

inv.m

Do not import this package directly. `inv.m` memoise many values automatically and is imported or cleared by `group.m`.

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Symmetry

`symmetryGroup`

`symmetryGroup` represents the global symmetry of CFT.

`clearCG`

`clearCG[]` clears all values calculated by this package.

Clebsch-Gordan Coefficients

irrep-object

An irrep-object `r` is a symbol such that `symmetryGroup[isrep[r]]` is True. We use `r,s,t,r1,r2,...` to denote irrep-objects, and `id` is the irrep-object of the trivial irrep. `a,b,c,a1,a2,...` are indices of irreps. An index `a` of irrep `r` must satisfy `1 <= a <= symmetryGroup[dim[r]]`. `n,m` represents multiplicity of Clebsch-Gordan coefficients. For more information, please refer to [arXiv:1903.10522](#).

`inv`

`inv[r,s,t]` gives multiplicity of `id` in decomposition of $r \otimes s \otimes t$.

`inv[{r,s},{t}]` gives multiplicity of `t` in decomposition of $r \otimes s$.

`inv[r1,r2,r3,r4]` gives an association whose key is a irrep `s` such that `inv[{r1,r2},{s}]>0` and `inv[r3,r4,s]>0`, whose value is a list `{inv[{r1,r2},{s}], inv[r3,r4,s]}`.

`invs`

`invs[r1,r2,r3,r4]` gives a list of `{s,n,m}` such that `cor[r1,r2,r3,r4][s,n,m]` is defined.

`ope`

`ope[r,s,t][n][a,b,c]` gives Clebsch-Gordan coefficient defined by $|r,a\rangle\langle s,b| = \sum_c \text{ope}[r,s,t][n][a,b,c] |t,c\rangle$.

`ope[r][a,b]` gives $\sqrt{\dim[r]} \text{ope}[r,\text{dual}[r],\text{id}][1][a,b,1]$.

`cor`

`cor[r,s,t][n][a,b,c]` gives $\sum_c \text{ope}[r,s,\text{dual}[t]][n][a,b,c2] \text{ope}[\text{dual}[t]][c2,c] / \sqrt{\dim[t]}$.

`cor[r1,r2,r3,r4][s,n,m][a1,a2,a3,a4]` gives $\sum_c \text{cor}[r1,r2,\text{dual}[s]][n][a1,a2,b] \text{ope}[r3,r4,\text{dual}[s]][a3,a4,b]$.

Symmetries of CG Coefficients

`\[Sigma]`

`\[Sigma][r,s,t][n]` gives the sign change in swap between `r` and `s` in `cor`, i.e. $\text{cor}[r,s,t][n][a,b,c] = \text{\[Sigma]}[r,s,t][n] \text{cor}[s,r,t][n][b,a,c]$.

`\[Sigma][r]` gives $\text{\[Sigma]}[r,\text{dual}[r],\text{id}]$.

`\[Sigma][op[x,r,p,q]]` gives `p`.

`\[Tau]`

`\[Tau][r,s,t][n,m]` describes the behavior of `cor` under cyclic permutation of `r,s,t`, i.e. $\text{cor}[s,t,r][m][b,c,a] = \sum_c \text{cor}[r,s,t][n][a,b,c] \text{\[Tau]}[r,s,t][n,m]$.

`\[Omega]`

`\[Omega][r,s,t][n,m]` describes the behavior of `cor` under complex conjugate, i.e. $\sum_c \text{ope}[\text{dual}[r]][a2,a] \text{ope}[\text{dual}[s]][b2,b] \text{ope}[\text{dual}[t]][c2,c] \text{cor}[\text{dual}[r],\text{dual}[s],\text{dual}[t]][m][a2,b2,c2] \text{\[Conjugate]} = \sum_c \text{cor}[r,s,t][n][a,b,c] \text{\[Omega]}[r,s,t][n,m]$.

