K. G. C. E. Karjat - Raigad

Experiment 5

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Aim: Implement fuzzy controller for washing mashine System using python API. Theory' 1] What are fuzzy controller? -) - fuzzy controller are a type of control system used in engineering and various application to manage complex and uncertain situations. They are part of the broader field of fuzzy logic. Which is a mathe mulical framework designed to model and handle uncertainty in decision-making process. - Euzzy controller are particularly useful when dealing with systems that have impression or ambigures input-output retationships or when diffuse to model the system using tradition mathematical methods - They have been applied in various field in various field, including engineering, robotics, control systems and decision making process where human expensis intuition play a significant vole 2) Explaim different stages in fuzzy control system? 10 fuzification: - This Stage Involves converting emisp numerical inputs Click Gensor reading into fuzzy linguistic variables linguistic terms are used to describe the inputs characteristics, such as "low", "midium", "high" - fuzzyfication is achived by mapping the crisp input values to membership degrees in the liquish terms using membership Rundians

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CENOCENOCENGCENOC	Estant rule base a Contain a set of If-then rules that express the control strategy. Each new consist of a combination of Input Conditions.
	the fuzzy rule based on the furified input values.  The determines the degree to which each rule is statished by current input values
	3 Defuzzification:  The aggregated fuzzy outputs need to be convented back into crisps control action that can be applied to the system
	To this Stage the output of the individual rules or combined to form on overall luzzy output
	3] what are mandani type fuzzy controller?  The mandane type fuzzy controller is one of the most common and well-known type of fazzy controller.  The was introduced by floration mandan; in we igtor and has bee widely used in various applications for its simplicity and effectiveness in dedling with uncertain and imprecision information.  The mandani fuzzy controller follow a specific structure and methodology for moking control decision based on fuzzy logic.
	- mandani type of fuzzy controllers one particularly sib

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43 with arbitary example explain creating mandans hary controller > Stept: Define ligusinis variable and membership functions Il Tempreture (input): of inquistic terms: law, mediusm, high a membership hindrens: hidragular or maposial membership 2) Humidility annul ; chiquistic teams: low, medium, high emembership Rinchions: Triangular or trapagal minembers his Steps: Define Rizzy rules ITF temprehave is low and humidity is low then low if mali um Pan speed medium, if high fan bredium 23TF temprehere is making and humidity is law them Run speed medium if medium lanspeed high 31 If temprehere is high and humidity is low the kinspeed 15 medium, if medium fan Speed high step3: hozzy fication: if from temp is 28° c & homidit lylis tol. o temp: medium (0.0), o humiding: high (01) Step4: Intelevence engine . Temprealere march degre : 0:6 (medium) othernidity match degree - 0.7 (high) · Degree of activation - rain (0.6,0.1) =0.6 Stept: pagregation -> polivetion of 0.6 has adjustion a the aggregated output for "High" for spee be more (oco. 1 04 into crisp value for fun speed using defuzzification. Steps - output scaling and activation Scale the crisp control output to appropriate range for the lung control mechanism

code.
pip install simpful
1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
The state of the s
fuzzy sees and buzzy rules and to Perform Puzzy interence
from simplus import *
import function labject from simpful library
FS - Puzzy 50 FS = Fuzzy System ()
creare a Ruzzy system object
Tisfung Selllunction = Triungular Mf (as o, bso, c= (a), lerm= sm
1172 = 1224 Sel Gurdion - manquer Mila Creation 100 min
I 3 : Fuzzyser (function= Triungular Mf (a-50, b=100, c=100), term="large")
# Deline Ruzzy set and linguistic variables
# perrameters
1 a - universe of discourse coordinate of the leftmost vertex
to, c - universe of discouses coordinate of the upper, rightmatical
Herm: omna remest the linguishing term to be
associated to fuzzy sel
Fs. add linguistic variable ('dist,' Linguistic Variable [7], 7,73
content : "amount dirt", universe of discours [0,100]
F5 add, linguistic variable ("grease", linguistic variable [], [], []
concept = "amount grase", universe of discource ( 0.100
# Adds a new linguistic variables to the first system
amount diff and grease
HUNIVERSE OF discourse: A 1854 OF aleman
min and more of the univers of discourse Hover Oismin

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GCEKGCEKGCEKG	CENGCENGCENGCENGCENGCENGCENGCENGCENGCENG
	Grancept: a string providency a briefly discomption of the
	concep represented by the linguistic vericustle
	Hoeline Purzy rules for luzzy sytem washing machine controller
	R TE (dir L Is small) AND (grease Is small) THEN (Washime Is verys Rote dir L IS small) AND (grease Is small) THEN (Washime Is redium)
	Restriction TS Small) AND (grouse TS longe) THEN (washing TS long)" Restriction TS Small) AND (grouse TS small) THEN (washing TS Short)"
	Prite(dire To medium) AND (grouse Is medium) THEN (wasting Is reclaim)"
	RESTELDINE TS medium) AND (grease Is medium) THEN (washing Is needium)"  RESTELDINE TS medium) AND (grease Is longe) THEN (washing Is long)  RESTELDINES medium) AND (grease Is small) THEN (washing Is medium)
	ROSIF (dirk Is large) AND (grease is nedam) THAN (washing Is land)"  129-IF (dirk Is large) AND (grease is large) THAN (washing Is verylang)"
	# add Pules to Pury system
	pt set input values
	FS Sel voriable ("grase", 60)
	4 perform mondani Interence and prine output organ
	print (FS-Mandon; inference (E"washine"))

OULPUL

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Q'washime': 30.5816305423949863