f

 $f: \mathbb{R}^2$

 $f: \mathbb{R}^2 \to \mathbb{R}$

 $f: \mathbb{R}^2 \to \mathbb{R}$

 $f: \mathbb{R}^2 \to \mathbb{R}$ $\gamma: (\alpha, \beta)$

 $f: \mathbb{R}^2 \to \mathbb{R}$ $\gamma: (\alpha, \beta) \to \mathbb{R}^2$

 $f: \mathbb{R}^2 \to \mathbb{R}$ $\gamma: (\alpha, \beta) \to \mathbb{R}^2$ $\gamma(t)$

 $f: \mathbb{R}^2 \to \mathbb{R}$ $\gamma: (\alpha, \beta) \to \mathbb{R}^2$ $\gamma(t) = (x(t), y(t))$

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f: \mathbb{R}^2 \to \mathbb{R}
\gamma: (\alpha, \beta) \to \mathbb{R}^2
\gamma(t) = (x(t), y(t))
f \circ \gamma
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 $f: \mathbb{R}^2 \to \mathbb{R}$ $\gamma: (\alpha, \beta) \to \mathbb{R}^2$ $\gamma(t) = (x(t), y(t))$ $f \circ \gamma: (\alpha, \beta)$

 $f: \mathbb{R}^2 \to \mathbb{R}$ $\gamma: (\alpha, \beta) \to \mathbb{R}^2$ $\gamma(t) = (x(t), y(t))$ $f \circ \gamma: (\alpha, \beta) \to \mathbb{R}$

$$f: \mathbb{R}^2 \to \mathbb{R}$$

$$\gamma: (\alpha, \beta) \to \mathbb{R}^2$$

$$\gamma(t) = (x(t), y(t))$$

$$f \circ \gamma: (\alpha, \beta) \to \mathbb{R}$$

$$(f \circ \gamma)'(t_0)$$

$$f: \mathbb{R}^2 \to \mathbb{R}$$

$$\gamma: (\alpha, \beta) \to \mathbb{R}^2$$

$$\gamma(t) = (x(t), y(t))$$

$$f \circ \gamma: (\alpha, \beta) \to \mathbb{R}$$

$$(f \circ \gamma)'(t_0) = f_x(x(t_0), y(t_0))x'(t_0) + f_y(x(t_0), y(t_0))y'(t_0)$$

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$$\gamma(t) = (x(t), y(t))$$

$$f \circ \gamma: (\alpha, \beta) \to \mathbb{R}$$

$$(f \circ \gamma)'(t_0) = f_x(x(t_0), y(t_0))x'(t_0) + f_y(x(t_0), y(t_0))y'(t_0) = (f_x(x, y), f_y(x, y)).\dot{\gamma}(t_0)$$

```
f: \mathbb{R}^2 \to \mathbb{R}
\gamma: (\alpha, \beta) \to \mathbb{R}^2
\gamma(t) = (x(t), y(t))
f \circ \gamma: (\alpha, \beta) \to \mathbb{R}
```

$$(f \circ \gamma)'(t_0) = f_x(x(t_0), y(t_0))x'(t_0) + f_y(x(t_0), y(t_0))y'(t_0) = \nabla(f)(x(t_0), y(t_0)).\dot{\gamma}(t_0),$$
where $\nabla(f)(x, y) = (f_x(x, y).f_y(x, y)),$

$$f: \mathbb{R}^2 \to \mathbb{R}$$

$$\gamma: (\alpha, \beta) \to \mathbb{R}^2$$

$$\gamma(t) = (x(t), y(t))$$

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$$\underline{f_{\mathbf{v}}(x(t_0), y(t_0)) := (f \circ \gamma)'(t_0) = \nabla(f)(x(t_0), y(t_0)).\mathbf{v}},$$
where $\nabla(f)(x, y) = (f_x(x, y).f_y(x, y)),$

$$\mathbf{v} = \dot{\gamma}(t_0),$$

$$f: \mathbb{R}^2 \to \mathbb{R}$$

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$$f_{\mathbf{v}}(x(t_0), y(t_0)) := (f \circ \gamma)'(t_0) = \nabla(f)(p).\mathbf{v},$$
where $\nabla(f)(x, y) = (f_x(x, y).f_y(x, y)),$

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and $p = (x(t_0), y(t_0))$

$$f$$

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 $f: \mathbb{R}^2$

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 $f: \mathbb{R}^2 \to \mathbb{R}$ $\gamma: \mathbb{R}^2$

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$$\mathbf{v} = \dot{\gamma}(t_0),$$
and $p = (x(t_0), y(t_0))$

 $f: \mathbb{R}^2 \to \mathbb{R}$ $\gamma: \mathbb{R}^2 \to \mathbb{R}^2$

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$$\gamma(t) = (x(t), y(t))$$

$$f \circ \gamma: (\alpha, \beta) \to \mathbb{R}$$

$$\begin{aligned}
& f_{\mathbf{v}}(x(t_0), y(t_0)) := (f \circ \gamma)'(t_0) = \nabla(f)(p).\mathbf{v}, \\
& \text{where } \nabla(f)(x, y) = (f_x(x, y).f_y(x, y)), \\
& \mathbf{v} = \dot{\gamma}(t_0), \\
& \text{and } p = (x(t_0), y(t_0))
\end{aligned}$$

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f: \mathbb{R}^2 \to \mathbb{R}\gamma: \mathbb{R}^2 \to \mathbb{R}^2\gamma(u, v)
```

$$f: \mathbb{R}^2 \to \mathbb{R}$$

$$\gamma: (\alpha, \beta) \to \mathbb{R}^2$$

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$$f \circ \gamma: (\alpha, \beta) \to \mathbb{R}$$

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$$f: \mathbb{R}^{2} \to \mathbb{R}$$

$$\gamma: (\alpha, \beta) \to \mathbb{R}^{2}$$

$$\gamma(t) = (x(t), y(t))$$

$$f \circ \gamma: (\alpha, \beta) \to \mathbb{R}$$

$$\boxed{f_{\mathbf{v}}(x(t_{0}), y(t_{0})) := (f \circ \gamma)'(t_{0}) = \nabla(f)(p).\mathbf{v}},$$
where $\nabla(f)(x, y) = (f_{x}(x, y).f_{y}(x, y)),$

$$\mathbf{v} = \dot{\gamma}(t_{0}),$$
and $p = (x(t_{0}), y(t_{0}))$

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$$\gamma: \mathbb{R}^{2} \to \mathbb{R}^{2}$$

$$\gamma(u, v) = (x(u, v), y(u, v))$$

$$f \circ \gamma$$

$$f: \mathbb{R}^2 \to \mathbb{R}$$

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$$\mathbf{v} = \dot{\gamma}(t_0),$$
and $p = (x(t_0), y(t_0))$

