Lecture 3 Reasoning in Datalog

COMP24412: Symbolic Al

Giles Reger

February 2019

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Aim and Learning Outcomes

The aim of this lecture is to:

Introduce you to the main concepts around *quering a knowledge base* and how these are concretely realised in the *Datalog* language.

Learning Outcomes

By the end of this lecture you will be able to:

- Describe what it means to query a knowledge base
- ② Define matching and compute matching substitutions
- Apply the forward chaining algorithm to find consequences of a knowledge base
- Explain certain optimisations of the algorithm

In General

Abstraction

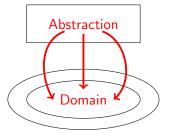
Reality

In General

Abstraction

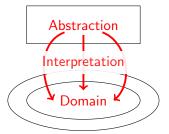
Domain

In General



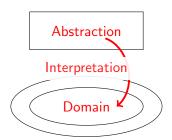
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In General



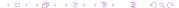
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In General



Database Semantics

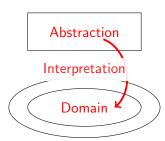
- Closed World
- Domain Closure
- Unique Names



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In General



Database Semantics

- Closed World
- Domain Closure
- Unique Names

Datalog

Has Database Semantics

Fact: concrete relationship between objects e.g. loves(giles, cheese)

Rule:
$$\underbrace{loves(X,Y), has(X,Y)}_{body} \Rightarrow \underbrace{happy(X)}_{head}$$

Knowledge Base KB: set of facts and rules

Fact f is a consequence of KBIf all interpretations satisfying KB satisfy fwritten $KB \models f$

Given a knowledge base there are a finite number of consequences

Why?

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Why? Each rule has a finite number of instances (finite new facts)

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Why? Each rule has a finite number of instances (finite new facts)

Checking if f is a consequence of KB is decidable.

- An interpretation can be defined by the facts true in it
- ullet Due to database semantics, \mathcal{KB} has a single minimal interpretation \mathcal{M} satisfying it. If a fact is satisfied by this it is a consequence of \mathcal{KB}
- ullet The set of all facts built from ${\mathcal O}$ and ${\mathcal R}$ is finite, call this ${\mathcal A}$
- ullet Clearly $\mathcal{M}\subseteq\mathcal{A}$; we can search all subsets of \mathcal{A}

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Finally, can a Datalog knowledge base be inconsistent?

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Finally, can a Datalog knowledge base be inconsistent? No, the set of all consequences always exists and defines a satisfying interpretation.

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Queries

Given a knowledge base we want to ask queries

These can be ground e.g. is ancestor(giles, adam) true?

Or, more interestingly, they can contain variables e.g. give me all ancestors of giles or more formally all X such that ancestor(giles, X) is true.

A query is a fact, possibly containing variables.

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The answer to a query q of a knowledge base \mathcal{KB} is the set

$$ans(q) = \{ \sigma \mid \mathcal{KB} \models \sigma(q) \}$$

e.g. the set of all substitutions, which when applied to q produce a ground fact that is a consequence of \mathcal{KB} .

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If the query has no answers then ans is empty. Can this happen?

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What will happen if q is ground?

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What will happen if q is ground? The substitution will be empty

Will ans(q) always be finite?

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e.g. the set of all substitutions, which when applied to q produce a ground fact that is a consequence of \mathcal{KB} .

If the query has no answers then ans is empty. Can this happen?

What will happen if q is ground? The substitution will be empty

Will ans(q) always be finite? Yes - there are finite consequences

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Computing the Set of Consequences

Given our initial set of facts \mathcal{F}_0 we want to add *new* consequences until we reach a fixed-point

Let our knowledge base \mathcal{KB} consist of facts \mathcal{F}_0 and rules \mathcal{RU}

Define the *next* set of facts as follows

$$\mathcal{F}_i = \mathcal{F}_{i-1} \cup \left\{ \sigma(\textit{head}) \mid egin{array}{c} \textit{body} \Rightarrow \textit{head} \in \mathcal{RU} \\ \sigma(\textit{body}) \in \mathcal{F}_{i-1} \end{array}
ight\}$$

This reaches a fixed point when $\mathcal{F}_j = \mathcal{F}_{j+1}$

As there are finite consequences this will terminate

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How do we find σ ? How do we compute \mathcal{F}_{i+1} efficiently?

