f

 $f: \mathbb{R}^2$

 $f: \mathbb{R}^2 \to \mathbb{R}$

 $f: \mathbb{R}^2 \to \mathbb{R}$

 $f: \mathbb{R}^2 \to \mathbb{R}$ $\gamma: (\alpha, \beta)$

 $f: \mathbb{R}^2 \to \mathbb{R}$ $\gamma: (\alpha, \beta) \to \mathbb{R}^2$

 $f: \mathbb{R}^2 \to \mathbb{R}$ $\gamma: (\alpha, \beta) \to \mathbb{R}^2$ $\gamma(t)$

 $f: \mathbb{R}^2 \to \mathbb{R}$ $\gamma: (\alpha, \beta) \to \mathbb{R}^2$ $\gamma(t) = (x(t), y(t))$

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f: \mathbb{R}^2 \to \mathbb{R}
\gamma: (\alpha, \beta) \to \mathbb{R}^2
\gamma(t) = (x(t), y(t))
f \circ \gamma
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 $f: \mathbb{R}^2 \to \mathbb{R}$ $\gamma: (\alpha, \beta) \to \mathbb{R}^2$ $\gamma(t) = (x(t), y(t))$ $f \circ \gamma: (\alpha, \beta)$

 $f: \mathbb{R}^2 \to \mathbb{R}$ $\gamma: (\alpha, \beta) \to \mathbb{R}^2$ $\gamma(t) = (x(t), y(t))$ $f \circ \gamma: (\alpha, \beta) \to \mathbb{R}$

$$f: \mathbb{R}^2 \to \mathbb{R}$$

$$\gamma: (\alpha, \beta) \to \mathbb{R}^2$$

$$\gamma(t) = (x(t), y(t))$$

$$f \circ \gamma: (\alpha, \beta) \to \mathbb{R}$$

$$(f \circ \gamma)'(t_0)$$

$$f: \mathbb{R}^2 \to \mathbb{R}$$

$$\gamma: (\alpha, \beta) \to \mathbb{R}^2$$

$$\gamma(t) = (x(t), y(t))$$

$$f \circ \gamma: (\alpha, \beta) \to \mathbb{R}$$

$$(f \circ \gamma)'(t_0) = f_x(x(t_0), y(t_0))x'(t_0) + f_y(x(t_0), y(t_0))y'(t_0)$$

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$$\gamma(t) = (x(t), y(t))$$

$$f \circ \gamma: (\alpha, \beta) \to \mathbb{R}$$

$$(f \circ \gamma)'(t_0) = f_x(x(t_0), y(t_0))x'(t_0) + f_y(x(t_0), y(t_0))y'(t_0) = (f_x(x, y), f_y(x, y)).\dot{\gamma}(t_0)$$

```
f: \mathbb{R}^2 \to \mathbb{R}
\gamma: (\alpha, \beta) \to \mathbb{R}^2
\gamma(t) = (x(t), y(t))
f \circ \gamma: (\alpha, \beta) \to \mathbb{R}
```

$$(f \circ \gamma)'(t_0) = f_x(x(t_0), y(t_0))x'(t_0) + f_y(x(t_0), y(t_0))y'(t_0) = \nabla(f)(x(t_0), y(t_0)).\dot{\gamma}(t_0),$$
where $\nabla(f)(x, y) = (f_x(x, y).f_y(x, y)),$

$$f: \mathbb{R}^2 \to \mathbb{R}$$

$$\gamma: (\alpha, \beta) \to \mathbb{R}^2$$

$$\gamma(t) = (x(t), y(t))$$

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$$\underline{f_{\mathbf{v}}(x(t_0), y(t_0)) := (f \circ \gamma)'(t_0) = \nabla(f)(x(t_0), y(t_0)).\mathbf{v}},$$
where $\nabla(f)(x, y) = (f_x(x, y).f_y(x, y)),$

$$\mathbf{v} = \dot{\gamma}(t_0),$$

$$f: \mathbb{R}^2 \to \mathbb{R}$$

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$$f_{\mathbf{v}}(x(t_0), y(t_0)) := (f \circ \gamma)'(t_0) = \nabla(f)(p).\mathbf{v},$$
where $\nabla(f)(x, y) = (f_x(x, y).f_y(x, y)),$

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and $p = (x(t_0), y(t_0))$

$$f$$

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 $f: \mathbb{R}^2$

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 $f: \mathbb{R}^2 \to \mathbb{R}$ $\gamma: \mathbb{R}^2$

