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| (cf)' = cf', | |
| where $c \in \mathbb{R}$ | |

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| Rule | Example |
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| $(cf)' = cf',$ where $c \in \mathbb{R}$ | $(2\sin(x))' =$ |

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| $(cf)' = cf',$ where $c \in \mathbb{R}$ | $(2\sin(x))' = 2\cos(x)$ |

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| (f-g)' = f' - g' | $(\sin(x) + x^3)' = \cos(x) + 3x^2$ $(\sin(x) - x^3)' = \cos(x) - 3x^2$ |
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| (fg)' = f'g + fg' | $(x^2 \sin(x))' = 2x \sin(x) + x^2 \cos(x)$ |
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| (fg)' = f'g + fg' | $(x^2 \sin(x))' = 2x \sin(x) + x^2 \cos(x)$ |
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| (f-g)' = f' - g' | $ \begin{aligned} (\sin(x) - x^3)' &= \\ \cos(x) - 3x^2 \end{aligned} $ |
| (fg)' = f'g + fg' | $(x^2\sin(x))' = 2x\sin(x) + x^2\cos(x)$ |
| $(f/g)' = \frac{f'g - fg'}{g^2}$ | $\left(\frac{\sin(x)}{x^2}\right)' = \frac{\cos(x)x^2 - \sin(x)2x}{x^4}$ |

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| (f-g)' = f' - g' | $ \begin{vmatrix} \sin(x) - x^3)' = \\ \cos(x) - 3x^2 \end{vmatrix} $ |
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| (fg)' = f'g + fg' | $\begin{cases} (x^2 \sin(x))' = \\ 2x \sin(x) + x^2 \cos(x) \end{cases}$ |
| $(f/g)' = \frac{f'g - fg'}{g^2}$ | $\frac{\left(\frac{\sin(x)}{x^2}\right)'}{\cos(x)x^2 - \sin(x)2x}$ |
| (f(g(x)))' = f'(g(x))g'(x) | $\sin(x^2))' =$ |

1.
$$c' = 0$$

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$$(x^n)' = nx^{n-1}$$

$$3. (\sin(x))' = \cos(x)$$

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| Rule | Example |
|---|---|
| $(cf)' = cf',$ where $c \in \mathbb{R}$ | $(2\sin(x))' = 2\cos(x)$ |
| (f+g)' = f' + g' | $ \begin{vmatrix} \sin(x) + x^3)' = \\ \cos(x) + 3x^2 \end{vmatrix} $ |
| (f-g)' = f' - g' | $ \begin{vmatrix} \sin(x) - x^3)' = \\ \cos(x) - 3x^2 \end{vmatrix} $ |
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Example.

$$(x^2\sin(x^3) + \cos(x))' =$$

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 γ

Example $\gamma: (-\pi,$

Example $\gamma:(-\pi,\pi)$

Example $\gamma: (-\pi, \pi) \to \mathbb{R}^2$

 $\gamma: (-\pi,\pi) o \mathbb{R}^2$ $\gamma(t)$

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Can we find a parametrization of the circle

Making the "speed" 1

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Making the "speed" 1

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Can we find a parametrization of the circle to ensure the speed is 1?

Making the "speed" 1

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Making the "speed" 1

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$$\sqrt{v_1(t)^2 + v_2(t)^2} = \sqrt{(-\sin(t))^2 + (\cos(t))^2}$$

$$\gamma: (-\pi, \pi) \to \mathbb{R}^2$$

$$\gamma(t) := (r\cos(t), r\sin(t))$$

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The "speed" at time t is defined as

$$\sqrt{v_1(t)^2 + v_2(t)^2} = \sqrt{(-r\sin(t))^2 + (r\cos(t))^2}
= \sqrt{r^2 \underbrace{((\sin(t))^2 + (\cos(t))^2)}_{1}}
= \sqrt{r^2}
= r$$

Can we find a parametrization of the circle to ensure the speed is 1?

Making the "speed" 1

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Acceleration of such a "unit speed parametrization" is,

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\underbrace{v_1(t)} v_2(t)$$

The "speed" at time t is defined as

$$\sqrt{v_1(t)^2 + v_2(t)^2} = \sqrt{(-r\sin(t))^2 + (r\cos(t))^2}
= \sqrt{r^2 \underbrace{((\sin(t))^2 + (\cos(t))^2)}_{1}}
= \sqrt{r^2}
- r$$

Can we find a parametrization of the circle to ensure the $\ddot{\gamma}(t)$ speed is 1?