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Matching

A fact is ground if it does not contain variables

Given a fact f_1 and a ground fact f_2 we say f_2 matches f_1 if there exists a substitution σ such that $f_2 = \sigma(f_1)$.

Examples:

fact f_1 using	substitution σ
happy(X)	$\{X\mapsto giles\}$
loves(X, cheese)	$\{X\mapsto giles\}$
loves(X, Y)	$\{X \mapsto giles, Y \mapsto cheese\}$
happy(giles)	{}
	happy(X) $loves(X, cheese)$ $loves(X, Y)$

Note that loves(giles, cheese) does not match with loves(X, X).

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Match two facts given an existing substitution

```
\begin{array}{c|c} \mathbf{def} \ \mathsf{match}(f_1 = \mathsf{name}_1(\mathsf{args}_1), f_2 = \mathsf{name}_2(\mathsf{args}_2), \sigma) \mathbf{:} \\ \mathbf{if} \ \mathsf{name}_1 \ \mathsf{and} \ \mathsf{name}_2 \ \mathsf{are} \ \mathsf{different} \ \mathbf{then} \ \mathsf{return} \ \bot; \\ \mathbf{for} \ i \leftarrow 0 \ \mathsf{to} \ \mathsf{length}(\mathsf{args}_1) \ \mathsf{do} \\ & | \ \mathbf{if} \ \mathsf{args}_1[i] \ \mathsf{is} \ \mathsf{a} \ \mathsf{variable} \ \mathsf{and} \ \mathsf{args}_1[i] \notin \sigma \ \mathsf{then} \\ & | \ \sigma = \sigma \cup \{\mathsf{args}_1[i] \mapsto \mathsf{args}_2[i]\} \\ & \mathbf{else} \ \mathbf{if} \ \sigma(\mathsf{args}_1[i]) \neq \mathsf{args}_2[i]) \ \mathsf{then} \\ & | \ \mathsf{return} \ \bot \\ & \mathbf{end} \\ & \mathbf{return} \ \sigma \end{array}
```

If names are different, no match. For each parameter of f_1 , if it is an unseen variable then extend σ , otherwise check that things are consistent.

Matching is an instance of unification, which we will meet later. In unification both sides can contain variables.

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```
def match(f_1 = name_1(args_1), f_2 = name_2(args_2), \sigma):
    if name_1 and name_2 are different then return \perp;
    for i \leftarrow 0 to length(args_1) do
        if args_1[i] is a variable and args_1[i] \notin \sigma then
         \mid \sigma = \sigma \cup \{args_1[i] \mapsto args_2[i]\} 
        else if \sigma(args_1[i]) \neq args_2[i]) then
         return
    end
    return \sigma
match(parent(X, Y), parent(giles, mark), \{X \mapsto giles\})
```

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                               • f_1 = parent(X, Y)
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        else if \sigma(args_1[i]) \neq args_2[i]) then
        return
    end
    return \sigma
match(parent(X, Y), parent(giles, mark), \{X \mapsto giles\})
   • f_1 = parent(X, Y)
                            • args_1[0] = X
   • f_2 = parent(giles, mark) • args_2[0] = giles
   • \sigma = \{X \mapsto \text{giles}\}
```