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$$\mathbf{v} = \dot{\gamma}(t_0),$$
and $p = (x(t_0), y(t_0))$

 $f: \mathbb{R}^2 \to \mathbb{R}$ $\gamma: \mathbb{R}^2 \to \mathbb{R}^2$

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$$\gamma(t) = (x(t), y(t))$$

$$f \circ \gamma: (\alpha, \beta) \to \mathbb{R}$$

$$\begin{aligned}
& f_{\mathbf{v}}(x(t_0), y(t_0)) := (f \circ \gamma)'(t_0) = \nabla(f)(p).\mathbf{v}, \\
& \text{where } \nabla(f)(x, y) = (f_x(x, y).f_y(x, y)), \\
& \mathbf{v} = \dot{\gamma}(t_0), \\
& \text{and } p = (x(t_0), y(t_0))
\end{aligned}$$

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f: \mathbb{R}^2 \to \mathbb{R}\gamma: \mathbb{R}^2 \to \mathbb{R}^2\gamma(u, v)
```

$$f: \mathbb{R}^2 \to \mathbb{R}$$

$$\gamma: (\alpha, \beta) \to \mathbb{R}^2$$

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$$f \circ \gamma: (\alpha, \beta) \to \mathbb{R}$$

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$$f: \mathbb{R}^{2} \to \mathbb{R}$$

$$\gamma: (\alpha, \beta) \to \mathbb{R}^{2}$$

$$\gamma(t) = (x(t), y(t))$$

$$f \circ \gamma: (\alpha, \beta) \to \mathbb{R}$$

$$\boxed{f_{\mathbf{v}}(x(t_{0}), y(t_{0})) := (f \circ \gamma)'(t_{0}) = \nabla(f)(p).\mathbf{v}},$$
where $\nabla(f)(x, y) = (f_{x}(x, y).f_{y}(x, y)),$

$$\mathbf{v} = \dot{\gamma}(t_{0}),$$
and $p = (x(t_{0}), y(t_{0}))$

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$$\gamma: \mathbb{R}^{2} \to \mathbb{R}^{2}$$

$$\gamma(u, v) = (x(u, v), y(u, v))$$

$$f \circ \gamma$$

$$f: \mathbb{R}^2 \to \mathbb{R}$$

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$$\mathbf{v} = \dot{\gamma}(t_0),$$
and $p = (x(t_0), y(t_0))$

```
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\gamma: \mathbb{R}^2 \to \mathbb{R}^2
\gamma(u, v) = (x(u, v), y(u, v))
f \circ \gamma: \mathbb{R}^2
```

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```
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\gamma: \mathbb{R}^2 \to \mathbb{R}^2
\gamma(u, v) = (x(u, v), y(u, v))
f \circ \gamma: \mathbb{R}^2 \to \mathbb{R}
```

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$$(f \circ \gamma)_u(u_0, v_0)$$

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$$\gamma: \mathbb{R}^2 \to \mathbb{R}^2$$

$$\gamma(u, v) = (x(u, v), y(u, v))$$

$$f \circ \gamma: \mathbb{R}^2 \to \mathbb{R}$$

$$(f \circ \gamma)_u(u_0, v_0)$$

$$= f_x(x(u_0, v_0), y(u_0, v_0))x_u(u_0, v_0)$$

$$+ f_y(x(u_0, v_0), y(u_0, v_0))y_u(u_0, v_0)$$

Curves on surfaces

Definition. $\mathbf{v} \in \mathbb{R}^3$ is a tangent vector of the surface S at a point p, if there is a γ

$$f: \mathbb{R}^2 \to \mathbb{R}$$

$$\gamma: (\alpha, \beta) \to \mathbb{R}^2$$

$$\gamma(t) = (x(t), y(t))$$

$$f \circ \gamma: (\alpha, \beta) \to \mathbb{R}$$

$$f_{\mathbf{v}}(x(t_0), y(t_0)) := (f \circ \gamma)'(t_0) = \nabla(f)(p).\mathbf{v},$$
where $\nabla(f)(x, y) = (f_x(x, y).f_y(x, y)),$

$$\mathbf{v} = \dot{\gamma}(t_0),$$
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$$\gamma: \mathbb{R}^2 \to \mathbb{R}^2$$

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$$f \circ \gamma: \mathbb{R}^2 \to \mathbb{R}$$

$$(f \circ \gamma)_u(u_0, v_0)$$

$$= f_x(x(u_0, v_0), y(u_0, v_0))x_u(u_0, v_0)$$

$$+ f_y(x(u_0, v_0), y(u_0, v_0))y_u(u_0, v_0)$$

Curves on surfaces

Definition. $\mathbf{v} \in \mathbb{R}^3$ is a tangent vector of the surface S at a point p, if there is a $\gamma : (\alpha, \beta)$

