



**BITS** Pilani  
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## PROBABILISTIC GRAPHICAL MODEL SESSION # 6 : UNDIRECTED GRAPHICAL MODEL

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The instructor is gratefully acknowledging  
the authors who made their course  
materials freely available online.

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## 1 UNDIRECTED GRAPHICAL MODELS

## SCENARIO 1

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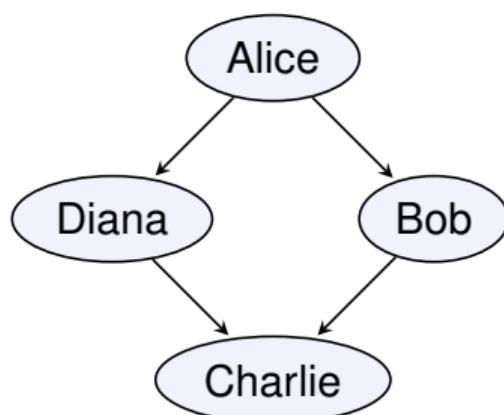
- Four people; Alice, Bob, Charlie, Diana; go out for dinner in different groups of two.
- Alice goes out with Bob, Bob goes out with Charlie, Charlie with Diana, and Diana with Alice.
- Bob doesn't go with Diana, and Alice doesn't go with Charlie.
- Let's think about the probability of them ordering food of the same cuisine.
- From our social experience, we know that people interacting with each other may influence each others choice of food.
- Alice can influence Bob's choice of cuisine. Bob can influence Charlie's choice of cuisine. But Alice and Charlie won't agree.
- How can we represent this in Bayesian Network?

$$Alice \perp\!\!\!\perp Charlie | Bob, Diana$$
$$Bob \perp\!\!\!\perp Diana | Alice, Charlie$$

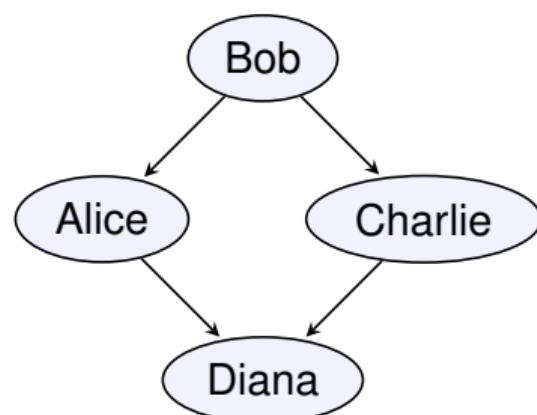
# SCENARIO 1

$$Alice \perp Charlie \mid Bob, Diana \quad (1)$$

$$Bob \perp Diana \mid Alice, Charlie \quad (2)$$



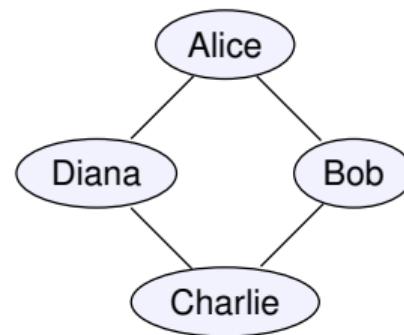
Satisfies Eq(1) but not Eqn(2).



Satisfies Eq(2) but not Eqn(1).

# SCENARIO 1

- Directed models have a limitation that they cannot represent symmetric interactions.
- Undirected graphical model to encode influence flows in both directions.
- Example:

$$\begin{aligned}Alice &\perp\!\!\!\perp Charlie \mid Bob, Diana \\Bob &\perp\!\!\!\perp Diana \mid Alice, Charlie\end{aligned}$$


# MARKOV NETWORK

## DEFINITION

Markov network is an undirected graph, where

- the nodes represent the random variables and
  - the dependencies or direct probabilistic interaction between these random variables are represented with undirected edges.
- 
- No parent-child relationship.
  - So we do not use CPD.
  - Use **factor** to represent how likely it is for some states of a variable to agree with the states of other variables.