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        else if \sigma(args_1[i]) \neq args_2[i]) then
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    end
    return \sigma
```

 $match(parent(X, Y), parent(giles, mark), \{X \mapsto giles\})$

- $f_1 = parent(X, Y)$
- $f_2 = parent(giles, mark)$ $args_2[0] = giles$
- $\sigma = \{X \mapsto \text{giles}\}$
- $args_1[0] = X$

 - $\sigma(args_1[0]) = \{X \mapsto giles\}(X) = giles$

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def match(f_1 = name_1(args_1), f_2 = name_2(args_2), \sigma):
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   • f_1 = parent(X, Y)
                                      • args_1[1] = Y
   • f_2 = parent(giles, mark)
                                      • args_2[1] = mark
   • \sigma = \{X \mapsto \text{giles}\}
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def match(f_1 = name_1(args_1), f_2 = name_2(args_2), \sigma):
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    • f_1 = parent(X, Y)
                                               • args_1[1] = Y
    • f_2 = parent(giles, mark)
                                                • args_{2}[1] = mark
    • \sigma = \{X \mapsto \text{giles}, Y \mapsto \text{mark}\}
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def match(f_1 = name_1(args_1), f_2 = name_2(args_2), \sigma):
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                           • f_1 = parent(X, Y)
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        else if \sigma(args_1[i]) \neq args_2[i]) then
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    end
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match(parent(X, Y), parent(giles, mark), \{X \mapsto bob\})
                               • f_1 = parent(X, Y)
                               • f_2 = parent(giles, mark)
                              • \sigma = \{X \mapsto \mathsf{bob}\}\
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def match(f_1 = name_1(args_1), f_2 = name_2(args_2), \sigma):
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```

- $f_1 = parent(X, Y)$
- $args_1[0] = X$
- $f_2 = parent(giles, mark)$ $args_2[0] = giles$

• $\sigma = \{X \mapsto \mathsf{bob}\}$

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def match(f_1 = name_1(args_1), f_2 = name_2(args_2), \sigma):
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 $match(parent(X, Y), parent(giles, mark), \{X \mapsto bob\})$

- $f_1 = parent(X, Y)$
- $f_2 = parent(giles, mark)$ $args_2[0] = giles$
- $\sigma = \{X \mapsto \mathsf{bob}\}$
- $args_1[0] = X$

 - $\sigma(args_1[0]) = \{X \mapsto bob\}(X) = bob$

Computing Matching Substitutions

```
def match(f_1 = name_1(args_1), f_2 = name_2(args_2), \sigma):
    if name_1 and name_2 are different then return \perp;
    for i \leftarrow 0 to length(args_1) do
        if args_1[i] is a variable and args_1[i] \notin \sigma then
         \mid \sigma = \sigma \cup \{args_1[i] \mapsto args_2[i]\} 
        else if \sigma(args_1[i]) \neq args_2[i]) then
         return 🗆
    end
    return \sigma
match(parent(X, Y), parent(giles, mark), \{X \mapsto bob\}) = \bot
```

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We lift the matching algorithm to match a list of facts (the rule body) against a set of ground facts (the known consequences).

```
def match(body, \mathcal{F}):
     matches = \{\emptyset\}
     for f_1 \in body do
           new = \emptyset
           for \sigma_1 \in matches do
                for f_2 \in \mathcal{F} do
               \sigma_2 = \mathsf{match}(f_1, f_2, \sigma_1)

if \sigma_2 \neq \bot then new.add(\sigma_2);
                end
           end
           matches = new
     end
     return matches
```

```
match(parent(X, Y), man(X), \begin{cases} parent(giles, mark), man(giles) \\ parent(bob, sara), man(bob) \end{cases}
def match(body, \mathcal{F}):
      matches = \{\emptyset\}
     for f_1 \in body do
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      matches = \{\emptyset\}
     for f_1 \in body do
           new = \emptyset
                                                                     matches = \{\emptyset\}
                                                                     f_1 = parent(X, Y)
           for \sigma_1 \in matches do
                for f_2 \in \mathcal{F} do
           \sigma_2 = \mathsf{match}(f_1, f_2, \sigma_1)

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                 for f_2 \in \mathcal{F} do
           \sigma_2 = \mathsf{match}(f_1, f_2, \sigma_1)

if \sigma_2 \neq \bot then new.add(\sigma_2);
                                                         \sigma_1 = \emptyset
                 end
           end
           matches = new
     end
      return matches
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match(parent(X, Y), man(X), \begin{cases} parent(giles, mark), man(giles) \\ parent(bob, sara), man(bob) \end{cases}
def match(body, \mathcal{F}):
       matches = \{\emptyset\}
      for f_1 \in body do
             new = \emptyset
                                                                                  matches = \{\emptyset\}
                                                                                  f_1 = parent(X, Y)
             for \sigma_1 \in matches do
                   for f_2 \in \mathcal{F} do
                                                                                  new = \emptyset
              | \sigma_2 = \mathsf{match}(f_1, f_2, \sigma_1) \qquad \sigma_1 = \emptyset 
 | \mathbf{if} \ \sigma_2 \neq \bot \ \mathbf{then} \ \mathsf{new.add}(\sigma_2); \ f_2 = \mathsf{parent}(\mathsf{giles}, \mathsf{mark}) 
                    end
             end
             matches = new
      end
       return matches
```

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return matches

