

Istanbul Technical University
Faculty of Electrical and Electronics Engineering
Spring Semester 2022-2023
EEF 212E
HOMEWORK – 1



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Each student is viewed as a responsible professional in engineering, and thus highest ethical standards are presumed.



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HOMEWORK – 1

Due: March 19, 2023, till 23.30

- You need to upload HW to Ninova. Other options are not accepted!
- You need to show all the steps during operations. Otherwise, the questions are not graded.
- Do Not forget to write your name!
- The total point is 100 and each question has the same importance.

Q-1) Given the vector field $\vec{A} = x\hat{a}_x + y\hat{a}_y$ and the volume specified by

$$\mathcal{V} : a \leq R \leq b, \quad 0 \leq \theta < \pi, \quad 0 \leq \phi < 2\pi$$

where, R, θ, ϕ are the usual spherical coordinate parameters, **verify** the Divergence Theorem through this defined volume above.

Hint: Verification of the Divergence Theorem is to show the following equality

$$\int_{\mathcal{V}} (\vec{\nabla} \cdot \vec{A}) \cdot dv = \oint_S \vec{A} \cdot d\vec{S}$$

You can use any tools to evaluate the integrals

One suggestion: <https://www.wolframalpha.com/>

QUESTION
Verify Div. Theorem



$$\int_V \nabla \cdot \vec{A} dV \stackrel{?}{=} \oint_S \vec{A} \cdot d\vec{S}$$

$$\nabla \cdot \vec{A} = \left[\frac{\partial}{\partial x} 0x + \frac{\partial}{\partial y} 0y + \frac{\partial}{\partial z} 0z \right] \cdot [x\vec{a}_x + y\vec{a}_y] = 1+1 = \underline{\underline{2}}$$

$$\int_V (\nabla \cdot \vec{A}) dV = \underbrace{\frac{4}{3}\pi [b^3 - a^3]}_{V} 2 = \boxed{\frac{8}{3}\pi [b^3 - a^3]}$$

RHS \rightarrow we have two surfaces S_1 & S_2

$$\oint_S = \int_{S_1} + \int_{S_2}$$

$$\boxed{\begin{aligned} d\vec{S}_1 &= -a^2 \vec{e}_r d\Omega \\ d\vec{S}_2 &= a^2 \vec{e}_r d\Omega \end{aligned}}$$

$$\int_{S_1} \vec{A} \cdot d\vec{S}_1 =$$

$$\vec{A} = x\vec{a}_x + y\vec{a}_y$$

$$d\vec{S}_1 = -a^2 \vec{e}_r \sin\theta d\theta d\phi$$

$$\vec{A} \cdot d\vec{S}_1 =$$

$$a_r \cdot a_x = \sin\theta \cos\phi$$

$$x = a \sin\theta \cos\phi$$

$$a_r \cdot a_y = \sin\theta \sin\phi$$

$$y = a \sin\theta \sin\phi$$

$$\int_{S_1} \vec{A} \cdot d\vec{S}_1 = - \int_0^\pi \int_0^{2\pi} \int [\underbrace{[a \sin\theta \cos\phi]}_{\vec{A}} \vec{a}_x + \underbrace{[a \sin\theta \sin\phi]}_{\vec{A}} \vec{a}_y] \cdot \underbrace{[-a^2 \vec{e}_r \sin\theta d\theta d\phi]}_{d\vec{S}_1}$$

$$= - \int_0^\pi \int_0^{2\pi} [a^2 (\sin^2\theta \cos^2\phi) (\sin\theta \cos\phi) + (a^2 \sin\theta \sin\phi) (\sin\theta \sin\phi)] d\theta d\phi$$

$$= - \frac{a^3}{2} \int_0^\pi \int_0^{2\pi} (\sin^2\theta \cos^2\phi + \sin^2\theta \sin^2\phi) d\theta d\phi$$

$$-a^2 \left[\underbrace{\int_0^{2\pi} \cos^2 \phi \, d\phi}_{\pi} \underbrace{\int_0^{\pi} \sin^2 \theta \, d\theta}_{\frac{4}{3}} + \underbrace{\int_0^{2\pi} \sin^2 \phi \, d\phi}_{\pi} \underbrace{\int_0^{\pi} \sin^2 \theta \, d\theta}_{\frac{4}{3}} \right]$$

$$= -a^2 \frac{4\pi}{3} \cdot 2 = \boxed{-\frac{8\pi a^3}{3}}$$

$\oint_{S_2} \vec{A} \cdot d\vec{S}_2$, similar to above integral
except $r=b$ $d\vec{S} = d\vec{S}_2$

