WP 43S REFERENCE MANUAL

This manual is very preliminary; it will change while we develop *WP 43S* in course of this project. We reserve the right to do so at any time. The very basic principles of *WP 43S* will stay constant, however. Stay informed by watching *http://sourceforge.net/p/wp43s/code/* .

 For the time being, the locations highlighted cyan are open construction sites – information is missing there or needs further discussion and investigation to be determined. Any contributions in this matter are highly appreciated.

HP is a registered trade mark of *Hewlett-Packard*.

The picture on p. 98 shows a detail of the backplane label of a *Voyager*. The pictures on p. 149 were kindly supplied by *SwissMicros*. The plots in *Appendix J* are based on material found in *Wikipedia*. The other photographs, pictures, diagrams, and graphics were created by the author.

Internet addresses are specified as found and verified at 2015-5-15. Please note such addresses may change without notice at any time.

This manual is published in English since it became the *lingua franca* of our time (after Greek, Latin, and French) – using it we can reach the maximum number of people without further translations. I apologize to the people of other languages and inserted some 'translator's notes' where applicable.

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WP 43S would not have been created without our love for *Classics, Woodstocks, Stings, Spices, Nuts, Voyagers*, and *Pioneers*. Thus we want to quote what was printed in *Hewlett-Packard* pocket calculator manuals until 1980, so it will not fade:

"The success and prosperity of our company will be assured only if we offer our customers superior products that fill real needs and provide lasting value, and that are supported by a wide variety of useful services, both before and after sales."

Statement of Corporate Objectives
Hewlett-Packard

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WELCOME!

This is the reference volume of the *WP 43S* documentation. It supplements the *WP 43S Owner's Manual* with detailed information about each and every *item* (i.e. command, *menu*, *catalog*, browser, application, constant, conversion, digit, and character) provided in your *WP 43S* The *Index of Items* in *Section 1* takes almost half of this volume.

Section 2 presents the structure and contents of all *menus* and *catalogs*. *Section 3* shows further access methods to operations and lists all operations requiring at least one parameter.

Twelve appendices cover additional special topics as listed in the *Table of Contents* above.

Enjoy!

Walter Bonin

Print Conventions and Common Abbreviations

- Throughout this manual, standard font is Arial. Emphasis is added by underlining or **bold** printing. Calculator COMMANDS and MENUS are called by their names, principally printed in capitals in running text (*menus* underlined). Translator's footnotes are printed blue. *Specific terms, titles, trademarks, names* or *abbreviations* are printed in italics, *hyperlinks* in blue underlined italics. The latter will beam you to its target in the original `.pdf` file – it cannot work in a printed copy for obvious reasons, thus either a page number or a full external address is given or the link points you to the *Table of Contents*.
- Bold italic Arial letters such as ***n*** are used for variables; bold normal letters for constant **sample values** (e.g. labels, numbers, or characters).
- This KEY font is taken for references to calculator keys, including SOFTKEYS in general. Alphanumeric and numeric calculator outputs (like 1.234×10^{-56} or $7{,}089\cdot10^{123}$) are printed using the respective calculator fonts.
- Courier is employed for `file names` and describing numeric formats.
- Times New Roman bold capitals are used for **REGISTER ADDRESSES**, lower case bold italics for ***register contents***. So e.g. the value ***y*** lives in register **Y** and ***r45*** in **R45**. Overall *stack* contents are generally quoted in the order [***x***, ***y***, ***z***, …] . We keep the term *register* for the space where an individual object is stored, although the actual size of such a *register* may vary widely following the size of the object.
- Lower case Times New Roman regular letters are for unit symbols (except in formulas - since the formula editor refuses to do this). Italics of this font are for *unit names*.
- We will use decimal points in most parts of this manual (but you may set your *WP 43S* to commas as well, of course). Although that point is less visible than a comma, 'comma people' seem to be more

tolerant against points used as radix marks than vice versa (based on the number of complaints read).

All this holds unless stated otherwise locally.

The following abbreviations are used throughout this manual:

ADM = angular display mode (see *Section 2* of the *OM*).

AIM = alpha input mode (see *Section 2* of the *OM*).

CDF = cumulated distribution function (see *Section 2* of the *OM*).

DP = double precision.

FM = flash memory (a special kind of *RAM*, s. *Sect. 3* of the *OM*).

HP = *Hewlett-Packard.*

IOI = *Index of Items* (see pp. 12ff).

LCD = liquid crystal display.

PDF = probability density function (see *Section 2* of the *OM*).

OM = Owner's Manual.

PEM = program-entry mode (see *Section 3* of the *OM*).

PMF = probability mass function (see *Section 2* of the *OM*).

px = pixels.

RAM = random access memory, allowing read and write operations.

RPN = reverse Polish notation (see *Section 1* of the *OM*).

SRS = subroutine return stack (see *App. B* on pp. 152ff).

TVM = *Time Value of Money* – a preprogrammed application for dealing with investments and credits, featured by all financial *HP* calculators since 1972 (s. *Sect. 5* of the *OM*).

Some more abbreviations may be used and explained locally.

SECTION 1: INDEX OF ITEMS (*IOI*)

All the *items* provided on your *WP 43S* (more than 850) are listed below with their reserved *names* and the keystrokes necessary to call them. Names printed in **bold** face in this table belong to operations directly accessible on the keyboard; the other *items* may be picked from *menus* (see pp. 112ff) or *catalogs*.[1]

Sorting in this index, in CATALOG, and CNST works in the following order:

␣ 0…9 A…Z a…z A…Ω α…ω ( ) + - × / ±

, . ! ? : ; ' " · * @ _ ~ → ← ↑ ↓ ↕

< ≤ = ≈ ≠ ≥ > % $ € £ ¥ √ ∫ ∞

& \ ^ | [ ] { } 🖶 #

Superscripts and subscripts are handled like normal characters in sorting. The 🖶 above is the printer symbol heading all print commands.

In principle, *WP 43S* operations work as the corresponding ones did on the *WP 34S* where applicable (cf. *App. E*). Referring to vintage calculators, most functions and keystroke-programming will work as they did on the *HP-42S*, bit and integer functions as on the *HP-16C*, unless specified otherwise. Also for functions inspired by other vintage calculators as mentioned in the index below, their manuals may contain helpful additional information.

Operations working with the accumulated statistical data are marked light blue. Operations operating also on complex parameters are marked light yellow.

[1] For commands stored in *menus*, we list the keys calling the respective *menu*, the *prefix(es)* of the respective *menu* row (if applicable), and the command as shown therein. We are confident you will find the corresponding *softkey*. *Items* stored in CNST are listed with their reserved names only, however, since they will be explained in detail in a separate chapter below.

Some 300 functions featured in your *WP 43S* are new compared to *HP's RPN* calculators.[2] Operations carrying familiar names but deviating in their functionality from previous *HP RPN* calculators or the *WP 34S* are marked light red.

For the vast majority of operations, remarks start with a number:

(0) represents functions without any effects on the *stack* (e.g. mode setting functions);

(1) is for *monadic functions*,

(2) for *dyadic functions*, and

(3) for *triadic functions* as defined in *Section 1* of the *OM*;

(−1) stands for functions pushing one object on the *stack* and

(−2) for functions pushing two objects on the *stack*.

Note some functions overwrite two *stack* levels instead of pushing two values on it: e.g. →POL and →REC, as you may have expected.[3]

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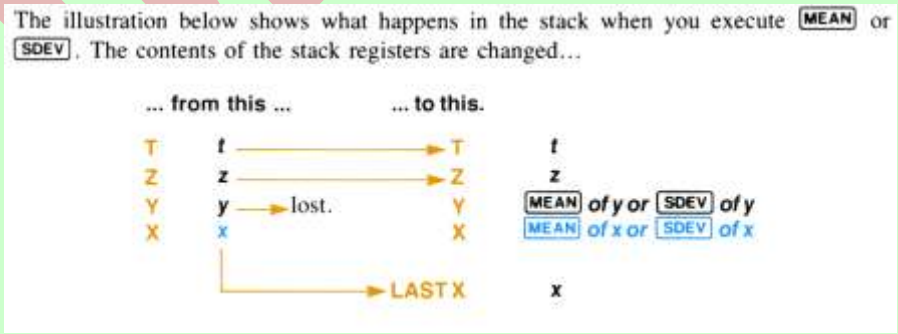
[2] We did not compare the *RPL* calculators of the last three decades or the *HP Prime*. They are exceeding the realm of shirt pocket calculators.

[3] On the *HP-42S*, however, also statistical functions returning two values do that – while the *Spices* (e.g. *HP-34C*) and *Voyagers* (e.g. *HP-15C*) push both results on the stack instead as you expect from *RPN* calculators. For your information, the picture below shows what the *HP-55*, *HP-19C/29C*, *HP-67/97*, *HP-41C*, and *HP-42S* do there:



Alas, *HP* does not give any reason for this deviation from simple logic until today. In our opinion this is not reasonable, so for the *WP 43S* we stick to the paradigm as implemented on the *Voyagers* in this matter (as we did for the *WP 34S / 31S* before).

Operation or function ***parameters*** will be taken from the lowest *stack register*(s) unless mentioned explicitly in second column of the *IOI* – then they have to trail the command. Some parameters of statistical distributions shall be given in *registers* **I**, **J**, and **K** as specified.

Three examples of the parameter notation used throughout the *IOI* are shown below; assume **R12** contains **15.67** generally here, i.e. ***r12*** = **15.67**.

1. ***n*** represents an arbitrary integer number which must be keyed in directly, while

   n represents such a number which may be specified indirectly via a *register* or variable as well (as shown in the tables in *Sect. 1* of the *OM*); and

   n stands for the respective number itself;

   Example:
   RSD **12** rounds ***x*** to 12 significant digits, while
   RSD →**12** rounds ***x*** to 15 significant digits.

2. ***r*** (or ***s***) represents an arbitrary *register* address or variable name which must be keyed in directly or picked from a *menu*, while

   r (or ***s***) represents such an address or name which may be specified indirectly as well; and

   r (or ***s***) stands for the contents of the address specified – ***r*** or ***s*** may be used as an address itself;

   Example:
   STO **12** stores ***x*** into **R12**, while
   STO →**12** stores ***x*** into **R15**.

3. ***labl*** represents an arbitrary label which must be keyed in directly or picked from a *menu*, while

   labl represents such a label which may be specified indirectly (as shown in the addressing table in *Section 3* of the *OM*); and

   labl stands for the respective label itself, regardless of the way it was specified.

Example:
GTO **12** goes to local label **12**, while
GTO →**12** goes to local label **15**.

Automatic stack lift is enabled after each command – except CLX, ENTER↑, Σ+, and Σ− (cf. *Section 1* of the *OM*); numeric input immediately following one of these four operations will overwrite ***x*** instead of pushing it on the *stack* as usual.[4]

The *data types* a particular function operates on are listed in { } under "remarks" if there are restrictions – cf. *App. B* on pp. 152ff. Most bit and integer functions operate on *finite integers* only (*data type* 10). The other functions typically work with more kinds of objects. Functions stating *data types* 8* or 9* instead of 8 or 9 operate on each matrix element instead of the entire matrix (as explained in *Section 2* of the *OM*). Wherever operations return *data types* differing from their input, the output types are listed as well.[5]

All operations may be entered in *PEM* as well unless stated otherwise – many functions contained in P.FN and TEST will make most sense in *PEM*.

Below, the functions checked already are highlighted green, those which didn't work (for whatever reason) are marked red. Green highlighting doesn't necessarily mean the function works correctly but its results look like in the right ballpark. What wasn't checked so far isn't highlighted at all. This applies to the respective *data types*.

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[4] Some reasoning why *automatic stack lift* is disabled for these four:

a) CLX is for clearing **X** to make room for a corrected value.

b) ENTER↑ is a *stack* lift manually initiated by the user. An additional *automatic stack lift* immediately after this command would not make sense.

c) Σ+ and Σ- are dedicated commands for adding or subtracting data points (see the chapter about *Statistical Calculations* in the *OM*). They were exclusively designed for data input since their first appearance on the *HP-45* and are not really meant to be mixed with calculations.

[5] E.g. for °C→°F: For single (double) precision real input, output stays single (double) precision real. For integer input, however, output is single precision real.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
°C→°F °F→°C	g U→ f °C→°F etc.	(1) {2, 11}; {1} → {2} Convert temperatures. See pp. 134ff.
10^x	g 10^x	(1) {1, 2, 3, 8*, 9*, 10, 11, 12} Returns 10^x, the inverse of $\lg(x)$.
1COMPL	g INTS ▲ 1COMPL g MODE ▲ 1COMPL	(0) Sets 1's complement mode for operations on finite integers. See *Sect. 2* of the *OM*.
½	g CNST ½	(−1) { } → {2} Trivial but helpful constant for iterations.
1/x	1/x	(1) {2, 3, 8*, 9*, 11, 12}; {1} → {2} Inverts the number x or all elements of the matrix x.
2COMPL	g INTS ▲ 2COMPL g MODE ▲ 2COMPL	(0) Sets 2's complement mode for operations on finite integers. See *Sect. 2* of the *OM*.
2^x	g EXP 2^x	(1) {1, 2, 3, 8*, 9*, 10, 11, 12} Returns 2^x.
$\sqrt[3]{x}$	g EXP $\sqrt[3]{x}$	(1) {1, 2, 3, 8*, 9*, 10, 11, 12}; ({1} → {2}) Returns the cube root of x.
A		Reserved variable for *register* **A**.
a	g CNST a	(−1) { } → {2} *Gregorian* year in *days*.
a_0	g CNST a_0	(−1) { } → {2} *Bohr* radius in *meter*.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
ABS	f CATALOG FCNS ABS	Works like |x| on p. 102. ABS is featured for backward compatibility only.
ACC	f ADV ∫fdx ACC	Reserved real variable for the accuracy of integration (see *Sect. 4* of the *OM*).
ac→m²	g U→ f A: acres→m²	(1) {2, 11}; {1} → {2} Convert areas. See pp. 134ff.
ac_{US}→m²	g U→ f A: $acres_{US}$→m²	
ADV	f ADV	*Menu*. See p. 118.
AGM	g X.FN AGM	(2) {2, 3, 11, 12}; {1} → {2} Returns the *arithmetic-geometric mean* of x and y. Will throw an error for x or y being negative. See p. 223 for more.
AGRAPH	g P.FN P.FN2 g AGRAPH *s*	(0) Alpha graphics. Displays a graphics image. Each character in the source **s** specifies an 8-dot column pattern. The X- and Y-*registers* specify the pixel location of the bottom left point of this column. $1 \le x \le 400$ and $1 \le y \le 232$ are possible (but cf. *App. K* on pp. 234ff). So one row (8 px high) starting in column 1 may need up to 400 characters to specify – the more blank space is found therein the less characters may be required for describing it entirely. Cf. *HP-42S Owner's Manual*, pp. 135 – 140, and *HP-42S Programming Examples and Techniques,* pp. 214 – 223.
ALL	g DISP ALL ***n***	(0) Sets the numeric display format to show all decimals of real or complex numbers whenever possible. ALL 00 works like ALL in *HP-42S* almost. For $x \ge 10^{10}$ (or earlier for complex numbers), however, display will switch to SCI or ENG with the maximum number of decimals necessary

Item	Keystrokes	Remarks (see pp. 12ff for general information)
		and displayable using the large font (see SCIOVR and ENGOVR). The same will happen if $x < 10^{-n}$ and more than 16 digits are required to show x entirely.
a_M	g CNST a_M	(−1) { } → {2} Semi-major axis of the Moon's orbit around the earth in *meter*.
AND	f BITS AND	(2) {10} Works bitwise as in *HP-16C* (see *Sect. 2* of the *OM*).
		(2) {1, 2, 11} → {1} Works like AND in *HP-28S*, i.e. x and y are interpreted before executing this operation. Zero is 'false'; any other real number is 'true'.
arccos	TRI arccos	(1) {3, 8*, 9*, 12}; {1, 2, 11} → {4}; Returns the tagged angle $arccos(x)$.[6]
arcosh	g EXP g arcosh	(1) {2, 3, 8*, 9*, 11, 12} Returns $arcosh(x)$.
arcsin	TRI arcsin	(1) {3, 8*, 9*, 12}; {1, 2, 11} → {4}; Returns the tagged angle $arcsin(x)$.[7]
arctan	TRI arctan	(1) {3, 8*, 9*, 12}; {1, 2, 11} → {4}; Returns the tagged angle $arctan(x)$.[8]

[6] Precisely, ARCCOS returns the principal value of $arccos(x)$, i.e. a real part ∈ [0, π] in $\angle^r$, or ∈ [0°, 180°] in $\angle^\circ$ or $\angle$", or ∈ [0^g, 200^g] in $\angle^g$, or ∈ [0, 1] in $\angle\pi$. Cf. ISO/IEC 9899.

[7] Precisely, ARCSIN returns the principal value of $arcsin(x)$, i.e. a real part ∈ [-π/2, π/2] in $\angle^r$, or ∈ [-90°, 90°] in $\angle^\circ$ or $\angle$", or ∈ [-100^g, 100^g] in $\angle^g$, or ∈ [-0.5, 0.5] in $\angle\pi$. Cf. ISO/IEC 9899.

[8] Precisely, ARCTAN returns the principal value of $arctan(x)$, i.e. a real part ∈ [-π/2, π/2] in $\angle^r$, for example (cf. ASIN), if *flag* **D** is set. Else the result interval for ATAN becomes (-π/2, π/2) in $\angle^r$, for example. Cf. ISO/IEC 9899.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
arsinh	g EXP g arsinh	(1) {2, 3, 8*, 9*, 11, 12} Returns $arsinh(x)$.
artanh	g EXP g artanh	(1) {2, 3, 8*, 9*, 11, 12} Returns $artanh(x)$.
ASR	f BITS f ASR ***n***	(1) {10} Works like ***n*** (≤ 63) consecutive ASR commands in *HP-16C,* corresponding to a division of ***x*** by 2^n. ASR **0** executes as NOP, but loads **L**. See *Sect. 2* of the *OM*.
ASSIGN	f ASN ***item, location***	(0) Assigns an *item* (i.e. a function, a *menu*, a label, or a character) to a specified sequence of keystrokes, corresponding to a specific location on the keyboard or in a *menu*. See *Section 6* of the *OM*. Not programmable.
atm→Pa	g U→ F&p: f atm→Pa	(1) {2, 11}; {1} → {2} Convert pressures and distances. See pp. 134ff.
au→m	g U→ x: au→m	
A...Z	f CATALOG CHARS A...Z	*Submenu*. See pp. 112ff.
A:	g U→ f A:	*Submenu*. See p. 134.
$a_\oplus$	g CNST $a_\oplus$	(−1) { } → {2} Semi-major axis of the Earth's orbit around the sun in *meter*.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
B		Reserved variable for *register* **B**.
BACK	g P.FN P.FN2 g BACK *n*	(0) Jumps ***n*** steps backwards ($0 \le n \le 255$) in a program. E.g. BACK 1 goes to the previous program step. If BACK attempts to cross an END, an error is thrown. Reaching step 000 stops program execution and lights ↟. Cf. SKIP. **ATTENTION:** If you edit a section of your routine crossed by one or more BACK, SKIP, or CASE jumps, this may well result in a need to **manually maintain all those statements individually.**
bar→Pa	g U→ F&p: bar→Pa	(1) {2, 11}; {1} → {2} Converts pressures. See pp. 134ff.
BATT?	g INFO f BATT?	(−1) { } → {2} Measures the battery voltage in the range between $1.9V$ and $3.4V$ and returns this value.
BC?	f BITS g BC? ***n***	(−1) {10} Tests if the specified bit in ***x*** is clear.
BEEP	g I/O BEEP	(0) Sounds a sequence of four tones. See also TONE and QUIET.
BeginP	g FIN TVM f Begin	(0) Sets "Begin" mode in *TVM*: payments occur at the beginning of each period. Typical for savings plans and leasing. Cf. ENDP.
BestF	g STAT ▲ f BestF	(0) Selects the 'best' curve fit model for the current statistical data by picking the one with maximum *correlation* (like BEST in *HP-42S*). Relevant for L.R., CORR, COV, s_{XY}, $\hat{x}$, and $\hat{y}$. Note ORTHOF is not part of the set of models under investigation. See pp. 196ff for more.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
Binom Binom_p Binom_u Binom^{-1}	f PROB g Binom: Binom etc.	(1) {2, 11} *Binomial distribution* with the number of successes ***g*** in **X**, the probability of a success p_0 in **I**, and the sample size ***n*** in **J**. See p. 196 for more. Binom^{-1} returns the maximum number of successes ***m*** for a given probability ***p*** in **X**, p_0 in **I** and ***n*** in **J**.
Binom:	f PROB g Binom:	*Submenu*. See p. 121.
BITS	f BITS	*Menu*. See p. 116.
B_n	g X.FN B_n	(1) {1, 2, 11} B_n and B_n^* return the Bernoulli number for an integer ***n*** > 0 given in **X**, working with different definitions (see both formulas on p. 194).
B_n^*	g X.FN B_n^*	
BS?	f BITS g BS? ***n***	(0) {10} Tests if the specified bit in ***x*** is set.
Btu→J	g U→ E: Btu→J	(1) {2, 11}; {1} → {2} Converts energies. See pp. 134ff.
C		Reserved variable for *register* **C**.
c	g CNST c	(−1) { } → {2} Speed of light in vacuum in *meter per second*; first and second radiation constants in *Planck's* Law (see p. 128).
c_1	g CNST c_1	
c_2	g CNST c_2	
cal→J	g U→ E: cal→J	(1) {2, 11}; {1} → {2} Converts energies. See pp. 134ff.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
CASE	g P.FN P.FN2 g CASE *s*	(0) Works like SKIP below but takes the number of steps to skip from *s*. **Example**: Assume a program section: ... 100 CASE 12 101 GTO 01 102 GTO 02 103 GTO 07 104 GTO 05 105 LBL 01 ... 132 LBL 02 ... 153 LBL 05 ... 234 LBL 07 ... In execution of this program, *r12* will be checked in step 100: if *r12* ≤ 1 then the program will proceed to step 101 and continue with a jump to step 105, for *r12* = 2 the program will go to step 102, etc., resulting in a nice controlled dispatcher for 1 ≤ *r12* ≤ 4 . **ATTENTION:** CASE might surprise you for *r12* > 4 in the example above. Take care of the input you provide! If you edit a section of your routine crossed by one or more BACK, SKIP, or CASE jumps, this may well result in a need to **manually maintain all those statements individually.**
CATALOG	f CATALOG	*Catalog* of everything. See pp. 112ff.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
Cauch Cauch_p Cauch_u Cauch^{-1}	f PROB f Cauch: Cauch etc.	(1) {2, 11} *Cauchy-Lorentz distribution* (also known as *Lorentz* or *Breit-Wigner distribution*) with the location x_0 specified in **I** and the shape γ in **J**. See p. 199 for more. Cauch^{-1} returns x for a given probability p in **X**, with x_0 in **I** and γ in **J**.
Cauch:	f PROB f Cauch:	*Submenu*. See p. 121.
CB	f BITS g CB *n*	(1) {10} Clears the specified bit in x, i.e. sets it to **0**.
CEIL	g INTS g CEIL	(1) {8*}; {1, 2, 11} → {1} Returns the smallest integer ≥ x. Cf. FLOOR.
CF	g FLAGS CF *n* g CLR CF *n*	(0) Clears the *flag* specified, i.e. sets it to **0**.
CHARS	f CATALOG CHARS	*Submenu*. See pp. 112ff.
CLALL	g CLR f CLall	(0) Clears all *registers*, *flags*, variables, and programs in *RAM* if confirmed. Not programmable. Cf. CLCVAR, CLFALL, CLPALL, CLREG, CLSTK, and RESET.
CLCVAR	g CLR f CLCVAR	(0) Clears all variables used in the *current program*, i.e. sets all such real and complex variables to **0.**, all integer ones to **0**, all *time* variables to **0:00:00**, all *date* variables to **January 1st** of year **0**, all character strings to zero length, and all the elements of all matrix variables used to zero.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
CLFALL	g FLAGS g CLFall g CLR f CLFall	(0) Clears all global and local user flags if confirmed. See CF.
CLK	g CLK	*Menu*. See p. 112.
CLK12	g CLK ▲ f CLK12	(0) Sets 12h time display mode: e.g. 1:23 will become 1:23 a.m., 23:45 will become 11:45 p.m. Shortens the date display in the *status bar* to two digits for the year. Cf. CLK24.
CLK24	g CLK ▲ f CLK24	(0) Sets international 24h time display mode. Cf. CLK12.
CLLCD	g CLR f CLLCD	(0) Clears the *LCD* in the rectangular window north and west of the point x, y. I.e. all pixels $\geq x$ and $\geq y$ are cleared.
CLMENU	g CLR CLMENU g P.FN P.FN2 …	(0) Clears all *menu* key definitions for the programmable *menu*. See MENU.
CLP	g CLR CLP	(0) Clears the *current program* in *RAM* or *FM*. Memory is given back to the pool of free space. Not programmable.
CLPALL	g CLR f CLPall	(0) Clears all programs in *RAM* if confirmed. Cf. CLP.
CLR	g CLR	*Menu*. See p. 118.
CLREGS	g CLR f CLREGS	(0) Clears all global and local general purpose *registers* allocated (see also LOCR). The contents of the *stack* and **L** are kept.[9]

[9] Clearing an individual *register* works as explained for CLCVAR on previous page.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
CLSTK	g CLR CLSTK 0 g FILL	Clears all *stack registers* currently allocated (i.e. either **X** … **T** or **X** … **D**). All other *register* contents are kept.[9]
CLX	g CLR CLX ←	(1) Clears *register* **X**, disabling *automatic stack lift*. The shortcut works for closed ***x*** only.[9]
CLΣ	g STAT g CLΣ g CLR CLΣ	(0) Clears the statistical summation *registers* and releases the memory allocated for them (see p. 154).
CNST	g CNST	*Menu*. See CONST below and pp. 134ff.
COMB	f PROB C_{yx}	(2) {1} Returns the number of possible subsets of ***x*** items taken out of a set of ***y*** items (i.e. choose ***x*** out of ***y***). No item occurs more than once in a subset, and different orders of the same ***x*** items are not counted separately. Cf. PERM.
		(2) {2, 3, 11, 12} See pp. 194ff for the formula.
CONJ	g CPX conj	(1) {3, 9*, 12} Returns the complex conjugate of ***x***.
CONST	g P.FN f CONST ***n***	(−1) { } → {2} Returns the constant stored at position ***n*** in CNST (see pp. 134ff and the *OM*, *Section 5*). Allows for indirectly addressing these contents.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
CONVG?	g TEST g CONVG? *r*	(0) {2, 11} Checks for convergence by comparing x and y as determined by the lowest five bits of r. a) The very lowest two bits set the tolerance limit: 0 = 10^{-14}, 1 = 10^{-24}, 2 = 10^{-32}. b) The next two bits determine the comparison mode using the tolerance limit set: 0 = compare the numbers x and y relatively, 1 = compare them absolutely. c) The top bit tells how special numbers are handled: 0 = NaN and ±∞ are considered converged, 1 = they are not considered converged. Now, $r = a + 4b + 16c$.
CORR	g STAT ▲ r	(−1) { } → {2} Returns the *coefficient of correlation* for the current statistical data and curve fit model. See pp. 196ff for more.
cos	TRI cos	(1) {2, 3, 8*, 9*, 11, 12}; {1, 4} → {2} Returns the cosine of the angle in X (see *Section 2* of the *OM* for details).
cosh	g EXP g cosh	(1) {2, 3, 8*, 9*, 11, 12} Returns the hyperbolic cosine of x.
COV	g STAT ▲ cov	(−1) { } → {2} Returns the population covariance for the two data sets entered via Σ+, depending on the curve fit model selected. See s_{XY} for the sample covariance and pp. 196ff for more.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
CPX	g CPX	*Menu*. See p. 119.
CPXi CPXj	g CPX g CPXi etc.	(0) Selects either the letter ***i*** or ***j*** for displaying the imaginary number ***i***.
CPXRES	g MODE f CPXRES g FLAGS SF 1	(0) Allows for complex results of real calculations. Cf. REALRES.
CPXS	f CATALOG VARS CPXS	*Submenu* of variables defined at execution time. See pp. 112f.
CPX?	g TEST ▲ CPX?	(0) Checks if ***x*** is complex. Returns true if **X** contains data of type 3, 9, or 12 with nonzero imaginary part.
CROSS	f MATX f cross	(2) {8} Requires two real 2D or 3D vectors in **X** and **Y** and returns their cross product. Crossing of 2D vectors works as for complex numbers.
	g CPX cross	(2) {3} → {2}; {12} → {11} When two complex numbers are crossed, your *WP 43S* simply returns a real number that is equal to the signed magnitude of the resulting moment vector.
cwt→kg	g U→ m: cwt→kg	(1) {2, 11}; {1} → {2} Converts masses. See pp. 134ff.
CX→RE	f CC or g CPX CC	(−1) {3} → {2}; {9} → {8}; {12} → {11} Cuts a closed complex object ***x***, putting either • (for ⌞) its real part in **X** and its imaginary part in **Y**, or • (for ⊙) magnitude in **X** and angle in **Y**.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
D		Reserved variable for *register* **D**.
DATE	g CLK DATE	(−1) { } → {6} Recalls the *date* from the real time clock and displays it in the format selected. See D.MY, M.DY, and Y.MD. Furthermore, DATE shows the day of week (see *Sect. 2* of the *OM*).
DATES	f CATALOG VARS f DATES	*Submenu* of variables defined at execution time. See pp. 112f.
DATE→	g CLK DATE→	(−2) {2, 6, 11} → {1} Assumes x containing a *date* in the format selected (or a real number in corresponding format) and pushes its three components as *integers* on the *stack*. Reversible by →DATE.
DAY	g CLK f DAY	(1) {2, 6, 11} → {1} Assumes x containing a *date* in the format selected (or a real number in corresponding format) and extracts the day.
DBL?	g TEST ▲ f DBL?	(0) Checks if x contains a double precision real or complex number.
DBLR DBL× DBL/	g INTS g DBLR etc.	{10} Double *word* length commands for remainder, multiplication and division.[10] DBLR and DBL / accept a double size dividend in **Y** and **Z** (most significant bits in **Y**), the divisor in **X** as usual, and return the result in **X**. DBL× takes x and y as factors as usual but returns the product in **X** and **Y** (most significant bits in **X**).

[10] See the *HP-16C Owner's Handbook*, *Section 4* (pp. 52ff).

Item	Keystrokes	Remarks (see pp. 12ff for general information)
dB→fr	g U→ ▲ dB→field ratio	(1) {2, 11}; {1} → {2}
dB→pr	g U→ ▲ dB→power ratio	Convert ratios. See pp. 134ff.
DEC	f LOOP f DEC *r*	(0) {1, 2, 10, 11} Decrements *r* by 1. Does not load L even for target address X.
DECOMP	f PARTS DECOMP	(−1) {1, 2, 11} → {1} Decomposes *x* (after converting it to an *improper fraction*, if applicable), returning a *stack* [***denominator(x), numerator(x),*** …]. Reversible by division. **Example:** If X contains 2.25 then DECOMP will return *x* = 4 and *y* = 9.
DEG	g MODE DEG	(0) Sets the *ADM* to *degrees*.
DEG→	f L→ f ∡°→∡	(1) {1, 2, 4, 11} → {4} Converts angles as described on p. 140.
DENANY	g MODE g DENANY	(0) Sets default fraction display format like in *HP-35S* – any denominator up to the value set by DENMAX may appear. This is the most precise way of displaying a decimal number as a fraction with DENMAX given. **Example:** If DENMAX = 5 then DENANY allows denominators 1, 2, 3, 4, and 5.
DENFAC	g MODE g DENFAC	(0) Sets 'factors of the maximum denominator', i.e. the denominator may be an integer factor of DENMAX only. **Example:** If DENMAX = 60 then DENFAC will allow for denominators 1, 2, 3, 4, 5, 6, 10, 12, 15, 20, 30, and 60. Now you know why 60 was a holy number in ancient Babylon.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
DENFIX	g MODE g DENFIX	(0) Sets fixed denominator format, i.e. the one and only denominator allowed is the value set by DENMAX.
DENMAX	g MODE g DENMAX	(1) Works like /c on *HP-35S*, but the maximum legal denominator is 9 999. For $x < 1$ or $x > 9\,999$, DENMAX will be set to 9 999. For $x = 1$, the current DENMAX setting is recalled, replacing x.
DET	f CATALOG FCNS DET	Works like |M| on p. 102. DET is featured for backward compatibility only.
DIGITS	f CATALOG DIGITS	*Submenu*. See pp. 112ff.
DISP	g DISP	*Menu*. See p. 119.
DOT	g CPX dot	(2) {3} → {2}; {12} → {11} Returns $Re(x) \cdot Re(y) + Im(x) \cdot Im(y)$
	f MATX f dot	(2) {8} → {2}; {9} → {3} Requires two matrices in x and y and returns their dot (scalar) product. The dot product is defined as the sum of the products of the corresponding elements in both matrices. Note both matrices must be of the same size; else DOT will throw an error. See *Sect. 2* of the *OM.*
DROP	g STK DROP	Drops x … from the stack. See *Sect. 1* of the *OM* for details.
DROPy	g STK f DROPy	Drops y

Item	Keystrokes	Remarks (see pp. 12ff for general information)
DSE	f LOOP DSE *r*	(0) {1, 2, 10, 11} Given `ccccc.fffii` in the source, DSE decrements ***r*** by `ii`, skipping next program step if then `ccccc` ≤ `fff` . If ***r*** features no fractional part then `fff` is 0. If `ii` = 0 , `ccccc` will be decremented by 1. DSE does not load **L** even for destination address **X**. Note that neither `fff` nor `ii` can be negative, and DSE is only sensible with `ccccc` > 0 .
DSL	f LOOP DSL *r*	(0) {1, 2, 10, 11} Works like DSE but skips if `ccccc` < `fff` .
DSP	f DSP *n* g DISP DSP *n*	(0) For real or complex ***x***, and FIX, SCI, or ENG set, DSP changes the number of decimals shown while keeping the basic display format as is. With ALL, DSP changes the switch point (see ALL).
DSTACK	g DISP ▲ g DSTACK	(0) Sets the maximum number of *stack registers* displayed. For an input of 1, only ***x*** will be shown directly above the *menu section*; for 2, ***x*** and ***y*** will be displayed; maximum input is 4. Expanded views of e.g. matrices and multi-level returns like SUM will work as described in the *OM* regardless of the number chosen. In any case, command input will be echoed directly below the *status bar*. This command is for old-school calculator users who may feel distracted by a multitude of *stack registers* displayed and changing simultaneously.
DSZ	f LOOP DSZ *r*	(0) {1, 2, 10, 11} Decrements ***r*** by 1 and skips the next step if $\lvert r \rvert < 1$ thereafter. Does not load **L** even for target address **X**. Known from *HP-16C*.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
D.MS	f d.ms	(0) Sets the *ADM* to sexagesimal *degrees*.
D.MS→	f L→ f ↲"→↲	(1) {1, 2, 4, 11} → {4} Converts angles as described on p. 140.
D.MY	g CLK ▲ D.MY	(0) Sets the format `dd.mm.yyyy` for *date* display.
D→J	g CLK f D→J	(1) {2, 6, 11} → {1} Assumes ***x*** containing a *date* in the format selected (or a real number in corresponding format) and converts it to a *Julian day number*[11] according to J/G setting.
D→R	f L→ g ↲°→↲r	(1) {1, 2, 4, 11} → {4} Convert angles as described on p. 140.
D→D.MS	f L→ g ↲°→↲"	
e	g CNST e	(−1) { } → {2} Elementary charge in *coulomb* and *Euler's e*.
e_E	g CNST e_E	
EIGVAL	f MATX ▲ g EIGVAL	(−1) {8, 9} Evaluates the matrix ***x*** and pushes a diagonal matrix containing its eigenvalues on the *stack*.
EIGVEC	f MATX ▲ g EIGVEC	(−1) {8, 9} Evaluates the matrix ***x*** and pushes a matrix containing its eigenvectors on the *stack*.
END	g P.FN END	(0) Last command in a routine and terminal for searching local labels as described in *Section 3* of the *OM*. Works like RTN in all other aspects.

[11] Translator's note: *Julian day number* translates to "Julianisches Datum" in German and «jour Julien» in French. See the corresponding articles in *Wikipedia* for more.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
ENDP	g FIN TVM f End	(0) Sets "End" mode in *TVM*: payments occur at the end of each period. Typical for loans and investments. Cf. BEGINP.
ENG	g DISP ENG ***n***	(0) Sets engineer's display format (see *Section 2* of the *OM*).
ENGOVR	g DISP ▲ f ENGOVR	(0) Defines that numbers exceeding the range displayable in ALL or FIX will be shown in engineer's format. Cf. SCIOVR.
ENORM	f MATX g ENORM	(1) {8, 9} → {2} Calculates the Euclidean norm of the matrix in **X**. The Euclidean norm is defined as the square root of the sum of squares of all matrix elements. Works like FNRM on *HP-42S*. For a vector, ENORM returns its length. Cf. |x| on p. 102.
ENTER↑	ENTER↑	(−1) Separates two numbers in input. Copies x into **Y**, disabling *automatic stack lift*. See p. 109 and the *OM* (*Section 1*) for details.
ENTRY?	g TEST g ENTRY?	(0) Checks the (internal) entry *flag*. It is set if: • any character is entered in *AIM*, or • any command is accepted for entry (be it via ENTER↑, a function key, or R/S with a partial command line). Useful in routines, e.g. after PAUSE.
EQN	g EQN	*Menu*. See p. 119.
EQ.DEL	g EQN f DELETE	Deletes an equation.
EQ.EDI	g EQN EDIT	Opens the *Equation Editor* to edit an existing equation.
EQ.NEW	g EQN NEW	Opens the *Equation Editor* to enter a new equation.

See *Section 4* of the *OM*.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
erf erfc	g X.FN erf etc.	(1) {2, 11}; {1} → {2} Returns the error function or its complement. See pp. 223ff for more.
ERR	g P.FN ERR *n*	(0) Raises the error specified. The consequences are the same as if the corresponding error really occurred, so e.g. a running routine will be stopped and the message will be thrown. See *App. C* on pp. 160ff for the respective error codes. Cf. MSG.
EVEN?	g TEST f EVEN?	(0) Checks if x is integer and even.
e^x	e^x	(1) {2, 3, 8*, 9*, 11, 12}; {1, 10} → {2} Returns e^x.
EXITALL	g P.FN P.FN2 EXITall	(0) Exits all *menus*.
EXP	g EXP	*Menu*. See p. 119.
ExpF	g STAT ▲ f ExpF	(0) Selects the exponential curve fit model. Relevant for CORR, COV, L.R., s_{XY}, $\hat{x}$, and $\hat{y}$. See pp. 196ff for more.
Expon $Expon_p$ $Expon_u$ $Expon^{-1}$	f PROB f Expon: Expon etc.	(1) {2, 11} *Exponential distribution* with the rate λ in **J**. See pp. 196ff for more. $Expon^{-1}$ returns the survival time t_s for a given probability ***p*** in **X**, with λ in **J**.
Expon:	f PROB f Expon:	*Submenu*. See p. 121.
EXPT	f PARTS f EXPT	(1) {1, 2, 11} → {1} Returns the exponent ***h*** of the number $x = m \cdot 10^h$ displayed. Cf. MANT.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
e^x-1	g EXP f e^x-1	(1) {2, 3, 8*, 9*, 11, 12} For $x \approx 0$, this returns a more accurate result for the fractional part than e^x does.
e/m_e	g CNST e/m_e	(−1) { } → {2} Electron charge to mass ratio in *coulomb per kilogram*.
E:	g U→ E:	*Submenu*. See p. 134.
F	g CNST F	(−1) { } → {2} *Faraday* constant in *coulomb per mol*.
FAST	g MODE f FAST	(0) Sets the processor speed to 'fast'. This is *startup default* and is kept for fresh batteries. Cf. SLOW.
FB	f BITS g FB ***n***	(1) {10} Inverts ('flips') the specified bit in x.
FBR	g α.FN g FBR	Font browser.
FCNS	f CATALOG FCNS	*Submenu*. See pp. 112ff.
FC?	g FLAGS FC? ***n***	(0) Tests if the specified *flag* is clear.
FC?C FC?F FC?S	g FLAGS f FC?C ***n*** etc.	(0) Tests if the specified *flag* is clear. Clears, flips, or sets this *flag* after testing, respectively.
FF	g FLAGS FF ***n***	(0) Flips the *flag* specified.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
FIB	g X.FN f FIB	(1) {1} Returns the Fibonacci number (s. pp. 194f for more).
		(1) {2, 3, 11, 12} Returns the extended Fibonacci number.
FILL	g FILL	Copies ***x*** to all *stack registers*.
FIN	g FIN	*Menu*. See p. 119.
FINTS	f CATALOG VARS FINTS	*Submenu* of finite length integer variables defined at execution time. See pp. 112f.
FIX	g DISP FIX ***n***	(0) Sets fixed point display format (see the *OM*, *Sect. 2*).
FLAGS	g FLAGS	*Menu*. See p. 119.
FLASH	f CATALOG PROGS FLASH	*Submenu* of global labels defined at execution time. See pp. 112f.
FLASH?	g INFO f FLASH?	(−1) { } → {1} Returns the number of free *words* in *FM* (1 *word* = 2 *bytes*).
FLOOR	g INTS g FLOOR	(1) {8*}; {1, 2, 11} → {1} Returns the greatest integer ≤ ***x***. Cf. CEIL.
FP	f PARTS FP	(1) {1, 2, 8*, 10, 11} Returns the fractional part of ***x***. Cf. IP.
FP?	g TEST f FP?	(0) Tests ***x*** for having a fractional part ≠ 0 .

Item	Keystrokes	Remarks (see pp. 12ff for general information)
$F_p(x)$	f PROB F: $F_p(x)$ etc.	(1) {2, 11} *Fisher's F distribution*. $F_u(x)$ equals Q(F) on *HP-21S*. The degrees of freedom are specified in **I** and **J**. See pp. 196ff for more.
$F_u(x)$		
F(x)		
$F^{-1}(p)$		
fr→dB	g U→ ▲ field ratio→dB	(1) {2, 11}; {1} → {2} Converts ratios. See pp. 134ff.
FS?	g FLAGS FS? ***n***	(0) Tests if the specified *flag* is set.
FS?C	g FLAGS f FS?C ***n*** etc.	(0) Tests if the specified *flag* is set. Clears, flips, or sets this *flag* after testing, respectively.
FS?F		
FS?S		
ft.→m	g U→ ×: f ft.→m	(1) {2, 11}; {1} → {2} Convert distances. See pp. 134ff.
ft_{US}→m	g U→ ×: ▲ s:$feet_{US}$→m	
FV	g FIN TVM FV	(1) Reserved variable for the future value of your investment or loan in *TVM*.
fz_{UK}→m^3	g U→ f V: f $floz_{UK}$→m^3	(1) {2, 11}; {1} → {2} Convert volumes. See pp. 134ff.
fz_{US}→m^3	g U→ f V: f $floz_{US}$→m^3	
F_α	g CNST F_α	(−1) { } → {2} *Feigenbaum's* α and δ.
F_δ	g CNST F_δ	
F:	f PROB F:	*Submenu*. See p. 121.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
f'	g EQN f'	{1, 2, 11} → {2} Calculate the first or second derivative of a given equation. See the *OM* (*Sect. 4*) for more.
f''	g EQN f''	
f'(x)	f ADV f' (x) ***labl***	{1, 2, 11} → {2} f'(x) [f''(x)] returns the 1st [2nd] derivative of the function ***f(x)*** at position ***x***. ***f(x)*** must be specified in a routine starting with LBL ***labl***. On return, **Y**, **Z**, and **T** will be cleared and the position ***x*** will be in **L**. See *Section 4* of the *OM* for more. **ATTENTION:** f'(x) and f''(x) fill all *stack registers* with ***x*** before calling the routine specified.
f''(x)	f ADV f f''(x) ***labl***	
F&p:	g U→ F&p:	*Submenu*. See p. 134.
G	g CNST G	(−1) { } → {2} *Newtonian* constant of gravitation in $^{m^3}/_{kg\ s^2}$; also called γ by other authors.
G_0	g CNST G_0	(−1) { } → {2} Conductance quantum in *siemens*.
GAP	g DISP GAP ***n***	(0) Defines the interval for inserting digit group separators in real numbers. For integers, the intervals are fixed to 4 digits for binary and 3 for any other base – except 4, 8, and 16 where the interval is 2. After GAP **0**, no group separators will be displayed at all neither in real nor integer numbers. See *App. D and Sect. 2* of the *OM*.
G_C	g CNST G_C	(−1) { } → {2} *Catalan's* (mathematical) constant.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
GCD	g INTS g GCD	(2) {1; 10} Returns the Greatest Common Divisor of x and y.[12] This will always be positive.
g_d g_d^{-1}	g X.FN f g_d etc.	(1) {2, 3, 11, 12} ; {1} → {2} Returns the Gudermannian function or its inverse. See p. 224 for details.
g_e	g CNST g_e	(−1) { } → {2} *Landé's* electron g-factor.
Geom $Geom_p$ $Geom_u$ $Geom^{-1}$	f PROB g Geom: Geom etc.	(1) {2, 11} *Geometric distribution*: The *CDF* returns the probability for a first success after $m = x$ Bernoulli experiments. The probability p_0 for a success in each such experiment must be specified in **J**. See pp. 196ff for more. $Geom^{-1}$ returns the number of failures f before 1st success for given probabilities p in **X**, p_0 in **J**.
Geom:	f PROB f Geom:	*Submenu*. See p. 121.
$gl_{UK}\rightarrow m^3$ $gl_{US}\rightarrow m^3$	g U→ f V: $gl_{UK}\rightarrow m^3$ g U→ f V: $gl_{US}\rightarrow m^3$	(1) {2, 11}; {1} → {2} Convert volumes. See pp. 134ff.
$GM_\oplus$	g CNST $GM_\oplus$	(−1) { } → {2} *Newtonian* constant of gravitation times the Earth's mass with its atmosphere included according to *WGS84*.[13] Displayed in m^3/s^2.

[12] See also LCM.

Translator's notes for French readers: GCD correspond à *PGCD* en français, Translator's notes for German readers: GCD entspricht *ggT* auf Deutsch.

[13] See http://earth-info.nga.mil/GandG/publications/tr8350.2/tr8350_2.html

Item	Keystrokes	Remarks (see pp. 12ff for general information)
GRAD	g MODE GRAD	(0) Sets the *ADM* to *grad/gon*.[14]
GRAD→	f L→ f $\angle^g \to \angle$	(1) {1, 2, 4, 11} → {4} Converts angles as described on p. 140.
GTO	f GTO ***labl***	(0) In *PEM*: inserts an unconditional branch to ***labl***. Else positions the program pointer to ***labl***.
GTO.	f GTO . ***n***	to step ***n*** (specify up to four digits until becoming unambiguous in used program memory).
	f GTO . ***labl***	to the global label specified.
	f GTO .▲	(0) Puts the program pointer … directly after previous END, going to the top of *current program* (see *Section 3* of the *OM*).
	f GTO .▼	(not programmable) directly after next END, going to the top of next program.
	f GTO ..	to the end of used program memory in *RAM* (i.e. to the final END statement).
$g_\oplus$	g CNST $g_\oplus$	(−1) { } → {2} Standard earth acceleration in m/s^2.

