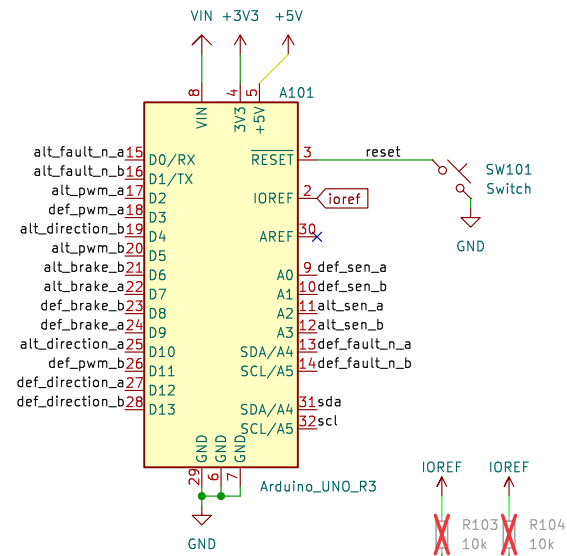


## Arduino Header



## Standard Motorshield Assignments:

Channel A:  
D12 – Direction  
D9 – PWM (work duty)  
D8 – Brake  
A0 – current sensing.

## Channel B:

D13 – Direction  
D11 – PWM (work duty)  
D8 – Brake  
A1 – current sensing

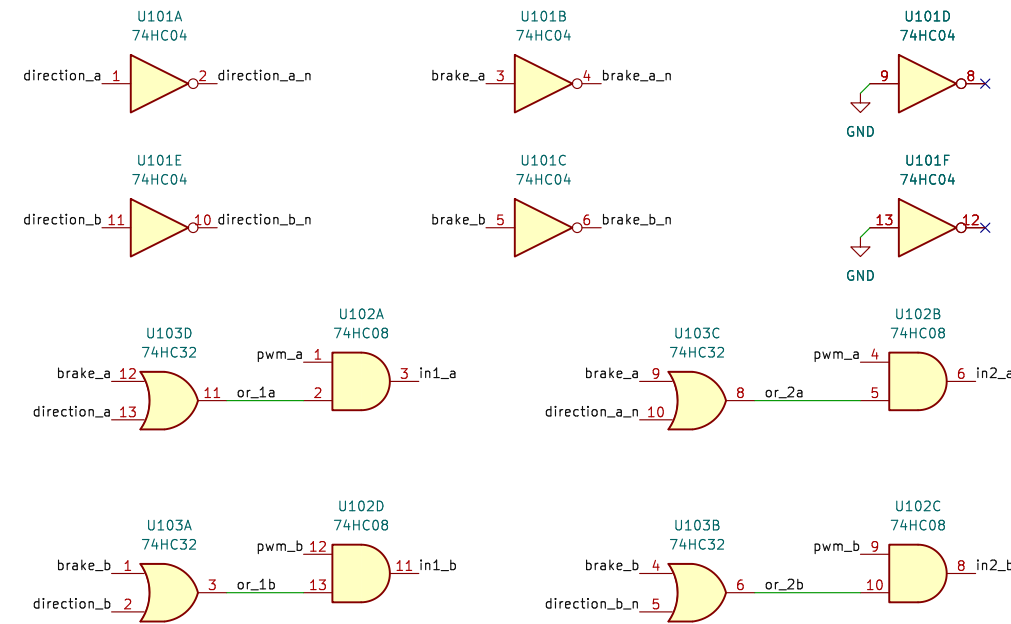
## DRV8874 control logic:

PH/EN Mode (PMODE Low)  
nSleep/EN/PH out1/2  
0 X X ZZ  
1 0 X 00  
1 1 0 01  
1 1 1 10

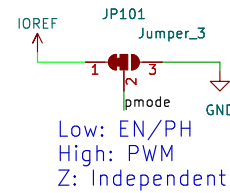
nSleep = high / pwm  
EN = not brake / pwm  
PH = dir

PWM Mode (PMODE High)  
nSleep/in1/2 out1/2  
0 X X ZZ  
1 0 0 ZZ  
1 0 1 01  
1 1 0 10  
1 1 1 00

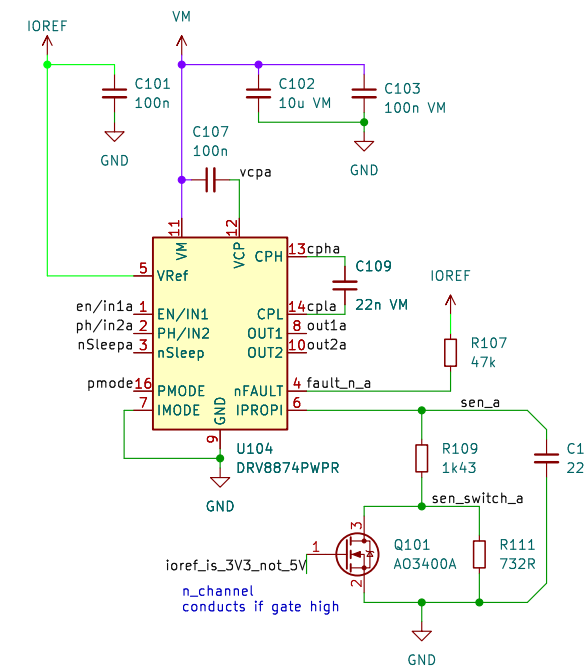
nSleep = high  
in1 = pwm and ( dir or brake)  
in2 = pwm and (not dir or brake)



