



CSCI 3104

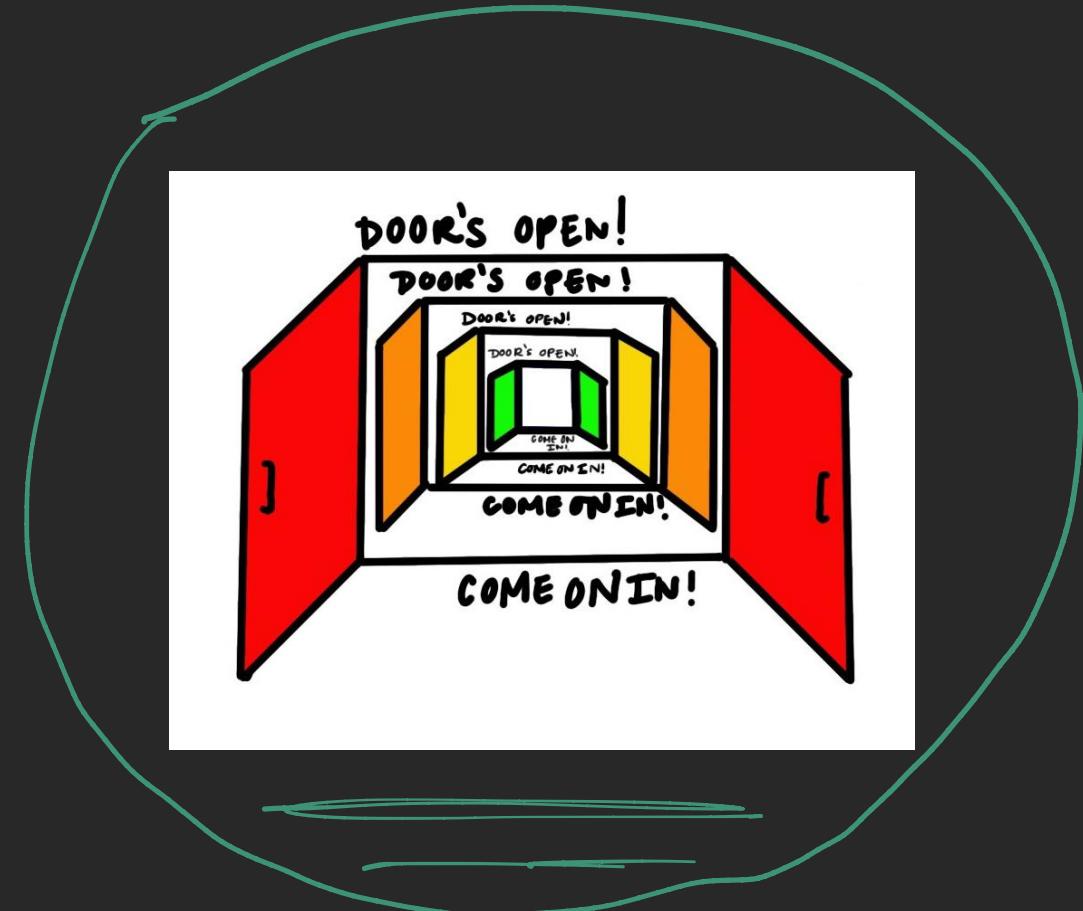
Lecture 4: Divide and Conquer Algorithms

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Lecture Outline

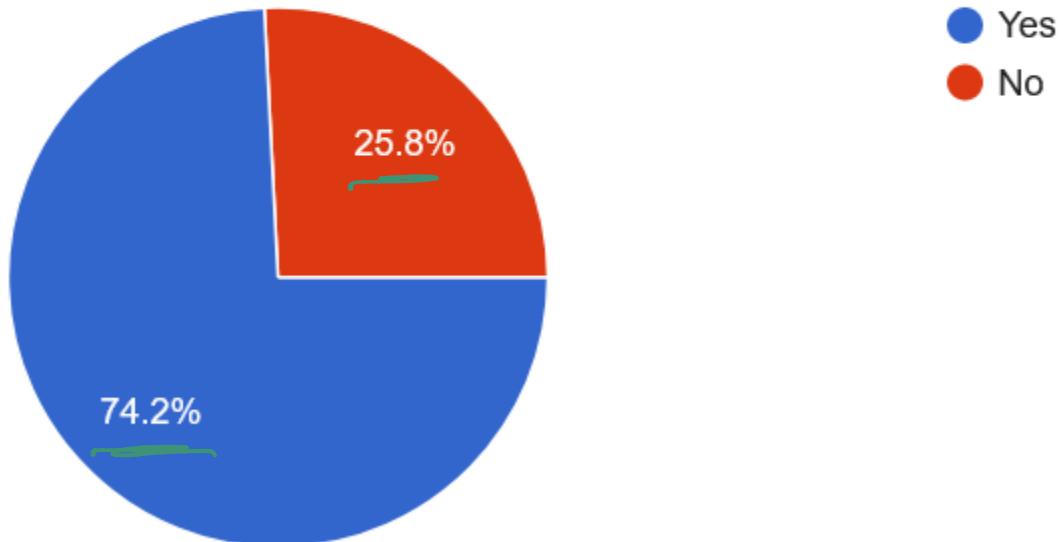
- Poll/Admin
- Divide and Conquer Algorithms
- Recurrence Relations
- Quicksort: Introduction
- Correctness
- Runtime