[14] This angular unit is also known as *gradian* in the English language.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
h	g CNST h	(−1) { } → {2} *Planck* constant in *joule-second*.
H_n	g X.FN Orthog H_n	(2) {2, 11}; {1} → {2} *Hermite polynomials* for probability (H_n) and physics (H_{np}). See p. 211 for details.
H_{np}	... Orthog f H_{np}	
$hp_E \rightarrow W$	g U→ P: $hp_E \rightarrow W$ etc.	(1) {2, 11}; {1} → {2} Convert powers. See pp. 134ff.
$hp_M \rightarrow W$		
$hp_{UK} \rightarrow W$		
Hyper	f PROB g Hyper: Hyper etc.	(1) {2, 11} *Hypergeometric distribution* with the number of successes ***g*** in **X**, the probability of a success p_0 in **I**, the sample size ***n*** in **J**, and the batch size n_0 in **K**. See pp. 196ff for the formula. $Hyper^{-1}$ returns the maximum number of successes ***m*** for a given probability ***p*** in **X**, p_0 in **I**, ***n*** in **J**, and n_0 in **K**.
$Hyper_p$		
$Hyper_u$		
$Hyper^{-1}$		
Hyper:	f PROB g Hyper:	*Submenu*. See p. 121.
ħ	g CNST ħ	(−1) { } → {2} $= h/2\pi$, so-called '*Dirac* constant' in *joule-second*.
I		Reserved variable for *register* **I**.
IDIV	g INTS f IDIV	(2) {1, 10}; {2, 11} → {1} Integer division, working like / IP.
IDIVR	f CATALOG FCNS IDIVR	{1, 10}; {2, 11} → {1} Works like IDIV but also returns the remainder in **Y**.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
iHg→Pa	g U→ F&p: f in.Hg→Pa	(1) {2, 11}; {1} → {2} Converts pressures. See pp. 134ff.
IINTS	f CATALOG VARS IINTS	*Submenu* of variables defined at execution time. See pp. 112ff.
Im	g CPX f Im	(1) {3} → {2}; {9} → {8}; {12} → {11} Returns the imaginary part of ***x***. Cf. RE.
IMPFRC	g d/c	(1) {2, 11} Allows only *improper fractions* in display (e.g. $^{5}/_{3}$ instead of $1\,^{2}/_{3}$). Displays any ***x*** according to the settings by DEN… as an *improper fraction*. Cf. PROFRC.
INC	f LOOP f INC ***r***	(0) {1, 2, 10, 11} Increments ***r*** by 1. Does not load **L** even for target address **X**.
INDEX	f MATX f INDEX ***name***	(1) Indexes a named matrix. You can also index a matrix by editing it (see M.EDIT or M.EDIN). After exiting the *Matrix Editor*, the matrix is no longer indexed. See also *Matrix Utility Functions* in the *HP-42S Owner's Manual*, pp. 223ff.
INFO	g INFO	*Menu*. See p. 120.
INPUT	g P.FN INPUT ***r***	Works in programs only: Recalls the content of the source specified into **X**, displays the name of the source along with ***r***, and halts program execution, allowing you to enter or calculate a value; pressing R/S then stores ***x*** into said destination and continues program execution – pressing EXIT instead cancels INPUT, so R/S thereafter will continue with the source content as it was.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
		If you use an input variable name undefined at execution time, INPUT automatically creates the variable with an initial value of zero.
INTS	g INTS	*Menu*. See p. 120.
INT?	g TEST f INT?	(0) Tests x for being an integer, i.e. having a fractional part equal to zero. Cf. FP?.
INVRT	f CATALOG FCNS INVRT	Works like $[M]^{-1}$ on p. 102. INVRT is featured for backward compatibility only.
in.→m	g U→ x: g in.→m	(1) {2, 11}; {1} → {2} Converts distances. See pp. 134ff.
IP	f PARTS IP	(1) {1, 2, 8*, 10, 11} Returns the integer part of x. Cf. FP.
ISE	f LOOP ISE *r*	(0) {1, 2, 10, 11} Given `cccccc.fffii` in the source, ISE increments r by `ii`, skipping next program step if `cccccc` ≥ `fff` then. If r has no fractional part then `fff` = 0 and `ii` = 0. If `ii` = 0, `cccccc` will be incremented by 1. ISE does not load **L** even for target address **X**. Note that neither `fff` nor `ii` can be negative, but `cccccc` can.
ISG	f LOOP ISG *r*	(0) {1, 2, 10, 11} Works like ISE above but skips if `cccccc` > `fff`.
ISZ	f LOOP ISZ *r*	(0) {1, 2, 10, 11} Increments r by 1, skipping next program step if then $\lvert r \rvert < 1$. ISZ does not load **L** even for target address **X**. Known from *HP-16C*.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
I_{xyz}	g X.FN f I_{xyz}	(3) {1, 2, 11} Returns the regularized beta function. See p. 224 for more.
$I\Gamma_p$ $I\Gamma_q$	g X.FN f $I\Gamma_p$ etc.	(2) {1, 2, 11} Returns the regularized gamma function (one of two kinds).
I+	f MATX ▲ I+	(1) Increments or decrements the row index of the indexed matrix. See INDEX and also J+, J −, RCLEL, STOEL, RCLIJ, and STOIJ.
I-	f MATX ▲ I-	
I/O	g I/O	*Menu*. See p. 120.
i%/a	g FIN TVM i%/a	(1) Reserved variable for the annual interest rate of your investment or loan in *TVM*.
J		Reserved variable for *register* **J**.
$J_y(x)$	g X.FN g $J_y(x)$	(2) {2, 11}; {1} → {2} $J_y(x)$ returns the *Bessel function of first kind* and order y. See p. 225 for details.
J+	f MATX ▲ J+	(1) Increments or decrements the column index of the indexed matrix. If M.GROW is set and the pointers I and J are at the last element of the matrix, executing J+ creates a new row at the end of the matrix. See INDEX and also I+, I−, RCLEL, STOEL, RCLIJ, and STOIJ.
J-	f MATX ▲ J-	
J/G	g CLK ▲ f J/G	(0) {2, 6} Sets the date the Gregorian calendar was introduced in the region you are interested in. See *Dates* in *Section 2* of the *OM*.
J→Btu	g U→ E: J→Btu	(1) {2, 11}; {1} → {2} Convert energies. See pp. 134ff.
J→cal	g U→ E: J→cal	

Item	Keystrokes	Remarks (see pp. 12ff for general information)
J→D	g CLK f J→D	(1) {1} → {6} Takes ***x*** as a *Julian day number*[15] and converts it to a common *date* according to J/G (s. above) and the date format selected.
J→Wh	g U→ E: J→Wh	(1) {2, 11}; {1} → {2} Converts energies. See pp. 134ff.
K		Reserved variable for *register* **K**.
k	g CNST k	(−1) { } → {2} *Boltzmann* constant in *joule per kelvin*.
KEY		See KEYG and KEYX below.
KEYG KEYX	g P.FN P.FN2 KEYG ***key#, labl*** etc.	Defines the label to be branched to (KEYG) or called (KEYX) when a particular *softkey* is pressed. KEYG and KEYX work in *PEM* only and will be translated to a program step KEY ***key#*** GTO ***labl*** or KEY ***key#*** XEQ ***labl*** , respectively. Key numbers go from 1 to 18 with 1 corresponding to F1, 9 to f F3, and 14 to g F2, for example.
KEY?	g TEST g KEY? ***r***	(0) Tests if a key was pressed while a routine was running or paused. If no key was pressed in that interval, the next program step after KEY? will be executed; else it will be skipped and the code of said key will be stored in the address specified. Key codes reflect the rows and columns on the keyboard (see the *OM, Sect. 3*).

[15] Translator's note: *Julian day number* translates to "Julianisches Datum" in German and «jour Julien» in French. See the corresponding articles in *Wikipedia* for more information about these numbers.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
kg→cwt kg→lbs kg→oz	g U→ m: kg→cwt etc.	
kg→scw	g U→ m: f kg→sh.cwt	(1) {2, 11}; {1} → {2} Convert masses. See pp. 134ff.
kg→sto	g U→ m: f kg→stones	
kg→s.t	g U→ m: ▲ kg→sh:tons	
kg→ton	g U→ m: ▲ kg→tons	
kg→tr.oz	g U→ m: f kg→tr.oz	
K_J	g CNST K_J	(−1) { } → {2} *Josephson* constant in *hertz* per *volt*.
KTYP?	g INFO KTYP? *r*	(−1) { } → {1} Assumes a key code in the address specified (see KEY?), checks it, and returns the key type: • 0 … 9 if it corresponds to a digit 0 … 9, • 10 if it corresponds to ., E, or +/−, • 11 if it corresponds to f or g, • 13 if it corresponds to a softkey, and • 12 if it corresponds to any other key. May help in user interaction with routines.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
L		Reserved variable for *register* **L**.
LASTx	RCL L	(−1) See *Section 1* of the *OM*. Actually, this command will be recorded as RCL L in routines.
lbf→N	g U→ F&p: lbf→N	(1) {2, 11}; {1} → {2} Converts forces. See pp. 134ff.
LBL	g LBL *labl*	(0) Identifies programs and routines for execution and branching. Read more about specifying labels in *Section 3* of the *OM*.
LBL?	g TEST g LBL? ***labl***	(0) Tests for the existence of the label specified, anywhere in program memory. See LBL for more.
lbs→kg	g U→ m: lbs→kg	(1) {2, 11}; {1} → {2} Converts masses. See pp. 134ff.
LCM	g INTS f LCM	(2) {1; 10} Returns the *Least Common Multiple* of x and y.[16] This will always be positive.
LEAP?	g TEST f LEAP?	(0) {2, 6, 11} Assumes x containing a *date* in the format selected (or a real number in corresponding format), extracts the year, and tests for a leap year.

[16] See also GCD. – Translator's note for French and German readers: LCM correspond à PPCM en français; LCM entspricht kgV auf Deutsch.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
LgNrm LgNrm$_p$ LgNrm$_u$ LgNrm^{-1}	f PROB f LgNrm: LgNrm etc.	(1) {2, 11} *Log-normal distribution* with $\mu = ln\,\bar{x}_g$ specified in **I** and $\sigma = ln\,\varepsilon$ in **J**. See $\bar{x}_g$ and ε below and pp. 196ff for more. LgNrm^{-1} returns ***x*** for a given probability ***p*** in **X**, with ***μ*** in **I** and ***σ*** in **J**.
LgNrm:	f PROB f LgNrm:	*Submenu*. See p. 121.
LinF	g STAT ▲ f LinF	(0) Selects the linear fit model. Relevant for CORR, COV, L.R., s_{XY}, $\hat{x}$, and $\hat{y}$. See pp. 196ff for more.
LJ	f BITS ▲ g LJ	(−1) {10} Left justifies a bit pattern within its *word* size as in *HP-16C*: The *stack* will lift, placing the left-justified *word* in **Y** and the count (of bit-shifts necessary to left justify the *word*) in **X**. **Example** for *word* size 8: 1 0110$_2$ LJ returns $x = 3$ and $y = 1011\ 0000_2$.
LN	ln	(1) {2, 3, 8*, 9*, 11, 12}; {1, 10} → {2} Returns the natural logarithm of ***x***.
L_n	g X.FN Orthog L_n	(2) {2, 11}; {1} → {2} *Laguerre polynomials*. See pp. 211f for more.
LN1+x	g EXP f ln 1+x	(1) {2, 3, 8*, 9*, 11, 12} For $x \approx 0$, this returns a more accurate result for the fractional part than $\ln(x)$ does.
$L_{n\alpha}$	g X.FN Orthog $L_{n\alpha}$	(3) {2, 11}; {1} → {2} *Laguerre's generalized polynomials*. See pp. 211f for more.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
LNβ	g X.FN g lnβ	(2) {2, 3, 11, 12}; {1} → {2} Returns the natural logarithm of *Euler's* Beta function (see p. 91).
LNΓ	g X.FN g lnΓ	(1) {2, 3, 11, 12}; {1} → {2} Returns the natural logarithm of $\Gamma(x)$ (see p. 91). Allows also for calculating really great factorials.
LOAD	g I/O LOAD ON + RCL + RCL	Restores the entire backup from *FM* and returns **Backup restored**. Thus, LOAD = LOADP + LOADR + LOADSS + LOADΣ. Not programmable.
LOADP	g I/O LOADP	(0) Loads the complete program memory from backup and appends it to the programs already in *RAM*. This will only work if there is enough space – else an error will be thrown. Not programmable.
LOADR	g I/O LOADR	(0) Recovers the numbered general purpose *registers* from backup. Lettered *registers* will not be recalled.
LOADSS	g I/O LOADSS	(0) Recovers the system state from backup.
LOADΣ	g I/O LOADΣ	(0) Recovers the statistical summation *registers* from backup. Throws an error if there are none.
LocR	g P.FN g LocR ***n***	(0) Allocates ***n*** *local registers* (≤ 100) and 16 *local flags* for the *current routine*. See *Section 3* of the *OM*.
LocR?	g INFO f LocR?	(−1) { } → {1} Returns the number of *local registers* currently allocated.

See SAVE on p. 72 and *App. A* on pp. 142f for more.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
LOG$_{10}$	g lg	(1) {1, 2, 3, 8*, 9*, 10, 11, 12} ({1} → {2}) Returns the logarithm of x for base 10.
LOG$_2$	g EXP lb x	(1) {1, 2, 3, 8*, 9*, 10, 11, 12} ({1} → {2}) Returns the logarithm of x for base 2.
LogF	g STAT ▲ f LogF	(0) Selects the logarithmic curve fit model. Relevant for CORR, COV, L.R., s_{XY}, $\hat{x}$, and $\hat{y}$. See pp. 196ff for more.
Logis Logis$_p$ Logis$_u$ Logis^{-1}	f PROB f Logis: Logis etc.	(1) {2, 11} *Logistic distribution* with μ given in I and s in J. See pp. 196ff for details.
Logis:	f PROB f Logis:	*Submenu*. See p. 121.
LOG$_x$y	g EXP log$_x$y	(2) {1, 2, 3, 8*, 9*, 10, 11, 12}; ({1} → {2}) Returns the logarithm of y for the base x .
LOOP	f LOOP	*Menu*. See p. 120.
l$_p$	g CNST l$_p$	(−1) { } → {2} *Planck* length in *meter*.
ly→m	g U→ x: ly→m	(1) {2, 11}; {1} → {2} Converts distances. See pp. 134ff.
LZOFF LZON	g DISP ▲ g LZOFF etc.	(0) Toggles leading zeros in *finite integers* like *flag* 3 does in *HP-16C*. Works in bases 2, 4, 8, and 16 only.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
L.R.	g STAT ▲ L.R.	(−2) { } → {2} Pushes the parameters a_1 (in Y) and a_0 (in X) of the fit curve through the data points accumulated in the statistical summation *registers*, according to the curve fit model selected (s. LINF, ORTHOF, EXPF, POWERF, LOGF). For a straight line, a_0 is its y-intercept and a_1 is its slope. See pp. 196ff for more.
$m^2 \rightarrow ac$	g U→ f A: $m^2 \rightarrow acres$	(1) {2, 11}; {1} → {2} Convert areas. See pp. 134ff.
$m^2 \rightarrow ac_{US}$	g U→ f A: $m^2 \rightarrow acres_{US}$	
$m^3 \rightarrow fz_{UK}$	g U→ f V: f $m^3 \rightarrow floz_{UK}$ etc.	(1) {2, 11}; {1} → {2} Convert volumes. See pp. 134ff.
$m^3 \rightarrow fz_{US}$		
$m^3 \rightarrow gl_{UK}$	g U→ f V: $m^3 \rightarrow gl_{UK}$ etc.	
$m^3 \rightarrow gl_{US}$		
MANT	f PARTS f MANT	(1) {2, 11}; {1} → {2} Returns the mantissa ***m*** of the number $x = m \cdot 10^h$ displayed. Cf. EXPT.
MASKL	f BITS MASKL ***n***	(−1) { } → {10} Work like MASKL and MASKR on *HP-16C*, but with the mask length (or its address) following the command instead of taken from X. Thus, the mask is pushed on the *stack*. **Example:** For WSIZE **8**, MASKL **3** returns a mask *word* $1110\ 0000_2$. Use it e.g. for extracting the three most significant bits of an arbitrary *byte* via AND.
MASKR	f BITS MASKR ***n***	

Item	Keystrokes	Remarks (see pp. 12ff for general information)
MATRS	f CATALOG VARS MATRS	*Submenu* of variables defined at execution time. See pp. 112f.
MATR?	g TEST ▲ MATR?	(0) Checks if x is a real or complex matrix.
MATX	f MATX	*Menu*. See p. 120.
Mat_A	Mat A	Reserved variables for solving systems of linear equations (*SLE*, see *Sect. 2* of the *OM*).
Mat_B	Mat B	
Mat_X	Mat X	(−1) Returns the solution vector of an *SLE*.
max	g X.FN g max	(2) {1, 2, 4, 5, 6, 10, 11} Returns the maximum of x and y.
m_e	g CNST m_e	(−1) { } → {2} Electron mass in *kilogram*.
MEM?	g INFO MEM?	(−1) { } → {2} Returns the number of free *words* in program memory (1 *word* = 2 *bytes*), also taking into account the local *registers* allocated.
MENU	g P.FN P.FN2 MENU	Displays the programmable *menu*. See the *HP-42S OM, Part 2, Section 10*, p. 146.
MENUS	f CATALOG MENUS	*Submenu* of *menus* defined at execution time. See pp. 112ff.
min	g X.FN g min	(2) {1, 2, 4, 5, 6, 10, 11} Returns the minimum of x and y.
MIRROR	f BITS f MIRROR	(1) {10} Reflects the bit pattern in x (e.g. 0001 0111_2 would become 1110 1000_2 for *word* size 8).

Item	Keystrokes	Remarks (see pp. 12ff for general information)
mi.→m	g U→ × f mi.→m	(1) {2, 11}; {1} → {2} Converts distances. See pp. 134ff.
M_M m_n m_n/m_p	g CNST M_M etc.	(−1) { } → {2} Masses of the Moon and the neutron in *kilogram*; neutron to proton mass ratio.
MOD	g INTS f MOD	(2) {1, 2, 3, 10, 11, 12} Returns $y \bmod x$ (see the *OM* for examples). Cf. RMDR.
MODE	g MODE	*Menu*. See p. 120.
MONTH	g CLK f MONTH	(1) {2, 6, 11} → {1} Assumes x containing a *date* in the format selected (or a real number in corresponding format) and extracts the month.
M_P m_P m_P/m_e	g CNST M_P etc.	(−1) { } → {2} *Planck* mass and proton mass in *kilogram*; proton to electron mass ratio.
MSG	g P.FN P.FN2 f MSG	(0) {1, 2, 11} Throws the (*temporary*) *error message* specified by the integer part of x. Cf. ERR. See *App. C* on pp. 160ff for the respective error codes.
m_u m_uc^2	g CNST M_u g CNST m_uc^2	(−1) { } → {2} Atomic mass constant in *kilogram* and its energy equivalent in *joule*.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
MULT×	g DISP ▲ f MULT×	(0) Select the symbol × or · for multiplication display.
MULT·	g DISP ▲ f MULT·	
MULπ	g MODE MULπ	(0) Sets the *ADM* to *multiples of* π.
MULπ→	f L→ f ∡π→∡	(1) {1, 2, 4, 11} → {4} Converts angles as described on pp. 140f.
MVAR	g P.FN P.FN2 f MVAR ***name***	(0) Defines a *menu variable*. Such variables are required for VARMNU. Works in *PEM* only.
MyMenu	f CATALOG MENUS MyMenu	*Menu*.
Myα	f CATALOG CHARS Myα	See the *OM, Sect. 6.* *Menu* in *AIM*.
m_μ	g CNST m_μ	(−1) { } → {2} Muon mass in *kilogram*.
M.DELR	f DELR while editing a matrix	(0) {8, 9} Deletes the current row of elements (where the cursor is in). Will not work if the matrix has only one row.
M.DIM	f MATX f DIM ***name***	(0) {1, 2} Creates a new named matrix or re-dimensions an existing matrix to IP(***y***) rows and IP(***x***) columns. See DIM in the *HP-42S Owner's Manual*, p. 217.
M.DIM?	g INFO g DIM? f MATX ▲ f DIM?	{8, 9} → {1} Returns the dimensions of the matrix ***x*** (rows to **Y**, columns to **X**). Note the matrix is saved in **L**. Previous ***y*** goes into **Z**, previous ***z*** into **T**, etc.
M.DY	g CLK ▲ M.DY	(0) Sets the format `mm/dd/yyyy` for *date* display.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
M.EDI	f MATX EDIT	(2) {8, 9} Opens x using the *Matrix Editor* (like MATRIX EDIT in *HP-42S*). See *Section 2* of the *OM*.
M.EDIN	f MATX f EDITN ***name***	(2) Opens a named matrix using the *Matrix Editor* (like MATRIX EDITN in *HP-42S*). See *Section 2* of the *OM*.
M.EDIT		*Submenu* for matrix editing, called by M.EDI or M.EDIN. See p. 120.
M.GET	f MATX g GETM	(0) {1, 2} → {8, 9} Gets a sub-matrix with IP(y) rows and IP(x) columns out of the indexed matrix into **X** (like GETM in *HP-42S*). Cf. M.PUT.
M.GOTO	f GOTO while editing a matrix	(0) Asks for target row and column and moves to this matrix element.
M.GROW	f GROW while editing a matrix	(0) Allows the indexed matrix to grow automatically (see J+ above and *Section 2* of the *OM*; see also GROW in the *HP-42S Owner's Manual*, p. 213.). Cf. M.WRAP.
M.INSR	f INSR while editing a matrix	(0) {8, 9} Inserts a new row of elements containing zero, left of the current cursor position in the matrix.
M.LU	f MATX ▲ f M.LU	(1) Takes a *descriptor* of a square matrix in **X**. Transforms (X) into its LU decomposition in-situ. The value in **X** is replaced by a *descriptor* that defines the pivots that were required to calculate the decomposition. The most significant digit is the pivot for the first diagonal entry, the next most significant for the second and so forth.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
M.NEW	f MATX NEW	(2) {1, 2} → {8} Creates a new matrix (like NEW in *HP-42S*). Its number of rows is supplied in **Y** and its number of columns in **X**. M.NEW returns an empty matrix in **X** – all its elements are set to zero.
M.OLD	OLD while editing a matrix	(0) Recalls the old element content (like OLD in *HP-42S*). See *Section 2* of the *OM*.
M.PUT	f MATX g PUTM	(0) {8, 9} Puts the matrix ***x*** as is into the indexed matrix (like PUTM in *HP-42S*). Cf. M.GET.
M.R⇄R	f MATX ▲ f R⇄R	(0) {8, 9} Swaps row ***x*** and row ***y*** of the indexed matrix (like R<>R in *HP-42S*).
M.SIMQ		*Submenu* of MATX, called by SIM_EQ.
M.SQR?	g TEST ▲ f M.SQR?	(0) Returns true if ***x*** is a square matrix.
M.WRAP	f WRAP while editing a matrix	(0) Controls the index pointers (see *Section 2* of the *OM*). Cf. M.GROW.
m:	g U→ m:	*Submenu*. See p. 134.
m→au	g U→ x: m→au	(1) {2, 11}; {1} → {2} Convert distances or heights. See pp. 134ff.
m→ft.	g U→ x: f m→ft.	
m→ft$_{US}$	g U→ x: ▲ m→s:feet$_{US}$	
m→in.	g U→ x: g m→in.	
m→ly	g U→ x: m→ly	
m→mi.	g U→ x: f m→mi.	

Item	Keystrokes	Remarks (see pp. 12ff for general information)
m→nmi.	g U→ x: f m→nmi.	
m→pc	g U→ x: m→pc	
m→pt.	g U→ x: g m→pt.	
m→yd.	g U→ x: g m→yd.	
$m_\odot$ $m_\oplus$	g CNST $m_\odot$ etc.	(−1) { } → {2} Masses of the Sun and Earth in *kilogram*.
N_A	g CNST N_A	(−1) { } → {2} *Avogadro's* number in *particles per mol*.
NaN	g CNST NaN	(−1) *Not a Number*.
NAND	f BITS f NAND	(2) Works in analogy to AND. See p. 18.
NaN?	g TEST ▲ f NaN?	(0) Returns `true` if x is *Not a Number*.
NBin $NBin_P$ $NBin_U$ $NBin^{-1}$	f PROB g NBin: NBin etc.	(1) {2, 11} *Negative binomial distribution* with the total number of failures ***f*** in **X**, the probability of a success p_0 in **I**, and the number of draws ***n*** in **J**. See pp. 196ff for more information.
NBin:	f PROB g NBin:	*Submenu*. See p. 121.
NEIGHB	g INFO f NEIGHB	(2) {1} Returns … • $x+1$ for $x<y$; • x for $x=y$; • $x-1$ for $x>y$.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
		(2) {2, 3, 11, 12} Returns the nearest machine-representable number to x in the direction towards y in the mode set. For • ... $x < y$, it is the machine successor of x; • ... $x = y$, it is y; • ... $x > y$, it is the machine predecessor of x. NEIGHB may be useful investigating numeric stability (see NEIGHBOR in the *HP-71 Math Pac*).
NEXTP	g X.FN g NEXTP	(1) {1, 2, 11} → {1} Returns the next prime number greater than x. If the result exceeds the greatest integer displayable, output format will switch to SCI.
nmi.→m	g U→ x: f nmi.→m	(1) {2, 11}; {1} → {2} Converts distances. See pp. 134ff.
NOP	g P.FN P.FN2 f NOP	(0) 'Empty' program step (for historical reasons only).
NOR	f BITS f NOR	(2) Works in analogy to AND. See p. 18.
Norml Norml_p Norml_u Norml^{-1}	f PROB f Norml: Norml etc.	(1) {2, 11} *Normal distribution* with an arbitrary mean μ given in $\mathbf{I}$ and a *standard deviation* σ in $\mathbf{J}$. See *Sect. 2* of the *OM* for an application example and pp. 196ff for more. Norml^{-1} returns x for a given probability p in $\mathbf{X}$, with μ in $\mathbf{I}$ and σ in $\mathbf{J}$.
Norml:	f PROB f Norml:	*Submenu*. See p. 121.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
NOT	f BITS NOT	(1) {10} Inverts x bit-wise as on *HP-16C*.
		(1) {1, 2, 11} → {1} Returns 1 for $x = 0$, and 0 for $x \neq 0$.
NPER	g FIN TVM n_{PER}	(1) Reserved variable for the total number of payment periods for your loan or total number of compounding periods for your investment in *TVM*.
nΣ	g STAT ▼ n	(−1) { } → {1} Recalls the number of accumulated data points.
N→lbf	g U→ F&p: N→lbf	(1) {2, 11}; {1} → {2} Converts forces. See pp. 134ff.
ODD?	g TEST f ODD?	(0) Checks if x is integer and odd.
OFF	g OFF	(0) In *PEM*, inserts a step to turn your *WP 43S* off under program control. Else turns your *WP 43S* off.
OR	f BITS OR	(2) Works in analogy to AND. See p. 18.
OrthoF	g STAT ▲ g OrthoF	(0) Selects the linear orthogonal fit model. Relevant for CORR, COV, L.R., s_{XY}, $\hat{x}$, and $\hat{y}$. See pp. 205ff for more.
ORTHOG	g X.FN Orthog	*Submenu*. See p. 124.
oz→kg	g U→ m: oz→kg	(1) {2, 11}; {1} → {2} Converts masses. See pp. 134ff.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
P_0	g CNST P_0	(−1) { } → {2} Standard atmospheric pressure in *pascal*.
PAUSE	g P.FN PAUSE ***n***	(0) With a routine running, refreshes the display and pauses program execution for ***n*** ticks (see TICKS), with $0 \le n \le 99$. The pause will terminate early when you press a key.
Pa→atm	g U→ F&p: f Pa→atm	(1) {2, 11}; {1} → {2} Convert pressures. See pp. 134ff.
Pa→bar	g U→ F&p: Pa→bar	
Pa→iHg	g U→ F&p: f Pa→in.Hg	
Pa→psi	g U→ F&p: Pa→psi	
Pa→tor	g U→ F&p: f Pa→torr	
PARTS	f PARTS	*Menu*. See p. 121.
pc→m	g U→ x: pc→m	(1) {2, 11}; {1} → {2} Converts distances. See pp. 134ff.
PERM	f PROB P_{yx}	(2) {1} Returns the number of possible arrangements (a.k.a. *permutations*) of ***x*** *items* taken out of a set of ***y*** *items*. No *item* occurs more than once in an arrangement, and different orders of the same ***x*** *items* are counted separately. Cf. COMB.
		(2) {2, 3, 11, 12} See pp. 194ff for the formula.
PER/a	g FIN TVM f per/a	(1) Reserved variable for the annual number of payments for your loan or compounding periods of your investment in *TVM*.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
PGMINT	f ADV f PGMINT ***labl***	Specifies the address of the expression to be integrated or solved, respectively. See *Section 4* of the *OM*.
PGMSLV	f ADV f PGMSLV ***labl***	
PIXEL	g P.FN P.FN2 g PIXEL	(0) Turns on a single pixel (dot) on the screen. The location of the pixel is given by the numbers in the **X**- and **Y**-*registers*. See AGRAPH on p. 17 for more.
PLOT	g STAT g PLOT	(0) See p. 234 for more.
PMT	g FIN TVM PMT	(1) Reserved variable for the payment per period for your investment or loan in *TVM*.
P_n	g X.FN Orthog P_n	(1) {2, 11}; {1} → {2} *Legendre polynomials*. See pp. 211f for more.
POINT	g P.FN P.FN2 g POINT	(1) {1, 2, 11} Turns on a square point (3×3 px ■) on the screen. The location of its center is given by integer parts of the numbers in the **X**- and **Y**-*registers*. See AGRAPH on p. 17 for more.
Poiss $Poiss_p$ $Poiss_u$	f PROB g Poiss: Poiss etc.	(1) {2, 11}; {1} → {2} *Poisson distribution* with the number of successes ***g*** in **X** and the *Poisson* parameter ***λ*** in **I**. See pp. 196ff for details.
$Poiss^{-1}$	f PROB g Poiss: $Poiss^{-1}$	(1) {2, 11} Returns the maximum number of successes ***m*** for a given probability ***p*** in **X** and ***λ*** in **I**.
Poiss:	f PROB g Poiss:	*Submenu*. See p. 121.
POLAR	g MODE POLAR g CPX g POLAR	(0) Sets polar format for displaying complex numbers.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
PopLR	g P.FN g PopLR	(0) Pops the local *registers* allocated to the *current routine* (see *Section 3* of the *OM*) without returning to the calling routine. See LOCR and RTN.
PowerF	g STAT ▲ f PowerF	(0) Selects the power curve fit model. Relevant for CORR, COV, L.R., s_{XY}, $\hat{x}$, and $\hat{y}$ (see pp. 196ff for more).
pr→dB	g U→ ▲ power ratio→dB	(1) {2, 11}; {1} → {2} Converts ratios. See pp. 134ff.
PRCL	g P.FN f PRCL	(0) Copies the *current program* (from *FM* or *RAM*) and appends it to *RAM*, where it can then be edited (see the *OM*). PRCL allows for duplicating programs in *RAM*. Will only work with enough space at destination. Recall a library routine from *FM*, edit it, and PSTO – this way you can modify this part of the *FM* library (see PSTO).
PRIME?	g TEST f PRIME?	(0) {1, 2, 11} Checks if the absolute value of IP(x) is a prime. The method is believed to work for integers up to 9×10^{18}.
PROB	f PROB	*Menu*. See p. 121.
PROFRC	f a b/c	(1) {2, 11} Allows only *proper fractions* in display. Displays any x according to the settings by DEN… as a *proper fraction*, e.g. 1.25 or $^{5}/_{4}$ as $1\,^{1}/_{4}$. Cf. IMPFRC.
PROGS	f CATALOG PROGS	*Submenu* of global labels defined at execution time. See pp. 112f.
psi→Pa	g U→ F&p: psi→Pa	(1) {2, 11}; {1} → {2} Converts pressures. See pp. 134ff.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
PSTO	g P.FN f PSTO	(0) Copies the *current program* (see the *OM)* from *RAM* and appends it to the *FM* library. Not programmable. Cf. PRCL. This program must include at least one LBL statement with a global label (preferably at its beginning). If a program with the same label already exists in the library it will be deleted first. Global labels may be browsed in CATALOG PROGS and called by XEQ.
pt.→m	g U→ x: g pt.→m	(1) {2, 11}; {1} → {2} Converts heights. See pp. 134ff.
PUTK	g P.FN f PUTK *r*	(0) Assumes a key code in the address specified. Stops program execution, takes said code and puts it in the keyboard buffer resulting in immediate execution of the corresponding call. R/S is required to resume program execution then. May help in user interaction with routines.
PV	g FIN TVM PV	(1) Reserved variable for the present value of your investment or loan in *TVM*.
P.FN	g P.FN	*Menu*. See p. 122.
P.FN2	g P.FN P.FN2	*Submenu*. See p. 122.
P:	g U→ P:	*Submenu*. See p. 134.
QUIET	g I/O f QUIET g MODE f QUIET	(0) Toggles the *flag* to disable or enable the beeper (not programmable).

Item	Keystrokes	Remarks (see pp. 12ff for general information)
R	g CNST R	(−1) { } → {2} Molar gas constant in *joule per mol and kelvin*.
RAD	g MODE RAD	(0) Sets the *ADM* to *radians*.
RAD→	f L→ f $\measuredangle^r\to\measuredangle$	(1) {1, 2, 4, 11} → {4} Converts angles as described on p. 140.
RAM	f CATALOG PROGS RAM	*Submenu* of global labels defined at execution time. See pp. 112f.
RAN#	f PROB ▲ RAN#	(−1) { } → {2} Returns a random number between 0 and 1 like RAN does in *HP-42S*.
RBR	g RBR	Calls the *register browser*. See *Sect. 5* of the *OM*. You may call RBR also in *PEM* but it is not programmable.
RCL	RCL *r*	(−1) Recalls the content of a *register* or variable.
RCLCFG	RCL f Config *r*	(0) Recalls a configuration stored by STOCFG (see *Section 2* of the *OM*).
RCLEL	f MATX g RCLEL	(−1) { } → {2, 3} Recalls a copy of the current element a_{ij} of the indexed matrix. Cf. STOEL.
RCLIJ	f MATX ▲ RCLIJ	(−2) { } → {1} Recalls the current values of the matrix index pointers into **X** (= column number) and **Y** (= row number). If the pointers both equal zero, then there is currently no indexed matrix. Cf. STOIJ.
RCLS	RCL f Stack *r*	Recalls 4 or 8 values from a set of *registers* starting at address ***r***, and pushes them on the *stack*. This is the converse command of STOS.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
RCL+	RCL + *r*	(1) Recalls a content of a *register* or variable, executes the operation specified, and puts the result on the *stack* like a *monadic* function.[17] **Example:** RCL−12 replaces x with $x-r12$.
RCL−	RCL − *r*	
RCL×	RCL × *r*	
RCL/	RCL / *r*	
RCL↑	RCL f Max *r* RCL ▲ *r*	(1) {1, 2, 4, 5, 6, 10, 11} Replaces x with the maximum of r and x.[17]
RCL↓	RCL f Min *r* RCL ▼ *r*	(0) {1, 2, 4, 5, 6, 10, 11} Replaces x with the minimum of r and x.[17]
RDP	f PARTS f RDP *n*	(1) {2, 3, 5, 8*, 9*, 11, 12} Rounds x to n decimal places ($0 \le n \le 99$, think of FIX format), taking the RM setting into account. See RM and compare RSD.
RDX, RDX.	g DISP ▲ f RDX, etc.	(0) Select a comma or a point as decimal radix mark.
r_e	g CNST r_e	(−1) { } → {2} Classical electron radius in *meter*.
Re	g CPX f Re	(1) {3} → {2}; {9} → {8}; {12} → {11} Returns the real part of x. Cf. IM.
REALRES	g MODE f REALRE g FLAGS CF	(0) Allows only real results, no complex ones. The letter S cannot be shown in the *menu view* for space reasons there. Cf. CPXRES.

[17] Only legal operations according to the matrices in *Section 2* of the *OM* will work. See also the examples given there.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
REALS	f CATALOG VARS REALS	*Submenu* of real variables defined at execution time. See pp. 112f.
REAL?	g TEST ▲ REAL?	(0) Checks if x is a real number or matrix.
RECT	g MODE RECT g CPX g RECT	(0) Sets rectangular (Cartesian) format for displaying complex numbers.
REGS		Reserved variable for the 100×1 matrix of registers – if required.
RECV	g I/O f RECV	(0) Prepares your *WP 43S* for receiving data via serial I/O. See SEND and *Section 3* in the *OM* for more.
RESET	g CLR g RESET	If confirmed, executes CLALL and resets all modes to *startup default*, i.e. 24h, 2COMPL, ALL **0**, CPXi, DEG, DENANY, DENMAX **0**, DSTACK **4**, GAP **3**, J/G **1752-01-01**, LinF, LocR **0**, LZOFF, MULT×, PROFRC, RDX., REALRES, RECT, RM **0**, SCIOVR, SSIZE4, TDISP **−1**, WSIZE **64**, and Y.MD. See these individual commands for more. RESET is not programmable.
RE→CX	f CC or g CPX CC	(2) {2} → {3}; {11} → {12} Composes a complex number out of two real numbers x and y, taking either • (for ⌙) the real part from **X** and the imaginary part from **Y**, or • (for ⊙) the magnitude from **X** and the angle from **Y**. Sets ℂ unless set before.
		(2) {8} → {9} Works in analogy for two real matrices x and y.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
Re⇄Im	g CPX f Re⇄Im	(1) {3, 9*, 12} Swaps the real and imaginary parts of complex objects.
RJ	f BITS ▲ f RJ	(−1) {10} Right justifies a bit pattern within its word size, in analogy to LJ on *HP-16C*. **Example:** 10 1100_2 RJ results in $y = 1011_2$ and $x = 2$. Cf. LJ.
R_K	g CNST R_K	(−1) { } → {2} *Von Klitzing* constant in *ohm*.
RL RLC	f BITS ▲ RL ***n*** etc.	(1) {10} Work like ***n*** consecutive RLs / RLCs on *HP-16C*, similar to RLn / RLCn there. For RL, $0 \le n \le 63$. For RLC, $0 \le n \le 64$. RL 0 / RLC 0 execute as NOP, but load **L**. See the *OM, Sect. 2,* for more.
R_M	g CNST R_M	(−1) { } → {2} Mean radius of the Moon in *meter*.
RM	g MODE f RM ***n***	(0) Sets floating point rounding mode. This rounding mode is used only for RSD or when converting from the high precision internal format (39 digits) to packed real numbers. It will not alter the display nor change the behavior of ROUND. The following seven modes are supported: 0: round half even: ½ = 0.5 rounds to next even number (default).[18] 1: round half up: 0.5 rounds up *('businessman's*

[18] This is the way of rounding used in science.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
		rounding' [19]). 2: round half down: 0.5 rounds down. 3: round up: rounds away from 0. 4: round down: rounds towards 0 (truncates). 5: ceiling: rounds towards + ∞. 6: floor: rounds towards – ∞.
RM?	g INFO RM?	(–1) { } → {1} Returns the floating point rounding mode set. See RM for more.
RMDR	f RMDR g INTS f RMDR	(2) {1, 2, 3, 10, 11, 12} Returns the remainder of a division. Equals RMD on *HP-16C* but works for real numbers as well. See *Section 2* of the *OM* for examples. Cf. MOD.
RNORM	f MATX g RNORM	(1) {8, 9} Calculates the row norm of the matrix in **X**, i.e. the maximum value (over all rows) of the sums of the absolute values of all elements in a row (like RNRM on *HP-42S*). For a vector, the row norm is the largest absolute value of any of its elements.
ROUND	f PARTS ROUND	(1) {2, 3, 4, 5, 6, 8*, 9*, 11, 12} Rounds ***x*** using the current display format like RND on *HP-42S*.
ROUNDI	f PARTS f ROUNDI	(1) {8}; {2, 11} → {1}; Rounds ***x*** to next integer. ½ rounds to 1.

[19] Translator's notes for French and German readers: Cela correspond à l'arrondi commercial. / Das entspricht kaufmännischer Rundung.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
RR RRC	f BITS ▲ RR ***n*** etc.	(1) {10} Work like ***n*** consecutive RRs / RRCs on *HP-16C*, similar to RRn / RRCn there. For RR, 0 ≤ ***n*** ≤ 63 . For RRC, 0 ≤ ***n*** ≤ 64 . RR 0 / RRC 0 execute as NOP, but load **L**. See the *OM, Sect. 2,* for more.
RSD	g RSD ***n*** f PARTS RSD ***n***	(1) {2, 3, 5, 8*, 9*, 11, 12} Rounds ***x*** to ***n*** significant digits (1 ≤ ***n*** ≤ 34), taking the RM setting into account. See RM, cf. RDP.
RSUM	f MATX ▲ f RSUM	(1) {8, 9} Calculates the row sum of the matrix in **X**, returning an ***m*** × 1 matrix filled with the row sums of the ***m*** × ***n*** input matrix.
RTN	g RTN	(0) In *PEM*: RTN is the logically last command in a routine (see *Section 3* of the *OM*). In a routine executing: RTN pops local data (cf. PopLR) and returns to the caller, i.e. moves the program pointer one step behind the XEQ instruction that called said routine. If there is none (i.e. this routine is top level), program execution halts, the program pointer is set to step 0000, and ⤒ is lit. If RTN is pressed in *run mode* with no routine executing, it resets the program pointer to the start of *current program* (see *Section 3* of the *OM*). If the program is in *FM*, the pointer is set to step 0000 in *RAM*, and ⤒ is lit.
RTN+1	g P.FN P.FN2 RTN+1	(0) Works like RTN, but moves the program pointer two steps behind the XEQ instruction that called said routine.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
R-CLR	g P.FN g R-CLR	(0) {2, 11} Interprets x in the form `sss.nn`. Clears ***nn*** *registers* starting with address ***sss***. **Example:** For $x = 34.567$, R-CLR will clear **R34** through **R89**. **ATTENTION:** For ***nn* = 0**, clearing will cover the maximum available: • For $sss \in [0; 99]$, it will stop at **R99**. • For $sss \in [100; 111]$, it will stop at **K**. • For $sss \geq 112$, it will stop at the highest allocated local *register*.
R-COPY	g P.FN g R-COPY	(0) {2, 11} Interprets x in the form `sss.nnddd`. Takes ***nn*** *registers* starting with address ***sss*** and copies their contents to ***ddd*** etc. **Example:** For $x = 7.0304567$, ***r07, r08, r09*** will be copied into **R45, R46, R47**, respectively. For $x < 0$, R-COPY will take ***nn*** *registers* from *FM* instead, starting with *register* number $\lvert sss \rvert$. Destination will be in *RAM* always. **ATTENTION:** For ***nn* = 0**, copying will cover the maximum available as explained with R-CLR. Then x must be negative.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
R-SORT	g P.FN g R-SORT	(0) {2, 11} Interprets ***x*** in the form `sss.nn`. Sorts the contents of ***nn*** *registers* starting with address ***sss*** . **Example:** Assume ***x*** = 49.036 9, ***r49*** = 1.2, ***r50*** = −3.4, and ***r51*** = 0; then R-SORT will return ***r49*** = −3.4, ***r50*** = 0, and ***r51*** = 1.2. **ATTENTION:** For ***nn* = 0** , sorting will cover the maximum available as explained with R-CLR.
R-SWAP	g P.FN g R-SWAP	(0) {2, 11} Works like R-COPY but swaps the contents of source and destination *registers*.
R→D	f L→ g $x^r \to x^\circ$	(1) {1, 2, 4, 11} → {4} Converts angles as described on p. 140.
R↑	f R↑	Rotates the *stack* contents one level up or down, respectively. See *Section 1* of the *OM* for details.
R↓	R↓	
R_∞	g CNST R_∞ etc.	(−1) { } → {2} *Rydberg* constant (see p. 131);
$R_\odot$		mean radii of the Sun and Earth in *meter*.
$R_\oplus$		

Item	Keystrokes	Remarks (see pp. 12ff for general information)
s	g STAT **s**	(−2) { } → {2} Takes the statistical sums accumulated, calculates the *sample standard deviations* s_y and s_x and pushes them on the *stack*. See *Sect. 2* of the *OM* for the output format and pp. 196ff for the formula.
Sa	g CNST **Sa**	(−1) { } → {2} Semi-major axis in *meter* of the Earth model *WGS84*.[20]
SAVE	f SAVE	(0) Saves user program space, *registers* and system state to *FM*, and returns **Saved**. Recall your backup using the different flavors of LOAD. Not programmable. See App. A for more.
SB	f BITS g **SB** ***n***	(1) {10} Sets the specified bit in x .
Sb	g CNST **Sb**	(−1) { } → {2} Semi-minor axis in *meter* of *WGS84*.[20]
SCI	g DISP **SCI** ***n***	(0) Sets scientific display format (see *Sect. 2* of the *OM*).
scw→kg	g U→ m: f **sh.cwt→kg**	(1) {2, 11}; {1} → {2} Converts masses. See pp. 134ff.
SCIOVR	g DISP ▲ f **SCIOVR**	(0) Defines that numbers exceeding the range displayable in ALL or FIX will be shown in scientific format. Cf. ENGOVR, see RESET.
SDIGS?	g INFO f **SDIGS?**	(−1) { } → {1} Returns the number of significant digits set by SETSIG.

[20] This model is used to define the Earth's surface for surveying and GPS. See http://earth-info.nga.mil/GandG/publications/tr8350.2/tr8350_2.html

Item	Keystrokes	Remarks (see pp. 12ff for general information)
SDL SDR	g P.FN P.FN2 f SDL ***n*** etc.	(1) {2, 11} Shifts digits left (right) by ***n*** decimal positions, equivalent to multiplying (dividing) ***x*** by 10^{n}. Cf. SL and SR for binary integers.
Se^2	g CNST Se^2	(−1) { } → {2} First eccentricity squared of the Earth model *WGS84* (see footnote 20 on p. 72).
SEED	f PROB ▲ SEED	(0) {2, 11} Stores a seed for random number generation. If ***x*** = 0 , the seed is taken from the real-time clock.
SEND	g I/O f SEND	(0) Sends all *RAM* data to the device connected via serial I/O. See RECV and *Section 3* in the *OM* for more.
SETCHN	g DISP ▲ CHINA	(0) Sets some regional preferences (see *Section 2* of the *OM*).
SETDAT	g CLK ▲ SETDAT	(0) Sets the date for the real time clock (the emulator takes this information from the PC clock).
SETEUR	g DISP ▲ EUROPE	(0) Set some regional preferences (see *Section 2* of the *OM*).
SETIND	g DISP ▲ INDIA	
SETJPN	g DISP ▲ JAPAN	
SETSIG	g MODE ▲ SETSIG	(0) {1} Sets the number of significant digits (0 ... 34) for rounding after each operation. SETSIG 0 sets maximum precision.
SETTIM	g CLK ▲ SETTIM	(0) Sets the time for the real time clock (the emulator takes this information from the PC clock).