```
match(parent(X, Y), man(X), \begin{cases} parent(giles, mark), man(giles) \\ parent(bob, sara), man(bob) \end{cases}
def match(body, \mathcal{F}):
       matches = \{\emptyset\}
       for f_1 \in body do
              new = \emptyset
                                                                                    matches = \{\emptyset\}
                                                                                    f_1 = parent(X, Y)
             for \sigma_1 \in matches do
                                                                                   new = \emptyset
                    for f_2 \in \mathcal{F} do
              \sigma_2 = \mathsf{match}(f_1, f_2, \sigma_1) \qquad \sigma_1 = \emptyset
\mathsf{if} \ \sigma_2 \neq \bot \ \mathsf{then} \ \mathsf{new.add}(\sigma_2); \ f_2 = \mathsf{parent}(\mathsf{giles}, \mathsf{mark})
                                                                                   \sigma_2 = \{X \mapsto \text{giles}, Y \mapsto \text{mark}\}\
                    end
             end
              matches = new
       end
```

```
match(parent(X, Y), man(X), \begin{cases} parent(giles, mark), man(giles) \\ parent(bob, sara), man(bob) \end{cases}
def match(body, \mathcal{F}):
      matches = \{\emptyset\}
                                                                         matches = \{\emptyset\}
      for f_1 \in body do
                                                                         f_1 = parent(X, Y)
            new = \emptyset
            for \sigma_1 \in matches do
                                                                         new =
                                                                         \{ \{X \mapsto \mathsf{giles}, Y \mapsto \mathsf{mark} \} \}
                 for f_2 \in \mathcal{F} do
               \sigma_2 = \mathsf{match}(f_1, f_2, \sigma_1)

if \sigma_2 \neq \bot then new.add(\sigma_2); \sigma_1 = \emptyset
                                                                         f_2 = parent(giles, mark)
                 end
                                                                        \sigma_2 = \{X \mapsto \text{giles}, Y \mapsto \text{mark}\}\
            end
            matches = new
      end
      return matches
```

```
match(parent(X, Y), man(X), \begin{cases} parent(giles, mark), man(giles) \\ parent(bob, sara), man(bob) \end{cases})
def match(body, \mathcal{F}):
      matches = \{\emptyset\}
                                                                       matches = \{\emptyset\}
     for f_1 \in body do
                                                                       f_1 = parent(X, Y)
           new = \emptyset
           for \sigma_1 \in matches do
                                                                       new =
                                                                       \{ \{X \mapsto \text{giles}, Y \mapsto \text{mark} \} \}
                 for f_2 \in \mathcal{F} do
            \sigma_2 = \mathsf{match}(f_1, f_2, \sigma_1)
if \sigma_2 \neq \bot then new.add(\sigma_2); \sigma_1 = \emptyset
                                                                       f_2 = man(giles)
                 end
           end
           matches = new
     end
      return matches
```

```
match(parent(X, Y), man(X), \begin{cases} parent(giles, mark), man(giles) \\ parent(bob, sara), man(bob) \end{cases})
def match(body, \mathcal{F}):
      matches = \{\emptyset\}
                                                                             matches = \{\emptyset\}
      for f_1 \in body do
                                                                             f_1 = parent(X, Y)
            new = \emptyset
            for \sigma_1 \in matches do
                                                                             new =
                                                                             \{ \{X \mapsto \mathsf{giles}, Y \mapsto \mathsf{mark} \} \}
                  for f_2 \in \mathcal{F} do
             | \sigma_2 = \mathsf{match}(f_1, f_2, \sigma_1) 
| \mathbf{if} \ \sigma_2 \neq \bot \ \mathbf{then} \ \mathsf{new.add}(\sigma_2); \ \sigma_1 = \emptyset
                                                                             f_2 = man(giles)
                  end
            end
                                                                            \sigma_2 = \bot
            matches = new
      end
      return matches
```

