

## Sheet 8

$$1) \Delta X_t = \beta_0 + \alpha t + \beta_1 X_{t-1} + u_t$$

I don't get why this term ~~doesn't~~ imply that as  $t \rightarrow \infty, \Delta X_t \rightarrow \infty$ . There must be some cancelling out happening?

I think it does.

If  $X_t \sim I(1)$ , it's the cumulation of a stationary series. So then  $\Delta X_t := X_t - X_{t-1} = \beta_0 + \alpha t + (\beta_1 - 1)X_{t-1} + u_t$  will have  $\delta := \beta_1 - 1 = 0$ , since  $\{X_t\}$  is AR(p) with unit root ( $\Rightarrow \{\Delta X_t\}$  is AR(p-1)).

So the relevant  $H_0: \delta = 0, H_1: \delta < 0$ .

Let  $X_t$  be an AR(p) process, i.e.  $X_t = \beta_0 + \alpha t + \beta_1 X_{t-1} + \dots + \beta_p X_{t-p} + u_t$ . Then  $\Delta X_t := X_t - X_{t-1} = \beta_0 + \alpha t + \beta_1 X_{t-1} + \sum_{i=1}^{p-1} \beta_i \Delta X_{t-i} + u_t$  and define  $\delta := \beta_1 - 1$ .

The slides

sum up to  $\delta$ , but  
the notes only to

$\beta_1 - 1$ , in

$\sum_{i=1}^p \beta_i \Delta X_{t-i}$ .

Seems like  $\beta_1 = 0$ ?

So we can regress  $\Delta X_t$  onto  $X_{t-1}$  and

$p-1$  lags of  $\Delta X_t$ , and obtain  $\delta$  as above by OLS.

Because you could just short from  $\Delta X_t$  here?

If our alternative  $X_t \sim I(0)$  holds, then  $X_t$  itself is stationary. This implies that  $\sum \beta_i < 1$  (given that (by the requirements for stationarity of AR(p) processes) and thus  $\delta < 0$ ).

Conversely, if  $X_t \sim I(1)$  then it has a unit root, i.e.  $\sum \beta_i = 1$  (exactly one).

**we'll clear this up in class**

So  $H_0: \delta = 0, H_1: \delta < 0$ . We can then calculate the test

Statistic  $t := \frac{\hat{\delta}}{\text{se}(\hat{\delta})} \xrightarrow{\text{DF}_{tr}}$  and find the appropriate  $c_\alpha$  to compare it against.

**Great** rejecting  $H_0$  iff  $t < c_\alpha$ .

b). Advantage: without including an  $\alpha t$  term, we exclude the possibility under  $H_0$  of  $\{X_t\}$  containing a deterministic trend, because  $H_1$  corresponds to stationarity, where by definition  $\mu_t$  must be time-invariant. So we might incorrectly fail to reject  $H_0$  (i.e. we increase our Type II errors) when  $\{X_t\}$  does have drift.

✓ Disadvantage: the  $D\bar{F}_{tr}$  distribution is shifted left even further than our  $D\bar{F}_{cn}$ , so the critical values are smaller more negative and thus we lose power.

c) You could use an information criterion such as BIC or AIC and find the  $p^*$  which minimises loss. Alternatively, you could use stepwise testing from  $p_{max}$  on the hypothesis  $H_0: p_{max} = 0$ , and then reducing  $p$  until you reject  $H_0$ .

✓ d) AIC suggests  $\gamma_t$  is  $AR(2)$  and  $C_t$  is  $AR(3)$ , since we want  $\min_p AIC(p)$ . Stepwise testing at the 1% level gives us the same conclusion, looking at the t-prob column.

✓  $C_{1,1} = -3.96$  and in both cases we fail to reject that  $X_t$  has a unit root but do reject that  $\Delta X_t$  has a unit root, so both are  $I(1)$ , since we look for  $t^{obs} < C_\alpha$ .

e) i. We've already verified that  $\gamma_t, C_t \sim I(1)$ . So now we can proceed to regressing  $\gamma_t$  onto  $C_t$  and calculating the residual  $\{\xi_t\}$  in the model  $\gamma_t = C_t + \xi_t$ . If  $\gamma_t$  and  $C_t$  really are cointegrated with  $\theta=1$ , then  $\xi_t$  will be  $I(0)$ , so we can/should perform an ADF test to check this with a null that  $\xi_t \sim I(1)$  because  $\gamma_t$  and  $C_t$  aren't cointegrated with  $\theta=1$  and thus  $\xi_t$  inherited a stochastic trend.

ii. Similarly to above, except we need to estimate  $\hat{\theta}$  by OLS with the model  $\gamma_t = \hat{\theta} C_t + \xi_t$  before computing residuals. For our ADF test, use the adjusted Engle-Granger  $C_\alpha$ .