Item	Keystrokes	Remarks (see pp. 12ff for general information)
SETUK SETUSA	g DISP ▲ UK etc.	(0) Set some regional preferences (see *Section 2* of the *OM*).
Se'^{2}	g CNST Se'^{2}	(−1) { } → {2} Second eccentricity squared of the Earth model *WGS84* (see footnote 20 on p. 72).
SF	g FLAGS SF ***n***	(0) Sets the *flag* specified.
Sf^{-1}	g CNST Sf^{-1}	(−1) { } → {2} Flattening parameter of the Earth model *WGS84* (see footnote 20 on p. 72).
SHOW	g X.FN ▲ SHOW	(0) {3} Shows all digits stored in a *DP* number.
SIGN	f PARTS f sign	(1) {8}; {1, 2, 10, 11} → {1} Returns 1 for $x > 0$, -1 for $x < 0$, and 0 for $x = 0$ or non-numeric data. Corresponds to the mathematical function $\mathrm{signum}(x)$.
	g CPX f sign	(1) {3, 12} Returns the unit vector of the complex number x (cf. UNITV). Maintained for backward compatibility only.
SIGNMT	g INTS ▲ SIGNMT g MODE ▲ SIGNMT	(0) Sets sign-and-mantissa mode for operations on finite integers. See *Section 2* of the *OM*.
SIM_EQ	f MATX SIM EQ ***n***	(0) Solves a system of n linear equations $(MATA) \cdot \overrightarrow{MATX} = \overrightarrow{MATB}$. If these matrices are not defined before, they will be created automatically at execution time. See *Sect. 2* of the *OM* for more.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
sin	TRI sin	(1) {2, 3, 8*, 9*, 11, 12}; {1, 4} → {2} Returns the sine of the angle in **X**.
sinc	g X.FN ▲ sinc	(1) {2, 3, 8*, 9*, 11, 12} Returns $\frac{\sin(x)}{x}$ for $x \neq 0$ and **1** for $x = 0$. Note input has to be supplied in *radians* for calculating SINC.
sinh	g EXP g sinh	(1) {2, 3, 8*, 9*, 11, 12} Returns the hyperbolic sine of x.
SKIP	g P.FN P.FN2 g SKIP ***n***	(0) Skips ***n*** program steps forwards ($0 \le n \le 255$). So e.g. SKIP **2** skips over the next two steps, going e.g. from step 123 to step 126. If SKIP attempts to cross an END, an error is thrown. **ATTENTION:** If you edit a section of your routine crossed by one or more BACK, SKIP, or CASE jumps, this may well result in a need to **manually maintain all those statements individually.**
SL	f BITS ▲ SL ***n***	(1) {10} Works like ***n*** (≤ 63) consecutive SLs on *HP-16C*. SL 0 executes as NOP, but loads **L**. See *Sect. 2* of the *OM* for more.
SLOW	g MODE f SLOW	(0) Sets the processor speed to 'slow', about 50% of 'fast'. This is also automatically set for low battery voltage (s. the *OM, Sect. 2*). Cf. FAST.
SLVQ	f ADV SLVQ	{1, 2, 3} → {2 or 3} Solves the quadratic equation $ax^2 + bx + c = 0$ with its parameters on the input *stack* [***c, b, a***, …], and tests the result. • If $r := b^2 - 4ac \ge 0$, SLVQ returns $-\frac{b \pm \sqrt{r}}{2a}$

Item	Keystrokes	Remarks (see pp. 12ff for general information)
		in **Y** and **X**. In a routine, the step after SLVQ will be executed. • Else, SLVQ returns the first complex root in **X** and the second in **Y** (the complex conjugate of the first). In a routine, the step after SLVQ will be skipped. In either case, SLVQ returns ***r*** in **Z**. Higher *stack registers* are kept unchanged. **L** will contain equation parameter ***c***.
s_m	g STAT s_m	(−2) { } → {2} Takes the statistical data accumulated and pushes the *standard errors* (i.e. *std. deviations* of the means $\bar{y}$ and $\bar{x}$) on the *stack*. Output format will be like the one of s (see the *OM, Sect. 2*).
SMODE?	g INFO SMODE?	(−1) { } → {1} Returns the integer sign mode set for finite integers, i.e. true 2 for 2's complement, true 1 for 1's complement, false 0 for unsigned, or true −1 for sign & mantissa mode.
s_{mw}	g STAT f s_{mw}	(−1) { } → {2} Returns the *standard error* for weighted data, i.e. the *standard deviation* of the mean $\bar{x}_w$.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
SOLVE	f ADV SOLVE ***var***	{2} Solves the equation f(*var*) = 0, with **f** calculated by the equation specified (in *PEM* by PGMSLV). Two initial estimates of the root must be supplied in **X** and **Y** when calling SOLVE. It returns $\boldsymbol{var_{root}}$ in **X**, the second last ***var***-value tested in **Y**, then $\mathbf{f(var_{root})}$ in **Z**, and 0 in **T**. Additionally, SOLVE acts as test in programs, so the next program step will be skipped if SOLVE fails to find a root. See *Section 4* of the *OM* for more. **ATTENTION:** SOLVE fills all *stack registers* with ***x*** before calling the routine specified.
Solver	g EQN Solver	{2, 3} Solves a given equation. See the *OM, Sect. 4,* for more.
SPEC?	g TEST ▲ f SPEC?	(0) True if ***x*** is 'special' (±∞ or non-numeric).
SR	f BITS ▲ SR ***n***	(1) {10} Works like ***n*** (≤ 63) consecutive SRs on *HP-16C*. SR 0 executes as NOP, but loads **L**. See *Section 2* of the *OM* for more.
SSIZE4 SSIZE8	g STK g SSIZE4 etc. or g MODE g SSIZE4 etc.	Set the *stack* size to 4 or 8 *registers*, respectively (see *Section 1* of the *OM*). Note *register* contents will remain unchanged in this operation (as well as if *stack* size is modified by any other operation – e.g. by RCLCFG).
SSIZE?	g INFO SSIZE?	(−1) { } → {1} Returns the number of *stack registers* currently allocated, 4 or 8.
STAT	g STAT	*Menu*. See p. 122.
STATUS	g FLAGS STATUS	*Flag browser*. See *Section 5* of the *OM*.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
STK	g STK	*Menu*. See p. 122.
STO	STO *r*	(0) Stores *x* into destination.
STOCFG	STO f Config *r*	(0) Stores the current configuration for later use as described in *Section 2* of the *OM*. RCLCFG recalls such data.
STOEL	f MATX g STOEL	(1) {1, 2, 3} Stores a copy of *x* into the indexed matrix at the current element, a_{ij}. Cf. RCLEL.
STOIJ	f MATX ▲ STOIJ	(1) {1} Sets the index pointers to IP(*x*) (= column number) and IP(*y*) (= row number). Cf. RCLIJ.
STOP	R/S	(0) Stops program execution. May be inserted in programs to wait for input, for example.
STOS	STO f Stack *r*	(0) Stores the entire *stack* in a set of 4 or 8 *registers*, starting at the destination address specified. See RCLS.
STO+	STO + *r*	(0) Executes the specified operation on *r* and stores the result (e.g. $r-x$) at the address specified.[21]
STO−	STO − *r*	
STO×	STO × *r*	
STO/	STO / *r*	
STO↑	STO f Max *r* STO ▲ *r*	(0) {1, 2, 4, 5, 6, 10, 11} Stores the maximum of *r* and *x* in the address specified.[21]

[21] Only legal operations according to the matrices in *Section 2* of the *OM* will work. See also the examples given there.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
STO↓	STO f Min *r* STO ▼ *r*	(0) {1, 2, 4, 5, 6, 10, 11} Stores the minimum of ***r*** and ***x*** in the address specified. [21]
sto→kg	g U→ m: f stones→kg	(1) {2, 11}; {1} → {2} Converts masses. See pp. 134ff.
STRI?	g TEST g STRI?	(0) True if ***x*** is an alphanumeric string (like STR? in *HP-42S*).
STRING	f CATALOG VARS STRING	*Submenu* of variables defined at execution time. See pp. 112f.
ST.A ST.B ST.C ST.D ST.T ST.X ST.Y ST.Z		Reserved variables for *stack registers* **A** … **Z**
SUM	g STAT SUM	(−2) { } → {2} Recalls the linear sums ***Σy*** and ***Σx***. Useful in basic 2D vector algebra. Output is labeled in analogy to s.
s_w	g STAT f s_w	(−1) { } → {2} Calculates the *standard deviation* for weighted data (where the weight ***y*** of each data point ***x*** was entered via Σ+). See pp. 196ff for the formula.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
s_{xy}	g STAT ▲ s_{xy}	(−1) { } → {2} Calculates the *sample covariance* for the two data sets entered via Σ+, depending on the curve fit model selected. See pp. 196ff for the formula and COV for the *population covariance*.
s.t→kg	g U→ m: ▲ sh:tons→t	(1) {2, 11}; {1} → {2} Convert masses and times. See pp. 134ff.
s→year	g U→ f s→year	
T_0	g CNST T_0	(−1) { } → {2} = 0°C, standard temperature in *kelvin*.
tan	TRI tan	(1) {2, 3, 8*, 9*, 11, 12}; {1, 4} → {2} Returns the tangent of the angle in **X**. Returns "*Not a Number*" for $x = \pm 90°$ or equivalents if *flag* **D** is set.
tanh	g EXP g tanh	(1) {2, 3, 8*, 9*, 11, 12} Returns the hyperbolic tangent of x.
TDISP	g CLK ▲ TDISP ***n***	(0) Sets time display format. TDISP 0 allows for displaying just *hours* and *minutes*, TDISP 2 for *seconds*, too, and $n \geq 3$ also for $n-2$ digits showing decimal fractions of *seconds*. TDISP 1 is interpreted as TDISP 0. TDISP −1 allows for displaying all digits.
TEST	g TEST	*Menu*. See p. 122.
TICKS	g P.FN TICKS	(−1) { } → {1} Returns the number of ticks from the real time clock at execution time. 1 *tick* = 0.1 *s*. Counting starts when the calculator is turned on.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
TIME	g CLK TIME	(−1) { } → {5} Recalls the time from the real time clock at execution (see *Sect. 2* of the *OM* for the output format).
TIMER	f TIMER	Starts the timer application based on the real time clock and following the timer of *HP-55*. See *Sect. 5* of the *OM* for a detailed description.
TIMES	f CATALOG VARS f TIMES	*Submenu* of *time* variables defined at execution time. See pp. 112f.
T_n	g X.FN Orthog T_n	(2) {2, 11}; {1} → {2} *Chebyshev polynomials of first kind*. See pp. 211f for details.
TONE	g I/O f TONE ***n***	(0) Sounds a tone according to ***n*** (= 1 … 9) .
ton→kg	g U→ m: ▲ tons→kg	(1) {2, 11}; {1} → {2} Converts masses. See pp. 134ff.
TOP?	g TEST g TOP?	(0) Returns ... • `false` if called with the program pointer being in a subroutine; • `true` if called in the top routine (i.e. if the program-running *flag* is set and the *SRS* pointer is clear).
tor→Pa	g U→ F&p: f torr→Pa	(1) {2, 11}; {1} → {2} Converts pressures. See pp. 134ff.
T_p	g CNST T_p	(−1) { } → {2} Planck temperature in *kelvin*.
t_p	g CNST t_p	(−1) { } → {2} Planck time in *seconds*.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
$t_p(x)$ $t_u(x)$ $t(x)$ $t^{-1}(p)$	f PROB t: $t_p(x)$ etc.	(1) {2, 11} *Student's t distribution*. The degrees of freedom are stored in **J**. $t_u(x)$ equals Q(t) on *HP-21S*. See *Section 2* of the *OM* for an application example and pp. 196ff for more mathematical details.
TRANS	f CATALOG FCNS TRANS	Works like $[M]^T$ on p. 102. TRANS is featured for backward compatibility only.
TRI	TRI	*Menu*. See p. 122.
trz→kg	g U→ m: f tr.oz→kg	(1) {2, 11}; {1} → {2} Converts masses. See pp. 134ff.
TVM	g FIN TVM	Application. See *Section 5* of the *OM*.
t:	f PROB t:	*Submenu*. See p. 121.
t⇄	g STK t⇄ *r*	Swaps *t* and *r*, in analogy to $x\leftrightarrows$
ULP?	g INFO f ULP?	(1) {1, 2, 11} Returns 1 times the smallest power of ten which can be added to x or subtracted from x to actually change the value of x in your *WP 43S* in the mode set. Thus 1 is returned for *integers*.
U_n	g X.FN Orthog U_n	(2) {2, 11}; {1} → {2} *Chebyshev polynomials of second kind*. See pp. 211f for details.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
UNITV	f MATX f UNITV	(1) {8, 9} Returns the unit vector for the matrix ***x*** (like UVEC in *HP-42S*). Each element of the matrix is adjusted so its overall Euclidean norm becomes 1 (see ENORM); for a vector, its magnitude will become 1.
	g CPX UNITV	(1) {3, 12} Returns a complex number with magnitude |***r***| = 1 in direction of ***x***.
UNSIGN	g INTS ▲ UNSIGN g MODE ▲ UNSIGN	(0) Sets unsigned mode for mode for operations on finite integers. Cf. UNSGN on *HP-16C*. See *Section 2* of the *OM*.
U→	g U→	*Menu*. See p. 122.
VARMNU	g P.FN P.FN2 f VARMNU ***labl***	Creates a variable *menu* using MVAR instructions following the global label specified. Cf. the *HP-42S Owner's Manual.*
VARS	f CATALOG VARS	*Submenu* of variables defined at execution time. See pp. 112f.
VERS?	g INFO g VERS?	(0) Shows your firmware version and build number (see *Section 2* of the *OM*).
VIEW	f VIEW ***r***	(0) Shows ***r*** until the next key is pressed. **Example:** If ***r*** is e.g. a variable called **Test12** containing **−123.45**, VIEW α **Test12** ENTER↑ will display Test12 = −123.45
V_m	g CNST V_m	(−1) { } → {2} Molar volume of an ideal gas at standard conditions in *cubic meter per mol*.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
V:	g U→ f V:	*Submenu*. See p. 134.
WDAY	g CLK WDAY	(1) {2, 6, 11} → {1} Assumes x containing a *date* in the format selected (or a real number in corresponding format) and returns the name of the respective day and a corresponding integer (Monday = 1).[22]
Weibl Weibl_p Weibl_u Weibl^{-1}	f PROB f Weibl: Weibl etc.	(1) {2, 11} *Weibull distribution* with its shape parameter b in I and its characteristic lifetime T in J. See pp. 196ff for details. Weibl^{-1} returns the survival time t_s for a given probability p in X, with b in I and T in J.
Weibl:	f PROB f Weibl:	*Submenu*. See p. 121.
WHO?	g INFO g WHO?	(0) Displays credits to the brave men who made this project work.
Wh→J	g U→ E: Wh→J	(1) {2, 11}; {1} → {2} Converts energies. See pp. 134ff.
W_m W_p W^{-1}	g X.FN ▲ W_m etc.	(1) {2, 3, 11, 12}; {1} → {2} W_p returns the principal branch of *Lambert's* W for given $x \geq -1/e$. W_m returns its negative branch (works for $x \in \mathbb{R}$ only). W^{-1} returns x for a given W_p (≥ -1). See pp. 223ff for more.

[22] Translator's note: These day numbers correspond to Chinese weekdays 1 to 6 directly. For Portuguese weekdays ('segunda-feira' etc.), add 1 to days 1 to 5.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
WSIZE	g INTS ▲ WSIZE ***n***	(0) Works almost like on *HP-16C*, but with the parameter $1 \le n \le 64$ trailing the command instead of taken from X. Reducing *word* size truncates the values in the *stack* as allocated and in L. All other memory content stays as is (see *App. B* on pp. 152ff). Increasing the *word* size will add empty bits to each *stack register*. WSIZE **0** sets the *word* size to maximum, i.e. 64 *bits*.
	g MODE ▲ WSIZE ***n***	
WSIZE?	g INFO g WSIZE?	(−1) { } → {1} Recalls the *word* size set.
W→hp$_E$	g U→ P.8 W→hp$_E$ etc.	(1) {2, 11}; {1} → {2} Convert powers. See pp. 134ff.
W→hp$_M$		
W→hp$_{UK}$		
x^2	g x^2	(1) {1, 2, 3, 8*, 9*, 10, 11, 12} Return the square or cube of x, respectively.
x^3	g EXP x^3	
XEQ	XEQ ***labl***	(0) Executes the function or routine with the label specified. – In *PEM*, inserts a call to the subroutine with the label specified.
xIN	XEQ ***type***	with ***type*** = NILADIC, MONADIC, DYADIC, TRIADIC, or ..._COMPLEX defines how many *stack* levels are used for parameter input to the function under consideration. Furthermore it does some initialization work (e.g. SSIZE8 and DBLON). xIN is the recommended way to start an *XROM routine*. Thereafter, SSIZE4 is legal but DBLOFF is not. **Note xIN cannot nest** and *XROM routines* using xIN cannot call user code.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
XNOR	f BITS f XNOR	(2) Work in analogy to AND. See p. 18.
XOR	f BITS XOR	
xOUT	XEQ ***way***	Cleans and reverts the settings of xIN, taking care of a proper return including the correct setting of ***I*** and the *stack*. Typically, ***way*** = `xOUT_NORMAL` . Generally, xOUT shall be the last command of an *XROM routine*.
$\bar{x}$	g STAT $\bar{x}$	(−2) { } → {2} Calculates the *arithmetic means* of the y- and x-data accumulated and pushes them on the *stack*. See also s, s_m, and σ.
$\bar{x}_G$	g STAT g $\bar{x}_G$	(−2) { } → {2} Calculates the *geometric means* of the y- and x-data accumulated and and pushes them on the *stack*. See pp. 205ff for the formula. Output format will be similar to the one of $\bar{x}$. See also ε , ε_m , and ε_P .
$\bar{x}_w$	g STAT f $\bar{x}_w$	(−1) { } → {2} Returns the *arithmetic mean* for weighted data (where the weight y of each data point x was entered via Σ+). See pp. 205ff for the formula. See also s_w and s_{mw}.
$\hat{x}$	g STAT ▲ $\hat{x}$	(1) {2, 11}; {1} → {2} Returns a forecast ***x*** for a given ***y*** (in $\mathbf{X}$) according to the curve fit model chosen. See L.R. for more.
X.FN	g X.FN	*Menu*. See p. 124.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
x!	g x!	(1) {1, 10} Returns the *factorial* $n!$.
		(1) {2, 3, 11, 12} Returns $\Gamma(x + 1)$.
x:	g U→ x:	*Submenu*. See p. 134.
x→DATE	g CLK x→DATE	(1) {2} → {6} Interprets the real number x as a date coded in the date format selected (Y.MD, D.MY, or M.DY) and converts it to a proper *date*.
x→α	g α.FN x→α	(1) {1, 2, 10, 11} → {7} Interprets x as a character code and converts the integer part of x to the respective character x, similar to XTOA in the *HP-42S*.
x⇄	f x⇄ r	Swaps x and r, analogous to $x \leftrightarrows y$. Will be listed like x⇄ J, x⇄ .12, x⇄ →12, etc.
	g STK x⇄ r	
x⇄y	x⇄y	Swaps the *stack* contents x and y.
x = ?	g TEST x= ? r	(0) Compare x with r. See x< ? for more.
x ≠ ?	g TEST x≠ ? r	
x = +0?	g TEST ▲ x=+0? etc.	(0) {1, 2, 3, 10, 11, 12} These tests are for comparing finite integers in modes 1COMPL and SIGNMT, and for infinite integers, real or complex numbers if *flag* **D** is set. Then e.g. 0 / (−7) will display −0.
x = −0?		
x ≈ ?	g TEST ▲ x≈ ? r	(0) {2, 3, 4, 5, 8*, 9*, 11, 12} Will be true if the rounded values of x and r are equal (see ROUND). See x< ? for more.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
x < ? x ≤ ? x ≥ ? x > ?	g TEST x< ? *r* etc.	(0) {1, 2, 4, 5, 6, 10, 11} Compare ***x*** with ***r***. **Example:** TEST x< ? K compares ***x*** with ***k***, and will be listed as x<? K in a routine. It will return true if ***x*** < ***k*** at execution time. See examples in *Sect. 1* of the *OM* for more.
$\sqrt[x]{y}$	g EXP $\sqrt[x]{y}$	(2) {1, 2, 3, 10, 11, 12}; ({1} → {2}) Returns the x^{th} root of ***y***. Roots of negative integer or real numbers may return complex numbers if CPXRES is set.
yd.→m	g U→ x: g yd.→m	(1) {2, 11}; {1} → {2} Converts distances. See pp. 134ff.
YEAR	g CLK f YEAR	(1) {2, 6, 11} → {1} Assumes ***x*** containing a *date* in the format selected (or a real number in corresponding format) and extracts the year.
year→s	g U→ f year→s	(1) {2, 11}; {1} → {2} Converts times. See pp. 134ff.
y^x	y^x	(2) {1, 2, 3, 10, 11, 12} Returns the x^{th} power of ***y***. It allows for raising any positive real number to an arbitrary real power, as well as any negative real number to an arbitrary integer power, all returning real results. Exceeding these boundaries may produce complex results (and errors unless CPXRES is set).
$\hat{y}$	g STAT ▲ $\hat{y}$	(1) {2, 11}; {1} → {2} Returns a forecast ***y*** (in **X**) for a given ***x*** according to the curve fit model chosen. See L.R. for more.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
Y.MD	g CLK ▲ Y.MD	(0) Sets the format yyyy-mm-dd for *date* display.
y⇄	g STK y⇄ r	Swaps ***y*** and ***r***, in analogy to x⇆.
Z_0	g CNST Z_0	(−1) { } → {2} Characteristic impedance of vacuum in *ohm*.
z⇄	g STK z⇄ r	Swaps ***z*** and ***r***, in analogy to x⇆.
α	g CNST α	(−1) { } → {2} Fine-structure constant.
αINTL	f CATALOG CHARS αINTL	*Submenu*. See pp. 112ff.
	g +	*Menu* in *AIM* (see p. 124).
αLENG?	g INFO g αLENG? r	(−1) { } → {1} Returns the number of characters found in ***r***, similar to ALENG in *HP-42S*. This command will throw an error if there is no string in ***r*** at execution time.
	g α.FN f αLENG? r	
αMATH	f CATALOG CHARS αMATH	*Submenu*. See pp. 112ff.
	g −	*Menu* in *AIM*. See p. 125.
αOFF αON	g P.FN f αOFF etc.	(0) Turn *AIM* off and on, like AOFF and AON in *HP-42S*.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
αPOS?	g INFO g αPOS? *r*	(−1) {7} → {1} Looks in ***r*** for the ***target*** given in **X**. If a match is found, αPOS returns the position number where the ***target*** was found (counting the left-most character as position 0). If a match is not found, αPOS returns –1. The ***target*** may be an individual character code or an *alpha string*. αPOS saves a copy of the target in **L**. It works similar to POSA in *HP-42S*. This command will throw an error if there is no string in ***r*** at execution time.
	g α.FN αPOS? *r*	
αRL	g α.FN αRL *r*	(1) {7} Rotates ***r*** by ***x*** characters like AROT in *HP-42S*, but with ***x*** ≥ *0* . αRL **0** executes as NOP, but loads **L**. This command will throw an error if there is no closed string in **X** at execution time.
αRR	g α.FN αRR *r*	(1) {7} Works like αRL but rotates to the right.
αSL	g α.FN αSL *r*	(1) {7} Shifts the ***x*** leftmost characters out of ***r***, like ASHF in *HP-42S*. αSL **0** equals NOP, but loads **L**. This command will throw an error if there is no closed string in **X** at execution time.
α.FN	g α.FN	*Menu*. See p. 125.
A...Ω	f CATALOG CHARS A...Ω	*Submenu*. See pp. 112ff.
α●	f CATALOG CHARS α·	*Submenu*. See pp. 112ff.
	g .	*Menu* in *AIM*. See p. 125.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
α→x	g α.FN α→x *r*	(−1) { } → {1} Pushes the character code of the leftmost character in ***r*** on the *stack* and removes this character from the string, similar to ATOX in *HP-42S*. This command will throw an error if there is no closed string in ***r*** at execution time.
β(x,y)	g X.FN ▲ β(x,y)	(2) {2, 3, 11, 12}; {1} → {2} Returns *Euler's Beta* $B(x,y)=\frac{\Gamma(x)\,\Gamma(y)}{\Gamma(x+y)}$ with $Re(x)>0$ and $Re(y)>0$. Called β here to avoid ambiguity. See $\Gamma(x)$ below.
γ	g CNST γ	(−1) { } → {2} *Newtonian* constant of gravitation (also called G by other authors) in $m^3/_{kg\,s^2}$; *Euler-Mascheroni* constant (for mathematics); proton gyromagnetic ratio (see p. 132).
γEM	g CNST γEM	
γp	g CNST γp	
γxy Γxy	g X.FN ▲ f γxy etc.	(2) {2, 11}; {1} → {2} Return the lower or upper incomplete gamma function, respectively. See pp. 223ff for details.
Γ(x)	f PROB ▲ Γ(x)	(1) {2, 3, 11, 12}; {1} → {2} Returns $\Gamma(x)$. Note x! calls $\Gamma(x+1)$. See also LNΓ.
δx	f CATALOG PROGS δx	Predefined global label for f'(x) and f"(x) – see *Section 4* of the *OM*.
Δ%	f Δ%	(1) {2, 11}; {1} → {2} Returns $100\cdot\frac{x-y}{y}$ leaving y unchanged, like %CH in *HP-42S*. Use it also for calculating mark-ups or margins as explained in the *OM*, *Sect. 2*.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
ε	g STAT g ε	(−2) { } → {2} Calculates the *scattering factors* ε_y and ε_x for *log-normally* distributed sample data and pushes them on the *stack*. This ε_x works for the *geometric mean* $\bar{x}_g$ in analogy to the *standard deviation* s for the *arithmetic mean* $\bar{x}$ but multiplicative instead of additive. See pp. 196ff for more information.
ε_0	g CNST ε_0	(−1) { } → {2} Electric constant or vacuum permittivity in *ampere-second per volt-meter*.
ε_m	g STAT g ε_m	(−2) { } → {2} Works like ε on previous page but returns the *scattering factors* of the two *geometric means* (in analogy to the standard error for *arithmetic means*).
ε_p	g STAT g ε_p	(−2) { } → {2} Works like ε but returns the *scattering factors* of the two populations.
ζ(x)	g X.FN ▲ f ζ(x)	(1) {2, 3} Returns *Riemann's Zeta*. See p. 226 for more.
λ_C λ_{Cn} λ_{Cp}	g CNST λ_C etc.	(−1) { } → {2} *Compton* wavelength of the electron, neutron, and proton in *meter*.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
μ_0 μ_B μ_e μ_e/μ_B μ_n μ_p μ_u μ_μ	g CNST μ_0 etc.	(−1) { } → {2} Magnetic constant or vacuum permeability in *volt-second per ampere-meter*; Bohr magneton in *joule per tesla*; electron magnetic moment in *joule per tesla*; ratio of electron magnetic moment to *Bohr* magneton; neutron and proton magnetic moments, nuclear magneton, and Muon magnetic moment in *joule per tesla*.
Π	f ADV Π ***labl***	Computes a product using the routine specified. See *Section 4* of the *OM* for more. **ATTENTION:** Π fills all *stack registers* with x before calling the routine specified.
π	g π	(−1) { } → {2} Recalls π.
Σ	f ADV Σ ***labl***	Computes a sum using the routine specified. See *Section 4* of the *OM* for more. **ATTENTION:** Σ fills all *stack registers* with x before calling the routine specified.
σ	g STAT σ	(−2) { } → {2} Works like s but returns the *standard deviations* of the two *populations* instead. See pp. 196ff for the formula.
σ_B	g CNST σ_B	(−1) { } → {2} *Stefan-Boltzmann* constant (see p. 134).

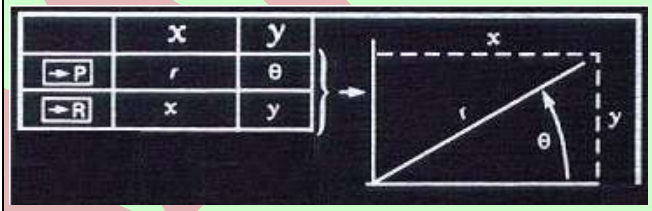
Item	Keystrokes	Remarks (see pp. 12ff for general information)
$\Sigma\ln^2 x$	g STAT ▼ f $\Sigma\ln^2 x$ etc.	(−1) { } → {2} Recall the corresponding statistical sums, necessary for curve fit models beyond pure linear. Calling the sums by name significantly improves program readability. Note they are stored in dedicated *registers* of your *WP 43S* (see *App. B* on pp. 152ff.). **ATTENTION:** Depending on input data, some of the logarithmic sums may become non-numeric. If this happens no error will be thrown, however, regardless of *flag* **D**.
$\Sigma\ln^2 y$		
$\Sigma\ln x$		
$\Sigma\ln xy$		
$\Sigma\ln y$		
σ_w	g STAT f σ_w	(−1) { } → {2} Works like s_w but returns the *standard deviation* of the *population* instead. See pp. 196ff. for the formula.
Σx	g STAT ▼ Σx etc.	(−1) { } → {2} Recall the corresponding statistical sums, necessary for basic statistics and fits (see above).
Σx^2		
$\Sigma x^2 y$	g STAT ▼ g $\Sigma x^2 y$ etc.	
$\Sigma x\ln y$		
Σxy	g STAT ▼ Σxy etc.	
Σy		
Σy^2		
$\Sigma y\ln x$	g STAT ▼ g $\Sigma y\ln x$	

Item	Keystrokes	Remarks (see pp. 12ff for general information)
Σ+	g STAT Σ+	{8} → {2} If **X** contains an ***n*** × 2 matrix then Σ+ adds ***n*** 2D data points to the statistical sums. The *temporary information* mentioned in the footnote will show the last data point added.[23]
		{1, 2, 11} Adds one 2D data point to the statistical sums.[23]
Σ–	g STAT f Σ-	{1, 2, 11} Subtracts one 2D data point from the statistical sums.[23]
Φ	g CNST Φ	(−1) { } → {2} Golden ratio and magnetic flux quantum, the latter in *volt-second*.
Φ_0	g CNST Φ_0	
$\Phi_u(x)$	f PROB Φ: $\Phi_u(x)$	(1) {2, 11} *Standard normal* (a.k.a. *Gaussian*) *error probability* with $\mu = 0$ and $\sigma = 1$ (equal to Q in *HP-32E* and Q(z) in *HP-21S*), *CDF, PDF, and quantile function*. See pp. 196ff for the formulas. Take NORML for arbitrary means and standard deviations.
Φ(x)	… Φ(x)	
φ(x)	… φ(x)	
$\Phi^{-1}(p)$	… $\Phi^{-1}(p)$	
Φ:	f PROB Φ:	*Submenu*. See p. 121.

[23] Σ+ and Σ– return *temporary information* as shown in *Sect. 2* of the *OM* and disable *automatic stack lift*. Both may also be used for 2D vector adding and subtracting (see SUM).

Item	Keystrokes	Remarks (see pp. 12ff for general information)
$\chi^2(x)$ $\chi^2_p(x)$ $\chi^2_u(x)$ $(\chi^2)^{-1}$	f PROB χ^2: $\chi^2(x)$ etc.	(1) {2, 11} *Chi-square distribution* (with its degrees of freedom given in I). $\chi^2_u(x)$ equals $Q(\chi^2)$ on *HP-21S*. See *Section 2* of the *OM* for an application example and pp. 196ff for more.
χ^2:	f PROB χ^2:	*Submenu*. See p. 121.
ω	g CNST ω	(−1) { } → {2} Angular velocity of the Earth in *radian per second* according to *WGS84* (see footnote 20 on p. 72).
$(-1)^x$	g X.FN ▲ f $(-1)^x$	(1) {1, 2, 3, 8*, 9*, 10, 11, 12} If x is non-integer, returns $cos(\pi x)$.
+	+	(2) Returns $y + x$ for compatible objects. See the tables in the *OM*, *Sect. 2,* for details.
+/−	+/− (for closed input)	(1) 'Unary minus', returns $x \times (-1)$. See the tables in the *OM*, *Sect. 2,* for details.
−	−	(2) Returns $y - x$ for compatible numeric objects. See the tables in *Section 2* of the *OM* for details.
-∞	g CNST - ∞	(−1) { } → {2} Minus infinity. May the Lord of Mathematics forgive us calling this a constant, but it is counted as numeric value in your *WP 43S*.
×	×	(2) Returns $y \times x$ for compatible numeric objects. See the tables in *Section 2* of the *OM* for details.
×MOD	g INTS f ×MOD	(3) {1, 2, 10, 11} Returns $(z \times y) \bmod x$ for $x > 1$, $y > 0$, $z > 0$.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
/	/	(2) Returns $y \times x^{-1}$ for compatible numeric objects. See the tables in the *OM, Sect. 2,* for details. Returns $y \operatorname{div} x$ if both y and x are of *data type* 1 or 10. Cf. IDIV.
±∞?	g INFO g ±∞?	(0) {2, 11} → {1} Tests x for infinity. Returns true 1 for $x = +\infty$, true -1 for $x = -\infty$, and false 0 else.
→		Reserved symbol for indirect addressing.
→DATE	g CLK →DATE	(3) {1, 2} → {6} Assumes the three components of a date (year, month, and day) supplied on the *stack* in proper order for the date format selected and converts them to a single *date* in x. Thus inverts DATE→.
→DEG	f L→ ∢→∢°	(1) {1, 2, 4, 11} → {4} Converts angles as described on pp. 140f.
→DP	g X.FN ▲ f →DP	(1) {1, 2, 11} → {11}; {3, 12} → {12} Converts x into a *DP* number. Numbers shown as fractions will be displayed as decimal numbers (cf. IMPFRC and PROFRC). Compare →SP.
→D.MS	f L→ ∢→∢"	(1) {1, 2, 4, 11} → {4} Convert angles as described on pp. 140f.
→GRAD	f L→ ∢→∢ᵍ	
→HR	f CATALOG FCNS →HR	(1) {5} → {2} Operates on times like →REAL below. →HR is featured for backward compatibility only..

Item	Keystrokes	Remarks (see pp. 12ff for general information)
→H.MS	f h.ms (for closed input)	(1) {1, 2, 5, 11} → {5} Converts ***x*** to a sexagesimal *time* – cf. p. 108.
→INT	f # ***base*** (for closed input)	(1) {1, 2, 10, 11} → {10} Converts the integer part of ***x*** to a finite integer of the base specified – cf. p. 108.
→MULπ	f L→ ∠→∠π	(1) {1, 2, 4, 11} → {4} Converts angles as described on pp. 140f.
→POL	g →P	{2, 11}; {1} → {2} Assumes **X** and **Y** containing 2D *Cartesian* coordinates of a point or components of a vector (***x , y***). Converts them to the respective polar coordinates or components (***r, ϑ***). See the picture and cf. →REC.  For switching the format of complex numbers, choose POLAR.
→RAD	f L→ ∠→∠r	(1) {1, 2, 4, 11} → {4} Converts angles as described on pp. 140f
→REAL	f .d (for closed input)	(1) {1, 2, 4, 5, 6, 10, 11} → {2} Converts ***x*** to a real number of *single precision*. For {6}, the date format chosen is taken into account. Numbers shown as fractions will be displayed as decimal numbers (cf. IMPFRC and PROFRC). For returning the real part of a complex number, choose RE. For cutting a complex number into its parts, use CC.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
→REC	f R←	{2, 11}; {1, 4} → {2} Assumes **X** and **Y** containing 2D polar coordinates of a point or components of a vector (***r***, ***ϑ***). Converts them to the respective Cartesian coordinates or components (***x***, ***y***). See →POL. For switching the format of complex numbers, choose RECT.
→SP	g X.FN ▲ f →SP	(1) {1, 2, 11} → {2}; {3, 12} → {3} Converts ***x*** into a *single precision* number. Numbers shown as fractions will be displayed as decimal numbers (cf. IMPFRC and PROFRC). Compare →DP.
↑Lim ↓Lim	f ADV fdx ↑Lim etc.	Reserved real variables for the upper and lower limit of integration (see *Section 4* of the *OM*).
⥮	g STK ⥮____	Shuffles the contents of the bottom four *stack registers* at execution time. **Examples:** ⥮xxyz works like ENTER↑ (but does not disable *automatic stack lift!*), ⥮yxzt works like x⇆y, ⥮yztx works like R↓ in a 4-level *stack*, ⥮txyz works like R↑ in a 4-level *stack*, but also ⥮zzzx is possible. **ATTENTION:** This is a very powerful command although it does not look it. Note it will only affect the lowest four *stack registers* regardless of *stack* size. There is no connection to *register* **A** and above. If you play with this command, you may lose some *stack* contents and easily make a mess of the *stack*.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
%	f %	(1) {2, 11}; {1} → {2} Returns $\frac{xy}{100}$, leaving y unchanged.
%MRR	g FIN %MRR	(3) {2, 11}; {1} → {2} Returns the mean rate of return in percent per period, i.e. $100 \cdot \left(\sqrt[z]{x/y} - 1\right)$ with x = FV = future value after z periods, y = PV = present value. For z = 1, Δ% returns the same result easier.
%T	g FIN %T	(2) {2, 11}; {1} → {2} Returns $\frac{100\,x}{y}$, interpreted as % of total.
%Σ	g FIN %Σ	(1) {2, 11}; {1} → {2} Returns $\frac{100\,x}{\sum x}$.
%+MG	g FIN %+MG	(2) {2, 11}; {1} → {2} Calculates a sales price by adding a margin of x % to the cost y, as %MU-Price in *HP-17B*. Formula: $p_{sale} = \frac{y}{1 - \frac{x}{100}}$ You may use %+MG for calculating net amounts as well; just enter a negative percentage in x.
√x	√x	(1) {1, 2, 3, 8*, 9*, 10, 11, 12}; ({1} → {2}) Returns the square root of x. Square roots of negative integer or real numbers will return complex numbers if CPXRES is set.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
∫	f ADV ∫fdx ∫ ***var*** (listed in programs as ∫fd trailed by the integration variable)	{2} Integrates the function given in the routine specified by PGMINT over the variable specified. Lower and upper integration limits must be supplied by the corresponding variables ↓Lim and ↑Lim, accuracy by ACC. ∫ returns the (approximated) integral in **X** and an upper limit of its uncertainty in **Y**. **ATTENTION:** ∫ fills all *stack registers* with ***x*** before calling the routine specified. See *Section 4* of the *OM* for more.
	g EQN ∫f ∫	Integrates the current equation. Not programmable.
∫f	g EQN ∫f	*Submenus*. See pp. 118f.
∫fdx	f ADV ∫fdx	
∞	g CNST ∞	(−1) { } → {2} Infinity. May the Lord of Mathematics forgive us calling this a constant, but it is counted as numeric value in your *WP 43S*.
^MOD	g INTS g ^MOD	(3) {1, 2, 10, 11} Returns $(z^y) \bmod x$ for $x > 1$, $y > 0$, $z > 0$.
|M|	f MATX |M|	(1) {8} → {2}; {9} → {3} Requires a square matrix in **X** and returns its determinant. The matrix itself is stored in **L** unmodified.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
|x|	f PARTS |x|	(1) {1, 2, 4, 10, 11} Returns the absolute (unsigned) value of x.
	or g CPX |x|	(1) {3} → {2}; {12} → {11} Returns the magnitude $\sqrt{\mathrm{Re}(x)^2+\mathrm{Im}(x)^2}$ in X.
		(1) {8*, 9*} → {8} Returns a real matrix with the absolute (unsigned) value of each input matrix element. Complex matrix elements will become real this way. Cf. ENORM.
| |	g X.FN ▲ g ||	(2) {2, 3, 11, 12}; {1} → {2} Returns $\left(\frac{1}{x}+\frac{1}{y}\right)^{-1}$, being useful in electrical engineering especially. Returns 0. for x or y being zero.
[M]^T	f MATX [M]^T	(1) {8, 9} Returns the transpose of the matrix x (like TRANS in *HP-42S*). The transpose is another matrix with rows changed by columns. If A is an $n \times m$ matrix and a_{ij} is an element of it then A^T will be an $m \times n$ matrix B with $b_{ij} = a_{ji}$. The transpose is done in-situ and does not require any additional memory.
[M]$^{-1}$	f MATX [M]$^{-1}$	(0) {8, 9} Takes the square matrix in X and inverts it in-situ (like INVRT on *HP-42S*).
∡	g CPX f ∡	(1) {3} → {2}; {9*} → {8}; {12} → {11} Returns $arctan\left(\frac{Im(x)}{Re(x)}\right)$ for $x \geq 1$, else $arctan\left(\frac{Im(x)}{Re(x)}\right) + \pi\, sign(Im(x))$. Cf. SIGN and |x|.
∡→	f L→	*Menu*. See p. 126.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
🖶ADV	g I/O ▲ 🖶ADV	(0) Prints the current contents of the print buffer and a linefeed. **ATTENTION:** The printer will actually print only when a linefeed is sent to it.
🖶CHAR	g I/O ▲ 🖶CHAR ***n***	(0) Sends a single character (with the code specified) to the printer. Character codes ***n*** > 127 can only be specified indirectly. 🖶MODE setting will be honored. See 🖶ADV.
🖶DLAY	g I/O ▲ 🖶DLAY ***n***	(0) Sets a delay of ***n*** ticks (see TICKS) to be used with each linefeed on the printer.
🖶LCD	g I/O ▲ 🖶LCD	(0) Sends the contents of the entire *LCD* to the printer.
🖶MODE	g I/O ▲ 🖶MODE ***n***	(0) Sets print mode. Legal print modes are: 0: Use the printer font and character set wherever possible (default). All characters feature the same width (5 columns + 2 columns spacing). 1: Use the variable pitch display font, resulting in some jitter on the printout but packing more characters in a row. 2: Use the small display font, which allows for packing even more info in a row. 3: Send the output to the serial channel. Works for plain ASCII only – no characters will be translated. Line setup is the same as for serial communication: 9600 baud, 8 bits, no parity.
🖶PROG	g I/O ▲ 🖶PROG	(0) Prints the listing of the *current program* (see *Sect. 3* of the *OM*), 1 row per step. See 🖶ADV.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
🖶r	g I/O ▲ f 🖶r *r* f 🖶x	(0) Prints the *register* specified, right adjusted, without labeling the output. Note 🖶r **X** is on the keyboard. If you want a heading label, compose the string in **X** first or use 🖶REGS. See 🖶ADV.
🖶REGS	g I/O ▲ f 🖶REGS	(1) Interprets ***x*** in the form `sss.nn`. Prints the contents of ***nn*** *registers* starting with number ***sss***. Each *register* takes one row starting with a label. See also 🖶ADV. **ATTENTION for *nn* = 0 :** • For $sss \in [0;99]$, printing will stop at **R99**. • For $sss \in [100;111]$, printing stops at **K**. • For $ss \geq 112$, printing will stop at the highest allocated local *register*.
🖶STK	g I/O ▲ f 🖶STK	(0) Prints the *stack* contents. Each *register* prints in a separate row starting with a label indicating said *register*. See 🖶ADV.
🖶TAB	g I/O ▲ f 🖶TAB *n*	(0) Positions the print head to print column ***n*** (0 to 165, where ***n*** > 127 can only be specified indirectly). Useful in formatting (in 🖶MODE 1 or 2 in particular). Allows also for printer plots. If ***n*** is less than current print head position, a linefeed will be entered to reach the new position. See 🖶ADV.
🖶USER	g I/O ▲ f 🖶USER	(0) Prints all variable names and global program labels. The variable names are printed first, so if you are not interested in the program labels, press R/S to stop the listing.

Item	Keystrokes	Remarks (see pp. 12ff for general information)
🖶WIDTH	g I/O ▲ f 🖶WIDTH	(−1) Returns the number of print columns that ***x*** would take in the print mode set. See 🖶ADV and 🖶MODE. Second use: in 🖶MODE 1 or 2, 🖶WIDTH returns the width of ***x*** in pixels (including the last column being always blank) in the specified font.
🖶Σ	g I/O ▲ g 🖶Σ	(0) Prints the summation *registers*. Each *register* prints in one row starting with its label. See 🖶ADV.
🖶#	g I/O ▲ g 🖶# ***n***	(0) Sends a single *byte*, without translation, to the printer (e.g. a control code). ***n*** > 127 can only be specified indirectly. 🖶MODE setting will not be honored. See 🖶ADV.
#B	f BITS g #B	(1) {10} Counts the bits set in ***x*** (like on *HP-16C*).

Nonprogrammable Commands and Keys

The commands ASSIGN, CLALL, CLP, CLPALL, CLREGS, FBR, GTO., LOAD, LOADP, PSTO, RBR, RESET, SAVE, STATUS, TIMER, and TVM cannot be programmed. The same applies to the operations of the *Matrix Editor* and *Equation Editor*, as well as answers to questions your *WP 43S* asks.

Furthermore, all *catalog* and *menu* calls themselves as well as the operations called by EXIT, P/R, UM, α, ↩, ≡Δ, ▲, ≡∇, and ▼ are neither programmable nor will they show any input echo in the top numeric row as the other commands do (cf. the *OM*, *Sect. 2*). See also *Section 2: Menus and Catalogs* (on pp. 112ff) for more about this topic.

The *browsers* RBR and STATUS as well as the *application* TIMER use some keys for particular control purposes (e.g. STO, RCL, ., and numeric keys – see the *OM, Section 5*).

Command Parameter Input and Closing It

The following table shows what will happen when particular keys are pressed while command parameter input is not finished yet (see p. 108ff for input in **X** instead) Note that characters include also digits and punctuation marks. The table lists the respective keys beginning top left on the keyboard:

Keystrokes	Situation	Remarks
A … Z	addressing	*Register* or *flag* input. See the *virtual keyboard* in *Section 1* of the *OM* for the letters applicable.
A … Z	entering a label or a variable name	Appends the corresponding Latin or Greek letter to the label or variable name pending. Use ▼ and ▲ to switch cases. See the picture overleaf (and cf. *Section 2* of the *OM*).
g A … g O		
ENTER↑	arbitrary parameter input pending	If there is no input yet, assumes the default, if applicable. Closes pending input, interprets it as a *register* or *flag* address or a variable name or a label, and executes the command. Cf. *Section 1* of the *OM*.
←	arbitrary parameter input pending	Deletes the rightmost character keyed in. If there is nothing left, cancels the pending command, returning to the status of your *WP 43S* as it was before that input was started.
0 … 9	addressing	*Register* or *flag* input. See *Section 1* of the *OM* for the valid number ranges.
.	addressing	Header for *local registers* or *flags*.
EXIT	arbitrary input pending	If there is an open *menu*, closes it. Else cancels pending command input, returning to the status of your *WP 43S* as it was before that command was called.


Α α
Β β
Γ γ
Δ δ
Ε ε
Φ φ
A
B
C
D
E
F
ASN
Γ γ
Χ χ
Ι ι
α.FN
G
H
I
UM
f
g
CATALOG
Η η
Κ κ
Λ λ
CLR
ENTER
J
K
L
Μ μ
Ν ν
Ω ω
Π π
M
7
N
8
O
9
P
Q
Ρ ρ
Σ σ
Τ τ
Θ ϑ
MODE
R
4
S
5
T
6
U
αMATH
Ψ ψ
Ξ ξ
Υ υ
FLAGS
V
1
W
2
X
3
Y
αINTL
Ζ ζ
α•
?
0
Z
•
,
EXIT
ON
OFF

Alphanumeric Input in X and Closing It

The following table shows what will happen when particular keys are pressed <u>while alphanumeric input in X is open still</u> (see p. 106 for command parameter input instead). Alphanumeric input includes pure numeric as well. The table lists the respective keystrokes top left to bottom right on the keyboard:

Keystrokes	in mode(s)	Remarks
f # ***base***	¬ (A, α)	Closes input of a *finite integer* in x.[24]
g INTS A ... F	¬ (A, α)	Numeric input for bases >10, appending the corresponding digit to x. See *Section 2* of the *OM* for more. Digits will be checked when input is closed (see the description of ENTER↑ overleaf).
f h.ms	¬ (A, α)	Closes input of a sexagesimal *time* in x.[24]
f d.ms	¬ (A, α)	Closes input of a sexagesimal angle in x.[24]
f .d	¬ (A, α)	Closes input of a *date* in x.[24]
A ... Z g A ... g O	A, α	Appends the corresponding Latin or Greek letter to the *alpha string* x. Use ▼ and ▲ to switch cases. See the picture on previous page and cf. *Section 2* of the *OM*.
f CC or g CPX CC	¬ (A, α)	Closes input of the first part of a complex number and waits for input of its second part (see the *Key Response Table* and *Section 2* of the *OM*).

[24] See *Section 2* of the *OM*. At closure, input will be checked – illegal digits (e.g. 8 in octal input or C in decimal) or bases or numbers (e.g. 72 *minutes* in a *time*) or characters found or out-of-range conditions detected will cause an error thrown (see also the description of ENTER↑ on next page and the error messages in *App. C*).

Keystrokes	in mode(s)	Remarks
ENTER↑	arbitrary input pending	If there was no input before, sets input to zero. Else closes input (in **X**) and checks the following conditions top-down: • If this input is alphanumeric (i.e. if it contains at least one non-numeric character except .), takes it as an *alpha string*. • Else (i.e. if this input is purely numeric) if it contains one CC, takes it as a *complex number*. • Else if it contains two ., takes it as a *fraction*. • Else if it contains one . or one E, takes it as a *real number*. • Else (i.e. if it contains neither a CC nor a . nor an E), tests it for #: ○ If it contains one # and a valid base trailing it then takes it as a *finite integer*; ○ else looks up if previous entry was a *finite integer*: if true then takes the new input as another *finite integer* of the same base; else takes the new input as an *infinite integer*. Then checks the new input (according to the condition met) as outlined in footnote 24 and interprets it. Finally, unless an error had to be thrown, copies ***x*** into **Y**.
f x≷	A, α	Appends x≷ to the *alpha string* ***x***.
+/−	¬ (A, α)	Changes the sign of the mantissa or exponent in numeric input as explained in *Section 1* of the *OM*.
E	¬ (A, α)	Closes input of the mantissa and waits for input of the exponent (see *Section 1* of the *OM*).
←	arbitrary input pending	Deletes the last (rightmost) character keyed in. If there is nothing left, cancels the pending input, returning to the status of your *WP 43S* as it was before that input was started.