```
match(parent(X, Y), man(X), \begin{cases} parent(giles, mark), man(giles) \\ parent(bob, sara), man(bob) \end{cases})
def match(body, \mathcal{F}):
      matches = \{\emptyset\}
                                                                            matches = \{\emptyset\}
      for f_1 \in body do
                                                                            f_1 = parent(X, Y)
            new = \emptyset
            for \sigma_1 \in matches do
                                                                            new =
                                                                            \{ \{X \mapsto \text{giles}, Y \mapsto \text{mark} \} \}
                  for f_2 \in \mathcal{F} do
             \sigma_2 = \mathsf{match}(f_1, f_2, \sigma_1)
\mathsf{if} \ \sigma_2 \neq \bot \ \mathsf{then} \ \mathsf{new.add}(\sigma_2); \ \sigma_1 = \emptyset
                                                                            f_2 = man(giles)
                  end
            end
                                                                           \sigma_2 = \bot
            matches = new
      end
      return matches
```

```
match(parent(X, Y), man(X), \begin{cases} parent(giles, mark), man(giles) \\ parent(bob, sara), man(bob) \end{cases}
def match(body, \mathcal{F}):
      matches = \{\emptyset\}
                                                                      matches = \{\emptyset\}
     for f_1 \in body do
                                                                      f_1 = parent(X, Y)
           new = \emptyset
           for \sigma_1 \in matches do
                                                                      new =
                                                                      \{ \{X \mapsto \text{giles}, Y \mapsto \text{mark} \} \}
                 for f_2 \in \mathcal{F} do
            \sigma_2 = \mathsf{match}(f_1, f_2, \sigma_1)
if \sigma_2 \neq \bot then new.add(\sigma_2); \sigma_1 = \emptyset
                                                                      f_2 = parent(bob, sara)
                 end
           end
           matches = new
     end
      return matches
```

```
match(parent(X, Y), man(X), \begin{cases} parent(giles, mark), man(giles) \\ parent(bob, sara), man(bob) \end{cases})
def match(body, \mathcal{F}):
      matches = \{\emptyset\}
                                                                             matches = \{\emptyset\}
      for f_1 \in body do
                                                                             f_1 = parent(X, Y)
             new = \emptyset
            for \sigma_1 \in matches do
                                                                             new =
                                                                             \{ \{X \mapsto \text{giles}, Y \mapsto \text{mark} \} \}
                   for f_2 \in \mathcal{F} do
             | \sigma_2 = \mathsf{match}(f_1, f_2, \sigma_1) 
| \mathbf{if} \ \sigma_2 \neq \bot \ \mathbf{then} \ \mathsf{new.add}(\sigma_2); \ \sigma_1 = \emptyset
                                                                             f_2 = parent(bob, sara)
                   end
                                                                             \sigma_2 = \{X \mapsto \mathsf{bob}, Y \mapsto \mathsf{sara}\}
            end
             matches = new
      end
      return matches
```

```
match(parent(X, Y), man(X), \begin{cases} parent(giles, mark), man(giles) \\ parent(bob, sara), man(bob) \end{cases}
def match(body, \mathcal{F}):
        matches = \{\emptyset\}
                                                                                             matches = \{\emptyset\}
       for f_1 \in body do
                                                                                             f_1 = parent(X, Y)
               new = \emptyset
                                                                                             new =
               for \sigma_1 \in matches do
                                                                                              \left\{ \begin{array}{l} \left\{ X \mapsto \mathsf{giles}, Y \mapsto \mathsf{mark} \right\} \\ \left\{ X \mapsto \mathsf{bob}, Y \mapsto \mathsf{sara} \right\} \end{array} \right\} 
                      for f_2 \in \mathcal{F} do
                 | \sigma_2 = \mathsf{match}(f_1, f_2, \sigma_1) | \{X \} 
 | \mathsf{if} \ \sigma_2 \neq \bot \ \mathsf{then} \ \mathsf{new.add}(\sigma_2); \ \sigma_1 = \emptyset 
                      end
                                                                                             f_2 = parent(bob, sara)
                                                                                             \sigma_2 = \{X \mapsto \mathsf{bob}, Y \mapsto \mathsf{sara}\}
               end
               matches = new
       end
        return matches
```

