AIRCRAFT AUTOPILOT/FLIGHT ASSISTANCE EVENTS

The event IDs listed here are all related to the aircraft autopilot and flight assistance systems.

Autopilot

> ***IMPORTANT!*** *The events listed here are* ***not*** *applicable and will not work correctly (if at all) when used with a helicopter.*

Event Name	Parameters	Description
`AP_AIRSPEED_HOLD`	N/A	Toggles airspeed hold mode
`AP_AIRSPEED_OFF`	N/A	Turns airspeed hold off
`AP_AIRSPEED_ON`	N/A	Turns airspeed hold on
`AP_AIRSPEED_SET`	[0]: TRUE/FALSE to enable/disable	Sets airspeed hold on/off (1,0)
`AP_ALT_VAR_DEC`	[0]: New reference altitude [1]: Index	Decrements the reference altitude.
`AP_ALT_VAR_INC`	[0]: New reference altitude [1]: Index	Increments the reference altitude.
`AP_ALT_HOLD`	N/A	Toggles altitude hold mode
`AP_ALT_HOLD_OFF`	N/A	Turns off altitude hold mode

`AP_ALT_HOLD_ON`	N/A	Turns altitude hold mode on
`AP_ALT_RADIO_MODE_OFF`	N/A	Deactivate autopilot radio altitude mode.
`AP_ALT_RADIO_MODE_ON`	N/A	Activate autopilot radio altitude mode.
`AP_ALT_RADIO_MODE_SET`	[0]: bool	Set autopilot radio altitude mode.
`AP_ALT_RADIO_MODE_TOGGLE`	N/A	Toggle autopilot radio altitude mode.
`AP_ALT_VAR_SET_ENGLISH`	[0]: New reference altitude [1]: Index	Sets altitude reference in feet
`AP_ALT_VAR_SET_METRIC`	[0]: New reference altitude [1]: Index	Sets reference altitude in meters
`AP_APR_HOLD`	N/A	Toggles approach hold (localizer and glide-slope)
`AP_APR_HOLD_OFF`	N/A	Turns off approach hold mode
`AP_APR_HOLD_ON`	N/A	Turns both AP localizer and glide-slope modes on/armed
`AP_ATT_HOLD`	N/A	Toggle attitude hold mode
`AP_ATT_HOLD_OFF`	N/A	Turns off attitude hold mode
`AP_ATT_HOLD_ON`	N/A	Turns on AP wing leveler and pitch hold mode
`AP_AVIONICS_MANAGED_OFF`	N/A	Turn off the Managed Avionics mode. This is linked to the SimVar `AUTOPILOT AVIONICS MANAGED`.
`AP_AVIONICS_MANAGED_ON`	N/A	Turn on the Managed Avionics mode. This is linked

		to the SimVar `AUTOPILOT AVIONICS MANAGED`.
`AP_AVIONICS_MANAGED_SET`	[0]: TRUE/FALSE to enable/disable	Set the autopilot managed avionics mode (TRUE for on, FALSE for off).
`AP_AVIONICS_MANAGED_TOGGLE`	N/A	Toggle on/off the avionics managed mode on the autopilot.
`AP_BANK_HOLD`	N/A	Toggles the autopilot bank hold mode on / off.
`AP_BANK_HOLD_OFF`	N/A	Turns off the autopilot bank hold mode.
`AP_BANK_HOLD_ON`	N/A	Turns on the autopilot bank hold mode.
`AP_BC_HOLD`	N/A	Toggles the backcourse mode for the localizer hold
`AP_BC_HOLD_OFF`	N/A	Turns off backcourse mode for localizer hold
`AP_BC_HOLD_ON`	N/A	Turns localizer back course hold mode on/armed
`AP_HDG_HOLD`	N/A	Toggles heading hold mode
`AP_HDG_HOLD_OFF`	N/A	Turns off heading hold mode
`AP_HDG_HOLD_ON`	N/A	Turns heading hold mode on
`AP_LOC_HOLD`	N/A	Toggles localizer (only) hold mode
`AP_LOC_HOLD_OFF`	N/A	Turns off localizer hold mode
`AP_LOC_HOLD_ON`	N/A	Turns AP localizer hold on/armed and glide-slope hold mode off
`AP_MACH_VAR_DEC`	[0]: the Index of the engine to	Decrements the reference mach by the amount set in

