



# Semillero de Investigación “Hands - on” Computer Vision



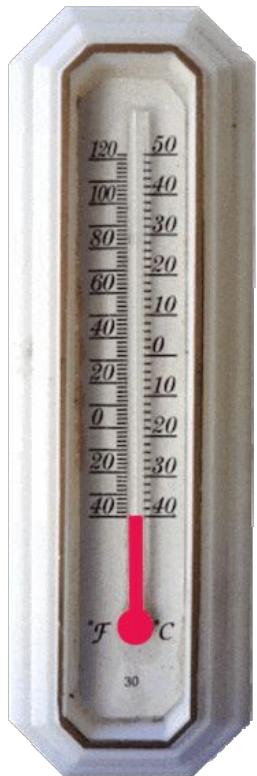
# SESIÓN 8: IMÁGENES TÉRMICAS

# Contenidos

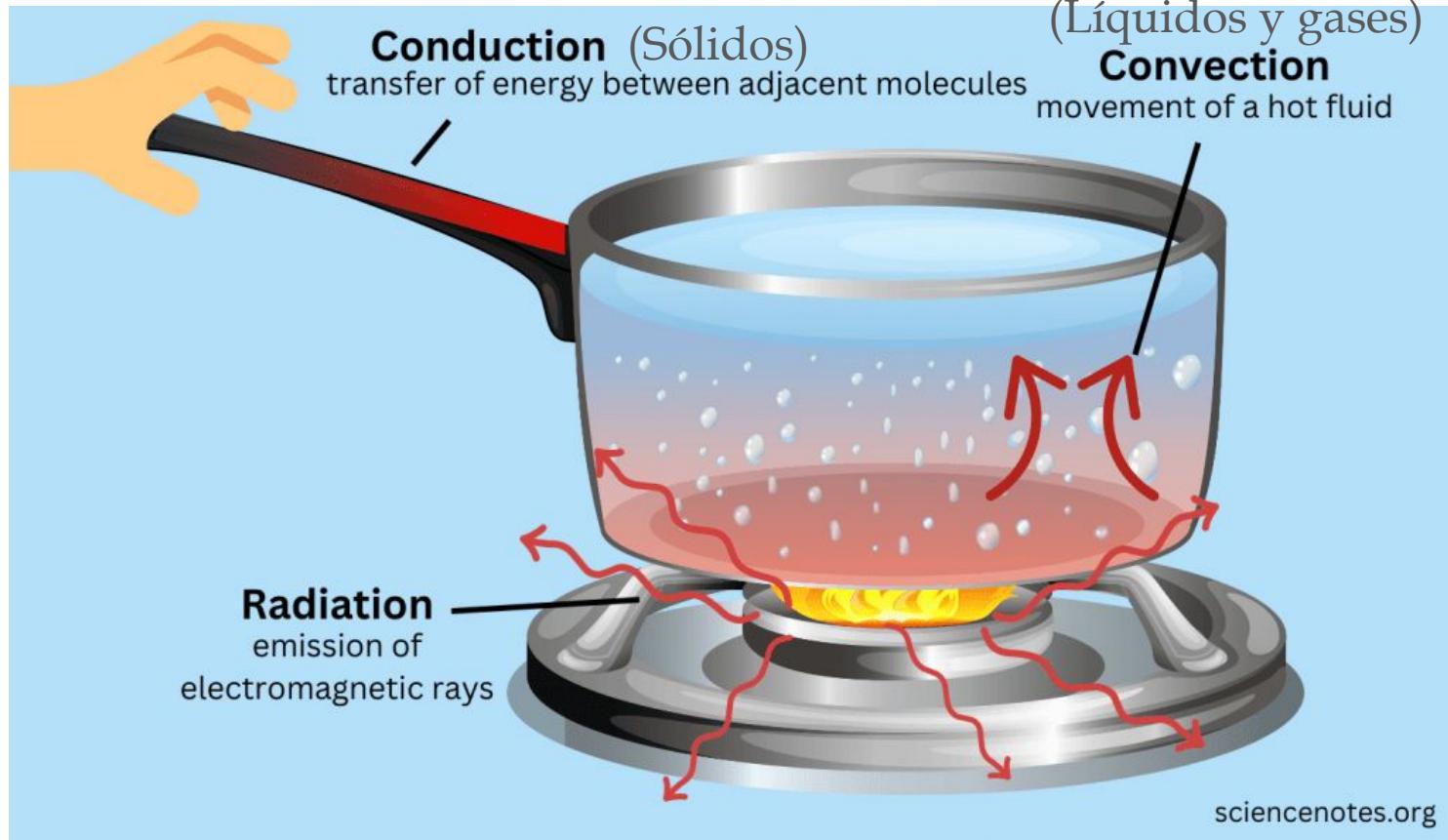
1. Imágenes térmicas y aplicaciones
2. Luz y radiación
  - a. Ley de Kirchhoff
  - b. Radiación de cuerpo negro (Planck)
  - c. Emisividad y atenuación
3. Imágenes espectrales térmicas
4. Sensores infrarrojos
5. Thermal & CV
6. Hands-on Thermal Imaging



# ¿Cómo podemos medir la temperatura?



# Transferencia de calor



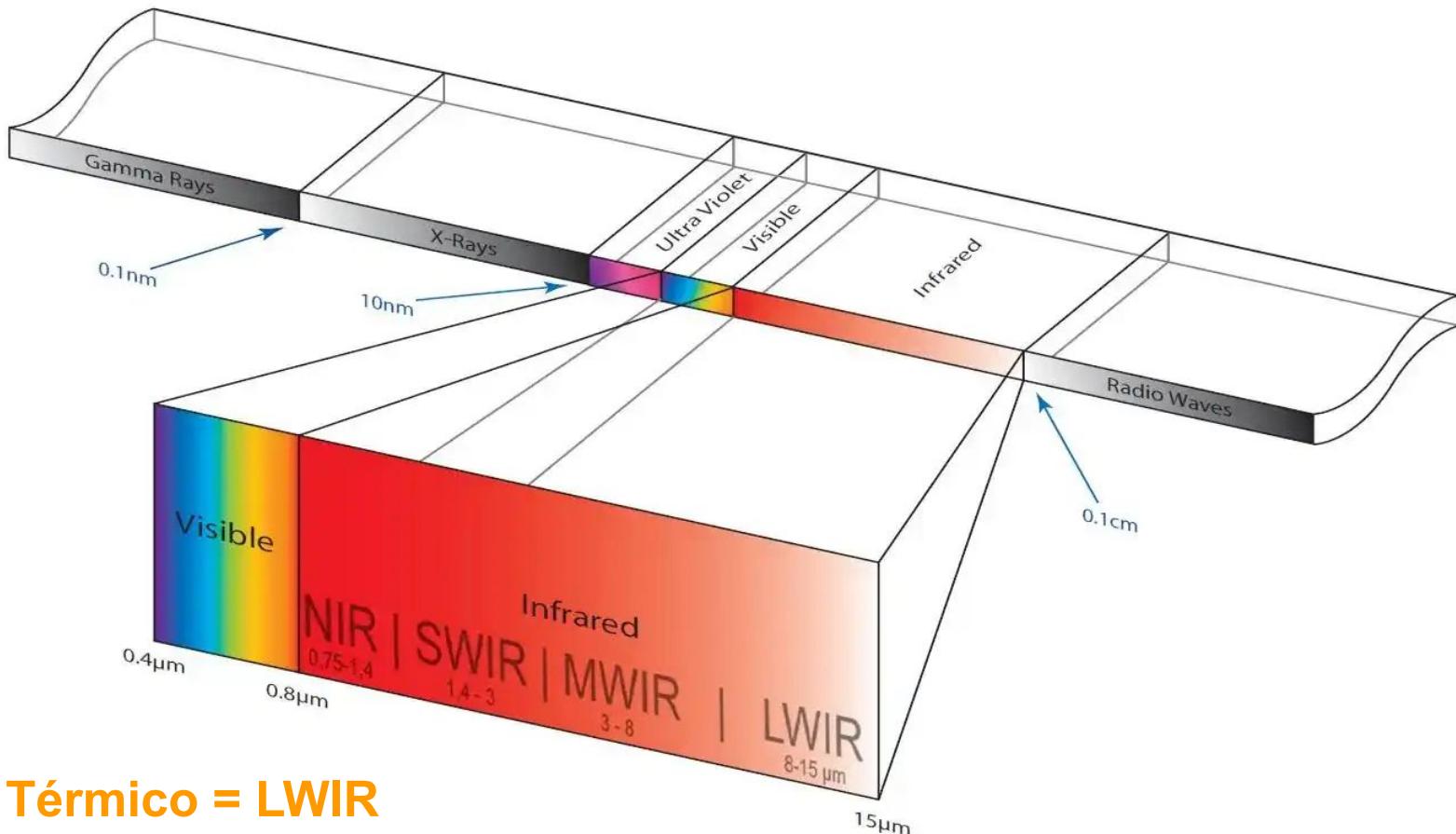
La conducción requiere contacto. La convección requiere flujo de fluido. La radiación no requiere ningún medio.

# 1. Imágenes Térmicas

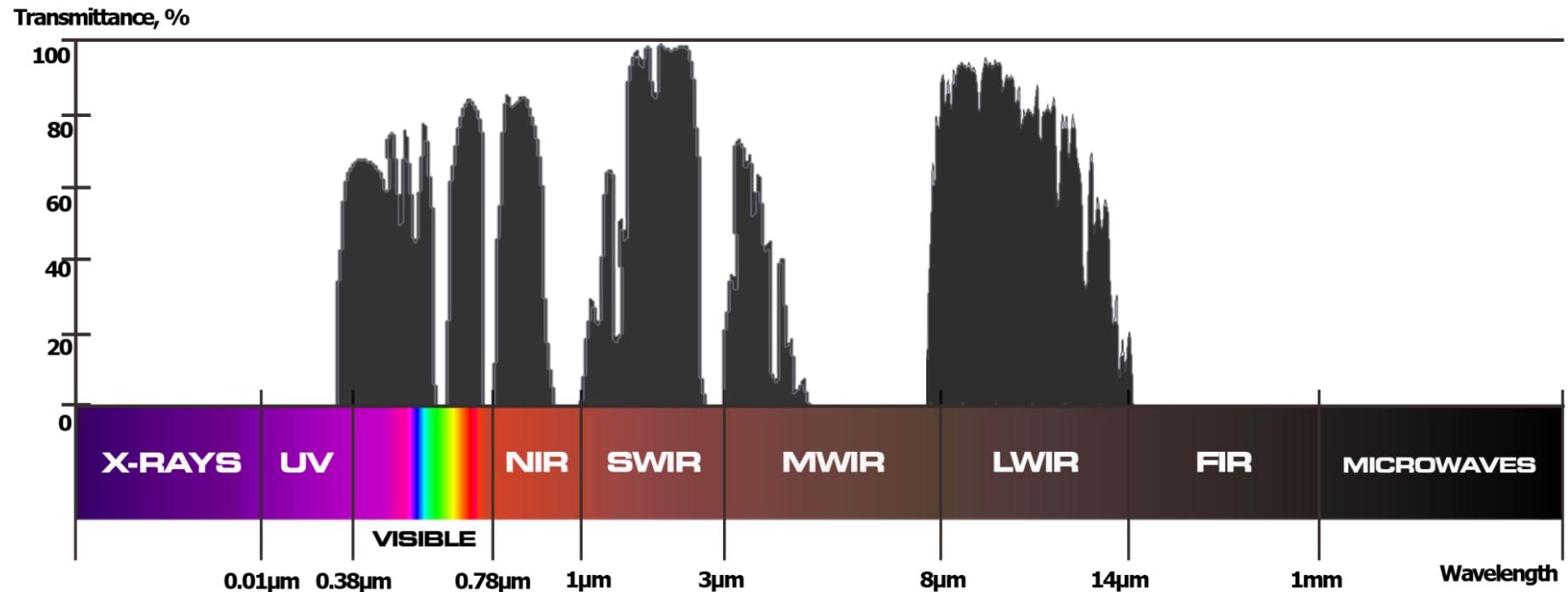
Frederick William Herschel (1738, Germany)

