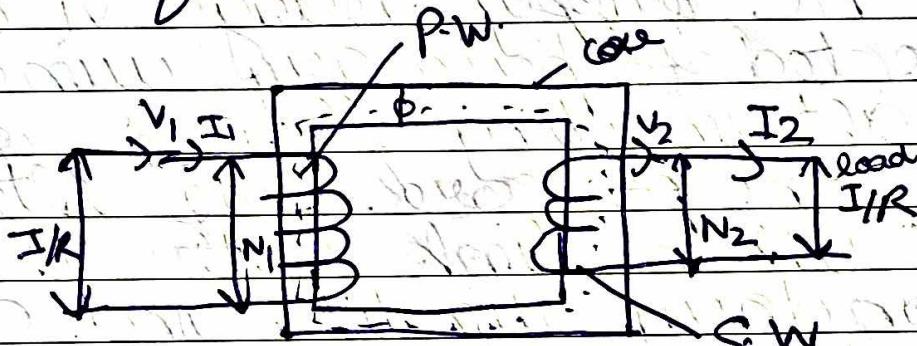


Unit - 2

Magnetic Circuits

Transformer



$$V = V_m \sin \omega t$$

It is a static device which transfers AC electric power from one circuit to the other at the same frequency but with change in voltage level.

If $V_2 > V_1$, the transformer is step up transformer.

If $V_2 < V_1$, the transformer is step down transformer.

Working Principle of Transformer:

The basic principle is Electromagnetic induction whenever a conductor is placed around a magnetic field and e.m.f is induced in it.

When AC supply voltage V_1 is connected to primary winding and alternating flux is set up in the core. This alternating flux links with the secondary winding and e.m.f is induced which is known as mutually induced e.m.f. The dirⁿ of this induced e.m.f is opposite to that of applied voltage given V_1 .

Although there is no electrical connection b/w primary and secondary winding but still the power is transferred from one side to the other side through mutual flux.

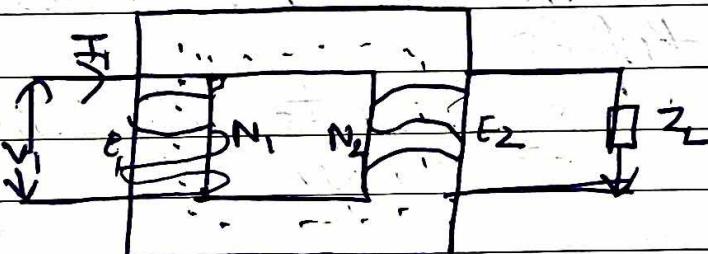
The induced e.m.f in the primary and secondary winding depends on the rate of change of flux.

$$\frac{N d\Phi}{dt}$$

The rate of change of flux is same for both primary and secondary therefore the induced e.m.f. is proportional to no. of turns in primary winding and same for the other winding.

$$E_1 \propto N_1$$

Ideal Transformer:



→ In ideal transformer there are no ohmic losses (I^2R).

→ No winding resistance → The primary and secondary winding have zero resistance which means there is no ohmic power loss.

→ No magnetic leakage → There is no leakage flux and all the flux set up is confined to the

Core and links both the winding.

- No iron load (~~core~~ hysteresis & eddy current)
- zero magnetising Current.

Transformer losses

→ Iron loss

Also known as fixed losses.
They are mainly caused by alternating flux in the core and are of two types

- Hysteresis
- Eddy

Hysteresis → The core of the transformer is subjected to an alternating magnetising force and of each cycle of emf a hysteresis loop is traced down.

$$P_H = \eta' (B_{max})^2 f V$$

Where, f = Hysteresis frequency
 η' = Hysteresis constant
 V = Volume of core

α lies b/w 1.5 to 2.5.