```
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\gamma: \mathbb{R}^2 \to \mathbb{R}^2
\gamma(u, v) = (x(u, v), y(u, v))
f \circ \gamma: \mathbb{R}^2
```

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```
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\gamma: \mathbb{R}^2 \to \mathbb{R}^2
\gamma(u, v) = (x(u, v), y(u, v))
f \circ \gamma: \mathbb{R}^2 \to \mathbb{R}
```

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$$(f \circ \gamma)_u(u_0, v_0)$$

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$$\gamma: \mathbb{R}^2 \to \mathbb{R}^2$$

$$\gamma(u, v) = (x(u, v), y(u, v))$$

$$f \circ \gamma: \mathbb{R}^2 \to \mathbb{R}$$

$$(f \circ \gamma)_u(u_0, v_0)$$

$$= f_x(x(u_0, v_0), y(u_0, v_0))x_u(u_0, v_0)$$

$$+ f_y(x(u_0, v_0), y(u_0, v_0))y_u(u_0, v_0)$$

Curves on surfaces

Definition. $\mathbf{v} \in \mathbb{R}^3$ is a tangent vector of the surface S at a point p, if there is a γ

$$f: \mathbb{R}^2 \to \mathbb{R}$$

$$\gamma: (\alpha, \beta) \to \mathbb{R}^2$$

$$\gamma(t) = (x(t), y(t))$$

$$f \circ \gamma: (\alpha, \beta) \to \mathbb{R}$$

$$f_{\mathbf{v}}(x(t_0), y(t_0)) := (f \circ \gamma)'(t_0) = \nabla(f)(p).\mathbf{v},$$
where $\nabla(f)(x, y) = (f_x(x, y).f_y(x, y)),$

$$\mathbf{v} = \dot{\gamma}(t_0),$$
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$$\gamma: \mathbb{R}^2 \to \mathbb{R}^2$$

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$$f \circ \gamma: \mathbb{R}^2 \to \mathbb{R}$$

$$(f \circ \gamma)_u(u_0, v_0)$$

$$= f_x(x(u_0, v_0), y(u_0, v_0))x_u(u_0, v_0)$$

$$+ f_y(x(u_0, v_0), y(u_0, v_0))y_u(u_0, v_0)$$

Curves on surfaces

Definition. $\mathbf{v} \in \mathbb{R}^3$ is a tangent vector of the surface S at a point p, if there is a $\gamma : (\alpha, \beta)$

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$$\gamma(t) = (x(t), y(t))$$

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where $\nabla(f)(x, y) = (f_x(x, y).f_y(x, y)),$

$$\mathbf{v} = \dot{\gamma}(t_0),$$
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$$= f_x(x(u_0, v_0), y(u_0, v_0))x_u(u_0, v_0)$$

$$+ f_y(x(u_0, v_0), y(u_0, v_0))y_u(u_0, v_0)$$

Curves on surfaces

Definition. $\mathbf{v} \in \mathbb{R}^3$ is a tangent vector of the surface S at a point p, if there is a $\gamma : (\alpha, \beta) \to S$

$$f: \mathbb{R}^2 \to \mathbb{R}$$

$$\gamma: (\alpha, \beta) \to \mathbb{R}^2$$

$$\gamma(t) = (x(t), y(t))$$

$$f \circ \gamma: (\alpha, \beta) \to \mathbb{R}$$

$$f_{\mathbf{v}}(x(t_0), y(t_0)) := (f \circ \gamma)'(t_0) = \nabla(f)(p).\mathbf{v},$$
where $\nabla(f)(x, y) = (f_x(x, y).f_y(x, y)),$

$$\mathbf{v} = \dot{\gamma}(t_0),$$
and $p = (x(t_0), y(t_0))$

$$f: \mathbb{R}^2 \to \mathbb{R}$$

$$\gamma: \mathbb{R}^2 \to \mathbb{R}^2$$

$$\gamma(u, v) = (x(u, v), y(u, v))$$

$$f \circ \gamma: \mathbb{R}^2 \to \mathbb{R}$$

$$(f \circ \gamma)_u(u_0, v_0)$$

$$= f_x(x(u_0, v_0), y(u_0, v_0))x_u(u_0, v_0)$$

$$+ f_y(x(u_0, v_0), y(u_0, v_0))y_u(u_0, v_0)$$

Curves on surfaces

Definition. $\mathbf{v} \in \mathbb{R}^3$ is a tangent vector of the surface S at a point p, if there is a $\gamma : (\alpha, \beta) \to S \subset \mathbb{R}^3$ so that $p = \gamma(t)$ and

$$f: \mathbb{R}^2 \to \mathbb{R}$$

$$\gamma: (\alpha, \beta) \to \mathbb{R}^2$$

$$\gamma(t) = (x(t), y(t))$$

$$f \circ \gamma: (\alpha, \beta) \to \mathbb{R}$$

$$f_{\mathbf{v}}(x(t_0), y(t_0)) := (f \circ \gamma)'(t_0) = \nabla(f)(p).\mathbf{v},$$
where $\nabla(f)(x, y) = (f_x(x, y).f_y(x, y)),$

$$\mathbf{v} = \dot{\gamma}(t_0),$$
and $p = (x(t_0), y(t_0))$

$$f: \mathbb{R}^2 \to \mathbb{R}$$

$$\gamma: \mathbb{R}^2 \to \mathbb{R}^2$$

$$\gamma(u, v) = (x(u, v), y(u, v))$$

$$f \circ \gamma: \mathbb{R}^2 \to \mathbb{R}$$

$$(f \circ \gamma)_u(u_0, v_0)$$

$$= f_x(x(u_0, v_0), y(u_0, v_0))x_u(u_0, v_0)$$

$$+ f_y(x(u_0, v_0), y(u_0, v_0))y_u(u_0, v_0)$$

Curves on surfaces

Definition. $\mathbf{v} \in \mathbb{R}^3$ is a tangent vector of the surface S at a point p, if there is a $\gamma : (\alpha, \beta) \to S \subset \mathbb{R}^3$ so that $p = \gamma(t)$ and $\mathbf{v} = \dot{\gamma}(t)$

 $\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$ is a curve.

$$f: \mathbb{R}^2 \to \mathbb{R}$$

$$\gamma: (\alpha, \beta) \to \mathbb{R}^2$$

$$\gamma(t) = (x(t), y(t))$$

$$f \circ \gamma: (\alpha, \beta) \to \mathbb{R}$$

$$f_{\mathbf{v}}(x(t_0), y(t_0)) := (f \circ \gamma)'(t_0) = \nabla(f)(p).\mathbf{v},$$
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and $p = (x(t_0), y(t_0))$

$$f: \mathbb{R}^2 \to \mathbb{R}$$

$$\gamma: \mathbb{R}^2 \to \mathbb{R}^2$$

$$\gamma(u, v) = (x(u, v), y(u, v))$$

$$f \circ \gamma: \mathbb{R}^2 \to \mathbb{R}$$

$$(f \circ \gamma)_u(u_0, v_0)$$

$$= f_x(x(u_0, v_0), y(u_0, v_0))x_u(u_0, v_0)$$

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Curves on surfaces

Definition. $\mathbf{v} \in \mathbb{R}^3$ is a tangent vector of the surface S at a point p, if there is a $\gamma : (\alpha, \beta) \to S \subset \mathbb{R}^3$ so that $p = \gamma(t)$ and $\mathbf{v} = \dot{\gamma}(t)$

 $\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$ is a curve.

