

soft.com

### **Motorcomm**

### YT8521SH-CA/YT8521SC-CA

Datasheet

INTEGRATED 10/100/1000 GIGABIT ETHERNET TRANSCEIVER

VERSION V1.05

2025-03-21 2025-03-21 2023-02-24 DATE

裕太微电子 | Motorcomm



#### **Copyright Statement**

ny 250 ft. COM This document is copyright of Motorcomm Electronic Technology Co., Ltd. ("Motorcomm"). All rights reserved. No company or individual may copy, disseminate, disclose or otherwise distribute any part of this document to any third party without the written consent of Motorcomm. If any company or individual so does, Motorcomm reserves the right to hold it or him liable therefor.

#### **Disclaimer**

1.5° 2025-03-27 21:5°

表MM基III yms@senyasoft.com 2025-03

2025-03-27 2025-03-27 2025-03-27



	<b>是限以</b> 国	
Motorcon	ım YT8521SH-CA/Y	T8521SC-CA Datasheet 裕太微电子 Motorcomm
岩洲州		Revision History
Revision	Release Date	Summary
V1.00	2020/06/15	First version.
V1.01	2020/06/17	Add description in section 4.1.5.
V1.02	2020/06/21	Modify serveral description.
V1.03	2021/07/23	In section 8.3, change the minimum value of Internal LDO ready time to 100us.
	温 州 是 1111	<ul><li>2. Update Sync-E register description.</li><li>3. Modify parameter Vil in section 7.3 and 7.4.</li></ul>
V1.04	2023/01/31	1. Remove parameter Tr/Tf in Table 137.
		2. Modify parameter T3/T4 in Table 144.
		<ul><li>3. Modify description of Duty_T in Table 137.</li><li>4. Modify parameter Vil in section 7.3 and 7.4.</li></ul>
		4. Modify parameter Vil in section 7.3 and 7.4.
		5. Modify parameter Ltx to parameter IL in section 7.2.1
V1.05	2023/02/24	Modify 6.2.11 bit10 and bit11 description

2025-03 2025-03 yms@senyasoft.com yms@senyasoft.

2025-03-27 2025-03-27



### Content

	~ · ·
(本版/A)	$_{\rm C} \circ \%$
	,
Motorcomm YT8521SH-CA/YT8521SC-CA Datasheet	裕太微电子
S S	Motorcomm
Content	
1. General Description	1
1.1. TARGET APPLICATIONS	
2. Features	2.
3. Pin Assignment	4
3.1. Y 18521S QFN48 6x6mm	4
3.2. Pin Descriptions 3.3. Pin Assignment	5
3.4. Transceiver Interface	5
3.5. Clock	
3.6. RGMII	
3.7. SerDes	1
3.8. Reset	• /
3.9. Mode Selection	
3.10. LED Default Settings	
3.12. Power Related	8
3.12. Power Related	8
3.14. Miscellaneous Pins	9
4. Function Description 4.1. Application Diagram	
4.1. Application Diagram	
4.1.1. UTP (UTP<->RGMII / UTP<->SGMII) Application	10 10
4.1.3. UTP/Fiber to RGMII (UTP/FIBER Media Auto Detection RGMII) Application	onlication10
4.1.4. SGMII to RGMII (SGMII <->RGMII Bridge Mode) Application	
4.1.5. Fiber to UTP (UTP<->FIBER Media Converter) Application	
4.2. Transmit Functions	
4.2.1. Transmit Encoder Modes	
4.3. Receive Functions	
4.4. LRE100-4	
4.5. Echo Canceller	
4.6. NEXT Canceller	12
4.7. Baseline Wander Canceller	12
4.8. Digital Adaptive Equalizer	13
4.9. Management Interface 4.10. Auto-Negoitation	13
4.11. LDS (Link Discover Signaling)	13
4.12. Polarity Detection and Auto Correction	13
4.13. Loopback Mode	
4.13.1. Digital Loopback	13
4.13.2. External loopback	
4.13.3. Remote PHY loopback	15
4.14. Energy Efficient Ethernet (EEE) 4.15. Synchronous Ethernet (Sync-E)	
4.16 Waka On I AN (WOI)	15 Å °
4.17. Link Down Power Saving (Sleep Mode)	
4.18. Interrupt	
5. Operational Description	
5.1. Reset	
5.2. PHY Address	
5.4. LED	17
5.5. INT N/PME N Pin Usage	17
5.6. Power Supplies	17
5.6.1. Internal Switch Regulator	
5.6.2. Internal LDO	17
J.M.S. S.	
96	
i m	



	-
TE LET	08111
Motorcomm YT8521SH-CA/YT8521SC-CA Datasheet  Register Overview	* * * * *
Notorcomm Y185215H-CA/Y185215C-CA Datasheet	裕太微电子
2 5 C	Motorcomm
Register Overview	18
6.1. Common Register	18
6.1.1. SMI_SDS_PHY (EXI_0xA000)	18
6.1.2. Cnip_Config (EXI_UXA001)	18 1C
6.1.4. RGMII Config1 (EXT_0xA003)	19
6.1.5. RGMII Config2 (EXT 0xA004)	
6.1.6. MDIO_Cfg_And_RGM!I_OOB_Mon (EXT_0xA005)	
6.1.7. Misc_Config (EXT_0xA006)	
6.1.8. MAC_Address_Cfg1 (EXT_0xA007)	
6.1.9. MAC_Address_Cfg2 (EXT_0xA008)	
6.1.10. MAC_Address_Cfg3 (EXT_0xA009)	
6.1.11. WOL_Cfg (EXT_0xA00A)	
6.1.12. LED_GENERAL_CFG (EXT_0XA00B)	
6.1.14. LED1_CFG (EXT_0xA00D)	24
6.1.15. LED2_CFG (EXT_0xA00E)	24
6.1.16. LED BLINK CFG (EXT 0xA00F)	25
6.1.16. LED_BLINK_CFG (EXT_0xA00F)	25
6.1.18. SyncE_CFG (EXT_0xA012)	26
6.2. UTP MII Register	26
6.2.1. Basic Control Register (0x00)	26
6.2.2. Basic Status Register (0x01)	2/
6.2.4. PHY Identification Register2 (0x03)	28
6.2.5. Auto-Negotiation Advertisement (0x04)	
6.2.6. Auto-Negotiation Link Partner Ability (0x05)	
6.2.7. Auto-Negotiation Expansion Register (0x06)	31
6.2.8. Auto-Negotiation NEXT Page Register (0x07)	32
6.2.9. Auto-Negotiation Link Partner Received NEXT Page Register (0x08)	32
6.2.10. MASTER-SLAVE control register (0x09)	···········33
6.2.11. MASTER-SLAVE Status Register (0x0A)	34
6.2.12. MMD Access Control Register (0x0D)	35
6.2.13. MMD Access Data Register (0x0E)	
6.2.15. PHY Specific Function Control Register (0x10)	35
6.2.16. PHY Specific Status Register (0x11)	36
6.2.17. Interrupt Mask Register (0x12)	37
6.2.18. Interrupt Status Register (0x13)	
6.2.19. Speed Auto Downgrade Control Register (0x14)	
6.2.20. Rx Error Counter Register (0x15)	
6.2.22. Extended Register's Data Register (0x1F)	
6.3. UTP MMD Register	
6.3.1. PCS Control 1 Register (MMD3, 0x0)	
6.3.2. PCS Status T Register (MMD3, 0x1)	
6.3.3. EEE Control and Capability Register (MMD3, 0x14)	
6.3.4. EEE Wake Error Counter (MMD3, 0x16)	
6.3.5. Local Device EEE Ability (MMD7, 0x3C)	
6.3.6. Link Partner EEE Ability (MMD7, 0x3D)  6.4. UTP LDS Register	
6.4.1. LRE Control (0x00)	41 41
6.4.2. LRE Status (0x01)	41
6.4.3. PHY ID Register1 (0x02)	42
6.4.4. PHY ID Register2 (0x03)	42
6.4.5. LDS Auto-Negotiation Advertised Ability (0x04)	42
6.4.6. LDS Link Partner Ability (0x07)	
6.4.7. LDS Expansion (0x0A)	43
6.4.7. LDS Expansion (0x0A)	
S	
100	



6.4.8. LDS Results (0x0B)	, <b>, , , ,</b> , ,
torcomm Y18521SH-CA/Y18521SC-CA Datasheet	裕太微电子
M 32 111	Motorcomm
6.4.8. LDS Results (0x0B)	43
6.5. UTP EXT Register	43
6.5.1. Pkgen Cfg1 (EXT_0x38)	43
6.5.2. Pkgen Cfg3 (EXT_0x3A)	4
6.5.3. PKg CIgU (EXI_UXAU)	44
6.5.4. Pkg Cfg1 (EXT_0xA1)	4. Δ <sup>4</sup>
6.5.6. Pkg Rx Valid0 (EXT_0xA3)	45
6.5.7. Pkg Rx Valid1 (EXT 9xA4)	
6.5.8. Pkg Rx Os0 (EXT_0xA5)	
6.5.9. Pkg Rx Os1 (EXT_0xA6)	
6.5.10. Pkg Rx Us0 (EXT_0xA7)	
6.5.11. Pkg Rx Us1 (EXT_0xA8)	
6.5.12. Pkg Rx Err (EXT_0xA9)	
6.5.13. Pkg Rx Os Bad (EXT_0xAA)	40 11
6.5.15. Pkg Rx Nosfd (EXT_0xAC)	47 27
6.5.16 Pkg Tx Valid0 (EXT_0xAD)	47
6.5.16. Pkg Tx Valid0 (EXT_0xAD)	47
6.5.18. Pkg Tx Os0 (EXT 0xAF)	47
6.5.18. Pkg Tx Os0 (EXT_0xAF)	47
6.5.20. Pkg Tx Us0 (EXT_0xB1)	47
6.5.20. Pkg Tx Us0 (EXT_0xB1) 6.5.21. Pkg Tx Us1 (EXT_0xB2) 6.5.22. Pkg Tx Err (EXT_0xB3)	48
6.5.22. Pkg Tx Err (EXT_0xB3)	48
6.5.23. Pkg Tx Os Bad (EXT_0xB4)	48
6.5.25. Pkg Tx Nosfd (EXT_0xB6)	
6.6. SDS MII Register	
6.6.1. Basic Control Register (0x00)	
6.6.2. Basic Status Register (0x01)	49
6.6.3. Sds Identification Register1 (0x02)	50
6.6.4. Sits Identification Register2 (0x03)	50
6.6.5. Auto-Negotiation Advertisement (0x04)	51
6.6.6. Auto-Negotiation Link Partner Ability (0x05)	51
6.6.8. Auto-Negotiation NEXT Page Register (0x07)	51 51
6.6.9. Auto-Negotiation Link Partner Received NEXT Page Register (0x08)	
6.6.10. Extended status register (0x0F)	52
6.6.10. Extended status register (0x0F)	52
6.6.12. 100BASE-FX Cfg (0x14)	53
6.6.13. Receive Err Counter (0x15)	
6.6.14. Link Fail Counter (0x16)	
6.7. SDS EXT Register	
6.7.1. Pkgen Cfg1 (EXT 0x38)	
6.7.3. Pkg Cfg0 (EXT 0x1A0)	
6.7.4. Pkg Cfg1 (EXT 0x1A1)	
6.7.5. Pkg Cfg2 (EXT 0x1A2)	
6.7.6. Pkg Rx Valid0 (EXT_0x1A3)	
6.7.7. Pkg Rx Valid1 (EXT_0x1A4)	
6.7.8. Pkg Rx Os0 (EXT_0x1A5)	55
6.7.9. Pkg Rx Os1 (EXT_0x1A6)	56
6.7.10. Pkg Rx Us0 (EXT_0x1A7)	50
6.7.11. Pkg Rx Us1 (EXT_0x1A8)	50 54
6.7.13. Pkg Rx Os Bad (EXT_0x1A4)	50 5 <i>6</i>
6.7.14 Pkg Ry Fragment (FXT 0v1AR)	56
6.7.15. Pkg Rx Nosfd (EXT 0x1AC)	56
, 'S	
e (' '	
6.7.15. Pkg Rx Nosfd (EXT_0x1AC)	

90			
* *	V	٧	٧
裕太	微	电	子
Mot	orc	om	m

113年			
Motorcomm YT8521SH-CA/YT8521SC-CA Datasheet  6.7.16. Pkg Tx Valid0 (EXT_0x1AD)		G	
Motorcomm YT8521SH-CA/YT8521SC-CA Datasheet	£ 1.	************************************	
Z III	60'	俗太似电士 Motorcomm	
CTAC DI CTACIONA CONTRA CALIDA	, 2, 3		
6.7.16. Pkg Tx Valid0 (EXT_0x1AD)		57	
6.7.17. Pkg Tx Valid1 (EXT_0x1AE)		57	
6.7.18. Pkg Tx Os0 (EXT_0x1AF)	<i>.</i>	57	
6.7.19. Pkg Tx Os1 (EXT_0x1B0)		57	
6.7.20. Pkg Tx Us0 (EXT_0x1B1)		57	
OITIES IN COLUMN ON DE J			
6.7.22. Pkg Tx Err (EXT_0x1B3)			
6.7.23. Pkg Tx Os Bad (EXT_0x B4)		38	
6.7.24. Pkg Tx Fragment (EXT_0x1B5)			
6.7.25. Pkg Tx Nosfd (EXT_0x1B6)			5
7. Timing and AC/DC Characteristics			۸ . ٥
7.2. AC Characteristics		P	2
7.2.1. SGMII Differential Transmitter Characteristics			
7.2.2. SGMII Differential Receiver Characteristics			
7.2.2. SOWIT Differential Receiver Characteristics		00	
7.2.3. RGMII Timing w/o delay		62	
7.2.4. RGMII Timing with internal delay	2'9	02	
7.2.5. SMI (MDC/MDIO) Interface Characteristics	2.0	63	
7.4. Oscillator/External Clock Requirement	~	63	
8. Power Requirements	~ O	64	
8.1 Absolute Maximum Ratings		64	
8.1. Absolute Maximum Ratings 8.2. Recommended Operating Conditions 8.3. Power Sequence 8.4. Power Consumption		64	
8.3. Power Sequence		64	
8.4. Power Consumption		65	
8.4.1. UTP <-> RGMII		65	
8.4.2. FIBER <->RGMII			0
8.4.3. SGMII <-> RGMII		65 🤈	5
8.4.4. UTP <-> SGMII		65	
8.4.5. UTP <->FIBER		66	
8.5. Maximum Power Consumption		66	
8.6. Power Noise			
9. Mechanical and Thermal		67	
9.1. RoHS-Compliant Packaging		67	
9.2. Thermal Resistance		67	
10. Mechanical Information		68	
11. Ordering Information		70	
i w			
10. Mechanical Information			
alixes			
一样。 1			
the the terminal of the termin			
JA WHITE			5
Et 1			21.5
			L '

2025-03-27 21.5°



	~ ~
toroopers VT0E21CLL CA WT0E21CC CA Datashoot	
List of Tables  Table 1. Pin Assignment Table 2. Transceiver Interface Table 3. Clock	1 <b>1 1 1</b> 1
torcomm YT8521SH-CA/YT8521SC-CA Datasheet	裕太微电子
N ZEILL S	Motorcomm
List of Tables	
List of Tables	
Table 1. Pin Assignment	5
Table 3. Clock	
	(
Table 4. RGMII Table 5. SerDes	
Table 6. Reset	
Table 7. Mode Selection	
Table 8. LED Default Settings	
Table 9. Regulator and Reference	
Table 10. Power Related	
Table 11. Management  Table 12. Miscellaneous Pins	
Table 13. Reset Timing Characteristics	16
Table 14. CFG_LDO[1:0] Configuration	1′
Table 15. Register Access Types	18
Table 15. Register Access Types  Table 16. SMI_SDS_PHY (EXT_0xA000)  Table 17. Chip_Config (EXT_0xA001)	18
Table 17. Chip_Config (EXT_0xA001)	18
Table 18. SDS_Config (EXT_0xA002)	19
Table 18. SDS_Config (EXT_0xA002)  Table 19. RGMII_Config1 (EXT_0xA003)  Table 20. RGMII_Config2 (EXT_0xA004)	19
Table 20. RGMII_Config2 (EXT_0xA004)	20
Table 21. MDIO_Cfg_And_RGMII_OOB_Mon (EXT_0xA005) Table 22. Misc_Config (EXT_0xA006)	20
Table 23. MAC Address Cfg1 (EXT 0xA007)	21 21
Table 24. MAC_Address_Cfg1 (EXT_0xA008)	21
Table 25. MAC_Address_Cfg3 (EXT_0xA009)	22
Table 26. WOL Cfg (EXT 0xA00A)	
Table 27. LED GENERAL CFG (EXT 0xA00B)	20
Table 28. LEDO_CFG (EXT_0xA00C)	23
Table 29. LED1_CFG (EXT_0xA00D)	24
Table 30. LFD2_CFG (EXT_0xA00E)	
Table 31. LED_BLINK_CFG (EXT_0xA00F)	
Table 32. Pad Drive Strength Cfg (EXT_0xA010)	26
Table 35. Basic Status Register (0x01)	27
Table 35. Basic Status Register (0x00)  Table 36. PHY Identification Register1 (0x02)  Table 37. PHV Identification Register2 (0x03)	28
Table 37. PHY Identification Register2 (0x03)	28
Table 39. Auto-Negotiation Link Partner Ability (0x05)	
Table 40. Auto-Negotiation Expansion Register (0x06)	
Table 41. Auto-Negotiation NEXT Page Register (0x07)	
Table 43. MASTER-SLAVE control register (0x09)	
Table 44. MASTER-SLAVE Status Register (0x0A)	
Table 45. MMD Access Control Register (0x0D)	
Table 46. MMD Access Data Register (0x0E)	35
Table 47. Extended status register (0x0F)	
Table 48. PHY Specific Function Control Register (0x10)	35
Table 49. PHY Specific Status Register (0x11)	36
Table 50. Interrupt Mask Register (0x12)	3
Table 51. Interrupt Status Register (0x13)	58 25
Table 53. Rx Error Counter Register (0x15)	30
Table 54. Extended Register's Address Offset Register (0x1E)	30
Table 55. Extended Register's Data Register (0x1F)	39
Table 56 DCS Control 1 Decision (MMD2 Ov0)	39
50	
6/1	
<u></u>	
Table 30. PCS Control 1 Register (MIVID3, 0x0)	



THE LATER OF THE PARTY OF THE P	
otorcomm YT8521SH-CA/YT8521SC-CA Datasheet	* * <b>*</b> * *
ptorcomm YT8521SH-CA/YT8521SC-CA Datasheet	裕太微电子
N/XE II	Motorcomm
Table 57. PCS Status 1 Register (MMD3, 0x1)  Table 58. EEE Control and Capability Register (MMD3, 0x14)  Table 59. EEE Wake Error Counter (MMD3, 0x16)	40
Table 58. EEE Control and Capability Register (MMD3, 0x14)	40
Table 60. Local Device FFF Ability (MMD7, 0x10)	40 10
Table 60. Local Device EEE Ability (MMD7, 0x3C)	40
Table 62. LRE Control (0x00)	41
Table 62. LRE Control (0x00)	41
Table 64. PHY ID Register1 (0x02)	
Table 65. PHY ID Register2 (0x03)	
Table 67. LDS Link Partner Ability (0x07)	
Table 68. LDS Expansion (0x0A)	
Table 69. LDS Results (0x0B)	
Table 70. Pkgen Cfg1 (EXT_0x38)	
Table 71. Pkgen Cfg3 (EXT_0x3A)  Table 72. Pkg Cfg0 (EXT_0xA0)	44
Table 73. Pkg Cfg1 (EXT_0xAt)	45
Table 74. Pkg Cfg2 (EXT 0xA2)	45
Table 74. Pkg Cfg2 (EXT_0xA2) Table 75. Pkg Rx Valid0 (EXT_0xA3)	45
Table 76. Pkg Rx Valid1 (EXT_0xA4)  Table 77. Pkg Rx Os0 (EXT_0xA5)	45
Table 77. Pkg Rx Os0 (EXT_0xA5)	46
Table 78. Pkg Rx Os1 (EXT_0xA6)  Table 79. Pkg Rx Us0 (EXT_0xA7)  Table 80. Pkg Rx Us1 (EXT_0xA8)	46
Table 80. Pkg Rx Us1 (EXT 0xA8)	46
Table 81. Pkg Rx Err (EXT 0xA9)	46
Table 82. Pkg Rx Os Bad (EXT_0xAA)	46
Table 83. Pkg Rx Fragment (EXT_0xAB)  Table 84. Pkg Rx Nosfd (EXT_0xAC)	
Table 85. Pkg Tx Valid0 (EXT 0xAD)	
Table 86. Pkg Tx Valid (EXT_0xAE)	
Table 87. Pkg Tx Os0 (EXT_0xAF)	47
Table 88. Pk; Tx Os1 (EXT_0xB0)	47
Table 89. Pkg Tx Us0 (EXT_0xB1)	47
Table 90. Pkg Tx Us1 (EXT_0xB2)	48 48
Table 92 Pkg Ty Os Rad (FXT OyR4)	48
Table 93. Pkg Tx Fragment (EXT_0xB5)  Table 94. Pkg Tx Nosfd (EXT_0xB6)  Table 95. Basic Control Register (0x00)  Table 96. Pagic Status Pagister (0x01)	48
Table 94. Pkg Tx Nosfd (EXT_0xB6)	48
Table 95. Basic Control Register (0x00)	48
Table 97. Sds Identification Register (0x02)	······································
Table 98. Sds Identification Register2 (0x03)	
Table 99. Auto-Negotiation Advertisement (0x04)	
Table 100. Auto-Negotiation Link Partner Ability (0x05)	
Table 101. Auto-Negotiation Expansion Register (0x06)	
Table 102. Auto-Negotiation NEXT Page Register (0x07)	
Table 104. Extended status register (0x0F)	
Table 105. Sds Specific Status Register (0x11)	
Table 106. 100BASE-FX Cfg (0x14)	, 53
Table 107. Receive Err Counter (0x15)	53
Table 108. Link Fail Counter (0x16)	53 53
Table 109. Pkgen Cfg1 (EXT_0x38)	54
Table 111. Pkg Cfg0 (EXT_0x1A0)  Table 112. Pkg Cfg1 (EXT_0x1A1)	54
Table 112. Pkg Cfg1 (EXT_0x1A1)	55
Table 114. Pkg Cfg2 (EXT_0x1A2)	
Table 114. Pkg Rx Valid0 (EXT_0x1A3)	
7 3 3	
80,	
@, <b>S</b>	
Table 114. Pkg Rx Valid0 (EXT_0x1A3)	
41.7	

W.		A	A
<b>V</b>	V	V	V
裕太		_	_
裕太 Mote		_	_

Table 115. Pkg Rx Valid1 (EXT_0x1A4)	COM	
torcomm YT8521SH-CA/YT8521SC-CA Datasheet	☆★微由ヱ	
(支)	Motorcomm	
Table 115 Dire Du Valida (EVT Out Ad)	5.5	
Table 116. Pkg Rx Valid1 (EA1_0x1A4)	55	
Table 117. Pkg Rx Ost (EXT_0x1A5)	55	
Table 118 Pkg Rx Us0 (EXT_0x1A7)	56	
Table 119. Pkg Rx Us1 (EXT_0x1A8)	56	
Table 120. Pkg Rx Err (EXT_0x1A9)	56	
Table 121. Pkg Rx Os Bad (EXT 0x1AA)	56	
Table 122. Pkg Rx Fragment (EXT 0x1AB)		
Table 123. Pkg Rx Nosfd (EXT 0x1AC)		
Table 124. Pkg Tx Valid0 (EXT_0x1AD)	57	
Table 125. Pkg Tx Valid1 (EXT_0x1AE)	57	. 5
Table 126. Pkg Tx Os0 (EXT_0x1AF)	57	0 1.
Table 127. Pkg Tx Os1 (EXT_0x1B0)	57	-
Table 128. Pkg Tx Us0 (EXT_0x1B1)	57	
Table 129. Pkg Tx Us1 (EXT_0x1B2)	57	
Table 130. Pkg Tx Err (EXT_0x1B3)	58	
Table 131. Pkg Tx Os Bad (EXT 0x1B4)	58	
Table 132. Pkg Tx Fragment (EXT_0x1B5) Table 133. Pkg Tx Nosfd (EXT_0x1B6)	58	
Table 133. Pkg Tx Nosfd (EXT_0x1B6)	58	
Table 134. DC Characteristics	59	
Table 135. SGMII Differential Transmitter Characteristics	59	
Table 136. SGMII Differential Receiver Characteristics	60	
Table 137. RGMII Timing w/o delay	61	
Table 138. RGMII Timing with internal delay	62	
Table 139. SMI (MDC/MDIO) Interface Characteristics	62	0
Table 141. Cocillator/Enternal Clark Programment		03
Table 142. Absolute Maximum Petrors		6
Table 142. Absolute Maximum Ratings		L
Table 144. Power Sequence Timing Parameters		
Table 145. UTP <-> RGMII Power Consumption		
Table 146. FIBER <-> RGMII Power Consumption		
Table 147 SGMII <-> RGMII Power Consumption		
Table 148. UTP <-> SGMII Power Consumption	65	
Table 148. UTP <-> SGMII Power Consumption	66	
Table 150. Maximum Power Consumption	66	
Table 151. Part Number	67	
Table 152. Thermal Resistance	67	
Table 153. Ordering Information		

带州圣亚特有限公司 2025-03-27 2025-03-27



		<i>-</i>
Mataura and ATDE 21 CLA ACTOE 21 CC. CA. D.	atasheet  Figures  plication	
Motorcomm YT8521SH-CA/YT8521SC-CA Da	atachoot	
MOTOLOGIM F102212H-CAV F102213C-CA Do	atasneet	裕太微电子 Motorcomm
THE WALL THE	25	Motorcomm
List of F	Figures ( )	
Figure 1. Blcok Diagram	<u></u>	3
Figure 2. Pin Assignment Diagram		4
Figure 3. UTP (UTP<->RGMII / UTP<->SGMII) Application (FIDER < > PGMII) Application	plication	10
Figure 5. LITP/Fiber to RGMII Application		10 10
Figure 6. SGMII to RGMII Application		11
Figure 7. Fiber to UTP Application		11
Figure 8. Digital Loopback		14
Figure 9. External Loopback		14
Figure 11. Reset Timing Diagram		1 <del>4</del> 16
Figure 12. Connection Diagram of RGMII		17
Figure 13. SGMII Differential Transmitter Eye Diagra	am	60
Figure 14. SGMII Differential Receiver Eye Diagram		61
Figure 15. RGMII Timing w/o delay		61
Figure 17. SMI (MDC/MDIO) Timing	20 6	62
Figure 18. Power Sequence Diagram		64
	G 0 ''	
	* *	
. 2	5	
27		
658		
5		
7 ("		20
		o W
THE LAND CONTRACTOR OF THE PARTY OF THE PART		C C
tr 14-15	E T.	
Figure 3. UTP (UTP<->RGMII / UTP<->SGMII) Application	@senyasof*.	
	12	
\',	6,0,	
	@,5	

2025-03 2025-03 yms@senyasoft.com yms@senyasoft. 2025-03-27 2025-03-27



### **General Description**

The YT8521S is a highly integrated Ethernet transceiver that complies with 10BASE-Te, 100BASE-TX, and 1000BASE-T IEEE 802.3 standards. It provides all the necessary physical layer functions to transmit and receive Ethernet packets over CAT.5E UTP cable.