`six`

`six[r1,r2,r3,r4][s,n,m,t,k,l]` describes the behavior of `cor` under swap between `r2` and `r4`, i.e. $\text{cor}[r1,r4,r3,r2][t,k,l][a1,a4,a3,a2] = \sum_c \text{cor}[r1,r2,r3,r4][s,n,m][a1,a2,a3,a4] \text{six}[r1,r2,r3,r4][s,n,m,t,k,l]$.

`isReal`

`isReal[r]` gives whether `r` is a real representation or not.

`isComplex`

`isComplex[r]` gives whether `r` is a complex representation or not.

`isPseudo`

`isPseudo[r]` gives whether `r` is a pseudo real representation or not.

Conformal Blocks

op

`op[x,r,p,q]` represents a primary operator object O whose name is `x`, which belongs to irrep `r`, which sign ($=\backslash[\text{Sigma}][O]$) is `p` and whose parity of spin is `q` ($=\pm 1$). If O appears in summation, we use 'op' as its name.

`op[x,r]` is a short-hand for `op[x,r,1,1]`.

`op[x]` is a short-hand for `op[x,r,1,1]` if you registered `op[x,r,1,1]` as a fundamental scalar.

dualOp

`dualOp[op[x,r,p,q]]` gives dual operator object of `op[x,r,p,q]`.

format

`format[eq]` gives readable format of `eq` with little loss of information. We need much redundancy to calculate properly, so formatted value cannot be used for any argument of our function. `format[eq]` is assumed to be used only for human-readability of last output.

sum

`sum[x,op[op,r,1,q]]` represents sum of `x` over all intermediate primary operator $O=\text{op}[op,r,1,q]$ which belongs to irrep `r` and whose parity of spin is `q`. `sum[...]` is automatically expanded so as `x` to be $(F \text{ or } H)*\backslash[\text{Beta}]^2$.

single

`single[x]` represents `x`. We need to wrap `x` for redundancy. `single[...]` is automatically expanded so as `x` to be $(Fp \text{ or } Hp)*\backslash[\text{Beta}]^2$, or $(Fp \text{ or } Hp)$.

F

`F[o1,o2,o3,o4,s,p]` represents generalized conformal block $F_{\{p,s\}^{\{1,2,3,4\}}}$, where `o1,...,o4` are primary scalars.

`F[a,b,c,d]` represents normal conformal block of type-F.

H

`H[a,b,c,d]` represents normal conformal block of type-H.

Fp

`Fp[o1,o2,o3,o4,o]` represents generalized conformal block $F_{\{o\}^{\{1,2,3,4\}}}$, where `o1,...,o4` and intermediate `o` are primary scalars.

`Fp[a,b,c,d,o]` represents normal conformal block of type-F with intermediate `o`.

Hp

Hp[a,b,c,d,o] represents normal conformal block of type-H with intermediate o.

OPE Coefficients

$\backslash[\text{Lambda}]$

$\backslash[\text{Lambda}][o_1,o_2,o_3][n]$ gives n-th OPE coefficient of $o_1 \backslash[\text{Times}] o_2 \backslash[\text{Rule}] \text{OverBar}[o_3]$.

$\backslash[\text{Alpha}]$

$\backslash[\text{Alpha}][o_1,o_2,o_3][n]$ gives n-th coefficient of three-point function $\backslash[\text{LeftAngleBracket}] o_1 o_2 o_3 \backslash[\text{RightAngleBracket}]$.

$\backslash[\text{Mu}]$

$\backslash[\text{Mu}][o_1,o_2,o_3][n]$ gives n-th OPE coefficient of $o_1 \backslash[\text{Times}] o_2 \backslash[\text{Rule}] \text{OverBar}[o_3]$, where o3 is registered as a fundamental scalar.