Keystrokes	in mode(s)	Remarks
f /	A, α	Appends / to the *alpha string* ***x***.
f ×	A, α	Appends × to the *alpha string* ***x***.
0 … 9	¬ (A, α)	Standard numeric input, appending the corresponding digit to ***x***. Note you can enter … • up to 16 digits plus a sign in the mantissa and up to three digits plus a sign in the exponent for a real number or any part of a complex number, • up to 20 digits plus a sign for an *infinite integer*, • up to 64 bits for a *finite integer*, or • up to 16 digits for the nominator and up to 4 digits for the denominator of a fraction.
f 0, …, f 9	A, α	Appends the respective digit to the *alpha string* ***x***.
▲	A, α	Turns to upper (or lower) case for the following letter(s).
▼		
f −	A, α	Appends - to the *alpha string* ***x***.
f +	A, α	Appends + to the *alpha string* ***x***.
?	A, α	Appends ? to the *alpha string* ***x***.
.	¬ (A, α)	Inserts a radix mark as selected.
		Separates *degrees* from *minutes*, *seconds*, and *hundredths of seconds* in angular input, so input format is `dddd.mmsshh` d.ms for sexagesimal angles.
		Separates *hours* from *minutes*, *seconds*, and fractions of *seconds* in *time* input, so input format is `hhhh.mmssfffff` h.ms for sexagesimal *times*.

Keystrokes	in mode(s)	Remarks
Second [.]	¬ (A, α)	A second [.] in input indicates a fraction. See *Section 2* of the *OM* for examples. The second [.] just separates the nominator and the denominator in input. Note you cannot enter [E] after you entered [.] twice – but you may delete the second dot while editing the input row.
[,]	A, α	Appends , to the *alpha string* x.
[f][.]	A, α	Appends . to the *alpha string* x.
[R/S]	program waiting for arbitrary input	Closes input and starts its checks and interpretation like [ENTER↑] above.
	A, α	Appends a blank space to the *alpha string* x.
[f][R/S]	A, α	Enters the printer character 🖶, e.g. for fast access to the print functions (see p. 116).
[EXIT]	arbitrary input pending	If there is an open *menu*, closes it. Else closes pending alphanumeric input and releases it for interpretation.

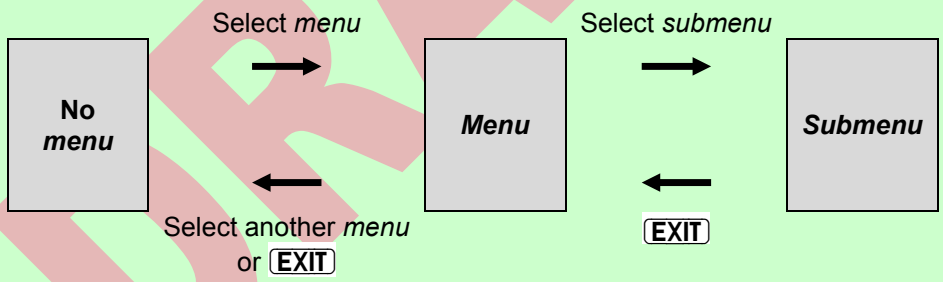
There are many more characters you can enter via the three alpha *menus* or [CATALOG] CHARS. See pp. 113 and 124ff for these menus and pp. 165ff for the entire character sets provided.

SECTION 2: MENUS AND CATALOGS

Due to the large set of operations your *WP 43S* features, most of them are stored in *menus* as they were discussed in the *OM*, *Section 1*. Besides operations, numeric constants, or characters (as in the alpha *menus*), there may be also other *items* contained in *menus* (e.g. *submenus*, digits).

Catalogs are a special kind of *menus* with their contents sorted alphabetically. Your *WP 43S* provides two *catalogs*, CATALOG and CNST. Also some *submenus* of CATALOG are treated as *catalogs* (i.e. A...Z, DIGITS, FCNS, MENUS, αINTL, A...Ω, and the *submenus* of VARS, see next chapter). Within *catalogs*, some special operations ease your path accessing the *items* stored there (as shown on pp. 116f).

You may switch *menus* (except *catalogs*) easily by just calling another *menu* accessible in current mode directly from the *menu* you are using – no need to EXIT first:



One to Rule Them All – the CATALOG

CATALOG calls a very particular *menu*: CATALOG contains all the *items* defined on your *WP 43S* and visible for the user. Many of them are sorted alphabetically in different branches; these *items* we call *cataloged*. *Cataloged items* may be accessed quickly in a way demonstrated on pp. 116f.

Note the contents of the various branches of CATALOG are presented below in reverse order compared to the display of your *WP 43S*, taking care of your top-down reading habits:

	^	^	^	^	^	^	Remarks
CATALOG:	FCNS	DIGITS	CHARS	PROGS	VARS	MENUS	top branches
FCNS:	°C→°F	°F→°C	10^x	1COMPL	1/x	2^x	functions provided
	2COMPL	$\sqrt[3]{x}$	ABS	ac→ha	ac_{US}→ha	AGM	
	ALL	AND	arccos	arcosh	arcsin	arctan	
	...						
	...	#B					
DIGITS:	0	1	2	3	4	5	digits defined
	6	7	8	9	A	B	
	C	D	E	F	i		
CHARS:	A...Z	A...Ω	αINTL	αMATH	Myα	α·	character branches
A…Z:	A	B	C	D	…		plain Latin letters
A…Ω:	A	B	Γ	Δ	…		Greek letters, see p. 125
αINTL:	Ā	...					additional (international) Latin letters, see p. 124
αMATH:	<	...					mathematical operators and symbols, see p. 125
α●:	!	...					punctuation marks, see p. 126
PROGS:	RAM					FLASH	programs (actually global labels) currently defined, sorted alphabetically in two branches
RAM:	...						
FLASH:	...						

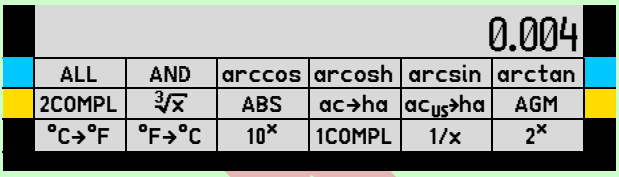
	^	^	^	^	^	^	Remarks
VARS:	IINTS	FINTS	REALS	CPXS	STRING	MATRS	branches for various types of variables
	DATES	TIMES	ANGLES				
ANGLES:	...						variables currently defined of various *data types*
CPXS:	...						
DATES:	...						
FINTS:	...						
IINTS:	...						
MATRS:	...						
REALS:	...						
STRING:	...						
TIMES:	...						
MENUS:	ANGLES	A...Z	A:	Binom:	BITS	Cauch:	*(sub-) menus* currently defined. See above and below for their contents.
	CHARS	CLK	CLR	CNST	CPX	CPXS	
	DATES	DIGITS	DISP	EQN	EXP	Expon:	
	...						
	...	4→					
A:	...						*(sub-) menus* provided unless mentioned above already, see pp. 118ff
Binom:	...						
BITS:	...						
...							
...							

Three branches of CATALOG are fixed size (FCNS, DIGITS, and CHARS) since all valid functions, digits, and characters are predefined; the other three are expandable (MENUS and the *submenus* of PROGS and VARS) since you may create *items* of these kinds (cf. *Section 6* of the *OM*).

Calling CATALOG will display its top level branches (one row of labels, being pointers to the *submenus* containing all the functions, digits, characters, programs,

variables, and *menus* defined at execution time):

Choosing one of these branches will show its first *view* of *items* (primary, f- and g-shifted, if applicable). Pressing the leftmost softkey, for instance, will call the *submenu* FCNS showing up as pictured below:



Within CATALOG branches, browsing by ▲ will advance by only six *items* per keystroke (and ▼ will go back by six).[25] Select an *item* by pressing the corresponding top row key (headed by a *prefix* if applicable). E.g. call a function by pressing the corresponding softkey. EXIT will just leave CATALOG without doing anything.

All the functions available on your *WP 43S* are stored in CATALOG'FCNS. Most of them are also found (and easier to access) in other predefined *menus*. Each and every command featured on your *WP 43S*, the keystrokes calling it, and the necessary particular explanations are also listed for your reference in the *IOI* on pp. 12ff.

Remember all labels printed underlined on the keyboard point to *menus*. All *menus* available are found in CATALOG'MENUS; predefined *menu* names are listed in the *IOI* as well; their particular contents are printed in next chapter. Individual *items* may appear in more than one *menu* and also on the keyboard.

See *Section 6* of the *OM* to learn how to customize your *WP 43S* by creating and filling your own *menus* (assignable to your favorite keyboard locations) and accessing the functions you stored therein. You may as well assign your favorite individual functions to almost any location on the keyboard. Actually, you can design your very own *WP 43S* user interface.

[25] Navigating in 'CATALOG, *AIM* is set as explained in the *OM*. So you may as well use the alphabetic searching method known from *WP 34S catalogs*, but the matching *item* will be displayed together with its up to 17 successors if applicable. See next chapter.

Accessing Cataloged Items Rapidly

You can browse a *catalog* like any other *menu* just using ▲ and ▼ as explained in previous chapter. In CNST and major parts of CATALOG, however, you may reach your target significantly faster taking advantage of the alphabetical access method demonstrated here.

Assume we are looking for the function FS?S, for example:

1 User input

CNST or CATALOG FCNS, MENUS, PROGS RAM or FLASH, CHARS αINTL, and *submenus* of VARS

Echo

Your *WP 43S* shows the first view in (this part of) this *catalog*[26]

e.g. in CATALOG FCNS

ALL	AND	arccos	arcosh	arcsin	arctan
2COMPL	$\sqrt[3]{x}$	ABS	ac→ha	ac_{US}→ha	AGM
°C→°F	°F→°C	10^x	1COMPL	1/x	2^x

2 User input

First character of the *item* desired (e.g. F)

Echo

Your *WP 43S* shows a view starting with the first *item* starting with this character[27]

[26] … unless you visited the same *catalog* before – then it will open showing the last view you looked at. The remaining procedure will stay unchanged though.

[27] This search is case independent (i.e. specifying **A** will find **a** as well). Note, however, that **A** and **a** remain different letters nevertheless. Remember you can also enter Greek letters in such a search using prefix g, e.g. g + A for α – though watch the sorting order printed at the beginning of the *IOI*. And will bring you to the print functions immediately. Note the *items* in the *catalog* you search may be displayed at positions in the *menu section* deviating from the ones you see in simple browsing using just ▼ or ▲.

You may put in more than one character (see overleaf) – though after 3 *seconds* or after pressing ▼ or ▲, whatever comes first, the search string will be reset. Then you may continue browsing using ▼ or ▲ or start a new search by entering a new first character.

	e.g.

FP	FP?	$F_p(x)$	FS?	FS?C	FS?F
FF	FIB	FILL	FIX	FLASH?	FLOOR
FAST	FB	FC?	FC?C	FC?F	FC?S

3 User input	Second character of the *item* desired (e.g. S)
Echo	**Your *WP 43S* shows a view starting with the first *item* starting with this sequence** e.g.

g_d^{-1}	Geom	$Geom_p$	$Geom_u$	$Geom^{-1}$	GRAD
$F^{-1}(p)$	f'(x)	f"(x)	GAP	GCD	g_d
FS?	FS?C	FS?F	FS?S	$F_u(x)$	F(x)

4 User input	Press the corresponding *softkey* e.g. for FS?S
Echo	**Your *WP 43S* executes or inserts the command, recalls the constant, or inserts the letter selected.** **Result** (in this example after specifying the *flag* number): true 1

At the bottom line, this means that ...

- any provided function can be called by f CATALOG FCNS + 4 keystrokes maximum if you know its first two characters (i.e. ≤ 7 keystrokes for an arbitrary function out of more than 750);
- any provided constant can be recalled by g CNST + 3 keystrokes maximum if you know its first character;
- any letter can be inserted by f CATALOG CHARS αINTL (or in *AIM* by g +) + 3 keystrokes maximum.

If a character or sequence specified is not found then the first *item* following alphabetically will be shown – see the sorting order in the *IOI*. If there is no such *item*, then the last *item* in this *catalog* will be displayed.

Menus and Their Contents

In the table below, all the *menus* provided for you beyond CATALOG are listed in alphabetical sorting order. For each *menu view*, the row of unshifted softkeys is listed first, then the f-shifted, then the g-shifted, following reading habits. Note, however, that on the screen of your *WP 43S* the order of these three rows is reverted with the unshifted row of each *menu view* displayed at the bottom (see the pictures above).

Different *views* within one *menu* are separated by a dashed line, *submenus* by a double line.

Menu	^	^	^	^	^	^	Remarks
ADV:	SOLVE	SLVQ	f'(x)	Π	Σ	∫fdx	see *Section 4* of the *OM*
			f''(x)				
∫fdx:			ACC	↓Lim	↑Lim	∫	
BITS:	AND	OR	XOR	NOT	MASKL	MASKR	encompasses all the Boole's and bit operations of *HP-16C* and *WP 34S*
	NAND	NOR	XNOR		MIRROR	ASR	
	SB	BS?	#B	FB	BC?	CB	
	SL	RL	RLC	RRC	RR	SR	
	LJ					RJ	
CLK:	DATE	→DATE	DATE→	WDAY	TIME	x→DATE	date and time functions and settings.
	J→D	D→J		DAY	MONTH	YEAR	
	SETTIM	TDISP	SETDAT	D.MY	Y.MD	M.DY	
	CLK12	CLK24				J/G	
CLR:	CLΣ	CLP	CF	CLMENU	CLSTK	CLX	almost as in *HP-42S*
	CLREGS	CLPall	CLFall	CLCVAR	CLLCD	CLall	
						RESET	
CNST:							*catalog* of constants, s. p. 118

Menu	^	^	^	^	^	^	Remarks
CPX:	CC	cross	dot	UNITV	|x|	conj	special complex functions
	Re	Im	Re≷Im	sign	∠		
	CPXi	CPXj			POLAR	RECT	
DISP:	FIX	SCI	ENG	ALL	DSP	GAP	operations and settings for real numbers
	ROUND	ROUNDI	RDP	RSD	SDL	SDR	
	CHINA	EUROPE	INDIA	JAPAN	UK	USA	
	SCIOVR	ENGOVR	MULT×	MULT·	RDX.	RDX,	
	DSTACK				LZOFF	LZON	
EQN:	NEW	EDIT	f''	f'	∫f	Solver	see *Section 4* of the *OM*
	DELETE						
Solver:							show the names of all variables of the current equation and more (s. the *OM, Sect. 4*).
∫f:							
f':							
f'':							
EQ.EDI	←	( )	^	:	=	→	Equation Editor
EXP:	x^3	$\sqrt[3]{x}$	$\sqrt[x]{y}$	$\log_x y$	2^x	lb x	exponential, logarithmic, and hyperbolic functions
				ln 1+x	e^x-1		
	sinh	arsinh	cosh	arcosh	tanh	artanh	
FIN:	%	%MRR	%T	%Σ	%+MG	TVM	financial functions, also for TVM (see the *OM, Section 5*)
TVM:	n_{PER}	i%/a	per/a	PV	PMT	FV	
	Begin					End	
FLAGS:	SF	FS?	FF	STATUS	FC?	CF	
	FS?S	FS?C	FS?F	FC?F	FC?S	FC?C	
						CLFall	
INFO:	SSIZE?	MEM?	RM?	SMODE?	WSIZE?	KTYP?	system information
	LocR?	FLASH?	ULP?	NEIGHB	SDIGS?	BATT?	
	WHO?	VERS?	DIM?	±∞?	αPOS?	αLENG?	

Menu	^	^	^	^	^	^	Remarks
INTS:	A	B	C	D	E	F	for integer numbers: extra digits for bases >10, and operations
	IDIV	RMDR	MOD	×MOD	FLOOR	LCM	
	DBL/	DBLR	DBL×	^MOD	CEIL	GCD	
	1COMPL	2COMPL	UNSIGN	SIGNMT		WSIZE	
I/O:	BEEP	LOAD	LOADP	LOADR	LOADSS	LOADΣ	data exchange incl. the PRINT commands of *HP-42S*
	QUIET	TONE			RECV	SEND	
	🖶ADV	🖶CHAR	🖶DLAY	🖶LCD	🖶MODE	🖶PROG	
	🖶r	🖶REGS	🖶STK	🖶TAB	🖶USER	🖶WIDTH	
	🖶Σ	🖶#					
LOOP:	DSE	DSZ	DSL	ISE	ISZ	ISG	
	DEC					INC	
MATX:	NEW	$[M]^{-1}$	$\lvert M\rvert$	$[M]^T$	SIM EQ	EDIT	almost as in *HP-42S*
	dot	cross	UNITV	DIM	INDEX	EDITN	
	ENORM	RNORM	STOEL	RCLEL	PUTM	GETM	
	I+	I-	STOIJ	RCLIJ	J-	J+	
	RSUM		M.LU	DIM?		R⇄R	
	EIGVAL					EIGVEC	
M.EDIT:	←	↑	OLD	GOTO	↓	→	Matrix Editor as in *HP-42S*
	INSR		DELR		WRAP	GROW	
M.SIMQ:	Mat A	Mat B				Mat X	solver for a *SLE* (works like SIMQ in the *HP-42S*)
MODE:	DEG	RAD	GRAD	MULπ	RECT	POLAR	top six almost as in *HP-42S*
	FAST	SLOW	RM	QUIET	REALRE	CPXRES	
	DENMAX	DENANY	DENFAC	DENFIX	SSIZE4	SSIZE8	
	1COMPL	2COMPL	UNSIGN	SIGNMT	WSIZE	SETSIG	
MyMenu:							will show up outside of *AIM* [28]

Menu	^	^	^	^	^	^	Remarks
Myα:							will show up in *AIM* [28]

PARTS:	IP	FP	|x|	DECOMP	RSD	ROUND	overlaps with *HP-42S* CONVERT
	MANT	EXPT	sign		RDP	ROUNDI	

PROB:	t:	Φ:	C_{yx}	P_{yx}	F:	χ^2:	15 probability distributions. Selecting one (e.g. Binom) opens a submenu featuring entries for its *PDF* (or *PMF*), *CDF*, error probability, and quantile function
	Norml:	LgNrm:	Cauch:	Expon:	Logis:	Weibl:	
	Binom:	Geom:	Hyper:	NBin:		Poiss:	
	RAN#	SEED				Γ(x)	
Binom:	$Binom_p$	Binom			$Binom_u$	$Binom^{-1}$	
Cauch:	$Cauch_p$	Cauch			$Cauch_u$	$Cauch^{-1}$	
Expon:	$Expon_p$	Expon			$Expon_u$	$Expon^{-1}$	
F:	$F_p(x)$	F(x)			$F_u(x)$	$F^{-1}(p)$	
Geom:	$Geom_p$	Geom			$Geom_u$	$Geom^{-1}$	
Hyper:	$Hyper_p$	Hyper			$Hyper_u$	$Hyper^{-1}$	
LgNrm:	$LgNrm_p$	LgNrm			$LgNrm_u$	$LgNrm^{-1}$	
Logis:	$Logis_p$	Logis			$Logis_u$	$Logis^{-1}$	
NBin:	$NBin_p$	NBin			$NBin_u$	$NBin^{-1}$	
Norml:	$Norml_p$	Norml			$Norml_u$	$Norml^{-1}$	
Poiss:	$Poiss_p$	Poiss			$Poiss_u$	$Poiss^{-1}$	
t:	$t_p(x)$	t(x)			$t_u(x)$	$t^{-1}(p)$	
Weibl:	$Weibl_p$	Weibl			$Weibl_u$	$Weibl^{-1}$	
Φ:	φ(x)	Φ(x)			$\Phi_u(x)$	$\Phi^{-1}(p)$	
χ^2:	$\chi^2{}_p(x)$	$\chi^2(x)$			$\chi^2{}_u(x)$	$(\chi^2)^{-1}$	

[28] ... as long as no other *menu* is called (see *Section 6* of the *OM*).

Menu	^	^	^	^	^	^	Remarks
P.FN:	INPUT	END	ERR	TICKS	PAUSE	P.FN2	additional programming functions (avoided *multi-view* here!).
	PSTO	PRCL	αOFF	αON	CONST	PUTK	
	R-CLR	R-COPY	R-SORT	R-SWAP	LocR	PopLR	
P.FN2:	MENU	KEYG	KEYX	CLMENU	EXITall	RTN+1	
	SDL	SDR	MSG	NOP	VARMNU	MVAR	
	BACK	CASE	SKIP	AGRAPH	PIXEL	POINT	
STAT:	Σ+	$\bar{x}$	s	σ	SUM	s_m	for sample statistics.
	Σ-	$\bar{x}_w$	s_w	σ_w		s_{mw}	
	CLΣ	$\bar{x}_G$	ε	ε_p	PLOT	ε_m	
	L.R.	r	s_{xy}	cov	$\hat{y}$	$\hat{x}$	for curve fitting and 2d sample statistics.
	LinF	ExpF	LogF	PowerF		BestF	
	OrthoF						
	n	Σx	Σx^2	Σxy	Σy^2	Σy	all the sums necessary for the statistics above.
		Σlnx	$\Sigma \ln^2 x$	Σlnxy	$\Sigma \ln^2 y$	Σlny	
	$\Sigma x^2 y$	Σxlny				Σylnx	
STK:	x⇶	y⇶	z⇶	t⇶	⇶	DROP	*stack* related operations.
						DROPy	
	SSIZE4	SSIZE8					
TEST:	x< ?	x≤ ?	x= ?	x≠ ?	x≥ ?	x> ?	binary test commands.
	INT?	EVEN?	ODD?	PRIME?	LEAP?	FP?	
	ENTRY?	KEY?	LBL?	STRI?	CONVG?	TOP?	
	x=+0?	x=-0?	x≈ ?	MATR?	CPX?	REAL?	
	SPEC?	NaN?		M.SQR?		DBL?	
TRI:	sin	arcsin	cos	arccos	tan	arctan	trigonometrics

Menu	^	^	^	^	^	^	Remarks
U→:	E:	P:	year→s	F&p:	m:	x:	unit conversions, see pp. 134ff.
	°C→°F	°F→°C	s→year		V:	A:	
	power ratio → dB	dB → power ratio			field ratio → dB	dB → field ratio	
E:	cal→J	J→cal	Btu→J	J→Btu	Wh→J	J→Wh	units of energy
P:	hp_E→W	W→hp_E	hp_{UK}→W	W→hp_{UK}	hp_M→W	W→hp_M	units of power
F&p:	lbf→N	N→lbf	bar→Pa	Pa→bar	psi→Pa	Pa→psi	units of force and pressure
	in.Hg → Pa	Pa → in.Hg	torr → Pa	Pa → torr	atm → Pa	Pa → atm	
m:	lbs→kg	kg→lbs	cwt→kg	kg→cwt	oz→kg	kg→oz	units of mass
	stones → kg	kg → stones	short cwt→kg	kg → sh.cwt	tr.oz → kg	kg → tr.oz	
	tons → kg	kg → tons	short tons → kg	kg → short tons			
x:	au→m	m→au	ly→m	m→ly	pc→m	m→pc	units of length
	mi.→m	m→mi.	nmi.→m	m→nmi.	ft.→m	m→ft.	
	in.→m	m→in.	pt.→m	m→pt.	yd.→m	m→yd.	
					s:$feet_{US}$ → m	m → s:$feet_{US}$	
A:	acres → m^2	m^2 → acres			$acres_{US}$ → m^2	m^2 → $acres_{US}$	units of area
V:	gl_{UK}→m^3	m^3→gl_{UK}	qt.→m^3	m^3→qt.	gl_{US}→m^3	m^3→gl_{US}	units of volume
	$floz_{UK}$ → m^3	m^3 → $floz_{UK}$			$floz_{US}$ → m^3	m^3 → $floz_{US}$	

Menu	^	^	^	^	^	^	Remarks
X.FN:	AGM	B_n	B_n^*	erf	erfc	Orthog	advanced mathematical functions like Bessel, Beta, etc.
	FIB	g_d	g_d^{-1}	I_{xyz}	$I\Gamma_p$	$I\Gamma_q$	
	$J_y(x)$	lnβ	lnΓ	max	min	NEXTP	
	SHOW	sinc	W_m	W_p	W^{-1}	β(x,y)	
	γ_{xy}	Γ_{xy}	ζ(x)	$(-1)^x$	→DP	→SP	
	||						
Orthog:	H_n	L_n	L_n^α	P_n	T_n	U_n	orthogonal polynomials
	H_{np}						

αINTL:	Ā ā	Á á	Ă ă	À à	Ä ä	Ã ã	[α] *catalog* of international letters, see *here*. Most letters in this (*sub-*) *menu* will change when case is switched in *AIM* – note you will see the individual letters displayed in either case only at one time. You will reach every letter by three keystrokes maximum since letters can be accessed alphabetically.
	Â â	Å å	Æ æ	Ą ą	Ć ć	Č č	
	Ç ç	Đ đ	Ď ď	Ē ē	É é	Ě ě	
	È è	Ë ë	Ê ê	Ė ė	Ě ě	Ę ę	
	Ğ ğ	Ī ī	Í í	Ĭ ĭ	Ì ì	Ï ï	
	Î î	Į į	İ i	I ı	Ł ł	Ĺ í	
	Ľ ľ	Ń ń	Ň ň	Ñ ñ	Ō ō	Ó ó	
	Ŏ ŏ	Ò ò	Ö ö	Õ õ	Ô ô	Ø ø	
	Œ œ	Ř ř	Ŕ ŕ	β	Ś ś	Š š	
	Ş ş	Ť ť	Ţ ţ	Ū ū	Ú ú	Ŭ ŭ	
	Ù ù	Ü ü	Ű ű	Û û	Ů ů	Ų ų	
	Ŵ ŵ	Ŷ ŷ	Ý ý	Ÿ ÿ	Ź ź	Ž ž	
	Ż ż						

Menu	^	^	^	^	^	^	Remarks
αMATH:	<	≤	=	≈	≥	>	[α] for comparison symbols, parentheses, and more mathematical and related symbols. You can reach every character by three keystrokes maximum.
	{	[	(	)	]	}	
	× / · [29]	÷	∫	∞	∞	∞	
	¬	∧	∨	≠	|	&	
	∢	⊾	⊥	∛	√	∜	
	x̄	ȳ	x̂	ŷ	x̄	ȳ	
	:=	≙	≡	ε	ℂ	ℝ	
	⊙	⊛	⊕				
	±	^	T	-1	ℏ		
α.FN:	x→α	αRL	αRR	αSL	αPOS?	α→x	dedicated functions for alpha strings, plus font browser
					αLENG?		
	FBR						
A…Ω:	Α α	ά	Β β	Γ γ	Δ δ	Ε ε	[α] Greek letters. The keyboard grants direct access to 24 of them. Note the two kinds of lower case Σ. See αINTL for more.
	έ	Ζ ζ	Η η	ή	Θ ϑ	Ι ι	
	ί	ΐ	Ϊ ϊ	Κ κ	Λ λ	Μ μ	
	Ν ν	Ξ ξ	Ο ο	ό	Π π	Ρ ρ	
	Σ σ	ς	Τ τ	Υ υ	ύ	Ϋ ϋ	
	ΰ	Φ φ	Χ χ	Ψ ψ	Ω ω	ώ	

[29] With startup default settings, the multiplication dot is found herein and the multiplication cross is called via f × in *AIM*. If MULT· is set, however, this dot is called via f × and the multiplication cross via 'αMATH.

Menu	^	^	^	^	^	^	Remarks
α•:	!	:	;	'	"	@	[α] for punctuation marks and further special characters.
	¡	¿	#	_	~	\	
	$	€	%	&	£	¥	
	←	↑	↕	↓	→	⤒	
	«	»	⌀	🕓	•	*	
						*	

∢→:	∢→∢°	∢→∢ʳ	∢→∢ᵍ		∢→∢"	∢→∢π	angular conversions, cf. pp. 140f.
	∢°→∢	∢ʳ→∢	∢ᵍ→∢		∢"→∢	∢π→∢	
	∢°→∢ʳ	∢ʳ→∢°		∢°→∢"	∢"→∢°		

Constants

Your *WP 43S* contains a *catalog* of 80 physical, astronomical, and mathematical constants sorted alphabetically:

	G	G_0	G_C	g_e	$GM_\oplus$	$g_\oplus$
	c_1	c_2	e	e_E	F_α	F_δ
	1/2	α	α_0	α_M	$\alpha_\oplus$	c

Names of astronomical and mathematical constants are printed on colored background in the table starting overleaf. Values of physical constants (including their relative standard deviations in *red print* below) are printed on light background if they are exactly defined or almost exactly known – the darker the background, the less precisely the particular value is known.[30]

[30] For the physical constants, their precise numeric values (incl. their units) and their relative standard deviations (*SD*) are from *CODATA* 2014xxx, copied in September 2015. These are the best values known in the scientific community, agreed on by the national standards institutes worldwide. Note that all of them feature less than 16 significant digits. – *Relative uncertainties* are included in the printed table here though

Now here are the contents of CNST (printing commas as radix marks for better visibility and multiplication dots for space reasons). Formulas are printed if applicable.

Name	Numeric value and rel. *SD*	Remarks
1/2	0,5	Trivial but helpful constant for some iterations.
a	365,242 5 d *(per definition)*	*Gregorian* year
a_0	5,291 772 106 7·10^{-11} m *(2,3·10^{-10})*	*Bohr* radius $a_0 = \alpha / 4\pi R_\infty$ [31]
a_M	3,844·10^{8} m *(1·10^{-3})*	Semi-major axis of the Moon's orbit around the earth ≈ 1,3 *light seconds*.

not contained in 'CNST. These uncertainties are important for determining the precision of results you obtain using the constants given, through the process of '*error propagation*' going back to *C. F. Gauß* (1777 – 1855). This procedure is essential if your results are to be trustworthy – not only in science (remember each and every scientific result shall include the indication of its uncertainty). Please consult suitable reference (e.g. http://physics.nist.gov/cgi-bin/cuu/Info/Constants/definitions.html gives a nice introduction). There is simply no way yardstick measurements can yield results accurate to four decimals.

By the way, the terms *resolution*, *precision*, and *accuracy* are confused frequently in measuring. In a nutshell, *resolution* is the least significant digit a measuring instrument indicates. Using this instrument for measuring the same object under identical conditions multiple times, you get an idea about its *repeatability* (or *precision*); this can be no better than its *resolution* but may be significantly worse – a factor of ten or more may be observed easily in real life. *Accuracy* of a measuring instrument, however, can never be better than its *repeatability*. Since you cannot know anything about a real life object or process any better than you can measure it, these considerations are of fundamental importance. We recommend watching them – in your very own interest.

[31] This is a good estimate for the radius of a hydrogen atom. On the other hand, a typical radius of an atomic nucleus is about $10^{-15}\,m$. So the nucleus takes far less than a billionth of the volume of an atom. Electrons are even smaller. Thus an atom is almost completely empty space. Our world as we know and see it every day is built of atoms. Think about it!

By the way, these facts also give some hand-waving arguments why cancer therapy using heavy ion beams works (and significantly better than using X-rays).

Name	Numeric value and rel. *SD*	Remarks
$a_\oplus$	1,495 979·10 **11** m *(1·10⁻⁶)*	Semi-major axis of the Earth's orbit around the sun. Within the uncertainty stated here, it equals 1 *astronomic unit* ≈ 499 *light seconds*.
c	2,997 924 58·10 **8** m/s *(per definition)*	Speed of light in vacuum $\approx 300\,000\,\frac{km}{s} = 300\,\frac{km}{ms} = 300\,\frac{m}{\mu s} = 30\,\frac{cm}{ns} = 0{,}3\,\frac{mm}{ps}$ etc.
c_1	3,741 771 79·10 **−16** m^2W *(1,2·10⁻⁸)*	First radiation constant $c_1 = 2\pi\, h\, c^2$
c_2	0,014 387 773 6 $m \cdot K$ *(5,7·10⁻⁷)*	Second radiation constant $c_2 = hc/k$
e	1,602 176 620 8·10 **−19** A s *(6,1·10⁻⁹)*	Elementary charge $e = \frac{2}{K_J R_K} = \Phi_0 G_0$
e_E	2,718 281 828 459 045 2…	*Euler's e*.
e/m_e	1,758 820 024·10 **11** As/kg *(6,2·10⁻⁹)*	Electron charge to mass ratio
F	96 485,332 89 As/mol *(6,2·10⁻⁹)*	*Faraday* constant $F = e\, N_A$
F_α	2,502 907 875 095 892 8...	*Feigenbaum's* α and δ
F_δ	4,669 201 609 102 990 6...	
G	6,674 08·10 **−11** $m^3/kg\,s^2$ *(4,7·10⁻⁵)*	*Newtonian* constant of gravitation; also known as γ from other authors. See $GM_\oplus$ below for a more precise value.

Name	Numeric value and rel. *SD*	Remarks
G_0	7,748 091 731·10^{-5} / Ω *(2,3·10^{-10})*	Conductance quantum $G_0 = {2e^2}/{h} = {2}/{R_K} = eK_j$
G_C	0,915 965 594 177 219 0…	*Catalan's* constant
g_e	−2,002 319 304 361 82 *(2,6·10^{-13})*	*Landé's* electron g-factor
$GM_\oplus$	3,986 004 418·10^{14} ${m^3}/{s^2}$ *(2,0·10^{-9})*	*Newtonian* constant of gravitation times the Earth's mass with its atmosphere included (according to *WGS84* [32])
$g_\oplus$	9,806 65 ${m}/{s^2}$ *(per def.)*	Standard earth acceleration
h	6,626 070 04·10^{-34} J s *(1,2·10^{-8})*	*Planck* constant
$\hbar$	1,054 571 8·10^{-34} J s *(1,2·10^{-8})*	So-called '*Dirac* constant' $\hbar = {h}/{2\pi}$
k	1,380 648 52·10^{-23} ${J}/{K}$ *(5,7·10^{-7})*	*Boltzmann* constant $k = {R}/{N_A}$
K_J	4,835 978 525·10^{14} ${Hz}/{V}$ *(6,1·10^{-9})*	*Josephson* constant $K_j = {2e}/{h}$
l_P	1,616 229·10^{-35} m *(2,3·10^{-5})*	*Planck* length $l_P = \sqrt{\frac{\eta G}{c^3}} = t_p c$
m_e	9,109 383 56·10^{-31} kg *(1,2·10^{-8})*	Electron mass $\triangleq 511{,}00\ keV$
M_M	7,349·10^{22} kg *(5·10^{-4})*	Mass of the Moon

[32] See http://earth-info.nga.mil/GandG/publications/tr8350.2/tr8350_2.html

Name	Numeric value and rel. *SD*	Remarks
m_n	1,674 927 471·10^{-27} kg *(1,2·10^{-8})*	Neutron mass $\triangleq 939{,}57\ MeV$
m_n/m_p	1,001 378 418 98 *(5,1·10^{-10})*	Neutron to proton mass ratio
m_p	1,672 621 898·10^{-27} kg *(1,2·10^{-8})*	Proton mass $\triangleq 938{,}27\ MeV$
M_P	2,176 47·10^{-8} kg *(2,3·10^{-5})*	*Planck* mass $M_P = \sqrt{\hbar c/G} \approx 22\ \mu g$
m_p/m_e	1 836,152 673 89 *(9,5·10^{-11})*	Proton to electron mass ratio
m_u	1,660 539 04·10^{-27} kg *(1,2·10^{-8})*	Atomic mass constant $= 10^{-3}\ kg/N_A$
$m_u c^2$	1,492 418 062·10^{-10} J *(1,2·10^{-8})*	Energy equivalent of the atomic mass constant $\approx 931{,}49\ MeV$
m_μ	1,883 531 594·10^{-28} kg *(2,5·10^{-8})*	Muon mass $\triangleq 105{,}66\ MeV$
$M_\odot$	1,989 1·10^{30} kg *(5·10^{-5})*	Mass of the Sun
$M_\oplus$	5,973 6·10^{24} kg *(5·10^{-5})*	Mass of the Earth. See $GM_\oplus$ above for a more precise value.
N_A	6,022 140 857·10^{23} / mol *(1,2·10^{-8})*	*Avogadro's* number
NaN	Not a number	See the corresponding entry in *Section 5* of the *OM.*
p_0	101 325 Pa *(per def.)*	Standard atmospheric pressure

Name	Numeric value and rel. *SD*	Remarks
R	8,314 459 8 $J/_{mol\,K}$ *(5,7·10⁻⁷)*	Molar gas constant
r_e	2,817 940 322 7·10⁻¹⁵ m *(6,8·10⁻¹⁰)*	Classical electron radius $r_e = \alpha^2\, a_0$
R_K	25 812,807 455 5 Ω *(2,3·10⁻¹⁰)*	*Von Klitzing* constant $R_K = h/e^2$
R_M	1,737 530·10⁶ m *(5·10⁻⁷)*	Mean radius of the Moon
R_∞	10 973 731,568 508 / m *(5,9·10⁻¹²)*	*Rydberg* constant $R_\infty = \frac{\alpha^2 m_e c}{2h}$
$R_\odot$	6,96·10⁸ m *(5·10⁻³)*	Mean radius of the sun
$R_\oplus$	6,371 010·10⁶ m *(5·10⁻⁷)*	Mean radius of the Earth
Sa	6,378 137 0·10⁶ m *(per definition)*	Semi-major axis
Sb	6,356 752 314 2·10⁶ m *(1,6·10⁻¹¹)*	Semi-minor axis
Se^2	6,694 379 990 14·10⁻³ *(1,5·10⁻¹²)*	First eccentricity squared
Se'^2	6,739 496 742 28·10⁻³ *(1,5·10⁻¹²)*	Second eccentricity squared
Sf^{-1}	298,257 223 563 *(per def.)*	Flattening parameter
T_0	273,15 K *(per def.)*	= 0°C, standard temperature

… according to *WGS84* (see footnote 32 on p. 129)

Name	Numeric value and rel. *SD*	Remarks
t_P	5,391 16·10^{-44} s *(2,3·10^{-5})*	*Planck* time $t_P = {l_P}/{c}$
T_P	1,416 808·10^{32} K *(2,3·10^{-5})*	*Planck* temperature $T_P = \frac{c^2}{k}\sqrt{\frac{\hbar c}{G}} = \frac{M_P c^2}{k} = \frac{E_P}{k}$
V_m	0,022 413 962 ${m^3}/{mol}$ *(5,7·10^{-7})*	Molar volume of an ideal gas at standard conditions $V_m = \frac{RT_0}{p_0} \approx 22{,}4\ {l}/{mol}$
Z_0	376,730 313 461 770 6… Ω	Characteristic impedance of vacuum $Z_0 = \mu_0 c$
α	7,297 352 566 4·10^{-3} *(2,3·10^{-10})*	Fine-structure constant $\alpha = \frac{e^2}{2\varepsilon_0 h c} \approx \frac{1}{137}$
γ	6,674 08·10^{-11} ${m^3}/{kg\ s^2}$ *(4,7·10^{-5})*	*Newtonian* constant of gravitation; also known as G from other authors. See $GM_\oplus$ below for a more precise value.
γ_{EM}	0,577 215 664 901 532 9…	*Euler-Mascheroni* constant
γ_p	2,675 221 9·10^{8} $\frac{1}{s \cdot T}$ *(6,9·10^{-9})*	Proton gyromagnetic ratio $\gamma_p = 4\pi\,{\mu_p}/{h}$
ε_0	8,854 187 81… ·10^{-12} $\frac{A\ s}{V\ m}$	Electric constant or vacuum permittivity $\varepsilon_0 = {1}/{\mu_0 c^2}$ (note the so-called *Coulomb's* constant is just ${1}/{4\pi\varepsilon_0} = {\mu_0 c^2}/{4\pi} = 10^{-7} c^2 \approx 8{,}987\,552 \cdot 10^9\ {V\ m}/{A\ s}$, cf. μ_0).

Name	Numeric value and rel. *SD*	Remarks
λ_C	2,426 310 236 7·10^{-12} m *(4,5·10^{-10})*	*Compton* wavelengths of the electron $\lambda_C = {}^{h}/_{m_e c}$, neutron $\lambda_{Cn} = {}^{h}/_{m_n c}$, and proton $\lambda_{Cp} = {}^{h}/_{m_p c}$, respectively
λ_{Cn}	1,319 590 904 81·10^{-15} m *(6,7·10^{-10})*	
λ_{Cp}	1,321 409 853 96·10^{-15} m *(4,6·10^{-10})*	
μ_0	1,256 637 061… ·10^{-6} $\frac{V\,s}{A\,m}$ *(per definition)*	Magnetic constant or vacuum permeability $\mu_0 := 4\pi \times 10^{-7}\ {}^{V\,s}/_{A\,m}$
μ_B	9,274 009 994·10^{-24} ${}^{J}/_{T}$ *(6,2·10^{-9})*	*Bohr* magneton $\mu_B = {}^{e\hbar}/_{2m_e}$
μ_e	−9,284 764 62·10^{-24} ${}^{J}/_{T}$ *(6,2·10^{-9})*	Electron magnetic moment
μ_e/μ_B	−1,001 159 652 180 91 *(2,6·10^{-13})*	Ratio of electron magnetic moment to *Bohr's* magneton
μ_n	−9,662 365·10^{-27} ${}^{J}/_{T}$ *(2,4·10^{-7})*	Neutron magnetic moment
μ_p	1,410 606 787 3·10^{-26} ${}^{J}/_{T}$ *(6,9·10^{-9})*	Proton magnetic moment
μ_u	5,050 783 699·10^{-27} ${}^{J}/_{T}$ *(6,2·10^{-9})*	Nuclear magneton $\mu_u = {}^{e\hbar}/_{2m_p}$
μ_μ	−4,490 448 26·10^{-26} ${}^{J}/_{T}$ *(2,3·10^{-8})*	Muon magnetic moment

Name	Numeric value and rel. *SD*	Remarks
σ_B	5,670 367·10^{-8} $\frac{W}{m^2K^4}$ *(2,3·10^{-6})*	*Stefan-Boltzmann* constant $\sigma_B = \frac{2\pi^5 k^4}{15h^3c^2}$
Φ	1,618 033 988 749 894 8…	Golden ratio $\Phi = \frac{1}{2}(1+\sqrt{5})$
Φ_0	2,067 833 831·10^{-15} V s *(6,1·10^{-9})*	Magnetic flux quantum $\Phi_0 = \frac{h}{2e}$
ω	7,292 115·10^{-5} rad/s *(2·10^{-8})*	Angular velocity of the Earth according to *WGS84* (see footnote 32 on p. 129)
-∞	$-\infty$	Note both are counted as numeric values in your *WP 43S*.
∞	∞	
#		Allows for inserting an integer $0 \le n \le 255$ in a single program step

Unit Conversions

Your *WP 43S* features 13 angular conversions provided in ∠→ (see p. 126) and 80 unit conversions in U→. The structure of U→ follows various branches as introduced in the *OM*, *Section 5*. Its top *view* looks like this:

with **E:** standing for the *submenu* of energy unit conversions, **P:** for power, **F&p:** for force and pressure, **m:** for mass, **x:** for length, **A:** for area, and **V:** for volume.

Conversions contained in U➔ either begin or end in basic *SI* units. Beyond them and products or powers of these, knowledge of the following *SI derived units* carrying special names may be helpful in your further calculations:

Quantity	**Unit**	**Symbol and formula**
Temperature	*degree Celsius*	$\vartheta[°C] = \mathrm{T}[K] - 273.15$
Force	*newton*	$1\,N = 1\,kg\ {}^{m}/_{s^2}$
Pressure	*pascal*	$1\,Pa = 1\ {}^{N}/_{m^2} = 1\ {}^{kg}/_{m\,s^2}$
Energy	*joule*	$1\,J = 1\,N\,m = 1\,kg\ {}^{m^2}/_{s^2}$
Power	*watt*	$1\,W = 1\,V\,A\,s = 1\ {}^{J}/_{s}$
Electric potential	*volt*	$1\,V = 1\ {}^{W}/_{A}$
Charge	*coulomb*	$1\,C = 1\,A\,s$
Capacitance	*farad*	$1\,F = 1\ {}^{C}/_{V} = 1\ {}^{A\,s}/_{V}$
Conductance	*siemens*	$1\,S = 1\ {}^{A}/_{V}$
Resistance	*ohm*	$1\,\Omega = 1\ {}^{V}/_{A}$
Magnetic flux	*weber*	$1\,Wb = 1\,V\,s$
Magnetic flux density	*tesla*	$1\,T = 1\ {}^{Wb}/_{m^2} = 1\ {}^{V\,s}/_{m^2}$
Inductance	*henry*	$1\,H = 1\ {}^{Wb}/_{A} = 1\ {}^{V\,s}/_{A}$
Frequency	*hertz*	$1\,Hz = {}^{1}/_{s}$
Absorbed dose	*gray*	$1\,Gy = 1\ {}^{J}/_{kg}$

For talking about inputs and results, knowing the symbols and names of the *SI* prefixes as listed here is beneficial:

Prefix symbol	Name	Factor
h	*hecto-*	10^{2}
k	*kilo-*	10^{3}
M	*mega-*	10^{6}
G	*giga-*	10^{9}
T	*tera-*	10^{12}
P	*peta-*	10^{15}
E	*exa-*	10^{18}

Prefix symbol	Name	Factor
d	*deci-*	10^{-1}
c	*centi-*	10^{-2}
m	*milli-*	10^{-3}
µ	*micro-*	10^{-6}
n	*nano-*	10^{-9}
p	*pico-*	10^{-12}
f	*femto-*	10^{-15}
a	*atto-*	10^{-18}

All conversions featured in U→ and ↯→ are explained in alphabetical order in the following two tables. Therein, numbers are generally rounded to six significant digits; they are for your orientation only; your *WP 43S* uses more precise values where applicable. Commas are used as radix marks for better visibility.

