# Names, Bindings, Type Checking and Scopes

BBM 301 – Programming Languages

# **Today**

- Introduction
- Names
- Variables
- The Concept of Binding
- Type Inference
- Scope
- Scope and Lifetime
- Referencing Environments
- Named Constants

#### Introduction

- Imperative programming languages are abstractions of the underlying von Neumann computer architecture.
- Architecture's two main components are:
  - Memory stores both instructions and data
  - Processor provides operations for modifying the contents of the memory

#### **Abstraction**

- Abstractions for memory are variables
- Sometimes abstraction is very close to characteristics of cells.
  - e.g. Integer represented directly in one or more bytes of a memory
- In other cases, abstraction is far from the organization of memory.
  - e.g. Three dimensional array.
  - requires software mapping function to support the abstraction

#### **Names**

- Variables, subprograms, labels, user defined types, formal parameters all have names.
- Design issues for names:
  - What is the maximum length of a name?
  - Are names case sensitive or not?
  - Are special words reserved words or keywords?

#### Length

- If too short, they cannot be connotative
- Language examples:
  - Earliest languages : single character
  - FORTRAN 95: maximum of 31 characters
  - C99: no limit but only the first 63 are significant; also, external names are limited to a maximum of 31 characters
  - C#, Ada, and Java: no limit, and all are significant
  - C++: no limit, but implementers often impose one

#### **Name Forms**

- Names in most PL have the same form:
  - A letter followed by a string consisting of letters, digits, and underscore characters
  - In some, they use special characters before a variable's name
- Today "camel" notation is more popular for C-based languages (e.g. myStack)
- In early versions of Fortran embedded spaces were ignored. e.g. following two names are equivalent

Sum Of Salaries SumOfSalaries

#### Special characters

- PHP: all variable names must begin with dollar signs
- Perl: all variable names begin with special characters (\$, @, %), which specify the variable's type
- Ruby: variable names that begin with @ are instance variables; those that begin with @@ are class variables

#### Case sensitivity

- In many languages (e.g. C-based languages) uppercase and lowercase letters in names are distinct
  - e.g. rose, ROSE, Rose
- Disadvantage: readability (names that look alike are different)
  - Names in the C-based languages are case sensitive
  - Names in others are not
  - Worse in C++, Java, and C# because predefined names are mixed case (e.g. IndexOutOfBoundsException)
- Also bad for writability since programmer has to remember the correct cases

#### Special words

- An aid to readability; used to delimit or separate statement clauses
  - A keyword is a word that is special only in certain contexts, e.g., in Fortran

Real VarName (Real is a data type followed with a name, therefore Real is a keyword)

Real = 3.4 (Real is a variable)

INTEGER REAL REAL INTEGER

This is allowed but not readable.

#### Special words

- A reserved word is a special word that cannot be used as a user-defined name
  - Can't define for or while as function or variable names.
  - Good design choice
  - Potential problem with reserved words: If there are too many, many collisions occur (e.g., COBOL has 300 reserved words!)

## **Special Words**

- Predefined names: have predefined meanings, but can be redefined by the user
- Between special words and user-defined names.
- For example, built-in data type names in Pascal, such as INTEGER, normal input/output subprogram names, such as readln, writeln, are predefined.
- In Ada, Integer and Float are predefined, and they can be redefined by any Ada program.

#### **Variables**

- A variable is an abstraction of a memory cell
- It is not just a name for a memory location
- A variable is characterized by a collection of attributes
  - Name
  - Address
  - Value
  - Type
  - Scope
  - Lifetime

#### Variable Attributes – Name

- Most variables are named (often referred as identifiers).
- Although nameless variables do exist (e.g. pointed variables).

#### Variable Attributes – Address

- Address the memory address with which it is associated
- It is possible that the same name refer to different locations
- in different parts of a program:
  - A program can have two subprograms sub1 and sub2 each of defines a local variable that use the same name, e.g. sum
- in different times:
  - For a variable declared in a recursive procedure, in different steps of recursion it refers to different locations.
- Address of a variable is sometimes called I-value, because address is required when a variable appears on the left side of an assignment.

