

1.2.

$y(t) = \cos(x(t))$ → the output depends on the input at that specific time
memoryless



→ the outputs are bounded by t
cosinus is oscillating $[1, -1]$
stable

from the graph

and the Taylor series of cos function → the output does not depend on future values

$$\cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} \dots$$

causal

we can clearly see that $a_1x_1(t) + b_1x_2(t) \rightarrow ay_1(t) + by_2(t)$
there's no linear combination
non-linear

$y(t) \rightarrow \cos(x(t))$ → output does not change

$y(t-t_0) \rightarrow \cos(x(t-t_0))$ → the same amount of time
time-variant

1.b.

$$y[n] = 2x[n] + u[n]$$

memoryless

- the output does not depend on previous values unstable
- we cannot bound outputs based on inputs Causal
- output does not depend on future values
- $y_1[n] + y_2[n] = 2u[n]x_1[n] + 2u[n]x_2[n]$ linear
- different inputs produce different $x[n]$ values. Therefore $y[n]$ is time-variant

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2.

$$x(t) = u(t+1) - u(t-1)$$

$$y(t) = u(t) + u(t-2) - 2u(t-4)$$

$$m(t) = \int_{-\infty}^{\infty} x(\tau) * y(t-\tau) d\tau = \int_{-\infty}^{\infty} y(\tau) x(t-\tau) d\tau$$

$$m(t) = \mathcal{L}^{-1} m(s)$$

$$x(s) = \frac{e^s}{s} - \frac{e^{-s}}{s}$$

$$y(s) = \frac{1}{s} + \frac{e^{-2s}}{s} - 2 \frac{e^{-4s}}{s}$$

$$m(s) = x(s) \cdot y(s) = \left(\frac{e^s - e^{-s}}{s} \right) \frac{1}{s} \left(1 + e^{-2s} - 2e^{-4s} \right)$$

$$m(s) = \frac{1}{s^2} e^s - \frac{3}{s^2} e^{-3s} + \frac{2}{s^2} e^{-5s}$$

$$m(t) = (t+1)u(t+1) - 3(t-3)u(t-3) + 2(t-5)u(t-5)$$

$$m(t) = \mathbf{1}_{(t+1)} - 3\delta(t-3) + 2\delta(t-5)$$

3.

$$\sin \theta = [e^{j\theta} - e^{-j\theta}] \frac{1}{2j}$$

$$\cos \theta = [e^{j\theta} + e^{-j\theta}] \frac{1}{2}$$

$$x(t) = \frac{1}{2j} [e^{j3\pi t} - e^{-j3\pi t}] + \frac{1}{2} [e^{j\pi t} + e^{-j\pi t}]$$

$$c_k = \frac{-2}{2\pi} \left[\frac{1}{2k-1} - \frac{1}{2k+1} \right] = \frac{-1}{\pi} \left[\frac{(2k+1) - (2k-1)}{4k^2 - 1} \right]$$

$$c_k = \frac{-2}{\pi(4k^2-1)}$$

$$a_0 = \frac{1}{T} \int_0^T x(t) dt$$

$$a_0 = \frac{-\cos \pi t}{\pi} \Big|_0^\pi = \frac{-[\cos \pi - \cos 0]}{\pi} = \frac{2}{\pi}$$

$$x(t) = \frac{2}{\pi} + \sum_{k=1}^{\infty} c_k e^{j\pi k t} \quad , \quad c_k = \frac{-2}{\pi(4k^2-1)}$$

4.

$$x(t) = \sum_{n=-\infty}^{\infty} c_n e^{jn\omega_0 t} \quad \omega_0 = 2\pi$$

$$c_1 = j \quad c_{-1} = -j \quad c_2 = 1 \quad c_3 = -1$$

$$x(t) = J e^{j2\pi t} - J e^{-j2\pi t} + e^{j3 \times 2\pi t} + e^{-j3 \times 2\pi t}$$

$$x(t) = \frac{-2(e^{j2\pi t} - e^{-j2\pi t})}{2j} + \frac{2(e^{j6\pi t} + e^{-j6\pi t})}{2}$$

$$\boxed{x(t) = 2\cos 6\pi t - 2\sin 2\pi t}$$

5.

