

EEE391 - Basics of Signals and Systems
Spring 2017
Computer Assignment 3

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Part 1

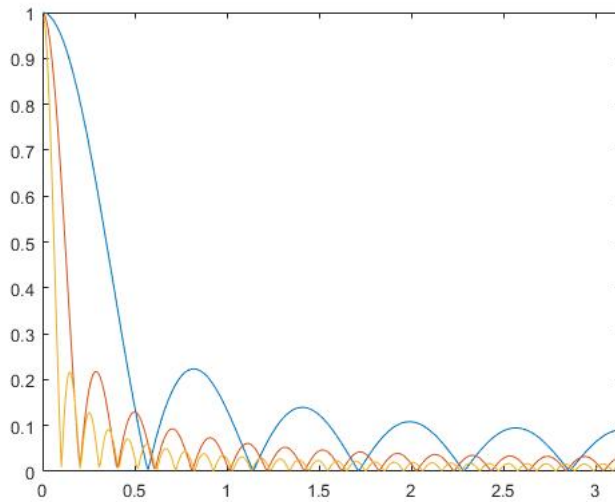


Figure 1: Plot of $H(\exp(-i\omega))$ values

i

This filter blurs the image.

ii

The details are getting less visible when the M value increases.

iii

The visual effect would not change.

iv

Since this filter was an averaging filter, on application the filter will average the values, smoothing it out.

v

The edges remain sharper than the inner parts of the image as we take 0 for the values out of index.



Figure 2: Original Image



Figure 3: $M = 11$ Averaging Filter



Figure 4: $M = 31$ Averaging Filter



Figure 5: $M = 61$ Averaging Filter



Figure 6: $c = 0.2$, $M = 11$

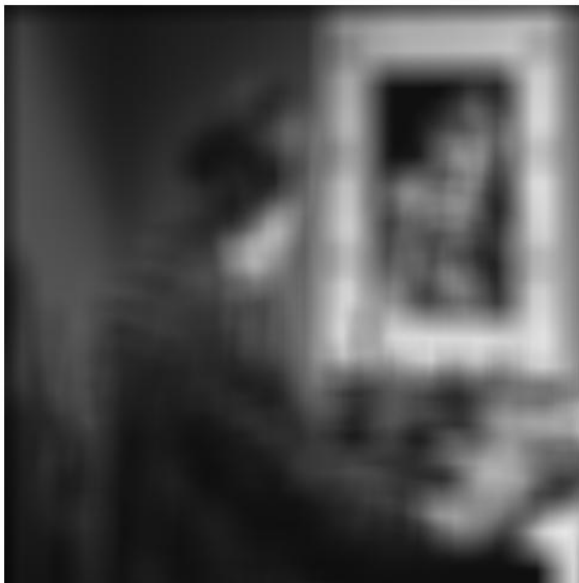


Figure 7: $c = 0.2$, $M=31$



Figure 8: $c = 0.2$, $M=61$



Figure 9: $c = 1$, $M=11$



Figure 10: $c = 1$, $M=31$

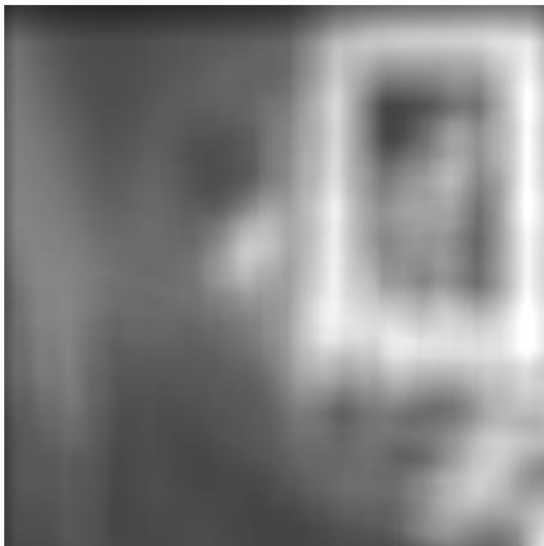


Figure 11: $c = 1$, $M=61$

vi

Yes it does. the noise reduces with larger M values.

vii

The image blurs, which may make the image unusable/non-understandable

vii

Out of the three $M = 11$ is the best choice.