# PARAMETERIZING MARKOV NETWORK

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- Markov Networks are parameterized using factors.
- Factors help in symmetric parameterization of random variables.
- Factors capture the affinities between related variables.
- Factors do not represent the probability.
- Factors are not constrained to sum up to 1 or to be in the range [0,1].
- The parameterization of the Markov network defines the local interactions between directly related variables.
- The scope of a factor to be the set of random variables over which it is defined.

# FACTOR

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- A **factor**  $\Phi$  is a function or a table that maps a set of random variables to a real value.

$$\Phi : Val(X_1, \dots, X_n) \rightarrow \mathbb{R} \quad (3)$$

- The argument of the factor is called **scope** of the factor.

$$Scope : \{X_1, \dots, X_n\} \quad (4)$$

- Factors are building blocks used for defining high dimensional spaces and distributions.
- Factors are used to define an exponentially large probability distribution of  $N$  random variables.
- Factors are manipulated in the same way as probability distributions.

# OPERATIONS ON FACTORS

## ① Factor Product

- ▶ **Factor product** refers to the product of factors  $\phi_1$  with a scope  $X$  and  $\phi_2$  with scope  $Y$  to produce a factor  $\phi_3$  with a scope  $X \cup Y$ .

## ② Factor Marginalization

- ▶ **Marginalize a factor  $\phi$**  whose scope is  $W$  with respect to a set of random variables  $X$ , sum out all the entries of  $X$ , to reduce its scope to  $\{W - X\}$ .

## ③ Factor Reduction

- ▶ **Reduction of a factor  $\phi$**  whose scope is  $W$  to the context  $X = x^i$  means removing all the entries from the factor where  $X = x^i$ . This reduces the scope to  $\{W - X\}$ .

# 1. FACTOR PRODUCT

- Factor product is the cross product of two factors.

A	B	$\Phi_1(A, B)$	B	C	$\Phi_2(B, C)$	A	B	C	$\Phi_3(A, B, C) = \Phi_1 * \Phi_2$
$a^1$	$b^1$	0.5	$b^1$	$c^1$	0.5	$a^1$	$b^1$	$c^1$	$0.5 * 0.5 = 0.25$
$a^1$	$b^2$	0.8	$b^1$	$c^2$	0.7	$a^1$	$b^1$	$c^2$	$0.5 * 0.7 = 0.35$
$a^2$	$b^1$	0.2	$b^2$	$c^1$	0.1	$a^1$	$b^2$	$c^1$	$0.8 * 0.1 = 0.08$
$a^2$	$b^2$	0	$b^2$	$c^2$	0.2	$a^1$	$b^2$	$c^2$	$0.8 * 0.2 = 0.16$
						$a^2$	$b^1$	$c^1$	$0.2 * 0.5 = 0.25$
						$a^2$	$b^1$	$c^2$	$0.2 * 0.7 = 0.35$
						$a^2$	$b^2$	$c^1$	$0 * 0.1 = 0$
						$a^2$	$b^2$	$c^2$	$0 * 0.2 = 0$

## 2. FACTOR MARGINALIZATION

- Remove one random variable.

A	B	C	$\Phi_1(A, B, C)$		
$a^1$	$b^1$	$c^1$	0.25		
$a^1$	$b^1$	$c^2$	0.35		$\Phi_2(A, C)$ marginalized on $B$
$a^1$	$b^2$	$c^1$	0.08	$a^1$	$0.25 + 0.08 = 0.33$
$a^1$	$b^2$	$c^2$	0.16	$a^1$	$0.35 + 0.16 = 0.51$
$a^2$	$b^1$	$c^1$	0.25	$a^2$	$0.25 + 0 = 0.25$
$a^2$	$b^1$	$c^2$	0.35	$a^2$	$0.35 + 0 = 0.35$
$a^2$	$b^2$	$c^1$	0		
$a^2$	$b^2$	$c^2$	0		

### 3. FACTOR REDUCTION

- Extract only one random variable.
- Observe  $C = c^1$ .

