## Inference Networks

Semih Akbayrak

April 12, 2017

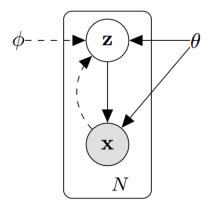
1 / 12

# Outline

- Latent Factor Models
- 2 Variational Inference
- Variational EM
- Variational Inference with Neural Nets

2 / 12

#### Latent Factor Models



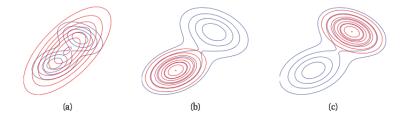
- Interpretable latent factors
- Breaking curse of dimensionality(use for different other tasks like classification)
- Visualization
- Complete missing x vals. restore defficient parts of x
- Explain the data distribution

## Variational Inference

- Approximate p(z|x) with  $q_{\phi}(z)$  by tuning its parameters with optimization methods.
- Objective:  $min\ KL(q_{\phi}(z)||p(z|x))$

4 / 12

# Why Reverse KL?



## Variational Inference

$$\begin{aligned} & \underset{\phi}{min} KL(q_{\phi}(z)||p(z|x)) = \int q_{\phi}(z) \log \frac{q_{\phi}(z)}{p(z|x)} dz \\ & KL(q_{\phi}(z)||p(z|x)) = \int q_{\phi}(z) \log \frac{q_{\phi}(z)p(x)}{p(x,z)} dz \\ & = \int q_{\phi}(z) \log \frac{q_{\phi}(z)}{p(x,z)} dz + \int q_{\phi}(z) \log p(x) dz \\ & = \int q_{\phi}(z) \log \frac{q_{\phi}(z)}{p(x,z)} dz + \log p(x) \end{aligned}$$

$$\log p(x) = L(\phi) + \mathit{KL}(q_\phi(z)||p(z|x))$$
 where  $L(\phi) = -\int q_\phi(z)\log rac{q_\phi(z)}{p(x,z)}dz$ 

•  $\log p(x)$  is constant w.r.t.  $\phi$  so  $\displaystyle \mathop{minKL}_{\phi}(q_{\phi}(z)||p(z|x)) = \mathop{maxL}_{\phi}(\phi)$ 

◆ロト ◆個ト ◆差ト ◆差ト 差 めらぐ

# Variational Inference

$$L(\phi) = -\int q_{\phi}(z) \log \frac{q_{\phi}(z)}{p(x,z)} dz$$

$$= E_q[-\log q_{\phi}(z) + \log p(x|z) + \log p(z)]$$

$$= E_q[\log p(x|z) + \log \frac{p(z)}{q_{\phi}(z)}]$$

$$= E_q[\log p(x|z)] + \int q_{\phi}(z) \log \frac{p(z)}{q_{\phi}(z)} dz$$

$$= E_q[\log p(x|z)] - KL(q_{\phi}(z)||p(z))$$

• we got rid of p(z|x). Use an appropriate optimization method to maximize L w.r.t. variational parameters  $\phi$ .

◆ロト ◆部ト ◆差ト ◆差ト 差 めなべ

# Variational EM

• What if model also has parameters?

$$\log p_{\theta}(x) = L(\theta, \phi) + KL(q_{\phi}(z)||p_{\theta}(z|x))$$

$$\text{E-step: } \phi = \underset{\phi}{\operatorname{argmax}} \mathit{L}(\theta, \phi)$$

M-step: 
$$\theta = \underset{\theta}{\operatorname{argmax}} L(\theta, \phi)$$

where 
$$L(\theta, \phi) = E_{q_{\phi}}[\log p_{\theta}(x|z)] - KL(q_{\phi}(z)||p_{\theta}(z))$$



- Can we approximate p(z|x) with Neural Networks?
- Objective:  $q_{\phi}(z|x) \leftarrow q_{\phi}(z)$

$$\begin{aligned} \max & L(\theta, \phi) = E_{q_{\phi}}[\log p_{\theta}(x|z)] - \mathit{KL}(q_{\phi}(z|x)||p_{\theta}(z)) \\ \min & Loss = \mathit{KL}(q_{\phi}(z|x)||p_{\theta}(z)) - E_{q_{\phi}}[\log p_{\theta}(x|z)] \end{aligned}$$

- First term works as encoder and second term works as decoder.
- A typical autoencoder with additional constraints on hidden layer.

◆ロト ◆部ト ◆恵ト ◆恵ト 恵 めのぐ

• We define a general model

$$p_{\theta}(z) = N(z; 0, I), p_{\theta}(x|z) = N(x; \mu_{\theta}, \Sigma_{\theta})$$
  
 $\mu_{\theta}, \Sigma_{\theta}$  are NNs which take z as input.

 $\theta$ : model parameters, weights of NNs in this model.

$$q_{\phi}(z|x) = N(z; \mu_{\phi}, \Sigma_{\phi})$$

 $\mu_{\phi}, \Sigma_{\phi}$  are NNs which take x as input.

 $\phi$ : variational parameters, weights of NNs in this model.

10 / 12

$$Loss = KL(q_{\phi}(z|x)||p_{\theta}(z)) - E_{q_{\phi}}[\log p_{\theta}(x|z)]$$

First term can be computed analytically.

$$KL(q_{\phi}(z|x)||p_{\theta}(z)) = \frac{1}{2}(tr(\Sigma_{\phi}) + \mu_{\phi}^{T}\mu_{\phi} - dim(z) - \log \det(\Sigma_{\phi}))$$
  
This is differentiable w.r.t.  $\phi$  and does not contain  $\theta$ 

Second term can be computed with Monte Carlo integration

$$E_{q_{\phi}}[\log p_{\theta}(x|z)] pprox rac{1}{S} \sum_{s=1}^{S} \log p_{\theta}(x|z^{(s)}) ext{ for } z^{(s)} \sim q_{\phi}(z|x)$$

However derivative of this integration w.r.t.  $\phi$  is 0 because it doesn't contain  $\phi$  parameters, although z depends on  $\phi$ .

• We will use reparametrization trick.

Instead of 
$$\frac{1}{S}\sum_{s=1}^{S}\log p_{\theta}(x|z^{(s)})$$
 for  $z^{(s)}\sim q_{\phi}(z|x)$  Use  $\frac{1}{S}\sum_{s=1}^{S}\log p_{\theta}(x|z^{(s)})$  for  $z^{(s)}=\mu_{\phi}+\Sigma_{\phi}^{\frac{1}{2}}.\epsilon^{(s)}$  and  $\epsilon^{(s)}\sim N(0,I)$ 

• This is now differentiable w.r.t.  $\phi$ . To compute gradient, we can compute it for every  $z^{(s)}$  and use this value in summation.

Semih Akbayrak Inference Networks April 12, 2017 12 / 12