The YT8521S uses state-of-the-art DSP technology and an Analog Front End (AFE) to enable high-speed data transmission and reception over UTP cable Functions such as Crossover Detection & Auto-Correction, polarity correction, adaptive equalization, cross-talk cancellation, echo cancellation, timing recovery, and error correction are implemented in the YT85213 to provide robust transmission and reception capabilities at 10Mbps, 100Mbps, or 1000Mbps.

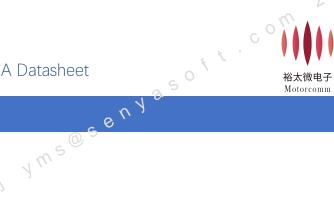
Data transfer between MAC and PHY is via the Reduced Gigabit Media Independent Interface (RGMII), or Serial Gigabit Media Independent Interface (SGMII) for 1000BASE-T, 100BASE-TX and 10BASE-Te. The YT8521S supports various RGMII signaling voltages, including 3.3V, 2.5V, and 1.8V.

The YT8521S also supports a SerDes interface that can be configured as SGMII, 1000BASE-X or 100BASE-FX. The YT8521S features a Motorcomm proprietary feature called LRE100-4, which enables the device to auto-negotiate and link up with LRE100-4 compliant link partners in extended cable reach applications up to 400 meter at 100Mbps over CAT.5E cable.

#### 1.1. TARGET APPLICATIONS

- DTV (Digital TV)
- MAU (Media Access Unit)
- ms@senyasof CNR (Communication and Network Riser)
- Game Console
- Printer and Office Machine
- DVD Player and Recorder
- Ethernet Hub
- Ethernet Switch
- Base Stations and Controllers
- Routers, DSLAMs, PON Equipment
- Test and Measurement Systems
- Industrial and Factory Automation Equipment
- Multimedia synchronization and Real Time Networking
- ms@senyasoft.com 2025-03 Any embedded system with an Ethernet MAC that needs a UTP physical connection.

2025-03-27 2025-03-27 2025-03-27



#### Features

- 1000BASE-T IEEE 802.3ab Compliant
- 100BASE-TX IEEE 802.3u Compliant
- Support 1000BASE-X / 100BASE-FX
  Support LRF100 4
- 2025-03-27 2025-03-27 2025-03-27 • Long Reach Ethernet up to 400 meter @100Mbps by 4-pairs in the CAT.5E UTP cable
- Supports RGMII/SGMII MAC interface
- Supports IEEE 802.3az-2010 (Energy Efficient Ethernet)
  - EEE Buffering
  - Incorporates EEE buffering for seamless support of legacy MACs
- Supports Synchronous Ethernet (Sync-E)
- Built-in Wake-on-LAN (WOL) over UTP/Fiber
- Supports interrupt function over UTP/Fiber
- Supports Parallel Detection
- Crossover Detection & Auto-Correction
- Automatic polarity correction
- **Baseline Wander Correction**
- Supports 120m for CAT.5E cable in 1000BASE-T
- Selectable 3.3V/2.5V/1.8V signaling for RGMII.
- Supports 25MHz external crystal or OSC
- Provides 125MHz clock source for MAC •
- Provides 3 network status LEDs
- 0 Supports Link Down Power Saving (Sleep Mode)
- Built-in Switching Regulator and LDO
- Industrial grade manufacturing process
- Supports SERDES (SGMII/1000BASE-X )
- yms@senyasoft.com
  2025-03 Supports Fiber-to-UTP Media Convertor mode or SGMII-to-RGMII Bridge mode
- Supports UTP/Fiber Auto Detection
- 2025-03-27 21:5 2025-03-27 Supports 18k bytes jumbo frame when 1000BASE-T and 100BASE-TX, and 10k bytes when 10BASE-Te
- 48-pin QFN Green Package



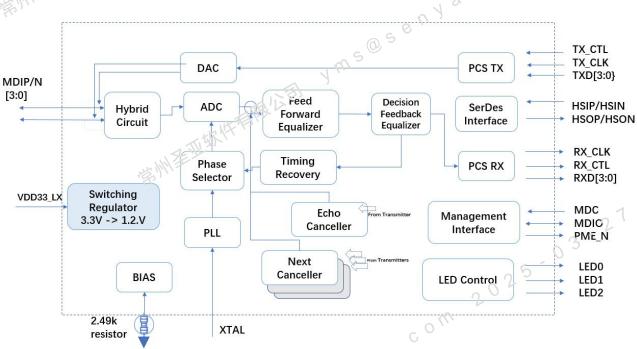


Figure 1. Blcok Diagram

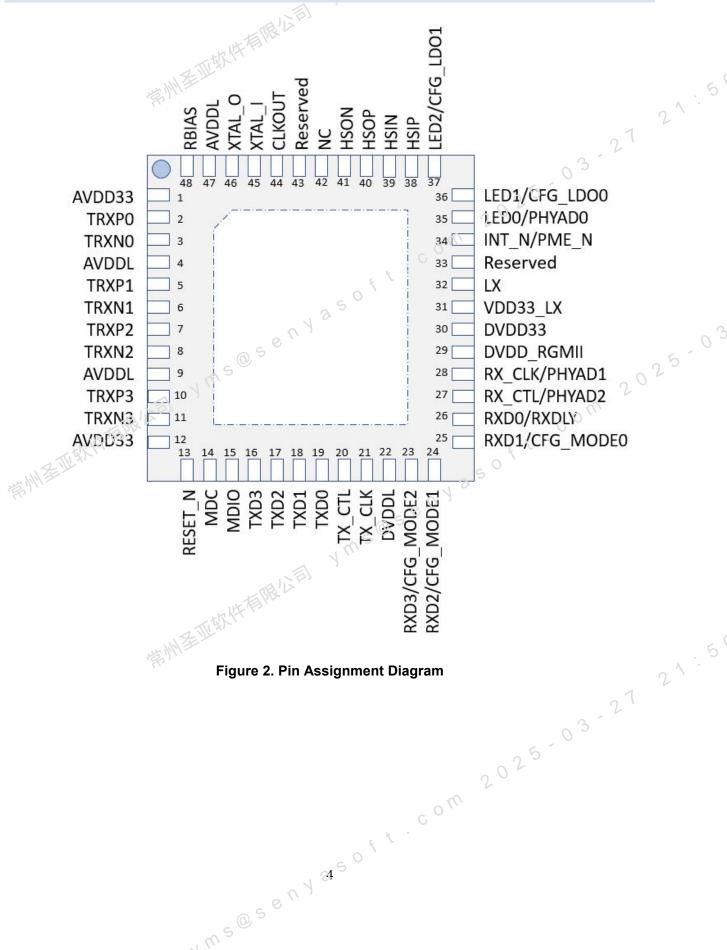
斯州圣亚特·阿根公司

2025-03-27 2025-03-27



### Pin Assignment

#### 3.1. YT8521S QFN48 6x6mm



05617



2025-03-21 2025-03-21

25-03

#### 3.2. Pin Descriptions

Some pins have multiple functions.

Refer to the Pin Assignment figures for a graphical representation.

I: Input

O: Output

IO: Bidirectional Input and Output

LI: Latched Input During Fower UP

P: Power

PU: Internal pull up

PD: Internal pull down

G: Ground

OD: Open Drain

XT: Crystal Related

#### 3.3. Pin Assignment

Table 1. Pin Assignment

<b>N</b> T	D. M	700	11 0		D: 3
No.	Pin Name	Type	)	No.	Pin N
1	AVDD33	Ps	-	26	RXD
2	TRXP0	JO		27	RX_0
3	TRXN0	IO		28	RX_0
4	AVDDL	P		29	DVD
5	TRXP1	IO		30	DVD
6	TRXN1	IO		31	VDD
7 25	TRXP2	IO		32	LX
8	TRXN2	IO		33	Rese
9	AVDDL	P		34	INT_
10	TRXP3	IO		35, 5	LED
11	TRXN3	IO	200	36	LED
12	AVDD33	P	7 1	37	LED
13	RESET_N	I/PU	5)	38	HSIP
14	MDC	I/PD		39	HSIN
15	MDIO	IO/PU		40	HSO
16	TXD3	I/PD		41	HSO
17	TXD2	I/PD		42	NC
18	TXD1	I/PD		43	Rese
19	TXD0	I/PD		44	CLK
20	TX_CTL	I/PD		45	XTA
21	TX_CLK	I/PD		46	XTA
22	DVDDL	P		47	AVD
23	RXD3/CFG_MODE2	O/LI/PD		48	RBIA
24	RXD2/CFG_MODE1	O/LI/PD		49	GND
25	RXD1/CFG_MODE0	O/LI/PD			0,0
		•	1	× .	
				,	
			25 5		
		0	Y		
		96,			
		\\$ <sup>®\$</sup>			
	7,10	`			

No.	Pin Name	Type
26	RXD0/RXDLY	O/LI/PU
27	RX_CTL/PHYAD2	O/LI/PD
28	RX_CLK/PHYAD1	O/LI/PD
29	DVDD_RGMII	P
30	DVDD33	P
31	VDD33_LX	P
32	LX	P/O
33	Reserved	IO/PD
34	INT_N/PME_N	O/OD
35, 5	LED0/PHYAD0	O/LI/PU
36	LED1/CFG_LDO0	O/LI/PU
37	LED2/CFG_LDO1	O/LI/PD
38	HSIP	I
39	HSIN	I
40	HSOP	O
41	HSON	O
42	NC	-
43	Reserved	G
44	CLKOUT	0 1
45	XTAL_I	XT
46	XTAL_O	XT
47	AVDDL	P
48	RBIAS O	О
49	GND	G
	01,	



#### 3.4. Transceiver Interface

#### Table 2. Transceiver Interface

No.	Pin Name	Type	Description
2	TRXP0	IO	Media-dependent interface 0, 100Ω transmission line
3	TRXN0	IO	Media-dependent interface 0, 100Ω transmission line
5	TRXP1	IO	Media-dependent interface 1, 100Ω transmission line
6	TRXN1	IO	Media-dependent interface 1, 100Ω transmission line
7	TRXP2	IO	Media-dependent interface 2, $100\Omega$ transmission line
8	TRXN2	Ю	Media-dependent interface 2, 100Ω transmission line
10	TRXP3	IO	Media-dependent interface 3, 100Ω transmission line
11	TRXN3	IO	Media-dependent interface 3, 100Ω transmission line

#### 3.5. Clock

#### Table 3. Clock

No.	Pin Name	Type	Description	
44	CLKOUT	О	Reference Clock Generated from Internal PLL. This pin should be kept floating if the clock is not used by the MAC.     UTP recovery receive clock for Sync Ethernet.     Fiber recovery receive clock for Sync Ethernet.     Crystal clock	
45	XTAL_I	XT	25MHz Crystal Input pin.  If use external oscillator or clock from another device.  1. When connect an external 25Hhz oscillator or clock from another device to XTAL_O pin, XTAL_I must be shorted to GND.  2. When connect an external 25Hhz oscillator or clock from another device to XTAL_I pin, keep the XTAL_O floating.	25
46	XTAL_O	XT	25Mhz Crystal Output pin.  If use external oscillator or clock from another device.  1. When connect an external 25Hhz oscillator or clock from another device to XTAL_O pin, XTAL_I must be shorted to GND.  2. When connect an external 25Hhz oscillator or clock from another device to XTAL I pin, keep the XTAL O floating.	

### 3.6. **RGMII**

#### Table 4. RGMII

No.	Pin Name	Type	Description
16	TXD3	1/PD	Transmit Data.
17	TXD2	I/PD	Data is transmitted from MAC to PHY via TXD[3:0].
18	TXD1	I/PD	1
19	TXD0	I/PD	2
20	TX_CTL	I/PD	Transmit Control Signal from the MAC.
21	TX_CLK	I/PD	The transmit reference clock will be 125Mhz, 25MHz or 2.5MHz depending on speed.
23	RXD3	O/LI/PD	Receive Data.
24	RXD2	O/LI/PD	Data is transmitted from PHY to MAC via RXD[3:0].
25	RXD1	O/LI/PD	G *
26	RXD0	O/LI/PU	4
		, m	3 @ S & N / 8 S



28	RX_CLK	O/LI/PD	The continuous receive reference clock will be 125MHz, 25MHz, or 2.5MHz, and is derived from the received data stream.
27	RX_CTL	O/LI/PD	Receive Control Signal to the MAC.

#### 3.7. SerDes

#### Table 5. SerDes

No.	Pin Name	Type	Description
38	HSIP		SerDes Differential Input: 1.25GHz serial interfaces to receive data from
39	HSIN	T	an External device that supports the SGMII interface.
3)	IISIIV	1	The differential pair has an internal 100 ohm termination resistor.
40	HSOP	О	SerDes Differential Output: 1.25GHz serial interfaces to transfer data
41	HSON	0	from an External device that supports the SGMII interface.
41	HSON	0	Both HSOP and HSON have an internal 50 ohm termination resistor to
			AVDDL, which means the differential impedence is 100 ohm.
			00

#### 3.8. Reset

#### Table 6. Reset

No.	Pin Name	Type	Description
13	RESET_N	I/PU	Hardware reset, active low. Requires an external pull-up resistor

#### 3.9. Mode Selection

#### **Table 7. Mode Selection**

No.	Name Name	Type	Description
35	PHYAD0	O/LI/PU	PHYAD[2:0]. PHY address config
28	PHYAD1	O/LI/PD	
27	PHYAD2	O/LI/PD	_aso`
26	RXDLY	O/LI/PU	RGMII receiver clock timing control Pull-up to add 2ns delay on RX_CLK, which shall be used to latch RXD.
36	CFG_LDO0	O/LI/PU	CFG_LDO[1:0], Voltage selection for RGMII I/O pad 2'b00: 3.3V
37	CFG_LDO1	O/LI/PD	2'b01: 2.5V 2'b10 or 2b'11: 1.8V
25	CFG_MODE0	O/LI/PD	CFG_MODE[2:0]: Operation Mode Configuration. 3'b000: UTP <-> RGMII 3'b001: FIBER <-> RGMII
24	CFG_MODE1	O/LI/PD	3'b010: UTP/FIBER <-> RGMII (Media Auto Detection) 3'b011: UTP <-> SGMII 2'1-100: SGMII (PUN cids) <> PCMII (MAC cids)
23	CFG_MODE2	O/LI/PD	3'b101: SGMII (MAC side) <-> RGMII (MAC side), 3'b101: SGMII (MAC side) <-> RGMII (PHY side) 3'b110: UTP <-> FIBER (Media Conversion auto mode) 3'b111: UTP <-> FIBER (Media Conversion force mode)

### 3.10. LED Default Settings

#### **Table 8. LED Default Settings**

No.	Pin Name	Type	Description
			75
			27 "
			6,
		10	



- 111111			Notifical in the second
35	LED0	O/LI/PU	Light = Link up at 10Mbps
			Blinking = Transiting or Receiving
36	LED1	O/LI/PU	Light = Link up at 100Meps
			Blinking = Transiting or Receiving
37	LED2	O/LI/PD	Light = Link up at 1000Mbps
			Blinking = Transiting or Receiving

#### 3.11. Regulator and Reference

#### Table 9. Regulator and Reference

No.	Pin Name	Type	Description
48	RBIAS	О	Bias Resistor.
			An external 2.49 k $\Omega$ ±1% resistor must be connected between the RBIAS pin and GND
32	LX	P/O	Switch regulator 1.2V output.
			Connect to an external 2.2 uH power inductor directly
			c. 0 m

#### 3.12. Power Related

#### Table 10. Power Related

No.	Pin Name	Type	Description \( \sqrt{0} \)	
30	DVDD33	P	3.3V Power	
			Digital non-RGMII I/O power	5
31	VDD33_LX	P	3.3V power for switching regulator	12
29	DVDD_RGMII	P	Digital RGMII I/O, MDC/MDIO power, adjusted by CFG_LDO[1:0].	Ĩ
	地性有限以下	2)	Note: When $CFG\_LDO[1:0] = 00$ , the I/O pad power is supplied from the external 3.3V power connected to DVDD_RGMII pin. Otherwise, it is supplied from the internal LDO.	
22	DVDDL	P	Digital power 1.2V	
1, 12	AVDD33	P	Analog Power 3.3V	
4, 9, 47	AVDDL	P	Analog power 1.2V	
49	GND	G	Exposed PAD	
			yms	

### 3.13. Management

#### Table 11. Management

No.	Pin Name	Type	Description			
14	MDC	L/PD	Management Data Clock.			
15	MDIO	IO/PU	Input/Output of Management Data. Pull up 3.3V/2.5V/1.8V for 3.3V/2.5V/1.8V I/O respectively			
34	INT_N/PME_N	O/OD	This pin is shared by two functions, the default pin setting is INT_N. Keep this pin floating if either of the functions is not used. The pin type depends on function selected:  1. Interrupt (should be 3.3V pulled up).  Set low if the specified events occurred; active low.  2. Power Management Event (should be 3.3V pulled up).  Set low if received a magic packet, active low.  Note 1: The behavior of INT_N is level-triggered, the behavior of PME N is level-triggered or pulse-triggered which is controled by			
		ν.	S@Seny 8501			



# 性有	AIN COL	
Motorcomm YT8	C C	· 浴太微电子 Motorcomm
The state of the s	EXT 0xA00A bit[0].	
	Note 2: The function of INT_N/PME_N can be assigned by E.	xt
	0xa00a bit[6].  1: Pin 34 functions as PME N.	
	0: Pin 34 functions as INT_N (default).	

#### 3.14. Miscellaneous Pins

#### Table 12. Miscellaneous Pins

No.	Pin Name	Type	Description			
33	Reserved	IO/PD	Reserved for internal use.			
			Keep floating or external pull down.			
			Should not external pull up.			
42	NC	-	NC, keep floating or connect to GND			
43	Reserved	G	Keep floating or connect to GND.			
			Should not connect to VDD or be pulled up.	25		

表別を別様を展展以前 yms@senyasoft.com 2025-03

2025-03-27 2025-03-27



### **Function Description**

#### 4.1. Application Diagram

#### 4.1.1. UTP (UTP<->RGMII / UTP<->SGMII) Application

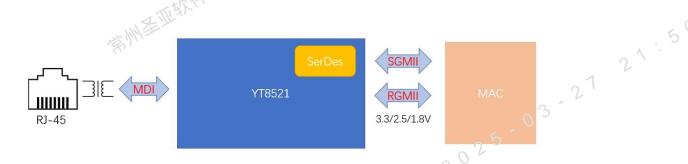


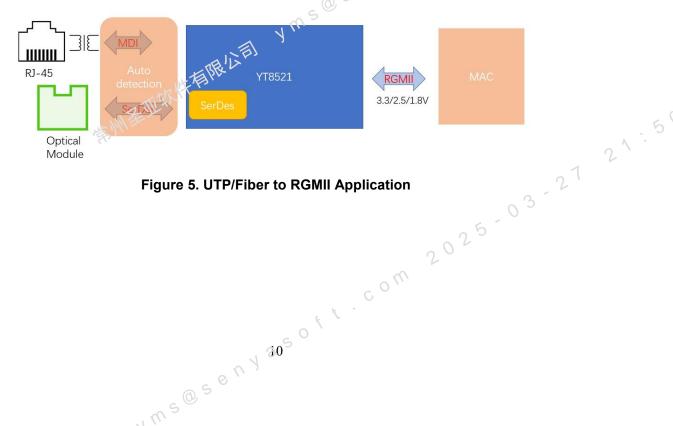
Figure 3. UTP (UTP<->RGMII / UTP<->SGMII) Application

#### 4.1.2. Fiber (FIBER<->RGMII) Application



Figure 4. Fiber (FIBER<->RGMII) Application

#### 4.1.3. UTP/Fiber to RGMII (UTP/FIBER Media Auto Detection RGMII) Application





21.5

#### 4.1.4. SGMII to RGMII (SGMII <->RGMII Bridge Mode) Application

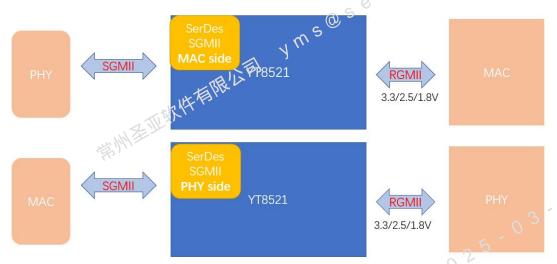


Figure 6. SGMII to RGMII Application

#### 4.1.5. Fiber to UTP (UTP<->FIBER Media Converter) Application



Figure 7. Fiber to UTP Application

There are two modes for Fiber applications. Media Conversion auto mode and Media Conversion force mode. In Media Conversion auto mode, SerDes can choose speed automaticity between 1000BASE-X and 100BASE-FX based on signal received and type of fiber module. Then UTP will choose the speed witch is matched with SerDes automaticly.

In Media Conversion force mode, UTP only has 1030BASET ability and SerDes is configured as 1000BASE-X by default. To manually choose UTP speed, please configure UTP MII register 0x4 and 0x9. To manually choose SerDes speed, please configure common EXT\_Reg\_0xA006 bit[0].

In FIBER <-> RGMII, UTP/FIBER to RGMII and UTP <-> FIBER (Media Conversion auto mode) mode, fiber works in Media Conversion auto mode. In UTP <->FIBER (Media Conversion force mode) mode, fiber works in Media Conversion force mode.

#### 4.2. Transmit Functions

#### 4.2.1. Transmit Encoder Modes

#### 4.2.1.1. 1000BASE-T

In 1000BASE-T mode, the YT8521S scrambles transmit data bytes from the MAC interfaces to 9-bit symbols and encodes them into 4D five-level PAM signals over the four pairs of CAT.5E UTP cable.

4.2.1.2. 100BASE-TX



In 100BASE-TX mode, 4-bit data from the MII is 4B/5B serialized, scrambled, and encoded to a three-level MLT3 sequence transmitted by the PMA.

#### 4.2.1.3. 10BASE-Te

In 10BASE-Te mode, the YT8521S transmits and receives Manchester-encoded data.

#### 4.3. Receive Functions

#### 4.3.1. Receive Decoder Modes

#### 4.3.1.1. 1000BASE-T

In 1000BASE-T mode, the PMA recovers the 4D PAM signals after accounting for the cabling conditions such as skew among the four pairs, the pair swap order, and the polarity of the pairs. The resulting code group is decoded into 8-bit data values. Data stream delimiters are translated appropriately and data is output to the MAC interfaces.

#### 4.3.1.2. 100BASE-TX

In 100BASE-TX mode, the receive data stream is recovered and descrambled to align to the symbol boundaries. The aligned data is then parallelized and 5B/4B decoded to 4-bit data. This output runs to MAC interfaces after data stream delimiters have been translated.

#### 4.3.1.3. 10BASE-Te

In 10BASE-Te mode, the recovered 10BASE-Te signal is decoded from Manchester then aligned.

