

S-3 Toolbox/SMOS-BOX

Maintenance and Evolution

NetCDF Format Conversion User Guide

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Changelog

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Contents

| 1 | Introduction | 4 |
|---|--|----|
| | 1.1 Document purpose and scope | 4 |
| | 1.2 Acronyms and abbreviations | 4 |
| | 1.3 References | 4 |
| | 1.3.1 Applicable Documents | 4 |
| | 1.3.2 Reference documents | 5 |
| 2 | Motivation | 6 |
| 3 | Output file format | 6 |
| | 3.1 Data Format | 6 |
| | 3.2 Metadata | 6 |
| | 3.3 Dimensions | 6 |
| | 3.4 Invalid-pixel values | 7 |
| | 3.5 Flag coding | 7 |
| | 3.6 Data types | 7 |
| | 3.7 Variable scaling | 8 |
| | 3.8 Variable name conversion | 8 |
| 4 | Supported SMOS product types | 8 |
| 5 | Functionality | 9 |
| | 5.1 Geographic sub-setting | 9 |
| | 5.2 Variable sub-setting | 9 |
| | 5.3 Compression | 11 |
| 6 | Installations | 12 |
| | 6.1 S-3 Toolbox Graph Processing Tool operator | 12 |
| | 6.1.1 Examples | 13 |
| | 6.2 Stand-alone program | 14 |
| | 6.2.1 Examples | 15 |
| 7 | NetCDF file structure | 16 |
| | 7.1 MIR BWLF1C | 16 |
| | 7.2 MIR BWSF1C | 17 |
| | 7.3 MIR OSUDP2 | 18 |
| | 7.4 MIR SCLF1C | 21 |
| | 7.5 MIR SCSF1C | |
| | 7.6 MIR SMUDP2 | 26 |



1 Introduction

1.1 Document purpose and scope

This User Guide covers all relevant information concerning the smos-ee-to-nc conversion tool. Subsections of the document explain the output file format, the supported SMOS product types, and the various possibilities to use the conversion tool. A concise description of the different interfaces and the parameters available is given.

1.2 Acronyms and abbreviations

| BC | Brockmann Consult GmbH |
|-------|-----------------------------------|
| ВТ | Brightness Temperature |
| CDL | Network Common Data form Language |
| DDDB | Data file Descriptor Data Base |
| EEF | Earth Explorer File |
| ЕО | Earth Observation |
| ESA | European Space Agency |
| ESRIN | European Space Research Institute |
| GPF | SNAP Graph Processing Framework |
| GPT | SNAP Graph Processing Tool |
| OGC | Open Geospatial Consortium |
| PDGS | Payload Data Ground Segment |
| ROI | Region Of Interest |
| RS | Remote Sensing |
| S-3 | Sentinel 3 |
| SMOS | Soil Moisture and Ocean Salinity |
| WKT | Well Known Text |

1.3 References

1.3.1 Applicable Documents

| [AD.1] | SMOS Level 1 and Auxiliary Data Products Specifications, issue 6.2, 31.08.2016 | SO-TN-IDR-GS-0005 |
|--------|--|------------------------|
| [AD.2] | SMOS Level 2 and Auxiliary Data Products Specifications, issue 8.4, 30.08.2016 | SO-TN-IDR-GS-0006 |
| [AD.3] | BEAM + SMOS-Box Review, issue 1.1 | IDEAS-SER-TOO-REP-1201 |
| [AD.4] | SMOS NRT Product Format Specification, issue 3.8 | SO-ID-DMS-GS-0002 |



| [AD.5] | BEAM/SMOS-Box Maintenance and Evolution Requirements Baseline (RB) | |
|--------|--|-------------------|
| [AD.6] | SMOS Toolbox upgrade for new L1C and L2OS data format | IDEAS-SMOS-CP-026 |

1.3.2 Reference documents

| [RD.1] | NetCDF Java Library Documentation (version 4.3) | http://www.unidata.ucar.edu/software/ thredds/current/netcdfjava/documentation.htm |
|--------|---|---|
| [RD.2] | Unidata NetCDF best practices | http://www.unidata.ucar.edu/software/ netcdf/docs/BestPractices.html |
| [RD.3] | NetCDF CF conventions (version 1.1) | http://cfconventions.org/ |
| [RD.4] | Well Known Text format description | http://en.wikipedia.org/wiki/Wellknown_text |
| [RD.5] | SNAP GPT documentation | http://www.brockmannconsult.de/beam-wiki/display/BEAM/Bulk+Processing+with+GPT |



2 Motivation

This SMOS Earth Explorer to NetCDF converter software shall enable a broader range of tools to make use of the SMOS data. Therefore, the widely supported NetCDF 4 file format has been chosen as target format.

The Earth Explorer format as being distributed by ESA is well suited for the SMOS data and for certain architectures of processing, especially cell-by-cell Level 3 operations. Nevertheless, in other situations it is more convenient to access the measurement variables directly than to be forced to iterate over a sequence of structures. The converter tool performs this re-mapping of the data by flattening the structures and mapping variables to data arrays ordered by grid-point or by snapshot.

3 Output file format

The converter output file format is NetCDF 4 with the option of writing the data in different compression levels.

3.1 Data Format

The data structure as present in the original Earth Explorer binary data files is not suited to be directly transformed to NetCDF. The essential structure in the SMOS EEF product format is the grid point, which contains all measurements that were acquired for that grid point by different snapshots. This original data structure can roughly be described as a "list of structures that contains lists of structures". Although, the format is perfectly suitable to represent the SMOS data, it needs to be modified to match the requirements of users.

Therefore, the NetCDF file contains a serialised version of the structured data. Each grid point or snapshot data variable is transformed into a NetCDF variable with an appropriate dimension. In the case of e.g. L1C Brightness Temperature (BT) measurements, the structure member is translated into a two-dimensional array, one dimension of this array is the number of grid-point measurements in the EE file, the other is the maximal number of snapshot measurements in all grid points of the product.

All size reference variables translate into NetCDF dimensions; all structures are flattened. Array data with a variable dimension (like e.g. Brightness Temperature data for grid points) translates into NetCDF arrays with a fixed dimension (either set to the maximum value allowed by the data type or to the maximum value occurring in a file).

Variable attributes in NetCDF files like scaling, units, fill values, valid ranges, flag masks, and flag meanings are defined according to the product specifications.

3.2 Metadata

All metadata contained in the Earth Explorer file is transferred to the NetCDF file. In contrast to the XML-based metadata in the original file, NetCDF does not allow for structured global metadata elements. Therefore, the inherent structure is mapped to the metadata attribute names. Any metadata attribute originally contained in a structure will be converted to a NetCDF attribute whose name is preceded by the structure name, separated by a colon (":"), nested structures are treated recursively, according to this rule.

Example:

The "Validity_Start" metadata-element contained in the "Validity_Period" structure nested within the "Fixed_Header" structure is stored in the NetCDF file as a global attribute, which is denoted "Fixed_Header:Validity_Period:Validity_Start".

3.3 Dimensions

A NetCDF file requires all dimensions being used for variables to be stored as global meta-information. The dimension names chosen for the output file reflect the entities stored from the Earth Explorer file and are self-explaining.

Table 1: Dimensions of NetCDF file

| Dimension Name | Description |
|------------------------|--|
| n_grid_points | Number of grid points stored. First dimension for all grid-point structure data members |
| n_bt_data | Number of brightness temperature measurements per grid point. Second dimension for all grid-point structure data members |
| n_snapshots | Number of snapshots. Dimension used for all snapshot related variables |
| n_radiometric_accuracy | Number of radiometric accuracy measurements |

3.4 Invalid-pixel values

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Not all values in a variable array contain valid measurement data; this is especially true for the grid-point brightness temperature measurements where a varying number of measurements are stored in an array of fixed dimensions.

Array fields not containing valid measurement data contain an invalid pixel value that is defined for each variable independently. A variable that has an invalid-pixel value defined owns an attribute named "_FillValue" that contains the invalid pixel value for this variable (RD.3). If no fill value is defined, invalid pixels contain a zero value.

3.5 Flag coding

Some of the variables in a SMOS product are flag variables. In addition to the raw flag data, these variables contain attributes that describe how the flag values are interpreted. The attribute naming follows the NetCDF CF conventions (RD.3).

Table 2: CF compliant variable attributes for flags

| Attribute Name | Description |
|---|--|
| flag_masks | Comma separated list of binary masks. The boolean conditions are identified by performing bitwise AND of the variable value and the flag_masks. The data type of the mask must match the data type of the associated variable. |
| flag_meanings Space-separated list of interpretations corresponding t flag_values and/or flag_masks. | |
| flag_values | Comma-separated list of map values. Flag_values maps each value in the variable to a value in the flag_meanings in order to interpret the meaning of the value in the array. |

3.6 Data types

Wherever possible, the converted NetCDF variables will have the same data type as the EE file structure members originally defined. In some cases a type promotion has to be applied. This is the case for all unsigned integer data types, which lack support from the NetCDF Java API used.

Following the best practices document by Unidata (RD.2), these variables are stored using their signed data type counterparts and adding an attribute "_Unsigned = true".

3.7 Variable scaling

When a variable value stored in the NetCDf file requires mathematical operations to be transformed to a value reflecting a physical unit, this is indicated by variable attributes.

The standard operation is the linear transformation. When this transformation is required, this is indicated by the two attributes "scale factor" and "scale offset". The transformation to be applied is in this case expressed as

$$value_{phys} = scale_factor * value_{stored} + scale_offset$$

Other operations are not required for the current version of the converter software.

3.8 Variable name conversion

Some of the variable names present in the Earth Explorer file structures cannot directly be mapped to the NetCDF variable names, as the original names violate the NetCDF naming conventions. For these variables, the original variable name is converted to a compatible name, as close to the original as possible.

Original Name Converted Name Tb_42.5H Tb_42_5H Sigma_Tb_42.5H Sigma_Tb_42_5H Tb_42.5V Tb_42_5V Sigma_Tb_42.5V Sigma_Tb_42_5V Tb_42.5X Tb_42_5X Sigma_Tb_42.5X Sigma_Tb_42_5X Tb 42.5Y Tb 42 5Y Sigma_Tb_42.5Y Sigma_Tb_42_5Y

Table 3: Variable name conversions

4 Supported SMOS product types

The converter software is designed to be backwards compatible. Internal conversion parameters and the variables, types and dimensions to be written into the target product are read from the associated file format schema files. These are available either from the internal file format database (DDDB) or an external extension of it (please refer to the SMOS-Box online manual available from the SNAP SMOS-Box Toolbox help menu).

The conversion software supports conversion of SMOS L1C and L2 user product formats. The SMOS-data can be read either form Earth Explorer *.HRD/*.DBL file pairs or from zip-compressed products. A detailed list of the supported types and schema versions is given below.

Table 4: Supported product types and schema versions

| Product type | BinX schema versions supported |
|--------------|--------------------------------|
| MIR_BWLD1C | 200, 201, 300, 400 |



| MIR_BWLF1C | 200, 201, 300, 400 |
|------------|-------------------------|
| MIR_BWND1C | 200 |
| MIR_BWNF1C | 200 |
| MIR_BWSD1C | 200, 201, 300, 400 |
| MIR_BWSF1C | 200, 201, 300, 400 |
| MIR_OSUDP2 | 200, 300, 400, 401 |
| MIR_SCLD1C | 200, 201, 300, 400, 401 |
| MIR_SCLF1C | 200, 201, 300, 400, 401 |
| MIR_SCND1C | 200 |
| MIR_SCNF1C | 200 |
| MIR_SCSD1C | 200, 201, 300, 400, 401 |
| MIR_SCSF1C | 200, 201, 300, 400, 401 |
| MIR_SMUDP2 | 200, 201, 202, 300, 400 |

5 Functionality

5.1 Geographic sub-setting

When desired, the converter can apply a geographic subset according to a user supplied Region of Interest (ROI). During the conversion process, the software compares each grid-point location with the ROI and writes only those contained in it to the target file. The current implementation supports ROIs consisting of either Polygons or Multi-Polygons. The polygons have to be passed as textual conversion arguments using the OGC defined Well Known Text (WKT) format. This format is described in detail at [RD.4].