```
match(parent(X, Y), man(X), \begin{cases} parent(giles, mark), man(giles) \\ parent(bob, sara), man(bob) \end{cases}
def match(body, \mathcal{F}):
        matches = \{\emptyset\}
                                                                                           matches = \{\emptyset\}
       for f_1 \in body do
                                                                                           f_1 = parent(X, Y)
               new = \emptyset
                                                                                           new =
               for \sigma_1 \in matches do
                                                                                            \left\{ \begin{array}{l} \left\{ X \mapsto \mathsf{giles}, Y \mapsto \mathsf{mark} \right\} \\ \left\{ X \mapsto \mathsf{bob}, Y \mapsto \mathsf{sara} \right\} \end{array} \right\} 
                for f_2 \in \mathcal{F} do \{X\}

\sigma_2 = \mathsf{match}(f_1, f_2, \sigma_1)

if \sigma_2 \neq \bot then new.add(\sigma_2); \sigma_1 = \emptyset
                      for f_2 \in \mathcal{F} do
                      end
                                                                                           f_2 = man(bob)
               end
               matches = new
       end
        return matches
```

```
match(parent(X, Y), man(X), \begin{cases} parent(giles, mark), man(giles) \\ parent(bob, sara), man(bob) \end{cases}
def match(body, \mathcal{F}):
        matches = \{\emptyset\}
                                                                                                matches = \{\emptyset\}
        for f_1 \in body do
                                                                                                f_1 = parent(X, Y)
                new = \emptyset
                                                                                                new =
               for \sigma_1 \in matches do
                                                                                                 \left\{ \begin{array}{l} \left\{ X \mapsto \mathsf{giles}, Y \mapsto \mathsf{mark} \right\} \\ \left\{ X \mapsto \mathsf{bob}, Y \mapsto \mathsf{sara} \right\} \end{array} \right\} 
                       for f_2 \in \mathcal{F} do
                \begin{array}{c|c} \sigma_2 = \mathsf{match}(f_1, f_2, \sigma_1) & \{X \\ \mathbf{if} \ \sigma_2 \neq \bot \ \mathbf{then} \ \mathsf{new.add}(\sigma_2); \ \sigma_1 = \emptyset \end{array}
                       end
                                                                                                f_2 = man(bob)
               end
                                                                                                \sigma_2 = \bot
                matches = new
       end
        return matches
```

```
match(parent(X, Y), man(X), \begin{cases} parent(giles, mark), man(giles) \\ parent(bob, sara), man(bob) \end{cases}
def match(body, \mathcal{F}):
        matches = \{\emptyset\}
                                                                                             matches = \{\emptyset\}
       for f_1 \in body do
                                                                                             f_1 = parent(X, Y)
               new = \emptyset
                                                                                             new =
               for \sigma_1 \in matches do
                                                                                              \left\{ \begin{array}{l} \left\{ X \mapsto \mathsf{giles}, Y \mapsto \mathsf{mark} \right\} \\ \left\{ X \mapsto \mathsf{bob}, Y \mapsto \mathsf{sara} \right\} \end{array} \right\} 
                      for f_2 \in \mathcal{F} do
                 | \sigma_2 = \mathsf{match}(f_1, f_2, \sigma_1) | \{X \} 
 | \mathsf{if} \ \sigma_2 \neq \bot \ \mathsf{then} \ \mathsf{new.add}(\sigma_2); \ \sigma_1 = \emptyset 
                      end
                                                                                             f_2 = man(bob)
               end
                                                                                             \sigma_2 = \bot
               matches = new
       end
        return matches
```

```
match(parent(X, Y), man(X), \begin{cases} parent(giles, mark), man(giles) \\ parent(bob, sara), man(bob) \end{cases}
def match(body, \mathcal{F}):
        matches = \{\emptyset\}
                                                                                               matches
        for f_1 \in body do
                                                                                                \left\{ \begin{array}{l} \{X \mapsto \mathsf{giles}, Y \mapsto \mathsf{mark}\} \\ \{X \mapsto \mathsf{bob}, Y \mapsto \mathsf{sara}\} \end{array} \right\} 
                new = \emptyset
               for \sigma_1 \in matches do
                       for f_2 \in \mathcal{F} do
                                                                                               f_1 = parent(X, Y)
                | \sigma_2 = \mathsf{match}(f_1, f_2, \sigma_1) \quad \mathsf{new} = \emptyset 
| \mathbf{if} \ \sigma_2 \neq \bot \ \mathbf{then} \ \mathsf{new.add}(\sigma_2); \ \sigma_1 = \{X \mapsto \mathsf{giles}, Y \mapsto \mathsf{mark}\} 
                       end
               end
                matches = new
        end
        return matches
```