#### 4.4. LRE100-4

YT8521S supports a Motorcomm proprietary feature called LRE100-4, the long reach Ethernet application up to 400m at 100Mbps days rate by 4-pairs in the CAT.5E UTP cable.

#### 4.5. Echo Canceller

A hybrid circuit is used to transmit and receive simultaneously on each pair. A signal reflects back as an echo if the transmitter is not perfectly matched to the line. Other connector or cable imperfections, such as patch panel discontinuity and variations in cable impedance along the twisted pair cable, also result in drastic SNR degradation on the receive signal. The YT8521S device implements a digital echo canceller to adjust for echo and is adaptive to compensate for the varied channel conditions.

#### 4.6. NEXT Canceller

The 1000BASE-T physical layer uses all four pairs of wires to transmit data. Because the four twisted pairs are bundled together, significant high frequency crosstalk occurs between adjacent pairs in the bundle. The YT8521S device uses three parallel NEXT cancellers on each receive channel to cancel high frequency crosstalk. The YT8521S cancels NEXT by subtracting an estimate of these signals from the equalizer output.

#### 4.7. Baseline Wander Canceller

Baseline wander results from Ethernet links that AC-couple to the transceivers and from AC coupling that cannot maintain voltage levels for longer than a short time. As a result, transmitted pulses are distorted, resulting in erroneous sampled values for affected pulses. Baseline wander is more problematic in the 1000BASE-T environment than in 100BASE-TX due to the DC baseline shift in the transmit and receive signals. The YT8521S device uses an advanced baseline wander cancellation circuit that continuously monitors and compensates for this effect, minimizing the impact of DC baseline shift on the overall error rate.



#### 4.8. Digital Adaptive Equalizer

The digital adaptive equalizer removes inter-symbol interference at the receiver. The digital adaptive equalizer takes unequalized signals from ADC output and uses a combination of feedforward equalizer (FFE) and decision feedback equalizer (DFE) for the best optimized signal-to-noise (SNR) ratio.

#### 4.9. Management Interface

The Status and Control registers of the device are accessible through the MDIO and MDC serial interface. The functional and electrical properties of this management interface comply with IEEE 802.3, Section 22 and also support MDC clock rates up to 12.5 MHz.

#### 4.10. Auto-Negoitation

The YT8521S negotiates its operation mode using the auto negotiation mechanism according to IEEE 802.3 clause 28 over the copper media. Auto negotiation supports choosing the mode of operation automatically by comparing its own abilities and received abilities from link partner. The advertised abilities include:

- Speed: 10/100/1000Mbps
- Duplex mode: full duplex and/or half duplex

Auto negotiation is initialized when the following scenarios happen:

- Power-up/Hardware/Software reset
- Auto negotiation restart
- Transition from power-down to power up
- Link down

Auto negotiation is enabled for YT8521S by default, and can be disabled by software control.

#### 4.11. LDS (Link Discover Signaling)

YT8521S supports long range ethernet (LRE), which uses link discoverr signaling (LDS) instead of auto negotiation since the extended cable reach attenuates the auto negotiation link pulses. LDS is an extended reach signaling scheme and protocol, which is used to:

- Master/Slave assignment
- Estimate cable length
- Confirm pair number and pair connectivity ordering
- Choose highest common operation mode

IEEE-compliant PHYs will ignore LDS signal since its frequency is less than 2MHz according to IEEE802.3 clause 14. If the link partner is an IEEE legacy ethernet PHY, YT\$521S can detect the standard NLP, FLP, or MLT-3 IDLE signal, and then transits LDS mode into Clause 28 auto negotiation mode.

Forcing pair number and speed mode is also supported. The same forcing must be done at both ends of the link. By default the LDS is disabled, and should be enabled before using this feature.

#### 4.12. Polarity Detection and Auto Correction

YT8521S can detect and correct two types of cable errors: swapping of pairs within the UTP cable (swapping between pair 0 and pair 1, and (or) swapping between pair 2 and pair 3) and swapping of wires within a pair.

#### 4.13. Loopback Mode

There are three loopback modes in YT8521S

#### 4.13.1. Digital Loopback

Digital loopback provides the ability to loop transmitted data back to the receiver using digital circuitry in rel com YT8521S.



21.5

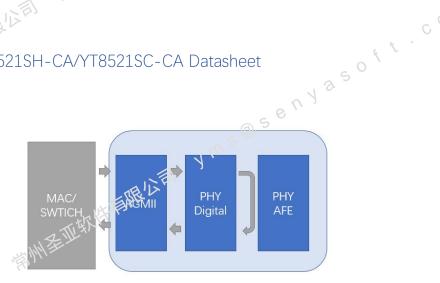


Figure 8. Digital Loopback

#### 4.13.2. External loopback

External cable loopback loops Tx to Rx through a complete digital and analog path and an external cable, thus testing all the digital data paths and all the analog circuits. Figure shows a block diagram of external cable loopback.

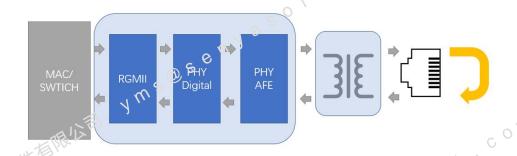


Figure 9. External Loopback

#### 4.13.3. Remote PHY loopback

The Remote loopback connects the MDI receive path to the MDI transmit path, near the RGMII interface, thus the remote link partner can detect the connectivity in the resulting loop. Figure below, shows the path of the remote loopback.

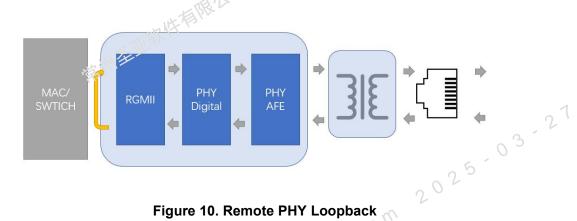


Figure 10. Remote PHY Loopback



#### 4.14. Energy Efficient Ethernet (EEE)

EEE is IEEE 802.3az, an extension of the IEEE 802.3 standard. EEE defines support for the PHY to operate in Low Power Idle (LPI) mode which, when enabled, supports QUIET times during low link utilization allowing both link partners to disable portions of each PHY's circuitry and save power.

YT8521S also helps legacy MAC without EEE ability to work as a complete EEE power saving system.

#### 4.15. Synchronous Ethernet (Sync-E)

YT8521S provides Synchronous Emernet (Sync-E) support when the device is operating in 1000BASE-T, 100BASE-TX, 1000BASE-X and 100BASE-FX on the transmission media. The CLKOUT pin can be assigned to output the recovered clock.

The recovery clock for Sync-E can be either a 125MHz or 25MHz clock.

When the PHY is in SLAVE mode, the CLKOUT will output the recoverd clock from the MDI. If the device is in MASTER mode, the CLKOUT will output the clock based on the local free run PLL.

#### 4.16. Wake-On-LAN (WOL)

Wake-on-LAN (WOL) is a mechanism to manage and regulate the total network power consumption. YT8521S supports automatic detection of a specific frame and notification via dedicated hardware interrupt pin. The specific frame contains a specific data sequence located anywhere inside the packet. The data sequence consists of 6 bytes of consecutive 1 (0xFFFFFFFFFF), followed by 16 repetitions of the MAC address of the computer to be waked up. The 48-bit MAC address can be set in MAC Address Cfg1~3 common registers, refer to section 6.1.8~6.1.10.

#### 4.17. Link Down Power Saving (Sleep Mode)

YT8521S supports link down power saving, also called sleep mode. When UTP port link down and no signals over UTP cable for 40 seconds, YT8521S will enter sleep mode.

For most of time in sleep mode, YT8521S will disable almost all the circuits except crystal clock and comparators for channel 0/1 of 10BASE-Te. Access by MDC/MDIO interface is available.

At a time interval in sleep mode, YT8521S will wake to transmit signals over TRXP1/TRXN1. The time interval is a random value around 2.7s.

Once detect signals over UTP cable, YT8521S will exit sleep mode.

#### 4.18. Interrupt

YT8521S provides an active low interrupt output pin (INT N) based on change of the PHY status. Every interrupt condition is represented by the read-only general interrupt status register (section 6.2.18. Interrupt Status Register (UTP MII register 0x13)).

The interrupts can be individually enable or disable by setting or clearing bits in the interrupt enable register (section 6.2.17. Interrupt Mask Register (UTF MII register 0x12)).

*Note 1: The interrupt of the YT8521S is a level-triggered mechanism.* 

2025-03-27 21.5 2025-03-27 Note 2: The INT N and PME N functions share the same pin (pin 34). Refer to section 5.5. INT N/PME N Pin Usage.



### **Operational Description**

#### 5.1. Reset

YT8521S have a hardware reset pin(RESET N) which is low active. RESET N should be active for at least 10ms to make sure all internal logic is reset to a known state. Hardware reset should be applied after power up. RESET N is also used for power on strapping. After RESET N is released, YT8521S latches input value on strapping pins which are used as configuration information to provide flexibility in application without mdio access.

YT8521S also provides three software reset control registers. Two of them are used to reset all UTP internal logic except some mdio configuration registers, by setting bit 15 of UTP mii register (address 0x0) or LDS mii register (address 0x0). And the third is used to reset all SerDes internal logic except CDR and some mdio configuration registers, by setting bit15 of SerDes mii register(address 0x0) to 1. These three bits are self-clear after reset process is done. For detailed information about what register will be reset by software reset, please refer to register table.

**Table 13. Reset Timing Characteristics** 

Symbol	Description	Min	Typ o	Max	Units
T1	The duration from all powers steady to reset	10		-	ms
	signal release to high		) \		
T2	The duration of reset signal remain low timing	10	-	-	ms

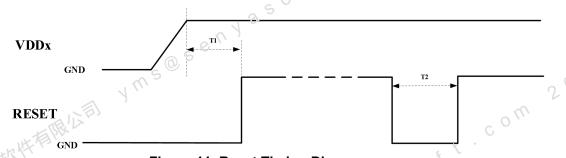


Figure 11. Reset Timing Diagram

#### 5.2. PHY Address

For YT8521S, Strapping PHYAD[2:0] is used to generate phy address.

YT8521S always responses to phy address 0. It can be disabled by configure bit[6] to 1'b0 of extended register(address 0xa005). It also has another broadcast phy address which is configurable through mdio. Bit[4:0] of extended register (address 0xa005) is broadcast phy address and its default value is 5'b11111. Bit[5] of extended register(address 0xa005) is enable control for broadcast phy address and its default value is 1'b0.

#### 5.3. RGMII Interface

Reduced gigabit media independent interface is a subset of GMII which is used for gigabit Ethernet. For 100M/10M application, RGMII is similar to MII. The only difference is that tx er/rx er is transmitted by an risi
2025 - 03
2025 - 03 TX CTL/RX CTL on the falling edge of clock. TXD[3:0] and RXD[3:0] will be duplicated on both rising and falling edge of clock.

For 100M application, TX CLK and RX CLK are 25MHz.

For 10M application, TX CLK and RX CLK are 2.5MHz.



03-21 21:5

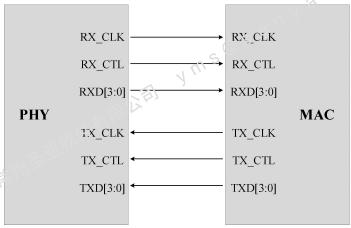


Figure 12. Connection Diagram of RGMII

#### 5.4. LED

The LED interface can either be controlled by the PHY or controlled manually, independent of the state of the PHY. Three status LEDs are available. These can be used to indicate operation speed, duplex mode, and link status. The LEDs can be programmed to different status functions from their default value. They can also be controlled directly from the register interface.

#### 5.5. INT N/PME N Pin Usage

The INT N/PME N pin (pin 34) is designed to notify both interrupt and WOL events. The default mode of this pin is INT N (Ext 0xa00a, bit[6]=0). For general use, indication of a WOL event is also integrated into one of the interrupt events which is triggered when any specified WOL event occurs. However, the 'Pulse Low' waveform' format is not supported during this mode; only the Active Low, level-triggered waveform is provided. If PME N mode is selected (Ext 0xa00a, bit[6]=1), pin 34 becomes a fully functional PME N pin. Note that the interrupt function is disabled in this mode.

#### 5.6. Power Supplies

The YT8521S device requires only one external power supply: 3.3 V. Inside the chip there is a 3.3V rail, 1.2V rail, 2.5V or 1.8V rail.

#### 5.6.1. Internal Switch Regulator

YT8521S integrates a switch regulator which converts 3.3V to 1.2V at a high-efficiency for core power rail. It is optional for an external regulator to provide this core voltage.

#### 5.6.2. Internal LDO

27.5 YT8521S also integrates a LDO which converts 3.3V to 2.5V or 1.8V for RGMII I/O power rail and configured by CFG LDO[1:0].

Table 14. CFG\_LDO[1:0] Configuration

Configuration	Description				
2'b01	LDO is set to 2.5V				
2'b10 or 2'b11	LDO is set to 1.8V				
2'b00	Use external 3.3V to supply to DVDD_RGMII pin.				
2 000	LDO is disabled				
, m	5@5eny 2750ft.com				



### 6. Register Overview

#### Table 15. Register Access Types

Type	Description
RW	Read and write
SC	Self-clear.  If default value is '0' ('1'), writing a '1' ('0') to this register field causes the function to be activated immediately, and then the field will be automatically cleared to '0' ('1').
RO	Read only.
LH	Latch high.
LL	Latch Low.
RC	Read clear.
SWC	Software reset to 0.
SWS	Software reset to 1.
POS	Default value depends on power on strapping.

### 6.1. Common Register

#### 6.1.1. SMI\_SDS\_PHY (EXT\_0xA000)

#### Table 16. SMI\_SDS\_PHY (EXT\_0xA000)

Bit	Symbol	Access	Default	Description
15:2	Reserved	RO	0x0	Reserved
1	Smi_sds_phy	RW POS	0x0	to control access whether UTP register or SDS register.  1 to access SDS;  0 to access UTP.  Default value depend on chip mode. When the UTP port exsits, default 0; else default 1. Refer AP note for details.
0	Reserved	RO	0x0	Reserved

#### 6.1.2. Chip\_Config (EXT\_0xA001)

#### Table 17. Chip Config (EXT\_0xA001)

Bit	Symbol	Access	Default	Description	
15	Sw_rst_n_mode	RW SC	0x1	A whole chip software reset, it will also be asserted when chip mode changed, low active, self clear	
14:12	Reserved	RO	0x0	Reserved	
11	Iddq_mode	RW	0x0	Iddq test mode	
10:9	Reserved	RO	0x0	Reserved	
8	Rxc_dly_en	RW POS	0x1	rgmii clk 2ns delay control, depends on strapping	
7	Reserved	RO	0x0	Reserved	
6	En_ldo	RW	0x1	rgmii ldo enable, default is 0 and will be set to 1 after power on strapping is done	
5:4	Cfg_ldo	RW POS	0x0	Rgmii ldo voltage control. Depends on strapping. 2'b11: 1.8v	
1 m s @ s e n y 38 s o					



Moto	preomm YT8521SH-CA	/YT8521SC	-CA Data	asheet ※A太微电子	
	<i>5</i> , <i>y</i>			2'b10: 1.8v 2'b01: 2.5v 2'b09: 3.3v	
3	Reserved	RO	0x0	Reserved	
2:0	Mode_sel	RW POS	0x0	chip mode, depend on strapping. 3'b000: UTP_TO_RGMII; 3'b001: FIBER_TO_RGMII; 3'b010: UTP_FIBER_TO_RGMII; 3'b011: UTP_TO_SGMII; 3'b100: SGPHY_TO_RGMAC; 3'b101: SGMAC_TO_RGPHY; 3'b110: UTP_TO_FIBER_AUTO; 3'b111: UTP_TO_FIBER_FORCE.	
6.1.3. SDS_Config (EXT_0xA002) Table 18. SDS_Config (EXT_0xA002)					
Bit	Symbol	Access	Default		

#### 6.1.3. SDS\_Config (EXT\_0xA002)

#### Table 18. SDS\_Config (EXT\_0xA002)

Bit	Symbol	Access	Default	<b>Description</b>
15:13	Reserved	RO	0x0	Reserved
12	En_surppress_txer	RW	0x1	1: to surppress the RX_ER generated by the serdes when it works in SGMII PHY full duplex mode and RX_DV is 0 and rx_lpi_active is 0; 0: to not surppress.
11	Reserved	RWS	0x1	Reserved
10:8	Reserved	RO	0x0	Reserved
7:0	Reserved	RW	0x80	Reserved

#### 6.1.4. RGMII\_Config1 (EXT\_0xA003)

### Table 19. RGMII\_Config1 (EXT\_0xA003) 5

	Table 19. Kdwiii_Colling1 (EX1_0XA003)					
Bit	Symbol	Access	Default	Description		
15	Rgmac_cfg_mode	RW	0x0	When chip mode is SGPHY_TO_RGMAC, it controls the source of the RGMII's speed, duplex and link status. These information will be sent to the SGMII PHY.  1: RGMII's speed, deplex, link status		
	11. 英	性有限		information comes from EXT 0xA004; 0: these information comes from RGMII OOB. Refer EXT 0xA005 for detail.		
14	Tx_clk_sel	RW	0x0	0: use original RGMII TX_CLK to drive the RGMII TX_CLK delay train; 1: use inverted RGMII TX_CLK to drive the RGMII TX_CLK delay train. Used for debug		
13:10	Rx_delay_sel	RW	0x0	RGMII RX_CLK delay train configuration, about 150ps per step		
9	En_rgmii_fd_crs	RW	0x0	See EXT 0xA003 bit[8].		
8	En_rgmii_crs	RW	0x0	0: to not encode GMII/MII CRS into RGMII OOB; 1: to encode GMII/MII CRS into RGMII OOB when it's half duplex mode or EXT 0xA003		
INSOSENY 39SO						



_					
	The same				bit[9] is 1.
	7:4	Tx_delay_sel_fe	RW	0xf	RGMH TX_CLK delay train configuration when speed is 100Mbps or 10Mbps, it's 150ps per step typically.
	3:0	Tx_delay_sel	RW	0x1	RGMII TX_CLK delay train configuration when speed is 1000Mbps, it's 150ps per step typically.

#### 6.1.5. RGMII\_Config2 (EXΓ\_0xA004)

#### Table 20. RGMII\_Config2 (EXT\_0xA004)

Bit	Symbol	Access	Default	Description
15:14	Speed_rgphy	RO	0x0	RGMII's speed information when it works as RGMII PHY. It's also the source of RGMII OOB.
13	Duplex_rgphy	RO	0x0	RGMII's duplex information when it works as RGMII PHY. It's also the source of RGMII OOB.
12	Link_up_rgphy	RO	0x0	RGMII's linkup information when it works as RGMII PHY. It's also the source of RGMII OOB.
11:10	Pause_rgphy	RO	0x0	RGMII's pause information when it works as RGMII PHY.
9	Eee_cap_rgphy	RO	0x0	RGMII's EEE capability information when it works as RGMII PHY.
8	Eee_clkstp_cap_rgphy	RO	0x0	RGMII's EEE clock stopable capability information when it works as RGMII PHY.
7:6	Speed_rgmac	RW	0x0	RGMII's speed configuration when it works as RGMII MAC and EXT A003 bit[15] is 1.
5	Duplex_1gmac	RW	0x0	RGMII's duplex configuration when it works as RGMII MAC and EXT A003 bit[15] is 1.
4	Link_up_rgmac	RW	0x0	RGMII's linkup configuration when it works as RGMII MAC and EXT A003 bit[15] is 1.
3:2	Pause_rgmac	RW	0x0	RGMII's pause configuration when it works as RGMII MAC.
1	Eee_cap_rgmac	RW	0x0	RGMII's EEE capability configuration when it works as RGMII MAC.
0	Eee_clkstp_cap_mac	RW	0x0	RGMII's EEE clock stopable capability configuration when it works as RGMII MAC.

#### 6.1.6. MDIO\_Cfg\_And\_RGMII\_OOB\_Mon (EXT\_0xA005)

#### Table 21. MDIO\_Cfg\_And\_RGMII\_OOB\_Mon (EXT\_0xA005)

Bit	Symbol	Access	Default	Description		
15:14	Speed_rgmac_ob	RO	0x0	speed information RGMII MAC decods from the OOB		
13	Duplex_rgmac_ob	RO	0x0	duplex information RGMII MAC decods from the OOB		
12	Link_up_rgmac_ob	RO	0x0	linkup information RGMII MAC decods from the OOB		
11	Reserved	RO	0x0	Reserved G		
10	Bypass_mdio_watchdog	RW	0x0	bypass mdio watch dog		
20°S						



Moto	reomm YT8521SH-CA/Y	T8521SC-	-CA Data	asheet 裕太微电子 Motorcomm
9:8	Reserved	RO	0x0	Reserved
7	En_mdc_la	RW	0x1	enable mdc latch for read data
6	En_phyaddr0	RW	0x1	1; to always respond to MDIO command whose PHYAD field is 0; 0: to only respond to MDIO command whose PHYAD filed equals to PHY address strapping.
5	En_bdcst_addr	RW	0x0	enable broadcast address
4:0	Bdcst_addr	RW	0x0	broadcast address

#### 6.1.7. Misc\_Config (EXT\_0xA006)

#### Table 22. Misc\_Config (EXT\_0xA006)

6.1.7.	Misc_Config (EXT_0xA			1
	Та	ble 22. Mis	sc_Config	(EXT_0xA006)
Bit	Symbol	Access	Default	Description
15:12	Clk_out_sel	RW	0x0	select debug clock output to pin RX_CLK
11	En_dbg_data_todac	RW	0x0	output adc data to dac for debug
10	En_output_clk	RW	0x0	enable debug clock output to pin RX_CLK
9	Reserved	RW	0x0	Reserved
8	Fiber_high_pri_cmb	RW	0x0	1=fiber has higher priority in UTP_FIBER_TO_RGMII mode, else UTP has higher priority
7	Jumbo_enable	RW	0x0	enable jumbo frame
6	Rem_lpbk_sds	RW e	0x0	set remote loopback for SDS
5	Rem_lpbk_phy	RWS	0x0	set remote loopback for UTP
4	Uldata_rloopback	RW	0x0	1=remain upload data when rem lpbk is set for phy or sds
3	Bp_gmii_fatal_rst	RW	0x1	bypass gmii fifo overflow and underflow rst
2:1	Comb_wes_timer_sel	RW	0x2	select wait timer for first priority media after second priority media is link up; 2'b00: 1s; 2'b01: 5s; 2'b10: 15s; 2'b11: 25s
0	Fib_speed_sel	RW	0x1	Select fiber speed when auto sensing is disable; 1: 1000BX; 0: 100FX

#### 6.1.8. MAC\_Address\_Cfg1 (EXT\_0xA007)

#### Table 23. MAC\_Address\_Cfg1 (EXT\_0xA007)

6.1.8. MAC_Address_Cfg1 (EXT_0xA007) Table 23. MAC_Address_Cfg1 (EXT_0xA007)						
Bit	Symbol	Access	Default	Description	21	
15:0	mac_addr_loc_47_32	RW	0x0	highest 16 bits of MAC address used for WOL		
				1	-	
6.1.9.	MAC_Address_Cfg2	(EXT_0xA0	008)	5		
	Tab	le 24. MAC_	Address_	Cfg2 (EXT_0xA008)		
Bit	Symbol	Access	Default	Description	]	

#### 6.1.9. MAC\_Address\_Cfg2 (EXT\_0xA008)

#### Table 24. MAC Address Cfg2 (EXT 0xA008)

		_	_	3 ( = 1117)
Bit	Symbol	Access	Default	Description
15:0	mac_addr_loc_31_16	RW	0x0	middle 16 bits of MAC address used for WOL



#### 6.1.10. MAC\_Address\_Cfg3 (EXT\_0xA009)

#### Table 25. MAC Address Cfg3 (EXT 0xA009)

Bit	Symbol	Access	Default	Description
15:0	mac_addr_loc_15_0	RW	0x0	lowest 16 bits of MAC address used for WOL

#### 6.1.11. WOL Cfg (EXT 0xA00A)

#### 1 able 26. WOL\_Cfg (EXT\_0xA00A)

Bit	Symbol	Access	Default	Description
15:7	Reserved	RO	0x0	Reserved
6	Pmeb_intb_sel	RW	0x0	1: Pin 34 functions as PME_N. 0: Pin 34 functions as INT_N.
5	Wol_src_manual	RW	0x0	1: control manually the source of the WOL event coms from which media; 0: the source of the WOL event is controlled automatically by chip mode: when UTP is present, it comes UTP; otherwise, it coms from SDS.
4	Wol_src_sel	RW	0x0	It's valid when EXT_0xA00A bit[5] is 1. 1: WOL event comes from SDS; 0: WOL event comes from UTP.
3	Wol_en	RW	0×0	enable WOL.
2:0	Wol_lth_sel	RWS	0x2	wol_lth_sel[0], 1: PME_N is level triggerd and active LOW; When PME_N is LOW, EXT 0xA00A bit3 wol_en should be set to 0 to clear the PME_N. 0: PME_N is pulse triggered and active LOW, the pusel width is controlled by wol_lth_sel[2:1].  Wol_lth_sel[2:1]: 00: 84ms; 01: 168ms; 10: 336ms; 11: 672ms.