	Calculation	Remarks	Branch
°C→°F	× 1,8 + 32		U→
°F→°C	– 32) / 1,8		
acres→m²	× 4 046,86	These *acres* are based on the *'international feet'*, see below	U→ A:
$acres_{US}$→m²	× 4 046,87	These *acres* are based on the *U.S. survey feet*, see below	
atm→Pa	× 1,013 25×10⁵	*Atmospheres*	U→ F&p:
au→m	× 1,495 98×10¹¹	*Astronomic units*	U→ x:

	Calculation	Remarks	Branch
bar→Pa	× 10^5	1 mbar = 1 hPa	U→ F&p:
Btu→J	× 1 055,06	*British thermal units*	U→ E:
cal→J	× 4,186 8	*Calories*	
cwt→kg	× 50,802 4	(*Long*) *hundredweight* = 112 lbs	U→ m:
dB→field ratio	$10^{R_{dB}/20}$	*Decibels*	U→ ▼
dB→power ratio	$10^{R_{dB}/10}$		
ft.→m	× 0,304 8	The so-called '*international feet*' of 1959 – 1 *foot* := $^1/_3$ *yard*	U→ x:
field ratio →dB	$20\ lg(^{a_1}/_{a_2})$	Also known as amplitude ratio	U→ ▼
$floz_{UK}$→m^3	× 2,841 31×10^{-5}	*Fluid ounces*	U→ f V:
$floz_{US}$→m^3	× 2,957 35×10^{-5}		
gl_{UK}→m^3	× 4,546 09×10^{-3}	*Gallons*	
gl_{US}→m^3	× 3,785 42×10^{-3}		
hp_E→W	× 746	*Electric horsepower*	U→ P:
hp_M→W	× 735,498 8	'*Metric*' *horsepower* (equivalent to PS in German)	
hp_{UK}→W	× 745,699 9	*British Imperial horsepower*	
in.→m	× 0,025 4	1 *inch* := $^1/_{12}$ *foot* and 1 *inch* := 1 000 *mil*	U→ x:
in.Hg→Pa	× 3 386,39	*Inches of mercury*	U→ F&p:
J→Btu	/ 1 055,06	*Joule*	U→ E:
J→cal	/ 4,186 8		
J→Wh	/ 3 600		

	Calculation	Remarks	Branch
kg→cwt	/ 50,802 4	1 t [*(metric) ton*] = 1 000 kg	U→ m:
kg→oz	/ 0,028 349 5		
kg→lbs	/ 0,453 592		
kg→sh.cwt	/ 45,359 2		
kg→sh:tons	/ 907,185		
kg→stones	/ 6,350 29		
kg→tons	/ 1 016,05		
kg→tr.oz	/ 0,031 103 5		
lbf→N	× 4,448 22	*Pounds force*	U→ F&p:
lbs→kg	× 0,453 592	*Pounds;* 1 lb := 16 *ounces*	U→ m:
ly→m	× 9,460 73×10 15	*Light years*	U→ x:
m^2→acres	/ 4 046,86	*Square meter*; 1 a [*are*] = 100 m^2, 1 ha [*hectare*] = 10 000 m^2	U→ f A:
m^2→$acres_{US}$	/ 4 046,87		
m^3→$floz_{UK}$	/ 2,841 31×10 -5	*Cubic meter*; 1 l [*liter*] = 10^{-3} m^3, 1 ml [*milliliter*] = 1 cm^3	U→ f V:
m^3→$floz_{US}$	/ 2,957 35×10 -5		
m^3→gl_{UK}	/ 4,546 09×10 -3		
m^3→gl_{US}	/ 3,785 42×10 -3		
m^3→qt.	/ 1,1365×10 −3		U→ V:
mi.→m	× 1 609,344	1 *mile* = 1 760 *yards*	
m→au	/ 1,495 98×10 11	*Meter*	
m→ft.	/ 0,304 8		U→ x:
m→in.	/ 0,025 4		
m→ly	/ 9,460 73×10 15		

	Calculation	Remarks	Branch
m→mi.	/ 1 609,344	*Meter*	
m→nmi.	/ 1 852		
m→pc	/ 3,085 68×10^16		
m→pt.	/ 352,778×10^−6		U→ x:
m→s:feet$_{US}$	/ 0,304 801		
m→yd.	/ 0,914 4		
nmi.→m	× 1 852	*Nautical miles*	
N→lbf	/ 4,448 22	*Newton*	U→ F&p:
oz→kg	× 0,028 349 5	1 *ounce* := $^1/_{16}$ *pound*	U→ m:
Pa→atm	/ 1,013 25×10^5	*Pascal*; 1 mbar = 1 hPa	
Pa→bar	/ 10^5		
Pa→in.Hg	/ 3 386,39		U→ F&p:
Pa→psi	/ 6 894,76		
Pa→torr	/ 133,322		
pc→m	× 3,085 68×10^16	*Parsec*	U→ x:
power ratio→dB	$10\ lg(^{p_1}/_{p_2})$		U→ ▼
psi→Pa	× 6 894,76	*Pounds per square inch*	U→ F&p:
pt.→m	× 352,778×10^−6	*(Typographical) point*	U→ x:
qt.→m^3	× 1,1365×10^−3	*(Imperial) quart*	U→ V:
sh.cwt→kg	× 45,359 2	1 *short hundredweight* = 100 lbs	
sh:tons→kg	× 907,185	1 *short ton* = 2 000 lbs	U→ m:
stones→kg	× 6,350 29		
s:feet$_{US}$→m	× 0,304 801	1 U.S. *survey foot* := $\frac{1200}{3937}\ m$	U→ x:

	Calculation	Remarks	Branch
s→year	/ 31 556 952		U→
tons→kg	× 1 016,05	1 *Imperial ton* = 200 *(long) cwt* = 2 240 lbs	U→ m:
torr→Pa	× 133.322	1 *torr* = 1 mm Hg	U→ F&p:
tr.oz→kg	× 0,031 103 5	*Troy ounces*	U→ m:
Wh→J	× 3 600	*Watt-hours*	U→ E:
W→hp$_E$	/ 746	*Watt*	U→ P:
W→hp$_M$	/ 735,498 8		
W→hp$_{UK}$	/ 745,699 9		
yd.→m	× 0,914 4	1 *yard* := 3 *feet* (and 2 *yards* := 1 *fathom*)	U→ x:
year→s	× 31 556 952	= 365,242 5 × 24 × 60^2	U→

L→ …	Remarks
x°→x (DEG→)	Interprets ***x*** as decimal *degrees* and converts them to the current *ADM*.
x°→x^r (D→R)	Interprets ***x*** as decimal *degrees* and converts them to *radians* (equaling the old command D→R).
x°→x" (D→D.MS)	Interprets ***x*** as decimal *degrees* and converts them to sexagesimal *degrees*.
x^g→x (GRAD→)	Interprets ***x*** as *grad/gon* and converts it to the current *ADM*.
x^r→x (RAD→)	Interprets ***x*** as *radians* and converts them to the current *ADM*.
x^r→x° (R→D)	Interprets ***x*** as *radians* and converts them to decimal *degrees* (equaling the old command R→D).

[L→] …	Remarks
x∠π→x∠ (MULπ→)	Interprets x as *multiples of* π and converts them to the current *ADM*.
x∠"→x∠ (D.MS→)	Interprets x as sexagesimal *degrees* and converts them to the current *ADM*.
x∠"→x∠° (D.MS→D)	Interprets x as sexagesimal *degrees* and converts them to decimal *degrees*.
x∠→x∠° (→DEG)	Interprets x as an angle of current *ADM* (regardless of x being tagged or not!) and converts it to decimal *degrees*, to *grad/gon*, to *radians*, to *multiples of* π, or to *sexagesimal degrees*, respectively.
x∠→x∠g (→GRAD)	
x∠→x∠r (→RAD)	
x∠→x∠π (→MULπ)	
x∠→x∠" (→D.MS)	

Generally, angular output is tagged. This tag is *temporary information*, it will vanish with the next keystroke.

SECTION 3: CALLING AND EXECUTING OPERATIONS

As mentioned at the beginning of *Section 2* and in the *OM*, the number of *items* featured on your *WP 43S* is far too large to fit them on the keyboard. Hence, there are several ways to call such an *item*. You have already learned how to call *items* appearing on the keyboard and in *menus* (including *catalogs*). In *Section 6* of the *OM*, you have seen that you can store *items* in user *menus* and/or assign them to specific locations on your *WP 43S*. In the following you will learn about one more way you can use for calling and executing operations:

- Using [XEQ] followed by the name of the operation typed in *AIM*.

Furthermore, we will summarize the functions requiring parameters.

Using XEQ for Executing Operations

Instead of picking an operation from a *menu* or *catalog*, you can also call it using XEQ as follows:

1. Press [XEQ].
2. Press [α]. You are in *AIM* thereafter; see *Section 2* of the *OM* for the *virtual keyboard* applying in this mode.
3. Key in the name of the function wanted. Either case will do.
4. Press [ENTER↑]. Your input will be checked – if the operation specified exists
   a. it will be checked for required parameters (cf. overleaf);
      i. if true, you will be prompted for these parameters; then the function will be executed. End.
      ii. else the function will be executed. End.
   b. else error 7 (`No such function`) will be thrown (see *App. C*). End.

Operations Requiring Parameters

Many functions require at least one parameter specifying what they shall do precisely. See the *OM*, *Section 1*. The following three lists summarize these operations:

Operations requiring one parameter **Operation**	**Numeric par.**	**Alpha par.**
AGRAPH CONVG? DEC DSE DSL DSZ INC INPUT ISE ISG ISZ KEY? KTYP? PUTK RCL RCLCFG RCLS RCL+ RCL- RCL× RCL/ RCL↑ RCL↓ STO STOCFG STOS STO+ STO- STO× STO/ STO↑ STO↓ t⇶ VIEW x⇶ x=? x≠? x≈? x<? x≤? x≥? x>? y⇶ z⇶ αLENG? αPOS? αRL αRR αSL α→x 🖶r	*Register* number	Variable name
ALL DSP ENG FIX GAP RDP RSD SCI SDL SDR	Number of decimals	
ASR MASKL MASKR RL RLC RR RRC SL SR WSIZE	Number of bits	
BACK CASE SKIP	Number of program steps	
BC? BS? CB FB SB	Bit number	
CF FC? FC?C FC?F FC?S FF FS? FS?C FS?F FS?S SF	*Flag* number	
CONST	Constant number	
DSTACK	Number of levels	
ERR MSG	Error number	
f'(x) f''(x) GTO LBL LBL? PGMINT PGMSLV XEQ Π Σ		Program label

Operations requiring one parameter		
Operation	**Numeric par.**	**Alpha par.**
GTO.	Number of program steps	Program label
INDEX MVAR M.DIM M.EDIN SOLVE VARMNU ∫		Variable name
LocR	Number of local *registers*	
PAUSE 🖶DLAY	Number of ticks	
RM 🖶MODE	Mode number	
SIM_EQ	Number of unknowns	
TDISP	Time format number	
TONE	Tone number	
→INT	Base	
🖶CHAR	Character code	
🖶TAB	Column number	
🖶#	Byte	

Operations requiring two parameters		
Operation	**First parameter**	**Second parameter**
ASSIGN	*Item*	Sequence of keystrokes
KEYG KEYX	Key number (1 ... 18)	Program label

Operation requiring four parameters	**First to fourth parameter**
⥮	*Stack registers*

Operations Changing Data Types

Most functions will return data of the same type they operate on. Some functions, however, will change the *data type* (*DT*) of the lowest *stack register(s)* regardless of the specific input values, as mentioned at various locations in the *OM*: these operations are collected in the list here.

Input *DT*	Operation(s)	Output *DT*	Output *registers* involved
1	1/x $\sqrt[3]{x}$ AGM cos erf erfc e^x f' f'' gd gd^{-1} IMPFRC $J_y(x)$ LN LNβ LNΓ LOG_{10} LOG_2 LOG_xy MANT POISS... PROFRC sin tan W_m W_p W^{-1} $\sqrt[x]{y}$ β(x,y) Γ_{xy} γ_{xy} Γ(x) Δ% →REAL % %MRR %T %Σ %+MG $\sqrt{x}$ || as well as all unit conversions and all orthogonal polynomials	2 [33]	X
	→POL →REC	2	X, Y
	SLVQ	2 or 3	X, Y, Z
	f'(x) f''(x) SOLVE	2	X, Y, Z, T
	ALL DSP ENG FIX SCI	2	X, Y, Z, T (...D)
	all angular conversions	4	X
	→H.MS	5	X
	J→D →DATE	6	X
	x→α	7	X
	M.NEW	8	X
	M.GET M.NEW	9	X
	→INT	10	X

[33] The functions printed on golden background will return integers (*data type 1*) wherever possible.

Input *DT*	Operation(s)	Output *DT*	Output *registers* involved
2	AND CEIL DATE→ DAY D→J EXPT FLOOR IDIV IDIVR MONTH NAND NEXTP NOR NOT OR ROUNDI SIGN WDAY XNOR XOR YEAR ±∞?	1	**X**
	DECOMP	1	**X, Y**
	SLVQ	2 or 3	**X, Y, Z**
	RE→CX	3	**X**
	arcos arcsin arctan and all angular conversions	4	**X**
	→H.MS	5	**X**
	x→DATE →DATE	6	**X**
	x→α	7	**X**
	M.GET M.NEW	8 or 9	**X**
	→INT	10	**X**
	→DP	11	**X**
3	ABS CROSS IM RE |x| ∢	2	**X**
	CX→RE	2	**X, Y**
	SLVQ	2 or 3	**X, Y, Z**
	→DP	12	**X**
4	cos sin tan	2	**X**
5	→HR	2	**X**
6	DAY D→J MONTH WDAY YEAR	1	**X**
	DATE→	1	**X, Y, Z**
	→REAL	2	**X**

Input *DT*	Operation(s)	Output *DT*	Output *registers* involved
8	M.DIM?	1	**X**, **Y**
	DOT ENORM |M|	2	**X**
	Σ+	2	**X**, **Y**, statistics
9	M.DIM?	1	**X**, **Y**
	ENORM	2	**X**
	DOT |M|	3	**X**
	ABS IM RE ROUNDI |x|	8	**X**
10	SIGN	1	**X**
	e^x LN $LOG_x y$ →REAL	2	**X**
	x→α	7	**X**
11	AND CEIL DATE→ DAY D→J EXPT FLOOR IDIV IDIVR MONTH NEXTP NAND NOR NOT OR ROUNDI SIGN WDAY XNOR XOR YEAR ±∞?	1	**X**
	DECOMP	1	**X**, **Y**
	→SP	2	**X**
	arccos arcsin arctan	4	**X**
	→H.MS	5	**X**
	x→α	7	**X**
	→INT	10	**X**
	RE→CX	12	**X**
12	ROUNDI	1	**X**
	arccos arcsin arctan →SP	3	**X**
	CROSS |x| ∢	11	**X**

APPENDIX A: HARDWARE

Overall dimensions: wedge-shaped: 77 mm × 144 mm × 13 mm or 8 mm (see p. 149)

Mass with battery: ~100 g

LCD dimensions: about 58.8 mm × 35.3 mm visible area, 400 × 240 quadratic pixels monochrome (see *App. D* on pp. 164ff)

Processor: STMicroelectronics STM32L476 incl. RTC (see this link to st.com for the development board used by *SwissMicros*) running at 25 MHz on battery power or 80 MHz connected to USB (see below).

Memory: 1 MB *FM*, 128 kB *RAM* (see *App. B* on pp. 152ff), 8 MB additional *FM* on a QSPI chip; user *RAM* is some 75 kB, user *FM* is 6 MB.

Power supply: 3 V by one *CR2032* coin cell; alternative power supply through USB port; typical average currents drawn for power on and busy: ~4.2 mA; idle: ~0.1 mA; power off: ~3 µA.

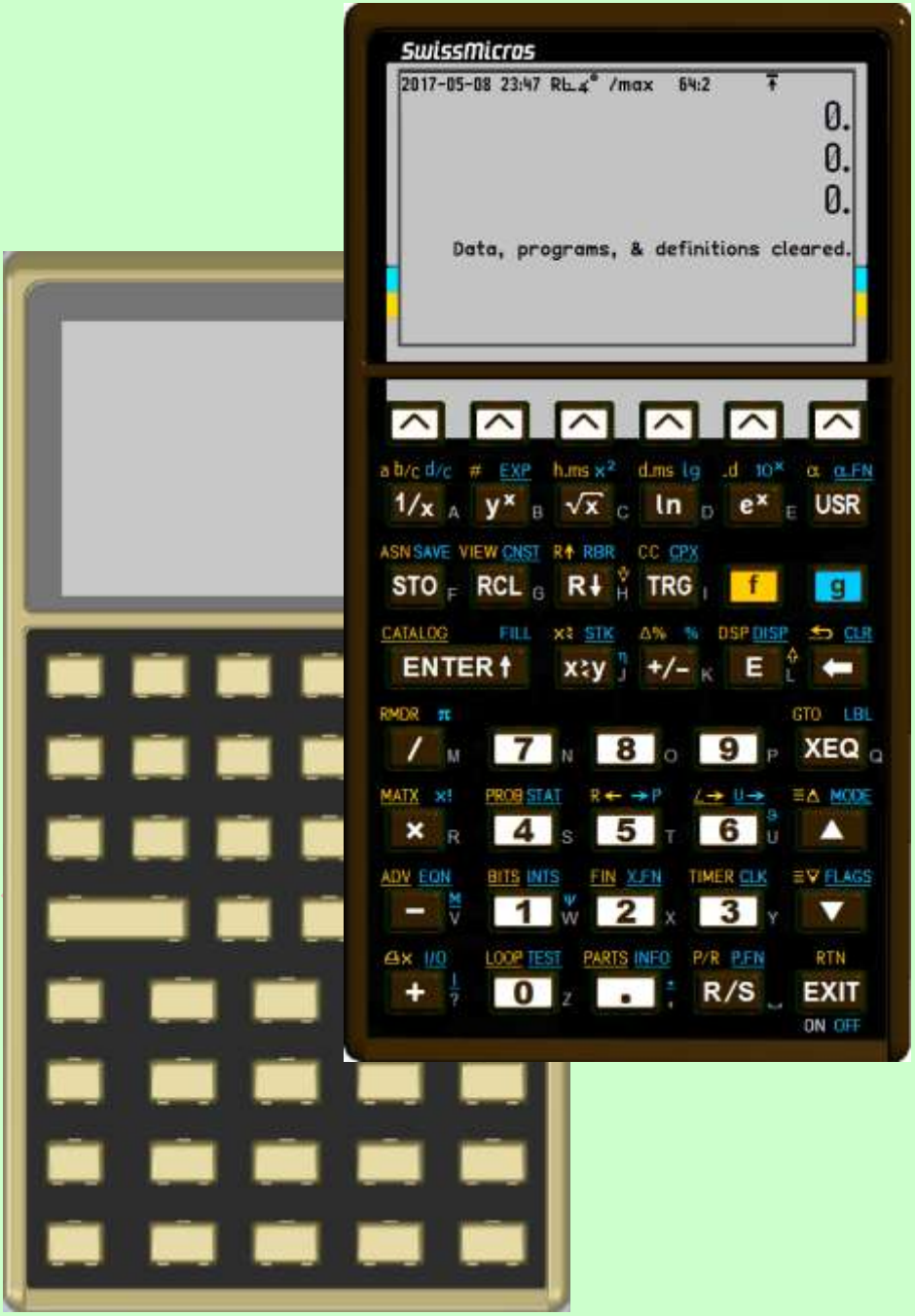
Buzzer frequency: ≥ 1 Hz up to > 20 kHz in steps of 1 Hz.

I/O: infrared printer port, standard micro-USB port.

Self-test: initiated by xxx

Keyboard overlays: Three short slots are provided in the calculator case on either side for easy fixing overlay sheets with your personal user layouts printed on them. See *App. G* for more.

Six pictures of the hardware are displayed here and on the two pages following. The default keyboard layout as delivered by *SwissMicros* (bottom right) and the front views on next page are printed approximately to scale.


SwissMicros
2017-05-08 23:47 Rb 4° /max 64:2
0.
0.
0.
Data, programs, & definitions cleared.
a b/c d/c # EXP h.ms x² d.ms lg .d 10ˣ α α FN
1/x A yˣ B √x C ln D eˣ E USR
ASN SAVE VIEW CNST R↑ RBR CC CPX
STO F RCL G R↓ H TRG I f g
CATALOG FILL x≷ STK Δ% % DSP DISP CLR
ENTER↑ x≷y J +/- K E L
RMDR π GTO LBL
/ M 7 N 8 O 9 P XEQ Q
MATX x! PROB STAT R← →P →R →U ≡Δ MODE
× R 4 S 5 T 6 U ▲
ADV EQN BITS INTS FIN X.FN TIMER CLK ≡▽ FLAGS
− V W 1 X 2 Y 3 ▼
Δx I/O LOOP TEST PARTS INFO P/R P.FN RTN
+ 0 Z . R/S EXIT
ON OFF

See here the internals, details below. Unfasten two bolts at the top of the calculator backside to get there.

To access the keyboard side of the *PCB* carrying the switching domes, carefully release the *LCD* connection Ⓐ, then unfasten the two Philips bolts Ⓑ pictured left and below. These operations are at your own risk.

APPENDIX B: MEMORY MANAGEMENT

Data Types

There are eleven *data types* you know from *Section 2* of the *OM*. Some more had to be defined for internal use, e.g.:

- seven-characters strings for all kinds of *labels*, also including names of commands and all other *menu items*; this is the reason why such names are confined to 7 characters,
- system integers in the range of ± 2 147 483 648,
- flag words for storing 128 (i.e. 112 global plus 16 local) user flags and the same amount of system flags,[34]
- a *data type* of variable length for storing configurations (modes and user assignments, see STOCFG),
- two more for program steps and routines (see *Section 3* of the *OM*).

Due to data typing, a 2- or 4-*byte header* is specified for each object indicating the *data type* in its first half and the length of data trailing.

	Data type number and meaning	Size [*bytes*]	
1	ℤ Integer number of infinite precision [35]	≥ 4 + 8 =	12
2	ℝ Real number [36]	4 + 8 =	12
3	ℂ Complex number	4 + 2 × 8 =	20
5	*Time* [37]	4 + 8 =	12

[34] Up to 256 flags would be possible.

[35] This *data type* is for number theory kind of problems. 64 *bits* allow for signed integers up to $2^{63} \approx 9 \times 10^{18}$. Size will be increased in steps of 2 *bytes* if required. Look up *App. K* for the display limits.

[36] As in the *WP 34S*, standard real numbers feature 64 *bits* and 16 digits precision.

[37] A *time* is stored as a real number of *seconds* internally, just with a specific header. A day corresponds to 86 400 s, a year to 31 556 952 s.

	Data type number and meaning	Size [*bytes*]
6	*Date* [38]	4 + 4 = 8
7	Alpha string (each character requires 16 *bits*)	4 + ***n*** × 2
8	Real matrix (featuring ***n*** rows and ***m*** columns)	4 + ***n*** × ***m*** × 8
9	Complex matrix (featuring ***n*** rows and ***m*** columns)	4 + ***n*** × ***m*** × 16
10	Integer number of finite precision [39]	≤ 4 + 8 = 12
11	Double precision real number	4 + 2 × 8 = 20
12	Double precision complex number	4 + 2 × 16 = 36
13	*Label* (each character requires 16 *bits*)	4 + 7 × 2 = 18
14	System integer	4 + 4 = 8
15	System and user *flags* (128 *flags* each)	4 + 2 = 6
16	User-created *menu*	4 + 18 × 7 × 2 = 256
17	Predefined *menu* (featuring ***n*** *views*)	4 + ***n*** × 18 × 7 × 2
18	*Configuration* [40]	M
19	Program step,[41] may be stored as alpha string (7)	M
20	Program	M
21	Expression (for members of EQN), may be stored as alpha string (7)	M
22	Directory (proposed by P. 2012-12)	M

[38] A *date* is stored as its Julian day number internally. Four *bytes* do for >10^7 years.

[39] This is for *HP-16C* kind of problems. Most probably, such a storage space will be either 4 + 2, 4 + 4, 4 + 6, or 4 + 8 *bytes* long (cf. the footnote for *data type* 1 on previous page).

[40] This size will vary according to the number of user assignments being part of it (see *Section 6* of the *OM*).

[41] This size will vary depending on parameters. Exact limits and methods are not decided yet.

Data types 7 - 9 and 17ff are of 'infinite' size limited by available memory (M) only. Individual size of each object of these types is fixed though.

As mentioned above, any object of any *data type* will take one storage space only: one *register* or one variable. In consequence, *register* lengths in your *WP 43S* may vary considerably. You do not have to bother – the operating system of your *WP 43S* will take care of all the necessary administration. Thus, the amount of RAM required for data storage is not fixed. Data and programs allocate their memory from the same large pool.

Statistical Summation Registers

Your *WP 43S* features a block of 14 special registers for storing statistical sums (like the *WP 34S* and *WP 31S* before).[42] The contents of these registers can be recalled using their names; please see pp. 59 and 94.

And like on our calculators before, this block of registers is allocated from the pool of free memory available as soon as the first statistical data are entered via [Σ+] or [Σ−]; it is deallocated and the memory is returned to the pool by [CLΣ].

Range of Real Numbers

Your *WP 43S* can calculate with real numbers of more than 750 orders of magnitude. Floating point numbers within $10^{-383} \le |x| < 10^{+385}$ may be entered directly easily.

Within this range, your *WP 43S* calculates with 16 digits precision (thus, it can display up to 16 digits in *startup default* display format). Results should be accurate within $\pm 1 \times 10^{-15}$ (e.g. ***n*** [1/x] **2*n*** [×] returns a plain 2 for all primes < 500 – just [7] [1/x] [1][4] [×] returns $2 + 1 \times 10^{-15}$; the

[42] These statistical registers do neither overlap nor interfere with any general purpose registers unlike they did on *HP's* pocket calculators.

same results for 79 and 89, and for 97 a $2 - 1\times10^{-15}$ is returned). Results $|x| < 10^{-398}$ are set to zero (see the *ReM*, *App. B*). For results $|x| \geq 10^{+385}$, error 4 or 5 will appear unless *flag* **D** is set (see *App. C*).

All these effects are caused by the **internal representation of real numbers**: *Standard floating point numbers* are stored in eight bytes using an internal format as follows:

- Real zero is stored as integer zero, i.e. all bits cleared.
- The mantissa of a real number (also known as *significand* in this context) is encoded in five groups of three digits. Each such group is packed into 10 bits straight forward, meaning e.g. 555_{10} = 10 0010 1100_2 or 999_{10} = 11 1110 0111_2 = $3E7_{16}$. So the 15 rightmost decimal digits of the *significand* take the least significant 50 bits. Trailing zeroes are omitted, so the *significand* will be right adjusted.
- The most significant (64th) bit takes the sign of the mantissa.
- The remaining 13 bits are used for the exponent and the leftmost digit of the mantissa. Of those 13, the lowest 8 are reserved for the exponent. For the top 5 bits it becomes complicated.[43] If they read
  - `00ttt`, `01ttt`, or `10ttt` then `ttt` takes the leftmost digit of the *significand* ($0 - 7_{10}$), and the top two bits will be the most significant bits of the exponent;
  - `11uut` then `t` will be added to 1000_2 and the result (8_{10} or 9_{10}) will become the leftmost digit of the *significand*. If `uu` reads 00, 01, or 10 then these two will be the most significant bits of the exponent. If `uu` reads 11 instead, there are codes left for encoding special numbers (e.g. infinities).

  In total, we get 16 digits for the mantissa and a bit less than 10 bits for the exponent: its maximum is 10 1111 1111_2 (i.e. 767_{10}). For reasons becoming obvious below, 398 must be subtracted from the value in this field to get the true exponent of the number represented. The 16 digits of the *significand* allow for a range from 1 to almost 10^{16}.

[43] Don't blame us – this part follows the standard IEEE 754.

Rewarding your patience so far, we will show you some illustrative **examples** of the encoding in your *WP 43S* instead of telling you more theory:

Floating point number	Hexadecimal value stored	Bottom bits in groups of 10	Top 14 bits in binary representation	Stored exponent
1.	22 38 00 00 00 00 00 01		0010 0010 0011 10	398
−1.	A2 38 00 00 00 00 00 01		1010 0010 0011 10	398
111.	22 38 00 00 00 00 00 6F	06F	0010 0010 0011 10	398
111.111	22 2C 00 00 00 01 bC 6F	06F 06F	0010 0010 0010 11	395
−123,000123	A2 20 00 00 07 b0 00 7b	07b 000 07b	1010 0010 0010 00	392
$9{,}99\cdot10^{99}$	23 bC 00 00 00 00 03 E7	3E7	0010 0011 1011 11	495
$1\cdot10^{-99}$	20 AC 00 00 00 00 00 01		0010 0000 1010 11	299
$1\cdot10^{-383}$	00 3C 00 00 00 00 00 01		0000 0000 0011 11	15
$0{,}000\,000\,000\,01\cdot10^{-383}$	00 04 00 00 00 00 00 01		0000 0000 0001 00	4

The last number is the smallest that can be entered directly from the keyboard. Dividing it by 10^4 results in $1\cdot10^{-398}$, being stored as hexadecimal 1. Divide this by 1,999 999 999 99 and the result will remain $1\cdot10^{-398}$ in default rounding mode (and in RM 1, 2, 3, and 5, see the command RM). Divide it by 2 instead and the result will become zero.

Let us look at the high end of our numeric range now:

Floating point number	Hexadecimal value stored	Bottom bits in groups of 10	Top 14 bits	Stored exp.
9,999 999 999 999 99·10^{384}	77 FF E7 F9 FE 7F 78 00	9 3E7 3E7 3E7 3dE 000	0111 0111 1111 11	767

This number (featuring 12 times the digit 9) is the maximum which can be keyed directly. Adding 9,999·10^{372} to it will display 1·10^{385} …

Floating point number	Hexadecimal value stored	Bottom bits in groups of 10	Top 14 bits	Stored exp.
1·10^{385}	77 FF E7 F9 FE 7F 9F E7	9 3E7 3E7 3E7 3E7 3E7	0111 0111 1111 11	767

… which is stored as 9,999 999 999 999 999·10^{384}. This is the greatest number representable in this format. Thus, the greatest *significand* possible is $9\,999\,999\,999\,999\,999 = 10^{16} - 1$;

All this follows *decimal64* floating point format, though not exactly. Additionally, your *WP 43S* features three special 'real numbers':

Floating point number	Hexadecimal value stored	Top byte in binary representation
+∞	78 00 00 00 00 00 00 00	0111 1000
−∞	F8 00 00 00 00 00 00 00	1111 1000
not a number	7C 00 00 00 00 00 00 00	0111 1100

An exponent is not applicable here. These three special numbers are legal results of your *WP 43S* if flag **D** is set – no error will be thrown then.

Calculations with Double Precision (*DP*) Real Numbers

Your *WP 43S* uses *single precision* (*data type* 2) in real calculations per default, wherein 16 digit precision is reached in all calculations. Additionally, you may use *double precision* real numbers (*data type* 11), allowing for 34 digits instead of 16 (see below).

☞ Matrix commands will not work with *DP* real numbers.

☞ *DP* allows for more precise calculations. While some computations will reach high accuracy, **we do not warrant 34 digit precision in all calculations with *DP* real numbers.** [44]

---

[44] Not all functions are expanded to *DP*, some stay in *single precision* or merely a little bit more.

The *WP 43S* software is based on the decNumber library supporting arbitrary precision *BCD* numbers. As mentioned at some places in the *IOP*, internal computations are carried out with 39 digits. Actually this is the minimum; some modulo calculations are performed with a few hundreds of digits to avoid cancellation (e.g. 2π features 451 digits for proper reduction to the standard range for trigonometric functions).

More elaborate algorithms are coded as *DP* keystroke programs to save flash space (for the cost of execution speed and the loss of a few digits of accuracy in *DP* mode). The internal formats used for storing numbers in your *WP 43S* (as shown just above for *single precision* and below for *DP*) need to be converted back and forth from and to the decNumber format. This is a lot of overhead and doesn't come for free in terms of execution speed.

There is a quasi standard to find out about processors and test accuracy of calculators to some extent – compute $arcsin\{arccos[arctan(tan\{cos[sin(9°)]\})]\}$. An ideal calculator would return exactly 9 without cheating. Real calculators (all computing with a finite number of digits) differ. Your *WP 43s* returns

- 9,000 000 000 029 361 = 9 + 3·10^{-11} for a *single precision* and
- 8,999 999 999 999 999 999 999 999 999 937 535 = 9 – 6·10^{-29} for a *DP* argument.

If you are interested in the results of other calculators in that test, too, look at *http://www.rskey.org/~mwsebastian/miscprj/results.htm*.
Another simple test discussed recently in the internet: Enter 1,000 000 1 and then execute x^2 just 27 times. Your *WP 43s* returns

- 674 530,470 539 687 4 for a *single precision* and
- 674 530,470 741 084 559 382 689 1*84 727 772 2* for a *DP* argument.

DP real numbers are stored coarsely following *decimal128* packed coding, though with some exceptions. The lowest 110 bits take the rightmost 33 digits of the *significand*. Going left, a 12 bit exponent field follows, then 5 bits used and coded exactly as in *single precision*, and finally the sign bit. The maximum absolute value of the stored exponent is $10\ 1111\ 1111\ 1111_2 = 12287_{10}$. For reasons as explained on pp. 154ff, 6176 must be subtracted from this value to get the true exponent of the floating point number represented. Thus, *data type* 11 supports 34-digit numbers within $10^{-6143} \leq |x| < 10^{+6145}$. Coding works in full analogy to the way described for *single precision* in previous chapter.

Even smaller numbers may be entered using a decimal mantissa, but you will lose one digit per factor of 10. The same happens if you divide 10^{-6143} by 10 several times. At 10^{-6176}, only one digit will be left, stored as hexadecimal 1. Divide it by 1.999 999 999 99 and the result will remain $10^{-6176.}$ Divide it by 2 instead and the result will become zero.

Full precision of a *DP* number x may be displayed by SHOW as a *temporary message* in small font. SHOW lives in X.FN. Remember not every number may be true to 34 digits. And errors accumulate as explained in the footnote on p. **Fehler! Textmarke nicht definiert.**.

Returning to *single precision* via →SP with input exceeding the *single precision* number range explained on pp. 154ff will cause 0 or ∞ being displayed instead.

As mentioned above, some calculations are executed in "*internal high precision*" even for *single precision* arguments. "*Internal high precision*" means even more digits than *DP* – it may go up to some hundred digits in special cases.

☞ Rounding mode settings (see RM) may affect the results of such calculations!

The latter is the most precise result known of a pocket calculator so far. Nevertheless, its last 9 digits deviate from the truth here. Take these results into account when assessing small systematic deviations or many decimals.

APPENDIX C: MESSAGES AND ERROR CODES

There are some commands generating *temporary information*, e.g. CORR, DAY, ERR, L.R., MSG, RBR, s, STATUS, VERS, WDAY, $\bar{x}$, $\hat{y}$, Σ+, Σ−, σ, →POL, →REC, and the binary test commands. Also three constants will return such information when called (see pp. 118ff).

Furthermore, there are a number of error messages issued by the system. Depending on conditions, the following messages will be displayed (EC means *error code*):

	EC	Explanations, countermeasures and examples
An argument exceeds the function domain	1	{1, 2, 3} An argument exceeds the domain of the mathematical function called. May be caused by roots of negative numbers or logs of $x \le 0$ (unless CPXRES is set), by $0/0$, $\Gamma(0)$, $\tan(90°)$ and equivalents, by $\operatorname{artanh}(x)$ for $\lvert \mathrm{Re}(x) \rvert \ge 1$, by $\operatorname{arcosh}(x)$ for $\mathrm{Re}(x) < 1$, etc.[45]
Bad time or date input	2	{2, 6} Invalid date format or incorrect *date* or time in input, e.g. month >12, day >31. Will be thrown as soon as the input is closed.
Cannot delete a predefined item	27	Self-explanatory.
Distribution parameter out of valid range	16	{1, 2} A parameter specified in **I**, **J**, or **K** is out of valid range for the distribution function called (e.g. if LGNRM is called with $j < 0$).
Flash memory is full	23	Delete a program from *FM* to regain space.
Flash memory is write protected	19	Attempt to edit or delete program steps in *FM*. See PRCL and PSTO.

[45] Note that e.g. tan(90°) and logs of 0 are legal if *flag* **D** is set. See the end of this appendix.

	EC	Explanations, countermeasures and examples
Illegal digit in integer input for this base	9	{10} E.g. 2 in binary or 9 in octal input. Will be thrown as soon as the respective base is entered (i.e. as soon as input is closed).
Illegal input data type for this operation	24	… called. Convert what is necessary. Cf. "*operation is undefined in this mode*".
Input is too long	10	Keyboard input is too long for the buffer. Will happen e.g. if you try to enter more than 21 digits (derzeit passiert da nichts, wird einfach gekürzt).
Invalid or corrupted data	18	Set when there is a checksum error either in *FM* or as part of a serial download. Also set if a *FM* segment is otherwise not usable.
I/O error	17	See *Section 3* of the *OM*.
Matrix mismatch	21	{8, 9} • A matrix isn't square although it should be. • Matrix sizes aren't miscible.
No root found	20	{2} The *Solver* did not converge.
No such function	7	... calling a nonexistent function via XEQ α ... ENTER↑ (check for typos!) or running a routine containing a nonprogrammable command.
No such label found	6	Attempt to address an undefined label.
Operation is undefined in this mode	13	Caused e.g. by calling a real operation in *AIM*. Cf. "*illegal input data type for this operation*".

	EC	Explanations, countermeasures and examples
Out of range	8	{1, 2, 3} • A number exceeds the valid range. This can be caused by specifying decimals > 16, *word size* > 64, negative *flag* numbers, integers ≥ 2^{64}, *hours* or *degrees* > 9 000, invalid *dates* or *times*, denominators ≥ 9 999, etc. • A *register* or *flag* address exceeds the valid range of currently allocated *registers* or *flags*. May also happen in indirect addressing or when calling nonexistent local addresses. • An R-operation (e.g. R-COPY) attempts accessing invalid *register* addresses.
Overflow at +∞	4	{1, 2, 3, 8, 9, 11, 12} • Division of a number >0 by zero. • Divergent sum or product or integral. • Positive overflow (see *Section 2* of the *OM*).
Overflow at -∞	5	{1, 2, 3, 8, 9, 11, 12} • Division of a number <0 by zero. • Divergent sum or product or integral. • Negative overflow (see *Section 2* of the *OM*). • Logarithm of (+)0 (note a logarithm of −0 returns NaN).
Please enter a NEW name	26	Trying to define a new variable or user *menu* with a name already in use.
RAM is full	11	May be caused by attempts to write too large routines, allocate too many variables, and the like (see p. 152 for the space required by different *data types*). May happen also in program execution due to dynamic allocations (see *Section 3* of the *OM*).

	EC	Explanations, countermeasures and examples
Singular matrix	22	{8, 9} • Attempt to use a LU decomposed matrix for solving a system of equations. • Attempt to invert a matrix which isn't of full rank.
Stack clash	12	STOS or RCLS attempts using *registers* that would overlap the *stack* (see *Section 1* of the *OM*). Will happen with e.g. SSIZE8 and STOS **94** .
Too few data points for this statistic	15	{2} A statistical calculation was attempted with too few data, e.g. *regression* or *standard deviation* for less than 2 points.
Undefined op-code	3	An instruction with an undefined operation code occurred. Should never happen – but who knows?
Word size is too small	14	{10} Input or *register* content is too great to be handled by the *word* size currently set.
	25	Left unused for *WP 34S* compatibility

Each error message is *temporary information* (see *Sect. 2* of the *OM*), so ← or EXIT will erase it and allow continuation. Any other key pressed will erase the message as well, but will also execute with the *stack* contents present. Thus, another easy and safe return to the display shown before the error occurred is pressing an arbitrary *prefix* twice.

A final note about *flag* **D**: If it is set, errors 4 and 5 will not occur at all, and error 1 will happen less frequently, since ±∞ and NaN are legal results then (see the corresponding entries in CNST on pp. 118ff). E.g., 0 ln will return −∞.

APPENDIX D: DISPLAY INTERNALS

Segmentation

The *LCD* of your *WP 43S* is full dot matrix: 400 px wide and 240 high. Each pixel is 0.147 *mm* square. Going top down, you will find

- 20 px for the *status bar*,
- 4 blank rows for separation,
- 147 px for either
  a) the contents of up to 4 *stack registers*, or
  b) 7 program steps in *PEM*, and
- 69 px maximum for the *menu section*.

The reasons for these figures are as follows:

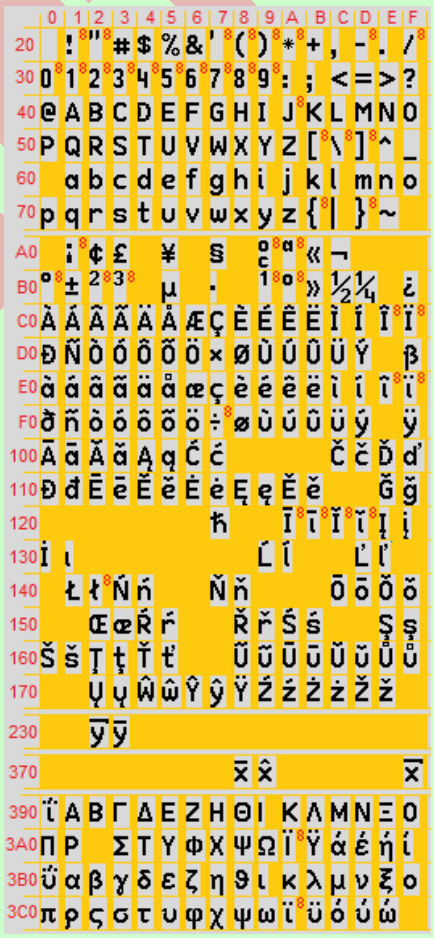
- Each regular alphanumeric row (e.g. labels or status or program steps) requires 20 px vertically (cf. pp. 165f). There shall be at least 1 pixel separating it from the next row.
- Hence, each *menu* row takes (counting bottom-up) 1 + 20 + 1 + 1 = 23 px (the first pixel is for the distance to the black frame, the latter for its upper frame line). Thus, three *menu* rows require 69 px. In U→, extra-large labels may appear (cf. p. 126): they will require 1 + 20 + 1 + 20 + 1 + 1 = 44 px for double height or 1 + 20 + 1 + 20 + 1 + 20 + 1 + 1 = 65 px for triple height then.
- At top of the *LCD*, the *status bar* takes another 20 px plus 4 for separation. Thus, 240 – 69 – 24 = 147 px minimum remain.
- Each regular numeric output requires 32 px vertically (cf. pp. 167f) plus 5 px separating it from the next such row. Thus, for four rows we need 4 × 32 + 3 × 5 = 143 px. We put the remaining 4 px below this output block.
- On the other hand, 147 = 7 × 21 corresponds to a block of 7 alpha-numeric program rows.
- If there will be more space left, we will put it below this block. This is for clear separation from the *menu section* and avoiding vertical output jitter.

In the *menu section*, we also have a horizontal structure for the six *softkeys*. We start one pixel off the black frame at left display edge. On the right edge, the characters themselves contain at least one blank column. A minimum of two pixels separate *softkey* labels from each other (one black and one blank). This way we lose a total of 1 + 5 × 2 px. The remaining 389 px mean a width of 65 available for 6 *softkey* labels, corresponding to six standard width letters (though letters may extend from 4 to 14 px in small font) which should be centered as good as possible. Note that labels in *menu views* may be not fully displayed if they are wider than 64 px, so labels deviating only in their very last characters may become visually indistinguishable.

Character Sets

The table at right and overleaf shows the entire small font of alphanumeric characters as designed and implemented, sorted according to their hexadecimal character codes (most of them following Unicode). Characters with codes < 20_{16} are for control purposes; some of them (4, 10_{10}, 27_{10}) may be useful for printer control (e.g. of *HP 82240 A/B*).

All the characters of this font live in a matrix of up to 14 × 20 px (variable width, fixed height). Standard characters start at column one and feature two empty pixel columns at their right side. There are exceptions, however: see e.g. the multiplication dot at $B7_{16}$ and the roots in row 2210_{16}. All characters marked with an **8** are as wide as digits – they will help where constant character spacing is wanted.



Eight blank characters are provided and listed with their hexadecimal addresses and their widths below. Using them, any spacing is feasible:

	Character code	Width in px
Standard space	20_{16}	10
m space	2003_{16}	12
m/3 space	2004_{16}	4
m/4 space	2005_{16}	3
m/6 space	2006_{16}	2
Figure space	2007_{16}	8
Punctuation sp.	2008_{16}	4
Hair space	$200A_{16}$	1

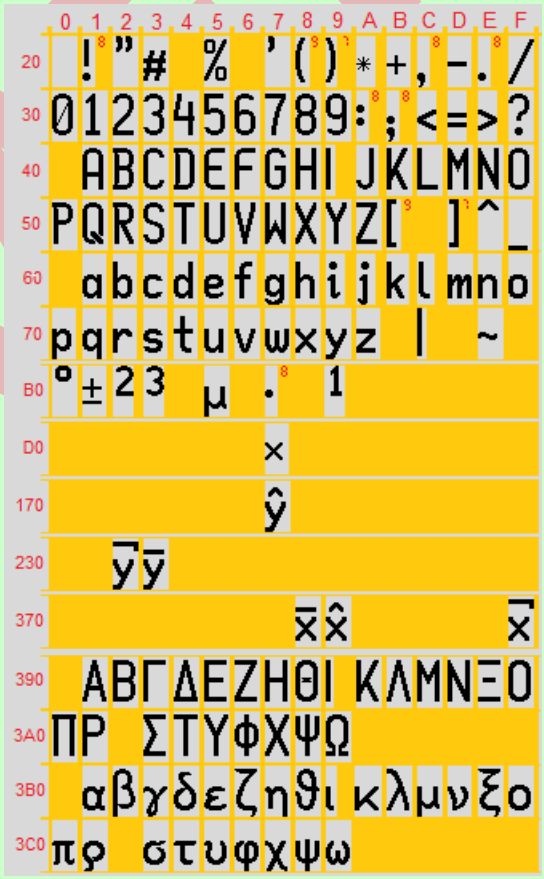
There is a number of super- and subscripts provided. They allow for displaying all the *items* featured on the *WP 43S*. Arbitrary numeric indices or exponents are possible as well.[46]

This character set allows for correctly spelling the languages of more than 3.5×10^9 people using either Greek or Latin alphabets, i.e. the following languages:

[46] Some characters shown in the table are not found in any *menu* of your *WP 43S*. They are not required for any *item* provided so far and may be for future use.

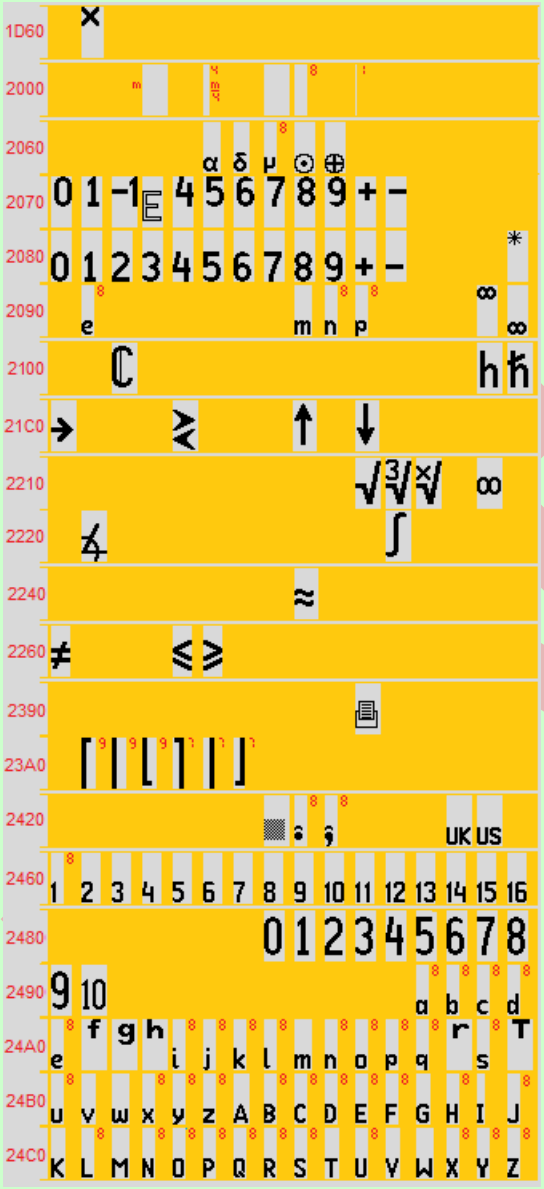
Afrikaans, Aymara, Bahasa Indonesia, Bahasa Melayu, Basa Jawa, Basa Sunda, Bosanski, Català, Cebuano, Česky, Cymraeg, Dansk, Deutsch, Eesti, Ελληνικά, English, Español, Euskara, Français, Gaeilge, Galego, Hrvatski, Italiano, Kiswahili, Kreyòl, Kurdî, Lietuvių, Magyar, Malagasy, Nāhuatl, Nederlands, Nihongo (Rōmanji), Norsk, Ŏzbek tili, Polskì, Português, Quechua, Română, Shqip, Slovenščina, Slovensky, Srpski, Suomi, Svenska, Tagalog, Tatarça, Türkçe, Türkmençe, and Zhōngwén (hànyŭ pīnyīn).

This makes the WP 43S the most versatile calculator available worldwide. If you know of further living languages covered (with one million speakers or more), please tell us.



For standard numeric output and command input echoing in the rows covering the *stack registers*, there is a larger character font provided. It is shown here in the same scale as the small font above. This large font uses a matrix of up to 16 × 32 px (variable width, fixed height again). Therein, the punctuation space (2008_{16}) is employed for separating groups of digits in longer numbers – so we follow ISO 31 for an unambiguous numeric display. The set of blank characters provided (being 16, 8, 4 and 1 px wide) allows for any spacing wanted.

Most of the elevated characters are for exponents and for numerators of fractions;



the digits below are for denominators. Please see at left.

Numeric indices are for indicating integer bases. Non-numeric indices are mainly provided for CNST.

Narrow digits can be used in complex numbers or in matrices or in finite integers of small base where space is scarce (see *App. K*).

Turn to the *OM* for examples where these characters are used. See here some sample strings in either font, approximately to a common realistic scale again:

$-1.602\,22\times10^{-19}$ $-1{,}602\,22\cdot10^{-19}$

$-1.602\,22\times10^{-19}$ As $-1{,}602\,22\cdot10^{-19}$ As


WP 345
RPN SCIENTIFIC
HEWLETT PACKARD
425
RPN SCIENTIFIC
812.6000
ENTER
EXIT
ON
HEWLETT-PACKARD

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APPENDIX E: COMPARISON TO THE FUNCTION SETS OF *HP-42S*, *HP-16C*, *HP-21S*, AND *WP 34S*

In the *IOI*, the corresponding functions of vintage *HP* calculators were mentioned under the respective entry of your *WP 43S*. The tables below revert this in a way. The first table shows the functions of the *HP-42S* and the corresponding ones of your *WP 43S* unless they carry identical names and are either both keyboard accessible or both stored in a *catalog* or *menu*. There is an analog table for *HP-16C* functions starting on p. 176, one for the *HP-21S* on p. 178, and another one for the *WP 34S* on p. 180.

Functional differences of homonymous commands are covered in the *IOI* (on pp. 12ff)**.**

Corresponding Operations on *HP-42S*

Remarks printed on light grey indicate commands being either default settings or keyboard accessible on your *WP 43S* while you must use a *menu* on the *HP-42S*.

