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*Proof.*

$$\begin{aligned}\dot{\mathbf{T}}(t) &= 0\mathbf{T}(t) + \kappa(t)\mathbf{N}(t) + 0\mathbf{B}(t) \\ \dot{\mathbf{N}}(t) &= -\kappa(t)\mathbf{T}(t) + 0\mathbf{N}(t) + \tau(t)\mathbf{B}(t) \\ \dot{\mathbf{B}}(t) &= 0\mathbf{T}(t) - \tau(t)\mathbf{N}(t) + 0\mathbf{B}(t)\end{aligned}$$

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$$\dot{\mathbf{e}}_1(t) = 0\mathbf{e}_1(t) + \kappa(t)\mathbf{e}_2(t) + 0\mathbf{e}_3(t)$$

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By the theory of differential equations,

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2.  *$p = \gamma(t_0)$*
3.  *$\mathbf{E}_1 = \mathbf{T}(t_0), \mathbf{E}_2 = \mathbf{N}(t_0), \mathbf{E}_3 = \mathbf{B}(t_0)$*

**Theorem.** *Given,*

1. *functions  $\tilde{\kappa} : (\alpha, \beta) \rightarrow \mathbb{R}$ ,  $\tilde{\kappa}(t) > 0$  for all  $t$ , and  $\tilde{\tau} : (\alpha, \beta) \rightarrow \mathbb{R}$*
2.  *$p \in \mathbb{R}^3$ ,  $t_0 \in (\alpha, \beta)$ ,*
3. *an orthonormal basis  $\{\mathbf{E}_1, \mathbf{E}_2, \mathbf{E}_3\}$  based at  $p$ , such that  $\mathbf{E}_3 = \mathbf{E}_1 \times \mathbf{E}_2$ .*

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*Proof.*

$$\dot{\mathbf{e}}_1(t) = 0\mathbf{e}_1(t) + \kappa(t)\mathbf{e}_2(t) + 0\mathbf{e}_3(t)$$

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$$(\mathbf{e}_i \cdot \mathbf{e}_j)' = 0 \text{ (exercise!)}$$

□

**Theorem.** *Given,*

1. *functions  $\tilde{\kappa} : (\alpha, \beta) \rightarrow \mathbb{R}$ ,  $\tilde{\kappa}(t) > 0$  for all  $t$ , and  $\tilde{\tau} : (\alpha, \beta) \rightarrow \mathbb{R}$*
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$$\kappa(t)\mathbf{N}(t) = \dot{\mathbf{T}}(t) = \dot{\mathbf{e}}_1(t) = \kappa(t)\mathbf{e}_2(t)$$

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$$\mathbf{B}(t) \text{ unit}$$

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$\mathbf{B}(t)$  unit and orthogonal

□

**Theorem.** *Given,*

1. *functions  $\tilde{\kappa} : (\alpha, \beta) \rightarrow \mathbb{R}$ ,  $\tilde{\kappa}(t) > 0$  for all  $t$ , and  $\tilde{\tau} : (\alpha, \beta) \rightarrow \mathbb{R}$*
2.  *$p \in \mathbb{R}^3$ ,  $t_0 \in (\alpha, \beta)$ ,*
3. *an orthonormal basis  $\{\mathbf{E}_1, \mathbf{E}_2, \mathbf{E}_3\}$  based at  $p$ , such that  $\mathbf{E}_3 = \mathbf{E}_1 \times \mathbf{E}_2$ .*

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$$\begin{aligned}\dot{\mathbf{e}}_1(t) &= 0\mathbf{e}_1(t) + \kappa(t)\mathbf{e}_2(t) + 0\mathbf{e}_3(t) \\ \dot{\mathbf{e}}_2(t) &= -\kappa(t)\mathbf{e}_1(t) + 0\mathbf{e}_2(t) + \tau(t)\mathbf{e}_3(t) \\ \dot{\mathbf{e}}_3(t) &= 0\mathbf{e}_1(t) - \tau(t)\mathbf{e}_2(t) + 0\mathbf{e}_3(t)\end{aligned}$$

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$\mathbf{e}_3(t)$  unit

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products...