Térmico = LWIR

# Espectro electromagnético

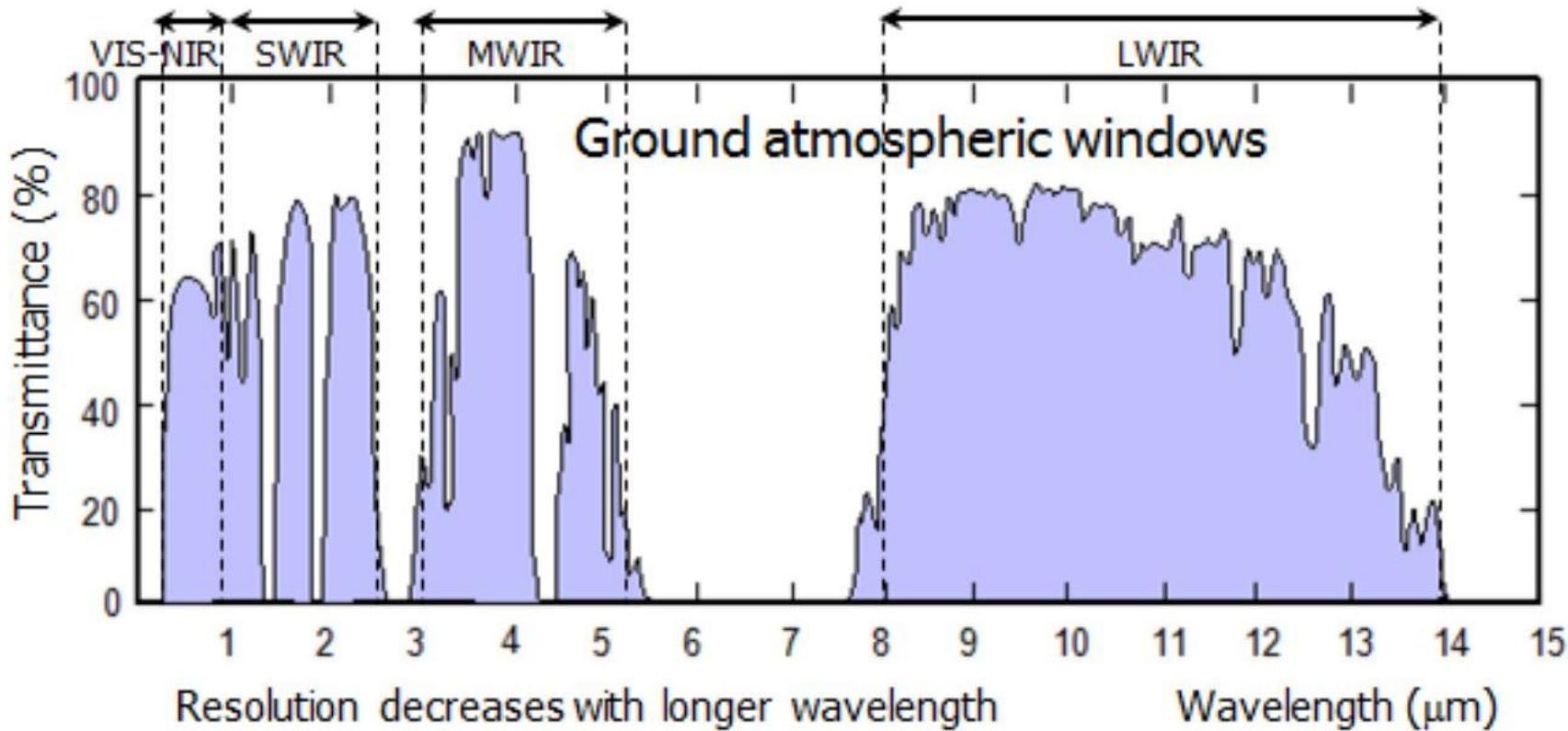


# Espectro electromagnético



Térmico = LWIR

# Importancia de la Atmósfera





**Color**



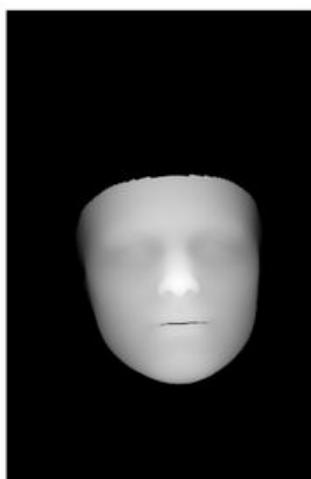
**Infrared**



**SWIR**



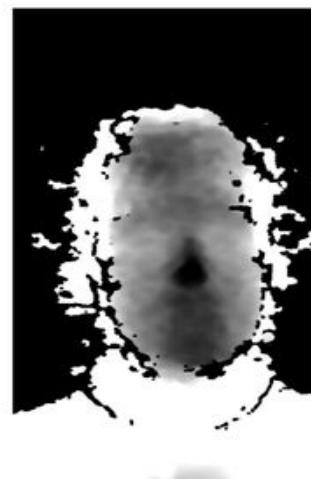
**Thermal**



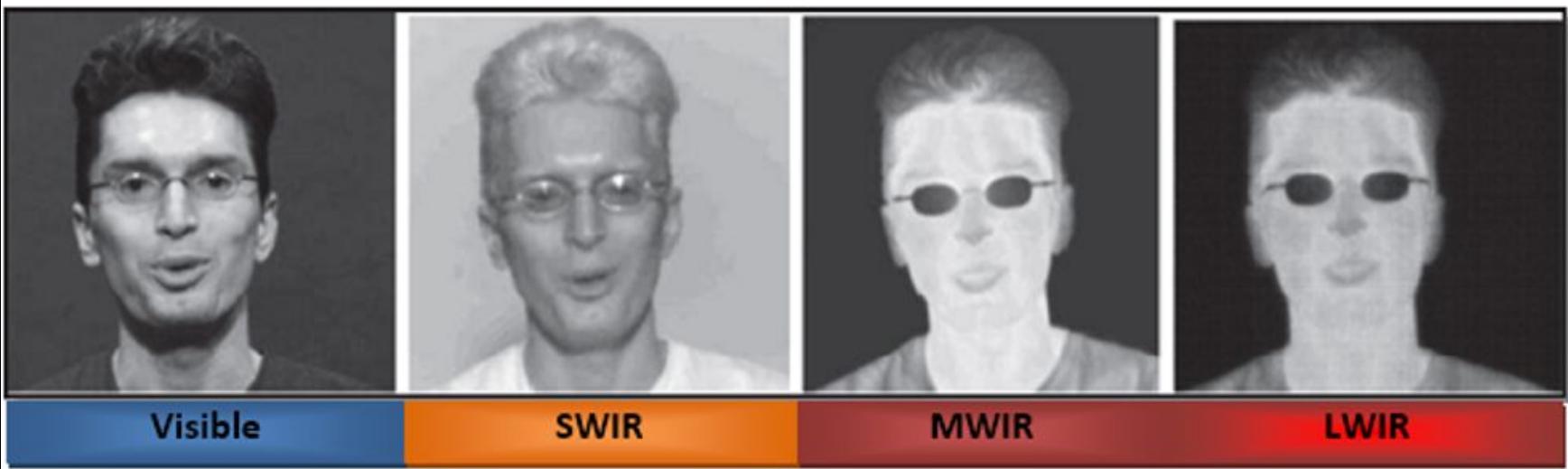
**3DDFA**



**Stereo**



**Depth**



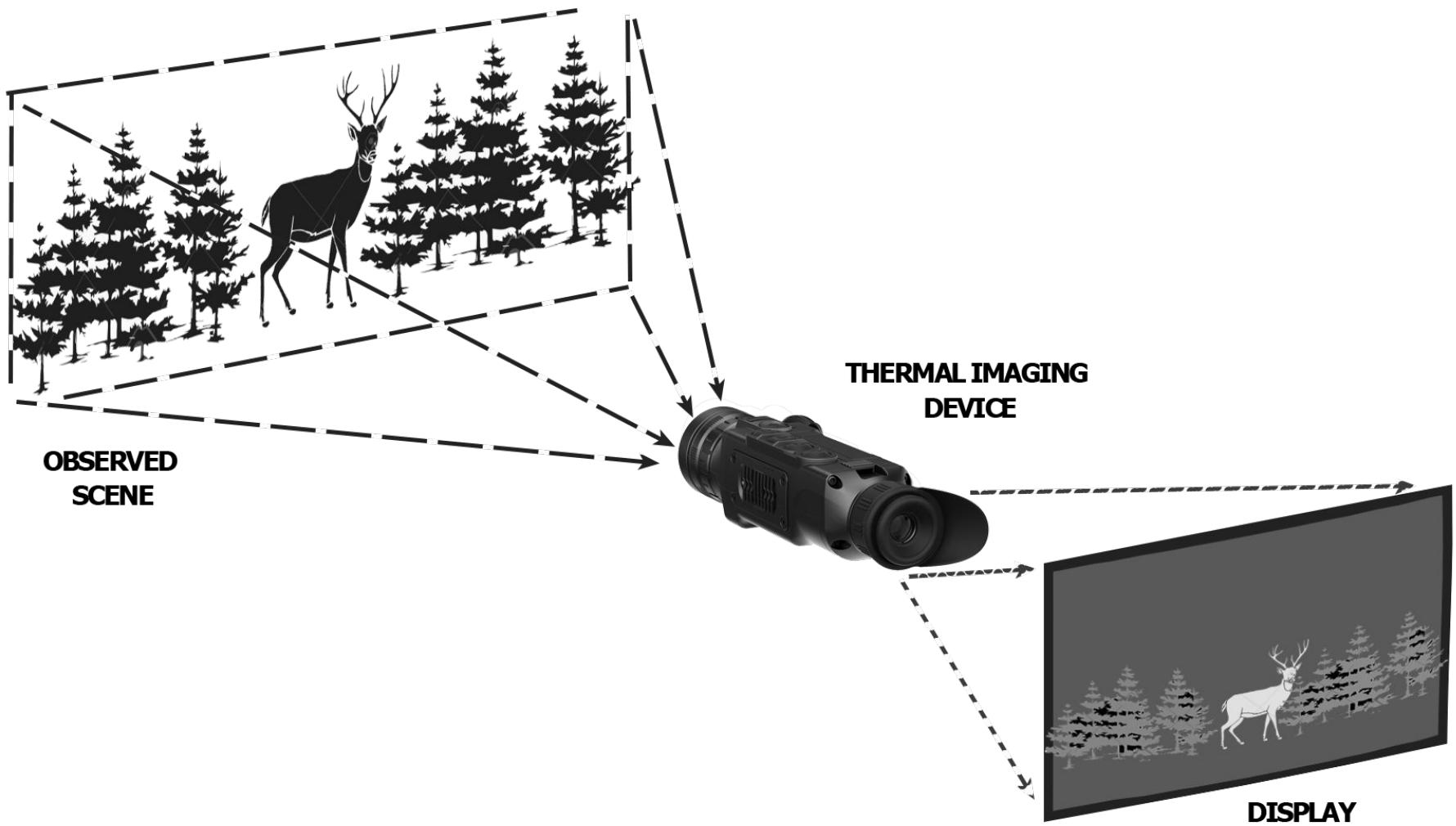
**Visible**

**SWIR**

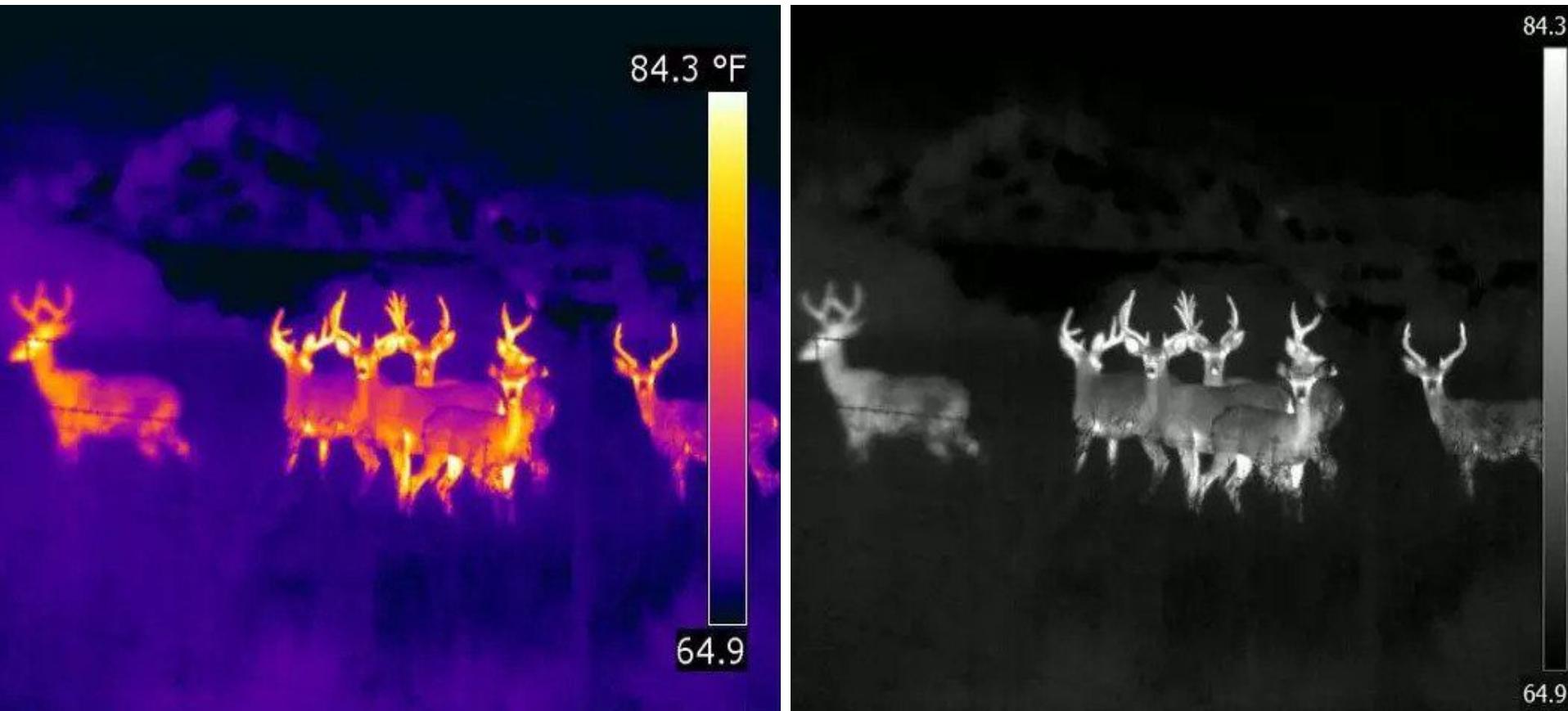
**MWIR**

**LWIR**

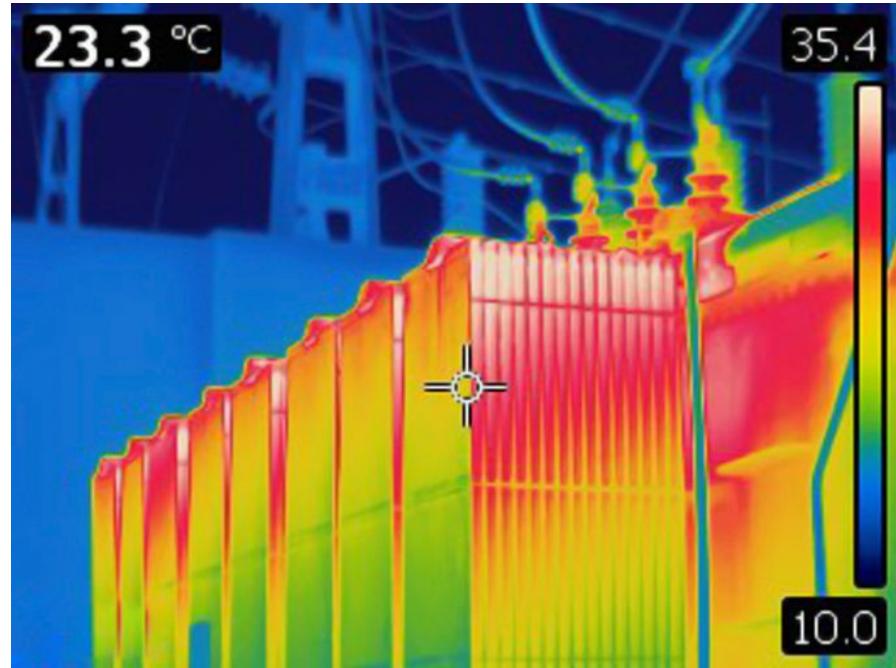
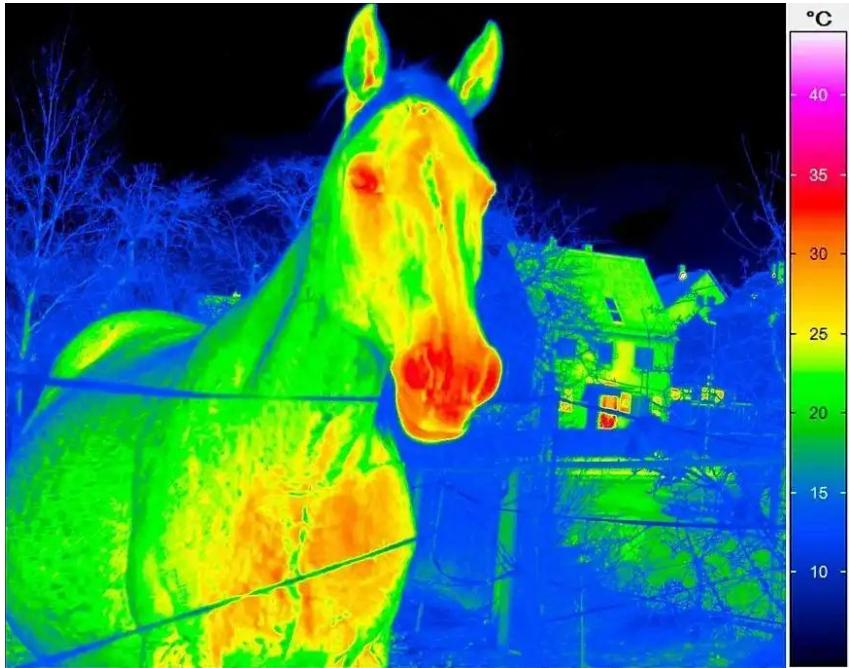




# Imágenes térmicas



# Imágenes térmicas



- Un termograma es una representación digital de la radiación térmica emitida por los objetos
- Las cámaras termográficas permiten detectar esta radiación en forma de luz infrarroja
- Una imagen térmica nos permite detectar de forma remota la temperatura de un objeto



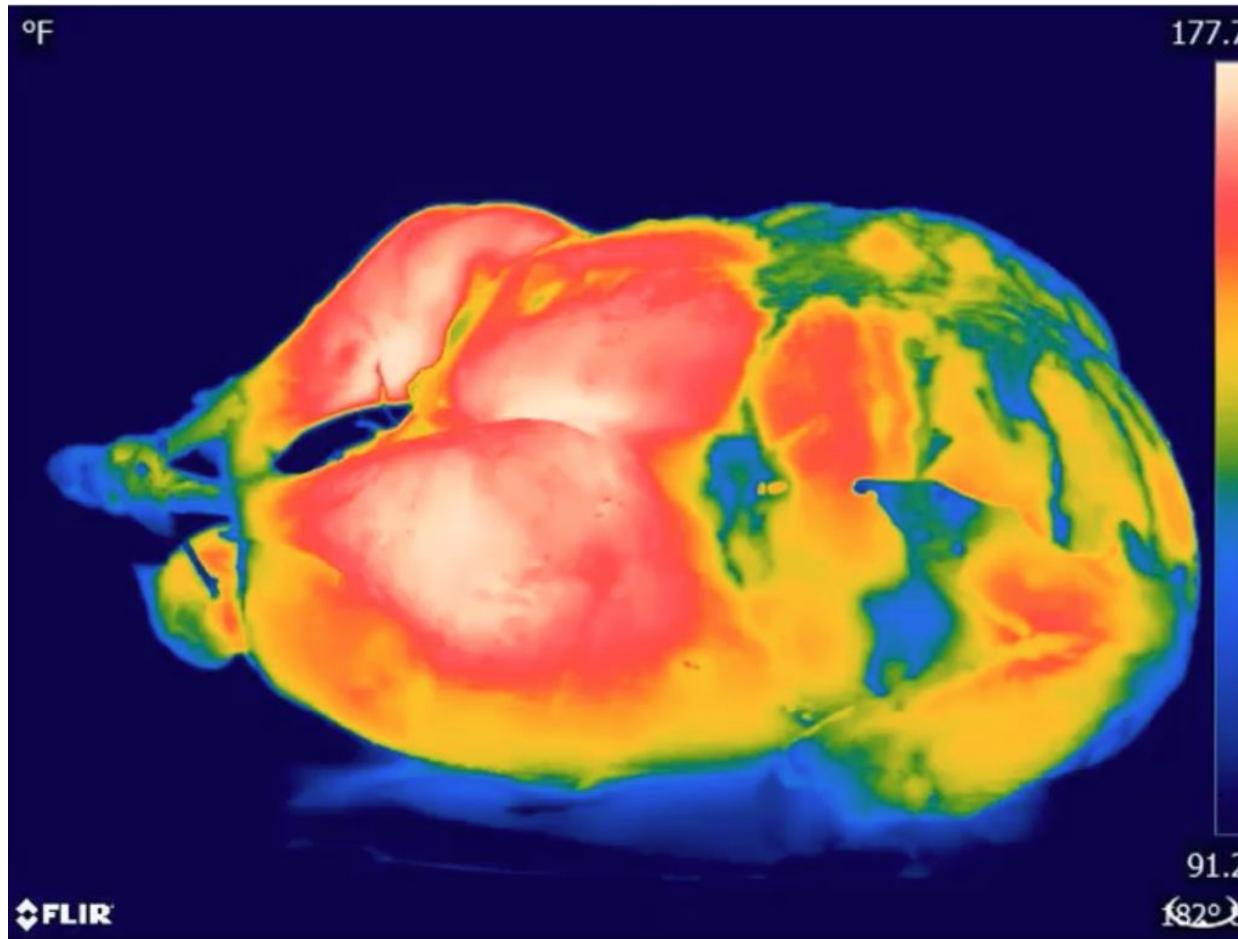
**FLIR** Pioneer



Cool stuff



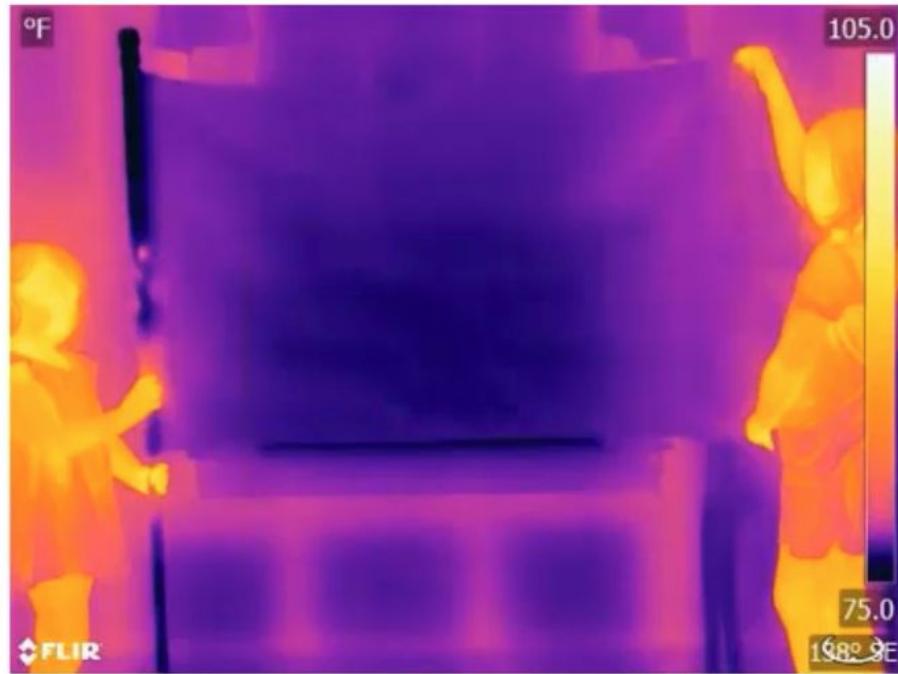
Las alas se enfriaron más rápido (heat capacity, humedad)