Poll Review

Have you started reading the book?

31 responses

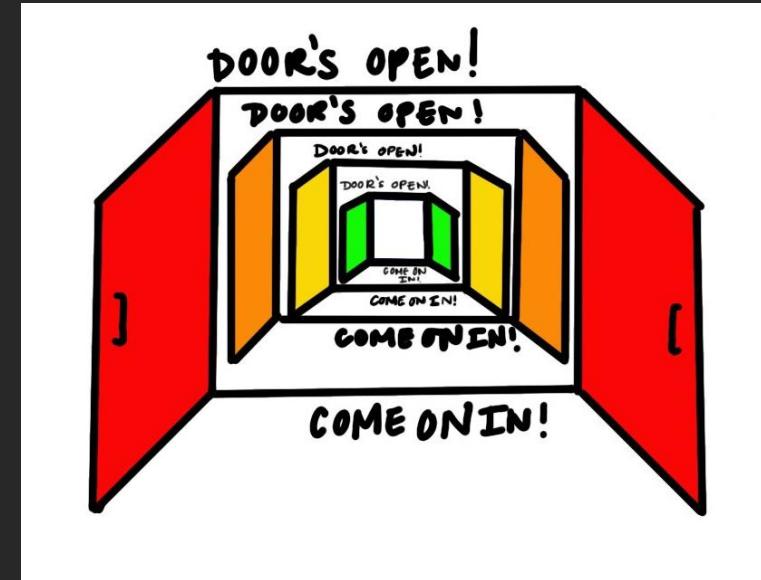


Administrative

- Reading list is on Canvas!
- Homework 1A is due on Tuesday
- Reading for this this and next lecture
 - Chapter 4 for Divide & Conquer
 - Chapter 7 for Quicksort**
- Daily Practice Problem added to lectures

Lecture Outline

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Divide and Conquer Algorithms

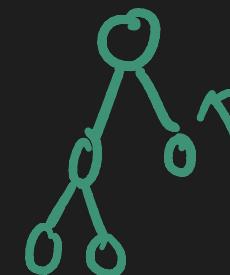
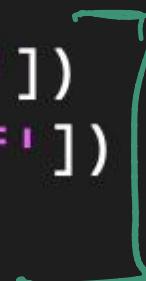
- Three parts:
 - Divide – break problem down
 - Conquer – if small or trivial then solve, else
 - Combine – small solutions into large solution
- Divide and Conquer Algorithm Examples
 - Quicksort - Today! Chapter 7
 - Merge Sort - On your own Chapter 4
 - Binary Search
 - Strassen's Algorithm – Matrix Multiplication



The Structure of Divide and Conquer

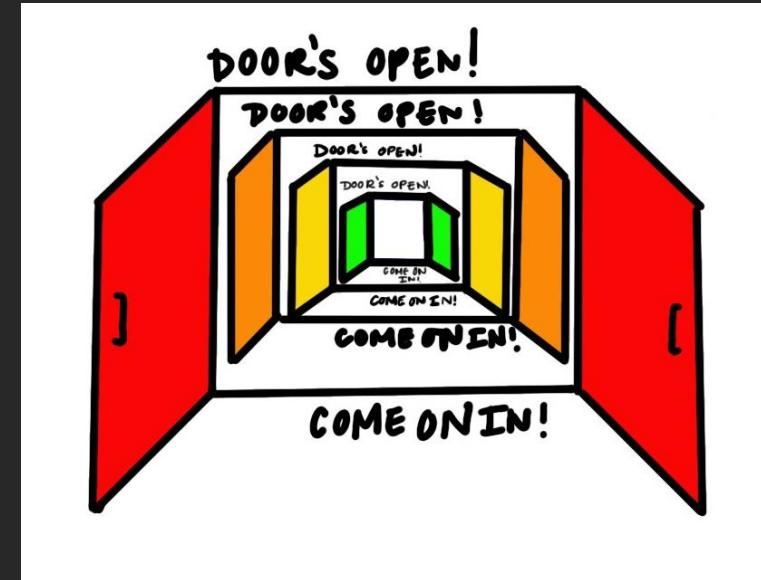
Divide and conquer is a recursive approach, and most divide and conquer algorithms have the following structure:

```
def fun(n):
    #base case if n is small or can easily be solved
    if (n==1 or n=='trivial'):] base case
        # solve and return
    else:
        a = fun(n['first half'])
        b = fun(n['second half'])
        ab = combine(a, b)
    return ab
```