	target (1 - 4)	the systems.cfg using the `mach_increment` parameter. ***NOTE**: along with the `AP_MACH_VAR_DEC`, `AP_MACH_VAR_SET`, and `AP_MACH_VAR_SET_EX1` keys, this value is clamped to to the values given in the systems.cfg by the parameters `min_Mach_ref` and `max_Mach_ref` (or their default values if not set).*
`AP_MACH_VAR_INC`	[0]: Index of the engine to target (1 - 4)	Increments the reference mach by the amount set in the systems.cfg using the `mach_increment` parameter. ***NOTE**: along with the `AP_MACH_VAR_INC`, `AP_MACH_VAR_SET`, and `AP_MACH_VAR_SET_EX1` keys, this value is clamped to to the values given in the systems.cfg by the parameters `min_Mach_ref` and `max_Mach_ref` (or their default values if not set).*
`AP_MACH_HOLD`	N/A	Toggles mach hold
`AP_MACH_OFF`	N/A	Turns mach hold off
`AP_MACH_ON`	N/A	Turns mach hold on

`AP_MACH_SET`	[0]: TRUE/FALSE to enable/disable	Sets mach hold on/off (1,0)
`AP_MACH_VAR_SET`	[0]: Integer mach value / 100 (eg: 100 as value results as mach 1) [1]: Index of the engine to target (1 - 4)	Sets the mach reference. ***NOTE**: along with the `AP_MACH_VAR_DEC`, `AP_MACH_VAR_INC`, and `AP_MACH_VAR_SET_EX1` keys, this value is clamped to to the values given in the systems.cfg by the parameters `min_Mach_ref` and `max_Mach_ref` (or their default values if not set).*
`AP_MACH_VAR_SET_EX1`	[0]: Integer mach value \ 1000000 (eg: 1000 as value results as mach 0.001) [1]: Index of the engine to target (1 - 4)	Sets the mach reference using a precise value. ***NOTE**: along with the `AP_MACH_VAR_DEC`, `AP_MACH_VAR_INC`, and `AP_MACH_VAR_SET` keys, this value is clamped to to the values given in the systems.cfg by the parameters `min_Mach_ref` and `max_Mach_ref` (or their default values if not set).*
`AP_MANAGED_SPEED_IN_MACH_OFF`	N/A	Turns off the use of the mach value to compute airspeed used by AP.

AP_MANAGED_SPEED_IN_MACH_ON	N/A	Turns on the use of the mach value to compute airspeed used by AP.
AP_MANAGED_SPEED_IN_MACH_SET	[0]: use TRUE/FALSE to enabled/disable	Sets the use of the mach value to compute airspeed used by AP.
AP_MANAGED_SPEED_IN_MACH_TOGGLE	N/A	Toggle the use of the mach value to compute airspeed used by AP.
AP_MASTER	N/A	Toggles AP on/off
AP_MASTER_ALT ***Deprecated***		*No longer used in the simulation.* Use AP_MASTER instead.
AP_MAX_BANK_ANGLE_SET	[0]: angle	Set the bank angle for the aircraft and override the predefined max bank angle of the aircraft.
AP_MAX_BANK_INC	N/A	Increment the AP max bank angle index. Note that if there is only one index possible then using this event will do nothing. However if there are 2 or more available indices, this event will increase the index by 1, and when the number passes the maximum available indices - 1, it will loop back around again to index 0. For example, if you have 3 indices, the maximum index is 2, and incrementing past that will go to index 0. ***NOTE**: for further information on indices, please see the AP_MAX_BANK_SET event.*

`AP_MAX_BANK_DEC`	N/A	Decrement the AP max bank angle index. Note that if there is only one index possible then using this event will do nothing. However if there are 2 or more available indices, this event will decrease the index by 1, and when the number passes 0, it will loop back around again to the max index - 1 position. For example, if there are 4 indices, and you decrement from 0, the new index will be 3. ***NOTE**: for further information on indices, please see the `AP_MAX_BANK_SET` event.*
`AP_MAX_BANK_SET`	[0]: the index to use for max bank angle.	Sets the autopilot max bank angle index to the parameter [0] value, where the value is clamped between 0 and the number of available indices. The indices correspond to the number of values set for the `max_bank` table, plus index 0 which corresponds to the auto banking system. When `auto_max_bank` is enabled, setting the index to 0 will turn on the AP auto banking. To give an example, if the `max_bank` table has 2 values and `auto_max_bank` is enabled, then the indices for this event would be: • 0: use auto banking