# Por qué la bandera se ve diferente?



Afuera de casa



Dentro de casa

# Metales reflejan luz y pueden ser difíciles de medir



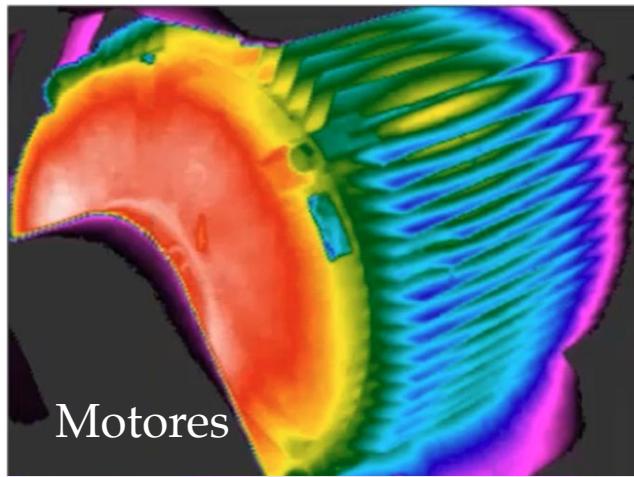
# Los vidrios son opacos en el rango térmico



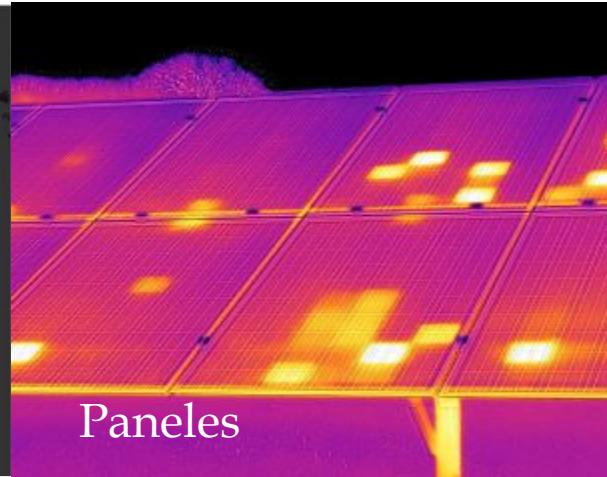
# Aplicaciones



Tanques



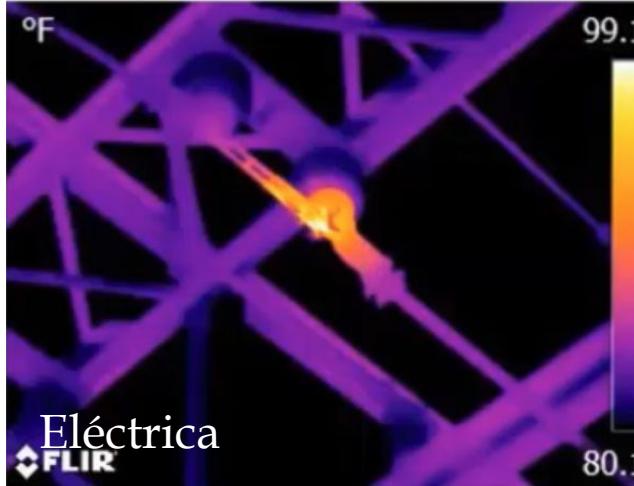
Motores



Paneles



Eléctrica



Eléctrica

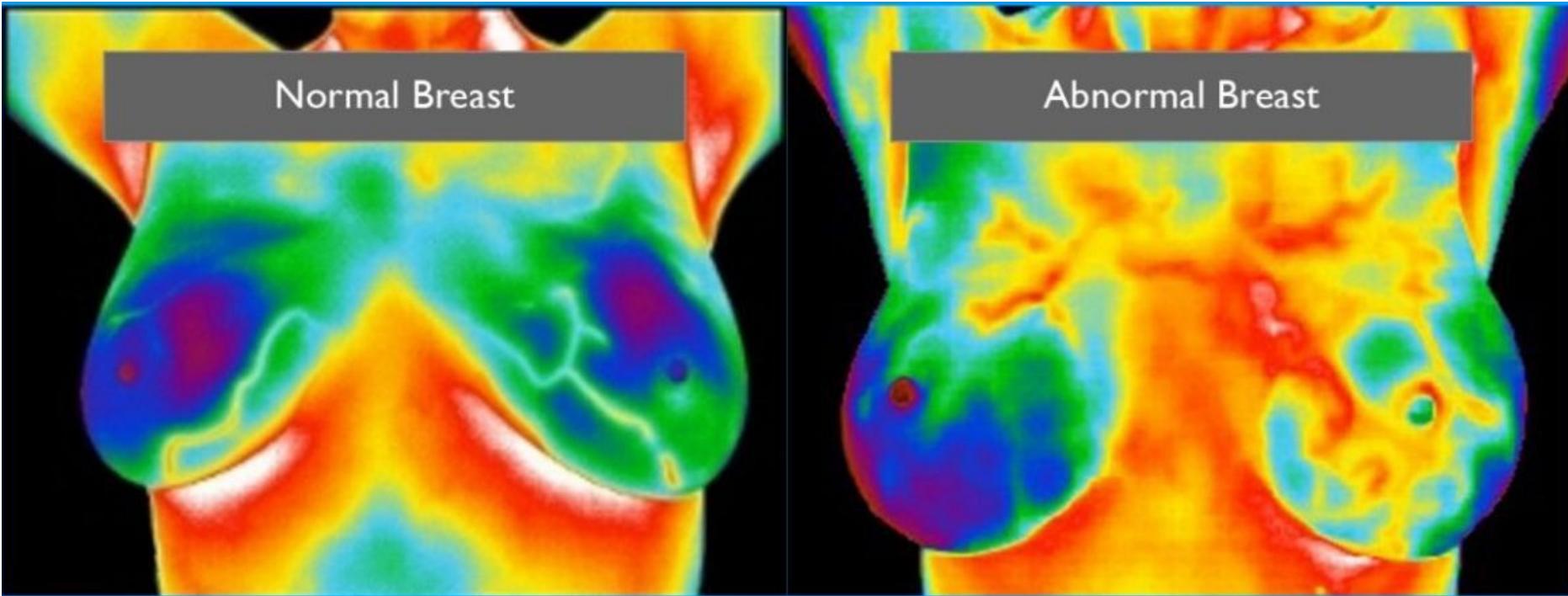


Búsqueda y rescate

# Aplicaciones en Salud

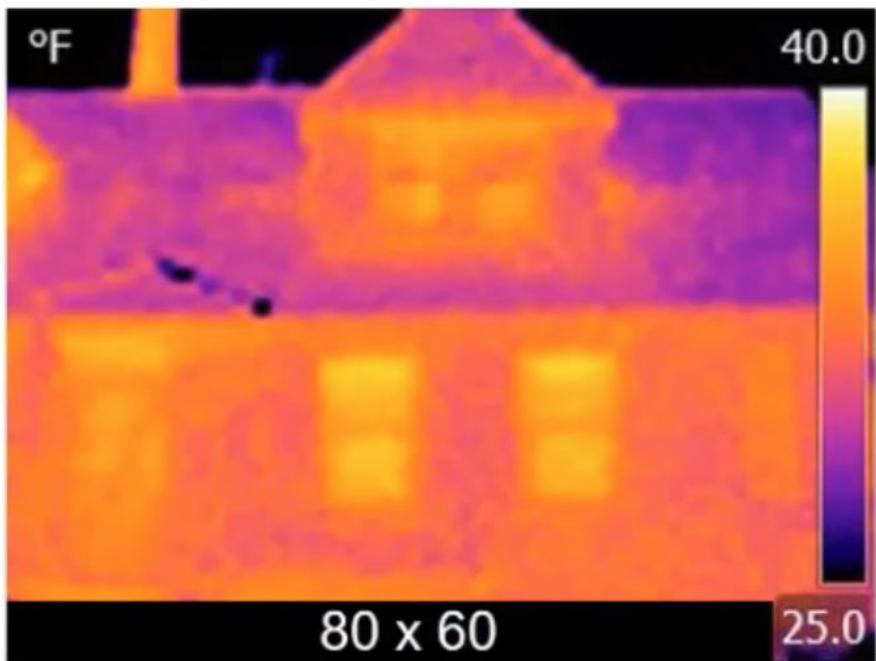
Normal Breast

Abnormal Breast



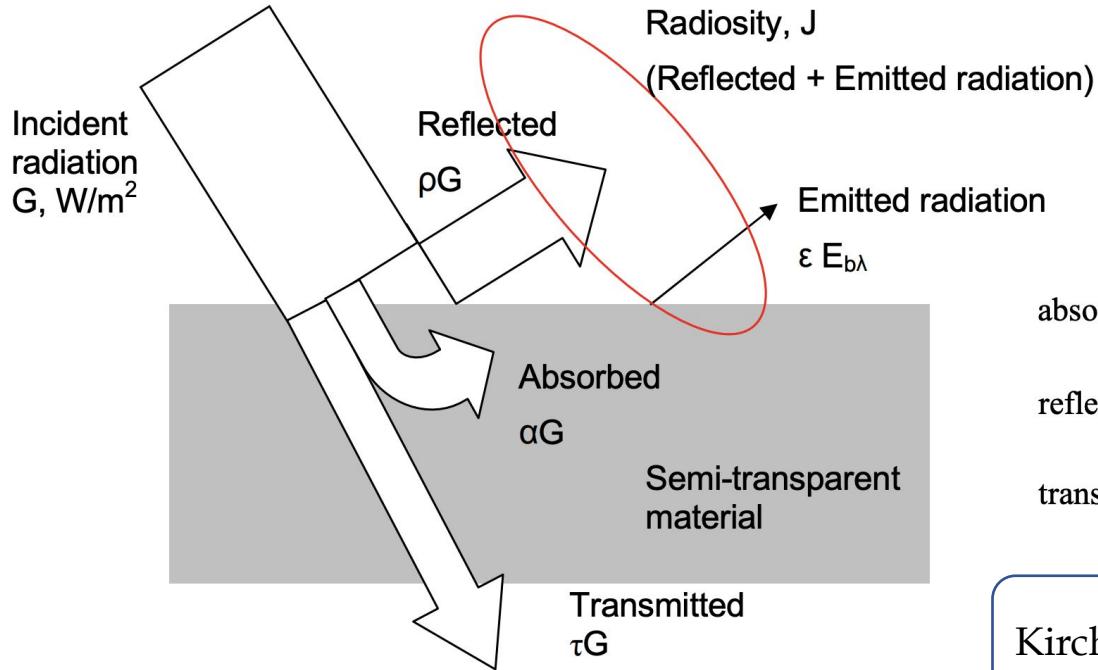


# Efecto de resolución



## 2. Luz y radiación

# Radiation



By first law of thermodynamics  
(conservation of energy):

$$G_{abs} + G_{ref} + G_{tr} = G$$
$$\alpha + \rho + \tau = 1$$

absorptivity :  $\alpha = \frac{\text{absorbed radiation}}{\text{incident radiation}} = \frac{G_{abs}}{G} \quad 0 \leq \alpha \leq 1$

reflectivity :  $\rho = \frac{\text{reflected radiation}}{\text{incident radiation}} = \frac{G_{ref}}{G} \quad 0 \leq \rho \leq 1$

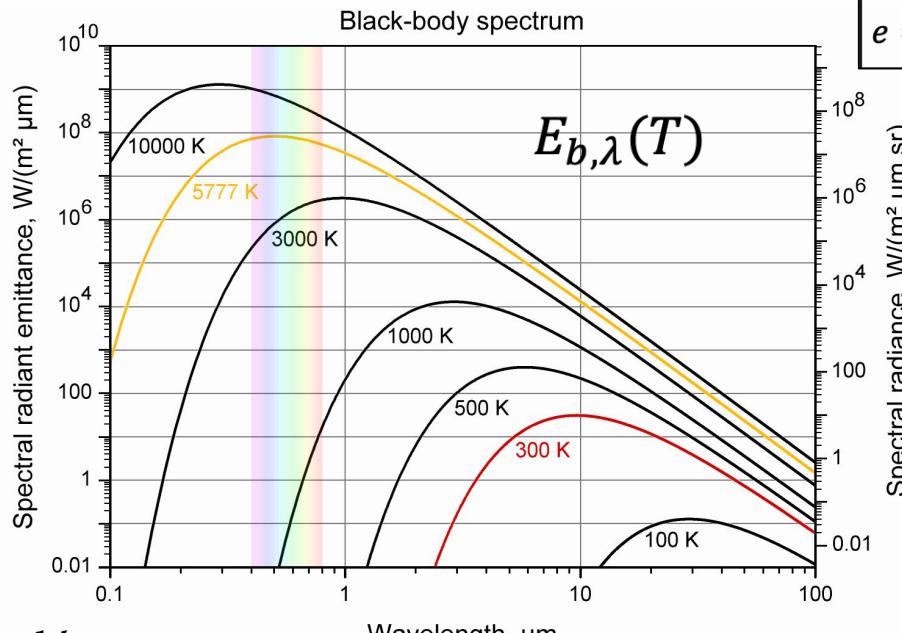
transmissivity :  $\tau = \frac{\text{transmitted radiation}}{\text{incident radiation}} = \frac{G_{tr}}{G} \quad 0 \leq \tau \leq 1$

Kirchhoff's law:  
Transparent ( $\rho = 0$ ):  $\alpha = 1 - \tau$   
Opaque ( $\tau = 0$ ):  $\alpha = 1 - \rho$

The radiation energy incident on a surface per unit area per unit time is called **irradiation**,  $G$ .

# Blackbody radiation

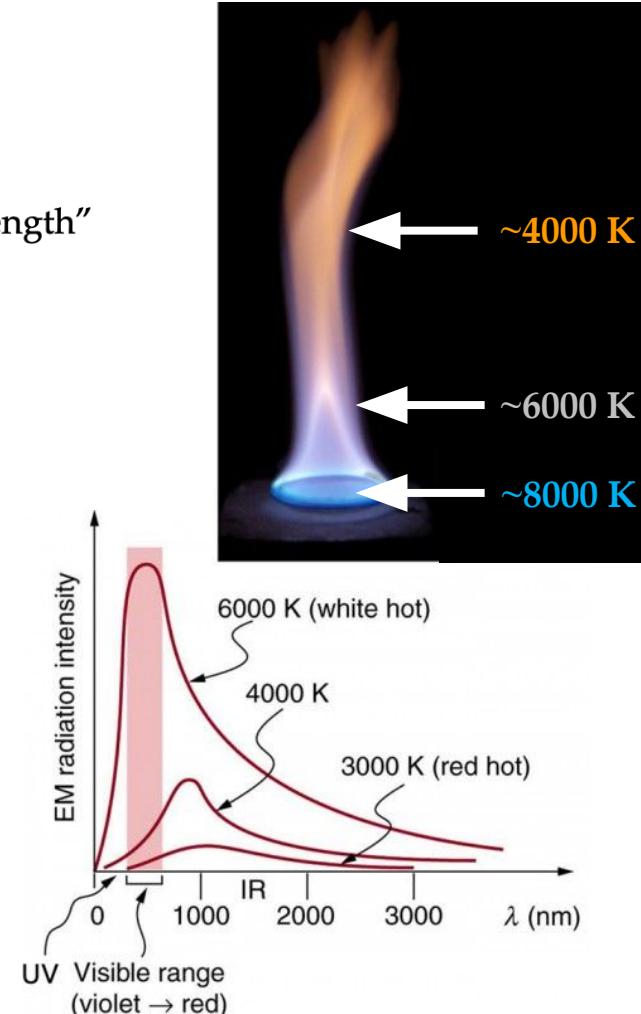
- At a fix  $T$  and  $\lambda$ , no surface can emit more energy than a blackbody
- Einstein: "Energy of a photon is inversely proportional to its wavelength"



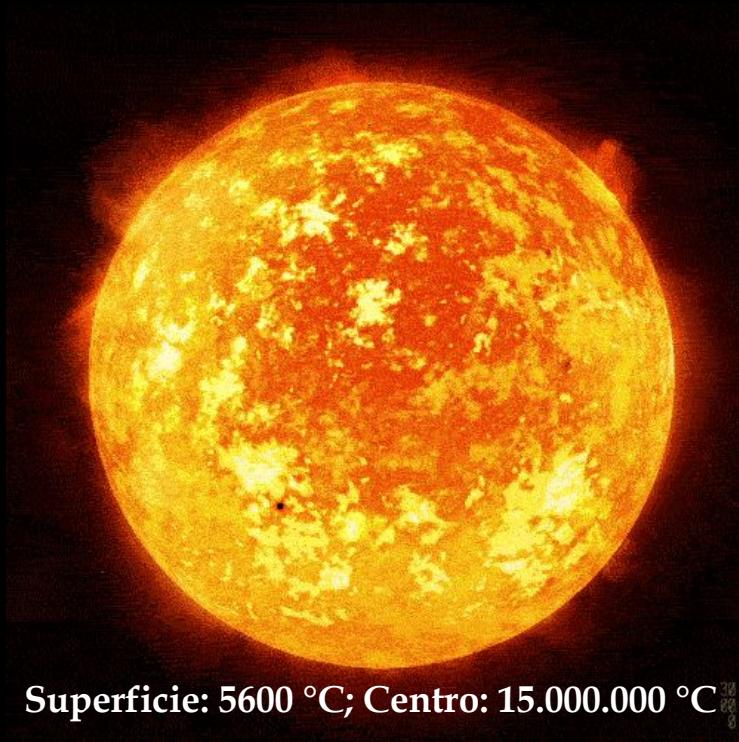
**Planck's law:**

$$E_{b,\lambda}(T) = \frac{2hc^2}{\lambda^5(e^{\frac{hc}{\lambda kT}} - 1)} \left( \frac{W}{\text{m}^2 \cdot \mu\text{m}} \right)$$

