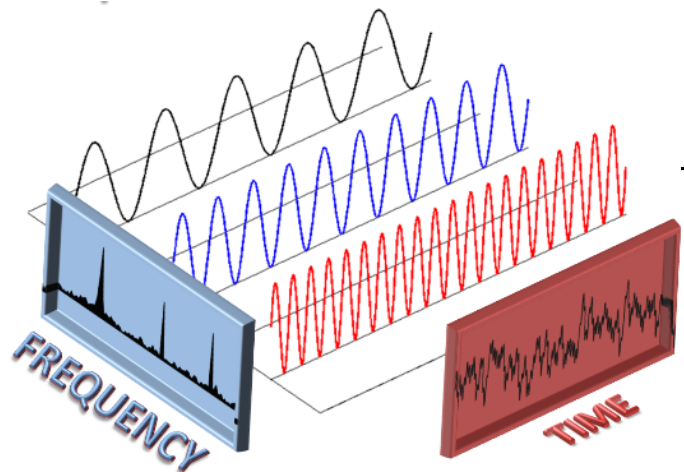
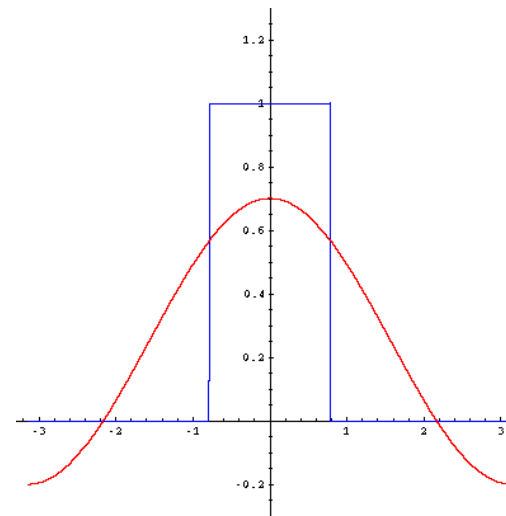
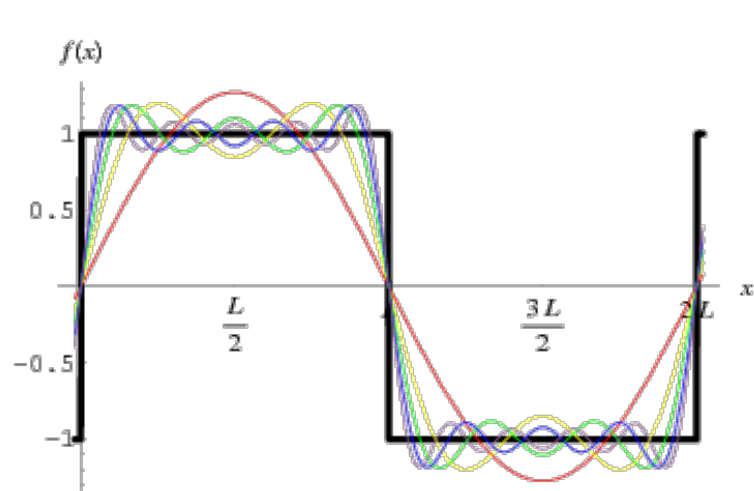


(Discrete) Fourier Decomposition

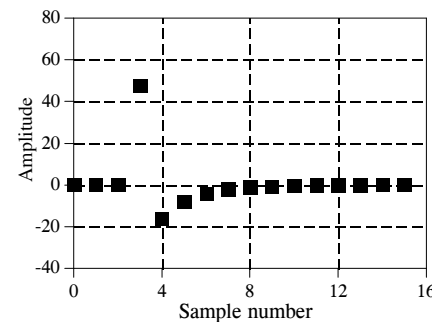
- Any signal can be expressed as the **sum of sines and cosines at different frequencies when they are appropriately scaled and shifted.**
- Fourier Transform consists of finding this amplitude and phase information.



different frequencies
are orthogonal to each other.
They capture independent information.

