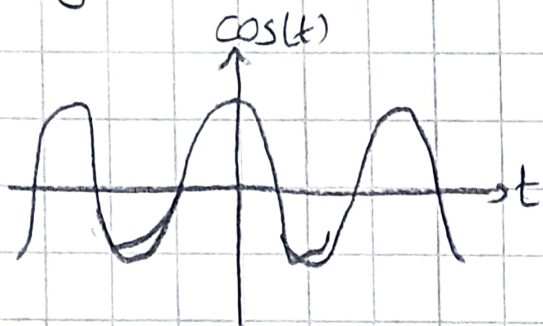


1.2.

$y(t) = \cos(x(t)) \rightarrow$ the output depends on the input at that specific time memoryless



\rightarrow the outputs are bounded by t cosine is oscillating $[-1, 1]$ stable

from the graph and the Taylor series of cos function

\Rightarrow the output does not depend on future values

$$\cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} \dots$$

causal

we can clearly see that there's no linear combination

$$ax_1(t) + bx_2(t) \rightarrow ay_1(t) + by_2(t)$$

non-linear

$$y(t) \rightarrow \cos(x(t))$$

$$y(t-t_0) \rightarrow \cos(x(t-t_0))$$

\rightarrow output does not change the same amount of time time-variant

1.b.

$$y[n] = 2x[n]u[n]$$

- the output does not depend on previous values memoryless
- we cannot bound outputs based on inputs unstable
- output does not depend on future values causal
- $y_1[n] + y_2[n] = 2u[n]x_1[n] + 2u[n]x_2[n]$ linear
- different inputs produce different $x[n]$ values. Therefore $y[n]$ is time-variant

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2.

$$x(t) = u(t+1) - u(t-1)$$

$$y(t) = u(t) + u(t-2) - 2u(t-4)$$

$$m(t) = \int_{-\infty}^{\infty} x(\tau) * y(t) d\tau = \int_{-\infty}^{\infty} y(\tau) x(t-\tau) d\tau$$

$$x(s) = \frac{e^s}{s} - \frac{e^{-s}}{s}$$

$$m(t) = \mathcal{L}^{-1} m(s)$$

$$y(s) = \frac{1}{s} + \frac{e^{-2s}}{s} - 2 \frac{e^{-4s}}{s}$$

$$m(s) = x(s) \cdot y(s) = \left(\frac{e^s - e^{-s}}{s} \right) \frac{1}{s} (1 + e^{-2s} - 2e^{-4s})$$

$$m(s) = \frac{1}{s^2} e^s - \frac{3}{s^2} e^{-3s} + \frac{2}{s^2} e^{-5s}$$

$$m(t) = (t+1)u(t+1) - 3(t-3)u(t-3) + 2(t-5)u(t-5)$$

$$m(t) = \lambda(t+1) - 3\gamma(t-3) + 2\delta(t-5)$$

3.

$$\sin \theta = \left[e^{j\theta} - e^{-j\theta} \right] \frac{1}{2j}$$

$$\cos \theta = \left[e^{j\theta} + e^{-j\theta} \right] \frac{1}{2}$$

$$x(t) = \frac{1}{2j} \left[e^{j3\pi t} - e^{-j3\pi t} \right] + \frac{1}{2} \left[e^{j\pi t} + e^{-j\pi t} \right]$$

$$a_k = \frac{-2}{2\pi} \left[\frac{1}{2k-1} - \frac{1}{2k+1} \right] = \frac{-1}{\pi} \left[\frac{2k+1 - (2k-1)}{4k^2 - 1} \right]$$

$$a_k = \frac{-2}{\pi(4k^2 - 1)}$$

$$a_0 = \frac{1}{T} \int_0^1 x(t) dt$$

$$a_0 = \frac{-\cos \pi t}{\pi} \Big|_0^1 = \frac{-[\cos \pi - \cos 0]}{\pi} = \frac{2}{\pi}$$

$$x(t) = \frac{2}{\pi} + \sum_{k=1}^{\infty} a_k e^{j\pi k t}, \quad a_k = \frac{-2}{\pi(4k^2 - 1)}$$

$$L. \quad x(t) = \sum_{n=-\infty}^{\infty} c_n e^{jn\omega_0 t}$$

$$\omega_0 = 2\pi$$

$$c_1 = j \quad c_{-1} = -j \quad c_3 = 1 \quad c_{-3} = -1$$

$$x(t) = j e^{j2\pi t} - j e^{-j2\pi t} + e^{j3 \times 2\pi t} + e^{-j3 \times 2\pi t}$$

$$x(t) = \frac{-2(e^{j2\pi t} - e^{-j2\pi t})}{2j} + \frac{2(e^{j6\pi t} + e^{-j6\pi t})}{2}$$

$$x(t) = 2 \cos 6\pi t - 2 \sin 2\pi t$$

5.

