from \mathbf{p} to \mathbf{H} , that is, $\inf\{\|\mathbf{p} - \mathbf{q}\| \mid \mathbf{q} \in \mathbf{H}\}$, is given by the length of the vector $\text{proj}_{\mathbf{v}}(\mathbf{p} - \mathbf{p}_0)$ where \mathbf{v} is the vector obtained in Theorem 2.5.21. Specialize this to obtain formulas for the distance from a point to a line in \mathbb{R}^2 and from a point to a plane in \mathbb{R}^3 .

We are given that \mathbf{v} is orthogonal to $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_{n-1}$ and that \mathbf{H} is the hyperplane through \mathbf{p}_0 spanned by $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_{n-1}$.

Since \mathbf{p} and \mathbf{p}_0 are points, we can think of $\text{proj}_{\mathbf{v}}(\mathbf{p} - \mathbf{p}_0)$ as a projection of the vector $(\mathbf{p} - \mathbf{p}_0)$ onto \mathbf{v} where $(\mathbf{p} - \mathbf{p}_0)$ is the hypotenuse of a right angle formed by $\text{proj}_{\mathbf{v}}(\mathbf{p} - \mathbf{p}_0)$. Which makes the $\text{proj}_{\mathbf{v}}(\mathbf{p} - \mathbf{p}_0)$ the line adjacent to the angle formed by $\text{proj}_{\mathbf{v}}(\mathbf{p} - \mathbf{p}_0)$ which is

parallel with \mathbf{v} which is orthogonal to \mathbf{H} . By the Pythagorean theorem, this must be the shortest distance from \mathbf{p} to \mathbf{H} , because if you took any other distance to the plane, it wouldn't form right angle with the plane and result in a greater distance.

Specializing this for \mathbb{R}^2 and \mathbb{R}^3 . We consider the $\text{proj}_{\mathbf{v}}(\mathbf{p} - \mathbf{p}_0)$. Let the vector $\mathbf{f} = (\mathbf{p} - \mathbf{p}_0)$. We only care about the length of the line so we should take it's norm, which is given

$$\|\text{proj}_{\mathbf{v}}(\mathbf{f})\| = \frac{|\langle \mathbf{f}, \mathbf{v} \rangle|}{\|\mathbf{v}\|}$$

For \mathbb{R}^2 , define vectors \mathbf{v}_1 and \mathbf{v} . Let \mathbf{v} be non zero orthogonal to \mathbf{v}_1 . This means the pair $\{\mathbf{v}_1, \mathbf{v}\}$ is a basis for \mathbb{R}^2 . Let \mathbf{H} be the plane through \mathbf{p}_0 be a point spanned by \mathbf{v}_1 , and contain points (p_{0_1}, p_{0_2}) . Let $\mathbf{p} = (p_1, p_2)$ to be any point in \mathbb{R}^2 . by Let d be the distance we are trying to find.

$$\begin{aligned} d &= \frac{|\langle \mathbf{f}, \mathbf{v} \rangle|}{\|\mathbf{v}\|} \\ &= \frac{|(f_1 v_1 + f_2 v_2)|}{\|\mathbf{v}\|} \\ &= \frac{|(p_1 - p_{0_1})v_1 + (p_2 - p_{0_2})v_2|}{\|\mathbf{v}\|} \\ &= \frac{|(p_1 - p_{0_1})v_1 + (p_2 - p_{0_2})v_2|}{\sqrt{v_1^2 + v_2^2}} \end{aligned}$$

For \mathbb{R}^3 , we have a similar result. define vectors $\mathbf{v}_1, \mathbf{v}_2$ to be linearly independent. Let \mathbf{v} be the determinant of $\mathbf{v}_1, \mathbf{v}_2$. Resulting in $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}\}$ as a basis \mathbb{R}^3 Let \mathbf{H} be the plane through the point \mathbf{p}_0 spanned by $\mathbf{v}_1, \mathbf{v}_2$, and contain points $(p_{0_1}, p_{0_2}, p_{0_3})$. Let $\mathbf{p} = (p_1, p_2, p_3)$ to be any point in \mathbb{R}^3 . by Let d be the distance we are trying to find.

$$\begin{aligned} d &= \frac{|\langle \mathbf{f}, \mathbf{v} \rangle|}{\|\mathbf{v}\|} \\ &= \frac{|(f_1 v_1 + f_2 v_2 + f_3 v_3)|}{\|\mathbf{v}\|} \\ &= \frac{|(p_1 - p_{0_1})v_1 + (p_2 - p_{0_2})v_2 + (p_3 - p_{0_3})v_3|}{\|\mathbf{v}\|} \\ &= \frac{|(p_1 - p_{0_1})v_1 + (p_2 - p_{0_2})v_2 + (p_3 - p_{0_3})v_3|}{\sqrt{v_1^2 + v_2^2 + v_3^2}} \end{aligned}$$

Exercise 2.5.30

Consider the vectors $\mathbf{v}_1 = (1, 1, -1, 0)$, $\mathbf{v}_2 = (1, 0, 0, -1)$ and $\mathbf{v}_3 = (0, 1, 1, 1)$ in \mathbb{E}^4 .