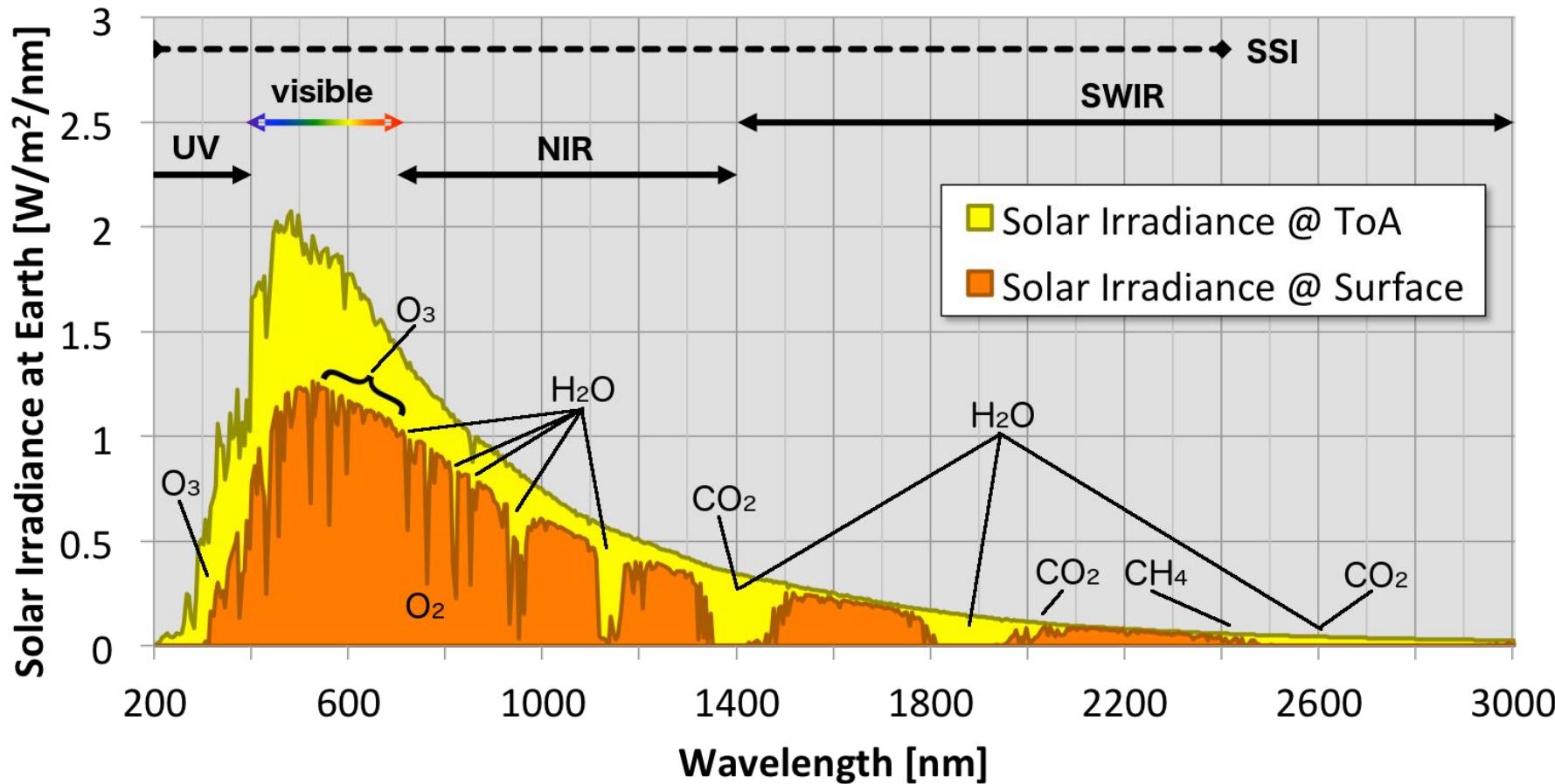
- $c$ : Speed of light
- $h$ : Planck's constant
- $k$ : Boltzmann's constant



# Incandescencia



# Irradiancia Solar



Apparent  
Temperature



Actual  
Temperature



TOTAL

% emission

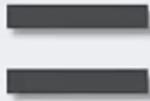
% transmission

% reflection

Reflected  
Apparent  
Temperature

$$\epsilon < 1.0$$

Apparent  
Temperature

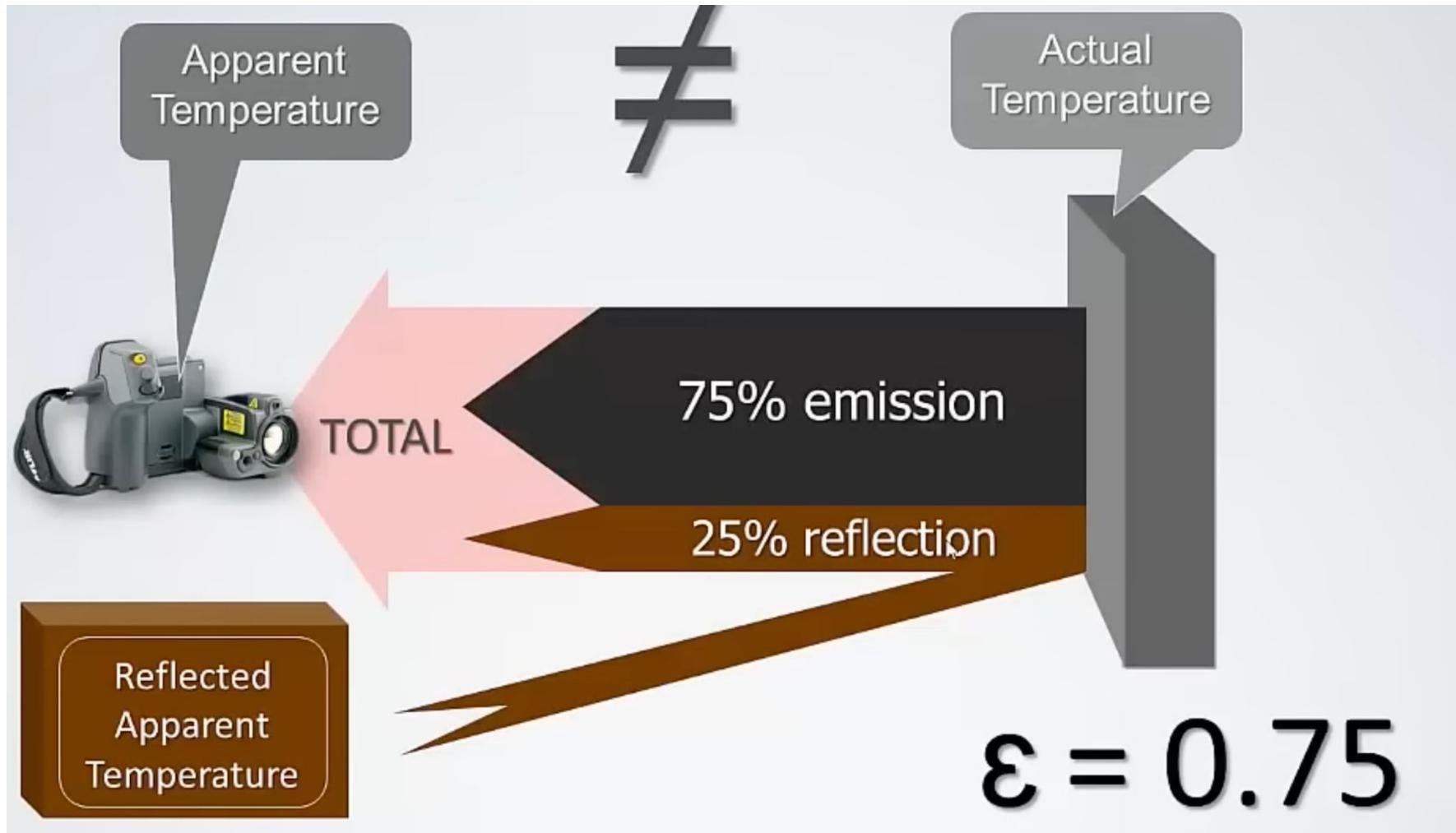


Actual  
Temperature



100% emission

$$\epsilon = 1.0$$



Apparent  
Temperature

Actual  
Temperature  
40°C



TOTAL

75% emission

25% reflection



$$\epsilon = 0.75$$

Apparent  
Temperature

>

Actual  
Temperature  
40°C



TOTAL

75% emission

25% reflection



$$\epsilon = 0.75$$

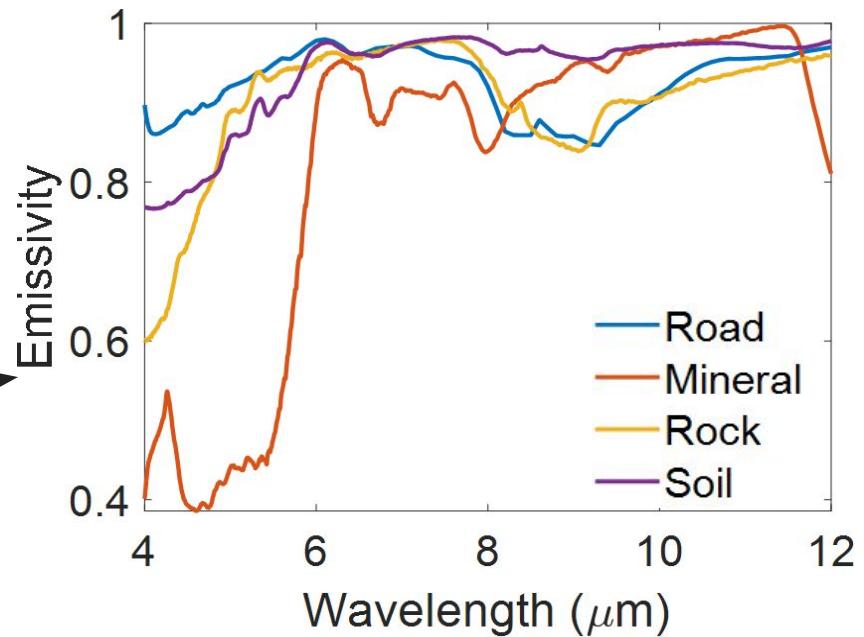
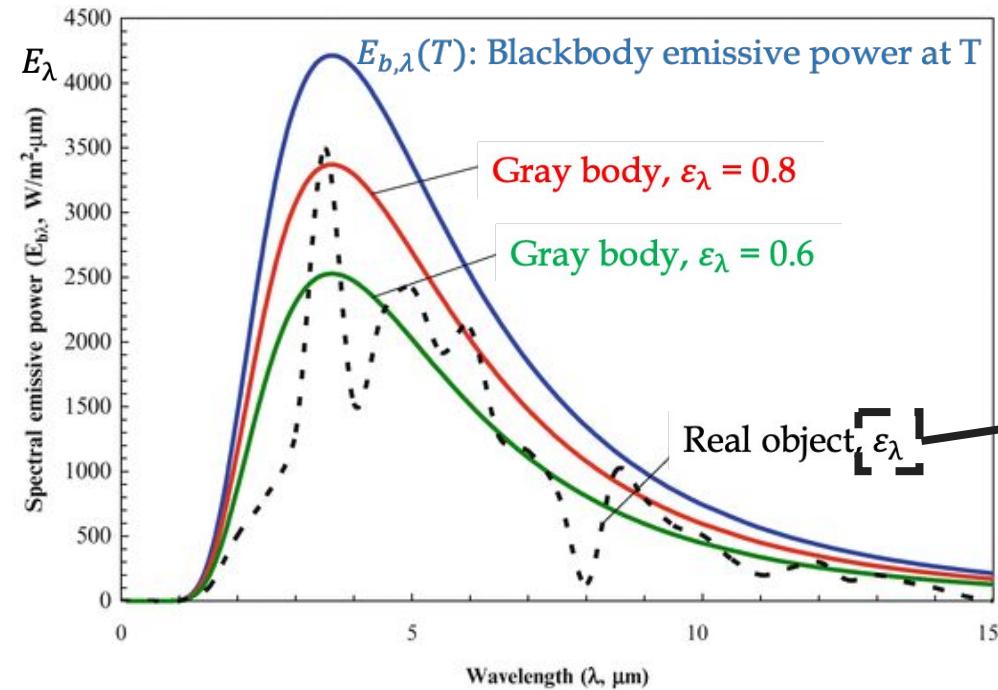
# Emissivity de materiales comunes

Metal	Emissivity	Non-metal	Emissivity
Bare aluminum	0.02–0.4	Concrete (rough)	0.93–0.96
Gold	0.02–0.37	Glass	0.76–0.94
Copper	0.02–0.74	Wood	0.8–0.95
Lead	0.06–0.63	Carbon	0.96
Brass	0.03–0.61	Human skin	0.98
Nickel	0.05–0.46	Paper	0.7–0.95
Steel	0.07–0.85	Plastic	0.8–0.95
Tin	0.04–0.08	Rubber	0.86–0.94
Silver	0.01–0.07	Water	0.67–0.96
Zinc	0.02–0.28	Sand	0.76–0.9