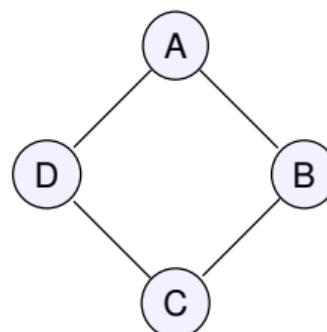
A	B	C	$\Phi_1(A, B, C)$
$a^1$	$b^1$	$c^1$	0.25
$a^1$	$b^1$	$c^2$	0.35
$a^1$	$b^2$	$c^1$	0.08
$a^1$	$b^2$	$c^2$	0.16
$a^2$	$b^1$	$c^1$	0.25
$a^2$	$b^1$	$c^2$	0.35
$a^2$	$b^2$	$c^1$	0
$a^2$	$b^2$	$c^2$	0

A	B	C	$\Phi_1(A, B, c^1)$
$a^1$	$b^1$	$c^1$	0.25
$a^1$	$b^2$	$c^1$	0.08
$a^2$	$b^1$	$c^1$	0.25
$a^2$	$b^2$	$c^1$	0

# FACTOR

$D$	$A$	$\phi(D, A)$
$d^0$	$a^0$	100
$d^0$	$a^1$	1
$d^1$	$a^0$	1
$d^1$	$a^1$	100



$A$	$B$	$\phi(A, B)$
$a^0$	$b^0$	90
$a^0$	$b^1$	5
$a^1$	$b^0$	1
$a^1$	$b^1$	10

$C$	$D$	$\phi(C, D)$
$c^0$	$d^0$	1
$c^0$	$d^1$	100
$c^1$	$d^0$	100
$c^1$	$d^1$	1

$B$	$C$	$\phi(B, C)$
$b^0$	$c^0$	100
$b^0$	$c^1$	1
$b^1$	$c^0$	1
$b^1$	$c^1$	100

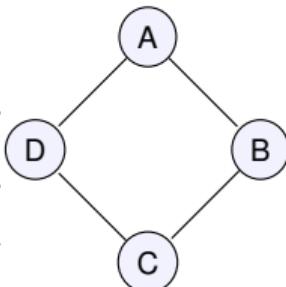
# QUERIES USING FACTORS

- Compute the probability corresponding to  $a^1, b^1, c^0, d^1$ .

$$\begin{aligned}\tilde{P}(a^1, b^1, c^0, d^1) &= \phi_1(a^1, b^1) \times \phi_2(b^1, c^0) \times \phi_3(c^0, d^1) \times \phi_4(d^1, a^1) \\ &= 10 * 1 * 100 * 100 = 700,000\end{aligned}$$