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#### **Aliases**

- Multiple identifiers reference the same address more than one variable are used to access the same memory location
- Such identifier names are called aliases.
- Aliases are created via pointers, reference variables, C and C++ unions
- Aliases are harmful to readability (program readers must remember all of them)

## Variable Attributes – Type

- Type determines
  - the range of values the variable can take, and
  - the set of operators that are defined for values of this type.
  - in the case of floating point, type also determines the precision
- For example int type in Java specifies a range of
  - -2147483648 to 2147483647

#### Variable Attributes – Value

- The contents of the location with which the variable is associated
- e.g. *I\_value* ← *r\_value* (assignment operation)
  - The I-value of a variable is its address
  - The r-value of a variable is its value

$$X = 5$$

## **Abstract memory cell**

- Abstract memory cell the physical cell or collection of cells associated with a variable
  - Physical cells are 8 bits
  - This is too small for most program variables

# The concept of Binding

- A binding is association between
  - entity ↔ attribute (such as between a variable and its type or value), or
  - operation ← symbol

- Binding time is the time at which a binding takes place.
  - important in the semantics of PLs

# **Possible Binding Times**

- Language design time bind operator symbols to operations
  - \* is bound to the multiplication operation,
  - pi=3.14159 in most PL's.
- Language implementation time
  - bind floating point type to a representation
  - int in C is bound to a range of possible values
- Compile time -- bind a variable to a type in C or Java

# **Possible Binding Times (continued)**

#### Link time

 A call to the library subprogram is bound to the subprogram code.

#### Load time

- A variable is bound to a specific memory location.
- e.g. bind a C or C++ static variable to a memory cell

#### Runtime

- A variable is bound to a value through an assignment statement.
- A local variable of a Pascal procedure is bound to a memory location.

# **Binding Times**

#### Example:

```
- count + 5
```

- The type of count is bound at compile time
- The set of possible values of count is bound at compiler design time
- The meaning of the operator symbol + is bound at compile time, when the types of its operands have been determined
- The internal representation of the literal 5 is bound at compiler design time
- The value of count is bound at execution times with this statement

## **Static and Dynamic Binding**

- A binding is static if it first occurs before run time and remains unchanged throughout program execution.
- A binding is dynamic if it first occurs during execution or can change during execution of the program

## **Type Bindings**

 Before a variable can be referenced in a program, it must be bound to a data type.

- Two important aspects
  - How is a type specified?
  - When does the binding takes place?

 If static, the type may be specified by either an explicit or an implicit declaration

# Static Type Binding – Explicit/Implicit Declarations

- explicit declaration (by statement)
  - A statement in a program that lists variable names and specifies that they are a particular type
- implicit declaration (by first appearance)
  - Means of associating variables with types through default conventions, rather than declaration statements. First appearance of a variable name in a program constitutes its implicit declaration
- Both creates static binding to types

# **Static Type Binding**

- Most current PLs require explicit declarations of all variables
  - Exceptions: Perl, Javascript, ML
- Early languages (Fortran, BASIC) have implicit declarations
  - e.g. In Fortran, if not explicitly declared, an identifier starting with I,J,K,L,M,N are implicitly declared to integer, otherwise to real type
- Implicit declarations are not good for reliability and writability because misspelled identifier names cannot be detected by the compiler
  - e.g. In Fortran variables that are accidentally left undeclared are given default types, and leads to errors that are difficult to diagnose

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# **Static Type Binding**

 Some problems of implicit declarations can be avoided by requiring names for specific types to begin with a particular special characters

Example: In Perl

- \$apple : scalar

-@apple :array

-%apple :hash

# **Dynamic Type Binding**

- Type of a variable is not specified by a declaration statement, nor it can be determined by the spelling of its name (JavaScript, Python, Ruby, PHP, and C# (limited))
- Type is bound when it is assigned a value by an assignment statement.
- Advantage: Allows programming flexibility.
   example languages: Javascript and PHP
- e.g. In JavaScript
  - -list = [10.2 5.1 0.0]
    - list is a single dimensioned array of length 3.
  - -list = 73
    - list is a simple integer.