 $\sigma: U \to S$ a surface patch.

$$f: \mathbb{R}^2 \to \mathbb{R}$$

$$\gamma: (\alpha, \beta) \to \mathbb{R}^2$$

$$\gamma(t) = (x(t), y(t))$$

$$f \circ \gamma: (\alpha, \beta) \to \mathbb{R}$$

$$f_{\mathbf{v}}(x(t_0), y(t_0)) := (f \circ \gamma)'(t_0) = \nabla(f)(p).\mathbf{v},$$
where $\nabla(f)(x, y) = (f_x(x, y).f_y(x, y)),$

$$\mathbf{v} = \dot{\gamma}(t_0),$$
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$$f: \mathbb{R}^2 \to \mathbb{R}$$

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$$\gamma(u, v) = (x(u, v), y(u, v))$$

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$$(f \circ \gamma)_u(u_0, v_0)$$

$$= f_x(x(u_0, v_0), y(u_0, v_0))x_u(u_0, v_0)$$

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Curves on surfaces

Definition. $\mathbf{v} \in \mathbb{R}^3$ is a tangent vector of the surface S at a point p, if there is a $\gamma : (\alpha, \beta) \to S \subset \mathbb{R}^3$ so that $p = \gamma(t)$ and $\mathbf{v} = \dot{\gamma}(t)$

 $\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$ is a curve.

 $\sigma: U \to S$ a surface patch.

So, $\gamma(t) = \sigma(x(t), y(t))$

$$f: \mathbb{R}^2 \to \mathbb{R}$$

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$$\gamma(t) = (x(t), y(t))$$

$$f \circ \gamma: (\alpha, \beta) \to \mathbb{R}$$

$$f_{\mathbf{v}}(x(t_0), y(t_0)) := (f \circ \gamma)'(t_0) = \nabla(f)(p).\mathbf{v},$$
where $\nabla(f)(x, y) = (f_x(x, y).f_y(x, y)),$

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$$+ f_y(x(u_0, v_0), y(u_0, v_0))y_u(u_0, v_0)$$

Curves on surfaces

Definition. $\mathbf{v} \in \mathbb{R}^3$ is a tangent vector of the surface S at a point p, if there is a $\gamma : (\alpha, \beta) \to S \subset \mathbb{R}^3$ so that $p = \gamma(t)$ and $\mathbf{v} = \dot{\gamma}(t)$

 $\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$ is a curve.

 $\sigma: U \to S$ a surface patch.

So, $\gamma(t) = \sigma(x(t), y(t)) = p \in S$

$$f: \mathbb{R}^2 \to \mathbb{R}$$

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where $\nabla(f)(x, y) = (f_x(x, y).f_y(x, y)),$

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The tangent vectors at $p \in S \subset \mathbb{R}^3$ always belong to the span of $\sigma_x(p)$ and $\sigma_y(p)$.

Exercise. Show that any vector that belongs to the span of $\sigma_x(p)$ and $\sigma_y(p)$, is a tangent vector.

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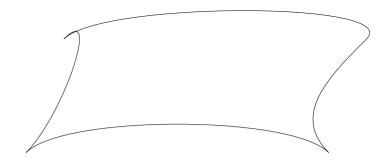
The tangent vectors at $p \in S \subset \mathbb{R}^3$ always belong to the span of $\sigma_x(p)$ and $\sigma_y(p)$.

Exercise. Show that any vector that belongs to the span of $\sigma_x(p)$ and $\sigma_y(p)$, is a tangent vector.

Exercise. Show that σ is regular at p if and only if the tangent vectors at p form a two dimensional subspace of \mathbb{R}^3 .

Note: This was not part of the lecture, however, since there seemed to be some confusion, this adds a diagram to support along with "subtitles".

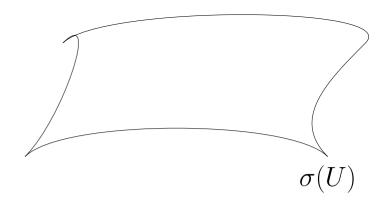
$$S \subset \mathbb{R}^3$$



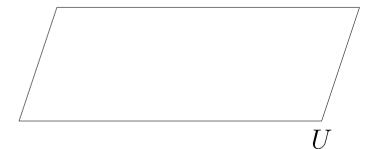
Consider a surface in space

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$$U \to S \subset \mathbb{R}^3$$



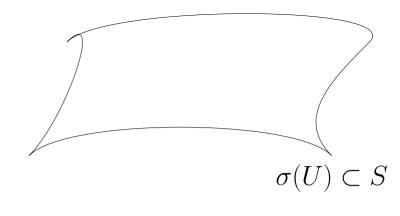




and a surface patch which is a map

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$$U \to S \subset \mathbb{R}^3$$

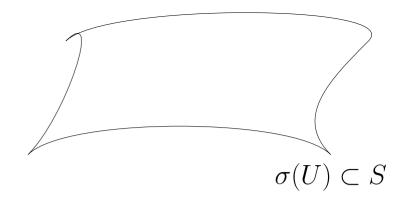




onto a part of the surface

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$$\sigma: U \to S \subset \mathbb{R}^3$$





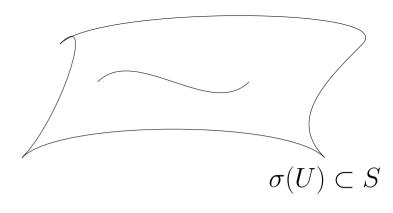


As usual we denote it by σ .