An example polygon:

For L1C science data, a geographic sub-setting is eventually followed by an associated sub-setting of the snapshot information stored. During the geographic processing, the converter keeps track of all snapshots that are covered by the grid-cell measurements written to the output file. A subsequent step reduces the list of all available snapshot informations to keep only those that are referenced by measurement data exported.

5.2 Variable sub-setting

The NetCDF Converter software allows users to convert only a subset of the original variables contained in the Earth Explorer file. This is achieved by adding a comma-separated list of variable names desired to the command (please refer to 6 for details). Please note that the available variable names differ from the band names displayed in the S-3 Toolbox. The S-3 Toolbox displays the SMOS data as interpreted variable bands (e.g. polarisations applied) projected onto a rectangular longitude/latitude raster. The converter instead directly reads and writes the variable data as defined in the Earth Explorer BinX schema files. These may be obtained from ESA.

A list of variable names per product type can be found below; this table lists the variables as defined by the latest schema versions (version 400). Variable naming and availability may differ for older file versions.

Table 5: Variable names for products using schema version V400

| Product Type | Variable Names |
|---------------------------|--|
| MIR_BWLD1C, MIR_BWSD1C | Flags, BT_Value, Radiometric_Accuracy_of_Pixel, Azimuth_Angle, Footprint_Axis1, Footprint_Axis2, Grid_Point_ID, Grid_Point_Latitude, Grid_Point_Longitude, Grid_Point_Altitude, Grid_Point_Mask, BT_Data_Counter |
| MIR_BWLF1C, MIR_BWSF1C | Flags, BT_Value_Imag, BT_Value_Real, Radiometric_Accuracy_of_Pixel, Azimuth_Angle, Footprint_Axis1, Footprint_Axis2, Grid_Point_ID, Grid_Point_Latitude, Grid_Point_Longitude, Grid_Point_Altitude, Grid_Point_Mask, BT_Data_Counter |
| MIR_OSUDP2 | Dg_chi2_1, Dg_chi2_2, Dg_chi2_3, Dg_chi2_Acard, Dg_chi2_P_1, Dg_chi2_P_2, Dg_chi2_P_3, Dg_chi2_P_Acard, Dg_quality_SSS_1, Dg_quality_SSS_2, Dg_quality_SSS_3, Dg_quality_Acard, Dg_num_iter_1, Dg_num_iter_2, Dg_num_iter_3, Dg_num_iter_4, Dg_num_meas_l1c, Dg_num_meas_valid, Dg_border_fov, Dg_af_fov, Dg_sun_tails, Dg_sun_glint_area, Dg_sun_glint_fov, Dg_sun_fov, Dg_sun_glint_L2, Dg_Suspect_ice, Dg_galactic_Noise_Error, Dg_sky, Dg_moonglint, Dg_RFI_L1, Dg_RFI_X, Dg_RFI_Y, Dg_RFI_probability, X_swath, Equiv_ftprt_diam, Mean_acq_time, SSS1, Sigma_SSS1, SSS2, Sigma_SSS2, SSS3, Sigma_SSS3, A_card, Sigma_Acard, WS, SST, Tb_42.5H, Sigma_Tb_42.5H, Tb_42.5V, Sigma_Tb_42.5V, Tb_42.5X, Sigma_Tb_42.5X, Tb_42.5Y, Sigma_Tb_42.5Y, Grid_Point_ID, Latitude, Longitude, Control_Flags_1, Control_Flags_2, Control_Flags_3, Science_Flags_4 |
| MIR_SCLD1C, MIR_SCSD1C | Software_Error_flag, Instrument_Error_flag, ADF_Error_flag, Calibration_Error_flag, Days, Seconds, Microseconds, Flags, BT_Value, Pixel_Radiometric_Accuracy, Incidence_Angle, Azimuth_Angle, Faraday_Rotation_Angle, Geometric_Rotation_Angle, Snapshot_ID_of_Pixel, Footprint_Axis1, Footprint_Axis2, Snapshot_ID, Snapshot_OBET, X_Position, Y_Position, Z_Position", X_Velocity, Y_Velocity, Z_Velocity, Vector_Source, Q0, Q1, Q2, Q3, TEC, Geomag_F, Geomag_D, Geomag_I, Sun_RA, Sun_DEC, Sun_BT, Accuracy, Radiometric_Accuracy, X-Band, Grid_Point_ID, Grid_Point_Latitude, Grid_Point_Longitude, Grid_Point_Altitude, Grid_Point_Mask, BT_Data_Counter |
| MIR_SCLF1C, MIR_SCSF1C | Software_Error_flag, Instrument_Error_flag, ADF_Error_flag, Calibration_Error_flag, Days, Seconds, Microseconds, Flags, BT_Value_Imag, BT_Value_Real, Pixel_Radiometric_Accuracy, Incidence_Angle, Azimuth_Angle, Faraday_Rotation_Angle, Geometric_Rotation_Angle, Snapshot_ID_of_Pixel, Footprint_Axis1, Footprint_Axis2, Snapshot_ID, Snapshot_OBET, X_Position, Y_Position, Z_Position", X_Velocity, Y_Velocity, Z_Velocity, Vector_Source, Q0, Q1, Q2, Q3, TEC, Geomag_F, Geomag_D, Geomag_I, Sun_RA, Sun_DEC, Sun_BT, Accuracy, Radiometric_Accuracy, X-Band, Grid_Point_ID, Grid_Point_Latitude, Grid_Point_Longitude, Grid_Point_Altitude, Grid_Point_Mask, BT_Data_Counter |



| MIR_SMUDP2 | Days, Seconds, Microseconds, DGG_Current_Flags, Tau_Cur_DQX, HR_Cur_DQX, N RFI X, |
|------------|---|
| | / |
| | N_RFI_Y, RFI_Prob, Processing_Flags, S_Tree_1, S_Tree_2, Science_Flags, N_Sky, |
| | Confidence_Flags, GQX, Chi_2, Chi_2_P, N_Wild, M_AVA0, M_AVA, AFP, N_AF_FOV, |
| | N_Sun_Tails, N_Sun_Glint_Area, N_Sun_FOV, N_RFI_Mitigations, N_Strong_RFI, |
| | N_Point_Source_RFI, N_Tails_Point_Source_RFI, N_Software_Error, N_Instrument_Error, |
| | N_ADF_Error, N_Calibration_Error, N_X_Band, Soil_Moisture, Soil_Moisture_DQX, |
| | Optical_Thickness_Nad, Optical_Thickness_Nad_DQX, Surface_Temperature, |
| | Surface_Temperature_DQX, TTH, TTH_DQX, RTT, RTT_DQX, Scattering_Albedo_H, |
| | Scattering_Albedo_H_DQX, DIFF_Albedos, DIFF_Albedos_DQX, Roughness_Param, |
| | Roughness_Param_DQX, Dielect_Const_MD_RE, Dielect_Const_MD_RE_DQX, |
| | Dielect_Const_MD_IM, Dielect_Const_MD_IM_DQX, Dielect_Const_Non_MD_RE, |
| | Dielect_Const_Non_MD_RE_DQX, Dielect_Const_Non_MD_IM, |
| | Dielect_Const_Non_MD_IM_DQX, TB_ASL_Theta_B_H, TB_ASL_Theta_B_H_DQX, |
| | TB_ASL_Theta_B_V, TB_ASL_Theta_B_V_DQX, TB_TOA_Theta_B_H, |
| | TB_TOA_Theta_B_H_DQX, TB_TOA_Theta_B_V, TB_TOA_Theta_B_V_DQX, |
| | Grid_Point_ID, |
| | Latitude, Longitude, Altitude, X_Swath |

Note: A minimal set of variables is required to be able to open the exported file in the SMOS-Box. These variables are listed in the Table below:

Table 6: Required variables for SMOS-Box import

| Product Type | Required Variables |
|---------------------------|--|
| MIR_BWLD1C, MIR_BWSD1C | Grid_Point_ID, Grid_Point_Latitude, Grid_Point_Longitude |
| MIR_BWLF1C, MIR_BWSF1C | Grid_Point_ID, Grid_Point_Latitude, Grid_Point_Longitude |
| MIR_OSUDP2 | Grid_Point_ID, Latitude, Longitude |
| MIR_SCLD1C, MIR_SCSD1C | Grid_Point_ID, Grid_Point_Latitude, Grid_Point_Longitude, Flags, Incidence_Angle |
| MIR_SCLF1C, MIR_SCSF1C | Grid_Point_ID, Grid_Point_Latitude, Grid_Point_Longitude, Flags, Incidence_Angle |
| MIR_SMUDP2 | Grid_Point_ID, Latitude, Longitude |

5.3 Compression

The target file format NetCDF and the associated software library for reading and writing the files implements a built-in compression mechanism to reduce the storage size of the data on the hard-drive.

Data compression allows the user to balance between file size and conversion time. The higher the compression ratio, the longer it takes to calculate the inflation algorithm for the data. The same – of course – is true for reading access to the data files written.

The compression factor is adjustable as user parameter which ranges from 0 to 9. A factor of 0 means that no compression at all is applied. A factor of 9 implies that the highest data reduction is achieved, at the cost of higher CPU load.

The increased CPU load for compression algorithm execution goes in conjunction with a decreased time required for storage, as lesser data has to be written to the hard-drive. For each hardware-setup there is a specific optimum setting that minimizes the conversion time.

6 Installations

The conversion tool is delivered in two separate installations. Firstly, it is implemented as an operator to be used from the Sentinel Toolbox Graph Processing Tool. This installation is an add-on to a regular SNAP Toolbox /SMOS-Box installation. When using the GPT operator, the conversion tasks can be embedded into larger processing chains using the Graph Description File XML interface.

The second installation is a self-contained command line executable. This installation is completely independent from SNAP Toolbox /SMOS-Box and offers a simple command line interface.

Both installation possibilities are described in detail in the following chapters.

6.1 S-3 Toolbox Graph Processing Tool operator

The NetCDF conversion tool is implemented as a GPT operator. This allows using the converter in batch mode using the Graph Processing command line tool. Information about the GPT can be found in the S-3 Toolbox main documentation, chapter Graph Processing Framework and online in the S-3 Toolbox-Wiki: GPT bulk processing [RD.5]. This converter installation is automatically integrated into S-3 Toolbox when using the standard installer for the SMOS-Box software.

The hard- and software requirements for this installation follow the guidelines of SNAP Toolbox. Please refer to the SNAP Toolbox manual for details.

The GPT is invoked from the command-line using the syntax described in the corresponding sections of the SNAP Toolbox help. The conversion operator is invoked from GPT using the operator name "SmosNetcdfExport".

The following table lists the operator parameters.