# FACTOR PRODUCT

D	A	$\phi_4(D, A)$
$d^0$	$a^0$	80
$d^0$	$a^1$	60
$d^1$	$a^0$	20
$d^1$	$a^1$	10



C	D	$\phi_3(C, D)$
$c^0$	$d^0$	10
$c^0$	$d^1$	1
$c^1$	$d^0$	100
$c^1$	$d^1$	90

A	B	$\phi_1(A, B)$
$a^0$	$b^0$	90
$a^0$	$b^1$	100
$a^1$	$b^0$	1
$a^1$	$b^1$	10

B	C	$\phi_2(B, C)$
$b^0$	$c^0$	10
$b^0$	$c^1$	80
$b^1$	$c^0$	70
$b^1$	$c^1$	30

A	B	C	D	$\tilde{P}(A, B, C, D) = \Phi(A, B, C, D)$
$a^0$	$b^0$	$c^0$	$d^0$	$90 \cdot 10 \cdot 10 \cdot 80 = 720,000$
$a^0$	$b^0$	$c^0$	$d^1$	$90 \cdot 10 \cdot 1 \cdot 20 = 18,000$
$a^0$	$b^0$	$c^1$	$d^0$	$90 \cdot 80 \cdot 100 \cdot 80 = 57600,000$
$a^0$	$b^0$	$c^1$	$d^1$	$90 \cdot 80 \cdot 90 \cdot 20 = 12960,000$
$a^0$	$b^1$	$c^0$	$d^0$	$100 \cdot 70 \cdot 10 \cdot 80 = 5600,000$
$a^0$	$b^1$	$c^0$	$d^1$	$100 \cdot 70 \cdot 1 \cdot 20 = 140,000$
$a^0$	$b^1$	$c^1$	$d^0$	$100 \cdot 30 \cdot 100 \cdot 80 = 24000,000$
$a^0$	$b^1$	$c^1$	$d^1$	$100 \cdot 30 \cdot 90 \cdot 20 = 5400,000$
$a^1$	$b^0$	$c^0$	$d^0$	$1 \cdot 10 \cdot 10 \cdot 60 = 6,000$
$a^1$	$b^0$	$c^0$	$d^1$	$1 \cdot 10 \cdot 1 \cdot 10 = 100$
$a^1$	$b^0$	$c^1$	$d^0$	$1 \cdot 80 \cdot 100 \cdot 60 = 480,000$
$a^1$	$b^0$	$c^1$	$d^1$	$1 \cdot 80 \cdot 90 \cdot 10 = 72,000$
$a^1$	$b^1$	$c^0$	$d^0$	$10 \cdot 70 \cdot 10 \cdot 60 = 420,000$
$a^1$	$b^1$	$c^0$	$d^1$	$10 \cdot 70 \cdot 1 \cdot 10 = 70,000$
$a^1$	$b^1$	$c^1$	$d^0$	$10 \cdot 30 \cdot 100 \cdot 60 = 1800,000$
$a^1$	$b^1$	$c^1$	$d^1$	$10 \cdot 30 \cdot 90 \cdot 10 = 270,000$

# FACTOR PRODUCT

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- Factor Product

$$\tilde{P}(A, B, C, D) = \phi_1(A, B) \times \phi_2(B, C) \times \phi_3(C, D) \times \phi_4(D, A) \quad (5)$$

is un-normalized. It is not probability distribution.

- Normalize  $\tilde{P}(A, B, C, D)$  using partition function  $Z$ .  $Z$  is called the **partition function** and is function of the parameters.

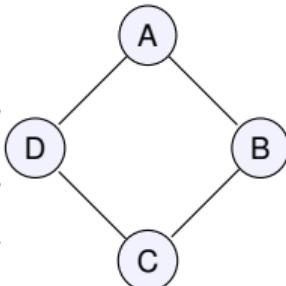
$$Z = \sum_{A,B,C,D} \tilde{P}(A, B, C, D) \quad (6)$$

- Normalized factor product

$$P(A, B, C, D) = \frac{1}{Z} \tilde{P}(A, B, C, D) \quad (7)$$

# NORMALIZED FACTOR PRODUCT

$D$	$A$	$\phi_4(D, A)$
$d^0$	$a^0$	80
$d^0$	$a^1$	60
$d^1$	$a^0$	20
$d^1$	$a^1$	10



$C$	$D$	$\phi_3(C, D)$
$c^0$	$d^0$	10
$c^0$	$d^1$	1
$c^1$	$d^0$	100
$c^1$	$d^1$	90

$A$	$B$	$\phi_1(A, B)$
$a^0$	$b^0$	90
$a^0$	$b^1$	100
$a^1$	$b^0$	1
$a^1$	$b^1$	10

$B$	$C$	$\phi_2(B, C)$
$b^0$	$c^0$	10
$b^0$	$c^1$	80
$b^1$	$c^0$	70
$b^1$	$c^1$	30