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Recurrence Relations

General form for asymptotic analysis:

$$\underline{T(n)} = \underline{a} \underline{T(g[n])} + \underline{f(n)}$$

$T(n)$ = runtime
 a = # of sub problems

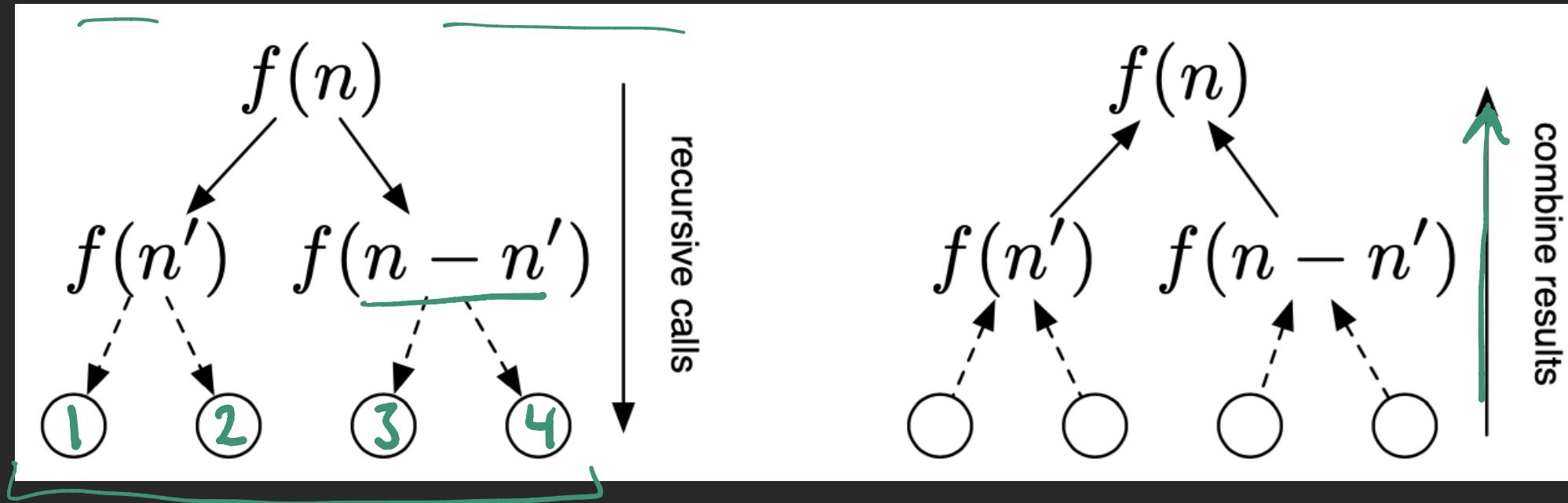
$g[n]$ = how we split up
our input

$f(n)$ = cost to split
and join

- Unrolling
- Master Method/Theorem
- Recurrence Trees
- See chapter 4.2!

