



Introduction to Artificial Intelligence

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CMSC 170 – Introduction to AI
2nd Semester 2009-2010

On a ¼ sheet of paper write...



Your name

Today's date (15 Dec 2009)

CMSC 170 + Laboratory Section

And then, answer the following questions...

Move one
Seat apart!

The UP rules on
Academic Honesty
apply!

Quiz question



In the 2nd CAS UPLB Student-Faculty Research Conference, who presented the topic “**Structural Analysis of the Collaboration Network of Filipino Scientists**”

This is a
Two-minute quiz!
Timer starts now!

This is the guy from chem.

Quiz question



In the Student-Faculty Research
Conference on the topic "Structural
Analysis and Design of Network of Filipino
Structures"

TIME IS UP!

Pass papers towards
the center aisle. People at
The center aisle pass
Forward. And two people in
Front pass them to teacher!

Answer to quiz



Prof. Jose Rene L. Micor

Issue last meeting



Is the complexity of BFS $O(b^d)$ or $O(b^m)$?

It should be $O(b^m)$
because I search
the Internet and it says so!

No! Internet does not give
you the correct answer always



Issue last meeting

Since the quiz question was asking for the respective complexities in terms of b , d , and m , the correct answer in this case is $O(b^d)$.

Most Internet sources only
Describe the complexities
In terms of b and m only.

Sometimes, we must think
hard enough before we accept
information from the Internet
as correct.



Hybrid Technique

DFS is efficient in space (or memory) but we are not guaranteed to get the optimal path length.

BFS guarantees it but is not efficient in using space (or memory).

Can we sort of find
a hybrid of the two?

What about if we
tease DFS to marry
BFS?



Iterative Deepening

Iterative Deepening: hybrid DFS and BFS

Perform a sequence of DFS searches with increasing depth-cut until goal is found.

It turns out that the two had been at it a long time ago.

Was their love child ever good?

Iterative Deepening



Cut-off Depth	Space	Time
1	$O(b)$	$O(b)$
2	$O(2b)$	$O(b^2)$
3	$O(3b)$	$O(b^3)$
4	$O(4b)$	$O(b^4)$
...
d	$O(db)$	$O(b^d)$
Total	Max= $O(db)$	Total = $O(b^{d+1})$

Uniform Cost Search



BFS and Iterative Deepening find find with fewest steps (or time).

But what if steps have unequal cost?

Kinda of like going from Manila to Davao via airplane which is faster...

But more expensive than if we go the ro-ro. way!

And probably would have taken the longer path!



Uniform Cost Search

How can we find the shortest path (measured by the sum of distances along the path)?

Uniform Cost Search:

- Nodes in agenda keeps track of total path length from start to that node

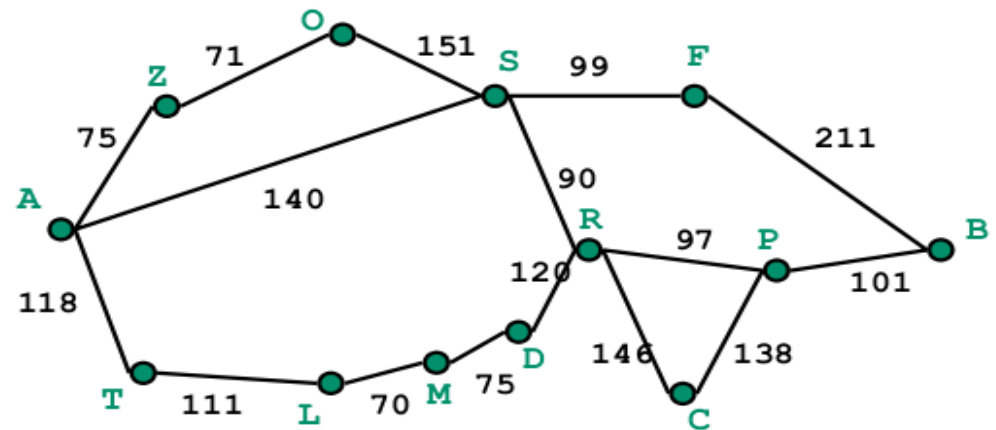
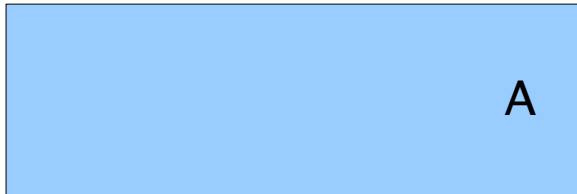
- Agenda is kept in priority queue ordered by path length