		• 1: use the first value in the `max_bank` table • 2: use the second value in the `max_bank` table. If auto banking is not enabled, then setting this to 0 will have no effect.
`AP_MAX_BANK_VELOCITY_SET`	[0]: Velocity	Set the bank velocity of the aircraft and overrides the predifined maximum bank velocity of the aircraft.
`AP_N1_HOLD`	N/A	Autopilot, hold the N1 percentage at its current level.
`AP_N1_REF_DEC`	N/A	Decrement the autopilot N1 reference.
`AP_N1_REF_INC`	N/A	Increment the autopilot N1 reference.
`AP_N1_REF_SET`	[0]: Integer N1 reference value [1]: Index of the engine to target (1 - 4)	Sets the autopilot N1 reference.
`AP_NAV_SELECT_SET`	[0]: the NAVindex to use	Sets the NAV (1 or 2) which is used by the Nav hold modes
`AP_NAV1_HOLD`	N/A	Toggles the nav hold mode
`AP_NAV1_HOLD_OFF`	N/A	Turns off nav hold mode
`AP_NAV1_HOLD_ON`	N/A	Turns lateral hold mode on
`AP_PANEL_ALTITUDE_HOLD`	N/A	Toggles altitude hold mode on/off

AP_PANEL_ALTITUDE_OFF	N/A	Turns altitude hold mode off
AP_PANEL_ALTITUDE_ON	N/A	Turns altitude hold mode on (without capturing current altitude)
AP_PANEL_ALTITUDE_SET	[0]: TRUE/FALSE to enable/disable	Sets altitude hold mode on/off (1,0)
AP_PANEL_HEADING_HOLD	N/A	Toggles heading hold mode on/off
AP_PANEL_HEADING_OFF	N/A	Turns heading mode off
AP_PANEL_HEADING_ON	N/A	Turns heading mode on (without capturing current heading)
AP_PANEL_HEADING_SET	[0]: TRUE/FALSE to enable/disable	Set heading mode on/off (1,0)
AP_PANEL_MACH_HOLD	N/A	Toggles mach hold
AP_PANEL_MACH_OFF	N/A	Turns off mach hold
AP_PANEL_MACH_ON	N/A	Turns on mach hold
AP_PANEL_MACH_SET	[0]: TRUE/FALSE to enable/disable	Sets mach hold on/off (1,0)
AP_PANEL_SPEED_HOLD	N/A	Toggles airspeed hold mode
AP_PANEL_SPEED_OFF	N/A	Turns off speed hold mode
AP_PANEL_SPEED_ON	N/A	Turns on speed hold mode
AP_PANEL_SPEED_SET	[0]: TRUE/FALSE to enable/disable	Set speed hold mode on/off (1,0)
AP_PANEL_VS_OFF	N/A	Turn off the AP mode that maintains a vertical speed.

AP_PANEL_VS_ON	N/A	Turn on the AP mode that maintains a vertical speed.
AP_PANEL_VS_SET	[0]: TRUE/FALSE to enable/disable	Enables or diables the AP mode that maintains a vertical speed.
AP_PANEL_VS_HOLD	N/A	Toggles the AP mode that maintains a vertical speed.
AP_PITCH_LEVELER	N/A	Toggles the AP mode that maintains the pitch and sets the pitch reference to 0°.
AP_PITCH_LEVELER_OFF	N/A	Turns off the AP mode that maintains the pitch and sets the pitch reference to 0°.
AP_PITCH_LEVELER_ON	N/A	Turns on the AP mode that maintains the pitch and sets the pitch reference to 0°.
AP_PITCH_REF_INC_DN	N/A	Decrements the pitch reference for pitch hold mode
AP_PITCH_REF_INC_UP	N/A	Increments the pitch reference for pitch hold mode
AP_PITCH_REF_SELECT		Selects pitch reference for use with +/-
AP_PITCH_REF_SET	[0]: pitch value between -16384 and 16384	Sets the pitch reference value that will be maintained by the AP pitch hold mode. The pitch value supplied as parameter [0] will be divided by 16384 before being multiplied by the max_pitch value.
AP_RPM_SLOT_INDEX_SET	[0]: slot index from 1 to 4	Sets the managed index for the RPM hold mode.