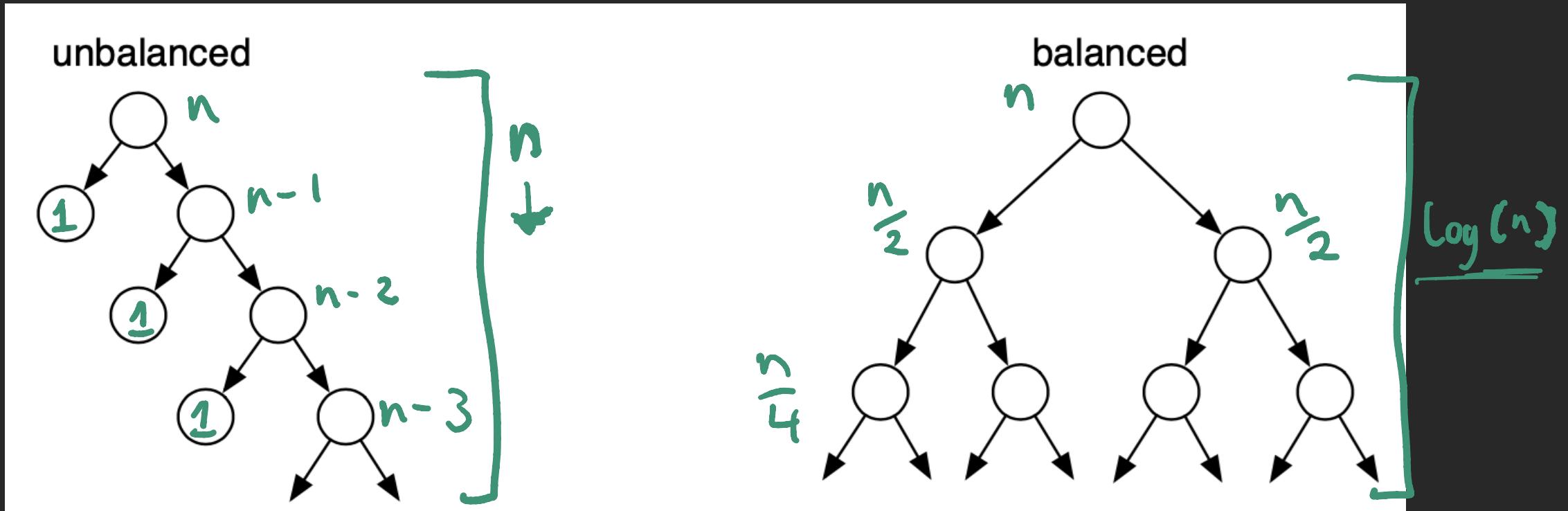
$n = [1, 2, 3, 4]$

Divide and Conquer

 $n' = [1] \quad n - n' = [2, 3, 4]$ 

$$T(n) = a T(g[n]) + f(n)$$

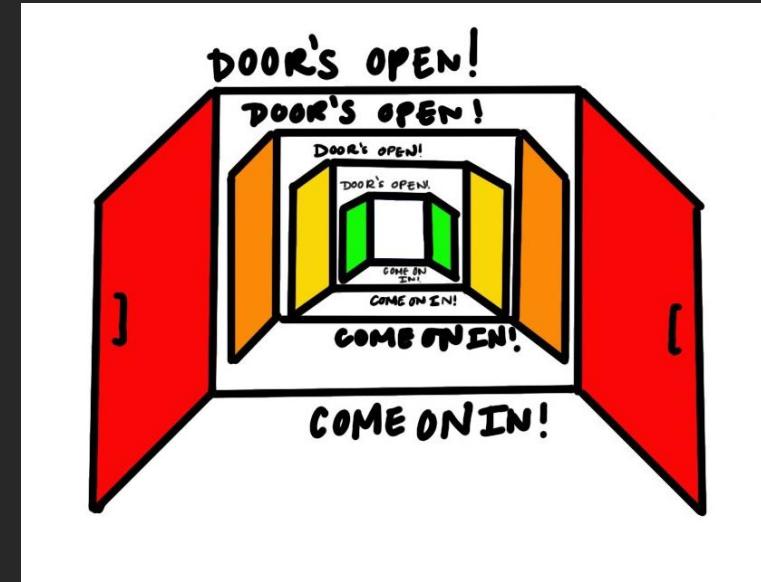
Divide and Conquer: Tree Depth



$$T(n) = a T(g[n]) + f(n)$$

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Quicksort: Recursive Sorting

- Quicksort and Mergesort are sorting algorithms that employ recursion and are less time complex than other well known sorting algorithms (Insertion, Bubble)
 - The average case for Quicksort is $O(n \log n)$
 - Randomized version of Quicksort is as fast as Mergesort
 - Worst case runtime Big-theta(n^2)