B_{max} = Maximum flux quantity

Eddy Current Loss \rightarrow The magnetic circuit is made up of iron and the flux setup in the core is variable due to which current will be induced by the induction in the core itself.

$$P_e = K_e (B_{max})^2 f^2 t^2 V$$

where, t = thickness of material.

K_e = eddy current constant

Both these losses are known as iron losses or constant losses and mainly occur during open circuit test of the transformer.

\rightarrow Copper or Variable losses:

These losses occur due to the ohmic resistance of the transformer winding.

$$C\text{-loss} = I_1^2 R_1 + I_2^2 R_2$$

Transformer efficiency:

Actual Transformer/ Equivalent Ckt of Transformer:



$$\cancel{Z_1 = R_1 + jX_1}$$

$$\cancel{Z_2 = R_2 + jX_2}$$

An actual Transformer has primary and secondary resistances (R_1 and R_2) and leakage reactances (X_1 and X_2) and iron and copper losses. Therefore primary impedance is given as

$$\boxed{Z_1 = R_1 + jX_1} \quad \textcircled{1}$$

$$\cancel{\boxed{Z_2 = R_2 + jX_2}}$$

The applied voltage is V_1 , and the resistance, and the leakage reactance of primary winding is responsible for the voltage drop.

$$\vec{V}_1 = \vec{E}_1 + \vec{I}_1 Z_1 \quad \textcircled{2}$$

Therefore secondary impedance is given as

$$Z_2 = R_2 + iX_2 \quad \text{--- (3)}$$

The voltage drop for the secondary winding is

$$V_2 = E_2 - I_2 Z_2 \quad \text{--- (4)}$$

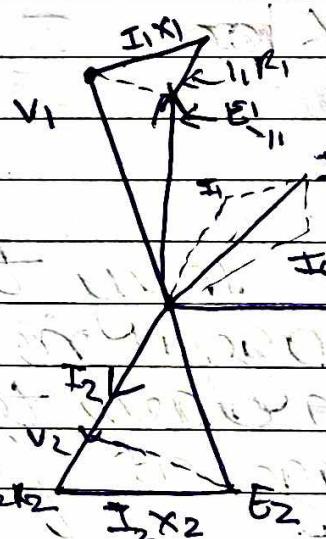
Put (4) in (2)

$$V_1 = E_1 + I_1 (R_1 + iX_1)$$

$$V_2 = E_2$$

Put (3) in (4)

$$V_2 = E_2 - I_2 (R_2 - iX_2)$$



Voltage Regulation:

When a transformer is loaded with a const. dtm supply voltage the terminal voltage changes depend upon the load and its power factor.

The algebraic difference b/w the no load and full load terminal voltage is measured in terms of voltage regulation.

At a constant supply voltage the change in secondary terminal voltage from no load to full load with respect to no load voltage is called voltage regulation of the transformer.

$$\frac{E_2 - V_2}{E_2} \times 100$$

where,

E_2 = secondary terminal voltage at no load

V_2 = secondary terminal voltage at full load.

Ordinary Transformer

It is a transformer with only one winding bound wound on a laminated core, a part of this winding is common to both primary and secondary side. In an ordinary transformer the primary and secondary winding are ~~not~~ electrically insulated with each other but connected magnetically or whereas in a ~~s~~ ordinary transformer the primary and secondary connected electrically as well as magnetically.

