

# Microprocessor Applications I

Supplementary Lecture 02

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# Lecture Overview

1. Present problem somewhat similar to Lab 2
  - Discuss problem and example data
2. Solve problem
  - Pose questions
  - Answer questions
  - Explain pseudocode/flowchart for design
  - Briefly explore Atmel datasheets
  - Write code (not everything will be given)
  - Discuss more concepts
  - Demo completed program
3. Answer any questions outstanding

**Please note:** Due to time allotment, it is quite possible that not all planned points will be discussed during this lecture.

# Problem

You must create and compile an assembly program on your Atmel XMEGA128A1U microprocessor to continuously blink the LEDs on your *Switch & LED Backpack* at a rate of 5Hz while tactile switch S1 is held down. In other words, when tactile switch S1 is not held down, your LEDs will remain OFF.

# Questions To First Pose

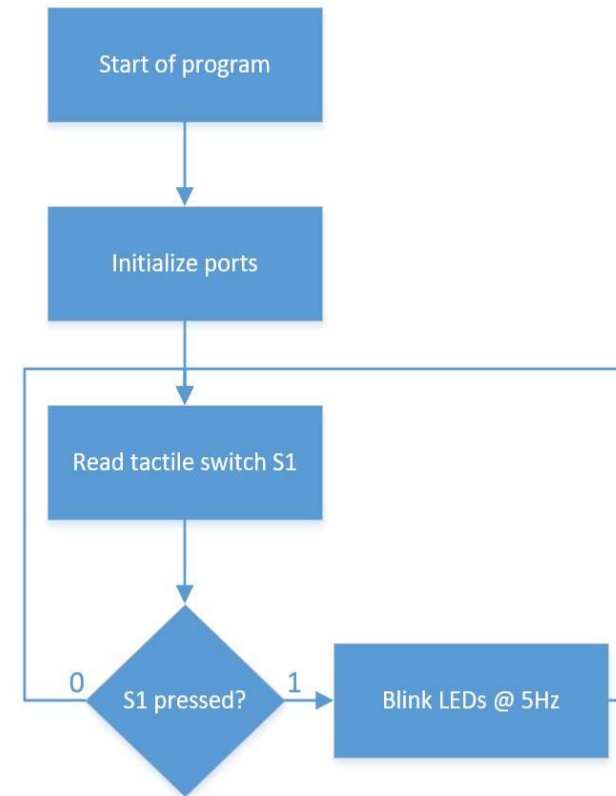
1. Where are the switches and LEDs?
2. What are the switches/LEDs connected to on the microprocessor?
3. What are I/O ports?

# I/O Ports

- In the context of this course, an **I/O port** can simply be related to a collection of physical pins that serve as either “inputs” or “outputs”.
- **The motivation for pins within an I/O port is to allow communication between the microprocessor and internal/external hardware**
- These pins hold an electrical voltage level, either a “high” voltage (also known as ‘1’), or a “low” voltage (also known as ‘0’).
- In our processor, there are many I/O ports, e.g., PORTA, PORTB, PORTC, ...
- The current “value” of each pin within a port (either ‘0’ or ‘1’) is stored within a specific bit of a predefined XMEGA *data* memory location, specified in the include file (see *PORTX\_IN*).
- There exist registers in the processor that allow you to access information about a port or configure a port, e.g., there exists a register that allows you to configure a port’s pins to serve as inputs or outputs (see *PORTX\_DIR*, *PORTX\_DIRSET*, *PORTX\_DIRCLR*), etc.

# Pseudocode & Flowchart

```
1 ; assembler directives
2 ; define necessary/useful constants
3
4 ; start of program
5 MAIN:
6
7 ; initialize necessary ports for switches/LEDs
8
9 ; start of infinite loop to read tactile switch S1
10 LOOP:
11
12 ; read tactile switch S1
13
14 ; if NOT pressed, jump back to loop
15
16 ; if pressed, blink LEDs at a rate of 5Hz
17
18 ; turn ON LEDs
19 ; delay 100ms (first half of period)
20 ; turn OFF LEDs
21 ; delay 100ms (second half of period)
22
23 ; jump back to LOOP to check if tactile switch is still pressed
24
25 ; end of program (never reached)
```



**Figure 1:** Pseudocode (left) and flowchart (right) for given problem

# Exploring The Atmel Datasheets

- See Dr. Schwartz' website: <https://mil.ufl.edu/3744/>
  - Navigate to the **Atmel AVR XMEGA** section of the *Software/Docs* webpage

# Time To Code

Doin' it live





Questions?