## DRV8874 Mode Select



## DRV8874 Motor Driver



DRV8874 (max 6A) Current Sensing:  
V<sub>prop</sub> is limited to V<sub>Ref</sub> inside DRV8874

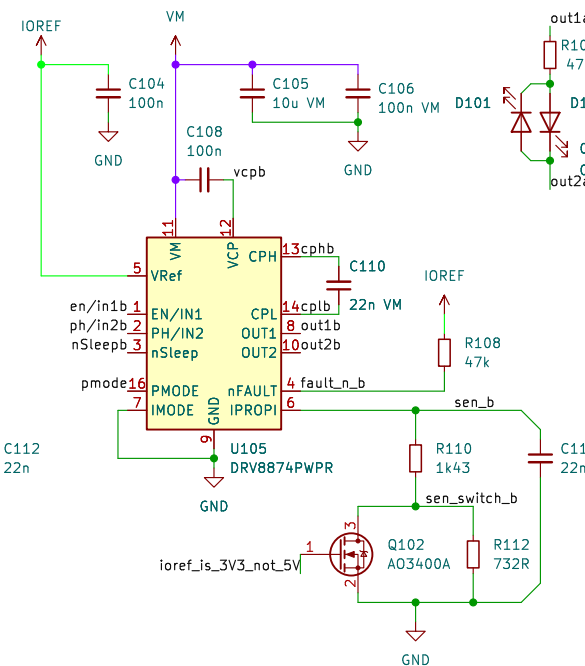
$$5V = 0.000455 \cdot (1430 + 732) \cdot A \Rightarrow A = 5.08$$

$$3.3V = 0.000455 \cdot 1430 \cdot A \Rightarrow A = 5.07$$

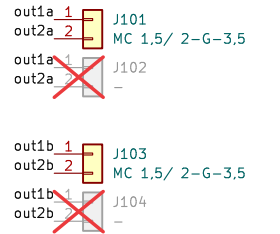
if subbed with DRV8876 (max 3.5A):  
 $5V = 0.001 \cdot (x + y) \cdot A \Rightarrow A =$   
 $3.3V = 0.001 \cdot x \cdot A \Rightarrow A =$

candidate values:  
2k+1k 3.63/1.65 1%  
1k8+(680+220) 4.0/1.83 1%  
1k5+(680+100) 4.8/2.2 0.2%  
1k43+732(extend.) 5.08 0.1% <-- USED HERE  
(1k2+120)+680 5.5/2.5 0.0%  
1k2+(470+180) 5.9/2.7 2%  
1k2+620(extend.) 5.9/2.7 0.1%  
1k1+560 (0603) 6.6/3.0 0.4%

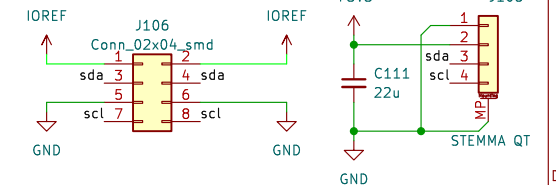
## Track LEDs



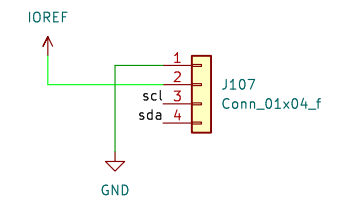
## Track Connector



## i2c headers



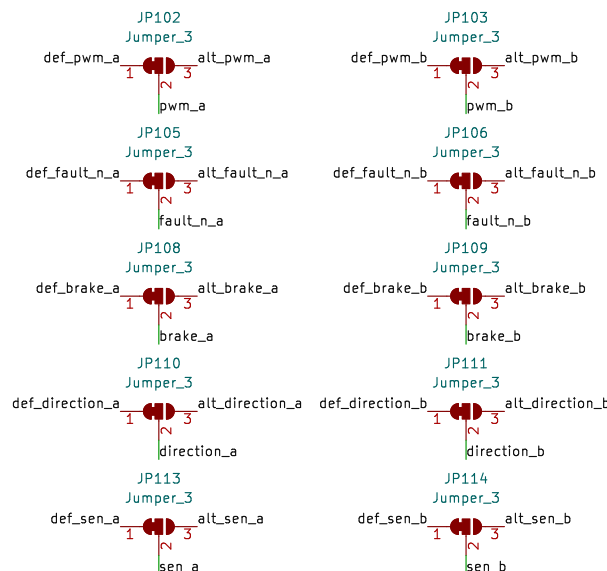
## OLED Header



## Power Sheet



## Alternative pinout to allow stacking



## OpAmp as IORef Comparator