Table 7: GPT operator parameters

| Name | Default Value | Description | |
|--------------------|---------------|--|--|
| sourceProducts | None | The source products to be converted. If not given, the parameter 'sourceProductPaths' must be provided. | |
| sourceProductPaths | None | Comma-separated list of file paths specifying the source products. | |
| | | Each path may contain the wildcards '**' (matches recursively any directory), '*' (matches any character sequence in path names) and '?' (matches any single character). | |
| targetDirectory | | The target directory for the converted data. If not existing, directory will be created. | |
| overwriteTarget | False | Set true to overwrite already existing target files. | |
| geometry | None | Target geographical region as a geometry in well-known text format (WKT). The output product will be tailored according | |



| | | to the region. |
|------------------|------|--|
| institution | None | Set institution field for file metadata. If left empty, no institution metadata is written to output file. |
| contact | None | Set contact field for file metadata. If left empty, no contact information is written to output file. |
| variableNames | None | Comma separated list of band names to export. If left empty, no band sub-setting is applied. |
| compressionLevel | 6 | Output file compression level. 0 - no compression, 9 - highest compression. |

6.1.1 Examples

The following examples assume a Windows operating system. The same examples apply to Linux or MacOS, just replace the operating system paths with the corresponding system specific paths.

Example 1: Conversion of a single file, output file will be written to gpt working directory

GPT allows using various methods to pass parameter; the following examples only use the approach of passing in a graph.xml file for the definition of processing parameters. For other methods, please refer to the S-3 Toolbox documentation [RD.5].

Assuming the graph definition is written to a file named "smos-conversion.xml", calls to GPT for the next examples always are:

gpt smos-conversion.xml or passing in an absolute path to the graph definition file if it is not in the current working directory.

Example 2: Conversion of all compressed products in a source directory to a target directory, forcing to overwrite already existing files, using geographic sub-setting. The example "smos-conversion.xml" is shown below:

Example 3: Conversion of all L1C full polarization science products in a source directory to a target directory, forcing to overwrite already existing files, using maximum compression level, using variables sub-setting. The example "smos-conversion.xml" is shown below:

```
<graph id="SMOS test conversion">
<version>1.0</version>
<node id="smos-conversion">
```

6.2 Stand-alone program

Additionally, the converter software is distributed as a self-contained zip archive that allows an installation independent from SNAP/SMOS-Box. This distribution comprises a command-line interface, allowing the tool to be integrated into various scripts or to be invoked from other third-party software.

The hard- and software requirements for this installation are described in the following table.

| | Minimum | Recommended |
|--------------|----------------|--------------------------------|
| CPU | Intel Core i5 | Intel Core i7, 3 GHz or better |
| RAM | 4 GB | 8 GB |
| Java Runtime | Java 8 (32bit) | Java 8 (64bit) |

Table 8: Hard- and Software Requirements

Important notes on the use of 32 bit Java Virtual Machines

Note: It is strongly recommended to use a 64bit Java Virtual Machine as it has been observed that a 32bit VM quickly reaches memory limits when converting large (especially L1C) files. If you are experiencing Java memory heap allocation failures using a Java 32bit VM, try to adapt the maximum heap size allocated by editing the shell script files smos-ee-to-nc.bat/.sh and adapt the maximal heap size by changing the value "-Xmx2048M". The optimal value for 32bit VMs is depending on the system status, 1280 MB is a good starting point.

Note: The use of a 32bit Java Virtual Machine is only recommended for the conversion of L1C Browse and L2 products.

To install the tool simply extract the content of the zip archive into a folder of your choice.

The conversion tool is invoked using a shell script file named smos-ee-to-nc.bat/.sh. The command line syntax is smos-ee-to-nc [options] file ...

When invoked without command line parameters, the conversion tool prints its usage to the console window. The possible options are listed in the table below.

| Option short name | Option long name | Argument | Default | Description |
|-------------------|-------------------|----------|---------|---|
| none | compression-level | Integer | 6 | Target file compression level. 0 – no compression, 9 – highest compression |
| none | contact | String | none | Contact information to be included in the global attributes of the target file. |

Table 9: Stand-alone converter command line options

| • | |
|-------|--|
| | |
| 4 - 1 | |
| | |

| -е | errors | none | none | Produce execution error messages when program ends with an exit code different from 0. |
|------|----------------------|--------|-------|--|
| -h | help | none | none | Display help information |
| none | institution | String | none | Institution information to be included in the global attributes of the target file. |
| -1 | log-level | String | INFO | Set the log-level, where the level must be one of {ALL, INFO, CONFIG, WARNING, SEVERE, OFF} |
| none | overwrite-target | none | false | If set, an eventually existing target product will be overwritten without warning |
| none | region | String | none | A region of interest (ROI) specified in geographic coordinates using well-knowntext (WKT) format. The target product will only contain grid-cells data that is contained in the ROI. |
| none | source-product-paths | String | none | Comma-separated list of file paths specifying the source products. Each path may contain the wildcards '**' (matches recursively any directory), '*' (matches any character sequence in path names) and '?' (matches any single character). |
| none | target-directory | String | · | The directory where the target NetCDF files are written to. |
| -V | version | none | none | Displays version information |
| none | variables | String | none | A comma separated list of variables to be included into the target product. If left empty, all variables are converted. |

Note: Command line parameters that require an argument composed of comma separated list of strings, like "--variables" or "--source-product-paths" should be entered either without blank characters between the comma and a value or the argument should be quoted.

6.2.1 Examples

The following examples assume a Linux operating system. The same examples apply to Windows, just exchange smos-ee-to-nc.sh with smos-ee-to-nc.bat.



```
Conversion of a single file with increased logging output: smos-ee-to-nc.sh -l ALL --target-directory /home/BC/data /usr/local/data/SMOS/
```

SM_OPER_MIR_SCSF1C_20120514T013734_20120514T023053_505_001_1.zip

Conversion of all Browse Products in a directory, recursive through all subdirectories:

smos-ee-to-nc.sh --target-directory /home/BC/data --source-product-paths /usr/local/data/**/*MIR_BW*

Conversion of a single product with variables sub-setting

```
smos-ee-to-nc.sh --target-directory /home/BC/data --variables
BT_Value,Grid_Point_Latitude,Grid_Point_Longitude
/usr/local/data/SMOS/SM_OPER_MIR_BWLF1C_20111026T143206_20111026T152520_503_001_1.HDR
```

Conversion of all L1C science products in a directory with geographic sub-setting

```
smos-ee-to-nc.sh \quad --target-directory \quad /home/BC/data \quad --source-product-paths \quad /usr/local/data/*SC*1C* \quad -region \\ "POLYGON((-60~0, -60~10, -20~10, -20~0, -60~0))"
```

7 NetCDF file structure

This chapter lists the variables and variable attributes of the NetCDF products in detail. The data is based on converted Earth Explorer files of schema version V400. The file structure examples are written in NetCDF CDL.

7.1 MIR BWLF1C

```
dimensions:
    n_grid_points = 40821;
n_bt_data = 4; variables:
    ubyte Grid_Point_Mask(n_grid_points);
Grid_Point_Mask:_Unsigned = "true";
Grid_Point_Mask:_FillValue = NaNf;
                                        float
Grid_Point_Altitude(n_grid_points);
Grid_Point_Altitude:_FillValue = NaNf;
Grid_Point_Altitude:units = "m" ;
Grid_Point_Latitude(n_grid_points);
Grid_Point_Latitude:_FillValue = NaNf;
Grid_Point_Latitude:units = "deg" ;
Grid_Point_ID(n_grid_points);
Grid_Point_ID:_Unsigned = "true" ;
Grid_Point_ID:_FillValue = NaNf;
    short Azimuth_Angle(n_grid_points, n_bt_data);
         Azimuth_Angle:_FillValue = 0.f;
         Azimuth_Angle:scale_factor = 0.0054931640625;
         Azimuth_Angle:scale_offset = 0.;
         Azimuth_Angle:_Unsigned = "true";
Azimuth_Angle:units = "deg";
Grid_Point_Longitude(n_grid_points);
Grid_Point_Longitude:_FillValue = NaNf ;
Grid_Point_Longitude:units = "deg";
Flags(n_grid_points, n_bt_data);
         Flags:flag_masks = 1s, 2s, 4s, 8s, 16s, 32s, 64s, 128s, 256s, 512s, 1024s, 2048s, 4096s, 8192s, 16384s, -32768s;
         Flags:flag_values = 1s, 2s, 4s, 8s, 16s, 32s, 64s, 128s, 256s, 512s, 1024s, 2048s, 4096s, 8192s, 16384s, -32768s;
         Flags:flag_meanings = "POL_FLAG_1 POL_FLAG_2 SUN_FOV SUN_GLINT_FOV MOON_GLINT_FOV
SINGLE_SNAPSHOT FTT SUN_POINT SUN_GLINT_AREA MOON_POINT AF_FOV EAF_FOV BORDER_FOV SUN_TAILS RFI_1
RFI_
2";
         Flags:_Unsigned = "true";
Flags:_FillValue = 0.f;
    ubyte BT_Data_Counter(n_grid_points);
BT_Data_Counter:_Unsigned = "true";
BT_Data_Counter:_FillValue = NaNf;
Footprint\_Axis2(n\_grid\_points, n\_bt\_data) \ ;
         Footprint_Axis2:_FillValue = 0.f;
         Footprint_Axis2:scale_factor = 1.52587890625e-005;
         Footprint_Axis2:scale_offset = 0.;
```

```
Footprint_Axis2:_Unsigned = "true";
Footprint_Axis2:units = "km";
    short Footprint_Axis1(n_grid_points, n_bt_data);
         Footprint_Axis1:_FillValue = 0.f;
         Footprint\_Axis1: scale\_factor = 1.52587890625e\text{-}005 \ ;
         Footprint_Axis1:scale_offset = 0.;
         Footprint_Axis1:_Unsigned = "true";
Footprint_Axis1:units = "km";
BT_Value(n_grid_points, n_bt_data);
         BT_Value:_FillValue = -999.f;
                                                 BT_Value:units = "K";
short Radiometric_Accuracy_of_Pixel(n_grid_points, n_bt_data);
         Radiometric_Accuracy_of_Pixel:_FillValue = 0.f;
         Radiometric_Accuracy_of_Pixel:scale_factor = 1.52587890625e-005;
         Radiometric Accuracy of Pixel:scale offset = 0.;
         Radiometric_Accuracy_of_Pixel:_Unsigned = "true";
Radiometric_Accuracy_of_Pixel:units = "K";
7.2 MIR BWSF1C
dimensions:
    n_grid_points = 116237;
    n_bt_data = 4; variables:
    ubyte \ Grid\_Point\_Mask(n\_grid\_points)\ ;
Grid_Point_Mask:_Unsigned = "true";
Grid_Point_Mask:_FillValue = NaNf;
                                         float
Grid_Point_Altitude(n_grid_points);
Grid_Point_Altitude:_FillValue = NaNf;
Grid_Point_Altitude:units = "m" ;
Grid_Point_Latitude(n_grid_points);
Grid_Point_Latitude:_FillValue = NaNf;
Grid_Point_Latitude:units = "deg";
Grid Point ID(n grid points);
Grid_Point_ID:_Unsigned = "true";
Grid_Point_ID:_FillValue = NaNf ;
Azimuth\_Angle(n\_grid\_points, n\_bt\_data) \ ;
         Azimuth_Angle:_FillValue = 0.f;
         Azimuth\_Angle:scale\_factor = 0.0054931640625;
         Azimuth\_Angle:scale\_offset = 0.;
         Azimuth_Angle:_Unsigned = "true";
Azimuth_Angle:units = "deg";
                                 float
Grid_Point_Longitude(n_grid_points);
Grid_Point_Longitude:_FillValue = NaNf;
Grid_Point_Longitude:units = "deg" ;
Flags(n_grid_points, n_bt_data);
         Flags:flag_masks = 1s, 2s, 4s, 8s, 16s, 32s, 64s, 128s, 256s, 512s, 1024s, 2048s, 4096s, 8192s, 16384s, -32768s;
         Flags:flag_values = 1s, 2s, 4s, 8s, 16s, 32s, 64s, 128s, 256s, 512s, 1024s, 2048s, 4096s, 8192s, 16384s, -32768s;
         Flags:flag_meanings = "POL_FLAG_1 POL_FLAG_2 SUN_FOV SUN_GLINT_FOV MOON_GLINT_FOV
SINGLE_SNAPSHOT FTT SUN_POINT SUN_GLINT_AREA MOON_POINT AF_FOV EAF_FOV BORDER_FOV SUN_TAILS RFL_1
RFI_
2";
         Flags:_Unsigned = "true";
Flags:_FillValue = 0.f;
                          ubvte
BT_Data_Counter(n_grid_points);
BT_Data_Counter:_Unsigned = "true";
BT_Data_Counter:_FillValue = NaNf;
Footprint Axis2(n grid points, n bt data);
         Footprint_Axis2:_FillValue = 0.f;
         Footprint_Axis2:scale_factor = 1.52587890625e-005;
         Footprint\_Axis2:scale\_offset = 0.;
         Footprint_Axis2:_Unsigned = "true";
Footprint_Axis2:units = "km";
    short Footprint_Axis1(n_grid_points, n_bt_data);
         Footprint_Axis1:_FillValue = 0.f;
         Footprint_Axis1:scale_factor = 1.52587890625e-005;
         Footprint_Axis1:scale_offset = 0.;
         Footprint_Axis1:_Unsigned = "true";
Footprint_Axis1:units = "km";
                                 float
BT_Value(n_grid_points, n_bt_data);
         BT_Value:_FillValue = -999.f;
                                                 BT_Value:units = "K";
short Radiometric_Accuracy_of_Pixel(n_grid_points, n_bt_data);
         Radiometric_Accuracy_of_Pixel:_FillValue = 0.f;
         Radiometric_Accuracy_of_Pixel:scale_factor = 1.52587890625e-005;
         Radiometric_Accuracy_of_Pixel:scale_offset = 0.;
Radiometric_Accuracy_of_Pixel:_Unsigned = "true";
         Radiometric_Accuracy_of_Pixel:units = "K";
```



