


**EEEN451**  
**POWER TRANSMISSION SYSTEMS**



**CHAPTER 1: BASIC CONCEPTS**

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**Review of Phasors**

Goal of phasor analysis is to simplify the analysis of constant frequency ac systems

$$v(t) = V_{\max} \cos(\omega t + \theta_v) \quad \longrightarrow \quad \text{Instantaneous voltage}$$

$$i(t) = I_{\max} \cos(\omega t + \theta_i) \quad \longrightarrow \quad \text{Instantaneous Current}$$

Root Mean Square (RMS) voltage of sinusoid

$$\sqrt{\frac{1}{T} \int_0^T v(t)^2 dt} = \frac{V_{\max}}{\sqrt{2}}$$

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**Phasor Representation**

Euler's Identity:  $e^{j\theta} = \cos \theta + j \sin \theta$

Phasor notation is developed by rewriting using Euler's identity

$$v(t) = \sqrt{2} |V| \cos(\omega t + \theta_V)$$

$$v(t) = \sqrt{2} |V| \operatorname{Re} \left[ e^{j(\omega t + \theta_V)} \right]$$

(Note:  $|V|$  is the RMS voltage)

The RMS, cosine-referenced voltage phasor is:

$$V = |V| e^{j\theta_V} = |V| \angle \theta_V$$

$$v(t) = \operatorname{Re} \sqrt{2} V e^{j\omega t} e^{j\theta_V}$$

$$V = |V| \cos \theta_V + j |V| \sin \theta_V$$

$$I = |I| \cos \theta_I + j |I| \sin \theta_I$$

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### Advantages of Phasor Analysis

Device	Time Analysis	Phasor
Resistor	$v(t) = R i(t)$	$V = R I$
Inductor	$v(t) = L \frac{di(t)}{dt}$	$V = j\omega L I$
Capacitor	$\frac{1}{C} \int_0^t i(t) dt + v(0)$	$V = \frac{1}{j\omega C} I$
$Z = \text{Impedance} = R + jX =  Z  \angle \phi$		
$R = \text{Resistance}$		
$X = \text{Reactance}$		
$ Z  = \sqrt{R^2 + X^2} \quad \phi = \arctan\left(\frac{X}{R}\right)$		

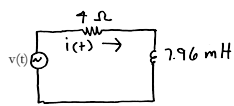
(Note:  $Z$  is a complex number but not a phasor)

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### RL Circuit Example



$$\begin{aligned}
 V(t) &= \sqrt{2} 100 \cos(\omega t + 30^\circ) \\
 f &= 60 \text{ Hz} \\
 R &= 4 \Omega \quad X = \omega L = 3 \\
 |Z| &= \sqrt{4^2 + 3^2} = 5 \quad \phi = 36.9^\circ \\
 I &= \frac{V}{Z} = \frac{100 \angle 30^\circ}{5 \angle 36.9^\circ} \\
 &= 20 \angle -6.9^\circ \text{ Amps} \\
 i(t) &= 20\sqrt{2} \cos(\omega t - 6.9^\circ)
 \end{aligned}$$

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### Power in Single Phase Circuits

**Power** (Instantaneous Power)

$$p(t) = v(t) i(t)$$

$$v(t) = V_{\max} \cos(\omega t + \theta_V)$$

$$i(t) = I_{\max} \cos(\omega t + \theta_I)$$

$$\cos \alpha \cos \beta = \frac{1}{2} [\cos(\alpha - \beta) + \cos(\alpha + \beta)]$$

$$p(t) = \frac{1}{2} V_{\max} I_{\max} [\cos(\theta_V - \theta_I) + \cos(2\omega t + \theta_V + \theta_I)]$$

Using max values

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### Instantaneous Power Using rms Values

$$p(t) = \underbrace{VI \cos \theta (1 + \cos 2\omega t)}_{\text{Instantaneous real/active power}} + \underbrace{VI \sin \theta \cos 2\omega t}_{\text{Instantaneous reactive power}}$$