- Get shortest path in queue

Uniform Cost Search



Example:



Uniform Cost Search

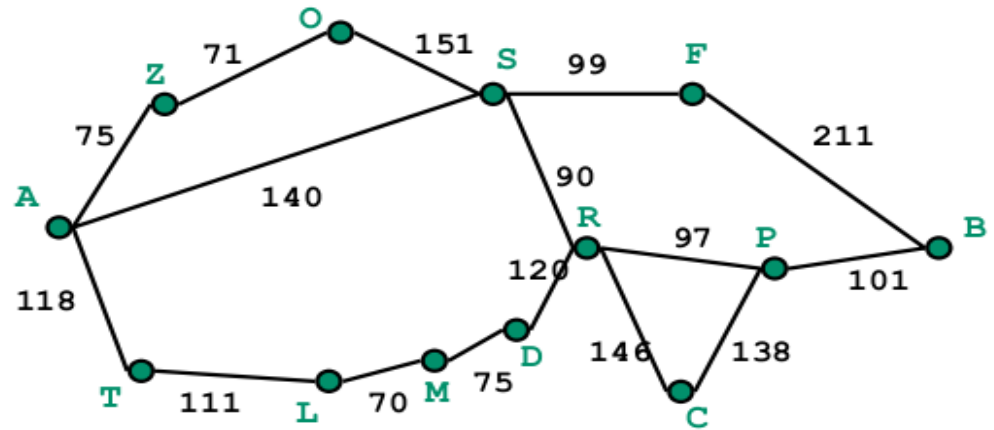


Example:

A

STZ

A



Uniform Cost Search

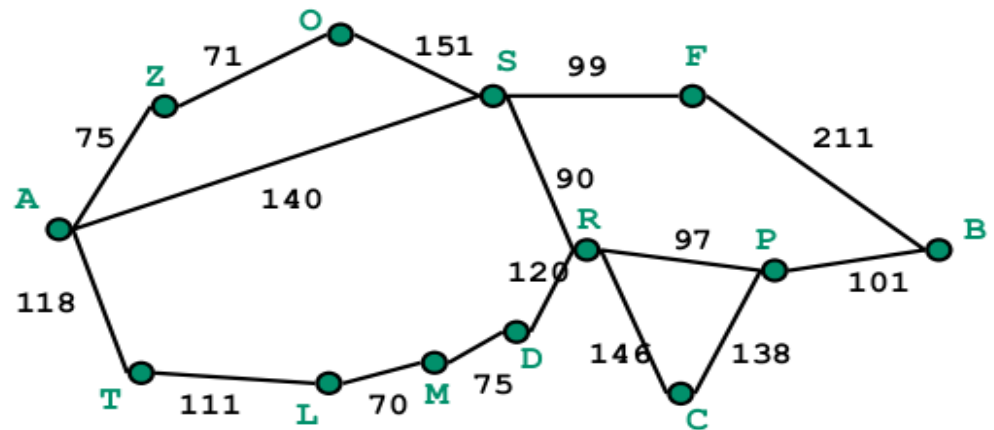


Example:



A

ZA



Uniform Cost Search



Example:

A

STZ

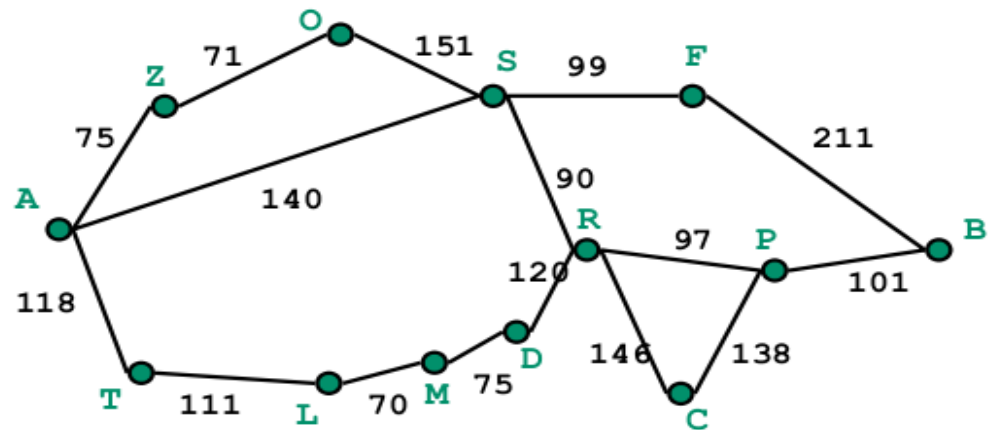
OST

LOS

A

ZA

TZA



Uniform Cost Search



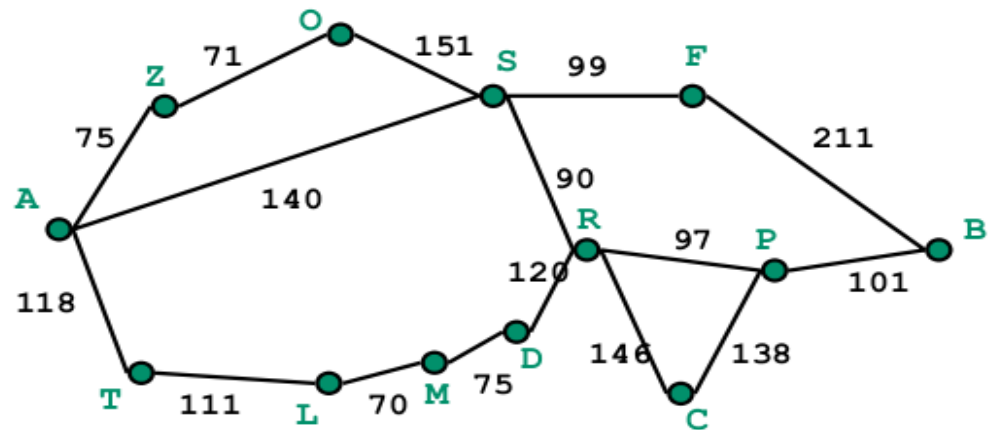
Example:

LOS

OFRLO

TZA

STZA



Uniform Cost Search



Example:

LOS

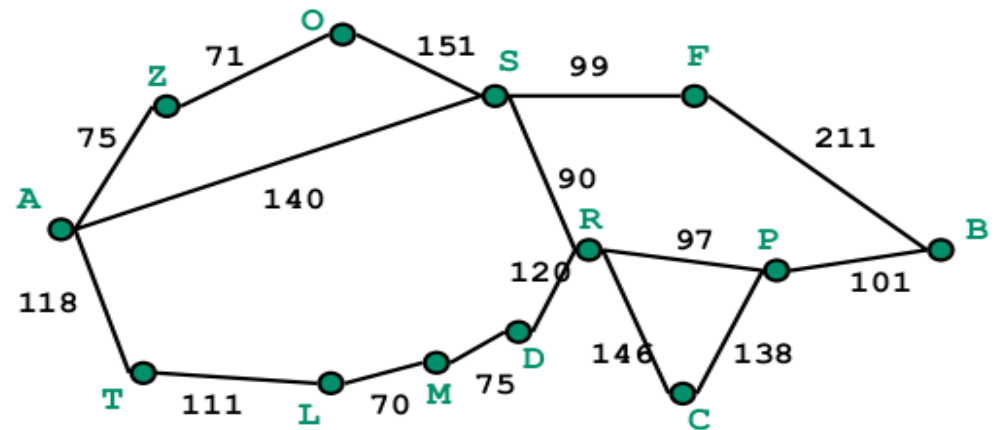
OFRLO

OFRL

TZA

STZA

OTZA

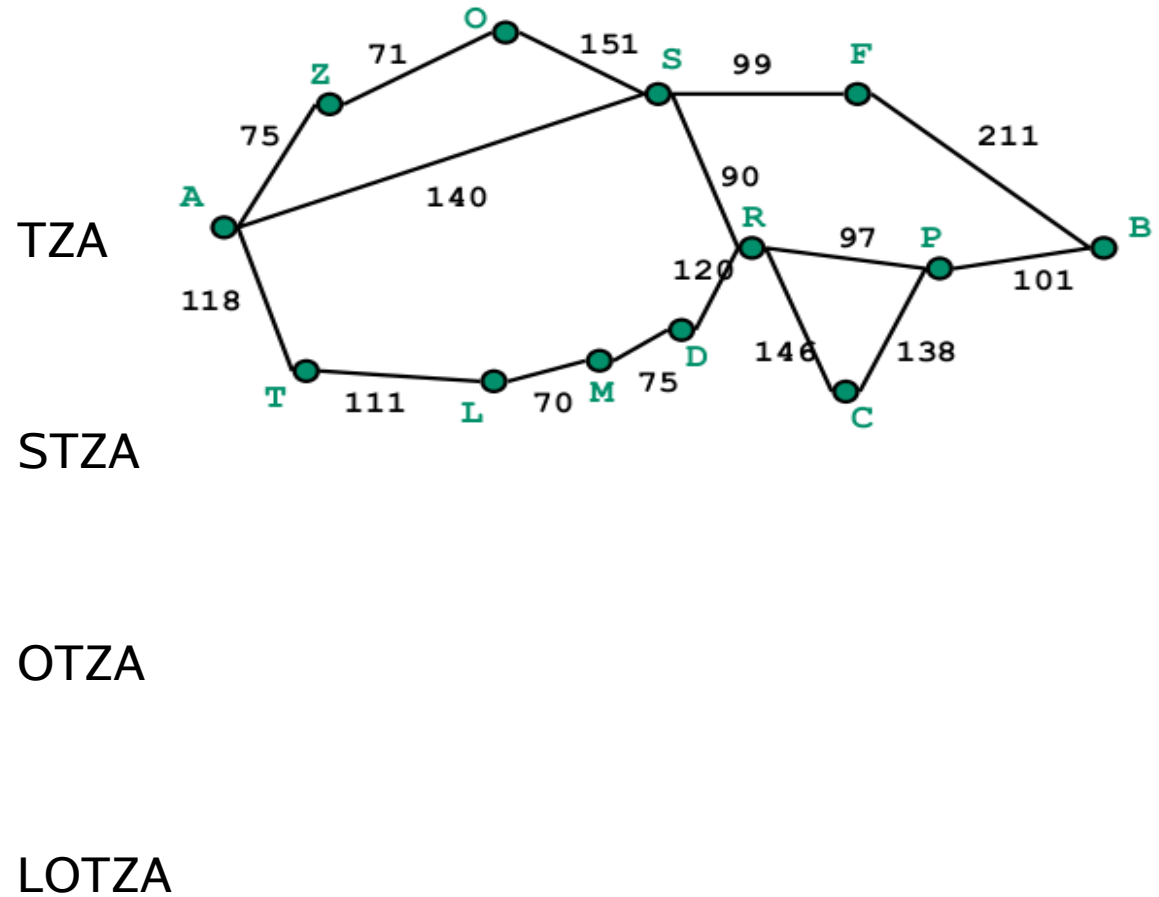


Uniform Cost Search



Example:

LOS
OFRLO
OFRL
MOFR



Uniform Cost Search



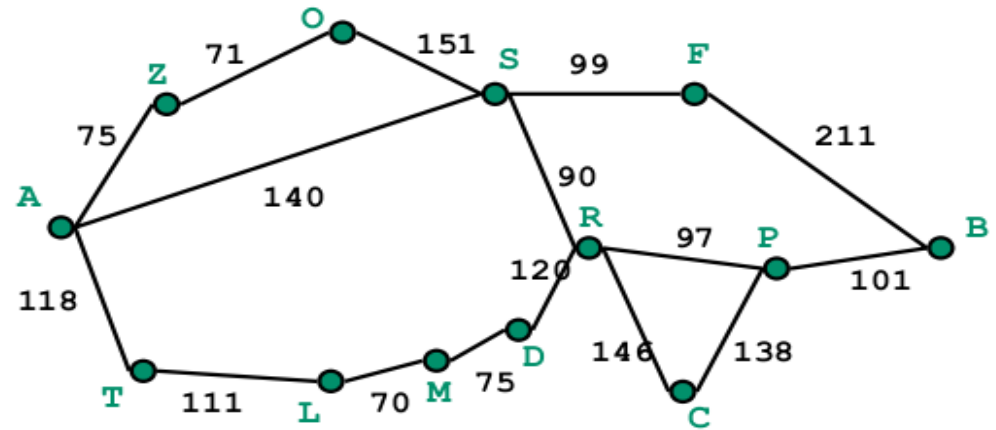
Example:

MOFR

CDPMOF

LOTZA

RLOTZA



Uniform Cost Search



Example:

MOFR

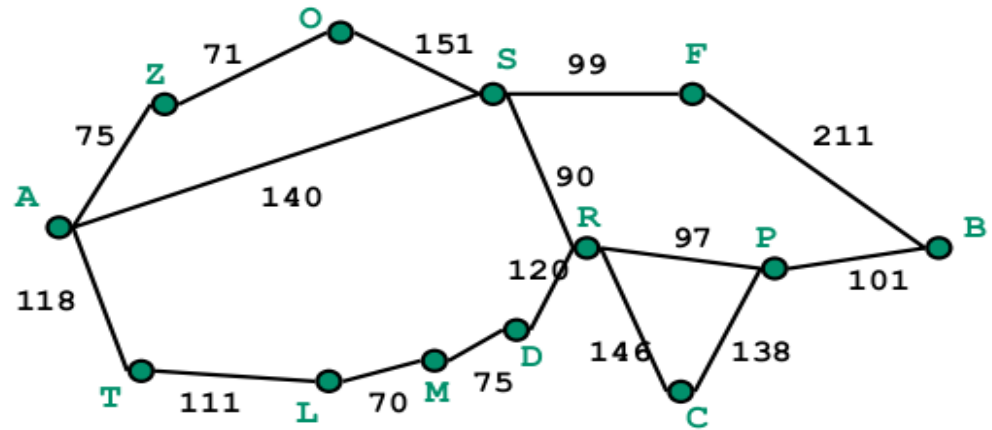
CDPMOF

BCDPMO

LOTZA

RLOTZA

FRLOTZA



The target is already in the agenda. Do we stop here?

Uniform Cost Search



Example:

MOFR

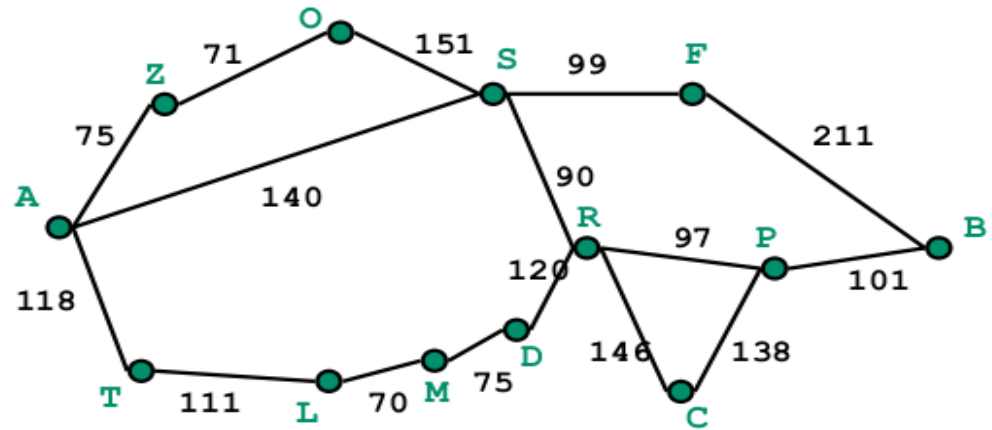
CDPMOF

BCDPMO

LOTZA

RLOTZA

FRLOTZA



But eventually, we will get to another B via S, R and P.