$$\Theta(n^2)$$

$$\Theta(n \log n) -$$

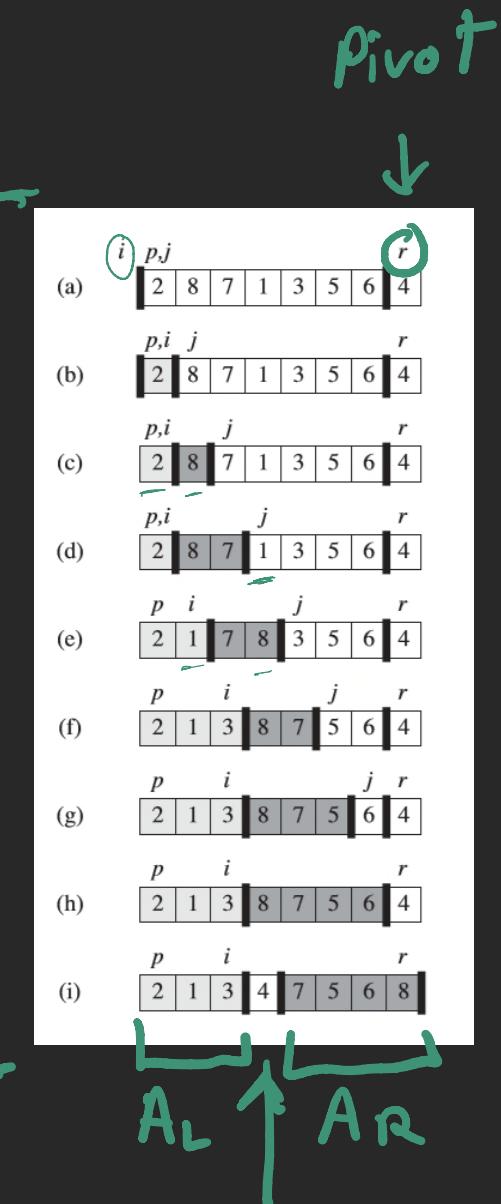
A The Steps of Quicksort

- Divide: pick a pivot r . $A_L \leq r, A_R > r$

- Conquer: call quick sort on A_L, A_R

or if small don't do anything

- Combine: In place Algo. don't do anything.



Looking Closer: Pseudocode

$A = [\cdot \dots \cdot]$

$p = 1$

$r = A.\text{len}$

```
// Precondition: A is the array to be sorted, p>=1; //  
// r is <= the size of A //  
// Postcondition: A[p..r] is in sorted order //
```

```
Quicksort(A,p,r) {  
    if (p<r){  
        q = Partition(A,p,r)  
        Quicksort(A,p,q-1) left  
        Quicksort(A,q+1,r) right  
    }  
}
```

```
//Precondition: A[p..r] is the array to be partitioned, p>=1 and r<= size of A,  
//A[r] is the pivot element  
//Postcondition: Let A' be the array A after the function is run. Then A'[p..r]  
contains the same elements as A[p..r]. Further, all elements in  
A'[p..res-1] are <= A[r], A'[res] = A[r], and all elements in  
A'[res+1..r] are > A[r]
```

```
Partition(A,p,r) {  
    x = A[r] pivot  
    i = p-1 ←  
    → for (j=p; j<=r-1; j++) {  
        if A[j]<=x {  
            i++  
            exchange(A[i],A[j])  
        }  
    }  
    exchange(A[i+1],A[r])  
    return i+1  
}
```

$$f(n) = O(n)$$

move to left
pivot in middle

$$T(n) = aT(g[n]) + f(n)$$

Example!

1 2 3 4

$A = [2, 6, 4, 1, 5, 3]$

1
3
↓

[2, 1]

s=1 e=2

1
1
↓

[2]

[6, 5, 4]

s=4 e=6

4
↓

[5, 6] →

1
6
↓
[5]

p = first element

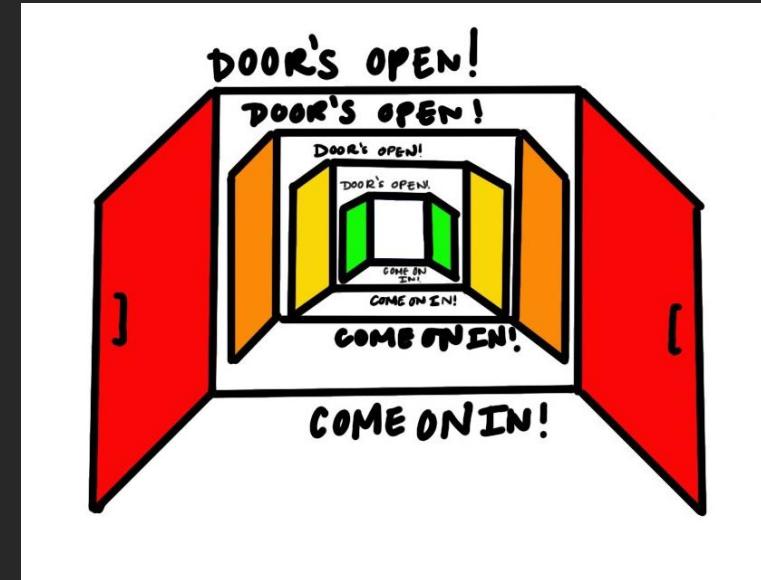
r = A.len

```
Quicksort(A, p, r) {  
    if (p < r){  
        q = Partition(A, p, r)  
        Quicksort(A, p, q-1)  
        Quicksort(A, q+1, r)  
    }  
}
```

```
Partition(A, p, r) {  
    x = A[r]  
    i = p-1  
    for (j=p; j <= r-1; j++) {  
        if A[j] <= x {  
            i++  
            exchange(A[i], A[j])  
        }  
    }  
    exchange(A[i+1], A[r])  
    return i+1  
}
```