#### 6.1.12. LED\_GENERAL\_CFG (EXT\_9xA00B)

#### Table 27 LED\_GENERAL\_CFG (EXT\_0xA00B)

Bit	Symbol	Access	Default	Description		
15	Col_blk_sel	RW	0x1	1 = when collision happens, and related LEDn cfg (n is 0/1/2) register's bit3 led_col_blk_en is 1, LED blink at Blink Mode2; 0 = when collision happens, and related LEDn cfg (n is 0/1/2) register's bit3 led_col_blk_en is 0, LED blink at Blink Mode1.  LED could blinks at different frequency in Blink Mode1 and Blink Mode2. Refer to EXT A00F[3:0] for the Blink Mode2 and Blink Mode1.		
14	Jabber_led_dis	RW	0x1	1 = when 10Mb/s Jabber happens, LED will not blink;		
	Dlink;					



					· ·
13	Lpbk_led_dis	RW	0x1	1 = In internal hoopback mode, LED will not blink;	
12	Dis_led_an_try	RW	0x0	1: DED will be ON when auto-negotiation is at LINK_GOOD_CHECK status, in which status, the link is not up already.	
11:9	Reserved	RO	0x0	Reserved	
8	Led_2_force_en	RV	0x0	1 = enable LED2 force mode.	
7:6	Led_2_force_mode	RW	0x0	Valid when bit8 is set.  00: force LED OFF;  01: force LED ON;  10: force LED Blink at Blink Mode2;  11: force LED Blink at Blink Mode1.  LED could blinks at different frequency in Blink Mode1 and Blink Mode2. Refer to EXT A00F[3:0] for the Blink Mode2 and Blink Mode1.	21.5
5	Led_1_force_en	RW	0x0	1 = enable LED1 force mode.	
4:3	Led_1_force_mode	RW	0x0	Valid when bit5 is set.  Refer EXT A00B[7:6] for the force mode description.	
2	Led_0_force_en	RW	0x0	1 = enable LED0 force mode.	
1:0	Led_0_force_mode	RW	0x0 5	Valid when bit2 is set.  Refer EXT A00B[7:6] for the force mode description.	03
		( (b) 5			-25
6.1.13	. LEDO_CFG (EXT_OXA		D0_CFG	(EXT_0xA00C)	
Bit	Symbol	Access	 Default	Description	
	+ · · · · · · · · · · · · · · · · · · ·	<b>-</b>			

#### 6.1.13. LED0\_CFG (EXT\_0xA00C)

#### Table 28. LED0\_CFG (EXT\_0xA00C)

Bit	Symbol	Access	Default	Description
15:14	Led_src_sel_0	RW POS	0x0	select the source of internal signals controlling LED0. 2'b00: UTP 2'b01: serdes 2'b10: UTP and serdes 2'b11: UTP or serdes Default value of LED0 cfg depends on the strapping of chip mode.
13	Led_act_blk_ind_0	RW POS	9x0	When traffic is present, make LED0 BLINK no matter the previous LED0 status is ON or OFF, or make LED0 blink only when the previous LED0 is ON.
12	Led_fdx_on_en_0	RW POS	0x0	1: If BLINK status is not activated, when PHY link up and duplex mode is full duplex, LED0 will be ON.
11	Led_hdx_on_en_0	RW POS	0x0	1: If BLINK status is not activated, when PHY link up and duplex mode is half duplex, LED0 will be ON.
10	Led_txact_blk_en_0	RW POS	0x1	1: If bit[13] is 1, or bit[13] is 0 and ON at certain speed or duplex more is/are activated, when PHY link up and TX is active, make LED0 blink at mode2.
9	Led_rxact_blk_en_0	RW POS	0x1	1: If bit[13] is 1, or bit[13] is 0 and ON at certain speed or duplex more is/are activated, when PHY link up and RX is active, make LED0 blink
		5@5e <sup>1</sup>	235	



	世有限以前,			com	
Moto	preomm YT8521SH-CA/Y	T8521SC	-CA Data	asheet 裕太微电子 Motorcomm	
K.				at mode2.	
8	Led_txact_on_en_0	RW POS	0x0	1: if BLINK status is not activated, when PHY link up and TX is active, make LED0 ON at least 10ms.	
7	Led_rxact_on_en_0	RW POS	0x0	1: if BLINK status is not activated, when PHY link up and RX is active, make LED0 ON at least 10ms.	
6	Led_gt_on_en_0	RW POS	0x0	1: if BLINK status is not activated, when PHY link up and speed mode is 1000Mbps, make LED0 ON.	E
5	Led_ht_on_en_0	RW POS	0x0	1: if BLINK status is not activated, when PHY link up and speed mode is 100Mbps, make LED0 ON;	21:
4	Led_bt_on_en_0	RW POS	0x1	1: if BLINK status is not activated, when PHY link up and speed mode is 10Mbps, make LED0 ON;	
3	Led_col_blk_en_0	RW POS	0x0	1: if PHY link up and collision happen, make LED0 BLINK;	
2	Led_gt_blk_en_0	RW POS	0x0	1: if PHY link up and speed mode is 1000Mbps, make LED0 BLINK;	
1	Led_ht_blk_en_0	RW POS	0x0	1: if PHY link up and speed mode is 100Mbps, make LED0 BLINK;	
0	Led_bt_blk_en_0	RW POS	0x0	1: if PHY link up and speed mode is 10Mbps, make LED0 BLINK;	
		@ S			5
6.1.14	I. LED1_CFG (EXT_0xA		D1_CFG	(EXT_0xA00D)	25.0
Bit	Symbol	Access	Default	Description	7

#### 6.1.14. LED1\_CFG (EXT\_0xA00D)

#### Table 29. LED1\_CFG (EXT\_0xA00D)

Bit	Symbol	Access	Default	Description
15:14	Led_src_sel_1	RW POS	0x0	Same logic as LED0 control.
13	Led_act_blk_ind_1	RW POS	0x0	Same logic as LED0 control.
12	Led_fdx_on_en_1	RW POS	0x0	Same logic as LED0 control.
4	Led_hdx_on_en_1	RW POS	0x0	Same logic as I ED0 control.
10	Led_txact_blk_en_1	RW POS	0x1	Same logic as LED0 control.
9	Led_rxact_blk_en_1	RW POS	0x1	Same logic as LED0 control.
8	Led_txact_on_en_1	RW POS	0x0	Same logic as LED0 control.
7	Led_rxact_on_en_1	RW POS	0x0	Same logic as LED0 control.
6	Led_gt_on_en_1	RW POS	0x0	Same logic as LED0 control.
5	Led_ht_on_en_1	RW POS	0x1	Same logic as LED0 control.
4	Led_bt_on_en_1	RW POS	0x0	Same logic as LED0 control.
3	Led_col_blk_en_1	RW POS	0x0	Same logic as LED0 control.
2	Led_gt_blk_en_f	RW POS	0x0	Same logic as LED0 control.
1	Led_ht_blk_en_1	RW POS	0x0	Same logic as LED0 control.
0	Led_bt_blk_en_1	RW POS	0x0	Same logic as LED0 control.

#### 6.1.15. LED2\_CFG (EXT\_0xA00E)

#### Table 30. LED2\_CFG (EXT\_0xA00E)

0	Led_bt_blk_en_1	RW POS	0x0	Same logic as LED0 control.	
				03	
6.1.15	. LED2_CFG (EXT_0xA	.00E)		25	
	T	able 30. LE	D2_CFG	(EXT_0xA00E)	
Bit	Symbol	Access	Default	Description	
15:14	Led_src_sel_2	RW POS	0x0	Same logic as LED0 control.	
13	Led_act_blk_ind_2	RW POS	0x0	Same logic as LED0 control.	
1 m 5 @ 5 e n y 24 5 0					



N.A.	TOFOLOU CAN	T050400					
OJOIVI	Motorcomm YT8521SH-CA/YT8521SC-CA Datasheet 裕太微电子						
12	Led_fdx_on_en_2	RW POS	0x0	Same logic as LED0 control.			
11	Led_hdx_on_en_2	RW POS	0x0	Same logic as LED0 control.			
10	Led_txact_blk_en_2	RW POS	0x1	Same logic as LED0 control.			
9	Led_rxact_blk_en_2	RW POS	0x1	Same logic as LED0 control.			
8	Led_txact_on_en_2	RW POS	0x0	Same logic as LED0 control.			
7	Led_rxact_on_en_2	RW POS	0x0	Same logic as LED0 control.			
6	Led_gt_on_en_2	RW POS	0x1	Same logic as LED0 control.			
5	Led_ht_on_en_2	RW POS	0x0	Same logic as LED0 control.			
4	Led_bt_on_en_2	RW POS	0x0	Same logic as LED0 control.			
3	Led_col_blk_en_2	RW POS	0x0	Same logic as LED0 control.			
2	Led_gt_blk_en_2	RW POS	0x0	Same logic as LED0 control.			
1	Led_ht_blk_en_2	RW POS	0x0	Same logic as LED0 control.			
0	Led_bt_blk_en_2	RW POS	0x0	Same logic as LED0 control.			

#### 6.1.16. LED\_BLINK\_CFG (EXT\_0xA00F)

#### Table 31. LED BLINK CFG (EXT 0xA00F)

Table of EED_DEHAT_of G (EXT_GXXTOF)						
Symbol	Access	Default	Description			
Reserved	RO	0x0	Reserved			
Led duty	RW	0x0 s	Select duty cycle of Blink:			
			000: 50% ON and 50% OFF;			
	0. (	,	001: 67% ON and 33% OFF;	03		
	@5		010: 75% ON and 25% OFF;	6		
	5		011: 83% ON and 17% OFF;	25		
1 4				)		
			101: 33% ON and 67% OFF;			
AE IX			110: 25% ON and 75% OFF;			
11 11 11 11 11 11 11 11 11 11 11 11 11			111: 17% ON and 83% OFF.			
Freq sel 2	RW	0x1	Select frequency of Blink Mode2:			
			00: 2Hz;			
			01: 4Hz;			
			10: 8Hz;			
			11: 16Hz.			
Freq_sel_1	RW	0x2	Select frequency of Blink Model:			
		10	00: 2Hz;			
			01: 4Hz;			
	TRU		10: 8Hz;			
	此相外		11: 16Hz.			
	Reserved Led_duty  Freq_sel_2	Reserved RO Led_duty RW  Freq_sei_2 RW	Symbol Access Default   Reserved RO 0x0   Led_duty RW 0x0   Freq_sei_2 RW 0x1	Reserved   RO   0x0   Reserved		

#### 6.1.17. Pad Drive Strength Cfg (EXT\_0xA010)

#### Table 32. Pad Drive Strength Cfg (EXT\_0xA010)

Bit	Symbol	Access	Default	Description		
15:10	Reserved	RO	0x0	Reserved		
9:8	Dr_sync_e	RW	0x3	Drive strenght of SyncE pad. 2'b11: strongest; 2'b00: weakest		
7:6	Dr_mdio	RW	0x3	Drive strenght of mdio pad 2'b11: strongest; 2'b00: weakest		
5:4	Dr_rx_rgmii	RW POS	0x1	Drive strenght of rx rgmii pad. 2'b11: strongest; 2'b00: weakest, depend on rgmii IO voltage level		
25 <sup>5</sup>						



3:2	Reserved	RW	0x3	Reserved
1:0	Dr_led	RW	0x3	Drive strenght of led io pad. 2'b11: strongest; 2'b00: weakest

#### 6.1.18. SyncE CFG (EXT 0xA012)

#### Table 33. SyncE\_CFG (EXT\_0xA012)

Bit   Symbol   Access   Default   Description     15:7   Reserved   RO   0x0   Reserved     6   Phy_do_fib   RW   0x1   1: In UTP_TO_FIBER mode, do not enable UTP until fiber links up.   5   En_sync_e   RW   0x0   enable SyncE clock output     4   En_sync_e_during_lnkdn   RW   0x0   always output SyncE clock even when link is down     3   Clk_fre_sel   RW   0x1   1'b1: output 125m clock;     1'b0: output 25m clock;     2'b0: pll clock;     2'b0: pll clock;     2'b0: pll clock;     2'b0: pll clock;     2'b1: 25MHz crystal clock     0   Reserved   RW   0x0   Reserved     6.2.1   Basic Control Register (0x00)     Table 34. Basic Control Register (0x00)			<u></u>			1
Phy_do_fib   RW   0x1   1: In UTP_TO_FIBER mode, do not enable UTP until fiber links up.	Bit	Symbol	Access	Default	Description	
until fiber links up.	15:7	Reserved	RO	0x0	Reserved	
4 En_sync_e_during_lnkdn RW 0x0 always output SyncE clock even when link is down  3 Clk_fre_sel RW 0x1 l'b1: output 125m clock; l'b0: output 25m clock; l'b0: output 25m clock  2:1 Clk_src_sel RW 0x0 select clock source of SyncE. 2'b00: pll clock; 2'b01: utp recovered rx clock; 2'b10: sds recovered rx clock; 2'b11: 25MHz crystal clock  0 Reserved RW 0x0 Reserved  6.2. UTP MII Register  6.2.1. Basic Control Register (0x00) Table 34. Basic Control Register (0x00)	6	Phy_do_fib	RW	0x1		21.
down  Clk_fre_sel RW 0x1 1'b1: output 125m clock; 1'b0: output 25m clock  Clk_src_sel RW 0x0 select clock source of SyncE. 2'b00: pll clock; 2'b01: utp recovered rx clock; 2'b10: sds recovered rx clock; 2'b11: 25MHz crystal clock  RW 0x0 Reserved  6.2. UTP MII Register  6.2.1. Basic Control Register (0x00)  Table 34. Basic Control Register (0x00)	5	En_sync_e	RW	0x0	enable SyncE clock output	
1'b0: output 25m clock  2:1 Clk_src_sel RW 0x0 select clock source of SyncE. 2'b00: pll clock; 2'b01: utp recovered rx clock; 2'b10: sds recovered rx clock; 2'b11: 25MHz crystal clock  0 Reserved RW 0x0 Reserved  6.2. UTP MII Register  6.2.1. Basic Control Register (0x00) Table 34. Basic Control Register (0x00)	4	En_sync_e_during_lnkdn	RW	0x0		
2'b00: pll clock; 2'b01: utp recovered rx clock; 2'b10: sds recovered rx clock; 2'b11: 25MHz crystal clock  RW 0x0 Reserved  6.2. UTP MII Register  6.2.1. Basic Control Register (0x00)  Table 34. Basic Control Register (0x00)	3	Clk_fre_sel	RW	0x1	-	
6.2. UTP MII Register  6.2.1. Basic Control Register (0x00)  Table 34. Basic Control Register (0x00)	2:1	Clk_src_sel	RW	0x0	2'b00: pll clock; 2'b01: utp recovered rx clock; 2'b10: sds recovered rx clock;	
6.2.1. Basic Control Register (0x00)  Table 34. Basic Control Register (0x00)	0	Reserved	RW	0x0	Reserved	
tunio in a sin a s		Basic Control Register	` '	ia Contra	L Pagintar (0x00)	25
	Bit	Symbol	Access	Default		1

# 6.2. UTP MII Register

#### 6.2.1. Basic Control Register (0x00)

#### Table 34. Basic Control Register (0x00)

Bit	Symbol	Access	Default	Description
15 	Reset	RW SC	0x0	PHY Software Reset. Writing 1 to this bit causes immediate PHY reset. Once the operation is done, this bit is cleared automatically.  9: Normal operation 1: PHY reset
14	Loopback	RW SWC	0x0	Internal loopback control 1'b0: disable loopback 1'b1: enable loopback
13	Speed_Selection(LSB)	RW	0x0	LSB of speed_selection[1:0]. Link speed can be selected via either the Auto-Negotiation process, or manual speed selection speed_selection[1:0]. Speed_selection[1:0] is valid when Auto-Negotiation is disabled by clearing bit 0.12 to zero.  Bit6 bit13  1 1 = Reserved 1 0 = 1000Mb/s 0 1 = 100Mb/s 0 0 = 10Mb/s
12	Autoneg_En	RW	0x1	1: to enable auto-negotiation; 0: auto-negotiation is disabled.
11	Power_down	RW SWC	0x0	1 = Power down
	, 10	5 <sup>@</sup> 5 <sup>©</sup>	265	



Moto	preomm YT8521SH-CA/Y	T8521SC-	CA Data	
			El ym	0 = Normal operation When the port is switched from power down to normal operation, software reset and Auto-Negotiation are performed even bit[15] RESET and bit[9] RESTART_AUTO_NEGOTIATION are not set by the user.
10	Isolate	RW SWC	0x0	Isolate phy from RGMII/SGMII/FIBER. 1'b0: Normal mode 1'b1: Isolate mode
9	Re_Autoneg	RW SC SWS	0x0	Auto-Negotiation automatically restarts after hardware or software reset regardelss of bit[9] RESTART.  1 = Restart Auto-Negotiation Process 0 = Normal operation
8	Duplex_Mode	RW	0x1	The duplex mode can be selected via either the Auto-Negotiation process or manual duplex selection. Manual duplex selection is allowed when Auto-Negotiation is disabled by setting bit[12] AUTO NEGOTIATION to 0.  1 = Full Duplex 0 = Half Duplex
7	Collision_Test	RW SWC	0x0	Setting this bit to 1 makes the COL signal asserted whenever the TX_EN signal is asserted.  1 = Enable COL signal test 0 = Disable COL signal test
6	Speed_ Selection(MSB)	RW	0x1	See bit13.
5:0	Reserved	RO	0x0	Reserved. Write as 0, ignore on read

#### 6.2.2. Basic Status Register (0x01)

#### Table 35. Basic Status Register (0x01)

Bit	Symbol	Access	Default	<b>Description</b>		
15	100BASE-T4	RO	0x0	PHY doesn't support 100BASE-T4		
14	100BASE-X_Fd	RO	0x1	PHY supports 100BASE-X_FD		
13	100BASE-X_Hd	RO	0x1	PHY supports 100BASE-X_HD		
12	10Mbps_Fd	RO	0x1	PHY supports 10Mbps_Fd		
11	10Mbps_Hd	RO	0x1	PHY supports 10Mbps_Hd		
10	100BASE-T2_Fd	RC	0x0	PHY doesn't support 100BASE-T2_Fd		
9	100BASE-T2_Hd	RO	0x0	PHY doesn't support 100BASE-T2_Hd		
8	Extended_Status	RO	0x1	Whether support EXTended status register in MII 0xF 0: Not supported 1: Supported		
7	Unidirect_Ability	RO	0x0	1'b0: PHY able to transmit from MII only when the PHY has determined that a valid link has been established 1'b1: PHY able to transmit from MII regardless of whether the PHY has determined that a valid link has been established		
6	Mf_Preamble_Suppression	RO	0x1	1'b0: PHY will not accept management frames with preamble suppressed 1'b1: PHY will accept management frames with		
21 <sup>5</sup>						



· N 11/11 1 -				'/
F				preamble suppressed
5	Autoneg_Complete	RO SWC	0x0	1'b0: Auto-negotiation process not completed 1'b1: Auto-negotiation process completed
4	Remote_Fault	RO RC SWC LH	0x0	1'b0: no remote fault condition detected 1'b1: remote fault condition detected
3	Autoneg_Ability	RO	0x1	1'b0: PHY not able to perform Auto-negotiation 1'b1: PHY able to perform Auto-negotiation
2	Link_Status	RO LL SWC	0x0	Link status 1'b0: Link is down 1'b1: Link is up
1	Jabber_Detect	RO RC SWC LH	0x0	10BASE-Te jabber detected. It would assert if TX activity lasts longer than 42ms. 1'b0: no jabber condition detected 1'b1: Jabber condition detected.
0	Extended_Capability	RO	0x1	To indicate whether support EXTended registers, to access from address register 0x1E and data register 0x1F 1'b0: Not supported 1'b1: Supported

#### 6.2.3. PHY Identification Register1 (0x02)

#### Table 36. PHY Identification Register1 (0x02)

Bit	Symbol	Access	Default	Description
15:0	Phy_Id	RO 0	0x0	Bits 3 to 18 of the Organizationally Unique
		0,5		Identifier

#### 6.2.4. PHY Identification Register2 (0x03)

#### Table 37. PHY Identification Register2 (0x03)

Bit	Symbol	Access	Default	Description
15:10	Phy_Id	RO	0x0	Bits 19 to 24 of the Organizationally Unique Identifier
9:4	Type_No	RO	0x11	6 bits manufacturer's type number
3:0	Revision_No	RO	0xa	4 bits manufacturer's revision number

#### 6.2.5. Auto-Negotiation Advertisement (0x04)

#### Table 38. Auto Negotiation Advertisement (0x04)

Bit	Symbol	Access	Default	Description
15	NEXT_Page	RW	0x0	This bit is updated immediately after the writing operation; however the configuration does not take effect until any of the following occurs: This bit is updated immediately after the writing operation; however the configuration does not take effect until any of the following occurs:  • Software reset is asserted by writing register 0x0 bit[15]  • Restart Auto-Negotiation is triggered by writing register 0x0 bit[9]  • The port is switched from power down to normal operation by writing register 0x0 bit[11]  • Link goes down If 1000BASE-T is advertised, the required next
		5 <sup>©</sup> 5	285	



	四件有限公司			COM
Moto	rcomm YT8521SH-CA/Y	T8521SC-	CA Data	行人版も
RAM!			14	pages are automatically transmitted. This bit must be set to 0 if no additional next page is needed.  1 = Advertise 0 = Not advertised
14	Ack	RO	0x0	Always 0.
13	Remote_Fault	RW	0x0	1 = Set Remote Fault bit 0 = Do not set Remote Fault bit
12	Extended_NEXT_Page	RW	0x1	Extended nEXT page enable control bit  1 = Local device supports transmission of extended next pages  0 = Local device does not support transmission of extended next pages.
11	Asymmetric_Pause	RW	0x1	This bit is updated immediately after the writing operation; however the configuration does not take effect until any of the following occurs:  • Software reset is asserted by writing register 0x0 bit[15]  • Restart Auto-Negotiation is triggered by writing register 0x0 bit[9]  • The port is switched from power down to normal operation by writing register 0x0 bit[11]  • Link goes down  1 = Asymmetric Pause  0 = No asymmetric Pause
10	Pause	RWS	0x1	This bit is updated immediately after the writing operation; however the configuration does not take effect until any of the following occurs:  This bit is updated immediately after the writing operation; however the configuration does not take effect until any of the following occurs:  • Software reset is asserted by writing register 0x0 bit[15]  • Restart Auto-Negotiation is triggered by writing register 0x0 bit[9]  • The port is switched from power down to normal operation by writing register 0x0 bit[11]  • Link goes down  1 = MAC PAUSE implemented  0 = MAC PAUSE not implemented
9	100BASE-T4	RO	0x0	1 = Able to perform 100BASE-T4 0 = Not able to perform 100BASE-T4 Always 0
8	100BASE-TX_Full_Duplex	RW	0x1	This bit is updated immediately after the writing operation; however the configuration does not take effect until any of the following occurs:  • Software reset is asserted by writing register 0x0 bit[15]  • Restart Auto-Negotiation is triggered by writing register 0x0 bit[9]  • The port is switched from power down to normal operation by writing register 0x0 bit[11]  • Link goes down  1 = Advertise  0 = Not advertised
7	100BASE-TX Half Duple	RW	0x1	This bit is undated immediately after the writing
		5@5er	295	



				M .	
Motor	reomm YT8521SH-CA/Y	T0521CC		shoot CO	
IVIOLOI	COMMITTIOSZISTI-CAVI	1002130-	CA Data	SNEEL 裕太微电子 Motorcomm	
	X	件有限心		operation; however the configuration does not take effect until any of the following occurs:  This bit is updated immediately after the writing operation; however the configuration does not take effect until any of the following occurs:  • Software reset is asserted by writing register 0x0 bit[15]  • Restart Auto-Negotiation is triggered by writing register 0x0 bit[9]  • The port is switched from power down to normal operation by writing register 0x0 bit[11]  • Link goes down  1 = Advertise  0 = Not advertised	21.5
6	10BASE-Te_Full_Duplex	RW	0x1	This bit is updated immediately after the writing operation; however the configuration does not take effect until any of the following occurs:  • Software reset is asserted by writing register 0x0 bit[15]  • Restart Auto-Negotiation is triggered by writing register 0x0 bit[9]  • The port is switched from power down to normal operation by writing register 0x0 bit[11]  • Link goes down  1 = Advertise  0 = Not advertised	3
5	10BASE-Te_Half_Duplex	RW	0x1	This bit is updated immediately after the writing operation; however the configuration does not take effect until any of the following occurs:  • Software reset is asserted by writing register 0x0 bit[15]  • Restart Auto-Negotiation is triggered by writing register 0x0 bit[9]  • The port is switched from power down to normal operation by writing register 0x0 bit[11]  • Link goes down  1 = Advertise  0 = Not advertised	25
4:0	Selector_Field	RW	0x1 /	Selector Field mode. 00001 = IEEE 802.3	