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$$\gamma(t) = (x(t), y(t))$$

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where $\nabla(f)(x, y) = (f_x(x, y).f_y(x, y)),$

$$\mathbf{v} = \dot{\gamma}(t_0),$$
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$$= f_x(x(u_0, v_0), y(u_0, v_0))x_u(u_0, v_0)$$

$$+ f_y(x(u_0, v_0), y(u_0, v_0))y_u(u_0, v_0)$$

Curves on surfaces

Definition. $\mathbf{v} \in \mathbb{R}^3$ is a tangent vector of the surface S at a point p, if there is a $\gamma : (\alpha, \beta) \to S$

$$f: \mathbb{R}^2 \to \mathbb{R}$$

$$\gamma: (\alpha, \beta) \to \mathbb{R}^2$$

$$\gamma(t) = (x(t), y(t))$$

$$f \circ \gamma: (\alpha, \beta) \to \mathbb{R}$$

$$f_{\mathbf{v}}(x(t_0), y(t_0)) := (f \circ \gamma)'(t_0) = \nabla(f)(p).\mathbf{v},$$
where $\nabla(f)(x, y) = (f_x(x, y).f_y(x, y)),$

$$\mathbf{v} = \dot{\gamma}(t_0),$$
and $p = (x(t_0), y(t_0))$

$$f: \mathbb{R}^2 \to \mathbb{R}$$

$$\gamma: \mathbb{R}^2 \to \mathbb{R}^2$$

$$\gamma(u, v) = (x(u, v), y(u, v))$$

$$f \circ \gamma: \mathbb{R}^2 \to \mathbb{R}$$

$$(f \circ \gamma)_u(u_0, v_0)$$

$$= f_x(x(u_0, v_0), y(u_0, v_0))x_u(u_0, v_0)$$

$$+ f_y(x(u_0, v_0), y(u_0, v_0))y_u(u_0, v_0)$$

Curves on surfaces

Definition. $\mathbf{v} \in \mathbb{R}^3$ is a tangent vector of the surface S at a point p, if there is a $\gamma : (\alpha, \beta) \to S \subset \mathbb{R}^3$ so that $p = \gamma(t)$ and

$$f: \mathbb{R}^2 \to \mathbb{R}$$

$$\gamma: (\alpha, \beta) \to \mathbb{R}^2$$

$$\gamma(t) = (x(t), y(t))$$

$$f \circ \gamma: (\alpha, \beta) \to \mathbb{R}$$

$$f_{\mathbf{v}}(x(t_0), y(t_0)) := (f \circ \gamma)'(t_0) = \nabla(f)(p).\mathbf{v},$$
where $\nabla(f)(x, y) = (f_x(x, y).f_y(x, y)),$

$$\mathbf{v} = \dot{\gamma}(t_0),$$
and $p = (x(t_0), y(t_0))$

$$f: \mathbb{R}^2 \to \mathbb{R}$$

$$\gamma: \mathbb{R}^2 \to \mathbb{R}^2$$

$$\gamma(u, v) = (x(u, v), y(u, v))$$

$$f \circ \gamma: \mathbb{R}^2 \to \mathbb{R}$$

$$(f \circ \gamma)_u(u_0, v_0)$$

$$= f_x(x(u_0, v_0), y(u_0, v_0))x_u(u_0, v_0)$$

$$+ f_y(x(u_0, v_0), y(u_0, v_0))y_u(u_0, v_0)$$

Curves on surfaces

Definition. $\mathbf{v} \in \mathbb{R}^3$ is a tangent vector of the surface S at a point p, if there is a $\gamma : (\alpha, \beta) \to S \subset \mathbb{R}^3$ so that $p = \gamma(t)$ and $\mathbf{v} = \dot{\gamma}(t)$

 $\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$ is a curve.