Lecture Outline

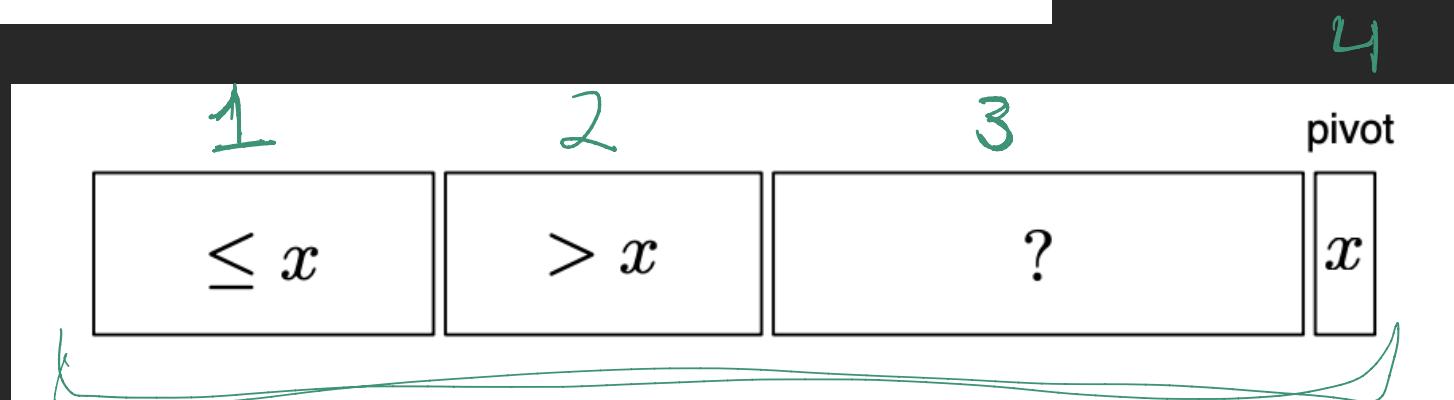
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Loop invariants: Correctness

- If an algorithm is correct, it yields the proper output on all possible inputs
 - Proving the correctness of Quicksort

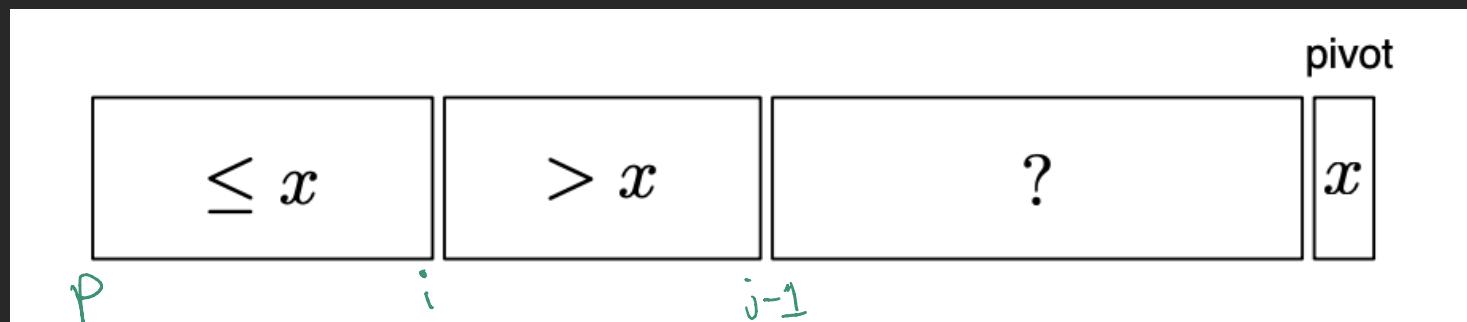
- Region 1: values that are $\leq \underline{x}$ (between locations p and i)
- Region 2: values that are $> x$ (between locations $i + 1$ and $j - 1$)
- Region 3: unprocessed values (between locations j and $r - 1$)
- Region 4: the value x (location r)