Part 2

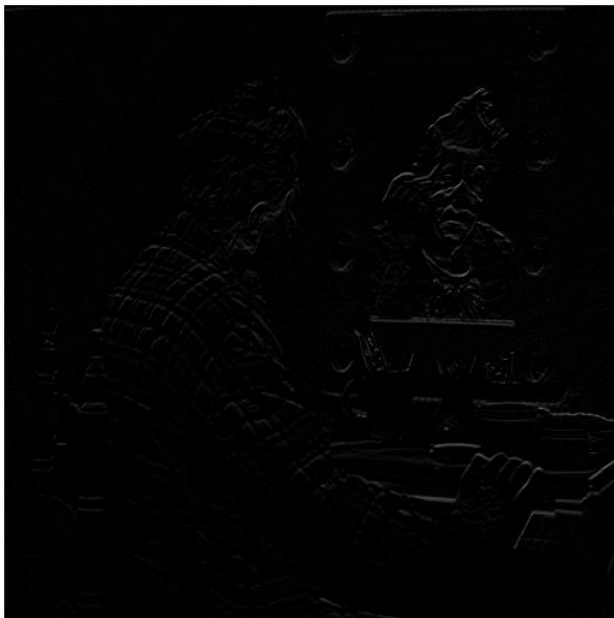


Figure 12: clown.bmp with a first differentiator filter

i

The whitest/brightest parts of the image is seen, since we subtract a certain amount from each pixel.

ii

I would expect it to be peaking in some points but mostly in the same level theoretically so it is similar to expectation.

iii



Figure 13: The first differentiator filter with reverse indicies.

Matlab Code

```
1 %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
2 %                                PART 1                                %
3 %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
4 A=imread('clown.bmp');
5 J=mat2gray(A, [0 255]);
6 %Averaging
7 A1 = conv2(J, ones(11,11)/121);
8 A2 = conv2(J, ones(31,31)/(31*31));
9 A3 = conv2(J, ones(61,41)/(61*41));
10 figure;
```

```

11 imshow(J);
12 figure;
13 imshow(A1(6:512-5,6:512-5));
14 figure;
15 imshow(A2(16:512-15, 16:512-15));
16 figure;
17 imshow(A3(31:512-30,31:512-30 ));
18 %Noise c = 0.2
19 J1= J + (rand(512,512)*((0.5)*0.2));
20 A1 = conv2(J1, ones(11,11)/121);
21 A2 = conv2(J1, ones(31,31)/(31*31));
22 A3 = conv2(J1, ones(61,41)/(61*41));
23 figure;
24 imshow(A1(6:512-5,6:512-5));
25 figure;
26 imshow(A2(16:512-15, 16:512-15));
27 figure;
28 imshow(A3(31:512-30,31:512-30 ));
29 %Noise c = 1
30 J2= J + (rand(512,512)*(0.5));
31 A1 = conv2(J2, ones(11,11)/121);
32 A2 = conv2(J2, ones(31,31)/(31*31));
33 A3 = conv2(J2, ones(61,41)/(61*41));
34 figure;
35 imshow(A1(6:512-5,6:512-5));
36 figure;
37 imshow(A2(16:512-15, 16:512-15));
38 figure;
39 imshow(A3(31:512-30,31:512-30 ));
40 %H values.
41 omega = -pi:pi/400:pi;
42 H11 = (1/11)*(1-exp(-1j*omega*11))./(1-exp(-1j*omega));
43 H31 = (1/31)*(1-exp(-1j*omega*31))./(1-exp(-1j*omega));
44 H61 = (1/61)*(1-exp(-1j*omega*61))./(1-exp(-1j*omega));
45 plot(omega,[abs(H11);abs(H31);abs(H61)]);
46 axis([0, pi, 0, 1]);
47
48 %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
49 %                                PART 2                                %
50 %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
51
52 for n = 1:512
53     for m = 2:512

```

```
54         A1(m,n) = J(m,n)-J(m-1,n);  
55     end  
56 end  
57 figure;  
58 imshow(A1(1:512,1:512));
```