Aktif/real/average power      Reactive Power

$$P_{av} = \frac{1}{T} \int p(t) dt = VI \cos \theta \text{ W, kW, MW, GW}$$

Reactive power =  $VI \sin \theta$ , VAR, kVAR, MVAR

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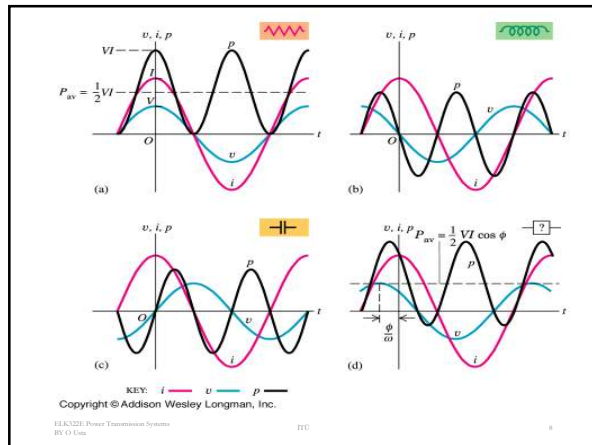
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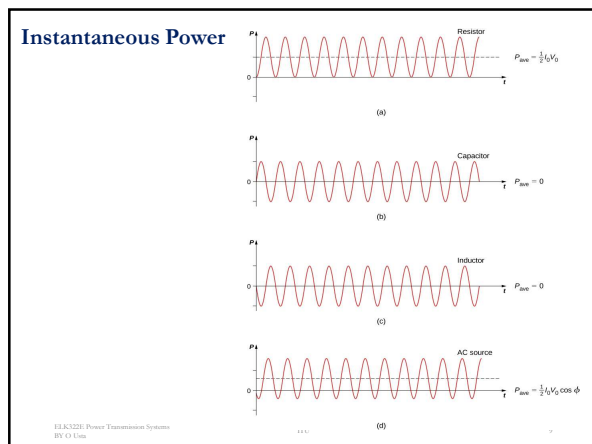
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### Complex Power

$$S = |V||I|[\cos(\theta_V - \theta_I) + j\sin(\theta_V - \theta_I)]$$

$$= P + jQ$$

$$= V I^*$$

P = Real Power (W, kW, MW)

Q = Reactive Power (var, kvar, Mvar)

S = Complex power (VA, kVA, MVA)

Power Factor (pf) =  $\cos\phi$

If current leads voltage then pf is leading

If current lags voltage then pf is lagging

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Relationships between real, reactive and complex power

$$P = |S|\cos\phi$$

$$Q = |S|\sin\phi = \pm|S|\sqrt{1-pf^2}$$

Example: A load draws 100 kW with a leading pf of 0.85. What are  $\phi$  (power factor angle), Q and  $|S|$ ?

$$\phi = -\cos^{-1}0.85 = -31.8^\circ$$

$$|S| = \frac{100kW}{0.85} = 117.6 \text{ kVA}$$

$$Q = 117.6\sin(-31.8^\circ) = -62.0 \text{ kVar}$$

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### Conservation of Power

● At every node (bus) in the power systems

- Sum of real power into node must equal zero
- Sum of reactive power into node must equal zero

● This is a direct consequence of Kirchhoff's current law, which states that the total current into each node must equal zero.

- Conservation of power follows since  $S = VI^*$

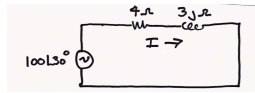
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### Conversation of Power Example



Earlier we found  
 $I = 20\angle-6.9^\circ$  amps

$$S = VI^* = 100\angle30^\circ \times 20\angle6.9^\circ = 2000\angle36.9^\circ \text{ VA}$$

$$\phi = 36.9^\circ \quad \text{pf} = 0.8 \text{ lagging}$$

$$S_R = V_R I^* = 4 \times 20\angle-6.9^\circ \times 20\angle6.9^\circ$$

$$P_R = 1600W = |I|^2 R \quad (Q_R = 0)$$

$$S_L = V_L I^* = 3j \times 20\angle-6.9^\circ \times 20\angle6.9^\circ$$

$$Q_L = 1200 \text{ var} = |I|^2 X \quad (P_L = 0)$$

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### Power Consumption in Devices