```
def match(body, \mathcal{F}):
     matches = \{\emptyset\}
     for f_1 \in body do
           new = \emptyset
           for \sigma_1 \in matches do
                for f_2 \in \mathcal{F} do
                \sigma_2 = \mathsf{match}(f_1, f_2, \sigma_1)

if \sigma_2 \neq \bot then new.add(\sigma_2);
                end
           end
           matches = new
     end
     return matches
```

Clearly inefficient

The order in which we check elements in the body can effect the complexity as we can get a large set of initial fact on the first item and find that most are inconsistent with the next one

In reality we do something cleverer

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```
def forward(facts \mathcal{F}_0, rules \mathcal{RU}, query q):
      \mathcal{F} = \emptyset; new = \mathcal{F}_0
      do
            \mathcal{F} = \mathcal{F} \cup \textit{new}; \textit{new} = \emptyset
            for body \Rightarrow head \in \mathcal{RU} do
                 for \sigma \in \mathsf{match}(\mathit{body}, \mathcal{F}) do
                   if \sigma(head) \notin \mathcal{F} then new.add(\sigma(head))
                  end
            end
      while new \neq \emptyset
      ans = \emptyset
      for f \in \mathcal{F} do \sigma = \mathsf{match}(q, f, \emptyset); if \sigma \neq \bot then ans.add(\sigma)
      return ans
```

```
def forward(facts \mathcal{F}_0, rules \mathcal{RU}, query q):
      \mathcal{F} = \emptyset: new = \mathcal{F}_0
      do
            \mathcal{F} = \mathcal{F} \cup \textit{new}; \textit{new} = \emptyset
            for body \Rightarrow head \in \mathcal{RU} do
                 for \sigma \in \mathsf{match}(\mathit{body}, \mathcal{F}) do
                   if \sigma(head) \notin \mathcal{F} then new.add(\sigma(head))
                  end
            end
      while new \neq \emptyset
      ans = \emptyset
      for f \in \mathcal{F} do \sigma = \mathsf{match}(q, f, \emptyset); if \sigma \neq \bot then ans.add(\sigma)
      return ans
```

```
def forward(facts \mathcal{F}_0, rules \mathcal{RU}, query q):
      \mathcal{F} = \emptyset; new = \mathcal{F}_0
      do
            \mathcal{F} = \mathcal{F} \cup \textit{new}; \textit{new} = \emptyset
            for body \Rightarrow head \in \mathcal{RU} do
                 for \sigma \in \mathsf{match}(\mathit{body}, \mathcal{F}) do
                   if \sigma(head) \notin \mathcal{F} then new.add(\sigma(head))
                  end
            end
      while new \neq \emptyset
      ans = \emptyset
      for f \in \mathcal{F} do \sigma = \mathsf{match}(q, f, \emptyset); if \sigma \neq \bot then ans.add(\sigma)
      return ans
```

```
def forward(facts \mathcal{F}_0, rules \mathcal{RU}, query q):
      \mathcal{F} = \emptyset; new = \mathcal{F}_0
      do
            \mathcal{F} = \mathcal{F} \cup \textit{new}; \textit{new} = \emptyset
            for body \Rightarrow head \in \mathcal{RU} do
                 for \sigma \in \mathsf{match}(\mathit{body}, \mathcal{F}) do
                   if \sigma(head) \notin \mathcal{F} then new.add(\sigma(head))
                  end
            end
      while new \neq \emptyset
      ans = \emptyset
      for f \in \mathcal{F} do \sigma = \mathsf{match}(q, f, \emptyset); if \sigma \neq \bot then ans.add(\sigma)
      return ans
```

```
def forward(facts \mathcal{F}_0, rules \mathcal{RU}, query q):
      \mathcal{F} = \emptyset; new = \mathcal{F}_0
      do
            \mathcal{F} = \mathcal{F} \cup \textit{new}; \textit{new} = \emptyset
            for body \Rightarrow head \in \mathcal{RU} do
                 for \sigma \in \mathsf{match}(\mathit{body}, \mathcal{F}) do
                   if \sigma(head) \notin \mathcal{F} then new.add(\sigma(head))
                  end
            end
      while new \neq \emptyset
      ans = \emptyset
      for f \in \mathcal{F} do \sigma = \mathsf{match}(q, f, \emptyset); if \sigma \neq \bot then ans.add(\sigma)
      return ans
```

```
def forward(facts \mathcal{F}_0, rules \mathcal{RU}, query q):
      \mathcal{F} = \emptyset; new = \mathcal{F}_0
      do
            \mathcal{F} = \mathcal{F} \cup \textit{new}; \textit{new} = \emptyset
            for body \Rightarrow head \in \mathcal{RU} do
                 for \sigma \in \mathsf{match}(\mathit{body}, \mathcal{F}) do
                   if \sigma(head) \notin \mathcal{F} then new.add(\sigma(head))
                  end
            end
      while new \neq \emptyset
      ans = \emptyset
      for f \in \mathcal{F} do \sigma = \mathsf{match}(q, f, \emptyset); if \sigma \neq \bot then ans.add(\sigma)
      return ans
```