$$\int_{S_2} \vec{A} \cdot d\vec{S}_2 =$$

$$\vec{a}_r \cdot \vec{a}_x = \sin \theta \cos \phi$$

$$\vec{a}_r \cdot \vec{a}_y = \sin \theta \sin \phi$$

$$\vec{a}_r \cdot \vec{a}_y = \sin \theta \sin \phi$$

$$x = b \sin \theta \cos \phi \text{ on surface}$$

$$y = b \sin \theta \sin \phi$$

$$= \int_0^{\pi} \int_0^{2\pi} [(b \sin \theta \cos \phi) \vec{a}_x + (b \sin \theta \sin \phi) \vec{a}_y] \cdot (a_r b^2 \sin \theta \, d\theta \, d\phi)$$

$$\theta \rightarrow \pi, \phi \rightarrow 0$$

$$= \int_0^{\pi} \int_0^{2\pi} [b^3 (\sin^2 \theta \cos^2 \phi) + (b^3 \sin^2 \theta \sin^2 \phi)] d\theta \, d\phi$$

$$\theta \rightarrow \pi, \phi \rightarrow 0$$

$$= b^3 \int_0^{\pi} \int_0^{2\pi} (\sin^2 \theta \cos^2 \phi + \sin^2 \theta \sin^2 \phi) d\theta \, d\phi$$

$$= b^3 \left[\int_0^{2\pi} \cos^2 \phi \, d\phi \int_0^{\pi} \sin^2 \theta \, d\theta + \int_0^{2\pi} \sin^2 \phi \, d\phi \int_0^{\pi} \sin^2 \theta \, d\theta \right]$$

$$= \frac{b^3 4\pi}{3} \cdot 2 = \frac{8\pi b^3}{3}$$

$$\oint_{S_1} + \oint_{S_2} \Rightarrow \frac{8\pi}{3} [b^3 - a^3] \quad \underline{\underline{\text{verified}}} \quad \oint d\vec{S} = \oint d\vec{S}$$

Q-2) Verify the Divergence Theorem for the vector field $\vec{A} = 3R\hat{a}_R$ given in spherical coordinates, and for the conical region (of height $h = 2$ and apex angle $\theta_0 = \frac{\pi}{4}$) shown in the figure below.

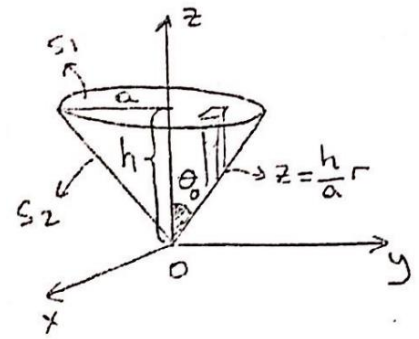


Figure 1. The geometry of Q-2.



$$\theta_0 = \pi/4 = 45^\circ$$

$$\int_V \vec{\nabla} \cdot \vec{A} dV = \oint_{\text{LHS}} \vec{A} \cdot d\vec{S}$$

$$\vec{\nabla} \cdot \vec{A} = \vec{\nabla} \cdot (A_r \hat{e}_r) = \frac{1}{r^2} \frac{\partial}{\partial r} [r^2 A_r] = \frac{1}{r^2} \frac{\partial}{\partial r} [3r^3] = 9$$

Choose cylindrical coordinate system

$$\tan(90^\circ - \theta) = \frac{z}{\rho}$$

Let us write z in terms of ρ and given parameter

$$\tan(90^\circ - \theta) = \frac{h}{a}$$

constat \downarrow

$$z = \tan(90^\circ - \theta) \rho$$

$$\boxed{z = \frac{h\rho}{a}} \rightarrow z \text{ can be obtained in terms of } \rho$$

$$\text{LHS} = \int_V \vec{\nabla} \cdot \vec{A} dV = \int_{\rho=0}^a \int_{z=\frac{h}{a}\rho}^h \int_{\phi=0}^{2\pi} 9\rho d\phi d\rho dz = 2\pi 9 \int_{\rho=0}^a \rho \left[\left(h - \frac{h}{a}\rho \right) \right] d\rho$$

$\rho d\phi d\rho dz$

$$\text{LHS} = 3 \cdot 2\pi \left(\frac{ha^2}{2} - \frac{ha^2}{3} \right) = \boxed{\frac{9}{3} h\pi a^2}$$