1. Use the Gram-Schmidt orthogonalization process on these three vectors to produce a set of three mutually orthogonal vectors that span the same subspace.

Let $\mathbf{v}_1 = \tilde{\mathbf{v}}_1$

For $\tilde{\mathbf{v}}_2 = \mathbf{v}_2 - \text{proj}_{\tilde{\mathbf{v}}_1}(\mathbf{v}_2)$

$$\text{proj}_{\tilde{\mathbf{v}}_1}(\mathbf{v}_2) = \frac{\langle \mathbf{v}_2, \tilde{\mathbf{v}}_1 \rangle}{\|\tilde{\mathbf{v}}_1\|} \frac{\tilde{\mathbf{v}}_1}{\|\tilde{\mathbf{v}}_1\|}$$

$$\begin{aligned} \langle \mathbf{v}_2, \tilde{\mathbf{v}}_1 \rangle &= (1)(1) + (0)(1) + (0)(-1) + (-1)(0) \\ &= 1 \\ \|\tilde{\mathbf{v}}_1\| &= \sqrt{1^2 + 1^2 + (-1)^2 + 0^2} \\ &= \sqrt{3} \end{aligned}$$

$$\begin{aligned} \text{proj}_{\tilde{\mathbf{v}}_1}(\mathbf{v}_2) &= \frac{1}{\sqrt{3}} \frac{\tilde{\mathbf{v}}_1}{\sqrt{3}} \\ &= \frac{1}{3} \tilde{\mathbf{v}}_1 \\ &= \frac{1}{3} \begin{bmatrix} 1 & 1 & -1 & 0 \end{bmatrix} \\ &= \begin{bmatrix} \frac{1}{3} & \frac{1}{3} & -\frac{1}{3} & 0 \end{bmatrix} \end{aligned}$$

$$\begin{aligned} \tilde{\mathbf{v}}_2 &= \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix} - \begin{bmatrix} \frac{1}{3} \\ \frac{1}{3} \\ -\frac{1}{3} \\ 0 \end{bmatrix} \\ &= \begin{bmatrix} \frac{2}{3} & -\frac{1}{3} & \frac{1}{3} & 1 \end{bmatrix} \end{aligned}$$

For $\tilde{\mathbf{v}}_3 = \mathbf{v}_3 - \text{proj}_{\tilde{\mathbf{v}}_1}(\mathbf{v}_3) - \text{proj}_{\tilde{\mathbf{v}}_2}(\mathbf{v}_3)$

$$\text{proj}_{\tilde{\mathbf{v}}_1}(\mathbf{v}_3) = \frac{\langle \mathbf{v}_3, \tilde{\mathbf{v}}_1 \rangle}{\|\tilde{\mathbf{v}}_1\|} \frac{\tilde{\mathbf{v}}_1}{\|\tilde{\mathbf{v}}_1\|}$$

$$\begin{aligned}
\langle \mathbf{v}_3, \tilde{\mathbf{v}}_1 \rangle &= (0)(1) + (1)(1) + (1)(-1) + (1)(0) \\
&= 1 \\
\|\tilde{\mathbf{v}}_1\| &= \sqrt{3}
\end{aligned}$$

$$\begin{aligned}
\text{proj}_{\tilde{\mathbf{v}}_1}(\mathbf{v}_3) &= \frac{1}{\sqrt{3}} \frac{\tilde{\mathbf{v}}_1}{\sqrt{3}} \\
&= \frac{1}{3} \tilde{\mathbf{v}}_1 \\
&= \frac{1}{3} \begin{bmatrix} 1 & 1 & -1 & 0 \end{bmatrix} \\
&= \begin{bmatrix} \frac{1}{3} & \frac{1}{3} & -\frac{1}{3} & 0 \end{bmatrix}
\end{aligned}$$

$$\text{proj}_{\tilde{\mathbf{v}}_2}(\mathbf{v}_3) = \frac{\langle \mathbf{v}_3, \tilde{\mathbf{v}}_2 \rangle}{\|\tilde{\mathbf{v}}_2\|} \frac{\tilde{\mathbf{v}}_2}{\|\tilde{\mathbf{v}}_2\|}$$