$$f: \mathbb{R}^2 \to \mathbb{R}$$

$$\gamma: (\alpha, \beta) \to \mathbb{R}^2$$

$$\gamma(t) = (x(t), y(t))$$

$$f \circ \gamma: (\alpha, \beta) \to \mathbb{R}$$

$$f_{\mathbf{v}}(x(t_0), y(t_0)) := (f \circ \gamma)'(t_0) = \nabla(f)(p).\mathbf{v},$$
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and $p = (x(t_0), y(t_0))$

$$f: \mathbb{R}^2 \to \mathbb{R}$$

$$\gamma: \mathbb{R}^2 \to \mathbb{R}^2$$

$$\gamma(u, v) = (x(u, v), y(u, v))$$

$$f \circ \gamma: \mathbb{R}^2 \to \mathbb{R}$$

$$(f \circ \gamma)_u(u_0, v_0)$$

$$= f_x(x(u_0, v_0), y(u_0, v_0))x_u(u_0, v_0)$$

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Curves on surfaces

Definition. $\mathbf{v} \in \mathbb{R}^3$ is a tangent vector of the surface S at a point p, if there is a $\gamma : (\alpha, \beta) \to S \subset \mathbb{R}^3$ so that $p = \gamma(t)$ and $\mathbf{v} = \dot{\gamma}(t)$

 $\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$ is a curve.

 $\sigma: U \to S$ a surface patch.

$$f: \mathbb{R}^2 \to \mathbb{R}$$

$$\gamma: (\alpha, \beta) \to \mathbb{R}^2$$

$$\gamma(t) = (x(t), y(t))$$

$$f \circ \gamma: (\alpha, \beta) \to \mathbb{R}$$

$$f_{\mathbf{v}}(x(t_0), y(t_0)) := (f \circ \gamma)'(t_0) = \nabla(f)(p).\mathbf{v},$$
where $\nabla(f)(x, y) = (f_x(x, y).f_y(x, y)),$

$$\mathbf{v} = \dot{\gamma}(t_0),$$
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$$f: \mathbb{R}^2 \to \mathbb{R}$$

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$$\gamma(u, v) = (x(u, v), y(u, v))$$

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$$(f \circ \gamma)_u(u_0, v_0)$$

$$= f_x(x(u_0, v_0), y(u_0, v_0))x_u(u_0, v_0)$$

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Curves on surfaces

Definition. $\mathbf{v} \in \mathbb{R}^3$ is a tangent vector of the surface S at a point p, if there is a $\gamma : (\alpha, \beta) \to S \subset \mathbb{R}^3$ so that $p = \gamma(t)$ and $\mathbf{v} = \dot{\gamma}(t)$

 $\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$ is a curve.

 $\sigma: U \to S$ a surface patch.

So, $\gamma(t) = \sigma(x(t), y(t))$

$$f: \mathbb{R}^2 \to \mathbb{R}$$

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$$\gamma(t) = (x(t), y(t))$$

$$f \circ \gamma: (\alpha, \beta) \to \mathbb{R}$$

$$f_{\mathbf{v}}(x(t_0), y(t_0)) := (f \circ \gamma)'(t_0) = \nabla(f)(p).\mathbf{v},$$
where $\nabla(f)(x, y) = (f_x(x, y).f_y(x, y)),$

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Curves on surfaces

Definition. $\mathbf{v} \in \mathbb{R}^3$ is a tangent vector of the surface S at a point p, if there is a $\gamma : (\alpha, \beta) \to S \subset \mathbb{R}^3$ so that $p = \gamma(t)$ and $\mathbf{v} = \dot{\gamma}(t)$

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Exercise. Show that σ is regular at p if and only if the tangent vectors at p form a two dimensional subspace of \mathbb{R}^3 .

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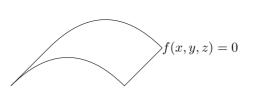
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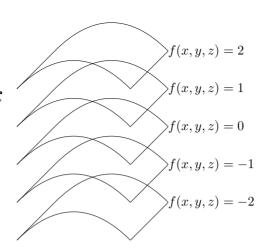
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Given f(x, y, z) = t, can we "solve for" z in terms of x and y?

Can we write $z = \theta(x, y)$ so that $f(x, y, \theta(x, y)) = t$?

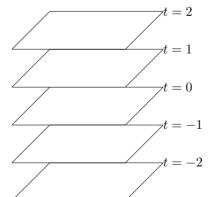


Equivalently, can we find, $F(x, y, t) := (x, y, \theta(x, y))$ so that $f(x, y, \theta(x, y)) = t$

Equivalently, can we define an inverse of

$$G(x, y, z) := (x, y, f(x, y, z))$$

so that G(F(x, y, z)) = (x, y, z)



$$F_x = (1, 0, f_x(x, y, z))$$

$$F_y = (0, 1, f_y(x, y, z))$$

$$F_z = (0, 0, f_z(x, y, z))$$

linearly independent if and only if $f_z(x, y, z) \neq 0$

Can "solve for z" if and only if $f_z(x, y, z) \neq 0$

 $F_x = (1, 0, f_x(x, y, z))$

 $F_y = (0, 1, f_y(x, y, z))$

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linearly independent if and only if $f_z(x, y, z) \neq 0$