Resistors only consume real power

$$P_{\text{Resistor}} = |I_{\text{Resistor}}|^2 R$$

Inductors only consume reactive power

$$Q_{\text{Inductor}} = |I_{\text{Inductor}}|^2 X_L$$

Capacitors only generate reactive power

$$Q_{\text{Capacitor}} = -|I_{\text{Capacitor}}|^2 X_C \quad X_C = \frac{1}{\omega C}$$

$$Q_{\text{Capacitor}} = -\frac{|V_{\text{Capacitor}}|^2}{X_C} \quad (\text{Note-some define } X_C \text{ negative})$$

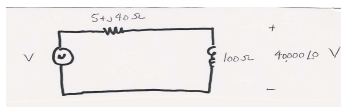
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### Example

First solve basic circuit



$$I = \frac{40000\angle0^\circ V}{100\angle0^\circ \Omega} = 400\angle0^\circ \text{ Amps}$$

$$V = 40000\angle0^\circ + (5 + j40) 400\angle0^\circ$$

$$= 42000 + j16000 = 44.9\angle20.8^\circ \text{ kV}$$

$$S = VI^* = 44.9\text{k}\angle20.8^\circ \times 400\angle0^\circ$$

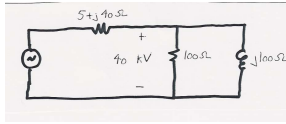
$$= 17.98\angle20.8^\circ \text{ MVA} = 16.8 + j6.4 \text{ MVA}$$

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Example, cont'd



Now add additional reactive power load and resolve

$$Z_{Load} = 70.7 \angle 45^\circ \quad pf = 0.7 \text{ lagging}$$

$$I = 564 \angle -45^\circ \text{ Amps}$$

$$V = 59.7 \angle 13.6^\circ \text{ kV}$$

$$S = 33.7 \angle 58.6^\circ \text{ MVA} = 17.6 + j28.8 \text{ MVA}$$

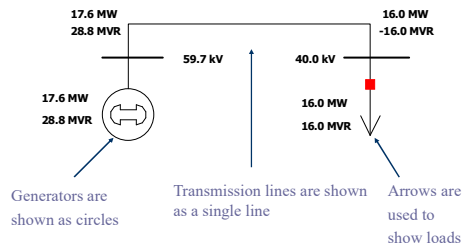
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## Power System Notation

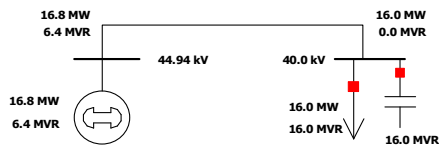
Power system components are usually shown as “one-line diagrams.” Previous circuit redrawn



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## Reactive Compensation

Key idea of reactive compensation is to supply reactive power locally. In the previous example this can be done by adding a 16 MVAR capacitor at the load



Compensated circuit is identical to first example with just real power load

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- Reactive compensation decreased the line flow from 564 Amps to 400 Amps.

This has advantages

- Lines losses, which are equal to  $I^2 R$  decrease
- Lower current allows utility to use small wires, or alternatively, supply more load over the same wires
- Voltage drop on the line is less
- Reactive compensation is used extensively by utilities
- Capacitors can be used to “correct” a load’s power factor to an arbitrary value.

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### Power Factor Correction Example

Assume we have 100 kVA load with  $\text{pf}=0.8$  lagging, and would like to correct the pf to 0.95 lagging

$$S = 80 + j60 \text{ kVA} \quad \phi = \cos^{-1} 0.8 = 36.9^\circ$$

$$\text{PF of } 0.95 \text{ requires } \phi_{\text{desired}} = \cos^{-1} 0.95 = 18.2^\circ$$

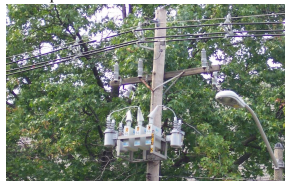
$$S_{\text{new}} = 80 + j(60 - Q_{\text{cap}})$$

$$\frac{60 - Q_{\text{cap}}}{80} = \tan 18.2^\circ \Rightarrow 60 - Q_{\text{cap}} = 26.3 \text{ kvar}$$

$$Q_{\text{cap}} = 33.7 \text{ kvar}$$

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### Balanced 3 Phase ( $\phi$ ) Systems