Uniform Cost Search



Example:

MOFR

CDPMOF

BCDPMO

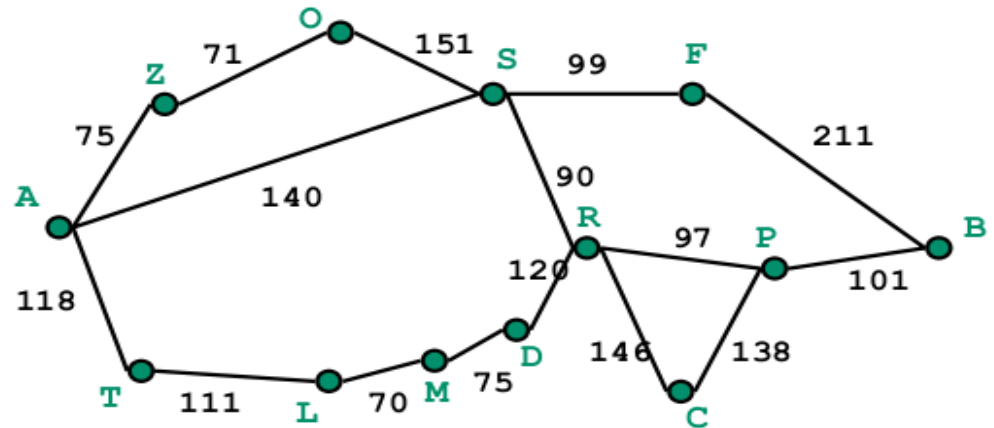
BCDPM

LOTZA

RLOTZA

FRLOTZA

OFRLOTZA



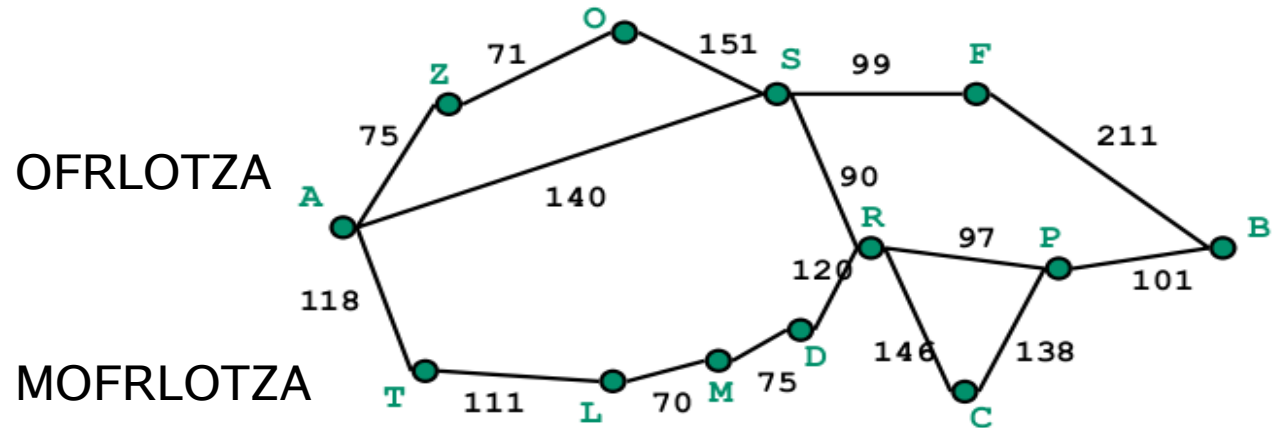
Uniform Cost Search



Example:

BCDPM

DBC DP



Uniform Cost Search



Example:

BCDPM

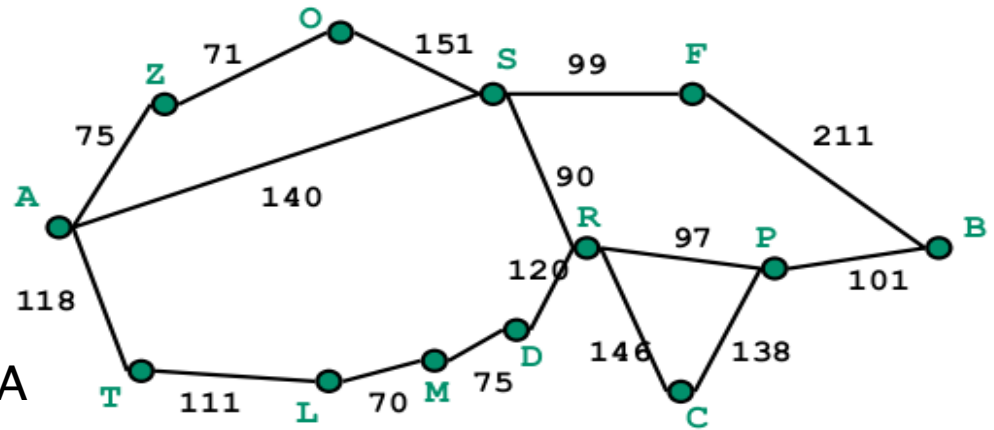
DBC DP

CBBCD

OFRLOTZA

MOFRLOTZA

PMOFRLOTZA



Uniform Cost Search



Example:

BCDPM

DBCDP

CBBCD

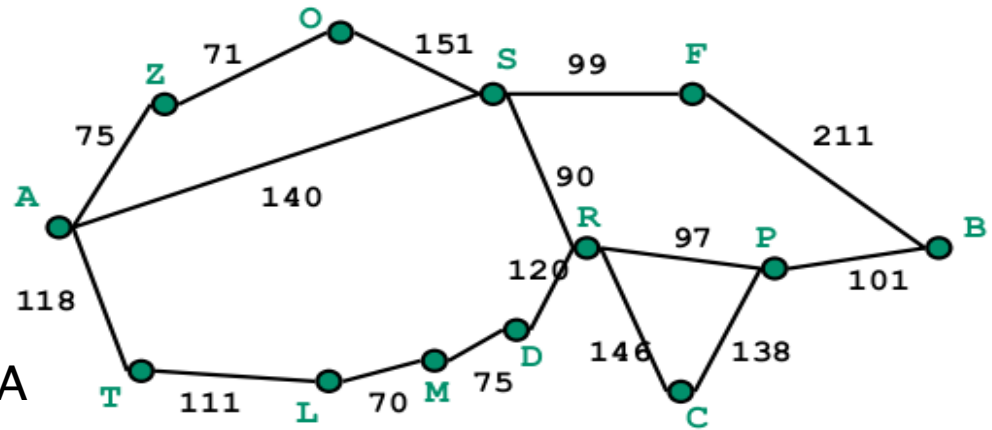
ASRPB = 428

ASFB = 140

OFRLOTZA

MOFRLOTZA

PMOFRLOTZA





Uniform Cost Search

Example:

BCDPM

DBC DP

CBBCD

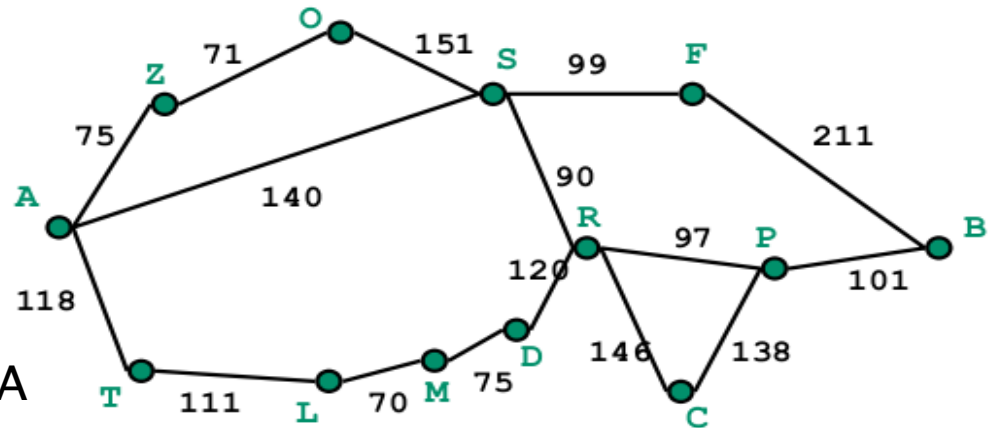
ASRPB = 428

ASFB = 140

OFRLOTZA

MOFRLOTZA

PMOFRLOTZA



It turns out that the first goal node that we remove from the agenda is the shortest path.