#### **Dynamic Type Binding – Disadvantages**

- 1. Less reliable: compiler cannot check and enforce types.
- Example: Suppose I and X are integer variables, and Y is a floating-point.
- The correct statement is

$$I := X$$

But by a typing error

$$I := Y$$

- Is typed. In a dynamic type binding language, this error cannot be detected by the compiler.
  - I is changed to float during execution.
- The value of I becomes erroneous.

## **Dynamic Type Binding – Disadvantages**

#### 2. Cost:

- Type checking must be done at run-time.
- Every variable must have a descriptor to maintain current type.
- The correct code for evaluating an expression must be determined during execution.
- Languages that use dynamic type bindings are usually implemented as interpreters (LISP is such a language).

# **Type Inference**

- ML is a PL that supports both functional and imperative programming
- In ML, the types of most expressions can be determined without requiring the programmer to specify the types of the variables
- General syntax of ML

```
fun function_name(formal parameters) =
expression;
```

- The type of an expression and a variable can be determined by the type of a constant in the expression
- Examples

```
fun circum (r) = 3.14 *r*r; (circum is real)
fun times10 (x) = 10*x; (times10 is integer)
```

[Note: fun is for function declaration.]

## **Type Inference**

```
fun square (x) = x*x;
```

- Determines the type by the definition of \* operator
- Default is int. if called with square (2.75) it would cause an error
- ML does not coerce real to int
- It could be rewritten as:

```
fun square (x: real) = x*x;
fun square (x):real = x*x;
fun square (x) = (x:real)*x;
fun square (x) = x*(x:real);
```

- In ML, there is no overloading, so only one of the above can coexist
- Purely functional languages Miranda and Haskell uses Type Inference.

# **Storage Bindings and Lifetime**

- Allocation: process of taking the memory cell to which a variable is bound from a pool of available memory
- Deallocation: process of placing the memory cell that has been unbound from a variable back into the pool of available memory
- Lifetime of a variable: Time during the variable is bound to a specific memory location
- According to their lifetimes, variables can be separated into four categories:
  - static,
  - stack-dynamic,
  - explicit heap-dynamic,
  - implicit dynamic.

#### **Static Variables**

- Static variables are bound to memory cells before execution begins, and remains bound to the same memory cells until execution terminates.
- Applications: globally accessible variables, to make some variables of subprograms to retain values between separate execution of the subprogram
- Such variables are history sensitive.
- Advantage: Efficiency. Direct addressing (no run-time overhead for allocation and deallocation).
- Disadvantage: Reduced flexibility (no recursion).
- If a PL has only static variables, it cannot support recursion.
- Examples:
  - All variables in FORTRAN I, II, and IV
  - Static variables in C, C++ and Java

## **Stack-Dynamic Variables**

- Storage binding: when declaration statement is elaborated (in run-time).
- Type binding: static.
- The local variables get their type binding statically at compile time, but their storage binding takes place when that procedure is called. Storage is deallocated when the procedure returns.
- Local variables in C functions.

# **Stack-Dynamic Variables**

- Advantages:
  - Dynamic storage allocation is needed for recursion. Each subprogram can have its own copy of the variables
  - Same memory cells can be used for different variables (efficiency)
- Disadvantages: Runtime overhead for allocation and deallocation
- In C and C++, local variables are, by default, stackdynamic, but can be made static through static qualifier.

```
foo ()
{
static int x;
...
}
```

# **Explicit Heap-Dynamic Variables**

- Nameless variables
- storage allocated/deallocated by explicit run-time instructions
- can be referenced only through pointer variables
- e.g. dynamic objects in C++ (via new and delete),
   all objects in Java
- types can be determined at run-time
- storage is allocated when created explicitly

### **Explicit Heap-Dynamic Variables**

### Example:

- In C++

### Advantages:

Required for dynamic structures (e.g., linked lists, trees)

### Disadvantages:

 Difficult to use correctly, costly to refer, allocate, deallocate.