- A balanced 3 phase ( $\phi$ ) system has
  - three voltage sources with equal magnitude, but with an angle shift of  $120^\circ$
  - equal loads on each phase
  - equal impedance on the lines connecting the generators to the loads
- Bulk power systems are almost exclusively 3 $\phi$
- Single phase is used primarily only in low voltage, low power settings, such as residential and some commercial

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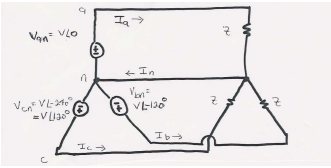
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**Balanced 3 $\phi$  -- No Neutral Current**

$$I_n = I_a + I_b + I_c$$

$$I_n = \frac{V}{Z} (1\angle 0^\circ + 1\angle -120^\circ + 1\angle 120^\circ) = 0$$

$$S = V_{an} I_{an}^* + V_{bn} I_{bn}^* + V_{cn} I_{cn}^* = 3 V_{an} I_{an}^*$$

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**Advantages of 3 $\phi$  Power**

- Can transmit more power for same amount of wire (twice as much as single phase)
- Torque produced by 3 $\phi$  machines is constant
- Three phase machines use less material for same power rating
- Three phase machines start more easily than single phase machines

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**Three Phase - Wye Connection**

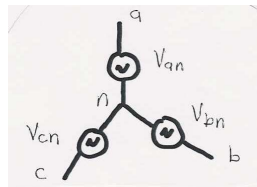
- There are two ways to connect 3 $\phi$  systems
  - Wye (Y)
  - Delta ( $\Delta$ )

Wye Connection Voltages

$$V_{an} = |V| \angle \alpha^\circ$$

$$V_{bn} = |V| \angle \alpha^\circ - 120^\circ$$

$$V_{cn} = |V| \angle \alpha^\circ + 120^\circ$$



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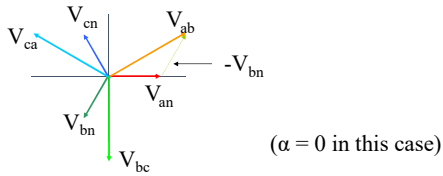
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### Wye Connection Line Voltages



$$\begin{aligned} V_{ab} &= V_{an} - V_{bn} = |V|(1\angle\alpha - 1\angle\alpha + 120^\circ) \\ &= \sqrt{3} |V| \angle\alpha + 30^\circ \\ V_{bc} &= \sqrt{3} |V| \angle\alpha - 90^\circ \\ V_{ca} &= \sqrt{3} |V| \angle\alpha + 150^\circ \end{aligned}$$

Line to line voltages are also balanced

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### Wye Connection, cont'd

- Define voltage/current across/through device to be phase voltage/current
- Define voltage/current across/through lines to be line voltage/current

$$\begin{aligned} V_{Line} &= \sqrt{3} V_{Phase} \angle 30^\circ = \sqrt{3} V_{Phase} e^{j\pi/6} \\ I_{Line} &= I_{Phase} \\ S_{3\phi} &= 3 V_{Phase} I_{Phase}^* \end{aligned}$$

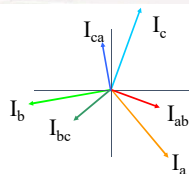
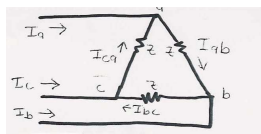
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### Delta Connection



For the Delta  
phase voltages equal  
line voltages

For currents

$$\begin{aligned} I_a &= I_{ab} - I_{ca} \\ &= \sqrt{3} I_{ab} \angle -30^\circ \\ I_b &= I_{bc} - I_{ab} \\ I_c &= I_{ca} - I_{bc} \\ S_{3\phi} &= 3 V_{Phase} I_{Phase}^* \end{aligned}$$

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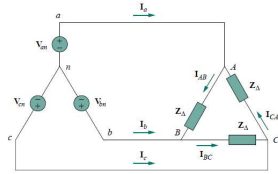
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### Three Phase Example