$$x(t) = \begin{cases} 1 & : |t| < 2 \\ 0 & : |t| > 2 \end{cases}$$

$$x(t) = 1 \quad -\infty \leq t \leq 2$$

$$x(t) = 0 \quad 2 \leq t \leq \infty$$

$$x(\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt$$

$x(t)$ between

-2 and +2

$$x(\omega) = \int_{-\infty}^{\infty} e^{-j\omega t} dt = \left[\frac{e^{-j\omega t}}{-j\omega} \right]_{-\infty}^{\infty}$$

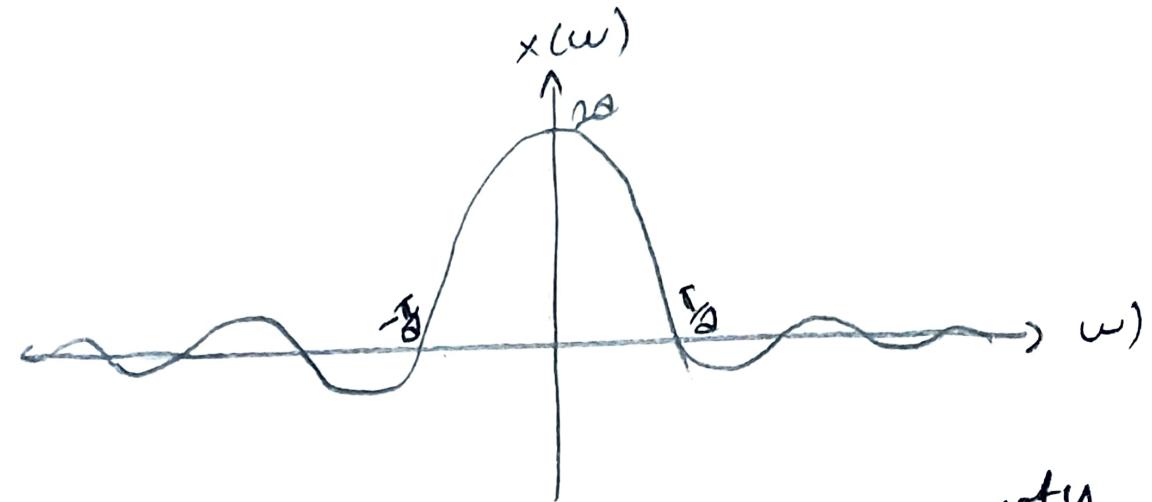
$$= \left[\frac{e^{j2\omega} - e^{-j2\omega}}{-j\omega} \right] \quad \omega \neq 0 \text{ let's say}$$

$$= \frac{2 \sin(\omega)}{\omega}$$

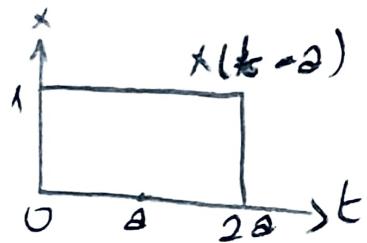
$$= 2 \cdot \frac{\sin(\omega)}{2\omega}$$

$\sin(x)$

$\omega x = \omega \omega$



shifting property



$$\text{FT of } x(t - t_0) = e^{-j\omega t_0} x(\omega)$$

$t_0 = a$

$$\text{FT of } x(t - a) = e^{-j\omega a} 2a \frac{\sin \omega}{\omega}$$

6.

$$x(j\omega) = e^{-2j\omega} = \begin{cases} e^{-2\omega} & \omega \geq 0 \\ e^{2\omega} & \omega < 0 \end{cases}$$

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} x(j\omega) e^{j\omega t} d\omega$$

$$= \frac{1}{2\pi} \left[\int_{-\infty}^0 e^{2\omega} \cdot e^{j\omega t} d\omega + \int_0^{\infty} e^{-2\omega} \cdot e^{j\omega t} d\omega \right]$$

$$= \frac{1}{2\pi} \left[\left. \frac{e^{(2+jt)\omega}}{2+jt} \right|_0^\infty + \left. \frac{e^{-(2-jt)\omega}}{-(2-jt)} \right|_0^\infty \right]$$

$$= \frac{1}{2\pi} \left[\frac{e^0 - e^{-\infty}}{2+jt} + \frac{e^{-\infty} - e^0}{-(2-jt)} \right]$$

$$= \frac{1}{2\pi} \left[\frac{1}{2+jt} + \frac{1}{2-jt} \right] = \frac{1}{2\pi} \left[\frac{4}{4+t^2} \right]$$

$$x(t) = \frac{2}{\pi(4+t^2)}$$