Compute the next set of consequences whilst there are new consequences. Search all consequences for facts matching the query.

```
def forward(facts \mathcal{F}_0, rules \mathcal{RU}, query q):
      \mathcal{F} = \emptyset; new = \mathcal{F}_0
      do
            \mathcal{F} = \mathcal{F} \cup \textit{new}; \textit{new} = \emptyset
            for body \Rightarrow head \in \mathcal{RU} do
                 for \sigma \in \mathsf{match}(\mathit{body}, \mathcal{F}) do
                   if \sigma(head) \notin \mathcal{F} then new.add(\sigma(head))
                  end
            end
      while new \neq \emptyset
      ans = \emptyset
      for f \in \mathcal{F} do \sigma = \mathsf{match}(q, f, \emptyset); if \sigma \neq \bot then ans.add(\sigma)
      return ans
```

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```
def forward(facts \mathcal{F}_0, rules \mathcal{RU}, query q):
      \mathcal{F} = \emptyset; new = \mathcal{F}_0
      ob
            \mathcal{F} = \mathcal{F} \cup \textit{new}; \textit{new} = \emptyset
            for body \Rightarrow head \in \mathcal{RU} do
                 for \sigma \in \mathsf{match}(\mathit{body}, \mathcal{F}) do
                    if \sigma(head) \notin \mathcal{F} then new.add(\sigma(head))
                   end
            end
      while new \neq \emptyset
      ans = \emptyset
      for f \in \mathcal{F} do \sigma = \mathsf{match}(q, f, \emptyset); if \sigma \neq \bot then \mathsf{ans.add}(\sigma)
      return ans
```

Efficient Matching

Observation: The current algorithm for matching against known consequences is inefficient; it involves multiple iterations over all known consequences.

Solution 1: Use heuristics to select the order in which facts in the body are matched e.g. pick least frequently occurring name first.

Solution 2: Store known facts in a data structure that facilitates quick lookup of matching facts. We will see such a data structure for *unification* towards the end of the course

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Incremental Forward Chaining

Observation: On each step the only new additions come from rules that are triggered by new facts.

Solution: Use the previous set of new facts as an initial filter to identify which rules are relevant and which further facts need to match against existing facts

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Dealing with Irrelevant Facts

Observation: We can derive a lot of facts that are irrelevant to the query

Solution 1: Rewrite the knowledge base to remove/reduce rules that produce irrelevant facts. Computationally expensive but may be worth it if similar queries executed often. Similar to query optimisation in database.

Solution 2: Backward Chaining. Start from the query and work backwards to see which facts support it. This is what Prolog does.

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Summary

Queries are facts possibly containing variables

To answer queries we can compute all consequences and check these

We can use forward chaining to compute consequences

This relies on matching, which can be tricky to implement efficiently

Next time: Prolog!

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