Loop invariants: Correctness

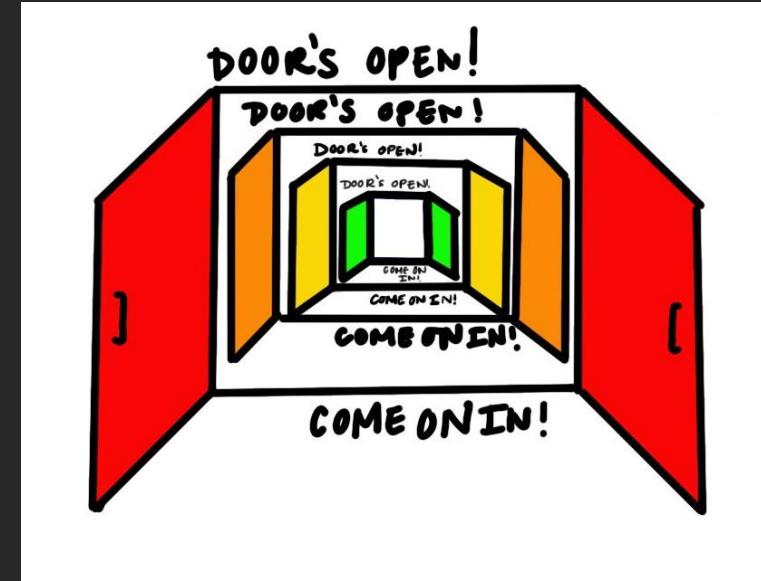
1. If $p \leq k \leq i$ then $\underline{A[k] \leq x}$
2. If $\underline{i + 1 \leq k \leq j - 1}$ then $\underline{A[k] > x}$
3. If $k = r$ then $\underline{A[k] = x}$

Chapter 7.1 page: 173



Lecture Outline

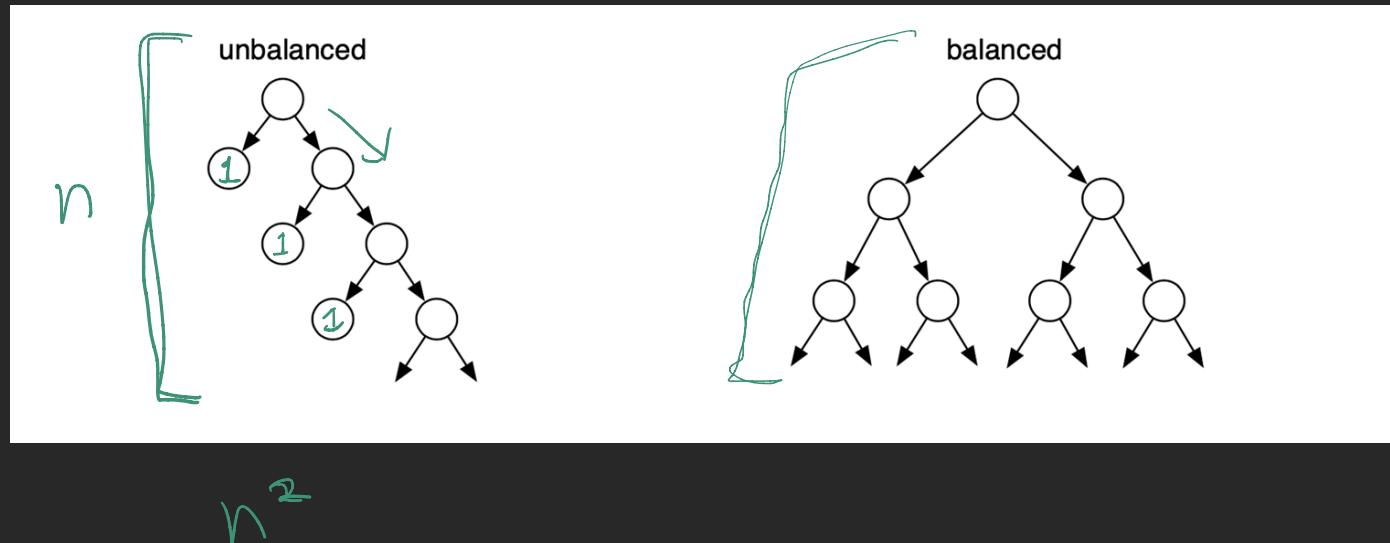
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Running Time: Computation Tree

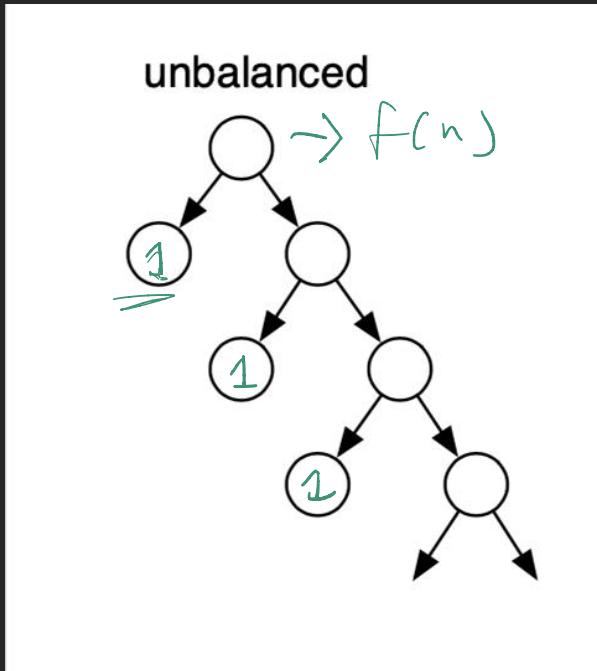
[1, 2, 3, 4]