### 3. Imágenes Espectrales Térmicas

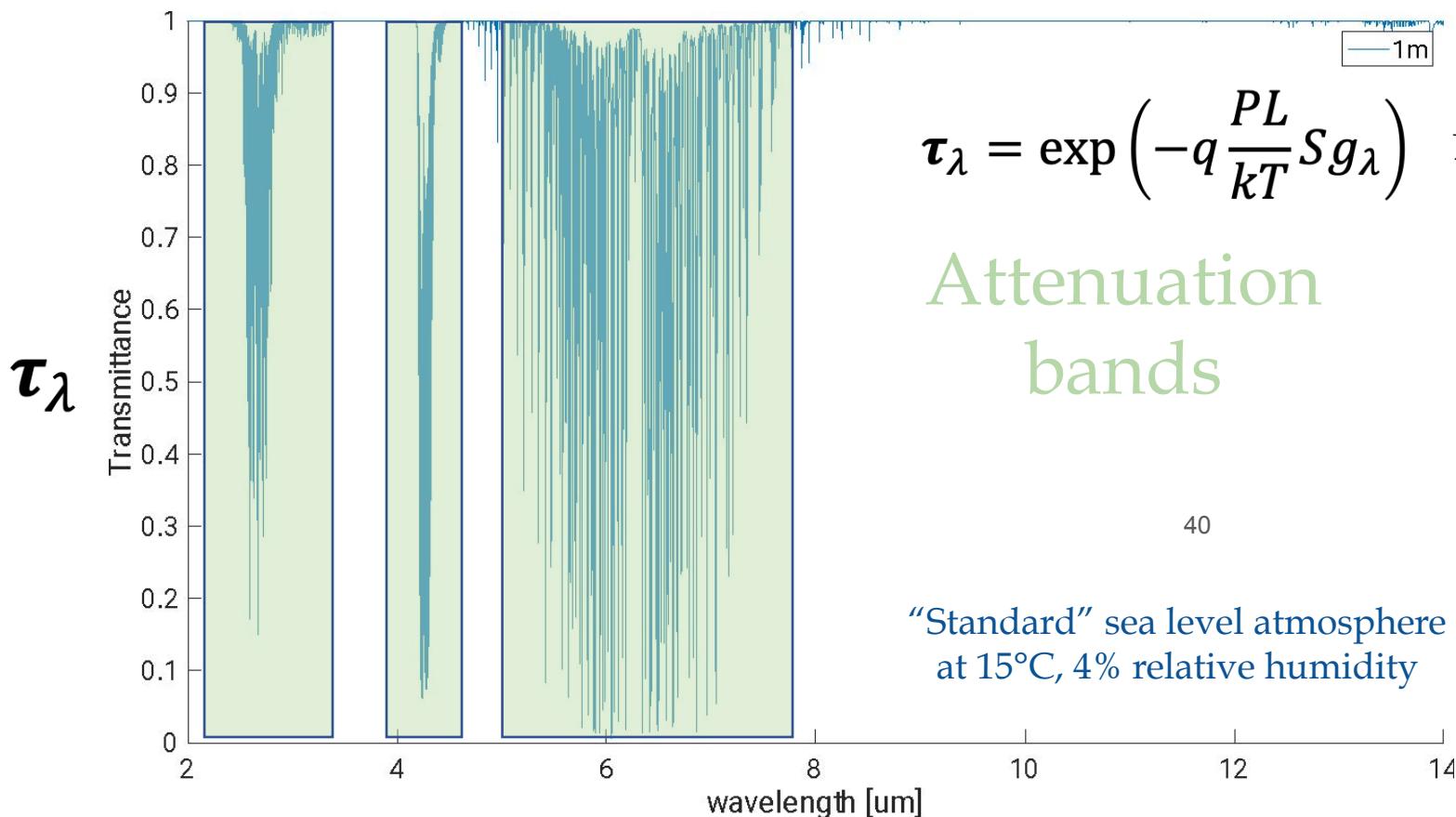
# Emissivity depends on $\lambda$

$$E_\lambda(T) = \varepsilon_\lambda E_{b,\lambda}(T)$$

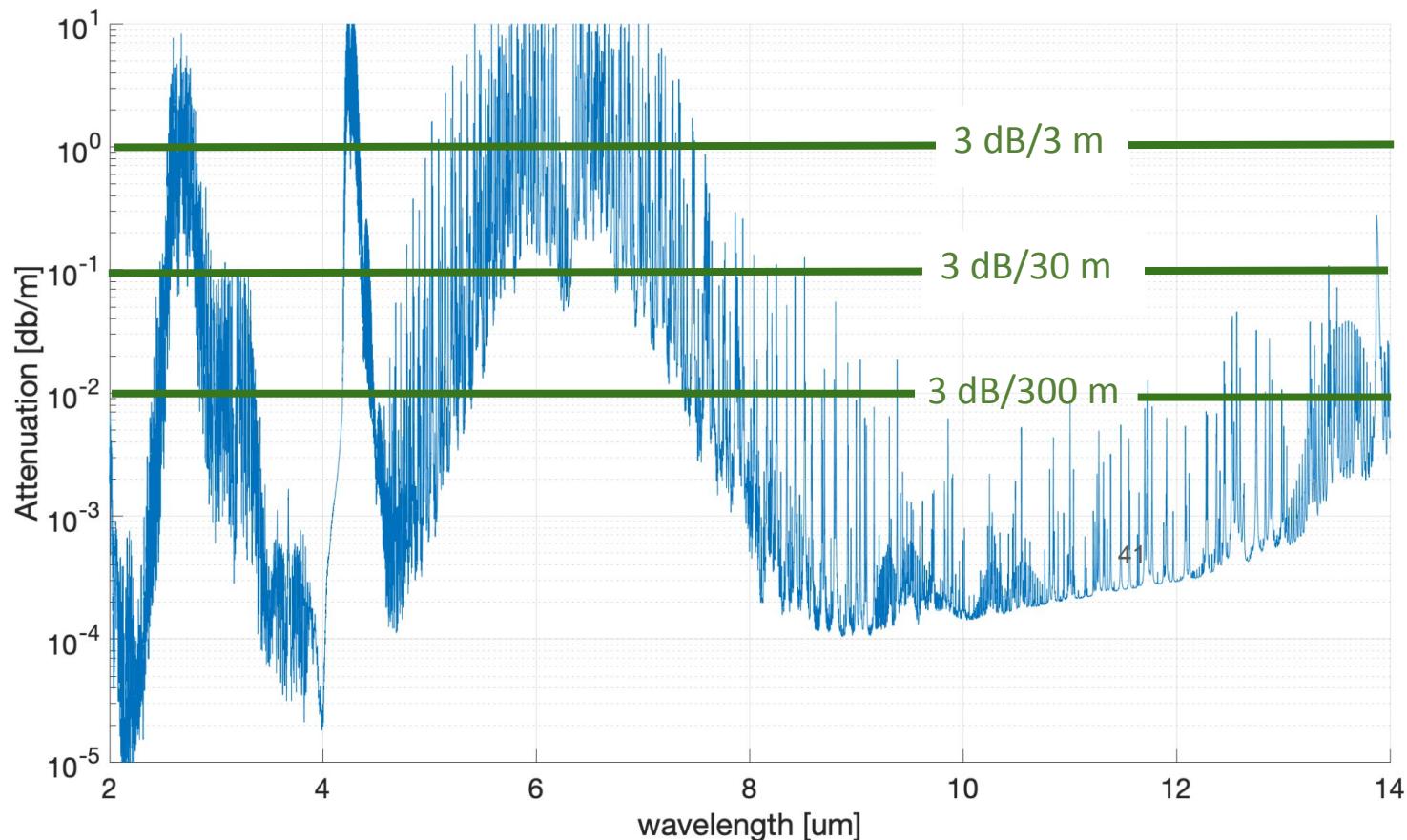




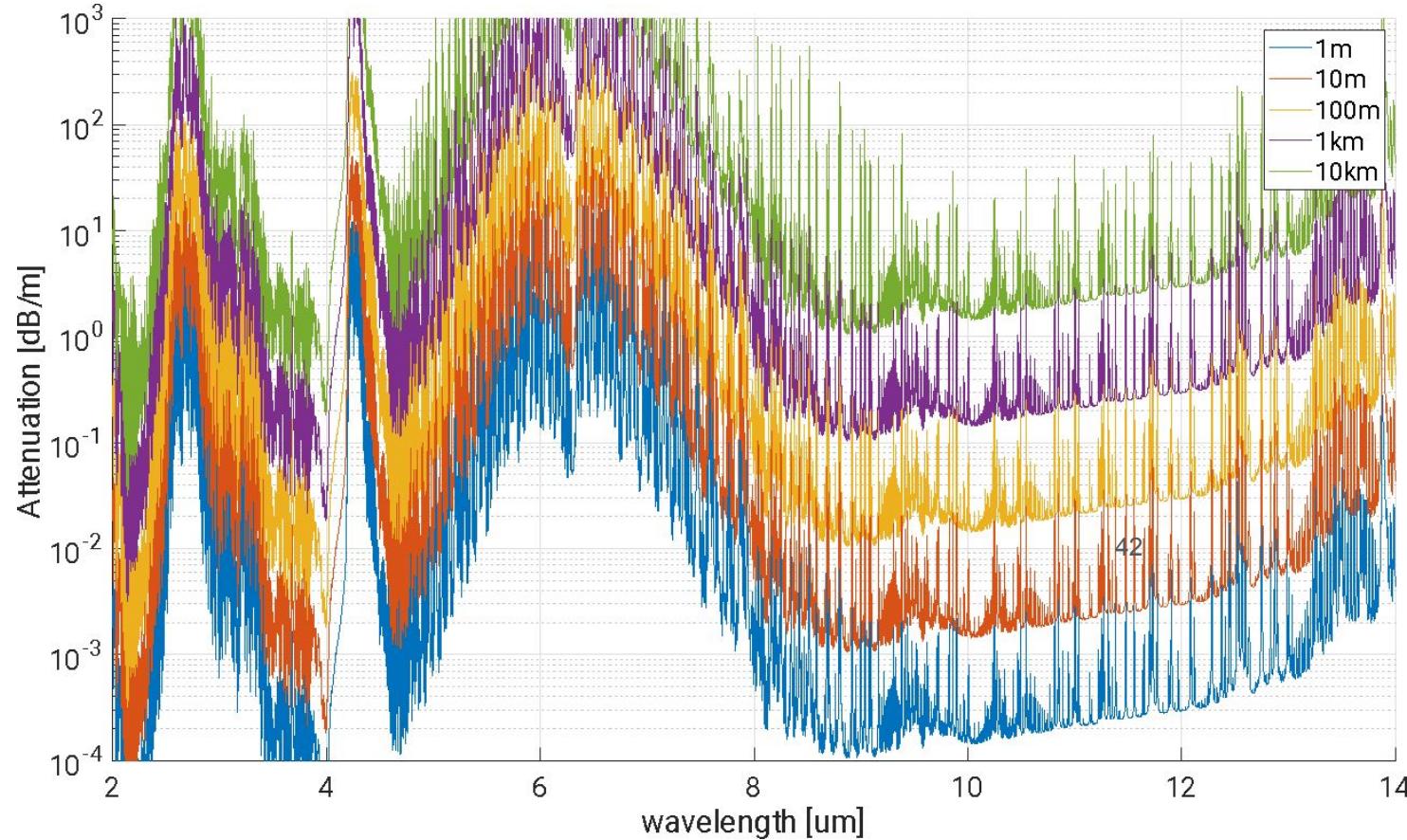
# Atmospheric transmittance



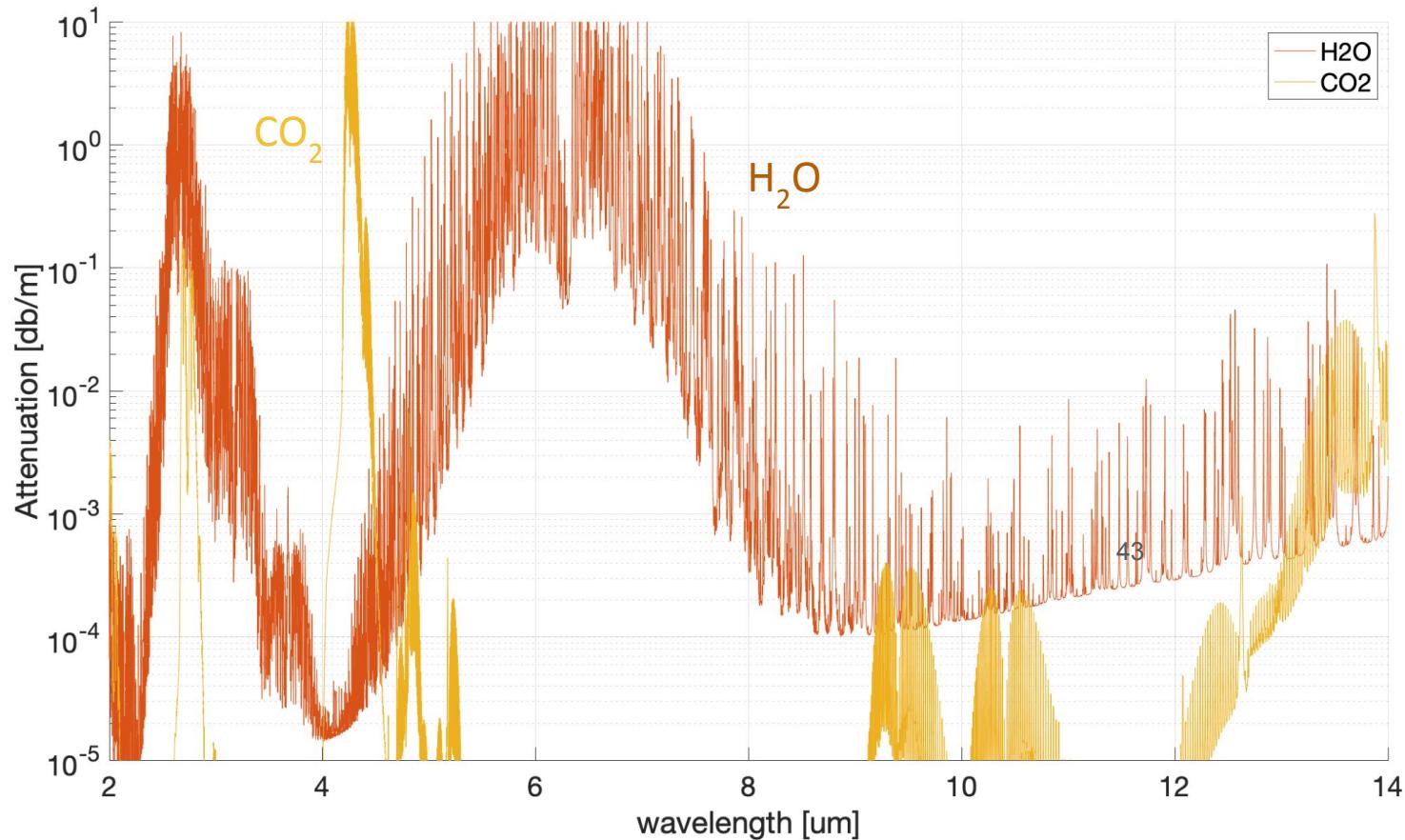
# Atmospheric attenuation



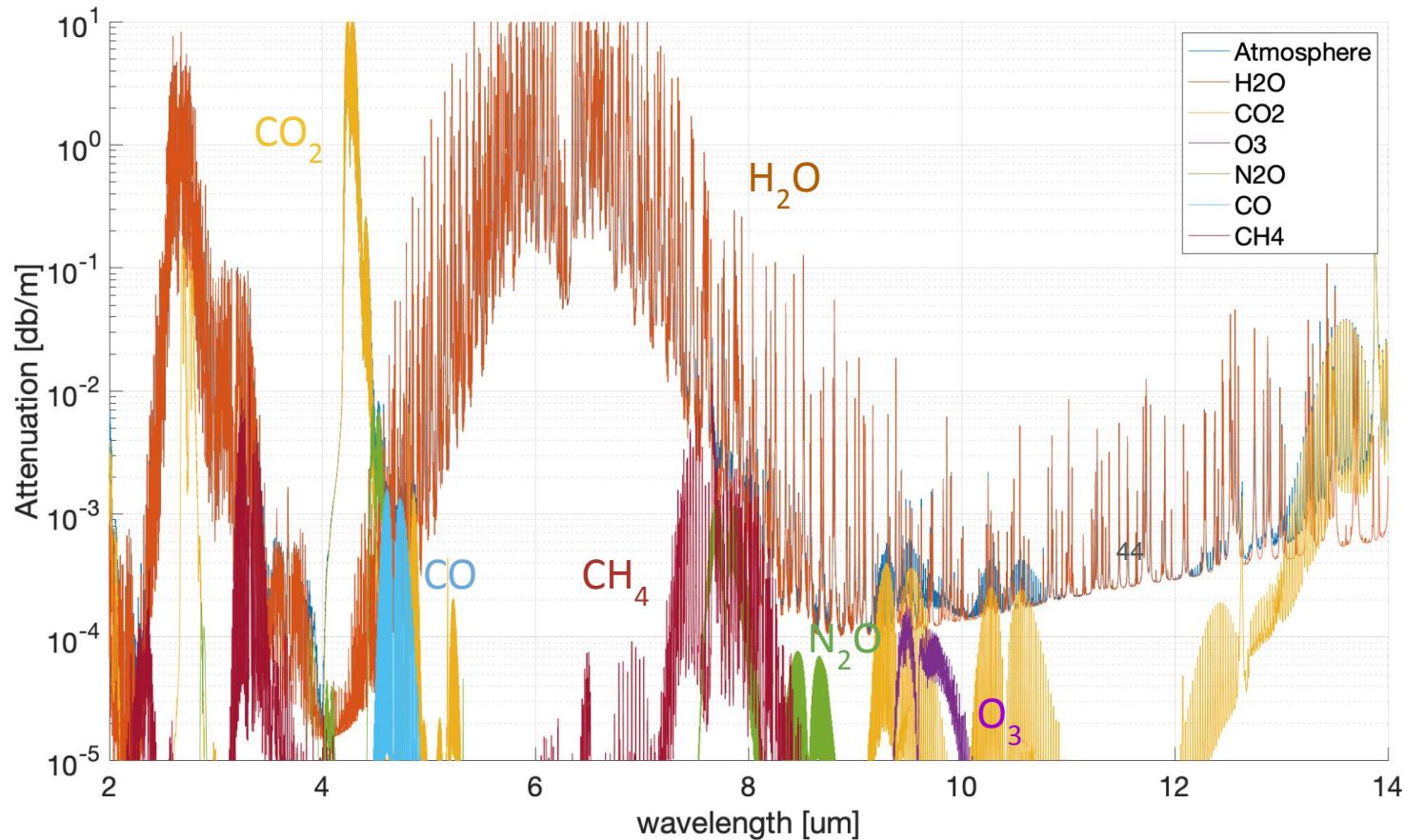
# Atmospheric attenuation for different L



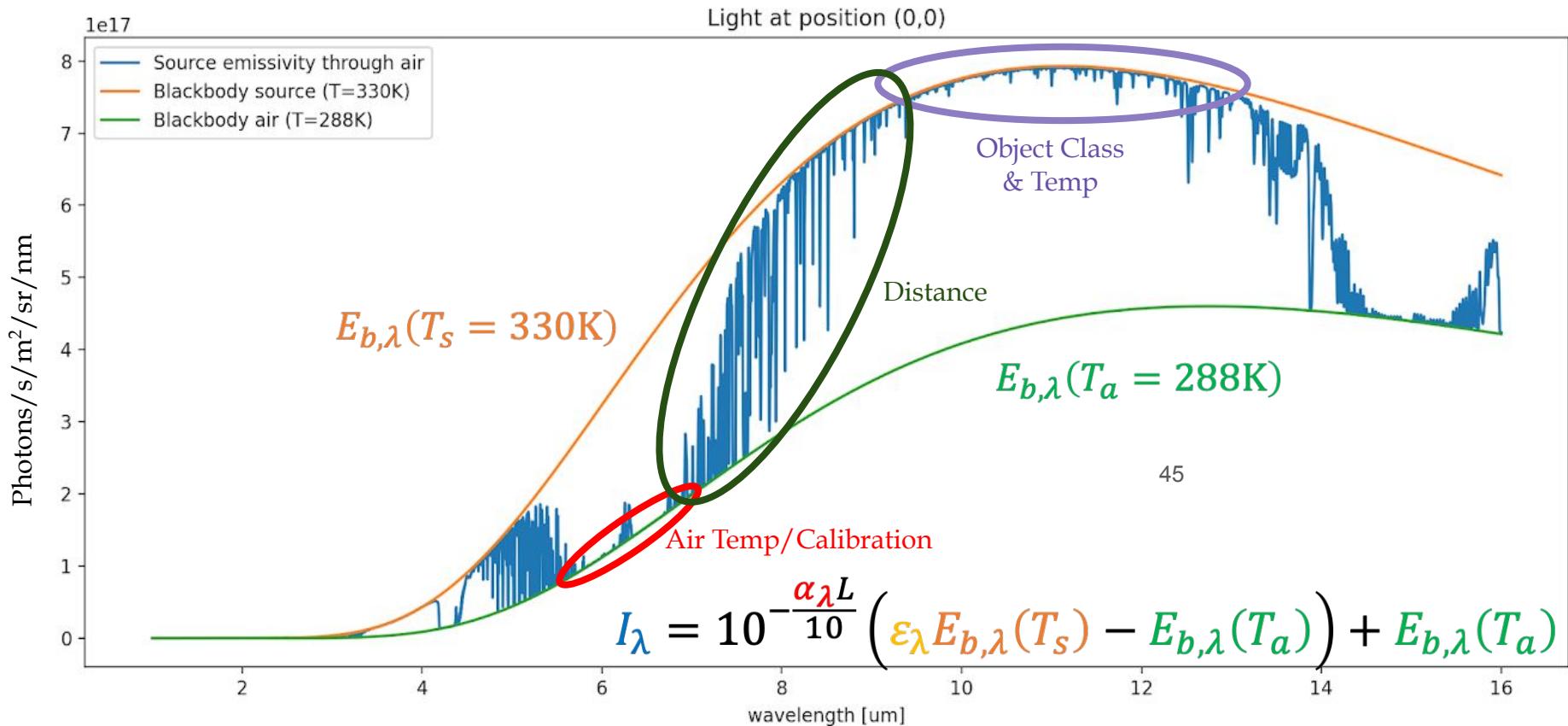
# Atmospheric attenuation by gas composition



# Atmospheric attenuation by gas composition



# Emissivity through air



# Forward (sensing) model

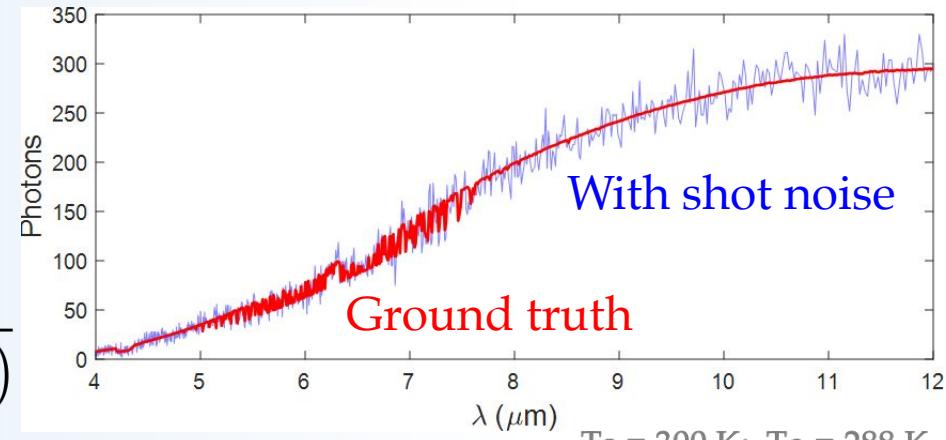
## Physics

Kirchhoff's law:  $\alpha_\lambda = \varepsilon_\lambda = 1 - \tau_\lambda$

Beer-Lambert:  $\tau_\lambda = \exp\left(-q \frac{PL}{kT} S g_\lambda\right)$

Planck's law:  $E_{b,\lambda}(T) = \frac{2hc^2}{\lambda^5 \left(\exp\left(\frac{hc}{\lambda kT}\right) - 1\right)}$

Light radiance:  $I_\lambda = 10^{-\frac{\alpha_\lambda L}{10}} \left( \varepsilon_\lambda E_{b,\lambda}(T_s) - E_{a,\lambda}(T_a) \right) + E_{a,\lambda}(T_a)$



