

Standard Motorshield Assignments: Channel A:

D12 - Direction D3 - PWM (work duty) D9 - Brake AO - current sensing.

Channel B:

D13 - Direction D11 - PWM (work duty) D8 - Brake A1 - current sensing

DRV8874 Mode Select

Jumper_3

GND

nmode

Z: Independent

in1_a__pwm_a

brake_a_n → JP104

en/in1a

brake_b_n

→ JP107

pwm_b

en/in1b

ph/in2a

JP112

Jumper_3 in2_a___direction_a

> JP115 Jumper 3

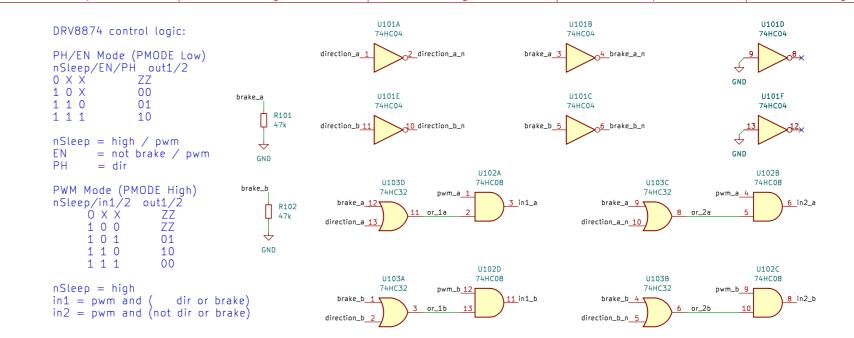
N Jumper_4

Jumper_4

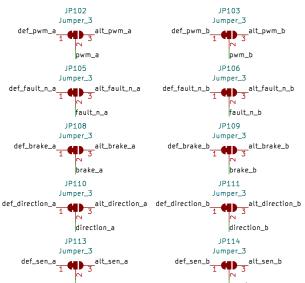
Low: EN/PH

High: PWM

IOREF JP101



GND



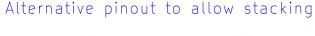
LMV321

100n C114

R114

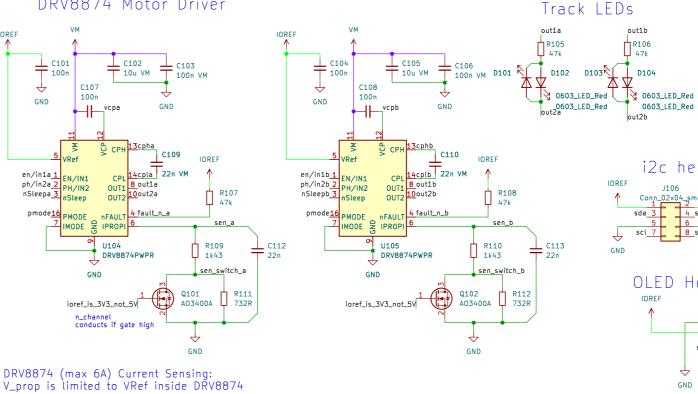
470k

100n C115









DRV8874 (max 6A) Current Sensing:

5V = 0.000455*(1430+732)*A => A=5.08 .3V = 0.000455*1430 *A => A=5.073.3V = 0.000455*1430

if subbed with DRV8876 (max 3.5A): 5V = 0.001*(x+y)*A => A= 3.3V = 0.001* x *A => A *A => A=

candidate values: 3.63/1.65 1% 2k+1k1k8+(680+220) 4.0/1.83 1% 1k5+(680+100) 4.8/2.2 0.2% 1k43+732(extend.) 5.08 0.1% <-- USED HERE (1k2+120)+680 5.5/2.5 0.0% 1k2+(470+180) 5.9/2.7 2% 1k2+620(extend.) 5.9/2.7 0.1% 1k1+560 (0603) 6.6/3.0 0.4%

Power Sheet

Track Connector

out1a 1 J101 out2a 2 MC 1,5/ 2-G-3,5

out1b 1 J103 out2b 2 MC 1,5/ 2-G-3,5

C111 Sda 3 scl 4

GND

out1a out2a J102

R106

IOREF

GND

D104

0603_LED_Red

J106

Conn_02x04_smd

1 2
sda_3 4 sda
5 6
scl_7 8 scl

IOREF

i2c headers

OLED Header

GND

IOREF

1 2 scl 3 sda 4 J107 Conn_01x04_f

Engineer: Erwin Peterlin semify-eda.com Sheet: / File: motor-shield.kicad_sch

Title: Motor Shield

O FID101
Toolinghole_jlc
O FID102
Toolinghole_jlc

O FID103
Toolinghole_jlc

O FID104 Fiducial

O FID105 Fiducial

O FID106 Fiducial

Size: A3 Date: 2023-02-23 KiCad E.D.A. kicad 7.0.1

DCC-EX

File: power.kicad_sch