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$$\sigma: U \to S \subset \mathbb{R}^3$$

$$\gamma:(\alpha,\beta)\to S$$





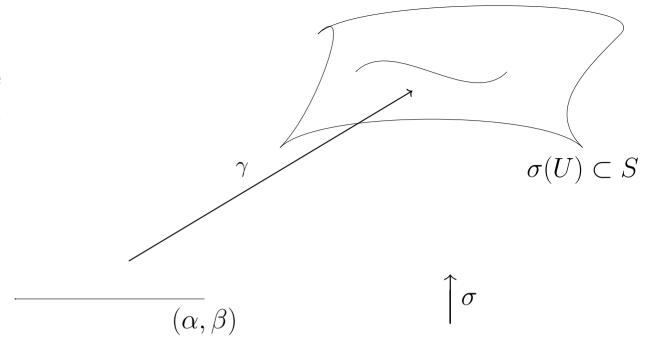


Now consider a curve on the surface

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$$\sigma: U \to S \subset \mathbb{R}^3$$

$$\gamma:(\alpha,\beta)\to S$$

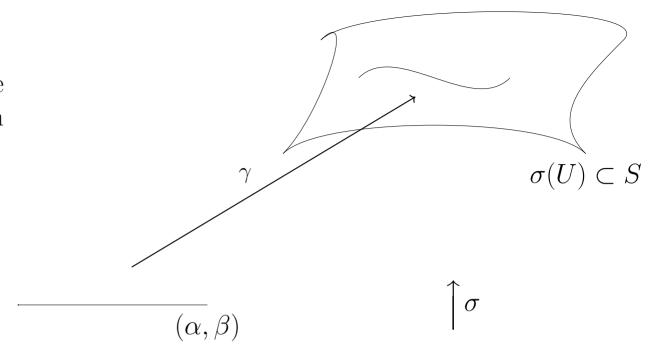




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$$\sigma: U \to S \subset \mathbb{R}^3$$

$$\gamma:(\alpha,\beta)\to\sigma(U)\subset S$$



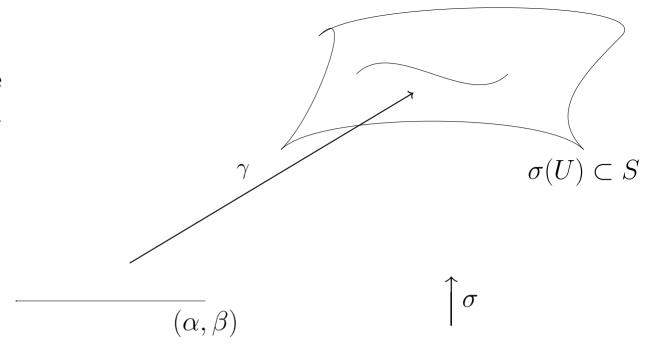


and let us assume it lies in the image of the surface patch

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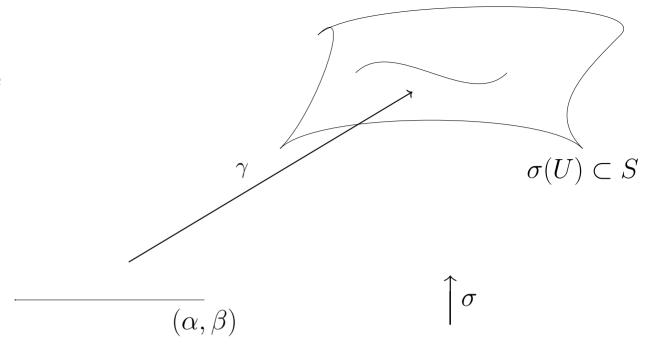


But it is also a curve in space

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$$\sigma: U \to S \subset \mathbb{R}^3$$

$$\gamma:(\alpha,\beta)\to\sigma(U)\subset S$$



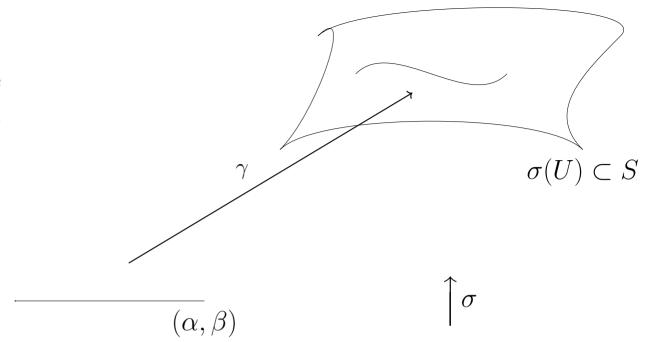


that happens to lie on a surface.

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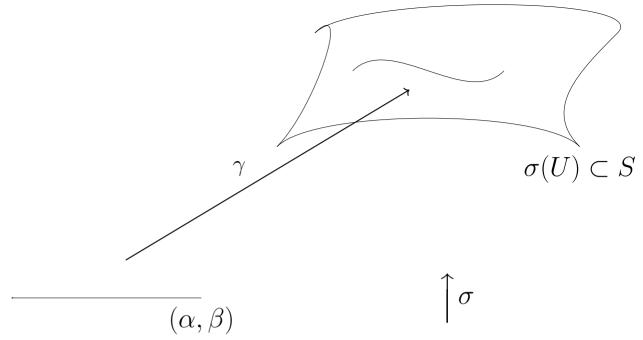


Let us see what lying on a surface

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$$\gamma:(\alpha,\beta)\to\sigma(U)\subset S\subset\mathbb{R}^3$$



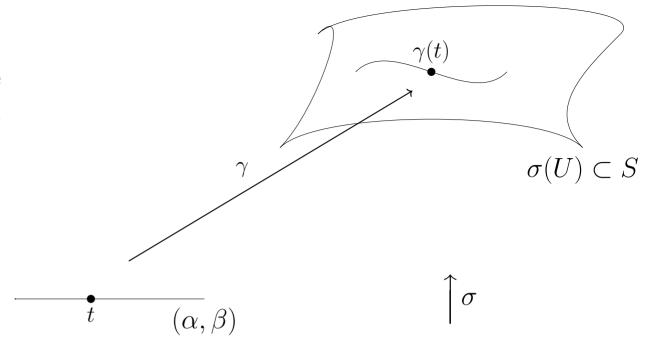


tells us about this space curve.