2a) [Do you ever include lags of  $C_t$  /  $\gamma_t$  in the regression being done here?]

→ Not for what we'll be concerned with.

2a) We have  $\pi_t = \beta_0 + \beta_1 \pi_{t-1} + u_t$  and want to test  $H_0: \beta_1 = 0$  vs  $H_1: \beta_1 \neq 0$ . Our t-statistic  $t = 21$ .

What is the dist. of  $t$  under the null?

We wouldn't expect the  $N(0, 1)$  to be appropriate here, because our residuals are we're dealing with a unit root process and so CLTs

Hmm, so  $\pi_t$  is unit root, but likely not  $\pi_t$ , given this regression output.

do not apply. However, the t-statistic is extremely large so we can surely reject  $H_0$  at the 5% level, whatever the limiting distribution.

b)  $\pi_{2017Q2|2017Q1} = 0.68 + 0.84 \times 0.002 = \text{rough } 2.36\%$

Because  $\beta_i$  is close to 1, our estimate  $\hat{\beta}_i = 0.84$  is heavily biased downwards, and this affects accuracy/reliability.

c) Our  $\beta_i$ 's are now further from 1, so the bias should be reduced.

In principle,  
run an F  
test.

- However, it seems surprising that the effect sizes ~~are~~ ~~is~~ larger for  $t=2$  and  $t=3$  than of the second and third lags of  $\Delta \pi_t$  have larger effects than the first lag, and that the direction of the effect switches. [Maybe interpreting this is finicky because of the  $\Delta$ s though]
- The effect sizes are small relative to the STs and the some of the 95% CIs look likely to cross 0.

d) ~~What does this mean?~~ Note that we could also express her model as

$$\pi_t = 0.467 + 0.706 \pi_{t-1} - 0.067 \pi_{t-2} + 0.45 \pi_{t-3} - 0.196 \pi_{t-4} + u_t$$

$$\text{since } \Delta \pi_{t-i} := \pi_{t-i} - \pi_{t-i-1}.$$

seems like ↴

we could potentially test here whether

$\Delta \pi_t$  is AR(3)  $\Leftrightarrow \pi_t$  is AR(4) and has a unit root. (\*)

$\sum \beta_i > 1$ , though calculating the variance of the sum would be hard because of dependence.

Suppose  $\pi_t = \beta_0 + \beta_1 \pi_{t-1} + \beta_2 \pi_{t-2} + \beta_3 \pi_{t-3} + \beta_4 \pi_{t-4} + u_t$ .  
Then  $\Delta \pi_t := \pi_t - \pi_{t-1} = \beta_0 + (\beta_1 - 1) \pi_{t-1} + \beta_2 (\pi_{t-1} - \Delta \pi_{t-1}) + \beta_3 (\pi_{t-2} - \Delta \pi_{t-1} - \Delta \pi_{t-2}) + \beta_4 (\pi_{t-3} - \Delta \pi_{t-2} - \dots) + u_t$   
 $= \beta_0 + (\beta_1 + \beta_2 + \beta_3 + \beta_4 - 1) \pi_{t-1} + (-\beta_2 - \beta_3 - \beta_4) \Delta \pi_{t-1} + (-\beta_3 - \beta_4) \Delta \pi_{t-2} - \beta_4 \Delta \pi_{t-3} + u_t$

I guess this is really just a proof of  $\sum \beta_i = 1$ ?  
 $=: \beta_0 + \gamma \pi_{t-1} + \sum_{i=1}^3 \gamma_i \Delta \pi_{t-i} + u_t$ .

The unit root condition  $\sum_{i=1}^3 \beta_i = 1$  can thus be captured by

✓

**Looks right!**

④

Am confused  
well.

the statement  $\delta = 0$ . We're effectively performing an ADF test (?), and so have  $H_0: \delta = 0$  vs  $H_1: \delta < 0$  corresponding to  $\Delta \pi_t$  being AR(3) vs ???.

$$\text{Our test statistic } t = \frac{\text{obs} - 0.107}{\text{std}} = -2.610 *$$

$$\text{And } t \xrightarrow{d} DF_{n-1}. \text{ So } c_{107} = -2.57, c_{35} = -2.86.$$

(I think we're just doing a constant-only ADF test?)

we fail to reject  $H_0$  at the 5% level.

e) we're interested in whether the parameters of our time series process might have changed as we entered/exited the 1979-1987 epoch. Specifically, perhaps more aggressive responsiveness in MP to inflation deviations meant that previous-period lags of  $\pi_t$  were less useful in predicting  $\pi_t$ .