## **Implicit Heap-Dynamic Variables**

- Storage and type bindings are done when they are assigned values.
- Advantages:
  - Highest degree of flexibility (generic code)
- Disadvantages:
  - Runtime overhead for allocation/deallocation and maintaining all the attributes which can include array subscript types and ranges.
  - Loss of error detection by compiler
- Examples: All variables in APL; all strings and arrays in Perl, JavaScript, and PHP.

# Variable Attributes – Scope

- Scope of a variable is the range of statements in which the variable is visible.
- A variable is visible in a statement if it can be referenced in that statement.
- The scope rules of a language determine how references to variables declared outside the currently executing subprogram or block are associated with variables

# Variable Attributes – Scope

- The local variables of a program unit are those that are declared in that unit
- The nonlocal variables of a program unit are those that are visible in the unit but not declared there
- Global variables are a special category of nonlocal variables

- Scope of variables can be determined statically
  - by looking at the program
  - prior to execution
- First defined in ALGOL 60.

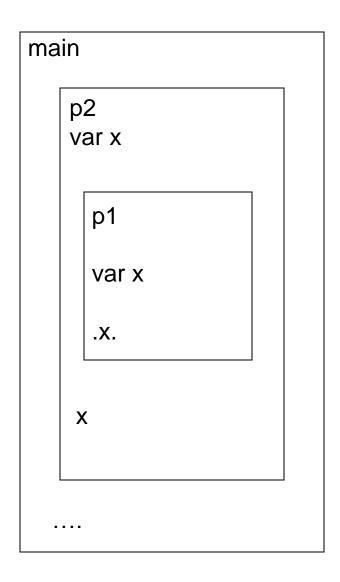
- Based on program text
- To connect a name reference to a variable, you (or the compiler) must find the declaration

### Search process:

- search declarations,
  - first locally,
  - then in increasingly larger enclosing scopes,
  - until one is found for the given name

- In all static-scoped languages (except C), procedures are nested inside the main program.
- Some languages also allow nested subprograms, which create nested static scopes
  - Ada, JavaScript, Common LISP, Scheme, Fortran
     2003+, F#, and Python do
  - C based languages do not
- In this case all procedures and the main unit create their scopes.

- Enclosing static scopes (to a specific scope) are called its static ancestors
- the nearest static ancestor is called a static parent



- main is the static parent
   of p2 and p1.
- p2 is the static parent of p1

```
Procedure Big is
  x : integer
  procedure sub1 is
    begin - of
      sub1
     .... X ....
     end - of sub1
  procedure sub2 is
    x: integer;
    begin - of
      sub2
     end - of sub2
  begin - of big
  end - of big
```

- The reference to variable x in sub1 is to the x declared in procedure Big
- x in Big is hidden from sub2 because there is another x in sub2

```
function big() {
       function sub1() {
       var x = 7;
       sub2();
       function sub2() {
       var y = x;
var x = 3;
sub1();
```

- In some languages that use static scoping, regardless of whether nested subprograms are allowed, some variable declarations can be hidden from some other code segments
- e.g. In C++

```
void sub1() {
int count;
...
while (...) {
int count;
...
}
```

- The reference to count in while loop is local
- count of sub1 () is hidden from the code inside the while loop

- Variables can be hidden from a unit by having a "closer" variable with the same name
- C++ and Ada allow access to these "hidden" variables
  - In Ada: unit.name
  - In C++: class name::name

- Some languages allow new static scopes to be defined without a name.
- It allows a section of code its own local variables whose scope is minimized.
- Such a section of code is called a block
- The variables are typically stack dynamic so they have their storage allocated when the section is entered and deallocated when the section is exited
- Blocks are first introduced in Algol 60

### In Ada

```
declare TEMP: integer;
begin
TEMP := FIRST;
FIRST := SECOND; Block
SECOND := TEMP;
end;
```

### C and C++ allow blocks.

```
int first, second;
first = 3; second = 5;
{ int temp;
     temp = first;
     first = second;
     second = temp;
```

temp is undefined here.