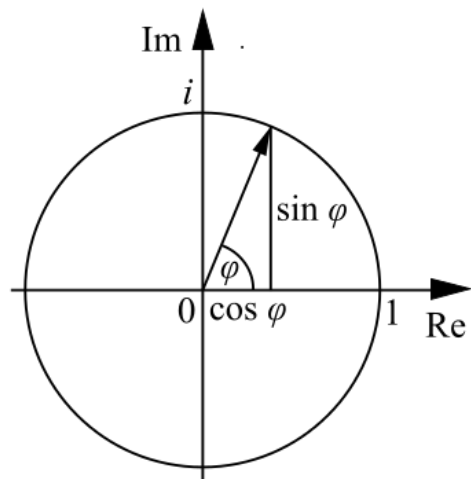
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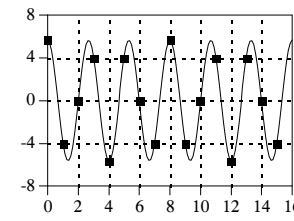
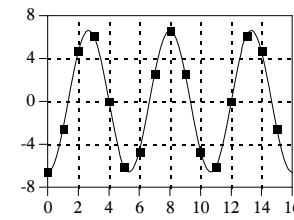
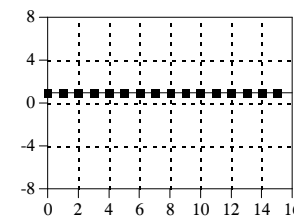
DECOMPOSE

SYNTHESIZE

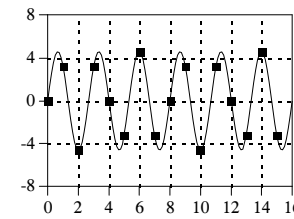
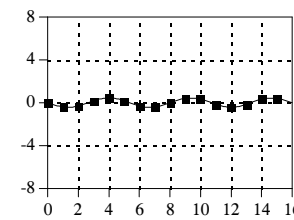
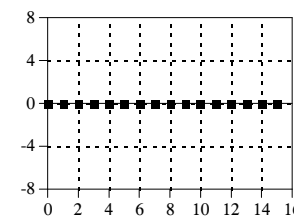


sine and cosine pairs can be represented as a complex number.

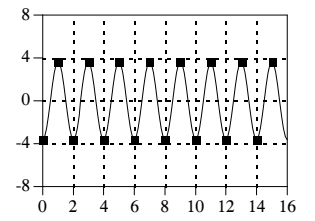
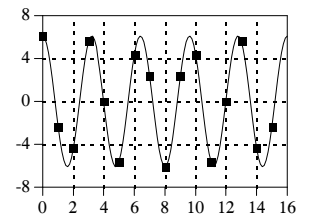
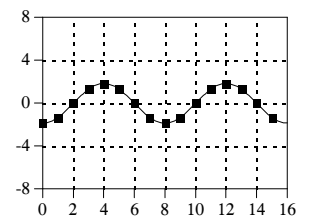
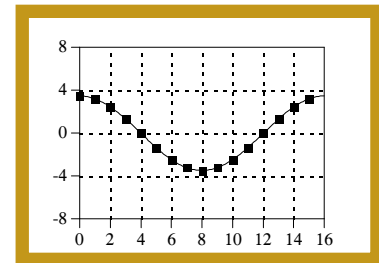
Cosine Waves



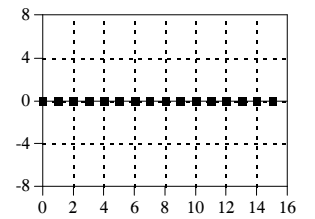
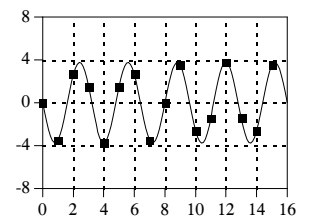
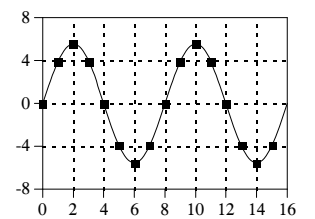
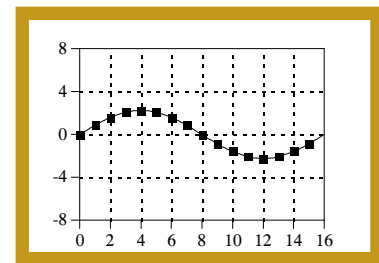
Sine Waves



real



imaginary



DFT Basis Functions

- For each frequency k , a pair of unit amplitude cosines and sines forms the DFT basis.