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$$\gamma:(\alpha,\beta)\to\sigma(U)\subset S\subset\mathbb{R}^3$$





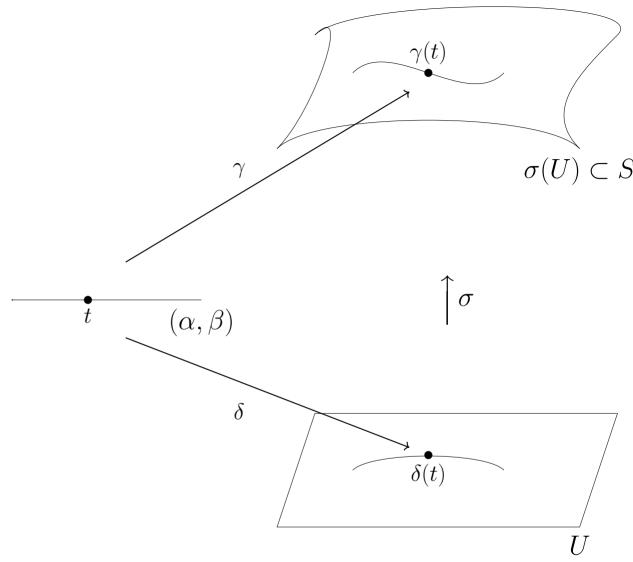
A parameter t goes to $\gamma(t)$

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$$\sigma: U \to S \subset \mathbb{R}^3$$

$$\gamma: (\alpha, \beta) \to \sigma(U) \subset S \subset \mathbb{R}^3$$
$$\delta: (\alpha, \beta) \to U$$

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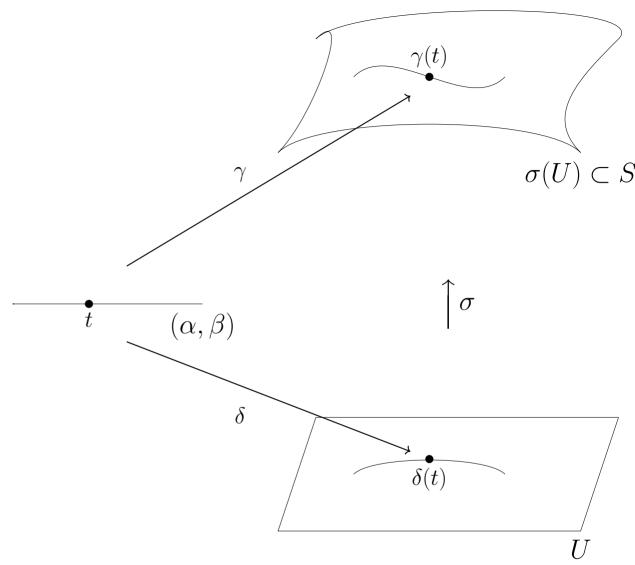
But to each $\gamma(t) \in \sigma(U)$, σ corresponds a $\delta(t) \in U$

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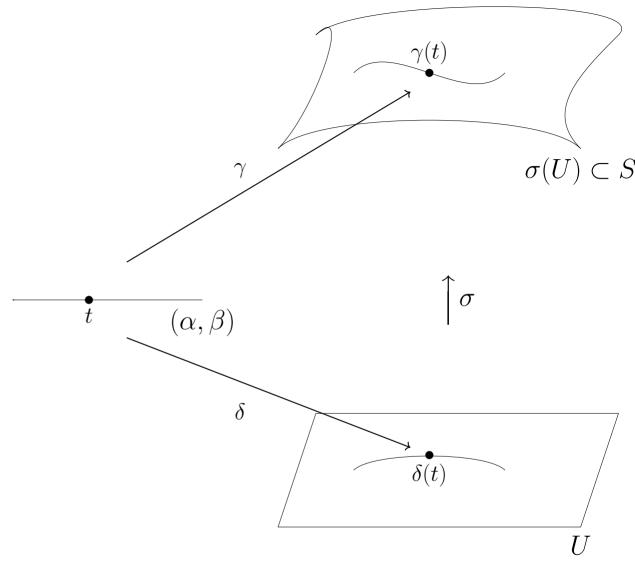
so that $\gamma(t) = \sigma(\delta(t))$

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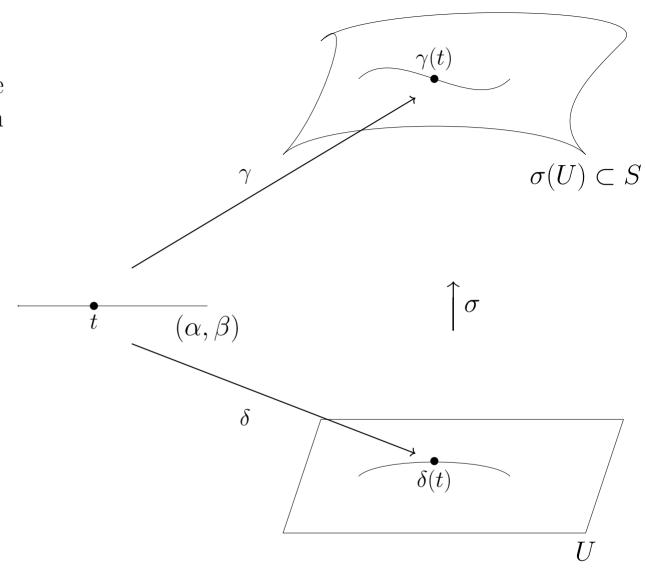
Note that this gives a $\delta(t)$ for each t

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so it defines a map.

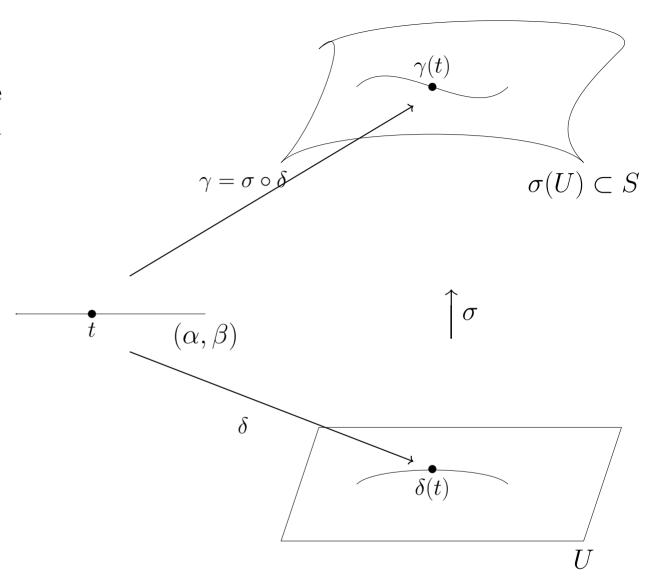
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$$\gamma:(\alpha,\beta)\to\sigma(U)\subset S\subset\mathbb{R}^3$$

$$\delta: (\alpha, \beta) \to U$$

$$\gamma(t) = \sigma(\delta(t))$$



Its smoothness takes some work, but assume it for now.