$$\begin{aligned}
\langle \mathbf{v}_3, \tilde{\mathbf{v}}_2 \rangle &= (0)\left(\frac{2}{3}\right) + (1)\left(-\frac{1}{3}\right) + (1)\left(\frac{1}{3}\right) + (1)(1) \\
&= 1 \\
\|\tilde{\mathbf{v}}_2\| &= \sqrt{\frac{2^2}{3} + -\frac{1^2}{3} + \frac{1^2}{3} + 1^2} \\
&= \sqrt{\frac{5}{3}}
\end{aligned}$$

$$\begin{aligned}
\text{proj}_{\tilde{\mathbf{v}}_2}(\mathbf{v}_3) &= \frac{1}{\sqrt{\frac{5}{3}}} \frac{\tilde{\mathbf{v}}_2}{\sqrt{\frac{5}{3}}} \\
&= \frac{3}{5} \tilde{\mathbf{v}}_2 \\
&= \frac{3}{5} \begin{bmatrix} \frac{2}{3} & -\frac{1}{3} & \frac{1}{3} & 1 \end{bmatrix} \\
&= \begin{bmatrix} \frac{6}{15} & -\frac{3}{15} & \frac{3}{15} & \frac{3}{5} \end{bmatrix}
\end{aligned}$$

$$\begin{aligned}
\tilde{\mathbf{v}}_3 &= \begin{bmatrix} 0 \\ 1 \\ 1 \\ 1 \end{bmatrix} - \begin{bmatrix} \frac{1}{3} \\ \frac{1}{3} \\ -\frac{1}{3} \\ 0 \end{bmatrix} - \begin{bmatrix} \frac{6}{15} \\ -\frac{3}{15} \\ \frac{3}{15} \\ \frac{9}{15} \end{bmatrix} \\
&= \begin{bmatrix} -\frac{11}{15} & \frac{13}{15} & \frac{17}{15} & -\frac{6}{15} \end{bmatrix}
\end{aligned}$$

2. Extend the set of three vectors produced in part 1 to a mutually orthogonal basis for

Consider the matrix comprised of $\tilde{\mathbf{v}}_1, \tilde{\mathbf{v}}_2, \tilde{\mathbf{v}}_3$ and vectors $\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3, \mathbf{e}_4 \in \mathbb{E}^4$ where 1 is in the the j th term and 0 otherwise.

$$\begin{bmatrix} \mathbf{e}_1 & \mathbf{e}_2 & \mathbf{e}_3 & \mathbf{e}_4 \\ 1 & 1 & -1 & 0 \\ \frac{2}{3} & -\frac{1}{3} & \frac{1}{3} & 1 \\ -\frac{11}{15} & \frac{13}{15} & \frac{17}{15} & -\frac{6}{15} \end{bmatrix} \quad (7)$$

The vector that will complete the basis can be created by taking the determinant of the matrix (7).

Step 1

$$\begin{aligned} \mathbf{e}_1 & \begin{bmatrix} 1 & -1 & 0 \\ -\frac{1}{3} & \frac{1}{3} & 1 \\ \frac{13}{15} & \frac{17}{15} & -\frac{6}{15} \end{bmatrix} - \mathbf{e}_2 \begin{bmatrix} 1 & -1 & 0 \\ \frac{2}{3} & \frac{1}{3} & 1 \\ -\frac{11}{15} & \frac{17}{15} & -\frac{6}{15} \end{bmatrix} \\ & + \mathbf{e}_3 \begin{bmatrix} 1 & 1 & 0 \\ \frac{2}{3} & -\frac{1}{3} & 1 \\ -\frac{11}{15} & \frac{13}{15} & -\frac{6}{15} \end{bmatrix} - \mathbf{e}_4 \begin{bmatrix} 1 & 1 & -1 \\ \frac{2}{3} & -\frac{1}{3} & \frac{1}{3} \\ -\frac{11}{15} & \frac{13}{15} & \frac{17}{15} \end{bmatrix} \end{aligned}$$

Then the next step...

$$\begin{aligned} & \mathbf{e}_1 \left(1 \begin{bmatrix} \frac{1}{3} & 1 \\ \frac{17}{15} & -\frac{6}{15} \end{bmatrix} - -1 \begin{bmatrix} -\frac{1}{3} & 1 \\ \frac{13}{15} & -\frac{6}{15} \end{bmatrix} - \right. \\ & \mathbf{e}_2 \left(1 \begin{bmatrix} \frac{1}{3} & 1 \\ \frac{17}{15} & -\frac{6}{15} \end{bmatrix} - -1 \begin{bmatrix} \frac{2}{3} & 1 \\ -\frac{11}{15} & -\frac{6}{15} \end{bmatrix} + \right. \\ & \mathbf{e}_3 \left(1 \begin{bmatrix} -\frac{1}{3} & 1 \\ \frac{13}{15} & -\frac{6}{15} \end{bmatrix} - 1 \begin{bmatrix} \frac{2}{3} & 1 \\ -\frac{11}{15} & -\frac{6}{15} \end{bmatrix} - \right. \\ & \left. \left. \mathbf{e}_4 \left(1 \begin{bmatrix} -\frac{1}{3} & \frac{1}{3} \\ \frac{13}{15} & \frac{17}{15} \end{bmatrix} - 1 \begin{bmatrix} \frac{2}{3} & \frac{1}{3} \\ -\frac{11}{15} & \frac{17}{15} \end{bmatrix} + -1 \begin{bmatrix} \frac{2}{3} & -\frac{1}{3} \\ -\frac{11}{15} & \frac{13}{15} \end{bmatrix} \right) \right) \end{aligned}$$