$A$	$B$	$C$	$D$	$\tilde{P}(A, B, C, D)$	$P(A, B, C, D)$
$a^0$	$b^0$	$c^0$	$d^0$	720,000	0.0055
$a^0$	$b^0$	$c^0$	$d^1$	18,000	0.0001
$a^0$	$b^0$	$c^1$	$d^0$	57600,000	0.4365
$a^0$	$b^0$	$c^1$	$d^1$	12960,000	0.0982
$a^0$	$b^1$	$c^0$	$d^0$	5600,000	0.0424
$a^0$	$b^1$	$c^0$	$d^1$	140,000	0.0011
$a^0$	$b^1$	$c^1$	$d^0$	24000,000	0.1819
$a^0$	$b^1$	$c^1$	$d^1$	5400,000	0.0409
$a^1$	$b^0$	$c^0$	$d^0$	6,000	0.0000
$a^1$	$b^0$	$c^0$	$d^1$	100	0.0000
$a^1$	$b^0$	$c^1$	$d^0$	480,000	0.0036
$a^1$	$b^0$	$c^1$	$d^1$	72,000	0.0005
$a^1$	$b^1$	$c^0$	$d^0$	420,000	0.0318
$a^1$	$b^1$	$c^0$	$d^1$	70,000	0.0005
$a^1$	$b^1$	$c^1$	$d^0$	1800,000	0.1364
$a^1$	$b^1$	$c^1$	$d^1$	270,000	0.0205
				109493,100	

# QUERIES USING FACTOR PRODUCT

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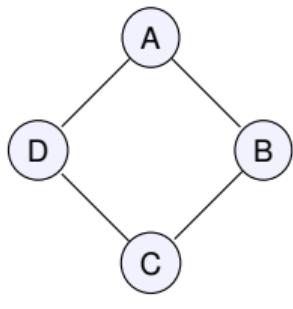
- Compute the probability of B.  
Marginalize wrt A,C,D

$$P(b^1) = 0.4555$$
$$P(b^0) = 0.5445$$

- Compute the probability of B agreeing with C given  $c^0$ .

$$P(b^1|c^0) = 0.0759$$

# FACTORS VS PROBABILITY DISTRIBUTION

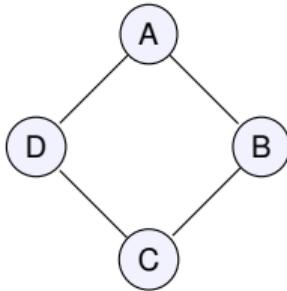


A	B	$\phi_1(A, B)$
$a^0$	$b^0$	90
$a^0$	$b^1$	100
$a^1$	$b^0$	1
$a^1$	$b^1$	10

Marginal Probability of A and B

A	B	C	D	$P(A, B, C, D)$	$P_\phi(A, B)$
$a^0$	$b^0$	$c^0$	$d^0$	0.0055	
$a^0$	$b^0$	$c^0$	$d^1$	0.0001	
$a^0$	$b^0$	$c^1$	$d^0$	0.4365	
$a^0$	$b^0$	$c^1$	$d^1$	0.0982	0.5403
$a^0$	$b^1$	$c^0$	$d^0$	0.0424	
$a^0$	$b^1$	$c^0$	$d^1$	0.0011	
$a^0$	$b^1$	$c^1$	$d^0$	0.1819	
$a^0$	$b^1$	$c^1$	$d^1$	0.0409	0.2663
$a^1$	$b^0$	$c^0$	$d^0$	0.0000	
$a^1$	$b^0$	$c^0$	$d^1$	0.0000	
$a^1$	$b^0$	$c^1$	$d^0$	0.0036	
$a^1$	$b^0$	$c^1$	$d^1$	0.0005	0.0042
$a^1$	$b^1$	$c^0$	$d^0$	0.0318	
$a^1$	$b^1$	$c^0$	$d^1$	0.0005	
$a^1$	$b^1$	$c^1$	$d^0$	0.1364	
$a^1$	$b^1$	$c^1$	$d^1$	0.0205	0.1892