Can "solve for z" if and only if $f_z(x, y, z) \neq 0$

Can "solve for y" if and only if $f_y(x, y, z) \neq 0$

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Can "solve for z" if and only if $f_z(x, y, z) \neq 0$

Can "solve for y" if and only if $f_y(x, y, z) \neq 0$

Can "solve for x" if and only if $f_x(x, y, z) \neq 0$

$$F_x = (1, 0, f_x(x, y, z))$$

$$F_y = (0, 1, f_y(x, y, z))$$

$$F_z = (0, 0, f_z(x, y, z))$$

linearly independent if and only if $f_z(x, y, z) \neq 0$

Can "solve for z" if and only if $f_z(x, y, z) \neq 0$

Can "solve for y" if and only if $f_y(x, y, z) \neq 0$

Can "solve for x" if and only if $f_x(x, y, z) \neq 0$

Can solve for either x, y, or z if and only if $\nabla(f)(x,y,z) \neq 0$

$$\mathbf{T}(t) \times \mathbf{N}(t) = \mathbf{B}(t)$$

$$\mathbf{T}(t) \times \mathbf{N}(t) = \mathbf{B}(t)$$

$$\mathbf{B}(t) \times \mathbf{T}(t) = \mathbf{N}(t)$$

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$$\mathbf{B}(t) \times \mathbf{T}(t) = \mathbf{N}(t)$$

 $\mathbf{T}(t) = (\cos(\theta(t)), \sin(\theta(t)))$

 $\mathbf{T}(t) = (\cos(\theta(t)), \sin(\theta(t)))$ $\dot{\mathbf{T}}(t)$

$$\mathbf{T}(t) = (\cos(\theta(t)), \sin(\theta(t)))$$

$$\dot{\mathbf{T}}(t) = \theta'(t)(-\sin(\theta(t)), \cos(\theta(t)))$$

$$\begin{aligned} \mathbf{T}(t) &= (\cos(\theta(t)), \sin(\theta(t))) \\ \dot{\mathbf{T}}(t) &= \theta'(t)(-\sin(\theta(t)), \cos(\theta(t))) = \theta'(t)\mathbf{N}(t) \end{aligned}$$

$$\mathbf{T}(t) = (\cos(\theta(t)), \sin(\theta(t)))$$

$$\dot{\mathbf{T}}(t) = \theta'(t)(-\sin(\theta(t)), \cos(\theta(t))) = \theta'(t)\mathbf{N}(t)$$

$$\kappa_s(t) = \theta'(t)$$
If $\kappa_s(t) = \kappa$,

$$\mathbf{T}(t) = (\cos(\theta(t)), \sin(\theta(t)))$$

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If $\kappa_s(t) = \kappa$,
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If $\kappa_s(t) = \kappa$,
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$$\theta(t) = \kappa t$$

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If $\kappa_s(t) = \kappa$,
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$$\theta(t) = \kappa t + \theta_0$$

$$\mathbf{T}(t) = (\cos(\theta(t)), \sin(\theta(t)))$$

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If $\kappa_s(t) = \kappa$,

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$$\gamma'(t) = \mathbf{T}(t) = (\cos(at + \theta_0), \sin(at + \theta_0))$$

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$$\gamma'(t) = \mathbf{T}(t) = (\cos(at + \theta_0), \sin(at + \theta_0))$$
$$\gamma(t) = (\frac{1}{\kappa}\sin(\kappa t + \theta_0) + p_1, -\frac{1}{\kappa}\cos(\kappa t + \theta_0) + p_2)$$

$$\mathbf{T}(t) = (\cos(\theta(t)), \sin(\theta(t)))$$

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where $p = (p_1, p_2)$

Solution.
$$\ddot{\gamma}(t) = 0$$

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$$\dot{\gamma}(t) = \mathbf{v}$$

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 $\dot{\gamma}(t) = \mathbf{v} \text{ for some } \mathbf{v} \in \mathbb{R}$

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$$\ddot{\gamma}(t) = 0$$

 $\dot{\gamma}(t) = \mathbf{v} \text{ for some } \mathbf{v} \in \mathbb{R}$
 $\gamma(t) = t\mathbf{v} + p$