7.3 MIR OSUDP2

```
dimensions:
    n_grid_points = 143890;
variables:
    float Sigma_SSS3(n_grid_points);
Sigma_SSS3:_FillValue = -999.f;
Sigma\_SSS3:units = "psu";
Sigma_SSS1(n_grid_points);
Sigma_SSS1:_FillValue = -999.f;
Sigma_SSS1:units = "psu";
                              short
Dg_af_fov(n_grid_points);
Dg_af_fov:_Unsigned = "true";
Dg_af_fov:_FillValue = 0.f;
                              float
Sigma_SSS2(n_grid_points);
Sigma_SSS2:_FillValue = -999.f;
Sigma_SSS2:units = "psu";
Dg_border_fov(n_grid_points);
Dg_border_fov:_Unsigned = "true";
Dg_border_fov:_FillValue = 0.f;
                                  int
Grid\_Point\_ID(n\_grid\_points);
Grid_Point_ID:_Unsigned = "true";
Grid_Point_ID:_FillValue = 0.f;
                                  short
Dg_chi2_1(n_grid_points);
Dg_chi2_1:_Unsigned = "true";
Dg_chi2_1:_FillValue = 0.f;
Dg_moonglint(n_grid_points);
Dg_moonglint:_Unsigned = "true";
Dg_moonglint:_FillValue = 0.f;
Dg_chi2_2(n_grid_points);
Dg_chi2_2:_Unsigned = "true";
Dg_chi2_2:_FillValue = 0.f;
Science_Flags_4(n_grid_points);
        Science_Flags_4:flag_masks = 1s, 2s, 4s, 8s, 16s, 32s, 64s, 128s, 256s, 512s, 1024s, 2048s, 4096s, 8192s, 16384s,
-32768s, 0s, 0s, 0s, 0s, 0s, 0s :
        Science_Flags_4:flag_values = 1s, 2s, 4s, 8s, 16s, 32s, 64s, 128s, 256s, 512s, 1024s, 2048s, 4096s, 8192s, 16384s, -32768s, 0s, 0s,
0s. 0s. 0s. 0s:
         Science_Flags_4:flag_meanings = "FG_SC_LAND_SEA_COAST1 FG_SC_LAND_SEA_COAST2
FG_SC_TEC_GRADIENT FG_SC_IN_CLIM_ICE FG_SC_ICE FG_SC_SUSPECT_ICE FG_SC_RAIN FG_SC_HIGH_WIND
FG_SC_LOW_WIND
FG_SC_HIGHT_SST FG_SC_LOW_SST FG_SC_HIGH_SSS FG_SC_LOW_SSS FG_SC_SEA_STATE_1
FG\_SC\_SEA\_STATE\_2 \ FG\_SC\_SEA\_STATE\_3 \ FG\_SC\_SEA\_STATE\_4 \ FG\_SC\_SEA\_STATE\_5 \ FG\_SC\_SEA\_STATE\_6
FG_SC_SST_FRONT FG_SC_SSS_FRONT F
G_SC_ICE_ACARD";
        Science_Flags_4:_Unsigned = "true";
Science_Flags_4:_FillValue = 0.f;
Dg_chi2_3(n_grid_points);
Dg_chi2_3:_Unsigned = "true";
Dg_chi2_3:_FillValue = 0.f;
Science_Flags_3(n_grid_points);
        Science_Flags_3:flag_masks = 1s, 2s, 4s, 8s, 16s, 32s, 64s, 128s, 256s, 512s, 1024s, 2048s, 4096s, 8192s, 16384s,
-32768s, 0s, 0s, 0s, 0s, 0s, 0s;
        Science_Flags_3:flag_values = 1s, 2s, 4s, 8s, 16s, 32s, 64s, 128s, 256s, 512s, 1024s, 2048s, 4096s, 8192s, 16384s, -32768s, 0s, 0s,
0s, 0s, 0s, 0s;
        Science_Flags_3:flag_meanings = "FG_SC_LAND_SEA_COAST1 FG_SC_LAND_SEA_COAST2
FG_SC_TEC_GRADIENT FG_SC_IN_CLIM_ICE FG_SC_ICE FG_SC_SUSPECT_ICE FG_SC_RAIN FG_SC_HIGH_WIND
FG_SC_LOW_WIND
FG\_SC\_HIGHT\_SST\ FG\_SC\_LOW\_SST\ FG\_SC\_HIGH\_SSS\ FG\_SC\_LOW\_SSS\ FG\_SC\_SEA\_STATE\_1
FG_SC_SEA_STATE_2 FG_SC_SEA_STATE_3 FG_SC_SEA_STATE_4 FG_SC_SEA_STATE_5 FG_SC_SEA_STATE_6
FG SC SST FRONT FG SC SSS FRONT F
G_SC_ICE_ACARD";
        Science_Flags_3:_Unsigned = "true" ;
Science_Flags_3:_FillValue = 0.f;
                                   short
Dg_chi2_Acard(n_grid_points);
Dg_chi2_Acard:_Unsigned = "true";
Dg_chi2_Acard:_FillValue = 0.f;
                                   short
Dg_Suspect_ice(n_grid_points);
Dg_Suspect_ice:_Unsigned = "true";
Dg_Suspect_ice:_FillValue = 0.f;
Dg_chi2_P_Acard(n_grid_points);
Dg_chi2_P_Acard:_Unsigned = "true" ;
Dg_chi2_P_Acard:_FillValue = 0.f;
                                     short
Dg_RFI_probability(n_grid_points);
Dg_RFI_probability:_FillValue = NaNf;
```



```
Dg_RFI_probability:_Unsigned = "true" ;
Dg_RFI_probability:units = "%";
Science_Flags_1(n_grid_points);
        Science_Flags_1:flag_masks = 1s, 2s, 4s, 8s, 16s, 32s, 64s, 128s, 256s, 512s, 1024s, 2048s, 4096s, 8192s, 16384s,
-32768s, 0s, 0s, 0s, 0s, 0s, 0s;
        Science_Flags_1:flag_values = 1s, 2s, 4s, 8s, 16s, 32s, 64s, 128s, 256s, 512s, 1024s, 2048s, 4096s, 8192s, 16384s,
-32768s, 0s, 0s, 0s, 0s, 0s, 0s;
        Science_Flags_1:flag_meanings = "FG_SC_LAND_SEA_COAST1 FG_SC_LAND_SEA_COAST2
       TEC_GRADIENT FG_SC_IN_CLIM_ICE FG_SC_ICE FG_SC_SUSPECT_ICE FG_SC_RAIN FG_SC_HIGH_WIND
FG_SC_LOW_WIND
FG SC HIGHT SST FG SC LOW SST FG SC HIGH SSS FG SC LOW SSS FG SC SEA STATE 1
FG_SC_SEA_STATE_2 FG_SC_SEA_STATE_3 FG_SC_SEA_STATE_4 FG_SC_SEA_STATE_5 FG_SC_SEA_STATE_6
FG_SC_SST_FRONT FG_SC_SSS_FRONT F
G_SC_ICE_ACARD";
        Science_Flags_1:_Unsigned = "true";
Science_Flags_1:_FillValue = 0.f;
Science_Flags_2(n_grid_points);
        Science_Flags_2:flag_masks = 1s, 2s, 4s, 8s, 16s, 32s, 64s, 128s, 256s, 512s, 1024s, 2048s, 4096s, 8192s, 16384s,
-32768s, 0s, 0s, 0s, 0s, 0s, 0s;
        Science_Flags_2:flag_values = 1s, 2s, 4s, 8s, 16s, 32s, 64s, 128s, 256s, 512s, 1024s, 2048s, 4096s, 8192s, 16384s, -32768s, 0s, 0s,
0s, 0s, 0s, 0s;
        Science_Flags_2:flag_meanings = "FG_SC_LAND_SEA_COAST1 FG_SC_LAND_SEA_COAST2
FG_SC_TEC_GRADIENT FG_SC_IN_CLIM_ICE FG_SC_ICE FG_SC_SUSPECT_ICE FG_SC_RAIN FG_SC_HIGH_WIND
FG SC LOW WIND
FG_SC_HIGHT_SST FG_SC_LOW_SST FG_SC_HIGH_SSS FG_SC_LOW_SSS FG_SC_SEA_STATE_1
FG_SC_SEA_STATE_2 FG_SC_SEA_STATE_3 FG_SC_SEA_STATE_4 FG_SC_SEA_STATE_5 FG_SC_SEA_STATE_6
FG_SC_SST_FRONT FG_SC_SSS_FRONT F
G_SC_ICE_ACARD";
        Science_Flags_2:_Unsigned = "true";
Science_Flags_2:_FillValue = 0.f;
                                   short
Dg_num_meas_valid(n_grid_points);
Dg num meas valid: Unsigned = "true";
Dg_num_meas_valid:_FillValue = 0.f;
                                       short
Dg_RFI_L1(n_grid_points);
Dg_RFI_L1:_Unsigned = "true";
Dg_RFI_L1:_FillValue = NaNf;
Dg_chi2_P_1(n_grid_points);
Dg_chi2_P_1:_Unsigned = "true";
Dg_chi2_P_1:_FillValue = 0.f;
                                float
X_swath(n_grid_points);
                                X_swath:_FillValue
= -999.f;
                 X_swath:units = "m";
                                          short
Dg_chi2_P_2(n_grid_points);
Dg_chi2_P_2:_Unsigned = "true";
Dg_chi2_P_2:_FillValue = 0.f;
                                 short
Dg_chi2_P_3(n_grid_points);
Dg_chi2_P_3:_Unsigned = "true";
Dg_chi2_P_3:_FillValue = 0.f;
                                short
Dg_sun_tails(n_grid_points);
Dg_sun_tails:_Unsigned = "true";
