

# COMP26120: Lab 7 — Graphs

Year 2019-2020, Semester 2, Week 2–5

In this lab, you will explore several graph algorithms, and a heap-based priority queue data structure.

## 1 Intended Learning Outcomes (ILOs)

Upon successful completion of this lab, you will be able to

1. explain the various shortest path algorithms and their advantages/disadvantages
2. use existing data structures in your algorithms
3. combine existing data structures to get new functionality
4. write C code for the above concepts
5. use a test-driven development approach for algorithms and data structures

## 2 Assignment

Summary: Implement the interfaces specified in `pq.h`, `sp_algorithms.h`, and the functionality described in `ap.c`.

### 2.1 General Notes

- Unless otherwise specified, it's fine to over-estimate required array sizes to avoid dynamic re-allocation. For example, the queue required for

BFS can be implemented as array with a size of `num_nodes`. This is the worst-case space required, but in most cases, significantly less nodes will be required, such that a dynamically growing queue would be more efficient (but also more complicated to implement<sup>1</sup>)

- Try to program in a modular way. Do not duplicate functionality, but move it to own functions. Also, do not artificially inline unrelated functionality (for example, priority queue operations should not go inline into Dijkstra's algorithm!). This only makes the algorithms complicated to read, and does not even bring efficiency advantages, as modern compilers are very good at automatically inlining themselves.
- The assignment comes with a test-generator `sp.c`, which will test your data-structures and algorithms on randomly generated input data. Use this to test each module in isolation, before you build modules depending on it! It's much simpler to debug Dijkstra's algorithms if you know that your priority queue is correct!

Also, feel free to modify the tests, e.g., to generate additional output useful for debugging your problem, or to pin down a particular bug. You can use the `msg` and `assertmsg` macros, that accept `printf` format strings.

Have a look at `tests.sh` for the tests that we will run on your submission!

## 2.2 Min-Heaps

The elements of the heap will be nodes (`node_t` = unsigned integer). The priorities are given by an array `D` from nodes to weights (see `weights.h` for the available operations on weights)..

You have already seen a heap data structure, implemented by a tree encoded into an array. In this assignment, you will extend this idea to support an efficient operation to decrease the priority of a node that is already on the heap, as well as an efficient check whether a node is on the heap. For this, you maintain an additional mapping from nodes to heap-indexes. After decreasing a node's priority, you use its heap-index to start a sift-up operation.

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<sup>1</sup>At least in a language like C that lacks a proper data-structure library.

The file `pq.h` specifies the interface, including the required complexities for most operations. The file `pq.c` provides some suggestions how to implement the operations. You are free to follow them, or do your own implementation from scratch.

## 2.3 Shortest Paths Algorithms

The file `graph.h` specifies basic graph operations. The file `shortest_path.h` provides an interface how to return results for single-source shortest path algorithms. You have to implement:

- BFS, that ignores the weights and returns paths with minimal number of edges.
- Bellman-Ford. First, don't care about negative weight cycles. Once you have got the algorithm correct for this case, you can try to correctly handle negative weight cycles: If, after  $|V| - 1$  steps, you can still relax edges, set their target node's distance to  $-\infty$ . Continue (for at most  $|V| - 1$  more steps) until all nodes reachable via negative weight cycles have distance  $-\infty$ . However, do not update the predecessor map in this second phase!
- Dijkstra. This will need a working priority queue implementation.
- A\*. We strongly recommend to implement this after Dijkstra! You can assume a monotone heuristics, such that it will be very similar to Dijkstra.

## 2.4 The Airport Example

In this example you will work on a graph generated from the openflight database, that encodes connections between airports on the world.

Your task is to implement a (DFS) based algorithm to count the number of airports that can be reached from a given start airport, and to compute shortest routes between two given airports. Use your graph algorithms!

See `airports.h` for the interface, and `ap.c` for a description what to implement. Exactly stick to the output format described there!