#### 6.2.6. Auto-Negotiation Link Partner Ability (0x05)

#### Table 39. Auto-Negotiation Link Partner Ability (0x05)

Bit	Symbol	Access	Default	Description	
15	1000BASE-X_Fd	RO SWC	0x0	Received Code Word Bit 15 1 = Link partner is capable of next page 0 = Link partner is not capable of next page	
14	ACK	RO SWC	0x0	Acknowledge. Received Code Word Bit 14  1 = Link partner has received link code word  0 = Link partner has not received link code word	
13	REMOTE_FAULT	RO SWC	0x0	Remote Fault. Received Code Word Bit 13 1 = Link partner has detected remote fault 0 = Link partner has not detected remote fault	
12	RESERVED	RO SWC	0x0	Technology Ability Field. Received Code Word	
1m 5@ 5 e n y 30 5					



N / a + -	VT0F010LL CA A	T0E0100	C	about 1	
Moto	rcomm YT8521SH-CA/Y	185215C-	CA Data	SNEET 裕太微电子 Motorcomm	
THE STATE OF THE PARTY OF THE P				Bit 12	
11	ASYMMETRIC_PAUSE	RO SWC	0x0	Technology Ability Field. Received Code Word Bit 1  1 = Link partner requests asymmetric pause 0 = Link partner does not request asymmetric pause	
10	PAUSE	RO SWC	0x0	Technology Ability Field. Received Code Word Bit 10 1 = Link partner supports pause operation 0 = Link partner does not support pause operation	, · ·
9	100BASE-T4	RO SWC	0x0	Technology Ability Field. Received Code Word Bit 9 1 = Link partner supports 100BASE-T4 0 = Link partner does not support100BASE-T4	2
8	100BASE-TX_FULL_DUP LEX	RO SWC	0x0	Technology Ability Field. Received Code Word Bit 8  1 = Link partner supports 100BASE-TX full-duplex 0 = Link partner does not support 100BASE-TX full-duplex	
7	100BASE-TX_HALF_DUP LEX	RO SWC	0x0	Technology Ability Field. Received Code Word Bit 7 1 = Link partner supports 100BASE-TX half-duplex 0 = Link partner does not support 100BASE-TX half-duplex	25.0
6	10BASE-Te_FULL_DUPL EX	RO SWC	0x0	Technology Ability Field. Received Code Word Bit 6 1 = Link partner supports 10BASE-Te full-duplex 0 = Link partner does not support 10BASE-Te full-duplex	
SE WITH	10BASE-Te_HALF_DUPL EX	RO SWC	0x0	Technology Ability Field. Received Code Word Bit 5  1 = Link partner supports 10BASE-Te half-duplex  0 = Link partner does not support 10BASE-Te half-duplex	
4:0	SELECTOR_FIELD	RO SWC	0x0	Selector Field Received Code Word Bit 4:0	1

#### 6.2.7. Auto-Negotiation Expansion Register (0x06)

Table 40. Auto-Negotiation Expansion Register (0x06)

Bit	Symbol	Access	Default	Description				
15:5	Reserved	RO	0x0	Reserved				
4	Parallel Detection fault	RO RC LH SWC	0x0	1 = Fault is detected 0 = No fault is detected				
3	Link partner nEXT page able	RO LH SWC	0x0	1 = Link partner supports NEXT page 0 = Link partner does not support next page				
2	Local NEXT Page able	RO	0x1	1 = Local Device supports NEXT Page 0 = Local Device does not support Next Page				
1	Page received	RO RC LH	0x0	1 = A new page is received 0 = No new page is received				
	LH 0= No new page is received							



OF	Link Partner Auto	RO	0x0	1 = Link partner supports auto-negotiation 0 = Link partner does not support
	negetiation dote			auto-negotiation

#### 6.2.8. Auto-Negotiation NEXT Page Register (0x07)

Table 41. Auto-Negotiation NEXT Page Register (0x07)

Page  ved ge page mode	RW RO RW	0x0 0x0 0x1	Transmit Code Word Bit 15 1 = The page is not the last page 0 = The page is the last page Reserved Transmit Code Word Bit 13	21.5
				2
ge page mode	RW	0x1	Transmit Code Word Bit 13	
			1 = Message Page 0 = Unformatted Page	
	RW	0x0	Transmit Code Word Bit 12 1 = Comply with message 0 = Cannot comply with message	
÷	RO	0x0	Transmit Code Word Bit 11 1 = This bit in the previously exchanged Code Word is logic 0 0 = The Toggle bit in the previously exchanged Code Word is logic 1	
ge/Unformatte	RW	0x1	Transmit Code Word Bits [10:0]. These bits are encoded as Message Code Field when bit[13] is set to 1, or as Unformatted Code Field when bit[13] is set to 0.	25-03
1			5 m	_
_	A COLOR	JAP JAP	J PP	These bits are encoded as Message Code Field when bit[13] is set to 1, or as Unformatted Code Field when bit[13] is set to 0.  Negotiation Link Partner Received NEXT Page Register (0x08)

## 6.2.9. Auto-Negotiation Link Partner Received NEXT Page Register (0x08)

Table 42. Auto-Negotiation Link Partner Received NEXT Page Register (0x08)

Bit	Symbol	Access	Default	Description
15	NEXT Page	RO	0x0	Received Code Word Bit 15 1 = This page is not the last page 0 = This page is the last page
14	Ack	RO	0x0	Received Code Word Bit 14  1 = successfully received its Link Partner's ack  0 = didn't receive its Link Partner's ack
13	Message page mode	RO	0x0	Received Code Word Bit 13 1 = Message Page 0 = Unformatted Page
12	Ack2	RO	0x0	Received Code Word Bit 12 1 = Comply with message 0 = Cannot comply with message
11	Toggle	RO	0x0	Received Code Word Bit 11 1 = This bit in the previously exchanged Code Word is logic 0 0 = The Toggle bit in the previously exchanged Code Word is logic 1
10:0	Message/Unformatte	RO	0x0	Received Code Word Bit 10:0 These bits are encoded as Message Code Field when bit[13] is set to 1, or as Unformatted Code Field when bit[13] is set to 0.
	<i>~</i>	5@5e1	325	



# 6.2.10. MASTER-SLAVE control register (0x09)

#### Table 43. MASTER-SLAVE control register (0x09)

Bit	Symbol	Access	Default	Description	]
15:13	Test mode	RW	0x0	The TX TCLK signals from the RX CLK pin	-
13.13	rest mode	海限区	OXO ,	is for jitter testing in test modes 2 and 3. When exiting the test mode, hardware reset or software reset through writing register 0x0 bit[15] must be performed to ensure normal operation.  000 = Normal Mode	5
				001 = Test Mode 1 - Transmit Waveform Test 010 = Test Mode 2 - Transmit Jitter Test (MASTER mode) 011 = Test Mode 3 - Transmit Jitter Test (SLAVE mode) 100 = Test Mode 4 - Transmit Distortion Test 110, 111 = Reserved, normal operation.	2 1.
12	Master/Slave Manual configuration Enable	RW	0x0	This bit is updated immediately after the writing operation; however the configuration does not take effect until any of the following occurs:  • Software reset is asserted by writing register 0x0 bit[15]  • Partent Auto Negotieties in trippered by	
	y m	5@5er	125	<ul> <li>Restart Auto-Negotiation is triggered by writing register 0x0 bit[9]</li> <li>The port is switched from power down to normal operation by writing register 0x0 bit[11]</li> <li>Link goes down</li> <li>Manual MASTER/SLAVE configuration</li> <li>Automatic MASTER/SLAVE configuration.</li> </ul>	25-03
11	Master/Slave configuration	RW	0x0	This bit is updated immediately after the writing	
	在大学。			operation; however the configuration does not take effect until any of the following occurs:	
الدار				<ul> <li>Software reset is asserted by writing register</li> </ul>	
常》				0x0 bit[15] • Restart Auto-Negotiation is triggered by	
				writing register 0x0 bit[9]	
			.00	• The port is switched from power down to normal operation by writing register 0x0 bit[11]	
			" A "	• Link goes down	
		TE!L	[2]	This bit is ignored if bit[12] is 0.	
		性相似		<ul><li>1 = Manual configuration as MASTER</li><li>0 = Manual configuration as SLAVE.</li></ul>	
10	Port Type	RW	0x0	This bit is updated immediately after the writing	
	對例			operation; however the configuration does not	. 5
	\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\			take effect until any of the following occurs:  • Software reset is asserted by writing register	21
				0x0 bit[15]	
				• Restart Auto-Negotiation is triggered by writing register 0x0 bit[9]	
				• The port is switched from power down to	
				normal operation by writing register 0x0 bit[11]	
				• Link goes down This bit is ignored if bit[12] is 1.	
				1 = Prefer multi-port device (MASTER)	
9	1000DASE T Evil	DW	0 <sub>v</sub> 1	0 = Prefer single port device (SLAVE)  This bit is undeted immediately after the writing	-
9	1000BASE-T Full	RW	0x1	This bit is updated immediately after the writing	J
			33		
		5 ® 5 ° °	,		
	_ (	503			
	, m	-			



Moto	rcomm YT8521SH-CA/Y	T8521SC-	CA Data	sheet	₩±₩₽.7
		性有限公	1 / m	operation; however the configuration do take effect until any of the following oc • Software reset is asserted by writing reverse of two bit[15] • Restart Auto-Negotiation is triggered writing register 0x0 bit[9] • The port is switched from power down normal operation by writing register 0x • Link goes down 1 = Advertise 0 = Not advertised	by n to
8	1000BASE-T Half-	RW	0x0	This bit is updated immediately after the operation; however the configuration do take effect until any of the following oce • Software reset is asserted by writing r 0x0 bit[15] • Restart Auto-Negotiation is triggered writing register 0x0 bit[9] • The port is switched from power down normal operation by writing register 0x0 bit[9] • Link goes down 1 = Advertise 0 = Not advertised (default)	oes not ceurs: by n to
7:0	Reserved	RW	0x0 S	Write as 0, ignore on read.	

#### 6.2.11. MASTER-SLAVE Status Register (0x0A)

7:0	Reserved	RW	0x0 S	Write as 0, ignore on read.					
		ase (	, 3		-25 03				
6.2.11. MASTER-SLAVE Status Register (0x0A)  Table 44. MASTER-SLAVE Status Register (0x0A)									
Bit	Symbol	Access	Default	Description					
15	Master/Slave_cfg_error	RO RC SWC LH	0x0	This register bit will clear on read, rising of MII 0.12 and rising of AN complete.  1 = Master/Slave configuration fault detected 0 = No fault detected					
14	Master/Slave	RO	0x0	This bit is not valid unless register 0x1 bit5 is 1.  1 = Local PHY configuration resolved to Master  0 = Local PHY configuration resolved to Slave					
13	Local Receiver Status	RO	0x0	1 = Local Receiver OK 0 = Local Receiver not OK					
12	Remote Receiver	RO	0x0	1 = Remote Receiver OK 0 = Remote Receiver not OK					
11	Link Partner 1000T FD	RO	0x0	This bit is not valid unless register 0x1 bit5 is 1.  1 = Link Partner supports 1000BASE-T full duplex  0 = Link Partner does not support 1000BASE-T full duplex	21.5				
10	Link Partner 1000T HD	RO	0x0	This bit is not valid unless register 0x1 bit5 is 1.  1 = Link Partner supports 1000BASE-T half duplex  0 = Link Partner does not support 1000BASE-T half duplex					
9:8	Reserved	RO	0x0	Reserved					
7:0	Idle Error Count	RO RC	0x0	MSB of Idle Error Counter. The register indicates the idle error count since the last read operation performed to this register. The counter					
	7, 10	5 <sup>@</sup> 5 <sup>©</sup> (	34 <sup>5</sup>	o `					



7	8			pegs at 11111111 and does not roll over.	
				r -8	

#### 6.2.12. MMD Access Control Register (0x0D)

#### Table 45. MMD Access Control Register (0x0D)

Bit	Symbol	Access	Default	Description
15:14	Function	RW	0x0	00 = Address
	加其			01 = Data, no post increment
				10 = Data, post increment on reads and writes
				11 = Data, post increment on writes only
13:5	Reserved	RO	0x0	Reserved
4:0	DEVAD	RW	0x0	MMD register device address.
				00001 = MMD1
				00011 = MMD3
				00111 = MMD7

#### 6.2.13. MMD Access Data Register (0x0E)

#### Table 46. MMD Access Data Register (0x0E)

Bit	Symbol	Access	Default	Description
15:0	Address data	RW	0x0 5	If register 0xD bits [15:14] are 00, this register is used as MMD DEVAD address register.
		0,500		Otherwise, this register is used as MMD DEVAD data register as indicated by its address
		( O )		register.

#### 6.2.14. Extended status register (0x0F)

#### Table 47. Extended status register (0x0F)

Table 47. Extended status register (exer)							
Bit	Symbol	Access	Default	Description			
15	1000BASE-X Full Duplex	RO	0x0	1 = PHY supports 1000BASE-X Full Duplex 0 = PHY does not supports 1000BASE-X Full Duplex Always 0.			
14	1000BASE-X Half Duplex	RO	0x0 , 100	I = PHY supports 1000BASE-X Half Duplex. 0 = PHY does not support 1000BASE-X Half Duplex. Always 0			
13	1000BASE-T Full Duplex	RO	0x1	1 = PHY supports 1000BASE-T Full Duplex 0 = PHY does not supports 1000BASE-T Full Duplex Always 1			
12	1000BASE-T Half Duplex	RO	0x0	1 = PHY supports 1000BASE-T Half Duplex 0 = PHY does not support 1000BASE-T Half Duplex Always 0.			
11:0	Reserved	RO	0x0	Reserved			

#### 6.2.15. PHY Specific Function Control Register (0x10)

#### Table 48. PHY Specific Function Control Register (0x10)

Bit Symbol Access Default Des	cription
-------------------------------	----------





21.5

	大大学有限以高	(7050400		
Moto	reomm YT8521SH-CA/	Y18521SC-	CA Data	Sheet 裕太微电子 Motorcomm
15.7	Reserved	RO	0x0	Reserved
6:5	Cross_md	RW	0x3	Changes made to these bits disrupt normal operation, thus a software reset is mandatory after the change. And the configuration does not take effect until software reset.  00 = Manual MDI configuration 01 = Manual MDIX configuration 10 = Reserved 11 = Enable automatic crossover for all modes
4	Reserved	RO	0x0	Reserved
3	Crs_on_tx	RW	0x0	This bit is effective in 10BASE-Te half-duplex mode and 100BASE-TX mode:  1 = Assert CRS on transmitting or receiving 0 = Never assert CRS on transmitting, only assert it on receiving.
2	En_sqe_test	RW	0x0	1 = SQE test enabled, 0 = SQE test disabled Note: SQE Test is automatically disabled in full-duplex mode regardless the setting in this bit.
1	En_pol_inv	RW	0x1	If polarity reversal is disabled, the polarity is forced to be normal in 10BASE-Te.  1 = Polarity Reversal Enabled 0 = Polarity Reversal Disabled
0	Dis_jab	RW S S	0x0	1 = Disable 10BASE-Te jabber detection function 0 = Enable 10BASE-Te jabber detection function

### 6.2.16. PHY Specific Status Register (0x11)

#### Table 49. PHY Specific Status Register (0x11)

Bit	Symbol	Access	Default	<b>Description</b>		
43;14	Speed_mode	RO	0x0	These status bits are valid only when bit11 is 1.  Bit11 is set when Auto-Negotiation is completed or Auto-Negotiation is disabled.  11 = Reserved  10 = 1000 Mbps  01 = 100 Mbps  00 = 10 Mbps		
13	Duplex	RC	0x0	This status bit is valid only when bit11 is 1.  Bit11 is set when Auto-Negotiation is completed or Auto-Negotiation is disabled.  1 = Full-duplex 0 = Half-duplex		
12	Page Received real-time	RO	0x0	1 = Page received 0 = Page not received		
11	Speed and Duplex Resolved	RO	0x0	When Auto-Negotiation is disabled, this bit is set to 1 for force speed mode.  1 = Resolved  0 = Not resolved		
10	Link status real-time	RO	0x0	1 = Link up 0 = Link down		
9:7	Reserved	RO	0x0	Reserved		
6	MDI Crossover Status	RO	0x0	This status bit is valid only when bit11 is 1.		
	36 <sup>S</sup>					



Moto	oreomm YT8521SH-CA/Y	T8521SC-	CA Data	Motorcomm	
R.T.		此有限心		Bit11 is set when Auto-Negotiation is completed or Auto-Negotiation is disabled. The bit value depends on register 0x10 "PHY specific function control register" bits6~bit5 configurations. Register 0x10 configurations take effect after software reset.  1 = MDIX 0 = MDI	
5	Wirespeed downgrade	RO	0x0	1 = Downgrade 0 = No Downgrade	6
4	Reserved	RO	0x0	Reserved	۲ . ۲
3	Transmit Pause	RO	0x0	This status bit is valid only when bit11 is 1. Bit11 is set when Auto-Negotiation is completed. This bit indicates MAC pause resolution. This bit is for information purposes only and is not used by the device. When in force mode, this bit is set to be 0.  1 = Transmit pause enabled 0 = Transmit pause disabled	2 `
2	Receive Pause	RO S O T	0x0	This status bit is valid only when bit[11] is 1.  Bit[11] is set when Auto-Negotiation is completed. This bit indicates MAC pause resolution. This bit is for information purposes only and is not used by the device. When in force mode, this bit is set to be 0.  1 = Receive pause enabled 0 = Receive pause disabled	25-0
1	Polarity Real Time	RO	0x0	1 = Reverted polarity 0 = Normal polarity	
0	Jabber Real Time	RO	0x0	1 = Jabber 0 = No jabber	

#### 6.2.17. Interrupt Mask Register (0x12)

#### Table 50. Interrupt Mask Register (0x12)

Bit	Symbol	Access	Default	Description
15	Auto-Negotiation Error INT mask	RW	0x0	1 = Interrupt enable 0 = Interrupt disable
14	Speed Changed INT mask	RW	0x0	same as bit 15
13	Duplex changed INT mask	RW	0x0	same as bit 15
12	Page Received INT mask	RW	0x0	same as bit 15
11	Link Failed INT mask	RW	0x0	same as bit 15
10	Link Succeed INT mask	RW	0x0	same as bit 15
9:7	reserved	RW	0x0	No used.
6	WOL INT mask	RW	0x0	same as bit 15
5	Wirespeed downgraded INT mask	RW	0x0	same as bit 15
4	Reserved	RW	0x0	No used.
3	Serdes Link Failed INT mask	RW	0x0	same as bit 15
2	Serdes Link Success INT mask	RW	0x0	same as bit 15
	~	5 <sup>@56</sup>	y 37 <sup>5</sup>	



0 Jabber Happened INT mask RW 0x0 same as 6it 15		Polarity changed INT mask	RW	0x0	same as bit 15
m <sup>s</sup>	0	Jabber Happened INT mask	RW	0x0	same as bit 15
$\nearrow$ .					

#### 6.2.18. Interrupt Status Register (0x13)

Table 51. Interrupt Status Register (0x13)

Bit	Symbol	Access	Default	Description	
15	Auto-Negotiation Error INT	RO RC	0x0	Error can take place when any of the following happens:  • MASTER/SLAVE does not resolve correctly  • Parallel detect fault  • No common HCD  • Link does not come up after negotiation is complete  • Selector Field is not equal  • flp_receive_idle=true while Autoneg  Arbitration FSM is in NEXT PAGE WAIT state  1 = Auto-Negotiation Error takes place  0 = No Auto-Negotiation Error takes place	21.5
14	Speed Changed INT	RO RC	0x0	1 = Speed changed 0 = Speed not changed	
13	Duplex changed INT	RO RC	0x0 5	1 = duplex changed 0 = duplex not changed	
12	Page Received INT	RO RC	0x0	1 = Page received 0 = Page not received	25-0
11	Link Failed INT	RO RC	0x0	1 = Phy link down takes place 0 = No link down takes place	2
10	Link Succeed INT	RO RC	0x0	1 = Phy link up takes place 0 = No link up takes place	
9:7	reserved	RO RC	0x0	No used.	
6	WOL INT	RO RC	0x0	1 = PHY received WOL magic frame. 0 = PHY didn't receive WOL magic frame	
5	Wirespeed downgraded INT	RO RC	0x0	1 = speed downgraded. 0 = Speed didn't downgrade.	
4	Reserved	RO RC	0x0	Reserved	
3	Serdes Link Failed INT	RO RC	0x0	1 = Sds link down takes place 0 = No Sds link down takes place	
2	Serdes Link Success INT	RO RC	0x0	1 = Sds link up takes place 0 = No Sds link up takes place	
1	Polarity changed INT	RO RC	0x0	1 = PHY revered MDI polarity 0 = PHY didn't revert MDI polarity	
0	Jabber Happened INT	RO RC	0x0	1 = 10BASE-Te TX jabber happened 0 = 10BASE-Te TX jabber didn't happen Please refer to UTP MII Register 0x1 bit[1] Jabber Detect.	21.5

#### 6.2.19. Speed Auto Downgrade Control Register (0x14)

Table 52. Speed Auto Downgrade Control Register (0x14)

Bit	Symbol	Access	Default	Description		
15:12	Reserved	RO	0x0	Reserved		
11:6	Reserved	RW	0x20	Reserved		
ms@seny 385						



5	En_speed_downgrade	RW POS	0x1	When this bit is set to 1, the PHY enables
				smart-speed function. Writing this bit requires a
				software reset to update. This bit will be set to
			77	Tb0 in UTP_TO_FIBER mode; else set to 1'b1,
			1	only take effect after software reset
4:2	Autoneg retry limit	RW	0x3	If these bits are set to 3, the PHY attempts five
	pre-downgrade	TE BR		times (set value 3 + additional 2) before
	۲	件节		downgrading. The number of attempts can be
				changed by these bits. Only take effect after
				software reset
1	Reserved	RW	0x0	Reserved
0	Reserved	RO	0x0	Reserved
				2.1

#### 6.2.20. Rx Error Counter Register (0x15)

#### Table 53. Rx Error Counter Register (0x15)

Bit	Symbol	Access	Default	Description
15:0	Rx_err_counter	RO SWC	0x0	This counter increase by 1 at the 1st rising of RX_ER when RX_DV is 1. The counter will hold at maximum 16'hFFFF and not roll over.

#### 6.2.21. Extended Register's Address Offset Register (0x1E)

#### Table 54. Extended Register's Address Offset Register (0x1E)

Bit	Symbol	Access	Default	Description
15:8	Reserved	RO	0x0	Reserved
7:0	Extended Register Address Offset	RW	0x0	It's the address offset of the extended register that will be Write or Read

#### 6.2.22. Extended Register's Data Register (0x1F)

#### Table 55. Extended Register's Data Register (0x1F)

Bit	Symbol	Access	Default	Description
15:0	Extended Register Data	RW	0x0	It's the data to be written to the extended register
			1,	indicated by the address offset in register 0x1E,
				or the data read out from that extended register.

## 6.3. UTP MMD Register

#### 6.3.1. PCS Control 1 Register (MMD3, 0x0)

#### Table 56. PCS Control 1 Register (MMD3, 0x0)

Bit	Symbol	Access	Default	Description		
15	Pcs_rst	RW SC	0x0	Setting this bit will set all PCS registers to their default states. This action also initiate a reset in MMD1 and MMD7.		
14:11	Reserved	RO	0x0	Reserved		
10	Clock_stoppable	RW SWC	0x0	Not used.		
9:0	Reserved	RO	0x0	Reserved		
9:0 Reserved RO 0x0 Reserved						



#### 6.3.2. PCS Status 1 Register (MMD3, 0x1)

#### Table 57. PCS Status 1 Register (MMD3, 0x1)

Bit	Symbol	Access	Default	Description
15:12	Reserved	RO	0x0 \ (1)	Reserved
11	Tx_lpi_rxed	RO LH	0x0	When read as 1, it indicates that the transmit PCS has received low power idle signaling one or more times since the register was last read. Lach High.
10	Rx_lpi_rxed	RO LH	0x0	When read as 1, it indicates that the receive PCS has received low power idle signaling one or more times since the register was last read. Lach High.
9	Tx_lpi_indic	RO	0x0	When read as 1, it indicates that the transmit PCS is currently receiving low power idle signals.
8	Rx_lpi_indic	RO	0x0	When read as 1, it indicates that the receive PCS is currently receiving low power idle signals.
7:3	Reserved	RO	0x0	Reserved
2	Pcsrx_lnk_status	RO LL	0x0	PCS status, latch low.
1:0	Reserved	RO	0x0	Peserved

#### 6.3.3. EEE Control and Capability Register (MMD3, 0x14)

#### Table 58. EEE Control and Capability Register (MMD3, 0x14)

Bit	Symbol	Access	Default	Description
15:3	Reserved	RO	0x0	Reserved
2	1000BASE-T EEE	RO	0x1	Always 1. EEE is supported for 1000BASE-T
1	100BASE-TX EEE	RO	0x1	Always 1. EEE is supported for 100BASE-TX
0	Reserved	RO	0x0	Reserved

#### 6.3.4. EEE Wake Error Counter (MMD3, 0x16)

#### Table 59. EEE Wake Error Counter (MMD3, 0x16)

Bit	Symbol	Access	Default	Description
15:0	Lpi_wake_err_cnt	RO RC SWC	0x0	Count wake time faults where the PHY fails to complete its normal wake sequence within the
		. 183		time required for the specific PHY type.

