

# Prometheus mirror quick guide

## The first step is to update the system

sudo apt-get update

## The second step, download and compile

### Download prometheus\_px4:

Open a terminal (ctrl+alt+t) and execute the following download command:

git clone https://gitee.com/amovlab/prometheus\_px4.git

## Compile prometheus\_px4:

Enter the prometheus\_px4 path, update the submodule first, and then compile the software-in-the-loop code, the instructions are as follows:

cd prometheus\_px4/

make submodulesclean update the submodules for a little longer (5 minutes) (or use git submodules update --init --recursive)

make amovlab\_sitl\_default (compilation instruction)

#### Download the Prometheus code:

Open a new terminal (ctrl+alt+t), the download instruction is as follows:

git clone https://gitee.com/amovlab/Prometheus.git

1 www.amovlab.com 邮箱: service@amovauto.com 电话/传真: 028-87872048



### Compile Prometheus code

Enter the Prometheus code directory and execute the compilation instructions as follows:

cd Prometheus/

./compile\_all.sh

If the downloading and compiling are executed normally, so far, congratulations, the downloading and compiling are executed very well, and all open terminals can be closed.

## The third step, test whether the system is normal

### Test prometheus\_px4

Open a new terminal, enter the prometheus\_px4 path, run and start the gazebo simulation, the instructions are as follows:

roscd px4/

make amovlab\_sitl gazebo\_p450

If gazebo is successfully opened and the p450 model is loaded, it means it is normal.

Use **ctrl+c** to close the terminal.

Then open a new terminal, use roslaunch to start the gazebo+mavros+prometheus\_px4 simulation, and run the command as under:

2 www.amovlab.com 邮箱: service@amovauto.com 电话/传真: 028-87872048



roslaunch px4 mavros\_posix\_sitl.launch

If gazebo is successfully opened and the p450 model is loaded, it means it is normal.

Use **ctrl+c** to close the terminal.

Prometheus can be tested!

#### **Test Prometheus**

The normal operation of prometheus depends on the normal operation of prometheus\_px4. Open a new terminal and execute the following instructions:

roslaunch prometheus\_gazebo sitl\_control.launch

After waiting for **gazebo** and **rviz** to start normally, if you select 0 in the terminal, enter the terminal command control, and follow the terminal command prompt, the simulation of the Prometheus system is ready.

If there are no problems, congratulations, you have mastered the quick start of prometheus mirroring. Learn more about the functions.

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