

Istanbul Technical University

Faculty of Electrical and Electronics Engineering

Spring Semester 2022-2023

EEF 212E

HOMEWORK – 1



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Each student is viewed as a responsible professional in engineering, and thus highest ethical standards are presumed.



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Due: March 19, 2023, till 23.30

- You need to upload HW to Ninova. Other options are not accepted!
- You need to show all the steps during operations. Otherwise, the questions are not graded.
- Do Not forget to write your name!
- The total point is 100 and each question has the same importance.

Q-1) Given the vector field $\vec{A} = x\hat{a}_x + y\hat{a}_y$ and the volume specified by

$$V : a \leq R \leq b, \quad 0 \leq \theta < \pi, \quad 0 \leq \phi < 2\pi$$

where, R, θ, ϕ are the usual spherical coordinate parameters, verify the Divergence Theorem through this defined volume above.

Hint: Verification of the Divergence Theorem is to show the following equality

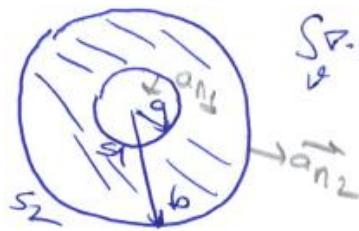
$$\int_V (\vec{\nabla} \cdot \vec{A}) dV = \oint_S \vec{A} \cdot d\vec{S}$$

You can use any tools to evaluate the integrals

One suggestion: <https://www.wolframalpha.com/>

Question

Verify Div. Theorem



$$\int \nabla \cdot \vec{A} dV = \oint \vec{A} \cdot d\vec{s}$$

$$\nabla \cdot \vec{A} = \left[\frac{\partial}{\partial x} a_x + \frac{\partial}{\partial y} a_y + \frac{\partial}{\partial z} a_z \right] - [x a_x + y a_y] = 1+1=2$$

$$\int_V (\nabla \cdot \vec{A}) dV = \underbrace{\frac{4\pi}{3} [b^3 - a^3]}_{V} 2 = \boxed{\frac{8\pi}{3} [b^3 - a^3]}$$

RHS \rightarrow we have two surfaces $S_1 \neq S_2$

$$\oint_S = \int_{S_1} + \int_{S_2}$$

$$\begin{aligned} d\vec{S}_1 &= -\vec{a}_r dS_1 \\ d\vec{S}_2 &= \vec{a}_r dS_2 \end{aligned}$$

$$\int_{S_1} \vec{A} \cdot d\vec{S}_1 =$$

$$\vec{A} = x \vec{a}_x + y \vec{a}_y$$

$$d\vec{S}_1 = -\vec{a}_r a^2 \sin\theta d\theta d\phi$$

$$\vec{A} \cdot d\vec{S}_1 =$$

$$a_r a_x = \sin\theta \cos\phi$$

$$x = a \sin\theta \cos\phi$$

$$y = a \sin\theta \sin\phi$$

$$a_r a_y = \sin\theta \sin\phi$$

$$\int_{S_1} \vec{A} \cdot d\vec{S}_1 = \int_0^\pi \int_0^{2\pi} [a \sin\theta \cos\phi \vec{a}_x + a \sin\theta \sin\phi \vec{a}_y] \cdot [\vec{a}_r a^2 \sin\theta d\theta d\phi]$$

$$= - \int_0^\pi \int_0^{2\pi} [a^2 (\sin^2 \theta \cos^2 \phi) (\sin\theta \cos\phi) + (a^2 \sin^2 \theta \sin\phi) (\sin\theta \sin\phi)] d\theta d\phi$$

$$= -a^3 \int_0^\pi \int_0^{2\pi} (\sin^2 \theta \cos^2 \phi + \sin^2 \theta \sin^2 \phi) d\theta d\phi$$

$$-\alpha^2 \left[\underbrace{\int_0^{2\pi} \cos^2 \phi d\phi}_{\frac{\pi}{2}} \underbrace{\int_0^{\pi} \sin^2 \theta d\theta}_{\frac{\pi}{2}} + \underbrace{\int_0^{2\pi} \sin^2 \phi d\phi}_{\pi} \underbrace{\int_0^{\pi} \sin^2 \theta d\theta}_{\frac{3\pi}{2}} \right]$$