$\backslash[\text{Nu}]$

$\backslash[\text{Nu}][o_1,o_2,o_3][n]$ gives n-th coefficient of three-point function $\backslash[\text{LeftAngleBracket}] o_1 o_2 o_3 \backslash[\text{RightAngleBracket}]$, where o3 is registered as a fundamental scalar."

$\backslash[\text{Beta}]$

$\backslash[\text{Beta}][o_1,o_2,o_3][n]$ gives minimal basis to describe $\backslash[\text{Lambda}]$, $\backslash[\text{Alpha}]$, etc.

$\backslash[\text{Lambda}]$, $\backslash[\text{Alpha}]$, $\backslash[\text{Mu}]$ and $\backslash[\text{Nu}]$ are linear combination of $\backslash[\text{Beta}]$.

Bootstrap Equations

eqn

eqn[{a,b,...}] represents bootstrap equation that claims a,b,... must equals to 0, where a,b,... are real-linear combination of sum and single.

eqn[sec,{a,b,...}] represents extracted part of eqn[{...}] which contains only sum or single related to sec.

bootAll

bootAll[ops] generates bootstrap equation from all four-point functions of ops.

bootAll[] generates bootstrap equation from all four-point functions of fundamental scalars.

setOps

setOps[ops] registers ops and duals of ops as fundamental scalars.

Fundamental scalars are used to separate sum of conformal blocks over scalars to `single[...]` and `sum[...]`.

`one`

`one` represents the unit operator. This is implicitly registered as a fundamental scalar.

`extract`

`extract[x,op[op,r,1,p]]` extracts terms of the form `sum[... ,op[op,r,1,p]]` from `x`.

`extract[x,scalar]` extracts terms of the form `single[(Fp or Hp)*\[Beta]^2]` from `x`.

`extract[x,unit]` extracts terms of the form `single[Fp or Hp]` from `x` (contribution of the unit operator).

`extract` is a projection: `x == extract[x,unit] + extract[x,scalar] + \[Sum]_{r,p} extract[x,op[op,r,1,p]]` and `extract[x,sec] == extract[extract[x,sec]]`.

`unit`

`unit` is a option for `extract` and means contribution of unit operator.

`scalar`

`scalar` is a option for `extract` and means contribution of fundamental scalars but unit operator.

`sector`

`sector[eq]` gives a list of all nontrivial option `sec` for `extract` applied to `eq`, i.e. `{sec | extract[eq,sec] != 0}`.

Conversions of Bootstrap Equations

`makeG`

`makeG[eqn[sec,{a,b,...}]]` gives an undirected graph whose vertices are OPE coefficients `\[Beta]` in extracted bootstrap equation `eqn[sec,{a,b,...}]`.

`makeMat`

`makeMat[eqn[sec,{a,b,...}]]` gives a matrix-representation of extracted bootstrap equation `eqn[sec,{a,b,...}]`.

`makeSDP`

`makeSDP[eqn[{a,b,...}]]` converts whole bootstrap equation `eqn[{a,b,...}]` into sdp-object.

`sdpobj`

`sdpobj[secs,scalarnum,vals,mats]` is a sdp-object. `secs` is section data of bootstrap equation. `scalarnum` is the number of connected components in scalar sections. `vals` are real constants in bootstrap equation. `mats` are matrix-representation of bootstrap equation.

toQboot

toQboot[sdp] converts sdp-object into `c++` code for `qboot`.

toCboot

toCboot[sdp] converts sdp-object into `python` code for `cboot`.

toTeX

toTeX[eq] gives `LaTeX` string of `eq` (you need call `Print[toTeX[eq]]` to paste to your `tex` file).

toTeX[eqn[{a,b,...}]] gives `LaTeX` string of `eq` with `align` environment (you need call `Print[toTeX[eq]]` to paste to your `tex` file).

repToTeX

repToTeX[r] is needed to transrate irrep-object `r` as `LaTeX` string. Please set appropriate value.

opToTeX

opToTeX[o] is needed to transrate operator name `o` as `LaTeX` string. Please set appropriate value.