$$x(t) = \begin{cases} 1 & : |t| < 2 \\ 0 & : |t| > 2 \end{cases}$$

$$x(t) = 1 \quad -\infty \leq t < 2$$

$$x(t) = 0 \quad 2 \leq t \leq \infty$$

$$x(\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt$$

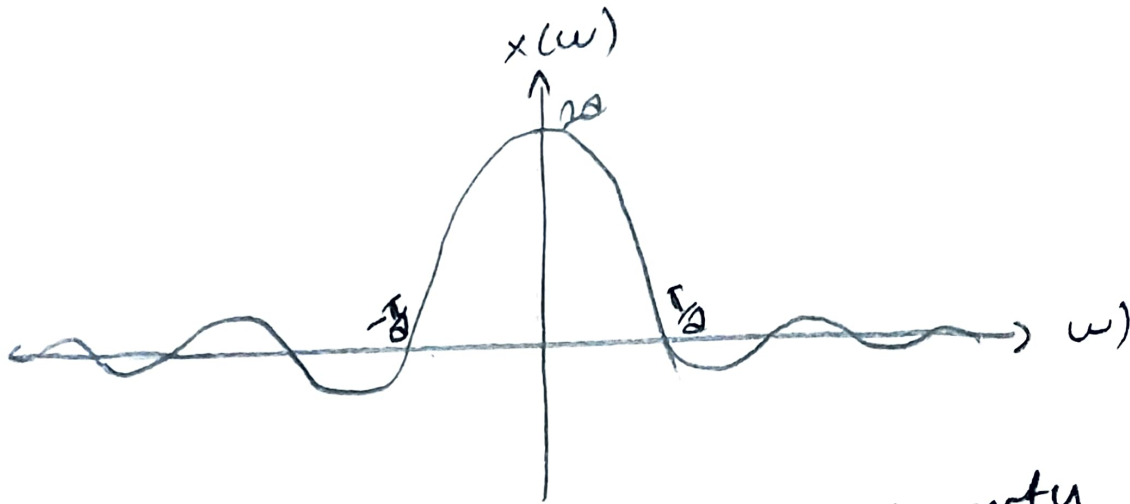
$x(t)$ between
-2 and +2

$$x(\omega) = \int_{-2}^{2} e^{-j\omega t} dt = \left[\frac{e^{-j\omega t}}{-j\omega} \right]_{-2}^{2}$$

$$= \left[\frac{e^{j2\omega}}{-j\omega} - \frac{e^{-j2\omega}}{-j\omega} \right]$$

$2\omega \neq x$ let's say

$$= \frac{2 \sin(2\omega)}{\omega} = 2 \sin\left(\frac{\sin(2\omega)}{2\omega}\right) \quad \text{sinc}(x) \quad \hookrightarrow x = 2\omega$$



shifting property

$$\text{FT of } x(t - t_0) = e^{-j\omega t_0} x(\omega)$$

$t_0 = a$



$$\text{FT of } x(t-a) = e^{-j\omega a} 2a \frac{\sin a\omega}{a\omega}$$

6.

$$x(\omega) = e^{-2|\omega|} = \begin{cases} e^{-2\omega} & \omega \geq 0 \\ e^{2\omega} & \omega < 0 \end{cases}$$

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} x(\omega) e^{j\omega t} d\omega$$

$$= \frac{1}{2\pi} \left[\int_{-\infty}^0 e^{2\omega} \cdot e^{j\omega t} d\omega + \int_0^{\infty} e^{-2\omega} e^{j\omega t} d\omega \right]$$

$$= \frac{1}{2\pi} \left[\frac{e^{(2+jt)\omega}}{2+jt} \Big|_{-\infty}^0 + \frac{e^{-(2-jt)\omega}}{-(2-jt)} \Big|_0^{\infty} \right]$$

$$= \frac{1}{2\pi} \left[\frac{e^0 - e^{-\infty}}{2+jt} + \frac{e^{-\infty} - e^0}{-(2-jt)} \right]$$

$$= \frac{1}{2\pi} \left[\frac{1}{2+jt} + \frac{1}{2-jt} \right] = \frac{1}{2\pi} \left[\frac{4}{4+t^2} \right]$$

$$x(t) = \frac{2}{\pi(4+t^2)}$$