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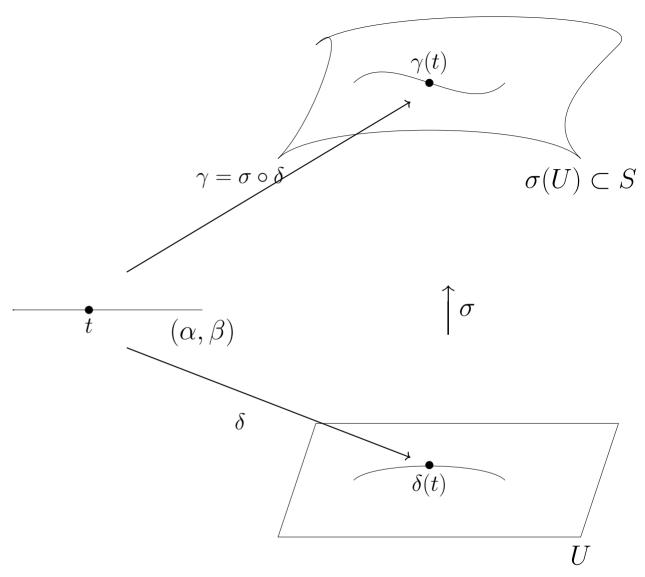
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$$\gamma:(\alpha,\beta)\to\sigma(U)\subset S\subset\mathbb{R}^3$$

$$\delta:(\alpha,\beta)\to U$$

$$\gamma(t) = \sigma(\delta(t))$$

$$\delta(t) = (x(t), y(t))$$



If we let x(t) and y(t) denote the coordinates of $\delta(t)$,

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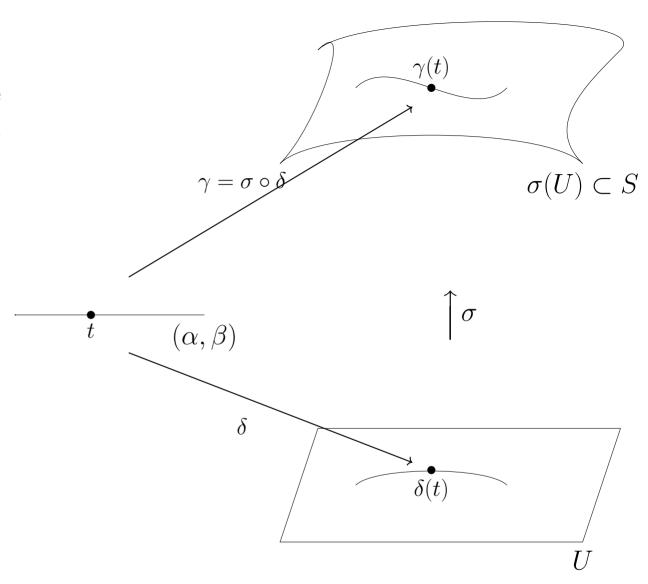
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$$\gamma:(\alpha,\beta)\to\sigma(U)\subset S\subset\mathbb{R}^3$$

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$$\gamma(t) = \sigma(\delta(t))$$

$$\delta(t) = (x(t), y(t))$$



chain rule allows us to express the derivatives

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$$\sigma: U \to S \subset \mathbb{R}^3$$

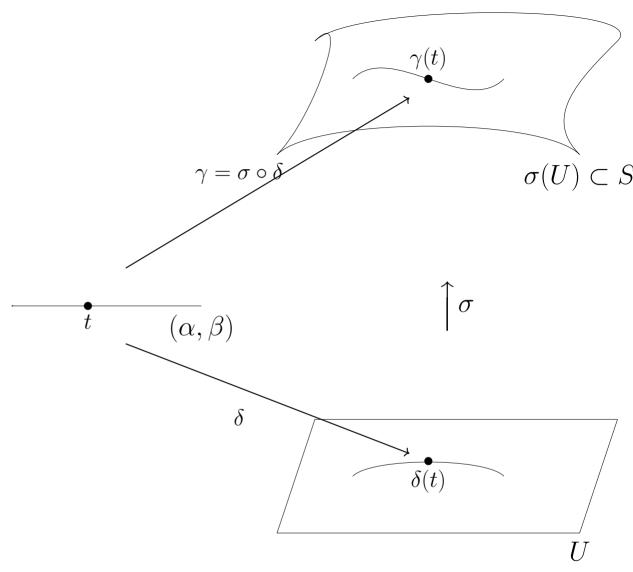
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$$\delta:(\alpha,\beta)\to U$$

$$\gamma(t) = \sigma(\delta(t))$$

$$\delta(t) = (x(t), y(t))$$

$$\dot{\gamma}(t) = x'(t)\sigma_x(\delta(t)) +$$



entirely in terms of the derivatives of δ and σ

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$$\sigma: U \to S \subset \mathbb{R}^3$$

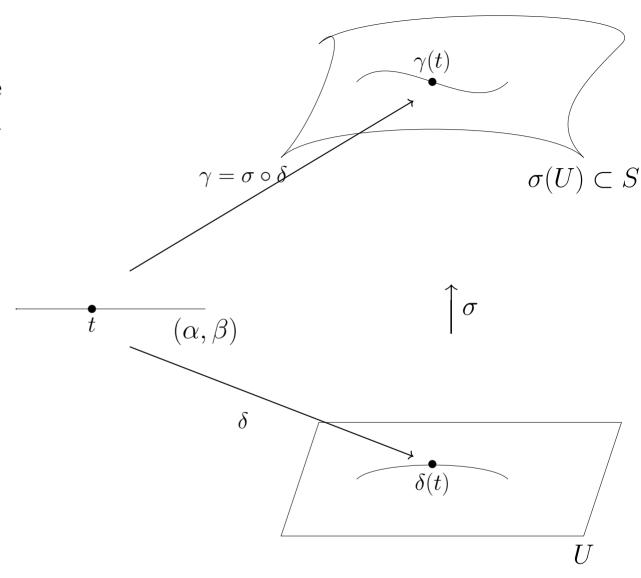
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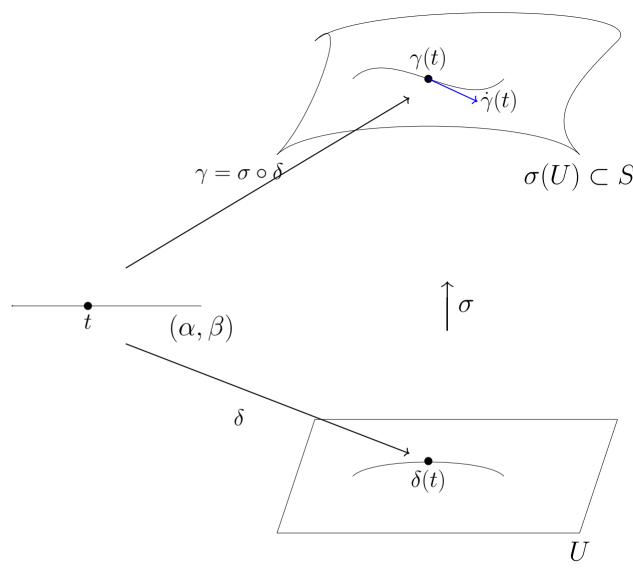
$$\gamma:(\alpha,\beta)\to\sigma(U)\subset S\subset\mathbb{R}^3$$

$$\delta: (\alpha, \beta) \to U$$

$$\gamma(t) = \sigma(\delta(t))$$

$$\delta(t) = (x(t), y(t))$$

$$\dot{\gamma}(t) = x'(t)\sigma_x(\delta(t)) + y'(t)\sigma_y(\delta(t))$$



The left hand side is the velocity vector of γ in space

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$$\sigma: U \to S \subset \mathbb{R}^3$$