$$= -\alpha^2 \frac{4\pi}{2} \cdot 2 = \boxed{-\frac{8\pi\alpha^3}{3}}$$

\oint_{S_2} $\int_{S_2} \vec{A} \cdot d\vec{s}_2$, similar to above integral
except $f=b$ $d\vec{s}=dS \hat{e}_2$

$$\int_{S_2} \vec{A} \cdot d\vec{s}_2 =$$

$$\vec{a}_R \cdot \vec{a}_x = \sin \theta \cos \phi \\ \vec{a}_R \cdot \vec{a}_y = \\ \vec{a}_R \cdot \vec{a}_z = \sin \theta \sin \phi$$

$$x = b \sin \theta \cos \phi \text{ on surface} \\ y = b \sin \theta \sin \phi$$

$$= \int_0^{\pi} \int_0^{2\pi} [(b \sin \theta \cos \phi) dx + (b \sin \theta \sin \phi) dy] \cdot (\vec{a}_R \cdot b^2 \sin \theta d\theta d\phi)$$

$$\Rightarrow \phi = 0$$

$$= \int_0^{\pi} \int_0^{2\pi} [b^2 (\sin^2 \theta \cos^2 \phi) (\sin \theta \cos \phi) + (b^2 \sin^2 \theta \sin^2 \phi) (\sin \theta \sin \phi)] d\theta d\phi$$

$$= b^2 \int_0^{\pi} \int_0^{2\pi} [\sin^2 \theta \cos^2 \phi + \sin^2 \theta \sin^2 \phi] d\theta d\phi$$

$$= b^2 \left[\int_0^{2\pi} \cos^2 \phi d\phi \int_0^{\pi} \sin^2 \theta d\theta + \int_0^{2\pi} \sin^2 \phi d\phi \int_0^{\pi} \sin^2 \theta d\theta \right]$$

$$= b^2 \frac{4\pi}{2} \cdot 2 = \frac{8\pi b^2}{3}$$

$$\oint = \int_{S_1} + \int_{S_2} \Rightarrow \frac{8\pi}{3} [b^3 - \alpha^3] \quad \underline{\text{verified}} \quad \text{Left} = \text{Right}$$

Q-2) Verify the Divergence Theorem for the vector field $\vec{A} = 3R\hat{a}_R$ given in spherical coordinates, and for the conical region (of height $h = 2$ and apex angle $\theta_0 = \frac{\pi}{4}$) shown in the figure below.

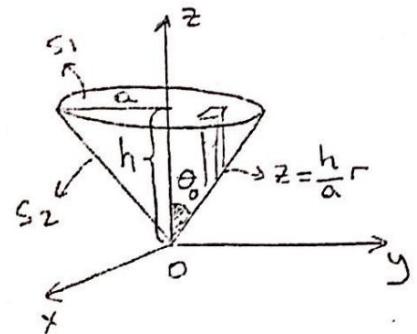
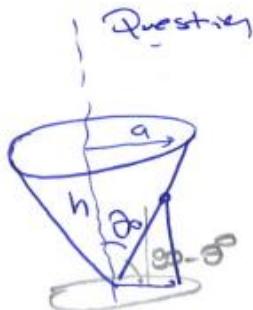


Figure 1. The geometry of Q-2.



$$\theta_0 = \pi/4 = 45^\circ$$

$$\int \nabla \cdot \vec{A} dV = \oint \vec{A} \cdot d\vec{s}$$

LHS RHS

$$\nabla \cdot \vec{A} = \nabla \cdot (Ar \hat{\omega}_e) = \frac{1}{r^2} \frac{\partial}{\partial r} [r^2 A_r] = \frac{1}{r^2} \frac{\partial}{\partial r} [3r^3] = 9$$

choose cylindrical coordinate system

$$\tan(\phi - \theta_0) = \frac{z}{r}$$

Let us write z in terms of r and given parameter

$$\underbrace{\tan(\phi - \theta_0)}_{\text{constant}} = \frac{h}{a}$$

$$z = \tan(\phi - \theta_0) r$$

$$\boxed{z = \frac{hp}{a}} \rightarrow z \text{ can be obtained in terms of } r$$

$$\text{LHS} = \int_V \nabla \cdot \vec{A} dV = \int_0^a \int_{\rho=0}^h \int_{\phi=0}^{2\pi} 9pr \sin \phi d\phi d\rho dz = 2\pi 9 \left[pr x \right]_0^a \left[x \left(h - \frac{h}{a} r \right) \right]_0^a$$