Dg_sun_tails:_FillValue = 0.f;
                                short
Dg_sun_glint_area(n_grid_points);
Dg_sun_glint_area:_Unsigned = "true";
Dg_sun_glint_area:_FillValue = 0.f;
                                     ubvte
Dg_num_iter_1(n_grid_points);
Dg num iter 1: Unsigned = "true";
Dg\_num\_iter\_1:\_FillValue = 0.f;
                                  float
Longitude(n_grid_points);
Longitude:_FillValue = -999.f;
Longitude:units = "deg";
    short Dg_galactic_Noise_Error(n_grid_points);
Dg_galactic_Noise_Error:_Unsigned = "true";
                                                  Dg_galactic_Noise_Error:_FillValue =
0.f;
    float A_card(n_grid_points);
A_{card:}FillValue = -999.f;
Dg_num_iter_3(n_grid_points);
Dg_num_iter_3:_Unsigned = "true" ;
Dg_num_iter_3:_FillValue = 0.f;
                                  short
Dg_sky(n_grid_points);
Dg_sky:_Unsigned = "true";
Dg_sky:_FillValue = NaNf;
                             ubyte
Dg_num_iter_2(n_grid_points);
Dg_num_iter_2:_Unsigned = "true" ;
Dg\_num\_iter\_2:\_FillValue = 0.f \; ;
                                  ubvte
Dg_num_iter_4(n_grid_points);
Dg_num_iter_4:_Unsigned = "true" ;
```

```
Dg_num_iter_4:_FillValue = 0.f;
Control_Flags_4(n_grid_points);
               Control_Flags_4:flag_masks = 2s, 4s, 8s, 16s, 64s, 128s, 256s, 1024s, 2048s, 4096s, 8192s, 16384s, -32768s, 0s, 0s, 0s, 0s, 0s, 0s, 0s,
0s, 0s, 0s, 0s, 0s, 0s, 0s, 0s, 0s;
               Control_Flags_4:flag_values = 2s, 4s, 8s, 16s, 64s, 128s, 256s, 1024s, 2048s, 4096s, 8192s, 16384s, -32768s, 0s, 0s, 0s, 0s, 0s, 0s, 0s,
0s, 0s, 0s, 0s, 0s, 0s, 0s, 0s, 0s;
               Control_Flags_4:flag_meanings = "FG_CTRL_RANGE FG_CTRL_SIGMA FG_CTRL_CHI2 FG_CTRL_CHI2_P
FG\_CTRL\_SUNGLINT\ FG\_CTRL\_MOONGLINT\ FG\_CTRL\_GAL\_NOISE\ FG\_CTRL\_REACH\_MAXITER
FG CTRL NUM MEAS MIN
 FG_CTRL_NUM_MEAS_LOW FG_CTRL_MANY_OUTLIERS FG_CTRL_MARQ FG_CTRL_ROUGHNESS FG_CTRL_FOAM
FG_CTRL_ECMWF FG_CTRL_VALID FG_CTRL_NO_SURFACE FG_CTRL_RANGE_ACARD FG_CTRL_SIGMA_ACARD
FG_CTRL_QUALITY_ACARD FG_
CTRL_USED_FARATEC FG_CTRL_POOR_GEOPHYS FG_CTRL_POOR_RETRIEVAL FG_CTRL_SUSPECT_RFI
FG_CTRL_RFI_PRONE_X FG_CTRL_RFI_PRONE_Y FG_CTRL_ADJUSTED_RA FG_CTRL_RETRIEV_FAIL";
               Control_Flags_4:_Unsigned = "true";
Control_Flags_4:_FillValue = 0.f;
Control_Flags_2(n_grid_points);
               Control_Flags_2:flag_masks = 2s, 4s, 8s, 16s, 64s, 128s, 256s, 1024s, 2048s, 4096s, 8192s, 16384s, -32768s, 0s, 0s, 0s, 0s, 0s, 0s,
0s, 0s, 0s, 0s, 0s, 0s, 0s, 0s, 0s;
               Control_Flags_2:flag_values = 2s, 4s, 8s, 16s, 64s, 128s, 256s, 1024s, 2048s, 4096s, 8192s, 16384s, -32768s, 0s, 0s, 0s, 0s, 0s, 0s, 0s,
0s, 0s, 0s, 0s, 0s, 0s, 0s, 0s, 0s;
               Control_Flags_2:flag_meanings = "FG_CTRL_RANGE FG_CTRL_SIGMA FG_CTRL_CHI2 FG_CTRL_CHI2_P
FG_CTRL_SUNGLINT FG_CTRL_MOONGLINT FG_CTRL_GAL_NOISE FG_CTRL_REACH_MAXITER
FG CTRL NUM MEAS MIN
FG_CTRL_NUM_MEAS_LOW FG_CTRL_MANY_OUTLIERS FG_CTRL_MARQ FG_CTRL_ROUGHNESS FG_CTRL_FOAM
FG\_CTRL\_ECMWF\ FG\_CTRL\_VALID\ FG\_CTRL\_NO\_SURFACE\ FG\_CTRL\_RANGE\_ACARD\ FG\_CTRL\_SIGMA\_ACARD\ FG\_CTRL\_SIGMA\_ACARD\
FG_CTRL_QUALITY_ACARD FG_
\tt CTRL\_USED\_FARATEC\ FG\_CTRL\_POOR\_GEOPHYS\ FG\_CTRL\_POOR\_RETRIEVAL\ FG\_CTRL\_SUSPECT\_RFI
FG_CTRL_RFI_PRONE_X FG_CTRL_RFI_PRONE_Y FG_CTRL_ADJUSTED_RA FG_CTRL_RETRIEV_FAIL";
               Control_Flags_2:_Unsigned = "true";
Control_Flags_2:_FillValue = 0.f;
Sigma_Tb_42_5H(n_grid_points);
Sigma_Tb_42_5H:_FillValue = -999.f;
Sigma_Tb_42_5H:units = "K";
Control_Flags_3(n_grid_points);
               0s, 0s, 0s, 0s, 0s, 0s, 0s, 0s, 0s;
               Control_Flags_3:flag_values = 2s, 4s, 8s, 16s, 64s, 128s, 256s, 1024s, 2048s, 4096s, 8192s, 16384s, -32768s, 0s, 0s, 0s, 0s, 0s, 0s, 0s,
0s, 0s, 0s, 0s, 0s, 0s, 0s, 0s, 0s;
               Control_Flags_3:flag_meanings = "FG_CTRL_RANGE FG_CTRL_SIGMA FG_CTRL_CHI2 FG_CTRL_CHI2_P
FG_CTRL_SUNGLINT FG_CTRL_MOONGLINT FG_CTRL_GAL_NOISE FG_CTRL_REACH_MAXITER
FG_CTRL_NUM_MEAS_MIN
FG_CTRL_NUM_MEAS_LOW FG_CTRL_MANY_OUTLIERS FG_CTRL_MARQ FG_CTRL_ROUGHNESS FG_CTRL_FOAM
FG\_CTRL\_ECMWF\ FG\_CTRL\_VALID\ FG\_CTRL\_NO\_SURFACE\ FG\_CTRL\_RANGE\_ACARD\ FG\_CTRL\_SIGMA\_ACARD\ FG\_CTRL\_SIGMA\_ACARD\
FG_CTRL_QUALITY_ACARD FG_
CTRL_USED_FARATEC FG_CTRL_POOR_GEOPHYS FG_CTRL_POOR_RETRIEVAL FG_CTRL_SUSPECT_RFI
FG_CTRL_RFI_PRONE_X FG_CTRL_RFI_PRONE_Y FG_CTRL_ADJUSTED_RA FG_CTRL_RETRIEV_FAIL";
               Control Flags 3: Unsigned = "true";
Control_Flags_3:_FillValue = 0.f;
Control_Flags_1(n_grid_points);
               0s, 0s, 0s, 0s, 0s, 0s, 0s, 0s, 0s;
               Control_Flags_1:flag_values = 2s, 4s, 8s, 16s, 64s, 128s, 256s, 1024s, 2048s, 4096s, 8192s, 16384s, -32768s, 0s, 0s, 0s, 0s, 0s, 0s, 0s,
0s, 0s, 0s, 0s, 0s, 0s, 0s, 0s, 0s;
               Control_Flags_1:flag_meanings = "FG_CTRL_RANGE FG_CTRL_SIGMA FG_CTRL_CHI2 FG_CTRL_CHI2_P
FG\_CTRL\_SUNGLINT\ FG\_CTRL\_MOONGLINT\ FG\_CTRL\_GAL\_NOISE\ FG\_CTRL\_REACH\_MAXITER
FG_CTRL_NUM_MEAS_MIN
FG\_CTRL\_NUM\_MEAS\_LOW \\ FG\_CTRL\_MANY\_OUTLIERS \\ FG\_CTRL\_MARQ \\ FG\_CTRL\_ROUGHNESS \\ FG\_CTRL\_FOAM
FG_CTRL_ECMWF FG_CTRL_VALID FG_CTRL_NO_SURFACE FG_CTRL_RANGE_ACARD FG_CTRL_SIGMA_ACARD
FG_CTRL_QUALITY_ACARD FG_
CTRL_USED_FARATEC FG_CTRL_POOR_GEOPHYS FG_CTRL_POOR_RETRIEVAL FG_CTRL_SUSPECT_RFI
FG_CTRL_RFI_PRONE_X FG_CTRL_RFI_PRONE_Y FG_CTRL_ADJUSTED_RA FG_CTRL_RETRIEV_FAIL";
               Control_Flags_1:_Unsigned = "true";
Control_Flags_1:_FillValue = 0.f;
                                                                short
Dg_sun_glint_fov(n_grid_points);
Dg_sun_glint_fov:_Unsigned = "true";
Dg_sun_glint_fov:_FillValue = 0.f;
                                                                  float
Sigma_Acard(n_grid_points);
Sigma_Acard:_FillValue = -999.f;
                                                                 float
Latitude(n_grid_points);
Latitude:_FillValue = -999.f;
Latitude:units = "deg";
        short Dg_quality_Acard(n_grid_points);
Dg_quality_Acard:_Unsigned = "true";
```