HP-42S	*WP 43S*	Remarks
ACOS	**arccos**	In TRI
ACOSH	**arcosh**	In EXP
ADV	🖶**ADV**	In I/O
AIP	Superfluous	You can easily merge text and numeric data as described in *Section 2* of the *OM*.
ALENG	**αLENG**	In α.FN
ALLΣ	Superfluous	Your *WP 43S* runs in ALLΣ mode always.
ALPHA	α	See the description of *AIM* in *Sect. 2* of the *OM*.
AOFF	**αOFF**	In α.FN
AON	**αON**	

HP-42S	*WP 43S*	**Remarks**
ARCL	Superfluous	You can easily merge text and numeric data as described in *Section 2* of the *OM*.
AROT	**αRL** or **αRR**	In α.FN
ASHF	**αSL**	
ASIN	**arcsin**	In TRI
ASINH	**arsinh**	In EXP
ASTO	Superfluous	Any *register* or variable can take an *alpha string*. Simply press STO instead.
ATAN	**arctan**	In TRI
ATANH	**artanh**	In EXP
ATOX	**α→x**	In α.FN
AVIEW	Superfluous	Any *register* or variable can take an *alpha string*. Simply press VIEW instead.
BASE	INTS or BITS	
BASE+	Superfluous	Your *WP 43S* executes these arithmetic commands automatically for integer inputs.
BASE−		
BASE×		
BASE÷		
BASE+/−		
BINM	Superfluous	Press # 2 for converting any closed integer number or integer part in *x* to binary.
BIT?	**BS?**	In BITS
BST	(▲)	Shortcut works if no *multi-view menu* is open.
CLA	**0** STO K	
CLD	Superfluous	Any keystroke will clear *temporary information*.
CLEAR	CLR	
CLKEYS	n/a	See *Section 6* of the *OM*.
CLRG	**CLREGS**	In CLR
CLST	**CLSTK**	Press 0 FILL in run mode.

HP-42S	*WP 43S*	**Remarks**
CLV	See remark	Variables are cleared as specified in *Section 6* of the *OM.*
COMPLEX	CC	You can enter complex numbers directly as well as explained in *Section 2* of the *OM*.
CONVERT	L→ & PARTS	
CUSTOM	n/a	You can create as many *menus* as memory will hold – not just one CUSTOM *menu*. See *Section 6* of the *OM*.
DECM	Superfluous	Any input featuring a . or an E is interpreted as a real (decimal) number.
DEL	n/a	Not featured. Too dangerous, in our opinion.
DELAY	DLAY	In I/O
DELR	M.DELR	In MATX
DET	|M|	
DIM	M.DIM	
DIM?	M.DIM?	
DISP	DISP	DSP is on the keyboard.
EDIT	M.EDI	In MATX
EDITN	M.EDIN	
FCSTX	x̂	In STAT
FCSTY	ŷ	
FLAGS	FLAGS	
FNRM	ENORM	In MATX. Euclid is older than Frobenius.
GAMMA	Γ(x)	In PROB
GETKEY	KEY?	In P.FN
GETM	M.GET	In MATX
GROW	M.GROW	
HEXM	Superfluous	Press # H for converting any closed integer number or integer part in *x* to hexadecimal.

HP-42S	*WP 43S*	**Remarks**
H.MS+	Superfluous	Your *WP 43S* executes these arithmetic commands automatically if sexagesimal times are in x and y and [+] or [−] is pressed, respectively.
H.MS−		
INSR	M.INSR	In MATX
INTEG	∫	In ADV
INVRT	[M]$^{-1}$	In MATX
KEYASN	Superfluous	Not needed since no CUSTOM *menu* is featured (see CUSTOM).
LASTx	RCL L	
LBL		Press LBL.
LCLBL	Superfluous	Obsolete since no CUSTOM *menu* is featured (see CUSTOM). Nevertheless, your *WP 43S* provides local labels (cf. *Section 3* of the *OM*).
LINΣ	Superfluous	Your *WP 43S* runs in ALLΣ mode always. Since statistical *registers* are separate from general purpose *registers*, there is no benefit in saving statistical *registers*.
LIST	n/a	Use PROG instead.
LOG	LOG_{10}	Press lg.
MAN	CF T	Manual print mode is *startup default* on your *WP 43S*.
MAT?	MATR?	In TEST
MEAN	$\bar{x}$	In STAT
MODES	MODE	
N!	x!	Press x!.
NEWMAT	M.NEW	In MATX
NORM	n/a	Not featured.
OCTM	Superfluous	Press # 8 for converting any closed integer number or integer part in x to octal.
OLD	M.OLD	In MATX

HP-42S	*WP 43S*	**Remarks**
ON	n/a	Programmable ON is not featured.
PGM.FCN	P.FN	GTO, RTN, and VIEW are on the keyboard.
PI	π	Press π.
POSA	αPOS	In α.FN
PRA	🖶r K	In I/O
PRGM	P/R	
PRINT	I/O	PRx is on the keyboard.
PRLCD	🖶LCD	In I/O
PROFF	CF T	
PROMPT	Superfluous	Use VIEW, STOP instead.
PRON	SF T	
PRP	🖶PROG	In I/O
PRSTK	🖶STK	
PRUSR	🖶USER	
PRV	🖶r	
PRX	🖶r X	Press 🖶x.
PRΣ	🖶Σ	In I/O
PUTM	M.PUT	In MATX
PWRF	PowerF	In STAT
RAN	RAN#	In PROB
RND	ROUND	In PARTS
RNRM	RNORM	In MATX
ROTXY	RL, RLC, RR, and RRC	In BITS
RTN		Press RTN.
SDEV	s	In STAT
SHOW	Superfluous	Displaying up to 16 digits in SCI should suffice.

HP-42S	*WP 43S*	**Remarks**
SIZE	Superfluous	There are 100 global general purpose *registers* always.
SLOPE	L.R.	In STAT
SOLVE	SLV	In ADV
SQRT	$\sqrt{x}$	
SST	▼ (▼)	Shortcut works if no *multi-view menu* is open.
STR?	STRI?	In TEST
TOP.FCN	Superfluous	Obsolete since no top functions are overwritten.
TRACE	SF T	
TRANS	[M]^T	In MATX
UVEC	UNITV	In MATX and CPX
VARMENU	VARMNU	Truncated to 6 characters to fit the *menu* space.
VIEW		Press VIEW.
WMEAN	$\bar{x}_w$	In STAT
WRAP	M.WRAP	In MATX
XTOA	x→α	The conversion is done in **X**.
X<>		Press x<>.
X<0?, X<Y?	x< ?	In TEST
X≤0?, X≤Y?	x≤ ?	
X=0?, X=Y?	x= ?	
X≠0?, X≠Y?	x≠ ?	
X≥0?, X≥Y?	x≥ ?	
X>0?, X>Y?	x> ?	
YINT	L.R.	In STAT
y^x		Press y^x.
ΣREG	Superfluous	There are 100 global general purpose *registers* always.
ΣREG?		

HP-42S	*WP 43S*	**Remarks**
→DEC	→INT 10	Press # 10 or # D ... for closed input.
→HR		Press .d
→H.MS		Press h.ms
→OCT	→INT 8	Press # 8
→POL		Press →P.
→REC		Press R←.
%CH	Δ%	Press Δ%.

Corresponding Operations on *HP-16C*

The table for the functions of the *HP-16C* is sorted following their appearance on its keyboard, starting top left. As for the *HP-42S*, only functions carrying different names on both calculators are listed.

HP-16C	*WP 43S*	**Remarks**
RL , RLn	RL	In BITS
RR , RRn	RR	
RLC , RLCn	RLC	
RRC , RRCn	RRC	
DBL÷	DBL/	In INTS
x≥(i)	Superfluous	Any *register* may be used for indirection.
x≥I		
SHOW HEX	n/a	
SHOW DEC		
SHOW OCT		
SHOW BIN		
B?	BS?	In BITS
GSB	XEQ	

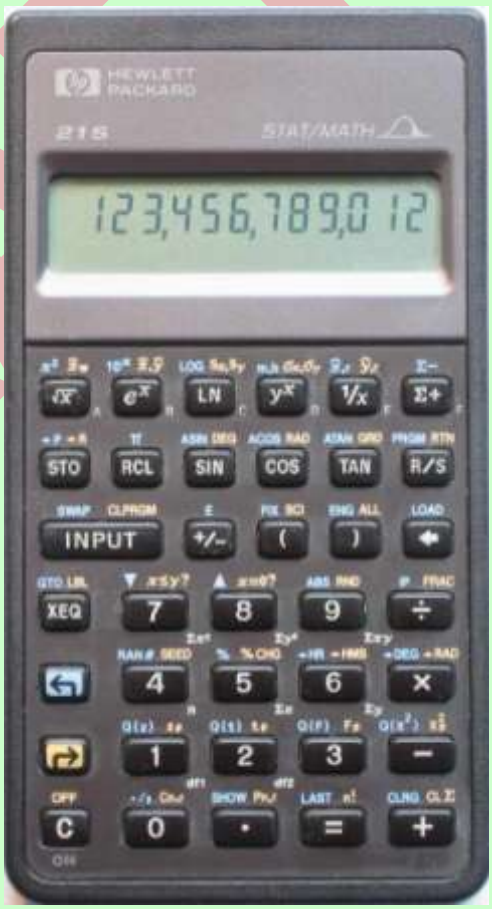
HP-16C	*WP 43S*	**Remarks**
HEX	# H	
DEC	# D	
OCT	# 8	
BIN	# 2	
SF 3 , CF 3	LZON, LZOFF	In DISPL. Control display of leading zeros.
SF 4 , CF 4	SF C , CF C	*Carry*. SF and CF live in FLAGS.
SF 5 , CF 5	SF B , CF B	*Overflow*.
F?	FS?	In FLAGS
(i)	Superfluous	Any *register* may be used for indirection.
I		
CLEAR PRGM	CLP	In CLR. Note here is also CLPALL.
CLEAR REG	CLREGS	In CLR
CLEAR PREFIX	Superfluous	See *Section 2* of the *OM*.
WINDOW	Superfluous	64 *bits* can be displayed in one row.
SET COMPL 1S	1COMPL	In INTS. Note here is also SIGNMT.
SET COMPL 2S	2COMPL	
SET COMPL UNSGN	UNSIGN	
SST	▼ (▼)	▼ works if no *multi-view menu* is open.
BSP	←	
BST	▲ (▲)	▲ works if no *multi-view menu* is open.
x≤y	x≤ ?	In TEST. Note more tests are covered here.
x<0	x< ?	
x>y	x> ?	
x>0		
FLOAT	FIX	In DISP
MEM	STATUS	In FLAGS
CHS	+/-	

HP-16C	*WP 43S*	**Remarks**
◀	Superfluous	64 *bits* can be displayed in one row.
▶		
LSTX	RCL L	
x≠y	x≠ ?	In TEST. Note more tests are covered here.
x≠0		
x=y	x= ?	
x=0		

Corresponding Operations on *HP-21S*

The table for the functions of *HP-21S* (starting overleaf) follows the same rules as the one for *HP-16C*. The *HP-21S*, however, is an algebraic calculator; hence its keys INPUT, (,), and = have no direct equivalent on your *WP 43S*.

Consult the *HP-21S OM* for additional information about the four most important continuous statistical distributions and their applications.



HP-21S	*WP 43S*	**Remarks**
$\bar{x}_w$	$\bar{x}_w$	In STAT
$\bar{x},\bar{y}$	$\bar{x}$	
s_x,s_y	s	
m,b	L.R.	
σ_x,σ_y	σ	
$\hat{x},r$	r, $\hat{x}$	
$\hat{y},r$	r, $\hat{y}$	
PRGM	P/R	
SWAP	x⇄y	
CLPRGM	CLP	In CLR
LOAD	n/a	Loads predefined programs in the *HP-21S*. Also your *WP 43S* features a command called LOAD but this recalls data from backup.
ABS	|x|	In PARTS
RND	ROUND	
FRAC	FP	
SEED	SEED	In PROB
%CHG	Δ%	
Q(z)	$\Phi_u(x)$	In *submenus* of PROB. Note the implementation of inverse distribution functions deviates on both calculators: your *WP 43S* calculates with the probability *P* while the *HP-21S* calculates with the error probability *Q* = 1 – *P* as input (cf. the *OM*, *Section 2*). Labeling these functions on the *HP-21S* using the letter *p* may add some confusion.
z_p	$\Phi^{-1}(p)$	
Q(t)	$t_u(x)$	
t_p	$t^{-1}(p)$	
Q(F)	$F_u(x)$	
F_p	$F^{-1}(p)$	
$Q(\chi^2)$	$\chi^2{}_u(x)$	
χ^2_p	$(\chi^2)^{-1}$	
Cn,r	COMB	In PROB
SHOW	Superfluous	A standard display of up to 16 digits should suffice.

HP-21S	*WP 43S*	**Remarks**
Pn,r	PERM	In PROB
LAST	RCL L	
n!	x!	
CLRG	CLREGS	In CLR

Corresponding Operations on *WP 34S*

The *WP 34S* and your *WP 43S* share over 90% of their function sets. Most of the discrepancies are caused by their different displays and by your *WP 43S* supporting various *data types*. As demonstrated above, it also features *softkeys* – the *WP 34S* can only carry four *hotkeys* instead for hardware reasons. Also dealing with matrices is greatly eased by the large high resolution dot matrix display of your *WP 43S*; thus some of the elementary matrix commands of the *WP 34S* are not required anymore by your *WP 43S*.

Remarks printed on light grey indicate commands being either default settings or obsolete on your *WP 43S* while you must use them on the *WP 34S*.

WP 34S	*WP 43S*	**Remarks**
ANGLE	∡	
CLα	0 STO K	Check the *OM* for the conditions when this register is used.
CONST	CNST	For keyboard space reasons.
DBLOFF	Superfluous	Your *WP 43S* features *DP data types* – it does neither need nor feature a *DP* mode. Use →DP to convert individual data to *DP*; use →SP to reconvert real *DP* data to default precision.
DBLON		
DET	|M|	
dRCL	Superfluous	Your *WP 43S* features various *data types*.

WP 34S	*WP 43S*	**Remarks**
gCLR, gDIM, gDIM?, gFLP, gPIX?, gPLOT, gSET	n/a	The *LCD* of your *WP 43S* features 240 pixel rows compared with 6 rows of *HP-30b* – the graphic paradigm of *WP 34S* makes no sense on your *WP 43S* anymore. On the other hand, it was not our objective to design a graphing calculator. Thus, we include just the basic graphic support of the *HP-42S* (AGRAPH, CLLCD, and PIXEL) plus POINT.
GTOα	Superfluous	Use GTO with an appropriate parameter instead.
H.MS+, H.MS−	Superfluous	Your *WP 43S* features a dedicated *data type* for *times*, so + and − suffice for adding or subtracting sexagesimal times, respectively.
INTM?	Superfluous	Your *WP 43S* features dedicated *data types* for integers – it does neither need nor feature an integer mode.
iRCL	Superfluous	Your *WP 43S* features various *data types*.
I_x	I_{xyz}	This is a triadic function after all.
MROW+×, MROW×	Superfluous	Obsolete matrix commands.
MROW⇆	M.R⇄R	
M+×	Superfluous	Obsolete matrix command.
M^{-1}	$[M]^{-1}$	
M-ALL, M-COL, M-DIAG, M-ROW	Superfluous	Obsolete matrix commands.
M×	Superfluous	Your *WP 43S* features two dedicated *data types* for matrices. Thus you can simply multiply two matrices using × and copy matrices like any other objects.
M.COPY		
M.IJ, M.REG	Superfluous	Obsolete matrix commands.
nBITS	#B	

WP 34S	*WP 43S*	**Remarks**
nCOL, nROW	Superfluous	Obsolete matrix commands.
REALM?	Superfluous	Your *WP 43S* features a dedicated *data type* for real numbers – it does neither need nor feature a real mode.
REGS, REGS?	Superfluous	The number of global general purpose *registers* is fixed to 100 on your *WP 43S.*
SENDA, SENDP, SENDR, SENDΣ	**SEND**	SEND combines all those four commands of the *WP 34S*.
SEPOFF, SEPON	**GAP**	
SHOW	**RBR**	
sRCL	Superfluous	Your *WP 43S* features various *data types*.
TRANSP	**[M]^T**	
TSOFF	**GAP** 0	
TSON	**GAP** 3	
VIEWα, VWα+	Superfluous	Simply use VIEW instead; alpha strings are just another *data type*. You can combine text and numeric data easily using + as shown in *Sect. 2* of the *OM.*
XEQα	Superfluous	Use XEQ with an appropriate parameter instead.
XTAL?	Superfluous	A quartz crystal is installed by default.
YDOFF, YDON	Superfluous	Your *WP 43S* displays y whenever possible and wanted.
αDATE, αDAY	Superfluous	You can combine text and numeric data easily using + as shown in *Section 2* of the *OM.*
αGTO	Superfluous	Use GTO with an appropriate parameter instead.
αIP, αMONTH	Superfluous	You can combine text and numeric data easily using + as shown in *Section 2* of the *OM.*

WP 34S	*WP 43S*	**Remarks**
αRCL, αRC#	Superfluous	Your *WP 43S* features various *data types* and 'knows' which type is in the *register* specified. Appending *alpha strings* is done by [+].
αSR	n/a	Deleted since found pointless.
αSTO	Superfluous	Any *register* can take an *alpha string*. Simply press [STO] instead.
αTIME	Superfluous	You can combine text and numeric data easily using [+] as shown in *Section 2* of the *OM.*
αXEQ	Superfluous	Use [XEQ] with an appropriate parameter instead.
β	β(x,y)	
Γ	Γ(x)	
ΔDAYS	Superfluous	Simply subtract two *dates*.
ζ	ζ(x)	
→H	→HR	
🖶PLOT	n/a	See gCLR.
🖶$^{C}r_{XY}$	Superfluous	Use 🖶r instead. [🖶x] is on the keyboard.
🖶α, 🖶α+, 🖶+α	Superfluous	You can combine text and numeric data easily using [+] as shown in *Section 2* of the *OM.* Then use 🖶r. [🖶x] is on the keyboard.
🖶?	Superfluous	A quartz crystal and the proper firmware for printing are installed by default.

New Commands on your *WP 43S*

The following table lists the commands and pseudo-commands created for your *WP 43S* (and for preceding *WP* calculators, if applicable), offering new or extended functionality compared to earlier *HP RPN* and algebraic pocket calculators. In total, these are more than 340 operations, excluding the unit conversions provided. The commands are printed below as spelled on your *WP 43S*.

Command	*WP 43S*	*WP 31S*	*WP 34S*
2^x AGM	●	—	new
ALL	●	●	extended
AND ASR NOT OR XOR	●	—	extended
BACK CASE SKIP	●	—	new
BATT?	●	●	new
BC? FB	●	—	new
Binom $Binom_p$ (of *Binomial distribution*)	●	●	new
B_n B_n^* CEIL FLOOR	●	—	new
Cauch $Cauch_p$ $Cauch_u$ $Cauch^{-1}$	●	●	new
CLCVAR	**new**	—	—
CLFall CLK12 CLK24 CLPall CONJ CONVG? COV	●	—	new
CPXi CPXj CX→RE RE→CX	**new**	—	—
DATE TIME	●	—	(●)
DATE→ DAY MONTH YEAR →DATE	●	—	new
DBL?	**modified**	—	new
DEC DSL INC ISE	●	—	new
DECOMP	●	●	new
DEG→ D.MS→ GRAD→ RAD→	●	—	new
DROP	●	—	new
DROPy DSTACK	**new**	—	—
D→J J→D	●	—	new
EIGVAL EIGVEC	**new**	—	—
ENGOVR SCIOVR	●	—	new
ENTRY?	●	—	new
EQ.DEL EQ.EDI EQ.NEW	**new**	—	—
erf erfc ERR MSG	●	—	new
EVEN? ODD?	●	—	new

Command	*WP 43S*	*WP 31S*	*WP 34S*
Expon $Expon_p$ $Expon_u$ $Expon^{-1}$	●	●	new
EXPT MANT	●	—	new
FAST SLOW	●	—	new
FBR	**new**	—	—
FC?F FC?S FF FS?F FS?S	●	—	new
FIB	●	—	new
FILL	●	●	new
FLASH? FP?	●	—	new
$F_p(x)$ F(x) (of *F distribution*)	●	●	new
f' f''	**new**	—	—
f'(x) f''(x)	**extended**	—	new
GAP	**extended**	●	new
GCD LCM	●	●	new
g_d g_d^{-1}	●	—	new
Geom $Geom_p$ $Geom_u$ $Geom^{-1}$	●	—	new
H_n H_{nP} L_n $L_{n\alpha}$ P_n T_n U_n	●	—	new
Hyper $Hyper_p$ $Hyper_u$ $Hyper^{-1}$	**new**	—	—
IDIV	●	—	new
IM RE	**new**	—	—
IMPFRC PROFRC	●	●	new
INT? I_{xyz} $I\Gamma_p$ $I\Gamma_q$	●	—	new
$J_y(x)$	**new**	—	—
J/G	**extended**	●	new
KEY? KTYP? LBL? LEAP?	●	—	new
LgNrm $LgNrm_p$ $LgNrm_u$ $LgNrm^{-1}$	●	—	new
LNβ LNΓ LOADP LOADR LOADSS LOADΣ LocR LocR? LOG_2 LOG_xy	●	—	new

Command	*WP 43S*	*WP 31S*	*WP 34S*
LOAD	●	●	new
Logis $Logis_p$ $Logis_u$ $Logis^{-1}$	●	●	new
max min MIRROR	●	—	new
MOD	●	●	new
MULT× MULT· MULπ MULπ→ ∢°→∢ ∢ᵍ→∢ ∢ʳ→∢ ∢π→∢ ∢″→∢	new	—	—
M.LU M.SQR? NAND NaN? NEIGHB NOR	●	—	new
NBin $NBin_p$ $NBin_u$ $NBin^{-1}$	new	—	—
NEXTP PRIME?	●	●	new
Norml $Norml_p$ $Norml_u$ $Norml^{-1}$	●	●	new
nΣ (callable by name)	●	●	new
PLOT POINT	new	—	—
PAUSE	●	—	extended
Poiss $Poiss_p$ $Poiss_u$ $Poiss^{-1}$	●	●	new
PopLR PRCL PSTO PUTK	●	—	new
RBR	●	●	new
RCLCFG STOCFG	extended	—	new
RCLS STOS	●	—	new
RCL↑ RCL↓ STO↑ STO↓	●	—	new
RDP RECV SEND	●	—	new
Re≷Im	new	—	—
RJ	●	—	new
RL RLC RR RRC	●	—	extended
RMDR	●	●	extended
RM RM? ROUNDI RSD RTN+1 R-CLR R-COPY R-SORT R-SWAP	●	—	new
SAVE	●	●	new
SDIGS? SETSIG	new	—	—

Command	***WP 43S***	*WP 31S*	*WP 34S*
SDL SDR SETCHN SETEUR SETIND SETJPN SETUK SETUSA	●	—	new
SETDAT SETTIM	●	—	(●)
SIGNMT sinc	●	—	new
SL SR	●	—	extended
SLVQ SMODE? SPEC?	●	—	new
s_{mw} s_w	●	●	new
SSIZE4 SSIZE8 SSIZE?	●	●	new
STATUS	**extended**	—	new
s_{xy}	●	—	new
TDISP	**new**	—	—
TICKS	●	—	new
TIMER	●	—	(●)
TOP? ULP?	●	—	new
$t_p(x)$ $t(x)$ (of *t distribution*)	●	●	new
$t_{\vec{x}}$ $y_{\vec{x}}$ $z_{\vec{x}}$ $_{\vec{x}}$	●	—	new
↩ (UNDO)	●	new	—
VERS? WDAY WHO?	●	●	new
Weibl $Weibl_p$ $Weibl_u$ $Weibl^{-1}$	●	●	new
W_m W_p W^{-1} WSIZE? $\bar{x}_G$ XNOR	●	—	new
x→DATE	**new**	—	—
x< ? x≤ ? x= ? x≠ ? x≥ ? x> ?	●	—	extended
x= +0? x= -0? x≈ ?	●	—	new
Y.MD	●	●	new
αLENG?	**extended**	—	●
αPOS?	**extended**	—	—
αRL αRR αSL	●	—	extended
$\beta(x,y)$ γ_{xy} Γ_{xy} ε ε_m ε_p $\zeta(x)$ Π Σ σ_w	●	—	new

Command	*WP 43S*	*WP 31S*	*WP 34S*
Σln²x Σln²y Σlnx Σlnxy Σlny Σx Σx² Σx²y Σxlny Σxy Σy Σylnx Σy² (callable by names)	●	●	new
Φ(x) φ(x) (of *Gaussian distribution*)	●	—	new
$\chi^2_p(x)$ $\chi^2(x)$ (of *chi-square distribution*)	●	●	new
(-1)^x ×MOD ^MOD	●	—	new
±∞?	**new**	—	—
→DEG →RAD	●	●	new
→DP →SP	**new**	—	—
→D.MS →MULπ	**new**	—	—
→GRAD	●	—	new
→INT →REAL	**new**	—	—
🖶ADV 🖶CHAR 🖶r 🖶REGS 🖶TAB 🖶#	●	—	(new)
🖶MODE	●	—	new
🖶WIDTH	**extended**	—	new
| |	●	●	new

The statements in parentheses in the rightmost column refer to the *WP 34S* with optional quartz and capacitors installed.

Reference Literature

As mentioned above, some advanced functionality of your *WP 43S* is taken over from previous *HP* calculators. The following vintage *HP* material is recommended as source of in-depth information (as far as calculating, programming, and applications are concerned) about the topics listed, from a calculator point of view. The manuals listed below are entirely contained in a document set distributed by the *Museum of HP Calculators* (see http://www.hpmuseum.org/cd/cddesc.htm).

Depending on your educational background and professional qualification, textbooks about various mathematical, scientific, or engineering

topics may be helpful in addition. Ensure you know enough about what you compute (and check footnote 49 on p. 205 below as well as the last paragraph on p. 16 of the *OM*).

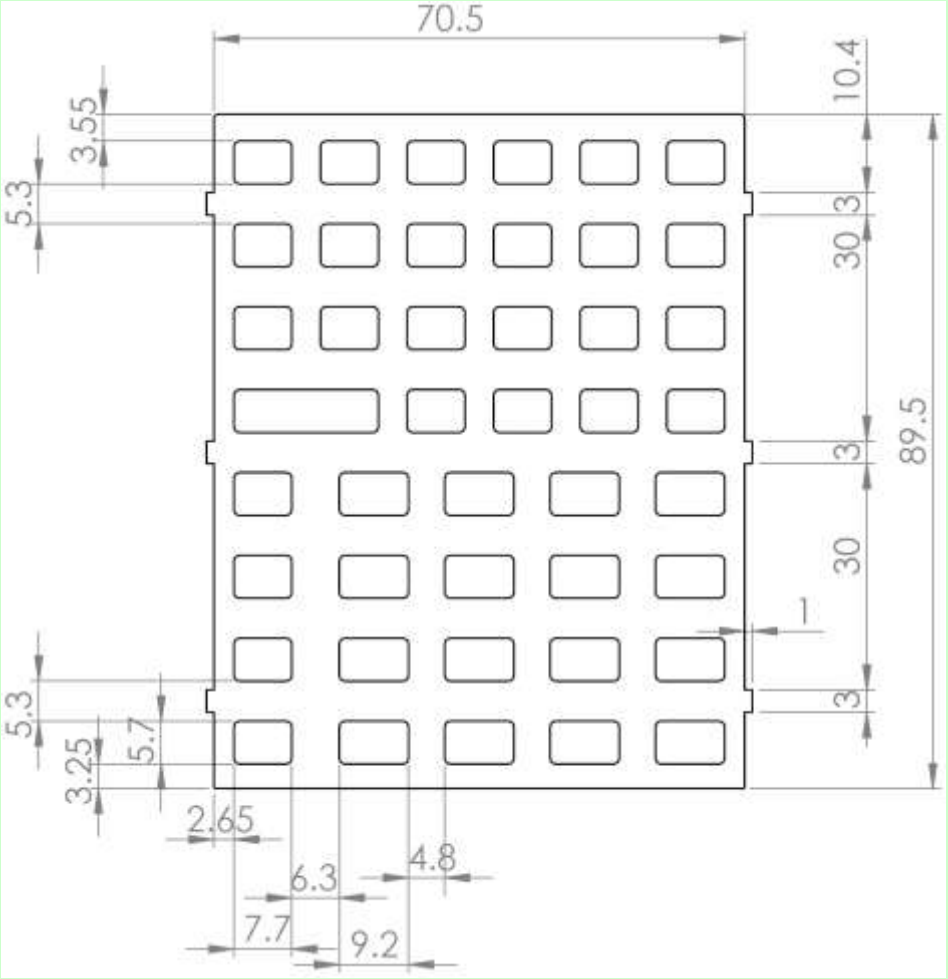
Topic	**Recommended literature**
General calculation examples and applications	All vintage *HP* calculator manuals can be recommended
Root finding and numeric integration	*HP-34C Owner's Handbook and Programming Guide* *HP-15C Owner's Handbook* *HP-15C Advanced Functions Handbook* *HP-42S Programming Examples and Techniques*
Statistical distributions and their application	*HP-21S Owner's Manual*
Financial calculations	*HP-17BII+ User's Guide*
Manipulating finite integers	*HP-16C Owner's Handbook*
Programming	*HP-42S Owner's Manual* *HP-42S Programming Examples and Techniques*

APPENDIX F: FLASHING AND UPDATING YOUR *WP 43S*

xxx

APPENDIX G: OVERLAYS

See below the drawing for an overlay – all dimensions are given in mm.
Note the overall width is 72.5 mm.



APPENDIX H: TROUBLESHOOTING GUIDE

xxx

APPENDIX I: EMULATING A *WP 43S* ON YOUR COMPUTER

Xxx

APPENDIX J: ADVANCED MATHEMATICAL FUNCTIONS AND TASKS

Your *WP 43S* contains several operations covering advanced mathematics. Most of them are taken over from *WP 34S*, some are implemented here for the first time on an *RPN* calculator. Find those functions collected here and described in more detail than in the *IOI*, together with a few traditional pocket calculator functions matching the topic.

For reasons explained in *Section 1*, we assume you are able to read and understand mathematical formulas for real domain functions.

Wherever complex numbers may be valid input or output, the command name is printed on light yellow background. Ensure you understand the respective fundamental mathematical concepts; else leave these functions aside. By experience, it is only beneficial to use something you overview and know the background of – otherwise it may even become dangerous for you and your fellow men.

Number Generating Functions

The following are all *monadic* functions except COMB and PERM.

Name	Remarks (see pp. 12ff for general information)
B_n	B_n returns the Bernoulli number for an integer ***n*** > 0 given in **X**: $B_n = (-1)^{n+1} \cdot n \cdot \zeta(1-n)$
B_n*	B_n* works with the old definition instead: $B_n^* = 2 \cdot \frac{(2n)!}{(2\pi)^{2n}} \cdot \zeta(2n)$ See p. 226 for $\zeta(x)$.

Name	Remarks (see pp. 12ff for general information)
COMB, PERM	For $y \geq x \geq 0$ and $x, y \in \mathbb{N}$, $C_{y,x} = \binom{y}{x} = \frac{y!}{x!\cdot(y-x)!}$ is the number of *combinations* and $P_{y,x} = \frac{y!}{(y-x)!} = x!\cdot C_{y,x}$ the number of *permutations* of ***x*** and ***y*** as explained in the *IOP* (see pp. 25 and 60, respectively). Note $C_{y,0} = 1$, $C_{y,1} = y$, and $C_{y,2} = \frac{1}{2}y(y-1)$. $C_{y,x}$ applies to the *binomial distribution* (see p. 196): In a *Galton box*[47] (a.k.a. *bean machine*) featuring ***y*** rows of pins and fed with 2^y balls, $C_{y,x}$ is the number of balls expected in column ***x*** of that box (start column counting with zero). $P_{y,x} = \frac{\Gamma(y+1)}{\Gamma(y-x+1)}$ and $C_{y,x} = \frac{\Gamma(y+1)}{\Gamma(x+1)\cdot\Gamma(y-x+1)}$ work also for non-integer numbers and in complex domain, too.
FIB	For integers, FIB returns the Fibonacci number f_n with ***n*** = ***x***. These numbers are defined as $f_0 = 0$, $f_1 = 1$, and $f_n = f_{n-1} + f_{n-2}$ for ***n*** ≥ *2*. With UNSIGN, f_{93} is the maximum before an overflow occurs. Else FIB returns the extended Fibonacci number $$F_x = \frac{1}{\sqrt{5}}[\Phi^x - \Phi^{-x}cos(x\pi)]$$ for an arbitrary real or complex number ***x***, with $\Phi = \frac{1+\sqrt{5}}{2}$ denoting the golden ratio.

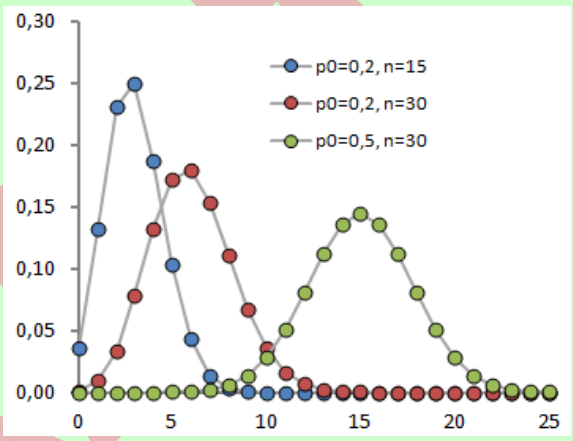
[47] Translator's note: This is called «Planche de Galton» in French, "Galtonbrett" in German, and "macchina di Galton" in Italian. Note the subtle differences in naming. Galton invented his box in 1889.

Statistical Distributions

Stack-wise, the following are all *monadic* functions, stored in PROB. Actually, they feature more parameters though. Those are supplied in the *registers* **I**, **J**, and **K** as applicable and mentioned below.

In the following text, the five discrete distributions are covered first, the continuous ones thereafter. Typical plots are shown for the *PMF*s or *PDF*s.

Binom: *Binomial distribution* with the *number of successes* ***g*** in **X**, the *gross probability of a success* $\boldsymbol{p_0}$ in **I** and the *sample size* ***n*** in **J**.



Binom$_P$ returns

$$p_B(g;n;p_0)=\binom{n}{g}\cdot p_0^g\cdot(1-p_0)^{n-g}$$

$$=C_{n,g}\cdot p_0^g\cdot(1-p_0)^{n-g}$$ (see COMB on p. 195).

Binom returns $F_B(m;n;p_0)=\sum_{g=0}^{m}p_B(g;n;p_0)$ with the maximum number of successes ***m*** in **X**.

The *binomial distribution* is fundamental for error statistics in industrial sampling, e.g. for designing test plans.

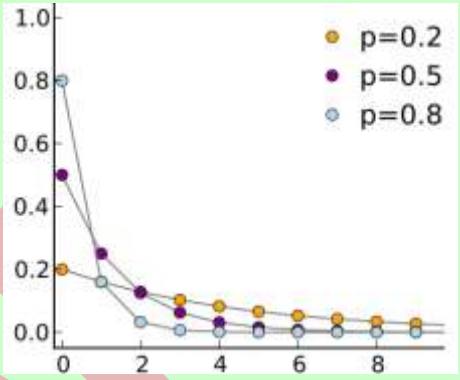
If you want to know, for example, the probability for finding no faulty items in a sample of 15 items drawn from a batch of 300 wherein you expect 3% defective items overall, this will tell you:

.03 STO J **15** STO K **0** PROB g Binom: Binom

returns 0.633 – so the odds are almost two out of three that you will not detect any defect in your sample! [48]

Read here for more information:
http://www.itl.nist.gov/div898/handbook/eda/section3/eda366i.htm .

Geom: *Geometric distribution*:



Geom$_P$ returns

$$p_{Ge}(n) = p_0(1-p_0)^n$$

Geom returns

$$F_{Ge}(m) = 1-(1-p_0)^{m+1}$$

, being the probability for a first success after ***m = x*** *Bernoulli* experiments. The probability ***p₀*** for a success in each such experiment must be specified in **I**.

Start reading here for more:
http://en.wikipedia.org/wiki/Geometric_distribution .

Hyper: *Hypergeometric distribution* with the *number of successes* ***g*** in **X**, *gross probability of a success* ***p₀*** in **I**, *sample size* ***n*** in **J**, and batch size ***n₀*** in **K**.

Hyper$_P$ returns $p_H(g;n;p_0;n_0) = \dfrac{\binom{n_0 p_0}{g} \cdot \binom{n_0(1-p_0)}{n-g}}{\binom{n_0}{n}}$ (see COMB on p. 195 for the explanation of the notation).

[48] The exact result for said probability is 0.626, calculated using the *hypergeometric distribution*. These results show nicely that two significant digits are a typical accuracy of theoretical statistical statements – frequently the (simplified) statistical model used matches reality no better than that.

While the *binomial distribution* is based on the assumption that each sample part is returned to the batch after drawing and checking, the *hypergeometric distribution* lets you keep your samples out of the batch. This is found more often in real life, but may be neglected in 'large' batches ($n_0 > 10$) and small sample sizes (<10% of n_0).

Start reading here for more:
http://en.wikipedia.org/wiki/Hypergeometric_distribution .

NBin: *Negative binomial distribution* with the *total number of failures* ***f*** (in ***n*** draws) in $\mathbf{X}$, the *gross probability of a success in a single draw* p_0 in $\mathbf{I}$, and ***n*** in $\mathbf{J}$.

NBin$_P$ returns $p_{NB}(f;n;p_0) = \binom{n-1}{f-1} \cdot p_0^f \cdot (1-p_0)^{n-f}$

$= C_{n-1,f-1} \cdot p_0^f \cdot (1-p_0)^{n-f}$ (see COMB on p. 195).

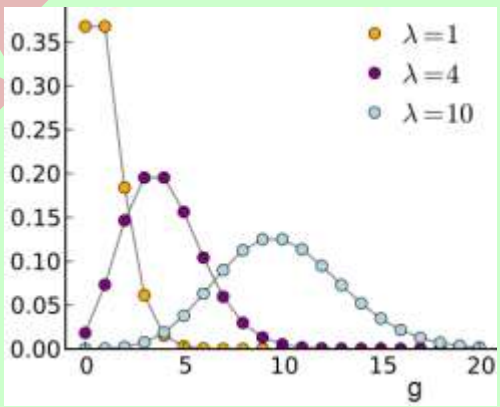
Start reading here for more:
http://en.wikipedia.org/wiki/Negative_binomial_distribution .

Poiss: *Poisson distribution* with the *number of successes* ***g*** in $\mathbf{X}$ and the *Poisson parameter* $\boldsymbol{\lambda}$ in $\mathbf{J}$.

Poiss$_P$ computes

$$p_P(g;\lambda) = \frac{\lambda^g}{g!} e^{-\lambda}$$

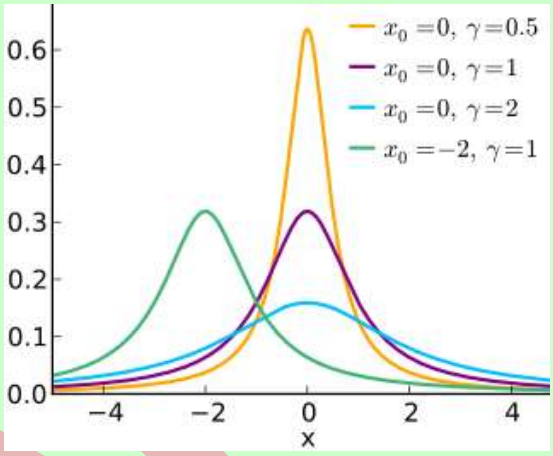
and Poiss returns the corresponding *CDF* for the maximum number of successes ***m*** in $\mathbf{X}$.



The *Poisson distribution* provides the mathematically simplest model for industrial sampling tests – use $\lambda = np_0$ with the gross error probability p_0 and the sample size ***n*** (cf. BINOM). For the example introduced with BINOM above, we get 0.638 here.

Read here for more information:
http://www.itl.nist.gov/div898/handbook/eda/section3/eda366j.htm .

Cauch: *Cauchy-Lorentz distribution* (also known as *Lorentz* or *Breit-Wigner distribution*) with the *location* x_0 specified in **I** and the *shape* γ in **J**.



Cauch$_P$ returns $f_{Ca}(x) = \left\{ \pi\gamma \cdot \left[1 + \left(\frac{x - x_0}{\gamma} \right)^2 \right] \right\}^{-1}$,

Cauch returns $F_{Ca}(x) = \frac{1}{2} + \frac{1}{\pi} \arctan\left(\frac{x - x_0}{\gamma} \right)$,

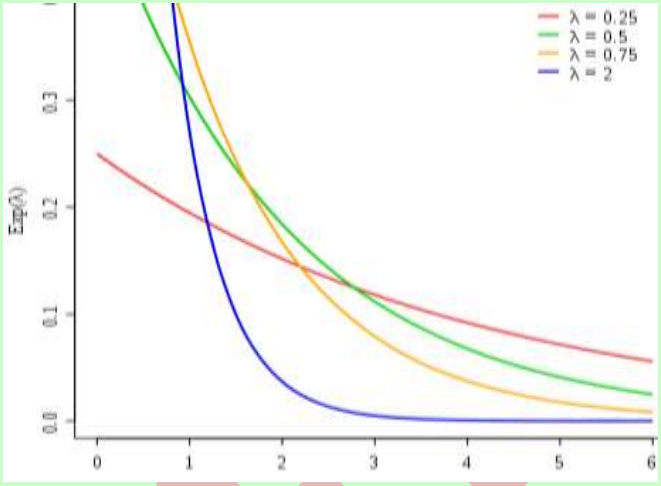
Cauch^{-1} returns $F_{Ca}^{-1}(p) = x_0 + \gamma \tan\left[\pi \cdot \left(p - \frac{1}{2} \right) \right]$.

This distribution is quite popular in physics. It is a special case of *Student's t distribution*. Start reading here for more:
http://en.wikipedia.org/wiki/Cauchy_distribution .

Expon: *Exponential distribution* with the *rate* λ in **I**.

Expon$_P$ returns $f_{Ex}(x) = \lambda \cdot e^{-\lambda x}$. See the *PDF* plotted overleaf.

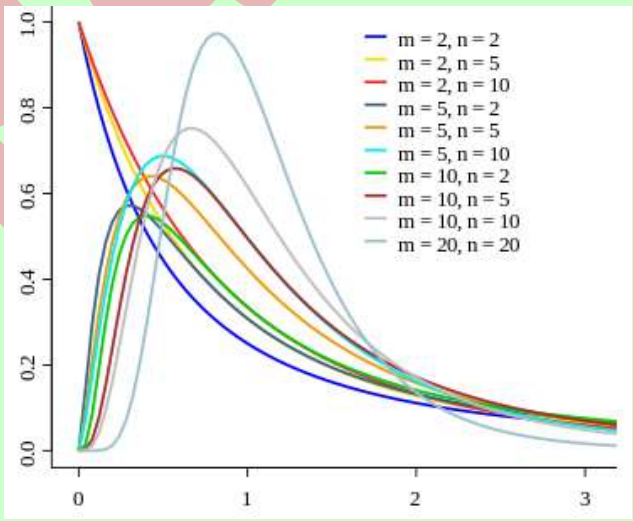
Expon returns $F_{Ex}(x) = 1 - e^{-\lambda x}$.



Read here for more information:
http://www.itl.nist.gov/div898/handbook/eda/section3/eda3667.htm

F(x): *Fisher's F distribution* with the *degrees of freedom* in **I** and **J**. It is used e.g. for analyses of variance (ANOVA).

The picture shows the *PDF* plotted for different *degrees of freedom* ***m*** *and* ***n*** corresponding to ***i*** and ***j***.

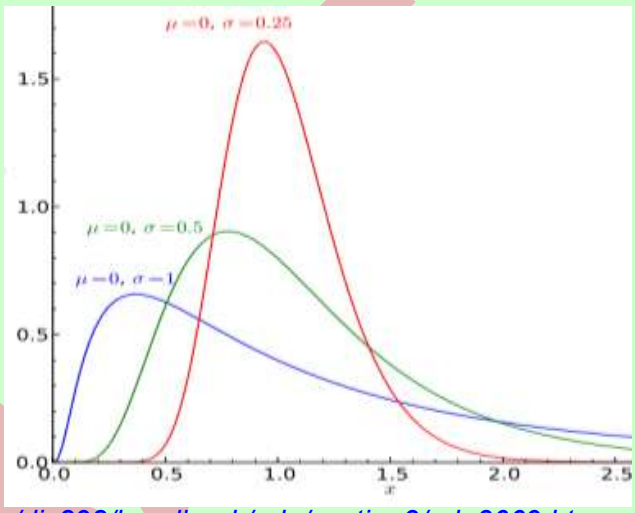


Read here for more information:
http://www.itl.nist.gov/div898/handbook/eda/section3/eda3665.htm

LgNrm: *Log-normal distribution* with the parameters $\mu = \ln \bar{x}_g$ in **I** and $\sigma = \ln \varepsilon$ in **J** (see some *PDF* plots below).

LgNrm$_P$ returns $f_{Ln}(x) = \frac{1}{x\sigma\sqrt{2\pi}} e^{-\frac{[ln(x)-\mu]^2}{2\sigma^2}}$.

LgNrm returns $F_{Ln}(x) = \Phi\left(\frac{ln(x)-\mu}{\sigma}\right)$ with $\Phi(z)$ denoting the *standard normal CDF* as presented on p. 204.



Read here for more information:
http://www.itl.nist.gov/div898/handbook/eda/section3/eda3669.htm

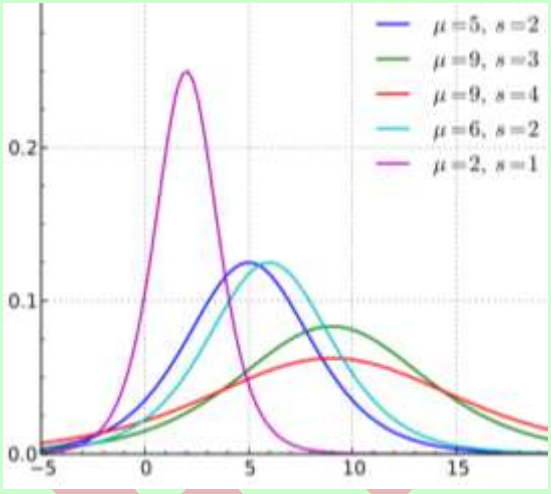
Logis: *Logistic distribution* with an arbitrary *mean* ***μ*** given in **I** and a *scale parameter* ***s*** in **J**.

Substituting $\xi = \frac{x-\mu}{s}$,

Logis$_P$ returns $f_{Lg}(x) = \frac{e^{-\xi}}{(1+e^{-\xi})^2 s}$ and

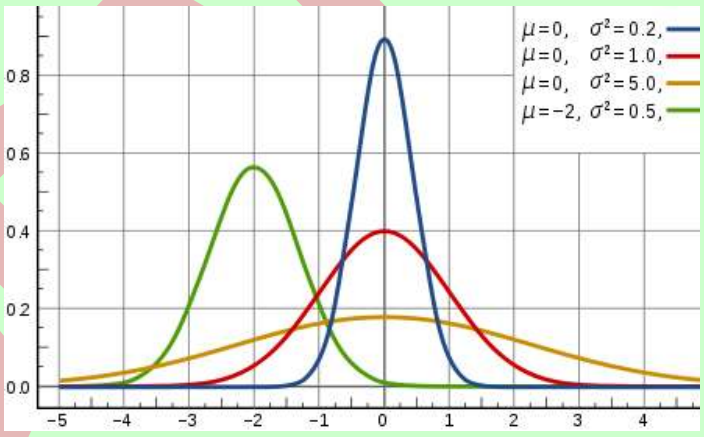
Logis returns $F_{Lg}(x) = \frac{1}{1+e^{-\xi}}$.

Logis^{-1} returns $F_{Lg}^{-1}(p) = \mu + s\ ln\left(\frac{p}{1-p}\right)$.



Start reading here for more:
http://en.wikipedia.org/wiki/Logistic_distribution .

Norml: *Normal distribution* with an arbitrary *mean* **μ** given in **I** and an arbitrary *standard deviation* **σ** in **J**.