Assume a  $\Delta$ -connected load is supplied from a 3 $\phi$  13.8 kV (L-L) source with  $Z = 100\angle 20^\circ \Omega$



$$\begin{aligned} V_{ab} &= 13.8\angle 0^\circ \text{ kV} \\ V_{bc} &= 13.8\angle -120^\circ \text{ kV} \\ V_{ca} &= 13.8\angle 120^\circ \text{ kV} \end{aligned}$$

$$I_{ab} = \frac{13.8\angle 0^\circ \text{ kV}}{100\angle 20^\circ \Omega} = 138\angle -20^\circ \text{ amps}$$

$$I_{bc} = 138\angle -140^\circ \text{ amps} \quad I_{ca} = 138\angle 100^\circ \text{ amps}$$

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### Three Phase Example, cont'd

$$\begin{aligned} I_a &= I_{ab} - I_{ca} = 138\angle -20^\circ - 138\angle 100^\circ \\ &= 239\angle -50^\circ \text{ amps} \end{aligned}$$

$$I_b = 239\angle -170^\circ \text{ amps} \quad I_c = 239\angle 70^\circ \text{ amps}$$

$$\begin{aligned} S &= 3 \times V_{ab} I_{ab}^* = 3 \times 13.8\angle 0^\circ \text{ kV} \times 138\angle 20^\circ \text{ amps} \\ &= 5.7\angle 20^\circ \text{ MVA} \\ &= 5.37 + j1.95 \text{ MVA} \end{aligned}$$

$$\text{pf} = \cos 20^\circ = 0.94 \text{ lagging}$$

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### Delta-Wye Transformation

To simplify analysis of balanced 3 $\phi$  systems:

1)  $\Delta$ -connected loads can be replaced by

$$\text{Y-connected loads with } Z_Y = \frac{1}{3} Z_\Delta$$

2)  $\Delta$ -connected sources can be replaced by

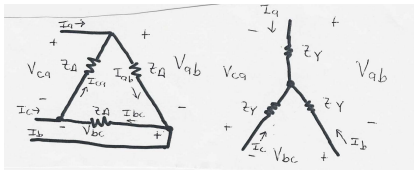
$$\text{Y-connected sources with } V_{\text{phase}} = \frac{V_{\text{Line}}}{\sqrt{3}\angle 30^\circ}$$

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## Delta-Wye Transformation Proof



From the  $\Delta$  side we get

$$I_a = \frac{V_{ab}}{Z_{\Delta}} - \frac{V_{ca}}{Z_{\Delta}} = \frac{V_{ab} - V_{ca}}{Z_{\Delta}}$$

Hence  $Z_{\Delta} = \frac{V_{ab} - V_{ca}}{I_a}$

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## Delta-Wye Transformation, cont'd

From the  $Y$  side we get

$$V_{ab} = Z_Y(I_a - I_b) \quad V_{ca} = Z_Y(I_c - I_a)$$

$$V_{ab} - V_{ca} = Z_Y(2I_a - I_b - I_c)$$

Since  $I_a + I_b + I_c = 0 \Rightarrow I_a = -I_b - I_c$

Hence  $V_{ab} - V_{ca} = 3Z_Y I_a$

$$3Z_Y = \frac{V_{ab} - V_{ca}}{I_a} = Z_{\Delta}$$

Therefore  $Z_Y = \frac{1}{3}Z_{\Delta}$

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## APPLICATIONS

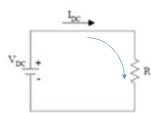
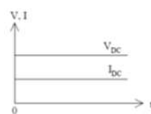


Fig. 1-2: A simple DC circuit.



Voltage and current waveforms of the simple DC circuit.

Example 1-1: A DC circuit, as shown in Figure 1-2, has a DC voltage of 12 volts and a resistor of  $2 \Omega$ . What are the DC current in the circuit and the power consumed by the resistor?

$$I_{DC} = \frac{12}{2} = 6 \text{ (A)}$$

$$P_{DC} = 12 \times 6 = 72 \text{ (W)}$$

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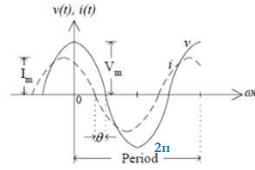
Since in power systems the sinusoidal voltages are generated, and consequently, most likely sinusoidal currents are flowed in the generation, transmission and distribution systems, sinusoidal quantities are assumed throughout this material, unless otherwise specified.