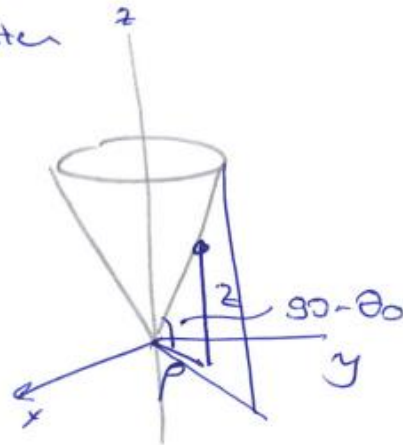
$$a, h = 2$$

$$a^2 = 4$$

$$h = 2$$

volume of the cone

$$\Rightarrow \boxed{24\pi} \text{ LHS}$$




RHS

$$\oint \vec{A} \cdot d\vec{S} = \int_{S_1} [3R \cos \theta \cdot \hat{a}_z] \cdot \hat{a}_z dS_z + \int_{S_2} (3R \cos \theta) \cdot \hat{a}_\theta dS_\theta$$

$\hat{a}_R \cdot \hat{a}_\theta = 0$

$$= \int_{S_1} 3R \cos \theta dS_z = 6 \int_{S_1} dS_z = \boxed{24\pi} \quad \text{RHS}$$

$R \cos \theta$ on surface



$\pi a^2 = 4\pi$

$(h=2)$

$$\oint \vec{A} \cdot d\vec{S} = \text{RHS} = \underline{\underline{24\pi}}$$

Div. Theorem is verified

Q-3) A vector field \vec{F} , is defined with the following expression:

$$\vec{F} = \hat{a}_x + \hat{a}_y z^4 + \hat{a}_z (4yz^3 + 5)$$

- Determine the divergence of \vec{F}
- Determine the curl of \vec{F}
- Find $\int_C \vec{F} \cdot d\vec{l}$ where the contour C is defined from the point $P_1(0,0,3)$ to point $P_2(1,0,3)$ as shown in the figure

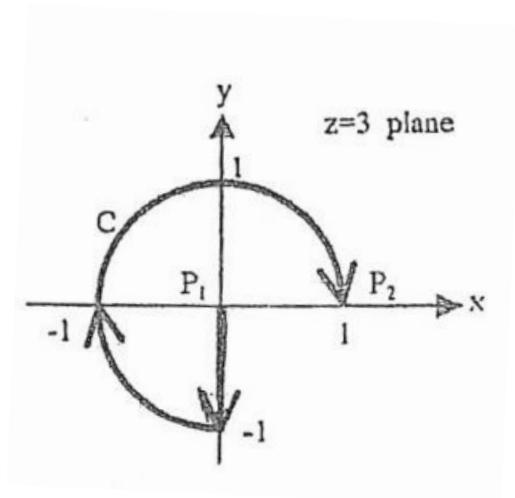


Figure 2. The geometry of Q-3.

Question

$$\vec{F} = \vec{a}_x + z^4 \vec{a}_y + (4yz^3 + 5) \vec{a}_z$$

$z=3$

②

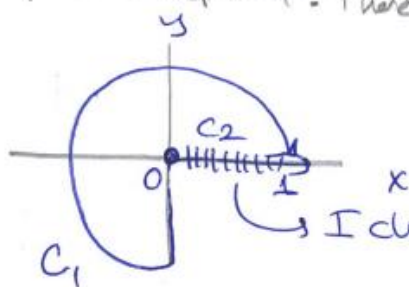
$$\vec{\nabla} \cdot \vec{F} = \left(\frac{\partial}{\partial x} a_x + \frac{\partial}{\partial y} z^4 + \frac{\partial}{\partial z} (4yz^3 + 5) \right) \cdot (\vec{a}_x + z^4 \vec{a}_y + (4yz^3 + 5) \vec{a}_z)$$

$$\frac{\partial}{\partial z} (4yz^3 + 5) = 12yz^2 = \underline{\underline{12yz^2}}$$

③

$$\vec{\nabla} \times \vec{F} = \begin{vmatrix} \vec{a}_x & \vec{a}_y & \vec{a}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 1 & z^4 & 4yz^3 + 5 \end{vmatrix} = \underline{\underline{0}}$$

\vec{F} is irrotational, conservative field.
path independent. Therefore I choose simple contour



$$\int_{C1} \vec{F} \cdot d\vec{e} = \int_{C2} \vec{F} \cdot d\vec{e} \Rightarrow \text{all of them are full credit}$$