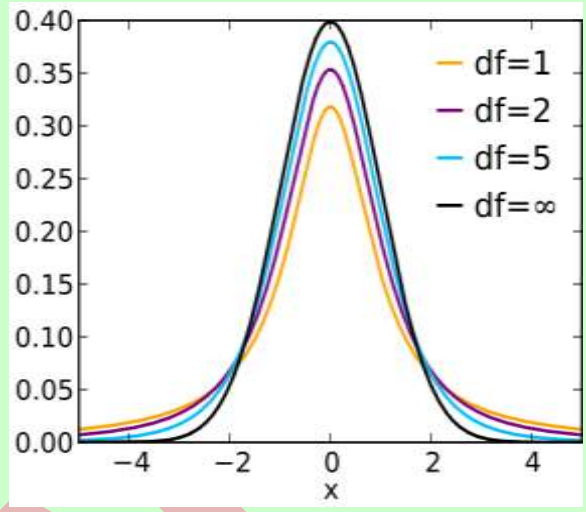
Norml$_P$ returns $f_N(x) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$ and

Norml returns $F_N(x) = \Phi\left(\frac{x-\mu}{\sigma}\right)$ with $\Phi(z)$ denoting the *standard normal* (or *Gaussian*) *CDF* as presented on p. 204.

Read here for more information:
http://www.itl.nist.gov/div898/handbook/eda/section3/eda3661.htm

t(x): Standardized *Student's t distribution* with its *degrees of freedom* in **I**.

It is used for hypothesis testing and calculating confidence intervals e.g. for means. The picture shows its *PDF* plotted for different *degrees of freedom*. For $\boldsymbol{df} \to \infty$, the shoulders of $t(x)$ shrink and it approaches the *PDF* of the *standard normal distribution* (compare the red *Gaussian* curve at NORML on p. 202).



Read here for more information:
http://www.itl.nist.gov/div898/handbook/eda/section3/eda3664.htm

Weibl: *Weibull distribution* with its *shape parameter* ***b*** in **I** and its *characteristic lifetime* ***T*** in **J**.

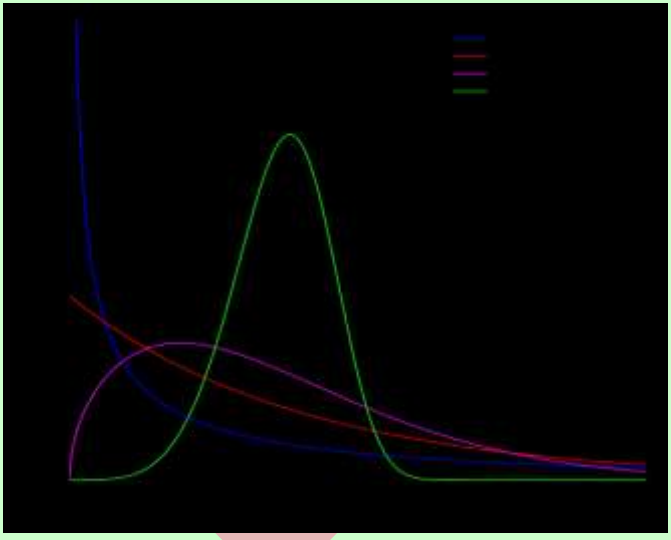
Weibl$_P$ returns $f_W(t) = \frac{b}{T} \cdot \left(\frac{t}{T}\right)^{b-1} e^{-\left(t/T\right)^b}$ for $t \geq 0$ (else it returns 0).

This is a very flexible function – see the curves plotted on next page.

Weibl returns $F_W(t) = 1 - e^{-\left(t/T\right)^b}$

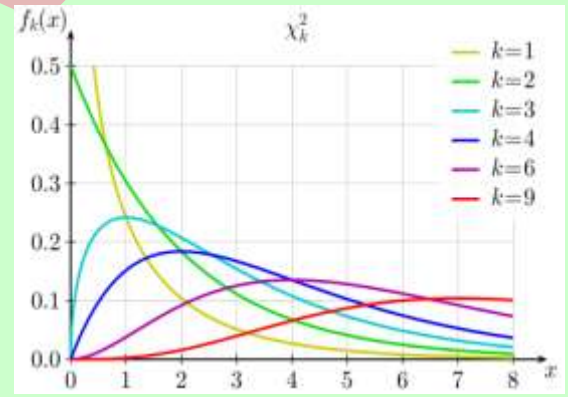
This distribution is widely used e.g. for analyzing tool and product lifetimes.

Read here for more information:
http://www.itl.nist.gov/div898/handbook/eda/section3/eda3668.htm .
You may check also
http://en.wikipedia.org/wiki/Weibull_distribution#Uses for some more application fields.



φ(x) and **Φ(x):** $\varphi(x) = \frac{1}{\sqrt{2\pi}} e^{-x^2/2}$ is the *standard normal PDF* (the famous *Gaussian* bell curve, pictured as red curve under NORML on p. 202), while $\Phi(x) = \int_{-\infty}^{x} \varphi(\tau) d\tau$ is the corresponding *CDF* (cf. the *error function* on p. 223). Take NORML instead for arbitrary means and standard deviations. See the link there for more information.

χ^2(x): *Chi-square distribution* with its *degrees of freedom* given in **I**. It is used for calculating confidence intervals for *standard deviations, variances, process and machine capabilities*, and the like. The diagram shows *PDF* plots for different *degrees of freedom*.



Read here for more information:
http://www.itl.nist.gov/div898/handbook/eda/section3/eda3666.htm

More Statistical Formulas, also for Fitting

The following equations are for data measured at samples of n specimens (i.e. n is the *sample size*). Note that complete measurement results must include both: information about the expected value and about its uncertainty.

- For samples drawn out of a *Gaussian* (additive) process, the expected value is the *arithmetic mean* (or *average*) and its uncertainty is given by its *standard error* (see $\overline{x}$ and s_m).
- For samples drawn out of a *log-normal* (multiplicative) process, the expected value is the *geometric mean* and its uncertainty is given by its *scattering factor* (see $\overline{x}_g$ and ε_m).
- For samples drawn out of other kinds of processes other measures apply.

Be assured not everything is *Gaussian* in real world![49] Process features can be detected (and should be checked well in advance of calculating e.g. means) using suitable tests – turn to applicable statistical reference literature.

The following functions as named in the left column are all found in STAT:

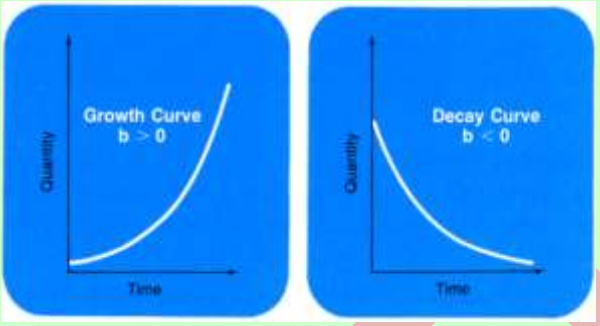
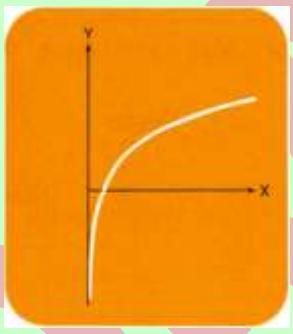
---

[49] Generally, the statistical model shall be chosen that matches observations best – within their statistical errors. In real life cases, however, dramatic deviations from the model distribution are frequently found – then you cannot expect the calculated consequences matching reality any better.

As mentioned in the main text, we recommend you look deeply into statistics textbooks to ensure you fully understand what you do with the functions provided in your *WP 43S*. The real world shows lots of sad examples where people full of good will caused large damages by applying tools they did not know sufficiently – or applied standard tools in areas where those are not applicable. "*Wenn Dumme fleißig werden, wird's gefährlich*" (i.e. "*It's getting dangerous when ignorant become busy*"), a former boss of mine used to say (cf. e.g. D.T. recently).

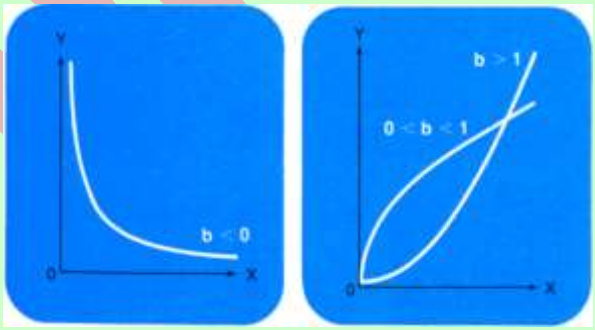
By the way: Since the *PDF* of the *Gaussian* distribution will never reach zero, this statistical model tells you to expect individual items far, far away from the mean value when your sample becomes large enough. This, however, does not match reality. So we must conclude nothing at all is really *Gaussian* in real world. Nevertheless, the *Gaussian* distribution is a very successful model describing a lot of real world observations very well. Just never forget the limits of such models.

Name	Remarks (see pp. 12ff for general information)
CORR	For an arbitrary fit model $R(\boldsymbol{x})$, the *coefficient of correlation* squared $$r^2 = 1 - \frac{\sum[R(x_i) - y_i]^2}{\sum(\bar{y} - y_i)^2}$$ is its *coefficient of determination* indicating the fraction of the variation of the dependent data $\boldsymbol{y}$ determined by the variation of the independent data $\boldsymbol{x}$. For $r^2 = 1$, $\boldsymbol{y}$ is fully determined by $\boldsymbol{x}$; for $r^2 = 0$, $\boldsymbol{y}$ is completely independent of $\boldsymbol{x}$; and e.g. $r^2 = 0.85$ means 85% of the variation of $\boldsymbol{y}$ is due to $\boldsymbol{x}$. Note BESTF picks the fit model showing the maximum $\boldsymbol{r^2}$ out of LINF, EXPF, LOGF, and POWERF. A two-parameter regression (like the fit models provided on your *WP 43S*) is said being (statistically) *significant* if $$\sqrt{\frac{r^2}{1-r^2}(n-2)} > t_{n-2}^{-1}(0.99)$$ with the right side being the inverse of the *t distribution* for the *degrees of freedom* $n - 2$ and *confidence level* 99% (see p. 203). For a linear fit model, the *coefficient of correlation* is $r = \frac{s_{xy}}{s_x \cdot s_y}$. See s_{XY} and s below.
COV	For a linear fit model, the *population covariance* is $$COV_{xy} = \frac{1}{n^2}\left(n\sum x_i y_i - \sum x_i \sum y_i\right)$$ Compare s_{XY} below.

Name	Remarks (see pp. 12ff for general information)
ExpF	Selects the exponential curve fit model $R(x) = a_0 e^{a_1 x}$ for least squares regression.[50] Generally, this will be a good choice if the measured data follow the shape of one of the curves pictured here.[51] 
LinF	Selects the linear fit model $R(x) = a_0 + a_1 x$ for least squares regression.[50] Generally, this will be a good choice if the measured data follow a straight line, raising or falling (but cf. ORTHOF below).
LogF	 Selects the logarithmic curve fit model $R(x) = a_0 + a_1 ln(x)$ for least squares regression.[50] Generally, this will be a good choice if the measured data follow a curve looking like shown at left.
L.R.	For a linear fit model, the least squares regression[50] line parameters are $a_0 = \frac{\sum x_i^2 \cdot \sum y_i - \sum x_i \cdot \sum x_i y_i}{n \cdot (n-1) \cdot s_x^2}$ and $a_1 = \frac{s_{xy}}{s_x^2} = r \cdot \frac{s_y}{s_x}$ (see CORR above, s_{XY} and s below).

[50] Note that *least squares regression* is best for data point errors in direction ***y*** being significantly greater than errors in direction ***x***.

[51] Plots on this and next page are taken from the *HP-27* manual; $b = a_1$ on your *WP 43S*.

Name	Remarks (see pp. 12ff for general information)
	Their *standard errors* can be calculated using the formulas $s(a_1) = \frac{s_y}{s_x}\sqrt{\frac{1-r^2}{n-2}}$ and $s(a_0) = s(a_1)\cdot\sqrt{\frac{n-1}{n}s_x^2 + \bar{x}^2}$. For all curve fit models provided on your *WP 43S*, a regression parameter is (statistically) *significant* if $\left|a_i\right| / s(a_i) > t_{n-2}^{-1}(0.995)$, with the right side being the inverse of the *t distribution* for the *degrees of freedom* $n-2$ and 99% *confidence level* (see p. 203).
OrthoF	Selects the linear fit model $R(x) = a_0 + a_1 x$ like LINF, though assuming data point errors in ***x*** are equal to those in ***y*** (precisely: their variances are equal). The sum of squared distances of the data points to the fit line will be minimized. This model is called *orthogonal regression*. The line parameters are $a_1 = \frac{1}{2s_{xy}}\left[s_y^2 - s_x^2 \pm \sqrt{\left(s_y^2 - s_x^2\right)^2 + 4s_{xy}^2}\right]$ *and* $a_0 = \bar{y} - a_1\bar{x}$ (see s_{XY} and s below).
PowerF	Selects the power curve fit model $R(x) = a_0\, x^{a_1}$ for least squares regression.[50] Generally, this will be a good choice if the measured data follow the shape of one of the curves shown here.[51] 

Name	Remarks (see pp. 12ff for general information)
s_{XY}	For any linear fit model (LinF or OrthoF), the *sample covariance* is $$s_{xy} = \frac{1}{n(n-1)}\left(n\sum x_i y_i - \sum x_i \sum y_i\right)$$ Compare COV above.
s, s_m	The *sample standard deviation* (*SD*) is the positive square root of the *sample variance* $$s_x^2 = \frac{1}{n(n-1)}\left[n\sum x_i^2 - \left(\sum x_i\right)^2\right] = \frac{1}{n-1}\left(\sum x_i^2 - n\,\bar{x}^2\right)$$ And the *standard error* (i.e. the *SD* of the *mean* $\bar{x}$) is $s_{mx} = {s_x}/{\sqrt{n}}$
s_W , s_{mW}	The *sample SD* for weighted data (where the weight y_i of each data point x_i was entered via Σ+) is $$s_w = \sqrt{\frac{\sum y_i \sum y_i x_i^2 - (\sum y_i x_i)^2}{\sum y_i\,(\sum y_i - 1)}}$$ And the corresponding *standard error* (the *SD* of the *mean* $\bar{x}_w$) is $$s_{mw} = \frac{1}{\sum y_i}\sqrt{\frac{\sum y_i \sum y_i x_i^2 - (\sum y_i x_i)^2}{\sum y_i - 1}}$$
$\bar{x}$	The *arithmetic mean* is calculated as $\bar{x} = \frac{1}{n}\sum x_i$
$\bar{x}_G$	The *geometric mean* is calculated as $\bar{x}_G = \sqrt[n]{(\prod x_i)} = e^{\left[\frac{1}{n}\sum ln(x_i)\right]}$.
$\bar{x}_w$	The *arithmetic mean* for weighted data (where the weight y_i of each data point x_i was entered via Σ+) is $$\bar{x}_w = {\sum x_i y_i}/{\sum y_i}.$$

Name	Remarks (see pp. 12ff for general information)
ε	The *scattering factor* ε_x for a sample of *log-normally* distributed data is calculated via: $$ln(\varepsilon_x) = \sqrt{\frac{1}{n-1}\left[\sum ln^2(x_i) - 2n\, ln\,(\bar{x}_G)\right]}$$ Compare s.
ε_m	The *scattering factor* of the *geometric mean* is $\varepsilon_m = \varepsilon^{1/\sqrt{n}}$. Compare s_m.
ε_p	The *scattering factor* ε_p for a population of *log-normally* distributed data is calculated via: $$ln(\varepsilon_P) = \sqrt{\frac{n-1}{n}}\ ln(\varepsilon_x)$$ Compare σ.
σ	The *SD* of a population of *normally* distributed data is calculated via: $$\sigma_x = \frac{1}{n}\sqrt{\sum x_i^2 - n\,\bar{x}^2} = \sqrt{\frac{n-1}{n}}\ s_x$$ Compare ε_p.
σ_W	The *SD* of the population for weighted data (where the weight y_i of each data point x_i was entered via Σ+) is $$\sigma_w = \sqrt{\frac{\sum y_i\,(x_i - \bar{x}_w)^2}{\sum y_i}}$$

About Error Propagation

As mentioned in footnote 30 on p. **Fehler! Textmarke nicht definiert.**, experimental data are always attended with errors, caused by e.g. the uncertainty of the measuring method, the instrument used, and environmental variations. Even under controlled measuring conditions, random errors remain. These errors must be taken into account for a proper estimation of the uncertainty of your results computed using those experimental data. For about 200 years, *Gauß' least squares method* can be employed for this task.

Assume you know that your result ***R*** depends on several experimental parameters x_1 through x_n. Each such parameter x_i has an uncertainty or error Δx_i. Now, if $R = f(x_1, \dots, x_n)$ then

$$\Delta R = f(x_1 \pm \Delta x_1, \dots, x_n \pm \Delta x_n) - f(x_1, \dots, x_n)$$
$$= \pm\sqrt{\left(\frac{df}{dx_1}\right)^2 {\Delta x_1}^2 + \dots + \left(\frac{df}{dx_n}\right)^2 {\Delta x_n}^2}$$

Often, however, the differential terms under the square root are tedious to determine analytically.

But this root can be written simpler: $\Delta R = \pm\sqrt{{\Delta f_1}^2 + \dots + {\Delta f_n}^2}$.

And with your *WP 43S*, the following algorithm will do for computing ΔR, even if f is 'strongly curved':

1. Program the function $R = f(x_1, x_2, \dots, x_n)$ in a way you can vary its parameters easily.
2. Let your *WP 43S* compute $= f(x_1, x_2, \dots, x_n)$.
3. Let it compute $R_{1+} = f(x_1 + \Delta x_1, x_2, \dots, x_n)$ and $\Delta R_{1+} = R_{1+} - R$.
4. Let it compute $R_{1-} = f(x_1 - \Delta x_1, x_2, \dots, x_n)$ and $\Delta R_{1-} = R_{1-} - R$.
5. Let it compute $R_{2+} = f(x_1, x_2 + \Delta x_2, \dots, x_n)$ and $\Delta R_{2+} = R_{2+} - R$.
6. Let it compute $R_{2-} = f(x_1, x_2 - \Delta x_2, \dots, x_n)$ and $\Delta R_{2-} = R_{2-} - R$.
7. Repeat the last two steps for each remaining parameter.

Being through with all n parameters, you will end with

$$\Delta R = \pm\sqrt{\frac{1}{2}\left(\Delta R_{1+}^2 + \Delta R_{1-}^2 + \Delta R_{2+}^2 + \Delta R_{2-}^2 + \cdots + \Delta R_{n+}^2 + \Delta R_{n-}^2\right)}$$

So the terms under the square root have become simple differences which are determined most easily with the help of your *WP 43S*.

For 'small' errors or less curvature, the following simpler algorithm will do, requiring down to half as many steps only:

1. Program the function $R = f(x_1, x_2, \ldots, x_n)$ in a way you can vary its parameters easily.
2. Let your *WP 43S* compute $= f(x_1, x_2, \ldots, x_n)$.
3. Let it compute $R_1 = f(x_1 + \Delta x_1, x_2, \ldots, x_n)$ and $\Delta R_1 = R_1 - R$.
4. Let it compute $R_2 = f(x_1, x_2 + \Delta x_2, \ldots, x_n)$ and $\Delta R_2 = R_2 - R$.
5. Repeat the last step for each remaining parameter.

Being through with all n parameters, you will end with

$$\Delta R = \pm\sqrt{\Delta R_1^2 + \Delta R_2^2 + \cdots + \Delta R_n^2}$$

More about Curve Fitting

Actually, a proper linear regression is computed for LINF and ORTHOF only. For the other three models (EXPF, LOGF, and POWERF) the same method is applied to transformed data. Your data might follow a straight line if you plot...

- the LN of your ***y***-data over your ***x***-data (then EXPF will fit);
- the LN of your ***y***-data over the LN of your ***x***-data (then POWERF will fit);
- your ***y***-data over the LN of your ***x***-data (then LOGF will fit).

This is what your *WP 43S* does when you enter statistical data points and compute a fit curve thereafter:

1. It accumulates the 13 sums listed on p. 94.

2. The evaluation depends on the model you select:

   a. If you choose LINF then the least squares regression line parameters a_0 and a_1 will be computed following the formulas on p. 207. Their standard errors can be calculated using the formulas on p. 208 with

$$r = \frac{n\sum x_i y_i - \sum x_i \sum y_i}{\sqrt{n\sum x_i^2 - (\sum x_i)^2} \cdot \sqrt{n\sum y_i^2 - (\sum y_i)^2}}$$

   b. If you choose EXPF then the least squares regression line parameters for the transformed data x_i, $ln(y_i)$ will be computed using

$$a_{0,tEXP} = \frac{\sum x_i^2 \cdot \sum ln(y_i) - \sum x_i \cdot \sum x_i ln(y_i)}{n\sum x_i^2 - (\sum x_i)^2}$$

$$a_{1,tEXP} = \frac{n\sum x_i ln(y_i) - \sum x_i \sum ln(y_i)}{n\sum x_i^2 - (\sum x_i)^2}$$

   The correlation coefficient for the transformed data will be

$$r_{tEXP} = \frac{n\sum x_i ln(y_i) - \sum x_i \sum ln(y_i)}{\sqrt{n\sum x_i^2 - (\sum x_i)^2} \cdot \sqrt{n\sum ln^2(y_i) - [\sum ln(y_i)]^2}}$$

   The standard errors of $a_{0,tEXP}$ and $a_{1,tEXP}$ can be calculated using the formulas on p. 208 with the transformed results.

   The parameters of the fit curve $R(x) = a_0 e^{a_1 x}$ turn out being $a_0 = e^{a_{0,tEXP}}$ and $a_1 = a_{1,tEXP}$.

c. If you choose POWERF then the least squares regression line parameters for the transformed data $ln(x_i)$, $ln(y_i)$ will be computed in analogy to the method shown for EXPF. Thus they will be

$$a_{0,tPOW} = \frac{\sum ln^2(x_i) \cdot \sum ln(y_i) - \sum ln(x_i) \cdot \sum ln(x_i) ln(y_i)}{n \sum ln^2(x_i) - [\sum ln(x_i)]^2}$$

$$a_{1,tPOW} = \frac{n \sum ln(x_i) ln(y_i) - \sum ln(x_i) \sum ln(y_i)}{n \sum ln^2(x_i) - [\sum ln(x_i)]^2}$$

$$r_{tPOW} = \frac{n \sum ln(x_i) ln(y_i) - \sum ln(x_i) \sum ln(y_i)}{\sqrt{n \sum ln^2(x_i) - [\sum ln(x_i)]^2} \cdot \sqrt{n \sum ln^2(y_i) - [\sum ln(y_i)]^2}}$$

The standard errors of $a_{0,tPOW}$ and $a_{1,tPOW}$ can be calculated using the formulas on p. 208 with the transformed results.

The parameters of the fit curve $R(x) = a_0 \, x^{a_1}$ turn out being $a_0 = e^{a_{0,tPOW}}$ and $a_1 = a_{1,tPOW}$.

d. If you choose LOGF then the least squares regression line parameters for the transformed data $ln(x_i)$, y_i will be computed in analogy to the method shown for EXPF. Thus they will be

$$a_{0,tLOG} = \frac{\sum ln^2(x_i) \cdot \sum y_i - \sum ln(x_i) \cdot \sum y_i ln(x_i)}{n \sum ln^2(x_i) - [\sum ln(x_i)]^2}$$

$$a_{1,tLOG} = \frac{n \sum y_i ln(x_i) - \sum ln(x_i) \sum y_i}{n \sum ln^2(x_i) - [\sum ln(x_i)]^2}$$

$$r_{tLOG} = \frac{n \sum y_i ln(x_i) - \sum ln(x_i) \sum y_i}{\sqrt{n \sum ln^2(x_i) - [\sum ln(x_i)]^2} \cdot \sqrt{n \sum y_i^2 - [\sum y_i]^2}}$$

The standard errors of $a_{0,tLOG}$ and $a_{1,tLOG}$ can be calculated using the formulas on p. 208 with the transformed results.

The parameters of the fit curve $R(x) = a_0 + a_1 ln(x)$ are just $a_0 = a_{0,tLOG}$ and $a_1 = a_{1,tLOG}$.

e. If you choose BESTF then the correlation coefficient will be computed with your data for model a and with the transformed data for models b, c, and d. The model delivering the greatest absolute r value will be selected.

Solving Differential Equations

The method applied to the examples in the respective chapter in *Section 3* of the *OM* develops as explained below:

First, we solve one-dimensional problems of the kind

$$\frac{d^2f}{dt^2} = a - b\left(\frac{df}{dt}\right)^2$$

This is the equation for a body (of mass M) falling through a medium featuring drag proportional to the velocity squared of said body. For earthly problems, take $a = 9.81\frac{m}{s^2} = g$ and $b = {}^{\delta}/_{M}$ with the constant parameter δ taking care of the viscosity of the medium as well as size and shape of the falling body as a whole.

For a first guess, let us assume $b = 0$. So there will be no drag at all, the body will be just accelerated by $a = g$. Then for two arbitrary subsequent points in time,

- vertical velocity will develop like $\left(\frac{df}{dt}\right)_{i+1} \approx \left(\frac{df}{dt}\right)_i + a\Delta t$ and
- position over ground like $f_{i+1} \approx f_i + \left(\frac{df}{dt}\right)_i \Delta t$.

Proceeding from time zero in small, constant time steps $\Delta t = t_{i+1} - t_i$:

- $f_1 = f_0 + \left(\frac{df}{dt}\right)_0$ and $\left(\frac{df}{dt}\right)_1 = \left(\frac{df}{dt}\right)_0 + a\Delta t$,

- $f_2 = f_1 + \left(\frac{df}{dt}\right)_1$ and $\left(\frac{df}{dt}\right)_2 = \left(\frac{df}{dt}\right)_1 + a\Delta t$, etc.

Principally, a better approximation of the slope of f is achieved using the so-called *half-step method*:

$$\left(\frac{df}{dt}\right)_{1/2} \approx \left(\frac{df}{dt}\right)_0 + a\frac{\Delta t}{2}$$

$$\left(\frac{df}{dt}\right)_{i+\frac{1}{2}} \approx \left(\frac{df}{dt}\right)_{i-\frac{1}{2}} + a\Delta t$$

$$f_{i+1} \approx f_i + \left(\frac{df}{dt}\right)_{i+1/2} \Delta t$$

Proceeding from time zero in small steps Δt again, we get

- $\left(\frac{df}{dt}\right)_{1/2} = \left(\frac{df}{dt}\right)_0 + a\frac{\Delta t}{2}$
- $f_1 = f_0 + \left(\frac{df}{dt}\right)_{1/2}$ and $\left(\frac{df}{dt}\right)_{3/2} = \left(\frac{df}{dt}\right)_{1/2} + a\Delta t$,
- $f_2 = f_1 + \left(\frac{df}{dt}\right)_{3/2} \Delta t$, etc.

Let us drop the restriction for b now. Replacing *a* in the previous set of equations by the right side of the differential equation on p. 215, we will get the following new set:

$$\frac{df}{dt_{1/2}} \approx \frac{df}{dt_0} + \left[a - b\left(\frac{df}{dt}\right)_0^2\right]\frac{\Delta t}{2}$$

$$\left(\frac{df}{dt}\right)_{i+1/2} \approx \left(\frac{df}{dt}\right)_{i-\frac{1}{2}} + \left[a - b\left(\frac{df}{dt}\right)_{i-\frac{1}{2}}^2\right]\Delta t$$

$$f_{i+1} \approx f_i + \left(\frac{df}{dt}\right)_{i+1/2} \Delta t$$

Proceeding from time zero in small steps Δt again, we get

- $\left(\frac{df}{dt}\right)_{1/2} = \left(\frac{df}{dt}\right)_0 + \left[a - b\left(\frac{df}{dt}\right)_0^2\right]\frac{\Delta t}{2}$
- $f_1 = f_0 + \left(\frac{df}{dt}\right)_{1/2}$ and $\left(\frac{df}{dt}\right)_{3/2} = \left(\frac{df}{dt}\right)_{1/2} + \left[a - b\left(\frac{df}{dt}\right)_{1/2}^2\right]\Delta t,$
- $f_2 = f_1 + \left(\frac{df}{dt}\right)_{3/2}\Delta t$, etc.

This half-step method as explained above can be applied easily to all ordinary differential equations of second order which can be written like

$$\frac{d^2f}{dt^2} = h\left(t, f, \frac{df}{dt}\right)$$

with an arbitrary real function h depending on time, the function itself and its first derivative. The equations applicable in this general case are

- $\left(\frac{df}{dt}\right)_{1/2} = \left(\frac{df}{dt}\right)_0 + h\left(t_0\,,\, f_0\,,\, \left[\frac{df}{dt}\right]_0\right)\frac{\Delta t}{2}$
- $\left(\frac{df}{dt}\right)_{i+1/2} = \left(\frac{df}{dt}\right)_{i-1/2} + h\left(t_{i-1/2}\,,\, f_{i-1/2}\,,\, \left[\frac{df}{dt}\right]_{i-1/2}\right)\Delta t$
- $f_{i+1} = f_i + \left[\frac{df}{dt}\right]_{i-1/2}\Delta t$

For solving a 2D problem like e.g. finding the orbit of a satellite in the gravitational field of the earth, we need two differential equations, one for ***x*** and one for ***y***:

$$\frac{d^2x}{dt^2} = \frac{F_x}{m} = -\frac{F}{m}\frac{x}{\sqrt{x^2+y^2}} \quad \text{and} \quad \frac{d^2y}{dt^2} = \frac{F_y}{m} = -\frac{F}{m}\frac{y}{\sqrt{x^2+y^2}}\,.$$

And we know $F = {}^{G\,m\,M}/_{(x^2+y^2)}$, thus

$$\frac{d^2x}{dt^2} = -\frac{GM}{(x^2+y^2)^{3/2}}x = K_x \quad \text{and} \quad \frac{d^2y}{dt^2} = -\frac{GM}{(x^2+y^2)^{3/2}}y = K_y$$

This is a pair of coupled differential equations. It is solved as follows:

$$\left(\frac{dx}{dt}\right)_{1/2} \approx \left(\frac{dx}{dt}\right)_0 + K_x \frac{\Delta t}{2} \qquad \left(\frac{dy}{dt}\right)_{1/2} \approx \left(\frac{dy}{dt}\right)_0 + K_y \frac{\Delta t}{2}$$

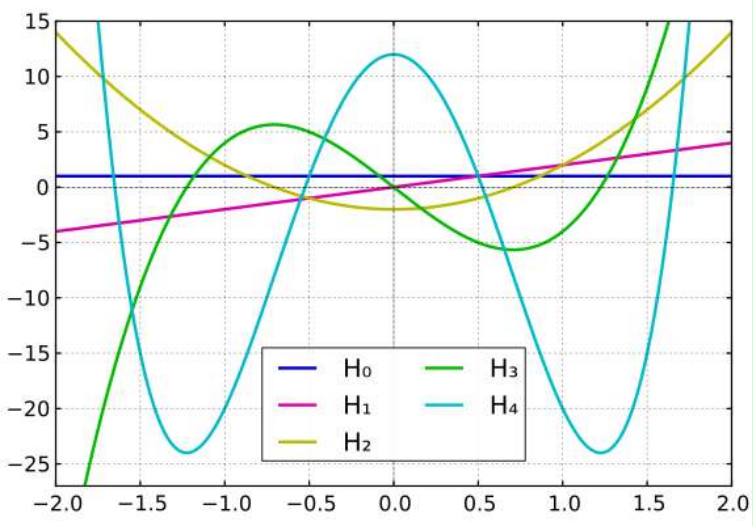
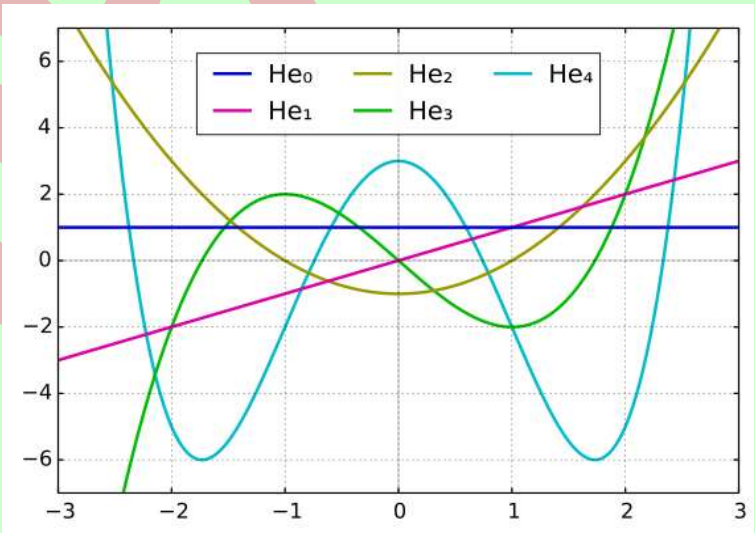
$$\left(\frac{dx}{dt}\right)_{i+\frac{1}{2}} \approx \left(\frac{dx}{dt}\right)_{i-\frac{1}{2}} + K_x \Delta t \qquad \left(\frac{dy}{dt}\right)_{i+\frac{1}{2}} \approx \left(\frac{dy}{dt}\right)_{i-\frac{1}{2}} + K_y \Delta t$$

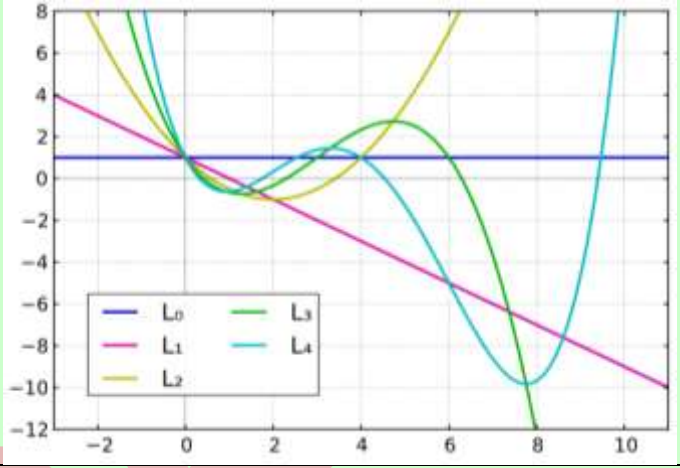
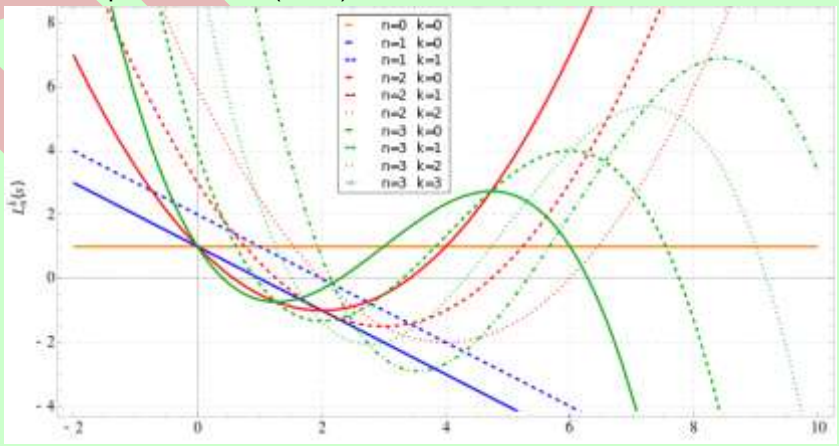
$$x_{i+1} \approx x_i + \left(\frac{dx}{dt}\right)_{i+1/2} \Delta t \qquad y_{i+1} \approx y_i + \left(\frac{dy}{dt}\right)_{i+1/2} \Delta t$$

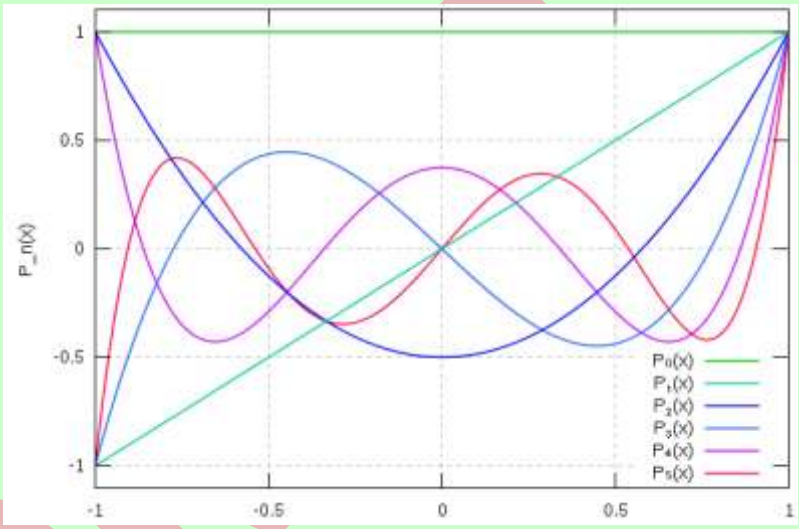
Orthogonal Polynomials

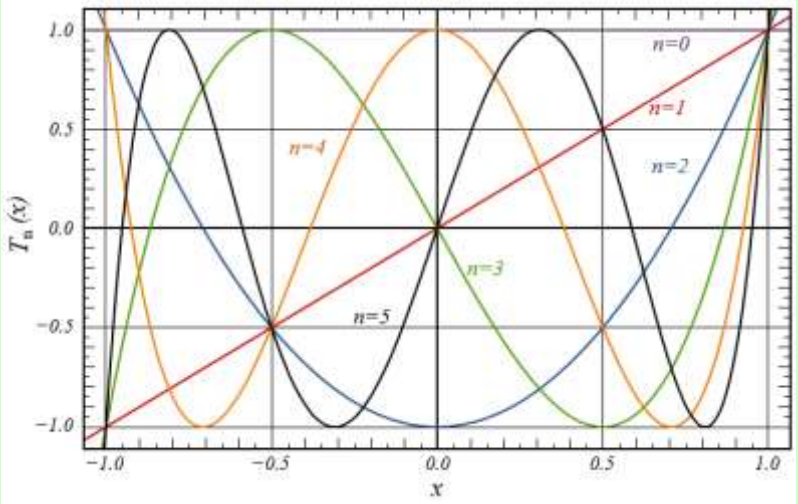
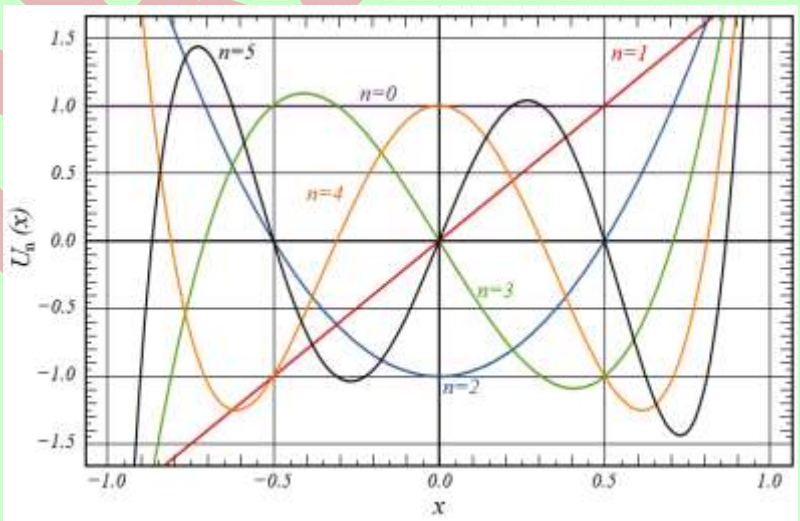
The following polynomials are all collected in X.FN'ORTHOG.

Name	Remarks (see pp. 12ff for general information)
H_n	***Hermite** polynomials* for probability: $H_n(x) = (-1)^n \cdot e^{x^2/2} \cdot \frac{d^n}{dx^n}\left(e^{-x^2/2}\right)$ with ***n*** in $\mathbf{Y}$, solving the differential equation $f''(x) - 2x \cdot f'(x) + 2n \cdot f(x) = 0$. See the first five polynomials plotted overleaf.

Name	Remarks (see pp. 12ff for general information)
	
H_{np}	***Hermite*** *polynomials* for <u>physics</u>: $H_{np}(x) = (-1)^n \cdot e^{x^2} \cdot \frac{d^n}{dx^n}\left(e^{-x^2}\right)$ with ***n*** in $\mathbf{Y}$, solving the same differential equation. See the first five polynomials plotted below. 

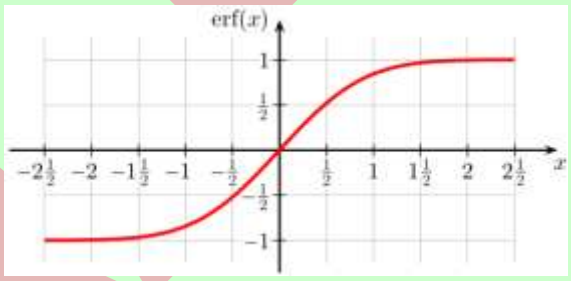
Name	Remarks (see pp. 12ff for general information)
L_n	***Laguerre*** *polynomials* (compare $L_{n\alpha}$ below): $L_n(x) = \frac{e^x}{n!} \cdot \frac{d^n}{dx^n}\left(x^n e^{-x}\right) = L_n^{(0)}(x)$ with ***n*** in $\mathbf{Y}$, solving the differential equation $x \cdot f''(x) + (1-x) \cdot f'(x) + n \cdot f(x) = 0$. See the first five *Laguerre polynomials* plotted here. 
$L_{n\alpha}$	***Laguerre's generalized*** *polynomials* (compare L_n above): $L_n^{(\alpha)}(x) = \frac{x^{-\alpha} e^x}{n!} \cdot \frac{d^n}{dx^n}\left(x^{n+\alpha} e^{-x}\right)$ with ***n*** in $\mathbf{Y}$ and α in $\mathbf{Z}$. Some of them are plotted below (k = α). 

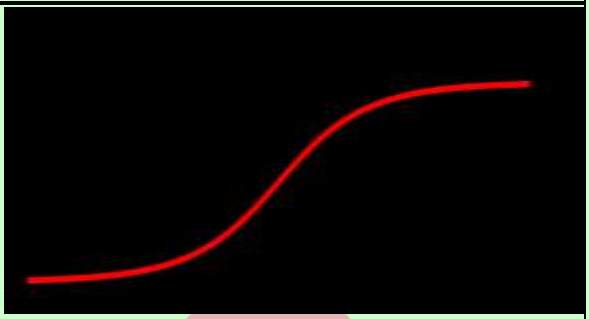
Name	Remarks (see pp. 12ff for general information)
P_n	***Legendre*** *polynomials*: $P_n(x) = \frac{1}{2^n n!} \cdot \frac{d^n}{dx^n}\left[\left(x^2-1\right)^n\right]$ with ***n*** in **Y**, solving the differential equation $\frac{d}{dx}\left[\left(1-x^2\right)\cdot\frac{d}{dx}f(x)\right]+n(n+1)f(x)=0\cdot$ See the first six polynomials plotted here. 
T_n	***Chebyshev*** (a.k.a. *Čebyšev, Tschebyschow, Tschebyscheff*) *polynomials of* ***first*** *kind* $T_n(x) = \begin{cases} \cos(n\arccos(x)) & \text{for } -1 \le x \le 1 \\ \cosh\left(n\,\text{arcosh}(x)\right) & \text{for } x > 1 \\ (-1)^n \cosh\left(n\,\text{arcosh}(-x)\right) & \text{for } x < -1 \end{cases}$ with ***n*** in **Y**, solving the differential equation $f''(x) - \frac{x}{1-x^2}f'(x) + \frac{n^2}{1-x^2}f(x) = 0$ The plot overleaf shows $T_0(x)$ ... $T_5(x)$.

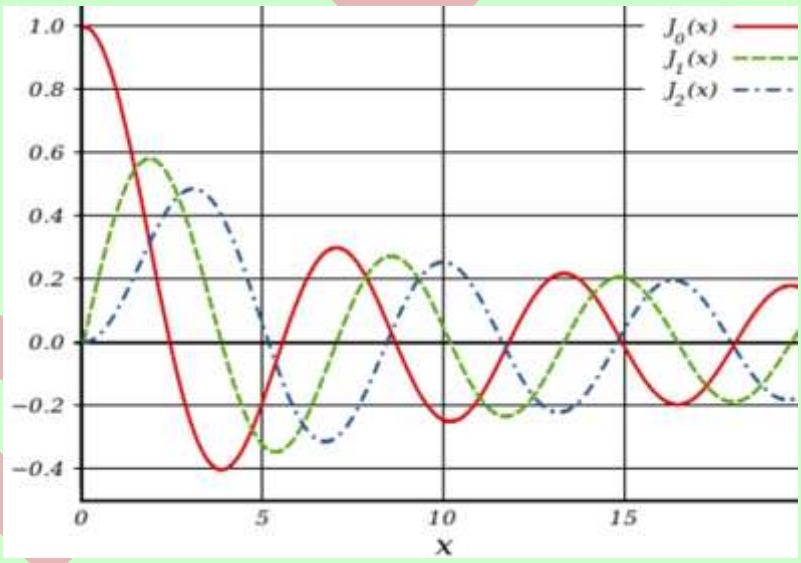
Name	Remarks (see pp. 12ff for general information)
	
U_n	***Chebyshev** polynomials of **second** kind* $U_n(x)$ with ***n*** in $\mathbf{Y}$, solving the differential equation $$f''(x) - \frac{3x}{1-x^2} f'(x) + \frac{n(n+2)}{1-x^2} f(x) = 0$$ The plot below shows $U_0(x)$ ... $U_5(x)$: 

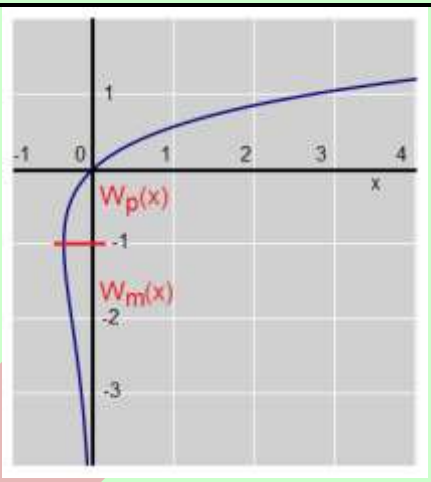
Even More Mathematical Functions

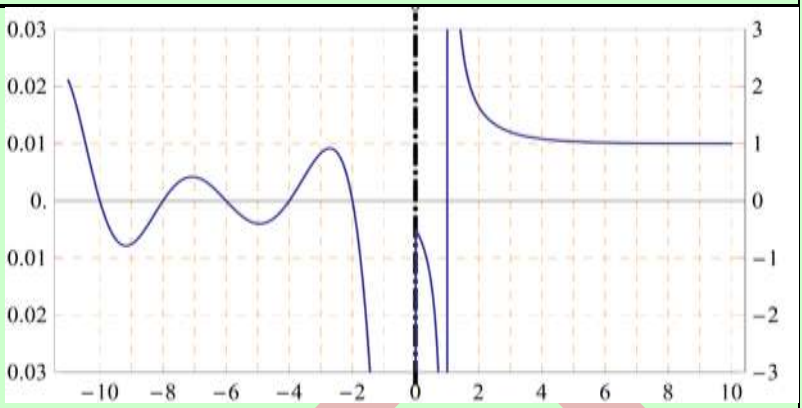
All the following functions are found in X.FN. Some of them are for pure mathematics only but were useful at some stages of the *WP 34S* or *WP 43S* projects, so we made them accessible for the public.

Name	Remarks (see pp. 12ff for general information)
AGM	Returns the *arithmetic-geometric mean*. Find more about it here: http://mathworld.wolfram.com/Arithmetic-GeometricMean.html .
erf	Returns the *error function* $erf(x)=\frac{2}{\sqrt{\pi}}\int_0^x e^{-\tau^2}\,d\tau$.  Note that $erf\left(\frac{x}{\sqrt{2}}\right)=2\cdot\Phi(x)-1$ with $\Phi(x)$ representing the *standard normal CDF* as described on p. 204.
erfc	This command returns the *complementary error function* $erfc(x)=1-erf(x)=\frac{2}{\sqrt{\pi}}\int_x^\infty e^{-\tau^2}\,d\tau$. This function is related to the *error probability* of the *standard normal distribution*.