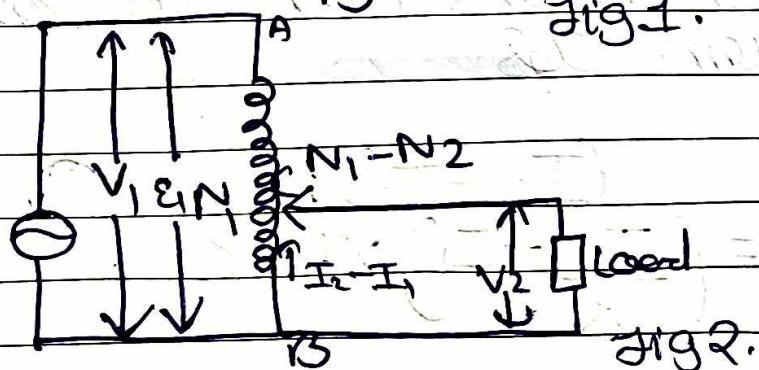
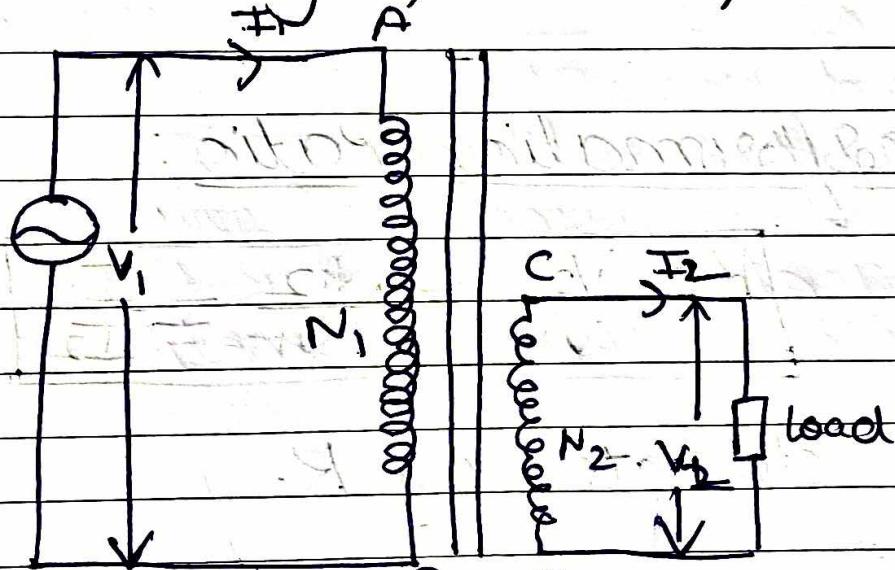


Fig 2. shows the primary winding AB from which a tapping at point C is taken such that CB act as a secondary winding the supply voltage is applied across AB and the load is connected across CB.

When AC voltage V_1 is applied across AB and alternating flux is set up in the core which induce an emf E_1 in the winding AB the part of this e.m.f is taken in the secondary side.

Transformation Ratio :

$$K = \frac{V_2}{V_1} = \frac{N_2}{N_1} = \frac{I_1}{I_2}$$

It is denoted by K.

Ammphere turn due to section BC is given as

$$(I_2 - I_1) N_2 = 1$$

$$= \left(\frac{I_1 - I_1}{K} \right) \times N_1 K$$

$$= I_1 N_1 (1 - K) - \textcircled{2}$$

Amphere Turn due to section ~~AB~~
AC is given as

$$= I_1 (N_1 - N_2) - \textcircled{3}$$

$$= I_1 (N_1 - N_1 K)$$

$$= I_1 N_1 (1 - K) - \textcircled{4}$$

Eqs $\textcircled{2}$ & $\textcircled{4}$ show that the
amphere turn due to section
BC and AC balance each other
and define the characteristics of
transformer action.

Use of ordinary Transformer:

- It is used to give a small boost to a distribution cable to correct the voltage drop.
- It is used as a regulating transformer.
- It mainly gives 5% to 60 percent of aising V_o rise in voltage to the induction motor while starting.

Limitations:

→ It is advisable not to use an auto transformer for inter connecting high voltage and low voltage system therefore it is only limited to the places where slight variation of output voltage from the input voltage is required.

→ BH Curve (Magnetic Hysteresis Curve):

When a magnetic material is magnetised in one direction and then in the other direction than the flux density (B) in the material lags behind the applied magnetising force (H).

The phenomenon of flux density (B) lagging behind the magnetising force (H) in the magnetic material is called magnetic hysteresis.