\downarrow
 $\rho d\rho d\phi dz$

$$\text{LHS} = 9 \cdot 2\pi \left(\frac{ha^2}{2} - \frac{ha^2}{3} \right) = \boxed{\frac{9}{3} h \pi a^2}$$

$$a, h = 2$$

$$\begin{matrix} a^2 = 4 \\ h = 2 \end{matrix}$$

volume of the core

$$\Rightarrow \boxed{24\pi} \text{ LHS}$$

RHS

$$\begin{aligned} \oint \vec{A} \cdot d\vec{s} &= \int_{S_1} [3R\hat{a}_r \cdot \hat{a}_z ds_z] + \int_{S_2} \cancel{(3R\hat{a}_r) \cdot \hat{a}_\theta ds_\theta} \\ &\quad a_r \cdot a_\theta = 0 \\ &= \int_{S_1} 3R \underbrace{\cos\theta}_{h} ds_z = 6 \int_{S_2} ds_z = \boxed{24\pi} \quad \text{RHS} \\ &\quad \text{Rcos}\theta \text{ on surface} \quad h \quad R \\ &\quad (h=2) \\ \oint \text{LHS} &= R \int_{S_1} ds_z = \underline{24\pi} \\ &\quad \text{Div. Theorem is verified} \end{aligned}$$

Q-3) A vector field \vec{F} , is defined with the following expression:

$$\vec{F} = \hat{a}_x + \hat{a}_y z^4 + \hat{a}_z (4yz^3 + 5)$$

- (a) Determine the divergence of \vec{F}
- (b) Determine the curl of \vec{F}
- (c) Find $\int_C \vec{F} \cdot d\vec{l}$ where the contour C is defined from the point $P_1(0,0,3)$ to point $P_2(1,0,3)$ as shown in the figure

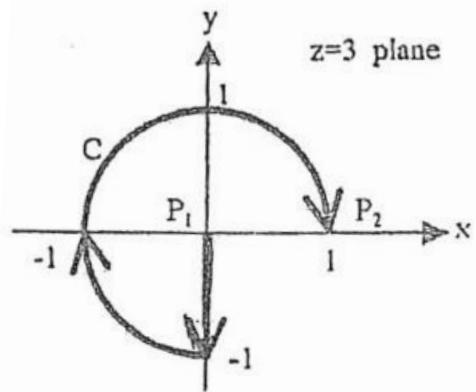


Figure 2. The geometry of Q-3.

$$\tilde{F} = \vec{a}_x + z^4 \vec{a}_y + (4yz^3 + 5) \vec{a}_z$$

$$z=3$$

(a)

$$\nabla \cdot \tilde{F} = \left(\frac{\partial}{\partial x} a_x + \frac{\partial}{\partial y} a_y + \frac{\partial}{\partial z} a_z \right) \cdot (a_x + z^4 a_y + (4yz^3 + 5) a_z)$$

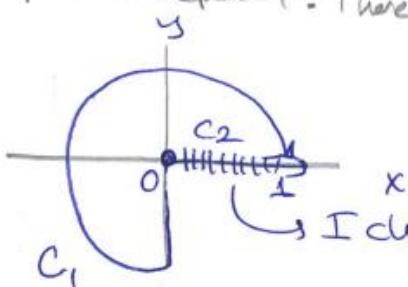
$$\frac{\partial}{\partial z} (4yz^3 + 5) = 12yz^2 = \underline{\underline{12yz^2}}$$

(b)

$$\nabla \times \tilde{F} = \begin{vmatrix} a_x & a_y & a_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 1 & z^4 & 4yz^3 + 5 \end{vmatrix} = 0$$

\tilde{F} is irrotational, conservative field.

path independent. Therefore I choose simple contour



$$\int_{C_1} \tilde{F} \cdot d\vec{r} = \int_{C_2} \tilde{F} \cdot d\vec{r} \Rightarrow \text{all of the full credit}$$