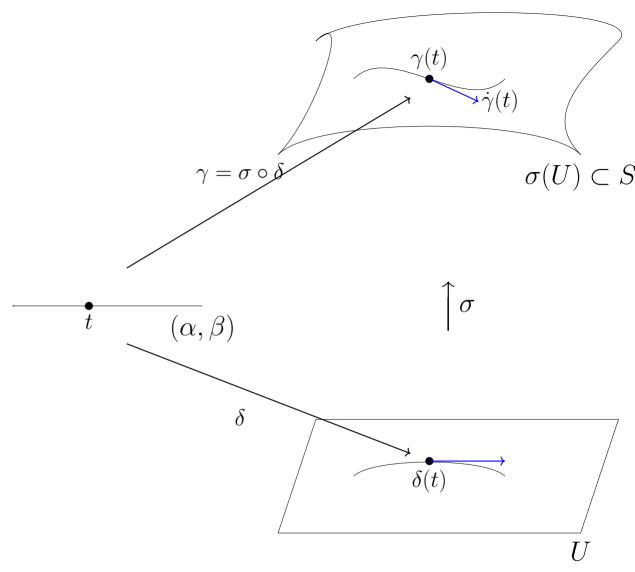
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$$\dot{\gamma}(t) = x'(t)\sigma_x(\delta(t)) + y'(t)\sigma_y(\delta(t))$$



The right hand side expresses it in terms of the patch

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$$\sigma: U \to S \subset \mathbb{R}^3$$

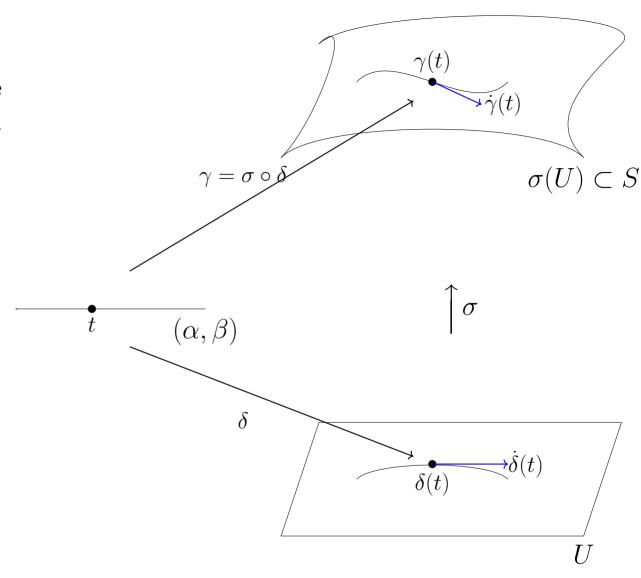
$$\gamma:(\alpha,\beta)\to\sigma(U)\subset S\subset\mathbb{R}^3$$

$$\delta:(\alpha,\beta)\to U$$

$$\gamma(t) = \sigma(\delta(t))$$

$$\delta(t) = (x(t), y(t))$$

$$\dot{\gamma}(t) = x'(t)\sigma_x(\delta(t)) + y'(t)\sigma_y(\delta(t))$$



i.e., in terms of the velocity of δ .

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$$\sigma: U \to S \subset \mathbb{R}^3$$

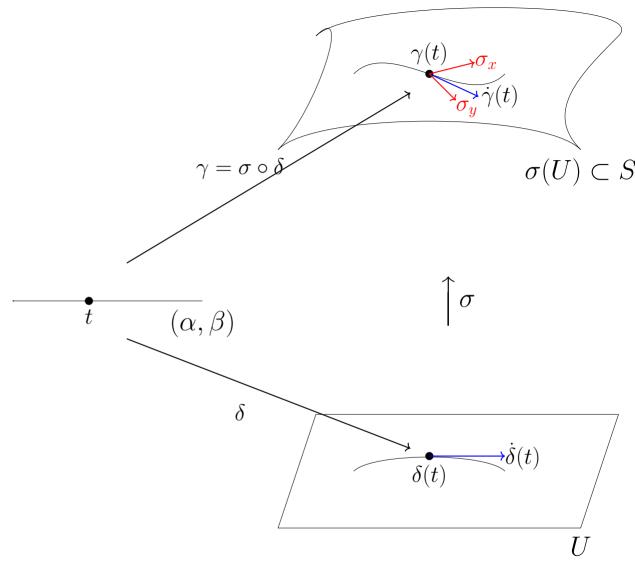
$$\gamma:(\alpha,\beta)\to\sigma(U)\subset S\subset\mathbb{R}^3$$

$$\delta: (\alpha, \beta) \to U$$

$$\gamma(t) = \sigma(\delta(t))$$

$$\delta(t) = (x(t), y(t))$$

$$\dot{\gamma}(t) = x'(t)\sigma_x(\delta(t)) + y'(t)\sigma_y(\delta(t))$$



Essentially, $\dot{\gamma}(t)$ can be written in terms of the surface patch, specifically, σ_x and σ_y .

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$$\sigma: U \to S \subset \mathbb{R}^3$$

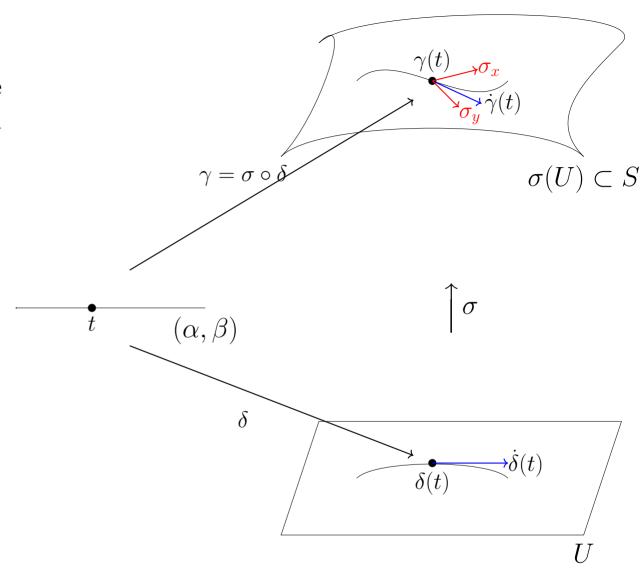
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$$\gamma(t) = \sigma(\delta(t))$$

$$\delta(t) = (x(t), y(t))$$

$$\dot{\gamma}(t) = x'(t)\sigma_x(\delta(t)) + y'(t)\sigma_y(\delta(t))$$



The coefficients come from $\dot{\delta}(t)$

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$$\sigma: U \to S \subset \mathbb{R}^3$$