We could use the QLT test to investigate this: for a variety of  $T \in \{1979Q3, \dots, 1987Q3\}$ , fit models with added break-point dummies of the form  $\gamma_0 D_T(t), \gamma_i D_T(t) \pi_{t-i}$ , where  $D_T(t) = 1$  if  $t \geq T$  and 0 otherwise. Then we can (implicitly) perform an F test of whether some  $\gamma_i$  is nonzero for each choice of  $T$ , and then check for significance at the  $T$  which maximises  $F(T)$ . Rejecting  $H_0$  would mean we had evidence that Volcker's tenure led to structural changes in how inflation evolves.

We might also simply look at a plot of  $\pi_t$  and see whether there are any obvious changes to its variance, ACF, or mean in this epoch.

[Maybe you'd want to allow for multiple breakpoints, incl. some outside his tenure. But probably then you'd end up with extremely low power.]

3)  $\hat{Y}_t = \beta_0 + \beta_1 Y_{t-1} + \beta_2 Y_{t-2} + u_t$ , where  $\{u_t\}$  is stationary and unforecastable white noise with  $\mu=0$

a)  $\{Y_t\}$  has a unit root iff  $\beta_1 + \beta_2 = 0$ .

$$\begin{aligned} b) \Delta Y_t &:= Y_t - Y_{t-1} = \beta_0 + (\beta_1 - 1) Y_{t-1} + \beta_2 (Y_{t-1} - \Delta Y_{t-1}) + u_t \\ &= \beta_0 + (\beta_1 + \beta_2 - 1) Y_{t-1} - \beta_2 \Delta Y_{t-1} + u_t \end{aligned}$$

but since  $\{Y_t\}$  is unit root,  $\beta_1 + \beta_2 - 1 = 0$

$$= \beta_0 + \underline{\beta_2} \Delta Y_{t-1} + u_t =: \gamma_0 + \underline{\gamma_1} \Delta Y_{t-1} + u_t$$

[Hm, this Q makes me think my answer to 2d) must've been needlessly long-winded]

c) If  $\Delta Y_t$  is stationary, then one differencing of  $Y_t$  was required to reach stationarity. So by definition,  $Y_t \sim I(1)$ , since it's the cumulation of an  $I(0)$  process - namely,  $\Delta Y_t$ .

Note that given  $|f|, |l| < 1$ , it straightforwardly follows that  $\{\Delta Y_t\}$  is stationary, by the condition for AR(1) processes. (with suitable conditions on  $\Delta Y_0$ ), and vice versa. So we don't really need both parts of the "Suppose" statement here.

$$\begin{aligned} d) Y_t &= Y_0 + \sum_{j=1}^t \Delta Y_j \quad \text{as stated above, and } \mathbb{E}[\Delta Y_t] =: \mu \text{ the unconditional, time-invariant mean.} \\ &= Y_0 + \mu t + \sum_{j=1}^t (\Delta Y_j - \mu) \\ &=: Y_0 + \mu t + \sum_{s=1}^t v_s \quad \text{with } v_s \text{ inheriting stationarity from } \Delta Y_t \text{, and demeaned.} \end{aligned}$$

i. Since  $\mathbb{E}[\Delta Y_t] = \mathbb{E}[\Delta Y_{t-1}]$ , we have

$$\mathbb{E}[\Delta Y_t] = \mathbb{E}[Y_0 + f, \Delta Y_{t-1} + u_t]$$

mean zero

$$\therefore \mathbb{E}[\Delta Y_{t-1}] = \gamma_0 + \gamma_1 \mathbb{E}[Y_{t-1}] + \cancel{\mathbb{E}[u_t]} \quad \text{by linearity}$$

$$\therefore \mathbb{E}[\Delta Y_t] := \mu = \frac{\gamma_0}{1-\gamma_1} = \frac{\beta_0}{1+\beta_2}$$

ii.  $v_t := \Delta Y_t - \mathbb{E}[\Delta Y_t]$  (is that it?)

$$= \gamma_0 + \gamma_1 \Delta Y_{t-1} + u_t - \cancel{\frac{\gamma_0}{1-\gamma_1} \mu}, \text{ where } \Delta Y_{t-1} = v_{t-1} + \mu$$

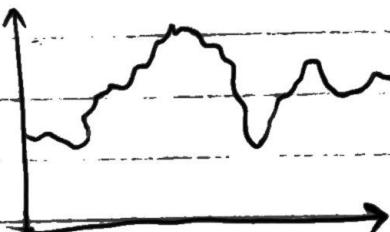
so  $v_t = \gamma_0 + \gamma_1 v_{t-1} + (\gamma_1 - 1)\mu + u_t$  different in practice?  
 $= \gamma_1 v_{t-1} + u_t$  (refc uncorr  $\Rightarrow$  indep, but does it matter?)