Dg_quality_Acard:_FillValue = 0.f;

```
SSS3(n_grid_points);
                              SSS3:_FillValue = -
               SSS3:units = "psu";
999.f;
    short Dg_num_meas_l1c(n_grid_points);
Dg_num_meas_11c:_Unsigned = "true";
Dg_num_meas_l1c:_FillValue = 0.f;
                                        float
SSS2(n_grid_points);
                              SSS2:\_FillValue = \text{-}
999.f;
               SSS2:units = "psu" \; ; \\
                                        float
SSS1(n\_grid\_points)\;;
                              SSS1:_FillValue = -
999.f;
               SSS1:units = "psu";
Tb_42_5Y(n_grid_points);
Tb_{42_5Y:FillValue = -999.f;
Tb 42 5Y:units = "K";
Tb_42_5X(n_grid_points);
Tb_42_5X:_FillValue = -999.f;
Tb_42_5X:units = "K";
                           float WS(n_grid_points);
WS:_FillValue = -999.f;
                                 WS:units = "m s-1"
      short Dg_quality_SSS_1(n_grid_points);
Dg_quality_SSS_1:_Unsigned = "true";
Dg_quality_SSS_1:_FillValue = 0.f;
Tb_42_5V(n_grid_points);
Tb_42_5V:_FillValue = -999.f;
Tb_42_5V:units = "K";
Dg_quality_SSS_3(n_grid_points);
Dg_quality_SSS_3:_Unsigned = "true" ;
Dg_quality_SSS_3:_FillValue = 0.f;
Dg_quality_SSS_2(n_grid_points);
                                       short
Dg_quality_SSS_2:_Unsigned = "true";
Dg_quality_SSS_2:_FillValue = 0.f;
                                       float
Sigma_Tb_42_5V(n_grid_points);
Sigma_Tb_42_5V:_FillValue = -999.f;
Sigma_Tb_42_5V:units = "K";
Sigma_Tb_42_5X(n_grid_points);
Sigma_Tb_42_5X:_FillValue = -999.f;
Sigma\_Tb\_42\_5X{:}units = "K" \; ;
Tb_42_5H(n_grid_points);
Tb_42_5H:_FillValue = -999.f;
Tb_42_5H:units = "K";
Sigma_Tb_42_5Y(n_grid_points);
Sigma_Tb_42_5Y:_FillValue = -999.f;
Sigma_Tb_42_5Y:units = "K";
Dg\_sun\_glint\_L2(n\_grid\_points)\ ;
Dg_sun_glint_L2:_Unsigned = "true" ;
Dg_sun_glint_L2:_FillValue = 0.f;
                                      short
Dg_RFI_Y(n_grid_points);
Dg_RFI_Y:_Unsigned = "true";
Dg_RFI_Y:_FillValue = NaNf;
                                   short
Dg_RFI_X(n_grid_points);
Dg_RFI_X:_Unsigned = "true";
Dg_RFI_X:_FillValue = NaNf;
                                   float
SST(n_grid_points);
                             SST:_FillValue = -
999.f;
         SST:units = "°C";
7.4 MIR SCLF1C
dimensions:
    n_grid_points = 68595;
n_bt_data = 300;
n_radiometric_accuracy = 2;
n_snapshots = 1746; variables:
    double Geomag_F(n_snapshots);
         Geomag_F:_FillValue = 0.f;
Geomag_F:units = "nT";
Grid_Point_Altitude(n_grid_points);
Grid_Point_Altitude:_FillValue = -999.f;
Grid_Point_Altitude:units = "m" ;
Geomag_I(n_snapshots);
         Geomag_I:_FillValue = 0.f;
Geomag_I:units = "deg";
                             double
Y_Position(n_snapshots);
         Y_Position:_FillValue = 0.f;
Y_Position:units = "m";
                           short
Azimuth_Angle(n_grid_points, n_bt_data);
Azimuth_Angle:_FillValue = 0.f;
         Azimuth_Angle:scale_factor = 0.0054931640625;
         Azimuth_Angle:scale_offset = 0.;
```



```
Azimuth_Angle:_Unsigned = "true";
Azimuth_Angle:units = "deg";
Sun_RA(n_snapshots);
Sun_RA:_FillValue = 0.f;
Sun_RA:units = "deg";
                           float
Accuracy(n_snapshots);
Accuracy:_FillValue = 0.f;
Accuracy:units = "K";
                          double
Y_Velocity(n_snapshots);
         Y_Velocity:_FillValue = 0.f;
         Y_Velocity:units = "m/s";
    short\ Incidence\_Angle(n\_grid\_points,\ n\_bt\_data)\ ;
         Incidence_Angle:_FillValue = 0.f;
         Incidence_Angle:scale_factor = 0.001373291015625;
         Incidence_Angle:scale_offset = 0.;
         Incidence_Angle:_Unsigned = "true" ;
Incidence_Angle:units = "deg" ;
                                   ubyte
Instrument_Error_flag(n_snapshots);
Instrument\_Error\_flag:\_Unsigned = "true" \ ;
Instrument\_Error\_flag:\_FillValue = 0.f;
                                           double
Geomag_D(n_snapshots);
         Geomag_D:_FillValue = 0.f;
Geomag_D:units = "deg";
Grid_Point_Mask(n_grid_points);
Grid_Point_Mask:_Unsigned = "true" ;
Grid_Point_Mask:_FillValue = NaNf;
                                         int
Snapshot_ID(n_snapshots);
Snapshot_ID:_Unsigned = "true";
Snapshot_ID:_FillValue = 0.f;
                                  int
Grid\_Point\_ID(n\_grid\_points);
Grid_Point_ID:_Unsigned = "true";
Grid_Point_ID:_FillValue = 0.f;
    float Radiometric_Accuracy(n_snapshots, n_radiometric_accuracy);
         Radiometric_Accuracy:_FillValue = 0.f;
         Radiometric_Accuracy:scale_factor = 48.;
         Radiometric\_Accuracy:scale\_offset = 0.;
Radiometric_Accuracy:units = "K";
                                       float
                               Sun_BT:_FillValue =
Sun_BT(n_snapshots);
             Sun_BT:units = "K";
                                      double
0.f;
Z_Position(n_snapshots);
Z_Position:_FillValue = 0.f;
                                    Z_Position:units
           int Microseconds(n_snapshots);
= "m" ;
Microseconds:_Unsigned = "true";
Microseconds:_FillValue = 0.f;
Seconds(n_snapshots);
                               Seconds:_Unsigned =
                Seconds: FillValue = 0.f;
"true";
                                              int
Days(n_snapshots);
                            Days:_FillValue = 0.f;
    int Snapshot_ID_of_Pixel(n_grid_points, n_bt_data);
         Snapshot_ID_of_Pixel:_Unsigned = "true" ;
Snapshot_ID_of_Pixel:_FillValue = 0.f;
Calibration_Error_flag(n_snapshots);
Calibration_Error_flag:_Unsigned = "true";
Calibration_Error_flag:_FillValue = 0.f;
                                           ubyte
ADF_Error_flag(n_snapshots);
ADF_Error_flag:_Unsigned = "true";
ADF_Error_flag:_FillValue = 0.f;
    short Faraday_Rotation_Angle(n_grid_points, n_bt_data);
Faraday_Rotation_Angle:_FillValue = 0.f;
         Faraday\_Rotation\_Angle: scale\_factor = 0.0054931640625 \ ;
         Faraday_Rotation_Angle:scale_offset = 0.;
         Faraday_Rotation_Angle:_Unsigned = "true";
Faraday_Rotation_Angle:units = "deg";
X_Position(n_snapshots);
         X_{position:FillValue = 0.f;
X_Position:units = "m";
                            double
TEC(n_snapshots);
         TEC:_FillValue = 0.f;
                                        TEC:units = "TECU";
short Geometric_Rotation_Angle(n_grid_points, n_bt_data);
Geometric_Rotation_Angle:_FillValue = 0.f;
         Geometric_Rotation_Angle:scale_factor = 0.0054931640625;
         Geometric_Rotation_Angle:scale_offset = 0.;
         Geometric_Rotation_Angle:_Unsigned = "true";
Geometric_Rotation_Angle:units = "deg";
                                            float
Sun\_DEC(n\_snapshots);
                                 Sun_DEC:_FillValue = 0.f;
Sun_DEC:units = "deg";
    short Footprint_Axis2(n_grid_points, n_bt_data);
```



```
Footprint_Axis2:_FillValue = 0.f;
        Footprint\_Axis2:scale\_factor = 0.0007476806640625;
        Footprint_Axis2:scale_offset = 0.;
        Footprint_Axis2:_Unsigned
                                          "true
Footprint_Axis2:units = "km"
                                                short
Footprint_Axis1(n_grid_points, n_bt_data);
        Footprint_Axis1:_FillValue = 0.f;
        Footprint\_Axis1: scale\_factor = 0.0007476806640625 \ ;
        Footprint_Axis1:scale_offset = 0.;
        Footprint_Axis1:_Unsigned = "true";
Footprint_Axis1:units = "km";
Z_Velocity(n_snapshots);
        Z_Velocity:_FillValue = 0.f;
Z_Velocity:units = "m/s";
    float BT_Value_Real(n_grid_points, n_bt_data);
        BT_Value_Real:_FillValue = -999.f;
BT_Value_Real:units = "K";
Snapshot_OBET(n_snapshots);
Snapshot_OBET:_Unsigned = "true";
Snapshot_OBET:_FillValue = 0.f;
BT_Value_Imag(n_grid_points, n_bt_data);
        BT_Value_Imag:_FillValue = -999.f;
BT_Value_Imag:units = "K";
                             double
                         Q0:_FillValue = 0.f;
Q0(n_snapshots);
            Grid\_Point\_Latitude(n\_grid\_points)
    float
Grid_Point_Latitude:_FillValue
Grid_Point_Latitude:units = "deg";
    double Q1(n_snapshots);
Q1:_FillValue = 0.f;
                       double
Q2(n_snapshots);
Q2:_FillValue = 0.f;
                       double
Q3(n\_snapshots);
Q3:_FillValue = 0.f;
    ubyte Software_Error_flag(n_snapshots);
Software_Error_flag:_Unsigned = "true";
Software_Error_flag:_FillValue = 0.f;
Grid_Point_Longitude(n_grid_points);
Grid_Point_Longitude:_FillValue = -999.f;
Grid_Point_Longitude:units = "deg" ;
                                      short
Flags(n_grid_points, n_bt_data);
        Flags:flag_values = 1s, 2s, 4s, 8s, 16s, 32s, 64s, 128s, 256s, 512s, 1024s, 2048s, 4096s, 8192s, 16384s, -32768s;
        Flags:flag meanings = "POL FLAG_1 POL_FLAG_2 SUN_FOV SUN_GLINT_FOV MOON_GLINT_FOV
SINGLE_SNAPSHOT FTT SUN_POINT SUN_GLINT_AREA MOON_POINT AF_FOV EAF_FOV BORDER_FOV SUN_TAILS RFL_1
RFI_
2";
        Flags:_Unsigned = "true";
Flags:_FillValue = 0.f;
    short BT_Data_Counter(n_grid_points);
BT_Data_Counter:_Unsigned = "true";
BT_Data_Counter:_FillValue = NaNf;
                                       ubvte
Vector_Source(n_snapshots);
                                    Vector_Source:_Unsigned = "true";
                                 double X_Velocity(n_snapshots);
Vector_Source:_FillValue = 0.f;
X_Velocity:_FillValue = 0.f;
                                  X_Velocity:units = "m/s";
short Radiometric_Accuracy_of_Pixel(n_grid_points, n_bt_data);
        Radiometric\_Accuracy\_of\_Pixel:\_FillValue = 0.f \ ;
        Radiometric_Accuracy_of_Pixel:scale_factor = 0.000732421875;
        Radiometric\_Accuracy\_of\_Pixel:scale\_offset = 0.;
        Radiometric_Accuracy_of_Pixel:_Unsigned = "true";
Radiometric_Accuracy_of_Pixel:units = "K";
    ubyte X-Band(n_snapshots);
Band:_Unsigned = "true";
        X-Band:_FillValue = 0.f;
7.5 MIR SCSF1C
dimensions:
    n_{grid_points} = 116041;
n_bt_data = 300;
n_radiometric_accuracy = 2;
n_snapshots = 2507; variables:
```