# FACTORS VS PROBABILITY DISTRIBUTION



$A$	$B$	$\phi_1(A, B)$
$a^0$	$b^0$	90
$a^0$	$b^1$	100
$a^1$	$b^0$	1
$a^1$	$b^1$	10

$A$	$B$	$P_\phi(A, B)$
$a^0$	$b^0$	0.5403
$a^0$	$b^1$	0.2663
$a^1$	$b^0$	0.0042
$a^1$	$b^1$	0.1892

Marginal Probability of A and B

$A$	$B$	$C$	$D$	$P(A, B, C, D)$	$P_\phi(A, B)$
$a^0$	$b^0$	$c^0$	$d^0$	0.0055	
$a^0$	$b^0$	$c^0$	$d^1$	0.0001	
$a^0$	$b^0$	$c^1$	$d^0$	0.4365	
$a^0$	$b^0$	$c^1$	$d^1$	0.0982	0.5403
$a^0$	$b^1$	$c^0$	$d^0$	0.0424	
$a^0$	$b^1$	$c^0$	$d^1$	0.0011	
$a^0$	$b^1$	$c^1$	$d^0$	0.1819	
$a^0$	$b^1$	$c^1$	$d^1$	0.0409	0.2663
$a^1$	$b^0$	$c^0$	$d^0$	0.0000	
$a^1$	$b^0$	$c^0$	$d^1$	0.0000	
$a^1$	$b^0$	$c^1$	$d^0$	0.0036	
$a^1$	$b^0$	$c^1$	$d^1$	0.0005	0.0042
$a^1$	$b^1$	$c^0$	$d^0$	0.0318	
$a^1$	$b^1$	$c^0$	$d^1$	0.0005	
$a^1$	$b^1$	$c^1$	$d^0$	0.1364	
$a^1$	$b^1$	$c^1$	$d^1$	0.0205	0.1892

There is no natural mapping between factors and probability distribution.

# FACTORIZATION AND INDEPENDENCIES

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- $P \models (B \perp D | A, C)$  should have a decomposition

$$P = \frac{1}{Z} [\phi_1(A, B) \times \phi_2(B, C)] \times \phi_3(C, D) \times \phi_4(D, A)$$

B and D are separated given A and C.

- $P \models (A \perp C | B, D)$  should have a decomposition

$$P = \frac{1}{Z} [\phi_4(D, A) \times \phi_1(A, B)] \times \phi_2(B, C) \times \phi_3(C, D)$$

A and C are separated given B and D.

# FACTORIZATION AND INDEPENDENCIES

$$P \models (X \perp Y|Z) \quad \text{if and only if} \quad P = \phi_1(X, Z)\phi_2(Y, Z) \quad (8)$$

- Independence properties of the distribution  $P$  correspond directly to separation properties in the graph over which  $P$  factorizes.

# GIBBS DISTRIBUTION

## DEFINITION

A distribution  $P_\Phi$  is called a Gibbs distribution parameterized by a set of factors  $\Phi = \{\phi_1(D_1), \dots, \phi_k(D_k)\}$  if it can be expressed as product of the factors.

$$P_\Phi(X_1, \dots, X_n) = \frac{1}{Z_\Phi} [\phi_1(D_1) \times \dots \times \phi_k(D_k)]$$

$$\tilde{P}(X_1, \dots, X_n) = \prod_{i=1}^k \phi_i(D_i) \tag{9}$$

$$Z_\Phi = \sum_{X_1, \dots, X_n} \tilde{P}(X_1, \dots, X_n) \tag{10}$$

$$P_\Phi(X_1, \dots, X_n) = \frac{1}{Z_\Phi} \tilde{P}(X_1, \dots, X_n) \tag{11}$$