- C++ allows variable definitions to appear anywhere in functions. The scope is from the definition statement to the end of the function
- In C, all data declarations (except the ones for blocks) must appear at the beginning of the function
- for statements in C++, Java and C# allow variable definitions in their initialization expression. The scope is restricted to the for construct

## **Dynamic Scope**

- APL, SNOBOL4, early dialects of LISP use dynamic scoping.
- COMMON LISP and Perl also allows dynamic scope but also uses static scoping
- In dynamic scoping
  - scope is based on the calling sequence of subprograms
  - not on the spatial relationships
  - scope is determined at run-time.

## **Dynamic Scope**

```
Procedure Big is
   x : integer
   procedure subl is
       begin - of sub1
       .... x ....
                       (1)
       end - of sub1
   procedure sub2 is
       x: integer;
       begin - of sub2
                        (2)
       . . . .
       end - of sub2
   begin - of big
```

end - of big

- When the search of a local declaration fails, the declarations of the dynamic parent is searched
- Dynamic parent is the calling procedure

Big -> sub2 -> sub1

- Big calls sub2
- sub2 calls sub1
- Dynamic parent of sub1 is sub2, sub2 is Big

	Visible	Hidden
1	x (sub2)	x (Big)
2	x (sub2)	x (Big)

# **Dynamic Scope**

```
procedure big
                                        To determine the correct
        var x. ←integer;
                                        meaning of a variable, first
                            static
dynamic
                                        look at the local declarations.
        procedure sub1;
                            scoping
scoping
(called form begin
                                        For
                                              static
                                                       or dynamic
                                        scoping, the local variables
                            dynamic
                                        are the same.
                            scoping
        end; {sub1}
                            (called
                                        In dynamic scoping, look at
                            form sub1)
       procedure sub2;
                                        the dynamic parent (calling
            var x: integer;
                                        unit).
       begin
                                        In static scoping, look at the
                                        static
                                                parent (unit
            sub1 :
                                                                 that
                                        declares, encloses).
        end;
   begin
                         Case1 (call of sub2 in big)
                                                P1- x of sub2
                         big->sub2->sub1
        sub2;
        sub1;
                         Case2: (call of sub1 in big)
   end;
                         big -> sub1
                                                   P1- x of big
                                                                      59
```

### function big() { function sub1() { var x = 7; (1)function sub2() { $\mathbf{var} \ \mathbf{y} = \mathbf{x};$ var z = 3; (2) (3)var x = 3; sub1() big-> sub1 -> sub2

First, big calls sub1, which calls sub2.

Next, sub2 is called directly from big

big -> sub2

#### **Static Scoping**

Point in code	Visible	Hidden
1	x (sub1)	x (big)
2	y,z (sub2), x(big)	
3	x (big)	

#### **Dynamic Scoping**

Point in code	Visible	Hidden
1	x (sub1)	x (big)
2	y,z (sub2), x(sub1)	x (big)
3	x (big)	

#### **Dynamic Scoping**

Point in code	Visible	Hidden
2	y,z (sub2), x(big)	
3	x (big)	

# **Referencing Environments**

- The referencing environment of a statement is the collection of all names that are visible in the statement
- In a static-scoped language, it is the local variables plus all of the visible variables in all of the enclosing scopes
- A subprogram is active if its execution has begun but has not yet terminated
- In a dynamic-scoped language, the referencing environment is the local variables plus all visible variables in all active subprograms

```
void sub1() {
int a, b;
. . . 1
} /* end of sub1 */
void sub2() {
int b, c;
...2
sub1();
} /* end of sub2 */
void main() {
int c, d;
. . . 3
sub2();
} /* end of main */
```

```
Point Referencing Environment
1 a and b of sub1, c of sub2, d of main, (c of main and b of sub2 are hidden)
2 b and c of sub2, d of main, (c of main is hidden)
3 c and d of main
```