We can begin to simplify...

$$\begin{aligned} & \mathbf{e}_1 \left(1 \left(-\frac{6}{45} - \frac{17}{15} \right) + 1 \left(\frac{6}{45} - \frac{13}{15} \right) \right) - \\ & \mathbf{e}_2 \left(1 \left(-\frac{6}{45} - \frac{17}{15} \right) + 1 \left(-\frac{12}{45} + \frac{11}{15} \right) \right) + \\ & \mathbf{e}_3 \left(1 \left(\frac{6}{45} - \frac{17}{15} \right) - 1 \left(-\frac{12}{45} + \frac{11}{15} \right) \right) - \\ & \mathbf{e}_4 \left(1 \left(-\frac{17}{45} - \frac{13}{45} \right) - 1 \left(\frac{34}{45} + \frac{11}{45} \right) - 1 \left(\frac{26}{45} - \frac{11}{45} \right) \right) \end{aligned}$$

And further

$$\mathbf{e}_1(-2) - \mathbf{e}_2(-\frac{2}{5}) + \mathbf{e}_3(-\frac{6}{5}) - \mathbf{e}_4(-2)$$

We now compute our new vector to be $(-2, \frac{2}{5}, -\frac{6}{5}, 2)$ and define it as \mathbf{v} . Which gives us the basis $\{\tilde{\mathbf{v}}_1, \tilde{\mathbf{v}}_2, \tilde{\mathbf{v}}_3, \mathbf{v}\}$ over \mathbb{E}^4 .

In order to make this a mutually orthogonal basis for \mathbb{E}^4 , apply the Gram-Schmidt orthogonalization process once again.

Let $\tilde{\mathbf{v}} = \mathbf{v}$

For $\tilde{\mathbf{v}}_1 = \tilde{\mathbf{v}}_1 - \text{proj}_{\tilde{\mathbf{v}}}(\tilde{\mathbf{v}}_1)$

$$\text{proj}_{\tilde{\mathbf{v}}}(\tilde{\mathbf{v}}_1) = \frac{\langle \mathbf{v}_1, \tilde{\mathbf{v}} \rangle}{\|\tilde{\mathbf{v}}\|} \frac{\tilde{\mathbf{v}}}{\|\tilde{\mathbf{v}}\|}$$

$$\begin{aligned} \langle \tilde{\mathbf{v}}_1, \tilde{\mathbf{v}} \rangle &= (1)(-2) + (1)(-\frac{2}{5}) + (-1)(-\frac{6}{5}) + (0)(2) \\ &= -\frac{6}{5} \end{aligned}$$

$$\|\tilde{\mathbf{v}}\| = \sqrt{-2^2 + \frac{2^2}{5} + -\frac{6^2}{5} + 2^2} = \sqrt{\frac{48}{5}}$$

$$\begin{aligned} \text{proj}_{\tilde{\mathbf{v}}}(\tilde{\mathbf{v}}_1) &= -\frac{\frac{6}{5}}{\sqrt{\frac{48}{5}}} \frac{\tilde{\mathbf{v}}_1}{\sqrt{\frac{48}{5}}} \\ &= -\frac{1}{8} \tilde{\mathbf{v}} \\ &= -\frac{1}{8} \begin{bmatrix} -2 & \frac{2}{5} & -\frac{6}{5} & 2 \end{bmatrix} \\ &= \begin{bmatrix} \frac{2}{8} & -\frac{2}{40} & \frac{6}{40} & -\frac{2}{8} \end{bmatrix} \end{aligned}$$

$$\tilde{\mathbf{v}}_1 = \begin{bmatrix} 1 \\ 1 \\ -1 \\ 0 \end{bmatrix} - \begin{bmatrix} \frac{2}{8} \\ -\frac{2}{40} \\ \frac{6}{40} \\ -\frac{2}{8} \end{bmatrix} = \begin{bmatrix} \frac{6}{8} & \frac{42}{40} & -\frac{46}{40} & \frac{2}{8} \end{bmatrix}$$