AP_SPD_VAR_DEC	N/A	Decrements airspeed hold reference
AP_SPD_VAR_INC	N/A	Increments airspeed hold reference
AP_SPD_VAR_SET	[0]: value in *Knot*s. [1]: the managed index, from 1 to 4, or 0.	Sets airspeed reference in knots
AP_SPD_VAR_SET_EX1	[0]: value in *Knot*s. [1]: the managed index, from 1 to 4, or 0.	Set the airspeed reference, in knots, for the maintain speed AP mode. The speed supplied as parameter [0] will be divided by 100 to give you more precision with the value, for example: giving 55050 will result in an airspeed hold of 550.50 knots. For parameter [1], giving a value of 0 instead of a single index from 1 to 4, then the speed value will be copied to *all* managed indices.
AP_SPEED_SLOT_INDEX_SET	[0]: slot index from 1 to 4	Sets the managed index for the speed hold mode.
AP_VS_HOLD	N/A	Toggles the AP mode that maintains a vertical speed.
AP_VS_OFF	N/A	Turn off the AP mode that maintains a vertical speed.
AP_VS_ON	N/A	Turn on the AP mode that maintains a vertical speed.
AP_VS_SET	[0]: TRUE/FALSE to enable/disable	Sets the AP mode that maintains a vertical speed.

AP_VS_SLOT_INDEX_SET	[0]: slot index from 1 to 4	Sets the managed index for the vertical speed hold mode.
AP_VS_VAR_DEC	N/A	Decrements vertical speed reference
AP_VS_VAR_INC	N/A	Increments vertical speed reference
AP_VS_VAR_SET_CURRENT		Sets the current managed index vertical speed reference to be the current vertical speed (the current index can be set using AP_VS_SLOT_INDEX_SET). If no vertical speed indicator is on the aircraft, the vertical speed reference will calculated based on the world Y-axis velocity. Note that the resulting value will be clamped between the CFG parameters min_vertical_speed_ref and max_vertical_speed_ref.
AP_VS_VAR_SET_ENGLISH	[0]: New VS reference [1]: Index	Sets reference vertical speed in feet per minute
AP_VS_VAR_SET_METRIC	[0]: New VS reference [1]: Index	Sets vertical speed reference in meters per minute
AP_WING_LEVELER	N/A	Toggles wing leveler mode
AP_WING_LEVELER_OFF	N/A	Turns off wing leveler mode
AP_WING_LEVELER_ON	N/A	Turns wing leveler mode on
AP_PANEL_SPEED_HOLD_TOGGLE	N/A	Turns airspeed hold mode on with current airspeed

AP_PANEL_MACH_HOLD_TOGGLE	N/A	Sets mach hold reference to current mach
AUTOPILOT_AIRSPEED_ACQUIRE ***Legacy***	N/A	Triggers both the AP_SPD_VAR_SET (with value 0) event and the AP_AIRSPEED_ON event. ***NOTE**: This is a legacy event and you should be calling the above mentioned events directly.*
AUTOPILOT_DISENGAGE_SET	[0]: boolean value to enable/disable the disengage value	Set if the AP should be disengaged or not.
AUTOPILOT_DISENGAGE_TOGGLE	N/A	Toggle the status of the AP disengage value.
AUTOPILOT_OFF	N/A	Turns AP off
AUTOPILOT_ON	N/A	Turns AP on
AUTOPILOT_PANEL_AIRSPEED_SET	N/A	*Not currently used in the simulation.*
AUTOPILOT_PANEL_CRUISE_SPEED ***Deprecated***	N/A	*No longer used in the simulation.* Previously used by the Concorde flight model.
AUTOPILOT_PANEL_MAX_SPEED ***Deprecated***	N/A	*No longer used in the simulation.* Previously used by the Concorde flight model.
ALTITUDE_SLOT_INDEX_SET		Sets the index for the SimVar AUTOPILOT ALTITUDE LOCK VAR which the altitude