double Geomag_F(n_snapshots);
 Geomag_F:_FillValue = 0.f;

 $Geomag_F:units = "nT";$



```
float Grid_Point_Altitude(n_grid_points);
Grid_Point_Altitude:_FillValue = -999.f;
Grid_Point_Altitude:units = "m";
Geomag_I(n_snapshots);
         Geomag_I:_FillValue = 0.f;
         Geomag_I:units = "deg";
    double Y_Position(n_snapshots);
         Y_Position:_FillValue = 0.f;
Y_Position:units = "m";
    short Azimuth_Angle(n_grid_points, n_bt_data);
         Azimuth_Angle:_FillValue = 0.f;
         Azimuth\_Angle:scale\_factor = 0.0054931640625 \ ;
         Azimuth_Angle:scale_offset = 0.;
         Azimuth_Angle:_Unsigned = "true";
Azimuth_Angle:units = "deg";
Sun_RA(n_snapshots);
Sun_RA:_FillValue = 0.f;
Sun_RA:units = "deg";
                           float
Accuracy(n_snapshots);
Accuracy:_FillValue = 0.f;
Accuracy:units = "K";
                          double
Y_Velocity(n_snapshots);
Y_Velocity:_FillValue = 0.f;
Y_Velocity:units = "m/s";
    short Incidence_Angle(n_grid_points, n_bt_data);
         Incidence_Angle:_FillValue = 0.f;
         Incidence_Angle:scale_factor = 0.001373291015625;
         Incidence_Angle:scale_offset = 0.;
         Incidence_Angle:_Unsigned = "true" ;
Incidence_Angle:units = "deg";
Instrument_Error_flag(n_snapshots);
Instrument_Error_flag:_Unsigned = "true";
Instrument_Error_flag:_FillValue = 0.f;
                                          double
Geomag_D(n_snapshots);
         Geomag_D:_FillValue = 0.f;
Geomag_D:units = "deg";
                             ubyte
Grid_Point_Mask(n_grid_points);
Grid Point Mask: Unsigned = "true";
Grid_Point_Mask:_FillValue = NaNf;
                                         int
Snapshot_ID(n_snapshots);
Snapshot_ID:_Unsigned = "true";
Snapshot_ID:_FillValue = 0.f;
Grid_Point_ID(n_grid_points);
Grid_Point_ID:_Unsigned = "true" ;
Grid_Point_ID:_FillValue = 0.f;
    float Radiometric_Accuracy(n_snapshots, n_radiometric_accuracy);
         Radiometric_Accuracy:_FillValue = 0.f;
         Radiometric_Accuracy:scale_factor = 48.;
         Radiometric_Accuracy:scale_offset = 0.;
Radiometric_Accuracy:units = "K";
                                      float
                              Sun_BT:_FillValue =
Sun_BT(n_snapshots);
             Sun_BT:units = "K";
                                      double
Z_Position(n_snapshots);
Z_Position:_FillValue = 0.f;
                                    Z_Position:units
         int Microseconds(n_snapshots);
= "m" ;
Microseconds:\_Unsigned = "true" \ ;
Microseconds:_FillValue = 0.f;
                               Seconds:_Unsigned =
Seconds(n_snapshots);
                Seconds:_FillValue = 0.f;
"true";
Days(n_snapshots);
                            Days:_FillValue = 0.f;
    int Snapshot_ID_of_Pixel(n_grid_points, n_bt_data);
         Snapshot_ID_of_Pixel:_Unsigned = "true";
Snapshot_ID_of_Pixel:_FillValue = 0.f;
                                           ubyte
Calibration\_Error\_flag(n\_snapshots) \ ;
Calibration_Error_flag:_Unsigned = "true";
Calibration_Error_flag:_FillValue = 0.f;
                                           ubyte
ADF_Error_flag(n_snapshots);
ADF_Error_flag:_Unsigned = "true";
ADF_Error_flag:_FillValue = 0.f;
    short Faraday_Rotation_Angle(n_grid_points, n_bt_data);
Faraday_Rotation_Angle:_FillValue = 0.f;
         Faraday_Rotation_Angle:scale_factor = 0.0054931640625;
         Faraday_Rotation_Angle:scale_offset = 0.;
         Faraday_Rotation_Angle:_Unsigned = "true";
Faraday_Rotation_Angle:units = "deg";
X_Position(n_snapshots);
```



```
X_{position:FillValue = 0.f;
X_Position:units = "m";
TEC(n_snapshots);
         TEC:_FillValue = 0.f;
TEC:units = "TECU";
                          short
Geometric_Rotation_Angle(n_grid_points,
n_bt_data);
         Geometric\_Rotation\_Angle:\_FillValue = 0.f \; ;
         Geometric_Rotation_Angle:scale_factor = 0.0054931640625;
         Geometric_Rotation_Angle:scale_offset = 0.;
         Geometric_Rotation_Angle:_Unsigned = "true";
Geometric_Rotation_Angle:units = "deg";
    float Sun_DEC(n_snapshots);
Sun_DEC:_FillValue = 0.f;
                                   Sun DEC:units =
"deg";
    short Footprint_Axis2(n_grid_points, n_bt_data);
         Footprint_Axis2:_FillValue = 0.f;
         Footprint_Axis2:scale_factor = 0.0007476806640625;
         Footprint_Axis2:scale_offset = 0.;
         Footprint_Axis2:_Unsigned
                                             "true"
Footprint Axis2:units = "km"
                                                  short
Footprint_Axis1(n_grid_points, n_bt_data);
         Footprint_Axis1:_FillValue = 0.f;
         Footprint_Axis1:scale_factor = 0.0007476806640625;
         Footprint_Axis1:scale_offset = 0.;
         Footprint_Axis1:_Unsigned = "true";
Footprint_Axis1:units = "km";
Z_Velocity(n_snapshots);
         Z_Velocity:_FillValue = 0.f;
Z_Velocity:units = "m/s";
    float BT_Value_Real(n_grid_points, n_bt_data);
         BT_Value_Real:_FillValue = -999.f;
BT_Value_Real:units = "K";
Snapshot_OBET(n_snapshots);
Snapshot_OBET:_Unsigned = "true" ;
Snapshot_OBET:_FillValue = 0.f;
BT\_Value\_Imag(n\_grid\_points, n\_bt\_data) \ ;
         BT_Value_Imag:_FillValue = -999.f;
BT_Value_Imag:units = "K";
                                double
Q0(n_snapshots);
                          Q0:_FillValue = 0.f;
             Grid_Point_Latitude(n_grid_points)
    float
Grid_Point_Latitude:_FillValue
Grid_Point_Latitude:units = "deg";
    double Q1(n_snapshots);
Q1:_FillValue = 0.f;
                        double
Q2(n_snapshots);
Q2:_FillValue = 0.f;
                        double
Q3(n\_snapshots);
Q3:_FillValue = 0.f;
    ubyte Software_Error_flag(n_snapshots);
Software_Error_flag:_Unsigned = "true";
Software_Error_flag:_FillValue = 0.f;
Grid_Point_Longitude(n_grid_points);
Grid_Point_Longitude:_FillValue = -999.f;
Grid_Point_Longitude:units = "deg" ;
                                        short
Flags(n_grid_points, n_bt_data);
                  Flags:flag_masks = 1s, 2s, 4s, 8s, 16s, 32s, 128s, 256s, 512s, 1024s, 4096s, 8192s, 64s, 16384s, -32768s, 2048s;
             Flags:flag_values = 1s, 2s, 4s, 8s, 16s, 32s, 128s, 256s, 512s, 1024s, 4096s, 8192s, 64s, 16384s, -32768s, 2048s;
         Flags:flag_meanings = "POL_FLAG_1 POL_FLAG_2 SUN_FOV SUN_GLINT_FOV MOON_FOV
SINGLE_SNAPSHOT SUN_POINT SUN_GLINT_AREA MOON_POINT AF_FOV BORDER_FOV SUN_TAILS RFI_H_POL
RFI_V_POL RFI_2 RF
I_3";
         Flags:_Unsigned = "true";
Flags:\_FillValue = 0.f;
    short BT_Data_Counter(n_grid_points);
BT_Data_Counter:_Unsigned = "true";
BT_Data_Counter:_FillValue = NaNf;
                                         ubyte
Vector_Source(n_snapshots);
                                     Vector\_Source:\_Unsigned = "true" \ ;
Vector_Source:_FillValue = 0.f;
                                   double X_Velocity(n_snapshots);
X_Velocity:_FillValue = 0.f;
                                    X_Velocity:units = "m/s";
short Radiometric_Accuracy_of_Pixel(n_grid_points, n_bt_data);
         Radiometric_Accuracy_of_Pixel:_FillValue = 0.f;
         Radiometric\_Accuracy\_of\_Pixel: scale\_factor = 0.000732421875 \ ;
         Radiometric_Accuracy_of_Pixel:scale_offset = 0.;
```



```
Radiometric_Accuracy_of_Pixel:_Unsigned = "true";
Radiometric_Accuracy_of_Pixel:units = "K";
                                             ubvte X-
Band(n_snapshots);
                           X-Band:_Unsigned = "true";
        X-Band:_FillValue = 0.f;
7.6
       MIR SMUDP2
dimensions:
               n_grid_points = 81759; variables:
                                                   short
N_Sun_FOV(n_grid_points);
N_Sun_FOV:_Unsigned = "true";
N_Sun_FOV:_FillValue = 0.f;
TB_ASL_Theta_B_H(n_grid_points);
TB_ASL_Theta_B_H:_FillValue = -999.f;
TB_ASL_Theta_B_H:units = "K"; flo
TB_ASL_Theta_B_H_DQX(n_grid_points);
TB\_ASL\_Theta\_B\_H\_DQX:\_FillValue = -999.f \ ;
TB\_ASL\_Theta\_B\_H\_DQX:units = "K";
    short N_Wild(n_grid_points);
N_Wild:_Unsigned = "true";
N_Wild:FillValue = 0.f;
    float \ TB\_TOA\_Theta\_B\_V(n\_grid\_points)\ ;
TB\_TOA\_Theta\_B\_V:\_FillValue = -999.f;
TB TOA Theta B V:units = "K";
DGG_Current_Flags(n_grid_points);
        DGG_Current_Flags:flag_masks = 1s, 2s, 4s, 8s, 16s;
                                                                  DGG_Current_Flags:flag_values
= 1s, 2s, 4s, 8s, 16s;
        DGG_Current_Flags:flag_meanings = "FL_CURRENT_TAU_NADIR_LV FL_CURRENT_TAU_NADIR_FO
FL_CURRENT_HR FL_CURRENT_RFI FL_CURRENT_FLOOD";
        DGG_Current_Flags:_Unsigned = "true";
DGG_Current_Flags:_FillValue = 0.f;
                                       float
                            TTH:_FillValue = -
TTH(n\_grid\_points)\ ;
999.f;
    float\ Scattering\_Albedo\_H(n\_grid\_points)\ ;
Scattering_Albedo_H:_FillValue = -999.f;
    short M_AVA(n_grid_points)
M_AVA:_Unsigned
                            "true"
M_AVA:_FillValue = 0.f;
    float TB_TOA_Theta_B_H(n_grid_points);
TB_TOA_Theta_B_H:_FillValue = -999.f;
TB_TOA_Theta_B_H:units = "K"; flo
Scattering_Albedo_H_DQX(n_grid_points);
Scattering_Albedo_H_DQX:_FillValue = -999.f;