 $\mathbf{N}(t).\mathbf{T}(t) = 0$

 $\mathbf{N}(t).\mathbf{T}(t) = 0$ $(\mathbf{N}(t).\mathbf{T}(t))' = 0$

 $\mathbf{N}(t).\mathbf{T}(t) = 0$ $(\mathbf{N}(t).\mathbf{T}(t))' = 0$ $\dot{\mathbf{N}}(t).\mathbf{T}(t) + \mathbf{N}(t).\dot{\mathbf{T}}(t) = 0$

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$$(\mathbf{N}(t).\mathbf{T}(t))' = 0$$

$$\dot{\mathbf{N}}(t).\mathbf{T}(t) + \mathbf{N}(t).\dot{\mathbf{T}}(t) = 0$$

$$\dot{\mathbf{N}}(t).\mathbf{T}(t) + \kappa_s(t)\mathbf{N}(t).\dot{\mathbf{N}}(t) = 0$$

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 $\dot{\mathbf{N}}(t).\mathbf{T}(t) = -\kappa_s(t)$

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$$\dot{\mathbf{N}}(t).\mathbf{T}(t) = -\kappa_s(t)$$

$$\mathbf{N}(t).\mathbf{N}(t) = 0$$
$$\dot{\mathbf{N}}(t).\mathbf{N}(t) = 0$$

So,

$$\mathbf{N}(t).\mathbf{T}(t) = 0$$

$$(\mathbf{N}(t).\mathbf{T}(t))' = 0$$

$$\dot{\mathbf{N}}(t).\mathbf{T}(t) + \mathbf{N}(t).\dot{\mathbf{T}}(t) = 0$$

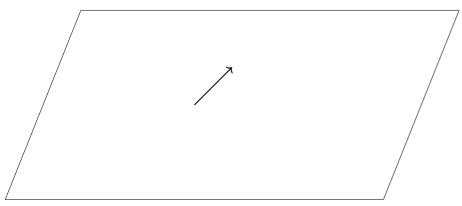
$$\dot{\mathbf{N}}(t).\mathbf{T}(t) + \kappa_s(t)\mathbf{N}(t).\dot{\mathbf{N}}(t) = 0$$

$$\dot{\mathbf{N}}(t).\mathbf{T}(t) + \kappa_s(t) = 0$$

$$\mathbf{N}(t).\mathbf{N}(t) = 0$$
$$\dot{\mathbf{N}}(t).\mathbf{N}(t) = 0$$

 $\dot{\mathbf{N}}(t).\mathbf{T}(t) = -\kappa_s(t)$

So,
$$\dot{\mathbf{N}}(t) = -\kappa(t)\mathbf{T}(t)$$



 $P = \{(x, y, z) \in \mathbb{R}^3 \mid ax + by + cz = d\}$

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= \{(x, y, z) \in \mathbb{R}^3 \cong (a, b, c).(x, y, z) = d\}

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$$\gamma:(\alpha,\beta)$$

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$$\gamma:(\alpha,\beta)\to\mathbb{R}^3$$

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 $\gamma:(\alpha,\beta)\to\mathbb{R}^3$ parametrizes a curve

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 $\gamma:(\alpha,\beta)\to\mathbb{R}^3$ parametrizes a curve that lies on the plane, P,

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$$\mathbf{n} \cdot \gamma(t) = d$$

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 $\gamma:(\alpha,\beta)\to\mathbb{R}^3$ parametrizes a curve that lies on the plane, P, if and only if

$$\mathbf{n} \cdot \gamma(t) = d$$

for all t

$$P = \{(x, y, z) \in \mathbb{R}^3 \mid ax + by + cz = d\}$$

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 $\gamma:(\alpha,\beta)\to\mathbb{R}^3$ parametrizes a curve that lies on the plane, P, if and only if

$$\mathbf{n} \cdot \gamma(t) = d$$

for all $t \in (\alpha, \beta)$.

Alternatively,

$$P = \{(x, y, z) \in \mathbb{R}^3 \mid ax + by + cz = d\}$$

= \{(x, y, z) \in \mathbb{R}^3 \cong (a, b, c).(x, y, z) = d\}
= \{\mathbf{v} \in \mathbb{R}^3 \cong \mathbf{n}.\mathbf{v} = d\}

 $\gamma:(\alpha,\beta)\to\mathbb{R}^3$ parametrizes a curve that lies on the plane, P, if and only if

$$\mathbf{n} \cdot \gamma(t) = d$$

for all $t \in (\alpha, \beta)$.