In general, a set of typical steady-state voltage and current waveforms of an AC circuit can be drawn as shown in following Figure, and their mathematical expressions can be written as follows:

$$v(t) = V_m \cos(\omega t),$$

and

$$i(t) = I_m \cos(\omega t + \theta),$$



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There is an important quantity called "root mean square" value, or rms, and is defined as

$$V_{\text{rms}} = \sqrt{\frac{1}{T} \int_0^T v^2(t) dt}.$$

For a sinusoidal voltage, its rms value equals

$$V_{\text{rms}} = \sqrt{\frac{1}{T} \int_0^T [V_m \cos(\omega t)]^2 dt} = \sqrt{\frac{V_m^2}{\omega T} \int_0^T \frac{1 + \cos 2\omega t}{2} d(\omega t)} = \sqrt{\frac{V_m^2}{2\pi} \left[ \frac{\omega t}{2} + \frac{\sin 2\omega t}{4} \right]_0^{2\pi}} = \frac{V_m}{\sqrt{2}}.$$

**Example 1-2: What are the phasor representations of the following instantaneous quantities?**

$$v(t) = 170 \cos(\omega t) \text{ volts, and } i(t) = 85 \cos(\omega t + 30^\circ)$$

**Solution:**

$$\bar{V} = \frac{170}{\sqrt{2}} \angle 0^\circ = 120 \angle 0^\circ \text{ volts}$$

$$\bar{Z} = \frac{\bar{V}}{\bar{I}} = R + j(\omega L + \frac{1}{\omega C}) = R + j(X_L - X_C) = R + jX = Z \angle \theta \quad \Omega.$$

$$\bar{I} = \frac{85}{\sqrt{2}} \angle 30^\circ = 60.1 \angle 30^\circ \text{ amps}$$

where

$$Z = \sqrt{R^2 + X^2},$$

and

$$\theta = \tan^{-1}\left(\frac{X}{R}\right).$$

Unlike in DC circuits, the loads in AC circuits can be expressed as its impedance, consisting of resistance R and reactance X, as follows

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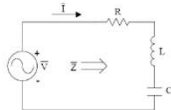
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**Example 1-3:** A 60 Hz 120 volts AC voltage source is connected to a 10Ω resistor, a 31.83 mH inductor and 1326.26μF capacitor, as shown in Figure.

Find

- (1) The total impedance Z.
- (2) The current I in polar form.
- (3) The voltage and current in instantaneous forms.



**Solution:**

- (1) Since the frequency is 60 Hz, the inductive and capacitive reactances can be obtained as

$$X_L = \omega L = 377 \times 31.83 \times 10^{-3} = 12 \Omega$$

$$X_C = \frac{1}{\omega C} = \frac{1}{377 \times 1326.26 \times 10^{-6}} = 2 \Omega$$

The total impedance seen by the voltage source

$$\bar{Z} = R + j(X_L - X_C) = 10 + j(12 - 2) = 10 + j10 = \sqrt{10^2 + 10^2} \angle \tan^{-1}\left(\frac{10}{10}\right) = 10\sqrt{2} \angle 45^\circ \Omega$$

- (2) To calculate the current, the angle of the voltage is set to be the reference, namely,  $0^\circ$ . Then,

$$\bar{I} = \frac{\bar{V}}{\bar{Z}} = \frac{120 \angle 0^\circ}{10\sqrt{2} \angle 45^\circ} = 8.485 \angle -45^\circ \text{ amps}$$

- (3) To convert the phasors to the instantaneous forms

$$v(t) = 120\sqrt{2} \cos(377t) = 170 \cos(377t) \text{ volts}$$

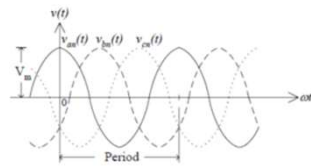
$$i(t) = 8.485\sqrt{2} \cos(377t - 45^\circ) = 12 \cos(377t - 45^\circ) \text{ amps}$$