- Analyzing time complexity using computation trees



```
Partition(A,p,r) {  
    x = A[r] ←  
    i = p-1  
    for (j=p; j<=r-1; j++) {  
        if A[j]<=x {  
            i++  
            exchange(A[i],A[j])  
        }  
    }  
    exchange(A[i+1],A[r])  
    return i+1  
}
```

Analysis: Worst Case



$$T(n) = a T(g[n]) + f(n)$$

$$A = [1, \dots]$$

$$g[n] = n - b, b \text{ is a constant}$$

$$b = O(1)$$

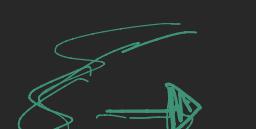
$$T(n) = a T(g[n]) + \Theta(n)$$

$$T(n) = T(n-1) + \cancel{\Theta(1)} + \Theta(n)$$

$$T(n) = T(n-2) + \cancel{\Theta(n-1)} + \Theta(n)$$

\vdots

$$T(n) = \Theta(1) + \dots \Theta(n-2) + \Theta(n-1) + \Theta(n)$$



$$T(n) = \sum_{i=1}^n \Theta(i) = \frac{n(n+1)}{2}$$

$$T(n) = \Theta(n^2)$$

$$n^{\log_2(4)} = n^2$$

Chapter 4.3

Analysis: Best Case/Master Theorem

$$n^2 = n$$

$$n^2 = \cancel{n^{\log_b a}} \quad \begin{array}{l} a=2 \\ b=2 \quad a=2 \end{array}$$

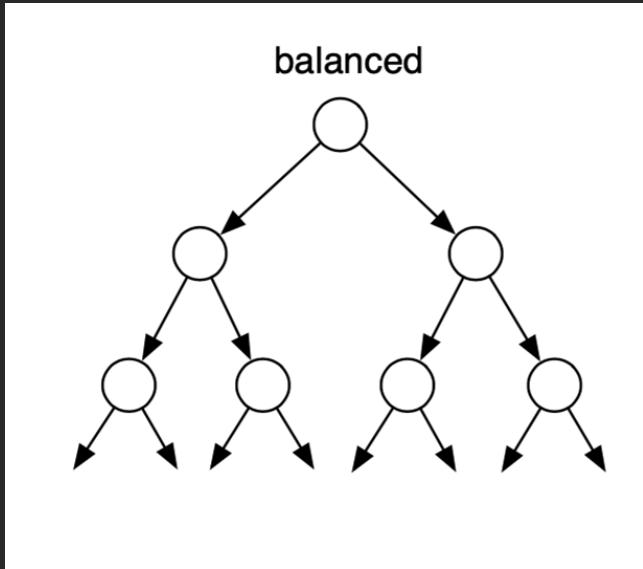
Master theorem. Let $a \geq 1$ and $b > 1$ be constants, let $f(n)$ be a function and let $T(n)$ be defined on the non-negative integers by the recurrence,

$$\underbrace{T(n) = aT(n/b) + f(n)}_{},$$

where we interpret n/b to mean either $\lfloor n/b \rfloor$ or $\lceil n/b \rceil$. Then $T(n)$ can be bounded asymptotically as follows:

- 1. If $f(n) = \cancel{O(n^{\log_b a - \epsilon})}$ for some constant $\epsilon > 0$, then $T(n) = \Theta(n^{\log_b a})$
- 2. If $f(n) = \cancel{\Theta(n^{\log_b a})}$, then $T(n) = \Theta(n^{\log_b a} \log n)$
- 3. If $f(n) = \Omega(n^{\log_b a + \epsilon})$ for some constant $\epsilon > 0$, and if $a f(n/b) \leq c f(n)$ for some constant $c < 1$ and all sufficiently large n , then $T(n) = \Theta(f(n))$. \square

Analysis: Best Case/Master Theorem



$$\underline{g[n]} = \frac{n}{b}, \underline{b=2}, \underline{a=2}$$

$$f(n) = \Theta\left(n^{\log_b a}\right)$$

$$n^{\log_2 2} = n$$

$$T(n) = \underline{a} T(g[n]) + \underline{f(n)}$$

$$f(n) = n$$

$$f(n) = \Theta(n)$$

$$T(n) = n \log(n)$$