$$c_k[i] = \cos(2\pi ki/N)$$

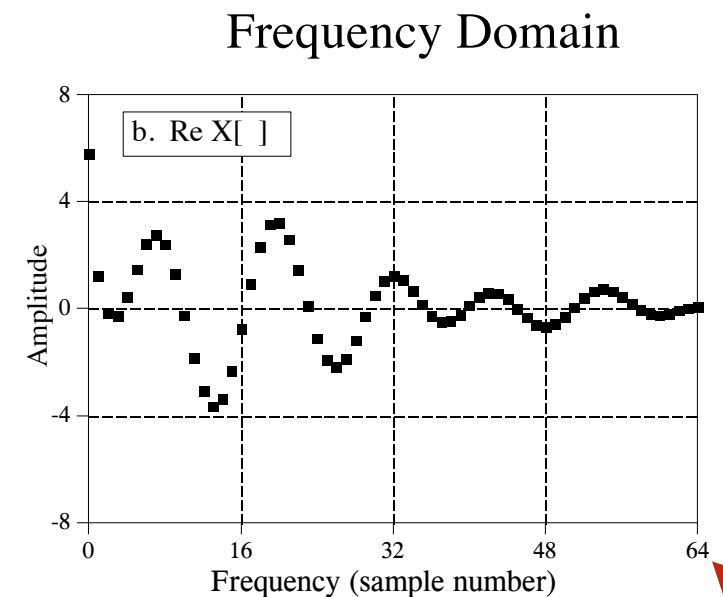
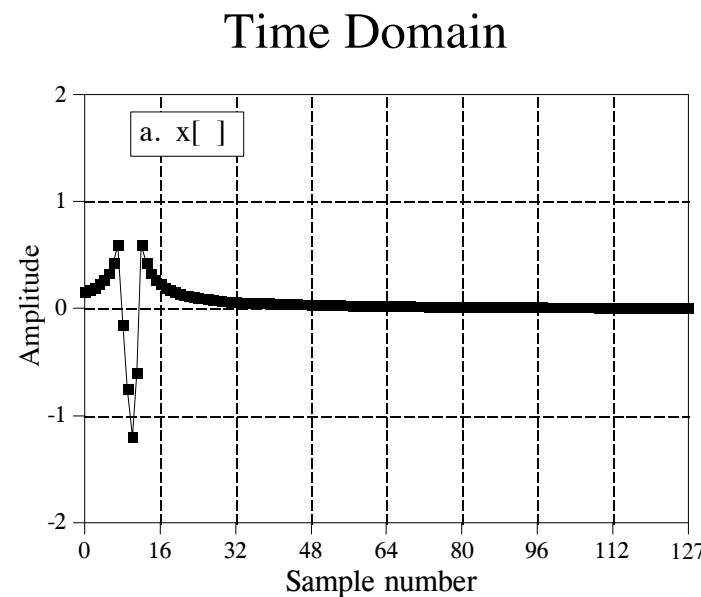
$$s_k[i] = \sin(2\pi ki/N)$$

- Synthesis Equation:

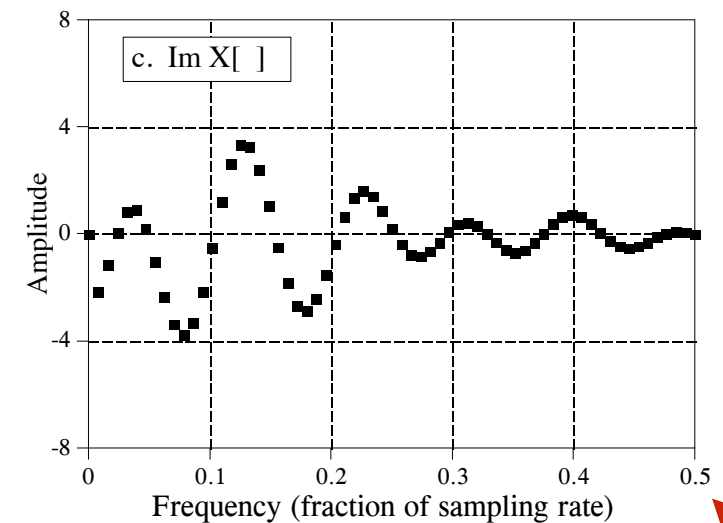
$$x[i] = \sum_{k=0}^{N/2} \text{Re} \bar{X}[k] \cos(2\pi ki/N) + \sum_{k=0}^{N/2} \text{Im} \bar{X}[k] \sin(2\pi ki/N)$$

How many basis functions?