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In general, the phase voltages of a balanced three-phase voltage source with “positive” sequence can be expressed as



Their phasor representations are obtained as discussed for single-phase systems

$$\begin{aligned}\bar{V}_m &= V \angle 0^\circ, \\ \bar{V}_{bn} &= \bar{V}_m \angle -120^\circ = V \angle -120^\circ, \\ \bar{V}_{cn} &= \bar{V}_m \angle 120^\circ = V \angle 120^\circ.\end{aligned}$$

Waveforms of phase voltages of balanced three-phase systems.

$$v_m(t) = \sqrt{2}V \cos(\omega t).$$

$$v_{bn}(t) = v_m(t - \frac{T}{3}) = \sqrt{2}V \cos(\omega t - 120^\circ),$$

$$v_{cn}(t) = v_m(t - \frac{2T}{3}) = \sqrt{2}V \cos(\omega t - 240^\circ) = \sqrt{2}V \cos(\omega t + 120^\circ).$$

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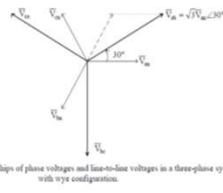
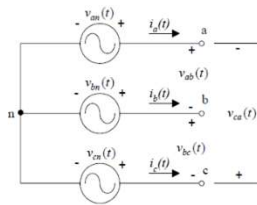
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### Phasor values of Line voltages (phase to phase)

$$\bar{V}_{ab} = \bar{V}_m - \bar{V}_{bn} = V \angle 0^\circ - V \angle -120^\circ = V[1 - (-0.5 - j0.866)] = \sqrt{3}V \angle 30^\circ = \sqrt{3}\bar{V}_m \angle 30^\circ.$$

$$\bar{V}_{bc} = \sqrt{3}V \angle -90^\circ = \sqrt{3}\bar{V}_{bn} \angle 30^\circ,$$

$$\bar{V}_{ca} = \sqrt{3}V \angle 150^\circ = \sqrt{3}\bar{V}_{cn} \angle 30^\circ.$$



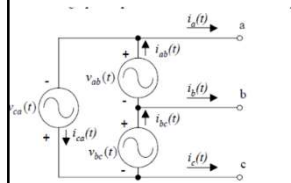
The relationships of phase voltages and line-to-line voltages in a three-phase system with wye configuration.

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The other configuration of the three-phase voltage source is to connect them in a delta configuration, as shown in Figure



Three-phase voltage source with delta configuration.

$$\bar{I}_a = \bar{I}_{ab} - \bar{I}_{ca} = I \angle 0^\circ - I \angle 120^\circ = I[1 - (-0.5 + j0.866)] = \sqrt{3}I \angle -30^\circ = \sqrt{3}\bar{I}_{ab} \angle -30^\circ.$$

Similarly, at nodes b and c, the other two line currents can be obtained as follows

$$\bar{I}_b = \sqrt{3}I \angle -150^\circ = \sqrt{3}\bar{I}_{bc} \angle -30^\circ,$$

$$\bar{I}_c = \sqrt{3}I \angle 90^\circ = \sqrt{3}\bar{I}_{ca} \angle -30^\circ.$$

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Example 1-4: A balanced three-phase load of 50 kVA,  $\text{pf} = 0.85$  lagging is supplied from a balanced three-phase wye connected voltage source of positive sequence such that  $V_L = 4157$  volts. Calculate:

Phase voltage, Line & Phase currents, and 3 phase powers

Solution:

$$(1) V_\phi = \frac{V_L}{\sqrt{3}} = \frac{4157}{\sqrt{3}} = 2400 \text{ volts} \quad I_\phi = I_L = \frac{S_{3\phi}}{\sqrt{3}V_L} = \frac{50 \times 10^3}{\sqrt{3} \times 4157} = 6.94 \text{ amps}$$

$$(2) \bar{S}_{3\phi} = 50 \angle \cos^{-1}(0.85) = 50 \angle 31.8^\circ \text{ kVA}$$

$$S_{3\phi} = 50 \text{ kVA}$$

$$P_{3\phi} = 50 \times 0.85 = 42.5 \text{ kW}$$

$$Q_{3\phi} = 50 \sin[\cos^{-1}(0.85)] = 50 \sin 31.8^\circ = 26.34 \text{ kvar}$$

#### DIRECTION OF POWER FLOW

The relation among  $I$ ,  $Q$ , and bus voltage, or generated voltage  $E_f$ , with respect to the sign of  $P$  and  $Q$  is important when the flow of power in a system is considered. The question involves the direction of flow of power, that is, whether power is being generated or absorbed when a voltage and a current are specified.