#### 6.3.5. Local Device EEE Ability (MMD7, 0x3C)

#### Table 50. Local Device EEE Ability (MMD7, 0x3C)

Bit	Symbol	Access	Default	Description
15:3	Reserved	RO	0x0	Reserved
2	EEE_1000BT	RW	0x0	PHY's 1000BASE-T EEE ability.
1	EEE_100BT	RW	0x0	PHY's 100BASE-TX EEE ability.
0	Reserved	RO	0x0	Reserved

#### 6.3.6. Link Partner EEE Ability (MMD7, 0x3D)

#### Table 61. Link Partner EEE Ability (MMD7, 0x3D)

Bit	Symbol	Access	Default	Description		
15:3	Reserved	RO	0x0	Reserved		
	305					



2	LP_ge_eee_ability	RO	0x0	Link partner's 1000BASE-T EEE ability.
1	LP_ge_eee_ability	RO	0x0	Link partner's 100BASE-TX EEE ability.
0	Reserved	RO	0x0	Reserved

# 6.4. UTP LDS Register

#### 6.4.1. LRE Control (0x00)

#### Table 62. LRE Control (0x00)

	Table 62. LRE Control (0x00)					
Bit	Symbol	Access	Default	Description		
15	Reset	RW SC	0x0	PHY Software Reset. Writing 1 to this bit causes immediate PHY reset. Once the operation is done, this bit is cleared automatically.  1'b0: Normal operation;  1'b1: PHY reset		
14	Reserved	RW	0x0	Reserved		
13	Restart_LDS	RW SC	0x0	1'b1: restart LDS process		
12	LDS_Enable	RW	0x0	1'b1: LDS enabled; 1'b0: LDS disabled		
11	Reserved	RW	0x0 S	Reserved		
10	Reserved	RW	0x0	Reserved		
9:6	Speed_selection	RW 6	0x0	4'b0000: 10Mbps; 4'b1000: 100Mbps; Others: reserved		
5:4	Pair_selection	RW	0x0	2'b00: 1 pair connection; 2'b01: 2 pair connections; 2'b10: 4 pair connections; 2'b11: reserved		
3	M/S_selection	RW	0x0	1'b1: manually force local device to master, when reg0.12 = 0; 1'b0: manually force local device to slave, when reg0.12 = 0		
2	Force auto negotiation	RW	0x0	1'b1: manually force local device to auto negotiation state, when reg0.12 = 0		
1:0	Reserved	RO	0x0	Reserved. Write as 0, ignore on read		

#### 6.4.2. LRE Status (0x01)

#### Table 63. LRE Status (0x01)

Bit	Symbol	Access	Default	Description		
15:14	Reserved	RO	0x0	Ignore on read		
13	100Mbps_1-pair_apable	RO	0x0	1'b1: 100Mbps 1-pair capable; 1'b0: Not 100Mbps 1-pair capable		
12	100Mbps_4-pair capable	RO	0x1	1'b1: 100Mbps 4-pair capable; 1'b0: Not 100Mbps 4-pair capable		
11	100Mbps_2-pair capable	RO	0x0	1'b1: 100Mbps 2-pair capable; 1'b0: Not 100Mbps 2-pair capable		
10	10Mbps_2-pair capable	RO	0x0	1'b1: 10Mbps 2-pair capable; 1'b0: Not 10Mbps 2-pair capable		
9	10Mbps_1-pair capable	RO	0x0	1'b1: 10Mbps 1-pair capable; 1'b0: Not 10Mbps 1-pair capable		
8:6	Reserved	RO	0x7	Reserved		
8.0 Keserved KO 0x7 Reserved						



5	LDS_Complete	RO SWC	0x0	1'b1: LDS auto-negotiation complete;
				1'b0: LDS auto-negotiation not complete
4	Support_IEEE_802.3 _PHY	RO	0x1	1'bl. Support IEEE 802.3 PHY operation;
			110	1'b0: Not Support IEEE 802.3 PHY operation
3	LDS_Ability	RO	0x1	1'b1: LDS auto-negotiation capable;
		TRID	<b>/</b> - 3	1'b0: Not LDS auto-negotiation capable
2	Link_Status	RO LL	0x0	Link status;
	训技	SWC		1'b0: Link is down;
				1'b1: Link is up
1	Reserved	RO	0x0	Reserved
0	Reserved	RO	0x1	Reserved

#### 6.4.3. PHY ID Register1 (0x02)

Table 64. PHY ID Register1 (0x02)

Bit	Symbol	Access	Default	Description
15:0	PHY_ID	RO	0x0	M

#### 6.4.4. PHY ID Register2 (0x03)

Table 65. PHY ID Register2 (0x03)

Bit	Symbol	Access	Default	Description
15:0	PHY_ID	RO S	0x11a	

#### 6.4.5. LDS Auto-Negotiation Advertised Ability (0x04)

	1,,			2)
6.4.5.	LDS Auto-Negotiation A			(0x04) Advertised Ability (0x04)
Bit	Symbol	Access	Default	Description
15:6	Reserved	RO	0x0	reserved
5	100Mbps_1-pair capable	RW	0x0	1'b1: 100Mbps 1-pair capable; 1'b0: No: 100Mbps 1-pair capable
4	100Mbps_4-pair capable	RW	0x1	1'b1. 100Mbps 4-pair capable; 1'b0: Not 100Mbps 4-pair capable
3	100Mbps_2-pair capable	RW	0x0	1'b1: 100Mbps 2-pair capable; 1'b0: Not 100Mbps 2-pair capable
2	10Mbps_2-pair capable	PW	0x0	1'b1: 10Mbps 2-pair capable; 1'b0: Not 10Mbps 2-pair capable
1	10Mbps_1-pair capable	RW	0x0	1'b1: 10Mbps 1-pair capable; 1'b0: Not 10Mbps 1-pair capable
0	Auto negotiation capable	RW	0x1	1'b1: Auto negotiation capable; 1'b0: Not auto negotiation capable

#### 6.4.6. LDS Link Partner Ability (0x07)

Table 67. LDS Link Partner Ability (0x07)

Bit	Symbol	Access	Default	Description		
15:6	Reserved	RO	0x0	Reserved		
5	100Mbps_1-pair_capable	RO	0x0	1'b1: link partner 100Mbps 1-pair capable;		
				1'b0: link partner not 100Mbps 1-pair capable		
ms@seny 8250						



1'b0: link partner not 100Mbps 4-pair capable  1'b1: link partner 100Mbps 2-pair capable; 1'b0: link partner not 100Mbps 2-pair capable; 1'b0: link partner not 100Mbps 2-pair capable  1'b1: link partner 100Mbps 2-pair capable; 1'b0: link partner 10Mbps 2-pair capable; 1'b0: link partner not 10Mbps 2-pair capable; 1'b0: link partner 10Mbps 1-pair capable; 1'b0: link partner 10Mbps 1-pair capable; 1'b0: link partner not 10Mbps 1-pair capable  RO  Reserved  6.4.7. LDS Expansion (0x0A)	Table 68. LDS Expansion (0x0A)  Bit Symbol Access Default Description						
1'b0: link partner not 100Mbps 4-pair capable  1'b0: link partner not 100Mbps 4-pair capable  1'b1: link partner 100Mbps 2-pair capable;  1'b0: link partner not 100Mbps 2-pair capable  1'b0: link partner 10Mbps 2-pair capable;  1'b0: link partner not 10Mbps 2-pair capable;  1'b0: link partner not 10Mbps 2-pair capable;  1'b0: link partner not 10Mbps 1-pair capable;  1'b0: link partner not 10Mbps 1-pair capable;  1'b0: link partner not 10Mbps 1-pair capable;							
1'b0: link partner not 100Mbps 4-pair capable  1'b0: link partner not 100Mbps 4-pair capable  1'b1: link partner 100Mbps 2-pair capable;  1'b0: link partner not 100Mbps 2-pair capable  1'b0: link partner 10Mbps 2-pair capable;  1'b0: link partner not 10Mbps 2-pair capable;  1'b0: link partner not 10Mbps 2-pair capable;  1'b0: link partner not 10Mbps 1-pair capable;  1'b0: link partner not 10Mbps 1-pair capable;  1'b0: link partner not 10Mbps 1-pair capable;		A. T.				21:	
1'b0: link partner not 100Mbps 4-pair capable  1'b1: link partner not 100Mbps 4-pair capable  1'b1: link partner 100Mbps 2-pair capable; 1'b0: link partner not 100Mbps 2-pair capable  1'b0: link partner 10Mbps 2-pair capable; 1'b0: link partner 10Mbps 2-pair capable; 1'b0: link partner not 10Mbps 2-pair capable  1'b0: link partner 10Mbps 1-pair capable  1'b1: link partner 10Mbps 1-pair capable;	0	Reserved	RO	0x0	Reserved	5	
1'b0: link partner not 100Mbps 4-pair capable  1'b0: link partner not 100Mbps 4-pair capable  1'b1: link partner 100Mbps 2-pair capable; 1'b0: link partner not 100Mbps 2-pair capable  2 10Mbps_2-pair_capable  RO 0x0 1'b1: link partner 10Mbps 2-pair capable;	1	10Mbps_1-pair_capable	RO	0x0			
1'b0: link partner not 100Mbps 4-pair capable  3 100Mbps_2-pair_capable RO 0x0 1'b1: link partner 100Mbps 2-pair capable;	2	10Mbps_2-pair_capable	RO	0x0			
	3	100Mbps_2-pair_capable	RO	0x0	1 1 1 1		
100Mbns 4-nair canable RO 0v0 11b1: link nartner 100Mbns 4-nair canable:	4	100Mbps_4-pair_capable	RO	0x0	1'b1: link partner 100Mbps 4-pair capable; 1'b0: link partner not 100Mbps 4-pair capable		

#### 6.4.7. LDS Expansion (0x0A)

#### Table 68. LDS Expansion (0x0A)

Bit	Symbol	Access	Default	Description
15	Reserved	RO	0x0	Reserved
14	Master/Slave	RO	0x0	1 = Local PHY configuration resolved to
				Master;
				0 = Local PHY configuration resolved to Slave
13:12	Connections_pairs	RO	0x0	Number of pairs;
			(	2'b00: 1 pair;
			25	2'b01: 2 pairs;
		.0	1	2'b10: 4 pairs;
		66,		2'b11: reserved
11:0	Estimated_cable_length	RO	0x0	

#### 6.4.8. LDS Results (0x0B)

#### Table 69. LDS Results (0x0B)

	Table 60: EDG Results (OXOD)					
Bit	Symbol	Access	Default	Description		
15:6	Reserved	RO	0x0	23		
5	4-pair_100M	RO	0x0	1'b1: local PHY configuration resolved to 4-pair 100M		
4	Auto_negotiation	RO	0x0	4'b1: local PHY configuration resolved to AN		
3	1-pair_100M	RO	0x0	1'b1: local PHY configuration resolved to 1-pair 100M		
2	1-pair_10M	RO	0x0	1'b1: local PHY configuration resolved to 1-pair 10M		
1	2-pair_100M	RO	0x0	1'b1: local PHY configuration resolved to BR 2-pair 100M		
0	2-pair_10M	RO	0x0	1'b1: local PHY configuration resolved to BR 2-pair 10M		

## 6.5. UTP EXT Register

#### 6.5.1. Pkgen Cfg1 (EXT\_0x38)

#### Table 70. Pkgen Cfg1 (EXT\_0x38),

Bit	Symbol	Access	Default	Description			
15:13	Reserved	RO	0x0	Reserved			
	43						
	93						
	e '						
	$^{\prime\prime}$ $^{\prime\prime}$						



N 4 - +	TOF21CH CAN	T0F2100		
MOTO	reomm YT8521SH-CA/Y	185215C-	CA Data	SNEEL 裕太微电子 Motorcomm
12	En_pkgen_da_sa	RW	0x0	1: set the DA/SA of the packet generated by pkg_gen to a programmed value; For DA, if UTP EXT 0x38 bit[11] is 1, the DA is set to broadcase address FF-FF-FF-FF-FF-FF; else, the DA is set to fix value, the highest 5 Bytes are 00-00-00-00-00, and the lowest 1 Byte is programmed by UTP EXT 0x3A bit[15:8]. For SA, the highest 5 Bytes are 00-00-00-00, and the lowest 1 Byte is programmed by UTP EXT 0x3A bit[7:0].  0: the DA/SA is not programmed value
11	Pkgen_brdcst	RW	0x0	Valid when UTP EXT 0x38 bit12 is 1.  1: set the DA to broadcase address FF-FF-FF-FF-FF  0: set the DA to a fixed programmed value.
10	Pkgchk_txsrc_sel	RW	0x0	1'b1: the package checker on TX side will check the tx data generated by pkg_gen; 1'b0: the package checker on TX side will check the tx data of UTP GMII/MII.
9:0	Reserved	RW	0x1ff	Reserved

# 6.5.2. Pkgen Cfg3 (EXT\_0x3A)

#### Table 71. Pkgen Cfg3 (EXT\_0x3A)

Bit	Symbol	Access	Default	Description
15:8	Pkgen_da	RW	0x0	Lowest 8 bits of DA, others is zero. Refer to UTP EXT 0x38 bit[12] for detail.
7:0	Pkgen_sa	RW	0x0	Lowest 8 bits of SA, others is zero. Refer to UTP EXT 0x38 bit[12] for detail.

#### 6.5.3. Pkg Cfg0 (EXT\_0xA0)

#### Table 72. Pkg Cfg0 (EXT 0xA0)

	Table 72. Pkg Cigu (EXT_0XAC)						
Bit	Symbol	Access	Default	Description			
15	Pkg_chk_en	RW	0x0	4: to enable UTP RX/TX package checker. RX checker checks the UTP GMII/MII RX data; TX checker checks the UTP GMII/MII TX data.			
14	Pkg_en_gate	RW	0x1	1: to enable gate all the clocks to package self-test module when bit15 pkg_chk_en is 0, bit13 bp_pkg_gen is 1 and bit12 pkg_gen_en is 0; 0: not gate the clocks.			
13	Bp_pkg_gen	RW	0x1	1: normal mode, to send GMII/MII TX data from RGMII, SGMII or SerDes; 0: test mode, to send out the GMII/MII data generated by UTP pkg_gen module.			
12	Pkg_gen_en	RW SC	0x0	1: to enable pkg_gen generating GMII/MII packages. But, the data will only be sent to transceiver when Bit13 bp_pkg_gen is 1'b0. If pkg_burst_size is 0, continuous packages will be generated and will be stopped only when pkg_gen_en is set to 0; Otherwise, after the expected packages are			
	34 <sup>S</sup>						



				Motorcomin
展力				generated, pkg_gen will stop, pkg_gen_en will be self-cleared.
11:8	Pkg_prm_lth	RW	0x8	The preamble length of the generated packages, in Byte unit. Pkg_gen function only support >=2 Byte preamble length. Values smaller than 2 will be ignored by the pkg_gen module.
7:4	Pkg_ipg_lth	RW	0xd	The IPG of the generated packages, in Byte unit for setting smaller than 12. For setting 13, ipg is 2ms; for setting 14, ipg is 20ms; for 15, ipg is 400ms; Pkg_gen function only support >=2  Byte preamble length. Values smaller than 2 will be ignored by the pkg_gen module.
3	Reserved	RW	0x0	Reserved
2	Pkg_corrupt_crc	RW	0x0	1: to make pkg_gen to send out CRC error packages. 0: pkg_gen sends out CRC gcod packages.
1:0	Pkg_payload	RW	0x0	Control the payload of the generated packages. 00: increased Byte payload; 01: random payload; 10: fix pattern 0x5AA55AA5 11: reserved.

#### 6.5.4. Pkg Cfg1 (EXT\_0xA1)

#### Table 73. Pkg Cfg1 (EXT\_0xA1)

Bit	Symbol	Access	Default	Description
15:0	Pkg_length	RW	0x40	To set the length of the generated packages.
	<b>地域</b> 人			com
<i></i>	DI CENTE O AN			A Comment of the Comm

#### 6.5.5. Pkg Cig2 (EXT\_0xA2)

#### Table 74. Pkg Cfg2 (EXT 0xA2)

1 7	1 abio 1 ii ii iig 0 ig 1 (2/1 _ 0/2 i 2 )					
Bit	Symbol	Access	Default	Description		
15:0	Pkg_burst_size	RW	0x0	To set the number of packages in a burst of		
				package generation.		

#### 6.5.6. Pkg Rx Valid0 (EXT 0xA3)

#### Table 75. Pkg Rx Valid0 (EXT\_0xA3)

Bit	Symbol	Access	Default	Description
15:0	Pkg_ib_valid_high	RO RC	0x0	Pkg_ib_valid[31:16], pkg_ib_valid is the
				number of RX packages from wire whose CRC
	7.			are good and length are >=64Byte and
				<=1518Byte.

#### 6.5.7. Pkg Rx Valid1 (EXT\_0xA4)

#### Table 76. Pkg Rx Valid1 (EXT\_0xA4)

Bit	Symbol	Access	Default	Description		
15:0	Pkg_ib_valid_low	RO RC	0x0	Pkg_ib_valid[13:0], pkg_ib_valid is the number of RX packages from wire whose CRC are good and length are >=64Byte and <=1518Byte.		
	and religin are >=04Byte and <=1318Byte.					



#### 6.5.8. Pkg Rx Os0 (EXT\_0xA5)

#### Table 77. Pkg Rx Os0 (EXT\_0xA5)

Bit	Symbol	Access	Default	Description
15:0	Pkg_ib_os_good_high	RO RC	0x0	Pkg_ib_os_good[31:16], pkg_ib_os_good is the number of RX packages from wire whose CRC are good and length are >1518Byte.

#### 6.5.9. Pkg Rx Os1 (EXT\_0xA6)

#### Table 78. Pkg Rx Os1 (EXT\_0xA6)

Bit	Symbol	Access	Default	Description
15:0	Pkg_ib_os_good_low	RO RC	0x0	Pkg_ib_os_good[15:0], pkg_ib_os_good is the number of RX packages from wire whose CRC are good and length are >1518Byte.

#### 6.5.10. Pkg Rx Us0 (EXT\_0xA7)

#### Table 79. Pkg Rx Us0 (EXT\_0xA7)

Bit	Symbol	Access	Default	Description
15:0	Pkg_ib_us_good_high	RO RC	0x0	Pkg_ib_us_good[31:16], pkg_ib_us_good is the number of RX packages from wire whose CRC
		0,5		are good and length are <64Byte.

#### 6.5.11. Pkg Rx Us1 (EXT\_0xA8)

#### Table 80. Pkg Rx Us1 (EXT 0xA8)

	1 date 3011 kg 137 301 (271 _ 377 76)					
Bit	Symbol	Access	Default	Description		
15:0	Pkg_ib_us_good_low	RO RC	0x0	Pkg_ib_us_good[15:0], pkg_ib_us_good is the number of RX packages from wire whose CRC are good and length are >1518Byte.		

#### 6.5.12. Pkg Rx Err (EXT\_0xA9)

#### Table 81 Pkg Rx Err (EXT\_0xA9)

			<u> </u>	\ ' '/
Bit	Symbol	Access	Default	Description
15:0	Pkg_ib_err	RO RC	0x0	pkg_ib_err is the number of RX packages from wire whose CRC are wrong and length are >=64Byte, <=1518Byte.

#### 6.5.13. Pkg Rx Os Bad (EXT\_0xAA)

#### Table 82. Pkg Rx Os Bad (EXT\_0xAA)

				· = '
Bit	Symbol	Access	Default	Description
15:0	Pkg_ib_os_bad	RO RC	0x0	pkg_ib_os_bad is the number of RX packages from wire whose CRC are wrong and length are >=1518Byte



#### 6.5.14. Pkg Rx Fragment (EXT\_0xAB)

#### Table 83. Pkg Rx Fragment (EXT 0xAB)

Bit	Symbol	Access	Default	Description
15:0	Pkg_ib_frag	RO RC	0x0 / (1)	pkg_ib_frag is the number of RX packages from
				wire whose length are <64Byte.

#### 6.5.15. Pkg Rx Nosfd (EXT GxAC)

#### Table 84. Pkg Rx Nosfd (EXT 0xAC)

Bit	Symbol	Access	Default	Description
15:0	Pkg_ib_nosfd	RO RC	0x0	pkg_ib_nosfd is the number of RX packages from wire whose SFD is missed.

#### 6.5.16. Pkg Tx Valid0 (EXT 0xAD)

#### Table 85. Pkg Tx Valid0 (EXT\_0xAD)

Bit	Symbol	Access	Default	Description
15:0	Pkg_ob_valid_high	RO RC	0x0	Pkg_ob_valid[31:16], pkg_ob_valid is the number of TX packages from MII whose CRC
				are good and length are >=64Byte and
			9	<=1518Byte.

#### 6.5.17. Pkg Tx Valid1 (EXT 0xAE)

#### Table 86. Pkg Tx Valid1 (EXT 0xAE)

e e n y								
6.5.17. Pkg Tx Valid1 (EXT_0xAE)								
	Table 86. Pkg Tx Valid1 (EXT_0xAE)							
Bit	Symbol	Access	Default	Description				
15:0	Pkg_ob_valid_low	RO RC	0x0	Pkg_ob_valid[15:0], pkg_ob_valid is the number of TX packages from MII whose CRC are good and length are >= 64Byte and <=1518Byte.				

#### 6.5.18. Pkg Tx Os0 (EXT\_0xAF)

#### Table 87. Pkg Tx Os0 (EXT\_0xAF)

Bit	Symbol	Access	Default	Description
15:0	Pkg_ob_os_good_high	RO RC	0x0	Pkg_ob_os_good[31:0], pkg_ob_os_good is the number of TX packages from GMII whose CRC are good and length are >1518Byte.

#### 6.5.19. Pkg Tx Os1 (EXT\_0xB0)

#### Table 88. Pkg Tx Os1 (EXT\_0xB0)

Bit	Symbol	Access	Default	Description
15:0	Pkg_ob_os_good_low	RO RC	0x0	Pkg_ob_os_good[15:0], pkg_ob_os_good is the number of TX packages from GMII whose CRC are good and length are >1518Byte.

#### 6.5.20. Pkg Tx Us0 (EXT\_0xB1)

Table 89. Pkg Tx Us0 (EXT\_0xB1)



_					1/4
	Bit	Symbol	Access	Default	Description
	15:0	Pkg_ob_us_good_high	RO RC		Pkg_ob_us_good[31:0], pkg_ob_us_good is the number of TX packages from GMII whose CRC are good and length are <64Byte.

#### 6.5.21. Pkg Tx Us1 (EXT\_0xB2)

#### Table 90. Pkg Tx Us1 (EXT\_0xB2)

Bit	Symbol	Access	Default	Description		
15:0	Pkg_ob_us_good_low	RO RC	0x0	Pkg_ob_us_good[15:0], pkg_ob_us_good is the number of TX packages from GMII whose CRC are good and length are >1518Byte.		
				03-12		
6.5.22	6.5.22. Pkg Tx Err (EXT 0xB3)					

#### 6.5.22. Pkg Tx Err (EXT 0xB3)

#### Table 91. Pkg Tx Err (EXT\_0xB3)

Bit	Symbol	Access	Default	Description
15:0	Pkg_ob_err	RO RC	0x0	pkg_ob_err is the number of TX packages from GMII whose CRC are wrong and length are >=64Byte, <=1518Byte.

#### 6.5.23. Pkg Tx Os Bad (EXT\_0xB4) ⊗

#### Table 92. Pkg Tx Os Bad (EXT\_0xB4)

Bit	Symbol	5	Access	Default	Description
15:0	Pkg_ob_os_bad		RO RC	0x0	pkg_ob_os_bad is the number of TX packages from GMII whose CRC are wrong and length are >=1518Byte.

#### 6.5.24. Pkg Tx Fragment (EXT 0xB5)

#### Table 93. Pkg Tx Fragment (EXT 0xB5)

Bit	Symbol	Access	Default	Description
15:0	Pkg_ob_frag	RO RC	0x0	pkg_ob_frag is the number of TX packages from GMII whose length are <64Byte.

#### 6.5.25. Pkg Tx Nosfd (EXT\_0xB6)

#### Table 94. Pkg Tx Nosfd (EXT 0xB6)

	3/// //·····							
Bit	Symbol	Access	Default	Description				
15:0	Pkg_ob_nosfd	RO RC	0x0	pkg_ob_nosfd is the number of TX packages from GMII whose SFD is missed.				