		hold mode will track when captured. See `alt_mode_slot_index` for more information.
`FLIGHT_LEVEL_CHANGE`	N/A	Toggles the autopilot *FLC* mode on or off. When on, the AP will adjust the engine power to try and fly the aircraft at a pitch attitude corresponding to the desired flight profile (climb or descent), while maintaining the airspeed reference.
`FLIGHT_LEVEL_CHANGE_OFF`	N/A	Turns off the autopilot *FLC* mode.
`FLIGHT_LEVEL_CHANGE_ON`	N/A	Turn on the autopilot *FLC* mode. This mode adjusts engine power to fly the aircraft at a pitch attitude corresponding to the desired flight profile (climb or descent), while maintaining the airspeed reference.
`HEADING_SLOT_INDEX_SET`		Set autopilot heading slot index.
`RPM_SLOT_INDEX_SET`		Set autopilot RPM slot index.
`SPEED_SLOT_INDEX_SET`		Set autopilot speed slot index.
`VS_SLOT_INDEX_SET`		Set autopilot vertical speed slot index.

Flight Assistance

Event Name	Parameters	Description

`AIRSPEED_BUG_SELECT`	[0]: the reference value	Selects the airspeed reference for use with +/-
`ALTITUDE_BUG_SELECT`	[0]: the reference value	Selects the altitude reference for use with +/-
`AUTO_THROTTLE_ARM`	N/A	Toggles autothrottle arming mode
`AUTO_THROTTLE_DISCONNECT`	[0]: The engine to target. Use 0 to target all engines, or 1 to 4 to target a specific engine.	Disconnect the AutoThrottle of the AP for one engine or all engines.
`AUTO_THROTTLE_TO_GA`	N/A	Toggles Takeoff/Go Around mode
`AUTOBRAKE_DISARM`	N/A	Sets the autobrake switch to either : • the off position (position 1) when the `auto_brakes` parameter is greater than 0. • the *RTO* position (position 0) when the `auto_brakes` parameter is 0.
`AUTOBRAKE_HI_SET`	N/A	Sets the autobrake switch to the maximum position (ie: the `auto_brakes` number, so that the maximum braking force will be applied).
`AUTOBRAKE_LO_SET`	N/A	Sets the autobrake switch to the minimum position (position 2, the first position after the off position).

AUTOBRAKE_MED_SET	N/A	Sets the autobrake switch to a medium position (the exact position will depend on the number of autobreaks defined by the auto_brakes parameter).
DECREASE_AUTOBRAKE_CONTROL	N/A	Decrements the autobrake level by 1. When the level reaches 0, autobreaks will be off, and the event will no longer decrement further.
FLY_BY_WIRE_ELAC_TOGGLE	N/A	Turn on or off the fly by wire Elevators and Ailerons computer.
FLY_BY_WIRE_FAC_TOGGLE	N/A	Turn on or off the fly by wire Flight Augmentation computer.
FLY_BY_WIRE_SEC_TOGGLE	N/A	Turn on or off the fly by wire Spoilers and Elevators computer.
GPWS_SWITCH_TOGGLE	N/A	Turn the ground proximity warning system (GPWS) on or off.
HEADING_BUG_DEC	N/A	Decrements heading hold reference bug
HEADING_BUG_INC	N/A	Increments heading hold reference bug
HEADING_BUG_SELECT	[0]: heading bug index	Selects the heading bug for use with +/-
HEADING_BUG_SET	[0]: Value in degrees [1]: Index	Set the heading hold reference bug in degrees. The event takes integer values only, from 0º to 360º.
AP_HEADING_BUG_SET_EX1	[0]: Value between 0 and 16384	Set the heading hold reference bug. This is the

	[1]: Index	same as the `HEADING_BUG_SET` event only it permits a much greater degree of precision by permitting the input of a larger integer value that is then transformed by the simulation into a floating point heading. The way this works is that the integer value you supply is multiplied by (360/16384) to give the correct higher precision value, for example if you supply the value 477, you're heading would be calculated like this:
		`input value: 477`
		`process: 477 * (360/16384)`
		`actual value: 10.504º`

`INCREASE_AUTOBRAKE_CONTROL`	N/A	Increases the autobrake level by 1. When the level reaches the `auto_brakes` value, the event will no longer increment further.
`SET_AUTOBRAKE_CONTROL`	[0]: autobreak level	Uses the input parameter [0] to set the autobreak level from 0 (off) to the value set for the `auto_brakes` parameter (maximum breaking). If a value greater than that specified for `auto_brakes` is given as input, it will be clamped to the `auto_brakes` value.