Name	Remarks (see pp. 12ff for general information)
g_d	Returns the *Gudermannian function* $g_d(x)=\int_0^x \frac{d\xi}{\cosh\xi}$ linking hyperbolic and trigonometric functions. See the plot for its real values. The *inverse Gudermannian function* is $g_d^{-1}(x)=\int_0^x \frac{d\xi}{\cos\xi}$.  Start reading here for more: http://en.wikipedia.org/wiki/Gudermannian_function .
I_{xyz}	Returns the *regularized beta function* $\frac{\beta_x(x,y,z)}{B(y,z)}$ with $\beta_x(x,y,z)=\int_0^x t^{y-1}(1-t)^{z-1}dt$ being the *incomplete beta function* and $B(y,z)$ being *Euler's Beta function* (see p. 91).
$I\Gamma_p$	Returns the *regularized gamma function* $P(x,y)=\frac{\gamma(x,y)}{\Gamma(x)}$. See γ_{XY} below for $\gamma(x,y)$ and p. 91 for $\Gamma(x)$.
$I\Gamma_q$	Returns the *regularized gamma function* $Q(x,y)=\frac{\Gamma_u(x,y)}{\Gamma(x)}$. See Γ_{XY} below for $\Gamma_u(x,y)$ and p. 91 for $\Gamma(x)$.

Name	Remarks (see pp. 12ff for general information)
$J_y(x)$	Generally, the *Bessel functions* solve the differential equation $x^2 f''(x) + x f'(x) + (x^2 - v^2) f(x) = 0$ with $v \in \mathbb{C}$. $J_y(x)$ returns the *Bessel function of first kind* and order $y = v$. For arbitrary v, this is $$J_v(x) = \sum_{m=0}^{\infty} \frac{(-1)^m}{m!\ \Gamma(m+v+1)} \left(\frac{x}{2}\right)^{2m+v}$$ For integer v, this is also $$J_v(x) = \frac{1}{\pi} \int_0^{\pi} cos[v\,t - x\,sin(t)]\,dt$$  Start reading here for more information: http://en.wikipedia.org/wiki/Bessel_function .

Name	Remarks (see pp. 12ff for general information)
W_p, W_m	Returns *Lambert's W* with its principal branch (called W_p here) and its negative branch (called W_m for minus). The connecting point is (−1/e, −1). The diagram shows the real values of both branches.  Start reading here for more information: http://en.wikipedia.org/wiki/Lambert_W_function . Learn more here: http://mathworld.wolfram.com/LambertW-Function.html .
γ_{XY}	Returns the *lower incomplete gamma function* $\gamma(x,y)=\int_0^y t^{x-1}e^{-t}dt$. Required for IΓ_p above.
Γ_{XY}	Returns the *upper incomplete gamma function* $\Gamma_u(x,y)=\int_y^\infty t^{x-1}e^{-t}dt$. Required for IΓ_q above.
ζ(x)	Returns *Riemann's Zeta* for real arguments, with $\zeta(x)=\sum_{n=1}^{\infty}\frac{1}{n^x}$ for x > 1 , and its analytical continuation for x < 1 : $\zeta(x)=2^x\pi^{x-1}\sin\left(\frac{\pi}{2}x\right)\cdot\Gamma(1-x)\cdot\zeta(1-x).$ Note the different vertical scales for negative and positive x. in the plot overleaf.

Name	Remarks (see pp. 12ff for general information)
	 Look here for more: *http://mathworld.wolfram.com/RiemannZetaFunction.html* .

You will find lots of information about the special functions implemented in your *WP 43S* in the internet in addition. Generally speaking, *Wikipedia* is a good starter – we recommend checking the articles in different languages since they may well contain different material and use different approaches. *Mathworld* (quoted on pp. 223ff) may contain more details than you ever want to know. And for applied statistics, the *NIST Sematech* online handbook (quoted on pp. 196ff) is a competent source. Further references are found at these sites.

APPENDIX K: BACKGROUND CONSIDERATIONS

Alpha Register

For long I thought we could do without a dedicated *alpha register*. Some special programming functions like KEYG and KEYX, however, seem to require such a *register* – else handling these functions would become more complicated than it was on the *HP-42S*. Especially direct entry of alphanumeric constants in programs is easier when the destination is automatically defined, and people became used to this method in decades since the *HP-42S* was launched. Thus, I introduced this *register* in v0.7, taking **K** for this task.

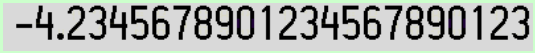
Angles

Originally, a separate *data type* for *angles* was planned. It was removed in v0.9 since its scope is quite limited and the opinion rose that '*angles* work like reals'. It turned out, however, that D.MS data would need special treatment in calculations, so *data type* 4 returned with v0.10 for sake of keeping algebraic operations simple and avoiding special purpose commands like D.MS+, D.MS−, etc.

Actually, angles are displayed in five 'modes' (*decimal* and *sexagesimal degrees*, *radians*, *multiples of* π, and *gon* or *grads*) but may be represented in a fixed format internally – similar to finite integers where a fixed bit pattern may be displayed in various *integer sign modes* and bases. *Decimal degrees* or *multiples of* π may be beneficial as internal representations since avoiding the necessity for high precision storage of π for modulo calculations.

Display Limits

Due to the character sizes mentioned in *Appendix D: Display Internals*, the screen could take inputs of up to 23 digits, a sign, and an 8-pixel radix mark:



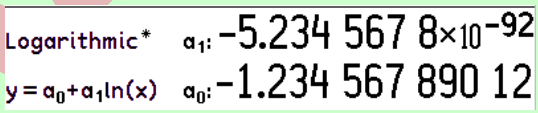
occupying 15 + 23 × 16 + 8 = 391 px. Numeric output would allow for the same 23 digits. Without separators at all, however, this would be hardly readable. With 3-digit separators (*startup default* mode), 20 digits are displayable in one row instead:

taking 15 + 20 × 16 + 7 × 8 = 391 px. This maximum precision is independent of the position of the radix mark. Scientific or engineering notation allows for a 16-digit mantissa

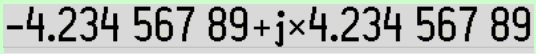
taking 394 px for displaying this number this way.

For double precision numbers, a 34-digit mantissa plus exponent can be shown using the small font:

Some *temporary information* may limit output precision. For linear regression, for example, up to 8 digits are possible allowing for 2-digit exponents in SCI or ENG and up to 12 digits in FIX:

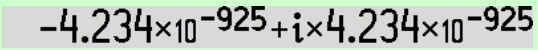


Complex numbers in Cartesian notation require 44 px for +i× in addition to the space for two real numbers. Only the real part may need extra space for a 15-pixel sign. Thus, there are 343 px left for the digits, allowing for

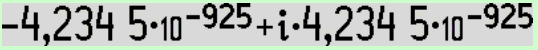


i.e. 8 decimals per part in worst case (since 44 + 15 + 2 × (16 + 8 + 48 + 8 + 48 + 8 + 32) = 59 + 2 × 159 = 397 px in total). This applies if both real and imaginary parts are in the same order of magnitude and the multiplication cross is chosen.

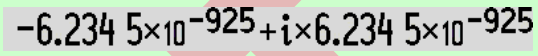
With SCI or ENG, a minimum of 3 decimals can be shown:



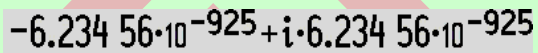
Using multiplication dots, displaying one decimal more is feasible:



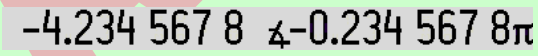
Else, 13 pixel wide narrow digits will allow for 4 decimals even with multiplication crosses:



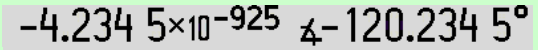
With dots instead of crosses, 5 decimals minimum are feasible for both parts here:



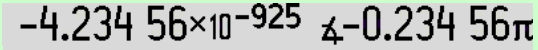
Complex numbers in polar notation require 32 px for a plus 16 px for the angular unit in addition to the space for two signed real numbers. Both magnitude and angle may need a 15-pixel sign. Thus, there are 322 px left for the digits, allowing for 7 decimals output in FIX:



With SCI or ENG, the minimum number of decimals depends on the angular display mode since output is confined to the interval –180° to +180° or its equivalents, e.g. –π to +π in *radians* or -200^g to $+200^g$ in *gon* (see *Sect. 2* of the *OM*). Hence, the angular parts can be displayed without exponents always. This allows for a minimum of 4 decimals for *degrees* and *gon*:



For *radians* or *multiples of* π, however, a minimum of 5 decimals can be displayed always:

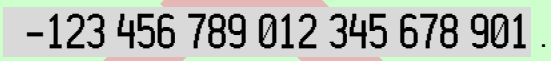


Digits in **fractions** (and exponents) are 13 px wide. Thus, 4-digit numerator and denominator take 4 × 13 + 8 = 60 px each; the fraction

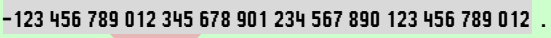
bar takes another 16 px and the trailer 27. The remaining 237 px would suffice for 11 digits, the 16-pixel gap between integer and fraction, and the optional sign (15 + 12 × 16 + 3 × 8 = 231 px) in a proper fraction:

So we would need 394 px in total here (cf. *Section 2* of the *OM*).

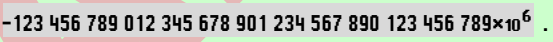
For ***infinite integers***, up to 21 digits and a sign may be displayed using large digits:



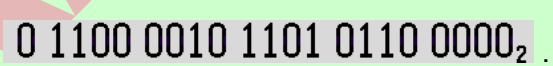
Larger *infinite integers* are shown using the small font, allowing for 42 digits and a sign:



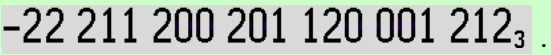
Even larger infinite integers are displayed with an exponent replacing as many of their least significant digits as necessary:



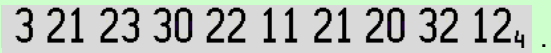
For unsigned ***finite integers***, up to 21 *bits* may be shown in large digits in binary representation:



Base 3 (with narrow blanks every three digits) allows for displaying 20 digits and a sign:



Base 4 (with narrow blanks every two digits) allows for showing 19 digits representing 38 *bits*:



Also bases 5, 6, and 7 allow for displaying 20 digits and a sign like base 3, base 8 for 19 digits like base 4 (but representing 57 *bits* in base 8).

By using the narrow digits provided, up to 25 *bits* may be shown in binary representation:

$$0\ 1110\ 1100\ 0010\ 1101\ 0110\ 0000_2 .$$

Then 24 digits and a sign can be displayed for bases 3, 5, 6, and 7, as well as 22 digits for bases 4 and 8. Longer integers in bases 2 – 6 must be displayed using the small font. This allows for showing up to 44 *bits* in binary notation:

$$1110\ 1100\ 0101\ 1101\ 0110\ 1110\ 1100\ 0010\ 1101\ 0110\ 0000_2 .$$

41 digits and a sign can be displayed for base 3 being already sufficient for 64 *bits*, as well as the 39 digits theoretically displayable for base 4.

For showing all possible 64 *bits* in binary notation, two special 5 pixel wide characters were created:

$$111_0\ 11_{00}\ 00_1\ 11_0\ 1_{01}\ 1_{11}\ 111_0\ 11_{00}\ 00_1\ 11_0\ 1_{01}\ 1_{11}\ 111_0\ 11_{00}\ 00_1\ 11_0\ 1_{01}\ 1_{11}\ 0000_2 .$$

Summing up, for given base and word size, the following fonts will do for finite integers:

Base ▼	Allowable size of digits for display			
	large	narrow	small	special
2	≤ 21 *bits*	≤ 25 *bits*	≤ 44 *bits*	≤ 64 *bits*
3	≤ 31 *bits*	≤ 38 *bits*		
4	≤ 38 *bits*	≤ 44 *bits*		
5	≤ 46 *bits*	≤ 55 *bits*		
6	≤ 51 *bits*	≤ 62 *bits*	≤ 64 *bits*	
7	≤ 56 *bits*			
8	≤ 57 *bits*	≤ 64 *bits*		
> 8	≤ 64 *bits*			

One row of four arbitrary **real matrix elements** (with absolute values $< 10^{100}$) takes 399 px in small font, SCI 3:

$$\left[-6{,}609\cdot10^{-19}\ \ -6{,}609\cdot10^{-19}\ \ -1{,}609\cdot10^{-19}\ \ -1{,}609\cdot10^{-19}\right]$$

... using multiplication dots. Else you will lose one decimal. A slightly different notation allows for SCI 4:

$$\left[-6.609\ 2\text{E}^{-19}\ \ -6.609\ 2\text{E}^{-19}\ \ -1.609\ 2\text{E}^{-19}\ \ -1.609\ 2\text{E}^{-19}\right]$$

Matrices with more than four columns will need ellipses added on one or both sides:

$$\left[\ldots\ -6{,}609\ 2\cdot10^{-19}\ \ -6{,}609\ 2\cdot10^{-19}\ \ -1{,}609\ 2\cdot10^{-19}\ \ \ldots\right] .$$

... allowing to display a section of three elements in SCI 4 format. Using multiplication crosses will cost one decimal.

Vertically, each such matrix row requires 20 px as other small font strings do. Within the space of 3 standard numeric output rows, 3 × 32 + 2 × 5 = 106 px are available, allowing for 5 matrix rows (5 × 20 + 4). Thus, a 5×4 real matrix can be displayed entirely always, using SCI 3 in worst case.

In consequence, any chosen 3×3 section out of a real matrix of arbitrary size can be shown in SCI 3 minimum with surrounding ellipses. In FIX format, 8 decimals can be displayed always.

In analogy, for a **complex matrix** of arbitrary size any chosen 3×2 section can be displayed in FIX 6 format maximum with surrounding ellipses like

$$\left[\ldots\ -6.609\ 226+\text{i}\cdot6.609\ 226\ \ \ -1.609\ 226+\text{i}\cdot1.609\ 226\ \ \ldots\right]$$

while displaying complex matrix elements featuring large exponents may become inconvenient very soon, regardless of the symbols used:

$$\left[\ldots\ -6.60\text{E}^{-199}+\text{i}\cdot6.60\text{E}^{-199}\ \ -1.60\text{E}^{-199}+\text{i}\cdot1.60\text{E}^{-199}\ \ \ldots\right] .$$

Also displaying an arbitrary 3×3 section out of a larger complex matrix is viable up to FIX 3 as long as the numbers stay in a reasonable range:

$$\left[\ldots\ -6{,}609+\text{i}\cdot6{,}609\ \ \ -6{,}609+\text{i}\cdot1{,}609\ \ \ -1{,}609+\text{i}\cdot1{,}609\ \ \ldots\right] .$$

One row of **alphanumeric text** will typically take some 40 characters. The actual number will vary depending on their individual widths as mentioned above.

The *status bar* is a good example for such an alphanumeric row: Loaded to maximum, it might look like

2017-05-08 23:49 Rʟ∠π /3 546f 64:υ A

containing 45 characters.

Putting the alphabet in a row allows for

abcdefghijklmnopqrstuvwxyz ABCDEFGHIJKLMN

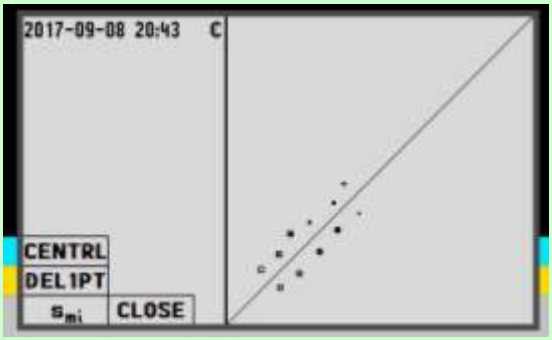
i.e. 41 characters.

Echoing command input requires up to 16 characters (the 17th will close input) for a 7-character command indirectly addressing a 7-character variable entered in *AIM*. This can be done in either font.

Command and variable names in menus were discussed on top of p. 165 already. Although seven characters are allowed for such names, six may well fill the screen space available there. Thus, it is recommended to keep such names as short as possible, though meaningful.

Plotting?

It is mentioned elsewhere we are not out for creating a graphing calculator. There is, however, a very useful application where a basic scatter plot of measured data points would support decision making significantly (see the 3rd industrial statistics application example in *Section 2* of the *OM*). This would require the statistical data (e.g. max. 100 data points, i.e. 100 pairs of x and y values) to



be stored point by point in a matrix, not just summed up as in the *WP 34S* and earlier *RPN* calculators.

The plot could be called by a command PLOT stored in STAT displaying the data points collected in a quadratic diagram. Both axes shall reach from minimum value measured to maximum value measured (plus a little extension which can be calculated based on the data points). Axis scales are not required for analysis so I omitted them. Drawing area has to be quadratic (240 × 240 px for data, 242 × 240 px incl. the vertical axis). Hence softkeys can be positioned on one side of the diagram (max. 3 × 2 labels). The *status bar* would be partially overwritten by the diagram. See the sketch (to scale) for general screen layout and various data point symbols for checking visibility.

CLLCD is modified for clearing just the *LCD* section required for the diagram. – Four characters are provided in small font for 'drawing' the vertical axis and the 45° line:

Alternatively, both lines may be created using AGRAPH and PIXEL (see also the *further considerations* below).

Data points can then be plotted using POINT (containing 3×3 px) – positioning them properly in the diagram, however, will require some background calculations. For POINT, also some of the control modes of *HP-42S* shall be implemented in analogy (the picture below is copied from the *HP-42S OM*, p. 137; settings 1 and 3 should do for our plotting):

Flag 34	Flag 35	How the AGRAPH Image is Displayed
Clear*	Clear*	The image is merged with the existing display (logical OR).
Clear	Set	The image overwrites all pixels in that portion of the display.
Set	Clear	Duplicate "on" pixels get turned "off."
Set	Set	All pixels are reversed (logical XOR).

* Default setting.

Softkey functions could be ...

- CENTRL for fitting the center line to the data points and plotting it for checking deviations from the 45° line (some background calculations in analogy to LINF and L.R. using a special mode for orthogonal regression are required for the plot, setting 1 in the picture above will do when plotting),
- DEL1PT for deleting the data point located most distant from the center line fitted (could be done by plotting it once more using setting 3),
- s_{mi} for calculating the minimum standard deviation of the measuring instrument (some background calculations required again), and
- CLOSE for closing the plot screen, returning to normal display.

It may be beneficial to define a general origin for graphics at a location deviating from 0, 0 (i.e. the bottom left corner of the *LCD*) – the point 158, 0 may be a useful origin. This would allow for creating also other graphics than just the correlation diagrams mentioned above, while reserving a 'protected screen space' for up to six softkeys. Any user may do his own thing in this almost quadratic drawing area then, employing the provided commands AGRAPH, CLLCD, CLOSE, PIXEL, and POINT.

Stack Depth

At a very early stage of this project (2013), *stack* depth was discussed. At the bottom line, eight *registers* turn out being sufficient for solving any real world mathematical problem. An RPL-like 'infinite' *stack* would allow for saving (pushing) everything thereon before calling a (sub-) routine and popping it after RTN but make traditional R↓, R↑, and top level repetition obsolete (and FILL as well); I suggested creating two commands called CLOSES and OPENS for closing the bottom section (4 or 8 *registers*) of an infinite stack for the time when R↓, R↑, FILL, and top level repetition were required, and opening it thereafter.

After all, we decided sticking to *RPN* as implemented on the *WP 34S* and *WP 31S*. It covers everything needed with minimum complexity.

Stack Lift Disabling Functions

Also these functions were subject of discussion. For sake of backward compatibility, we decided to keep them as they were on the *HP-42S* (and *WP 34S* and *WP 31S*): ENTER↑, CLX, Σ+, and Σ− disable *automatic stack lift*, all other functions enable it.

Structured Programming

In 2013, I suggested the following control structures:

- IF – THEN – ELSE – END,
- FOR – FROM – TO – END,
- REPEAT – UNTIL,
- WHILE – END.

Traditional END would need to be called ENDPGM then. Later, we discussed some *PASCAL*-like structures:

- IF – THEN BEGIN – END ELSE BEGIN – END;
- FOR – DO BEGIN – END;
- WHILE – DO BEGIN – END;

We refrained from implementing such commands since we had our doubts about mixing keystroke programming and structured programming features.

UNDO

In 2013, UNDO was planned as it works in *HP-48*, recalling the *stack* as it was before executing last command. *WP 31S*, on the other hand, features an UNDO recalling the entire calculator status as it was...

APPENDIX L: RELEASE NOTES

	Date	Release notes
0	29.11.12	**Official project start with first publication on the forum of the *MoHPC*.** There are found, however, far older traces of a '*43S*' denoting a '*Super HP-42S*', though in various more or less fictional cases – pure vapourware™.
0.1	2.2.14 23.5.15	Manual setup based on the one of *WP 34S*. Passed to *Jake Schwartz*, *Eric Smith*, and *Richard Ottosen* for first information.
0.2	3.10.15	Update based on Jake's feedback and further thoughts, distributed to *Eric*, *Jake*, *Marcus*, and *Pauli*.
0.3	21.3.16	Split the manual in three; moved LBL onto the keyboard, renamed STOM to STOCFG, RCLM to RCLCFG, SERR to s_m, and SERR$_w$ to s_{mw}; refined the *Key Response Table*. Passed to *Michael Steinmann* for information.
0.4	28.3.16	Renamed LOGS to EXP and EEX to E. Added hardware information from 2nd manufacturer.
0.5	29.10.16	Returned EEX. Changed the keyboard layout.
0.6	22.8.17	Merged the Applications and Owner's Manual. Changed the input order of complex number parts on Pauli's request. Changed the keyboard layout introducing D.MS, SST, BST, and % while removing ŷ, RAN#, 'FRC, and 'CFIT. Put 'CFIT into 'STAT and 'FRC into 'MODE. Placed OFF below EXIT for easier customizing. Renamed cc to C5, EEX to E, STOPW to TIMER, SHOW to REGS, 'SOLVE to 'ADV, DLINES to DSTACK, 12h to CLK12, and 24h to CLK24. Replaced IND by →. Deleted %MG since covered by Δ%, added EIGVAL and EIGVEC. Swapped CNST and CONST. Defined the echo rows for alphanumeric and command input. Expanded and modified the character sets for better use of display space. Added the *QRG*.
0.7	2.4.18	Changed keyboard layout. Replaced the labels BST by ▲, SST by ▼, and UNDO by ↶; added some *alpha input mode* reminders on the keyboard. Added AGRAPH, CLLCD, EQ.xxx, HYP, J/G, M.GOTO, ORTHOF, PIXEL, POINT, TDISP, and USER. Moved the background considerations out of *ReM App. D*. Introduced **K** as *alpha register* for alphanumeric constants in programs. Removed

	Date	Release notes
		fraction data type. Extended *items* from 6 to 7 characters to match *HP-42S*. Specified *data types* more precisely in *ReM App. D*. Reduced the maximum number of *local registers* from 888 to 100. Deleted JG1582 and JG1752. Renamed two commands for TVM. Replaced the heading apostrophe for *menu* names. Put SUMS in STAT. Renamed the trigonometric and hyperbolic functions according to mathematical standards, and 🖶CHR to 🖶CHAR. Redistributed the chapter about constants. Modified STATUS display. Refined the unit conversions to ensure *SI* on one side. Specified 0 SEED. Expanded *ReM App. A*. Added formula output for L.R. Modified CPX?, DBL?, and REAL?. Changed output of binary tests for compatibility with *HP-42S*.
0.8	7.5.18 20.9.18	Changed keyboard layout: introduced TRG containing trigonometric functions, removed HYP into EXP and [π] to g-shifted [/], swapped some shifted labels. Refined the chapters about register arithmetic, *Command Parameter Input*, *Alphanumeric Input*, *Matrix Calculations*, and *Orthogonal Polynomials*. Introduced CLCVAR and more vintage examples. Rearranged *temporary information* on the screen. Renamed REGS to RBR and CLx to CLX. Deleted ANGLE. Corrected errors and inconsistencies. Added one more example. Moved the key response table into an appendix.
0.9	3.1.19	Removed *angle data type*. Added another industrial application and many more examples. Exchanged keyboard pictures due to changed bezel. Expanded *App. B*. Added SHOW for displaying full precision of *DP* numbers and FBR for browsing our two fonts. Split a chapter. Expanded some titles. Added the overlay drawing. Modified functionality of [EXIT] and [1/x] to match *HP-42S*. Added a chapter about curve fitting. Modified functionalities of [ENTER↑] and [↩]. Moved the printer character to [f][R/S]. Expanded *App. K*. Renamed DOUBLE to →DP. Added →SP and conversions of quarts. Rearranged X.FN. Replaced [USR] by [UM]. Changed keyboard moving [UM], [√x], and [TRI]. Added XIN and XOUT. Added a chapter in *App. E* and information about infinite integers Extended the domain of GCD and LCM. Refined and corrected.
0.10	25.1.19	Returned *angle data type*. Added IDIVR. Refined the explanation of ALL and the summary of integer functions. Refined FP, IP, IMPFRC, PROFRC, SDIGS?, →DP, →HR, →INT, →REAL, and →SP. Changed the contents of CPX. Added a summary of matrix functions. Corrected.

WP 43S QUICK REFERENCE GUIDE

USING MENUS

A *menu* defines the top row of keys by displaying up to three softkeys above each [^]. If the current *menu* has more than three rows, its current view is limited by a dashed line indicating that it is a *multi-view menu* and [▲] or [▼] can be used to display the additional views of this *menu*.

MEMORY

The stack is a workspace for calculations. Each *stack register* may contain any type of data. Choose a *stack* of four (**X**, **Y**, **Z**, and **T**) or eight *registers* (**X**, **Y**, **Z**, **T**, **A**, **B**, **C**, and **D**). Last ***x*** is saved in *register* **L**.

General purpose registers: There are 100 numbered global general purpose *registers* (00 ... 99). And there are **I**, **J**, and **K** serving special purposes in matrix handling (see p. vii), probability distributions (see p. viii), and programming but may be used globally otherwise. Also **A**, **B**, **C**, and **D** may be used this way unless being part of *stack*. Each *register* may contain any type of data. [STO] ***nn*** stores a copy of ***x*** into **R*nn***, [RCL] ***nn*** recalls a copy of the contents of **R*nn*** into **X**, and [x⇄] ***nn*** swaps ***x*** and the contents of **R*nn***.

Variables are named storage locations that may contain any type of data. E.g. for storing ***x*** into a new variable named **XYZ**, enter [STO] [α] **XYZ** [ENTER↑]. Variable names shall be unique, ≤7 characters long, and contain ≥1 letter.

Flags: There are 112 global user *flags*. Of these, the following have a special meaning if set:

103	**T**	sets print mode to Tracing
105	**B**	Overflow
106	**C**	Carry
107	**D**	allows for infinite and non-numeric results (“Danger”)
109	**I**	allows for complex results

Programs consist of ≥3 program steps: LBL with a global label, at least one action step, and RTN. Each program may contain subroutines (up to 8 levels deep). See p. v for more.

Available memory: [INFO] MEM? (or [FLAGS] STATUS) displays the amount of free memory. Use CLP for clearing programs or clear variables to deallocate memory that is no longer needed.

DATA TYPES

Infinite integers are the simplest type of data. Any number you enter without using [.] or [E] is regarded an infinite integer of base 10.

Real numbers: Any number you enter using [.] and/or [E] is a real number.

Complex numbers: A complex number consists of two real numbers combined to represent its real and imaginary part like 1.23-i×4.56 in rectangular mode (set RECT and press **1.23** [CC] **4.56** [+/-]) or its magnitude and angle like 7.89 ∠-120° in polar mode (set POLAR and press **7.89** [CC] **120** [+/-]).

Angles: Any input of a real number trailed by [d.ms] is interpreted as an *angle* in *sexagesimal degrees*. Alternatively, *angles* may be entered as well in *decimal degrees*, *radians*, *multiples of* π, or *gradians*. Choose the appropriate angular display mode via [MODE] (see overleaf).

Times: Any input of a real number trailed by [h.ms] is interpreted as a sexagesimal *time*. It will be displayed like 23:45:43.210 9 with as many decimal *seconds* as needed.

Dates: Any input of a real number trailed by [.d] is interpreted as a *date* in the format selected (yyyy.mmdd for Y.MD or dd.mmyyyy for D.MY or mm.ddyyyy for M.DY).

Matrices: see the dedicated paragraph on p. vii.

Finite integers: Any numeric input trailed by [#] and a legal base is interpreted as a *finite integer* of the base specified. [D] and [H] are shortcuts for base 10 and 16, respectively. Finite integers may occupy 1 ... 64 bits.

Alphanumeric strings: Any data entered in *alpha input mode* (*AIM*) become such strings when closed (unless they are function parameters). Enter *AIM* by pressing [α]. International (e.g. accented) letters are found in [g] [+]. Greek letters are accessed via [g] plus the corresponding Latin letter. Switch to lower case by [▼] and back to upper by [▲] for all these letters.

Use [f] plus one of the keys [+], [−], [×], [/], [.], and [0] – [9] to enter the corresponding character. Special characters are found in [g] [−] and [g] [.].

[f] [R↓] makes the subsequent character entered a subscript, [f] [E] makes it a superscript, if applicable.

MODES

	1COMPL	2COMPL	UNSIGN	SIGNMT	WSIZE	SETSIG
MODE	DENMAX	DENANY	DENFAC	DENFIX	SSIZE4	SSIZE8
	FAST	SLOW	RM	QUIET	REALRE	CPXRES
	DEG	RAD	GRAD	MULπ	RECT	POLAR

DEG Selects *degrees* as angular display mode.
RAD Selects *radians* as angular display mode.
GRAD Selects *gradians*, a.k.a. *gon*, as angular display mode.
MULπ Selects *multiples of* π as angular display mode.
RECT Sets rectangular format for displaying complex numbers.
POLAR Sets polar format for displaying complex numbers.
FAST Sets processor to normal speed.
SLOW Reduces processor speed (approx. 2 times slower than fast).
RM Sets rounding mode.
QUIET Disables or enables the beeper.
REALRE Allows only real results.
CPXRES Allows also complex results of real calculations (e.g. $\sqrt{-1}$).
DENMAX Sets the maximum denominator for calculating with fractions.
DENANY Any denominator up to DENMAX is legal.
DENFAC Any integer factor of the maximum denominator is legal
DENFIX Sets DENMAX as fixed denominator.
SSIZE4, SSIZE8 Sets *stack* size to four (or eight) *registers*.
1COMPL, 2COMPL One's (two's) complement mode for finite integers.
UNSIGN Unsigned mode for finite integers.
SIGNMT Sign-and-mantissa mode for finite integers.
WSIZE Sets the word size (1 ... 64 bits) for finite integers.
SETSIG Calculator precision (1 ... 34 significant digits).

Display Formats

	DSTACK				LZON	LZOFF
	SCIOVR	ENGOVR	MULT×	MULT·	RDX.	RDX,
	CHINA	EUROPE	INDIA	JAPAN	UK	USA
DISP	ROUND	ROUNDI	RDP	RSD	SDL	SDR
	FIX	SCI	ENG	ALL	DSP	GAP

FIX	Fixed number of decimals.
SCI, ENG	Scientific (or engineering) notation.
ALL	Displays all digits required as far as possible.
DSP	Specifies the number of decimals shown keeping the format.
GAP	Inserts a digit group gap after every ***n*** digits.
ROUND	Rounds a *time*, real, or complex ***x*** to current display format.
ROUNDI	Rounds to next integer.
RDP	Rounds ***x*** to ***n*** decimal places (1 ... 99, think of FIX)
RSD	Rounds ***x*** to ***n*** significant digits (1 ... 34, think of SCI).
SDL, SDR	Shifts digits left (right) by ***n*** decimal positions.
CHINA, EUROPE, INDIA, JAPAN, UK, USA	Sets local display preferences.
SCIOVR, ENGOVR	Specifies the display format if ALL is not viable anymore.
MULT×, MULT·	Selects the multiplication symbol.
RDX., RDX,	Selects the radix mark.
DSTACK	Specifies the number of *stack registers* displayed (1 ... 4).
LZON, LZOFF	Toggles leading zeros for finite integers.

EXECUTING FUNCTIONS AND PROGRAMS

Any function or program can be executed via XEQ α ***name*** ENTER↑ where ***name*** is the function name or the program label. If ***name*** is not unique, the global label closest to the permanent end (.END.) has precedence. If ***name*** is a local label, *WP 43S* searches the current program only.

Smart program menu: XEQ PROGS displays all programs (actually: global labels) defined. Specify the required program by pressing the corresponding softkey.

Single stepping: To execute the current program step, press ≡∇ (or ▼ if no *multi-view menu* is displayed).

The Run/Stop key: Pressing R/S runs the current program beginning with the current step or stops a running program after the current step is complete.

The catalog of functions: Browse CATALOG FCNS and execute the required function by pressing the corresponding softkey. This catalog can be searched alphabetically.

Specifying Function Parameters

Numeric parameters: Functions accepting numeric parameters prompt you with a cursor for each digit expected. To key in a numeric parameter, just

enter its digits. If you provide a digit for each underscore, the function will execute. You can also provide fewer digits and complete input with [ENTER↑].

Alphanumeric parameters: Many functions accept alphanumeric parameters as well. The parameter you want will often be an object already existing, so your *WP 43S* will display a *menu* for quick entry. If it does not exist yet, type it. E.g. for creating a variable **PAUL** just type [STO] [α] **PAUL** [ENTER↑].

Stack parameters: Any function accepting a 'usual' *register* as parameter also accepts a *stack register*. Just press the corresponding softkey for **X** ... **T** or the keys in second row for **A** ... **D**, if applicable.

Indirect addressing: Rather than providing an actual parameter, you can specify the variable or *register* containing the parameter. Just press the softkey [→]. E.g. to display the contents of the variable or *register* specified in **R12**, key in [VIEW] [→] **12** . This works with *stack registers* as well.

CLEARING AND DELETING

[CLR]

					RESET
CLREGS	CLPall	CLFall	CLCVAR	CLLCD	CLall
CLΣ	CLP	CF	CLMENU	CLSTK	CLX

CLΣ Clears all statistical data.
CLP Clears (deletes) the *current program*.
CF ***n*** Clears *flag* ***n***.
CLMENU Clears the *programmable menu*.
CLSTK Clears the entire *stack* (i.e. fills all its *registers* with zero).
CLX Clears *stack register* **X**.
CLREGS Clears all *registers* (except the *stack* and statistical data).
CLPALL Clears (deletes) all programs in *RAM*.
CLFALL Clears all user *flags*.
CLCVAR Clears all variables used in *current program*.
CLLCD Clears the *LCD* above and to the right of pixel ***x***, ***y***.
CLALL Clears everything but the modes set.
RESET Resets the *WP 43S* to *startup default*.

[CATALOG] VARS ... [^] [←] allows for deleting the variable selected.
[CATALOG] MENUS ... [^] [←] allows for deleting the user *menu* selected.
[CATALOG] PROGS ... [^] [←] allows for deleting the program selected.

PROGRAMMING

Program Entry

P/R	toggles *program entry mode*.	
GTO . .	moves the *program pointer* to a new program space.	
GTO . ***nnnn***	moves it to step number ***nnnn***.	
≡Δ	moves it to previous step	(use ▲ or ▼ if no *multi-*
≡∇	moves it to next step	*view menu* is displayed).
←	deletes the *current program step* entirely.	

Labels

A program label is a marker used to identify an entire program or a section within a program. Each program must begin with a global label.

Global labels can be accessed from anywhere in memory (thus, they should be unique). Global labels are alphanumeric and up to 7 characters long.

Local labels can be accessed only within the current program (thus, they should be unique within this program). Local labels are numeric (00 ... 99).

Local registers

... are allocated via LOCR ***n*** with the amount of *registers* specified (≤100). 16 *local flags* come with them. Local data are valid in the calling routine only.

Tests (Do if True, Skip if False)

When a test step (a.k.a. conditional function) is executed, the program step immediately following the conditional is executed if the condition is "true"; if the condition is "false", the step following the conditional is skipped.

Looping

The functions ISE, ISG, ISZ, DSE, DSL, and DSZ (found in LOOP) control looping. Each accesses a variable or *register* containing a loop control number in the form ccccc.fffii with ccccc being the current counter value, fff the final counter value, and ii the increment (or decrement) size (default is 1). As long as the count is not complete, the step following the instruction is executed (usually a branch to the top of the loop). E.g. the program segment pictured here counts from 1 to 52 by threes (executing the loop 18 times) and then beeps.

```
  ...
  1.05203
  STO "Count"
LBL 01
  ...
  ISG "Count"
  GTO 01
  BEEP
  ...
```

USING A VARIABLE MENU

A *variable menu* may be displayed by the *Solver* or the numeric integrator or by VARMNU within a program. Each label in the *menu* represents a variable. While the *menu* is displayed, you can:

Store a value into a variable: Key in the value and then press the softkey.

Recall the contents of a variable: Press RCL and then the softkey.

View the contents of a variable without recalling it: Press VIEW and then the softkey.

Select a variable: Press the corresponding softkey without keying in a number first. (For the *Solver*, this is how you select the unknown variable; for the integrator, this is how you select the variable of integration.)

You can call and use any function *menu* without exiting from the *variable menu*.

MATRIX OPERATIONS

A matrix is an array of real or complex elements. This array has ***m*** rows and ***n*** columns.

To create a new *m* × *n* matrix, enter its dimensions (***m*** ENTER↑ ***n***) and then press

MATX NEW for a matrix in X or

MATX DIM α ***name*** ENTER↑ for a matrix in a variable. If the variable already exists, DIM re-dimensions it.

For editing the matrix in X, use MATX EDIT .

For editing a named matrix, use MATX EDITN ***name***.

When a matrix is being edited it is said to be *indexed* (to index a named matrix without editing it, use INDEX). Whenever there is an indexed matrix, two pointers are used to indicate the row and column of the current element: they are stored in I and J, respectively. If I and J are pointing to the last element (bottom right) in a matrix and you press → then ...

- the pointers wrap around to the first element of the matrix (**Wrap mode**, automatically set whenever you enter or exit the *Matrix Editor*) or ...
- the matrix grows by one complete row and the pointers move to the new row (**Grow mode**).

WRAP and GROW are in the f-shifted row of the *Matrix Editor menu*.

Matrix arithmetic: Most arithmetic and other operations work for matrices just as for individual numbers. Anytime a matrix is used in a mathematical operation with a complex object, the result will be a complex matrix.

To solve a system of simultaneous linear equations represented by the matrix equation $(A)\vec{X} = \vec{B}$:

1. Key in MATX SIM EQ ***n*** with ***n*** being the number of unknowns. Your *WP 43S* will automatically create or re-dimension the matrix variables **Mat_A**, **Mat_B**, and **Mat_X**.
2. Press Mat A; fill the matrix; press EXIT.
3. Press Mat B; fill the matrix; press EXIT.
4. Press Mat X to compute the solution matrix.

PROBABILITY

PROB

	RAN#	SEED				Γ(x)
	Binom:	Geom:	Hyper:	NBin:		Poiss:
	Norml:	LgNrm:	Cauch:	Expon:	Logis:	Weibl:
	t:	Φ:	C_{yx}	P_{yx}	F:	χ^2:

Binom:

$Binom_p$	Binom			$Binom_u$	$Binom^{-1}$

C_{yx} , P_{yx} Returns the number of possible combinations (or permutations, a.k.a. arrangements) of ***x*** items taken out of a set of ***y*** items.

RAN# Returns a random real number between 0 and 1.

SEED Stores a seed for RAN#.

Γ(x) Returns a Gamma function value.

t c *Student's t distribution* (***i*** = degrees of freedom)

Φ c *Standard normal* (or *Gaussian*) *distribution*

F c *Fisher's F d.* (***i*** = degrees of freedom 1, ***j*** = degr. of freedom 2)

χ^2 c *Chi-square d.* (***i*** = degrees of freedom)

Norml: c *Normal d.* (***i*** = ***μ***, ***j*** = ***σ***)

LgNrm: c *Log-normal d.* (***i*** = ***μ***, ***j*** = ***σ***)

Cauch: c *Cauchy-Lorentz* (a.k.a. *Breit-Wigner*) *d.* (***i*** = location, ***j*** = shape)

Expon: c *Exponential d.* (***i*** = rate)

Logis: c *Logistic d.* (***i*** = ***μ***, ***j*** = scale parameter)

Weibl: c *Weibull d.* (***i*** = shape, ***j*** = characteristic lifetime)

Geom:	d	*Geometric distribution*	(***i*** = p_0 = gross probability of a success)
Binom:	d	*Binomial d.*	(***i*** = p_0 , ***j*** = ***n*** = sample size)
Hyper:	d	*Hyperbolic d.*	(***i*** = p_0 , ***j*** = ***n*** , ***k*** = batch size)
NBin:	d	*Negative Binomial d.*	(***i*** = p_0 , ***j*** = ***n***)
Poiss:	d	*Poisson d.*	(***i*** = *Poisson* parameter)

For the distributions, e.g. the *normal* one, Norml_p denotes the *probability density function (PDF)*, Norml the *cumulated distribution function (CDF)*, Norml_u the *error probability*, and Norml^{-1} the *quantile function*. Store the required parameters listed above in **I**, **J**, and **K** as applicable. The remaining parameter must be given in **X** before calling the function.

STATISTICS

Statistical data are accumulated in 14 dedicated *registers*, separate from all the other *registers* introduced above.

Clear the statistical registers before doing a new stat. analysis: STAT **CLΣ**.

Then, accumulate the data:

- For each x-y data pair: ***y-value*** ENTER↑ ***x-value*** **Σ+** .
- For each single-point data value: ***x-value*** **Σ+** .
- For each weighted data point: ***weight-value*** ENTER↑ ***x-value*** **Σ+** .
- For x-y data pairs stored in a two-column matrix (*x-values* in column 1, *y-values* in column 2): Place the matrix in **X** and then press **Σ+** .

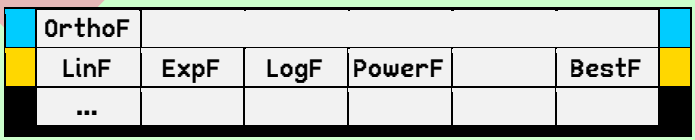
To undo input mistakes or remove erroneous data,

- either press ↶ (for the very last data point)
- or recall the (earlier) incorrect y and x data in the *stack* and press **Σ-** .

Evaluate the data by pressing the corresponding softkey(s) in STAT.

Curve Fitting (and Forecasting) Models

STAT ▲



LINF	Linear fit model:	$y = a_0 + a_1 x$.
EXPF	Exponential fit model:	$ln(y) = ln(a_0) + a_1 x$ or $y = a_0 e^{a_1 x}$.
LOGF	Logarithmic fit model:	$y = a_0 + a_1 ln(x)$.
POWERF	Power fit model:	$ln(y) = ln(a_0) + a_1 ln(x)$ or $y = a_0\, x^{a_1}$.

BESTF Blindly selects the model returning the best correlation coefficient.

ORTHOF like LINF but assumes equal errors in x and y.

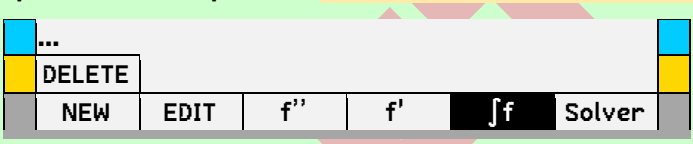
ADVANCED OPERATIONS

EQN is for interactive editing, storing, recalling, solving, integrating, and deriving equations.

ADV is for programmed summing, multiplying, solving, integrating, and deriving.

Interactive Operations on Equations

EQN



For creating a new equation, press NEW. The *Equation Editor menu* will open, and the blue row will display the current equation. Press EXIT when finished.

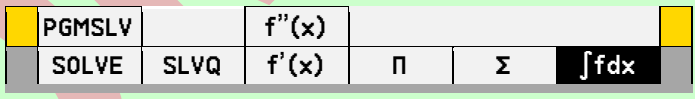
For browsing existing equations, press ▲ or ▼.

For editing (or deleting) the current equation, press EDIT (or DELETE).

For operating on the current equation, press the respective softkey. A *menu* will pop up displaying the names of all variables used and more.

Using Advanced Operations in Programs

ADV



SLVQ solves the quadratic equation $ax^2 + bx + c = 0$ with its parameters on the input *stack* [***c, b, a***, …]. It returns two real or complex solutions.

Π *label* calculates the product of the terms given by the routine specified, using the loop control number given in **X** (cf. p. vi).

Σ *label* calculates the sum of the terms given by the routine specified, using the loop control number given in **X** (cf. p. vi).

SOLVE *var* solves for an unknown variable in an expression, given values for all the other variables. The expression *f(x₁, x₂, ...)* shall be written as a program (let's call it **AB**, for example):

- **AB** must begin with a global label.
- The body of **AB** shall evaluate the expression. For an expression to be solved, it must be coded that $f(x_1, x_2, ...) = 0$ is fulfilled. Recall the variables of the expression as they are required and calculate *f*.
- **AB** must logically end with RTN.

Then write a program calling the *Solver* (let's call it **CD**, for example). At the position where you need the expression solved, press ADV :

1. Press PGMSLV and specify **AB**.
2. Store a value into each known variable, e.g. using STO. Optionally store a guess into the unknown variable to direct the *Solver* to a solution.
3. Press SOLVE and specify the unknown variable.

When running **CD** later on, SOLVE will solve for the unknown.

f'(x) (or **f"(x)**) calculates the first (or second) derivative of *f(x)* at location ***x***. The function *f(x)* shall be written as a program (e.g. called **EF**);; it must begin with a global label, take care of all variables used, and evaluate *f(x)*.

Then write a program calling the derivator (let's call it **GH**, for example).

1. Store a value into each of the variables that shall remain constant under derivation.
2. At the position where you need the derivative, put the respective location into X, then press ADV f'(x) (or f"(x)) specifying **EF**.

When running **GH** later on, the derivative will be returned in X.

∫fd *var* numerically computes a definite integral. The integrand *f(x)* shall be written as a program (e.g. called **IJ**); it must begin with a global label, recall all integration constants used, and evaluate *f(x)*.

Then write a program calling the integrator (let's call it **KL**, for example). At the position where you need the integral, press ADV :

1. Press ∫fdx . A *submenu* will open.
2. Press PGMINT and specify **IJ**.
3. Store a value into each of the variables that shall remain constant under integration, e.g. using STO.
4. Store the lower limit (↓LIM), the upper limit (↑LIM), and the accuracy factor (ACC).
5. Press ∫ and specify the variable of integration.

When running **KL** later on, the integral will be returned in X and the uncertainty of computation will be returned in Y.

OPERATIONS ON FINITE INTEGERS

	1COMPL	2COMPL	UNSIGN	SIGNMT		WSIZE
INTS	DBL /	DBLR	DBL ×	^MOD	CEIL	GCD
	IDIV	RMDR	MOD	×MOD	FLOOR	LCM
	A	B	C	D	E	F

A ... F — Digits for bases >10.

IDIV ℝ — Integer divide.

RMDR, MOD ℝ — Remainder and modulo.

×MOD, ^MOD ℝ — Returns $(z \cdot y) \bmod x$ or $(z^y) \bmod x$, respectively.

FLOOR ℝ — Returns the greatest integer $\leq x$.

CEIL ℝ — Returns the smallest integer $\geq x$.

LCM — Returns the least common multiple of x and y.

GCD — Returns the greatest common divisor of x and y.

DBL /, DBLR, DBL× — Double *word* length commands for division, remainder, and multiplication.

For the commands 1COMPL through WSIZE see *MODES* on p. iii.

	LJ					RJ
	SL	RL	RLC	RRC	RR	SR
BITS	SB	BS?	#B	FB	BC?	CB
	NAND	NOR	XNOR		MIRROR	ASR
	AND	OR	XOR	NOT	MASKL	MASKR

AND, OR, XOR, NAND, NOR, XNOR — Boole's binary operators.

NOT — Inverts every bit in $\mathbf{X}$.

MASKL, MASKR — Create masks of x bits on the left (or right) side.

MIRROR — Reflects all bits.

ASR ***n*** — Arithmetic shift x right by ***n*** places.

SB, FB, or CB ***n*** — Sets, flips, or clears bit **#*n*** in x.

BS?, BC? — Checks if bit **#*n*** in x is set (or clear).

#B — Returns the number of bits set in x.

SL, SR ***n*** — Shift x left (or right) by ***n*** places.

RL, RR ***n*** — Rotate x left (or right) by ***n*** places.

RLC, RRC ***n*** — Rotate x left (or right) by ***n*** places through Carry.

LJ, RJ — Adjust the bits set in x to the left (or right).

OPERATIONS ON ALPHANUMERIC STRINGS

Connect strings by pressing [+]. Then x will be appended to the string y. With numeric data in $\mathbf{X}$, their current format is taken into account.