                                                 float
Dielect_Const_Non_MD_IM_DQX(n_grid_points);
Dielect_Const_Non_MD_IM_DQX:_FillValue = -999.f;
Dielect_Const_Non_MD_IM_DQX:units = "Fm-1";
Surface_Temperature_DQX(n_grid_points);
Surface_Temperature_DQX:_FillValue = -999.f;
Surface\_Temperature\_DQX:units = "K";
    float Altitude(n_grid_points);
Altitude:_FillValue = -99999.f;
Altitude:units = "m";
Grid_Point_ID(n_grid_points);
Grid_Point_ID:_Unsigned = "true";
Grid Point ID: FillValue = 0.f:
    float TB_TOA_Theta_B_H_DQX(n_grid_points);
TB_TOA_Theta_B_H_DQX:_FillValue = -999.f;
TB_TOA_Theta_B_H_DQX:units = "K";
                                          short
N_AF_FOV(n_grid\_points);
                                   N_AF_FOV:_Unsigned
= "true" ;
                 N_AF_FOV:_FillValue = 0.f;
                               Seconds:_FillValue = NaNf
Seconds(n_grid_points);
        Seconds:_Unsigned = "true";
        Seconds:units = "s";
    short N_Sun_Glint_Area(n_grid_points);
N_Sun_Glint_Area:_Unsigned = "true";
N_Sun_Glint_Area:_FillValue = 0.f;
Dielect_Const_MD_IM_DQX(n_grid_points);
Dielect_Const_MD_IM_DQX:_FillValue = -999.f;
Dielect_Const_MD_IM_DQX:units = "Fm-1";
Confidence_Flags(n_grid_points);
        Confidence_Flags:flag_masks = 2s, 4s, 16s, 32s, 64s, 128s, 256s;
                                                                             Confidence Flags:flag values =
2s, 4s, 16s, 32s, 64s, 128s, 256s;
        Confidence_Flags:flag_meanings = "FL_RFI_PRONE_H FL_RFI_PRONE_V FL_NO_PROD FL_RANGE FL_DQX
FL_CHI2_P FL_FARADAY_ROTATION_ANGLE";
        Confidence_Flags:_Unsigned = "true";
Confidence_Flags:_FillValue = 0.f;
```



```
N_Software_Error(n_grid_points);
N_Software_Error:_Unsigned = "true";
N_Software_Error:_FillValue = 0.f;
                                     short
N_Sun_Tails(n_grid_points);
N_Sun_Tails:_Unsigned = "true";
N_Sun_Tails:_FillValue = 0.f;
Soil_Moisture(n_grid_points);
Soil_Moisture:_FillValue = -999.f;
Soil_Moisture:units = "m3 m-3";
Soil_Moisture_DQX(n_grid_points);
Soil_Moisture_DQX:_FillValue = -999.f;
Soil_Moisture_DQX:units = "m3 m-3";
                                        short
N\_RFI\_Mitigations(n\_grid\_points)\ ;
N_RFI_Mitigations:_Unsigned = "true";
N_RFI_Mitigations:_FillValue = 0.f;
Science_Flags(n_grid_points);
        Science_Flags:flag_masks = 1s, 2s, 4s, 8s, 16s, 32s, 64s, 128s, 256s, 512s, 1024s, 2048s, 4096s, 8192s, 16384s, -
Science_Flags:flag_values = 1s, 2s, 4s, 8s, 16s, 32s, 64s, 128s, 256s, 512s, 1024s, 2048s, 4096s, 8192s, 16384s, 32768s, 0s, 0s, 0s,
Science_Flags:flag_meanings = "FL_NON_NOM FL_SCENE_T FL_BARREN FL_TOPO_S FL_TOPO_M FL_OW
FL SNOW MIX FL SNOW WET FL SNOW DRY FL FOREST FL NOMINAL FL FROST FL ICE FL WETLANDS
FL FLOOD P
ROB FL_URBAN_LOW FL_URBAN_HIGH FL_SAND FL_SEA_ICE FL_COAST FL_OCCUR_T FL_LITTER FL_PR
FL_INTERCEP FL_EXTERNAL FL_RAIN FL_TEC FL_TAU_FO FL_WINTER_FOREST FL_DUAL_RETR_FNO_FFO";
        Science_Flags:_Unsigned = "true" ;
Science_Flags:_FillValue = 0.f;
    float Dielect_Const_MD_RE_DQX(n_grid_points);
Dielect_Const_MD_RE_DQX:_FillValue = -999.f;
                                                      Dielect_Const_MD_RE_DQX:units =
"Fm-1";
    short\ N\_Sky(n\_grid\_points)\ ;
N_Sky:_Unsigned = "true";
N_Sky:_FillValue = 0.f;
DIFF_Albedos(n_grid_points);
DIFF_Albedos:_FillValue = -999.f;
                                    ubvte
Chi_2(n_grid_points);
        Chi_2:scale_factor = 0.207843149546534;
        Chi_2:scale_offset = 0.;
        Chi_2:_Unsigned = "true";
Chi 2: FillValue = 0.f:
    float \ TB\_ASL\_Theta\_B\_V(n\_grid\_points)\ ;
TB_ASL_Theta_B_V:_FillValue = -999.f;
TB_ASL_Theta_B_V:units = "K"; float
Longitude(n_grid_points);
Longitude:_FillValue = -999.f;
Longitude:units = "deg";
    short N_Point_Source_RFI(n_grid_points);
N_Point_Source_RFI:_Unsigned = "true";
N_Point_Source_RFI:_FillValue = 0.f;
Processing_Flags(n_grid_points);
        Processing_Flags:flag_masks = 1s, 2s, 4s, 8s;
        Processing_Flags:flag_values = 1s, 2s, 4s, 8s;
        Processing_Flags:flag_meanings = "FL_R4 FL_R3 FL_R2 FL_MD_A";
        Processing Flags: Unsigned = "true";
Processing_Flags:_FillValue = 0.f;
Optical_Thickness_Nad(n_grid_points);
Optical_Thickness_Nad:_FillValue = -999.f;
Optical_Thickness_Nad:units = "Np";
N_Tails_Point_Source_RFI(n_grid_points);
N_Tails_Point_Source_RFI:_Unsigned = "true";
N_Tails_Point_Source_RFI:_FillValue = 0.f;
    short
            N\_X\_Band(n\_grid\_points)
N_X_Band:_Unsigned
                              "true"
N_X_Band:_FillValue = 0.f;
    float Surface_Temperature(n_grid_points);
Surface_Temperature:_FillValue = -999.f;
Surface_Temperature:units = "K";
N_RFI_Y(n_grid_points);
N_RFI_Y:_Unsigned = "true";
N_RFI_Y:_FillValue = 0.f;
    float\ Optical\_Thickness\_Nad\_DQX(n\_grid\_points)\ ;
Optical_Thickness_Nad_DQX:_FillValue = -999.f;
Optical\_Thickness\_Nad\_DQX:units = "Np" \; ;
                                N_RFI_X:_Unsigned =
N_RFI_X(n_grid_points);
               N_RFI_X:_FillValue = 0.f;
Chi\_2\_P(n\_grid\_points)\ ;
```



```
Chi_2_P:scale_factor = 0.00392156885936856;
         Chi_2_P:scale\_offset = 0.;
         Chi_2_P:_Unsigned = "true";
Chi_2_P:_FillValue = 0.f;
            DIFF_Albedos_DQX(n_grid_points)
    float
DIFF_Albedos_DQX:_FillValue = -999.f;
N_Calibration_Error(n_grid_points)
N_Calibration_Error:_Unsigned
                                        "true"
N_Calibration_Error:_FillValue = 0.f;
                                              float
Dielect_Const_Non_MD_IM(n_grid_points)
Dielect_Const_Non_MD_IM:_FillValue = -999.f
Dielect_Const_Non_MD_IM:units = "Fm-1";
                                              float
Dielect_Const_Non_MD_RE(n_grid_points)
Dielect_Const_Non_MD_RE:_FillValue = -999.f
Dielect_Const_Non_MD_RE:units = "Fm-1";
RTT_DQX(n_grid_points)
RTT DOX: FillValue = -999.f;
                                              float
TTH_DQX(n_grid_points)
TTH_DQX:_FillValue = -999.f ;
                                                int
Microseconds(n_grid_points)
Microseconds:_FillValue = NaNf;
         Microseconds:_Unsigned = "true";
Microseconds:units = "?s";
Dielect_Const_MD_IM(n_grid_points);
Dielect_Const_MD_IM:_FillValue = -999.f;
Dielect_Const_MD_IM:units = "Fm-1";
S_Tree_1(n_grid_points);
                                 S_Tree_1:_Unsigned
                 S_Tree_1:_FillValue = 0.f;
= "true" ;
Days(n_grid_points);
                            Days:_FillValue = NaNf
          Days:units = "days";
                                  ubyte
S\_Tree\_2(n\_grid\_points);
                                 S_Tree_2:_Unsigned
                 S_Tree_2:_FillValue = 0.f;
= "true" ;
                                               float
RTT(n_grid_points);
                            RTT:_FillValue = -999.f;
float Latitude(n_grid_points);
Latitude:_FillValue = -999.f;
                                    Latitude: units = \\
"deg";
           short X_Swath(n_grid_points);
X_Swath:_FillValue = 0.f;
         X_Swath:scale_factor = 0.0320444367825985;
         X_Swath:scale\_offset = 0.;
X_Swath:units = "km";
Roughness_Param_DQX(n_grid_points);
Roughness\_Param\_DQX:\_FillValue = -999.f \; ; \\
Roughness_Param_DQX:units = "K";
Roughness_Param(n_grid_points);
Roughness_Param:_FillValue = -999.f;
Roughness\_Param:units = "K" \; ;
                                ubyte
                             GQX:_Unsigned = "true";
GQX(n_grid_points);
GQX:_FillValue = 0.f;
                          ubyte RFI_Prob(n_grid_points)
         RFI_Prob:scale_factor = 0.00499999988824129;
         RFI_Prob:scale_offset = 0.;
         RFI_Prob:_Unsigned = "true";
RFI_Prob:_FillValue = 0.f;
                              float
HR\_Cur\_DQX(n\_grid\_points)\ ;
HR_Cur_DQX:_FillValue = -999.f;
                                      short
N ADF Error(n grid points);
N_ADF_Error:\_Unsigned = "true";
N_ADF_Error:_FillValue = 0.f;
                                  short
N_Strong_RFI(n_grid_points);
N_Strong_RFI:_Unsigned = "true";
N_Strong_RFI:_FillValue = 0.f;
                                  short
N_Instrument_Error(n_grid_points);
N_Instrument_Error:_Unsigned = "true" :
N_Instrument_Error:_FillValue = 0.f; flo
TB_TOA_Theta_B_V_DQX(n_grid_points);
TB_TOA_Theta_B_V_DQX:_FillValue = -999.f;
TB_TOA_Theta_B_V_DQX:units = "K";
    float AFP(n_grid_points);
                                      AFP:_FillValue = -
999.f;
               AFP:units = "km";
                                      short
M_AVA0(n_grid_points);
                                  M_AVA0:_Unsigned =
               M_AVA0:_FillValue = 0.f;
"true";
Dielect_Const_MD_RE(n_grid_points);
Dielect_Const_MD_RE:_FillValue = -999.f;
Dielect_Const_MD_RE:units = "Fm-1";
TB\_ASL\_Theta\_B\_V\_DQX(n\_grid\_points)\ ;
TB_ASL_Theta_B_V_DQX:_FillValue = -999.f;
TB_ASL_Theta_B_V_DQX:units = "K";
```



Tau_Cur_DQX(n_grid_points);
Tau_Cur_DQX:_FillValue = -999.f; float
Dielect_Const_Non_MD_RE_DQX(n_grid_points);
Dielect_Const_Non_MD_RE_DQX:_FillValue = -999.f;
Dielect_Const_Non_MD_RE_DQX:units = "Fm-1";