- N data points in the time domain are transformed into $N/2+1$ frequency points.



- However you can increase the frequency resolution by using more basis functions.



Two ways of thinking: Polar Notation

- **Real vs. Imag.**

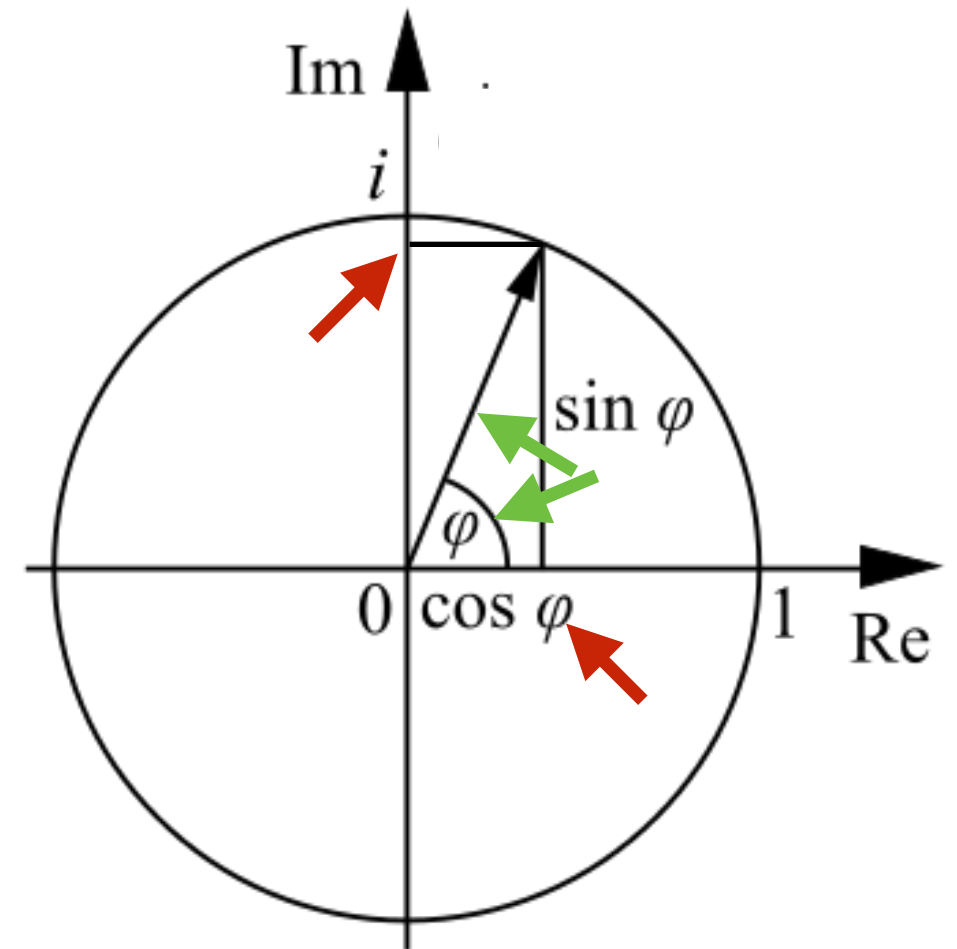
- Matlab: `real()`, `imag()`

$$A \cos(x) + B \sin(x) = M \cos(x + \theta)$$

- **Magnitude vs. Phase**

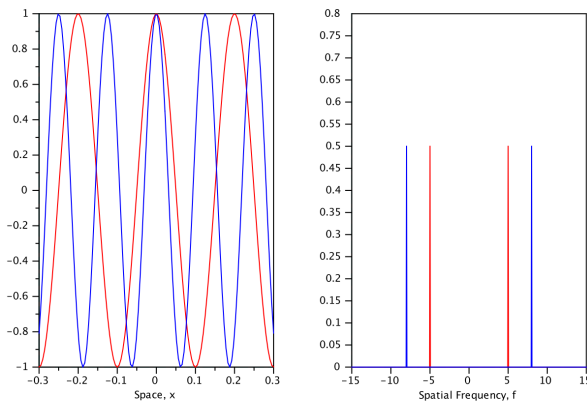
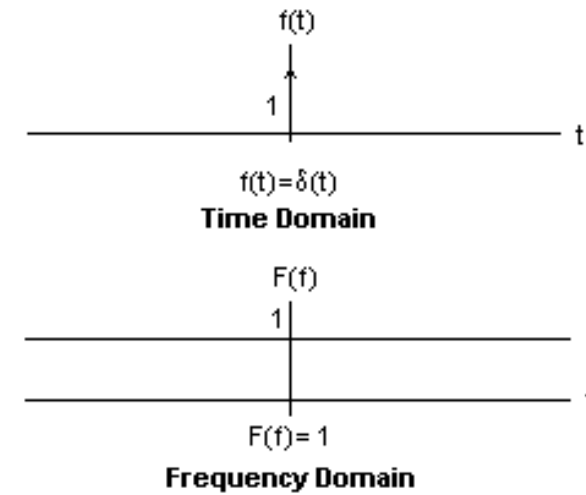
- Matlab: `abs()`, `phase()`

- $N/2+1$ cosine and sine pairs with different amplitudes
or
 $N/2+1$ cosine functions with different phases and amplitudes.