Example 1.5. Two ideal voltage sources designated as machines 1 and 2 are connected, as shown below. If  $E_1 = 100 \angle 0^\circ \text{ V}$ ,  $E_2 = 100 \angle 30^\circ \text{ V}$ , and  $Z = (0 + j5) \text{ ohm}$ .

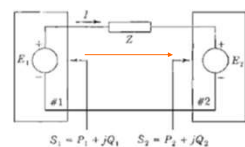
Determine

- whether each machine is generating or consuming real power and the amount,
- whether each machine is receiving or supplying reactive power and the amount,
- the  $P$  and  $Q$  absorbed by the impedance.

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Assume that Machine 1 is a generator and Machine 2 is a motor.  
If the result is +, assumption is correct  
If the result is -, assumption is incorrect

Solution

$$I = \frac{E_1 - E_2}{Z} = \frac{100 + j0 - (86.6 + j50)}{j5} = \frac{13.4 - j50}{j5} = -10 - j2.68 = 10.35 \angle 195^\circ \text{ A}$$

$$S_1 = E_1 I^* = 100 (-10 + j2.68) = (-1000 + j268) \text{ VA}$$

Machine 1 is motor and consuming active power, producing reactive power

$$S_2 = E_2 I^* = (86.6 + j50) (-10 + j2.68) = (-1000 - j268) \text{ VA}$$

Machine 2 is generator and generating active and reactive power

The reactive power absorbed by the line ( $r=0$ , and  $X=5 \text{ ohm}$ )

$$X I^2 = 5 \times 10.35^2 = 536 \approx 268 + 268$$

Produced

Absorbed

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Example 1.6: The terminal voltage of a Y-connected load consisting of 3 equal impedances of  $20 \angle 30^\circ \Omega$  is 4.4 kV. The impedance in each of the 3 lines connecting the load to a bus bar at a sub-station is  $1.4 \angle 75^\circ \Omega$ . Find out the line-to-line voltage at the substation.

**Solution: Using single phase equivalent circuit:**

**Solution.** The magnitude of the voltage to neutral at the load is  $4400/\sqrt{3} = 2540$  V. If  $V_{an}$ , the voltage across the load, is chosen as reference,

$$V_{an} = 2540 \angle 0^\circ \text{ V} \quad \text{and} \quad I_{an} = \frac{2540 \angle 0^\circ}{20 \angle 30^\circ} = 127.0 \angle -30^\circ \text{ A}$$

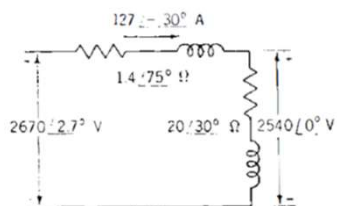
The line-to-neutral voltage at the substation is

$$\begin{aligned} V_{sn} + I_{an} Z_l &= 2540 \angle 0^\circ + 127 \angle -30^\circ \times 1.4 \angle 75^\circ \\ &= 2540 \angle 0^\circ + 177.8 \angle 45^\circ \\ &= 2666 + j125.7 = 2670 \angle 2.70^\circ \text{ V} \end{aligned}$$

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and the magnitude of the voltage at the substation bus is

$$\sqrt{3} \times 2.67 = 4.62 \text{ kV}$$

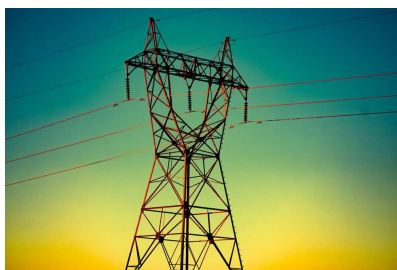


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THANKS



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