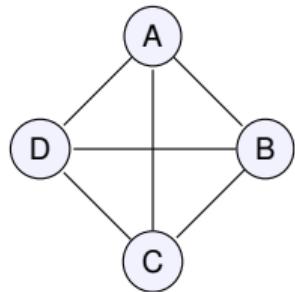
# GIBBS DISTRIBUTION

## DEFINITION

A distribution  $P_\Phi$  with  $\Phi = \{\phi_1(D_1), \dots, \phi_k(D_k)\}$  factorizes over a Markov Network  $\mathcal{H}$  if each  $D_k$  is a complete subgraph of  $\mathcal{H}$ .

- The factors that parametrize a Markov network are often called **clique potentials**.
- Reduce the number of factors in the parameterization by allowing factors only for maximal cliques.
- Let  $C_1, \dots, C_k$  be the cliques in  $\mathcal{H}$ .
- Parametrize  $P$  using a set of factors  $\phi_1(C_1), \dots, \phi_l(C_l)$ .

# GIBBS DISTRIBUTION EXAMPLE



- Cliques (Option 1):  
 $\{A, B\}, \{B, C\}, \{C, D\},$   
 $\{D, A\}, \{D, B\}, \{A, C\}$
- Cliques (Option 2):  
 $\{A, B, D\}, \{B, C, D\}$
- Cliques (Option 3):  
 $\{A, B, C\}, \{A, C, D\}$

# PAIRWISE MARKOV NETWORK

## DEFINITION

Pairwise Markov Network is an undirected graph whose nodes  $X_1, \dots, X_n$  and edges  $X_i - X_j$  are associated with a factor  $\phi_{ij}(X_i, X_j)$ .

- A subclass of Markov networks.
- Eg:

$$P(A, B, C, D) = \frac{1}{Z} [\phi_1(A, B) \times \phi_2(B, C) \times \phi_3(C, D) \times \phi_4(D, A)]$$

- How many parameters for  $n$  RV with  $d$  values each?

$$\text{Number of parameters in Pairwise Markov Network} = O(n^2d^2) \quad (13)$$

# INDUCED MARKOV NETWORK

## DEFINITION

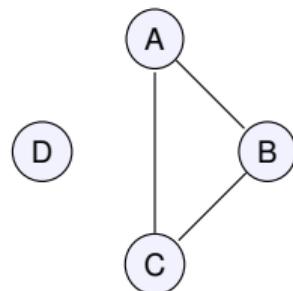
For a set of factors  $\phi_i$ , with a scope  $D_i$ , the Induced Markov Network  $H_\Phi$ , has an edge between a pair of variables  $X_i$  and  $X_j$  whenever there exists a factor  $\phi_m \in \Phi$  such that  $X_i, X_j \in D_m$ .

- $X$  and  $Y$  will have an undirected edge
  - ▶ if they appear together in some factor  $\phi$
  - ▶ if there exists a factor  $\phi(X, Y)$ .

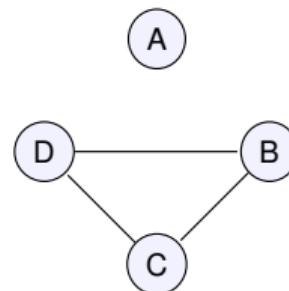
# INDUCED MARKOV NETWORK

Consider 4 RVs A,B,C, and D. The factor and its induced Markov Network is given below.