## Sensor

Rate at sensor:  $\rho_i = A \Omega t_d \int_{\lambda_i}^{\lambda_{i+1}} I_\lambda d\lambda$

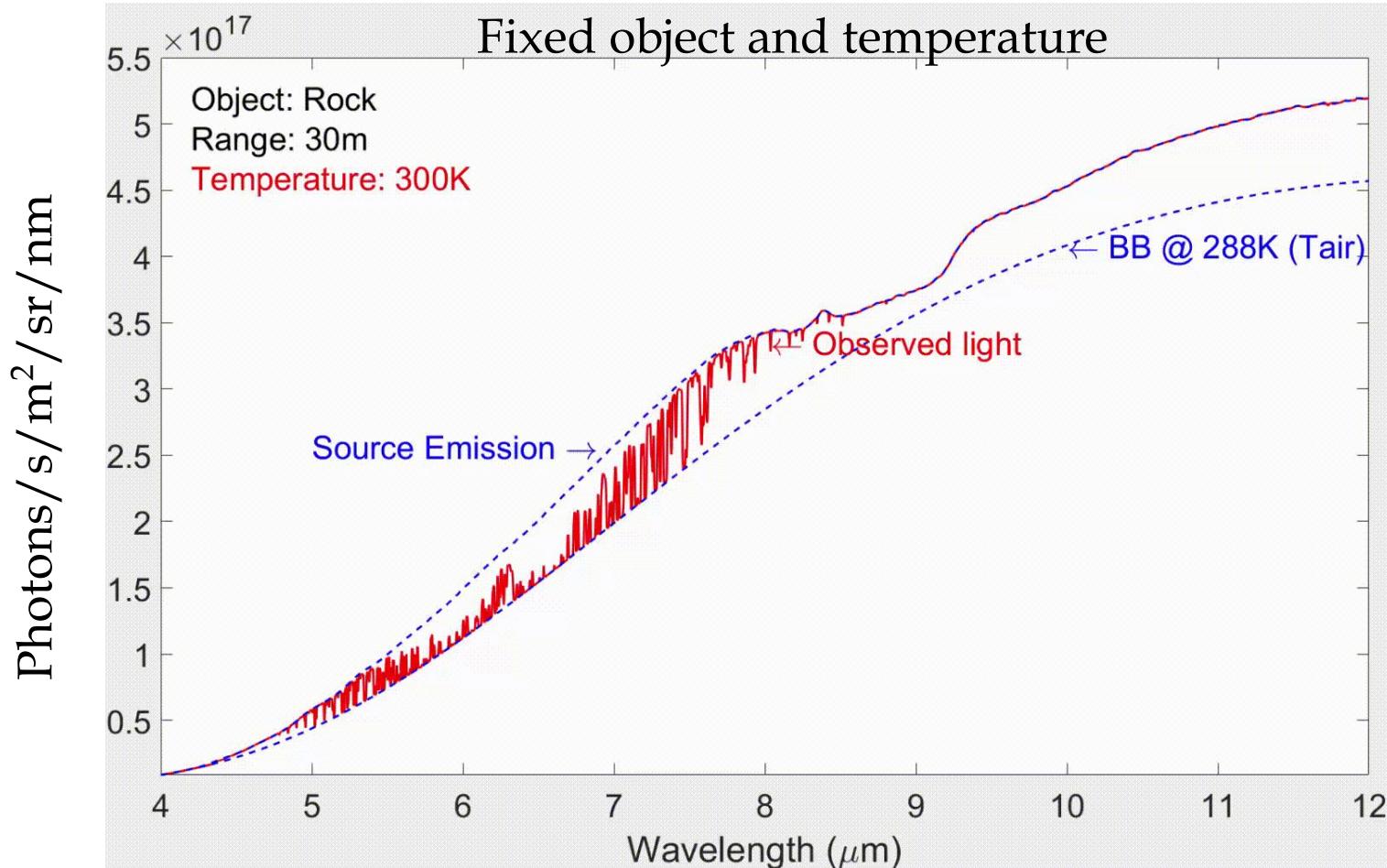
Measurements:  $\mathbf{y} = \mathcal{P}(\eta \boldsymbol{\rho}) + \boldsymbol{\nu}$

46

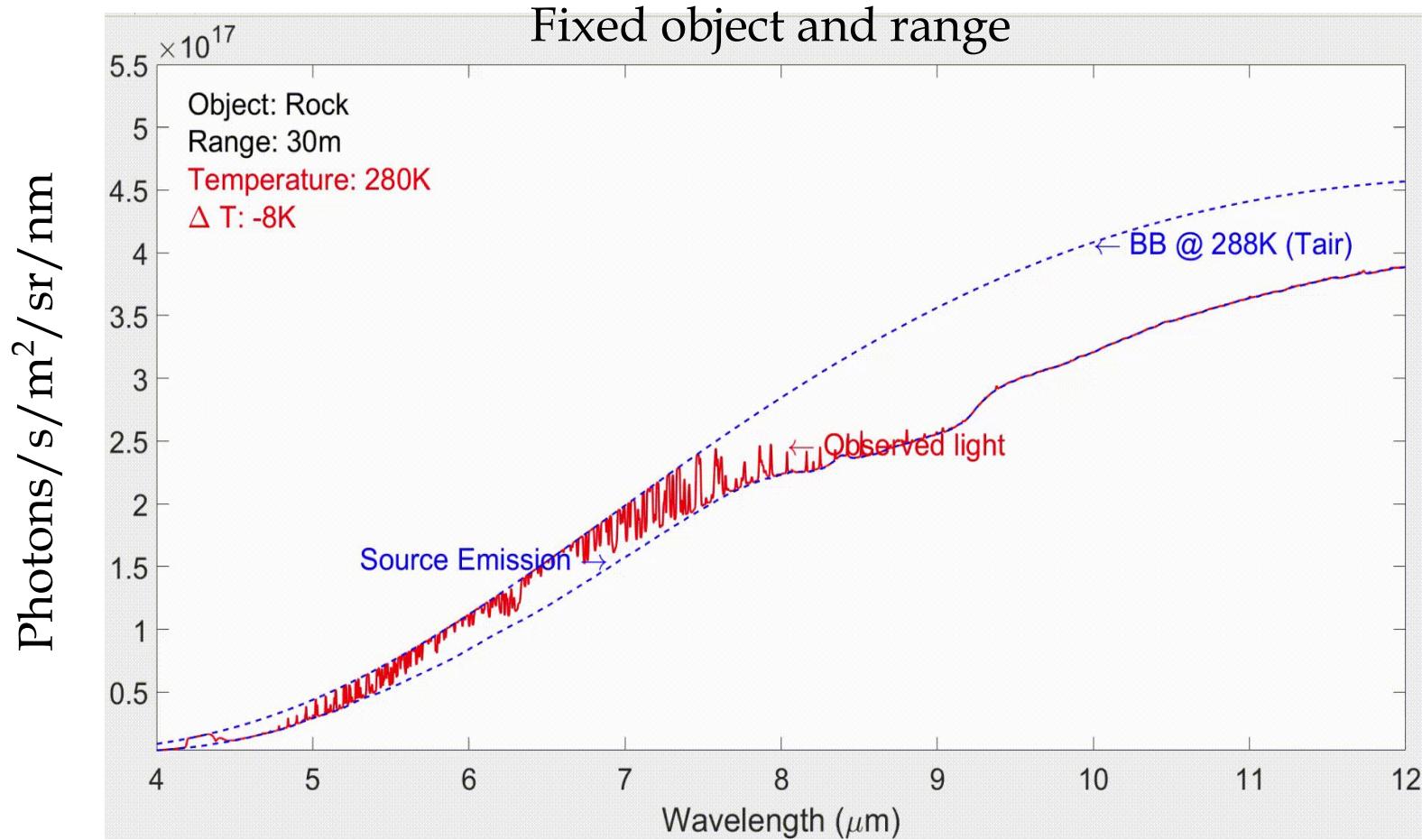
$R = 1,000 (\Delta\lambda = 6 \text{ nm})$   
 $A = 10 \times 10 \mu\text{m}^2 \text{ pixels}$   
 $\Omega = f/2.9 \text{ cold f-stop}$   
 $t = 10 \mu\text{s integration}$   
 $\eta = 80\%$

SNSPD: Superconducting nanowire single-photon detector

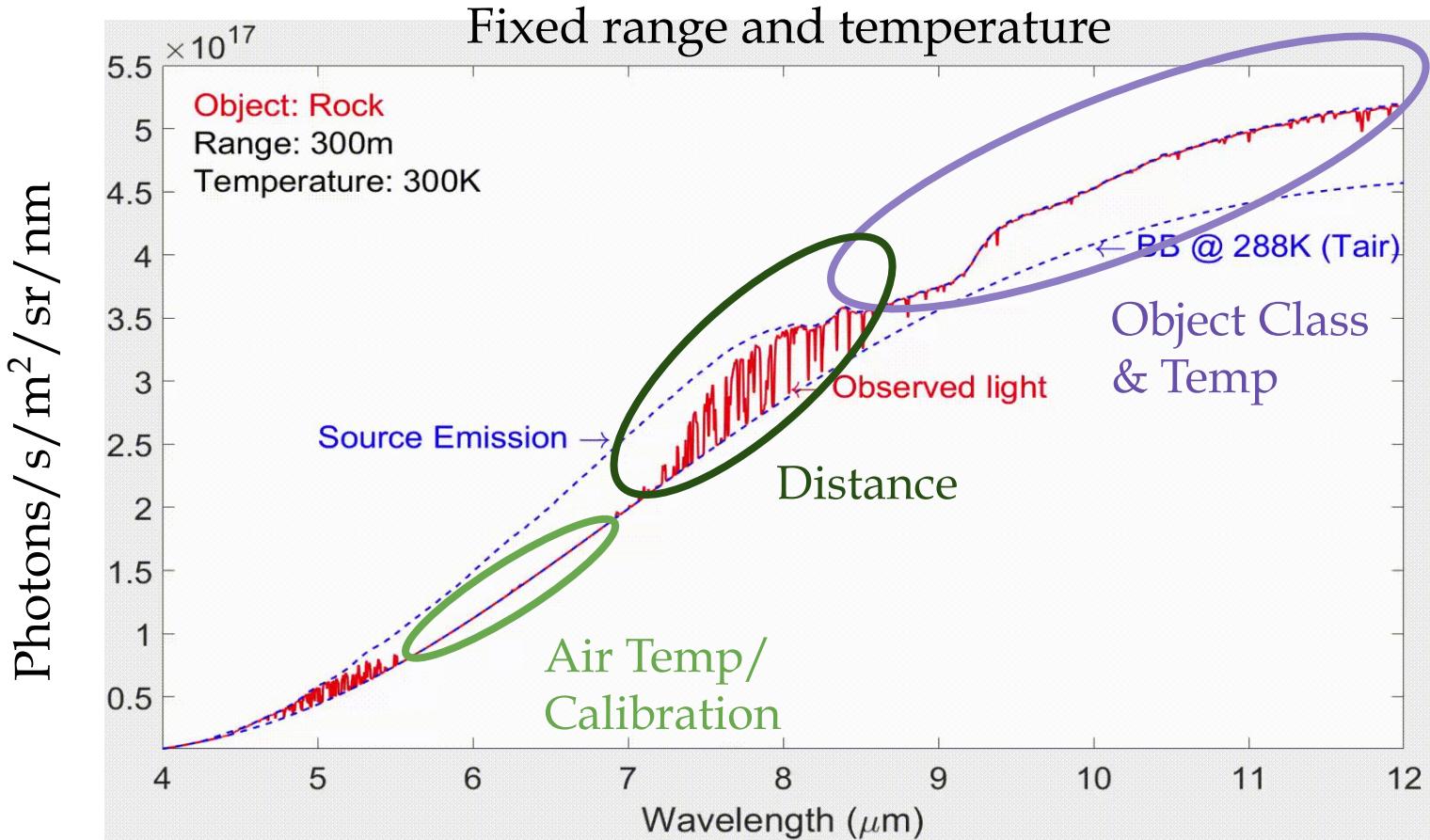
# Range variation



# Temperature variation



# Emissivity variation



# 4. Sensores infrarrojos

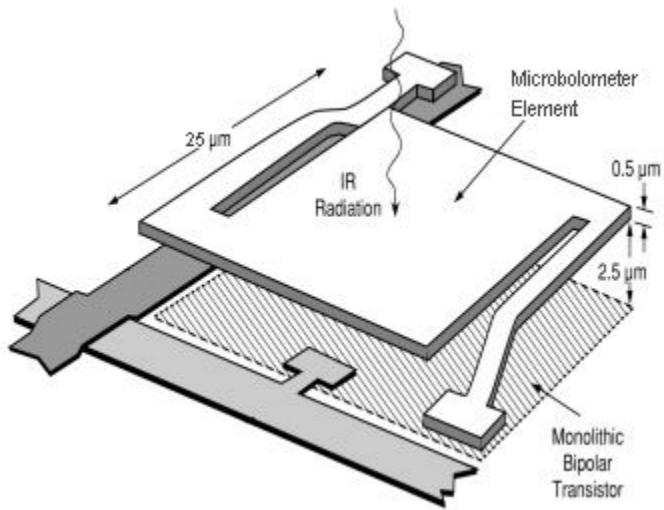


**How does a thermal imaging camera work?**

Thermal radiation through fog or smoke



# Microbolómetro



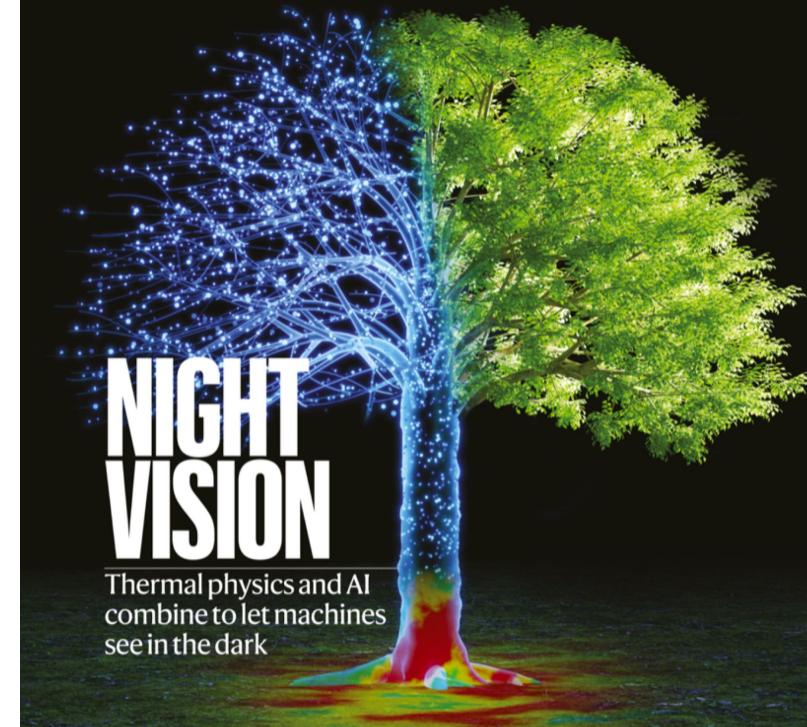
Germanium (metal en vez de vidrio para el lente)

# Cooled vs Uncooled

# 5. Thermal & CV

The international journal of science / 27 July 2023

nature



**Turing point**

The hunt for better ways to test the intelligence of chatbots

**A place out of the sun**

Why planning for shade is key to keeping cool in hot cities

**Parasite restrained**

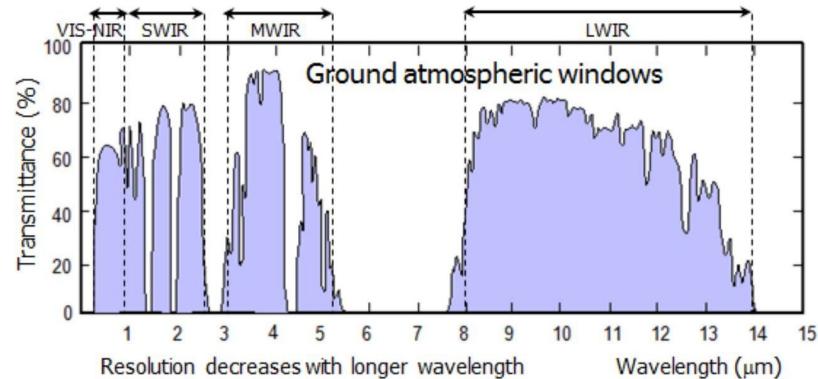
A sustainable way to tackle the snails behind schistosomiasis

Nat. Rev. No. 7071  
nature.com

# Let me ask you something ...



- How can we estimate the range at which objects are?
  - **Passive methods:** Stereo, light fields, **another?**
  - **Active methods:** Structured light, ToF, **another?**
- But, what if we don't want to be detected?
  - **Passive**
- Need to work 24/7 and at varying conditions?
  - LWIR + Atmospheric absorption



VIS

NIR

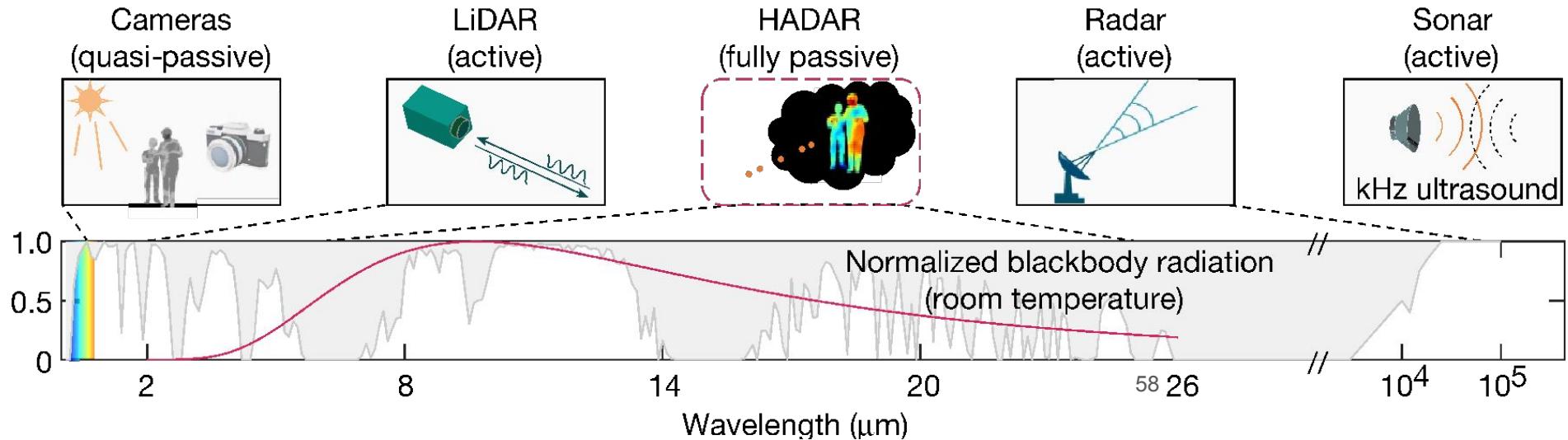
SWIR

LWIR

Resolution decreases with longer wavelength

Wavelength (μm)