SYNC_FLIGHT_DIRECTOR_PITCH	N/A	Synchronizes flight director pitch with current aircraft pitch
TOGGLE_FLIGHT_DIRECTOR	N/A	Toggles flight director on/off
YAW_DAMPER_TOGGLE	N/A	Toggles yaw damper on/off
YAW_DAMPER_ON	N/A	Turns yaw damper on
YAW_DAMPER_OFF	N/A	Turns yaw damper off
YAW_DAMPER_SET	[0]: enable/disable yaw damper (TRUE, FALSE)	Sets yaw damper on/off (1,0)
VSI_BUG_SELECT	[0]: reference value	Selects the vertical speed reference for use with +/-

G1000 (Multi-Function Display)

Event Name	Parameters	Description
G1000_MFD_CLEAR_BUTTON	N/A	Clears the current input.
G1000_MFD_CURSOR_BUTTON	N/A	Toggles on or off a screen cursor.
G1000_MFD_DIRECTTO_BUTTON	N/A	Turn to the Direct To page.
G1000_MFD_ENTER_BUTTON	N/A	Enters the current input.
G1000_MFD_FLIGHTPLAN_BUTTON	N/A	The multi-function display (MFD) should display its current flight plan.
G1000_MFD_GROUP_KNOB_DEC	N/A	Step down through the page groups.

G1000_MFD_GROUP_KNOB_INC	N/A	Step up through the page groups.
G1000_MFD_MENU_BUTTON	N/A	If a segmented flight plan is highlighted, activates the associated menu.
G1000_MFD_PAGE_KNOB_DEC	N/A	Step down through the individual pages.
G1000_MFD_PAGE_KNOB_INC	N/A	Step up through the individual pages.
G1000_MFD_PROCEDURE_BUTTON	N/A	Turn to the Procedure page.
G1000_MFD_SOFTKEY1 G1000_MFD_SOFTKEY2 G1000_MFD_SOFTKEY3 G1000_MFD_SOFTKEY4 G1000_MFD_SOFTKEY5 G1000_MFD_SOFTKEY6 G1000_MFD_SOFTKEY7 G1000_MFD_SOFTKEY8 G1000_MFD_SOFTKEY9 G1000_MFD_SOFTKEY10 G1000_MFD_SOFTKEY11 G1000_MFD_SOFTKEY12	N/A	Initiate the action for the icon displayed in the softkey position.
G1000_MFD_ZOOMIN_BUTTON	N/A	Zoom in on the current map.
G1000_MFD_ZOOMOUT_BUTTON	N/A	Zoom out on the current map.
G1000_PFD_CLEAR_BUTTON	N/A	Clears the current input.
G1000_PFD_CURSOR_BUTTON	N/A	Turns on or off a screen cursor.
G1000_PFD_DIRECTTO_BUTTON	N/A	Turn to the Direct To page.
G1000_PFD_ENTER_BUTTON	N/A	Enters the current input.

`G1000_PFD_FLIGHTPLAN_BUTTON`	N/A	The primary flight display (PFD) should display its current flight plan.
`G1000_PFD_GROUP_KNOB_INC`	N/A	Step up through the page groups.
`G1000_PFD_GROUP_KNOB_DEC`	N/A	Step down through the page groups.
`G1000_PFD_MENU_BUTTON`	N/A	If a segmented flight plan is highlighted, activates the associated menu.
`G1000_PFD_PAGE_KNOB_INC`	N/A	Step up through the individual pages.
`G1000_PFD_PAGE_KNOB_DEC`	N/A	Step down through the individual pages.
`G1000_PFD_PROCEDURE_BUTTON`	N/A	Turn to the Procedure page.

`G1000_PFD_SOFTKEY1`
`G1000_PFD_SOFTKEY2`
`G1000_PFD_SOFTKEY3`
`G1000_PFD_SOFTKEY4`
`G1000_PFD_SOFTKEY5`
`G1000_PFD_SOFTKEY6`
`G1000_PFD_SOFTKEY7`
`G1000_PFD_SOFTKEY8`
`G1000_PFD_SOFTKEY9`
`G1000_PFD_SOFTKEY10`
`G1000_PFD_SOFTKEY11`
`G1000_PFD_SOFTKEY12`
	N/A	Initiate the action for the icon displayed in the softkey position.

`G1000_PFD_ZOOMIN_BUTTON`	N/A	Zoom in on the current map.
`G1000_PFD_ZOOMOUT_BUTTON`	N/A	Zoom out on the current map.