I choose this path (since path independent)

$$C2: d\vec{e} = dx \vec{a}_x$$

$$\int_{C1} \vec{F} \cdot d\vec{e} = \int_{C2} \vec{F} \cdot d\vec{e} \Rightarrow \int_0^1$$

$$\int_0^1 (a_x + z^4 a_y + 4yz^3 + 5) \cdot \vec{a}_x dx$$

$$(z=3) \Rightarrow \underline{\underline{1}}$$

$$\int_C \vec{F} \cdot d\vec{e} = \underline{\underline{1}}$$

Any path can be chosen.
Since it is path independent

Q-4) Find the angle between the surfaces $x^2 + y^2 + z^2 = 9$ and $x^2 + y^2 - z = 3$ at the point $(2, -1, 2)$

Hint: Think about the Gradient operator and then Dot Product

The angle between the surfaces at the point is the angle between the normals to the surfaces at the point.

A normal to $x^2 + y^2 + z^2 = 9$ at $(2, -1, 2)$ is

$$\nabla\phi_1 = \nabla(x^2 + y^2 + z^2) = 2x\mathbf{i} + 2y\mathbf{j} + 2z\mathbf{k} = 4\mathbf{i} - 2\mathbf{j} + 4\mathbf{k}$$

A normal to $z = x^2 + y^2 - 3$ or $x^2 + y^2 - z = 3$ at $(2, -1, 2)$ is

$$\nabla\phi_2 = \nabla(x^2 + y^2 - z) = 2x\mathbf{i} + 2y\mathbf{j} - \mathbf{k} = 4\mathbf{i} - 2\mathbf{j} - \mathbf{k}$$

$(\nabla\phi_1) \cdot (\nabla\phi_2) = |\nabla\phi_1| |\nabla\phi_2| \cos \theta$, where θ is the required angle. Then

$$\begin{aligned} (4\mathbf{i} - 2\mathbf{j} + 4\mathbf{k}) \cdot (4\mathbf{i} - 2\mathbf{j} - \mathbf{k}) &= |4\mathbf{i} - 2\mathbf{j} + 4\mathbf{k}| |4\mathbf{i} - 2\mathbf{j} - \mathbf{k}| \cos \theta \\ 16 + 4 - 4 &= \sqrt{(4)^2 + (-2)^2 + (4)^2} \sqrt{(4)^2 + (-2)^2 + (-1)^2} \cos \theta \end{aligned}$$

$$\text{and } \cos \theta = \frac{16}{6\sqrt{21}} = \frac{8\sqrt{21}}{63} = 0.5819; \text{ thus the acute angle is } \theta = \arccos 0.5819 = 54^\circ 25'.$$

Q-5) Prove that $\nabla^2 \left(\frac{1}{r} \right) = 0$

Here \mathbf{r} can be taken as $r = \sqrt{x^2 + y^2 + z^2}$

$$\nabla^2\left(\frac{1}{r}\right) = \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}\right)\left(\frac{1}{\sqrt{x^2+y^2+z^2}}\right)$$

$$\frac{\partial}{\partial x}\left(\frac{1}{\sqrt{x^2+y^2+z^2}}\right) = \frac{\partial}{\partial x}(x^2+y^2+z^2)^{-1/2} = -x(x^2+y^2+z^2)^{-3/2}$$

$$\begin{aligned}\frac{\partial^2}{\partial x^2}\left(\frac{1}{\sqrt{x^2+y^2+z^2}}\right) &= \frac{\partial}{\partial x}[-x(x^2+y^2+z^2)^{-3/2}] \\ &= 3x^2(x^2+y^2+z^2)^{-5/2} - (x^2+y^2+z^2)^{-3/2} = \frac{2x^2 - y^2 - z^2}{(x^2+y^2+z^2)^{5/2}}\end{aligned}$$

Similarly,

$$\frac{\partial^2}{\partial y^2}\left(\frac{1}{\sqrt{x^2+y^2+z^2}}\right) = \frac{2y^2 - z^2 - x^2}{(x^2+y^2+z^2)^{5/2}} \quad \text{and} \quad \frac{\partial^2}{\partial z^2}\left(\frac{1}{\sqrt{x^2+y^2+z^2}}\right) = \frac{2z^2 - x^2 - y^2}{(x^2+y^2+z^2)^{5/2}}$$

$$\text{Then by addition, } \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}\right)\left(\frac{1}{\sqrt{x^2+y^2+z^2}}\right) = 0.$$

The equation $\nabla^2\phi = 0$ is called *Laplace's equation*. It follows that $\phi = 1/r$ is a solution of this equation.