#### main() -> sub2() -> sub1()

	Visible	Hidden
1	a,b(sub1), c(sub2), d(main)	b (sub2), c(main)
2	b,c(sub2),d(main)	c(main)
3	c,d(main)	

# **Further Examples**

Assume the following JavaScript program was interpreted using

- A- **static-scoping rules**. What value of x is displayed in function sub1?
- B- Under **dynamic-scoping rules**, what value of x is displayed in function sub1?

```
var x;
function sub1() {
document.write("x = " + x + " < br /> ");
function sub2() {
var x;
x = 10:
sub1();
x = 5:
sub2();
```

```
Static Scoping
```

```
in sub1 x(main) is visible x = 5
```

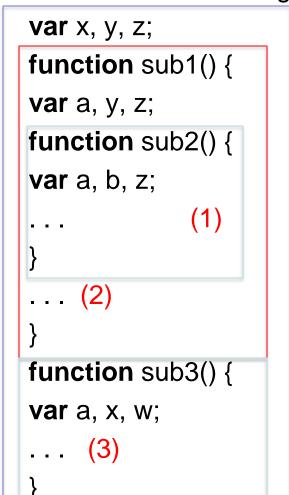
**Dynamic Scoping** 

```
main()-> sub2() -> sub1()
```

in sub1 x(sub2) is visible, x(main) is hidden

$$x = 10$$

#### Consider the following JavaScript program:



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	Visible	Hidden
1	a,b,z(sub2), y(sub1), x(main)	a,z(sub1), y,z(main)
2	a,y,z(sub1), x(main)	y,z(main)
3	a,x,w(sub3), y,z (main)	x(main)

List all the variables, along with the program units where they are

declared, that are visible in the bodies of sub1, sub2, and sub3, assuming **static scoping** is

Consider the following skeletal C program: Dynamic scoping void fun1(void); /\* prototype \*/ void fun2(void); /\* prototype \*/ a) main->fun1->fun2->fun3 void fun3(void); /\* prototype \*/ void main() { Visible Hidden **int** a, b, c; d,e,f(fun3), (1) d,e(fun2) c(fun2), b(fun1) c,d(fun1) a(main) b,c(main) void fun1(void) { **int** b, c, d; Dynamic scoping (2) c) main->fun2->fun3->fun1 void fun2(void) { int c, d, e; **Visible** Hidden (2)b,c,d(fun1), d(fun3),e,f(fun3), c,d,e(fun2), void fun3(void) { a(main) b,c(main) int d, e, f; . . . (1)

Given the following calling sequences and assuming that **dynamic scoping** is used, what variables are visible during execution of the last function called? Include with each visible variable the name of the function in which it was defined.

- a. main calls fun1; fun1 calls fun2; fun2 calls fun3.
- b. main calls fun1; fun1 calls fun3.
- c. main calls fun2; fun2 calls fun3; fun3 calls fun1.
- d. main calls sub3; sub3 calls sub1.

f. main calls sub3: sub3 calls sub2: sub2 calls sub1.

e. main calls sub1; sub1 calls sub3; sub3 calls sub2.

```
void main() {
int x, y, z;
while ( . . . ) {
int a, b, c;
                       while1
. . .
while ( . . . ) {
int d, e;
                     while2
while ( . . . ) {
int f, g;
                       while3
. . .
. . .
```

## Summary

- Case sensitivity and the relationship of names to special words represent design issues of names
- Variables are characterized by the sextuples: name, address, value, type, lifetime, scope
- Binding is the association of attributes with program entities
- Scalar variables are categorized as: static, stack dynamic, explicit heap dynamic, implicit heap dynamic
- Scope of a variable is the range of statements in which the variable is visible and can be static, or dynamic.