

# Dicussion before the lecture

Reparametrization example by “shifting the phase”

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*Proof.*

$$\psi(\phi(t)) = t$$

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So,  $\psi'(t) \neq 0$  and  $\phi'(t) \neq 0$  for *each*  $t$  because  $\phi$  is bijective.  $\square$

# Regular parametrization

**Proposition.** *A reparametrization of a regular parametrization*

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**Proposition.** *A reparametrization of a regular parametrization is regular.*

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**Example.**  $\gamma(t) = (t^3, t^3)$  is singular at 0 because  $\dot{\gamma}(t) = (3t^2, 3t^2)$ .

**Lemma.**

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So,  $\psi'(\phi(t)) \neq 0$  and  $\phi'(t) \neq 0$  for each  $t$   
So,  $\psi'(t) \neq 0$  and  $\phi'(t) \neq 0$  for each  $t$  because  $\phi$  is bijective. □

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**Proposition.** *A reparametrization of a regular parametrization is regular.*

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$\dot{\gamma}(t) \neq 0$  and singular if  $\dot{\gamma}(t) = 0$ . The parametrization  $\gamma : (\alpha, \beta) \rightarrow \mathbb{R}^2$  is called regular if  $\dot{\gamma}(t) \neq 0$  for *every*  $t \in (\alpha, \beta)$ . □

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$\dot{\gamma}(t) \neq 0$  and singular if  $\dot{\gamma}(t) = 0$ . The parametrization  $\gamma : (\alpha, \beta) \rightarrow \mathbb{R}^2$  □  
 $\gamma$  is called regular if  $\dot{\gamma}(t) \neq 0$  for *every*  $t \in (\alpha, \beta)$ .

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**Proposition.** *A reparametrization of a regular parametrization is regular.*

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$$\dot{\gamma}(t) = f(t)\mathbf{v} =$$

## Dicussion after the lecture

$$\ddot{\tilde{\gamma}}(t) = \ddot{\gamma}(\phi(t))\phi'(t)\phi'(t) + \dot{\gamma}(\phi(t))\phi''(t)$$

(may change the direction of acceleration)

## Direction of velocity unchanged

$$\dot{\gamma}(t) = f(t)\mathbf{v} = (f(t)v_1, f(t)v_2)$$

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$$\dot{\gamma}(t) = f(t)\mathbf{v} = (f(t)v_1, f(t)v_2)$$
$$\ddot{\gamma}(t) = (f'(t)v_1, f'(t)v_2) =$$

## Dicussion after the lecture

$$\ddot{\tilde{\gamma}}(t) = \ddot{\gamma}(\phi(t))\phi'(t)\phi'(t) + \dot{\gamma}(\phi(t))\phi''(t)$$

(may change the direction of acceleration)

## Direction of velocity unchanged

$$\begin{aligned}\dot{\gamma}(t) &= f(t)\mathbf{v} = (f(t)v_1, f(t)v_2) \\ \ddot{\gamma}(t) &= (f'(t)v_1, f'(t)v_2) = f'(t)\mathbf{v}\end{aligned}$$

## Dicussion after the lecture

$$\ddot{\tilde{\gamma}}(t) = \ddot{\gamma}(\phi(t))\phi'(t)\phi'(t) + \dot{\gamma}(\phi(t))\phi''(t)$$

(may change the direction of acceleration)

## Direction of velocity unchanged

$$\dot{\gamma}(t) = f(t)\mathbf{v} = (f(t)v_1, f(t)v_2)$$

$$\ddot{\gamma}(t) = (f'(t)v_1, f'(t)v_2) = f'(t)\mathbf{v}$$

Direction of acceleration also unchanged