I choose this path (since path independent)

$$\int_{C_1} \tilde{F} \cdot d\vec{r} = \int_{C_2} \tilde{F} \cdot d\vec{r} \Rightarrow C_2: d\vec{r} = dx \vec{a}_x$$

$$\int_0^1 (a_x + z^4 a_y + 4yz^3 + 5) \cdot \vec{a}_x \, dx$$

$$(z=3) \Rightarrow \textcircled{1}$$

$$\int_C \tilde{F} \cdot d\vec{r} = 1$$

Any path? Any path can be chosen since it is path independent

Q-4) Find the angle between the surfaces $x^2 + y^2 + z^2 = 9$ and $x^2 + y^2 - z = 3$ at the point $(2, -1, 2)$

Hint: Think about the Gradient operator and then Dot Product

The angle between the surfaces at the point is the angle between the normals to the surfaces at the point.

A normal to $x^2 + y^2 + z^2 = 9$ at $(2, -1, 2)$ is

$$\nabla\phi_1 = \nabla(x^2 + y^2 + z^2) = 2x\mathbf{i} + 2y\mathbf{j} + 2z\mathbf{k} = 4\mathbf{i} - 2\mathbf{j} + 4\mathbf{k}$$

A normal to $z = x^2 + y^2 - 3$ or $x^2 + y^2 - z = 3$ at $(2, -1, 2)$ is

$$\nabla\phi_2 = \nabla(x^2 + y^2 - z) = 2x\mathbf{i} + 2y\mathbf{j} - \mathbf{k} = 4\mathbf{i} - 2\mathbf{j} - \mathbf{k}$$

$(\nabla\phi_1) \cdot (\nabla\phi_2) = |\nabla\phi_1| |\nabla\phi_2| \cos \theta$, where θ is the required angle. Then

$$(4\mathbf{i} - 2\mathbf{j} + 4\mathbf{k}) \cdot (4\mathbf{i} - 2\mathbf{j} - \mathbf{k}) = |4\mathbf{i} - 2\mathbf{j} + 4\mathbf{k}| |4\mathbf{i} - 2\mathbf{j} - \mathbf{k}| \cos \theta$$

$$16 + 4 - 4 = \sqrt{(4)^2 + (-2)^2 + (4)^2} \sqrt{(4)^2 + (-2)^2 + (-1)^2} \cos \theta$$

and $\cos \theta = \frac{16}{6\sqrt{21}} = \frac{8\sqrt{21}}{63} = 0.5819$; thus the acute angle is $\theta = \arccos 0.5819 = 54^\circ 25'$.

Q-5) Prove that $\nabla^2 \left(\frac{1}{r} \right) = 0$

Here r can be taken as $r = \sqrt{x^2 + y^2 + z^2}$

$$\nabla^2 \left(\frac{1}{r} \right) = \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) \left(\frac{1}{\sqrt{x^2+y^2+z^2}} \right)$$

$$\frac{\partial}{\partial x} \left(\frac{1}{\sqrt{x^2+y^2+z^2}} \right) = \frac{\partial}{\partial x} (x^2+y^2+z^2)^{-1/2} = -x(x^2+y^2+z^2)^{-3/2}$$

$$\begin{aligned} \frac{\partial^2}{\partial x^2} \left(\frac{1}{\sqrt{x^2+y^2+z^2}} \right) &= \frac{\partial}{\partial x} [-x(x^2+y^2+z^2)^{-3/2}] \\ &= 3x^2(x^2+y^2+z^2)^{-5/2} - (x^2+y^2+z^2)^{-3/2} = \frac{2x^2-y^2-z^2}{(x^2+y^2+z^2)^{5/2}} \end{aligned}$$

Similarly,

$$\frac{\partial^2}{\partial y^2} \left(\frac{1}{\sqrt{x^2+y^2+z^2}} \right) = \frac{2y^2-z^2-x^2}{(x^2+y^2+z^2)^{5/2}} \quad \text{and} \quad \frac{\partial^2}{\partial z^2} \left(\frac{1}{\sqrt{x^2+y^2+z^2}} \right) = \frac{2z^2-x^2-y^2}{(x^2+y^2+z^2)^{5/2}}$$

$$\text{Then by addition, } \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) \left(\frac{1}{\sqrt{x^2+y^2+z^2}} \right) = 0.$$

The equation $\nabla^2 \phi = 0$ is called *Laplace's equation*. It follows that $\phi = 1/r$ is a solution of this equation.