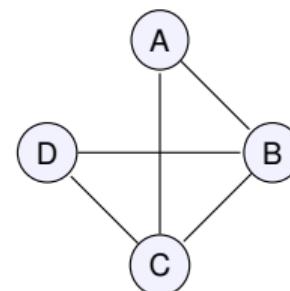
$$\phi_1(A, B, C)$$



$$\phi_2(B, C, D)$$



$$\Phi = \phi_1(A, B, C) \times \phi_2(B, C, D)$$



# $P$ FACTORIZES $H$

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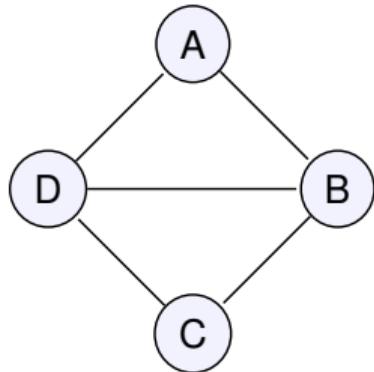
## DEFINITION

Gibbs distribution  $P$  factorizes a Markov Network  $H$  if there exists  $\Phi = \{\phi_1(D_1), \dots, \phi_k(D_k)\}$  such that

- $P = P_\Phi$ , normalized product of factors  $\phi_i$
- $H$  is the induced graph for  $\Phi$ .

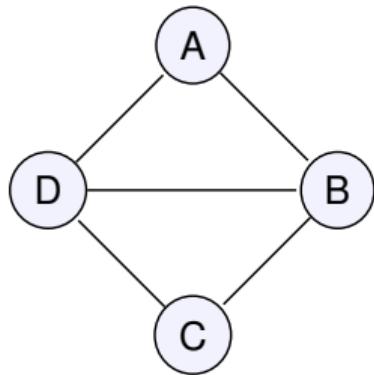
# $P$ FACTORIZES $H$

- From an induced Markov network  $H$ , we cannot read the factorization  $P_\phi$  from the graph, as there can be multiple possible factorization.



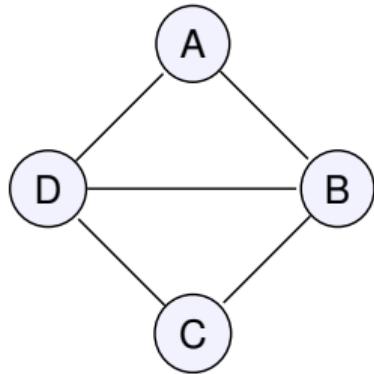
- $\phi_1(A, B, D), \phi_2(B, C, D)$
- $\phi_5(A, B), \phi_6(B, C), \phi_7(C, D), \phi_8(D, A), \phi_9(A, B)$

# FLOW OF INFLUENCE



- $\phi_1(A, B, D), \phi_2(B, C, D)$
- $\phi_5(A, B), \phi_6(B, C), \phi_7(C, D), \phi_8(D, A), \phi_9(B, D)$
- When can  $B$  influence  $D$ ?
- When can  $A$  influence  $C$ ?

# FLOW OF INFLUENCE



- $\phi_1(A, B, D), \phi_2(B, C, D)$
- $\phi_5(A, B), \phi_6(B, C), \phi_7(C, D), \phi_8(D, A), \phi_9(B, D)$
- When can  $B$  influence  $D$ ?
  - ▶ Direct influence
  - ▶  $\phi_1(A, B, D)$
  - ▶  $\phi_9(B, D)$
- When can  $A$  influence  $C$ ?
  - ▶ Indirect influence
  - ▶ Through  $B$  or  $D$
  - ▶  $\phi_1(B, C, D)$
  - ▶  $\phi_1(A, B, D)\phi_2(B, C, D)$
  - ▶  $\phi_5(A, B), \phi_6(B, C)$
  - ▶  $\phi_7(C, D), \phi_8(D, A)$

# FLOW OF INFLUENCE

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- Parameterization of the distributions are different.
- The trails in the graph through which influence can flow are the same.
- Active trails depend only on the graph structure.

# REFERENCES

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- ② Artificial Intelligence: A Modern Approach (3rd Edition) by Stuart Russell, Peter Norvig
- ③ Mastering Probabilistic Graphical Models using Python by Ankur Ankan, Abhinash Panda. Packt Publishing 2015.
- ④ Learning in Graphical Models by Michael I. Jordan. MIT Press. 1999

Thank You !!!