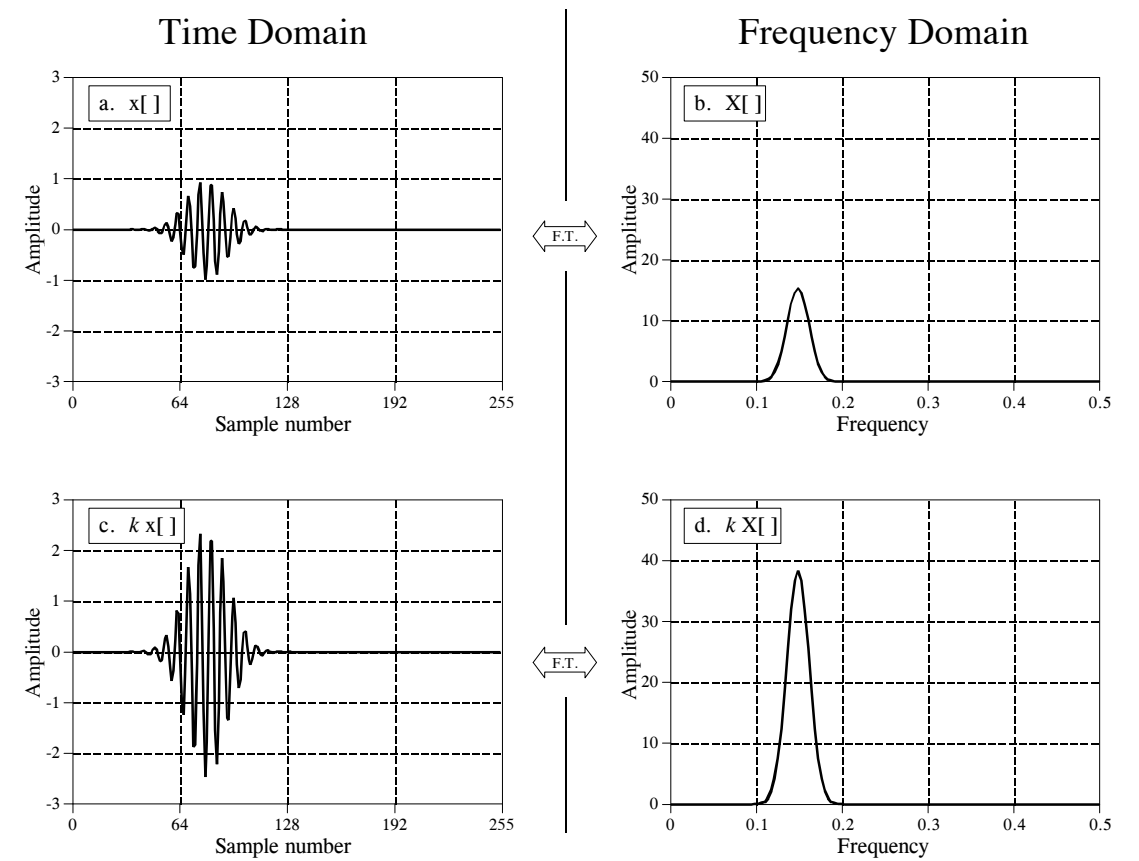
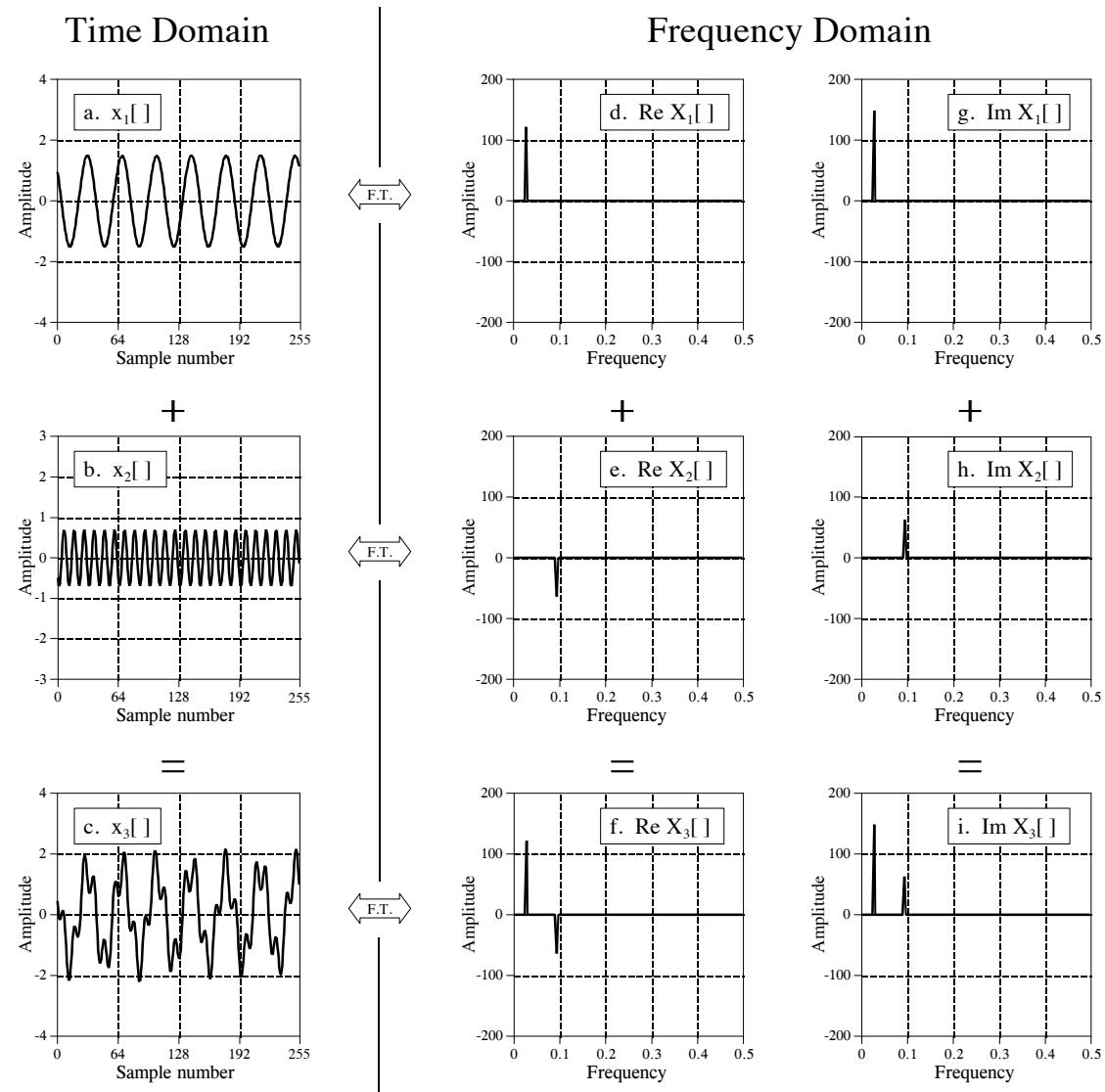


Fourier transform of an Impulse

- An Impulse contains all the frequencies.
 - Basically the impulse “tests” for all the frequencies equally.
 - Now it should make more sense why a linear system is characterized by an impulse.
 - White noise because all frequencies are equally present.
- an impulse in the frequency domain?

