

MATH 3311, FALL 2025: LECTURE 31, NOVEMBER 12

Video: <https://youtu.be/q05B0v3q2cA>

Finitely generated abelian groups

Definition 1. Suppose that G is a group and $X \subset G$ is a subset. The **subgroup generated by X** , denoted $\langle X \rangle \leq G$ is the smallest subgroup of G containing X .

Remark 1. This notion makes sense, since the intersection of any collection of subgroups containing X is once again a subgroup containing X , so $\langle X \rangle$ can be taken to be the intersection of all subgroups containing X .

Remark 2. More concretely, we have

$$\langle X \rangle = \{x_1^{\pm 1} x_2^{\pm 2} \cdots x_m^{\pm m} : x_i \in X, m \geq 1\}.$$

That is, we take all possible products of elements of X as well as of their inverses.

Remark 3. If $X = \{x\}$ is a singleton, then $\langle X \rangle = \langle x \rangle$ is just the cyclic subgroup generated by the element x .

Definition 2. G is **finitely generated** if there is a finite subset $X \subset G$ such that $\langle X \rangle = G$. In other words, there is a finite set of symbols such that every element of G can be expressed as a product of such symbols.

We will be concerned with the problem of *classifying* finitely generated abelian groups. That is, we want a complete, non-redundant list of such groups up to isomorphism. But before we enter the abelian realm, let us look at the following non-abelian example.

Example 1. Take

$$\mathrm{SL}_2(\mathbb{Z}) = \left\{ \begin{pmatrix} a & b \\ c & d \end{pmatrix} : a, b, c, d \in \mathbb{Z}, ad - bc = 1 \right\}$$

This is actually a *group* under matrix multiplication: The condition on the determinant tells us that we can write the inverse as

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix}^{-1} = \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$$

Elements of $\mathrm{SL}_2(\mathbb{Z})$ can be obtained as follows. Note that the condition $ad - bc = 1$ shows that the pairs a, b, a, c, c, d and b, d are all relatively prime. In other words, the entries of each row and column of the matrix have to be relatively prime to each other.

Conversely, if a, b are relatively prime, then by Bezout we can find c, d such that $ad - bc = 1$ (why?), and so we can find a matrix in $\mathrm{SL}_2(\mathbb{Z})$ with the first row given by (a, b) . For example, we have

$$\begin{pmatrix} 2 & 3 \\ -1 & -1 \end{pmatrix} \in \mathrm{SL}_2(\mathbb{Z}).$$

In particular, $\mathrm{SL}_2(\mathbb{Z})$ is an *infinite* group.

In any case, two matrices we can find in here are

$$T = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}; S = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

Note that we have $T^m = \begin{pmatrix} 1 & m \\ 0 & 1 \end{pmatrix}$ for any $m \in \mathbb{Z}$ and we have $S^2 = -I_2$ is the negative identity matrix. So T does not have finite order while S has order 4.

A non-trivial result now is that $\mathrm{SL}_2(\mathbb{Z}) = \langle \{S, T\} \rangle$: So this is a *non-abelian, finitely generated infinite* group.

Let us now move firmly into the abelian world. The starting point for our classification is the following observation.

Definition 3. For $1 \leq i \leq m$, the i -th **standard basis vector** $\vec{e}_i \in \mathbb{Z}^m$ is the element with 1 as its i -th coordinate and 0s everywhere else. For example, in \mathbb{Z}^3 , we have

$$\vec{e}_1 = (1, 0, 0), \vec{e}_2 = (0, 1, 0), \vec{e}_3 = (0, 0, 1).$$

Remark 4. The element $(a_1, \dots, a_m) \in \mathbb{Z}^m$ can be written (uniquely) as a linear combination $\sum_{i=1}^m a_i \vec{e}_i$.

Observation 1. Suppose that G is an abelian group and $X = \{x_1, \dots, x_m\} \subset G$ is a finite subset of elements. Then there is a unique homomorphism

$$f : \mathbb{Z}^m \rightarrow G$$

such that $f(\vec{e}_i) = x_i$ for $i = 1, \dots, m$.

Proof. The point is that, because of the homomorphism property, given this description for standard basis vectors, we must have

$$f((a_1, \dots, a_m)) = f\left(\sum_{i=1}^m a_i \vec{e}_i\right) = f(a_1 \vec{e}_1 + \dots + a_m \vec{e}_m) = f(a_1 \vec{e}_1)f(a_2 \vec{e}_2) \cdots f(a_m \vec{e}_m) = x_1^{a_1} \cdots x_m^{a_m}.$$

Here, in the third and fourth equalities, we have used the homomorphism property of f : Note that $f(a_i \vec{e}_i) = f(\vec{e}_i)^{a_i}$, because we are using multiplicative notation for the operation in G .

So the only possibility for f as a function is $f((a_1, \dots, a_m)) = x_1^{a_1} \cdots x_m^{a_m}$. We need to know that this is a *homomorphism*. For this, note:

$$\begin{aligned} f((a_1, \dots, a_m)) \cdot f((b_1, \dots, b_m)) &= (x_1^{a_1} \cdots x_m^{a_m})(x_1^{b_1} \cdots x_m^{b_m}) \\ &= x_1^{a_1+b_1} \cdots x_m^{a_m+b_m} \\ &= f((a_1 + b_1, \dots, a_m + b_m)) \\ &= f((a_1, \dots, a_m) + (b_1, \dots, b_m)). \end{aligned}$$

Here, in the second line, we have used the *abelianness* of G to collect all the powers of each x_i together. \square

Remark 5. We didn't actually use the full strength of abelianness of G . You just needed the elements x_1, \dots, x_m to commute with each other. So we can say that there is a canonical *bijection*

$$\text{Hom}(\mathbb{Z}^m, G) \xrightarrow[\simeq]{f \mapsto (f(\vec{e}_1), \dots, f(\vec{e}_m))} \{\text{m-tuples of commuting elements in } G\}.$$

Observation 2. If f is as in Observation 1, then we have

$$\text{im } f = \langle X \rangle \leq G.$$

Proof. This follows from the description of f in the proof of Observation 1, combined with Remark 2. \square

Observation 3. If f is as in Observation 1, then f is surjective if and only if $\langle X \rangle = G$.

Putting this all together, we get:

Proposition 1. Suppose that G is an abelian group. Then the following are equivalent:

- (1) G is finitely generated.
- (2) There exists $m \geq 1$ and a surjective homomorphism $f : \mathbb{Z}^m \rightarrow G$.
- (3) There exists $m \geq 1$ and a subgroup $H \trianglelefteq \mathbb{Z}^m$ such that we have an isomorphism

$$\mathbb{Z}^m / H \xrightarrow{\cong} G.$$

Proof. Observations 1-3 tell us that (1) \Leftrightarrow (2), and the equivalence (2) \Leftrightarrow (3) is just the first isomorphism theorem. \square