# Radar, Sonar, Lidar, Hadar (passive)



**Goal:** HADAR (24/7) = RGB (At daylight)

# TeX Vision: Temperature, emissivity, teXture

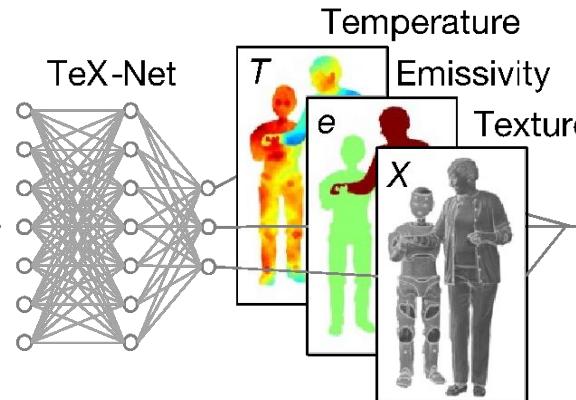
Ghosting effect  
(TeX degeneracy)



Hyperspectral  
heat cube



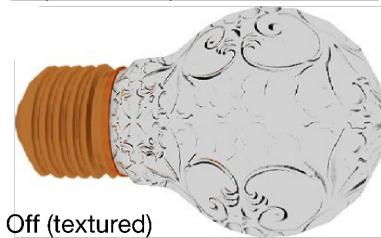
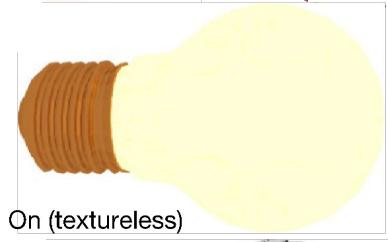
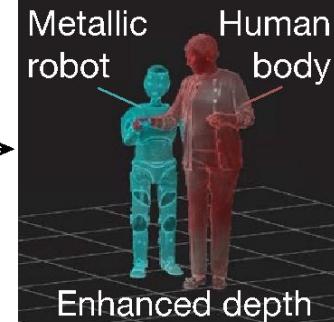
HADAR



TeX vision



HADAR perception



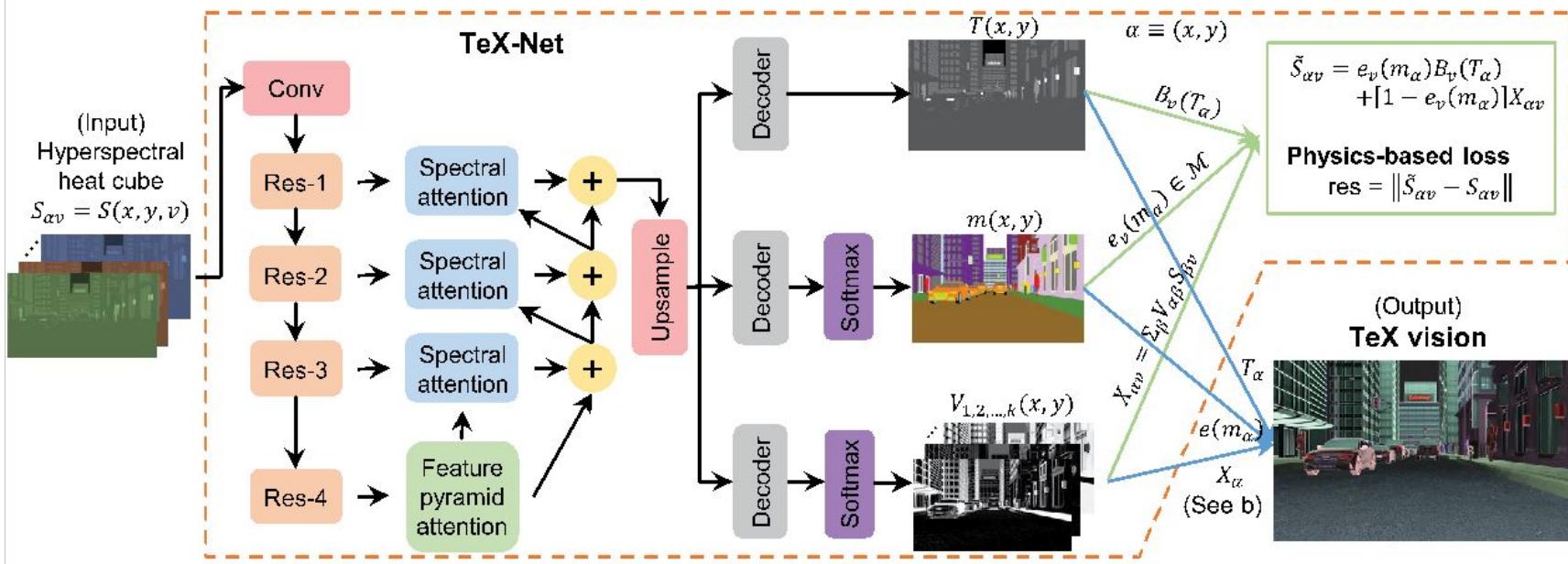
$$I_{\lambda} = 10^{-\frac{\alpha_{\lambda} L}{10}} \left( \varepsilon_{\lambda} E_{b,\lambda}(T_s) - E_{b,\lambda}(T_a) \right) + E_{b,\lambda}(T_a)$$

$$I_{\lambda} = 10^{-\frac{\alpha_{\lambda} L}{10}} \left( \varepsilon_{\lambda} E_{b,\lambda}(T_s) \right) + \left( 1 - 10^{-\frac{\alpha_{\lambda} L}{10}} \right) E_{b,\lambda}(T_a)$$

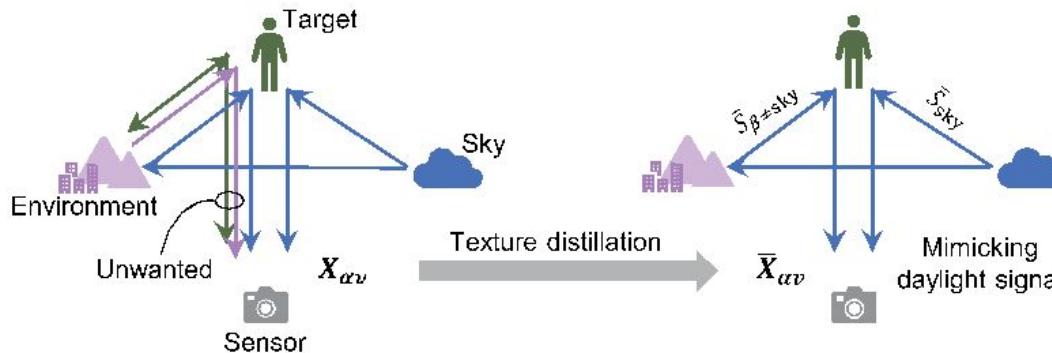
$$S_{\alpha\nu} = e_{\alpha\nu} B_{\nu}(T_{\alpha}) + [1 - e_{\alpha\nu}] X_{\alpha\nu}$$

# T e X - N e t

**a Inverse decomposition**



**b Forward rendering**

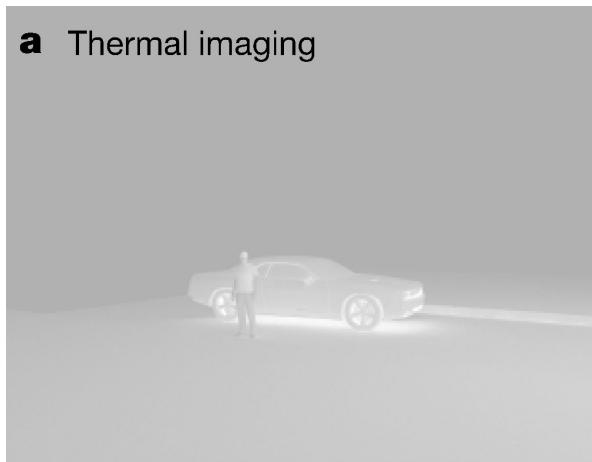


Forward texture distillation procedures:

- (1)  $\bar{S}_{\gamma v} \equiv \begin{cases} S_{\beta v} | \beta = \gamma, & \gamma = \text{sky} \\ 0, & \text{otherwise} \end{cases}$
- (2)  $\bar{S}_{\beta v} \equiv [1 - e_v(m_\beta)] \cdot \sum_\gamma V_{\beta \gamma} \bar{S}_{\gamma v}, \quad \beta \neq \text{sky}$
- (3)  $\bar{X}_{\alpha v} \equiv \sum_\beta V_{\alpha \beta} \bar{S}_{\beta v}$
- (4)  $X_\alpha \equiv \sum_v \bar{X}_{\alpha v} \oplus res$

# HADAR: Fundamental limits in ranging

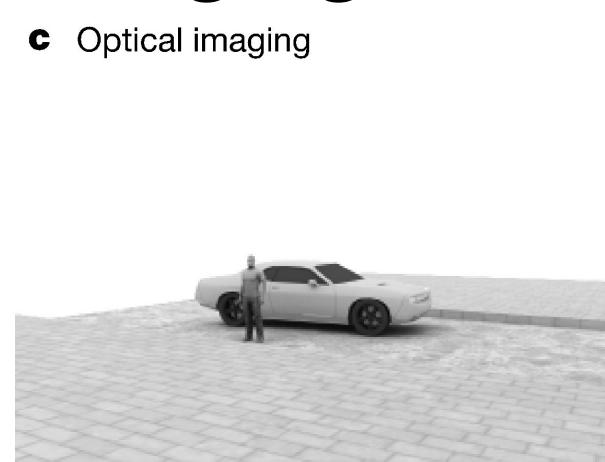
**a** Thermal imaging



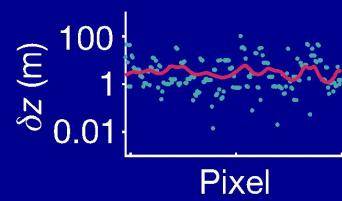
**b** HADAR



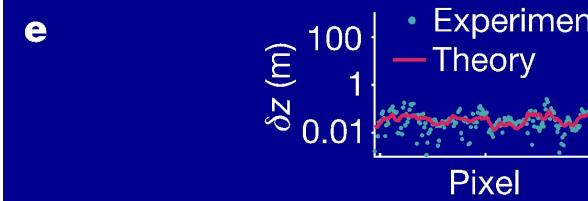
**c** Optical imaging



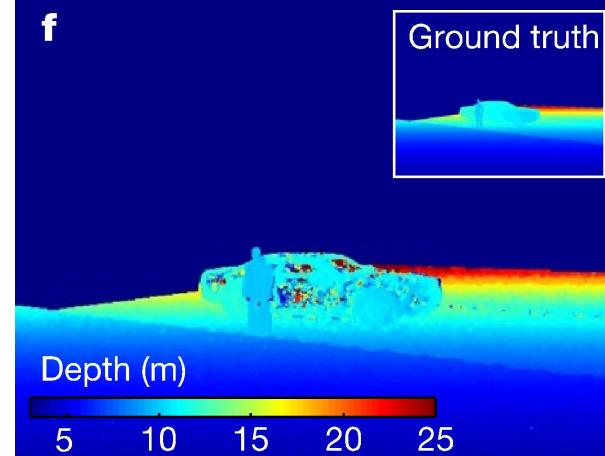
**d**



**e**

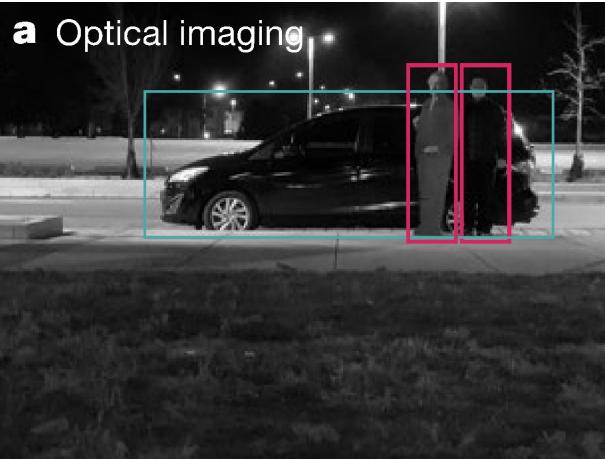


**f**

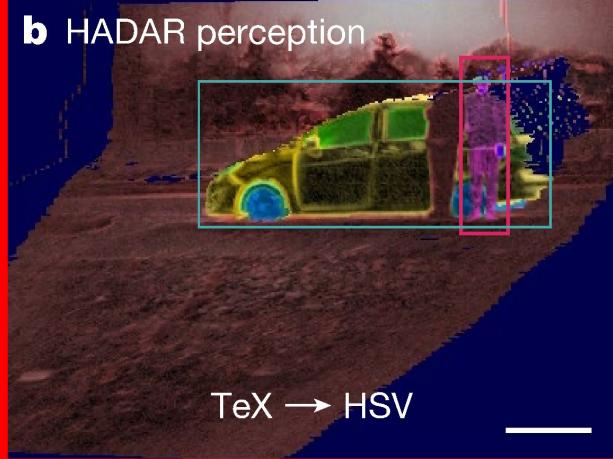


# HADAR: Physics-driven perception

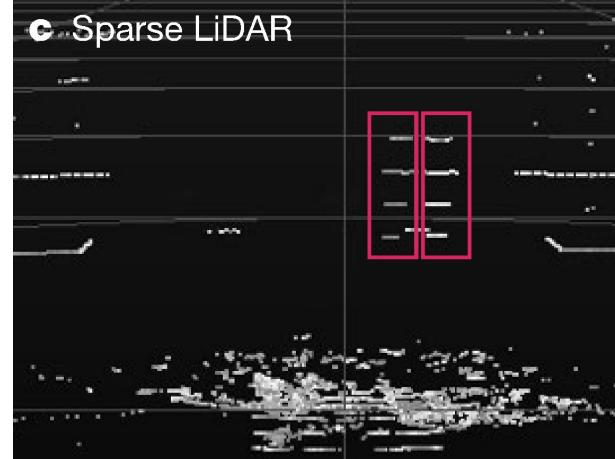
**a** Optical imaging



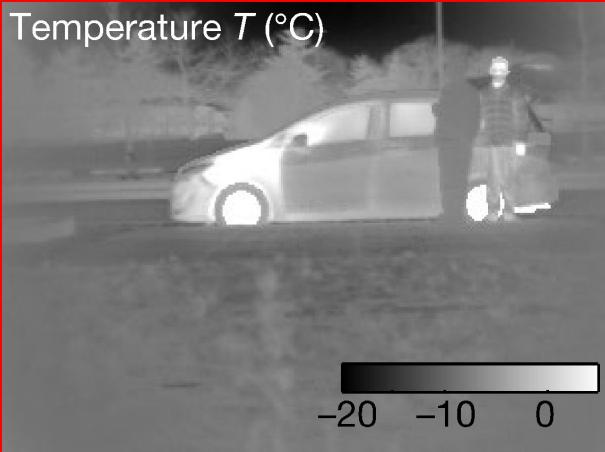
**b** HADAR perception



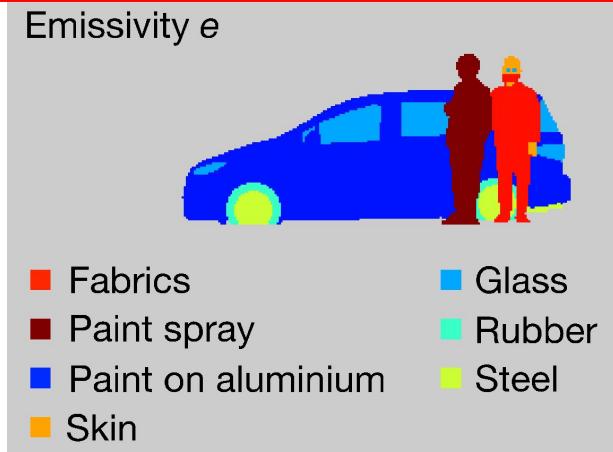
**c** Sparse LiDAR



Temperature  $T$  ( $^{\circ}\text{C}$ )