#### 6.6. SDS MII Register

#### 6.6.1. Basic Control Register (0x00)

#### Table 95. Basic Control Register (0x06)

Bit	Symbol	Access	Default	Description		
15	Reset	RW SC	0x0	SDS Software Reset. Writing 1 to this bit causes		





	<b>提供有限公司</b>			
Moto	rcomm YT8521SH-CA/Y	T8521SC-	CA Data	sheet 裕太微电子 Motorcomm
(1)			~~	immediate PHY reset. Once the operation is done, this bit is cleared automatically.  0: Normal operation  T: SDS reset
14	Loopback	RW SWC	0x0	Internal loopback control 1'b0: disable loopback 1'b1: enable loopback
13	Speed_Selection(LSB)	RW	0x0	Valid only when the SerDes works as SGMII MAC, for example, when the chip mode is SGMAC_TO_RGPHY.  LSB of speed_selection[1:0]. Link speed can be selected via either the Auto-Negotiation process, or manual speed selection
				speed_selection[1:0]. Speed_selection[1:0] is valid when Auto-Negotiation is disabled by clearing bit 0.12 to zero.  Bit6 bit13  1 1 = Reserved 1 0 = 1000Mb/s 0 1 = 100Mb/s 0 0 = 10Mb/s
12	Autoneg_En	RW	0x1	1: enable auto-negotiation; 0: disable auto-negotiation.
11	Power_down	RW SWC	0x0	1 = Power down 0 = Normal operation
10	Isolate	RW SWC	0x0	Isolate SerDes from RGMII/UTP.
9	Re_Autoneg	RW SC	0x0	1 = Restart SGMII/1000BASE-X Auto-Negotiation; 0 = Normal operation. It's self clear.
8	Duplex_Mode	RW	0x1	Valid only when the SerDes works as SGMII MAC, for example, when the chip mode is SGMAC_TO_RGPHY.
			a ym	The duplex mode can be selected via either the Auto-Negotiation process or manual duplex selection. Manual duplex selection is allowed when Auto-Negotiation is disabled by setting bit[12] Autoneg_En to 0.  1 = Full Duplex 0 = Half Duplex
7	Reserved	RW	0x0	Reserved
6	Speed_Selection(MSP)	RW	0x1	See bit13.
5:0	Reserved	RW	0x0	Reserved. Write as 0, ignore on read

#### 6.6.2. Basic Status Register (0x01)

Table 96. Basic Status Register (0x01)

Bit	Symbol	Access	Default	Description	
15	100BASE-T4	RO	0x0	PHY doesn't support 100BASE-T4	
14	100BASE-X_Fd	RO	0x0	PHY supports 100BASE-X_FD	
13	100BASE-X_Hd	RO	0x0	PHY supports 100BASE-X_HD	
12	10Mbps_Fd	RO	0x0	PHY supports 10Mbps_Fd	
12 TOWOPS_TU IKO OXO TITE SUPPORTS TOWOPS_TU					
	m <sup>s</sup>				



			Motorcomm	=
10Mbps_Hd	RO	0x0	PHY supports 10Mbps_Hd	
100BASE-T2_Fd	RO	0x0	PHY doesn't support 100BASE-T2_Fd	
100BASE-T2_Hd	RO	0x0	PFFY doesn't support 100BASE-T2_Hd	
Extended_Status	RO	0x0	Whether support Extended status register in MII register 0xF	
	此有限以	Ç-3	0: Not supported 1: Supported	
Unidirect_Ability	RO	0x0	1'b0: PHY able to transmit from MII only when the PHY has determined that a valid link has been established	. 5
47.			1'b1: PHY able to transmit from MII regardless of whether the PHY has determined that a valid link has been established	21.
Mf_Preamble_Suppression	RO	0x1	1'b0: PHY will not accept management frames with preamble suppressed 1'b1: PHY will accept management frames with preamble suppressed	
Autoneg_Complete	RO SWC	0x0	1'b0: Auto-negotiation process not completed 1'b1: Auto-negotiation process completed	
Remote_Fault	RO RC SWC LH	0x0	1'b0: no remote fault condition detected 1'b1: remote fault condition detected	
Autoneg_Ability	RO	0x1 5	1'b0: PHY not able to perform Auto-negotiation 1'b1: PHY able to perform Auto-negotiation	0
Link_Status	RO LL SWC	0x0	Link status 1'b0: Link is down 1'b1: Link is up	25.03
Reserved	RO	0x0	always 0	
Extended_Capability	RO	0x1	To indicate whether support EXTended registers, to access from address register MII 0x1E and data register MII 0x1F 1'b0: Not supported	
	100BASE-T2_Fd 100BASE-T2_Hd Extended_Status  Unidirect_Ability  Mf_Preamble_Suppression  Autoneg_Complete  Remote_Fault  Autoneg_Ability  Link_Status  Reserved	100BASE-T2_Fd RO 100BASE-T2_Hd RO Extended_Status RO  Unidirect_Ability RO  Mf_Preamble_Suppression RO  Autoneg_Complete RO SWC  Remote_Fault RO RC SWC LH  Autoneg_Ability RO  Link_Status RO LL SWC  Reserved RO	100BASE-T2_Fd       RO       0x0         100BASE-T2_Hd       RO       0x0         Extended_Status       RO       0x0         Unidirect_Ability       RO       0x0         Mf_Preamble_Suppression       RO       0x1         Autoneg_Complete       RO SWC       0x0         Remote_Fault       RO RC SWC LH       0x0         Autoneg_Ability       RO       0x1         Link_Status       RO LL SWC       0x0         Reserved       RO       0x0	100BASE-T2_Fd

#### 6.6.3. Sds Identification Register1 (0x02)

#### Table 97. Sds Identification Register1 (0x02)

				• ,
Bit	Symbol	Access	Default	Description
15:0	Phy_Id	RO	0x0	Bits 3 to 18 of the Organizationally Unique
	- kt	147		Identifier

#### 6.6.4. Sds Identification Register2 (0x03)

#### Table 98. Sds Identification Register2 (0x03)

Bit	Symbol	Access	Default	Description		
15:10	Phy_Id	RO	0x0	Bits 19 to 24 of the Organizationally Unique		
				Identifier		
9:4	Type_No	RO	0x11	6 bits manufacturer's type number		
3:0	Revision_No	RO	0xa	4 bits manufacturer's revision number		
ms@seny 50°s						



#### 6.6.5. Auto-Negotiation Advertisement (0x04)

#### Table 99. Auto-Negotiation Advertisement (0x04)

Bit	Symbol	Access	Default	Description
15	NEXT_Page	RW	0x0 / 1	Not used. YT8521S SGMII and 1000BASE-X autoneg doesn't support NEXT page.
14	Ack	RO RE	0x0	Always 0
13:12	Remote_Fault	RO	0x0	Always 0
11:9	Reserved	RO	0x0	Reserved
8	Asymmetric_Pause	RW	0x1	Asymmetric_Pause ability.
7	Pause	RW	0x1	Pause aiblity.
6	Half_duplex	RW	0x0	Half duplex ability
5	Full_duplex	RW	0x1	Full duplex ability
4:0	Reserved	RO	0x0	Reserved

#### 6.6.6. Auto-Negotiation Link Partner Ability (0x05)

#### Table 100. Auto-Negotiation Link Partner Ability (0x05)

Bit	Symbol	Access	Default	Description
15	NEXT Page	RO SWC	0x0	NEXT page. Received Code Word Bit 15
14	ACK	RO SWC	0x0 5	Acknowledge. Received Code Word Bit 14
13:12	REMOTE_FAULT	RO SWC	0x0	Remote Fault. Received Code Word Bit 13:12
11:9	RESERVED	RO e	0x0	Reserved. Received Code Word Bit 11:9
8:7	PAUSE	RO SWC	0x0	Pause. Received Code Word Bit 8:7
6	HALF_DUPLEX	RO SWC	0x0	Half duplex. Received Code Word Bit 6
5	FULL_DUPLEX	RO SWC	0x0	Full duplex. Received Code Word Bit 5
4:0	RESERVED	RO	0x0	Reserved. Received Code Word Bit 4:0

#### 6.6.7. Auto-Negotiation Expansion Register (0x06)

#### Table 101. Auto-Negotiation Expansion Register (0x06)

Bit	Symbol	Access	Default	Description
15:3	Reserved	RO	0x0	Reserved
2	Local NEXT Page able	RO	0x0 \	1 = Local Device supports NEXT Page
				0 = Local Device does not support Next Page
1	Page received	RO RO	0x0	1 = A new page is received
		LH		
0	Reserved	RO	0x0	Reserved

#### 6.6.8. Auto-Negotiation NEXT Page Register (0x07)

#### Table 102. Auto-Negotiation NEXT Page Register (0x07)

Bit	Symbol	Access	Default	Description	3
15:0	NEXT Page	RO	0x0	always be 0	

#### 6.6.9. Auto-Negotiation Link Partner Received NEXT Page Register (0x08)

#### Table 103. Auto-Negotiation Link Partner Received NEXT Page Register (0x08)

Bit	Symbol	Access	Default	Description			
			G (				
	51						
		6	7,				
	0,5						
	., 10	5					



	304	Link Partner NEXT Page	RO	OvO	always be 0
15.	3:0	Link Partner NEXT Page	KO	0x0	always be 0

#### 6.6.10. Extended status register (0x0F)

#### Table 104. Extended status register (0x0F)

5 0 S

Bit	Symbol	Access	Default	Description	
15	1000BASE-X Full Duplex	RO	0x1	1 = PHY supports 1000BASE-X Full Duplex	
14	1000BASE-X Half Duplex	RO	0x0	1 = PHY supports 1000BASE-X Half Duplex.	
13	1000BASE-T Full Duplex	RO	0x0	1 = PHY supports 1000BASE-T Full Duplex	. 5
12	1000BASE-T Half Duplex	RO	0x0	1 = PHY supports 1000BASE-T Half Duplex	0 1 .
11:0	Reserved	RO	0x0	Always 0	L

#### 6.6.11. Sds Specific Status Register (0x11)

#### Table 105. Sds Specific Status Register (0x11)

Bit	Symbol	Access	Default	Description	
15:14	Speed_mode	RO S S	0x0	When SerDes works as SGMII MAC, if Auto-Negotiation is enabled, the speed_mode is sourced from Auto-Negotiation process with SGMII PHY, otherwise, it's from SDS MII 0x0 Speed_Selection; When SerDes works as SGMII PHY, it equals to the UTP speed mode; When SerDes works as 1000BASE-X, it equals to 10; When SerDes works as 100BASE-FX, it equals to 01. Refer to SDS MII 0x11 bit5:4 for SerDes' working mode.	25-03
13	Duplex	RO	Ox0	When SerDes works as SGMII MAC, if Auto-Negotiation is enabled, the duplex is sourced from Auto-Negotiation process with SGMII PHY, otherwise, it's from SDS MII 0x0 Duplex_Mode; When SerDes works as SGMII PHY, it equals to the UTP duplex mode; When SerDes works as 1000BASE-X, it's the result of 1000BASE-X half/full priority resolution function; When SerDes works as 100BASE-FX, it equals to 1. Refer to SDS MII 0x11 bit[5:4] for SerDes' working mode.	21.5
12:11	Pause	RO	0x0	Pause to mac	-
10	Link status real-time	RO	0x0	1 = SGMII Link up 0 = SGMII link down	
9	Rx_lpi_active	RO	0x0	rx lpi is active	
8	Duplex_error	RO	0x0	realtime duplex error	
7	En_flowctrl_rx	RO	0x0	realtime en_flowctrl_rx	
6	En_flowctrl_tx	RO	0x0	realtime en_flowctrl_tx	
5:4	Ser_mode_cfg	RO	0x0	realtime serdes working mode, 00: SGMII MAC;	
		5 © 5 ° °	32 <sup>5</sup>		



THE STATE OF THE S				01: SGMII PHY;
				10: 1000BASE-X;
				11:00BASE-FX.
3:1	Xmit	RO	0x0	realtime transmit statemachine,
			7	001: Xmit Idle;
		18/12	(5)	010: Xmit Config;
		世相的		100: Xmit Data.
0	Syncstatus	RO	0x0	realtime SerDes PCS sync status

#### 6.6.12. 100BASE-FX Cfg (0x14)

#### Table 106. 100BASE-FX Cfg (0x14)

Bit	Symbol	Access	Default	Description
15	Force_sg_status	RW	0x0	Force sds linkup
14	Duplex_to_mac_100fx	RW	0x1	duplex setting to mac in 100BASE-FX mode
13:12	Pause_to_mac_100fx	RO	0x3	Pause setting to mac in 100BASE-FX mode
11:0	Reserved	RO	0x0	Reserved

#### 6.6.13. Receive Err Counter (0x15)

#### Table 107. Receive Err Counter (0x15)

Bit	Symbol	Access	Default	Description
15:0	error_counter_rx	RO SWC	0x0	This counter increase by 1 at the 1st rising of
				RX_ER when RX_DV is 1. The counter will
	110			hold at maximum 16'hFFFF and not roll over.

#### 6.6.14. Link Fail Counter (0x16)

#### **Table 108. Link Fail Counter (0x16)**

Bit	Symbol	Access	Default	<b>Description</b> 5
15:8	Reserved	RO	0x0	Reserved
7:0	Link_fail_cnt	RO RC SWC	0x0	link fail counter

#### 6.7. SDS EXT Register

#### 6.7.1. Pkgen Cfg1 (EXT 3x38)

#### Table 109. Pkgen Cfg1 (EXT\_0x38)

Bit	Symbol	Access	Default	Description
15:13	Reserved	RW	0x0	Reserved
12	En_pkgen_da_sa	RW	0x0	1: set the DA/SA of the packet generated by pkg_gen in SerDes to a programmed value; For DA, if SDS EXT 0x38 bit11 is 1, the DA is set to broadcase address FF-FF-FF-FF-FF-FF; else, the DA is set to fix value, the highest 5 Bytes are 00-00-00-00-00, and the lowest 1 Byte is programmed by SDS EXT 0x3A bit[15:8]. For SA, the highest 5 Bytes are 00-00-00-00, and the lowest 1 Byte is programmed by SDS EXT



"房"				0x3A bit[7:0].
				0: the DA/SA is not programmed value
11	Pkgen_brdcst	RW	0x0	Valid when SDS EXT 0x38 bit12 is 1.
			77	1: set the DA to broadcase address
			7	FF-FF-FF-FF-FF
		حلام	53	0: set the DA to a fixed programmed value.
10	Pkgchk_txsrc_sel	RV	0x0	1'b1: the package checker on SerDes TX side
	_ th	Mr.		will check the tx data generated by pkg_gen;
		1		1'b0: the package checker on SerDes TX side
				will check the tx data of SerDes GMII.
9:0	Reserved	RW	0x1ff	Reserved

# 6.7.2. Pkgen Cfg3 (EXT\_0x3A)

## Table 110. Pkgen Cfg3 (EXT\_0x3A)

				2'	
6.7.2.	Pkgen Cfg3 (EX	$T_0x3A$ )		3	
	Table 110. Pkgen Cfg3 (EXT_0x3A)				
Bit	Symbol	Access	Default	Description	
15:8	Pkgen_da	RW	0x0	Lowest 8 bits of DA, others is zero. Refer to SDS EXT 0x38 bit[12] for detail.	
7:0	Pkgen_sa	RW	0x0	Lowest 8 bits of SA, others is zero. Refer to SDS EXT 0x38 bit[12] for detail.	

#### 6.7.3. Pkg Cfg0 (EXT\_0x1A0)

# Table 111. Pkg Cfg0 (EXT\_0x1A0)

Bit	Symbol	Access	Default	Description	
15	Pkg_chk_en	RW	0x0	1: to enable SerDes RX/TX package checker. RX checker checks the SerDes GMII RX data; TX checker checks the SerDes GMII TX data.	
14	Pkg_en_gate	RW	0x1	1: to enable gate all the clocks to package self-test module when bit15 pkg_chk_en is 0, bit13 bp_pkg_gen is 1 and bit12 pkg_gen_en is 0; 0: not gate the clocks.	
13	Bp_pkg_gen	RW	0x1	1: normal mode, to send GMII TX data from upstream MAC; 0: test mode, to send out the GMII data generated by pkg_gen module.	
12	Pkg_gen_en	RW SC	0x0	1: to enable pkg_gen generating GMII packages. But, the data will only be sent to transceiver when Bit13 bp_pkg_gen is 1'b0. If pkg_burst_size is 0, continuous packages will be generated and will be stopped only when pkg_gen_en is set to 0; Otherwise, after the expected packages are generated, pkg_gen will stop, pkg_gen_en will be self-cleared.	
11:8	Pkg_prm_lth	RW	0x8	The preamble length of the generated packages, in Byte unit. Pkg_gen function only support >=2 Byte preamble length. Values smaller than 2 will be ignored by the pkg_gen module.	
7:4	Pkg_ipg_lth	RW	0xd	The IPG of the generated packages, in Byte unit, Pkg_gen function only support >=2 Byte preamble length. Values smaller than 2 will be	
	54 <sup>S</sup>				



				Motorcomm
E.				ignored by the pkg_gen module.
3	Reserved	RW	0x0	Reserved
2	Pkg_corrupt_crc	RW	0x0	1: 6 make pkg_gen to send out CRC error
			77 11	packages.
1:0	Pkg_payload	RW	0x0	Control the payload of the generated packages.
		TE!L	Ç-> 3	00: increased Byte payload;
		此為於		01: random payload;
	T, t.t.	MAY.		10: fix pattern 0x5AA55AA5
	1 × 111 1			11: reserved.

#### 6.7.4. Pkg Cfg1 (EXT\_0x1A1)

#### Table 112. Pkg Cfg1 (EXT\_0x1A1)

				<u> </u>
Bit	Symbol	Access	Default	Description
15:0	Pkg_length	RW	0x40	To set the length of the generated packages.
				202
				· · · · · · · · · · · · · · · · · · ·

#### 6.7.5. Pkg Cfg2 (EXT 0x1A2)

#### Table 113. Pkg Cfg2 (EXT\_0x1A2)

Bit	Symbol	Access	Default	Description
15:0	Pkg_burst_size	RW	0x0 S	To set the number of packages in a burst of
			1.0	package generation.

#### 6.7.6. Pkg Rx Valid0 (EXT\_0x1A3)

#### Table 114. Pkg Rx Valid0 (EXT\_0x1A3)

Bit	Symbol	Access	Default	Description
15:0	Pkg_ib_valid_high	RO RC	0x0	Pkg_ib_valid[31:16], pkg_ib_valid is the number of RX packages from wire whose CRC are good and length are >=64Byte and <=1518Byte.

#### 6.7.7. Pkg Rx Valid1 (EXT\_0x1A4)

#### Table 115. Pkg Rx Valid1 (EXT\_0x1A4)

Bit	Symbol	Access	Default	Description
15:0	Pkg_ib_valid_low	ROPC	0x0	Pkg_ib_valid[15:0], pkg_ib_valid is the number of RX packages from wire whose CRC are good and length are >=64Byte and <=1518Byte.

#### 6.7.8. Pkg Rx Os0 (EXT\_0x1A5)

#### Table 116. Pkg Rx Os0 (EXT 0x1A5)

D.,				) (EXT_0x1A5)
Bit	Symbol	Access	Default	Description
15:0	Pkg_ib_os_good_high	RO RC	0x0	Pkg_ib_os_good[31:16], pkg_ib_os_good is the
				number of RX packages from wire whose CRC
				are good and length are >1518Byte.
				c o w
				f t.
			. 25 <sup>5</sup>	3
		m <sup>s@se</sup>	7	



#### 6.7.9. Pkg Rx Os1 (EXT\_0x1A6)

#### Table 117. Pkg Rx Os1 (EXT\_0x1A6)

Bit	Symbol	Access	Default	Description
15:0	Pkg_ib_os_good_low	RO RC	0x0	Pkg_ib_os_good[15:0], pkg_ib_os_good is the
				number of RX packages from wire whose CRC
		TRIV		are good and length are >1518Byte.

#### 6.7.10. Pkg Rx Us0 (EXT 0x1A7)

#### Table 118. Pkg Rx Us0 (EXT\_0x1A7)

Bit	Symbol	Access	Default	Description
15:0	Pkg_ib_us_good_high	RO RC	0x0	Pkg_ib_us_good[31:16], pkg_ib_us_good is the number of RX packages from wire whose CRC are good and length are <64Byte.

#### 6.7.11. Pkg Rx Us1 (EXT\_0x1A8)

# Table 119. Pkg Rx Us1 (EXT\_0x1A8)

Bit	Symbol	Access	Default	Description
15:0	Pkg_ib_us_good_low	RO RC	0x0	Pkg_ib_us_good[15:0], pkg_ib_us_good is the number of RX packages from wire whose CRC are good and length are >1518Byte.

#### 6.7.12. Pkg Rx Err (EXT\_0x1A9)

#### Table 120. Pkg Rx Err (EXT\_0x1A9)

	1400 1201 119 121 (271 2071)					
Bit	Symbol	Access	Default	Description		
15:0	Pkg ib err	RO RC	0x0	pkg_ib_err is the number of RX packages from wire whose CRC are wrong and length are >=64Byte, <=1518Byte.		

#### 6.7.13. Pkg Rx Os Bad (EXT 0x1AA)

#### Table 121. Pkg Rx Os Sad (EXT\_0x1AA)

Bit	Symbol	Access	Default	Description
15:0	Pkg_ib_os_bad	RO RC	0x0	pkg_ib_os_bad is the number of RX packages from wire whose CRC are wrong and length are >=1518Byte.

#### 6.7.14. Pkg Rx Fragment (EXT\_0x1AB)

#### Table 122. Pkg Rx Fragment (EXT\_0x1AB)

Bit	Symbol	Access	Default	Description
15:0	Pkg_ib_frag	RO RC		pkg_ib_frag is the number of RX packages from wire whose length are <64By(e.

#### 6.7.15. Pkg Rx Nosfd (EXT\_0x1AC)

#### Table 123. Pkg Rx Nosfd (EXT 0x1AC)

Bit	Symbol	Acc	ess Default	Description		
	. 56°					
			e			
	i m s					



15.0	Pkg_ib_nosfd	RO RC	0x0	pkg_ib_nosfd is the number of RX packages from wire whose SFD is missed.
				from wife whose SFD is missed.

#### 6.7.16. Pkg Tx Valid0 (EXT 0x1AD)

#### Table 124 Pkg Tx Valid0 (EXT\_0x1AD)

Bit	Symbol	Access	Default	Description
15:0	Pkg_ob_valid_high	RO RC	0x0	Pkg_ob_valid[31:16], pkg_ob_valid is the number of TX packages from GMII whose CRC are good and length are >=64Byte and <=1518Byte.

#### 6.7.17. Pkg Tx Valid1 (EXT\_0x1AE)

#### Table 125. Pkg Tx Valid1 (EXT\_0x1AE)

Bit	Symbol	Access	Default	Description
15:0	Pkg_ob_valid_low	RO RC	0x0	Pkg_ob_valid[15:0], pkg_ob_valid is the number of TX packages from GMII whose CRC are good and length are >=64Byte and <=1518Byte.

#### 6.7.18. Pkg Tx Os0 (EXT\_0x1AF)

#### Table 126. Pkg Tx Os0 (EXT\_0x1AF)

Bit	Symbol	Access	Default	Description
15:0	Pkg_ob_os_good_high	RO RC	0x0	Pkg_ob_os_good[31:0], pkg_ob_os_good is the
	all E			number of TX packages from GMII whose CRC
	THE SECTION OF THE SE			are good and length are >1518Byte

#### 6.7.19. Pkg Tx Os1 (EXT\_0x1B0)

#### Table 127. Pkg Tx Os1 (EXT 0x1B0)

Bit	Symbol	Access	Default	Description	
15:0	Pkg_ob_os_good_low	RO RC	0x0	Pkg_ob_os_good[15:0], pkg_ob_os_good is the number of TX packages from GMII whose CRC	
		. 18	(2)	are good and length are >1518Byte.	

#### 6.7.20. Pkg Tx Us0 (EXT 6x1B1)

#### Table 128. Pkg Tx Us0 (EXT 0x1B1)

Bit	Symbol	Access	Default	Description
15:0	Pkg_ob_us_good_high	RO RC	0x0	Pkg_ob_us_good[31:0], pkg_ob_us_good is the number of TX packages from GMII whose CRC are good and length are <64Byte.

#### 6.7.21. Pkg Tx Us1 (EXT\_0x1B2)

#### Table 129, Pkg Tx Us1 (EXT\_0x1B2)

14515 12511 Kg 1X 551 (2X125X125X)								
Bit	Symbol	Access	Default	t Description				
15:0	Pkg_ob_us_good_low	RO RC	0x0	Pkg_ob_us_good[15:0], pkg_ob_us_good is the				

57<sup>5</sup>



	Motorcomm
得"	number of TX packages from GMII whose CRC
	are good and length are >1518Byte.
	S 0 5
	1,10

#### 6.7.22. Pkg Tx Err (EXT\_0x1B3)

#### Table 130. Pkg Tx Err (EXT\_0x1B3)

Bit	Symbol	Access	Default	Description
15:0	Pkg_ob_err	RO RC	0x0	pkg_ob_err is the number of TX packages from GMII whose CRC are wrong and length are >=64Byte, <=1518Byte.

#### 6.7.23. Pkg Tx Os Bad (EXT\_0x1B4)

#### Table 131. Pkg Tx Os Bad (EXT\_0x1B4)

Bit	Symbol	Access	Default	Description
15:0	Pkg_ob_os_bad	RO RC	0x0	pkg_ob_os_bad is the number of TX packages from GMII whose CRC are wrong and length are >=1518Byte.