- e)  $\sum_{s=1}^t v_s$  is a random walk iff it's the sum of ~~independent, mean zero~~ stationary random variables. For this to be, we need  $\text{cov}(v_t, v_{t+h}) = 0$  for all  $t, h$ . (we know it's time-invariant already, by stationarity).   
 serially uncorrelated,

recall that for an <sup>AR(2)</sup> stationary process, the  $\text{ACF}(h) = |\beta_1|^h$ . In this case, then, we require  $\gamma_1 = 0$ , i.e.  $\beta_2 = 0$ .

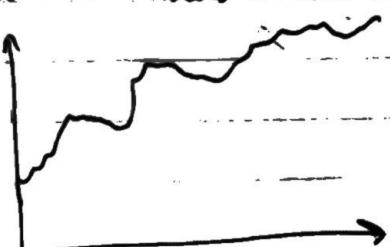
This means that  $Y_t$  would in fact be AR(1),  $\Delta Y_t$  is AR(0), and our partial sum  $\sum_{s=1}^t v_s$  is simply adding up white noise (since we demean any constant term anyway).

- f) i.  $\mu = 0 \Rightarrow \gamma_0 = 0 \Rightarrow \beta_0 = 0$ . There's no deterministic trend ("drift") in  $Y_t$  and its mean remains constant over time.



It probably looks similar to a random walk, but smoother since we may have autocorrelation in shocks.

- ii. We do now have a deterministic trend, as well as a stochastic one.



4a) They're both  $I(2)$ : we fail to reject  $H_0$  of a unit root for the levels but do reject it (against  $H_1$  of stationarity) for their first difference, at the  $1\%$  level with  $c_{\alpha} = -3.41$  (constant + trend).

b)  $\log(\frac{US}{UK}) - \log(\frac{US}{EU}) = \log(\frac{US}{UK} \div \frac{US}{EU}) = \log(\frac{EU}{UK})$   
which is the log of our rate of interest,  $E:f$ .

Seems plausible that we have drift in the rate overtime due to real macro changes, so let's use the ADF<sub>tr</sub> results.

At the 5% level we cannot reject  $H_0$  of a unit root in the levels ( $-3.113 \nmid -3.41 = c_{\alpha}$ ), but we can reject  $H_0$  (at the 1% level, even) for the differenced series.  $\Delta \ln - \Delta \ln$

pick  $\alpha = 10\%$   
and then argue

the opposite... So the Euro-Pound exchange rate is  $I(1)$ .

Normally when we test  $I(d)$  of  $f:t$  we're looking to see whether they're cointegrated. [This is different to an ADF test as part of a cointegration test, right? But there is a similarity in that we're assuming  $\theta = 1$ , finding the residual - i.e. the  $f:f$  rate - and seeing that it's not  $I(0)$ , so we fail to reject the null of no cointegration? Except surely  $\$:f$  and  $\$:e$  are!]

Not sure what this means about  $M^P$  independence, probably evidence for it?

The  $f:f$  rate wanders around, so BoE isn't pegging rates to Eurozone?

c) No, these results are highly doubtful. They're much more likely to be due to a spurious correlation from the presence of stochastic trends in both series, giving the illusion of a structural relationship when there in fact is none. This accounts for the high  $R^2$  and t-statistic, which  $\rightarrow \infty$  in large samples if we assume unity cointegration.

As noted, our residual is  $I(1)$ , so this is strong evidence of the regression relationship being spurious - otherwise, the stochastic trend would've been eliminated through the regression! You could verify the same using the analyst's values of  $\theta$ .

to see  
cointegration, but  
it doesn't mean  
UK lacks  
independent  $M^P$ , right?

d) Since our differenced series have the stochastic trends stripped out, you could test for Granger causality between DLUSEU and DLUSUK.

Maybe you can also do something like holding out part of the data for validation, or doing regressions on several splits + comparing for robustness, since you might get very different effect sizes (+ directions) due to spuriousness.