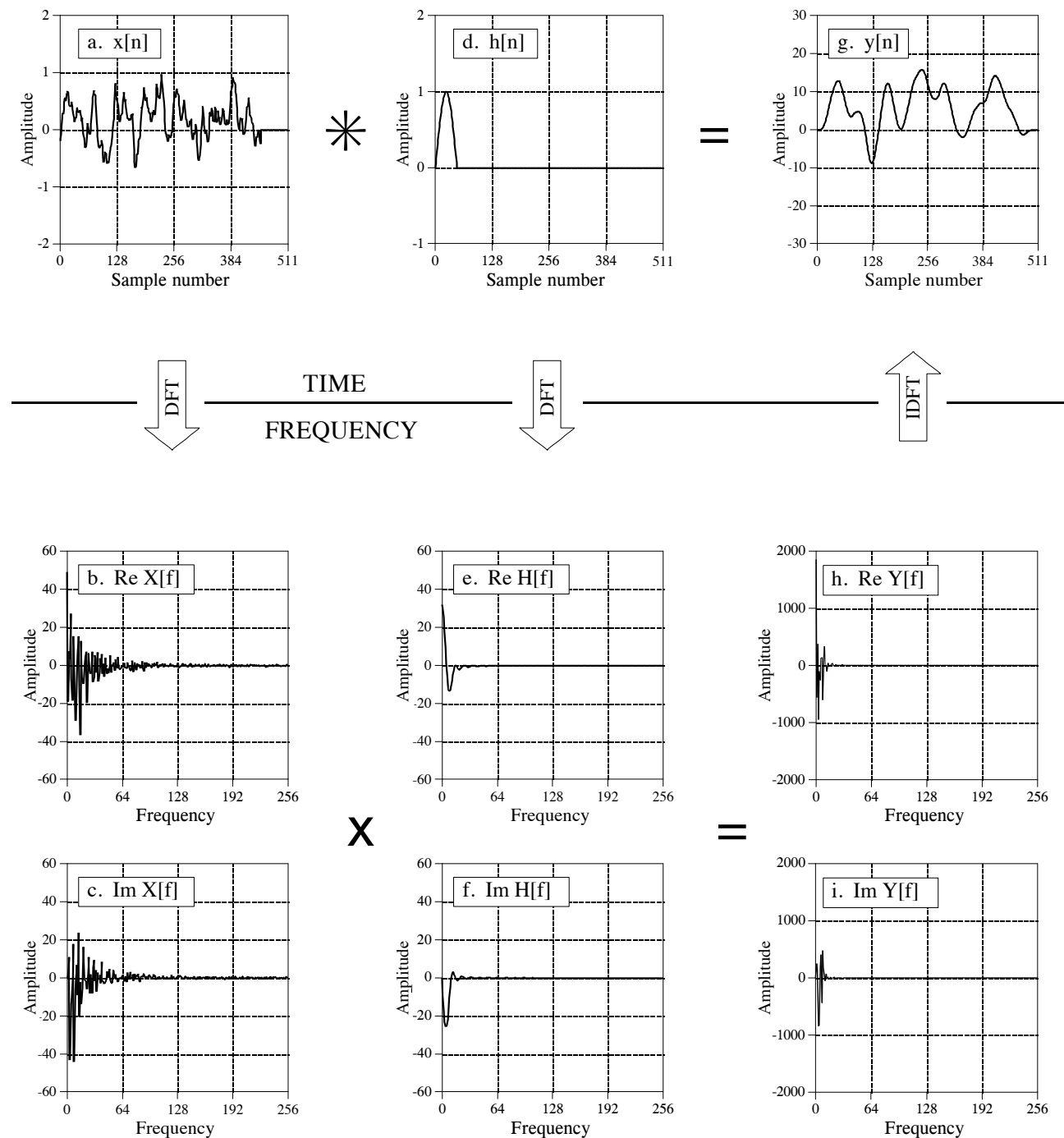


Linearity of DFT



Another view on convolution

- Convolution in the time domain is equivalent to multiplication in the Fourier domain.
- $y = \text{conv}(h, x)$ is equal to $y = \mathbf{F}^{-1}[\mathbf{F}(h) * \mathbf{F}(x)]$
- thanks to fft (fast fourier transform) convolution can be realized much faster.



Another view on convolution

- This is important because this means that the IRF decides which frequencies will be present in the output.