#### 6.7.24. Pkg Tx Fragment (EXT\_0x1B5)

#### Table 132. Pkg Tx Fragment (EXT\_0x1B5)

Bit	Symbol	Access	Default	Description
15:0	Pkg_ob_frag	RO RC	0x0	pkg_ob_frag is the number of TX packages
	10			from GMII whose length are <64Byte.

#### 6.7.25. Pkg Tx Nosfd (EXT\_0x1B6)

#### Table 133. Pkg Tx Nosfd (EXT\_0x1B6)

Bit	Symbol	Access	Default	<b>Description</b> 5
15:0	Pkg_ob_nosfd	RO RC	0x0	pkg_ob_nosfd is the number of TX packages from GMII whose SFD is missed.
		世有限心	国 Ym	
		中华有户区		





21.5

# Timing and AC/DC Characteristics DC Characteristics

#### 7.1. DC Characteristics

Symbol	Parameter	Min	Тур	Max	Units
DVDD33, AVDD33	3.3V Supply Voltage	2.97	3.3	3.63	V
2.5V MDIO, MDC, RGMII I/O	2.5V RGMII Supply Voltage	2.25	2.5	2.75	V
1.8V MDIO, MDC, RGMII 1/O	1.8V RGMII Supply Voltage	1.62	1.8	1.98	V
Voh (3.3V)	Minimum High Level Output Voltage	2.4	-	3.6	V
Voh (2.5V)	Minimum High Level Output Voltage	2	-	2.8	V
Voh (1.8V)	Minimum High Level Output Voltage	1.62	-	2.1	y2
Vol (3.3V)	Maximum Low Level Output Voltage	-0.3	-	0.4	V
Vol (2.5V)	Maximum Low Level Output Voltage	-0.3	- <	0.4	V
Vol (1.8V)	Maximum Low Level Output Voltage	-0.3	-0,7	0.4	V
Vih (3.3V)	Minimum High Level Input Voltage	2	1	-	V
Vil (3.3V)	Maximum Low Level Input Voltage	0 111	-	0.8	V
Vih (2.5V)	Minimum High Level Input Voltage	1.7	-	-	V
Vil (2.5V)	Maximum Low Level Input Voltage	-	-	0.7	V
Vih (1.8V)	Minimum High Level Input Voltage	1.2	-	-	V
Vil (1.8V)	Maximum Low Level Input Voltage	-	-	0.5	V
	_ @ S E ()				

## 7.2. AC Characteristics

#### 7.2.1. SGMII Differential Transmitter Characteristics

#### Table 135. SGMII Differential Transmitter Characteristics

Symbol	Parameter	Min	Typ	Max	Units	Notes
PI///	Unit Interval	799.94	800	800.06	ps	$800 \text{ps} \pm 75 \text{ppm}$
T_X1	Eye Mask	-	-	0.1875	UI	-
T_X2	Eye Mask	-	-	0.4	UI	-
T_Y1	Eye Mask	200	- 0	5-	mV	-
T_Y2	Eye Mask	-	-7	450	mV	-
V <sub>TX-DIFFp-p</sub>	Output Differential Voltage	400	700	900	mV	-
T <sub>TX-EYE</sub>	Minimum TX Eye Width	0.625	-	-	UI	-
T <sub>TX-JITTER</sub>	Output Jitter	-	-	0.375	UI	$T_{TX\text{-JITTER-MAX}} = 1 - T_{TX\text{-EYE-MIN}} = 0.375UI$
$R_{TX}$	Differential Resistance	80	100	120	ohm	-
$C_{TX}$	AC Coupling Capacitor	75	100	200	nF	-
IL	Insertion Loss@1.25GHz	-	-	10	dB	- 1
			59 <sup>5</sup>	Q		2025-03-27
	~ S (W)					



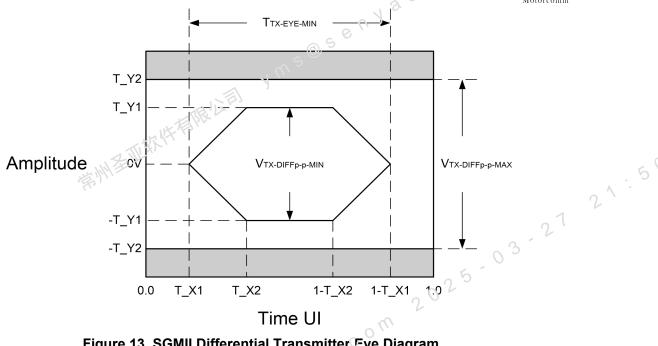


Figure 13. SGMII Differential Transmitter Eye Diagram

#### 7.2.2. SGMII Differential Receiver Characteristics

#### **Table 136. SGMII Differential Receiver Characteristics**

Symbol	Parameter	Min	Typ	Max	Units	Notes	5
UI	Unit Interval	799.94	800	800.06	ps	800ps ± 75ppm	2
R_X1	Eye Mask	-	-	0.3125	UI	- 2	
R_Y1	Eye Mask	50	-	-	mV	- 0 10	
R_Y2	Eye Mask	-	-	600	mV	-	
V <sub>RX-DIFFp-p</sub>	Input Differential Voltage	100	-	1200	mV	- 4	
T <sub>RX-EYE</sub>	Minimum RX Eye Width	0.375	-	-	UI	- 5	
RX-JITTER	Input Jitter Tolerance	-	-	0.625	UI	$T_{RX-JITTER-MAX} = 1 - T_{RX-EYE-MIN} = 0.625UI$	
$R_{RX}$	Differential Resistance	80	100	120	ohm	-	
	海州圣亚林	限以高	7	//			

2025-03-27 2025-03-27



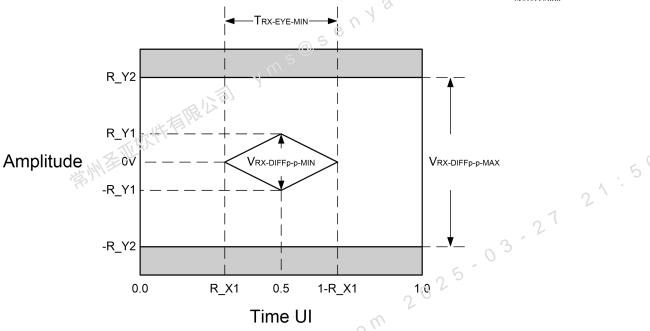


Figure 14. SGMII Differential Receiver Eye Diagram

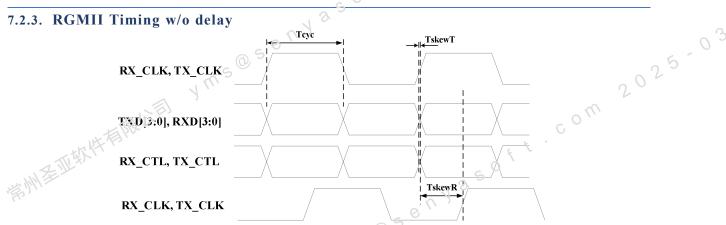


Figure 15. RGMII Timing w/o delay

Table 137. RGMII Timing w/o delay

Symbol	Parameter	Min	Тур	Max	Unit	
TskewT	Data to clock output skew (at Transmitter)	-500	0	500	ps	
TskewR	Data to clock input skew (at Receiver)	1	_	_	ns	
Тсус	Clock cycle duration	7.2	8.0	8.8	ns	5
Duty_G	Duty cycle for Gigabit	45	50	55	%	۸ .
Duty_T	Duty cycle for 10/100	40	50	60	%	2
	50 Seny 6150		w 50	25		



#### 7.2.4. RGMII Timing with internal delay

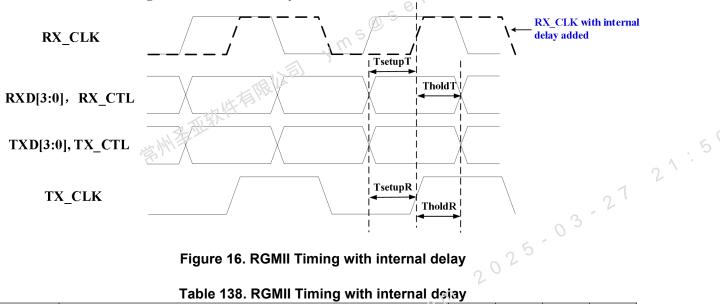


Figure 16. RGMII Timing with internal delay

Table 138. RGMII Timing with internal delay

Symbol	Parameter	Min	Тур	Max	Unit	
TsetupT	Data to Clock output Setup Time (at Transmitter — integrated delay)	1.0	2.0	-	ns	
TholdT	Clock to Data output Hold Time (at Transmitter — integrated delay)	1.0	2.0	-	ns	2
TsetupR	Data to Clock input Setup Time (at Receiver — integrated delay)	1.0	2.0	-	ns	0 0
TholdR	Clock to Data input Hold Time (at Reciever — integrated delay)	1.0	2.0	-	ns	25
	1 Mills				2	) -

### 7.2.5. SMI (MDC/MDIO) Interface Characteristics

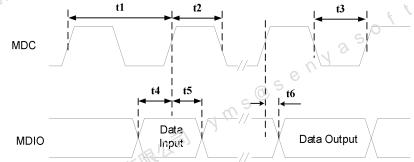


Figure 17. SMI (MDC/MDIO) Timing

Table 139. SMI (MDC/MDIO) Interface Characteristics

Symbol	Description	Min	Тур	Max	Units			
t1	MDC Clock Period	80	-	-	ns			
t2	MDC High Time	32	-	-	ns 🤈			
t3	MDC Low Time	32	-	- 0	ns			
t4	MDIO to MDC Rising Setup Time (Data Input)	10	-	- 0	ns			
t5	MDIO to MDC Rising Hold Time (Data Input)	10	- 2	Ō	ns			
t6	MDIO Valid from MDC rising edge (Data Output)	0	-2	20	ns			
ms@seny 6250ft.com								



# 7.3. Crystal Requirement

Table 140. Crystal Requirement

Table 1 101 or your 100 or you								
Symbol	Description	Min	Тур	Max	Unit			
Fref	Parallel Resonant Crystal Reference Frequency	-	25	-	MHz			
Fref Tolerance	Parallel Resonant Crystal Reference Frequency Tolerance	-50	-	50	ppm			
Fref Duty Cycle	Reference Clock Input Duty Cycle 40			60	%			
ESR	Equivalent Series Resistance	-		50	ohm			
DL	Drive Level	-	-	0.5	mW	5		
Vih	Crysial output high level	1.4	-	-	V	۷.,		
Vil	Crystal output low level	-	-	0.4	V	2 '		
					2			
				3				
7.4. Oscilla	7.4. Oscillator/External Clock Requirement							
	Table 444 Ossillator/Estamos Olask Barrina		7					

## 7.4. Oscillator/External Clock Requirement

Table 141. Oscillator/External Clock Requirement

Parameter	Min	Тур	Max	Unit
Frequency	-	25	- 0 10	MHz
Frequency tolerance	-50	- 10	50	PPM
Duty Cycle	40	- 0 1	60	%
Peak to Peak Jitter	-	- , 25	200	ps
Vih	1.4	6	AVDD33+0.3	V
Vil	- 0,5	-	0.4	V
Rise Time (10%~90%)	We	-	10	ns
Fall Time (10%~90%)	_	-	10	ns
Fall Time (10%~90%)			enyasof	. c o

IN COM 2025-03-27 2025-03-27



# Power Requirements

# 8.1. Absolute Maximum Ratings

Table 142. Absolute Maximum Ratings

Symbol	Description	Mini	Max	Unit	
VDD33/AVDD33	Supply Voltage 3.3V	-0.3	3.7	V	
AVDDL/DVDDL	Supply Voltage 1.2V	-0.2	1.4	V	
2.5V RGMII	Supply Voltage 2.5V	-0.3	2.8	V	
1.8V RGMII	Supply Voltage 1.8V	-0.3	2.3	V	
3.3V DC input	Input Voltage	-0.3	3.7	V	
1.2V DC input	Input Voltage	-0.3	1.4	v?	

## 8.2. Recommended Operating Conditions

Table 143. Recommended Operating Conditions

rubic 140. Recommended operating conditions							
Description	Pins	Min	Тур	Max	Unit		
Supply Voltage	DVDD33, AVDD33	2.97	3.3	3.63	V		
	AVDDL, DVDDL	1.08	1.2	1.32	V		
	2.5V RGMII	2.25	2.5	2.75	V		
	1.8V RGMII	1.62	1.8	1.98	V	0	
YT8521SC-CA An	0	-	70	°C	0 -		
YT8521SH-CA An	-40	-	85	°C	25		
Maximum Junction			125	°C 2			
			·		o W		
	TR'L				, 0		
0 0 D	c.						

# 8.3. Power Sequence

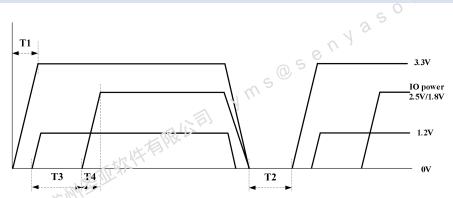


Figure 18. Power Sequence Diagram

**Table 144. Power Sequence Timing Parameters** 

Symbol	Description	Min	Тур	Max	Units		
T1	3.3V rising time	0.5	-	- 0	ms		
T2	3.3V and 1.2V power down duration	100	-	5	ms		
T3	Core power 1.2V ready time	-	- 00	2.5	ms		
T4	Internal LDO ready time	100	us				
IMS@SENY 64SOFT.CO							



#### 8.4. Power Consumption

#### 8.4.1. UTP <-> RGMII

#### Table 145. UTP <-> RGMII Power Consumption

//\						
Condition	DVDD_RGMII	DVDD33 + VDD33_LX	AVDD33	<b>Power Consumption</b>		
	(mA)	(mA)	(mA)	(mW)		
Reset	3	1.4	6	34.32		
Power Down	<b>©</b> 3	1.7	5	23.1		
Link Down	0.3	18.2	24.6	142.23		
Link Up @1000Mbps	5.6	131.8	72.2	691.68		
Traffic @1000Mbps	13	144.8	71.5	756.69		

Note: Test by TT IC with DVDD RGMII / DVDD33 / VDD33 LX / AVDD33 = 3.3V and VDDL = 1.2V (with inductor SWPA3012S2R2NT connected to VDD33 LX (pin33)) at room temperature.

#### 8.4.2. FIBER <->RGMII

#### Table 146. FIBER <-> RGMII Power Consumption

Condition	DVDD_RGMII	DVDD33 + VDD33_LX	AVDD33	Power Consumption
	(mA)	(mA)	(mA)	(mW)
Reset	3.1	1.45	6	34.65
Power Down	0.9	1.7	5	25.08
Link Down	0.9	21.7	26.3	161.37
Link Up @1000Mbps	5.8	26.5	26.2	193.05
Traffic @1000Mbps	13.7	25.1	26.2	214.5

Note: Test by TT IC with DVDD RGMII / DVDD33 / VDD33 LX / AVDD33 = 3.3V and VDDL = 1.2V (with inductor SWPA301282R2NT connected to VDD33 LX (pin33)) at room temperature.

#### 8.4.3. SGMII <-> RGMII

#### Table 147. SGMII <-> RGMII Power Consumption

Condition	DVDD_RGMII	DVDD33 + VDD33_LX	AVDD33	<b>Power Consumption</b>
	(mA)	(mA)	(mA)	(mW)
Reset	3.2	1,4 1	6	34.98
Power Down	2.6	1.8	5	31.02
Link Down	1.1	21.5	26.1	160.71
Link Up @1000Mbps	6.7	24.4	26.2	189.09
Traffic @1000Mbps	14/14/	23	26.2	208.56

Note: Test by TT IC with DVDD RGMII / DVDD33 / VDD33 LX / AVDD33 = 3.3V and VDDL = 1.2V (with inductor SWPA3012S2R2NT connected to VDD33 LX (pin33)) at room temperature.

#### 8.4.4. UTP <-> SGMII

#### Table 148, UTP <-> SGMII Power Consumption

Condition	DVDD_RGMII (mA)	DVDD33 + VDD33_LX (mA)	AVDD33 (mA)	Power Consumption (mW)
Reset	3.2	1.4	60	34.98
Power Down	2.6	1.8	G 3.1	31.35
Link Down	1.7	36	45.9	275.88
		5 E N Y 65 S		



			2	Motorcomin
Link Up @1000Mbps	1.9	150.5	92.7	808.83
Traffic @1000Mbps	1.9	164.3	≥ <u>92</u>	852.06

Note: Test by TT IC with DVDD RGMII / DVDD33 / VDD33 LX\(\nabla AVDD33 = 3.3V\) and VDDL = 1.2V (with inductor SWPA3012S2R2NT connected to VDD33 LX (pin33)) at room temperature.

#### 8.4.5. UTP <->FIBER

#### Table 149 UTP <-> FIBER Power Consumption

Condition	DVDD_RGMII (mA)	DVDD33 + VDD33_LX (mA)	AVDD33 (mA)	Power Consumption (mW)
Reset	4.1	1.4	6	37.95
Power Down	2.5	1.8	5	30.69
Link Down	1.8	36	45.8	275.88
Link Up @1000Mbps	0.9	150.6	92.7	805.86
Traffic @1000Mbps	0.9	165.7	92.4	854.7

Note: Test by TT IC with DVDD RGMII / DVDD33 / VDD33 LX / AVDD33 = 3.3V and VDDL = 1.2V (with inductor SWPA3012S2R2NT connected to VDD33 LX (pin33)) at room temperature.

## 8.5. Maximum Power Consumption

#### **Table 150. Maximum Power Consumption**

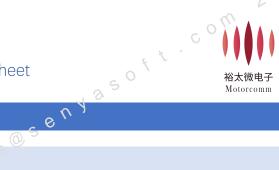
Condition	DVDD_RGMII	DVDD33 + VDD33_LX	AVDD33	Power Consumption	
	(mA)	(mA)	(mA)	(mW)	
Traffic @1000Mbps	2.0	5 171.9	97.3	894.96	

Note: Test by FF corner IC in UTP TO SGMII mode with DVDD RGMII / DVDD33 / VDD33 LX / AVDD33 = 3.3V and VDDL = 1.2V (with inductor SWPA3012S2R2NT connected to VDD33 LX (pin33)) at high temperature 85°C.

#### 8.6. Fewer Noise

JMENTER JAEL The max noise of 3.3V should be under 50mV, and that of 1.2V should be under 50mV.

2025-03-27 21.5°



# Mechanical and Thermal

## 9.1. RoHS-Compliant Packaging

Motorcomm offers a RoHS package that is compliant with RoHS

#### Table 151. Part Number

Part Number	Status	Package	Op temp (°C)	Note
YT8521SC-CA	Active	QFN48 6x6mm	0 to 70	
YT8521SH-CA	Active	QFN48 6x6mm	-40 to 85	

#### 9.2. Thermal Resistance

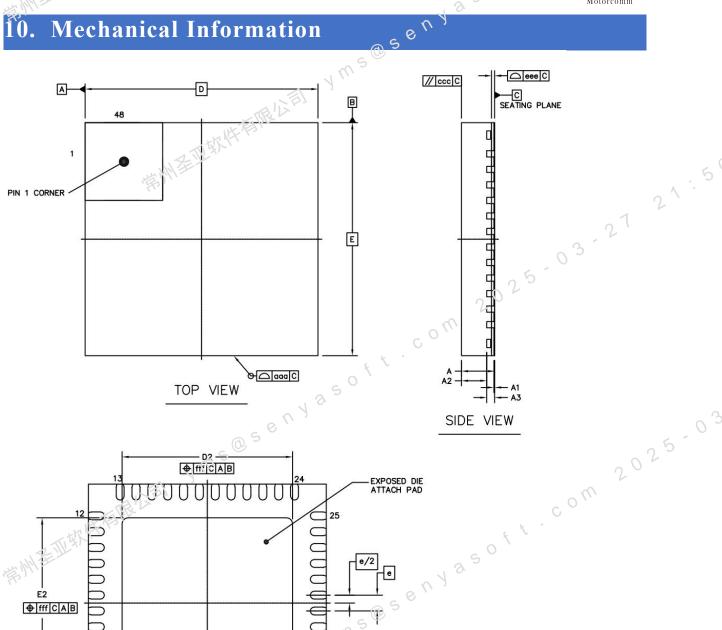
#### **Table 152. Thermal Resistance**

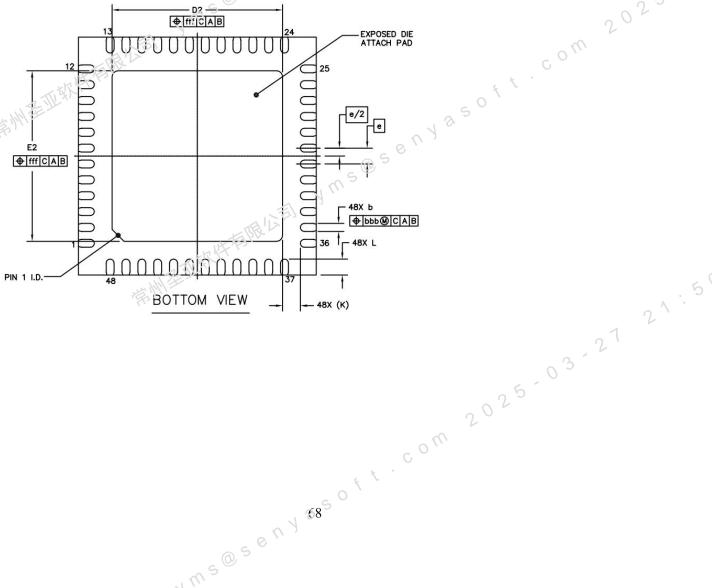
	14510 102: 1110		$\vee$		
Symbol	Parameter	Conditon	Typ	Units	
$\theta_{\mathrm{JA}}$	Thermal resistance - junction to ambient	JEDEC 3 in. x 4.5 in. 4-layer PCB with	27.2	°C/W	
	$\theta_{\rm JA} = (T_{\rm J} - T_{\rm A})/P$	no air flow TA=25°C			
	P = Total power dissipation	JEDEC 3 in. x 4.5 in. 4-layer PCB with	24.3	°C/W	
$\theta_{ m JC}$	Thermal resistance - junction to case	no air flow TA=100°C  JEDEC with no air flow	17.5	°C/W	
	$\theta_{\rm JC} = (T_{\rm J} - T_{\rm C})/P_{\rm top}$	60			
	$P_{top}$ = Power dissipation from the top of	23			
	the package				0
$\theta_{ m JB}$	Thermal resistance - junction to board	JEDEC with no air flow	7.1	°C/W	- 0
	$\theta_{\rm JB} = (T_{\rm J} - T_{\rm B})/P_{\rm bottom}$			_ 7	C
	P <sub>bottom</sub> = Power dissipation from the			20	
	bottom of the package to the PCB surface.		n		
崇州圣	近坎特有限心	enyasoft.	C O .		

以MS@SenyaSoft.C' 2025-03-27 2025-03-27



# 10. Mechanical Information





1			
	微 orc	_	-

otoreomm YT8521S	H-CA/Y185	215C-CA L	vatasneet	V 3	501	裕太微电子 Motorcomm	
		SYMBOL	MIN	<i>⊗</i> иом	MAX		
TOTAL THICKNESS		Α	0.80	0.85	0.9		
STAND OFF		A1		0.02	0.05		
MOLD THICKNESS		A2	9	0.65			
L/F THICKNESS		IA3		0.203 REF			
LEAD WIDTH	t	Ь	0.15	0.2	0.25	1	
BODY SIZE	XX	D		6 BSC	2	1	
BODT SIZE	J. J. Y	E		6 BSC			
LEAD PITCH	July	е		0.4 BSC			21:5
EP SIZE	Х	D2	4.2	4.3	4.4		2.
LI 5/2L	Y	E2	4.2	4.3	4.4	1	
LEAD LENGTH		L	0.3	0.4	0.5	2	
LEAD TIP TO EXPOSED	PAD EDGE	K		0.45 REF		03-27	
PACKAGE EDGE TOLERA	ANCE	aaa		0.1	5		
MOLD FLATNESS		ccc		0.1	23		
COPLANARITY		eee		0.08	2	1	
LEAD OFFSET		bbb		0,07	2	1	
EXPOSED PAD OFFSET		fff		<sup>©</sup> 0.1		1	
		2000	6 7	shood sho		1	
			0			1	

斯州基亚特高限公司

2025-03 2025-03 yms@senyasoft.com yms@senyasoft.

2025-03-27 2025-03-27



# 11. Ordering Information

Table 153. Ordering laformation

<b>3</b>							
Part Number	Grade	Package	Pack	Status	Operation Temp		
YT8521SC-CA	Consumer	QFN 48 6x6 mm	3000ea Tape&Reel	Mass	0 ~70°C		
		切及人	4900ea Tray	Production			
YT8521SH-CA	Industrial	QFN 48 6x6 mm	3000ea Tape&Reel	Mass	-40 ~ 85°C		
		亚龙,	4900ea Tray	Production			

2025-03-27 21:50 2025-0 表別を別様を展展以前 yms@senyasoft.com 2025-03

2025-03-27 2025-03-27 2025-03-27