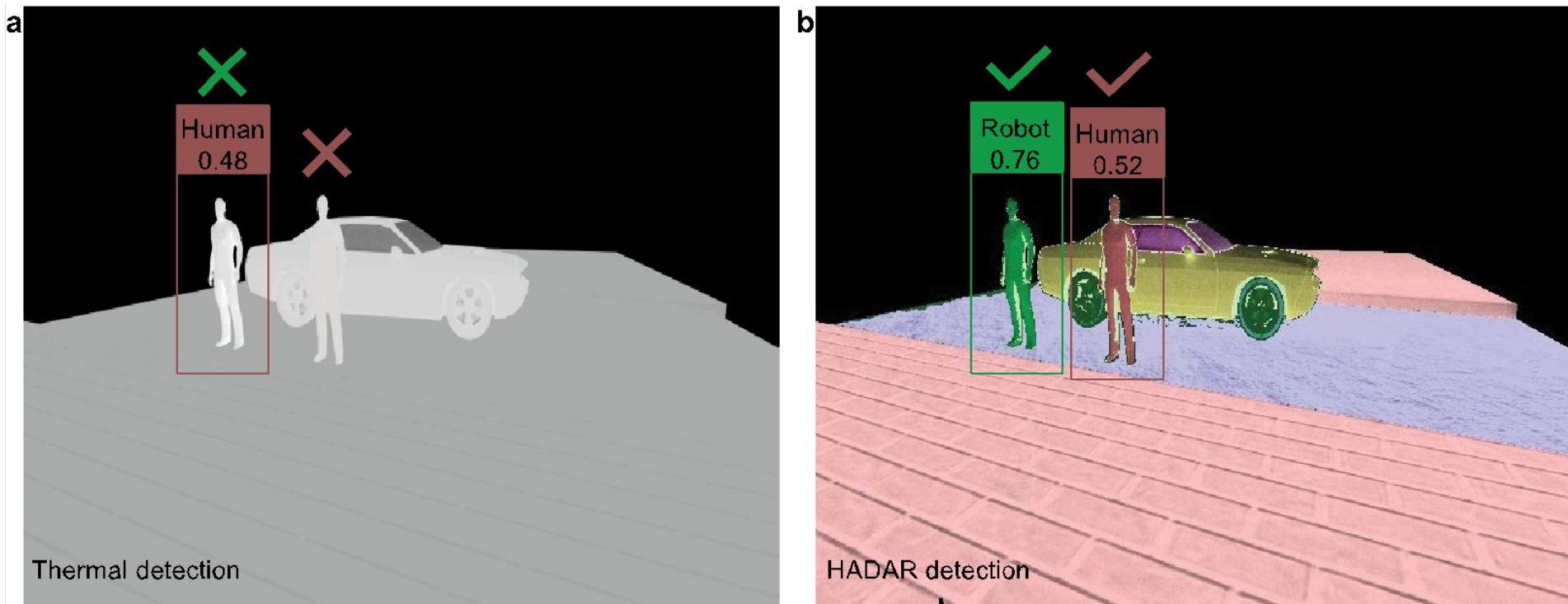
Emissivity  $e$



Texture X



# Thermal detection (thermal-YOLO-V5)



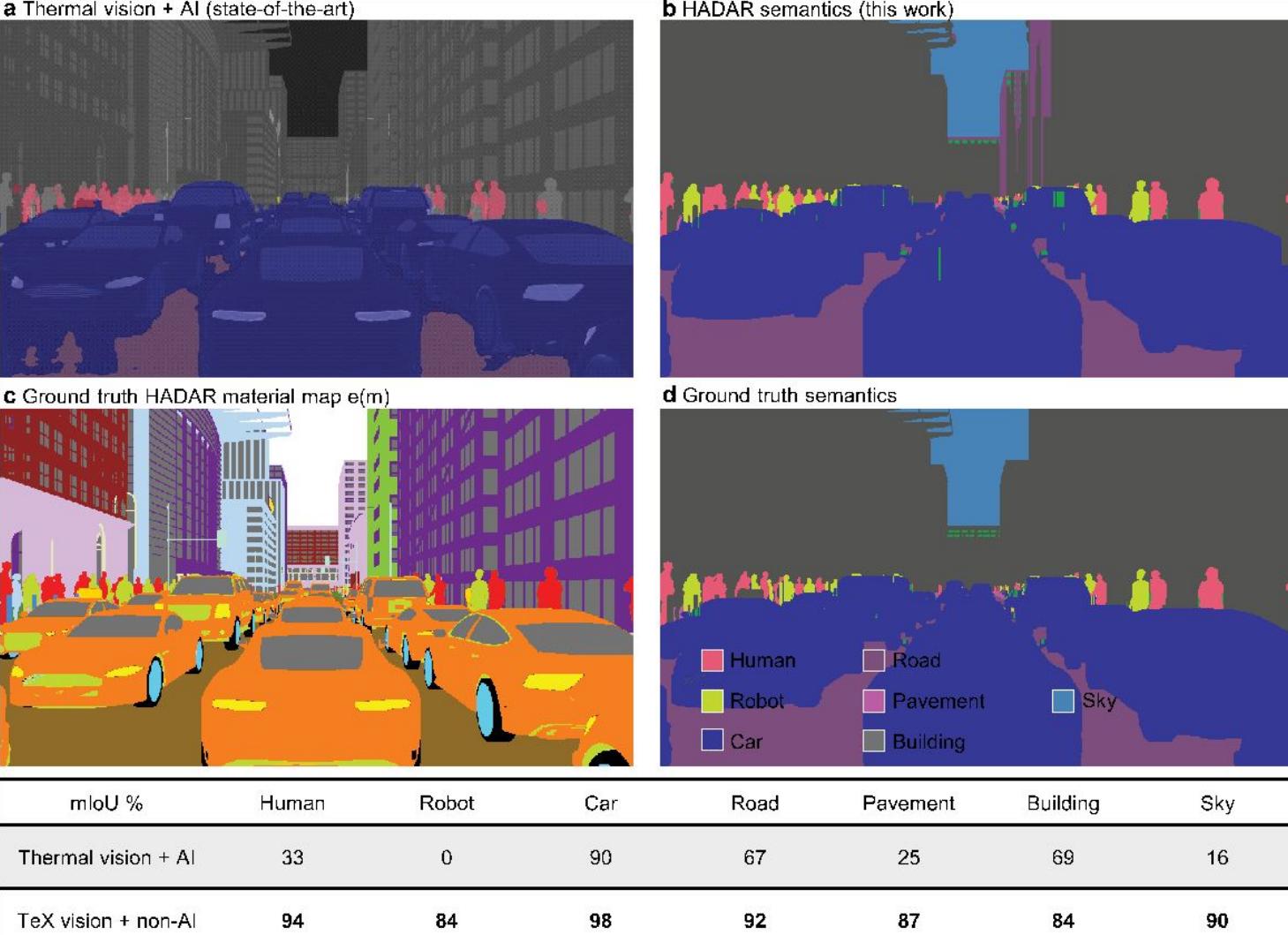
We first extract the material regions corresponding to human and robot, then we perform people detection individually and, combine detection results to form the final HADAR detection (b).

# Thermal Semantic Segment.

(DANet)

Fu, J. et al. in *CVPR*  
3146–3154, 2019.

**mIoU:**  
pixelwise mean  
intersection  
over union.



09-25-2022 Sun 05:43:22



Grill Temp: 451° F

Tri Tip 1 Sausage 1  
Start: 05:40 PM Start: 05:40 PM  
Duration: 03m:55s Duration: 01m:30s  
Temp: 261.4°F Temp: 253.0°F

Tri Tip 2 Sausage 2  
Start: 05:40 PM Start: 05:40 PM  
Duration: 03m:55s Duration: 01m:30s  
Temp: 262.0°F Temp: 254.1°F

Tri Tip 3 Sausage 3  
Start: 05:40 PM Start: 05:40 PM  
Duration: 03m:47s Duration: 01m:30s  
Temp: 261.5°F Temp: 253.4°F

Sausage 4  
Start: 05:40 PM Start: 05:40 PM  
Duration: 03m:38s Duration: 01m:30s  
Temp: 263.4°F Temp: 254.0°F

Cancer 0.1

# Navigation

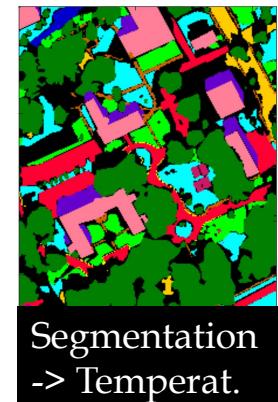




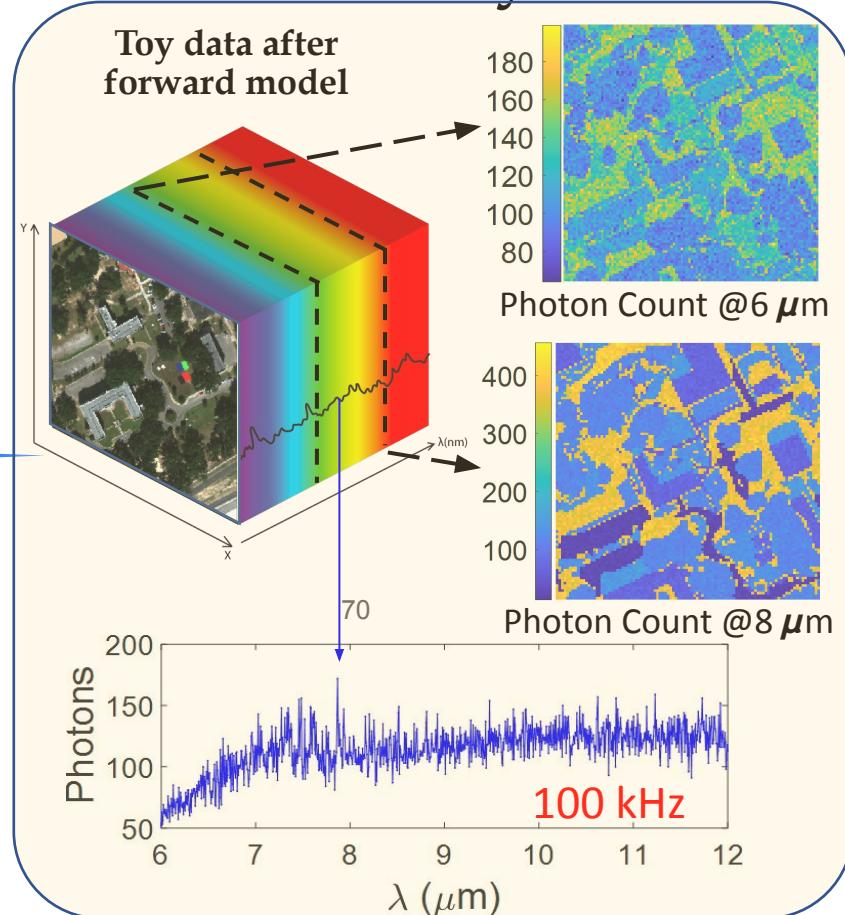
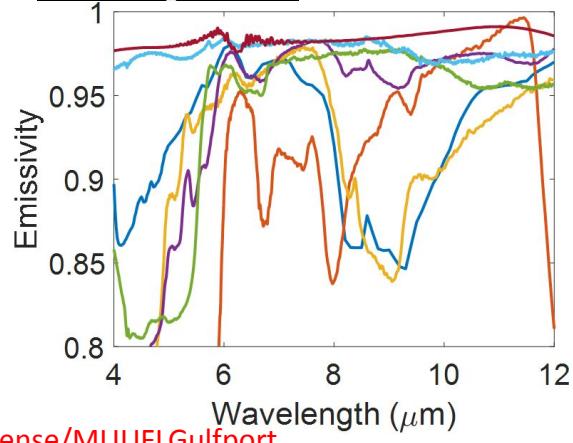
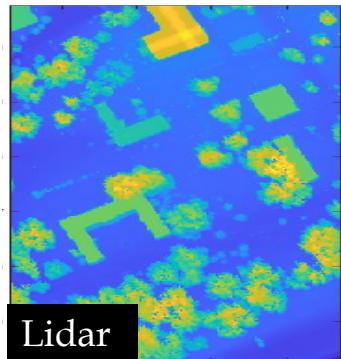
# Material Segmentation (Cooling-in, Cooling-off)

# 6. Hands-on: Thermal Imaging

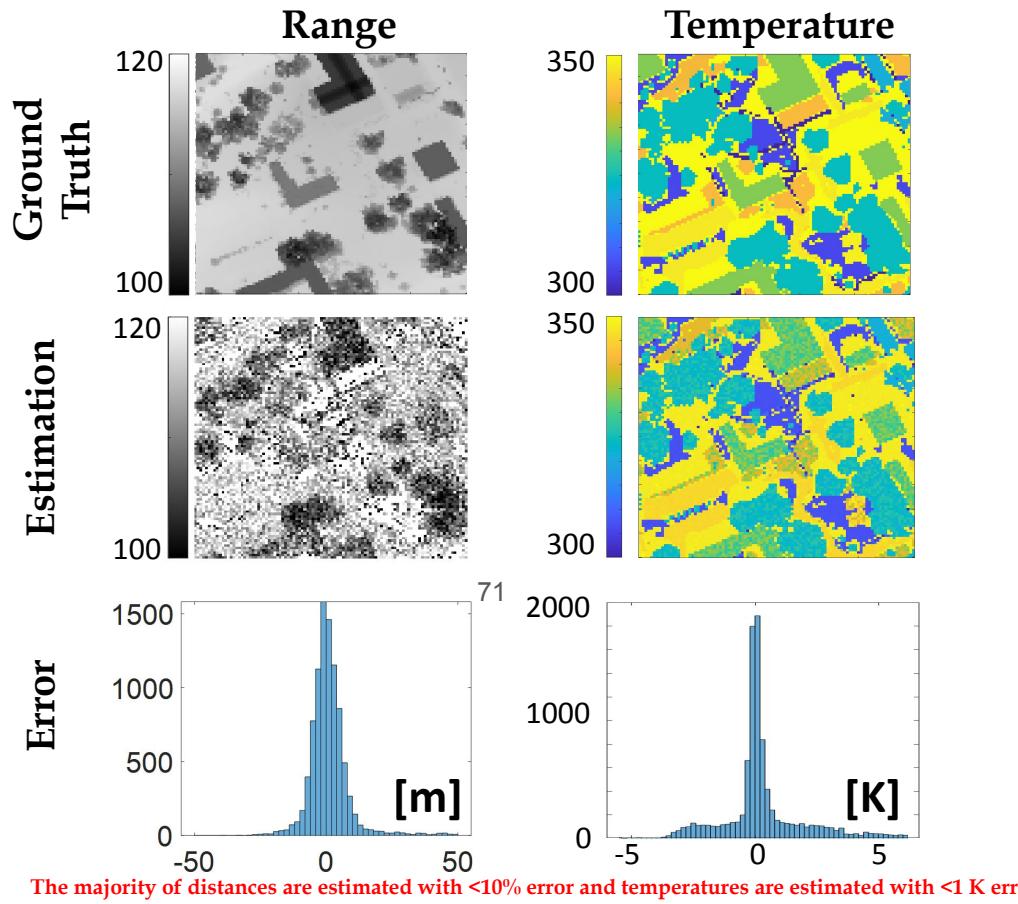
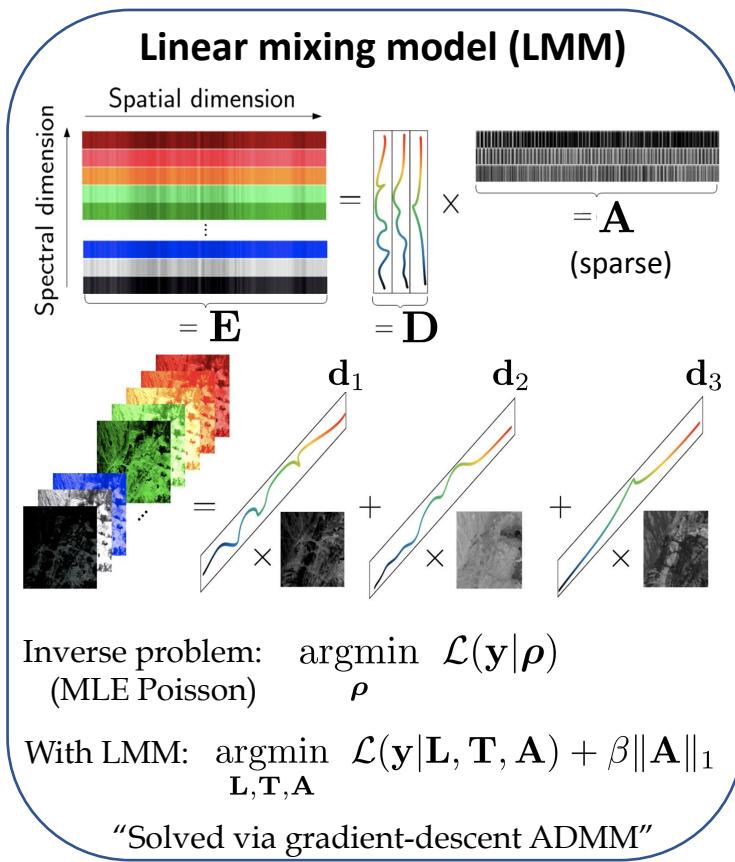
# Computational image formation and analysis



- unlabeled points
- green trees
- light green mostly grass
- light blue mixed ground surface
- yellow dirt/sand
- red road
- blue water
- purple building shadow
- pink buildings
- brown sidewalk
- yellow curb
- pink cloth panels



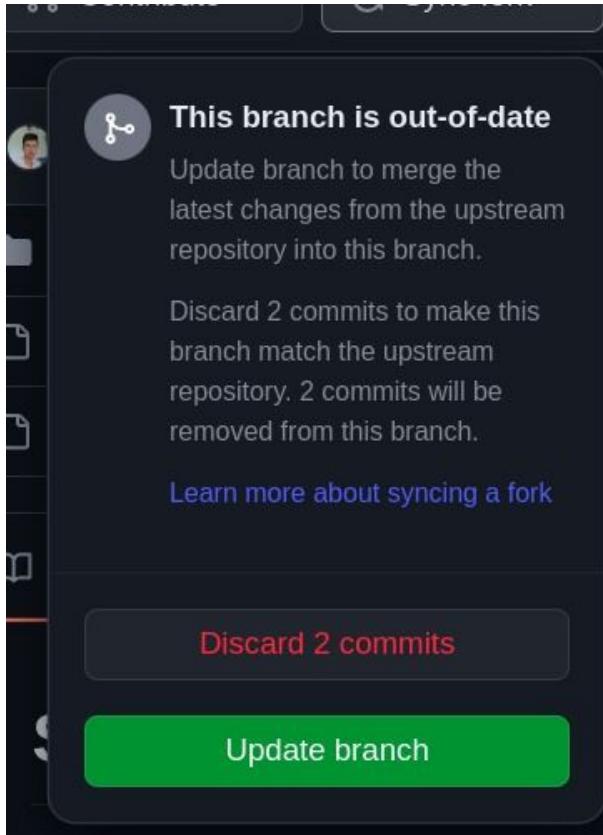
# Computational image estimation – Overview



# Actualicemos el repositorio!

A screenshot of a GitHub repository page. At the top, there are navigation links: 'main' (with a dropdown arrow), '1 Branch' (with a dropdown arrow), '0 Tags' (with a dropdown arrow). To the right are search bar ('Go to file'), a user icon ('t'), 'Add file' (with a dropdown arrow), and a green 'Code' button. Below this, a message states: 'This branch is 2 commits ahead of, 3 commits behind semilleroCV/Hands-on-Computer-Vision:main.' At the bottom left, there are two buttons: 'Contribute' (with a dropdown arrow) and 'Sync fork' (with a dropdown arrow). The 'Sync fork' button is highlighted with a thick red border.

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