Making the "speed" 1

$$\gamma: (-r\pi, r\pi) \to \mathbb{R}^2$$

$$\gamma(t) := (r\cos(t/r), r\sin(t/r))$$

$$\dot{\gamma}(t) := (\underbrace{-\sin(t/r)}_{v_1(t)}, \underbrace{\cos(t/r)}_{v_2(t)})$$

The "speed" is

$$\sqrt{v_1(t)^2 + v_2(t)^2} = \sqrt{(-\sin(t))^2 + (\cos(t))^2}
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= 1$$

Acceleration of such a "unit speed parametrization" is, $\ddot{\gamma}(t)$

$$\gamma: (-\pi, \pi) \to \mathbb{R}^2$$

$$\gamma(t) := (r\cos(t), r\sin(t))$$

$$\dot{\gamma}(t) := (\underbrace{-r\sin(t)}_{v_1(t)}, \underbrace{r\cos(t)}_{v_2(t)})$$

The "speed" at time t is defined as

$$\sqrt{v_1(t)^2 + v_2(t)^2} = \sqrt{(-r\sin(t))^2 + (r\cos(t))^2}
= \sqrt{r^2 \underbrace{((\sin(t))^2 + (\cos(t))^2)}_{1}}
= \sqrt{r^2}
- r$$

Can we find a parametrization of the circle to ensure the $\ddot{\gamma}(t) := (-1/r\cos(t/r),$ speed is 1?

Making the "speed" 1

$$\gamma: (-r\pi, r\pi) \to \mathbb{R}^2$$

$$\gamma(t) := (r\cos(t/r), r\sin(t/r))$$

$$\dot{\gamma}(t) := (\underbrace{-\sin(t/r)}_{v_1(t)}, \underbrace{\cos(t/r)}_{v_2(t)})$$

The "speed" is

$$\sqrt{v_1(t)^2 + v_2(t)^2} = \sqrt{(-\sin(t))^2 + (\cos(t))^2}
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Acceleration of such a "unit speed parametrization" is,

$$\ddot{\gamma}(t) := (-1/r\cos(t/r)$$

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= \sqrt{r^2}
- r$$

Can we find a parametrization of the circle to ensure the $\ddot{\gamma}(t) := (-1/r\cos(t/r), -1/r\sin(t/r))$ speed is 1?

Making the "speed" 1

$$\gamma: (-r\pi, r\pi) \to \mathbb{R}^2$$

$$\gamma(t) := (r\cos(t/r), r\sin(t/r))$$

$$\dot{\gamma}(t) := (\underbrace{-\sin(t/r)}_{v_1(t)}, \underbrace{\cos(t/r)}_{v_2(t)})$$

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Acceleration of such a "unit speed parametrization" is,

$$\ddot{\gamma}(t) := (-1/r\cos(t/r), -1/r\sin(t/r)$$



Example.

Example. $f(x) = \sin(x)$

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 $f(x)' = \cos(x)$

Example.
$$f(x) = \sin(x)$$

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Example. $f(x) = \sin(x)$ $f(x)' = \cos(x)$ $f(x)'' = -\sin(x)$ $f(x)''' = -\cos(x)$ $f(x)'''' = \sin(x)$

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```

Definition. A parametrized plane curve $\gamma(t) := (f_1(t), f_2(t))$ is differentiable

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Definition. A parametrized plane curve $\gamma(t) := (f_1(t), f_2(t))$ is differentiable if $f_1(t)$ and $f_2(t)$ are differentiable.

 $\dot{\gamma}(t)$

Example. $f(x) = \sin(x)$ $f(x)' = \cos(x)$ $f(x)'' = -\sin(x)$ $f(x)''' = -\cos(x)$ $f(x)'''' = \sin(x)$

Definition. A parametrized plane curve $\gamma(t) := (f_1(t), f_2(t))$ is differentiable if $f_1(t)$ and $f_2(t)$ are differentiable.

$$\dot{\gamma}(t) := \gamma'(t)$$

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```
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 $\dot{\gamma}(t) := \gamma'(t) := (f_1'(t), f_2'(t))$. It is smooth if it can be differentiated any number of times.

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Note. We will study only smooth parametrizations. From now on, all parametrizations will be assumed to be smooth.

Example. $f(x) = \sin(x)$ $f(x)' = \cos(x)$ $f(x)'' = -\sin(x)$ $f(x)''' = -\cos(x)$ $f(x)'''' = \sin(x)$ 1. $\gamma = (t, t)$

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1. $\gamma = (t, t)$ is a smooth parametrization.

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 $\dot{\gamma}(t) := \gamma'(t) := (f_1'(t), f_2'(t))$. It is smooth if it can be differentiated any number of times.

Note. We will study only smooth parametrizations. From now on, all parametrizations will be assumed to be smooth.

1.
$$\gamma = (t, t)$$
 is a smooth parametrization. $\dot{\gamma}(t) = (1, 1)$.

2.
$$\gamma = (\cos(t), \sin(t))$$

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- 2. $\gamma = (\cos(t), \sin(t))$ is a smooth parametrization. $\dot{\gamma}(t) = (-\sin(t), \cos(t)).$