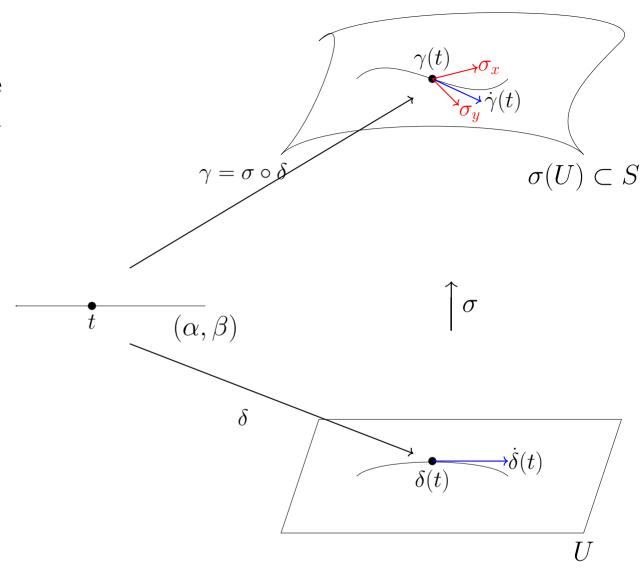
$$\gamma:(\alpha,\beta)\to\sigma(U)\subset S\subset\mathbb{R}^3$$

$$\delta: (\alpha, \beta) \to U$$

$$\gamma(t) = \sigma(\delta(t))$$

$$\delta(t) = (x(t), y(t))$$

$$\dot{\gamma}(t) = x'(t)\sigma_x(\delta(t)) + y'(t)\sigma_y(\delta(t))$$



(which is also the coordinates provides by the surface patch).

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$$\sigma: U \to S \subset \mathbb{R}^3$$

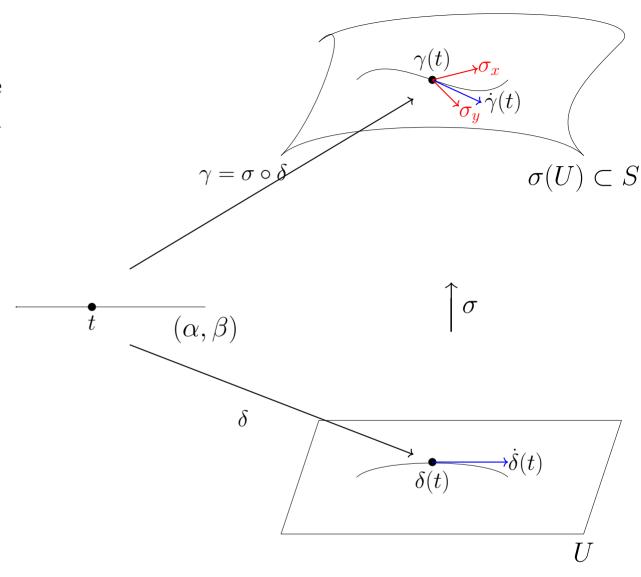
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$$\gamma(t) = \sigma(\delta(t))$$

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$$\dot{\gamma}(t) = x'(t)\sigma_x(\delta(t)) + y'(t)\sigma_y(\delta(t))$$



This shows why partial derivatives feature at all

Note: This was not part of the lecture, however, since there seemed to be some confusion, this adds a diagram to support along with "subtitles".

$$\sigma: U \to S \subset \mathbb{R}^3$$

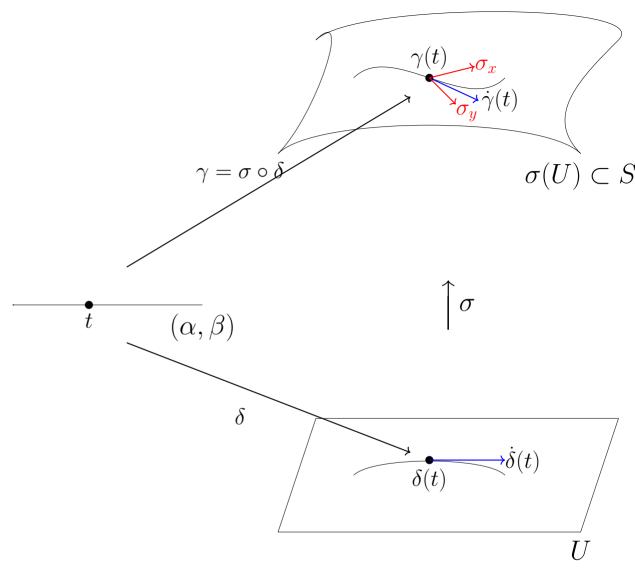
$$\gamma:(\alpha,\beta)\to\sigma(U)\subset S\subset\mathbb{R}^3$$

$$\delta:(\alpha,\beta)\to U$$

$$\gamma(t) = \sigma(\delta(t))$$

$$\delta(t) = (x(t), y(t))$$

$$\dot{\gamma}(t) = x'(t)\sigma_x(\delta(t)) + y'(t)\sigma_y(\delta(t))$$



and the importance of regularity...

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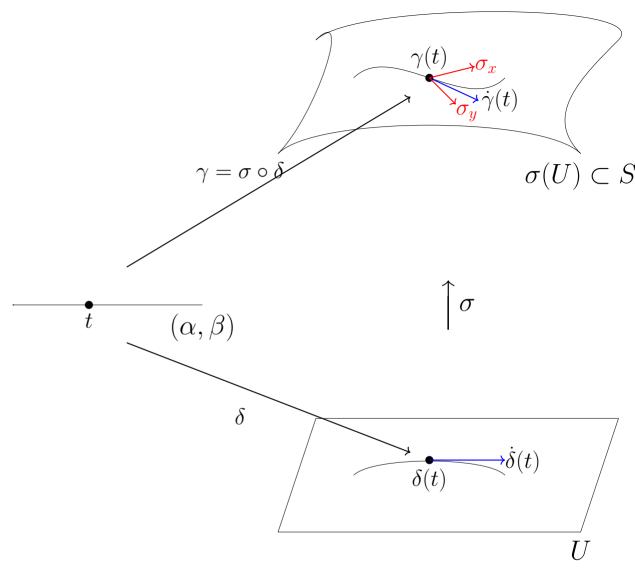
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...to ensure σ_x and σ_y are linearly independent